

FT62F21X Application note



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FT62F21X IR Receive 应用

1 IR 介绍

一个通用的红外遥控系统由发射和接收两大部分组成,如图 1 所示:

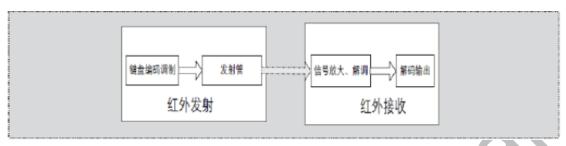


图 1

发射部分主要包括键盘矩阵、编码调制、红外发射管; 接收部分包括光、电信号的转换 以及放大、解调、解码电路。

举例来说,通常我们家电遥控器信号的发射,就是将相应按键所对应的控制指令和系统码(由 0 和 1 组成的序列),调制在 32~56kHz 范围内的载波上(目的为: 抗干扰及低功率),然后经放大(接三极管)、驱动红外发射管(透明的头)将信号发射出去。

本讲解以IC FT60F011A SOP8为示范,采用一体的红外接收头,接收头输出脚连到MCU的 IO口,IO口通过识别高低电平时间长短来解码,当收到的数据是合法的,指示LED的状态(开与关)会翻转一次。接收的IO口使用电平变化中断来识别信号,并使用定时器记录电平的时间长短。

本程序IR接收与LED所对应的IO引脚:

#define IRRIO RA2

#define LED RA4

2 应用范例

//**********************

/* 文件名: TEST_FT62F21x_IR_Receive.c

* 功能: FT62F21x-红外接收 功能演示

* IC: FT62F211 SOP8

* 晶振: 16M/4T

* 说明: 演示程序中,IR 红外是采用 6122 协议,起始信号是 9ms 低电平,到 4.5ms 高

电平,再到低 8 位用户识别码,到高 8 位的用户识别码, 8 位数据码, 8 位数据

* 码的反码。RXIO(PA2)每次收到遥控器发过来的数据后,如果数据合法(两

* 对补码,不对内容判断),LED(PA4)开关状态就改变一次。

*

FT62F211 SOP8

* ______

* LED------NC (PA3)8|-----NC

```
NC------|2(TKCAP) (PA0)7|-----NC
  VDD-----|3(VDD)
                    (PA1)6|----NC
 GND-----|4(VSS)
                    (PA2)5|-----IRRIO
*/
//*******************
#include "SYSCFG.h";
#include "FT62F21X.h";
#define uchar
                unsigned char
#define uint
                unsigned int
#define ulong
                unsigned long
                      //LED 指示灯的 IO
#define LED
                RA4
#define IRRIO
                RA2
                      //IR 的接收脚
uchar IRbitNum = 0;
                      //用于记录接收到第几位数据
                      //用于计时一位的时间长短
uchar IRbitTime = 0;
uchar IRDataTimer[4];
                      //存出来的 4 个数据
uchar bitdata=0x01;
                      //用于按位或的位数据
uchar ReceiveFinish = 0;
                      //用于记录接收完成
                      //用于读取 IO 口状态, 电平变化中断标志清除
uchar ReadAPin = 0;
uchar rdata1,rdata2;
   函数名:
          interrupt ISR
   功能:
          定时器 0 中断和 PA 电平变化中断
  输入:
          无
          无
  输出:
void interrupt ISR(void)
                      //PIC HI-TECH 使用
 if(T0IE && T0IF)
                            //104us
      TMR0 = 140;
                            //注意:对TMR0重新赋值TMR0在两个周期内不变化
      T0IF = 0;
      IRbitTime++;
      if(IRbitTime > 50)
      {
         T0IE = 0;
         IRbitTime = 0;
```

```
}
if(PAIE && PAIF)
{
    ReadAPin = PORTA;
                             //读取 PORTA 数据清 PAIF 标志
    PAIF = 0;
    if(IRRIO == 0)
        T0IE = 1;
        if(IRbitTime > 21)
            IRDataTimer[0] = 0;
            IRDataTimer[1] = 0;
           IRDataTimer[2] = 0;
            IRDataTimer[3] = 0;
            IRbitNum = 0;
           bitdata = 0x00;
        else if(IRbitTime > 3)
            IRDataTimer[IRbitNum-1] |= bitdata;
        IRbitTime = 0;
        bitdata<<=1;
        if(bitdata == 0)
            bitdata = 0x01;
           IRbitNum++;
        if(IRbitNum > 4)
            IRbitNum = 0;
            T0IE = 0;
            ReceiveFinish = 1;
函数名: POWER_INITIAL
       上电系统初始化
功能:
输入:
        无
```



```
输出:
          无
void POWER INITIAL (void)
   OSCCON = 0B01110000;
                             //WDT 32KHZ IRCF=111=16MHZ/4=4MHZ,0.25US/T
                               //暂禁止所有中断
   INTCON = 0;
   PORTA = 0B000000000:
                               //PA 输入输出 0-输出 1-输入
   TRISA = 0B00000100;
                               //PA 端口上拉控制 1-开上拉 0-关上拉
   WPUA = 0B00000100;
                              //Bit3=1 WDT MODE,PS=000=1:1 WDT RATE
   OPTION = 0B00001000;
                              //Bit7(PAPU)=0 由 WPUA 决定是否上拉
   MSCON = 0B000000000;
* 函数名称: TIMERO INITIAL
* 功能:初始化设置定时器
* 相关寄存器: TOCS TOCS TOSE PSA
* 设置 TMR0 定时时长 560us=(1/16000000)*4*16*140(16M-2T-PSA 1:16- TMR0=255 溢出)
void TIMERO INITIAL (void)
   OPTION = 0B00000011;
                           //预分频器分配给 Timer0, 预分频比为 1:16, 上升沿
   //Bit5 T0CS Timer0 时钟源选择
   //1-外部引脚电平变化 T0CKI 0-内部时钟(FOSC/2)
   //Bit4 T0CKI 引脚触发方式 1-下降沿 0-上升沿
   //Bit3 PSA 预分频器分配位 0-Timer0 1-WDT
   //Bit2:0 PS2 8 个预分频比 011 - 1:16
   TMR0 = 140
   T0IF = 0;
                           //清空 T0 软件中断
* 函数名: PA2 Level Change INITIAL
   功能: PA 端口(PA2)电平变化中断初始化
   输入: 无
* 输出: 无
void PA2 Level Change INITIAL(void)
{
   TRISA2 = 1;
                        //SET PA2 INPUT
   ReadAPin = PORTA;
                        //清 PA 电平变化中断
```

```
//清 PA INT 中断标志位
   PAIF = 0;
                            //使能 PA2 电平变化中断
   IOCA2 = 1;
                            //使能 PA INT 中断
   PAIE =1;
   //GIE = 1;
                            //使能全局中断
* 函数名: main
   功能: 主函数
           无
   输入:
   输出:
         无
void main()
{
                                  //系统初始化
   POWER_INITIAL();
   TIMER0_INITIAL();
                                  //初始化 PA 端口电平中图
   PA2_Level_Change_INITIAL();
   GIE = 1;
                                   //开总中断
   while(1)
   {
       if(ReceiveFinish)
           ReceiveFinish = 0;
           rdata1 = 0xFF - IRDataTimer[0];
           rdata2 = 0xFF - IRDataTimer[2];
           if((rdata1 == IRDataTimer[1])&&(rdata2 == IRDataTimer[3]))
                                   //翻转电平
               LED = \sim LED;
```



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