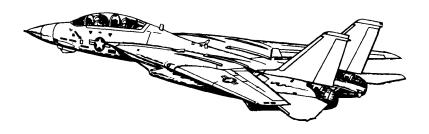
# **Pocket Checklist**

# F-14A/B AIRCRAFT

**REV: 20220125** 



**Procedures** 

Systems

AWG-9 Radar

TCS LANTIRN

A/G Weapons

A/A Weapons



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AIM-54 PHOENIX - PD-STT



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# **PROCEDURES**

# 1.1 PILOT - PRE-START

1.	Parking Brake	ENGAGED
2.	Ground Power	connected
3.	Compressed Air	connected
4.	ICS	HOT MIC
5.	TO RIO	"Begin Start-Up"
6.	ICS	Comm Check
7.	MASTER TEST Selector	<ul> <li>(a) LTS</li> <li>• Warning Lights</li></ul>
8.	Ejection Seat	Armed
9.	RIO	Canopy Closed
10.	Oxygen	ON (FWD)
11	Emergency Wing Sweep	OVERSWEEP

# **PILOT - ENGINE START**

1.	AIR SOURCE	OFF
2.	Hydraulics	(a) HYDTRANSFER PUMP SHUTOFF (b) Emerg. Hyd AUTO (LOW)
3.	L&R MASTER GEN	NORM
4.	RIO	"Ready to Start"
5.	Right Engine Start-Up	(a) Engine Crank       R         (b) R Eng N2       20%         (c) R Throttle       IDLE         (d) TIT       < 890 C during start
6.	Stabilized Parameters	<ul> <li>RPM</li></ul>
7.	Left Engine Start- Up	(a) Engine Crank       L         (b) L Eng N2       20%         (c) LThrottle       IDLE         (d) TIT       < 890 C during start
8.	Stabilized Pa- rameters	• RPM
9.	HYD TRANSFER PUMP	NORM
10.	HYD PRESSURE	3000 psi
11.	AIR SOURCE	BOTH ENG
12.	Ground Power	disconnected
13.	Compressed Air	disconnected

# 1.3 PILOT - POST-START

	TO RIO	"Bath Fraince Duration"
1.		"Both Engines Running"
2.	Displays Control Panel	• VDION
	ranei	• HUDON • HSDON
		• HDS MODE
		(monitor INS)
3.	RIO	Select Align Quality
		• INS GO NOW: shortest but least precise
		alignment
		<ul> <li>INS GO COARSE: does not meet Launch Criteria for AIM-7 / AIM-54</li> </ul>
		• INS GO MIN WPN LAUNCH: allows AIM-7 /
		AIM-54 launch
		INS GO FINE fine align (8 min)
4.	ACM Panel	GUN RATEas required
		• SW COOLOFF
		• MSL PREP OFF • Missile MODE/STP NORM
 5.	Gun Rounds	Set
		1
6.	ANTI-SKID SPOILER BK	OFF
7.	Emergency Wing	(a) <b>Handle</b>
	Sweep	(b) <b>Angle</b>
8.	AFCS Panel - SAS	• PITCHON
	STAB AUG	• ROLLON
		• YAWON
9.	WING/EXT TRANS	AUTO
10.	UHF 1 Function	вотн
	Selector	
11.	TACAN Function	T/R
	Selector	
12.	ARA-63 ICLS RE-	ON
	CEIVER	

			_
	CEB	<b>~</b> ′ ′	_
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13.	Radar Altimeter	(a) Control Knob one click CW to turn on
		(b) <b>Display</b> 6000 ft (warm up)
		(c) <b>Display</b> 0 ft (ready)
14.	Standby ADI	erect at least 2 min before T/O
15.	KY-28 Crypt. Key	Set (refer to GROUND SETTINGS kb)
16.	RIO	set D/L frequency
17.	Lights	As desired

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# 1.4 RIO - PRE-START

1.	Oxygen	ON (FWD)
2.	PILOT	• Ground Powerconnected • Compressed Airconnected
3.	ICS	Comm Check
4.	Lights	As required
5.	LTS Test	Coordinate with Pilot
6.	Ejection Seats	ARMED
7.	Canopy	CLOSED
8.	TO PILOT	"Ready to Start"

# 1.5 RIO - POST-START - SHORE

1.	PILOT	• Engines started
		• AIR SOURCEBOTH ENG
2.	<b>INS STARTUP</b>	(a) LIQUID COOLINGON (FWD)
		(b) WCS SwitchSTANDBY
		(c) IR/TV Power STBY/IR/TV
		(d) <b>TID/DDD</b> illuminated after 40 s
3.	Kneeboard	Retrieve Coordinates, Elevation, Magnetic Variation from GROUND SETTINGS Page
WA	RNING Input Coords	BEFORE selecting GND ALIGN if using ASH
4.	Start INS Align	(a) Nav Mode
		• Category NAV • MESSAGE OWN AC
		(c) <b>Keyboard</b>
		CLEAR, LAT, latitude, ENTER
		<ul> <li>LONG, longitude, ENTER</li> </ul>
		• ALT, altitude, ENTER
		(d) CAP MESSAGEMAG HDG VAR
		(e) <b>Keyboard HDG</b> , mag var, <b>ENTER</b>
		(f) Align ProgressMonitor
5.	U/VHF Mode	T/R G

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6.	Datalink	(a) Kneeboard       TACTICAL DL         (b) DL Power       ON (FWD)         (c) DL Mode       TAC (AFT)         (d) DL Freq.       Set
7.	TACAN	T/R
8.	RWR Panel	(a) Display Type         NORM           (b) PWR         ON           (c) TEST         SPL           (d) MODE         LMT
9.	DECM	STBY, then ACT
10.	IFF	(a) <b>MASTER</b>
11.	Altimeter	Reset
12.	CAP	Enter Data (WP, FP, etc.)
13.	Displays	• DDD
14.	Hand Control Panel	Set
15.	AN/ALE-39	Set (as required)  • AUTO (CHAFF)/MAN  • MAN
16.	Flare Mode	PILOT
17.	Complete INS Align	• Duration Full Fine
		(a) <b>Align Complete</b> Caret → Diamond (b) <b>NAV Mode</b>
18.	Standby ADI	Erect at least 2 min before T/O
19.	TO PILOT	"Ready to Taxi"
Onc	e Airborne	
20.	IR/TV Power	ON
21.	WCS Switch	WCS XMT

# 1.6 RIO - POST-START - CARRIER

1.	PILOT	• Engines started • AIR SOURCEBOTH ENG	
2.	INS STARTUP	(a) LIQUID COOLING         ON (FWD)           (b) WCS Switch         STANDBY           (c) IR/TV Power         STBY/IR/TV           (d) TID/DDD         illuminated after 40 s	
3.	Datalink	(a) <b>Kneeboard</b>	
4.	Start INS Align	(a) DL FREQ         Set           (b) DL Mode         CAINS/WAYPT           (c) Nav Mode         CVA	
5.	U/VHF Mode	T/R G	
6.	TACAN	T/R	
7.	RWR Panel	(a) Display Type         NORM           (b) PWR         ON           (c) TEST         SPL           (d) MODE         LMT	
8.	DECM	STBY, then ACT	
9.	IFF	(a) MASTER	
10.	Altimeter	Reset	
11.	CAP	Enter Data (WP, FP, <i>etc</i> .)	
12.	Displays	• DDD	
13.	Hand Control Panel	Set	
14.	AN/ALE-39	Set (as required) • AUTO (CHAFF)/MAN • MAN	
15.	Flare Mode	PILOT	
16.	Complete INS Align	<ul> <li>Duration Full Fine</li></ul>	
		(b) <b>NAV Mode INS NAV</b>	

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(a) DL Mode
Erect at least 2 min before T/O
"Ready to Taxi"

18.	Standby ADI	Erect at least 2 min before T/O
19.	TO PILOT	"Ready to Taxi"
Once	e Airborne	
20.	IR/TV Power	ON
21.	WCS Switch	WCS XMT
21.	WCS Switch	WCS XMT

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# 1.7 PRE-TAXI

1.	ANTI-SKID SPOILER BK	OFF
2.	HOOK BYPASS	As Required
3.	Nose Strut	RETRACTED
4.	HUD MODE	то
5.	Parking Brake	Released (IN)
6.	NWS	ENGAGED
7.	Path	verify clear

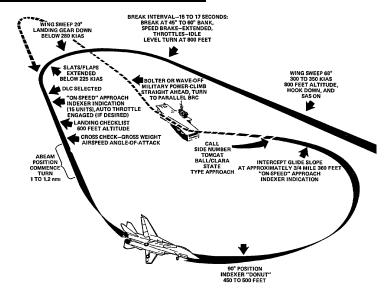
### 1.8 TAKEOFF - SHORE

After Lining Up On Runway		
1.	Wing Sweep	(a) EM WING SWEEP       FWD, then IN         (b) MASTER RESET       PRESS         (c) Wings       Verify thumb controller         (d) WING SWEEP       AUTO         (e) Wings       Verify at 20 deg
2.	ANTI SKID SPOILER BK	BOTH (UP)
3.	FLAPS	UP
4.	Trim	0 deg
5.	NWS	DISENGAGED
6.	Takeoff	(a) Throttle       MIL (90% RPM)         (b) Stick       Back at 130 KIAS         (c) Rotation       approx 140 KIAS         (d) GEAR       UP < 250 KIAS

# 1.9 TAKEOFF - CARRIER

Line	ıβ	Wait behind JBD until Catapult is clear
		Follow Taxi Directors Instructions to line up
		on Catapult
1. Wing	Sweep	(a) EM WING SWEEP FWD, then IN
		(b) MASTER RESET PRESS
		(c) Wings Verify thumb controller (d) WING SWEEP
		(e) <b>Wings</b>
2. FLAP	<u> </u>	DOWN
	ch Bar	(a) Nose Strut KNEEL when directed
Prep	aration	(b) Throttle UP when directed
		(c) Taxilaunch bar into shuttle
		(d) ThrottleIDLE when directed
4. Trim		2-3 deg nose up
5. Spee	d Brakes	IN
6. Final	Checks	(a) ThrottleMIL when directed
		(b) Control Wipeout
		<ul> <li>Stick Full Forward</li> </ul>
		<ul> <li>Stick Full Aft</li> </ul>
		<ul> <li>Stick Full Left</li> </ul>
		<ul> <li>Stick Full Right</li> </ul>
		Rudder Full Left
		<ul> <li>Rudder Full Right</li> </ul>
		(c) Eng. Inst Checked
		(d) Caution/Warnings None
7. Cata	pult Shot	(a) SaluteCAT SHOT
		(b) <b>Gear UP</b> < 250 KIAS
		(c) Flaps UP < 225 KIAS
	<u> </u>	(c) 11aps

### 1.10 LANDING - OVERHEAD PATTERN



1.	Initial Approach	• WING SWEEP	68 deg
		• HOOK	DOWN
		• SAS	ON
		• HUD	LDG
		Airspeed	300-350 KIAS
		Altitude	
2.	Initial Break	Break Interval	15-17 s
		• BANK	45-60 deg
		SPEED BRAKE	EXTEND
		• Throttle	IDLE
		• G	3-4 G
		Altitude	800 ft
3.	Break Turn	Wing Sweep	<b>AUTO</b> < 280 KIAS
		• Landing Gear	
		• FLAPS	<b>DOWN</b> < 225 KIAS
4.	Downwind	• DLCSe	lected once flaps out
		• AOA	•
		<ul> <li>LANDING CHECKLIST</li> </ul>	
		Altitude	descend to <b>600 ft</b>

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5.	Final Turn	180 Deg Position  • Abeam Pos 90 Deg Position	1-1.2 nmi
		• AOA	DONUT
		Altitude	400-500 ft
6.	Intercept Glides-	• Distance	3/4 Mile
	lope	Altitude	360 ft
		• AOA	ON-SPEED

### 1.11 LANDING - CHECKLIST

1.	Wing Sweep	20 deg AUTO
2.	Wheels	• Lights
3.	SAS	ON
4.	FLAPS	DOWN
5.	DLC	Checked
6.	Hook	HOOKDOWN     Transition LightOUT
7.	Harness	Locked
8.	Speedbrakes	EXT
9.	Brakes	Check
10.	Fuel	Check

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1.12 AERIAL REFUELING

# 1.13 AIRSTART

Before significant spooldown (a) Non-Running ENGIDLE or above
If no relight occurs (b) Non-Running ENG OFF then IDLE  If still no relight occurs (c) ENG MODE SEC (d) Non-Running ENG OFF then IDLE
With one ENG running, if Spooldown fails  (a) Non-Running ENG
(g) Non-Running ENG OFF then IDLE  If still no start  (h) ENG MODE SEC  (i) Non-Running ENG OFF then IDLE
(a) Airspeed       >450 kts         (b) Throttle       IDLE or above         (c) BACK UP IGNITION       ON         If no relight occurs       OFF then IDLE
If still no relight       (e) ENG MODE       SEC         (f) Throttle       OFF then IDLE         (a) BACK UP IGNITION       OFF         (b) ENG MODE       PRI

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### 2 SYSTEMS

# 2.1 AFCS - SAS

· SAS	Stability Augmentation System
	<ul><li>Not Fly-by-Wire</li></ul>
	<ul> <li>Automatic control surface commands generated by analog computer to im- prove stability</li> </ul>
· Controls	<ul> <li>Three individual Switches</li> </ul>
	- Pitch
	- Roll
	- Yaw
<ul> <li>Autopilot Emer-</li> </ul>	<ul> <li>Paddle on Stick</li> </ul>
gency Disengage Paddle	<ul> <li>Disengages Autopilot Modes</li> </ul>
	<ul> <li>Deactivates Pitch, Roll SAS Channels</li> </ul>

### 2.2 AFCS - AUTOPILOT

<ul> <li>Attitude Hold</li> </ul>	Basic Attitude Hold
	<ul> <li>Maintains existing pitch &amp; roll</li> <li>Attitude can be changed with stick input</li> <li>If engaged outside limits will automatically move within range</li> </ul>
	• Limits
	<ul><li>Pitch: 30 deg</li><li>Roll: 60 deg</li></ul>
	Engagement
	(a) SAS Switches
	(d) Heading Mode OFF (e) Autopilot Switch ENGAGE (FWD)

<ul> <li>Altitude Hold</li> </ul>	Barometric Altitude Hold
	<ul> <li>Maintains current barometric altitude</li> </ul>
	• Limits
	<ul><li>Vertical velocity: &lt; 100 ft/s</li></ul>
	• Engagement
	(a) SAS SwitchesON (FWD) (b) Autopilot Switch ENGAGE (FWD) (c) Alt. Hold ModeALT (FWD) (d) A/P REF Light Wait until appears (e) NWS ButtonPress
<ul> <li>Heading Hold</li> </ul>	<ul> <li>Magnetic Heading Hold</li> </ul>
	<ul> <li>Maintains current magneatic heading</li> </ul>
	• Limits
	- Bank angle < 5 deg
	• Engagement
	(a) SAS SwitchesON (FWD) (b) Autopilot Switch ENGAGE (FWD) (c) Heading ModeHDG (FWD)
Ground Track	Autopilot follows ground track
	- Similar to heading hold
	- Compensates for wind drift
	- Uses INS data instead of mag. bearing
	• Limits
	- Bank angle < 5 deg
	Engagement
	(a) SAS Switches       ON (FWD)         (b) Autopilot Switch       ENGAGE (FWD)         (c) Heading Mode       GT (AFT)         (d) A/P REF Light       Wait until appears         (e) NWS Button       Press
· VEC/PCD	Vector / Precision Course Direction
	<ul> <li>Allows Link 4 controller to remotely direct the aircraft</li> <li>Not Modelled in DCS</li> </ul>
• ACL	Automatic Carrier Landing
	- See relevant section

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- Autopilot Emergency Disengage Paddle
- Paddle on Stick
  - Disengages Autopilot Modes
  - Deactivates Pitch, Roll SAS Channels

# 2.3 APC/AUTOTHROTTLE

•	APC	Approach Power Compensator
		<ul><li>Automatic throttle control</li><li>Maintains ON SPEED AoA</li></ul>
•	Conditions	Engagement is inhibited / APC is disengaged if conditions not met  Throttles
•	Engage	Throttle Mode AUTO (FWD)
•	Disengage	Cage/Seam Button

### 2.4 ACLS

# 2.5 WING-SWEEP

• Overview	<ul> <li>In Flight Limited between 20 deg &amp; 68 deg</li> <li>On Ground can Oversweep to 75 deg</li> <li>Hydromechanically Controlled</li> </ul>		
	<ul><li>Automatically through CADC</li><li>Manually with emergency wing-sweep handle</li></ul>		
	<ul><li>15 deg/s at 1g loading</li><li>Mechanically linked to ensure symmetry</li></ul>		
· CADC Modes	• AUTO		
	<ul> <li>CADC controls wing position as function of current Mach via wing-sweep pro- gram</li> </ul>		
	• MAN		
	<ul> <li>Pilot manually chooses desired wing sweep angle with thumb controller</li> </ul>		
	• BOMB		
	<ul> <li>Sets wing sweep to 55 deg or further</li> </ul>		

• Emergency Mode		Emergency Wing-Sweep Handle	
		<ul> <li>Moved with wing sweep program by spider detent under normal operation</li> <li>Can be forced out of spider detent and moved manually</li> </ul>	
•	Oversweep	<ul> <li>Selected via Emergency Wing-Sweep Handle</li> </ul>	
		(a) Em. Wing-Sweep	
•	Return to CADC Control	After Emergency Mode / Oversweep	
		(a) <b>Em. Wing-Sweep Spider Detent</b> (Fwd on startup)	
		(b) MASTER RESET Press	

Indicated Mach	Max Forward Wing Position
0.4	20 deg
0.7	25 deg
0.8	50 deg
0.9	60 deg
1.0	68 deg

# 2.6 NAVIGATION - OVERVIEW

Pilot Cockpit Interface		
· HUD	Heads <b>U</b> p <b>D</b> isplay • Displays WRITE ME information	
· VDI	Vertical Display Indicator • placeholder	
• HSD	Horizontal Situation Display  • NAV Mode Information	
	<ul> <li>Diamond - Current heading</li> <li>Chevron - TACAN TO bearing</li> <li>+ - TACAN FROM bearing</li> <li>House - ADF bearing</li> <li>RNG - Range to Waypoint (nm)</li> <li>MODE - NAV STEER mode</li> <li>W - Wind heading / speed (kts)</li> <li>TAS - True AirSpeed (kts)</li> <li>GS - GroundSpeed (kts)</li> </ul>	
	TID Mode Information	
	<ul><li>Overhead View</li><li>Waypoint Coordinates</li></ul>	
• BDHI	placeholder	
Standby Mag- netic Compass	• placeholder	
<ul> <li>Tacan Control</li> <li>Panel</li> </ul>	• placeholder	
STEER CMD Selectors	• placeholder	

# 2.7 NAVIGATION - INS

<ul> <li>Contributing</li> </ul>	• IMU – Inertial Measurement Unit
Subsystems	<ul> <li>4 Gimbals - No gimbal-lock, corrects platform attitude errors</li> <li>2 Gyros - Source for aircraft attitude data</li> <li>3 Accelerometers - Source for aircraft acceleration data</li> </ul>
	CSDC - Computer Signal Data Converter
	<ul> <li>Processes sensor signals including IMU data</li> </ul>
CSDC Data	(a) INS - Primary nav mode
Modes	<ul><li>Velocity Data – IMU</li><li>Pitch/Roll Data – IMU</li></ul>
	(b) IMU/AM - Backup mode selected by RIO or automatically when CSDC determines IMU velocity data unreliable.
	<ul> <li>Velocity Data – Calculated from true airspeed &amp; stored wind</li> <li>Pitch/Roll Data – IMU</li> </ul>
	(c) AHRS/AM – Further degraded mode selected by RIO or automatically when CSDC detects total INS failure
	<ul> <li>Heading - Mag heading &amp; MAG VAR</li> <li>Velocity Data - Calculated from true airspeed &amp; stored wind</li> <li>Pitch/Roll Data - AHRS</li> </ul>

# 2.8 NAVIGATION - ALIGNMENT

<ul> <li>Ground Align</li> </ul>	(a)
· Carrier Align D/L	
<ul> <li>Carrier Align Handset</li> </ul>	
Reinitialization	
<ul> <li>Automatic Stored Heading</li> </ul>	
Catapult Align	

#### 2.9 NAVIGATION - WAYPOINT

- Reference Point Types
- Navigation Waypoint Used for navigation. Maximum of 3 stored simultaneously
- Fixed Point (FP) Arbitrary point to establish current position relative to external references
- Initial Point (IP) Starting point for A/G attack run
- Surface Target (ST) Enemy surface target
- **Defended Point (DP)** Area to protect (i.e friendly forces)
- Hostile Area (HA) Area with known ground or air hostiles
- Home Base (HB) Airfield / CV
- 2.10 NAVIGATION TACAN
- 2.11 NAVIGATION VOR/ADF

# 2.12 COMMS - OVERVIEW

• ARC-159 UHF 1	<ul> <li>Air-to-Air &amp; Air-to-Surface Communica- tion</li> <li>Pilot Controlled</li> <li>Frequency</li> </ul>
	<ul><li>Range - 225.000 - 399.975 MHz</li><li>Steps - 25 kHz</li><li>Channels - 20</li></ul>
• ARC-182 V/UHF 2	<ul> <li>Air-to-Air &amp; Air-to-Surface Communication</li> <li>RIO Controlled</li> <li>Frequency <ul> <li>Band 1 - 30 - 88 MHz</li> <li>Band 2 - 108 - 156 MHz</li> <li>Band 3 - 156 - 174 MHz</li> <li>Band 4 - 225 - 399.975 MHz</li> <li>Steps - 25 kHz</li> <li>Channels - 20</li> </ul> </li> </ul>
• ARA-50 UHF ADF	<ul> <li>UHF Automatic Direction Finder</li> <li>LoS bearing to UHF Transmitter</li> <li>Bearing displayed on BDHI, Pilot HSD</li> <li>5 min Warmup</li> </ul>
KY-28 Voice Security Equipment	<ul> <li>Voice Ciphering</li> <li>Integrated with UHF 1 and V/UHF 2</li> <li>2 min Warmup</li> </ul>

# 2.13 COMMS - ARC-159 UHF 1

• ARC-159 UHF1	<ul> <li>Air-to-Air &amp; Air-to-Surface Communication</li> <li>Pilot Controlled</li> <li>Frequency</li> </ul>
	<ul> <li>Range - 225.000 - 399.975 MHz</li> <li>Steps - 25 kHz</li> <li>Channels - 20</li> </ul>
• VOL Knob	Controls Pilot UHF 1 Audio Level
BRT/TEST Knob	<ul> <li>Controls Radio FREQ Display</li> <li>Turn past max to display 888.888</li> </ul>

SYSTEMS		F-14A/B	REV: 20220125
	_		

<ul> <li>SQL Switch</li> </ul>	<ul> <li>Toggles radio squelch (noise attenuation)</li> </ul>	
READ Switch	<ul> <li>Displays Frequency of Selected Preset Channel</li> </ul>	
LOAD Button	<ul> <li>Saves Displayed Frequency to Selected Preset Channel</li> </ul>	
TONE Button	<ul> <li>Steady 1.020 kHz Test Tone</li> </ul>	
Mode Selector	Frequency Selection Method	
	- <b>GUARD</b> - 243.000 MHz	
	<ul> <li>MANUAL – Manual tuning</li> </ul>	
	- PRESET - Preset channels	
• Function Selector	<ul> <li>Selects Transceivers to Energize</li> </ul>	
	<ul> <li>ADF – Not simulated</li> </ul>	
	- BOTH - Main & Guard	
	– MAIN – Main	
	- OFF - Secures UHF 1 radio	
· CHAN SEL	<ul> <li>Selects from 20 preset Channels</li> </ul>	

# 2.14 COMMS - ARC-182 V/UHF 2

•	ARC-182 V/UHF 2	<ul> <li>Air-to-Air &amp; Air-to-Surface Communication</li> <li>RIO Controlled</li> <li>Frequency</li> </ul>
		<ul> <li>Band 1 - 30 - 88 MHz</li> <li>Band 2 - 108 - 156 MHz</li> <li>Band 3 - 156 - 174 MHz</li> <li>Band 4 - 225 - 399.975 MHz</li> <li>Steps - 25 kHz</li> <li>Channels - 20</li> </ul>
•	VOL Knob	<ul> <li>Controls RIO UHF 2 Audio Level</li> </ul>
•	BRT/TEST Knob	Controls Radio FREQ Display
•	SQL Switch	Toggles radio squelch (noise attenuation)

SYSIEMS	1-14A/B REV: 20220125
• Mode Selector	Transceiver Settings
	<ul> <li>OFF - Secures V/UHF radio unless frequency mode set to 243</li> </ul>
	<ul> <li>T/R - Energizes transmitter and main receiver</li> </ul>
	<ul> <li>T/R &amp; G - Energizes transmitter, main, and guard receiver</li> </ul>
	<ul> <li>DF – Automatic direction finding from 108 - 399.975 MHz</li> </ul>
	- TEST - BIT
• CHAN SEL	<ul> <li>Selects Frequency Tuning Mode</li> </ul>
Outer Dial	- 243 - Selects UHF Guard
	- MAN - Manual Select frequency
	<ul> <li>G - Tunes Tranceiver to guard frequecy in last selected band</li> </ul>
	<ul> <li>PRESET – Allows selection between 40 preset channels (31-40 are Have Quick and not simulated)</li> </ul>
	READ – Displays frequency of selected preset channel
	<ul> <li>LOAD – Saves displayed frequency to</li> </ul>

# 2.15 COMMS - KY-28 VOICE SECURITY EQUIPMENT

**CHAN SEL** 

Inner Dial

•	KY-28 Voice Security Equipment	<ul><li>Voice Ciphering</li><li>Integrated with UHF 1 and V/UHF 2</li><li>2 min Warmup</li></ul>
•	ZEROIZE Switch	<ul><li>Lift Guard to Erase Preloaded Codes</li><li>Codes loaded via ground crew</li></ul>
•	Power-Mode Switch	<ul> <li>Selects Mode</li> <li>P/OFF - Removes power from system</li> <li>C - Transmit / Receive in secure mode</li> <li>DELAY - Between PTT and trans.</li> </ul>

• Selects one of 40 Preset Channels

F-14A/

REV: 20220125

Radio-Select Switch

- Selects Radio Mode
  - RELAY Acts as relay for other stations (not simulated)
  - RAD-2 Secure voice for V/UHF 2
  - RAD-1 Secure voice for UHF1

# 2.16 LINK 4 DATALINK - OVERVIEW

· Link 4	Modes – Mutually exclusive
	- Link 4A - AWACS / Surface Ship
	- Link 4C - Fighter to Fighter
	• Data Speed – up to 5000 bit/s!
· Link 4A	Network - AWACS / Surface Ship
	Additionally used for ACLS
· Link 4C	Network - Fighter to Fighter
	- Up to four F-14s
	- Unique to F-14
Basic Operation	(a) <b>Power Switch</b> As Desired
	• Link 4A ON
	• Link 4C AUX
	(b) Mode SwitchTAC
	(c) FrequencySet

# 2.17 LINK 4 DATALINK - CONTROL PANEL

• Test Switch	Controls Test / Anti-Jam Modes
	- TEST - Initiates BIT
	- NORM - Normal Operation
	<ul><li>A-J - Anti-Jam (not simulated)</li></ul>
• Frequency	Selects Datalink Frequency
Thumbwheels	- First Digit - Fixed as 3
	- Allowable Range - 300.0 - 324.9 MHz
• Power Switch	Controls System Power
	- ON - Enables Link 4A
	<ul> <li>OFF – Disables system</li> </ul>
	- AUX - Enables Link 4C

F-14A/B REV: 20220125

# 2.18 LINK 4 DATALINK - REPLY/ANTENNA PANEL

• ANTENNA	Selects Antenna
Switch	<ul> <li>Shared with UHF1 - Mutually exclusive</li> <li>UHF1 LWR / DL UPR</li> <li>UHF1 UPR / DL LWR</li> </ul>
• REPLY Switch	Sets Reply Mode
	<ul> <li>NORM - Own Aircraft replies to datalink messages</li> <li>CANC - Receive only</li> </ul>
• MODE Switch	Controls Overall Mode
	<ul><li>TAC - Normal airborne mode</li><li>CAINS/WAYPT - Enables CV align</li></ul>
Address Thumbwheels	<ul> <li>Sets Two Least Significant Bits of Aircraft D/L Address</li> </ul>

# 2.19 ALR-67 RWR - CONTROLS / OVERVIEW

DIAMP C : I	
• PWR Switch	Set to ON to Operate
· VOL Knob	Sets RIO Audio Level
• TEST Switch	<ul> <li>Springloaded to Center</li> <li>BIT - Initiates Build In Test</li> <li>SPL - Holds BIT status page while held</li> </ul>
• MODE Switch	<ul> <li>Springloaded to Center</li> <li>OFST - Separates overlapping symbols</li> <li>LMT - Displays 6 highest threats</li> </ul>
• DISPLAY TYPE	Changes Priority of Display
Selector	<ul> <li>NORM - Normal threat symbology</li> <li>AI - Airborne Interceptor prioritized</li> <li>AAA - Anti-aircraft artillery prioritized</li> <li>UNK - Unknown prioritized</li> <li>FRIEND - Friendly threats prioritized</li> </ul>
	<ul> <li>Indicated by Letter in Display Center</li> </ul>
· Display	Outer Band     Critical Band     Imminent threat to own aircraft     Blinking indicates engaging own aircraft craft
	Middle Band
	<ul> <li>Lethal Band</li> <li>Potentially threatening emitters</li> <li>Not actively engaging own aircraft</li> <li>Inner Band</li> </ul>
	- Non-Lethal Band
	Not currently within capability of emitter
	Inner Circle
	<ul> <li>N, I, A, U, F - Prioritization type</li> <li>O - Offset</li> <li>L - Limit</li> <li>B - BIT Failure</li> <li>T - Thermal overload</li> </ul>

F-14A/E

**REV: 20220125** 

**Alert Tones** 

- Short Tone New emitter / emitter moved
- Slow Warbling Threat in critical band
- Fast Warbling Threat actively engaging own aircraft
- **4-Tone Sequence** New threat capable of silently engaging own aircraft

## 2.20 ALR-67 RWR - THREAT SYMBOLOGY

SHIPS				
AB	Arleigh Burke			
AK	Admiral Kuznetsov			
GR	Grisha 5 (Albatros)			
HP   Oliver Hazard Perry				
J2	Type 054A Frigate, "Jiangkai II class"			
KK	Krivak 3 (Rezky)			
KV	Kirov (Pyotr Velikiy)			
LI	Type 052B Destroyer, "Luyang I class"			
L2	Type 052C Destroyer, "Luyang II class"			
N	Ship with Nav Radar			
NE	Neustrashimy			
NZ	Nimitz (Vinson, Stennis)			
SV	Slava (Moscow)			
TC	Ticonderoga			
TT	Tarantul 3 (Molniya)			
TW	Tarawa			
YU	Type 071 Amphibious Transport Dock, "Yuzhao class"			
	AIRCRAFT			
14	F-14A/B			
15	F-15C/E			
16	F-16C			
17	JF-17			
18	F/A-18C			
19	MiG-19			

21	MiG-21bis
23	MiG-23MLD
24	Su-24M/MR
25	MiG-25PD
29	MiG-29A/G/S Su-27 Su-33 J-11A
30	Su-30
31	MiG-31
34	Su-34
37	AJS-37
39	Su-25TM
50	A-50
52	B-52
AN	AN-26B AN-30M
AP	AH-64D
B1	B-1B
BE	Tυ-95   Tυ-142M
BF	Tu-22M3
BJ	Tu-160
<b>E2</b>	E-2D
E3	E-3C
F4	F-4E
F5	F-5E
нх	Ka-27
IL	IL-76MD IL-78M
KC	KC-135

KJ	KJ-2000		
M2	Mirage 2000-C		
	Mirage 2000-5		
<b>S3</b>	S-3B		
SH	SH-60B		
TO	Tornado		
TR	C-130 C-17A		
	AIR DEFENSE		
2	S-75 TR SNR (SA-2) "Fan Song"		
3	S-125 TR SNR-125 (SA-3) "Low Blow"		
6	Kub SA-6		
7	HQ-7TR		
8	OSA (SA-8)		
10	S-300PS 30N6 TR (SA- 10)		
11	Buk (SA-11)		
12	S-300V		
15	Tor 9A331 (SA-15)		
19	Tunguska 2C6M (SA-19)		
Α	Gepard		
	M-163 Vulcan ZSU-23-4 Shilka		
ВВ	S-300PS 64H6E SR (SA- 10/Big Bird)		
BF	Rapier Blindfire TR		
CS	S-300PS 5N66M SR (SA-10/Clam Shell)		
DE	Sborka (Dog Ear)		
FF	S-125 P-19 SR (SA-3/Flat   Face)		
GR	Roland SR		

НА	Hawk SR				
НК	<b>HK</b>   Hawk TR				
HQ	HQ-7 SR				
PT	Patriot				
RO	Roland				
RP	RP   Rapier SR				
S	<b>S</b> 1L13 55G6 EWR				
SD	SD   Buk TR (SA-11/Snow Drift)				
SN	PRW-11 (Side Net)				
	MISSILES				
М	M   AIM-54 AIM-120 MICA-EM R-37 R-77 SD-10				
	ATC				
Т	Airport ATC Radar				

## 2.21 ALE-39 CMS DISPENSER

Programmer				
• CHAFF Section	B QTY – Number of cartridges to eject in burst			
	<ul> <li>Options – 1-4 cartridges, C continuous,</li> <li>R random (4-6 cartridges)</li> </ul>			
	B INTV – Time in seconds between each car- tridge ejection			
	<ul> <li>Options1, .2, .5, .7, 1 seconds, R</li> <li>random</li> </ul>			
	S QTY – How many salvos of bursts			
	- Options - 1, 2, 4, 6, 8, 10, 15 salvos			
	• SINT - Time in seconds between salvos			
	- Options - 2, 4, 6, 8, 10 seconds			
WARNING R & C burst	settings have special <b>INTV</b> behavior			
- JAMMER Section	Jammer cartridges not implemented in DCS			
• FLARE Section	QTY – Number of cartridges to eject in burst			
	- Options - 2, 3, 4, 6, 8, 10 cartridges			
	• INTV - Time in seconds between each car- tridge ejection			
	- Options - 2, 4, 6, 8, 10 seconds			
	Control Panel			
• PWR/MODE Switch	AUTO (CHAFF) / MAN – Enables power to system and allows automatic chaff ejection program initiation			
	<ul> <li>MAN – Enables power to system</li> <li>OFF – Disables system</li> </ul>			
	1			

## 2.22 ALQ-100 / ALQ-126 DECM

#### 3 AWG-9 RADAR

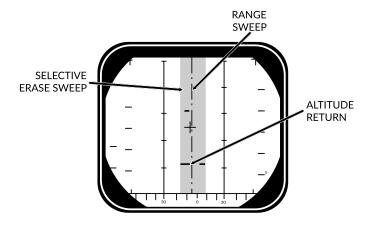
#### 3.1 MAIN MODES - OVERVIEW

	Pulse		Pulse Doppler			
	Pulse Search	P-STT	PD Search	RWS	TWS	PD-STT
Range	60 nm	50 nm	110 nm	90 nm	90 nm	90 nm
AIM-7	BRSIT	CW	BRS	SIT	-	PD
AIM-54	BRSIT	ACT	BRSIT		Multi TGT	PD/ACT

#### 3.2 MAIN MODES

· Pulse	<ul> <li>Basic Pulse w/o doppler filtering</li> </ul>		
	<ul><li>Cannot be notched</li><li>Ground Clutter</li><li>Rudimentary Ground mapping</li></ul>		
	Pulse Sub-Modes		
	<ul><li>Pulse Search</li><li>Pulse-STT</li></ul>		
· Pulse Doppler	Doppler filter> no ground returns		
	<ul> <li>Susceptible to notching</li> <li>No ground clutter</li> <li>Greater range</li> <li>Advanced sub modes</li> <li>AIM-54 Guidance</li> </ul>		
	<ul> <li>Pulse Doppler Sub-Modes</li> </ul>		
	<ul><li>PD Search</li><li>RWS</li><li>TWS</li><li>PD-STT</li></ul>		

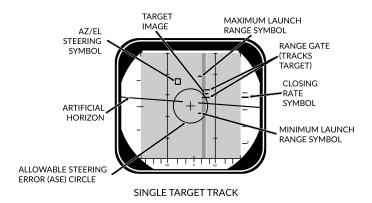
#### 3.3 PULSE MODE - PULSE SEARCH



SEARCH (±10° SCAN)

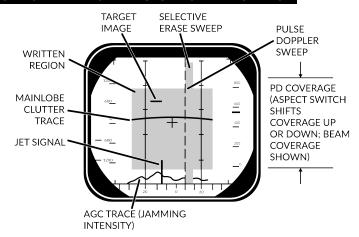
• Pulse Search		Basic Mode - AWG-9 does not use pulse doppler filtering  • Advantages		
		- All aspect target detection		
		<ul><li>Cannot be notched</li><li>Rudimentary ground mapping</li></ul>		
		Disadvantages		
		<ul> <li>Cannot discern ground returns and targets</li> </ul>		
		- Lower range		
•	DDD	Range/Azimuth		
		<ul> <li>Visual representation of radar and erase</li> </ul>		
		sweeps		
•	TID	No Information from Pulse		
		Cannot guide AIM-54		

#### 3.4 PULSE MODE - PSTT



<ul> <li>Pulse STT</li> </ul>	Lock Target w/o doppler filtering	
	<ul> <li>Advantages</li> </ul>	
	- Cannot be notched	
	<ul> <li>Disadvantages</li> </ul>	
	<ul> <li>Susceptible to ground clutter</li> </ul>	
<ul> <li>Lock Target</li> </ul>	<ul> <li>Conditions</li> </ul>	
	<ul><li>Pulse Search Mode selected</li><li>RDR HCU Mode selected</li></ul>	
	<ul> <li>Lock Target</li> </ul>	
	(a) Hold HCU Half-action	
	(b) Slew to desired Target	
	(c) HCU Full-Action to lock	
	<ul> <li>Unlock Target</li> </ul>	
	(d) HCU Half-action	
· DDD	<ul> <li>Track Indications</li> </ul>	
	- ANT TRK light	
	- RDROT light	
	<ul> <li>Tracking gates</li> </ul>	
	- Closure rate	
	– Attack Symbology	

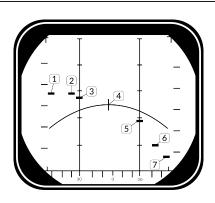
#### 3.5 PULSE DOPPLER MODE - PULSE DOPPLER SEARCH



SEARCH (±40° SCAN)

<ul> <li>Pulse Doppler Search</li> </ul>	"Early Warning" Mode - Longest Range, cannot display range  • Advantages
	<ul><li>Longest Range</li><li>Doppler Filtering</li><li>"Look Down Shoot Down"</li></ul>
	Disadvantages
	<ul><li>Can be notched</li><li>No range information</li></ul>
· DDD	<ul> <li>Closure Rate/Azimuth</li> <li>Visual representation of radar and erase sweeps</li> </ul>
Doppler Filters	Main Lobe Clutter (MLC) Filter
	<ul> <li>Own GS +/- 133 knots</li> <li>Removes main ground return</li> <li>Source of notching</li> </ul>
	• Zero Doppler Filter
	<ul> <li>Negative own GS +/- 100 knots</li> <li>Removes Radar reflection from ground directly beneath own AC</li> </ul>

• MLC Switch	<ul> <li>IN: Enables MLC filter</li> <li>AUTO: Enables MLC filter if look-up angle less than 3 deg</li> <li>OUT: Disables MLC filter</li> </ul>
• Vc Switch	<ul> <li>Changes closure rate DDD scale</li> <li>X-4: -800 to 4000 knots</li> <li>NORM: -200 to 1000 knots</li> <li>VID: -50 to 250 knots</li> </ul>
ASPECT Switch	Changes closure rate processing scale  • NOSE: -600 to 1800 knots  • BEAM: -1200 to 1200 knots  • TAIL: -1800 to 600 knots



	Look Angle	Line of Sight Rate	Target Heading
1	60 deg	1490	180 deg
2	45 deg	1500	120 deg
3	30 deg	1428	100 deg
4	0 deg	1200	90 deg
5	30 deg	672	80 deg
6	45 deg	210	60 deg
7	60 deg	-300	0 deg

#### 3.6 PULSE DOPPLER MODE - RWS

<ul> <li>Range While Search</li> </ul>	FM Ranging, used for getting good A/A picture before selecting TWS • FM Ranging	
	<ul> <li>Pulse Doppler with ranging</li> <li>TID shows momentary tracks with ranges</li> <li>Processing reduces max range</li> </ul>	
	Advantages	
	<ul> <li>Long Range</li> <li>Doppler Filtering</li> <li>"Look Down Shoot Down"</li> <li>Signal Processing</li> </ul>	
	Disadvantages	
	- Can be notched	
· DDD	<ul> <li>Closure Rate/Azimuth</li> <li>Visual representation of radar and erase sweeps</li> </ul>	
· TID	<ul> <li>Momentary Tracks</li> <li>Max concurrent tracks: 48</li> <li>Cannot lock targets from TID</li> </ul>	
<ul> <li>Filtering</li> </ul>	Same as Pulse Doppler Search	

## 3.7 PULSE DOPPLER MODE - TWS

Track While Scan	Builds Track Files, high situational awareness, multi-target AIM-54 launch  • Track Files
	<ul> <li>AWG-9 builds Trackfiles for contacts</li> <li>Can launch multiple AIM-54</li> <li>Processing reduces max range</li> <li>Can lock targets from TID</li> </ul>
	FM Ranging
	<ul> <li>Pulse Doppler with ranging</li> <li>TID shows momentary tracks with ranges</li> <li>Processing reduces max range</li> </ul>
	Advantages
	<ul><li>Doppler Filtering</li><li>Multi-Target AIM-54</li></ul>
	<ul> <li>Disadvantages</li> </ul>
	- Lowest Range
• DDD	- Can be notched  • Closure Rate/Azimuth
	Visual representation of radar and erase sweeps
· TID	Tracksfiles
	Max concurrent tracks: 24
	Max displayed tracks: 18
• Filtering	Same as Pulse Doppler Search
Scan Volume	Trackfiles require update every 2.5 s -> • 20 deg 4 bar (if selected) • 40 deg 2 bar (else)
• TID Mode Selector	<ul> <li>GND STAB: Ground Stabilized, True North is up on TID</li> <li>A/C STAB: Aircraft Stabilized</li> <li>ATTAK: same as A/C STAB with superimposed attack steering symbology</li> <li>TV: Displays TCS on TID, dispays LANTIRN on TID if equipped</li> </ul>

AWG-9 RADAR	F-14A/B	REV: 20220125
		<del> </del>

Selector Buttons	<ul> <li>RID DISABLE: Not simulated</li> <li>ALT NUM: Enables display of track altitudes on left side of track symbols</li> <li>SYM ELEM: Enables display of all supplementary symbology of tracks and waypoints</li> <li>DATA LINK: Enables display of D/L contacts</li> <li>JAM STROBE: Enables display of jam strobes</li> <li>NON-ATTK: enables/disables display of targets not possible to engage (friendlies)</li> <li>LAUNCH ZONE: Enables display of weapon launch zones</li> <li>VEL VECTOR: Enables display of velocity vectors</li> </ul>
TRACK HOLD CLSN Steering Buttons	<ul> <li>TRACK HOLD</li> <li>Normally: Tracks maintained for 14 s         after last observation</li> <li>Track Hold: maintained for 2 min after         last observation</li> </ul>
	CLSN Button
	<ul> <li>begins collision steering to currently tracked target</li> <li>enables Steering Centroid if in TWS</li> <li>LD CLSN presents azimuth steering only</li> <li>CLSN presents both azimuth and elevation steering</li> </ul>
• TWS AUTO / MAN	<ul> <li>TWS MAN: Manual azimuth/elevation control, target designation by RIO</li> <li>TWS AUTO: Automatic prioritization of targets and azimuth elevation control</li> </ul>

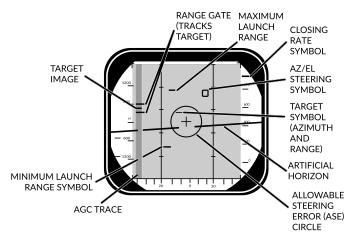
## 3.8 PULSE DOPPLER MODE - TWS MAN

• TWS MAN	• Target Selection: Manual				
	Scan Azimuth/Elevation: Manual				
<ul> <li>Target Selection</li> </ul>	<ul> <li>Conditions</li> </ul>				
	<ul><li>TWS MAN Radar Mode selected</li><li>TID CURSOR TID Mode selected</li></ul>				
	<ul> <li>Hook Target</li> </ul>				
	<ul><li>(a) Hold HCU Half-Action</li><li>(b) Slew TID Cursor over desired Tgt</li><li>(c) HCU Full-Action to select Tgt</li></ul>				
	TID Symbology				
	<ul> <li>Range (RA)</li> <li>Bearing (BR)</li> <li>Altitude (AL)</li> <li>Magnetic course (MC)</li> </ul>				
	<ul> <li>Lock Target</li> </ul>				
	(d) Press <b>PD STT</b> or <b>Pulse STT</b> buttons				
	Deselect Target				
	(e) press HCU Half-Action				
· AIM-54 Launch	Automatically selects TWS AUTO				
	<ul> <li>Prevents selection of TWS MAN</li> </ul>				

## 3.9 PULSE DOPPLER MODE - TWS AUTO

• TWS AUTO	<ul> <li>Target Selection: prioritizes contacts based off range, aspect, closure</li> <li>Scan Azimuth/Elevation: Geometric center of targets in scan volume</li> </ul>
· Centroid / Steer-	Steering Centroid
ing Cues	<ul> <li>facilitates steering cues</li> <li>HUD, VDI, TID, DDD</li> <li>Appears as X on TID</li> <li>Takes Gimbal limits into account</li> <li>Weights individual Tracks based on parameters</li> </ul>
	<ul> <li>Illumination Centroid</li> </ul>
	<ul> <li>Not Visible</li> <li>Controls azimuth and elevation of scan pattern</li> <li>Takes scan volume into account</li> </ul>
<ul> <li>Pilot Steering</li> </ul>	<ul> <li>Conditions</li> </ul>
Cues	<ul> <li>A-A HUD Mode selected</li> <li>Master Arm ON (UP)</li> <li>AIM-54 or AIM-7 selected</li> <li>TWS-AUTO selected</li> </ul>

#### 3.10 PULSE DOPPLER MODE - PDSTT



SINGLE TARGET TRACK

Pulse Doppler STT	Lock Target with doppler filtering  • Advantages			
	<ul> <li>Ground Clutter filtering</li> </ul>			
	Disadvantages			
	- Susceptible to notching			
<ul> <li>Lock Target</li> </ul>	Conditions			
	<ul><li>Pulse Doppler Mode selected (PD Search, RWS, TWS)</li><li>RDR HCU Mode selected</li></ul>			
	• Lock Target			
	<ul><li>(a) Hold HCU Half-action</li><li>(b) Slew to desired Target</li><li>(c) HCU Full-Action to lock</li></ul>			
	Unlock Target			
	(d) HCU Half-action			
· DDD	Track Indications			
	<ul> <li>ANT TRK light</li> <li>RDROT light</li> <li>Tracking gates</li> <li>Closure rate</li> <li>Attack Symbology</li> </ul>			

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#### 3.11 ACM MODES - OVERVIEW

	PLM	VSL	PAL	MRL
Range	5 nm	5 nm	15 nm	5 nm
Description	Boresight	Vertical	Horizontal	RIO
Weapons		Gun +	All Missiles	

• PLM	Pilot Lockon Mode     Highest Priority     ACM     Search Pattern     - Small Boresight     - Range: 5 nm
· VSL	<ul> <li>Vertical Scan Lockon</li> <li>HI Search Pattern</li> <li>Width: 5 deg</li> <li>Vertical: +15 to +55 deg</li> <li>Range: 5 nm</li> </ul>
	• LO Search Pattern  - Width: 5 deg  - Vertical: -15 to +25 deg  - Range: 5 nm
	RIO/PILOT Controlled
· PAL	<ul><li>Pilot Automatic Lockon</li><li>Search Pattern</li></ul>
	<ul><li>Width: +/- 20 deg</li><li>Vertical: 8-bar</li><li>Range: 15 nm</li></ul>
• MRL	<ul> <li>Manual Rapid Lockon</li> <li>RIO Controlled</li> <li>Search Pattern</li> </ul>
	<ul><li>HCU Controlled</li><li>Range: 5 nm</li></ul>

#### 3.13 TID SYMBOLOGY

GENERAL		
Center Dot	•	Basic Component of Symbols
		<ul> <li>Marks coordinates of symbol</li> </ul>
Own AC		Symbol representing own air- craft
		<ul> <li>Ground Stabilized: Moves</li> <li>Aircraft Stabilized: Stationary</li> <li>Outside TID: line drawn from TID center towards symbol</li> </ul>
TID Cursor		Hook Cursor
		<ul> <li>Controlled by HCU in TID mode</li> </ul>
		<ul> <li>Half-Action</li> </ul>
		<ul> <li>Enables display of symbol</li> <li>Enables HCU stick to move cursor</li> </ul>
		• Full-Action
		<ul> <li>Hooks closest symbol</li> <li>If no symbol near, cursor dropped at location</li> </ul>
TWS Steering Cen- troid	$ \times $	Steering centroid of TWS     tracks
		<ul> <li>Selected by WCS for weapons engagement</li> </ul>
ONBOARD SENSORS		Symbol Above Dot
Unknown	「・	<ul><li> Unknown Sensor Track</li><li> All Returns in RWS</li></ul>
Hostile		<ul> <li>Sensor Track designated Hostile by RIO</li> </ul>
Friend	•	<ul> <li>Sensor Track designated Friendly by RIO</li> </ul>
Angle-Tracked		Radar Angle Tracking
Radar Target		- Jamming Target

Angle-Tracked Radar Target with Altitude Difference Ranging TCS-Angle Tracked		<ul> <li>Radar Angle Tracking</li> <li>Jamming Target</li> <li>Alt. diff. ranging</li> <li>TCS Angle Tracking</li> </ul>
Target	•>	
TCS-Angle Tracked Target with Altitude Difference Ranging		TCS Angle Tracking     Alt. diff. ranging
D/L TARGETS		Symbol Below Dot
Unknown	•	D/L Track designated Un- known by Source
Hostile	•	<ul> <li>D/L Track designated Hostile by Source</li> </ul>
Friendly	$  \cdot  $	<ul> <li>D/L Track designated Friendly by Source</li> </ul>
MANUAL REF POI	NTS	
Home base		<ul> <li>Waypoint Representing</li> <li>Home Base</li> <li>Carrier</li> <li>Airfield</li> </ul>
Waypoint	•	<ul> <li>Nav Waypoint</li> <li>Supplanted by Number</li> <li>1, 2, or 3</li> </ul>
Defended Point		Waypoint to Defend
Fixed Point	$\times$	Generic Waypoint
Hostile Area		Waypoint Indicating Hostile Area
Surface Target		Waypoint Indicating Surface Target
IP D// DEE BOUNT	+	Initial Point     Waypoint for A/G engagement
D/L REF POINT	5	



or D/L Track

of symbol

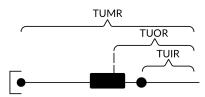
• Indicates Multiple Targets

- Horizontal bar on left side

Data Link Challenge		<ul> <li>Additional Symbology on D/L Track</li> </ul>
		<ul> <li>Small V with center at center dot</li> </ul>
		<ul> <li>Command to Visually Identify</li> </ul>
Track Extrapolated	\\hat{\chi}\	<ul> <li>Additional Symbology on TWS or D/L Track</li> </ul>
		<ul> <li>Small X with center at center dot</li> </ul>
		<ul> <li>No Update within 8 seconds</li> </ul>
		<ul> <li>Track deleted after 14 seconds</li> </ul>
		<ul> <li>Or after 2 min if track hold</li> </ul>
Altitude Numerics	<b>4</b> ∕•̂\	<ul> <li>Altitude to Nearest Ten Thou- sand</li> </ul>
		- example: 35000-45000
Firing Order Numer- ics	<b>/^</b> \4	<ul> <li>Indicates AIM-54 Prioritiza- tion</li> </ul>
		<ul><li>Numbers 1-6</li><li>Only in TWS</li></ul>
Time-to-Impact (TTI)	<i>^</i> \$\  6	After AIM-54 Launch
		<ul> <li>Prioritization replaced with estimated TTI</li> </ul>
		<ul> <li>Flashes after Pitbull</li> </ul>
Velocity Vector		<ul> <li>Additional Symbology from center Dot</li> </ul>
		<ul> <li>Direction represents track heading</li> </ul>
		<ul> <li>Length represents speed</li> </ul>
		<ul> <li>Varies with Mode</li> </ul>
		<ul> <li>Ground Stabilized: true heading and ground speed</li> <li>Aircraft Stabilized: relative heading and velocity</li> </ul>

#### Launch Zone Vectors





- Additional Symbology for AIM-54
  - Selected manually by RIO
  - Or 60 seconds from max launch

#### TUMR

- Time-Until-Minimum-Range
- Max: 180 seconds, 1.5 inches

#### TUOR

- Time-Until-Optimal-Range

- Indicates operator concern

 Start of bar is 8 seconds from optimum

#### TUIR

- Time-Until-In-Range

Jamming Strobe	• Line from own AC towards Jammer
Radar Antenna Scan Pattern Azimuth Limits	<ul> <li>Limits of Current Scan Azimuth</li> <li>Single Line in STT</li> </ul>
Data Link Jamming Strobe	<ul> <li>Line from D/L point towards</li> <li>Jammer</li> </ul>
Data Link Pointer	Additional Symbology on D/L Track     Circle

Data Link Priority Kill		<ul> <li>Additional Symbology on D/L Track         <ul> <li>Square</li> <li>Indicates target must be destroyed</li> <li>No effect on WCS prioritization</li> </ul> </li> </ul>
ATTACK DISPLAY SYME	OLUGI	
Artificial Horizon		<ul> <li>Represents Pitch and Roll</li> </ul>
Steering Guidance Symbol		<ul> <li>Represents Steering Error</li> <li>Should be placed as near as possible to center of ASE circle</li> </ul>
Allowable Steering Error Circle	•	<ul> <li>Indicates Allowable Steering Error for Missile Launch</li> <li>Size Varies with Geometry, Mode, Missile</li> </ul>
Breakaway Indica- tion	$\times$	Appears when Target Range Less than Minimum for Se- lected Weapon

TCS - LANTIRN

#### 5 LANTIRN

## 5.1 OVERVIEW

· LANTIRN	Low Altitude Navigation and Targeting Infra-Red for Night  Only Targeting Pod – Nav pod was deleted
	Incomplete Integration – Own control panel, supplants TCS feed
<ul> <li>Master Modes</li> </ul>	<ul> <li>A/G - Allows bomb release guidance</li> <li>A/A - Optimized for air targets</li> </ul>
• FOV Levels Overview	<ul> <li>Wide</li> <li>FOV - 5.9 deg</li> <li>Slew - 8.5 deg/s</li> </ul>
	<ul> <li>Narrow</li> <li>FOV – 1.7 deg</li> <li>Slew – 1.8 deg/s</li> </ul>
	• Expanded
	- FOV - 0.8 deg - Slew - 0.7 deg/s
	<ul> <li>Digital Zoom – Degraded quality</li> </ul>

#### 5.2 OVERVIEW - STARTUP

1.	Power Switch	POD
2.	Pod Startup Sequence	<ul> <li>8 min startup sequence</li> <li>MODE Switch shows STBY when complete</li> </ul>
3.	MODE Switch	Press
4.	Initialization Sequence	<ul><li>30 sec initialization</li><li>MODE Switch shows OPER when ready</li></ul>
5.	VIDEO Switch	FLIR
6.	TID MODE	TV

## 5.3 OVERVIEW - POINTING MODES

Sensor Modes	Contrast Lock
Overview	<ul><li>Area Track</li><li>Point Track</li></ul>
	• Q Designation
	<ul><li>Directional Q - QSNO / QADL / QHUD</li><li>Location Q - QWp / QDES</li></ul>
Directional Q	Do Not Allow Weapon Guidance     QSNO
	<ul> <li>Pod slaved to ground 15 nm in front along own aircraft heading</li> </ul>
	• QADL
	<ul><li>Pod slaved to ADL</li><li>In A/A mode</li></ul>
	• QHUD
	<ul><li>Pod slaved to HUD</li><li>In A/G mode</li></ul>
• Location Q	Allow Weapon Guidance     QWp
	<ul><li>Pod slaved to WCS waypoint</li><li>Cycled with QWp+ / QWp-</li></ul>
	• QDES
	<ul> <li>Designate targets for engagement</li> <li>LANTIRN Trigger Second Detent to designate</li> <li>Coordinates can be manually added to</li> </ul>
	WCS for navigation

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## 5.4 OVERVIEW - LASING/DESIGNATION

<ul> <li>A/G Designation</li> </ul>	(a) <b>Designate</b>	Trigger Full-Action	
	<ul> <li>Laser Fires</li> </ul>		
	Slant Range calculated		
	• Time-to-G	o calculated	
<ul> <li>Steering Cues</li> </ul>	<ul> <li>Automatically activated when QDES se- lected/designated</li> </ul>		
	<ul> <li>QDES remains e</li> </ul>	even if new Q selected	
	<ul> <li>Cues still point t another point</li> </ul>	owards QDES even if pod at	
Manual Lase	(a) <b>Lase</b>	Trigger Half-Action Hold	
Latched Lase	• Effect – Lases for 60 sec		
	(a) Activate	Latch Lase Button Press	
		Latch Lase Button Press	
	(c) <b>Deactivate</b>	Trigger Half-Action	
Auto Lase	• Effect – Fires fro	om -10 to +4 sec TIMP	
	(a) Laser Mode	Slider AFT Short	
	(b) <b>Cycle A/M</b>	Right 4-Way Depress	
• Laser Notes	Always at curre	ent Pod location	
	<ul> <li>Can point to diff</li> </ul>	ferent location than QDES	

## 5.5 CONTROLS - PANEL

• Power Switch	<ul> <li>OFF - Disables power to system</li> <li>IMU - Only powers LANTIRN IMU (Not Simulated in DCS)</li> <li>POD - Powers whole system</li> </ul>
• MODE Switch	• STBY – Standby • OPER – Operational
• LASER Switch	ARM – Arms laser     SAFE – Inhibits laser use
• VIDEO Switch	<ul> <li>FLIR – Displays LANTIRN FLIR on TID</li> <li>TCS – Displays TCS video on TID</li> </ul>
· Indicator Light	Indicate Error States
· IBIT Button	Initiates Build-In-Test

# 5.6 CONTROLS - STICK

•	Master Mode	<ul> <li>A/G Mode – Side 2-Way FWD</li> <li>A/A Mode – Side 2-Way AFT</li> </ul>	
•	Slew	Center Slew Hat	
•	WHOT/BHOT	Center Slew Hat Depress	
•	Contrast Track	<ul> <li>Point Track – Left 4-Way Up</li> <li>Area Track – Left 4-Way Down</li> </ul>	
•	Q Select	<ul> <li>QADL/QHUD - Right 4-Way Up</li> <li>QDES - Right 4-Way Right</li> <li>QSNO - Right 4-Way Down</li> </ul>	
•	Declutter	Right 4-Way Depress	
•	Zoom Level	FOV Button	
•	Cycle Gain Control Mode	Slider FWD short	
•	Manual Gain Control	(a) Slider FWD long (b) Gain Right 4-Way Up/Down Level Right 4-Way Left/Right	
•	Laser Code	(a) Slider AFT short (b) Select Digit Right 4-Way Left/Right (c) Change Digit Right 4-Way Up/Down	
•	Focus Control	(a) Slider AFT hold (b) Right 4-Way Up/Down	
•	Manual Lase	Trigger Half-Action	
•	Latched Laser	Latched Laser Fire Button	
•	Designate QDES	Trigger Full-Action	

# 5.7 DISPLAY

Top Left	Own Aircraft Datablock
	- Lat - deg:min.dec
	- Long - deg:min.dec
	- ALT - Altitude (ft)
	- KGS - Knots Ground Speed
	- DIVE - Dive Angle (deg)
Mid Left	Sensor Mode - WHOT / BHOT
- Mid Leit	Gain Control – Auto / Manual
B 44 1 6	
Bottom Left	Pod Info Datablock
	- SRA – Slant Range
	<ul> <li>AZ - Pod LoS Azimuth L/R</li> </ul>
	- EL - Pod LoS Elevation
	- Time - UTC Time
	- IBIT - Codes
Bottom Center	Master Mode – A/A / A/G
	<ul> <li>Track Mode – AREA / POINT / Q</li> </ul>
	Current Weapon
	• Laser Code
	• L
	<b>- Steady</b> - Laser Armed
	-
	- Flashing - Laser Firing
<ul> <li>Bottom Right</li> </ul>	Q Datablock
	- TTG - Time-To-Go
	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1
	- B/R - Bearing and Range
	- B/R - Bearing and Range
	<ul><li>B/R - Bearing and Range</li><li>ELEV - Elevation (ft) of Q</li></ul>
<ul> <li>Mid Center</li> </ul>	<ul> <li>B/R - Bearing and Range</li> <li>ELEV - Elevation (ft) of Q</li> <li>Lat - deg:min:dec</li> </ul>
Mid Center	<ul> <li>B/R - Bearing and Range</li> <li>ELEV - Elevation (ft) of Q</li> <li>Lat - deg:min:dec</li> <li>Long - deg:min:dec</li> <li>Crosshair</li> </ul>
Mid Center	<ul> <li>B/R - Bearing and Range</li> <li>ELEV - Elevation (ft) of Q</li> <li>Lat - deg:min:dec</li> <li>Long - deg:min:dec</li> </ul>
Mid Center	- B/R - Bearing and Range - ELEV - Elevation (ft) of Q - Lat - deg:min:dec - Long - deg:min:dec  • Crosshair - Bounding Box - Indicates currently
• Mid Center	<ul> <li>B/R - Bearing and Range</li> <li>ELEV - Elevation (ft) of Q</li> <li>Lat - deg:min:dec</li> <li>Long - deg:min:dec</li> <li>Crosshair</li> <li>Bounding Box - Indicates currently tracked target in point mode</li> </ul>
• Mid Center	<ul> <li>B/R - Bearing and Range</li> <li>ELEV - Elevation (ft) of Q</li> <li>Lat - deg:min:dec</li> <li>Long - deg:min:dec</li> <li>Crosshair</li> <li>Bounding Box - Indicates currently tracked target in point mode</li> <li>Zoom Boxes - Indicates next zoom lev-</li> </ul>

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<ul> <li>Mid Right</li> </ul>	Bomb Rlease Cue
	<ul> <li>Only shown if current Q is QDES, with valid weapon selected</li> <li>TREL - Time to release</li> </ul>
	- TIMP - Time to Impact (after release)
Top Center	Steering Guidance to Q
	<ul> <li>Relative bearing L/R to commanded</li> </ul>

heading

#### 6 A/GWEAPONS

## 6.1 A/G WEAPON SETTINGS - OVERVIEW

• WPN TYPE	Selects Weapon Type	
	<ul> <li>Configures WCS for selected weapon</li> <li>Refer to Kneeboard for list of mounted weapons</li> <li>Mk-81 / 82 / 83 have both L and H option refering to high and low drag</li> </ul>	
• DLVY MODE	<ul> <li>STP-SGL – Single weapon per press</li> <li>STP-PRS Single pair per press</li> <li>RPL-SGL – QTY of weapons per press</li> <li>RPL-PRS – QTY of pairs per press</li> </ul>	
• DLVY OPTNS	<ul> <li>INTERVAL – Interval in ms</li> <li>QTY – Number of stores to be released</li> </ul>	
• MECH FUZE	<ul> <li>NOSE – Arms nose fuze</li> <li>SAFE – Inhibits arming of fuzes</li> <li>NOSE/TAIL – Arms both fuzes</li> </ul>	
• ELEC FUZE	<ul> <li>SAFE - Inhibits electrical bomb fuzing</li> <li>VT - Sets air-burst mode at preset burst height for compatible stores</li> <li>INST - Sets instantaneous burst mode</li> <li>DLY 1 - Sets preset time delay 1</li> <li>DLY 2 - Sets preset time delay 2</li> </ul>	
· STA SEL	Selects Stations for Employment/Jettison	
	<ul> <li>Set to SEL to activate a pylon</li> <li>Stations 1 &amp; 8 should be set to B for selection</li> <li>Station 1 &amp; 8 SW was used for Sidewinder jettison, is now inoperable</li> </ul>	
· TANK JETT	Allows Drop Tank Jettison	
· SEL JETT	<ul> <li>JETT - Selective jettison</li> <li>SAFE - Inhibits jettison</li> <li>AUX - Backup mode</li> </ul>	
- JETT OPTIONS	<ul> <li>MERTER – Jettisons ejector racks</li> <li>WPNS – Jettisons weapons only</li> </ul>	

#### ATTK MODE

- CCMPTRTGT
  - Computer Target Similar to CCRP
- CMPTR IP
  - Computer initial point
  - Extended CMPTR TGT mode using known IP
  - For use when target hard to spot visually but close to landmark
- CMPTR PLT
  - Computer Pilot similar to CCIP
- MAN
  - Manual HUD displays pipper
  - Backup mode
- D/L BOMB
  - Data-Link Bomb Automatic mode steered by D/L cues
  - Not Implemented in DCS

#### 6.2 SELECTIVE ORNANCE JETTISON

1.	Pilot Conditions	MASTER ARM	ON
2.	RIO Conditions		
		JETT OPTIONS	As Desired
3.	Jettison	(a) SEL JETT Guard	Flipped
		(b) SEL JETT Switch	JETT

#### 6.3 M61 GUN

1.	Pilot Conditions	MASTER ARM ON     HUD A/G     WEAPON SELECTOR GUNS     Wing Sweep BOMB
2.	Employment	(a) Dive       20-30 deg         (b) Pipper       on target         (c) TRIGGER       FIRE
•	Note: TCS	<ul> <li>TCS slaved to radar impact point</li> <li>Rio can select NAR or WIDE</li> </ul>

#### 6.4 FFAR/ZUNI ROCKETS

1.	<b>RIO Conditions</b>	• WPN TYP	LAU-10
		Attack Mode	Pilot Attack
		Deliver Mode	RPL-SGL
		Mechanical Fuze	NOSE
		Electronic Fuze	INST
		Delivery Options	As Desired
		• Stations	Armed
2.	<b>Pilot Conditions</b>	• MASTER ARM	ON
		• HUD	A/G
		WEAPON SELECTOR	OFF
		• Stations	verify selected
		Wing Sweep	ВОМВ
3.	Employment	(a) <b>Dive</b>	20-30 deg
		(b) <b>Pipper</b>	<del>-</del>
		(c) <b>TRIGGER</b>	FIRE

#### 6.5 UNGUIDED BOMB - CCIP

1.	RIO Conditions	WPN TYP     MK-8X     Attack Mode    Pilot Attack     Deliver Mode    STP-PRS     Mechanical Fuze    NOSE     Electronic Fuze    INST     Delivery Options    As Desired     Stations    Armed
2.	Pilot Conditions	• MASTER ARM ON • HUD A/G • WEAPON SELECTOR OFF • Stations verify selected • Wing Sweep BOMB
3.	Employment	(a) Dive       40 deg         (b) Pipper       on target         (c) STORE RELEASE       Press and Hold

## A/G WEAPONS

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# 6.6 UNGUIDED BOMB - CCRP

1.	RIO Conditions	<ul> <li>WPN TYP</li></ul>
		• StationsArmed
2.	Pilot Conditions	• MASTER ARMON
		• HUD
		WEAPON SELECTOR OFF
		• Stationsverify selected
		Wing Sweep BOMB
3.	Designation	(a) Slew DiamondVSL HI/LO
		(b) DesignatePAL
4.	Employment	(a) Flight Path Straight, Level
	. ,	(b) Vel Vectoron Bomb Fall Line
		When Solution Cue meets Velocity Vector
		(c) STORE RELEASEPress and Hold

#### 6.7 LASER GUIDED BOMB

	To a contract of the contract
l. LANTIRN PREP	(a) Target Pod PowerPOD
T KET	<ul><li>Warm up takes approx. 8 min</li><li>Automatically switches to STANDBY</li></ul>
	(b) Laser Code as desired
	MUST BE SET ON THE GROUND
	• Default: 1688
	(c) LANTIRN ModeOPERATE
	• STANDBY caution will flash for 30 s
	<ul> <li>Then switches to OPER</li> </ul>
	(d) VIDEO SwitchFLIR
	(e) TID ModeTV
2. RIO Conditions	• WPN TYPGBU-XX
	Attack Mode
	Deliver ModeSTP-SGL
	Mechanical FuzeNOSE
	• Electronic FuzeINST
	Delivery Options As Desired
3. Pilot Conditions	• StationsArmed
3. Pilot Conditions	• MASTER ARMON • HUDA/G
	WEAPON SELECTOR OFF
	• VDI Mode
	• Stationsverify selected
	Wing SweepBOMB
4. Slew LANTIRN	Refer to LANTIRN Control Section
	Slave to WYPTLeft-4-Way RIGHT
	QSNO (Snowplow)S4 HAT Down
	Toggle FOV LANTIRN Toggle FOV
	SlewLANTIRN Stick
	Area Track Left-4-Way UP
	Point Track Left-4-Way Down
	UndesignateLANTIRN Undesignate

4.	Designate	Refer to LANTIRN Designation Section (a) DesignateTrigger Full-Action • Slant Range calculated • Time-to-Go calculated
		Once Time-to-Realease (TREL) is 0  (b) Auto-Lase If selected: lases 10s to impact (c) Manual LaseTrigger Full-Action (d) While LasingL blinks
5.	Employment	Once Time-to-Realease (TREL) is 0  (a) STORE RELEASE Press and Hold  (b) Flight Path Gentle right-hand turn  (to prevent masking)

#### 6.8 TALD DECOYS

1.	RIO Conditions	• WPN TYPTALD • Deliver ModeSTP-SGL
		Delivery Options As Desired
		StationsArmed
2.	<b>Pilot Conditions</b>	• MASTER ARM ON
		• HUDA/G
		WEAPON SELECTOR OFF
		• HSD ModeTID
		Stationsverify selected
3.	<b>Employment</b>	(a) Flight PathHigh / Fast
		(b) <b>RWR</b> Monitor to locate emitters
		(c) STORE RELEASEPress and Hold

## 7 A/AWEAPONS

## 7.1 M61 GUN - OVERVIEW

GUN RATE Button	<ul> <li>Cycles Gun Rate</li> </ul>
	- <b>HIGH</b> - 6000 rpm
	<b>- LOW</b> - 4000 rpm
• A/A Gun Modes	• RTGS
	<ul> <li>Real-Time Gunsight Mode</li> <li>Selected automatically with guns</li> <li>If No WCS Data Available displays bullet location at 2000 ft with diamond and 1000 ft with pipper</li> <li>If WCS Data Available pipper displays bullet location at targets current range out to 4000 ft</li> </ul>
	• MANUAL
	<ul><li>Fixed manual pipper</li><li>Adjust with GUN ELEV knob</li><li>Press CAGE/SEAM to select</li></ul>
CAGE/SEAM But- ton	Cycles RTGS / MANUAL Gun Modes
· ROUNDS Knob	Allows selection of remaining gun rounds

# **7.2** M61 GUN - MANUAL

1.	<b>Pilot Conditions</b>	• MASTER ARM	ON
		• HUD	A/A
		• Gun Rate	HIGH
		Gunsight Lead	as required
		WEAPON SELECTOR	GUNS
2.	<b>Employment</b>	(a) <b>Gun Mode</b>	MANUAL
		(b) <b>Pipper</b>	on target
		(c) Trigger	FIRE

## 7.3 M61 GUN - RTGS / NO RADAR

1.	Pilot Conditions	MASTER ARM     HUD     Gun Rate	A/A
		WEAPON SELECTOR	GUNS
2.	<b>Employment</b>	(a) <b>Gun Mode</b>	RTGS
		(b) <b>Pipper</b>	on target
		(c) <b>Trigger</b>	FIRE

## 7.4 M61 GUN - RTGS / RADAR

1.	Pilot Conditions	• MASTER ARM	ON
		• HUD	A/A
		• Gun Rate	HIGH
		WEAPON SELECTOR	GUNS
2.	<b>Employment</b>	(a) <b>Gun Mode</b>	RTGS
		(b) <b>Radar</b>	STT
		(c) <b>Pipper</b>	on target
		(d) Trigger	FIRE

## 7.5 AIM-9 SIDEWINDER - OVERVIEW

<ul> <li>Missile Prepara-</li> </ul>	MSL PREP
tion	<ul> <li>AIM-9 seeker must be cooled</li> </ul>
	<ul> <li>Either press SW COOL button</li> </ul>
	<ul> <li>Or activation of ACM</li> </ul>
<ul> <li>Seeker Head</li> </ul>	• SEAM
Modes	<ul> <li>Sidewinder Expanded Acquisition Mode</li> </ul>
	<ul> <li>Double-D search pattern invisible to pilot</li> </ul>
	<ul> <li>4.5 sec search time</li> </ul>
	<ul> <li>Allows AIM-9 to be uncaged and track target</li> </ul>
	- 40 deg track limit
	<ul> <li>Allows WCS to slave AIM-9 to radar</li> </ul>
	track
	Boresight
	<ul> <li>AIM-9 locked to ADL</li> </ul>
	- 2.5 deg FOV
	<ul> <li>Selected if MODE/STP set to BRSIT</li> </ul>
	- And <b>ACM</b> not active
<ul> <li>MODE/STP</li> </ul>	• NORM
Switch	- Allows <b>SEAM</b> seeker mode
	• BRSIT
	- Forces Boresight seeker mode
	- Overridden if <b>ACM</b> active
· CAGE/SEAM But-	Uncages Seeker
ton	<ul> <li>Starts 4.5 second double-D search</li> </ul>
	<ul> <li>If no IR source found cages again</li> </ul>
	Slaves Seeker
	- If radar STT locked

## 7.6 AIM-9 SIDEWINDER - SILENT

1.	Pilot Conditions	• MASTER ARM	ON
		• HUD	A/A
		• SW COOL	ON
		• MODE/STP	As Desired
		• WEAPON SELECTOR	SW
2.	Employment	(a) <b>CAGE/SEAM</b>	Uncage Seeker
		(b) <b>IR-Lock</b>	Good Tone
		(c) Trigger	FIRE

## 7.7 AIM-9 SIDEWINDER - RADAR

1.	Pilot Conditions	• MASTER ARM	ON
		• HUD	A/A
		• SW COOL	ON
		• MODE/STP	NORM
		WEAPON SELECTOR	SW
2.	Employment	(a) <b>Radar</b>	STT
		(b) <b>CAGE/SEAM</b>	Slave Seeker
		(c) IR-LOCK	Good Tone
		(d) <b>Steering</b> center T-sho	aped cue with ASE
		(e) Trigger	FIRE

## 7.8 AIM-7 SPARROW - OVERVIEW

•	Missile	Prepara-
	tion	

- MSL PREP
  - AIM-7 must be tuned to AWG-9
  - Either press MSL PREP button
  - Or activation of **ACM**

### Launch Modes

#### Normal

- Standard operation, STT target designated before launch
- AIM-7 uses SARH all the way to target
- WCS can use CS or PD for guidance set with MSL OPTIONS Switch

### Boresight

- Uses CS flood antenna of AWG-9
- Missile will track strongest return in Flood area
- Automatically activated if STT broken
- Selected if MODE/STP set to BRSIT
- Or if no STT available
- Shown Below

# • MSL SPD GATE Switch

#### NOSE QTR

- Standard setting in DCS
- All Others
  - Not simulated

# • MSL OPTIONS Switch

#### NORM

 WCS uses dedicated CW antenna for AIM-7 guidance

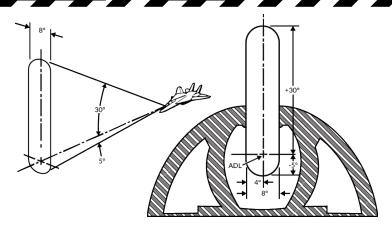
#### SP PD

 WCS uses PD from main flood antenna for AIM-7F/M guidance

#### MODE/STP Switch

#### NORM

- Sets normal launch mode logic
- BRSIT
  - Forces Boresight launch mode



## 7.9 AIM-7 SPARROW - STT

1.	Pilot Conditions	• MASTER ARM ON
		• HUD
		• MSL PREP ON
		• MODE/STPNORM
		WEAPON SELECTORSP
2.	<b>RIO Conditions</b>	MSL SPD GATE NOSE QTR
		MSL OPTIONSAs Desired
3.	Employment	(a) <b>Radar</b> STT
		(b) Steering
		• Target < 20 deg from ADL
		ASE center T-shaped cue within
		(c) TriggerPress and Hold
		(until weapon release)
		(d) Radar Maintain Lock (until impact)

Missile Prepara-	<ul> <li>Weapon Cooling</li> </ul>
tion	<ul> <li>AIM-54 requires liquid cooling</li> </ul>
	- RIO enabled <b>LIQUID COOLING</b> switch
	MSL PREP
	- AIM-54 must be tuned to AWG-9
	<ul> <li>Either press MSL PREP button</li> </ul>
	<ul> <li>Or activation of ACM</li> </ul>
Launch Modes	• PDSTT SARH
	<ul> <li>AIM-54 uses SARH all the way to target</li> </ul>
	<ul> <li>Faster update rate than TWS</li> </ul>
	<ul> <li>Slightly increased effective range as compared to a TWS launch</li> </ul>
	• TWS SARH/ARH
	- Allows 6 AIM-54 launches at 6 target:
	<ul> <li>Missile is initially SARH guided</li> </ul>
	<ul> <li>When within AIM-54 seeker range</li> </ul>
	AWG-9 sends activation command
	<ul> <li>Not Fire and Forget: Requires automatic activation command</li> </ul>
	ACM Active
	<ul> <li>Activated when BRSIT selected</li> </ul>
	<ul> <li>Or when ACM active with no radar track</li> </ul>
	<ul> <li>Missile commanded active before</li> </ul>
	launch
MSL SPD	NOSE QTR
<b>GATE Switch</b>	<ul> <li>Standard setting in DCS</li> </ul>
	All Others
	- Not simulated
MSL OPTIONS	• NORM
Switch	<ul> <li>Normal guidance (SARH or SARH/ARH)</li> </ul>
	DU 4.67

## • PH ACT

WCS immediately sends AIM-54 activation command on launchReverts to SARH if no target detected

- Must be selected before launch

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A/A WEAPONS	F-14A/B REV: 20220125
• TGTS Switch	<ul> <li>SMALL – 6nm activation range</li> <li>NORM – 10nm activation range</li> <li>LARGE – 13nm activation range</li> </ul>
Missile Next Launch Button	<ul> <li>Selects Hooked Track as Next Target for AIM-54 TWS Engagement</li> </ul>
• MODE/STP Switch	NORM  Normal operation  BRSIT  Commanded active before launch  Missile follows ADL and locks strongest return
TWS Symbology	Refer to TID Symbology Section     Pre-Launch     Prioritization numbers assigned to tracks automatically or manually     Blinking indicates optimal launch parameters

• When in ACM - 1 second

(LTE) Time

(until impac	
-TWS/MULTI	AIM-54 PHOENIX -
• MASTER ARM O	Pilot Conditions
• HUDA/	
• MSL PREP O	
• MODE/STPNOR	
WEAPON SELECTOR P	
• LIQUID COOLING ON (FWI	<b>RIO Conditions</b>
MSL SPD GATE NOSE QT	
MSL OPTIONS As Desire	
TGTS Switch As Desire	
WCS ModeTWS MAN/AUT	
(a) RadarTW	Employment
(b) TriggerPress and Ho	
(until weapon releas	
(c) <b>Repeat</b> for remaining targe	
(d) Radar Maintain Trac	
(until activ	

