# **Matrix Computations**

# **CPSC 5006-EL**

# **Assignment3**

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Q1

3.1.5

(a)

$$\begin{bmatrix} 1 & 1 \\ 1 & 1.5 \\ 1 & 2 \\ 1 & 2.5 \\ 1 & 3 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 1.1 \\ 1.2 \\ 1.3 \\ 1.3 \\ 1.4 \end{bmatrix}$$

(b)

```
t = 1:.5:3; t = t';

s = ones(5, 1); A = [s t];

y = [1.1 1.2 1.3 1.3 1.4]';

x = A \ y
```

 $x = 2 \times 1$ 0.9800
0.1400

(c)

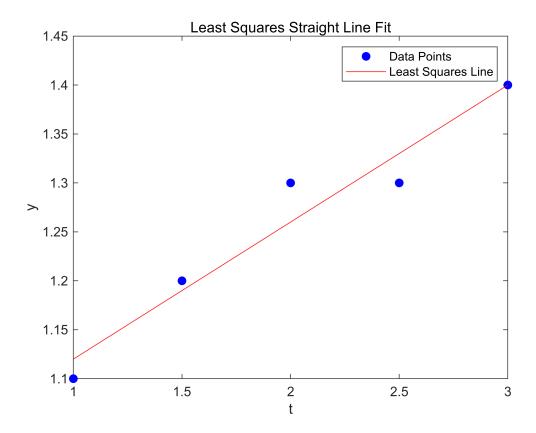
```
% Prepare for plotting
figure;
% Plot the data points
plot(t, y, 'bo', 'MarkerFaceColor', 'b', 'DisplayName', 'Data Points');
hold on; % Keep the plot open to add the least squares line

% Plot the least squares straight line
t_fine = linspace(min(t), max(t), 100); % finer division for line plot
y_fine = x(1) + x(2) * t_fine;
plot(t_fine, y_fine, 'r-', 'DisplayName', 'Least Squares Line');

% Set plot labels and title
xlabel('t');
ylabel('y');
title('Least Squares Straight Line Fit');

% Show legend
legend show;
```

% Show the plot
hold off;



(d)

ans = 0.0548

# 3.1.6

(a)

$$\begin{bmatrix} 1 & 1 & 1^2 \\ 1 & 1.5 & 1.5^2 \\ 1 & 2 & 2^2 \\ 1 & 2.5 & 2.5^2 \\ 1 & 3 & 3^2 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 1.1 \\ 1.2 \\ 1.3 \\ 1.3 \\ 1.4 \end{bmatrix}$$

(b)

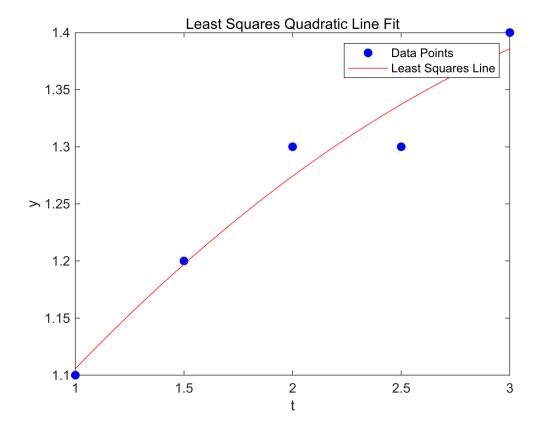
 $x = 3 \times 1$ 

0.8800

```
0.2543
-0.0286
```

(c)

```
% Prepare for plotting
figure;
% Plot the data points
plot(t, y, 'bo', 'MarkerFaceColor', 'b', 'DisplayName', 'Data Points');
hold on; % Keep the plot open to add the least squares line
% Plot the least squares straight line
t_fine = linspace(min(t), max(t), 100); % finer division for line plot
y_{fine} = x(1) + x(2) * t_{fine} + x(3) * power(t_{fine}, 2);
plot(t_fine, y_fine, 'r-', 'DisplayName', 'Least Squares Line');
% Set plot labels and title
xlabel('t');
ylabel('y');
title('Least Squares Quadratic Line Fit');
% Show legend
legend show;
% Show the plot
hold off;
```



(d)

$$norm(y - A*x)$$

ans = 0.0478

Q2

Q is orthogonal, then  $QQ^T = QQ^{-1} = I$ 

$$\langle Q\,x,Q\,y\rangle = (Q\,y)^T(Q\,x) = y^TQ^TQ\,x = y^Tx = \langle x,y\rangle$$

$$\langle Q x, Q x \rangle = \|Q x\|_2^2 = \langle x, x \rangle = \|x\|_2^2$$
, so  $\|Q x\|_2 = \|x\|_2$ 

Since 
$$||Q||_2 = \max_{||x||_2=1} ||Q x||_2$$
, for all **x**

So, 
$$||Q||_2 = \max_{||x||_2 = 1} ||x||_2 = 1$$

Since Q is orthognal,  $Q^T = Q^{-1}$  also preserves vector lengths,  $\|Q^{-1}\|_2 = 1$ 

then  $\kappa_2(Q) = \|Q\|_2 \|Q^{-1}\|_2 = 1$ 

Q3

3.2.14

$$c = \frac{2}{\sqrt{2^2 + 5^2}} = \frac{2}{\sqrt{29}}$$

$$s = \frac{5}{\sqrt{29}}$$

$$Q = \begin{bmatrix} c & -s \\ s & c \end{bmatrix} = \frac{1}{\sqrt{29}} \begin{bmatrix} 2 & -5 \\ 5 & 2 \end{bmatrix}$$

$$R = Q^{T} A = \frac{1}{\sqrt{29}} \begin{bmatrix} 2 & 5 \\ -5 & 2 \end{bmatrix} \begin{bmatrix} 2 & 3 \\ 5 & 7 \end{bmatrix} = \frac{1}{\sqrt{29}} \begin{bmatrix} 29 & 41 \\ 0 & -1 \end{bmatrix}$$

solving Q c = b

$$c = Q^T b = \frac{1}{\sqrt{29}} \begin{bmatrix} 2 & 5 \\ -5 & 2 \end{bmatrix} \begin{bmatrix} 12 \\ 29 \end{bmatrix} = \frac{1}{\sqrt{29}} \begin{bmatrix} 169 \\ -2 \end{bmatrix}$$

solving R x = c

$$x_2 = \frac{-2}{-1} = 2$$

$$x_1 = \frac{169 - 41 * 2}{29} = 3$$

$$x = \begin{bmatrix} 3 \\ 2 \end{bmatrix}$$

3.2.47

$$\tau = \|y\|_2 = \|1^2 + 1^2\|_2 = \sqrt{2}$$

Suppose, 
$$y = \begin{bmatrix} -\tau \\ 0 \end{bmatrix} = \begin{bmatrix} -\sqrt{2} \\ 0 \end{bmatrix}$$

$$u = \frac{(x-y)}{\|x-y\|_2} = \frac{\begin{bmatrix} 1\\1 \end{bmatrix} - \begin{bmatrix} -\sqrt{2}\\0 \end{bmatrix}}{\|\begin{bmatrix} 1\\1 \end{bmatrix} - \begin{bmatrix} -\sqrt{2}\\0 \end{bmatrix}\|} = \frac{\begin{bmatrix} 1+\sqrt{2}\\1 \end{bmatrix}}{\sqrt{(1+\sqrt{2})^2 + 1}} = \frac{1}{\sqrt{4+2\sqrt{2}}} \begin{bmatrix} 1+\sqrt{2}\\1 \end{bmatrix}$$

$$\hat{Q} = I - 2u u^T = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} - 2\left(\frac{1}{\sqrt{4+2\sqrt{2}}}\right)^2 \begin{bmatrix} 1+\sqrt{2} \\ 1 \end{bmatrix} \begin{bmatrix} 1+\sqrt{2} & 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} - \frac{1}{2+\sqrt{2}} \begin{bmatrix} 3+2\sqrt{2} & 1+\sqrt{2} \\ 1+\sqrt{2} & 1 \end{bmatrix}$$

$$= \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} - \begin{bmatrix} \frac{(3+2\sqrt{2})(2-\sqrt{2})}{2} & \frac{(1+\sqrt{2})(2-\sqrt{2})}{2} \\ \frac{(1+\sqrt{2})(2-\sqrt{2})}{2} & \frac{2-\sqrt{2}}{2} \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} - \begin{bmatrix} \frac{2+\sqrt{2}}{2} & \frac{\sqrt{2}}{2} \\ \frac{\sqrt{2}}{2} & \frac{2-\sqrt{2}}{2} \end{bmatrix}$$

$$= \begin{bmatrix} -\frac{\sqrt{2}}{2} & -\frac{\sqrt{2}}{2} \\ -\frac{\sqrt{2}}{2} & \frac{\sqrt{2}}{2} \end{bmatrix} = \frac{1}{\sqrt{2}} \begin{bmatrix} -1 & -1 \\ -1 & 1 \end{bmatrix}$$

$$\hat{R} = \hat{Q}^T A = \frac{1}{\sqrt{2}} \begin{bmatrix} -1 & -1 \\ -1 & 1 \end{bmatrix} \begin{bmatrix} 1 & 2 \\ 1 & 3 \end{bmatrix} = \frac{1}{\sqrt{2}} \begin{bmatrix} -2 & -5 \\ 0 & 1 \end{bmatrix}$$

(b)

$$D = \begin{bmatrix} -1 & 0 \\ 0 & 1 \end{bmatrix}$$

$$Q = \hat{Q}D = \frac{1}{\sqrt{2}} \begin{bmatrix} -1 & -1 \\ -1 & 1 \end{bmatrix} \begin{bmatrix} -1 & 0 \\ 0 & 1 \end{bmatrix} = \frac{1}{\sqrt{2}} \begin{bmatrix} 1 & -1 \\ 1 & 1 \end{bmatrix}$$

$$R = D\hat{R} = \begin{bmatrix} -1 & 0 \\ 0 & 1 \end{bmatrix} \frac{1}{\sqrt{2}} \begin{bmatrix} -2 & -5 \\ 0 & 1 \end{bmatrix} = \frac{1}{\sqrt{2}} \begin{bmatrix} 2 & 5 \\ 0 & 1 \end{bmatrix}$$

**Q4** 

3.2.37

(a)

$$u v^{T} = \begin{bmatrix} u_{1} \\ u_{2} \\ \vdots \\ u_{n} \end{bmatrix} \begin{bmatrix} v_{1} & v_{2} & \cdots & v_{n} \end{bmatrix} = \begin{bmatrix} u_{1}v_{1} & u_{1}v_{2} & \cdots & u_{1}v_{2} \\ u_{2}v_{1} & u_{2}v_{2} & \cdots & u_{2}v_{n} \\ \vdots & \vdots & \ddots & \vdots \\ u_{n}v_{1} & u_{n}v_{2} & \cdots & u_{n}v_{n} \end{bmatrix}$$

The outer product like  $u v^T$  results in nxn matrix.

$$(u v^{T}) B = \begin{bmatrix} u_{1}v_{1} & u_{1}v_{2} & \cdots & u_{1}v_{n} \\ u_{2}v_{1} & u_{2}v_{2} & \cdots & u_{2}v_{n} \\ \vdots & \vdots & \ddots & \vdots \\ u_{n}v_{1} & u_{n}v_{2} & \cdots & u_{n}v_{n} \end{bmatrix} \begin{bmatrix} B_{11} & B_{12} & \cdots & B_{1m} \\ B_{21} & B_{22} & \cdots & B_{1m} \\ \vdots & \vdots & \ddots & \vdots \\ B_{n1} & B_{n2} & \cdots & B_{nm} \end{bmatrix} = \begin{bmatrix} \sum_{i=1}^{n} u_{1}v_{i}B_{i1} & \sum_{i=1}^{n} u_{1}v_{i}B_{i2} & \cdots & \sum_{i=1}^{n} u_{1}v_{i}B_{im} \\ \sum_{i=1}^{n} u_{2}v_{i}B_{i1} & \sum_{i=1}^{n} u_{2}v_{i}B_{i2} & \cdots & \sum_{i=1}^{n} u_{2}v_{i}B_{im} \\ \vdots & \vdots & \ddots & \vdots \\ \sum_{i=1}^{n} u_{n}v_{i}B_{i1} & \sum_{i=1}^{n} u_{n}v_{i}B_{i2} & \cdots & \sum_{i=1}^{n} u_{n}v_{i}B_{im} \end{bmatrix}$$

Computing uvT

for i from 1 to n:

for j from 1 to n:

$$uvT[i, j] = u[i] * v[j]$$

Computing (uvT)B

for i from 1 to n:

for j from 1 to m:

$$C[i, j] = 0$$

for k from 1 to n:

$$C[i, j] = C[i, j] + uvT[i, k] * B[k, j]$$

flops = 
$$\sum_{i=1}^{n} \sum_{j=1}^{n} 1 + \sum_{i=1}^{n} \sum_{j=1}^{m} \sum_{k=1}^{n} 2 = n^2 + 2n^2 m \approx 2n^2 m$$

(b)

$$v^{T}B = \begin{bmatrix} v_{1} & v_{2} & \cdots & v_{n} \end{bmatrix} \begin{bmatrix} B_{11} & B_{12} & \cdots & B_{1m} \\ B_{21} & B_{22} & \cdots & B_{1m} \\ \vdots & \vdots & \ddots & \vdots \\ B_{n1} & B_{n2} & \cdots & B_{nm} \end{bmatrix} = \begin{bmatrix} \sum_{i=1}^{n} v_{i}B_{i1} & \sum_{i=1}^{n} v_{i}B_{i2} & \cdots & \sum_{i=1}^{n} v_{i}B_{im} \end{bmatrix}$$

The product like  $v^T B$  results in 1xm matrix.

$$u(v^{T}B) = \begin{bmatrix} u_{1} \\ u_{2} \\ \vdots \\ u_{n} \end{bmatrix} \begin{bmatrix} \sum_{i=1}^{n} v_{i}B_{i1} & \sum_{i=1}^{n} v_{i}B_{i2} & \cdots & \sum_{i=1}^{n} v_{i}B_{im} \end{bmatrix} = \begin{bmatrix} u_{1} \sum_{i=1}^{n} v_{i}B_{i1} & u_{1} \sum_{i=1}^{n} v_{i}B_{i2} & \cdots & u_{1} \sum_{i=1}^{n} v_{i}B_{im} \\ u_{2} \sum_{i=1}^{n} v_{i}B_{i1} & u_{2} \sum_{i=1}^{n} v_{i}B_{i2} & \cdots & u_{2} \sum_{i=1}^{n} v_{i}B_{im} \\ \vdots & \vdots & \ddots & \vdots \\ u_{n} \sum_{i=1}^{n} v_{i}B_{i1} & u_{n} \sum_{i=1}^{n} v_{i}B_{i2} & \cdots & u_{n} \sum_{i=1}^{n} v_{i}B_{im} \end{bmatrix}$$

Computing v^T B

for j from 1 to m:

vTB[j] = 0

for i from 1 to n:

$$vTB[j] = vTB[j] + v[i] * B[i, j]$$

Computing u(vTB)

for i from 1 to n:

for j from 1 to m:

$$C[i, j] = u[i] * vTB[j]$$

flops = 
$$\sum_{j=1}^{m} \sum_{i=1}^{n} 2 + \sum_{i=1}^{n} \sum_{j=1}^{m} 1 = 2nm + nm = 3nm$$

(c)

$$QB = B - uv^TB = B - u(v^TB)$$

We know that  $u(v^T B)$  needs 3nm flops. The minus operator takes 1nm flops

So the total flops =3nm + 1nm = 4nm

(d)

$$QB = \begin{bmatrix} q_{11} & q_{12} & \cdots & q_{1n} \\ q_{21} & q_{22} & \cdots & q_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ q_{n1} & q_{n2} & \cdots & q_{nn} \end{bmatrix} \begin{bmatrix} B_{11} & B_{12} & \cdots & B_{1m} \\ B_{21} & B_{22} & \cdots & B_{1m} \\ \vdots & \vdots & \ddots & \vdots \\ B_{n1} & B_{n2} & \cdots & B_{nm} \end{bmatrix} = \begin{bmatrix} \sum_{i=1}^{n} q_{1i}B_{i1} & \sum_{i=1}^{n} q_{1i}B_{i2} & \cdots & \sum_{i=1}^{n} q_{1i}B_{im} \\ \sum_{i=1}^{n} q_{2i}B_{i1} & \sum_{i=1}^{n} q_{2i}B_{i2} & \cdots & \sum_{i=1}^{n} q_{2i}B_{im} \\ \vdots & \vdots & \ddots & \vdots \\ \sum_{i=1}^{n} q_{ni}B_{i1} & \sum_{i=1}^{n} q_{ni}B_{i2} & \cdots & \sum_{i=1}^{n} q_{ni}B_{im} \end{bmatrix}$$

Computing QB

for i from 1 to n:

for j from 1 to m:

$$C[i, j] = 0$$

for k from 1 to n:

$$C[i, j] = C[i, j] + q[i, k] * B[k, j]$$

flops = 
$$\sum_{i=1}^{n} \sum_{j=1}^{m} \sum_{k=1}^{n} 2 = 2n^2 m$$

### Q5

$$Q = Q_1 Q_2 \cdots Q_{n-1}$$

$$Q_i = \begin{bmatrix} I_{i-1} & 0 \\ 0 & I - \gamma_i u^{(i)} u^{(i)T} \end{bmatrix}$$

where  $I_{i-1}$  denotes the identity matrix of dimension i-1.

According to Q4(c),

if  $(Q_2Q_3\cdots Q_{n-1})$  is computed,  $Q_1(Q_2Q_3\cdots Q_{n-1})$  takes  $4n^2$  flops

if  $(Q_3Q_4\cdots Q_{n-1})$  is computed,  $Q_2(Q_3Q_4\cdots Q_{n-1})$  takes  $4(n-1)^2$  flops

...

 $Q_{n-1}$  is computed

So, computing Q takes:

flops = 
$$4n^2 + 4(n-1)^2 + \dots + 1 \approx \frac{4}{3}n^3$$
.

#### Q6

$$Q_i = \begin{bmatrix} I_{i-1} & 0 \\ 0 & I - \gamma_i u^{(i)} u^{(i)T} \end{bmatrix}$$

where  $I_{i-1}$  denotes the identity matrix of dimension i-1.

for 
$$k = 1, ..., n-1$$

Determine  $Q_k = I - \gamma_k u^{(k)} u^{(k)T}$ 

$$a_{k:n, k+1:n} \leftarrow Q_k a_{k:n, k+1:n}$$

$$a_{\rm kk} \leftarrow -\tau_k$$

Computing  $a_{k:n, k+1:n} \leftarrow Q_k a_{k:n, k+1:n}$  costs a lot more than computing  $u^{(k)}$ .

So flops  $\approx$  Compute  $a_{k:n, k+1:n} \leftarrow Q_k a_{k:n, k+1:n}$ 

Since  $Q_k a_{k:n, k+1:n} = (I - \gamma_k u^{(k)} u^{(k)T}) a_{k:n, k+1:n}$ 

According to Q4(c), it takes  $4(n-k-1)^2$  flops, k=1,...,n

So, flops =  $4n^2 + 4(n-1)^2 + \dots + 1 \approx \frac{4}{3}n^3$ .

# Q7

#### 3.2.39

(a)

$$\tau = \|y\|_2 = \sqrt{3^2 + 4^2 + 1^2 + 3^2 + 1^2} = 6$$

$$y = \begin{bmatrix} -6 \\ 0 \\ 0 \\ 0 \\ 0 \end{bmatrix}, u = x - y = \begin{bmatrix} 3 \\ 4 \\ 1 \\ 3 \\ 1 \end{bmatrix} - \begin{bmatrix} -6 \\ 0 \\ 0 \\ 0 \end{bmatrix} = \begin{bmatrix} 9 \\ 4 \\ 1 \\ 3 \\ 1 \end{bmatrix}$$

$$\gamma = \frac{2}{\|u\|_2^2} = \frac{2}{9^2 + 4^2 + 1^2 + 3^2 + 1^2} = \frac{1}{54}$$

(i)

$$Q = I - \gamma u u^{T} = \begin{bmatrix} 1 & & & & 0 \\ & 1 & & & \\ & & 1 & & \\ & & & 1 & \\ 0 & & & & 1 \end{bmatrix} - \frac{1}{54} \begin{bmatrix} 9 \\ 4 \\ 1 \\ 3 \\ 1 \end{bmatrix} [9 \quad 4 \quad 1 \quad 3 \quad 1]$$

(ii)

$$=\begin{bmatrix} -\frac{1}{2} & -\frac{2}{3} & -\frac{1}{6} & -\frac{1}{2} & -\frac{1}{6} \\ -\frac{2}{3} & \frac{19}{27} & -\frac{2}{27} & -\frac{2}{9} & -\frac{2}{27} \\ -\frac{1}{6} & -\frac{2}{27} & \frac{53}{54} & -\frac{1}{18} & -\frac{1}{54} \\ -\frac{1}{2} & -\frac{2}{9} & -\frac{1}{27} & \frac{5}{6} & -\frac{1}{18} \\ -\frac{1}{6} & -\frac{2}{27} & -\frac{1}{54} & -\frac{1}{18} & \frac{53}{54} \end{bmatrix}$$

(b)

$$\tau = \|y\|_2 = \sqrt{0^2 + 2^2 + 1^2 + (-1)^2 + 0^2} = \sqrt{6}$$

$$y = \begin{bmatrix} -\sqrt{6} \\ 0 \\ 0 \\ 0 \\ 0 \end{bmatrix}, u = a - y = \begin{bmatrix} 0 \\ 2 \\ 1 \\ -1 \\ 0 \end{bmatrix} - \begin{bmatrix} -\sqrt{6} \\ 0 \\ 0 \\ 0 \\ 0 \end{bmatrix} = \begin{bmatrix} \sqrt{6} \\ 2 \\ 1 \\ -1 \\ 0 \end{bmatrix}$$

$$\gamma = \frac{2}{\|u\|_2^2} = \frac{2}{6 + 4 + 1 + 1 + 0} = \frac{1}{6}$$

(i)

$$Q a = (I - \gamma u u^{T}) a = \begin{bmatrix} 0 \\ 2 \\ 1 \\ -1 \\ 0 \end{bmatrix} - \frac{1}{6} \begin{bmatrix} \sqrt{6} \\ 2 \\ 1 \\ -1 \\ 0 \end{bmatrix} \begin{bmatrix} \sqrt{6} & 2 & 1 & -1 & 0 \end{bmatrix} \begin{bmatrix} 0 \\ 2 \\ 1 \\ -1 \\ 0 \end{bmatrix} = \begin{bmatrix} 0 \\ 2 \\ 1 \\ -1 \\ 0 \end{bmatrix} - \frac{1}{6} * 6 * \begin{bmatrix} \sqrt{6} \\ 2 \\ 1 \\ -1 \\ 0 \end{bmatrix} = \begin{bmatrix} -\sqrt{6} \\ 0 \\ 0 \\ 0 \end{bmatrix}$$

(ii)

$$= \begin{bmatrix} 0 & -\frac{\sqrt{6}}{3} & -\frac{\sqrt{6}}{6} & \frac{\sqrt{6}}{6} & 0 \\ -\frac{\sqrt{6}}{3} & \frac{1}{3} & -\frac{1}{3} & \frac{1}{3} & 0 \\ -\frac{\sqrt{6}}{6} & -\frac{1}{3} & \frac{5}{6} & \frac{1}{6} & 0 \\ \frac{\sqrt{6}}{6} & \frac{1}{3} & \frac{1}{6} & \frac{5}{6} & 0 \\ 0 & 0 & 0 & 0 & 1 \end{bmatrix}$$

$$Qa = \begin{bmatrix} 0 & -\frac{\sqrt{6}}{3} & -\frac{\sqrt{6}}{6} & \frac{\sqrt{6}}{6} & 0 \\ -\frac{\sqrt{6}}{3} & \frac{1}{3} & -\frac{1}{3} & \frac{1}{3} & 0 \\ -\frac{\sqrt{6}}{6} & -\frac{1}{3} & \frac{5}{6} & \frac{1}{6} & 0 \\ \frac{\sqrt{6}}{6} & \frac{1}{3} & \frac{1}{6} & \frac{5}{6} & 0 \\ 0 & 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 0 \\ 2 \\ 1 \\ -1 \\ 0 \end{bmatrix} = \begin{bmatrix} -\sqrt{6} \\ 0 \\ 0 \\ 0 \end{bmatrix}$$

#### 3.3.7

(a)

I guess 
$$x = \frac{(9+5)}{2} = 7$$

(b)

$$c = \frac{1}{\sqrt{2}}, s = \frac{1}{\sqrt{2}}$$

$$Q = \frac{1}{\sqrt{2}} \begin{bmatrix} 1 & -1 \\ 1 & 1 \end{bmatrix}$$

$$R = Q^{T}A = \frac{1}{\sqrt{2}} \begin{bmatrix} 1 & 1 \\ -1 & 1 \end{bmatrix} \begin{bmatrix} 1 \\ 1 \end{bmatrix} = \frac{1}{\sqrt{2}} \begin{bmatrix} 2 \\ 0 \end{bmatrix}$$

$$c = Q^{T}b = \frac{1}{\sqrt{2}} \begin{bmatrix} 1 & 1 \\ -1 & 1 \end{bmatrix} \begin{bmatrix} 9 \\ 5 \end{bmatrix} = \frac{1}{\sqrt{2}} \begin{bmatrix} 14 \\ -4 \end{bmatrix}$$

So, 
$$\hat{c} = 14$$
,  $\hat{R} = 2$ ,  $d = -4$ 

Since  $\hat{R}x = \hat{c}$ , so 2x = 14, x = 7

Since  $||s||_2^2 = ||\hat{c} - \hat{R}x||_2^2 + ||d||_2^2$  and  $||\hat{c} - \hat{R}x||_2^2 = 0$ 

then  $||s||_2 = ||d||_2 = 4$ .

#### Q8

### 3.3.10

#### (a)

```
n = 6; m = 3;
A = randn(n, m)
```

```
A = 6 \times 3
   -0.0068
              -1.0891
                          -1.4916
    1.5326
               0.0326
                          -0.7423
   -0.7697
               0.5525
                          -1.0616
    0.3714
               1.1006
                          2.3505
   -0.2256
               1.5442
                          -0.6156
    1.1174
               0.0859
                          0.7481
```

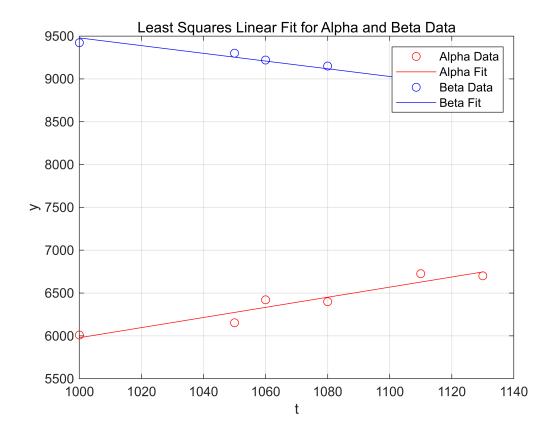
#### [Q, R] = qr(A)

ans =  $6 \times 6$ 

```
-0.0000
     1.0000
                      0.0000
                                0.0000
                                        0.0000
                                                 0.0000
    -0.0000
             1.0000
                      -0.0000
                                0.0000
                                        0.0000
                                                 -0.0000
     0.0000
             -0.0000
                       1.0000
                                0.0000
                                        0.0000
                                                 -0.0000
     0.0000
              0.0000
                       0.0000
                                1.0000
                                        -0.0000
     0.0000
              0.0000
                       0.0000
                               -0.0000
                                        1.0000
                                                 -0.0000
     0.0000
             -0.0000
                      -0.0000
                                        -0.0000
                                                  1.0000
 norm(eye(n) - Q' * Q)
 ans = 1.1462e-15
 norm(A - Q * R)
 ans = 2.7506e-15
(b)
 % Part (a): Prepare the Vandermonde matrix for quadratic polynomial fit
 t_a = [-1, -0.75, -0.5, 0, 0.25, 0.5, 0.75]';
 A_a = [ones(length(t_a), 1), t_a, t_a.^2];
 y_a = [1.00, 0.8125, 0.75, 1.00, 1.3125, 1.75, 2.3125]';
 % Solve for part (a)
 [x_a, residual_norm_a] = solve_least_squares(A_a, y_a)
 x_a = 3 \times 1
     1.0000
     1.0000
     1.0000
 residual_norm_a = 4.5776e-16
 % Part (b): Prepare the Vandermonde matrix for linear polynomial fit - alpha
 t_b_alpha = [1000, 1050, 1060, 1080, 1110, 1130]';
 A_b_alpha = [ones(length(t_b_alpha), 1) * 50, t_b_alpha - 1065];
 y_b_alpha = [6010, 6153, 6421, 6399, 6726, 6701]';
 % Solve for part (b) - alpha
 [x b alpha, residual norm b alpha] = solve least squares(A b alpha, y b alpha)
 x b alpha = 2 \times 1
   127.2458
     5.9067
 residual_norm_b_alpha = 194.1091
 % Part (b): Prepare the Vandermonde matrix for linear polynomial fit - beta
 t_b_beta = [1000, 1050, 1060, 1080, 1110, 1130]';
 A_b_beta = [ones(length(t_b_beta), 1) * 50, t_b_beta - 1065];
 y_b_beta = [9422, 9300, 9220, 9150, 9042, 8800]';
 % Solve for part (b) - beta
 [x b beta, residual norm b beta] = solve least squares(A b beta, y b beta)
 x b beta = 2 \times 1
```

183.7139

```
% Plotting for part (b)
figure; % Create a new figure
% Plot the data points for alpha
plot(t_b_alpha, y_b_alpha, 'ro', 'DisplayName', 'Alpha Data');
hold on; % Hold on to plot the fit on the same graph
% Compute the fitted values for alpha and plot
fitted_y_b_alpha = A_b_alpha * x_b_alpha;
plot(t_b_alpha, fitted_y_b_alpha, 'r-', 'DisplayName', 'Alpha Fit');
% Plot the data points for beta
plot(t_b_beta, y_b_beta, 'bo', 'DisplayName', 'Beta Data');
% Compute the fitted values for beta and plot
fitted_y_b_beta = A_b_beta * x_b_beta;
plot(t_b_beta, fitted_y_b_beta, 'b-', 'DisplayName', 'Beta Fit');
% Enhance the plot
title('Least Squares Linear Fit for Alpha and Beta Data');
xlabel('t');
ylabel('y');
legend('show');
grid on;
hold off; % Release the plot hold
```



#### 3.3.15

```
A = randn(5, 3)
A = 5 \times 3
   -0.1924
                         0.1978
              0.4882
    0.8886
              -0.1774
                         1.5877
   -0.7648
              -0.1961
                         -0.8045
   -1.4023
              1.4193
                         0.6966
   -1.4224
               0.2916
                         0.8351
A = A * diag([1 3 9])
A = 5 \times 3
                         1.7803
   -0.1924
              1.4646
    0.8886
              -0.5321
                        14.2893
   -0.7648
              -0.5882
                        -7.2402
   -1.4023
              4.2579
                         6.2696
   -1.4224
               0.8748
                         7.5158
[Q, R, P] = qr(A)
Q = 5 \times 5
   -0.0944
              0.3011
                         0.2088
                                   -0.8264
                                              -0.4171
                                              -0.4347
   -0.7578
              -0.4255
                         0.1439
                                    0.1873
    0.3840
               0.0172
                         -0.4872
                                    0.2194
                                              -0.7529
   -0.3325
               0.8522
                         0.0503
                                    0.3952
                                              -0.0675
   -0.3986
               0.0433
                        -0.8342
                                   -0.2788
                                               0.2563
R = 5 \times 3
  -18.8565
              -1.7252
                         0.0843
         0
              4.3235
                        -1.7056
         0
                         1.5763
```

diag command copy A's first column, 3 times A's second column, 9 times A's third column.

Permutation P is 
$$\begin{bmatrix} & & 1 \\ & 1 \\ 1 & & \end{bmatrix}$$
 , it swap A's first column and third column.

A's third column has been magnified by 9, which has maximal norm.