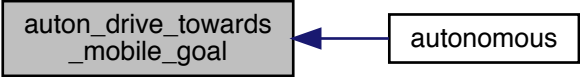


auton_drive_towards
_mobile_goal



```
graph LR; A[autonomous] --> B[auton_drive_towards _mobile_goal]
```

The diagram consists of two rectangular boxes. The box on the left is light gray with a black border and contains the text 'auton_drive_towards' on the top line and '_mobile_goal' on the bottom line. The box on the right is white with a black border and contains the text 'autonomous'. A dark blue arrow points from the right side of the 'autonomous' box to the right side of the gray box.

autonomous