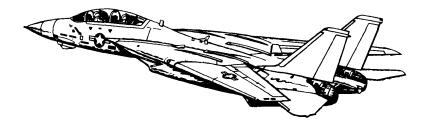
Pocket Checklist

F-14A/B AIRCRAFT

REV: 20210816



Procedures

Systems

AWG-9 Radar

TCS LANTIRN

A/G Weapons

A/A Weapons



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PROCEDURES

1.1 PILOT - PRE-START

1.	Parking Break	ENGAGED
2.	Ground Power	connected
3.	Compressed Air	connected
4.	ICS	HOT MIC
5.	TO RIO	"Begin Start-Up"
6.	ICS	Comm Check
7.	MASTER TEST Selector	 (a) LTS Warning Lights Caution Lights Checked Advisory Lights Checked (b) FIRE DET/EXT L FIRE GO illuminated R FIRE GO illuminated (c) INST RPM EGT 96% EGT FF 10500 pph AOA 18 ± 5 Wing Sweep 45 ± 2.5
		• FUEL QTY
8.	Ejection Seat	Armed
9.	RIO	Canopy Closed
10.	Oxygen	ON (FWD)
11	Emergency Wing Sweep	OVERSWEEP

PILOT - ENGINE START

1.	AIR SOURCE	OFF
2.	Hydraulics	(a) HYD TRANSFER PUMP SHUTOFF (b) Emerg. Hyd AUTO (LOW)
3.	L&R MASTER GEN	NORM
4.	RIO	"Ready to Start"
5.	Right Engine Start-Up	(a) Engine Crank R (b) R Eng N2 20% (c) R Throttle IDLE (d) TIT < 890 C during start
6.	Stabilized Parameters	 RPM
7.	Left Engine Start- Up	(a) Engine Crank L (b) L Eng N2 20% (c) L Throttle IDLE (d) TIT < 890 C during start
8.	Stabilized Parameters	 RPM
9.	HYD TRANSFER PUMP	NORM
10.	HYD PRESSURE	3000 psi
11.	AIR SOURCE	BOTH ENG
12.	Ground Power	disconnected
13.	Compressed Air	disconnected

1.3 PILOT - POST-START

1.	TO RIO	"Both Engines Running"
2.	Displays Control Panel	• VDI
		• HSD
3.	RIO	 Select Align Quality INS GO NOW: shortest but least precise alignment INS GO COARSE: does not meet Launch Criteria for AIM-7 / AIM-54 INS GO MIN WPN LAUNCH: allows AIM-7 / AIM-54 launch INS GO FINE fine align (8 min)
4.	ACM Panel	 GUN RATE
5.	Gun Rounds	Set
6.	ANTI-SKID SPOILER BK	OFF
7.	Emergency Wing Sweep	(a) Handle AFT (b) Angle Verify 68 deg
8.	AFCS Panel - SAS STAB AUG	• PITCH
9.	WING/EXT TRANS	AUTO
10.	UHF 1 Function Selector	ВОТН
11.	TACAN Function Selector	T/R
12.	ARA-63 ICLS RE- CEIVER	ON

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13.	Radar Altimeter	(a) Control Knob one click CW to turn on (b) Display 6000 ft (warm up) (c) Display 0 ft (ready)	
14.	Standby ADI	erect at least 2 min before T/O	
15.	KY-28 Crypt. Key	Set (refer to GROUND SETTINGS kb)	
16.	RIO	set D/L frequency	
17.	Lights	As desired	

1.4 RIO - PRE-START

1.	Oxygen	ON (FWD)
2.	PILOT	• Ground Power connected • Compressed Air connected
3.	ICS	Comm Check
4.	Lights	As required
5.	LTS Test	Coordinate with Pilot
6.	Ejection Seats	ARMED
7.	Canopy	CLOSED
8.	TO PILOT	"Ready to Start"

1.5 RIO - POST-START - SHORE

1.	PILOT	• Engines started • AIR SOURCEBOTH ENG
2.	INS STARTUP	(a) LIQUID COOLING ON (FWD) (b) WCS Switch STANDBY (c) IR/TV Power STBY/IR/TV (d) TID/DDD illuminated after 40 s
3.	Kneeboard	Retrieve Coordinates, Elevation, Magnetic Variation from GROUND SETTINGS Page
WA	RNING Input Coords E	BEFORE selecting GND ALIGN if using ASH
4.	Start INS Align	(a) Nav Mode GND ALIGN (b) CAP • Category NAV
		MESSAGE OWN AC (c) Keyboard
		 CLEAR, LAT, latitude, ENTER LONG, longitude, ENTER ALT, altitude, ENTER
		(d) CAP MESSAGE MAG HDG VAR (e) Keyboard HDG, mag var, ENTER (f) Align Progress
5.	U/VHF Mode	T/R G

6.	Datalink	(a) Kneeboard TACTICAL DL (b) DL Power ON (FWD) (c) DL Mode TAC (AFT) (d) DL Freq. Set
7.	TACAN	T/R
8.	RWR Panel	(a) Display Type NORM (b) PWR ON (c) TEST SPL (d) MODE LMT
9.	DECM	STBY, then ACT
10.	IFF	(a) MASTER
11.	Altimeter	Reset
12.	CAP	Enter Data (WP, FP, etc.)
13.	Displays	• DDD
14.	Hand Control Panel	Set
15.	AN/ALE-39	Set (as required) • AUTO (CHAFF)/MAN • MAN
16.	Flare Mode	PILOT
17.	Complete INS Align	 Duration Full Fine
		(a) Align Complete Caret → Diamond (b) NAV Mode
18.	Standby ADI	Erect at least 2 min before T/O
19.	TO PILOT	"Ready to Taxi"
Onc	e Airborne	
20.	IR/TV Power	ON
21.	WCS Switch	WCS XMT

1.6 RIO - POST-START - CARRIER

1.	PILOT	• Enginesstarted • AIR SOURCEBOTH ENG
2.	INS STARTUP	(a) LIQUID COOLING ON (FWD) (b) WCS Switch STANDBY (c) IR/TV Power STBY/IR/TV (d) TID/DDD illuminated after 40 states
3.	Datalink	(a) Kneeboard
4.	Start INS Align	(a) DL FREQ Set (b) DL Mode CAINS/WAYPT (c) Nav Mode CVA
5.	U/VHF Mode	T/R G
6.	TACAN	T/R
7.	RWR Panel	(a) Display Type NORM (b) PWR ON (c) TEST SPL (d) MODE LMT
8.	DECM	STBY, then ACT
9.	IFF	(a) MASTERSTBY (b) CODEas required
10.	Altimeter	Reset
11.	CAP	Enter Data (WP, FP, etc.)
12.	Displays	• DDD
13.	Hand Control Panel	Set
14.	AN/ALE-39	Set (as required) • AUTO (CHAFF)/MAN • MAN
15.	Flare Mode	PILOT
16.	Complete INS Align	Duration Full Fine
		(a) Align Complete Caret → Diamond(b) NAV Mode

PF	ROCEDURES	F-14A/B REV: 20210816
17.	Datalink	(a) DL Mode TAC (AFT) (b) DL Freq. Set
18.	Standby ADI	Erect at least 2 min before T/O
19.	TO PILOT	"Ready to Taxi"
On	ce Airborne	
20.	IR/TV Power	ON

WCS XMT

WCS Switch

21.

PROCEDURES F-14A/B REV: 20210816

1.7 PRE-TAXI

1.	ANTI-SKID SPOILER BK	OFF
2.	HOOK BYPASS	As Required
3.	Nose Strut	RETRACTED
4.	HUD MODE	ТО
5.	Parking Brake	Released (IN)
6.	NWS	ENGAGED
7.	Path	verify clear

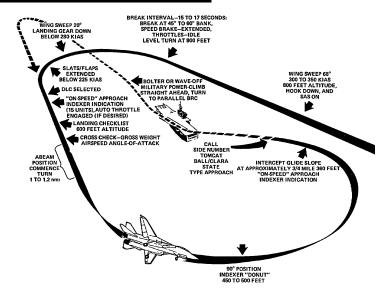
TAKEOFF - SHORE

After Lining Up On Runway		
1.	Wing Sweep	(a) EM WING SWEEP FWD, then IN (b) MASTER RESET PRESS (c) Wings Verify thumb controller (d) WING SWEEP AUTO (e) Wings Verify at 20 deg
2.	ANTI SKID SPOILER BK	BOTH (UP)
3.	FLAPS	UP
4.	Trim	0 deg
5.	NWS	DISENGAGED
6.	Takeoff	(a) Throttle MIL (90% RPM) (b) Stick Back at 130 KIAS (c) Rotation approx 140 KIAS (d) GEAR UP < 250 KIAS

1.9 TAKEOFF - CARRIER

	Lineup	 Wait behind JBD until Catapult is clear Follow Taxi Directors Instructions to line up on Catapult
1.	Wing Sweep	(a) EM WING SWEEP FWD, then IN (b) MASTER RESET PRESS (c) Wings Verify thumb controller (d) WING SWEEP AUTO (e) Wings Verify at 20 deg
2.	FLAPS	DOWN
3.	Launch Bar Preparation	(a) Nose Strut KNEEL when directed (b) Throttle UP when directed (c) Taxi launch bar into shuttle (d) Throttle IDLE when directed
4.	Trim	2-3 deg nose up
5.	Speed Brakes	IN
6.	Final Checks	(a) ThrottleMIL when directed (b) Control Wipeout
		 Stick Full Forward Stick Full Aft Stick Full Left Stick Full Right Rudder Full Left
		Stick Full AftStick Full LeftStick Full Right
7.	Catapult Shot	 Stick Full Aft Stick Full Left Stick Full Right Rudder Full Left Rudder Full Right (c) Eng. Inst

1.10 LANDING - OVERHEAD PATTERN



1.	nitial Approach	WING SWEEP68 deg
		• HOOKDOWN
		• SAS ON
		• HUDLDG
		• Airspeed300-350 KIAS
		• Altitude800 ft
2.	nitial Break	Break Interval 15-17 s
		• BANK45-60 deg
		SPEED BRAKE EXTEND
		• ThrottleIDLE
		• G 3-4 G
		Altitude800 ft
3. E	Break Turn	• Wing Sweep AUTO < 280 KIAS
		• Landing Gear DOWN < 280 KIAS
		• FLAPS DOWN < 225 KIAS
4.	Downwind	DLC Selected once flaps out
		• AOA ON-SPEED
		LANDING CHECKLIST
		Altitudedescend to 600 ft

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5.	Final Turn	180 Deg Position • Abeam Pos 90 Deg Position	1-1.2 nmi
		• AOA	DONUT
		Altitude	400-500 ft
6.	Intercept Glides-	Distance	3/4 Mile
	lope	Altitude	360 ft
		• AOA	ON-SPEED

1.11 LANDING - CHECKLIST

1.	Wing Sweep	20 deg AUTO
2.	Wheels	• Lights 3 DOWN • Transition Light OUT
3.	SAS	ON
4.	FLAPS	DOWN
5.	DLC	Checked
6.	Hook	HOOK DOWN Transition Light OUT
7.	Harness	Locked
8.	Speedbrakes	EXT
9.	Brakes	Check
10.	Fuel	Check

1.12 AIRSTART

• Spooldown	Before significant spooldown (a) Non-Running ENGIDLE or above If no relight occurs (b) Non-Running ENG OFF then IDLE If still no relight occurs
	(c) ENG MODE SEC (d) Non-Running ENG OFF then IDLE
Cross-Bleed Restart	With one ENG running, if Spooldown fails (a) Non-Running ENG
Windmill Restart	(a) Airspeed
Post Restart	(a) BACK UP IGNITION OFF (b) ENG MODE PRI

SYSTEMS

2.1 AFCS - SAS

•	SAS	 Stability Augmentation System
		 Not Fly-by-Wire Automatic control surface commands generated by analog computer to im-
		prove stability
•	Control	 Three individual channels (Pitch, Roll, Yaw)
•	Autopilot Emer-	Paddle on Stick
	gency Disengage Paddle	Disengages Autopilot ModesDeactivates Pitch, Roll SAS Channels

2.2 AFCS - AUTOPILOT

 Attitude Hold 	Basic Attitude Hold
	 Maintains existing pitch & roll Attitude can be changed with stick input If engaged outside limits will automatically move within range
	• Limits
	- Pitch: 30 deg
	- Roll: 60 deg
	 Engagement
	(a) SAS Switches ON (FWD)
	(b) Alt. Hold Mode OFF
	(c) VEC/PCD/ACL OFF
	(d) Heading ModeOFF
	(e) Autonilot Switch FNGAGE (FWD)

 Altitude Hold 	Barometric Altitude Hold
	 Maintains current barometric altitude
	• Limits
	Vertical velocity: < 100 ft/s
	Engagement
	(a) SAS Switches
 Heading Hold 	Magnetic Heading Hold
	 Maintains current magneatic heading
	• Limits
	Bank angle < 5 deg
	Engagement
	(a) SAS Switches ON (FWD) (b) Autopilot Switch ENGAGE (FWD) (c) Heading Mode HDG (FWD)
Ground Track	Autopilot follows ground track
	 Similar to heading hold
	Compensates for wind drift
	 Uses INS data instead of magnetic bearing
	• Limits
	Bank angle < 5 deg
	• Engagement
	(a) SAS Switches ON (FWD)
	(b) Autopilot Switch ENGAGE (FWD)
	(c) Heading Mode
	(d) A/P REF LightWait until appears (e) NWS Button Press
• VEC/PCD	Datalink Vector / Precision Course Direction
	 Allows Link 4 controller to remotely di-
	rect the aircraft
	 Not Modelled in DCS

	STEMS	F-14A/B REV: 20210816
•	ACL	Automatic Carrier Landing
		 See relevant section
•	Autopilot Emer-	Paddle on Stick
	gency Disengage	 Disengages Autopilot Modes
	Paddle	- Deactivates Pitch, Roll SAS Channels
2.3	APC / AUTOTHROT	TLE
•	APC	Approach Power Compensator
		 Automatic throttle control
		 Maintains ON SPEED AoA
•	Conditions	Engagement is inhibited / APC is disengaged if
		conditions not met
		• Throttles
		Landing Gear Handle Down Weight on Wheels
_	Engage	Weight on Wheels No Throttle Mode AUTO (FWD)
_	Disengage	
•		
•		Cage/Seam Button
	ACLS WING-SWEEP	• Cage/Seam Button
2.4 2.5	ACLS	 Cage/Seam Button In Flight Limited between 20 deg & 68 deg On Ground can Oversweep to 75 deg Hydromechanically Controlled
	ACLS WING-SWEEP	 In Flight Limited between 20 deg & 68 deg On Ground can Oversweep to 75 deg
	ACLS WING-SWEEP	 In Flight Limited between 20 deg & 68 deg On Ground can Oversweep to 75 deg Hydromechanically Controlled
	ACLS WING-SWEEP	 In Flight Limited between 20 deg & 68 deg On Ground can Oversweep to 75 deg Hydromechanically Controlled Automatically through CADC Manually with emergency wing-sweep handle 15 deg / s at 1 g loading
	ACLS WING-SWEEP Overview	 In Flight Limited between 20 deg & 68 deg On Ground can Oversweep to 75 deg Hydromechanically Controlled Automatically through CADC Manually with emergency wing-sweep handle 15 deg / s at 1 g loading Mechanically linked to ensure symmetry
	ACLS WING-SWEEP	In Flight Limited between 20 deg & 68 deg On Ground can Oversweep to 75 deg Hydromechanically Controlled - Automatically through CADC - Manually with emergency wing-sweep handle 15 deg / s at 1 g loading Mechanically linked to ensure symmetry AUTO
	ACLS WING-SWEEP Overview	 In Flight Limited between 20 deg & 68 deg On Ground can Oversweep to 75 deg Hydromechanically Controlled Automatically through CADC Manually with emergency wing-sweep handle 15 deg / s at 1 g loading Mechanically linked to ensure symmetry AUTO CADC controls wing position as function
	ACLS WING-SWEEP Overview	In Flight Limited between 20 deg & 68 deg On Ground can Oversweep to 75 deg Hydromechanically Controlled - Automatically through CADC - Manually with emergency wing-sweep handle 15 deg / s at 1 g loading Mechanically linked to ensure symmetry AUTO
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	ACLS WING-SWEEP Overview	In Flight Limited between 20 deg & 68 deg On Ground can Oversweep to 75 deg Hydromechanically Controlled Automatically through CADC Manually with emergency wing-sweep handle 15 deg / s at 1 g loading Mechanically linked to ensure symmetry AUTO CADC controls wing position as function of current Mach via wing-sweep program MAN Pilot manually chooses desired wing sweep angle with thumb controller
	ACLS WING-SWEEP Overview	In Flight Limited between 20 deg & 68 deg On Ground can Oversweep to 75 deg Hydromechanically Controlled Automatically through CADC Manually with emergency wing-sweep handle 15 deg / s at 1 g loading Mechanically linked to ensure symmetry AUTO CADC controls wing position as function of current Mach via wing-sweep program MAN Pilot manually chooses desired wing

• Emergency Mode	 Emergency Wing-Sweep Handle
	 Moved with wing sweep program by spider detent under normal operation Can be forced out of spider detent and moved manually
 Oversweep 	 Selected via Emergency Wing-Sweep Han- dle
	(a) Em. Wing-Sweep
	(b) HZ TAIL AUTHIlluminated (c) Em. Wing-Sweep75 deg
Return to CADC	After Emergency Mode / Oversweep
Control	(a) Em. Wing-SweepSpider Detent (Fwd on startup)
	(b) MASTER RESET Press

Indicated Mach	Max Forward Wing Position
0.4	20 deg
0.7	25 deg
0.8	50 deg
0.9	60 deg
1.0	68 deg

- 2.6 NAVIGATION
- 2.7 COMMUNICATION
- 2.8 DATALINK / IFF

2.9 RWR THREAT SYMBOLOGY

SHIPS				
AB	Arleigh Burke			
AK	Admiral Kuznetsov			
GR	Grisha 5 (Albatros)			
HP	Oliver Hazard Perry			
J2	Type 054A Frigate, "Jiangkai II class"			
KK	Krivak 3 (Rezky)			
ΚV	Kirov (Pyotr Velikiy)			
L1	Type 052B Destroyer, "Luyang I class"			
L2	Type 052C Destroyer, "Luyang II class"			
N	Ship with Nav Radar			
NE	Neustrashimy			
NZ	Nimitz (Vinson, Stennis)			
SV	Slava (Moscow)			
TC	Ticonderoga			
TT	Tarantul 3 (Molniya)			
TW	Tarawa			
YU	Type 071 Amphibious Transport Dock, "Yuzhao class"			
	AIRCRAFT			
14	F-14A/B			
15	F-15C/E			
16	F-16C			
17	JF-17			
18	F/A-18C			
19	MiG-19			

21	MiG-21bis		
23	MiG-23MLD		
24	Su-24M/MR		
25	MiG-25PD		
29	MiG-29A/G/S Su-27 Su-33 J-11A		
30	Su-30		
31	MiG-31		
34	Su-34		
37	AJS-37		
39	Su-25TM		
50	A-50		
52	B-52		
AN	AN-26B AN-30M		
AP	AH-64D		
B1	B-1B		
BE	Tu-95 Tu-142M		
BF	Tu-22M3		
BJ	Tu-160		
E2	E-2D		
E 3	E-3C		
F4	F-4E		
F5	F-5E		
НХ	Ka-27		
IL	IL-76MD IL-78M		
KC	KC-135		

KJ	KJ-2000		
M2	Mirage 2000-C Mirage 2000-5		
S3	S-3B		
SH	SH-60B		
ТО	Tornado		
TR	C-130 C-17A		
	AIR DEFENSE		
2	S-75 TR SNR (SA-2) "Fan Song"		
3	S-125 TR SNR-125 (SA- 3) "Low Blow"		
6	Kub SA-6		
7	HQ-7 TR		
8	OSA (SA-8)		
10	S-300PS 30N6 TR (SA- 10)		
11	Buk (SA-11)		
12	S-300V		
15	Tor 9A331 (SA-15)		
19	Tunguska 2C6M (SA-19)		
Α	Gepard M-163 Vulcan ZSU-23-4 Shilka		
ВВ	S-300PS 64H6E SR (SA- 10/Big Bird)		
BF	Rapier Blindfire TR		
CS	S-300PS 5N66M SR (SA-10/Clam Shell)		
DE	Sborka (Dog Ear)		
FF	S-125 P-19 SR (SA- 3/Flat Face)		
GR	Roland SR		

НА	Hawk SR		
HK	Hawk TR		
HQ	HQ-7 SR		
PT	Patriot		
RO	Roland		
RP	Rapier SR		
S	1L13 55G6 EWR		
SD	Buk TR (SA-11/Snow Drift)		
SN	PRW-11 (Side Net)		
	MISSILES		
M	AIM-54 AIM-120 MICA-EM R-37 R-77 SD-10		
	ATC		
	Airport ATC Radar		

AWG-9 RADAR

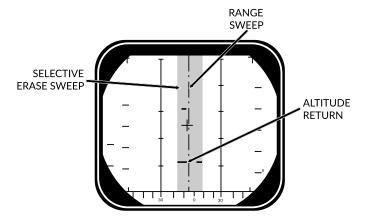
MAIN MODES - OVERVIEW

	Pulse		Pulse Doppler			
	Pulse Search	P-STT	PD Search	RWS	TWS	PD-STT
Range	60 nm	50 nm	110 nm	90 nm	90 nm	90 nm
AIM-7	BRSIT	CW	BRS	SIT	-	PD
AIM-54	BRSIT	ACT	BRS	SIT	Multi TGT	PD/ACT

MAIN MODES

• Pulse	 Basic Pulse w/o doppler filtering 	
	Cannot be notchedGround ClutterRudimentary Ground mapping	
	Pulse Sub-Modes	
	Pulse SearchPulse-STT	
 Pulse Doppler 	 Doppler filter -> no ground returns 	
	 Susceptible to notching No ground clutter Greater range Advanced sub modes AIM-54 Guidance 	
	 Pulse Doppler Sub-Modes 	
	PD SearchRWSTWSPD-STT	

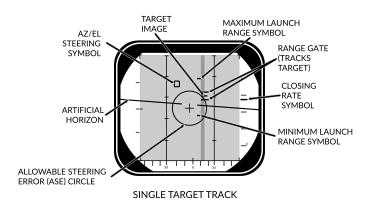
PULSE MODE - PULSE SEARCH 3.3



SEARCH (±10° SCAN)

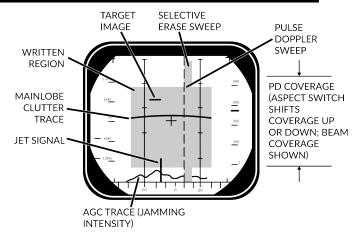
Pulse Search	Basic Mode, AWG-9 does not use pulse doppler filtering • Advantages
	All aspect target detectionCannot be notchedRudimentary ground mapping
	 Disadvantages
	Cannot discern ground returns and targetsLower range
• DDD	Range/Azimuth
	 Visual representation of radar and erase sweeps
• TID	No Information from PulseCannot guide AIM-54

3.4 PULSE MODE - PSTT



Pulse STT	Lock Target w/o doppler filtering • Advantages	
	 Cannot be notched 	
	 Disadvantages 	
	 Susceptible to ground clutter 	
Lock Target	Conditions	
	Pulse Search Mode selectedRDR HCU Mode selected	
	Lock Target	
	(a) Hold HCU Half-action(b) Slew to desired Target(c) HCU Full-Action to lock	
	Unlock Target	
	(d) HCU Half-action	
• DDD	Track Indications	
	 ANT TRK light RDROT light Tracking gates Closure rate Attack Symbology 	

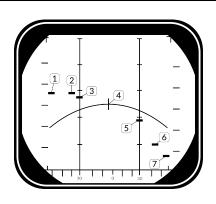
3.5 PULSE DOPPLER MODE - PULSE DOPPLER SEARCH



SEARCH (±40° SCAN)

 Pulse Doppler Search 	"Early Warning" Mode, Longest Range, cannot display rangeAdvantages	
	Longest RangeDoppler Filtering"Look Down Shoot Down"	
	 Disadvantages 	
	Can be notchedNo range information	
• DDD	 Closure Rate/Azimuth Visual representation of radar and erase sweeps 	
 Doppler Filters 	Main Lobe Clutter (MLC) Filter	
	Own GS +/- 133 knotsRemoves main ground returnSource of notching	
	Zero Doppler Filter	
	 Negative own GS +/- 100 knots Removes Radar reflection from ground directly beneath own AC 	

MLC Switch	 IN: Enables MLC filter AUTO: Enables MLC filter if look-up angle less than 3 deg OUT: Disables MLC filter
Vc Switch	Changes closure rate DDD scale • X-4: -800 to 4000 knots • NORM: -200 to 1000 knots • VID: -50 to 250 knots
ASPECT Switch	Changes closure rate processing scale NOSE: -600 to 1800 knots BEAM: -1200 to 1200 knots TAIL: -1800 to 600 knots



	Look Angle	Line of Sight Rate	Target Heading
1	60 deg	1490	180 deg
2	45 deg	1500	120 deg
3	30 deg	1428	100 deg
4	0 deg	1200	90 deg
5	30 deg	672	80 deg
6	45 deg	210	60 deg
7	60 deg	-300	0 deg

3.6 PULSE DOPPLER MODE - RWS

 Range While Search 	FM Ranging, used for getting good A/A picture before selecting TWS • FM Ranging
	 Pulse Doppler with ranging TID shows momentary tracks with ranges Processing reduces max range
	Advantages
	 Long Range Doppler Filtering "Look Down Shoot Down" Signal Processing
	 Disadvantages
	 Can be notched
• DDD	 Closure Rate/Azimuth Visual representation of radar and erase sweeps
• TID	 Momentary Tracks Max concurrent tracks: 48 Cannot lock targets from TID
 Filtering 	Same as Pulse Doppler Search

3.7 PULSE DOPPLER MODE - TWS

Track While Scan	Builds Track Files, high situational awareness, multi-target AIM-54 launch • Track Files
	 AWG-9 builds Trackfiles for contacts Can launch multiple AIM-54 Processing reduces max range Can lock targets from TID
	FM Ranging
	 Pulse Doppler with ranging TID shows momentary tracks with ranges Processing reduces max range
	Advantages
	Doppler FilteringMulti-Target AIM-54
	 Disadvantages
	Lowest RangeCan be notched
• DDD	 Closure Rate/Azimuth Visual representation of radar and erase sweeps
• TID	Tracksfiles
	Max concurrent tracks: 24
Pitta autorio	Max displayed tracks: 18
• Filtering	Same as Pulse Doppler Search
Scan Volume	Trackfiles require update every 2.5 s -> • 20 deg 4 bar (if selected) • 40 deg 2 bar (else)
TID Mode Selector	 GND STAB: Ground Stabilized, True North is up on TID A/C STAB: Aircraft Stabilized ATTAK: same as A/C STAB with superimposed attack steering symbology TV: Displays TCS on TID, dispays LANTIRN on TID if equipped

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TID Display Selector Buttons Track Hold & Col-	 RID DISABLE: Not simulated ALT NUM: Enables display of track altitudes on left side of track symbols SYM ELEM: Enables display of all supplementary symbology of tracks and waypoints DATA LINK: Enables display of D/L contacts JAM STROBE: Enables display of jam strobes NON-ATTK: enables/disables display of targets not possible to engage (friendlies) LAUNCH ZONE: Enables display of weapon launch zones VEL VECTOR: Enables display of velocity vectors TRACK HOLD
lision Steering	Normally: Tracks maintained for 14 s after last observation Track Hold: maintained for 2 min after last observation CLSN Button
	 begins collision steering to currently tracked target enables Steering Centroid if in TWS LD CLSN presents azimuth steering only CLSN presents both azimuth and elevation steering
TWS AUTO / MAN	 TWS MAN: Manual azimuth/elevation control, target designation by RIO TWS AUTO: Automatic prioritization of targets and azimuth elevation control

3.8 PULSE DOPPLER MODE - TWS MAN

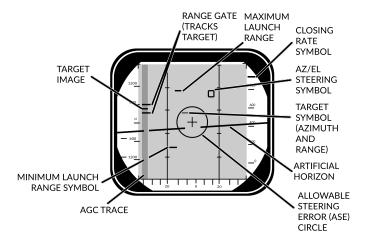
TWS MAN	Target Selection: Manual
	Scan Azimuth/Elevation: Manual
 Target Selection 	 Conditions
	TWS MAN Radar Mode selectedTID CURSOR TID Mode selected
	Hook Target
	(a) Hold HCU Half-Action(b) Slew TID Cursor over desired Tgt(c) HCU Full-Action to select Tgt
	TID Symbology
	 Range (RA) Bearing (BR) Altitude (AL) Magnetic course (MC)
	Lock Target
	(d) Press PD STT or Pulse STT buttons
	Deselect Target
	(e) press HCU Half-Action
AIM-54 Launch	Automatically selects TWS AUTO
	Prevents selection of TWS MAN

3.9 PULSE DOPPLER MODE - TWS AUTO

TWS AUTO	 Target Selection: prioritizes contacts based off range, aspect, closure Scan Azimuth/Elevation: Geometric center of targets in scan volume
 Centroid / Steer- 	Steering Centroid
ing Cues	 facilitates steering cues HUD, VDI, TID, DDD Appears as X on TID Takes Gimbal limits into account Weights individual Tracks based on parameters
	 Illumination Centroid
	 Not Visible Controls azimuth and elevation of scan pattern Takes scan volume into account
 Pilot Steering 	 Conditions
Cues	A-A HUD Mode selectedMaster Arm ON (UP)AIM-54 or AIM-7 selectedTWS-AUTO selected

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3.10 PULSE DOPPLER MODE - PDSTT



SINGLE TARGET TRACK

Pulse Doppler STT	Lock Target with doppler filtering • Advantages
	 Ground Clutter filtering
	 Disadvantages
	 Susceptible to notching
 Lock Target 	 Conditions
	Pulse Doppler Mode selected (PD Search, RWS, TWS)RDR HCU Mode selected
	 Lock Target
	(a) Hold HCU Half-action(b) Slew to desired Target(c) HCU Full-Action to lock
	 Unlock Target
	(d) HCU Half-action
• DDD	 Track Indications
	 ANT TRK light RDROT light Tracking gates Closure rate Attack Symbology

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3.11 ACM MODES - OVERVIEW

	PLM	VSL	PAL	MRL
Range	5 nm	5 nm	15 nm	5 nm
Description	Boresight	Vertical	Horizontal	RIO
Weapons		Gun +	- All Missiles	

• PLM	Pilot Lockon Mode Highest Priority ACM Search Pattern - Small Boresight - Range: 5 nm
• VSL	 Vertical Scan Lockon HI Search Pattern Width: 5 deg Vertical: +15 to +55 deg Range: 5 nm
	 LO Search Pattern Width: 5 deg Vertical: -15 to +25 deg Range: 5 nm RIO/PILOT Controlled
• PAL	 Pilot Automatic Lockon Search Pattern Width: +/- 20 deg Vertical: 8-bar Range: 15 nm
• MRL	 Manual Rapid Lockon RIO Controlled Search Pattern HCU Controlled Range: 5 nm

3.12 TID SYMBOLOGY

GENERAL		
Center Dot	•	Basic Component of Symbols Marks coordinates of sym-
		bol
Own AC	\square	 Symbol representing own aircraft
		 Ground Stabilized: Moves Aircraft Stabilized: Stationary Outside TID: line drawn
		from TID center towards symbol
TID Cursor		Hook Cursor
		 Controlled by HCU in TID mode
		Half-Action
		 Enables display of symbol Enables HCU stick to move cursor
		• Full-Action
		 Hooks closest symbol
		 If no symbol near, cursor dropped at location
TWS Steering Cen- troid	\times	 Steering centroid of TWS tracks
		 Selected by WCS for weapons engagement
ONBOARD SENS	ORS	Symbol Above Dot
Unknown		 Unknown Sensor Track All Returns in RWS
Hostile	•	Sensor Track designated Hos- tile by RIO
Friend	•	 Sensor Track designated Friendly by RIO
Angle-Tracked Radar		Radar Angle Tracking
Target	\•	 Jamming Target

Angle-Tracked Radar Target with Altitude Difference Ranging	\bigcirc	 Radar Angle Tracking Jamming Target Alt. diff. ranging
TCS-Angle Tracked Target	•>	TCS Angle Tracking
TCS-Angle Tracked Target with Altitude Difference Ranging	<u></u>	TCS Angle Tracking Alt. diff. ranging
D/L TARGETS	S	Symbol Below Dot
Unknown		D/L Track designated Un- known by Source
Hostile	•	D/L Track designated Hostile by Source
Friendly		D/L Track designated Friendly by Source
MANUAL REF PO	INTS	
Home base		Waypoint Representing Home Base Carrier Airfield
Waypoint	•	 Nav Waypoint Supplanted by Number 1, 2, or 3
Defended Point		Waypoint to Defend
Fixed Point	\times	Generic Waypoint
Hostile Area		Waypoint Indicating Hostile Area
Surface Target		Waypoint Indicating Surface Target
IP		Initial Point Waypoint for A/G engagement
D/L REF POIN	TS	
Home Base		D/L Waypoint Representing Home Base

AWG-9 RADAR REV: 20210816 Waypoint • D/L Generic Waypoint Data Link Fixed • D/L Waypoint Representing **Point Fixed Point** • D/L Waypoint Representing a Surface Target **Surface Target** POS SYMB MODIFIERS Additional Symbology on TWS Mandatory Attack **Track** - Horizontal bar through center dot Selected by RIO - Only 1 target can be designated - Guaranteed WCS priority number **Data Link Destroy** Additional Symbology on D/L **Track** - Horizontal bar through center dot Selected by Source - No effect on WCS prioritization **Do Not Attack** Additional Symbology on TWS or D/L Track Vertical bar through center dot If Set by RIO - Removes WCS prioritization **Multiple Targets** Additional Symbology on TWS or D/L Track Horizontal bar on left side of symbol • Indicates Multiple Targets

Data Link Challenge	Additional Symbology on D/L Track
	 Small V with center at center dot
	 Command to Visually Identify
Track Extrapolated	Additional Symbology on TWS or D/L Track
	 Small X with center at center dot
	 No Update within 8 seconds
	 Track deleted after 14 seconds
	 Or after 2 min if track hold
Altitude Numerics	Altitude to Nearest Ten Thousand
	example: 35000-45000
Firing Order Numer-	■ Indicates AIM-54 Prioritization
ics	Numbers 1-6Only in TWS
Time-to-Impact (TTI)	⊩ • After AlM-54 Launch
	 Prioritization replaced with estimated TTI
	Flashes after Pitbull
Velocity Vector	Additional Symbology from center Dot
	 Direction represents track heading
	 Length represents speed
	 Varies with Mode
	 Ground Stabilized: true heading and ground speed Aircraft Stabilized: relative heading and velocity

Launch Zone Vectors	Additional Symbology for AIM-54 Selected manually by RIO Or 60 seconds from max launch TUMR Time-Until-Minimum-Range Max: 180 seconds, 1.5 inches TUOR Time-Until-Optimal-Range Start of bar is 8 seconds from optimum TUIR
Jamming Strobe	Time-Until-In-RangeLine from own AC towardsJammer
Radar Antenna Scan Pattern Azimuth Limits	 Limits of Current Scan Azimuth Single Line in STT
Data Link Jamming Strobe	 Line from D/L point towards Jammer
Data Link Pointer	 Additional Symbology on D/L Track — Circle — Indicates operator concern
Data Link Priority Kill	 Additional Symbology on D/L Track Square Indicates target must be destroyed No effect on WCS prioritization

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ATTACK DISPLAY SYMBOLOGY

Artificial Horizon		Represents Pitch and Roll
Steering Guidance Symbol		Represents Steering Error Should be placed as near as possible to center of ASE circle
Allowable Steering Error Circle		 Indicates Allowable Steering Error for Missile Launch Size Varies with Geometry, Mode, Missile
Breakaway Indica- tion	X	Appears when Target Range Less than Minimum for Se- lected Weapon

TCS/ALQ-100

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5 LANTIRN

6 A/G WEAPONS

6.1 M61 GUN

1. Pilot Conditions	(a) MASTER ARMON
	(b) HUD
	(c) WEAPON SELECTOR GUNS
	(d) Stations verify selected
	(e) Wing SweepBOMB
2. Employment	(a) Dive
	(b) Pipper on target
	(c) TRIGGER FIRE
Note: TCS	TCS slaved to radar impact point
	 Rio can select NAR or WIDE

6.2 ZUNI ROCKETS

1. RIO Conditions	(a) WPN TYP LAU-10 (b) Attack Mode Pilot Attack (c) Deliver Mode RPL-SGL
	 STP (Step) single bomb per press RPL (Ripple) multiple bombs per press SGL (Single) single bomb per press PRS (Pairs) a pair of bombs per press
	(d) Mechanical Fuze NOSE (e) Electronic Fuze INST (f) Delivery Options set
	• INTERVAL
2. Pilot Conditions	(a) MASTER ARM

3.	Employment	(a) Dive 20-30) deg
		(b) Pipper on t	arget
		(c) TRIGGER	FIRE

 (c) WEAPON SELECTOR
 OFF

 (d) Stations
 verify selected

 (e) Wing Sweep
 BOMB

UNGUIDED BOMB - CCIP

1. RIO Conditions	(a) WPN TYP MK-82 (b) Attack Mode Pilot Attack (c) Deliver Mode STP-PRS
	 STP (Step) single bomb per press RPL (Ripple) multiple bombs per press SGL (Single) single bomb per press PRS (Pairs) a pair of bombs per press
	(d) Mechanical Fuze NOSE (e) Electronic Fuze INST (f) Delivery Options set • INTERVAL 010 msec • QTY 01
	(g) StationsArmed
2. Pilot Conditions	(a) MASTER ARM ON (b) HUD A/G (c) WEAPON SELECTOR OFF (d) Stations verify selected (e) Wing Sweep BOMB
3. Employment	(a) Dive 40 deg (b) Pipper on target (c) STORE RELEASE Press and Hold

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6.4 UNGUIDED BOMB - CCRP

1. RIO Conditions	(a) WPN TYP MK-82 (b) Attack Mode Target Attack (c) Deliver Mode STP-PRS
	 STP (Step) single bomb per press RPL (Ripple) multiple bombs per press SGL (Single) single bomb per press PRS (Pairs) a pair of bombs per press
	(d) Mechanical Fuze NOSE (e) Electronic Fuze INST (f) Delivery Options set
	• INTERVAL
	(g) StationsArmed
2. Pilot Conditions	(a) MASTER ARM
	(c) WEAPON SELECTOR OFF
	(d) Stations verify selected
	(e) Wing SweepBOMB
3. Designation	(a) Slew DiamondVSL HI/LO
	(b) DesignatePAL
4. Employment	(a) Flight PathStraight, Level
	(b) Vel Vector on Bomb Fall Line
	When Solution Cue meets Velocity Vector
	(c) STORE RELEASE Press and Hold

6.5 GBU-12 PAVEWAY II

1. LANTIRN PREP (a) Target Pod Power POD • Warm up takes approx. 8 min • Automatically switches to STANDBY (b) Laser Code as desired • MUST BE SET ON THE GROUND • Default: 1688 (c) LANTIRN Mode OPERATE • STANDBY caution will flash for 30 s • Then switches to OPER (d) VIDEO Switch FLIR (e) TID Mode TV 2. RIO Conditions (a) WPN TYP GBU-12 (b) Attack Mode Manual (c) Deliver Mode STP-SGL • STP (Step) single bomb per press • RPL (Ripple) multiple bombs per press • SGL (Single) single bomb per press • PRS (Pairs) a pair of bombs per press (d) Mechanical Fuze NOSE (e) Electronic Fuze INST (f) Delivery Options set (not necessary for STP-SGL) (g) Stations Armed 3. Pilot Conditions (a) MASTER ARM ON (b) HUD A/G (c) WEAPON SELECTOR OFF (d) VDI Mode TV (e) Stations verify selected (f) Wing Sweep BOMB 4. Slew LANTIRN • Slave to WYPT Left-4-Way RIGHT • QSNO (Snowplow) S4 HAT Down • Toggle FOV LANTIRN Toggle FOV • Slew LANTIRN Stick • Area Track Left-4-Way Down • Undesignate LANTIRN Undesignate		
Automatically switches to STANDBY (b) Laser Code	1. LANTIRN PREP	(a) Target Pod PowerPOD
(b) Laser Code		 Warm up takes approx. 8 min
MUST BE SET ON THE GROUND Default: 1688 (c) LANTIRN Mode		 Automatically switches to STANDBY
Default: 1688 (c) LANTIRN Mode		(b) Laser Codeas desired
(c) LANTIRN Mode OPERATE STANDBY caution will flash for 30 s Then switches to OPER (d) VIDEO Switch FLIR (e) TID Mode TV 2. RIO Conditions (a) WPN TYP GBU-12 (b) Attack Mode Manual (c) Deliver Mode STP-SGL STP (Step) single bomb per press RPL (Ripple) multiple bombs per press RPL (Ripple) multiple bombs per press PRS (Pairs) a pair of bombs per press PRS (Pairs) a pair of bombs per press (d) Mechanical Fuze NOSE (e) Electronic Fuze INST (f) Delivery Options set (not necessary for STP-SGL) (g) Stations Armed 3. Pilot Conditions (a) MASTER ARM ON (b) HUD A/G (c) WEAPON SELECTOR OFF (d) VDI Mode TV (e) Stations verify selected (f) Wing Sweep BOMB 4. Slew LANTIRN Slave to WYPT Left-4-Way RIGHT QSNO (Snowplow) S4 HAT Down Toggle FOV LANTIRN Toggle FOV Slew LANTIRN Stick Area Track Left-4-Way UP Point Track Left-4-Way UP		MUST BE SET ON THE GROUND
• STANDBY caution will flash for 30 s • Then switches to OPER (d) VIDEO Switch		• Default: 1688
• Then switches to OPER (d) VIDEO Switch		(c) LANTIRN ModeOPERATE
(d) VIDEO Switch		STANDBY caution will flash for 30 s
(e) TID Mode		 Then switches to OPER
2. RIO Conditions (a) WPN TYP		(d) VIDEO SwitchFLIR
(b) Attack Mode		(e) TID ModeTV
(c) Deliver Mode	2. RIO Conditions	(a) WPN TYP GBU-12
STP (Step) single bomb per press RPL (Ripple) multiple bombs per press SGL (Single) single bomb per press PRS (Pairs) a pair of bombs per press PRS (Pairs) a pair of bombs per press (d) Mechanical Fuze NOSE (e) Electronic Fuze INST (f) Delivery Options set (not necessary for STP-SGL) (g) Stations Armed 3. Pilot Conditions (a) MASTER ARM ON (b) HUD A/G (c) WEAPON SELECTOR OFF (d) VDI Mode TV (e) Stations verify selected (f) Wing Sweep BOMB 4. Slew LANTIRN Slave to WYPT Left-4-Way RIGHT QSNO (Snowplow) S4 HAT Down Toggle FOV LANTIRN Toggle FOV Slew LANTIRN Stick Area Track Left-4-Way UP Point Track Left-4-Way Down		
RPL (Ripple) multiple bombs per press SGL (Single) single bomb per press PRS (Pairs) a pair of bombs per press Rehamment of bombs per press Reha		(c) Deliver ModeSTP-SGL
SGL (Single) single bomb per press PRS (Pairs) a pair of bombs per press (d) Mechanical Fuze NOSE (e) Electronic Fuze INST (f) Delivery Options set		
PRS (Pairs) a pair of bombs per press (d) Mechanical Fuze		
(d) Mechanical Fuze		
(e) Electronic Fuze		
(f) Delivery Options set (not necessary for STP-SGL) (g) Stations Armed 3. Pilot Conditions (a) MASTER ARM ON (b) HUD A/G (c) WEAPON SELECTOR OFF (d) VDI Mode TV (e) Stations verify selected (f) Wing Sweep BOMB 4. Slew LANTIRN • Slave to WYPT Left-4-Way RIGHT • QSNO (Snowplow) S4 HAT Down • Toggle FOV LANTIRN Toggle FOV • Slew LANTIRN Stick • Area Track Left-4-Way UP • Point Track Left-4-Way Down		
(not necessary for STP-SGL) (g) Stations Armed 3. Pilot Conditions (a) MASTER ARM ON (b) HUD A/G (c) WEAPON SELECTOR OFF (d) VDI Mode TV (e) Stations verify selected (f) Wing Sweep BOMB 4. Slew LANTIRN Slave to WYPT Left-4-Way RIGHT QSNO (Snowplow) S4 HAT Down Toggle FOV LANTIRN Toggle FOV Slew LANTIRN Stick Area Track Left-4-Way UP Point Track Left-4-Way Down		
3. Pilot Conditions (a) MASTER ARM (b) HUD (c) WEAPON SELECTOR (d) VDI Mode TV (e) Stations (f) Wing Sweep BOMB 4. Slew LANTIRN Slave to WYPT Left-4-Way RIGHT QSNO (Snowplow) Toggle FOV Slew LANTIRN Toggle FOV Slew LANTIRN Stick Area Track Left-4-Way UP Point Track Left-4-Way Down		
(b) HUD		(g) Stations Armed
(c) WEAPON SELECTOR OFF (d) VDI Mode TV (e) Stations verify selected (f) Wing Sweep BOMB 4. Slew LANTIRN Slave to WYPT Left-4-Way RIGHT QSNO (Snowplow) S4 HAT Down Toggle FOV LANTIRN Toggle FOV Slew LANTIRN Stick Area Track Left-4-Way UP Point Track Left-4-Way Down	3. Pilot Conditions	(a) MASTER ARMON
(d) VDI Mode		
(e) Stations verify selected (f) Wing Sweep BOMB 4. Slew LANTIRN Slave to WYPT Left-4-Way RIGHT QSNO (Snowplow) S4 HAT Down Toggle FOV LANTIRN Toggle FOV Slew LANTIRN Stick Area Track Left-4-Way UP Point Track Left-4-Way Down		
4. Slew LANTIRN Slave to WYPT Left-4-Way RIGHT QSNO (Snowplow) S4 HAT Down Toggle FOV LANTIRN Toggle FOV Slew LANTIRN Stick Area Track Left-4-Way UP Point Track Left-4-Way Down		
Slew LANTIRN Slave to WYPT Left-4-Way RIGHT QSNO (Snowplow) S4 HAT Down Toggle FOV LANTIRN Toggle FOV Slew LANTIRN Stick Area Track Left-4-Way UP Point Track Left-4-Way Down		
 QSNO (Snowplow)	4 Claw I ANTIDN	1
 Toggle FOV LANTIRN Toggle FOV Slew LANTIRN Stick Area Track Left-4-Way UP Point Track Left-4-Way Down 	4. SIEW LANTIKN	
Slew		· · · · · · · · · · · · · · · · · · ·
Point TrackLeft-4-Way Down		
		Area Track Left-4-Way UP
UndesignateLANTIRN Undesignate		
		Undesignate LANTIRN Undesignate

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4.	Designate	 (a) DesignateTrigger Full-Action Time-to-Go calculated Slant Range calculated
		Once Time-to-Realease (TREL) is 0
		(b) Auto-LaseIf selected: lases 10s to impact (c) Manual Lase Trigger Full-Action (d) While Lasing L blinks
5.	Employment	Once Time-to-Realease (TREL) is 0
		(a) STORE RELEASE Press and Hold
		(b) Flight Path Gentle right-hand turn (to prevent masking)

6.6 TALD DECOYS

1. RIO Conditions	(a) WPN TYP TALD (b) Deliver Mode STP-SGL
	 STP (Step) single bomb per press RPL (Ripple) multiple bombs per press SGL (Single) single bomb per press
	• PRS (Pairs) a pair of bombs per press
	(c) Delivery Options set (not necessary for STP-SGL)
	(d) StationsArmed
2. Pilot Conditions	(a) MASTER ARMON
	(b) HUD
	(c) WEAPON SELECTOR OFF
	(d) HSD ModeTID
	(e) Stations verify selected
3. Employment	(a) Flight Path High / Fast
	(b) RWR Monitor to locate emitters
	(c) STORE RELEASE Press and Hold

6.7 SELECTIVE ORNANCE JETTISON

7 A/A WEAPONS

7.1 M61 GUN (MANUAL)

1.	Conditions	• MASTER ARM	ON
		• HUD	A / A
		• Gun Rate	HIGH
		Gunsight Lead	as required
		WEAPON SELECTOR	•
2.	Gun Mode	(a) Gun Mode	MANUAL
		 Press CAGE/SEAM to se 	elect
		 No ranging 	
		 No lead information 	
3.	Employment	(a) Pipper	on target
		(b) Trigger	FIRE

7.2 M61 GUN (RTGS/NO RADAR)

1.	Conditions	MASTER ARM ON HUD A/A Gun Rate HIGH WEAPON SELECTOR GUNS
2.	Gun Mode	 (a) Gun Mode
3.	Employment	(a) Pipper on target (b) Trigger FIRE

7.3 M61 GUN (RTGS/RADAR)

1. Conditions	MASTER ARM ON HUD A/A Gun Rate HIGH WEAPON SELECTOR GUNS
2. Radar Lock	(a) Gun ModeRTGS • Real-Time Gunsight Mode • Selected automatically with guns
	(b) Radar STT • RIO STT lock • ACM Modes
3. Employmen	t (a) Pipperon target (b) Trigger

7.4 AIM-9 SIDEWINDER (SIL)

1. Conditions	• MASTER ARM
	SW COOLON WEAPON SELECTORSW
2. IR Lock	(a) MODE/STPas desired
	• NORM
	 Uncage seeker with CAGE/SEAM
	 4.5 sec search time
	 40 deg track limit
	• BRSIT
	 Seeker slaved to ADL
	2.5 deg FOV
	(b) CAGE/SEAM press to uncage (if using NORM)
	(c) Tone high pitched
3. Employment	(a) Trigger FIRE

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7.5 AIM-9 SIDEWINDER (RADAR)

1. Condition	• MASTER ARMON
	• HUD
	• SW COOLON
	WEAPON SELECTORSW
2. Radar/IR	ck (a) MODE/STPNORM
	• NORM
	Uncage seeker with CAGE/SEAM4.5 sec search time
	 40 deg track limit
	BRSIT
	 Seeker slaved to ADL
	2.5 deg FOV
	(b) RadarSTT
	RIO STT lock
	ACM Modes
	(c) CAGE/SEAM press to slave to radar (d) Tone high pitched
3. Employm	(a) Steering center T-shaped cue with ASE (b) TriggerFIRE

7.6 AIM-7 SPARROW

1. Conditions	MASTER ARM ON HUD A/A MSL PREP ON WEAPON SELECTOR SP
2. RIO Conditions	
	(c) MSL OPTIONS
	PH ACT AIM-54 active launch
3. Radar Lock	(a) MODE/STP
	• BRSIT
	Boresight flood modeTracks strongest return
	(b) Radar STT
	RIO STT lockACM Modes
4. Employment	(a) Target <20 deg from ADL

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7.7 AIM-54 PHOENIX (SINGLE)

1. Conditions	• MASTER ARM ON • HUD A/A • MSL PREP ON • WEAPON SELECTOR PH
2. RIO Conditions	(a) LIQUID COOLING ON (FWD) (b) MSL SPD GATE NOSE QTR
	NOSE QTR Standard OperationAll Others Not Simulated
	(c) MSL OPTIONSNORM
	SP PD AIM-7 PD launch
	NORM Normal
	PH ACT AIM-54 active launch
3. Radar Lock	(a) MODE/STPNORM
	• NORM
	 Used for STT engagement
	 WCS can use CS or PD
	• BRSIT
	 Boresight flood mode
	 Tracks strongest return
	(b) Radar STT
	RIO STT lock
	ACM Modes
4. Employment	(a) Target<20 deg from ADL
	(b) Steering center T-shaped cue with ASE
	(c) TriggerPress and Hold (3-4 seconds)
	• TIDTTI appears
	(d) Radar Maintain Lock

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7.8 AIM-54 PHOENIX (MULTI)

1. Conditions	• MASTER ARMON • HUDA/A
	• MSL PREPON
	WEAPON SELECTORPH
2. RIO Conditio	(a) LIQUID COOLING ON (FWD) (b) MSL SPD GATE NOSE QTR
	NOSE QTR Standard OperationAll Others Not Simulated
	(c) MSL OPTIONSNORM
	 SP PD AIM-7 PD launch NORM Normal PH ACT AIM-54 active launch
	(d) WCS ModeTWS MAN/AUTO
3. Radar Track	(a) MODE/STP NORM (b) Radar TWS
	 WCS will automatically build trackfiles Track priorities to the right of contact symbol DO NOT STT LOCK
4. Employment	(a) Trigger Press and Hold (3-4 seconds)
	 TIDTTI appears WCS MODE switches to TWS AUTO
	(b) TriggerPress and Hold (3-4 seconds)
	Fires on next highest priorityRepeat for remaining targets
	(c) Radar

