# Overview of the Fairness Methods

### 1 Learning Fair Representations

This algorithm [1] learns fair representations to ensure fairness.  $Y \in \{0, 1\}$  is the binary random variable representing the classification decision for an individual. X denotes the entire data set of individuals.  $S \in \{0, 1\}$  is a binary random variable representing whether or not a given individual is a member of the protected set. Z is a multinomial random variable where each of the K values represents one of the intermediate set of prototypes. Each prototype is associated with a vector  $v_k$  in the same space as the individuals x. Define a distance measure d, e.g.,  $d(x_n, v_k) = ||x_n - v_k||_2$ .

A natural probabilistic mapping from X to Z via the softmax:

$$P(Z = k \mid x) = \exp(-d(x, v_k)) / \sum_{j=1}^{K} \exp(-d(x, v_j))$$
 (1)

Let  $M_{n,k} = P(Z = k \mid x_n)$ . Define

$$M_k^+ = \frac{1}{|X_0^+|} \sum_{n \in X_0^+} M_{nk} \tag{2}$$

and  $M_k^-$  is defined similarly. Note that  $X_0^+$  is the subset of individuals from the training set that are members of the protected set (i.e., S=1) and  $X_0^-$  denotes the subsets that are not members of the protected set (i.e., S=0) in the training set. Let  $L_z = \sum_{k=1}^K \left| M_k^+ - M_k^- \right|$ . This term ensures statistical parity.

Let  $\hat{x}_n = \sum_{k=1}^K M_{n,k} v_k$  be the reconstructions of  $x_n$  from Z. Let  $L_x = \sum_{n=1}^N (x_n - \hat{x}_n)^2$ , which constrains the mapping to Z to be a good description of X.

Let  $L_y = \sum_{n=1}^N -y_n log \hat{y}_n - (1-y_n) log (1-\hat{y}_n)$  where  $\hat{y}_n = \sum_{k=1}^K M_{nk} w_k$  is the prediction for  $y_n$ . The  $w_k$  values are constrained between 0 and 1.

The learning system minimizes the objective:

$$L = A_z \cdot L_z + A_x \cdot L_x + A_y \cdot L_y \tag{3}$$

where  $A_x, A_y, A_z$  are hyperparameters governing the tradeoff between the system desiderata.

In order to allow different input features to have different levels of impact, define

$$d(x_n, v_k, \alpha) = \sum_{i=1}^{D} \alpha_i (x_{ni} - v_{ki})^2$$
 (4)

and this model can be extended by using different parameter vectors  $\alpha^+$  and  $\alpha^-$  for the protected and unprotected groups respectively. These parameters together with  $\{v_k\}_{k=1}^K$ , w are optimized.

# 2 Fairness Constraints: Mechanisms for Fair Classification

This method [2] considers the signed distance from the users' feature vectors to the decision boundary  $\{d_{\theta}(x_i)\}_{i=1}^{N}$ , and compute

$$Cov(z, d_{\theta}(x)) \approx \frac{1}{N} \sum_{i=1}^{N} (z_i - \bar{z}) d_{\theta}(x_i)$$
 (5)

where z is the protected feature. This is a convex function with respect to the decision boundary parameters  $\theta$ .

### 2.1 Maximizing accuracy under fairness constraints

Let  $L(\theta)$  be the loss function.

min 
$$L(\theta)$$
  
s.t. 
$$\frac{1}{N} \sum_{i=1}^{N} (z_i - \bar{z}) d_{\theta}(x_i) \le c$$

$$\frac{1}{N} \sum_{i=1}^{N} (z_i - \bar{z}) d_{\theta}(x_i) \ge -c$$
(6)

where c trades off fairness and accuracy.

### 2.2 Maximizing fairness under accuracy constraints

min 
$$\left| \frac{1}{N} \sum_{i=1}^{N} (z_i - \bar{z}) d_{\theta}(x_i) \right|$$
  
s.t.  $L(\theta) \le (1 + \gamma) L(\theta^*)$  (7)

where  $L(\theta^*)$  denotes the optimal loss over the training set provided by the unconstrained classifier and  $\gamma \geq 0$  specifies the maximum additional loss with respect to the loss provided by the unconstrained classifier.

#### Fine-Grained Accuracy Constraints

In many classifiers, the loss function is additive over the points in the training set, i.e.  $L(\theta) = \sum_{i=1}^{N} L_i(\theta)$ . We can allow different levels of constraint for each individual,

$$\min \quad \left| \frac{1}{N} \sum_{i=1}^{N} (z_i - \bar{z}) d_{\theta}(x_i) \right|$$
s.t.  $L_i(\theta) \le (1 + \gamma_i) L_i(\theta^*) \quad \forall i \in \{1, ..., N\}$ 

where  $L_i(\theta^*)$  is the individual loss associated to the i-th user in the training set provided by the unconstrained classifier and  $\gamma_i \geq 0$ .

# 3 Fairness Beyond Disparate Treatment and Disparate Impact: Learning Classification without Disparate Mistreatment

Denote the user feature vectors as x, class labels as  $y \in \{-1, 1\}$ , sensitive features  $z \in \{0, 1\}$ , and the training dataset as  $\mathcal{D}$ . This method [3] considers the covariance between the users' sensitive attributes and the signed distance between the feature vectors of misclassified users and the classifier decision boundary,

$$Cov(z, g_{\theta}(y, x)) \approx \frac{1}{N} \sum_{(x, y, z) \in \mathcal{D}} (z - \bar{z}) g_{\theta}(y, x)$$
 (9)

where  $g_{\theta}$  can be defined as

$$g_{\theta}(y,x) = \min(0, yd_{\theta}(x))$$

$$g_{\theta}(y,x) = \min(0, \frac{1-y}{2}yd_{\theta}(x))$$

$$g_{\theta}(y,x) = \min(0, \frac{1+y}{2}yd_{\theta}(x))$$

However, since the problem

min 
$$L(\theta)$$
  
s.t.  $\frac{1}{N} \sum_{(x,y,z)\in\mathcal{D}} (z-\bar{z})g_{\theta}(y,x) \leq c$   
 $\frac{1}{N} \sum_{(x,y,z)\in\mathcal{D}} (z-\bar{z})g_{\theta}(y,x) \geq -c$  (10)

is nonconvex, the constraints are converted into a Disciplined Convex Concave Program which can be solved efficiently.

min 
$$L(\theta)$$
  
s.t. 
$$\frac{-N_1}{N} \sum_{(x,y) \in \mathcal{D}_0} g_{\theta}(y,x) + \frac{N_0}{N} \sum_{(x,y) \in \mathcal{D}_1} g_{\theta}(y,x) \le c$$

$$\frac{-N_1}{N} \sum_{(x,y) \in \mathcal{D}_0} g_{\theta}(y,x) + \frac{N_0}{N} \sum_{(x,y) \in \mathcal{D}_1} g_{\theta}(y,x) \ge -c$$

$$(11)$$

where  $\mathcal{D}_0$  and  $\mathcal{D}_1$  are the subsets of the training dataset  $\mathcal{D}$  taking values z = 0 and z = 1, respectively.  $N_0 = |D_0|$  and  $N_1 = |D_1|$ .

# 4 Fairness-aware Classifier with Prejudice Remover Regularizer

Y, X, and S are random variables corresponding to a class, non-sensitive features, and a sensitive feature, respectively. A training data set is denoted by  $\mathcal{D} = \{(y,x,s)\}$ . The conditional probability of a class given non-sensitive and sensitive features is modeled by  $M(Y \mid X, S; \theta)$ , where  $\theta$  represents model parameters.

This method [4] considers the objective function

$$-L(\mathcal{D};\theta) + \eta R(\mathcal{D},\theta) + \frac{\lambda}{2} \|\theta\|_2^2$$
 (12)

where  $\lambda$  and  $\eta$  are positive regularization parameters,  $R(\mathcal{D},\theta)$  is the prejudice index and

$$L(\mathcal{D}; \theta) = \sum_{(y_i, x_i, s_i) \in \mathcal{D}} log M(y_i \mid x_i, s_i; \theta)$$
(13)

The prejudice index is defined as

$$PI = \sum_{Y,S} \hat{P}(Y,S) log \frac{\hat{P}(Y,S)}{\hat{P}(S)\hat{P}(Y)}$$

$$(14)$$

which can be written as

$$\frac{1}{|\mathcal{D}|} \sum_{(x_i, s_i) \in \mathcal{D}} \sum_{y \in \{0.1\}} M(y \mid x_i, s_i; \theta) \log \frac{\hat{P}(y \mid s_i)}{\hat{P}(y)}$$

$$\tag{15}$$

where

$$\hat{P}(y \mid s) \approx \frac{\sum_{(x_i, s_i) \in \mathcal{D} \text{ s.t. } s_i = s} M(y \mid x_i, s; \theta)}{|\{(x_i, s_i) \in \mathcal{D} \text{ s.t. } s_i = s\}|}$$

$$(16)$$

$$\hat{P}(y) \approx \frac{\sum_{(x_i, s_i) \in \mathcal{D}} M(y \mid x_i, s_i; \theta)}{|\mathcal{D}|}$$
(17)

### 5 Handling Conditional Discrimination

This method [5] considers

$$D_{all} = D_{expl} + D_{bad} (18)$$

where  $D_{all} = P(y = + | s = m) - P(y = + | s = f)$ .  $D_{expl}$  is the explainable part of the discrimination. s is the protected variable.

Consider the scenario of admission to a university. Suppose there are k programs to apply, each of them is denoted by  $(e_i)$ . The gender of the candidates is the sensitive attribute  $(s \in \{f, m\})$  against which discrimination may occur. The acceptance (y = +) or rejection (y = -) decision is made personally for each candidate during the final interview.

What should be the correct acceptance rates for each program if males and females have been treated equally? Let it be the average acceptance rates between two sensitive groups,

$$P^*(+ \mid e_i) = \frac{P(+ \mid e_i, m) + P(+ \mid e_i, f)}{2}$$
(19)

Then the explainable part of discrimination is due to the phenomenon that certain program happens to be more popular among certain gender (while the males and females are treated equally within a program),

$$D_{expl} = \sum_{i=1}^{k} P(e_i \mid m) P^*(+ \mid e_i) - \sum_{i=1}^{k} P(e_i \mid f) P^*(+ \mid e_i)$$

$$= \sum_{i=1}^{k} (P(e_i \mid m) - P(e_i \mid f)) P^*(+ \mid e_i)$$
(20)

and

$$D_{bad} = P(+ \mid m) - P(+ \mid f) - \sum_{i=1}^{k} (P(e_i \mid m) - P(e_i \mid f))P^*(+ \mid e_i)$$
 (21)

To make the classifiers free from bad discrimination, the method modifies the original labels of the training data. It achieves

$$P'(+ \mid e_i, f) = P'(+ \mid e_i, m) = P^*(+ \mid e_i)$$
(22)

where P' denotes the probability in the modified data. It proposes two possible techniques called local massaging and local preferential sampling.

```
Algorithm 1: Local massaging input: dataset (\mathbf{X}, \mathbf{s}, \mathbf{e}, \mathbf{y}) output: modified labels \hat{\mathbf{y}} PARTITION (\mathbf{X}, \mathbf{e}) (Algorithm 3); for each partition X^{(i)} do learn a ranker \mathcal{H}_i: X^{(i)} \to y^{(i)}; rank males using \mathcal{H}_i; relabel DELTA (male) males that are the closest to the decision boundary from + to - (Algorithm 4); rank females using \mathcal{H}_i; relabel DELTA (female) females that are the closest to the decision boundary from - to + end
```

#### Algorithm 2: Local preferential sampling

```
input: dataset (X, s, e, y)
output: resampled dataset (a list of instances)
PARTITION (X, e) (see Algorithm 3);
for each partition X^{(i)} do
   learn a ranker \mathcal{H}_i: X^{(i)} \to y^{(i)};
   rank males using \mathcal{H}_i;
   delete \frac{1}{2}DELTA (male) (see Algorithm 4) males
   + that are the closest to the decision boundary;
   duplicate \frac{1}{2}DELTA (male) males – that are the
   closest to the decision boundary;
   rank females using \mathcal{H}_i;
   delete \frac{1}{2}DELTA (female) females – that are the
   closest to the decision boundary;
   duplicate \frac{1}{2}DELTA (female) females + that are
   the closest to the decision boundary;
end
```

### Algorithm 3: subroutine PARTITION(X, e)

```
find all unique values of e: \{e_1, e_2, \dots, e_k\}; for i=1 to k do \mid make a group X^{(i)}=\{X: e=e_i\}; end
```

### Algorithm 4: subroutine DELTA(gender)

**return**  $G_i|p(+|e_i, \text{gender}) - p^*(+|e_i)|$ , where  $p^*(+|e_i)$  comes from (Eq (19))  $G_i$  is the number of gender people in  $X^{(i)}$ ;

# 6 Information Theoretic Measures for Fairnessaware Feature selection

Consider a supervised learning setting in which each individual in the dataset is associated with the protected attribute(s) A, and a set of n features  $X^n = \{X_1, ..., X_n\}$ . For  $S \subseteq [n]$ ,  $X_S$  is the subset of features  $\{X_i : i \in S\}$ , and  $X_{S^c} = X_n \backslash X_S$ . For the classification task, let Y and  $\hat{Y}$  be the true label and the predicted label of an individual, respectively.

This method [6] proposes the accuracy measure for a subset of features  $X_S \subseteq X^n$ , denoted by  $v^{Acc}(X_S)$ .

$$v^{Acc}(X_S) = I(Y; X_S \mid \{A, X_{S^c}\})$$
  
=  $UI(Y; X_S \setminus \{A, X_{S^c}\}) + CI(Y; X_S, \{A, X_{S^c}\})$  (23)

where  $UI(T; R_1 \backslash R_2)$  denotes the unique information of  $R_1$  with respect to T and  $CI(T; R_1, R_2)$  denotes the information content that can be obtained only if both  $R_1$  and  $R_2$  are available.

For a subset of features  $X_S \subseteq X^n$ , the discrimination coefficient is defined as

$$v^{D}(X_S) = SI(Y; X_S, A) \times I(X_S; A) \times I(X_S; A \mid Y)$$
(24)

where  $SI(Y; X_S, A)$  is the shared information of  $X_S$  and A, representing the information content related to Y that both  $X_S$  and A possess. It is "discriminatory" in the sense that the information content is shared with the protected attribute A.  $I(X_S; A)$  measures the dependence between  $X_S$  and A.  $I(X_S; A \mid Y)$  measures the conditional dependence between  $X_S$  and  $X_S$  and  $X_S$  and  $X_S$  are  $X_S$  and  $X_S$  and  $X_S$  and  $X_S$  are  $X_S$  and  $X_S$  are  $X_S$  and  $X_S$  are  $X_S$  and  $X_S$  are  $X_S$  and  $X_S$  and  $X_S$  are  $X_S$  and  $X_S$  and  $X_S$  are  $X_S$  are  $X_S$  and  $X_S$  are  $X_S$  and  $X_S$  are  $X_S$  and  $X_S$  and  $X_S$  are  $X_S$  and  $X_S$  are  $X_S$  are  $X_S$  are  $X_S$  and  $X_S$  and  $X_S$  are  $X_S$  are  $X_S$  and  $X_S$  are  $X_S$  are  $X_S$  and  $X_S$  are  $X_S$  and  $X_S$  are  $X_S$  are  $X_S$  and  $X_S$  are  $X_S$  and  $X_S$  are  $X_S$  are  $X_S$  and  $X_S$  are  $X_S$  and  $X_S$  are  $X_S$  and  $X_S$  are  $X_S$  are  $X_S$  and  $X_S$  are  $X_S$  are  $X_S$  and  $X_S$  are  $X_S$  are  $X_S$  and  $X_S$  are  $X_S$  and  $X_S$  are  $X_S$  are  $X_S$  and  $X_S$  are  $X_S$  and  $X_S$  are  $X_S$  and  $X_S$  are  $X_S$  and  $X_S$  are  $X_S$  are  $X_S$  and  $X_S$  are  $X_S$  are  $X_S$  and  $X_S$  are  $X_S$  and  $X_S$  are  $X_S$  and  $X_S$  are  $X_S$  are  $X_S$  and  $X_S$  are  $X_S$  are  $X_S$ 

Given a characteristic function  $v(\cdot): \mathcal{P}([n]) \to \mathbb{R}$ , the Shapley value function  $\phi_{(\cdot)}: [n] \to \mathbb{R}$  is defined as:

$$\phi_i = \sum_{T \subseteq [n] \setminus i} \frac{|T|!(n-|T|-1)!}{n!} (v(T \cup \{i\}) - v(T)), \ \forall i \in [n]$$
 (25)

Given the characteristic functions  $v^{Acc}(\cdot)$  and  $v^D(\cdot)$ , the corresponding Shapley value functions are denoted by  $\phi^{Acc}_{(\cdot)}$  and  $\phi^D_{(\cdot)}$ . They are referred to as marginal accuracy coefficient and marginal discrimination coefficient. They can be used to define a score for each feature. Let  $\mathcal{F}_i = \phi^{Acc}_i - \alpha \phi^D_i$  where  $\alpha$  is a positive hyperparameter which trades off between accuracy and discrimination. The fairness utility score for each feature  $(\{\mathcal{F}_i\}_{i=1}^N)$  can be used for feature selection.

## References

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