

Relational Abstraction in HybridSAL

Ashish Tiwari

SRI International

Menlo Park

CA 94025

Relational Abstraction: Concept

Consider a dynamical system (X, \rightarrow) where

X : variables defining **state space** of the system

\rightarrow : binary relation over state space defining **system dynamics**

We do not care if

- the system is **discrete-** or **continuous-** or **hybrid-time**, or
- the system has a **discrete**, **continuous**, or **hybrid state space**

For discrete-time systems, \rightarrow is the one-step transition relation

For continuous-time systems, $\rightarrow = \bigcup_{t \geq 0} \xrightarrow{t}$ where \xrightarrow{t} is the transition relation corresponding to an elapse of t time units

Relational Abstraction: Concept

Relational abstraction of a dynamical system (X, \rightarrow) is another dynamical system (X, \rightarrow) such that

$$\text{TransitiveClosure}(\rightarrow) \subseteq \rightarrow$$

Relational Abstraction: An over-approximation of the transitive closure of the transition relation

Benefit:

Eliminates need for iterative fixpoint computation

Useful for proving safety properties, and establishing conservative safety bounds

Relational Abstraction: Example

For the continuous-time continuous-space dynamical system:

$$\begin{aligned}\frac{dx}{dt} &= -x + y \\ \frac{dy}{dt} &= -x - y\end{aligned}$$

we have the following continuous-space discrete-time relational abstraction:

$$(x, y) \rightarrow (x', y') \quad := \quad \max(|x|, |y|) \geq \max(|x'|, |y'|)$$

If initially $x \in [0, 3]$, $y \in [-2, 2]$, then in **any** future time, x, y will remain in the range $[-3, 3]$

Relational Abstraction: Challenge

Is it possible to **compute** relational abstractions?

We do **not** want to abstract discrete-time transition relations, because model checkers (and static analyzers) can handle them (compute fixpoint)

Is it possible to **compute** relational abstractions of continuous-time dynamics?

Computing Relational Abstractions

We have an **algorithm** for computing relational abstractions of **linear** systems

Dynamics	Relational Abstraction
$\dot{x} = 1, \dot{y} = 1$	$x' - x = y' - y$
$\dot{x} = 2, \dot{y} = 3$	$(x' - x)/2 = (y' - y)/3$
$\dot{\vec{x}} = A\vec{x}$	$(0 \leq p' \leq p) \vee (0 \geq p' \geq p)$, where $p = \vec{c}^T \vec{x}$, \vec{c} eigenvector of A^T corr. to negative eigenvalue
$\dot{\vec{x}} = A\vec{x} + \vec{b}$...

Computing Relational Abstractions

For linear systems, we can use plenty of linear algebra to **automatically** generate relational abstractions

More generally, there is a **standard** way to generate relational abstractions using **constraint solving**

The relation \rightarrow is a rel.abs. of \rightarrow if

$$\begin{aligned}\text{Init}(\vec{x}) &\Rightarrow \vec{x} \rightarrow \vec{x} \\ \vec{x} \rightarrow \vec{x} \wedge \vec{x}' \rightarrow \vec{y} &\Rightarrow \vec{x} \rightarrow \vec{y}\end{aligned}$$

We can search for \rightarrow that satisfies the above two formulas.

We can do so by fixing a form/template for \rightarrow

Then, we will get a $\exists\forall$ constraint, whose solution will give us a relational invariant

Note for Linear Systems

The algorithm for creating relational abstractions can be viewed as a special case of the generic method described above, where the $\exists\forall$ problems are being solved using linear algebra tricks.

HybridSAL Implementation of RelAbs

Old HybridSAL:

$$\text{HybridSAL} \xRightarrow{\text{QualitativeAbstraction}} \text{SAL}$$

Resulting SAL was finite-state model, could be model checked

Now we can also create relational abstractions from HybridSAL:

$$\text{HybridSAL} \xRightarrow{\text{RelationalAbstraction}} \text{SAL}$$

Resulting SAL is **infinite-state** model, can be **infinite bounded model checked**