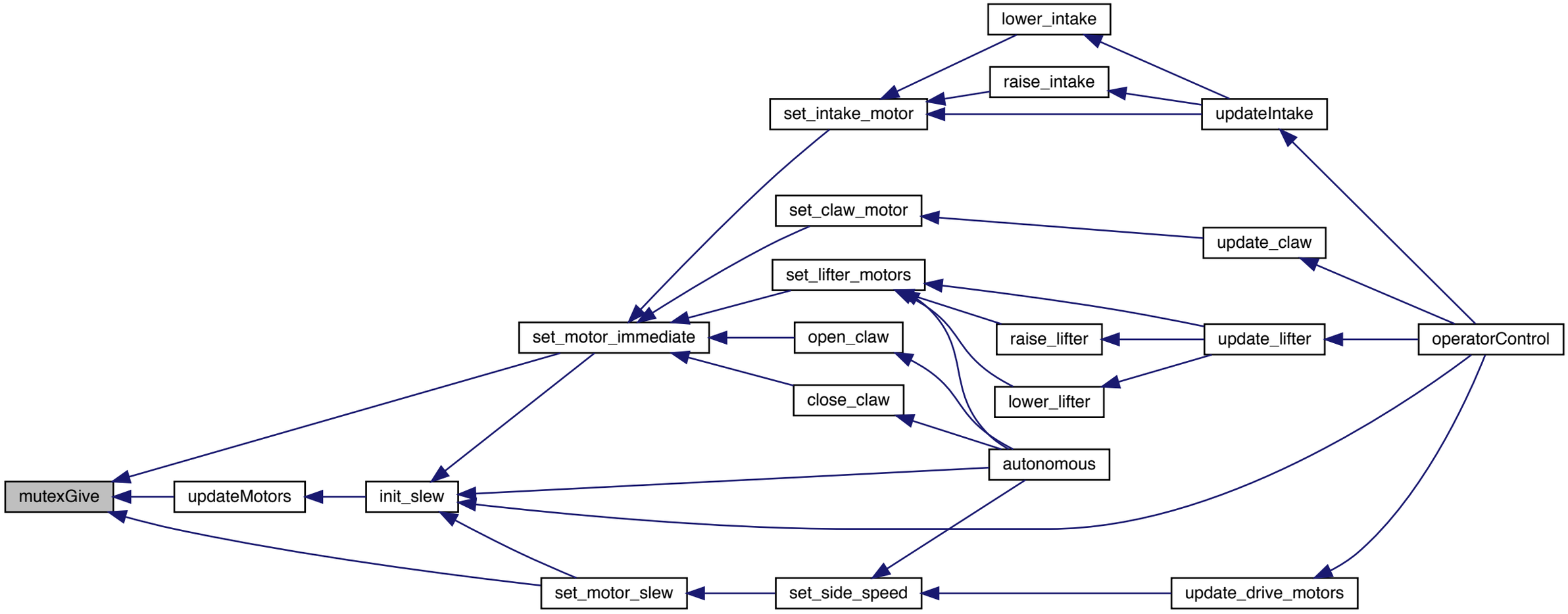
lower_intake
raise_intake
set_intake_motor
updateIntake
set_claw_motor
update_claw
set_lifter_motors
set_motor_immediate
open_claw
raise_lifter
update_lifter
operatorControl
close_claw
lower_lifter
autonomous
mutexGive
updateMotors
init_slew
set_motor_slew
set_side_speed
update_drive_motors