

The WDSP Guide

Using WDSP - for Software Developers

WDSP is a full-featured signal processing library for Software Defined Radio. While assuming general SDR and programming knowledge, this guide provides the specifics of setting up and accessing WDSP.



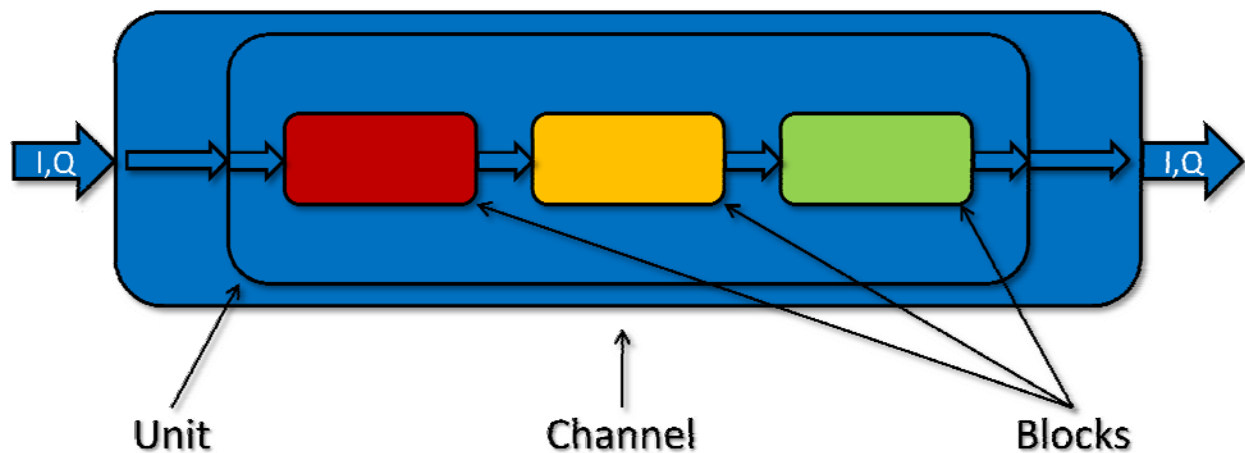
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WDSP Organization



Within WDSP, a “channel” is the home for a single “unit”. The channel provides input/output buffering to permit the unit to run asynchronously from the outside world and it provides to the unit a thread for its computations. When a channel is “opened”, it is told which type of unit, from a selection of types, it is to house. Channels are independent of each other. Each has its own fundamental parameters, e.g., buffer sizes and sample rates. Channels can operate in parallel, in series, or have no particular relationship at all to each other.

Units are generally major functional items such as a receiver, a transmitter, an interstellar exhorborator, or whatever other major signal processing one requires. However, should one need to wrap a single simple function within the channel structure, a unit could certainly be defined to do so.

The unit houses a number of blocks and buffers as needed to implement its function. For example, in the case of a transmitter, some of the blocks would be a compressor, a band-pass filter, and ALC.

The channel remains exactly the same no matter what unit is housed within. To function within a channel, there is, of course, a specific structure expected of the unit. Once written, the unit can be replicated in as many channels as desired. Likewise, there is a specific structure expected of the blocks that are housed within the units. This block structure supports multiple instances of any block within a unit; for example, you could write a block that implements a particular type of filter and then use three different instances of that filter with the same unit. Likewise, once written, a block can be instantiated within multiple types of units.

Operation of the Channel

Instantiation and Initialization

A channel is instantiated as the result of a call to `OpenChannel(...)`.

`void OpenChannel (int channel, int in_size, int dsp_size, int input_samplerate, int dsp_rate, int output_samplerate, int type, int state, double tdelayup, double tslewup, double tdelaydown, double tslewdown, int bfo)`

The return type is `void` and the parameters are:

`int channel` – The unique identifier you wish to assign to this channel. Currently a number ranging 0 to 31. This range can be extended as needed.

`int in_size` – The size (as a count of complex samples) that is to be provided as input to the channel each time an exchange function is called. This value is required to be a power of two.

`int dsp_size` – The size (as a count of complex samples) that is used internally for DSP processing. This sets the size of buffers of data that are passed through the unit and therefore through its blocks. This parameter is required to be a power of two.

`int input_samplerate` – The sample-rate of the input data to the channel.

`int dsp_rate` - The sample rate used internally within the blocks of the unit for DSP processing. This rate may affect certain performance characteristics such as filter shape factors. It must be related to the channel input and output sample-rates by powers of two. It may either be a sub-multiple, equal, or a multiple; however, the ratio must be a power of two.

`int output_samplerate` – The sample-rate of the output data from the channel (may or may not be the same as the input sample-rate). Note, however, that the output sample rate is required to be related to the input sample-rate by a power of two. It may either be a sub-multiple, equal, or a multiple; however, the ratio must be a power of two.

`int type` – A number that has been assigned to the particular type of unit that is to be housed within this particular channel. At this time, two channel types are available. For the RXA Receiver the type is 0 and for the TXA transmitter the type is 1.

`int state` - If set to 0 in `OpenChannel(...)`, the channel will be created but will not operate until the state is later changed to 1; if set to 1 in `OpenChannel(...)`, after creation, the channel will start, up-slew, and continue to operate as soon as it is provided with input data via an exchange function call.

`double tdelayup` - Time (in seconds) to delay before beginning an up-slew.

`double tslewup` - Length (in seconds) of an up-slew.

`double tdelaydown` - Time (in seconds) to delay before beginning a down-slew.

`double tslewdown` - Length (in seconds) of a down-slew.

`int bfo` - If non-zero, the call to an exchange function will NOT return until output data is available. This is useful in situations where input data is not guaranteed to arrive at regular intervals.

Setting the Channel State

The `state` variable of the channel is changed using

`int SetChannelState (int channel, int state, int dmode)`

This function returns the PRIOR value of `state`, i.e., the value at the time the call was made.

Setting channel state is used anytime it is desired to turn ON or OFF the operation of a channel. (This is the ONLY call to turn ON/OFF a channel.) One common situation is the transmit-receive transition.

Example 1: Receive to Transmit

For the receiver: `SetChannelState (0, 0, 1);`

[Deactivate receiver hardware and fully activate transmit hardware here]

Then, for the transmitter: `SetChannelState (5, 1, 0);`

The receiver will (1) wait `tdelaydown` before taking action, (2) down-slew its audio output during time `tslewdown`, (3) flush the channel and zero the output buffer, and (4) stop operating entirely so as to not use CPU cycles. With `dmode` set to 1, the function `SetChannelState(...)` will NOT return until these actions have been completed. Therefore, with the receiver and transmitter calls made in sequence, we know that the transmitter cannot begin its up-slew until the receiver is completely OFF. (More on `dmode == 0` later.) **Note that the receiver hardware should remain FULLY ACTIVE until the down-slew is complete; without samples flowing, it is impossible for the down-slew and a subsequent channel flush to occur.**

The transmitter will then (1) wait to see non-zero samples coming in, (2) wait `tdelayup` before taking action, (3) up-slew its MIC audio input during time `tslewup`, and (4) remain ON until its state is again changed. **Note that the transmitter hardware should be FULLY ACTIVE before the up-slew begins; otherwise, an abrupt turn-on in transmitter power (a discontinuity) would result.**

Example 2: Transmit to Receive

For the transmitter: `SetChannelState (5, 0, 1);`

[Deactivate transmitter hardware and fully activate receiver hardware here]

Then, for the receiver: `SetChannelState (0, 1, 0);`

The transmitter will (1) wait `tdelaydown` before taking action, (2) down-slew its I-Q output during time `tslewdown`, (3) flush the channel and zero the output buffer, and (4) stop operating entirely so as to not

use CPU cycles. With **dmode** set to 1, the function `SetChannelState(...)` will NOT return until these actions have been completed. Therefore, with the transmitter and receiver calls made in sequence, we know that the receiver cannot begin its up-slew until the transmitter is completely OFF. (More on **dmode** == 0 later.) **Note that the transmitter hardware should remain FULLY ACTIVE until the down-slew is complete; without samples flowing, it is impossible for the down-slew and a subsequent channel flush to occur.**

The receiver will then (1) wait to see non-zero samples coming in, (2) wait **tdelayup** before taking action, (3) up-slew its I-Q input during time **tslewup**, and (4) remain ON until its state is again changed. **Note that the receiver hardware should be FULLY ACTIVE before the up-slew begins; otherwise, an abrupt turn-on in received signal (a discontinuity) would result.**

Example 3: Receive to Transmit, when we want to turn off multiple receivers

The primary difference here is that if we were to turn-off all receivers with **dmode** set to 1, each would down-slew and turn-off in sequence. This would mean more delay than necessary in making the transition from receive to transmit. The receivers should slew down and turn-off in parallel.

For the first receiver: `SetChannelState (0, 0, 0);`

For the second receiver: `SetChannelState (1, 0, 1);`

[Deactivate receiver hardware and fully activate transmit hardware here]

For the transmitter: `SetChannelState (5, 1, 0);`

In this case, the call for the first receiver will immediately return. The call for the second receiver, however, will wait until that receiver has turned-off. As long as the first receiver has the same or less delay and slew time specified, it should also be off when the call to the second receiver returns. Then, after flipping the hardware, the transmitter is turned on.

There could be very minor differences in execution times for the two receivers; however, those should be relatively insignificant compared to any delay and slew times. A very small transmitter delay can be used to resolve any differences.

Important Additional Information

- When you call `SetChannelState(...)` with **state** == 1, **dmode** has no effect. The call begins the turn-on sequence and returns immediately. (Exception: If you call to begin the turn-on sequence while a turn-off sequence is in process, the function waits until the turnoff completes, initiates the turn-on, then returns.)
- If you call `SetChannelState(...)` with **state** == 1 when its state is already 1, nothing new happens; the function just returns. If an up-slew was in process, it just continues.
- If you call `SetChannelState(...)` with **state** == 0 when its state is already 0, nothing new happens; the function just returns. If a down-slew was in process, it just continues. Also, note here that if **dmode** is set to 1 to "shadow" a prior call to turn OFF a receiver, there will be no delay in the

return of the call and the "shadowing" will not happen. You can check for this condition since the call returns the prior `state`.

- This function has a "Time-Out." If no input data is being provided to the channel, and this function is called to set `state` to 0, and `dmode == 1`, then, in the absence of a Time-Out, the function would never return because without data it can never complete the down-slew and subsequent flush. Similarly, if the function is called to set `state` to 1 and if a previous down-slew has not completed and has no data to complete, the function would never return. The Time-Out will cause the function to return after an extended time, currently set internally to ~200mS. This Time-Out feature is useful if the console is, for some reason, trying to manipulate the channel state in the absence of dataflow, for example during console start-up before data is flowing.

Setting Other Channel Parameters

Primary channel parameters are those that are initially specified in the `OpenChannel(...)` call that creates the channel. These parameters can be reset to different values at later times using appropriate calls. Resetting the channel `state` has been discussed above. Resetting of other parameters is discussed here.

`void SetDSPBuffsize (int channel, int dsp_size)`

Sets the buffer size used for DSP internal processing. `dsp_size` will determine the size of FFTs used for the bandpass filters and many other filters, and it will determine the size of buffers processed by other blocks. `dsp_size` is required to be a power of two in order to achieve highest efficiency in FFT operation.

This function can be called at any time, **on the control thread**, including when data is flowing on the data input thread. It sets the channel `state` to 0, makes the necessary changes, and then sets the channel `state` back to its previous value. If data is flowing, it will necessarily pause channel processing to make the changes; however, it will not block the data input thread during this time. Data output will properly slew to zero, flush the channel, stay at zero during the changes, and properly slew back up to full strength.

Data flow should NOT be terminated during the time this function is executing. Doing so could result in a "broken" down-slew and the lack of a channel flush. This should be easily manageable when the flow of data is controlled on the same control thread that calls this function.

`void SetDSPSamplerate (int channel, int dsp_rate)`

Sets the sample rate used for internal DSP processing. Note that, among other things, `dsp_rate` will affect the shape factor of filters.

This function can be called at any time, **on the control thread**, including when data is flowing on the data input thread. It sets the channel `state` to 0, makes the necessary changes, and then sets the channel `state` back to its previous value. If data is flowing, it will necessarily pause channel processing to make the changes; however, it will not block the data input thread during this time. Data output will

properly slew to zero, flush the channel, stay at zero during the changes, and properly slew back up to full strength.

Data flow should NOT be terminated during the time this function is executing. Doing so could result in a "broken" down-slew and the lack of a channel flush. This should be easily manageable when the flow of data is controlled on the same control thread that calls this function.

void SetInputSamplerate (int channel, int in_rate)

The channel's **state** must be set to 0 (use **dmode == 1** if calling **SetChannelState(...)** to be sure the operation is complete) before this function is called. It may be useful to make other changes that have a similar requirement, for example changing the channel's "Input Buffsize," while the channel **state** is still 0 and then returning it to 1 if appropriate.

void SetInputBuffsize (int channel, int in_size)

The channel's **state** must be set to 0 (use **dmode == 1** if calling **SetChannelState(...)** to be sure the operation is complete) before this function is called. It may be useful to make other changes that have a similar requirement, for example changing the channel's "Input Samplerate," while the channel **state** is still 0 and then returning it to 1 if appropriate.

void SetOutputSamplerate (int channel, int out_rate)

The channel's **state** must be set to 0 (use **dmode == 1** if calling **SetChannelState(...)** to be sure the operation is complete) before this function is called.

void SetAllRates (int channel, int in_rate, int dsp_rate, int out_rate)

This is an alternative call that can be used to set all three channel rates at the same time. The channel's **state** must be set to 0 (use **dmode == 1** if calling **SetChannelState(...)** to be sure the operation is complete) before this function is called.

void SetChannelTDelayUp (int channel, double time)

channel: identifier/number of the channel being accessed

time: time (seconds) to delay before beginning an up-slew

void SetChannelTSlewUp (int channel, double time)

channel: identifier/number of the channel being accessed

time: length of the up-slew (seconds)

void SetChannelTDelayDown (int channel, double time)

channel: identifier/number of the channel being accessed

time: time (seconds) to delay before beginning a down-slew

void SetChannelTSlewDown (int channel, double time)

channel: identifier/number of the channel being accessed

time: length of the down-slew (seconds)

void SetType (int channel, int type)

Changing the channel **type** requires completely destroying the old unit and building a new one. While the channel parameters as specified in the **OpenChannel(...)** call will be preserved, all parameters that had been stored in the blocks of the unit will be destroyed and the new unit will be created with default values.

Exchanging Data

The channel uses a time-slice-exchange model meaning that, immediately after a channel consumes a set of samples representing the signal for a certain window of time, a set of samples representing that same amount of time will be written out in exchange. Note that the number of in-samples may be different than the number of out-samples if a sample-rate change occurred somewhere in the channel processing. For example, in the case of a receiver channel, the incoming I/Q sample rate might be 384K and the output audio sample rate might be 48K. Therefore, 1024 input samples would be exchanged for 128 output samples.

All exchanges are for a power-of-two quantity of complex samples. The input samples will be consumed just BEFORE the output samples are written out. Therefore, the same buffer can be used for input and output samples if desired. There is a choice of exchange calls, depending upon the organization of the data. For example, if your data is organized in buffers of datatype double with interleaved I and Q, you can call:

```
//double, interleaved I/Q
void fexchange0 (int channel, double* in, double* out, int* error)
```

You are providing the channel number, a pointer to the input buffer, a pointer to the output buffer (which could be the same as the input buffer), and a pointer to an error indicator. The error indicator will indicate whether the unit had provided data or whether zeros were returned instead. For example, suppose a unit isn't getting enough CPU cycles to keep up, in that case an error will be indicated and zeros will be returned. ***error** will be a non-zero value in the event of an error and will otherwise be returned as 0.

As another example, suppose your data is stored in separate I and Q buffers and the datatype is float. Then you'd use:

```
//separate I/Q buffers
void fexchange2 (int channel, INREAL* Iin, INREAL* Qin, OUTREAL* Iout, OUTREAL* Qout, int* error)
```

INREAL and OUTREAL is normally defined as `float` in the file "comm.h".

When changing "fundamental channel parameters", calls to a 'fexchange' function may continue; however, no new data will be accepted until the reconfiguration is complete. The thread calling 'fexchange' will not be blocked.

Note that the `fexchange0(...)` function (interleaved, double, I and Q) is the preferred method of providing samples. Interleaved values is the standard for type 'complex' and the FFTW library uses this format. Using `fexchange2(...)` with its separate I and Q buffers also requires more CPU cycles since a conversion to interleaved format must be made.

WDSP Wisdom Calculations

Several of the Blocks provided make use of the FFTW library for FFT operations. A function is provided to calculate the FFTW wisdom file.

void WDSPwisdom (char* directory)

'directory' is a pointer to a string containing the path to the directory where the wisdom file is to be stored.

This function should be called each time the application is opened. It will load the wisdom file if it is already present or create it if it is not.

The wisdom file includes all Forward/Backward, Complex/Real wisdom required for both RXA / TXA processing and for display processing.

The RXA Receiver Unit

Channel Parameters for RXA

The channel code serves as the interface between the unit it houses and the outside world. Considering this, some of the channel parameters relate only to the outside world. However, others impact the operation or perceived operation of the unit. It is this latter category of parameters that we discuss again here.

dsp_size: The unit only processes data when **dsp_size** samples have been accumulated. This parameter therefore impacts the latency incurred in DSP processing. Generally, using a lower **dsp_size** will reduce latency. However, these lower values mean a larger number of buffers are processed per unit time and each buffer requires some amount of processing overhead. Therefore, lower **dsp_size** implies some increase in the CPU load. **For RXA, running at a dsp_rate of 48000, dsp_size ranging from a minimum of 64 to a maximum of 1024 offers a reasonable range of trade-offs -- 64 for minimum latency and 1024 to minimize CPU load.**

Note, however, that there is an important relationship among **dsp_size**, **dsp_rate**, **in_size**, and **input_samplerate**. For example, consider the case where **dsp_size** = 64, **dsp_rate** = 48000, **input_samplerate** = 192000 and **in_size** = 256. As discussed below, a resampler will be automatically invoked to resample the input from 192000 down to 48000. For each four samples at the 192000 input rate, only one sample at the 48000 rate will be produced. Therefore, 256 input samples (**in_size**) will be required to populate a buffer of 64 such that DSP processing can proceed. This implies that making **in_size** less than 256 will not speed-up DSP processing. In this example, making it 128 would only mean that input must be supplied twice before a single DSP buffer could be processed.

dsp_rate: **dsp_rate** not only impacts latency, as described just above, it also impacts the results in filtering operations. Doubling **dsp_rate** doubles the width of filter transition bands. This can be precisely compensated by doubling the number of filter coefficients. (See later sections on band-pass filters.) Of course, increasing the rate and increasing the complexity of the filter, both require more CPU cycles. **RXA has been designed to run optimally at a dsp_rate of 48000 for modes other than FM and at a rate of 192000 for FM.**

tdelayup, tslewup, tdelaydown, tslewdown: Typical settings for these parameters are given here. Note that for non-CW modes they are more generous to give a very smooth sound while for CW they are more restricted for fast turnaround.

CW: tdelayup = 0.005; tslewup = 0.010; tdelaydown = 0.000; tslewdown = 0.005.

Other modes: tdelayup = 0.010; tslewup = 0.025; tdelaydown = 0.000; tslewdown = 0.010.

Signal Levels for RXA

RXA assumes that an input signal magnitude of 1.0 corresponds to 0dBm. $\text{Magnitude} = \sqrt{I^2 + Q^2}$.

It is recommended that the input be scaled to conform to this.

Since all computations in WDSP are done in double-precision floating point, and assuming levels stay well within that range, most RXA blocks are level-independent. However, that is not exclusively true. There are a few places where absolute level matters:

- 1) Metering outputs. The meter outputs provide a 0 dBm output for a signal magnitude of 1.0. If your input scaling differs from this, you can compensate externally by adding or subtracting some fixed dBm value from the metering outputs.
- 2) Spectrum display (data following the band-pass filter). This output will need to be scaled accordingly if your input scaling is different than that prescribed above.
- 3) Squelch Thresholds. These will need to be scaled accordingly if your input scaling is different than that prescribed above.
- 4) AGC. Various AGC features such as "Slope" and "Hang" require specification of a maximum input level. By default, this is set to 1.0. If your maximum input level is different, you can change this value by calling:

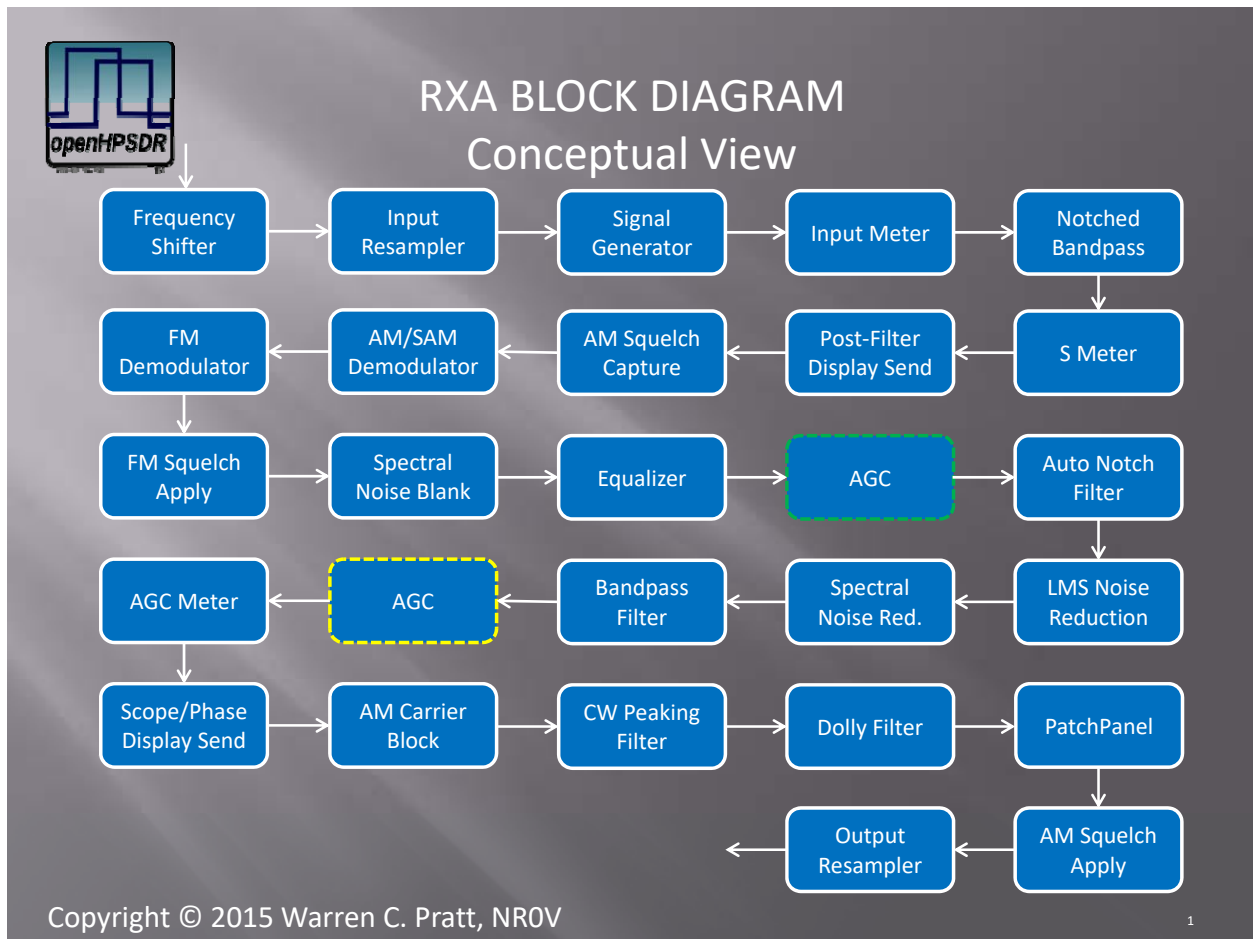
void SetRXAAGCMaxInputLevel (int channel, double level)

channel: number of the receiver channel being accessed

level: maximum input level.
[default = 1.0]

Block Diagram & Controls

A diagram showing the blocks comprising the RXA Unit is shown below. For clarity in explaining the operation, some minor simplifications have been made; therefore, this is titled as a "Conceptual View."



The purpose/function of each block and the calls to control each block will now be explained.

Frequency Shifter

The frequency shifter generates a complex oscillator and multiplies the incoming sample stream by this oscillator. In analog radio terms, it's functions would be that of a "local oscillator" and "mixer." This process effectively rotates the incoming frequency spectrum by the frequency of the complex oscillator. There are several uses of this functionality, for example: (1) Click-Tune functionality where the panadapter display spectrum is static but the user clicks on a particular signal to receive, and (2) applying a final frequency offset at the output of the DFC (Direct Fourier Conversion) process.

Note that this is done BEFORE the resampler. Therefore, if resampling is to be done to a lower rate for internal DSP processing, a portion of the total input spectrum can be selected for further processing rather than only being able to rotate the portion of the spectrum available at the lower rate.

void SetRXShiftRun (int channel, int run)

channel: number of the receiver channel being accessed

run: turns the shifter OFF/ON, 0 for OFF, 1 for ON
[default = 1]

void SetRXShiftFreq (int channel, double fshift)

channel: number of the receiver channel being accessed

fshift: frequency of the complex oscillator in Hertz
[default = 0.0]

Resamplers

In the discussion above of channel parameters, three distinct rates are mentioned:

input_samplerate: samplerate of data entering the channel

dsp_rate: internal rate at which the data is processed within the unit

output_samplerate: samplerate of data exiting the channel

Two resamplers are provided within the RXA unit to convert among these rates. The first of these, the "Input Resampler," converts from the **input_samplerate** to the **dsp_rate**. The second of these, the "Output Resampler," converts from the **dsp_rate** to the **output_samplerate**.

No external calls are provided or needed to control these resamplers. The three rates are set by the channel parameters and the resamplers are automatically activated when rates differ and therefore resampling is required.

Signal Generator

The signal generator is available to support testing and experimentation on RXA. When it is turned ON, it replaces the incoming samples with the signal samples from the generator output. It is not used for normal operation and is turned OFF by default. Therefore, its control calls can be completely ignored if the console does not desire to expose this functionality.

The signal generator can produce quite a few different types of signal outputs. However, only a subset of those have thus far been deemed useful for RXA and only that subset is currently supported with a full set of controls for RXA. The total set of possible outputs comprises: Tone, Two-Tone, Noise, Sweep, Sawtooth, Triangle, Pulse (can also pulse a tone on and off), and Silence. Sawtooth, Triangle, and Pulse produce an I-only (audio) output with Q = 0.0.

The set of outputs currently supported for RXA comprises: Tone, Noise, Sweep, and Silence.

void SetRXAPreGenRun (int channel, int run)

channel: number of the receiver channel being accessed

run: 0 to turn the generator OFF, 1 to turn the generator ON
[default = 0]

void SetRXAPreGenMode (int channel, int mode)

channel: number of the receiver channel being accessed

mode: Tone = 0, Noise = 2, Sweep = 3, Silence = 99
[default = 2]

void SetRXAPreGenToneMag (int channel, double mag)

channel: number of the receiver channel being accessed

mag: peak magnitude value of the single-tone (mode = 0). Typical range is 0.0 to 1.0.
[default = 1.0]

void SetRXAPreGenToneFreq (int channel, double freq)

channel: number of the receiver channel being accessed

freq: frequency (Hertz) of the single-tone (mode = 0). Can be either positive or negative.
[default = +1000.0]

void SetRXAPreGenNoiseMag (int channel, double mag)

channel: number of the receiver channel being accessed

mag: magnitude value of the noise (mode = 2). Typical range is 0.0 to 1.0.
[default = 1.0]

void SetRXAPreGenSweepMag (int channel, double mag)

channel: number of the receiver channel being accessed

mag: peak magnitude of swept single tone (mode = 3). Typical range is 0.0 to 1.0.
[default = 1.0]

void SetRXAPreGenSweepFreq (int channel, double freq1, double freq2)

channel: number of the receiver channel being accessed

freq1, freq2: frequency limits of the sweep range (Hertz). These may be either positive or negative. Sweep progresses from freq1 to freq2 and then repeats.
[defaults: freq1 = -20000.0, freq2 = +20000.0]

void SetRXAPreGenSweepRate (int channel, double rate)

channel: number of the receiver channel being accessed

rate: rate at which the sweep progresses (Hertz / Second).
[default = +4000.0]

Input, S, and AGC Meters

As shown in the block diagram, three sets of RXA metering data are available to the console: Input-level, S-level (after the bandpass and notch filtering), and AGC-level (after the AGC). For Input, Input_peak and Input_average are available. For S, S_peak and S_average are available. For AGC, AGC_peak, AGC_average, and AGC_gain are available.

The console can call for individual values any time it wants to update the respective meter user interfaces.

double GetRXAMeter (int channel, int mt)

return value: requested meter value (dBm, except dB for AGC_gain)

channel: number of the receiver channel being accessed

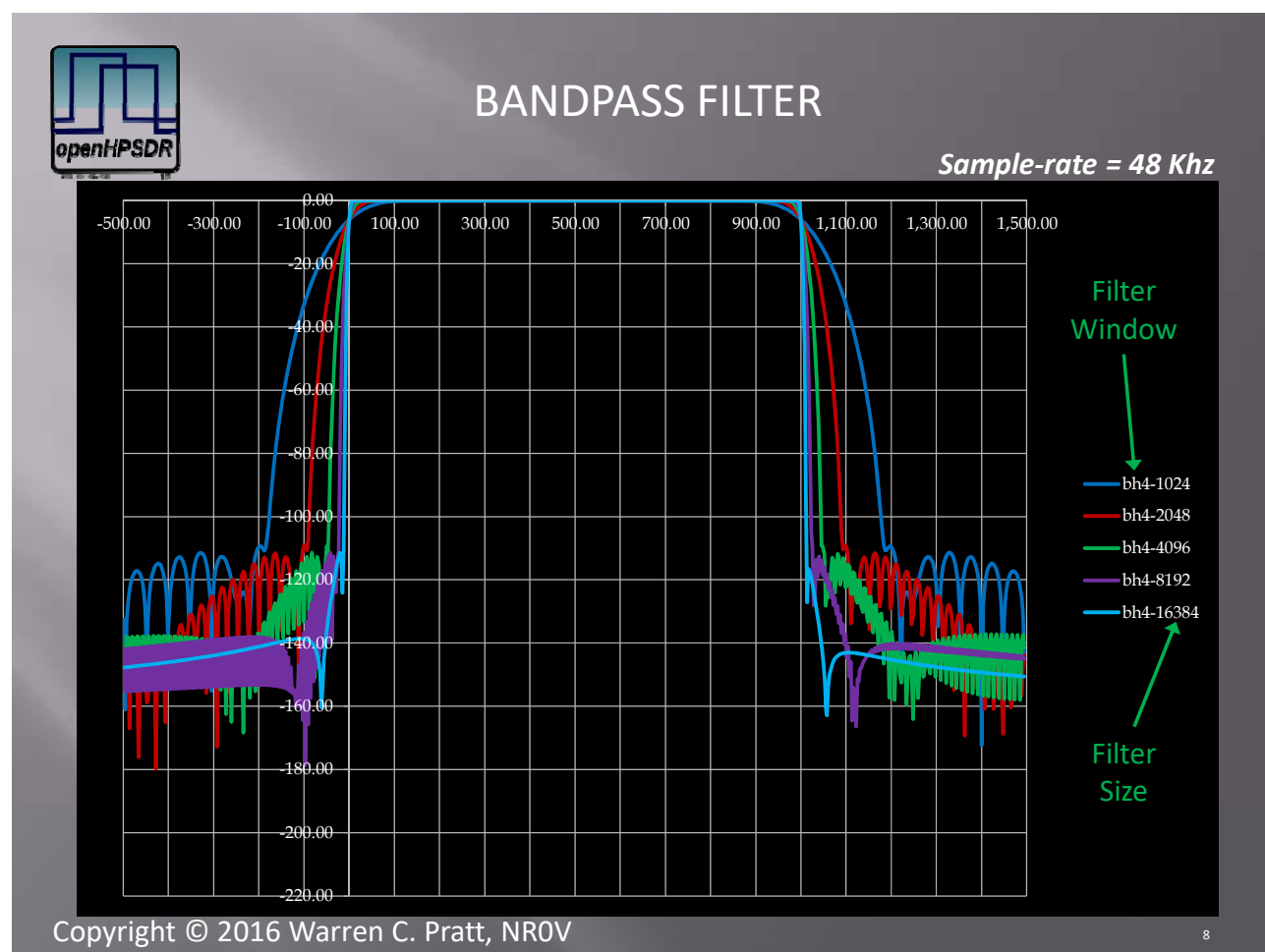
mt: type of meter data being requested. **mt** values are: S_peak = 0, S_average = 1, Input_peak = 2, Input_average = 3, AGC_gain = 4, AGC_peak = 5, AGC_average = 6.

Notched Bandpass Filter

The Notched Bandpass Filter provides both the primary bandpass filtering AND the fixed notch filtering (pre-specified notch frequencies as opposed to automatic notch filtering). Therefore, both the lower and upper bandpass limits and all the notch filtering information must be specified.

The "sharpness" of these filters, when running RXA at a `dsp_rate` of 48000, is shown in the following two figures. The first of these figures shows the response curves for different impulse response lengths, all using the 4-term Blackman-Harris window. The second figure is the same except using the 7-term Blackman-Harris window. The 4-term yields slightly sharper cutoff; however, less cutoff depth. The 4-term would be preferred in most situations since its cutoff depth approaches the dynamic range of the receiver hardware; the 7-term is overkill on cutoff depth for most situations.

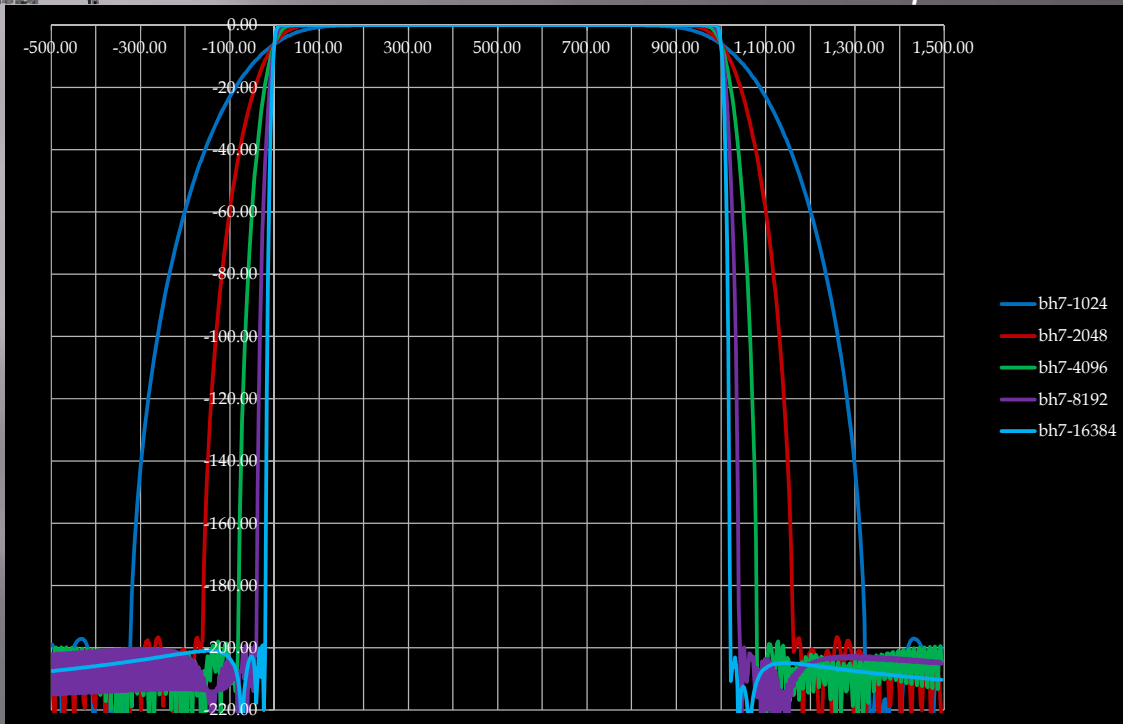
Note that the transition bands (regions between the pass-band and the cutoff bands) are the most important part to observe in these figures. These transition bands will maintain the same width independent of the width of the filter pass-band.





BANDPASS FILTER

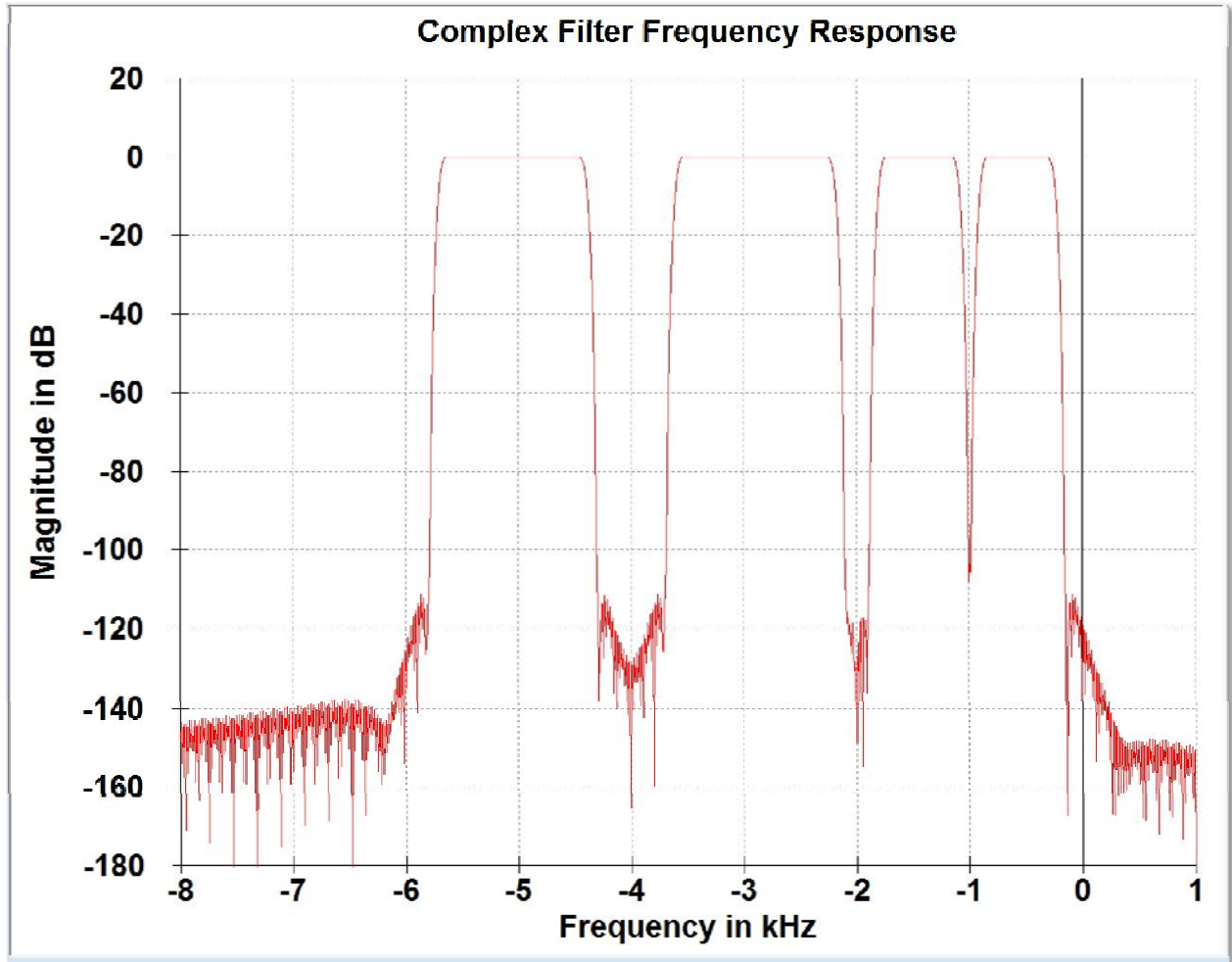
Sample-rate = 48 KHz



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The following figure displays an example of a Notched Bandpass Filter with three notches of three different widths. This example uses a filter size of 2048 at a `dsp_rate` of 48000. The notch at -1 KHz relative to the receiver tune frequency is 200 Hz in width, the notch at -2 KHz is 400 Hz in width, and the notch at -4 KHz is 800 Hz in width. Note that the width specifies the -6 dB points.



Bandpass Filter Settings

void RXANBPSetRun (int channel, int run)

channel: number of the receiver channel being accessed

run: 0 to turn the filter OFF; 1 to turn the filter ON.
[default = 1]

The lower and upper bandpass limits *can* be set with the **DEPRECATED** call:

void RXANBPSetFreqs (int channel, double f_low, double f_high) **DEPRECATED**

channel: number of the receiver channel being accessed

f_low: lower of the two frequencies (Hertz). May be negative or positive. This is a -6 dB point of the filter.
[default = -4150.0]

f_high: higher of the two frequencies (Hertz). May be negative or positive. This is a -6 dB point of the filter.

[default = -150.0]

The preferred way to set the lower and upper bandpass limits is to use a "Collective" call which not only sets this filter properly but also sets the bandpass limits for other blocks that need that same information. See the section of this document on "RXA Collectives" for this preferred call.

void RXANBPSetWindow (int channel, int wintype)

channel: number of the receiver channel being accessed

wintype: 0 for 4-term Blackman-Harris window; 1 for 7-term Blackman-Harris window.

[default = 0]

The length of the desired filter impulse response *can* be set with the following call. This is NOT the preferred method. Instead, a "Collective" call can be used. See the section on "RXA Collectives."

void RXANBPSetNC (int channel, int nc)

DEPRECATED

channel: number of the receiver channel being accessed

nc: length of the desired filter impulse response. This must be a power of two AND must be greater than or equal to the DSP Buffer Size in use.

[default = 2048]

The Filter-Type (Linear Phase or Low Latency) for the Notched Bandpass Filter can be set using the following call. This is NOT the preferred method. Instead, a "Collective" call can be used. See the section on "RXA Collectives."

void RXANBPSetMP (int channel, int mp)

DEPRECATED

channel: number of the receiver channel being accessed

mp: 0 for Linear Phase; 1 for Low Latency (Minimum Phase)

[default = 0]

Notch Filter Settings

void RXANBPSetNotchesRun (int channel, int run)

channel: number of the receiver channel being accessed

run: 0 to turn OFF all specified notches; 1 to turn ON all specified notches that are 'active'

[default = 0]

The width of each notch is specified and implies the frequencies at the edges of the notch where the response is 6dB down. The transition bands of notches are not perfectly vertical; the transition bands

have some non-zero width. Therefore, if essentially full-cutoff (>100dB) is to be attained at the center of a notch, the notch must be specified with some minimum width. The value of this minimum width can be found using the call:

void RXANBPGetMinNotchWidth (int channel, double* minwidth)

channel: number of the receiver channel being accessed

minwidth: pointer to the location into which the minimum notch width is to be stored. The value stored is in Hertz.

The width of all notches will be automatically increased, when necessary, to that required to achieve >100dB cutoff at the notches' centers if the "autoincr" flag is set.

void RXANBPSetAutoIncrease (int channel, int autoincr)

channel: number of the receiver channel being accessed

autoincr: 0 sets Auto-Increase to OFF; 1 sets Auto-Increase to ON
[default = 1]

Notches are specified at absolute RF frequencies. For example, if there is always an interfering carrier on 145.275 Mhz, a notch of a desired width may be specified at that frequency. The Notched Bandpass Filter then compares each notch frequency with the current RF frequency to which the radio is tuned to determine which notches are within the passband and where within the passband they are placed. To perform this comparison, the current radio Tune Frequency and any Shift Frequency offset to that must be specified. The following two calls are used for that purpose.

void RXANBPSetTuneFrequency (int channel, double tunefreq)

channel: number of the receiver channel being accessed

tunefreq: current RF tune frequency of the radio (Hertz)
[default = 0.0]

void RXANBPSetShiftFrequency (int channel, double shift)

channel: number of the receiver channel being accessed

shift: current RF shift frequency (Hertz)
[default = 0.0]

The Notched Bandpass Filter maintains a database of the desired notches. Several calls are provided to manage this database. Note that RXA currently supports a maximum of 1024 notches.

The following call can be made to determine the number of notches currently stored in the database.

void RXANBPGetNumNotches (int channel, int* nnotches)

channel: number of the receiver channel being accessed

nnotches: pointer to location where the number of notches currently in the database is to be stored

A new notch is added to the database using:

int RXANBPAddNotch (int channel, int notch, double fcenter, double fwidth, int active)

return value: 0 if the operation was successful; -1 if the specified value of 'notch' was \geq the total (new, including this addition) number of notches, i.e., it was out-of-range, OR, if adding another notch would exceed the maximum number of notches that are supported.

channel: number of the receiver channel being accessed

notch: identifier for the notch to be added. Notch identifiers begin at 0 and are positive. Notches in the database are required to be consecutive, i.e., with no gaps in used notch identifiers. Therefore, the value of 'notch' must be less than the total (new, including this addition) number of notches. If 'notch' is equal to new_number_of_notches minus one, this notch will be added at the end of the list. If 'notch' is less than new_number_of_notches minus one, this notch will be added with the 'notch' identifier specified and the notches with higher identifiers will be pushed-up in the list and their identifiers incremented accordingly.

fcenter: center frequency of the notch (Hertz)

fwidth: width of the notch (Hertz)

active: 0 implies that even though the notch will be stored in the database, it will not be used in filtering operations. 1 implies that it will be stored and will be used in filtering operations.

The current parameters of a specified notch can be obtained using:

int RXANBPGetNotch (int channel, int notch, double* fcenter, double* fwidth, int* active)

return value: 0 if the operation was successful; -1 if the value of 'notch' was \geq the current number of notches in the database.

channel: number of the receiver channel being accessed

notch: identifier for the notch to be read

fcenter: pointer to location to store center value of this notch (Hertz)

fwidth: pointer to location to store width of this notch (Hertz)

active: pointer to location to store the active flag for this notch

A specified notch can be deleted from the database using the following call. Note that any notches with higher identifiers will be pushed down in the list and their identifiers decremented accordingly.

int RXANBPDeleteNotch (int channel, int notch)

return value: 0 if the operation was successful; -1 if the value of 'notch' was \geq the current number of notches in the database.

channel: number of the receiver channel being accessed

notch: identifier for the notch to be deleted

One or more parameters of a specified notch can be changed using the following call. Note that ALL the parameters must be supplied even though perhaps only some of them are being changed in value.

int RXANBPEditNotch (int channel, int notch, double fcenter, double fwidth, int active)

return value: 0 if the operation was successful; -1 if the value of 'notch' was \geq the current number of notches in the database.

channel: number of the receiver channel being accessed

notch: identifier for the notch to be edited

fcenter: center frequency of the notch (Hertz)

fwidth: width of the notch (Hertz)

active: 0 implies that even though the notch will be stored in the database, it will not be used in filtering operations. 1 implies that it will be stored and will be used in filtering operations.

Post-filter Display Sender

The Post-filter Display Sender is used to transfer samples of the signal, taken after the Notched Bandpass Filter, to a WDSP Display Unit. This can provide a frequency-domain display showing the signal(s) within the passband and displaying the operation of the Notched Bandpass Filter and any other active preceding blocks in RXA.

Note that Display Units are instantiated and configured separately. See the appropriate section of this document for additional information on Display Units.

A single Display Unit may be used to process multiple data streams at different times, e.g., a full-bandwidth panadapter stream at some times as well as this post-filter data stream at others. Therefore, a 'flag' to turn the sender OFF/ON is needed.

Parameters are also needed to specify the target Display Unit, the target sub-span (in the event the display unit is set up for stitched displays), and which LO-position (in the event that spur-elimination mode is being used).

All this information is supplied in a single call:

void SetRXASpectrum (int channel, int flag, int disp, int ss, int LO)

channel: number of the receiver channel being accessed

flag: 0 to turn the sender OFF, 1 to turn the sender ON
[default = 0]

disp: identifier of the display unit. The overall configuration *might* be such that there is one display unit per DSP channel and the number is the same as the channel number. However, this is not necessarily the case.

ss: the sub-span which is to receive the data, normally this will be set to 0.

LO: the LO position to receive the data, normally this will be set to 0.

AM Squelch

The AM Squelch is provided for modes OTHER THAN FM. Special features of the WDSP implementation include raised-cosine OFF-ON-OFF transitions and a variable tail-length which depends upon the strength of the signal. Weaker signals get a longer tail-length to attempt to avoid the squelch turning the audio OFF/ON as the strength slightly varies.

void SetRXAAMSQRun (int channel, int run)

channel: number of the receiver channel being accessed

run: 0 for AM Squelch OFF; 1 for AM Squelch ON

void RXAAMSQThreshold (int channel, double threshold)

channel: number of the receiver channel being accessed

threshold: squelch threshold, i.e., if the passband signal strength is below this level the audio will be squelched (turned-off). 'threshold' is a negative dBm value.

[default = -40.0]

void SetRXAAMSQMaxTail (int channel, double tail)

channel: number of the receiver channel being accessed

tail: maximum tail length to be applied (seconds)

[default = 1.50]

AM/SAM Demodulator

This demodulator provides either AM demodulation or Synchronous-AM demodulation, dependent upon settings. Note that the **SetRXAMode(...)** collective makes the choice of AM or SAM, dependent upon the overall RXA Mode setting. (See the "RXA Collectives" section of this document.)

The following call exists to turn OFF/ON this demodulator; however, using this call is **NOT RECOMMENDED** as the demodulator is normally turned OFF/ON by using the **SetRXAMode(...)** collective.

void SetRXAAMDRun (int channel, int run) **DEPRECATED**

channel: number of the receiver channel being accessed

run: 0 to turn OFF the demodulator; 1 to turn ON the demodulator

For SAM ONLY, a choice of whether to receive both sidebands or only the lower or the upper sideband can be made. This is often useful in avoiding interference on one side or the other. Note that this is NOT a bandpass filtering operation; therefore, the received station does not have to be exactly centered on frequency for the sideband selection to function. This is particularly useful in AM round-tables where not all stations are on exactly the same frequency and interference exists on one side.

void SetRXAAMDSBMode (int channel, int sbmode)

channel: number of the receiver channel being accessed

sbmode: 0 = receive both sidebands; 1 = receive LSB only; 2 = receive USB only
[default = 0]

For both AM and SAM demodulation, there is an option to "level" the carrier in situations of carrier fading. This is accomplished by stripping out the varying carrier and replacing it with a stable carrier. This feature is deactivated/activated with the following call.

void SetRXAAMDFadeLevel (int channel, int levelfade)

channel: number of the receiver channel being accessed

levelfade: 0 = OFF; 1 = ON
[default = 1]

FM Demodulator

The FM Demodulator supports the standard FM audio bandwidth of 300 Hz to 3000 Hz and applies the standard de-emphasis of 6 dB / octave.

The FM demodulator is turned OFF/ON by using the **SetRXAMode(...)** collective. Hence, no call is provided here to accomplish that function.

The expected maximum deviation of the received signal is set as follows:

void SetRXAFMDeviation (int channel, double deviation)

channel: number of the receiver channel being accessed

deviation: deviation in Hertz

FM signals may have CTCSS tones used to trigger repeaters. Those may be passed through by the repeaters and it is sometimes desirable to notch those out of the audio output. A special notch filter is provided to perform this task. Two controls are provided for this filter:

void SetRXACTCSSRun (int channel, int run)

channel: number of the receiver channel being accessed

run: 0 = turn OFF the CTCSS notch filter; 1 = turn ON the CTCSS notch filter

void SetRXACTCSSFreq (int channel, double freq)

channel: number of the receiver channel being accessed

freq: frequency of the tone and notch (Hertz)

There are two filters (de-emphasis and audio) used in the FM demodulator and, for each of them, the length of the impulse response and the selection of Linear-Phase/Low-latency can be set. However, this is **NOT RECOMMENDED** and it is preferred that this be handled by calls to the RXA Collectives **RXASetNC(...)** and **RXASetMP(...)**. (See the "RXA Collectives" section of this document.)

void SetRXAFMNCde (int channel, int nc)

DEPRECATED

channel: number of the receiver channel being accessed

nc: length of the impulse response. This must be a power of two and must be greater than or equal to the **dsp_size** currently in use.

void SetRXAFMMPde (int channel, int mp)

DEPRECATED

channel: number of the receiver channel being accessed

mp: 0 = Linear Phase; 1 = Low Latency

`void SetRXAFMNCaud (int channel, int nc)`

DEPRECATED

`channel`: number of the receiver channel being accessed

`nc`: length of the impulse response. This must be a power of two and must be greater than or equal to the `dsp_size` currently in use.

`void SetRXAFMMPaud (int channel, int mp)`

DEPRECATED

`channel`: number of the receiver channel being accessed

`mp`: 0 = Linear Phase; 1 = Low Latency

FM Squelch

FM Squelch is turned OFF/ON using the following call:

void SetRXAFMSQRun (int channel, int run)

channel: number of the receiver channel being accessed

run: 0 = turn OFF the FM Squelch; 1 = turn ON the FM Squelch
[default = 0]

void SetRXAFMSQThreshold (int channel, double threshold)

channel: number of the receiver channel being accessed

threshold: squelch threshold. This is a positive value which normally ranges from 1.0 to 0.01. It can be generated with a slider from which the output value range is 0.0 to 100.0 and then applying the equation: $\text{threshold} = \text{pow}(10.0, -2.0 * \text{slider_value} / 100.0)$;

A filter is used in the FM squelch and the length of the impulse response and the selection of Linear-Phase/Low-latency can be set. However, this is **NOT RECOMMENDED** and it is preferred that this be handled by calls to the RXA Collectives **RXASetNC (...)** and **RXASetMP (...)**. (See the "RXA Collectives" section of this document.) The calls to individually set these values are:

void SetRXAFMSQNC (int channel, int nc) **DEPRECATED**

channel: number of the receiver channel being accessed

nc: length of the impulse response. This must be a power of two.



void SetRXAFMSQMP (int channel, int mp) **DEPRECATED**

channel: number of the receiver channel being accessed

mp: 0 = Linear Phase; 1 = Low Latency

Spectral Noise Blanker

The Spectral Noise Blanker uses Linear Predictive Coding (LPC) to detect impulses or other severe abnormalities in signals and to replace the corrupted samples with an estimate of the original signal.



SPECTRAL NOISE BLANKER

“SNB”

NR	ANF
NB	SNB
MUT	BIN
MNF	

- Linear Predictive Coding (LPC) for detection and correction
 - $\hat{y}(m) = \sum a_k y(m - k)$
 - a_k contain information about the Spectral Formants of the signal
- Detection:
 - Compare: $\text{Error}(m) = y(m) - \hat{y}(m)$
 - Normally we find a sequence of corrupt samples
- Correction:
 - Using coefficients a_k , solve a system of linear equations for the values of the samples in the corrupt sequence

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The Spectral Noise Blanker is turned OFF/ON by calls to:

void SetRXASNBARun (int channel, int run)

channel: number of the receiver channel being accessed

run: 0 for OFF; 1 for ON
[default = 0]

The output bandwidth of the Spectral Noise Blanker can be set to be consistent with the overall bandpass lower and upper limits using the following **DEPRECATED** call. This is NOT recommended. Instead, use the RXA Collective **RXASetPassband (...)** which sets all blocks that have need of passband frequency information. (See the "RXA Collectives" section of this document.)

void SetRXASNBABandwidth (int channel, double flow, double fhigh) DEPRECATED

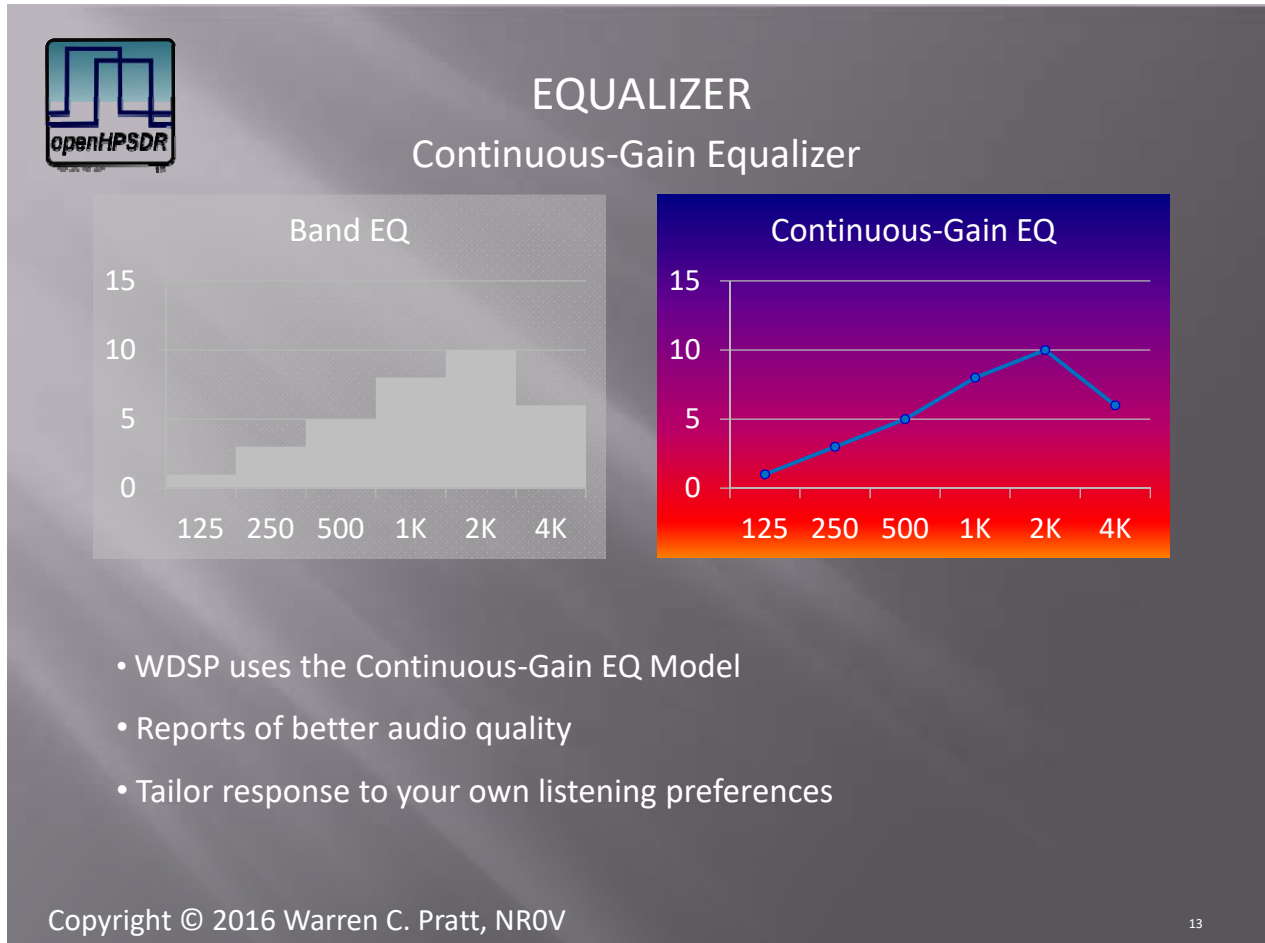
channel: number of the receiver channel being accessed

flow: lower bandpass limit (Hertz)

fhigh: upper bandpass limit (Hertz)

Equalizer

The equalizer uses a continuous frequency response algorithm meaning that the gain is specified at any number of frequencies and the response is interpolated between the specified points. This is in contrast to a frequency "band" approach.



The equalizer is turned OFF/ON using calls to:

void SetRXAEQRun (int channel, int run)

channel: number of the receiver channel being accessed

run: 0 for OFF; 1 for ON
[default = 0]

The length of the EQ filter impulse response can be set with the following call. However, this is **NOT RECOMMENDED**. The preferred method is to use the RXA Collective **RXASetNC(...)**. (See the "RXA Collectives" section of this document.)

void SetRXAEQNC (int channel, int nc)

DEPRECATED

channel: number of the receiver channel being accessed

nc: length of the EQ filter impulse response. 'nc' must be a power-of-two and must be greater than or equal to the DSP Buffer Size in use.

[default = 2048]

The Filter Type (Linear-Phase / Low-Latency) for the EQ filter can be set with the following call. However, this is **NOT RECOMMENDED**. The preferred method is to use the RXA Collective **RXASetMP(...)**. (See the "RXA Collectives" section of this document.)

void SetRXAEQMP (int channel, int mp)

DEPRECATED

channel: number of the receiver channel being accessed

mp: 0 for Linear-Phase; 1 for Low-Latency (Minimum Phase)

[default = 0]

The window-type used in the generation of the EQ filter can be selected. This setting should normally just be left at the default value.

void SetRXAEQWinType (int channel, int wintype)

channel: number of the receiver channel being accessed

wintype: 0 = 4-term Blackman-Harris; 1 = 7-term Blackman-Harris

[default = 0]

The cutoff-mode used in the generation of the EQ filter can be selected. This setting should normally just be left at the default value.

void SetRXAEQCtfmode (int channel, int mode)

channel: number of the receiver channel being accessed

mode: 0 = 4th-power roll-off on each side of the specified passband; 1 = no roll-off outside the specified passband

[default = 0]

The following call is the primary and preferred method of setting the equalizer response.

void SetRXAEQProfile (int channel, int nfreqs, double* F, double* G)

channel: number of the receiver channel being accessed

nfreqs: number of frequency/gain pairs to be specified

F: pointer to an array of frequencies (Hertz). NOTE: The 0th element of this vector is NOT USED. So, for example, if **nfreqs** is 5, F[0] is not used and the five frequencies will be stored in F[1] ... F[5]. The F[] array has (**nfreqs** + 1) values.

Note that acceptable values are between 0.0 Hz and **dsp_rate**/2.0 Hz. It is acceptable to specify the same frequency multiple times; however, if different gains are specified for the same frequency, it is indeterminate as to which of the gains will be applied at that frequency. Frequency/Gain pairs do not necessarily have to be specified in order of increasing frequency. If they are not, they will be sorted into the appropriate order prior to application.

G: pointer to a corresponding array of gain values (dB). The 0th element is used to specify a "preamp gain" value to be applied to all frequencies. The G[] array has (**nfreqs** + 1) values.

For convenience and consistency with legacy consoles, two "short-cut" calls with pre-specified frequencies are provided.

void SetRXAGrphEQ (int channel, int* rxeq)

DEPRECATED

channel: number of the receiver channel being accessed

rxeq: pointer to an array containing gain values (dB) corresponding to an implicit "F vector" of F[] = {0.0, 150.0, 400.0, 1500.0, 6000.0}. The value in G[0] is the "preamp gain" to be applied to all frequencies. G[1] through G[4] contain gains corresponding to 150.0 Hz through 6000.0 Hz, respectively.

void SetRXAGrphEQ10 (int channel, int* rxeq)

DEPRECATED

channel: number of the receiver channel being accessed

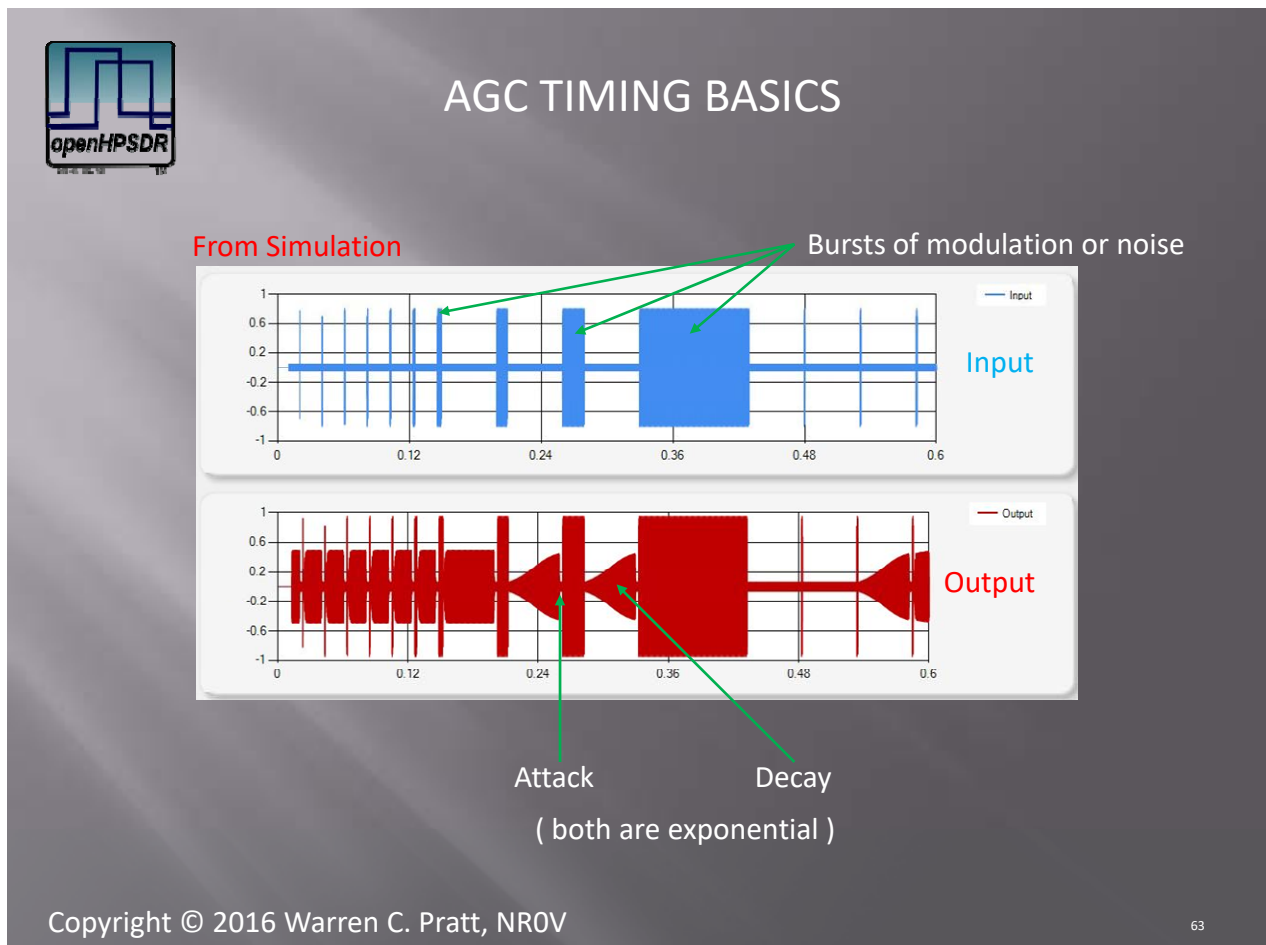
rxeq: pointer to an array containing gain values (dB) corresponding to an implicit "F vector" of F[] = {0.0, 32.0, 63.0, 125.0, 250.0, 500.0, 1000.0, 2000.0, 4000.0, 8000.0, 16000.0}. The value in G[0] is the "preamp gain" to be applied to all frequencies. G[1] through G[10] contain gains corresponding to 32.0 Hz through 16000.0 Hz, respectively.

AGC

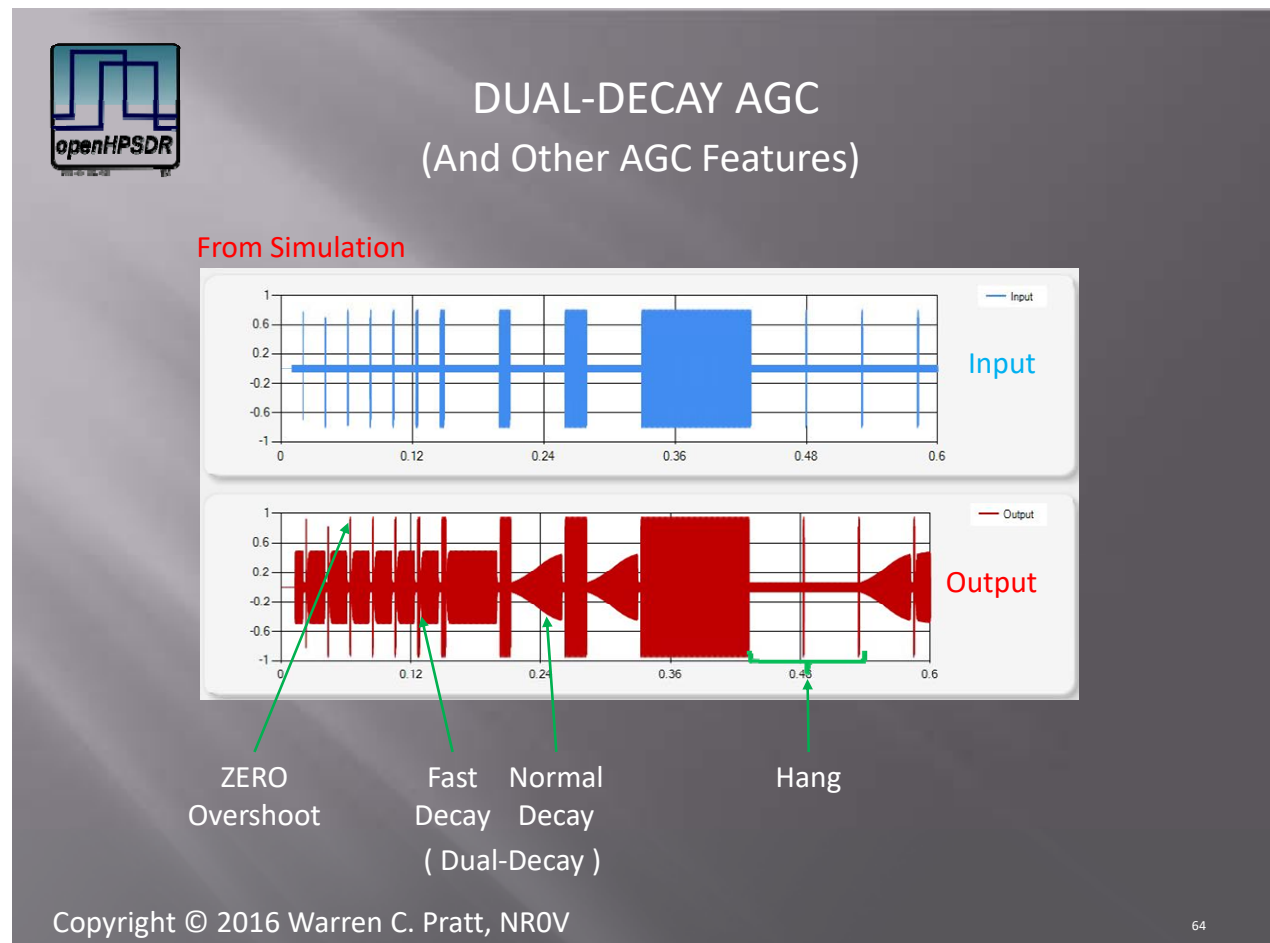
WDSP provides a full-featured AGC including:

- Exponential attack / decay
- Hang for quieting when listening to relatively strong stations
- Dual-decay for suppression of certain impulses not removable using wideband noise blankers
- Controls for on-panadapter adjustment of the AGC Threshold and Hang Level
- Zero Overshoot for avoidance of un-natural sound and AGC "pumping"
- Slope to allow stronger signals to yield higher audio output than weaker signals

The following figure illustrates the exponential attack and decay. The attack is typically set to be much faster than the normal decay. Note that the blue upper plot is of the AGC input signal and the lower red plot is of the AGC output signal.

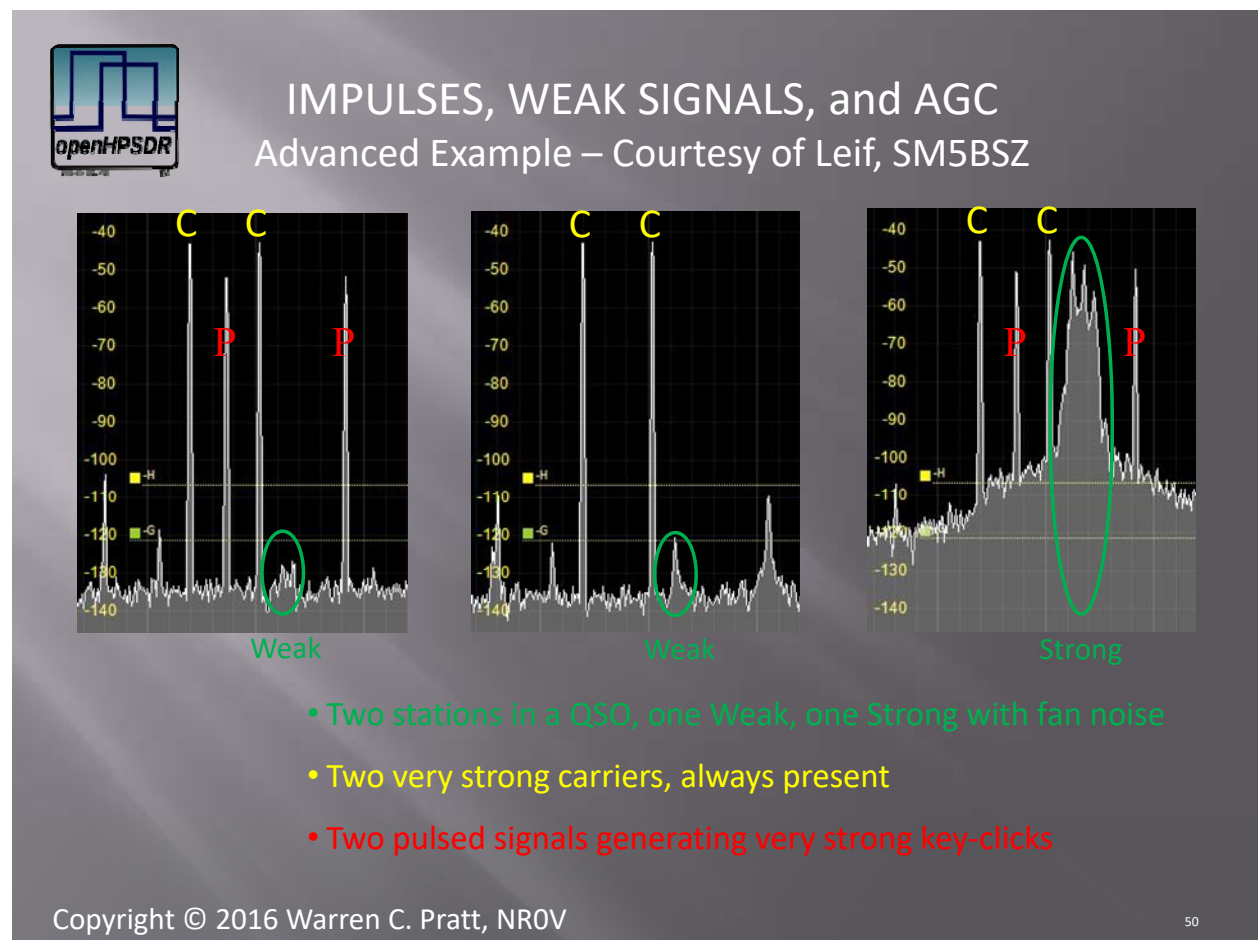


The following figure illustrates additional features of Zero Overshoot, Dual-Decay, and Hang. The Dual-Decay is used in the suppression of certain impulses that cannot be removed with wideband noise blankers. If the AGC judges a short burst to be an impulse, a fast-decay is invoked to avoid the AGC from blocking the reception of weak signals for an extended time following the impulse. Otherwise, the normal decay is used. Hang maintains the gain at a constant fixed level for a specified amount of time after a strong burst of reception.



The following figure demonstrates a situation in which the Dual-Decay feature provides a major improvement in reception. The IQ.wav file for this example is available from Leif Asbrink, SM5BSZ, and is posted on his website.

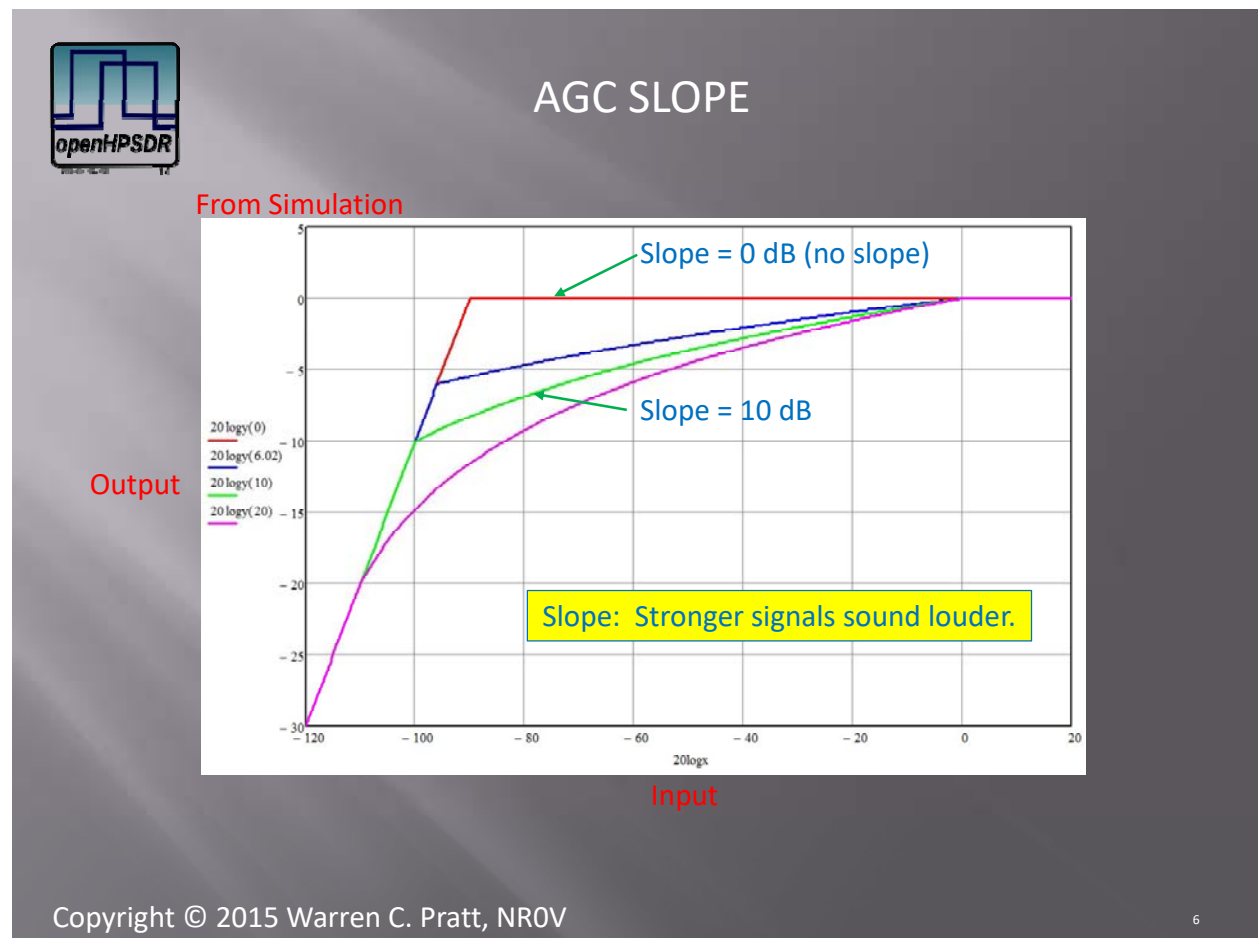
Shown are snapshots of the frequency spectrum taken at three different times. The two strong carriers render wideband noise blankers useless. The key clicks from the two pulsed carriers are the impulses we want to suppress. Strong fan noise on the strong signal implies that we need a relatively long decay as the normal decay for the AGC such that the fan noise is suppressed between words and phrases of the strong station. However, a long AGC time-constant would cause the AGC to block the weak station for an extended time after each impulse. Fortunately, the fast decay is invoked after the impulses and the weak station is not blocked.



The following figure illustrates the AGC Gain curve with four different values of slope: 0 dB (no slope), 6 dB, 10 dB, and 20 dB. The plot shows AGC Output level versus AGC Input level, both in dBm. The AGC maximum gain was set to 90 dB.

With no slope, all input levels above -90 dBm have the same output level, the AGC adjusts its gain to produce the same output. Since the maximum gain is set to 90 dB, the output drops (-10 dBm out for -10 dBm in) for input values lower than -90 dBm.

At a slope of 10dB, the output level gradually increases from -10 dBm to 0 dBm for input levels of -100 dBm to 0 dBm.



The following call is used to both (1) turn AGC OFF/ON, and (2) in the event it's ON, set some key parameters:

```
void SetRXAAGCMode (int channel, int mode)
```

channel: number of the receiver channel being accessed

mode: 0: AGC_OFF. A fixed gain equal to the AGC fixed gain setting will be applied to the signal.
1: AGC_LONG. Hangtime = 2000 ms. Decay_time_constant = 2000 ms.
2: AGC_SLOW. Hangtime = 1000 ms. Decay_time_constant = 500 ms.
3: AGC_MED. Hang is turned OFF. Decay_time_constant = 250 ms.
4: AGC_FAST. Hang is turned OFF. Decay_time_constant = 50 ms.
5: AGC_CUSTOM. AGC is ON; however, no parameters are set by this call. All parameters are set with other calls as needed.
[default = 3]

The following three calls can be used for setting various AGC time-constants or absolute times.

void SetRXAAGCAAttack (int channel, int attack)

channel: number of the receiver channel being accessed

attack: attack time constant (ms). It is recommended to leave this at the default value. Note that "attacks" are along exponential curves and this value is a time-constant as opposed to an absolute amount of time.
[default = 1 ms]

void SetRXAAGCDecay (int channel, int decay)

channel: number of the receiver channel being accessed

decay: decay time constant (ms). Note that "decays" are along exponential curves and this value is a time-constant as opposed to an absolute amount of time.
[default = 250 ms]

void SetRXAAGCHang (int channel, int hang)

channel: number of the receiver channel being accessed

hang: hang-time (ms). Note that this is an absolute amount of time as opposed to a time-constant.
[default = 250 ms]

Support is provided for setting the AGC Hang Level either on the bandscope or by use of a simple slider control. When one is changed, the other needs to be adjusted accordingly. Therefore, there are both 'get' and 'set' commands for each type of control. For example, when a 'set' is done on the slider, there is a 'get' that can be used to return the new position required on the bandscope.

void GetRXAAGCHangLevel (int channel, double* hanglevel)

channel: number of the receiver channel being accessed

hanglevel: pointer to location where the bandscope level (dBm) is to be stored.

void SetRXAAGCHangLevel (int channel, double hanglevel)

channel: number of the receiver channel being accessed

hanglevel: bandscope level being set as the hang-level (dBm)

void GetRXAAGCHangThreshold (int channel, int* hangthreshold)

channel: number of the receiver channel being accessed

hangthreshold: pointer to location where the slider setting is to be stored (setting range is 0 to 100)

void SetRXAAGCHangThreshold (int channel, int hangthreshold)

channel: number of the receiver channel being accessed

hangthreshold: slider setting being set as the hang-level (setting range is 0 to 100)

Support is provided for setting the AGC Maximum-Gain / Threshold both via a slider and by moving a line on the bandscope. When one is changed, the other needs to be adjusted accordingly. Therefore, there are both 'get' and 'set' commands for each type of control. For example, when a 'set' is done on the slider, there is a 'get' that can be used to return the new position required on the bandscope.

On the bandscope, the noise floor moves up and down depending upon the FFT_size and sample_rate of data used to compute the bandscope. Also, it is useful to reference the bandscope line to the noise floor, typically setting the line a few dB above the noise floor. Therefore, the display FFT_size and display sample_rate parameters must be supplied to achieve the correct bandscope results.

void GetRXAAGCThresh (int channel, double* thresh, double size, double rate)

channel: number of the receiver channel being accessed

thresh: pointer to location to store the bandscope level (dBm) for AGC Threshold

size: FFT_size being used to compute the bandscope display

rate: sample-rate of data being supplied to compute the bandscope display

void SetRXAAGCThresh (int channel, double thresh, double size, double rate)

channel: number of the receiver channel being accessed

thresh: the bandscope level (dBm) for AGC Threshold

size: FFT_size being used to compute the bandscope display

rate: sample-rate of data being supplied to compute the bandscope display

void GetRXAAGCTop (int channel, double* max_agc)

channel: number of the receiver channel being accessed

max_agc: pointer to location to store the maximum AGC Gain, i.e., the AGC Threshold (range is -20 dB to +120dB)

void SetRXAAGCTop (int channel, double max_agc)

channel: number of the receiver channel being accessed

max_agc: the maximum AGC Gain, i.e., the AGC Threshold (range is -20 dB to +120dB)
[default = +80 dB]

void SetRXAAGCSlope (int channel, int slope)

channel: number of the receiver channel being accessed

slope: Ten times the desired AGC slope value (dB). The typical range for slope would be 0 to 200, corresponding to 0dB to 20dB.
[default = 35, corresponding to 3.5dB]

void SetRXAAGCFixed (int channel, double fixed_agc)

channel: number of the receiver channel being accessed

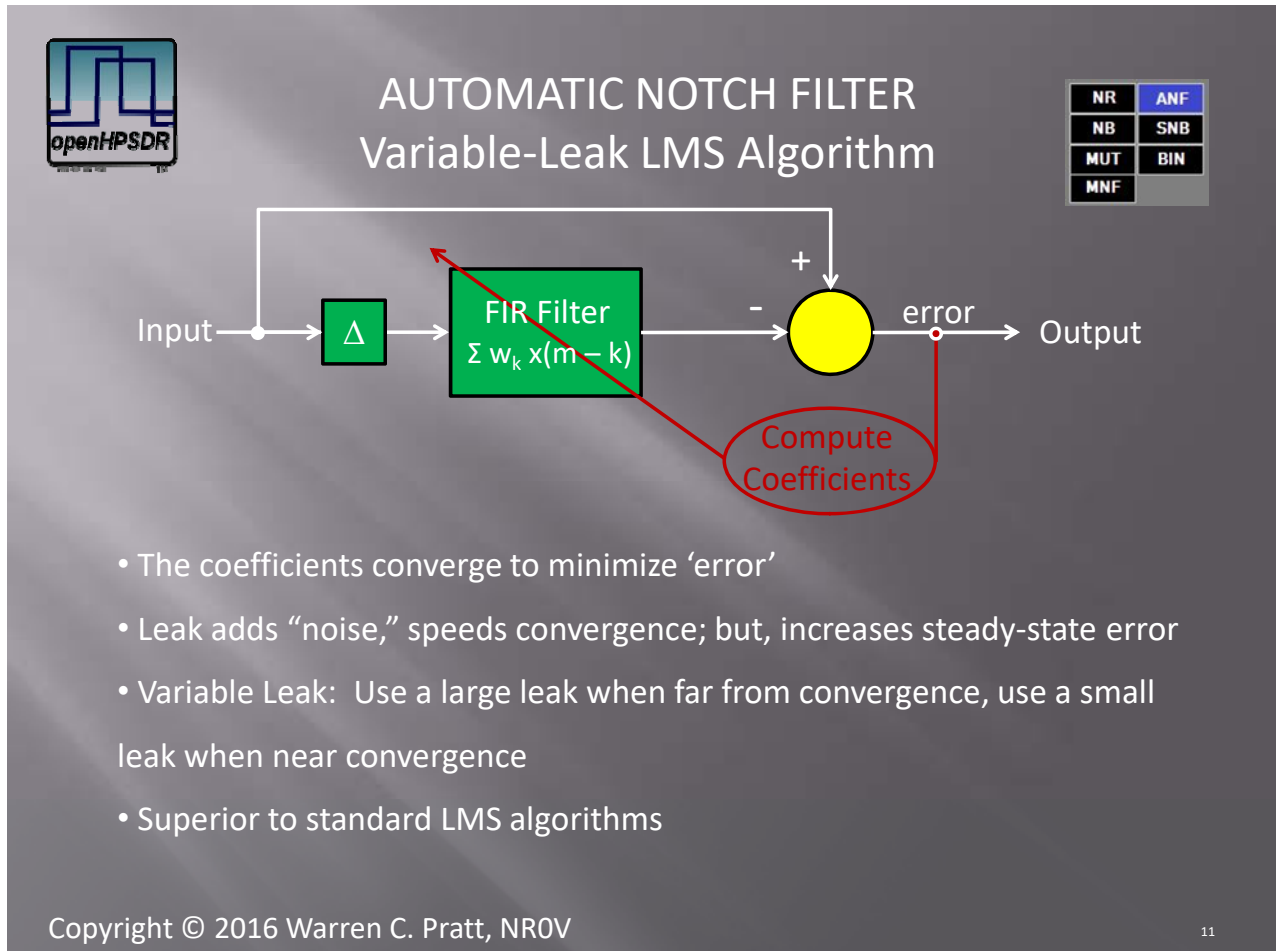
fixed_agc: fixed gain to use when the AGC is OFF, i.e., the 'mode' is set to 0. (dB)
[default = +60 dB]

Automatic Notch Filter

The WDSP Automatic Notch Filter is used primarily to "notch-out" carriers and similar signals.

The Least-Mean-Squares (LMS) algorithm used here dynamically computes the coefficients of an FIR filter such that the filter passes the carrier and rejects other signals. The carrier is then subtracted from the original signal to produce an output free of the carrier.

The filter coefficients are computed in such a way as to maximize the autocorrelation of the carrier. The delay, Δ , assists in the comparison of two different time periods of the signal.



The Automatic Notch Filter is turned OFF/ON using the call:

```
void SetRXAANFRun (int channel, int run)
```

channel: number of the receiver channel being accessed

run: 0 = OFF; 1 = ON
[default = 0]

The number of FIR filter taps is set with the call:

void SetRXAANFTaps (int channel, int taps)

channel: number of the receiver channel being accessed

taps: number of filter taps (coefficients) to be used
[default = 64]

The delay is set using the call:

void SetRXAANFDelay (int channel, int delay)

channel: number of the receiver channel being accessed

delay: delay, specified in number of samples
[default = 16]

void SetRXAANFGain (int channel, double gain)

channel: number of the receiver channel being accessed

gain: gain value. Typical range is 1.0e-06 to 1.0e-03.
[default = 1.0e-04]

Note that increasing gain allows the algorithm to more effectively lock-onto and notch carriers. HOWEVER, at higher gains the algorithm will begin to generate distortion on speech. I.e., there is a tradeoff between notching effectiveness and speech distortion.

void SetRXAANFLeakage (int channel, double leakage)

channel: number of the receiver channel being accessed

leakage: leak value. Typical range is 0.001 to 1.000.
[default = 0.100]

The following call can be used to set **taps**, **delay**, **gain**, and **leakage** using only a single call:

void SetRXAANFVals (int channel, int taps, int delay, double gain, double leakage)

channel: number of the receiver channel being accessed

taps: number of filter taps (coefficients) to be used
[default = 64]

delay: delay, specified in number of samples
[default = 16]

gain: gain value. Typical range is 1.0e-06 to 1.0e-03.
[default = 1.0e-04]

leakage: leak value. Typical range is 0.001 to 1.000.
[default = 0.100]

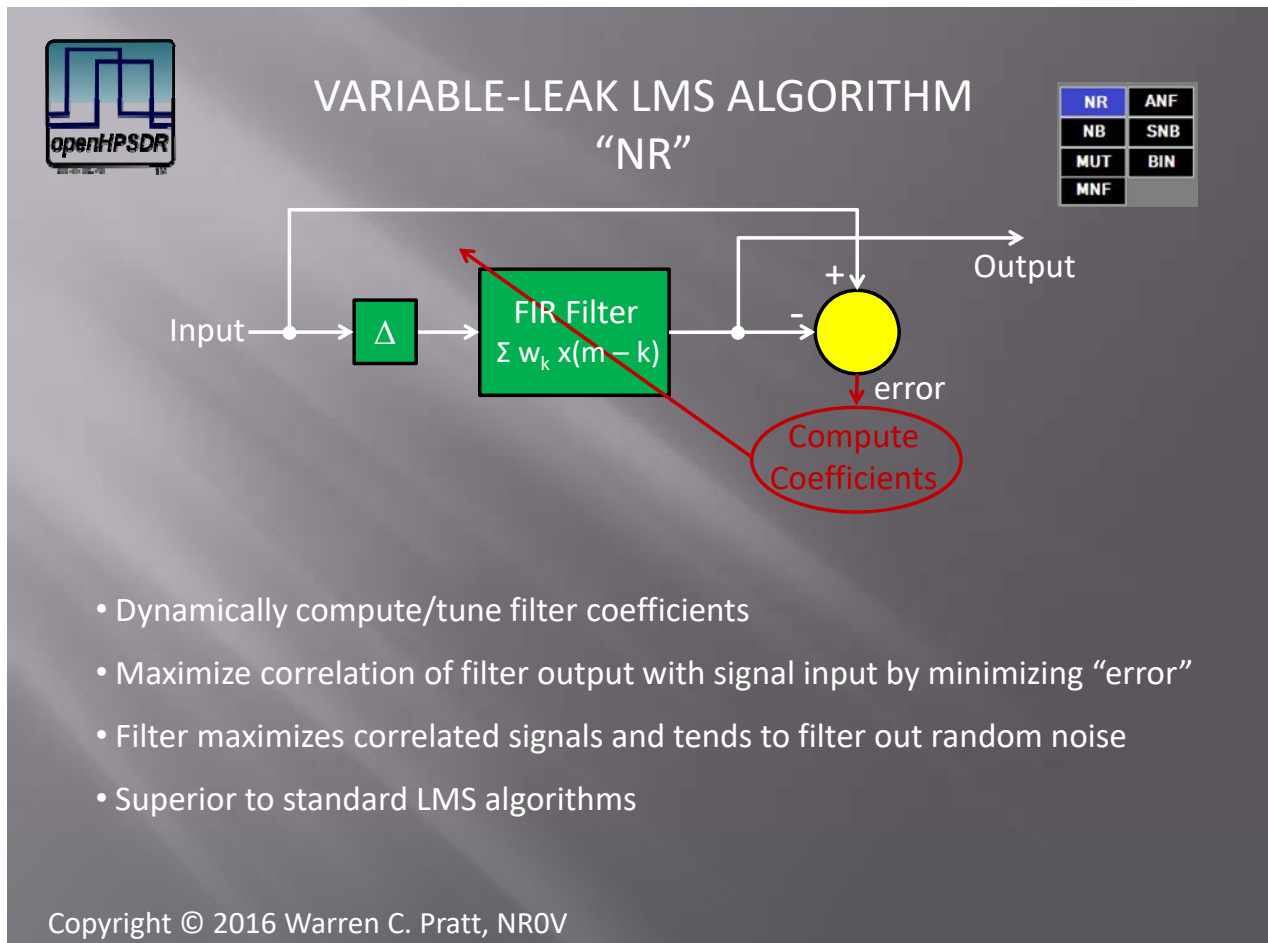
void SetRXAANFPosition (int channel, int position)

channel: number of the receiver channel being accessed

position: 0 = execute ANF before AGC; 1 = execute ANF after AGC.

LMS Noise Reduction

Setting your expectations: LMS Noise Reduction algorithms work best when there is already a good signal- to-noise ratio; they can be very effective in providing a quiet background under these circumstances. This is really their purpose. It is unlikely that you will be able to pull an otherwise unreadable signal out of the noise with this type algorithm.



The LMS Noise Reduction is turned OFF/ON using the call:

void SetRXAANRRun (int channel, int run)

channel: number of the receiver channel being accessed

run: 0 = OFF; 1 = ON
[default = 0]

The number of FIR filter taps is set with the call:

void SetRXAANRTaps (int channel, int taps)

channel: number of the receiver channel being accessed

taps: number of filter taps (coefficients) to be used
[default = 64]

The delay is set using the call:

void SetRXAANRDelay (int channel, int delay)

channel: number of the receiver channel being accessed

delay: delay, specified in number of samples
[default = 16]

void SetRXAANRGain (int channel, double gain)

channel: number of the receiver channel being accessed

gain: gain value. Typical range is 1.0e-06 to 1.0e-03.
[default = 1.0e-04]

void SetRXAANRLeakage (int channel, double leakage)

channel: number of the receiver channel being accessed

leakage: leak value. Typical range is 0.001 to 1.000.
[default = 0.100]

The following call can be used to set **taps**, **delay**, **gain**, and **leakage** using only a single call:

void SetRXAANRVals (int channel, int taps, int delay, double gain, double leakage)

channel: number of the receiver channel being accessed

taps: number of filter taps (coefficients) to be used
[default = 64]

delay: delay, specified in number of samples
[default = 16]

gain: gain value. Typical range is 1.0e-06 to 1.0e-03.
[default = 1.0e-04]

leakage: leak value. Typical range is 0.001 to 1.000.
[default = 0.100]

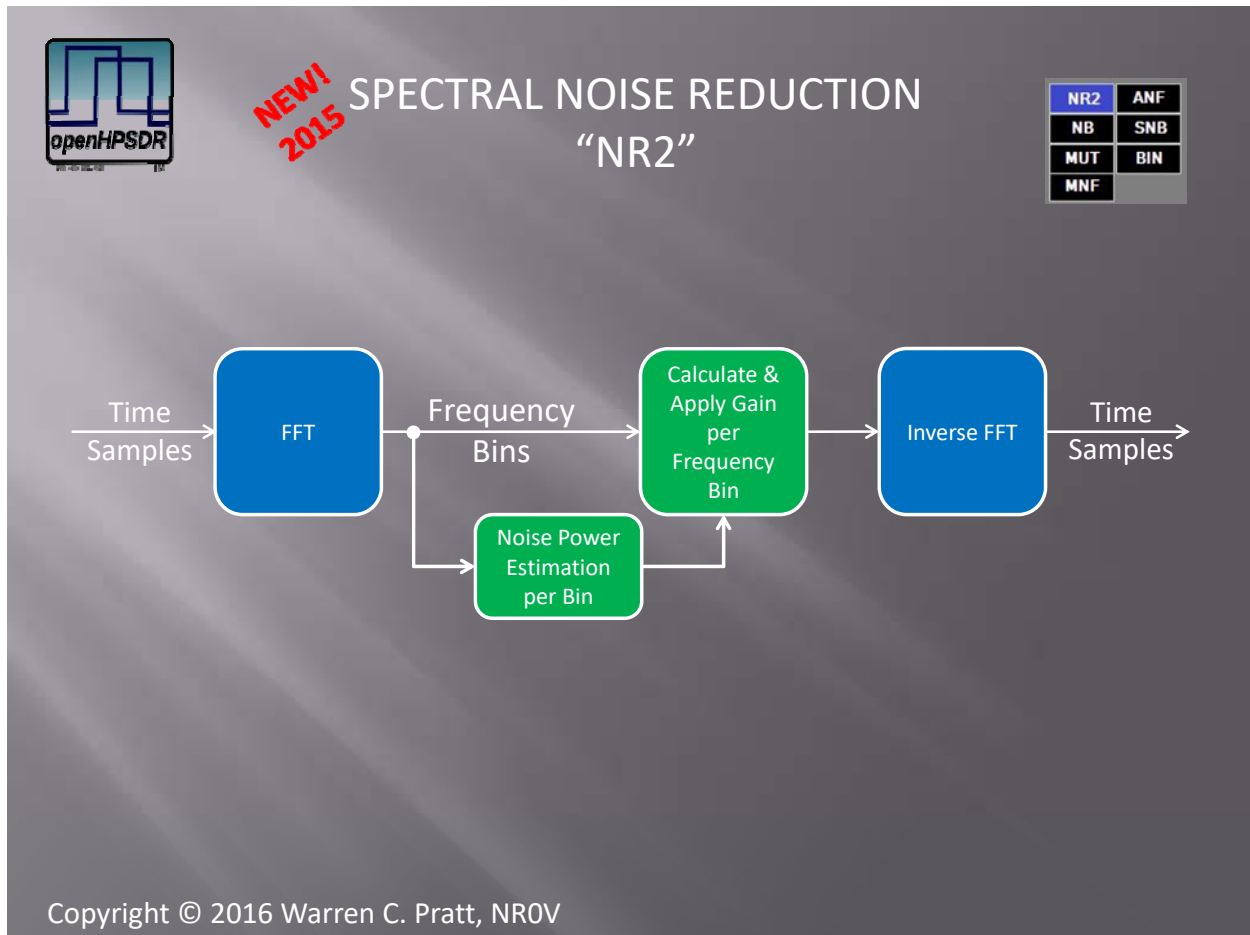
void SetRXAANFPosition (int channel, int position)

channel: number of the receiver channel being accessed

position: 0 = execute Noise Reduction before AGC; 1 = execute Noise Reduction after AGC.

Spectral Noise Reduction

The seminal work for the class of algorithm implemented here for the Spectral Noise Reduction block was published in 1984¹. At a basic level, an FFT is done to convert to the frequency domain, a gain is applied to each of the frequency bins based upon estimates of the amplitudes of speech and noise within the bins, and an inverse FFT is done to get back to time-domain samples. Statistical models of speech and noise amplitudes are used as "a priori" knowledge to enhance the accuracy of the estimates.



Over the years, various alternatives and improvements to the speech estimation algorithms and corresponding gain calculations have been developed. Three variants are included in this code and are selectable. Also, noise estimation is an important part of the process and two different noise estimation algorithms have been included.

The Spectral Noise Reduction is turned OFF/ON using the call:

```
void SetRXAEMNRRRun (int channel, int run)
```

channel: number of the receiver channel being accessed

¹ Yariv Ephraim and David Malah, "Speech Enhancement Using a Minimum Mean-Square Error Short-Time Spectral Amplitude Estimator," 1984.

run: 0 = OFF; 1 = ON
[default = 0]

The gain-per-bin calculation method is selected using the following call. All three choices will produce somewhat similar results with the default Gamma speech distribution being somewhat preferred.

void SetRXAEMNRgainMethod (int channel, int method)

channel: number of the receiver channel being accessed

method: 0 = Gaussian speech distribution, linear amplitude scale; 1 = Gaussian speech distribution, log amplitude scale; 2 = Gamma speech distribution
[default = 2]

The noise-power-estimation (per bin) method is selected using the following call. Both choices will produce somewhat similar results. For general operation, the default is preferred. In situation involving sudden changes in signal/noise amplitude, e.g., with "static crashes" caused by lightning, the MMSE method may be preferred due to its ability to more rapidly adjust to the changes.

void SetRXAEMNRnpeMethod (int channel, int method)

channel: number of the receiver channel being accessed

method: 0 = Optimal Smoothing Minimum Statistics (OSMS); 1 = Minimum Mean-Square Error (MMSE)
[default = 0]

An artifact-elimination post-filter is turned OFF/ON using the following call. It is recommended to leave it always ON, as per the default.

void SetRXAEMNRaeRun (int channel, int run)

channel: number of the receiver channel being accessed

run: 0 = OFF; 1 = ON
[default = 1]

The position in the processing pipeline where this algorithm is applied is selected by:

void SetRXAEMNRPosition (int channel, int position)

channel: number of the receiver channel being accessed

position: 0 = execute before AGC; 1 = execute after AGC
[default = 0]

ADDITIONAL REQUIREMENT: At initialization, the Spectral Noise Reduction algorithm expects to find the file "calculus" located in the same directory as the WDSP executable. "calculus" is a large data file containing information required for the best (also the default) gain-computation algorithm choice.

Bandpass Filter

For certain modes and features, a second bandpass filter is needed. It is automatically activated when required. Response curves are the same as the Notched Bandpass Filter discussed above.

Its lower and upper frequencies can be set using the following **DEPRECATED** call. However, the preferred method is by calling the RXA Collective **RXASetPassband(...)**.

void SetRXABandpassFreqs (int channel, double f_low, double f_high) **DEPRECATED**

channel: number of the receiver channel being accessed

f_low: lower of the two frequencies (Hertz). May be negative or positive.
[default = -4150.0]

f_high: higher of the two frequencies (Hertz). May be negative or positive.
[default = -150.0]

The window function used in designing the filter can be selected with the following call. See the discussion (preceding) on the Notched Bandpass Filter for more information on this selection.

void SetRXABandpassWindow (int channel, int wintype)

channel: number of the receiver channel being accessed

wintype: 0 for 4-term Blackman-Harris window; 1 for 7-term Blackman-Harris window.
[default = 1]

The length of the desired filter impulse response *can* be set with the following call. This is NOT the preferred method. Instead, a "Collective" call can be used. (See the section on "RXA Collectives.") See the discussion (preceding) on the Notched Bandpass Filter for more information on this selection.

void SetRXABandpassNC (int channel, int nc) **DEPRECATED**

channel: number of the receiver channel being accessed

nc: length of the desired filter impulse response. This must be a power of two AND must be greater than or equal to the DSP Buffer Size in use.
[default = 2048]

The Filter-Type (Linear Phase or Low Latency) for the Bandpass Filter can be set using the following call. This is NOT the preferred method. Instead, a "Collective" call can be used. See the section on "RXA Collectives."

void SetRXABandpassMP (int channel, int mp) **DEPRECATED**

channel: number of the receiver channel being accessed

mp: 0 for Linear Phase; 1 for Low Latency (Minimum Phase)
[default = 0]

Scope/Phase Display Sender

The console can call for buffers of processed samples to use for things like an oscilloscope or phase display. Two calls are provided for this purpose. One returns only the 'I' samples while the other returns interleaved I/Q samples.

void RXAGetaSipF (int channel, float* out, int size)

channel: number of the receiver channel being accessed

out: pointer to buffer into which the I-only samples (float format) are to be placed

size: number of I-only samples to retrieve. 'size' must be <= 4096 per an internal setting.

void RXAGetaSipF1 (int channel, float* out, int size)

channel: number of the receiver channel being accessed

out: pointer to buffer into which the interleaved I/Q samples (float format) are to be placed

size: number of I/Q samples to retrieve. 'size' must be <= 4096 per an internal setting.

AM Carrier Block

The AM carrier, a DC value, is left in the signal through the AGC. This is desirable such that the typical "AGC-quieting" of an AM receiver will be preserved. However, there are situations where it is desirable to remove this carrier before the WDSP audio output. One example would be when an AM signal is being recorded with the intention of playing it back through the transmitter. In that case, if the carrier were left in the signal, the carrier would be recorded also and the carrier level would be too high on playback through the transmitter since the AM transmitter would add carrier again.

This is a simple filter which removes this carrier, i.e., DC component.

The AM Carrier Block is turned OFF/ON using the call:

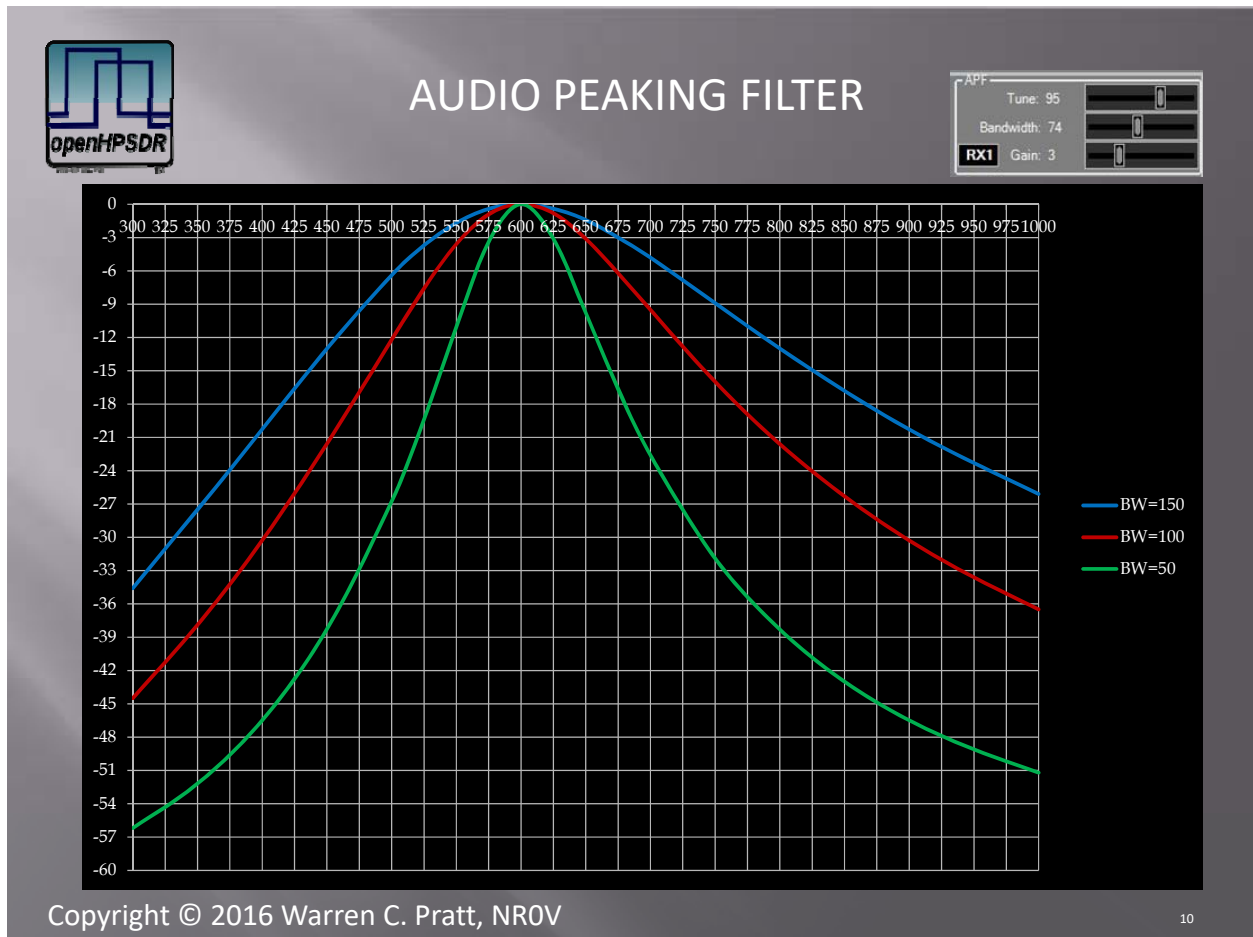
void SetRXACBLRun (int channel, int run)

channel: number of the receiver channel being accessed

run: 0 = OFF; 1 = ON
[default = 0]

CW Peaking Filter

The CW Peaking Filter is an audio IIR filter intended to peak a single frequency, the frequency of a desired CW signal. Gain, bandwidth, and tune frequency are all selectable. Examples (from measurements) of the frequency response are shown in the figure below.



Note that it is NOT desirable for this filter to be extremely sharp as this makes it difficult to find signals in the tuning process. Although the filter could be used with bandwidth reduced to, for example, 10 Hz, most operators will prefer something in the 50 Hz to 100 Hz bandwidth range.

The CW Peaking Filter is turned OFF/ON with the call:

```
void SetRXASPCWRun (int channel, int run)
```

channel: number of the receiver channel being accessed

run: 0 = OFF; 1 = ON
[default = 0]

Center frequency, bandwidth, and gain are set using the following three calls, respectively.

void SetRXASPCWFreq (int channel, double freq)

channel: number of the receiver channel being accessed

freq: center frequency in Hertz
[default = 600.0]

void SetRXASPCWBandwidth (int channel, double bw)

channel: number of the receiver channel being accessed

bw: approximate -6dB bandwidth in Hertz
[default = 100.0]

void SetRXASPCWGain (int channel, double gain)

channel: number of the receiver channel being accessed

gain: this is an absolute gain factor (multiplier) -- NOT dB.
[default = 2.0]

Dolly Filter

The Dolly Filter is a dual-lobe filter intended for use in RTTY reception. It comprises a pair of CW peaking filters whose inputs are the same and whose outputs are summed. Since it is set up for RTTY operation, only two peaks are desired; however, the underlying filter structure supports an arbitrary number of peaks, each with its own Enable, Center_Frequency, Bandwidth, and Gain.

void SetRXAmpeakRun (int channel, int run)

channel: number of the receiver channel being accessed

run: 0 = OFF; 1 = ON

[default = 0]

void SetRXAmpeakNpeaks (int channel, int npeaks)

channel: number of the receiver channel being accessed

npeaks: number of peaks (peaking filters) desired

[default = 2]

void SetRXAmpeakFilEnable (int channel, int fil, int enable)

channel: number of the receiver channel being accessed

fil: identifier of the filter being enabled. If npeaks is 2, the two filter identifiers will be 0 and 1.

enable: 0 = Disabled; 1 = Enabled

[defaults = { 1 , 1 }]

void SetRXAmpeakFilFreq (int channel, int fil, double freq)

channel: number of the receiver channel being accessed

fil: identifier of the filter being enabled. If npeaks is 2, the two filter identifiers will be 0 and 1.

freq: filter center frequency in Hertz

[defaults = { 2125.0, 2295.0 }]

void SetRXAmpeakFilBw (int channel, int fil, double bw)

channel: number of the receiver channel being accessed

fil: identifier of the filter being enabled. If npeaks is 2, the two filter identifiers will be 0 and 1.

bw: filter bandwidth in Hertz

[defaults = { 75.0, 75.0 }]

void SetRXAmpeakFilGain (int channel, int fil, double gain)

channel: number of the receiver channel being accessed

fil: identifier of the filter being enabled. If npeaks is 2, the two filter identifiers will be 0 and 1.

gain: gain of the filter. Note that this is an absolute gain --- NOT dB.
[defaults = { 1.0, 1.0 }]

Patch Panel - Audio Output Configuration

The PatchPanel block is used to configure the audio output. Operations such as volume control, binaural (I/Q) versus monaural output, audio-pan, I/Q swap, etc., can be performed using the provided controls.

void SetRXAPanelRun (int channel, int run)

channel: number of the receiver channel being accessed

run: 0 = OFF; 1 = ON
[default = 1]

void SetRXAPanelSelect (int channel, int select)

channel: number of the receiver channel being accessed

select: 0 = no input used; 1 = use only Q input; 2 = use only I input; 3 = Use both I and Q input
[default = 3]

void SetRXAPanelGain1 (int channel, double gain)

channel: number of the receiver channel being accessed

gain: gain to be applied to both I and Q outputs. This is an absolute gain, not dB.
[default = 4.0]

void SetRXAPanelGain2 (int channel, double gainI, double gainQ)

channel: number of the receiver channel being accessed

gainI: gain to be applied to the I output. This is an absolute gain, not dB.
[default = 1.0]

gainQ: gain to be applied to the Q output. This is an absolute gain, not dB.
[default = 1.0]

The following call provides an alternative way to set **gainI** and **gainQ**.

void SetRXAPanelPan (int channel, double pan)

channel: number of the receiver channel being accessed

pan: range is 0.0 to 1.0. If **pan** = 0.0, **gainI** = 1.0 and **gainQ** = 0.0. If **pan** = 1.0, **gainI** = 0.0 and **gainQ** = 1.0. If **pan** = 0.5, **gainI** = 1.0 and **gainQ** = 1.0. There are smooth transitions between these reference points as pan varies from 0.0 to 1.0, smoothly panning the sound.

void SetRXAPanelCopy (int channel, int copy)

channel: number of the receiver channel being accessed

copy: 0 = no copy; 1 = copy I to Q; 2 = copy Q to I; 3 = reverse I and Q.
[default = 0]

The following call provides an alternative way to set the '**copy**' flag.

void SetRXAPanelBinaural (int channel, int bin)

channel: number of the receiver channel being accessed

bin: 0 = copy I to Q (monaural mode); 1 = no copy (binaural mode).

RXA Collectives & General Controls

The following call sets the reception MODE for RXA. This single call turns OFF/ON and provides certain required settings to blocks such as the AM and FM demodulators.

void SetRXAMode (int channel, int mode)

channel: number of the receiver channel being accessed

mode: mode assignments are: 0 = LSB; 1 = USB; 2 = DSB; 3 = CWL; 4 = CWU; 5 = FM; 6 = AM; 7 = DIGU; 8 = SPEC; 9 = DIGL; 10 = SAM; 11 = DRM.

The following Collective calls combine the calls to multiple RXA blocks in cases where several blocks need the same information. This avoids having the console code make multiple calls, one per block. It also simplifies any future changes where new blocks might be added that require this same information. It is recommended to use these calls rather than individual calls to the blocks when possible.

The upper and lower pass-band frequency limits are set for all RXA blocks needing this information using the call:

void RXASetPassband (int channel, double f_low, double f_high)

channel: number of the receiver channel being accessed

f_low: lower of the two frequencies (Hertz). May be negative or positive. Must be lower (more negative) than **f_high**.

f_high: higher of the two frequencies (Hertz). May be negative or positive. Must be higher (more positive) than **f_low**.

The length of all RXA filter impulse responses for all RXA filters that accept variation in the length of impulse responses are simultaneously set using the call:

void RXASetNC (int channel, int nc)

channel: number of the receiver channel being accessed

nc: length of the desired filter impulse response. This must be a power of two AND must be greater than or equal to the DSP Buffer Size in use.

The choice of Linear Phase or Low Latency for all filters accepting such a choice is set by the call:

void RXASetMP (int channel, int mp)

channel: number of the receiver channel being accessed

mp: 0 for Linear Phase; 1 for Low Latency (Minimum Phase)

The TXA Transmitter Unit

Channel Parameters for TXA

The channel code serves as the interface between the unit it houses and the outside world. Considering this, some of the channel parameters relate only to the outside world. However, others impact the operation or perceived operation of the unit. It is this latter category of parameters that we discuss again here.

dsp_size: The unit only processes data when **dsp_size** samples have been accumulated. This parameter therefore impacts the latency incurred in DSP processing. Generally, using a lower **dsp_size** will reduce latency. However, these lower values mean a larger number of buffers are processed per unit time and each buffer requires some amount of processing overhead. Therefore, lower **dsp_size** implies some increase in the CPU load. **For TXA, for typical **dsp_rate**, **dsp_size** ranging from a minimum of 64 to a maximum of 1024 offers a reasonable range of trade-offs -- 64 for minimum latency and 1024 to minimize CPU load.**

Note, however, that there is an important relationship among **dsp_size**, **dsp_rate**, **in_size**, and **input_samplerate**. For example, consider the case where **dsp_size** = 64, **dsp_rate** = 96000, **input_samplerate** = 48000 and **in_size** = 64. As discussed below, a resampler will be automatically invoked to resample the input from 48000 up to 96000. For each one sample at the 48000 input rate, two samples at the 96000 rate will be produced. Therefore, 64 input samples (**in_size**) will produce 128 samples internally. This is 2 times the 64 samples (**dsp_size**) required for the unit to process data. Therefore, the unit will process twice before the channel will produce output. This implies that making **dsp_size** less than 128 will not speed-up DSP processing, given the other values of this example.

dsp_rate: **dsp_rate** not only impacts latency, as described just above, it also impacts the results in filtering operations. Doubling **dsp_rate** doubles the width of filter transition bands. This can be precisely compensated by doubling the number of filter coefficients. Of course, increasing the rate and increasing the complexity of the filter, both require more CPU cycles. **TXA has been designed to run optimally at a **dsp_rate** of 96000 for all modes.**

tdelayup, tslewup, tdelaydown, tslewdown: Typical settings for these parameters are given here. Note that, to minimize CW TX latency, the CW mode is intended to be implemented in firmware rather than through the DSP library. Therefore, lower times for CW are not considered here.

All modes: **tdelayup** = 0.010; **tslewup** = 0.025; **tdelaydown** = 0.000; **tslewdown** = 0.010.

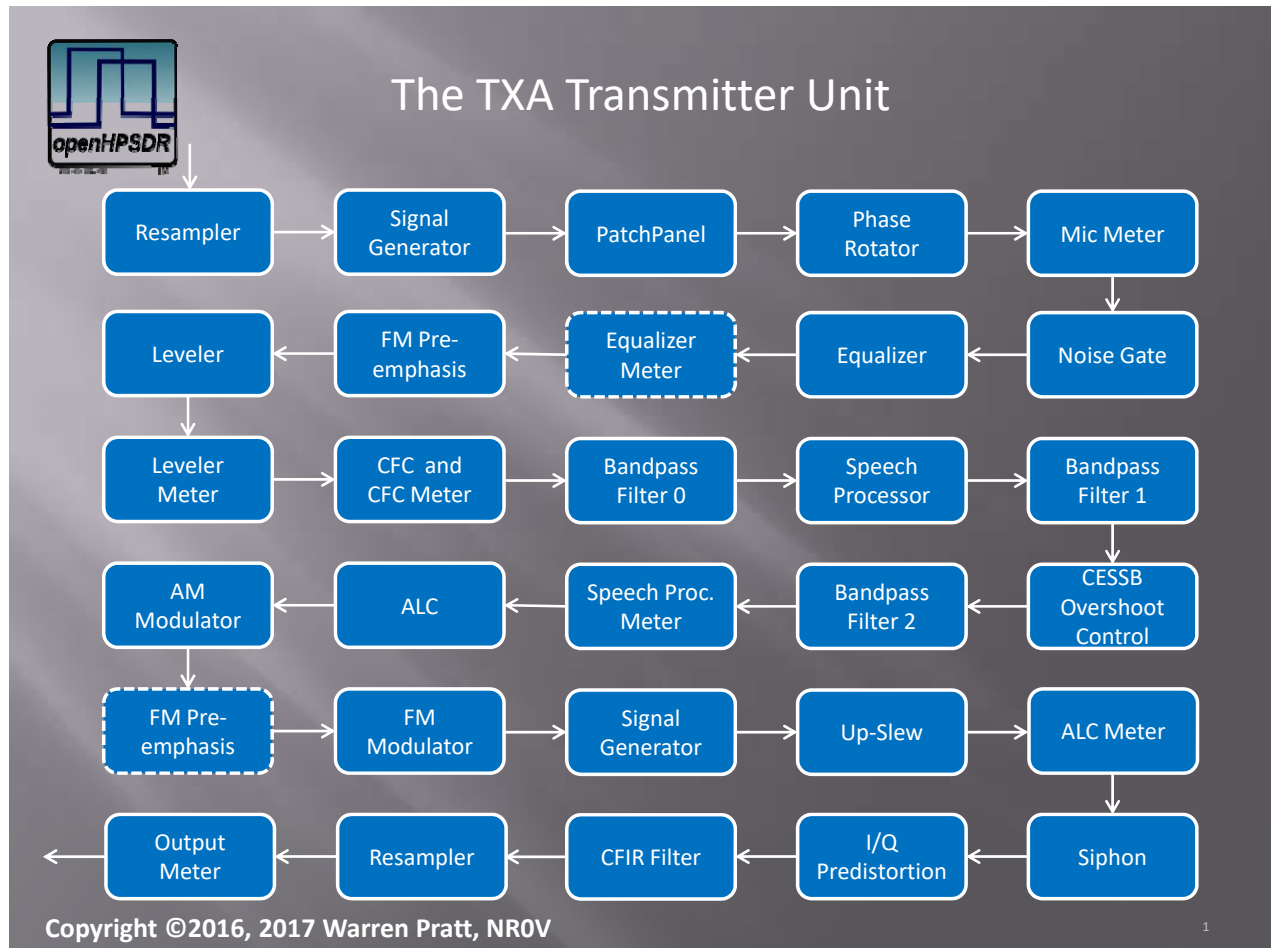
Signal Characteristics & Levels for TXA

The input to TXA is the audio MIC signal. Although, consistent with other channel input and output signals, this is delivered in an interleaved I-Q packet, this is an audio (NOT an I-Q signal). Hence, only the I values or the Q values will be used. See the "Patchpanel" for selection of whether I or Q data is to be used.

The peak amplitude of the MIC signal is limited only by the range of double-precision floating point calculations. However, it is expected that the product of the peak MIC signal and the MIC Gain setting will be roughly 1.0. See the "Patchpanel" for setting MIC Gain.

The TXA output is an I-Q signal with a peak magnitude of 1.0.

Block Diagram & Controls



The above figures displays the arrangement of blocks in the TXA transmitter unit. We will now discuss the operation and control of each block.

Resamplers

In the discussion above of channel parameters, three distinct rates are mentioned:

input_samplerate: samplerate of data entering the channel

dsp_rate: internal rate at which the data is processed within the unit

output_samplerate: samplerate of data exiting the channel

Two resamplers are provided within the TXA unit to convert among these rates. The first of these, the "Input Resampler," converts from the input_samplerate to the dsp_rate. The second of these, the "Output Resampler," converts from the dsp_rate to the output_samplerate.

No external calls are provided to control these resamplers. The three rates are set by the channel parameters and the resamplers are automatically activated when rates differ and therefore resampling is required.

Signal Generators

The TXA unit includes two signal generators. The first of these can replace the incoming MIC signal with a variety of waveforms that are useful for testing TXA setup and operation. The second of these generators is near the end of the processing chain and is intended for generating the TUNE signal, a Sweep Carrier, or a Two-Tone Test signal. Calls to set up the first of these generators contain the term "PreGen" while calls to set up the second of these two generators contain the term "PostGen".

The set of output modes currently supported for TXA "PreGen" comprises: Tone, Noise, Sweep, Sawtooth, Triangle, Pulse, and Silence.

void SetTXAPreGenRun (int channel, int run)

channel: number of the channel being accessed

run: 0 to turn the generator OFF; 1 to turn the generator ON
[default = 0]

void SetTXAPreGenMode (int channel, int mode)

channel: number of the channel being accessed

mode: Tone = 0; Noise = 2; Sweep = 3; Sawtooth = 4; Triangle = 5; Pulse = 6; Silence = 99
[default = 2]

void SetTXAPreGenToneMag (int channel, double mag)

channel: number of the channel being accessed

mag: peak magnitude value of the single-tone (mode = 0). Typical range is 0.0 to 1.0.
[default = 1.0]

void SetTXAPreGenToneFreq (int channel, double freq)

channel: number of the channel being accessed

freq: frequency (Hertz) of the single-tone (mode = 0). Can be either positive or negative.
[default = +1000.0]

void SetTXAPreGenNoiseMag (int channel, double mag)

channel: number of the channel being accessed

mag: magnitude value of the noise (mode = 2). Typical range is 0.0 to 1.0.
[default = 1.0]

void SetTXAPreGenSweepMag (int channel, double mag)

channel: number of the channel being accessed

mag: magnitude of the swept single tone (mode = 3). Typical range is 0.0 to 1.0.
[default = 1.0]

void SetTXAPreGenSweepFreq (int channel, double freq1, double freq2)

channel: number of the channel being accessed

freq1, freq2: frequency limits of the sweep range (Hertz). Sweep progresses from freq1 to freq2 and then repeats.
[defaults: freq1 = -20000.0, freq2 = +20000.0]

void SetTXAPreGenSweepRate (int channel, double rate)

channel: number of the channel being accessed

rate: rate at which the sweep progresses (Hertz / Second).
[default = +4000.0]

void SetTXAPreGenSawtoothMag (int channel, double mag)

channel: number of the channel being accessed

mag: peak magnitude value of the sawtooth. Typical range is 0.0 to 1.0.
[default = 1.0]

void SetTXAPreGenSawtoothFreq (int channel, double freq)

channel: number of the channel being accessed

freq: frequency (Hertz) of the sawtooth.
[default = +500.0]

void SetTXAPreGenTriangleMag (int channel, double mag)

channel: number of the channel being accessed

mag: peak magnitude value of the triangle. Typical range is 0.0 to 1.0.
[default = 1.0]

void SetTXAPreGenTriangleFreq (int channel, double freq)

channel: number of the channel being accessed

freq: frequency (Hertz) of the triangle.
[default = +500.0]

Note that the "Pulse" generator mode can produce a pulsed-tone, really a "burst mode", if the tone frequency is set to a non-zero value.

void SetTXAPreGenPulseMag (int channel, double mag)

channel: number of the channel being accessed

mag: peak magnitude value of the pulse. Typical range is 0.0 to 1.0.
[default = 1.0]

void SetTXAPreGenPulseFreq (int channel, double freq)

channel: number of the channel being accessed

freq: frequency (Hertz) of occurrence of the pulse.
[default = 0.25]

void SetTXAPreGenPulseDutyCycle (int channel, double dc)

channel: number of the channel being accessed

dc: Duty-cycle of the pulse = fraction of the time that the pulse is ON.
[default = 0.25]

void SetTXAPreGenPulseToneFreq (int channel, double freq)

channel: number of the channel being accessed

freq: Frequency of a pulsed tone (Hertz).
[default = 1000.0]

void SetTXAPreGenPulseTransition (int channel, double transtime)

channel: number of the channel being accessed

transtime: OFF-ON or ON-OFF transition time (seconds).
[default = 0.002]

The set of output modes currently supported for TXA "PostGen" comprises: Tone, Two-tone, Sweep, and Silence.

void SetTXAPostGenRun (int channel, int run)

channel: number of the channel being accessed

run: 0 to turn the generator OFF; 1 to turn the generator ON
[default = 0]

void SetTXAPostGenMode (int channel, int mode)

channel: number of the channel being accessed

mode: Tone = 0; Two-Tone = 1; Sweep = 3; Silence = 99
[default = 0]

void SetTXAPostGenToneMag (int channel, double mag)

channel: number of the channel being accessed

mag: peak magnitude value of the single-tone (mode = 0). Typical range is 0.0 to 1.0.
[default = 1.0]

void SetTXAPostGenToneFreq (int channel, double freq)

channel: number of the channel being accessed

freq: frequency (Hertz) of the single-tone (mode = 0). Can be either positive or negative.
[default = +1000.0]

void SetTXAPostGenTTMag (int channel, double mag1, double mag2)

channel: number of the channel being accessed

mag1: peak magnitude value of the first tone (mode = 0). Typical range is 0.0 to 1.0.
[default = 0.5]

mag2: peak magnitude value of the second tone (mode = 0). Typical range is 0.0 to 1.0.
[default = 0.5]

NOTE: With both **mag1** and **mag2** set to 0.5, the peak magnitude of the generator output will be 1.0. I.e., the peak magnitude of the generator output is **mag1 + mag2**.

void SetTXAPostGenTTFreq (int channel, double freq1, double freq2)

channel: number of the channel being accessed

freq1: frequency (Hertz) of the first tone (mode = 0). Can be either positive or negative.
[default = + 900.0]

freq2: frequency (Hertz) of the second tone (mode = 0). Can be either positive or negative.
[default = +1700.0]

void SetTXAPostGenSweepMag (int channel, double mag)

channel: number of the channel being accessed

mag: magnitude of swept single tone (mode = 3). Typical range is 0.0 to 1.0.
[default = 1.0]

void SetTXAPostGenSweepFreq (int channel, double freq1, double freq2)

channel: number of the channel being accessed

freq1, freq2: frequency limits of the sweep range (Hertz). Sweep progresses from freq1 to freq2 and then repeats.

[defaults: freq1 = -20000.0, freq2 = +20000.0]

void SetTXAPostGenSweepRate (int channel, double rate)

channel: number of the channel being accessed

rate: rate at which the sweep progresses (Hertz / Second).

[default = +4000.0]

PatchPanel

The TXA patchpanel is used to select which channel (I or Q) is used for MIC input and to set the MIC gain.
Available calls are:

void SetTXAPanelRun (int channel, int run)

channel: number of the channel being accessed

run: 0 = this patchpanel is not used; 1 = this patchpanel is active
[default = 1]

void SetTXAPanelSelect (int channel, int select)

channel: number of the channel being accessed

select: 1 for Q; 2 for I
[default = 2]

void SetTXAPanelGain1 (int channel, double gain)

channel: number of the channel being accessed

gain: MIC Gain to be applied (this is a linear value of gain, NOT a dB value)
[default = 1.0]

Meters

As shown in the block diagram, metering outputs from TXA are the Mic Meter, Equalizer Meter, Leveler Meter, Speech Processor Meter, ALC Meter, and the Output Meter. Taken together, these provide visibility of internal TXA processing levels that is sufficient to optimize many TXA settings.

Meter values are retrieved using the single call:

double GetRXAMeter (int channel, int mt)

return value: requested meter value (dBV, except dB for Leveler_Gain and ALC_Gain). This will return a value of 0.0 dBV for a signal magnitude level of 1.0.

channel: number of the channel being accessed

mt: type of meter data being requested. **mt** values are:

MIC_Peak = 0;

MIC_Average = 1;

EQ_Peak = 2;

EQ_Average = 3;

Leveler_Peak = 4;

Leveler_Average = 5;

Leveler_Gain = 6;

CFC_Peak = 7;

CFC_AV = 8;

CFC_Gain = 9;

Compressor_Peak = 10;

Compressor_Average = 11;

ALC_Peak = 12;

ALC_Average = 13;

ALC_Gain = 14;

Output_Peak = 15;

Output_Average = 16;

Noise Gate

The Noise Gate can be set to lower the microphone audio gain if the input signal for a period of time is below a specified level. This can be used to lower transmitted background noise (for example fan noise) during pauses in speech.

An instance of the same "AM Squelch" used in the RXA receiver is used for this purpose. Therefore, many of the same features, like raised-cosine transitions between gain levels, are available.

To activate this feature:

void SetTXAAMSQRUN (int channel, int run)

channel: number of the channel being accessed

run: 0 = OFF; 1 = ON
[default = 0]

To set the gain when "muted", i.e., the low gain level:

void SetTXAAMSQMutedGain (int channel, double dBlevel)

channel: number of the channel being accessed

dBlevel: gain (dB) to be used when the noise gate is MUTED. This is a negative value, relative to the UN-MUTED level.
[default = -13.98 dB]

To set the threshold for "un-mute":

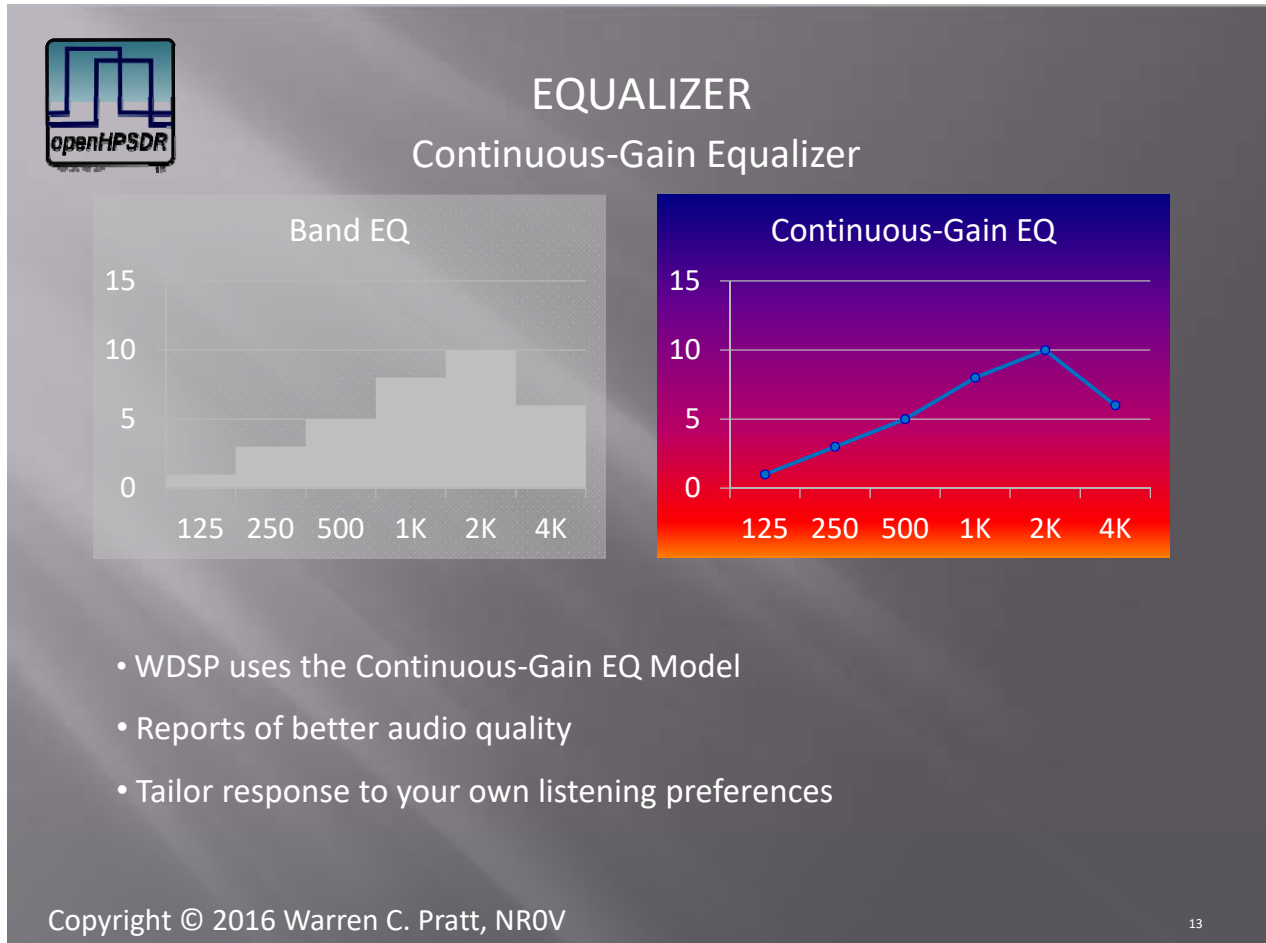
void SetTXAAMSQThreshold (int channel, double threshold)

channel: number of the channel being accessed

threshold: threshold (dB) at which to un-mute the noise gate.
[default = -13.98 dB]

Equalizer

The equalizer uses a continuous frequency response algorithm meaning that the gain is specified at any number of frequencies and the response is interpolated between the specified points. This is in contrast to a frequency "band" approach.



The equalizer is turned OFF/ON using calls to:

```
void SetTXAEQRun (int channel, int run)
```

channel: number of the channel being accessed

run: 0 for OFF; 1 for ON
[default = 0]

The length of the EQ filter impulse response can be set with the following call. However, this is **NOT RECOMMENDED**. The preferred method is to use the TXA Collective **TXASetNC(...)**. (See the section of this document on "TXA Collectives".)

```
void SetTXAEQNC (int channel, int nc)
```

DEPRECATED

channel: number of the channel being accessed

nc: length of the EQ filter impulse response. 'nc' must be a power-of-two AND must be greater than or equal to the DSP Buffer Size in use.

[default = 2048]

The Filter Type (Linear-Phase / Low-Latency) for the EQ filter can be set with the following call. However, this is **NOT RECOMMENDED**. The preferred method is to use the TXA Collective **TXASetMP(...)**. (See the section of this document on "TXA Collectives".)

void SetTXAEQMP (int channel, int mp)

DEPRECATED

channel: number of the channel being accessed

mp: 0 for Linear-Phase; 1 for Low-Latency (Minimum Phase)

[default = 0]

The window-type used in the generation of the EQ filter can be selected. This setting should normally just be left at the default value.

void SetTXAEQWintype (int channel, int wintype)

channel: number of the channel being accessed

wintype: 0 = 4-term Blackman-Harris; 1 = 7-term Blackman-Harris

[default = 0]

The cutoff-mode used in the generation of the EQ filter can be selected. This setting should normally just be left at the default value.

void SetTXAEQCtfmode (int channel, int mode)

channel: number of the channel being accessed

mode: 0 = 4th-power roll-off on each side of the specified passband; 1 = no roll-off outside the specified passband

[default = 0]

The following call is the primary and preferred method of setting the equalizer response.

void SetTXAEQProfile (int channel, int nfreqs, double* F, double* G)

channel: number of the channel being accessed

nfreqs: number of frequency/gain pairs to be specified

F: pointer to an array of frequencies (Hertz). NOTE: The 0th element of this vector is NOT USED. So, for example, if **nfreqs** is 5, F[0] is not used and the five frequencies will be stored in F[1] ... F[5]. The F[] array has (**nfreqs** + 1) values.

Note that acceptable values are between 0.0 Hz and **dsp_rate**/2.0 Hz. It is acceptable to specify the same frequency multiple times; however, if different gains are specified for the same frequency, it is indeterminate as to which of the gains will be applied at that frequency. Frequency/Gain pairs do not necessarily have to be specified in order of increasing frequency. If they are not, they will be sorted into the appropriate order prior to application.

G: pointer to a corresponding array of gain values (dB). The 0th element is used to specify a "preamp gain" value to be applied to all frequencies. The G[] array has (**nfreqs** + 1) values.

For convenience and consistency with legacy consoles, two "short-cut" calls with pre-specified frequencies are provided.

void SetTXAGrphEQ (int channel, int* rxeq)

DEPRECATED

channel: number of the channel being accessed

rxeq: pointer to an array containing gain values (dB) corresponding to an implicit "F vector" of F[] = {0.0, 150.0, 400.0, 1500.0, 6000.0}. The value in G[0] is the "preamp gain" to be applied to all frequencies. G[1] through G[4] contain gains corresponding to 150.0 Hz through 6000.0 Hz, respectively.

void SetTXAGrphEQ10 (int channel, int* rxeq)

DEPRECATED

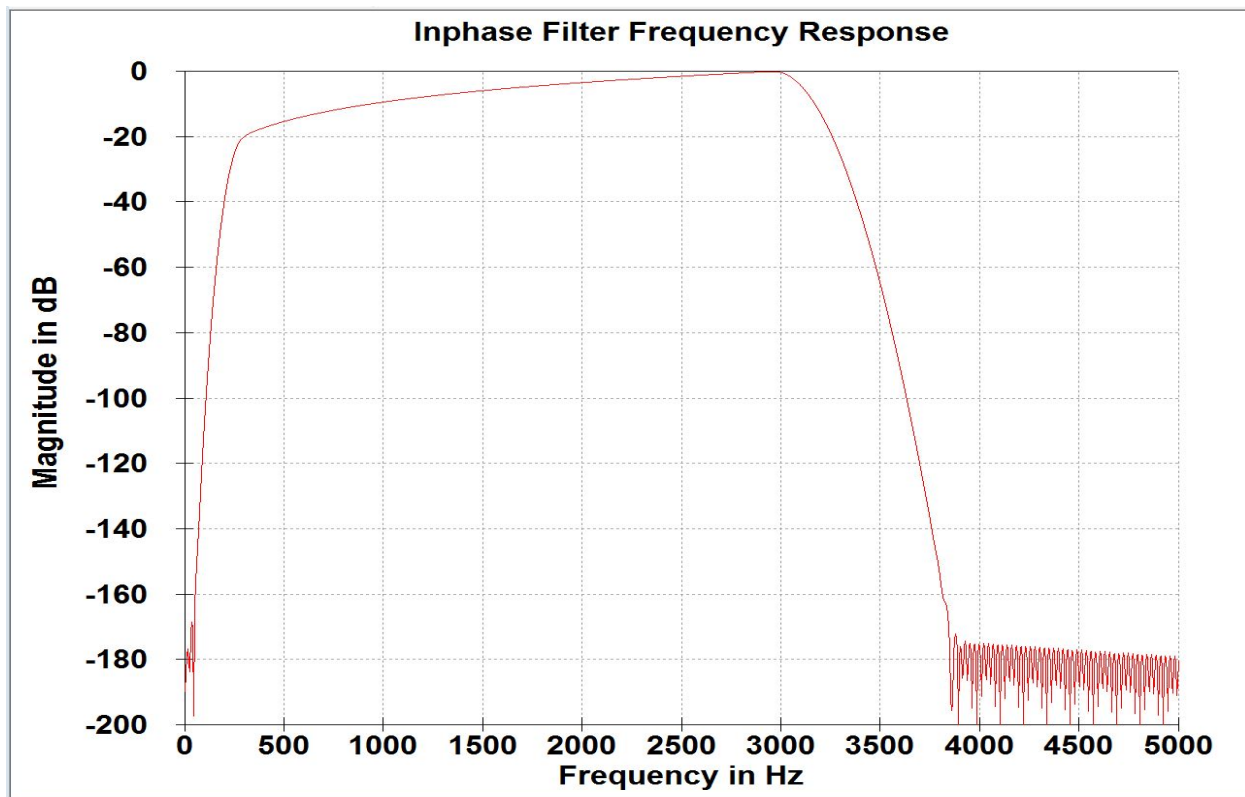
channel: number of the channel being accessed

rxeq: pointer to an array containing gain values (dB) corresponding to an implicit "F vector" of F[] = {0.0, 32.0, 63.0, 125.0, 250.0, 500.0, 1000.0, 2000.0, 4000.0, 8000.0, 16000.0}. The value in G[0] is the "preamp gain" to be applied to all frequencies. G[1] through G[10] contain gains corresponding to 32.0 Hz through 16000.0 Hz, respectively.

FM Pre-emphasis

FM transmit Pre-emphasis, along with companion receive de-emphasis, are used to improve the signal-to-noise ratio of FM transmission-reception.

The standard bandwidth for narrowband FM communications is 300 Hz to 3000 Hz. Pre-emphasis follows a 6 dB per octave (20 dB per decade) slope. When implemented with the default impulse response length (2048), the TXA pre-emphasis curve is as shown in the following figure. Note that the frequency scale shown here is linear; therefore the curve appears to be more rounded than the straight-line one would see if this were plotted with a log-domain frequency axis. Also, note that no attempt has been made here to make the cutoff extremely sharp as this will be controlled by the bandpass filter.



Referring back to the overall TXA block diagram, note that FM Pre-emphasis is shown twice, each time in a block with a dashed outside line. The meaning is that the FM pre-emphasis can be located in either position, controllable by a "switch":

```
void SetTXAFMEmphPosition (int channel, int position)
```

channel: number of the channel being accessed

position: 0 = BEFORE pre-processing and ALC; 1 = AFTER pre-processing and ALC
[default = 1]

The latter (default) position will absolutely limit the transmitted magnitude of a particular frequency, i.e., a 1000 Hz could never be transmitted with the same power as a 2000 Hz signal. The former position

has a different behavior which generally may allow the signal to sound louder. The correct positioning has been the subject of some discussion and so both options are provided via the switch.

The length of the Pre-emphasis filter impulse response can be set with the following call. However, this is **NOT RECOMMENDED**. The preferred method is to use the TXA Collective **TXASetNC(...)**.

void SetTXAFMEmphNC (int channel, int nc)

DEPRECATED

channel: number of the channel being accessed

nc: length of the Pre-emphasis filter impulse response. 'nc' must be a power-of-two AND must be greater than or equal to the DSP Buffer Size in use.

[default = 2048]

The Filter Type (Linear-Phase / Low-Latency) for the Pre-emphasis filter can be set with the following call. However, this is **NOT RECOMMENDED**. The preferred method is to use the TXA Collective **TXASetMP(...)**.

void SetTXAEmphMP (int channel, int mp)

DEPRECATED

channel: number of the channel being accessed

mp: 0 for Linear-Phase; 1 for Low-Latency (Minimum Phase)

[default = 0]

Leveler

The audio leveler can be invoked to provide additional gain when the audio signal is low and then to reduce gain as the audio level increases. This can be useful, for example, to provide a little extra gain if the operator momentarily turns away from the microphone or to reduce gain if the operator momentarily gets closer to the microphone, in other words, it "levels" the audio signal.

The Leveler also helps provide a known audio amplitude level for the phase rotator, CFC, and speech processor (compressor) that follow. This helps ensure that the requested compression level is the level delivered. In the absence of this assistance from the Leveler, it's solely up to the operator to ensure that the audio level before the following stages is peaking at about 0 dB.

The Leveler is implemented with an instance of AGC/ALC code; however, the settings are considerably different for the Leveler application. You will, however, notice similarity in some of the settings. Settings available for the Leveler are:

`void SetTXALevelerSt (int channel, int state)`

channel: number of the channel being accessed

state: 0 = OFF; 1 = ON
[default = 0]

`void SetTXALevelerAttack (int channel, int attack)`

channel: number of the channel being accessed

attack: attack time-constant in ms. Note that this is a time-constant for an exponential curve, NOT an absolute time. It is recommended to leave this at the default value.
[default = 1 ms]

`void SetTXALevelerDecay (int channel, int decay)`

channel: number of the channel being accessed

decay: decay time-constant in ms. Note that this is a time-constant for an exponential curve, NOT an absolute time. The default value works well for normal operating conditions.
[default = 500 ms]

`void SetTXALevelerTop (int channel, double maxgain)`

channel: number of the channel being accessed

maxgain: maximum gain (dB) that the leveler is to apply.
[default = 5.0 dB]

Phase Rotator

In some AM transmitters, it is possible to boost the peak output power by having an asymmetrical audio waveform (positive peaks greater than negative peaks) and modulating to greater than 100% on positive peaks while restricting to $\leq 100\%$ on negative peaks to avoid "pinch-off."

In other AM transmitters and in the case of our digital-up-conversion (DUC) SDRs, this is not the correct approach. We have hard-limits which cannot be exceeded, such as the dynamic range of the DAC. The application of an asymmetrical audio waveform, with positive peaks greater than negative peaks, cannot further increase modulation in the positive direction; it instead REDUCES average power. The correct approach in such cases is to make the audio waveform as symmetrical as possible, i.e., equal positive and negative peaks.

The Phase Rotator makes the audio waveform more symmetrical. It does so by shifting the phase of various audio frequencies by varying amounts, thereby changing the shape of the waveform away from the somewhat typical asymmetrical waveform of human speech. Experimentation and analysis show that a wide range of phase shift versus frequency generally tends to improve symmetry. This wide range leads to an implementation with multiple identical stages, where the total phase shift is the sum of the shifts obtained in each stage. The stages have a specified "corner frequency" where the phase shift of the stage is equal to one-half of the total that the stage provides at the maximum frequency.

While the above explanation focused on AM, note that this feature can be used to increase average power for any speech mode. Note also, however, that it could be detrimental for any digital mode that requires coherent phase versus frequency.

Settings for the Phase Rotator are:

void SetTXAPHROTRun (int channel, int run)

channel: number of the channel being accessed

run: 0 = OFF; 1 = ON
[default = 0]

void SetTXAPHROTCorner (int channel, double frequency)

channel: number of the channel being accessed

frequency: Corner frequency in Hertz.
[default = 338.0]

void SetTXAPHROTNstages (int channel, int nstages)

channel: number of the channel being accessed

nstages: The number of phase rotator stages to be used.
[default = 8]

Continuous Frequency Compressor (CFC)

Many audio racks and Digital Audio Workstations provide "Multiband Compressors" which allow specifying different amounts of compression for different audio frequency bands. The CFC offers a superset of that concept where, instead of utilizing multiple bands with constant compression in each, the compression varies smoothly between frequency points at which it is specified. This concept is similar to the WDSP Equalizer function discussed above; however, this time, we are varying the compression level across frequencies rather than gain. A Post-CFC Equalizer is also provided as an integral part of this function.

Use of this function for speech modes can significantly increase the "density" and average power of the signal. Note also that use for digital modes may be detrimental, depending upon the nature of the mode.

Settings for the CFC are:

void SetTXACFCOMPRun (int channel, int run)

channel: number of the channel being accessed

run: 0 = OFF; 1 = ON
[default = 0]

void SetTXACFCOMPprofile (int channel, int nfreqs, double* F, double* G, double* E)

channel: number of the channel being accessed

nfreqs: number of frequencies at which compression and post-CFC equalizer gain are specified

F: pointer to the array of frequency points (values in Hertz)

G: pointer to the array of compression at each frequency point (values in dB)

E: pointer to the array of post-CFC equalizer gains (values in dB)

void SetTXACFCOMPPrecomp (int channel, double precomp)

channel: number of the channel being accessed

precomp: an additional amount of compression to be applied equally across the frequency spectrum (dB) [default = 0.0]

void SetTXACFCOMPPeqRun (int channel, int run)

channel: number of the channel being accessed

run: Turn OFF/ON the post-CFC Equalizer: 0 = OFF; 1 = ON [default = 0]

void SetTXACFCOMPPrePeq (int channel, double prepeq)

channel: number of the channel being accessed

prepeq: an additional amount of gain to be applied equally across the frequency spectrum in the post-CFC equalizer (dB) [default = 0.0]

Bandpass Filters

There are three bandpass filters:

- The first of these, Bandpass Filter 0, is always ON. It "squares up" the pass-band and converts the audio to a complex I-Q signal. This is the primary bandpass filter.
- The second, Bandpass Filter 1, is used if and only if the Speech Processor is used. The speech processor is a non-linear device and therefore creates out-of-band frequency components. This bandpass filter removes those components. This filter is also a prerequisite for the CESSB Overshoot Control. The ON/OFF state of this filter is automatically set inside WDSP.
- The third, Bandpass Filter 2, is used if and only if the CESSB Overshoot Control is activated and serves as the final overshoot correction step for this algorithm. The ON/OFF state is automatically set inside WDSP.

For AM, AM_LSB, AM_USB, FM, and DSB modes, it is expected that the filter frequencies will be set by the console to cover an equal-sided range, e.g., $f_{\text{low}} = -5000.0$ and $f_{\text{high}} = +5000.0$. Any other necessary adjustments are handled internally in the WDSP code.

For other single-sided modes, such as LSB and USB, filter frequencies should be set as desired for the mode. For example, for LSB, $f_{\text{low}} = -3000.0$ and $f_{\text{high}} = -200.0$.

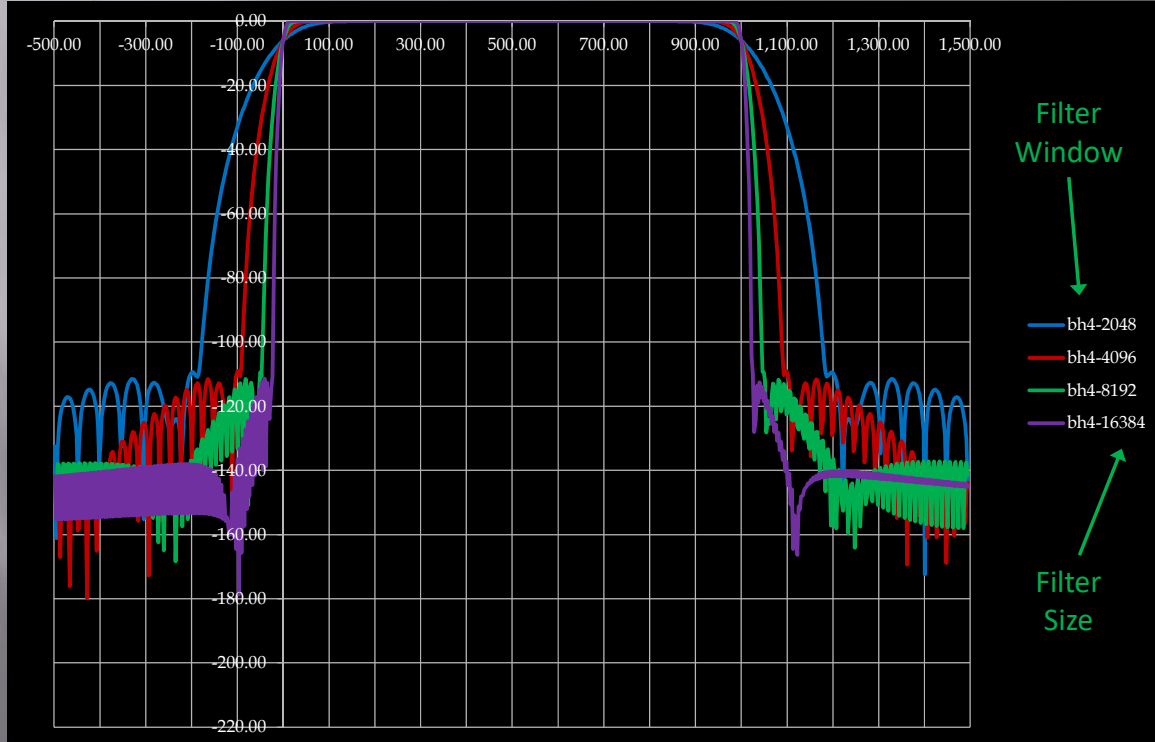
The "sharpness" of these filters, when running TXA at a `dsp_rate` of 96000, is shown in the following two figures. The first of these figures shows the response curves for different impulse response lengths, all using the 4-term Blackman-Harris window. The second figure is the same except using the 7-term Blackman-Harris window. The 4-term yields slightly sharper cutoff; however, less cutoff depth. The 4-term would be preferred in most situations since its cutoff depth is generally more than sufficient; the 7-term is overkill on cutoff depth for most situations.

Note that the transition bands (regions between the pass-band and the cutoff bands) are the most important part to observe in these figures. These transition bands will maintain the same width independent of the width of the filter pass-band.



BANDPASS FILTER

Sample-rate = 96 KHz



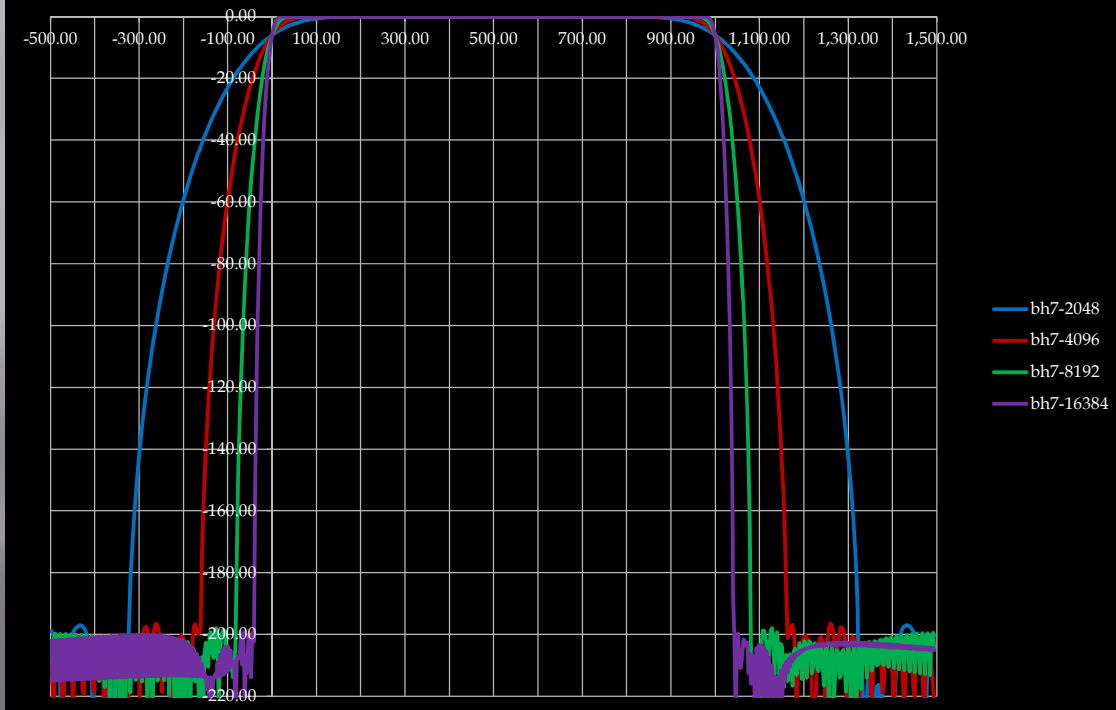
Copyright © 2016 Warren C. Pratt, NR0V

8



BANDPASS FILTER

Sample-rate = 96 Khz



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9

The lower and upper frequency cutoffs for the three bandpass filters are set using the call:

```
void SetTXABandpassFreqs (int channel, double f_low, double f_high)
```

channel: number of the channel being accessed

f_low: low cutoff frequency (Hz). May be either positive or negative. Must be less (more negative) than **f_high**.

[default = -5000.0 Hz]

f_high: high cutoff frequency (Hz). May be either positive or negative. Must be greater (more positive) than **f_low**.

[default = -100.0 Hz]

The window function to be used in generating the bandpass filters is set using:

```
void SetTXABandpassWindow (int channel, int wintype)
```

channel: number of the channel being accessed

wintype: 0 = Blackman-Harris 4-term; 1 = Blackman-Harris 7-term

The length of the bandpass filters' impulse responses could be set using the following call. However, this is **NOT RECOMMENDED**. Instead, it is recommended to use the TXA Collective call **TXASetNC(...)**. (See the section of this document on TXA Collectives.)

void SetTXABandpassNC (int channel, int nc)

DEPRECATED

channel: number of the channel being accessed

nc: length of the filter impulse response. Must be a power of two and must be greater than or equal to the DSP buffer size in use.

[default = 2048]

The choice of Linear Phase or Low Latency for the bandpass filters could be set using the following call. However, this is **NOT RECOMMENDED**. Instead, it is recommended to use the TXA Collective call **TXASetMP(...)**. (See the section of this document on TXA Collectives.)

void SetTXABandpassMP (int channel, int mp)

DEPRECATED

channel: number of the channel being accessed

mp: 0 = Linear Phase; 1 = Low Latency (Minimum Phase)

Speech Processor

The Speech Processor is the equivalent of an RF Speech Clipper; however, implemented at baseband rather than at RF frequencies.

Note that the specified compression level is accurate only when the input signal is achieving a peak magnitude of exactly 1.0. At lower peak input levels, less compression will be achieved and at higher peak input levels more compression will be achieved. As previously discussed (see "Leveler"), the Leveler can provide assistance in regulating the input level. Whether the Leveler is used or not, the metering functionality provides excellent feedback to the operator concerning the signal levels in the audio chain.

The Speech Processor is turned OFF/ON using the following call:

```
void SetTXACompressorRun (int channel, int run)
```

channel: number of the channel being accessed

run: 0 = OFF; 1 = ON
[default = 0]

The compression level is set using:

```
void SetTXACompressorGain (int channel, double gain)
```

channel: number of the channel being accessed

gain: compression level in dB.
[default = 3.0 dB]

CESSB Overshoot Control

The concept of CESSB (Controlled Envelope Single Sideband) was provided to the Amateur Radio community by Dave Hershberger, W9GR.² In brief, this is an algorithm to increase the average transmitted power of an SSB signal while introducing only minimal distortion. To understand more detail, please see Dave's article.

Only one control is needed, the OFF/ON control:

void SetTXAosctrlRun (int channel, int run)

channel: number of the channel being accessed

run: 0 = OFF; 1 = ON
[default = 0]

HOWEVER, note that it is the responsibility of the console application to ensure that the Speech Processor is turned ON as a prerequisite for this block! This block will NOT operate properly in the absence of the Speech Processor also being active!

Note that for optimum performance, Linear Phase bandpass filters should be used with this feature. The amount of performance degradation when using Low Latency filters has not been measured and will vary with voice characteristics.

² David L. Hershberger, W9GR, "Controlled Envelope Single Sideband," QEX Magazine, November/December 2014.

ALC

Unlike conventional radios, the Automatic Level Control function for TXA is accomplished in a single block; it does not include any kind of feedback from later blocks in the pipeline. ALC systems with feedback loops generally "drive by looking in the rear-view mirror," i.e., they react to an over-drive event in a later stage by reducing the gain in an earlier stage. However, that gain reduction is after-the-fact ... the over-drive and initial distortion have already occurred. The ALC system in TXA contains a short delay line which allows it to "see" events coming on the horizon before it has to provide output for them. Therefore, it can gradually reduce the gain along an exponential curve BEFORE the event happens rather than after.

In a Digital Up-Conversion (DUC) SDR, it is EXTREMELY important to insure that peak magnitudes NEVER exceed a specific level. Even though larger values would be no problem in WDSP floating-point calculations, they would overflow the (finite-range, integer-input) DAC, and, perhaps the integer calculations preceding the DAC. These overflows produce extreme distortion and very broadband splatter. The WDSP ALC system is designed to avoid this happening. For this reason, the ALC should ALWAYS be active.

Also, per this type ALC action, there is no ALC overshoot produced by this system.

For testing purposes, the ALC can be turned OFF/ON using the following call. HOWEVER, per the discussion above, it is expected that the ALC will ALWAYS BE ON.

void SetTXAALCSt (int channel, int state)

channel: number of the channel being accessed

state: 0 = OFF; 1 = ON
[default = 1]

The ALC Attack time-constant can be set using the following call. It is recommended to leave this at the default value.

void SetTXAALCAAttack (int channel, int attack)

channel: number of the channel being accessed

attack: attack time-constant (ms). Note that this is a time-constant for an exponential curve, not an absolute time.
[default = 1 ms]

The ALC Decay time-constant is set using the following call.

void SetTXAALCDecay (int channel, int decay)

channel: number of the channel being accessed

decay: decay time-constant (ms). Note that this is a time-constant for an exponential curve, not an absolute time.

[default = 10 ms]

A maximum gain for the ALC block is specified with the following call. This is "maximum gain" since the ALC will reduce the gain (compress) as needed to deliver the targeted output level.

void SetTXAALCMaxGain (int channel, double maxgain)

channel: number of the channel being accessed

maxgain: maximum gain (dB)

[default = 0dB]

AM Modulator

The AM Modulator is automatically activated/deactivated based upon the `SetTXAMode(...)` setting. (See the section on "TXA Collectives & General Controls.")

The only setting for the AM Modulator is the Carrier Level setting:

`void SetTXAAMCarrierLevel (int channel, double c_level)`

`channel`: number of the channel being accessed

`c_level`: 0.0 => NO CARRIER (DSB); 0.5 => 100% modulation; >0.5 => less than 100% modulation.
[default = 0.5]

Note that the carrier level setting applies to the modes AM_LSB and AM_USB as well as the AM mode.

FM Modulator

The FM Modulator is automatically activated/deactivated based upon the `SetTXAMode(...)` setting. (See the section on "TXA Collectives & General Controls.")

The peak deviation for the FM signal can be set using the call:

void SetTXAFMDeviation (int channel, double deviation)

channel: number of the channel being accessed

deviation: peak deviation of the FM modulation (Hz).
[default = 5000.0]

A CTCSS tone can optionally be transmitted on the FM signal. There are controls to turn the tone OFF/ON and to set its frequency.

void SetTXACTCSSRun (int channel, int run)

channel: number of the channel being accessed

run: 0 = tone OFF; 1 = tone ON.
[default = 1]

void SetTXACTCSSFreq (int channel, double freq)

channel: number of the channel being accessed

freq: tone frequency (Hz).
[default = 100.0]

The highest audio modulating frequency for the FM mode is 3000 Hz. Carson's Rule states that about 98% of the power of the resulting FM signal is contained within a bandwidth ranging from minus(deviation+highest_audio_frequency) to plus(deviation+highest_audio_frequency). While, at first glance, that may seem significant, that means that the power outside this range is only 17 dB below the power within the range. Therefore, the FM Modulator includes an output bandpass filter that limits the transmitted power to be within this specified range.

The length of the impulse response of this filter, and whether it is Linear Phase or Low Latency, can be set using the following calls. This is **NOT RECOMMENDED**. Instead, it is recommended to use the calls `TXASetNC(...)` and `TXASetMP(...)`, respectively, found in the TXA Collectives section.

void SetTXAFMNC (int channel, int nc)

DEPRECATED

channel: number of the channel being accessed

nc: length of the filter impulse response. This must be a power-of-two and must be greater than or equal to the **dsp_size** in use at the time.

[default = 2048]

void SetTXAFMMP (int channel, int mp)

DEPRECATED

channel: number of the channel being accessed

mp: 0 = Linear Phase; 1 = Low Latency (Minimum Phase).

Up-Slew

Note that the Up-Slew block is located after (1) the Signal Generators, (2) the AM Modulator, and (3) the FM Modulator. This block gradually increases the signal level from zero to maximum, along a raised-cosine curve, when one of these blocks is active and the TXA channel state transitions from OFF to ON.

In the case of SSB or DSB, the RF output is proportional to the audio input and there is no RF output until audio is present inside and processed through the TXA unit. The audio input to TXA must pass through the channel's initial up-slew. Hence, the RF output will in-turn up-slew also. However, with the three special cases mentioned above, signal is created internal to the TXA unit independently of audio being present. This signal requires an up-slew to avoid an abrupt transition, consequent "pop" in the audio, and consequent disturbance in the frequency spectrum. In the case of the signal generator, the signal referenced is whatever signal the generator is set to produce. In the case of the AM Modulator and FM Modulator, it is the carrier they generate whose up-slew must be controlled.

There are no controls for the up-slew. It's control is managed internal to the TXA unit.

Siphon

In the block diagram for TXA, after the Siphon block, there are two blocks that can alter the time-domain and frequency-domain content of the signal: (1) PureSignal Predistortion, which, by definition, is intended to predistort the signal to compensate for later non-linearities in the processing chain, and (2) the CFIR which intentionally distorts the frequency response to compensate for frequency-response distortion in later CIC filters in FPGA firmware. It is often desirable to monitor the content of the signal BEFORE these intentional distortions are applied. The Siphon provides the data output for this monitoring. It "siphons" copies of the data from the TXA processing pipeline as the data flows through and either (1) sends the data directly to a WDSP display unit, or (2) makes it available to the console through calls that the console can make to the siphon.

NOTE: Per the setting of an internal parameter, the number of contiguous samples being internally buffered is 4096. Therefore, retrievals of data are limited to this size.

void TXASetSipMode (int channel, int mode)

channel: number of the channel being accessed

mode: 0 = data is to be retained awaiting a retrieval call from the console; 1 = data is to be sent directly to a specified display unit.
[default = 0]

void TXASetSipDisplay (int channel, int disp)

channel: number of the channel being accessed

disp: identifier of the display unit to which data is to be sent.
[default = 0]

There are currently three calls the console can make to retrieve data. For historical reasons, at the time of this writing, all return 'float' data. At some future time, calls will likely be added to provide data in the 'double' type.

The following function returns a block of consecutive raw sample values (I-values only) in an array.

void TXAGetaSipF (int channel, float* out, int size)

channel: number of the channel being accessed

out: pointer to the array where the values are to be stored

size: number of values to be returned

The following function returns a block of consecutive raw sample values (complex interleaved I-Q samples) in an array.

void TXAGetaSipF1 (int channel, float* out, int size)

channel: number of the channel being accessed

out: pointer to the array where the interleaved I-Q values are to be stored

size: number of I-Q samples to be returned

The following call returns a set of values of the frequency-domain magnitudes to be used for a frequency-domain display. Values are in dBV, i.e., a sample magnitude of 1.0 yields an output value of 0.0 dB. Per the setting of an internal parameter, **fftsize**, 4096 magnitude values are returned; hence, there is no 'size' parameter.

void TXAGetaSpecF1 (int channel, float* out)

channel: number of the channel being accessed

out: pointer to the array where the magnitude values are to be stored

There are two possible orderings in which the values from **TXAGetaSpecF1(...)** can be returned. The choice of which to return is determined by the setting of the internal variable **specmode** which is set by the following call.

void TXASetSipSpecmode (int channel, int mode)

channel: number of the channel being accessed

mode: 0 => the "Normal Order" of the FFTW³ library output is re-arranged such that the two halves of the spectrum are swapped; 1 => the "Normal Order" of the FFTW⁴ library output is re-arranged to mirror each half of the FFTW output in place.

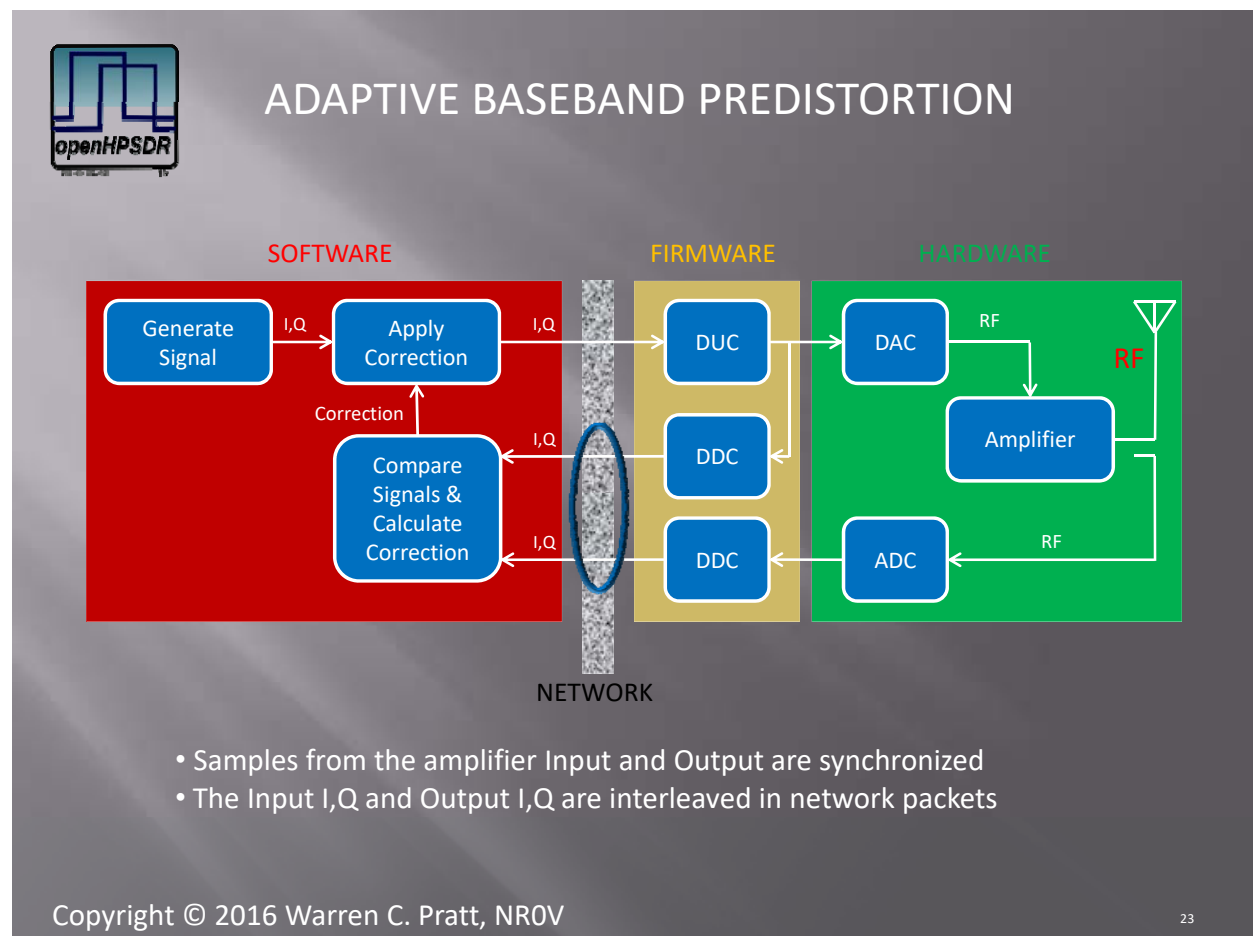
[default = 1]

³ FFTW is the FFT library used for WDSP. See <www.fftw.org> for more information.

⁴ FFTW is the FFT library used for WDSP. See <www.fftw.org> for more information.

PureSignal I/Q Predistortion

The following figure displays the operation of PureSignal in the complete SDR environment including software, FPGA firmware, and hardware. The software block "Apply Correction" is where the I-Q signal is modified, applying amplitude and phase correction. The block "Compare Signals & Calculate Correction" executes asynchronously with the dataflow through the TXA unit and uses as its input synchronized samples from the amplifier's input and the amplifier's output. The fact that two sample streams (amplifier input and amplifier output) are required, and the fact that they must be synchronous (each output sample must correspond to the input sample that drove the amplifier to that output), means that some mechanism other than normal channel input and dataflow must be used to provide these samples since the channel structure only supports input of a single sample stream.



Data Input

Buffers of the two sample streams are provided as input data using the following call.

```
void pscc (int channel, int size, double* tx, double* rx)
```

channel: number of the TXA channel being accessed

size: number of I-Q samples provided for each sample stream

tx: pointer to buffer containing the output-bound sample stream, i.e., the sample stream to drive the amplifier input

rx: pointer to buffer containing the sample stream received from the amplifier's output

Control

Considerable information about the state of affairs in PureSignal can be obtained using the following call. This information is often useful in software/firmware debugging and in understanding issues with specific hardware configurations. Some of the information is also used for normal monitoring, for example monitoring of the amplifier output feedback level.

void GetPSInfo (int channel, int* info)

channel: number of the channel being accessed

info: pointer to an array to hold 16 integer values. Assignment of these 16 values is as follows:

- 0 - status of correction curve builder for rx_scale
- 1 - status of correction curve builder for cm
- 2 - status of correction curve builder for cc
- 3 - status of correction curve builder for cs
- 4 - amplifier output feedback level
- 5 - count of attempted calibrations
- 6 - results from checking the computed correction solution
- 7 - results from checking the computation of peak power
- UNUSED
- 13 - dogcount
- 14 - indicates the state-machine says that iqcRun = 1, i.e., the state-machine says that correction values are being applied
- 15 - state of the control state-machine

Data collection and state machine operation is turned OFF/ON by the following call. Nothing happens unless **run** is set to 1. Note that the default is 1 and there are other ways to turn OFF/ON PureSignal operation; hence, this call may be unnecessary in your application.

void SetPSRunCal (int channel, int run)

channel: number of the channel being accessed

run: 0 = OFF; 1 = ON
[default = 1]

The sample-rate of the two streams provided to **pscc(...)** must be set using the following call.

void SetPSFeedbackRate (int channel, int rate)

channel: number of the channel being accessed

rate: the sample rate (samples / second)

The primary mode of operation is set by the following call. This call provides four control variables that affect the progression of the control state-machine. Note that often the call is made with only one of the last four parameters as '1' and the other three as zero. An example of where multiple parameters may be set to '1' would be in the event that Automatic Calibration Mode is active but we want to change to Single (Manual) Calibration mode. In that case, we can make the call **SetPSControl(channel, 1, 1, 0, 0);** . This call will reset PureSignal, turning off correction. It will also specify the Single/Manual Calibration mode and turn OFF the Automatic Calibration Mode.

void SetPSControl (int channel, int reset, int mancal, int automode, int turnon)

channel: number of the channel being accessed

reset: 0 = PS is free to operate as directed; 1 = turn-off PS and reset the control state-machine. To turn OFF PureSignal calibration and correction, call with parameters (1, 0, 0, 0).

mancal: Call with parameters (0, 1, 0, 0) to perform a single calibration run and then turn-on correction using that calibration. In this mode, the algorithm is not "adaptive"; it just continues to use this same correction.

automode: Call with parameters (0, 0, 1, 0) to turn on auto-calibration mode and correction. In this mode, the algorithm continues looping and re-calibrating, i.e., it is adaptive.

turnon: Call with parameters (0, 0, 0, 1) to tell the internal state-machine to continue indefinitely to use whatever correction has been loaded into the correction buffers. This variable is set in situations such as restoring calibration information from a file.

Calibration values can be saved in files and then restored to active correction. These calls save the current calibration and then restore that to active correction.

void PSSaveCorr (int channel, char* filename)

channel: number of the channel being accessed

filename: the file to which the calibration is to be stored

void PSRestoreCorr (int channel, char* filename)

channel: number of the channel being accessed

filename: the file from which the calibration is to be restored

When in automatic-calibration mode, it is possible to add some delay in the re-calibration (adaptation) loop. The benefit would be to slightly reduce CPU utilization. Such delay can be added using the following call.

void SetPSLoopDelay (int channel, double delay)

channel: number of the channel being accessed

delay: delay to insert after each calibration (seconds)
[default = 0.0]

Valid data for calibration can only be collected during transmit, i.e., when MOX is active. The following call conveys the state of MOX to PureSignal.

void SetPSMox (int channel, int mox)

channel: number of the channel being accessed

mox: 0 = not transmitting; 1 = transmitting

After MOX goes true, there is some delay required before valid samples are flowing back to the calibration functions. This delay can be adjusted, if desired, using the following call.

void SetPSMoxDelay (int channel, double delay)

channel: number of the channel being accessed

delay: delay to insert before beginning a calibration and after MOX is detected as being active (seconds)
[default = 0.1]

There is some delay between the two sample streams that must be compared to compute the calibration. This delay is partially due to time delay through the DAC and ADC; however, most of it is due to delay through the analog amplifier circuitry. This delay must be compensated in software to achieve optimum correction. For a solid-state amplifier, it will generally be in the range of 100ns to 1us and will depend upon the band of operation. The desired value of software delay compensation must be provided to the PureSignal software. That is done via the following call.

double SetPSTXDelay (int channel, double delay)

return value: the actual delay the PureSignal provides. The *exact* delay requested may not be available; so, the actual delay provided is returned for comparison.

channel: number of the channel being accessed

delay: desired delay in seconds

The peak magnitude value of the *returned* outbound sample stream (samples returned in the **tx** buffer for the **pssc(...)** call), i.e., the value when the samples have a value of 1.0 when leaving the TXA software, is a key parameter in computing the correction solution. This value will depend upon scaling in the DUC and DDC firmware/software. The following are calls to "set" this value, meaning to tell the PureSignal software what it is, and to "get" this value which is useful when the console needs to know the default value saved in TXA.

void SetPSHWPeak (int channel, double peak)

channel: number of the channel being accessed

peak: peak magnitude value

[default = 0.4072] Note: This is the value for the openHPSDR "old protocol" firmware.

void GetPSHWPeak (int channel, double* peak)

channel: number of the channel being accessed

peak: pointer to location to store the peak magnitude value

When testing new DUC/DDC firmware or software, it is also useful to be able to detect the measured peak magnitude. That is done using the following call. You may wish to call this repeatedly and display the result as it will increase until the maximum is found.

void GetPSMaxTX (int channel, double* maxtx)

channel: number of the channel being accessed

maxtx: pointer to location to store the maximum measured peak magnitude value

Certain amplifiers have a severe and slow memory effect when their power supply has very poor load regulation. In such cases, relaxing certain PureSignal calibration tolerances may allow calibration to proceed in situations where it otherwise will refuse to do so. A setting is provided for this purpose.

void SetPSPtol (int channel, double ptol)

channel: number of the channel being accessed

ptol: tolerance value. For normal amplifiers, a value of 0.8 is recommended. For "difficult" amplifiers, a value of 0.4 is recommended.

[default = 0.8]

Data points can be retrieved from PureSignal to produce a real-time display of the amplifier gain and phase curves (versus signal magnitude) and of the gain and phase correction curves that are being applied. This is done for the AmpView display available in the Thetis console application. This is accomplished with the following call.

void GetPSDisp (int channel, double* x, double* ym, double* yc, double* ys, double* cm, double* cc, double* cs)

channel: number of the channel being accessed

x: pointer to vector for magnitude value of the driving signal (0.0 to 1.0 range). These points are used as reference points to plot ym, yc, and ys data.

ym: pointer to vector for amplifier output magnitude

yc: pointer to vector for amplifier output cos (phase)

ys: pointer to vector for amplifier output sin (phase)

cm: pointer to vector for magnitude correction curve values

cc: pointer to vector for cos (phase) correction curve values

cs: pointer to vector for sin (phase) correction curve values

For each of **x**, **ym**, **yc**, and **ys**, 4096 values are returned.

For **cm**, **cc**, and **cs**, the nested-evaluation coefficients of 16-segment cubic splines are returned (64 values for each of **cm**, **cc**, and **cs**).

Pin-mode applies *a priori* knowledge of the required amplifier gain and phase correction in situations where the collected samples are insufficient for optimal calibration. This need can arise when the radio is not being properly driven to allow sample collection over the entire operating range, or due to some other fault or incorrect operation. This is very useful when there is a significant voltage regulation problem in an amplifier and, therefore, the gain and phase of the amplifier appear somewhat "unstable" as PureSignal collects feedback for calibration.

void SetPSPinMode (int channel, int pin)

channel: number of the channel being accessed

pin: 1 turns pin-mode ON; 0 turns pin-mode OFF
[default = 1]

Map-mode changes the sample-collection requirements to allow easier calibration in situations where the amplifier is detected to be in heavy gain compression. This is done by mapping the collection intervals to a different set of intervals based upon the level of compression. Note that this relaxation in sample-collection requirements MIGHT cause some degradation in high-order IMD. This is adaptive; the extent of the remapping depends upon the level of compression. If there is no compression, this function has no effect.

void SetPSMapMode (int channel, int map)

channel: number of the channel being accessed

map: 1 turns map-mode ON; 0 turns map-mode OFF
[default = 1]

Stbl-mode substantially separates the "static non-linearity" of the amplifier from the memory effects before computing the correction. This is a step toward further work on memory effects in a future release.

void SetPSStabilize (int channel, int stbl)

channel: number of the channel being accessed

stbl: 1 turns stbl-mode ON; 0 turns stbl-mode OFF
[default = 1]

Setting 'ints' and 'spi' to other than default values can be used to optimize performance. Since the code is currently set up to make all intervals of equal size, this can also be used to implement the "TINT" feature. "TINT" is a largely experimental feature allowing selection of the size of the upper interval within which samples are required to be collected. The dB value reflects the reduction from full-scale. For example, 2.5dB means ~75% of full-scale voltage or ~56% of full-scale power. This should normally be left at the default setting of 0.5dB (~94% of full-scale voltage and ~88% of full-scale power). This feature can be useful in situations where an external processing system, for example a Digital Audio Workstation, is used to precisely control the audio drive amplitude. Note, however, that Auto-Attenuate should probably be disabled when not driving to full-scale as there may not be enough information to accurately calculate its setting which can result in instability in the attenuator value.

void SetPSIntsAndSpi (int channel, int ints, int spi)

channel: number of the channel being accessed

ints: number of spline segments to use for the correction curves
[default = 16]

spi: number of samples to collect per spline segment
[default = 256]

CFIR Filter

A Compensating FIR (CFIR) filter is generally used in SDR situations where Cascaded Integrator Comb (CIC) filters are used in the Digital Up-Conversion (DUC) or Digital Down-Conversion (DDC) process. CIC filters are commonly used when the DUC or DDC is done in an FPGA as they require very few gates to implement. The CFIR is needed because the CIC filter has a downside that it does not have a flat passband. The CFIR offsets the "droop" in the CIC passband producing a flat frequency response for the combination of the CIC and CFIR. The CFIR can be implemented in either the FPGA or in software. A software implementation is provided here.

Note: For the openHPSDR "USB Protocol"/"Old Protocol", this software function is not used in TXA as it is performed in the FPGA firmware. However, for the openHPSDR "New Protocol", it is used in TXA.

NOTE: At this point, the only call provided for this CFIR in TXA is to turn it OFF/ON. However, there are a number of internal parameters used to specify the shape and characteristics of the filter. These parameters can be made externally available if we have different compensation needs in the future. The internal parameters are currently set to compensate for the CIC filters in the FPGA firmware of the openHPSDR "New Protocol". Key parameters are as follows:

- Input Sample Rate to this filter: **dsp_rate** (channel parameter)
- CIC Input Sample Rate: **output_samplerate** (channel parameter)
- CIC Differential Delay: 1
- CIC Interpolation Factor: 640
- CIC Integrator-Comb Pairs: 5

The following call is used to turn the CFIR OFF/ON.

void SetTXACFIRRun (int channel, int run

channel: number of the channel being accessed

run: 0 = OFF; 1 = ON
[default = 0]

TXA Collectives & General Controls

The following call sets the transmission MODE for TXA. This single call turns OFF/ON and provides certain required settings to blocks such as the AM and FM modulators.

void SetTXAMode (int channel, int mode)

channel: number of the channel being accessed

mode: 0 = LSB; 1 = USB; 2 = DSB; 5 = FM; 6 = AM; 7 = DIGU; 8 = SPEC; 9 = DIGL; 12 = AM_LSB; 13 = AM_USB. [default = 0]

The following collective is used to set the length of filter impulse responses within TXA. This is the **PREFERRED** method, compared to setting the filters individually.

void TXASetNC (int channel, int nc)

channel: number of the channel being accessed

nc: length of filter impulse responses. This must be a power-of-two and must be greater than or equal to the **dsp_size** currently in use.

The following collective is used to choose Linear Phase versus Low Latency for filters within TXA. This is the **PREFERRED** method, compared to setting the filters individually.

void TXASetMP (int channel, int mp)

channel: number of the channel being accessed

mp: 0 = Linear Phase; 1 = Low Latency (Minimum Phase).

Panadapter & Other Frequency-Domain Displays

WDSP contains functionality to accept raw wide-bandwidth time-domain samples and, from them, repetitively create the data ("pixel values") for panadapter displays and other frequency-domain displays. This full-featured implementation includes support for:

- combining or interpolating FFT output bins, as needed, to create a requested number of pixel values across the screen,
- symmetrical and asymmetrical clipping to support pan and zoom functionality,
- multiple averaging modes,
- multiple detectors (peak, average, rosenfell, and sample),
- normalization to a one Hertz bandwidth for noise measurements,
- multiple pixel outputs for the same input data set, for example, the panadapter and waterfall can be using different averaging modes,
- software spur elimination for spectrum analyzer applications,
- stitched display for viewing a spectrum exceeding the bandwidth of a single sample stream,
- both real and complex input samples,
- a selection of window functions used to window the input data, and
- curve-fitted amplitude calibration facilities.

Instances of such "Displays" are not created within RXA or TXA. These Displays must be separately instantiated. A typical scenario would be to create one Display for each RXA and for each TXA channel and also perhaps one Display for each ADC such that a view can simultaneously be provided for the entire frequency spectrum digitized by the ADC. However, if computing resources are constrained, it is also possible to create less Displays and share them among multiple views. For example, a single Display could be shared between being a panadapter during receive and displaying the frequency spectrum of the out-going transmitted signal during transmit.

The display code was originally written for a different project with different objectives and was then later included within WDSP. Therefore, there are some style differences between this Display code and the rest of WDSP. Expect that this code is likely to become more similar to the rest of WDSP over time, as development time permits.

The Display unit receives calls to set various parameters, to provide it with input data, and to retrieve "pixel values" from it. These calls to a Display unit may be made from either within an RXA or TXA channel or from outside WDSP entirely, depending upon the needs. For example, one of the supported features of the Display is to "stitch" multiple sub-spectra together to create a view of a wider received spectrum. However, a WDSP channel only supports the receipt of one continuous sample stream. Since stitching requires multiple continuous sample streams, calls to supply the input data to the Display would generally be made outside of the WDSP channel. On the other hand, for a view of the Spectrum data after the bandpass filter, the call to supply input data to the Display would need to be made within the WDSP channel.

Creating and Destroying a Display

Creating a display consists of allocating all the resources it requires. These resources are a function of things like the maximum FFT size to be used, the maximum number of LO positions to be used for spur elimination (a spectrum analyzer feature), and the maximum number of sub-spans to be stitched together to form the complete spectrum. A Display is created using the call:

```
void XCreateAnalyzer (int disp, int* success, int m_size, int m_LO, int m_stitch, char* app_data_path)
```

disp: number/identifier of the Display being created. This value currently ranges from 0 through 63. If one display is to be created per DSP channel, it may prove convenient to have the 'disp' value match the channel identifier.

success: a pointer to a return value that will be zero if the display has been successfully created.

m_size: the maximum FFT size to be used. The WDSP Wisdom calculations must include any selected values and currently calculate power-of-two values through 262144. This value must be a power-of-two.

m_LO: the maximum number of Local Oscillator positions to be used for spur elimination. This is a spectrum analyzer feature that provides comparison of spectra produced from multiple LO frequencies to automatically eliminate spurious responses. For non-spectrum-analyzer use, set this to 1.

m_stitch: the maximum number of sub-spans that will be stitched together to create a single spectrum to be displayed. For example, if no more than three firmware receiver sample streams are to be used to create a single display, set this to 3.

app_data_path: not used.

When the display is no longer needed, for example when the host application is preparing to close, its resources are freed using this call:

```
void DestroyAnalyzer (int disp)
```

disp: the identifier of the Display whose resources are to be freed.

Setting Display Parameters

The `SetAnalyzer(...)` call is used to set many of the parameters for the display unit.

```
void SetAnalyzer (int disp, int n_pixout, int n_fft, int typ, int* flp, int sz, int bf_sz, int win_type, double pi, int ovrlp, int clp, int fscLin, int fscHin, int n_pix, int n_stch, int calset, double fmin, double fmax, int max_w)
```

disp: the identifier of the Display whose parameters are to be set.

n_pixout: the number of pixel outputs being used. For example, this could be 1 if the same pixel-value data is to be used for the panadapter and waterfall; or, it could be 2 if different detectors or averaging modes are desired for the panadapter and waterfall.

n_fft: the number of LO positions to be used for spur elimination (a spectrum analyzer feature). This should be set to 1 if spur elimination is not being used.

typ: specifies whether REAL or COMPLEX sample data is to be provided. 0 for REAL which must be delivered in the 'I' channel; 1 for COMPLEX which will be delivered in I and Q channels.

flp: pointer to a vector with one element per LO frequency. The elements are used to specify whether the LO frequencies are on the low side or high side of the operating range. For non-SA use, this will be a single element with a value of 0. For example:

```
int[] flp = { 0 };
```

sz: size of the FFT to be used. This must be a power of two.

bf_sz: number of samples to be provided each time a call to provide input samples is made.

win_type: is used to specify the type of window function to be used for processing. Beginning with 0, assignments are: Rectangular, 4-term Blackman-Harris, Hann, Flat-top, Hamming, Kaiser, 7-term Blackman-Harris. For general purpose use, 5 (Kaiser) and 6 (7-term Blackman-Harris) are good choices. For best amplitude accuracy, use 3 (Flat-top).

pi: parameter used to shape the Kaiser window function. 14.0 is a reasonable default value.

ovrlp: the number of samples to be re-used from the previous FFT. For SA use, overlap can reveal transient signals that may otherwise not be displayed. For general purpose radio use, overlap allows the display frame-rate to be independent of the sample-rate. For example, at an FFT size of 262144 and a sample rate of 192000, it takes over one second to capture enough samples for an entirely new display frame. However, by re-using some number of samples from the previous FFT, we can create new frames at a much faster rate and have an interactive display. Overlap can be calculated as:

```
//set overlap as needed to achieve the desired frame_rate
overlap = (int)Math.Max(0.0, Math.Ceiling(fft_size - (double)sample_rate /
    (double)frame_rate));
```

where 'frame_rate' is in frames/second.

clp: the number of FFT bins to be (symmetrically) clipped from each side of each sub-span. Preceding firmware decimation filters (in either FPGA firmware or Direct Fourier Conversion code) are not perfectly rectangular --- they have a roll-off on each side of the spectrum. It is generally not desirable to display the roll-off area, especially if stitching is to be used. A primary use of this capability is to clip off those bins. The value for 'clp' can generally be set by specifying some fraction of the spectrum to be clipped on each side. For example:

```
//fraction of the spectrum to clip off each side of each sub-span
const double CLIP_FRACTION = 0.017;
//clip is the number of bins to clip off each side of each sub-span
clp = (int)Math.Floor(CLIP_FRACTION * fft_size);
```

fscLin: the number of bins to clip from low side of the entire (stitched) span. This parameter can be used along with **fscHin** to PAN and ZOOM within the spectrum represented by the entire stitched span. Based upon PAN and ZOOM settings, these parameters can be set as follows:

```
//the amount of frequency in each fft bin (for complex samples) is given
//by:
double bin_width = (double)sample_rate / (double)fft_size;

//the number of useable bins per subspan is
int bins_per_subspan = fft_size - 2 * clp;

//the amount of useable bandwidth we get from each subspan is:
bw_per_subspan = bins_per_subspan * bin_width;

//the total number of bins available to display is:
int bins = stitches * bins_per_subspan;

//apply log function to zoom slider value
double zoom_slider = Math.Log10(9.0 * z_slider + 1.0);

//limits how much you can zoom in; higher value means you zoom more
const double zoom_limit = 100;

int width = (int)(bins * (1.0 - (1.0 - 1.0 / zoom_limit) * zoom_slider));

//FSCLIPL is 0 if pan_slider is 0; it's bins-width if pan_slider is 1
//FSCLIPH is bins-width if pan_slider is 0; it's 0 if pan_slider is 1
fscLin = (int)Math.Floor(pan_slider * (bins - width));
fscHin = bins - width - span_clip_l;
```

fscHin: See above comments about fscLin.

n_pix: number of pixel values to be retrieved upon each call to retrieve pixels, i.e., the width, in pixels, of the window in which the results are to be displayed.

n_stch: number of sub-spans to be stitched. If only one DDC is to be used, this is 1. If, for example, the sample streams from 3 DDCs are to be stitched, this is 3.

calset: specifies which of multiple sets of calibration data is to be used to adjust signal amplitude across the range of the spectrum. If the calibration feature is not in use, set this value to 0.

fmin: the minimum frequency of the span (used for calibration). If calibration is not in use, set this value to 0.0.

fmax: the maximum frequency of the span (used for calibration). If calibration is not in use, set this value to 0.0.

max_w: a parameter used to determine how much data will be held in display buffers. It is calculated as:

```
const double KEEP_TIME = 0.1;
max_w = fft_size + (int)Math.Min(KEEP_TIME * sample_rate, KEEP_TIME *
    fft_size * frame_rate);
```

When the calibration feature is used, the following call is to set the calibration data. A table is to be provided with two columns, (0) frequency and (1) the calibration multipliers corresponding to those frequencies. The 'calibration multipliers' are NOT dB values to be added, they are linear multipliers. This table is interpolated using a cubic spline to create a smooth calibration curve.

void SetCalibration (int disp, int set_num, int n_points, double(* cal)[2])

disp: the identifier of the Display whose calibration is being set.

set_num: the identifier for this calibration data set.

n_points: the number of calibration points in the set; i.e., the number of rows in the following table.

cal: pointer to the table of calibration data.

The following call is used to select the detector-type for a particular Display and Pixel Output from that Display. The positive-peak detector is the best selection for measuring the amplitude of a signal. The average and sample detectors are provided specifically for noise measurements and the output is adjusted for the chosen window's equivalent noise bandwidth when using these two detectors. The rosenfell detector is common in spectrum analyzers and gives an indication of both signal and noise.

void SetDisplayDetectorMode (int disp, int pixout, int mode)

disp: identifier for the Display.

pixout: identifier of the pixel output for which the detector is being set.

mode: detector mode. 0 = positive peak; 1 = rosenfell; 2 = average/"rms"; 3 = sample.

The following call is used to select the averaging-mode for a particular Display and Pixel Output from that Display.

void SetDisplayAverageMode (int disp, int pixout, int mode)

disp: identifier for the Display.

pixout: identifier of the pixel output for which the averaging mode is being set.

mode: averaging mode. -1 = peak-hold; 0 = no averaging; 1 = weighted averaging of linear data; 2 = time-window averaging of linear data; 3 = weighted averaging of log data. This last mode, weighted averaging of log data, looks nice on the panadapter log scale; however, it is not mathematically accurate for time-varying signals or noise measurements.

When time-window averaging of data is used, the number of display frames to average needs to be specified. The following call performs that operation.

void SetDisplayNumAverage (int disp, int pixout, int num)

disp: identifier for the Display.

pixout: identifier of the pixel output for which the value is being set.

num: number of frames to average.

When weighted averaging is used, a multiplier value must be supplied. Averaging then proceeds as:
$$\text{new_display_value} = \text{mult} * \text{old_display_value} + (1.0 - \text{mult}) * \text{new_pixel_value};$$

void SetDisplayAvBackmult (int disp, int pixout, double mult)

disp: identifier for the Display.

pixout: identifier of the pixel output for which the value is being set.

mult: multiplier value.

The display code must know the sample-rate of the input data to be able to normalize measurements to a 1.0 Hz bandwidth, when desired. The bandwidth is set by:

void SetDisplaySampleRate (int disp, int rate)

disp: identifier for the Display.

rate: sample-rate (samples per second).

Pixel values will be normalized to a 1.0 Hz bandwidth if '**norm**' is set to 1.

void SetDisplayNormOneHz (int disp, int pixout, int norm)

disp: identifier for the Display.

pixout: identifier of the pixel output for which the parameter is being set.

norm: 0 = do not normalize; 1 = normalize to one Hz bandwidth.

Supplying Input Data

Several input functions have been developed over time to meet varying console needs.

When I and Q are kept in separate buffers, as opposed to being interleaved in a single buffer, use the `Spectrum(...)` call. Note that the type of the I/Q data is specified as `dINREAL` which is defined as either `double` or `float` in the file "comm.h".

`void Spectrum (int disp, int ss, int LO, dINREAL* pI, dINREAL* pQ)`

disp: identifier for the Display.

ss: sub-span (of a stitched display) for which data is being supplied. If stitching is not being used, ss = 0.

LO: LO position for which data is being supplied. (for Spectrum Analyzer software spur removal)
If spur removal is not being used, LO = 0.

pI: pointer to the array of I values

pQ: pointer to array of Q values

When I and Q are interleaved in a single buffer, one generally uses the `Spectrum2(...)` call. Note that the type of the I/Q data is specified as `dINREAL` which is defined as either `double` or `float` in the file "comm.h".

`void Spectrum2 (int run, int disp, int ss, int LO, dINREAL* pbuff)`

run: 0 = ignore input data and return; 1 = copy input data from pbuff and process.

disp: identifier for the Display.

ss: sub-span (of a stitched display) for which data is being supplied. If stitching is not being used, ss = 0.

LO: LO position for which data is being supplied. (for Spectrum Analyzer software spur removal)
If spur removal is not being used, LO = 0.

pbuff: pointer to the array of interleaved I/Q values

In the event interleaved I/Q data is to be supplied as `double`, but because float data is at times being supplied from elsewhere `dINREAL` is defined as `float`, the `Spectrum0(...)` call may be used.

`void Spectrum0 (int run, int disp, int ss, int LO, double* pbuff)`

run: 0 = ignore input data and return; 1 = copy input data from pbuff and process.

disp: identifier for the Display.

ss: sub-span (of a stitched display) for which data is being supplied. If stitching is not being used, ss = 0.

LO: LO position for which data is being supplied. (for Spectrum Analyzer software spur removal)
If spur removal is not being used, LO = 0.

pbuff: pointer to the array of interleaved I/Q values

Retrieving Pixel Values

As previously discussed, new frames of data are calculated periodically based upon several settings. Pixel values should be periodically retrieved, at this same desired frame-rate, using `GetPixels(...)`. If new data is available (indicated by `flag = 1`), it should be drawn. If not, check again later -- nothing new to draw now.

void GetPixels (int disp, int pixout, dOUTREAL* pix, int* flag)

disp: identifier for the Display.

pixout: identifier of the pixel output from which pixel values are to be retrieved.

pix: pointer to buffer into which the pixel values (dBm) will be placed.

flag: pointer to an integer that will be set to 1 if new data was available and will be set to 0 if no new data was available.

Blocks Used Outside Channels

There are several blocks included with the WDSP library that are often utilized OUTSIDE of the WDSP channels. Instantiating and accessing those blocks is discussed here.

Preemptive Wideband Noise Blanker

Noise blankers attempt to remove "impulse noise", brief time-domain impulses imposed upon the I-Q sample data. These impulses are often caused by things like power line arcing and may or may not be repetitive in nature. To remove these impulses, noise blankers must do two things: (1) detect the samples that have been corrupted by the impulses, and (2) replace those samples with some estimate of the original signal.

In the case of the Preemptive Wideband Noise Blanker, detection is done by comparing the power contained in each sample with the time-averaged power across the wide bandwidth seen by the blanker. "Wideband" implies that the sample stream has a high enough sample-rate to support the bandwidth of roughly the size of a typical amateur band, for example, a few hundred Khz for HF operation. Processing a wider bandwidth in the blanker has little if any benefit since the input bandwidth is usually restricted anyway by input bandpass filters or by the bandwidth of the antenna itself.

Correction, in this blanker, is done by replacing a sequence of samples believed to be corrupt with an estimate value of zero. However, there are several other considerations.

- We should not transition instantaneously from the uncorrupted signal level to zero and from zero back to the uncorrupted signal level; this would create a disturbance in the frequency spectrum and audible clicks.
- The leading and trailing edges of the impulse may not be detected even though the higher magnitude center is. Therefore, we may wish to "advance" the blanking to before the detected impulse and "hang" onto the blanking slightly after the impulse appears to have passed.

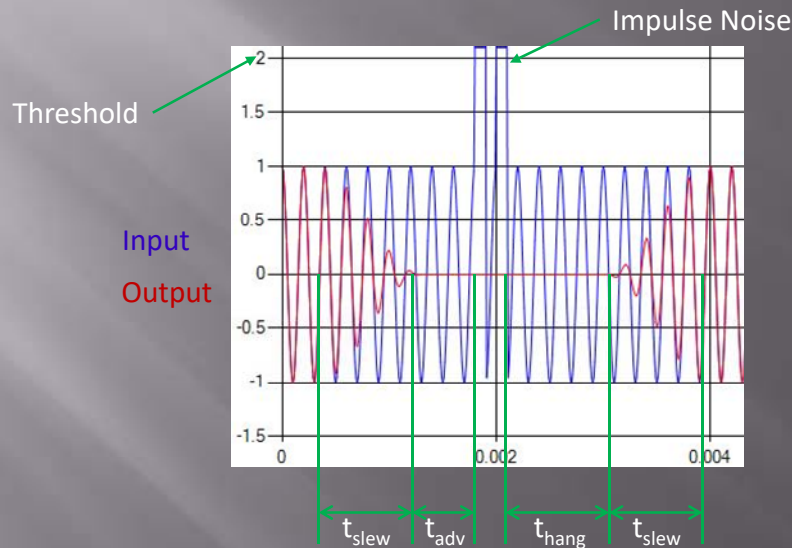
The following figure illustrates the operation of the Preemptive Wideband Noise Blanker. Signal amplitude slewing to zero and back, as well as advance and hang times are illustrated. Note also that the threshold at which a sample is judged to be part of an impulse is adjustable.

It is desirable to have the wideband blankers also affect the panadapter and waterfall displays. Since the data input for these occurs outside an RXA channel, the wideband blanker must be called from outside an RXA channel also.



PREEMPTIVE WIDEBAND BLANKER "NB"

NR	ANF
NB	SNB
MUT	BIN
MNF	



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There are two sets of calls that can be used to access the Preemptive Wideband Blanker:

- 1) When coding in C, one may include the "nob.h" header file and use calls that directly reference the pointer to the noise blunker data structure which is of type **ANB**. The 'create' function, creating an instance of the blunker, returns a pointer of type **ANB** and then this pointer is subsequently used in all communications with this instance of the blunker.
- 2) The more general set of calls requires the specification of an integer 'identifier' in the call to the create function. This identifier is then subsequently used in all communications with this same instance of the blunker.

Pointer-Based Calls

A blunker is instantiated (its resources are allocated and default values set) using the following call.

ANB create_anb (int run, int bufsize, double* in, double* out, double samplerate, double tau, double hangtime, double advtime, double backtau, double threshold)

run: default value of the **run** variable. 0 = OFF; 1 = ON. When this block is turned OFF, the input buffer is copied to the output buffer in the event the buffers are not the same.

buffsize: default number of complex I-Q samples in the input buffer.

in: default pointer to the input buffer.

out: default pointer to the output buffer which may be the same as the input buffer.

samplerate: default sample-rate.

tau: default duration (seconds) of the raised-cosine transitions between normal signal levels and the zero estimate during an impulse, t_{slew} . 0.0001 is a reasonable starting value, depending upon sample-rate.

hangtime: default hang-time, t_{hang} (seconds). 0.0001 is a reasonable starting value, depending upon sample-rate.

advtime: default advance-time, t_{adv} (seconds). 0.0001 is a reasonable starting value, depending upon sample-rate.

backtau: default time-constant for averaging power across the wide bandwidth. 0.05 is a reasonable starting value.

threshold: default threshold. A sample is judged to be part of an impulse if its magnitude is greater than $\text{threshold} * \text{average_power}$. An appropriate range for threshold is approximately 15.0 to 500.0. If **threshold** is too low, normal signals may be wrongly identified as impulse noise. If it is too high, successful detection will not occur.

Resources are freed using the following call.

void destroy_anb (ANB a)

a: pointer to the blanker data structure.

Note: This call must not be executed while data is flowing, i.e., while the execute function is being called.

Buffers are flushed of stale data and indexes are re-initialized using the following call.

void flush_anb (ANB a)

a: pointer to the blanker data structure.

Note: This call must not be executed while data is flowing, i.e., while the execute function is being called.

A buffer of input data is processed and a buffer of output data written using the following call.

void xanb (ANB a)

a: pointer to the blanker data structure.

Various parameters are reset using the following calls. Unless otherwise noted, these following calls may be made at any time including while data is flowing.

void setBuffers_anb (ANB a, double* in, double* out)

a: pointer to the blanker data structure.

in: pointer to the input buffer.

out: pointer to the output buffer which may be the same as the input buffer.

Note: This call must not be executed while data is flowing, i.e., while the execute function is being called.

void setSamplerate_anb (ANB a, int rate)

a: pointer to the blanker data structure.

rate: sample-rate.

Note: This call must not be executed while data is flowing, i.e., while the execute function is being called.

void setSize_anb (ANB a, int size)

a: pointer to the blanker data structure.

size: number of complex I-Q samples in the input buffer.

Note: This call must not be executed while data is flowing, i.e., while the execute function is being called.

void pSetRCVRANBRun (ANB a, int run)

a: pointer to the blanker data structure.

run: 0 = OFF, 1 = ON. When OFF, the input buffer will be copied to the output buffer if they are not the same.

void pSetRCVRANBTau (ANB a, double tau)

a: pointer to the blanker data structure.

tau: duration (seconds) of the raised-cosine transitions between normal signal levels and the zero estimate during an impulse, t_{slew} .

void pSetRCVRANBHangtime (ANB a, double time)

a: pointer to the blanker data structure.

time: hang-time, t_{hang} (seconds).

void pSetRCVRANBAdvtime (ANB a, double time)

a: pointer to the blanker data structure.

time: advance-time, t_{adv} (seconds).

void pSetRCVRANBBacktau (ANB a, double tau)

a: pointer to the blanker data structure.

tau: time-constant for averaging power across the wide bandwidth.

void pSetRCVRANBThreshold (ANB a, double thresh)

a: pointer to the blanker data structure.

thresh: detection threshold. (See explanation above in description of 'create' call.)

Identifier-Based Calls

A blanker is instantiated (its resources are allocated and default values set) using the following call.

ANB create_anbEXT (int id, int run, int buffsize, double samplerate, double tau, double hangtime, double advtime, double backtau, double threshold)

id: an integer value used as the identifier for this instance of the blanker. The number of blankers is currently restricted (by the setting of an internal variable) to 32. Correspondingly, identifiers must be in the range 0 through 31.

run: default value of the **run** variable. 0 = OFF; 1 = ON. When this block is turned OFF, the input buffer is copied to the output buffer in the event they are not the same.

buffsize: default number of complex I-Q samples in the input buffer.

samplerate: default sample-rate.

tau: default duration (seconds) of the raised-cosine transitions between normal signal levels and the zero estimate during an impulse, t_{slew} . 0.0001 is a reasonable starting value, depending upon sample-rate.

hangtime: default hang-time, t_{hang} (seconds). 0.0001 is a reasonable starting value, depending upon sample-rate.

advtime: default advance-time, t_{adv} (seconds). 0.0001 is a reasonable starting value, depending upon sample-rate.

backtau: default time-constant for averaging power across the wide bandwidth. 0.05 is a reasonable starting value.

threshold: default threshold. A sample is judged to be part of an impulse if its magnitude is greater than **threshold*average_power**. An appropriate range for threshold is approximately 15.0 to 500.0. If threshold is too low, normal signals may be wrongly identified as impulse noise. If it is too high, successful detection will not occur.

Resources are freed using the following call.

void destroy_anbEXT (int id)

id: identifier for this instance of the blanker.

Note: This call must not be executed while data is flowing, i.e., while the execute function is being called.

Buffers are flushed of stale data and indexes are re-initialized using the following call.

void flush_anbEXT (int id)

id: identifier for this instance of the blanker.

Note: This call must not be executed while data is flowing, i.e., while the execute function is being called.

A buffer of input data is processed and a buffer of output data written using the following call.

void xanbEXT (int id, double* in, double* out)

id: identifier for this instance of the blanker.

in: pointer to the input buffer.

out: pointer to the output buffer which may be the same as the input buffer.

Various parameters are reset using the following calls. Unless otherwise noted, these following calls may be made at any time including while data is flowing.

void SetEXTANBRun (int id, int run)

id: identifier for this instance of the blanker.

run: 0 = OFF, 1 = ON. When OFF, the input buffer will be copied to the output buffer if they are not the same.

void SetEXTANBSamplerate (int id, int rate)

id: identifier for this instance of the blanker.

rate: sample-rate.

void SetEXTANBBuffersize (int id, int size)

id: identifier for this instance of the blanker.

size: number of complex I-Q samples in the input buffer.

void SetEXTANBTau (int id, double tau)

id: identifier for this instance of the blanker.

tau: duration (seconds) of the raised-cosine transitions between normal signal levels and the zero estimate during an impulse, t_{slew} .

void SetEXTANBHangtime (int id, double time)

id: identifier for this instance of the blanker.

time: hang-time, t_{hang} (seconds).

void SetEXTANBAdvtime (int id, double time)

id: identifier for this instance of the blanker.

time: advance-time, t_{adv} (seconds).

void SetEXTANBBacktau (int id, double tau)

id: identifier for this instance of the blanker.

tau: time-constant for averaging power across the wide bandwidth.

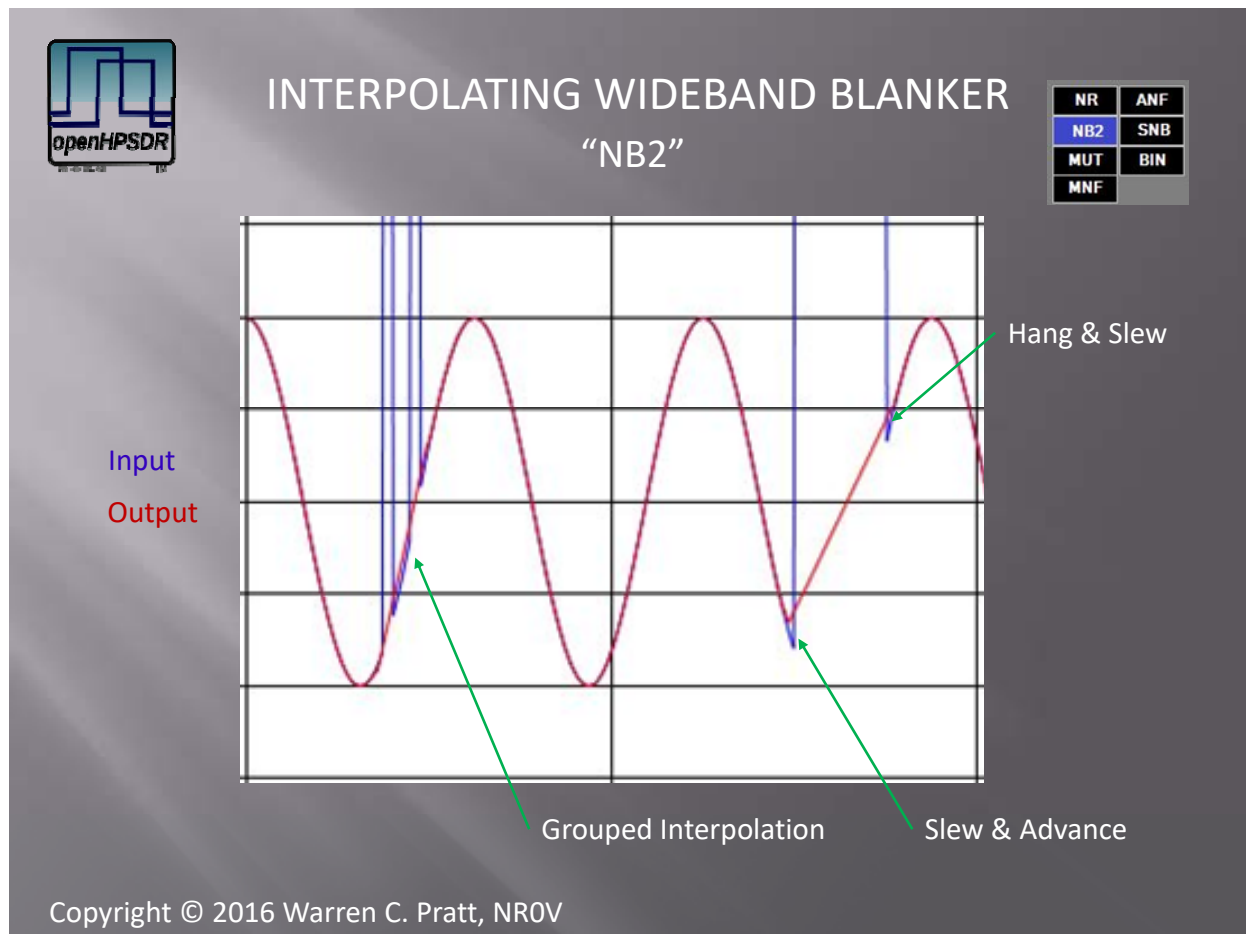
void SetEXTANBANBThreshold (int id, double thresh)

id: identifier for this instance of the blanker.

thresh: detection threshold. (See explanation above in description of 'create' call.)

Interpolating Wideband Noise Blanker

The Interpolating Wideband Noise Blanker is similar to the Preemptive Wideband Noise Blanker except that it has additional modes to estimate the original signal, rather than just estimating it as zero as is done by the Preemptive Wideband Noise Blanker. As shown in the following figure, it can do things like interpolate across impulses as its estimate of the original signal.



There are two sets of calls that can be used to access the Interpolating Wideband Blanker:

- 1) When coding in C, one may include the "nobll.h" header file and use calls that directly reference the pointer to the noise blanker data structure which is of type **NOB**. The 'create' function, creating an instance of the blanker, returns a pointer of type **NOB** and then this pointer is subsequently used in all communications with this instance of the blanker.
- 2) The more general set of calls requires the specification of an integer 'identifier' in the call to the create function. This identifier is then subsequently used in all communications with this same instance of the blanker.

Pointer-Based Calls

A blanker is instantiated (its resources are allocated and default values set) using the following call.

NOB create_nob (int run, int buffsize, double* in, double* out, double samplerate, int mode, double advslevertime, double advtime, double hangslevertime, double hangtime, double max_imp_seq_time, double backtau, double threshold)

run: default value of the **run** variable. 0 = OFF; 1 = ON. When this block is turned OFF, the input buffer is copied to the output buffer in the event they are not the same.

buffsize: default number of complex I-Q samples in the input buffer.

in: default pointer to the input buffer.

out: default pointer to the output buffer which may be the same as the input buffer.

samplerate: default sample-rate.

mode: default mode. **mode** determines what estimate values are used for the sequence of corrupt samples to be replaced. 0 = zero mode (estimate as zero); 1 = sample-hold (take the value of non-corrupt signal at the beginning of the impulse and hold that throughout the corrupt sequence); 2 = mean-hold (average the non-corrupt values at the beginning and end of the corrupt sequence and use that as the estimate during the corrupt sequence); 3 = hold-sample (take the value of non-corrupt signal at the end of the impulse and hold that throughout the corrupt sequence); 4 = linearly interpolate across the corrupt sequence.

advslevertime: default time (seconds) to slew from the non-corrupt signal before the advance time. 0.0001 is a reasonable initial value for typical sample rates.

advtime: default advance time (seconds). 0.0001 is a reasonable initial value for typical sample rates.

hangslevertime: default time (seconds) to slew after the hang time back to the non-corrupt signal. 0.0001 is a reasonable initial value for typical sample rates.

hangtime: default hang time (seconds). 0.0001 is a reasonable initial value for typical sample rates.

max_imp_seq_time: default maximum amount of time (seconds) across which a closely spaced sequence of impulses will be evaluated. 0.025 is a reasonably conservative value.

backtau: default time-constant for averaging power across the wide bandwidth. 0.05 is a reasonable starting value.

threshold: default threshold. A sample is judged to be part of an impulse if its magnitude is greater than **threshold*average_power**. An appropriate range for threshold is approximately 15.0 to 500.0. If threshold is too low, normal signals may be wrongly identified as impulse noise. If it is too high, successful detection will not occur.

Resources are freed using the following call.

void destroy_nob (NOB a)

a: pointer to the blanker data structure.

Note: This call must not be executed while data is flowing, i.e., while the execute function is being called.

Buffers are flushed of stale data and indexes are re-initialized using the following call.

void flush_nob (NOB a)

a: pointer to the blanker data structure.

Note: This call must not be executed while data is flowing, i.e., while the execute function is being called.

A buffer of input data is processed and a buffer of output data written using the following call.

void xnob (NOB a)

a: pointer to the blanker data structure.

Various parameters are reset using the following calls. Unless otherwise noted, these following calls may be made at any time including while data is flowing.

void setBuffers_nob (NOB a, double* in, double* out)

a: pointer to the blanker data structure.

in: pointer to the input buffer.

out: pointer to the output buffer which may be the same as the input buffer.

Note: This call must not be executed while data is flowing, i.e., while the execute function is being called.

void setSamplerate_nob (NOB a, int rate)

a: pointer to the blanker data structure.

rate: sample-rate.

Note: This call must not be executed while data is flowing, i.e., while the execute function is being called.

void setSize_nob (NOB a, int size)

a: pointer to the blanker data structure.

size: number of complex I-Q samples in the input buffer.

Note: This call must not be executed while data is flowing, i.e., while the execute function is being called.

void pSetRCVRNOBRun (NOB a, int run)

a: pointer to the blanker data structure.

run: 0 = OFF, 1 = ON. When OFF, the input buffer will be copied to the output buffer if they are not the same.

void pSetRCVRNOBMode (NOB a, int mode)

a: pointer to the blanker data structure.

mode: **mode** determines what estimate values are used for the sequence of corrupt samples to be replaced. 0 = zero mode (estimate as zero); 1 = sample-hold (take the value of non-corrupt signal at the beginning of the impulse and hold that throughout the corrupt sequence); 2 = mean-hold (average the non-corrupt values at the beginning and end of the corrupt sequence and use that as the estimate during the corrupt sequence); 3 = hold-sample (take the value of non-corrupt signal at the end of the impulse and hold that throughout the corrupt sequence); 4 = linearly interpolate across the corrupt sequence.

void pSetRCVRNOBTau (NOB a, double tau)

a: pointer to the blanker data structure.

tau: the duration (seconds) of both the **advsl Lewtime** and **hangsl Lewtime** are set to **tau**.

void pSetRCVRNOBHangtime (NOB a, double time)

a: pointer to the blanker data structure.

time: hang-time, t_{hang} (seconds).

void pSetRCVRNOBAdvtime (NOB a, double time)

a: pointer to the blanker data structure.

time: advance-time, t_{adv} (seconds).

void pSetRCVRNOBBacktau (NOB a, double tau)

a: pointer to the blanker data structure.

tau: time-constant for averaging power across the wide bandwidth.

void pSetRCVRNOBThreshold (NOB a, double thresh)

a: pointer to the blanker data structure.

thresh: detection threshold. (See explanation above in description of 'create' call.)

Identifier-Based Calls

A blanker is instantiated (its resources are allocated and default values set) using the following call.

NOB create_nobEXT (int id, int run, int mode, int buffsize, double samplerate, double slevertime, double hangtime, double advtime, double backtau, double threshold)

id: an integer value used as the identifier for this instance of the blanker. The number of blankers is currently restricted (by the setting of an internal variable) to 32. Correspondingly, identifiers must be in the range 0 through 31.

run: default value of the **run** variable. 0 = OFF; 1 = ON. When this block is turned OFF, the input buffer is copied to the output buffer in the event they are not the same.

mode: default mode. **mode** determines what estimate values are used for the sequence of corrupt samples to be replaced. 0 = zero mode (estimate as zero); 1 = sample-hold (take the value of non-corrupt signal at the beginning of the impulse and hold that throughout the corrupt sequence); 2 = mean-hold (average the non-corrupt values at the beginning and end of the corrupt sequence and use that as the estimate during the corrupt sequence); 3 = hold-sample (take the value of non-corrupt signal at the end of the impulse and hold that throughout the corrupt sequence); 4 = linearly interpolate across the corrupt sequence.

buffsize: default number of complex I-Q samples in the input buffer.

samplerate: default sample-rate.

slevertime: default duration (seconds) of both the slew before advance time and the slew after hang time.

hangtime: default hang-time, t_{hang} (seconds).

advtime: default advance-time, t_{adv} (seconds).

backtau: default time-constant for averaging power across the wide bandwidth.

threshold: default threshold. A sample is judged to be part of an impulse if its magnitude is greater than **threshold*****average_power**.

Resources are freed using the following call.

void destroy_nobEXT (int id)

id: identifier for this instance of the blanker.

Note: This call must not be executed while data is flowing, i.e., while the execute function is being called.

Buffers are flushed of stale data and indexes are re-initialized using the following call.

void flush_nobEXT (int id)

id: identifier for this instance of the blanker.

Note: This call must not be executed while data is flowing, i.e., while the execute function is being called.

A buffer of input data is processed and a buffer of output data written using the following call.

void xnobEXT (int id, double* in, double* out)

id: identifier for this instance of the blanker.

in: pointer to the input buffer.

out: pointer to the output buffer which may be the same as the input buffer.

Various parameters are reset using the following calls. Unless otherwise noted, these following calls may be made at any time including while data is flowing.

void SetEXTNOBRun (int id, int run)

id: identifier for this instance of the blanker.

run: 0 = OFF, 1 = ON. When OFF, the input buffer will be copied to the output buffer if they are not the same.

void SetEXTNOBMode (int id, int mode)

id: identifier for this instance of the blanker.

mode: **mode** determines what estimate values are used for the sequence of corrupt samples to be replaced. 0 = zero mode (estimate as zero); 1 = sample-hold (take the value of non-corrupt signal at the beginning of the impulse and hold that throughout the corrupt sequence); 2 = mean-hold (average the non-corrupt values at the beginning and end of the corrupt sequence and use that as the estimate during the corrupt sequence); 3 = hold-sample (take the value of non-corrupt signal at the end of the impulse and hold that throughout the corrupt sequence); 4 = linearly interpolate across the corrupt sequence.

void SetEXTNOBSamplerate (int id, int rate)

id: identifier for this instance of the blanker.

rate: sample-rate.

void SetEXTNOBBufferSize (int id, int size)

id: identifier for this instance of the blanker.

size: number of complex I-Q samples in the input buffer.

void SetEXTNOBTau (int id, double tau)

id: identifier for this instance of the blanker.

tau: the duration (seconds) of both the **advslawtime** and **hangslawtime** are set to **tau**.

void SetEXTNOBHangtime (int id, double time)

id: identifier for this instance of the blanker.

time: hang-time, t_{hang} (seconds).

void SetEXTNOBAdvtime (int id, double time)

id: identifier for this instance of the blanker.

time: advance-time, t_{adv} (seconds).

void SetEXTNOBBacktau (int id, double tau)

id: identifier for this instance of the blanker.

tau: time-constant for averaging power across the wide bandwidth.

void SetEXTANBNOBThreshold (int id, double thresh)

id: identifier for this instance of the blanker.

thresh: detection threshold. (See explanation above in description of 'create' call.)

Resampler

Resamplers are used to convert from one sample-rate to another sample-rate. Conceptually, the resamplers provided here accomplish this by finding a least common multiple of the input and output frequencies, interpolating up to this least common multiple, and then decimating down from this least common multiple. In the actual computations, care was taken not to perform operations for samples that, in the end, will be discarded anyway.

Resamplers are used within the RXA and TXA channels. However, they are also often useful within various other parts of the application to convert either complex I-Q or simple audio samples from one rate to another.

PROGRAMMING NOTE: There are two sets of calls that can be used to each of the below-described resamplers.

- 1) When calling from the C language, one can include the "resample.h" header file, use a 'create' call that returns a pointer of the native **RESAMPLE** (for the Complex Double-Precision Resampler) or **RESAMPLEF** (Non-Complex Single-Precision Resampler) pointer type, and then use that pointer to identify the resampler data structure in future references.
- 2) When calling from another language, or when it is not desirable to include the "resample.h" header file, there are calls that return and use pointers that have been cast to type **void***. This was originally done for historical reasons and this author acknowledges that there are potential problems with this approach. With limited exceptions, the C standard does NOT guarantee that pointers to different types will be of the same length or structure. Therefore, pointer type conversions back and forth cannot be guaranteed. This situation is even more questionable when multiple languages are involved. Practically, on common architectures in use and using common tools, this generally works out OK. However, please beware!

Complex Double-Precision Resampler

As the title implies, this resampler is for complex I-Q samples of double-precision floating-point values.

Native Pointers

The resampler is created (its resources allocated), destroyed (its resources freed), flushed (data cleared from buffers and indexes reset), and executed using the following four calls, respectively.

RESAMPLE **create_resample** (**int** run, **int** size, **double*** in, **double*** out, **int** in_rate, **int** out_rate, **double** fc, **int** ncoef, **double** gain)

return value: The return value is a pointer of type **RESAMPLE**, i.e., a pointer to the resampler data structure that has been created.

run: 0 = resampler does not run, it simply copies input buffer (length **size**) to output buffer; 1 = resampler runs. Normally, this parameter should be entered as 1.

size: number of complex I-Q samples in the input buffer.

in: pointer to the input buffer.

out: pointer to the output buffer.

in_rate: input sample-rate (samples / second)

out_rate: output sample-rate (samples / second)

fc: cut-off frequency for bandpass filtering. If entered as 0.0, this will be automatically set to $\pm 0.45 * \text{min_rate}$, where $\text{min_rate} = \min(\text{in_rate}, \text{out_rate})$. Setting this parameter to 0.0 is generally recommended.

ncoef: number of filter coefficients to use. If set to 0, this will be automatically calculated to deliver an excellent filter. Setting this parameter to 0 is generally recommended.

gain: a gain factor may be applied in the resampling process, if desired. Otherwise, set this gain to 1.0.

void destroy_resample (RESAMPLE a)

a: pointer to the resampler data structure.

Note: This call must not be executed while data is flowing, i.e., while the execute function is being called.

void flush_resample (RESAMPLE a)

a: pointer to the resampler data structure.

Note: This call must not be executed while data is flowing, i.e., while the execute function is being called.

int xresample (RESAMPLE a)

return value: number of samples written to the output buffer. Note that, unless $\text{out_rate} == \text{in_rate}$, the number of output samples will be different than the number of input samples. Also note that each successive buffer of input data MAY NOT produce the same number of output samples.

a: pointer to the resampler data structure.

void* Pointers

These are simplified wrappers around the above calls. The create function returns a void pointer and the void pointer is used to reference the resampler in future calls. Calls to create, destroy, and execute the resampler are as follows, respectively.

void* create_resampleV (int in_rate, int out_rate)

return value: a pointer to the resampler data structure that has been created.

in_rate: input sample-rate (samples / second)

out_rate: output sample-rate (samples / second)

Considering other parameters that are now internal, note that using this simplified approach, $fc = 0.0$, $ncoef = 0$, and $gain = 1.0$ in the creation of the resampling filters.

void destroy_resampleV (void* ptr)

ptr: pointer to the resampler data structure.

Note: This call must not be executed while data is flowing, i.e., while the execute function is being called.

void xresampleV (double* in, double* out, int size, int* outsamps, void* ptr)

in: pointer to the input buffer.

out: pointer to the output buffer.

size: number of complex I-Q samples in the input buffer.

outsamps: pointer to location where the number of output samples written to the output buffer is to be stored.

ptr: pointer to the resampler data structure.

Non-Complex (Audio) Single-Precision Resampler

As the title implies, this resampler is for non-complex (I-only) samples of single-precision floating-point values.

Native Pointers

The resampler is created (its resources allocated), destroyed (its resources freed), flushed (data cleared from buffers and indexes reset), and executed using the following four calls, respectively.

RESAMPLEF create_resampleF (int run, int size, float* in, float* out, int in_rate, int out_rate)

return value: The return value is a pointer of type **RESAMPLEF**; a pointer to the resampler data structure that has been created.

run: 0 = resampler does not run, simply copies input buffer (length **size**) to output buffer; 1 = resampler runs. Normally, this parameter should be entered as 1.

size: number of audio (I-only) samples in the input buffer.

in: pointer to the input buffer.

out: pointer to the output buffer.

in_rate: input sample-rate (samples / second)

out_rate: output sample-rate (samples / second)

void destroy_resampleF (RESAMPLEF a)

a: pointer to the resampler data structure.

Note: This call must not be executed while data is flowing, i.e., while the execute function is being called.

void flush_resampleF (RESAMPLEF a)

a: pointer to the resampler data structure.

Note: This call must not be executed while data is flowing, i.e., while the execute function is being called.

int xresampleF (RESAMPLEF a)

return value: number of samples written to the output buffer. Note that, unless **out_rate == in_rate**, the number of output samples will be different than the number of input samples. Also note that each successive buffer of input data MAY NOT produce the same number of output samples.

a: pointer to the resampler data structure.

void Pointers*

These are simplified wrappers around the above calls. The create function returns a void pointer and the void pointer is used to reference the resampler in future calls. Calls to create, destroy, and execute the resampler are as follows, respectively.

void* create_resampleFV (int in_rate, int out_rate)

return value: a pointer to the resampler data structure that has been created.

in_rate: input sample-rate (samples / second)

out_rate: output sample-rate (samples / second)

void destroy_resampleFV (void* ptr)

ptr: pointer to the resampler data structure.

Note: This call must not be executed while data is flowing, i.e., while the execute function is being called.

void xresampleFV (float* in, float* out, int size, int* outsamps, void* ptr)

in: pointer to the input buffer.

out: pointer to the output buffer.

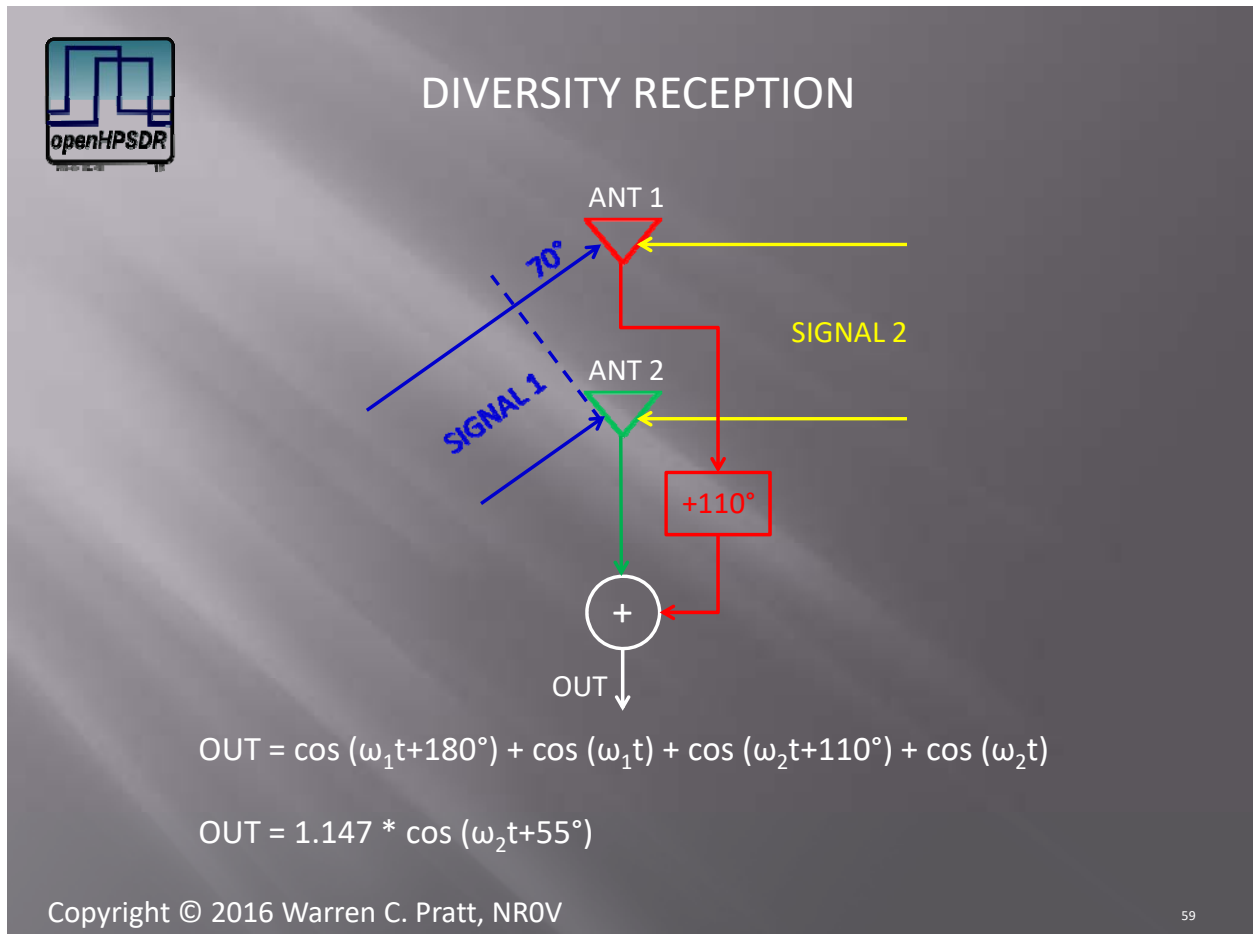
size: number of audio (I-only) samples in the input buffer.

outsamps: pointer to location where the number of output samples written to the output buffer is to be stored.

ptr: pointer to the resampler data structure.

Diversity Mixer

The Diversity Mixer is used to implement diversity reception, an important and unique interference reduction technique. Two ADCs, each connected to a separate antenna, are required for this technique. After the signals are digitized by the ADCs, they can be mixed, while applying amplitude and phase adjustments, to null a signal (or noise) that is arriving from a particular direction.



Consider the example shown in the above figure. Signals 1 and 2 are arriving at the antennas from different angles. The path-length (and therefore delay) for Signal 2 is the same to both antennas. However, for Signal 1, the path-length is longer to Antenna 1 which results in an added 70 degrees of phase shift of that signal. Now, suppose we digitize the signals (not shown) and then mix them applying an additional 110 degrees of phase shift to Signal 1. For simplicity, we also assume the signals are of the same magnitude. Looking at the output signal resulting from the mixing (summing), we see that Signal 2 has been slightly strengthened and that Signal 1 is completely absent!

Diversity mixing requires multiple data streams from multiple DDC units. Therefore, it does not fit in the DSP channel model. Diversity mixing is instead performed BEFORE data enters an RXA channel and then the single resulting stream from the mixer is provided as the input to an RXA channel. Note that we could mix more than the two signals shown using more antennas, ADCs, and DDCs.

A diversity mixer is created (its resources are allocated) using the following call.

void create_divEXT (int id, int run, int nr, int size)

id: an identifier assigned to this diversity mixer. The number of diversity mixers is currently limited to 2 by an internal parameter; so, this must currently be either 0 or 1. This identifier is used to refer to the mixer in subsequent calls.

run: default value of run variable. 0 => mixer does not operate, it does copy from **in[0]** to **out**; 1 => inputs are mixed if (**nr** == **output**), otherwise, **in[output]** is copied to **out**. (See below for setting **output**.)

nr: default number of streams to be mixed. The maximum is limited to 8 by an internal parameter.

size: default number of I-Q samples in each input buffer.

Resources for the mixer are freed using the following call.

void destroy_divEXT (int id)

id: identifier for the mixer.

Note: This call must not be executed while data is flowing, i.e., while the execute function is being called.

The mixer is flushed using the following call.

void flush_divEXT (int id)

id: identifier for the mixer.

Note: This call must not be executed while data is flowing, i.e., while the execute function is being called.

The mixer executes on the buffers of input data and writes a buffer of output data each time the following call is made.

void xdivEXT (int id, int size, double in, double* out)**

id: identifier for the mixer.

size: number of I-Q samples in each input buffer (and the number that will be written to the output buffer).

in: pointer to an array of pointers (**nr** of them) to the input buffers.

out: pointer to the output buffer.

The diversity mixer can be turned OFF/ON using:

void SetEXTDIVRun (int id, int run)

id: identifier for the mixer.

run: 0 => mixer does not operate, it does copy from **in[0]** to **out**; 1 => inputs are mixed if (**nr** == **output**), otherwise, **in[output]** is copied to **out**. (See below for setting **output**.)

The size of the input buffers can be changed using this call:

void SetEXTDIVBuffsize (int id, int size)

id: identifier for the mixer.

size: number of complex I-Q samples in each input buffer.

Note: This call must not be executed while data is flowing, i.e., while the execute function is being called.

The number of streams to be mixed can be changed using:

void SetEXTDIVNr (int id, int nr)

id: identifier for the mixer.

nr: number of streams to be mixed. The maximum is limited to 8 by an internal parameter.

Note: This call must not be executed while data is flowing, i.e., while the execute function is being called.

The **output** value provides a means of having a selected input copied to the **out** buffer rather than running the mixer. if (**output** == **nr**), the mixer runs. However, if (**output** != **nr**), **in[output]** is copied to **out**. **output** is set using the following call.

void SetEXTDIVOutput (int id, int output)

id: identifier for the mixer.

output: number of the input stream to copy to the output. if (**output** == **nr**), the mixer runs.

The I and Q gain/phase-rotation multipliers must be specified for each input stream. Note that I and Q multipliers of 1.0 and 0.0, respectively, may be specified for the "reference receiver."

void SetEXTDIVRotate (int id, int nr, double* Irotate, double* Qrotate)

id: identifier for the mixer.

nr: number of input streams

Irotate: pointer to vector of I gain/phase-rotation multipliers, one element per input stream.

Qrotate: pointer to vector of Q gain/phase-rotation multipliers, one element per input stream.

Before summing, each sample of each stream is modified by its respective I and Q multipliers as follows:

$$I_modified = Irotate[this_stream] * I - Qrotate[this_stream] * Q;$$
$$Q_modified = Irotate[this_stream] * Q + Qrotate[this_stream] * I;$$

EER

The EER module is present to support power amplifiers operating with modes such as "Envelope Elimination and Restoration" and "Envelope Tracking." Specifically, the EER block accepts the normal I-Q output of the TXA transmitter channel and converts that to two different output streams:

- (1) the original I-Q data multiplied by a scale factor, **mgain**, and
- (2) a choice of one of the following three:
 - a) Phase information only: I-Q phase information multiplied by a scale factor **pgain**. The overall magnitude of the output, $\sqrt{I^2 + Q^2}$, is constant at a value of **pgain**; however, I and Q vary in relationship to each other, thereby expressing the phase.
 - b) Magnitude and Phase Information: The original I-Q data multiplied by **pgain**.
 - c) Envelope only: The magnitude of the I-Q envelope, multiplied by **pgain**, and sent only as 'I' values.

When operating in EER/ETR type modes, compensation must be provided for delays in the analog circuitry. Adjustable delays are also included in this software for that purpose.

An EER unit is created (its resources are allocated) using the following call.

EER create_eerEXT (int run, int size, double* in, double* out, double* outM, int rate, double mgain, double pgain, int rundelays, double mdelay, double pdelay, int amiq)

RETURN VALUE: A pointer of type **EER** (this pointer is defined in the file "eer.h"). It points to a data structure retaining all the needed information for continuing operation of the EER unit. This pointer will be used in subsequent calls to the EER unit.

run: default value of run variable. 0 => EER unit does not operate, it does copy from **in** to **out**; 1 => EER unit operates per the settings specified.

size: default number of I-Q samples in each input buffer.

in: pointer to input buffer.

out: pointer to the output buffer where (a) phase, (b) phase and magnitude, or (c) envelope information are to be stored by the EER unit. Which is stored here will be determined by the setting of the parameter **amiq**. In all cases, the output is scaled by **pgain**. Also, the values may be delayed per EER settings.

outM: pointer to an output buffer where the original I-Q input, multiplied by the scale factor **mgain** and possibly delayed, will be stored by the EER unit.

rate: the sample-rate of the data.

mgain: default multiplier for the **outM** output.

pgain: default multiplier for the **out** output.

rundelays: 0 => delays will not be used in operation of the EER unit; 1 => delays will be activated in operation of the EER unit.

mdelay: default delay (us) for **outM** output.

pdelay: default delay (us) for **out** output.

amiq: default for what is to be provided on the **out** output.

0: Phase information only: I-Q phase information multiplied by a scale factor **pgain**.
The overall magnitude of the output, $\sqrt{I^2 + Q^2}$, is constant at a value of **pgain**; however, I and Q vary in relationship to each other, thereby expressing the phase.

1: Magnitude and Phase Information: The original I-Q data multiplied by **pgain**.

2: Envelope only: The magnitude of the I-Q envelope, multiplied by **pgain**, and sent only as 'I' values.

The EER unit can be turned OFF/ON using the call:

void pSetEERRun (EER a, int run)

a: pointer of type **EER** to the EER unit.

run: 0 => EER does not operate, it does copy from **in[0]** to **out**; 1 => EER is operational.

The size of the input buffers can be changed using this call:

void pSetEERSize (EER a, int size)

a: pointer of type **EER** to the EER unit.

size: number of complex I-Q samples in each input buffer.

The samplerate in use for input and output data can be changed using this call:

void pSetEERSamplerate (EER a, int rate)

a: pointer of type **EER** to the EER unit.

rate: the samplerate of the input and output data.

The gain to be applied to the **outM** output can be changed using this call:

void pSetEERMgain (EER a, double gain)

a: pointer of type **EER** to the EER unit.

gain: the gain (linear scale) to be applied to the **outM** output.

The gain to be applied to the **out** output can be changed using this call:

void pSetEERPgain (EER a, double gain)

a: pointer of type **EER** to the EER unit.

gain: the gain (linear scale) to be applied to the **out** output.

The use of delays can be turned OFF/ON using the call:

void pSetEERRunDelays (EER a, int run)

a: pointer of type **EER** to the EER unit.

run: 0 => delays do not operate; 1 => delays are operational.

The following call is used to set the delay to be used for the **outM** output data:

void pSetEERMdelay (EER a, double delay)

a: pointer of type **EER** to the EER unit.

delay: delay (us). Note that fractional us may be used.

The following call is used to set the delay to be used for the **out** output data:

void pSetEERPdelay (EER a, double delay)

a: pointer of type **EER** to the EER unit.

delay: delay (us). Note that fractional us may be used.

The following call is used to set the mode for the **out** output. See descriptions above for the various options.

void pSetEERAMIQ (EER a, int amiq)

a: pointer of type **EER** to the EER unit.

amiq: output type to be used, per above description of options.

WDSP Version Information

The calling application may wish to query WDSP for its version number. This allows enabling or disabling certain console features based upon which version of WDSP is in use. It also enables checking to be sure that an appropriate version of WDSP is found.

The following function is available for this purpose.

int GetWDSPVersion ()

As written in text, WDSP version numbers always contain exactly two digits to the right of the decimal point. However, for easy comparison with expected version values, the value returned by this function is `version_number*100`. E.g., for Version 1.14, the function will return 114.

Revision History

Rev	Date	Changes
0.1	2016-08-05	Initial version of this document; released for comments.
0.11	2016-08-24	Added TXASetSipSpecmode(...) in WDSP and in this document. Added comments on SetPSControl().
0.12	2016-11-28	Added new functions calls for PureSignal 2.0.
1.14	2017-03-17	Added GetWDSPVersion(). Added 1 to the revision number of this document such that it now matches the WDSP revision. Documented calls for EER.
1.15	2017-05-06	Added AM_LSB and AM_USB transmit modes. Added CFC and Phase Rotator audio tools.
1.16	2017-05-28	Added CFC Metering. Moved phase rotator in processing chain.