

LoRa Edge

Manual

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Version	Changes
1.0	First release.
1.2	Support for more configuration via downlink, sensor integration in Wi-Fi payload and radio beacon.
1.3	Changed downlink for software version 1.3

1. Hardware pinout

How the microcontroller (ATSAMD21G18) pins are connected on the board is displayed in Table 1: Pinout Skylab board. This table also displays the name in the Arduino IDE.

Table 1: Pinout Skylab board

PA02 A0 A0, DACO PA03 - - PA04 - - PA05 AINS (battery) AINS PA06 D0 D0 PA07 D8 D8 PA08 D3 D3 PA09 D4 D4 PA10 Busy (LR1110) EVENT PA11 Event (LR1110) EVENT PA12 - - PA13 - - PA14 NRESET (LR1110) NRESET PA15 LED Red LEDR PA16 MOSI MOSI PA17 SCK SCK PA18 NSS (LR1110) NSS PA19 MISO MISO PA20 INT2 (LSM303AGR) INT2 PA21 INT1 (LSM303AGR) INT1 PA22 SDA SDA PA23 SCL SCL PA24 D- (usb) PIN_USB_DM PA25 D-	uC pin	Board pin	Name in Arduino IDE
PA04 - - PA05 AIN5 (battery) AIN5 PA06 D0 D0 PA07 D8 D8 PA08 D3 D3 PA09 D4 D4 PA10 Busy (LR1110) BUSY PA11 Event (LR1110) EVENT PA12 - - PA13 - - PA14 NRESET (LR1110) NRESET PA15 LED Red LEDR PA16 MOSI MOSI PA17 SCK SCK PA18 NSS (LR1110) NSS PA19 MISO MISO PA20 INT2 (LSM303AGR) INT2 PA21 INT1 (LSM303AGR) INT1 PA22 SDA SDA PA21 INT1 (LSM303AGR) INT1 PA22 SDA SDA PA23 SCL SCL PA24 D- (usb) PIN_USB_DM PA25	PA02	A0	A0, DAC0
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PA21 INT1 (LSM303AGR) INT1 PA22 SDA SDA PA23 SCL SCL PA24 D- (usb) PIN_USB_DM PA25 D+ (usb) PIN_USB_DP PA27 PA27 (pad) PA27 PA28 PA28 (pad) PA28 PA30 SWDCLK/TCK (debug pins) - PA31 SWDIO/TMS (debug pins) - PB02 PB02 (pad) PB02 PB03 PB03 (pad) PB03 PB08 LNA (GNSS) LNA PB09 INT3 (LSM303AGR) INT3 PB10 LED Green LEDG PB11 LED Blue LEDB PB22 TX PIN_SERIAL_TX	PA19	MISO	MISO
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PA23 SCL SCL PA24 D- (usb) PIN_USB_DM PA25 D+ (usb) PIN_USB_DP PA27 PA27 (pad) PA27 PA28 PA28 (pad) PA28 PA30 SWDCLK/TCK (debug pins) - PA31 SWDIO/TMS (debug pins) - PB02 PB02 (pad) PB02 PB03 PB03 (pad) PB03 PB08 LNA (GNSS) LNA PB09 INT3 (LSM303AGR) INT3 PB10 LED Green LEDG PB11 LED Blue LEDB PB22 TX PIN_SERIAL_TX	PA21	INT1 (LSM303AGR)	INT1
PA24 D- (usb) PIN_USB_DM PA25 D+ (usb) PIN_USB_DP PA27 PA27 (pad) PA27 PA28 PA28 (pad) PA28 PA30 SWDCLK/TCK (debug pins) - PA31 SWDIO/TMS (debug pins) - PB02 PB02 (pad) PB02 PB03 PB03 (pad) PB03 PB08 LNA (GNSS) LNA PB09 INT3 (LSM303AGR) INT3 PB10 LED Green LEDG PB11 LED Blue LEDB PB22 TX PIN_SERIAL_TX	PA22	SDA	SDA
PA25 D+ (usb) PIN_USB_DP PA27 PA27 (pad) PA27 PA28 PA28 (pad) PA28 PA30 SWDCLK/TCK (debug pins) - PA31 SWDIO/TMS (debug pins) - PB02 PB02 (pad) PB02 PB03 PB03 (pad) PB03 PB08 LNA (GNSS) LNA PB09 INT3 (LSM303AGR) INT3 PB10 LED Green LEDG PB11 LED Blue LEDB PB22 TX PIN_SERIAL_TX	PA23	SCL	SCL
PA27 PA27 (pad) PA27 PA28 PA28 (pad) PA28 PA30 SWDCLK/TCK (debug pins) - PA31 SWDIO/TMS (debug pins) - PB02 PB02 (pad) PB02 PB03 PB03 (pad) PB03 PB08 LNA (GNSS) LNA PB09 INT3 (LSM303AGR) INT3 PB10 LED Green LEDG PB11 LED Blue LEDB PB22 TX PIN_SERIAL_TX	PA24	D- (usb)	PIN_USB_DM
PA28 PA28 (pad) PA28 PA30 SWDCLK/TCK (debug pins) - PA31 SWDIO/TMS (debug pins) - PB02 PB02 (pad) PB02 PB03 PB03 (pad) PB03 PB08 LNA (GNSS) LNA PB09 INT3 (LSM303AGR) INT3 PB10 LED Green LEDG PB11 LED Blue LEDB PB22 TX PIN_SERIAL_TX	PA25	D+ (usb)	PIN_USB_DP
PA30 SWDCLK/TCK (debug pins) - PA31 SWDIO/TMS (debug pins) - PB02 PB02 (pad) PB02 PB03 PB03 (pad) PB03 PB08 LNA (GNSS) LNA PB09 INT3 (LSM303AGR) INT3 PB10 LED Green LEDG PB11 LED Blue LEDB PB22 TX PIN_SERIAL_TX	PA27	PA27 (pad)	PA27
PA31 SWDIO/TMS (debug pins) - PB02 PB02 (pad) PB02 PB03 PB03 (pad) PB03 PB08 LNA (GNSS) LNA PB09 INT3 (LSM303AGR) INT3 PB10 LED Green LEDG PB11 LED Blue LEDB PB22 TX PIN_SERIAL_TX	PA28	PA28 (pad)	PA28
PB02 PB02 (pad) PB02 PB03 PB03 (pad) PB03 PB08 LNA (GNSS) LNA PB09 INT3 (LSM303AGR) INT3 PB10 LED Green LEDG PB11 LED Blue LEDB PB22 TX PIN_SERIAL_TX	PA30	SWDCLK/TCK (debug pins)	-
PB03 PB03 (pad) PB03 PB08 LNA (GNSS) LNA PB09 INT3 (LSM303AGR) INT3 PB10 LED Green LEDG PB11 LED Blue LEDB PB22 TX PIN_SERIAL_TX	PA31	SWDIO/TMS (debug pins)	-
PB08 LNA (GNSS) LNA PB09 INT3 (LSM303AGR) INT3 PB10 LED Green LEDG PB11 LED Blue LEDB PB22 TX PIN_SERIAL_TX	PB02	PB02 (pad)	PB02
PB09 INT3 (LSM303AGR) INT3 PB10 LED Green LEDG PB11 LED Blue LEDB PB22 TX PIN_SERIAL_TX	PB03	PB03 (pad)	PB03
PB10 LED Green LEDG PB11 LED Blue LEDB PB22 TX PIN_SERIAL_TX	PB08	LNA (GNSS)	LNA
PB11 LED Blue LEDB PB22 TX PIN_SERIAL_TX	PB09	INT3 (LSM303AGR)	INT3
PB22 TX PIN_SERIAL_TX	PB10	LED Green	LEDG
	PB11	LED Blue	LEDB
PB23 RX PIN_SERIAL_RX	PB22	TX	PIN_SERIAL_TX
	PB23	RX	PIN_SERIAL_RX

2. Charging

How to connect the battery and the solar panel is showed in Figure 1: How to connect the battery and solar panel.

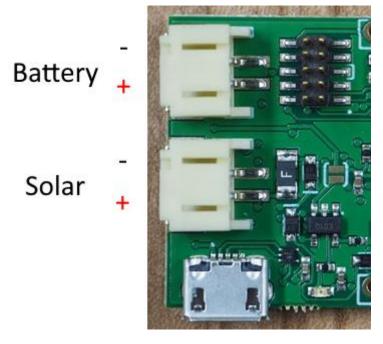


Figure 1: How to connect the battery and solar panel

Charging a lithium ion battery can be done by the USB port or by the solar connector (solar connector can be used with a solar panel or a direct DC power supply). The voltage must be a maximum of 5.5 volt. The meaning of the battery LED is explained in Table 2: Charge controller states.

Table 2: Charge controller states

Charge controller state	LED
No battery	OFF
Charging	ON
Charge complete	OFF
Shutdown	OFF

The battery jumper must be connected when using the charge controller (see Figure 2: Battery jumper).

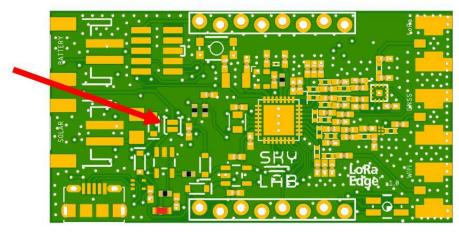


Figure 2: Battery jumper

3. Configure Arduino IDE

The Arduino IDE can be used for uploading software via the micro USB port. Before it can be used the IDE must be configured.

The first thing is to install the board via board manager.

Go to File → Preferences. Add the following link to Additional Boards Manager URLs:

https://github.com/SkyLabIoT/LoRaEdge BasicTracking/raw/master/package skylab index.json

The board package can be downloaded via Tools \rightarrow Board \rightarrow Boards Manager... by searching for SkyLab.

Select the board via Tools \rightarrow Board \rightarrow SkyLab Boards \rightarrow SkyLab LoRa Edge.

The example sketch can be loaded via File \rightarrow Examples \rightarrow SkyLab LoRa Edge \rightarrow BasicLoRaA.

4. Example mode A device (BasicLoRaA)

How to use the mode A example sketch.

4.1. Joining network

After uploading the mode A example sketch the serial monitor can be opened on a 9600 baud rate. The system starts with displaying the configured join_eui, dev_eui and app_key. The join_eui is requested from the LR1110 chip and is unique to that specific chip. This key should be used in the console of the used network. The dev_eui and app_key are configured in the code and should be changed for the correct keys, given by the used network console. If configured correctly the device automatically joins.

4.2. Configure via downlink

Downlinks should be send on port 2.

The downlink format should be as follows:

0	1-2	3	4	5
LED	Interval	Beacon	Wi-Fi	GNSS

Byte 0: LED

This byte configures the status LED

0 = OFF

1 = ON (during Wi-Fi scan (blue), GNSS scan (red) and radio beacon (green))

Others = keep current setting

Byte 1 and 2: Interval

These 2 bytes configure the standard interval time between messages

Time is in minutes. Interval set to 0 will keep current setting and will not set an new interval time. Maximum time is 65535 minutes.

Byte 3: Beacon

This byte configure the time that de beacon is turned on. Time is in minutes. Maximum time is 255 minutes.

When set to 0 the beacon will not be turned on.

Byte 4: Wi-Fi

This byte turns the Wi-Fi payload on or off.

0 = OFF

1 = ON

Others = keep current setting

Byte 5: GNSS

This byte turns the GNSS payload on or off.

0 = OFF

1 = ON

Others = keep current setting

Downlink examples:

LED on, interval on 5 minutes, no beacon, Wi-Fi and GNSS payload on: 01 00 05 00 00 00 01 01

LED off, interval 600 minutes, no beacon, Wi-Fi payload on, GNSS payload off: 00 15 36 00 00 00 01 00 $\,$

Keep current LED and interval setting, no beacon, Wi-Fi payload off, GNSS payload on: $02\,00\,00\,00\,00\,00\,01$

Turn beacon on for 5 minutes, keep all other current settings: 02 00 00 01 00 05 02 02

4.3. Uplink format

The mode A example sketch can send 4 types of payload. These payloads types are identifiable by the port number used.

On port 1:

The LR1110 sends an automated message when joining and every 24 hours after that. This message can be ignored.

On port 2:

This is the Wi-Fi and sensor payload. This payload has the information of 3 Wi-Fi points and the sensor data. The format is as follows:

	0	1-6	7	8-13	14	15-20
Ī	RSSI 1	MAC 1	RSSI 2	MAC 2	RSSI 3	MAC 3

21	22-23	24-25	26
Battery voltage	Temperature	Pressure	Humidity

Byte 0, 7 and 14:

These bytes have the RSSI / signal strength of the scanned Wi-Fi points. These values must be interpreted as signed integers.

Byte 1 to 6, 8 to 13 and 15 to 20:

These bytes have the MAC addresses of the scanned Wi-Fi points.

Byte 21: Battery voltage

This byte has the raw battery voltage value. The exact voltage can be calculated with:

Voltage = (float)((3.3 / 255) * ((4.7 + 10) / 10) * (Battery voltage));

Byte 22 to 23: Temperature

These bytes have the temperature value. The exact temperature in degree Celsius (°C) can be calculated with:

Temperature = (float)(Temperature / 100);

Byte 24 to 25: Pressure

These bytes have the air pressure value. The exact pressure in degree hector Pascal (hPa) can be calculated with:

Air pressure = (float)(Pressure / 10);

Byte 26: Humidity

This byte has the humidity value in %.

On port 3:

This is the GNSS payload. This payload only has the raw GNSS data and is variable in size.

On port 10:

This payload is used as a "I am awake" message. By default it is set to every 24 hours. This can be changed by changing the value "controlTime". The format is as follows:

0	
Battery	
voltage	

Byte 0: Battery voltage

This byte has the raw battery voltage value. The exact voltage can be calculated with: Voltage = (float)((3.3 / 255) * ((4.7 + 10) / 10) * (Battery voltage));

4.4. Beacon

When the beacon setting is set to 1 the beacon will be activated. The device will leave the network and sends a random LoRa payload every second on the 869800000 Hz frequency (outside the official LoRa frequency). The green LED will turn on if the LED activation is set to 1. The beacon will stop when the set time is reached. The system will rejoin the network and operate as before.