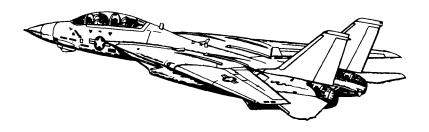
Pocket Checklist

F-14A/B AIRCRAFT

REV: 20220214



Procedures

Systems

AWG-9 Radar

TCS LANTIRN

A/G Weapons

A/A Weapons

DISCLAIMER

This document represents a personal project and is intended for entertainment purposes only. Do not use for training purposes or in real life scenarios.

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1.1 START-UP

1.1.1 PILOT - PRE-START

1.	Dandein a Danden	ENGAGED
	Parking Brake	1
2.	Ground Power	connected
3.	Compressed Air	connected
4.	ICS	HOT MIC
5.	TO RIO	"Begin Start-Up"
6.	ICS	Comm Check
7.	MASTER TEST	(a) LTS
	Selector	Warning Lights
		• RPM
8.	Ejection Seat	Armed
9.	RIO	Canopy Closed
10.	Oxygen	ON (FWD)
11	Emergency Wing Sweep	OVERSWEEP

1.1.2 PILOT - ENGINE START

1.	AIR SOURCE	OFF
2.	Hydraulics	(a) HYD TRANSFER PUMP SHUTOFF (b) Emerg. HydAUTO (LOW)
3.	L&R MASTER GEN	NORM
4.	RIO	"Ready to Start"
5.	Right Engine Start-Up	(a) Engine Crank R (b) R Eng N2 20% (c) R Throttle IDLE (d) TIT < 890 C during start
6.	Stabilized Parameters	 RPM
7.	Left Engine Start-Up	(a) Engine Crank L (b) L Eng N2 20% (c) L Throttle IDLE (d) TIT < 890 C during start
8.	Stabilized Parameters	 RPM
9.	HYD TRANSFER PUMP	NORM
10.	HYD PRESSURE	3000 psi
11.	AIR SOURCE	BOTH ENG
12.	Ground Power	disconnected
13.	Compressed Air	disconnected

1.1.3 PILOT - POST-START

1.	TO RIO	"Both Engines Running"
2.	Displays Control Panel	• VDI
3.	RIO	Select Align Quality INS GO NOW: shortest but least precise alignment INS GO COARSE: does not meet Launch Criteria for AIM-7 / AIM-54 INS GO MIN WPN LAUNCH: allows AIM-7 / AIM-54 launch INS GO FINE fine align (8 min)
4.	ACM Panel	GUN RATE as required SW COOL OFF MSL PREP OFF Missile MODE/STP NORM
5.	Gun Rounds	Set
6.	ANTI-SKID SPOILER BK	OFF
7.	Emergency Wing Sweep	(a) Handle
8.	AFCS Panel - SAS STAB AUG	• PITCH ON • ROLL ON • YAW ON
9.	WING/EXT TRANS	AUTO
10.	UHF1 Function Selector	ВОТН
11.	TACAN Function Selector	T/R
12.	ARA-63 ICLS RECEIVER	ON

13.	Radar Altimeter	(a) Control Knob one click CW to turn on (b) Display
14.	Standby ADI	erect at least 2 min before T/O
15.	KY-28 Crypt. Key	Set (refer to GROUND SETTINGS kb)
16.	RIO	set D/L frequency
17.	Lights	As desired

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PROCEDURES

WARNING

• PARKING BRAKE MUST BE ENGAGED DURING ALIGNMENT.
Lack of parking brake engagement inhibits INS alignment

1-7

T/R G

U/VHF Mode

5.

(e) **Keyboard** **HDG**, mag var, **ENTER** (f) **Align Progress** Monitor

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6.	Datalink	(a) Kneeboard TACTICAL DL (b) DL Power ON (FWD) (c) DL Mode TAC (AFT) (d) DL Freq. Set
7.	TACAN	T/R
8.	RWR Panel	(a) Display Type NORM (b) PWR ON (c) TEST SPL (d) MODE LMT
9.	DECM	STBY, then ACT
10.	IFF	(a) MASTER STBY (b) CODE as required
11.	Altimeter	Reset
12.	CAP	Enter Data (WP, FP, etc.)
13.	Displays	• DDD
14.	Hand Control Panel	Set
15.	AN/ALE-39	Set (as required) • AUTO (CHAFF)/MAN • MAN
16.	Flare Mode	PILOT
17.	Complete INS Align	Duration Full Fine
		(a) Align Complete Caret \rightarrow Diamond (b) NAV Mode
18.	Standby ADI	Erect at least 2 min before T/O
19.	TO PILOT	"Ready to Taxi"
Onc	e Airborne	
20.	IR/TV Power	ON
21.	WCS Switch	WCS XMT

1.1.6 RIO - POST-START - CARRIER

1		
1.	PILOT	• Enginesstarted
		AIR SOURCEBOTH ENG
2.	INS STARTUP	(a) LIQUID COOLINGON (FWD)
		(b) WCS SwitchSTANDBY
		(c) IR/TV Power STBY/IR/TV
		(d) TID/DDD illuminated after 40 s
3.	Datalink	(a) Kneeboard TACTICAL DL
		(b) DL PowerON (FWD)
4.	Start INS Align	(a) DL FREQ
		(b) DL ModeCAINS/WAYPT
		(c) Nav Mode CVA
5.	U/VHF Mode	T/R G
6.	TACAN	T/R
7.	RWR Panel	(a) Display TypeNORM
		(b) PWR ON
		(c) TEST SPL
		(d) MODE LMT
8.	DECM	STBY, then ACT
9.	IFF	(a) MASTER STBY
		(1) CODE
		(b) CODE as required
10.	Altimeter	Reset
10.	Altimeter	
		Reset
11.	CAP	Reset Enter Data (WP, FP, etc.)
11.	CAP	Reset Enter Data (WP, FP, etc.) • DDD
11.	CAP	Reset Enter Data (WP, FP, etc.) • DDD
11.	CAP Displays	Reset Enter Data (WP, FP, etc.) • DDD
11.	CAP Displays Hand Control	Reset Enter Data (WP, FP, etc.) • DDD
11.	CAP Displays Hand Control Panel	Reset Enter Data (WP, FP, etc.) • DDD
11.	CAP Displays Hand Control Panel	Reset Enter Data (WP, FP, etc.) • DDD

16.	Complete INS Align	Duration Full Fine
		(a) Align Complete Caret → Diamond
		(b) NAV Mode INS NAV
17.	Datalink	(a) DL Mode
		(b) DL Freq. Set
18.	Standby ADI	Erect at least 2 min before T/O
19.	TO PILOT	"Ready to Taxi"
Once	e Airborne	
20.	IR/TV Power	ON

F-14A/B

WARNING

WCS XMT

21.

WCS Switch

- Input Coords **BEFORE** selecting **GND ALIGN** if using ASH. Else alignment can progress too far to correct coordinates by the time they are input.
- PARKING BRAKE MUST BE ENGAGED DURING ALIGNMENT.
 Lack of parking brake engagement inhibits INS alignment

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1.	ANTI-SKID SPOILER BK	OFF
2.	HOOK BYPASS	As Required
3.	Nose Strut	RETRACTED
4.	HUD MODE	ТО
5.	Parking Brake	Released (IN)
6.	NWS	ENGAGED
7.	Path	verify clear

1.2 TAKEOFF & LANDING

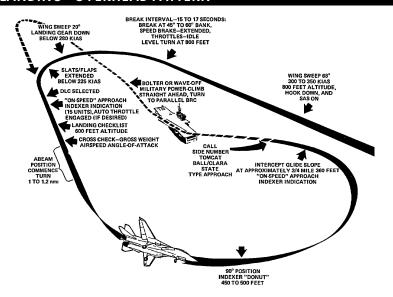
1.2.1 TAKEOFF - SHORE

	After Lining Up On Runway		
1.	Wing Sweep	(a) EM WING SWEEP FWD, then IN (b) MASTER RESET PRESS (c) Wings Verify thumb controller (d) WING SWEEP AUTO (e) Wings Verify at 20 deg	
2.	ANTI SKID SPOILER BK	BOTH (UP)	
3.	FLAPS	UP	
4.	Trim	0 deg	
5.	NWS	DISENGAGED	
6.	Takeoff	(a) Throttle MIL (90% RPM) (b) Stick Back at 130 KIAS (c) Rotation approx 140 KIAS (d) GEAR UP < 250 KIAS	

1.2.2 TAKEOFF - CARRIER

	Lineup	 Wait behind JBD until Catapult is clear Follow Taxi Directors Instructions to line up on Catapult
1.	Wing Sweep	(a) EM WING SWEEP FWD, then IN (b) MASTER RESET PRESS (c) Wings Verify thumb controller (d) WING SWEEP AUTO (e) Wings Verify at 20 deg
2.	FLAPS	DOWN
3.	Launch Bar Preparation	(a) Nose Strut
4.	Trim	2-3 deg nose up
5.	Speed Brakes	IN
6.	Final Checks	(a) Throttle
		(c) Eng. Inst
7.	Catapult Shot	(a) Salute
8.	Clearing Turn	

1.2.3 LANDING - OVERHEAD PATTERN



1.	Initial Approach	• WING SWEEP	68 deg
		• HOOK	DOWN
		• SAS	ON
		• HUD	LDG
		• Airspeed	300-350 KIAS
		Altitude	800 ft
2.	Initial Break	Break Interval	15-17 s
		• BANK	45-60 deg
		SPEED BRAKE	EXTEND
		• Throttle	IDLE
		• G	3-4 G
		Altitude	800 ft
3.	Break Turn	Wing Sweep	AUTO < 280 KIAS
		• Landing Gear	
		• FLAPS	
4.	Downwind	• DLC	Selected once flaps out
		• AOA	ON-SPEED
		 LANDING CHECKLIS 	Γ
		Altitude	descend to 600 ft

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5.	Final Turn	180 Deg Position • Abeam Pos	1-1.2 nmi
		• AOA	DONUT
		Altitude	400-500 ft
6.	Intercept Glides-	• Distance	3/4 Mile
	lope	Altitude	360 ft
		• AOA	ON-SPEED

1.2.4 LANDING - CHECKLIST

1.	Wing Sweep	20 deg AUTO
2.	Wheels	• Lights 3 DOWN
		Transition LightOUT
3.	SAS	ON
4.	FLAPS	DOWN
5.	DLC	Checked
6.	Hook	• HOOK DOWN
		Transition LightOUT
7.	Harness	Locked
8.	Speedbrakes	EXT
9.	Brakes	Check
10.	Fuel	Check

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1.3 IN-FLIGHT

1.3.1 AERIAL REFUELING

1.3.2 AIRSTART

Spooldown	Before significant spooldown (a) Non-Running ENGIDLE or above
	If no relight occurs (b) Non-Running ENG OFF then IDLE If still no relight occurs (c) ENG MODE SEC (d) Non-Running ENG OFF then IDLE
Cross-Bleed Restart	With one ENG running, if Spooldown fails (a) Non-Running ENG
	(g) Non-Running ENG OFF then IDLE If still no start (h) ENG MODE SEC (i) Non-Running ENG OFF then IDLE
Windmill Restart	(a) Airspeed>450 kts (b) Throttle
Post Restart	(f) Throttle OFF then IDLE (a) BACK UP IGNITION OFF (b) ENG MODE PRI

Chapter 2

SYSTEMS

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2.1 FLIGHT CONTROL

2.1.1 AFCS - SAS

• SAS	 Stability Augmentation System
	Not Fly-by-Wire
	 Automatic control surface commands generated by analog computer to im- prove stability
 Controls 	Three individual Switches
	- Pitch
	- Roll
	- Yaw
Autopilot Emer-	 Paddle on Stick
gency Disengage Paddle	Disengages Autopilot ModesDeactivates Pitch, Roll SAS Channels

2.1.2 AFCS - AUTOPILOT

Attitude Hold	Basic Attitude Hold
	 Maintains existing pitch & roll Attitude can be changed with stick input If engaged outside limits will automatically move within range
	• Limits
	Pitch: 30 degRoll: 60 deg
	• Engagement
	(a) SAS Switches ON (FWD) (b) Alt. Hold Mode OFF (c) VEC/PCD/ACL OFF (d) Heading Mode OFF
	(e) Autopilot Switch ENGAGE (FWD)

Engagement (a) SAS Switches ON (FWD)

(b)	Autopilot Switch ENGAGE	· (FWD	·)
(c)	Heading Mode HDG	(FWD)

Ground Track Autopilot follows ground track - Similar to heading hold - Compensates for wind drift - Uses INS data instead of mag. bearing Limits - Bank angle < 5 deg Fnaagement

(a) SAS SwitchesON (FWD)
(b) Autopilot Switch ENGAGE (FWD)
(c) Heading ModeGT (AFT)
(d) A/P REF Light Wait until appears
(e) NWS Button Press

•	ACL	Automatic Carrier Landing	
		 Not Modelled in DCS 	
		rect the aircraft	
		 Allows Link 4 controller to remotely di- 	
•	VEC/PCD	 Vector / Precision Course Direction 	

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- Autopilot Emergency Disengage Paddle
- Paddle on Stick
 - Disengages Autopilot Modes
 - Deactivates Pitch, Roll SAS Channels

2.1.3 APC/AUTOTHROTTLE

• APC	Approach Power Compensator		
	Automatic throttle controlMaintains ON SPEED AoA		
• Conditions	Engagement is inhibited / APC is disengaged if conditions not met • Throttles		
	Landing Gear Handle Down Weight on Wheels No		
• Engage	Throttle Mode AUTO (FWD)		
Disengage	Cage/Seam Button		

2.1.4 ACLS

2.1.5 WING-SWEEP

Overview	 In Flight Limited between 20 deg & 68 deg On Ground can Oversweep to 75 deg Hydromechanically Controlled
	Automatically through CADCManually with emergency wing-sweep handle
	15 deg/s at 1g loadingMechanically linked to ensure symmetry
CADC Modes	• AUTO
	 CADC controls wing position as function of current Mach via wing-sweep program
	• MAN
	 Pilot manually chooses desired wing sweep angle with thumb controller
	• BOMB
	 Sets wing sweep to 55 deg or further aft_

• Emergend	• Emergency Wing-Sweep Handle • Moved with wing sweep program by spider detent under normal operation • Can be forced out of spider detent and moved manually
• Overswee	 Selected via Emergency Wing-Sweep Handle
	(a) Em. Wing-Sweep
Return to	CADC • After Emergency Mode / Oversweep
Control	(a) Em. Wing-Sweep Spider Detent (Fwd on startup)
	(b) MASTER RESET Press

Indicated Mach	Max Forward Wing Position
0.4	20 deg
0.7	25 deg
0.8	50 deg
0.9	60 deg
1.0	68 deg

2.2 NAVIGATION

2.2.1 NAV - OVERVIEW

Pilot Cockpit Interface			
• HUD	Heads Up Display • Displays WRITE ME information		
• VDI	Vertical Display Indicator • placeholder		
• HSD	Horizontal Situation Display NAV Mode Information		
	 Diamond - Current heading Chevron - TACAN TO bearing + - TACAN FROM bearing House - ADF bearing RNG - Range to Waypoint (nm) MODE - NAV STEER mode W - Wind heading / speed (kts) TAS - True AirSpeed (kts) GS - GroundSpeed (kts) 		
	TID Mode Information		
	Overhead ViewWaypoint Coordinates		
• BDHI	placeholder		
Standby Mag- netic Compass	• placeholder		
Tacan Control Panel	• placeholder		
STEER CMD Se- lectors	• placeholder		

2.2.2 NAV - INS

SYSTEMS	F-14A/B	REV: 2	0220214

Contributing Subsystems	IMU – Inertial Measurement Unit - 4 Gimbals – No gimbal-lock, corrects platform attitude errors - 2 Gyros – Source for aircraft attitude data - 3 Accelerometers – Source for aircraft acceleration data CSDC – Computer Signal Data Converter
	Processes sensor signals including IMU data
CSDC Data Modes	 (a) INS - Primary nav mode Velocity Data - IMU Pitch/Roll Data - IMU (b) IMU/AM - Backup mode selected by RIO or automatically when CSDC determines IMU velocity data unreliable. Velocity Data - Calculated from true airspeed & stored wind Pitch/Roll Data - IMU
	 (c) AHRS/AM – Further degraded mode selected by RIO or automatically when CSDC detects total INS failure Heading – Mag heading & MAG VAR
	 Velocity Data – Calculated from true airspeed & stored wind Pitch/Roll Data – AHRS

2.2.3 NAV - ALIGNMENT

Ground Align	(a)
 Carrier Align D/L 	
 Carrier Align Handset 	
Reinitialization	
Automatic Stored Heading	
Catapult Align	

2.2.4 NAV - WAYPOINT

- Reference Point Types
- Navigation Waypoint Used for navigation. Maximum of 3 stored simultaneously
- Fixed Point (FP) Arbitrary point to establish current position relative to external references
- Initial Point (IP) Starting point for A/G attack run
- Surface Target (ST) Enemy surface target
- **Defended Point (DP)** Area to protect (i.e friendly forces)
- Hostile Area (HA) Area with known ground or air hostiles
- Home Base (HB) Airfield / CV

2.2.5 NAV - TACAN

2.2.6 NAV-VOR/ADF

2.3 COMMUNICATION

2.3.1 COMMS - OVERVIEW

• ARC-159 UHF1	 Air-to-Air & Air-to-Surface Communication Pilot Controlled Frequency Range - 225.000 - 399.975 MHz Steps - 25 kHz Channels - 20
• ARC-182 V/UHF 2	 Air-to-Air & Air-to-Surface Communication RIO Controlled Frequency Band 1 - 30 - 88 MHz Band 2 - 108 - 156 MHz Band 3 - 156 - 174 MHz Band 4 - 225 - 399,975 MHz Steps - 25 kHz Channels - 20
ARA-50 UHF ADF	UHF Automatic Direction Finder LoS bearing to UHF Transmitter Bearing displayed on BDHI, Pilot HSD 5 min Warmup
KY-28 Voice Se- curity Equipment	Voice CipheringIntegrated with UHF1 and V/UHF22 min Warmup

2.3.2 COMMS - ARC-159 UHF 1

• ARC-159 UHF1	 Air-to-Air & Air-to-Surface Communication Pilot Controlled Frequency
	- Range - 225.000 - 399.975 MHz - Steps - 25 kHz
	- Channels - 20
 VOL Knob 	Controls Pilot UHF 1 Audio Level

SYSTEMS	F-14A/B	REV: 20220214

BRT/TEST Knob	 Controls Radio FREQ Display
	 Turn past max to display 888.888
• SQL Switch	 Toggles radio squelch (noise attenuation)
READ Switch	 Displays Frequency of Selected Preset Channel
LOAD Button	 Saves Displayed Frequency to Selected Preset Channel
TONE Button	 Steady 1.020 kHz Test Tone
Mode Selector	Frequency Selection Method
	- GUARD - 243.000 MHz
	- MANUAL - Manual tuning
	- PRESET - Preset channels
Function Selector	 Selects Transceivers to Energize
	 ADF – Not simulated
	- BOTH - Main & Guard
	– MAIN – Main
	- OFF - Secures UHF 1 radio
• CHAN SEL	Selects from 20 preset Channels

2.3.3 COMMS - ARC-182 V/UHF 2

• ARC-182 V/UHF 2	 Air-to-Air & Air-to-Surface Communication RIO Controlled Frequency
	 Band 1 - 30 - 88 MHz Band 2 - 108 - 156 MHz Band 3 - 156 - 174 MHz Band 4 - 225 - 399.975 MHz Steps - 25 kHz Channels - 20
• VOL Knob	Controls RIO UHF 2 Audio Level
BRT/TEST Knob	Controls Radio FREQ Display
• SQL Switch	Toggles radio squelch (noise attenuation)

SYSTEMS	F-14A/B REV: 20220214
• Mode Selector	 Transceiver Settings OFF - Secures V/UHF radio unless frequency mode set to 243 T/R - Energizes transmitter and main receiver T/R & G - Energizes transmitter, main, and guard receiver DF - Automatic direction finding from 108 - 399.975 MHz TEST - BIT
• CHAN SEL Outer Dial	Selects Frequency Tuning Mode
• CHAN SEL	Selects one of 40 Preset Channels

2.3.4 COMMS - KY-28 VOICE SECURITY EQUIPMENT

Inner Dial

KY-28 Voice Se- curity Equipment	 Voice Ciphering Integrated with UHF1 and V/UHF2 2 min Warmup
Switch	 Lift Guard to Erase Preloaded Codes Codes loaded via ground crew
Power-Mode Switch	 Selects Mode P/OFF - Removes power from system C - Transmit / Receive in secure mode DELAY - Between PTT and trans.

Radio-Select Switch

• Selects Radio Mode

- RELAY Acts as relay for other stations (not simulated)
- RAD-2 Secure voice for V/UHF 2
- RAD-1 Secure voice for UHF1

2.3.5 LINK 4 DATALINK - OVERVIEW

•	Link 4	Modes – Mutually exclusive		
		- Link 4A - AWACS / Surface Ship		
		 Link 4C – Fighter to Fighter 		
		• Data Speed – up to 5000 bit/s!		
• Link 4A		Network - AWACS / Surface Ship		
		Additionally used for ACLS		
•	Link 4C	Network – Fighter to Fighter		
		- Up to four F-14s		
		- Unique to F-14		
•	Basic Operation	(a) Power Switch As Desired		
		• Link 4A ON		
		• Link 4C AUX		
		(b) Mode SwitchTAC		
		(c) FrequencySet		

2.3.6 LINK 4 DATALINK - CONTROL PANEL

		1			
 Test Switch 		 Controls Test / Anti-Jam Modes 			
		- TEST - Initiates BIT			
		- NORM - Normal Operation			
		A-J - Anti-Jam (not simulated)			
•	Frequency	Selects Datalink Frequency			
	Thumbwheels	– First Digit – Fixed as 3			
		- Allowable Range - 300.0 - 324.9			
		MHz			
•	Power Switch	Controls System Power			
		– ON – Enables Link 4A			
		- OFF – Disables system			
		- AUX - Enables Link 4C			

SYSTEMS F-14A/B REV: 20220214

2.3.7 LINK 4 DATALINK - REPLY/ANTENNA PANEL

• ANTENNA	Selects Antenna
Switch	- Shared with UHF1 - Mutually exclusive
	- UHF1LWR/DLUPR
	- UHF1UPR/DLLWR
• REPLY Switch	• Sets Reply Mode
	 NORM - Own Aircraft replies to
	datalink messages
	- CANC - Receive only
• MODE Switch	Controls Overall Mode
	- TAC - Normal airborne mode
	- CAINS/WAYPT - Enables CV align
• Address	Sets Two Least Significant Bits of Aircraft
Thumbwheels	D/L Address

2.4 DEFENSIVE SYSTEMS

2.4.1 ALR-67 RWR - CONTROLS / OVERVIEW

• PWR Switch	Set to ON to Operate			
• VOL Knob	Sets RIO Audio Level			
• TEST Switch	 Springloaded to Center BIT - Initiates Build In Test SPL - Holds BIT status page while held 			
• MODE Switch	 Springloaded to Center OFST – Separates overlapping symbols LMT – Displays 6 highest threats 			
• DISPLAY TYPE	Changes Priority of Display			
Selector	 NORM - Normal threat symbology AI - Airborne Interceptor prioritized AAA - Anti-aircraft artillery prioritized UNK - Unknown prioritized FRIEND - Friendly threats prioritized 			
	 Indicated by Letter in Display Center 			
• Display	Outer Band Critical Band Imminent threat to own aircraft Blinking indicates engaging own aircraft craft			
	Middle Band			
	Lethal BandPotentially threatening emittersNot actively engaging own aircraft			
	• Inner Band			
	 Non-Lethal Band Not currently within capability of emitter 			
	Inner Circle			
	 N, I, A, U, F - Prioritization type O - Offset L - Limit B - BIT Failure T - Thermal overload 			
	2-17			

SYSTEMS F-14A/B REV: 20220214

Alert Tones

• Short Tone - New emitter / emitter moved

- Slow Warbling Threat in critical band
- Fast Warbling Threat actively engaging own aircraft
- **4-Tone Sequence** New threat capable of silently engaging own aircraft

2.4.2 ALR-67 RWR - THREAT SYMBOLOGY

SHIPS				
AB	Arleigh Burke			
AK	Admiral Kuznetsov			
GR Grisha 5 (Albatros)				
HP Oliver Hazard Perry				
J2 Type 054A Frigate, "Jiangkai II class"				
KK	Krivak 3 (Rezky)			
KV	Kirov (Pyotr Velikiy)			
LI	Type 052B Destroyer, "Luyang I class"			
L2	Type 052C Destroyer, "Luyang II class"			
N	Ship with Nav Radar			
NE Neustrashimy NZ Nimitz (Vinson, Stennis				
			SV Slava (Moscow)	
TC Ticonderoga				
TT	Tarantul 3 (Molniya)			
TW Tarawa				
YU	Type 071 Amphibious Transport Dock, "Yuzhao class"			
	AIRCRAFT			
14	F-14A/B			
15	F-15C/E			
16 F-16C				
<u>17</u>	JF-17			
18	F/A-18C			
19	MiG-19			

21	MiG-21bis	
23	MiG-23MLD	
24	Su-24M/MR	
25	MiG-25PD	
29 MiG-29A/G/S Su-27 Su-33 J-11A		
30	Su-30	
31	MiG-31	
34	Su-34	
37	AJS-37	
39	Su-25TM	
50	A-50	
52	2 B-52	
AN AN-26B AN-30M		
AP	AH-64D	
B1	B-1B	
BE	Tu-95 Tu-142M	
BF	Tu-22M3	
BJ	Tu-160	
E2	E-2D	
E 3	E-3C	
F4 F-4E		
F5 F-5E		
нх	Ka-27	
IL	IL-76MD IL-78M	
KC	KC-135	

KJ	KJ-2000			
M2	Mirage 2000-C			
	Mirage 2000-5			
S3 S-3B				
SH SH-60B				
ТО	Tornado			
TR	C-130 C-17A			
	AIR DEFENSE			
2	S-75 TR SNR (SA-2) "Fan Song"			
3	S-125 TR SNR-125 (SA-3) "Low Blow"			
6	Kub SA-6			
7	HQ-7TR			
8	OSA (SA-8)			
10	S-300PS 30N6 TR (SA- 10)			
11 Buk (SA-11)				
12	S-300V			
15	Tor 9A331 (SA-15)			
19	Tunguska 2C6M (SA-19)			
Α	Gepard M-163 Vulcan			
	ZSU-23-4 Shilka			
ВВ	S-300PS 64H6E SR (SA- 10/Big Bird)			
BF	Rapier Blindfire TR			
CS	S-300PS 5N66M SR (SA-10/Clam Shell)			
DE	Sborka (Dog Ear)			
FF	S-125 P-19 SR (SA-3/Flat Face)			
GR Roland SR				

НА	Hawk SR			
НК	HK Hawk TR			
HQ	HQ-7 SR			
PT	Patriot			
RO	Roland			
RP	Rapier SR			
S	1L13 55G6 EWR			
SD	SD Buk TR (SA-11/Snow Drift)			
SN	SN PRW-11 (Side Net)			
	MISSILES			
M AIM-54 AIM-120 MICA-EM R-37 R-77 SD-10				
	ATC			
T	Airport ATC Radar			

2.4.3 ALE-39 CMS DISPENSER

Programmer				
	 Options – 1-4 cartridges, C continuous, R random (4-6 cartridges) 			
	B INTV – Time in seconds between each car- tridge ejection			
	 Options1, .2, .5, .7, 1 seconds, R random 			
	S QTY - How many salvos of bursts			
	- Options - 1, 2, 4, 6, 8, 10, 15 salvos			
	• S INT – Time in seconds between salvos			
	- Options - 2, 4, 6, 8, 10 seconds			
WARNING R & C burst	settings have special INTV behavior			
Section	Jammer cartridges not implemented in DCS			
• FLARE Section	QTY – Number of cartridges to eject in burst			
	- Options - 2, 3, 4, 6, 8, 10 cartridges			
	INTV – Time in seconds between each car- tridge ejection			
	- Options - 2, 4, 6, 8, 10 seconds			
	Control Panel			
• PWR/MODE Switch	 AUTO (CHAFF) / MAN – Enables power to system and allows automatic chaff ejection program initiation MAN – Enables power to system 			
	OFF – Disables system			

2.4.4 ALQ-100 / ALQ-126 DECM

Chapter 3

AWG-9 RADAR

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3.1	OVERVIEW
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	3.1.2 MAIN MODES
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3.3	PULSE DOPPLER MODES
	3.3.1 PD - PULSE DOPPLER SEARCH
	3.3.2 PD - RWS
	3.3.3 PD - TWS
	3.3.4 PD - TWS MAN
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	3.4.1 ACM MODES - OVERVIEW
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3.5	TACTICAL INFORMATION DISPLAY
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3.1 OVERVIEW

3.1.1 MAIN MODES - OVERVIEW

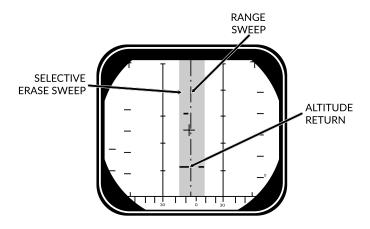
	Pulse		Pulse Doppler			
	Pulse Search	P-STT	PD Search	RWS	TWS	PD-STT
Range	60 nm	50 nm	110 nm	90 nm	90 nm	90 nm
AIM-7	BRSIT	CW	BRS	SIT	-	PD
AIM-54	BRSIT	ACT	BRS	SIT	Multi TGT	PD/ACT

3.1.2 MAIN MODES

• Pulse	Basic Pulse w/o doppler filtering		
	- Cannot be notched		
	 Ground Clutter 		
	 Rudimentary Ground mapping 		
	 Pulse Sub-Modes 		
	– Pulse Search		
	- Pulse-STT		
 Pulse Doppler 	 Doppler filter> no ground returns 		
	 Susceptible to notching 		
	 No ground clutter 		
	- Greater range		
	 Advanced sub modes 		
	- AIM-54 Guidance		
	 Pulse Doppler Sub-Modes 		
	- PD Search		
	- RWS		
	- TWS		
	- PD-STT		

3.2 PULSE MODES

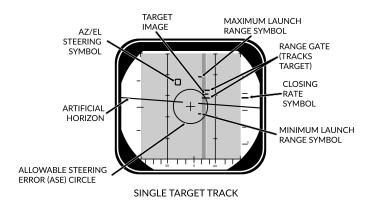
3.2.1 PULSE - PULSE SEARCH



SEARCH (±10° SCAN)

Pulse Search	Basic Mode - AWG-9 does not use pulse doppler filtering • Advantages
	All aspect target detectionCannot be notchedRudimentary ground mapping
	 Disadvantages
	Cannot discern ground returns and targetsLower range
• DDD	Range/Azimuth
	 Visual representation of radar and erase sweeps
• TID	No Information from PulseCannot guide AIM-54

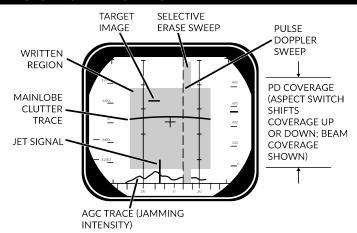
3.2.2 PULSE - PSTT



 Pulse STT 	Lock Target w/o doppler filtering
	Advantages
	- Cannot be notched
	 Disadvantages
	- Susceptible to ground clutter
 Lock Target 	• Conditions
	Pulse Search Mode selectedRDR HCU Mode selected
	Lock Target
	(a) Hold HCU Half-action
	(b) Slew to desired Target
	(c) HCU Full-Action to lock
	Unlock Target
	(d) HCU Half-action
• DDD	Track Indications
	- ANT TRK light
	- RDROT light
	- Tracking gates
	- Closure rate
	– Attack Symbology

3.3 PULSE DOPPLER MODES

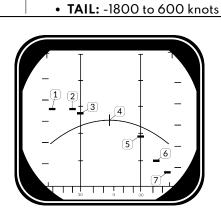
3.3.1 PD - PULSE DOPPLER SEARCH



SEARCH (±40° SCAN)

•	Pulse Doppler Search	"Early Warning" Mode - Longest Range, cannot display range • Advantages
		Longest RangeDoppler Filtering"Look Down Shoot Down"
		Disadvantages
		Can be notchedNo range information
•	DDD	 Closure Rate/Azimuth Visual representation of radar and erase sweeps
•	Doppler Filters	Main Lobe Clutter (MLC) Filter
		Own GS +/- 133 knotsRemoves main ground returnSource of notching
		• Zero Doppler Filter
		 Negative own GS +/- 100 knots Removes Radar reflection from ground directly beneath own AC

AWG-9 RADAR	F-14A/B REV: 20220214
• MLC Switch	 IN: Enables MLC filter AUTO: Enables MLC filter if look-up angle less than 3 deg OUT: Disables MLC filter
• Vc Switch	Changes closure rate DDD scale • X-4: -800 to 4000 knots • NORM: -200 to 1000 knots • VID: -50 to 250 knots
ASPECT Switch	Changes closure rate processing scale • NOSE: -600 to 1800 knots • BEAM: -1200 to 1200 knots



	Look Angle	Line of Sight Rate	Target Heading
1	60 deg	1490	180 deg
2	45 deg	1500	120 deg
3	30 deg	1428	100 deg
4	0 deg	1200	90 deg
5	30 deg	672	80 deg
6	45 deg	210	60 deg
7	60 deg	-300	0 deg

3.3.2 PD - RWS

Range While Search	FM Ranging, used for getting good A/A picture before selecting TWS • FM Ranging
	 Pulse Doppler with ranging TID shows momentary tracks with ranges Processing reduces max range
	Advantages
	Long RangeDoppler Filtering"Look Down Shoot Down"Signal Processing
	 Disadvantages
	- Can be notched
• DDD	 Closure Rate/Azimuth Visual representation of radar and erase sweeps
• TID	 Momentary Tracks Max concurrent tracks: 48 Cannot lock targets from TID
Filtering	Same as Pulse Doppler Search

3.3.3 PD-TWS

•	Track While Scan	Builds Track Files, high situational awareness, multi-target AIM-54 launch • Track Files
		 AWG-9 builds Trackfiles for contacts Can launch multiple AIM-54 Processing reduces max range Can lock targets from TID
		 FM Ranging Pulse Doppler with ranging TID shows momentary tracks with ranges
		Processing reduces max rangeAdvantages
		Doppler FilteringMulti-Target AIM-54
		 Disadvantages
		Lowest RangeCan be notched
•	DDD	 Closure Rate/Azimuth Visual representation of radar and erase sweeps
•	TID	 Tracksfiles Max concurrent tracks: 24 Max displayed tracks: 18
•	Filtering	Same as Pulse Doppler Search
•	Scan Volume	Trackfiles require update every 2.5 s -> • 20 deg 4 bar (if selected) • 40 deg 2 bar (else)
•	TID Mode Selector	 GND STAB: Ground Stabilized, True North is up on TID A/C STAB: Aircraft Stabilized ATTAK: same as A/C STAB with superimposed attack steering symbology TV: Displays TCS on TID, dispays LANTIRN on TID if equipped

AWG-9 RADAR	F-14A/B REV: 20220214
• TID Display Selector Buttons	 RID DISABLE: Not simulated ALT NUM: Enables display of track altitudes on left side of track symbols SYM ELEM: Enables display of all supplementary symbology of tracks and waypoints DATA LINK: Enables display of D/L contacts JAM STROBE: Enables display of jam strobes NON-ATTK: enables/disables display of targets not possible to engage (friendlies) LAUNCH ZONE: Enables display of weapon launch zones VEL VECTOR: Enables display of velocity vectors
• TRACK HOLD CLSN Steering Buttons	 TRACK HOLD Normally: Tracks maintained for 14 s after last observation Track Hold: maintained for 2 min after last observation
	CLSN Button
	 begins collision steering to currently tracked target enables Steering Centroid if in TWS LD CLSN presents azimuth steering only CLSN presents both azimuth and elevation steering
 TWS AUTO / MAN 	• TWS MAN: Manual azimuth/elevation con-

trol, target designation by RIO

• TWS AUTO: Automatic prioritization of targets and azimuth elevation control

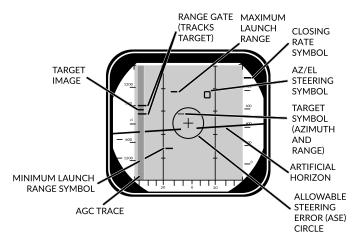
3.3.4 PD - TWS MAN

• TWS MAN	 Target Selection: Manual
	 Scan Azimuth/Elevation: Manual
• Target Selection	 Conditions
	- TWS MAN Radar Mode selected
	 TID CURSOR TID Mode selected
	 Hook Target
	(a) Hold HCU Half-Action
	(b) Slew TID Cursor over desired Tgt
	(c) HCU Full-Action to select Tgt
	 TID Symbology
	- Range (RA)
	- Bearing (BR)
	Altitude (AL)
	Magnetic course (MC)
	 Lock Target
	(d) Press PD STT or Pulse STT buttons
	 Deselect Target
	(e) press HCU Half-Action
AIM-54 Launch	 Automatically selects TWS AUTO
	 Prevents selection of TWS MAN

3.3.5 PD - TWS AUTO

TWS AUTO	 Target Selection: prioritizes contacts based off range, aspect, closure Scan Azimuth/Elevation: Geometric center of targets in scan volume
Centroid / Steer-	Steering Centroid
ing Cues	 facilitates steering cues HUD, VDI, TID, DDD Appears as X on TID Takes Gimbal limits into account Weights individual Tracks based on parameters
	Illumination Centroid
	 Not Visible Controls azimuth and elevation of scan pattern Takes scan volume into account
 Pilot Steering 	 Conditions
Cues	 A-A HUD Mode selected Master Arm ON (UP) AIM-54 or AIM-7 selected TWS-AUTO selected

3.3.6 PD - PDSTT



SINGLE TARGET TRACK

•	Pulse Doppler STT	Lock Target with doppler filtering • Advantages
		 Ground Clutter filtering
		Disadvantages
		 Susceptible to notching
•	Lock Target	Conditions
		Pulse Doppler Mode selected (PD Search, RWS, TWS)RDR HCU Mode selected
		• Lock Target
		(a) Hold HCU Half-action(b) Slew to desired Target(c) HCU Full-Action to lock
		Unlock Target
		(d) HCU Half-action
•	DDD	Track Indications
		- ANT TRK light
		 RDROT light
		 Tracking gates
		- Closure rate
		Attack Symbology

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3.4 ACM

3.4.1 ACM MODES - OVERVIEW

	PLM	VSL	PAL	MRL
Range	5 nm	5 nm	15 nm	5 nm
Description	Boresight	Vertical	Horizontal	RIO
Weapons		Gun +	All Missiles	

ANTENNA COVERAGE (NOT DISPLAYED) **PLM** • Pilot Lockon Mode Highest Priority **ACM** Search Pattern - Small Boresight - Range: 5 nm • Vertical Scan Lockon **VSL** HI Search Pattern - Width: 5 deg - Vertical: +15 to +55 deg - Range: 5 nm LO Search Pattern - Width: 5 deg - Vertical: -15 to +25 deg - Range: 5 nm RIO/PILOT Controlled Pilot Automatic Lockon PAL Search Pattern - Width: +/- 20 deg - Vertical: 8-bar - Range: 15 nm MRL • Manual Rapid Lockon RIO Controlled Search Pattern - HCU Controlled - Range: 5 nm

REV: 20220214

3.4.2 APX-76 IFF

3.5 TACTICAL INFORMATION DISPLAY

3.5.1 TID SYMBOLOGY

GENERAL				
Center Dot	•	Basic Component of Symbols		
		 Marks coordinates of symbol 		
Own AC		 Symbol representing own air- craft 		
		 Ground Stabilized: Moves Aircraft Stabilized: Stationary Outside TID: line drawn from TID center towards symbol 		
TID Cursor		Hook Cursor		
		 Controlled by HCU in TID mode 		
		Half-Action		
		 Enables display of symbol Enables HCU stick to move cursor 		
		Full-Action		
		 Hooks closest symbol If no symbol near, cursor dropped at location 		
TWS Steering Cen- troid	$ \times $	Steering centroid of TWS tracks		
		 Selected by WCS for weapons engagement 		
ONBOARD SENS	ORS	Symbol Above Dot		
Unknown	•	 Unknown Sensor Track All Returns in RWS		
Hostile	•	Sensor Track designated Hos- tile by RIO		
Friend	·	Sensor Track designated Friendly by RIO		

Angle-Tracked		Radar Angle Tracking
Radar Target		- Jamming Target
Angle-Tracked Radar Target with	(•)	Radar Angle Tracking
Altitude Difference Ranging		Jamming TargetAlt. diff. ranging
TCS-Angle Tracked Target	•>	TCS Angle Tracking
TCS-Angle Tracked		TCS Angle Tracking
Target with Altitude Difference Ranging		– Alt. diff. ranging
D/L TARGETS		Symbol Below Dot
Unknown		 D/L Track designated Un- known by Source
Hostile	•	D/L Track designated Hostile by Source
Friendly		D/L Track designated Friendly by Source
MANUAL REF PO	INTS	
Home base		Waypoint Representing
		– Home Base
		- Carrier
	1 .	- Airfield
Waypoint	•	Nav WaypointSupplanted by Number
Defended Point		- 1, 2, or 3 • Waypoint to Defend
Defended Foint		• waypoint to Defend
Fixed Point	X	Generic Waypoint
Hostile Area		Waypoint Indicating Hostile Area
Surface Target		Waypoint Indicating Surface Target
IP		Initial Point
		- Waypoint for A/G engage- ment

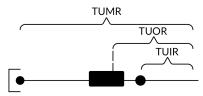
D/I REF POINTS

D/L REF POIN	ΓS			
Home Base		 D/L Waypoint Representing Home Base 		
Waypoint	***	 D/L Generic Waypoint 		
Data Link Fixed Point	X	 D/L Waypoint Representing Fixed Point 		
Surface Target		 D/L Waypoint Representing a Surface Target 		
POS SYMB MODII	FIERS			
Mandatory Attack		 Additional Symbology on TWS Track 		
		 Horizontal bar through center dot 		
		 Selected by RIO 		
		 Only 1 target can be designated Guaranteed WCS priority number 		
Data Link Destroy		 Additional Symbology on D/L Track 		
		 Horizontal bar through center dot 		
		 Selected by Source 		
		 No effect on WCS prioritization 		
Do Not Attack		 Additional Symbology on TWS or D/L Track 		
		 Vertical bar through center dot 		
		• If Set by RIO		
		 Removes WCS prioritiza- tion 		
Multiple Targets		 Additional Symbology on TWS or D/L Track 		
		 Horizontal bar on left side of symbol 		
		 Indicates Multiple Targets 		

Data Link Challenge		 Additional Symbology on D/L Track
		 Small V with center at center dot
		 Command to Visually Identify
Track Extrapolated	\hat{\hat{\chi}}	 Additional Symbology on TWS or D/L Track
		 Small X with center at center dot
		 No Update within 8 seconds
		 Track deleted after 14 seconds
		 Or after 2 min if track hold
Altitude Numerics	4/^\	 Altitude to Nearest Ten Thou- sand
		- example: 35000-45000
Firing Order Numerics	/^\4	 Indicates AIM-54 Prioritiza- tion
		Numbers 1-6Only in TWS
Time-to-Impact (TTI)	<u>_</u> 	After AIM-54 Launch
	, • \	 Prioritization replaced with estimated TTI
		Flashes after Pitbull
Velocity Vector		 Additional Symbology from center Dot
		 Direction represents track heading
		 Length represents speed
		 Varies with Mode
		 Ground Stabilized: true heading and ground speed Aircraft Stabilized: relative heading and velocity

Launch Zone Vectors





- Additional Symbology for AIM-54
 - Selected manually by RIO
 - Or 60 seconds from max launch

TUMR

- Time-Until-Minimum-Range
- Max: 180 seconds, 1.5 inches

TUOR

- Time-Until-Optimal-Range
- Start of bar is 8 seconds from optimum

TUIR

imuth

- Time-Until-In-Range

Radar Antenna Scan Pattern Azimuth Limits

Jamming Strobe



• Line from own AC towards Jammer

Limits of Current Scan Az-

• Single Line in STT

Data Link Jamming Strobe



• Line from D/L point towards
Jammer

Data Link Pointer



- Additional Symbology on D/L Track
 - Circle
 - Indicates operator concern

AWG-9 RADAR F-14A/B REV: 20220214

Data Link Priority Kill ATTACK DISPLAY SYM	ABOLOGY.	Additional Symbology on D/L Track Square Indicates target must be destroyed No effect on WCS prioritization
Artificial Horizon		Represents Pitch and Roll
Steering Guidance Symbol		 Represents Steering Error Should be placed as near as possible to center of ASE circle
Allowable Steering Error Circle		 Indicates Allowable Steering Error for Missile Launch Size Varies with Geometry, Mode, Missile
Breakaway Indica- tion	X	 Appears when Target Range Less than Minimum for Se- lected Weapon

Chapter 4

TCS - LANTIRN

Co	n	τ	е	n	τ	S

4.1	TCS
	4.1.1 OVERVIEW
4.2	LANTIRN
	4.2.1 OVERVIEW
	4.2.2 OVERVIEW - STARTUP
	4.2.3 OVERVIEW - POINTING MODES
	4.2.4 OVERVIEW - LASING/DESIGNATION
	4.2.5 CONTROLS - PANEL
	4.2.6 CONTROLS - STICK
	4.2.7 DISPLAY

F-14A/B

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4.1 TCS

4.1.1 OVERVIEW

TCS - LANTIRN F-14A/B REV: 20220214

4.2 LANTIRN

4.2.1 OVERVIEW

• LANTIRN		Low Altitude Navigation and Targeting Infra-Red for Night		
		 Only Targeting Pod – Nav pod was deleted 		
		 Incomplete Integration – Own control panel, supplants TCS feed 		
Master Modes		• A/G – Allows bomb release guidance		
		 A/A – Optimized for air targets 		
•	FOV Levels	• Wide		
	Overview	- FOV - 5.9 deg		
		FOV - 5.9 degSlew - 8.5 deg/s		
		Narrow		
		- FOV - 1.7 deg		
		- Slew - 1.8 deg/s		
		• Expanded		
		- FOV - 0.8 deg		
		- Slew - 0.7 deg/s		
		 Digital Zoom - Degraded quality 		

4.2.2 OVERVIEW - STARTUP

1.	Power Switch	POD
2.	Pod Startup Sequence	 8 min startup sequence MODE Switch shows STBY when complete
3.	MODE Switch	Press
4.	Initialization Sequence	 30 sec initialization MODE Switch shows OPER when ready
5.	VIDEO Switch	FLIR
6.	TID MODE	TV

4.2.3 OVERVIEW - POINTING MODES

Sensor Modes	Contrast Lock
Overview	Area TrackPoint Track
	• Q Designation
	Directional Q - QSNO / QADL / QHUDLocation Q - QWp / QDES
Directional Q	Do Not Allow Weapon Guidance QSNO
	 Pod slaved to ground 15 nm in front along own aircraft heading
	• QADL
	Pod slaved to ADLIn A/A mode
	• QHUD
	Pod slaved to HUDIn A/G mode
Location Q	Allow Weapon Guidance QWp
	Pod slaved to WCS waypointCycled with QWp+ / QWp-
	• QDES
	 Designate targets for engagement LANTIRN Trigger Second Detent to designate Coordinates can be manually added to WCS for navigation

TCS - LANTIRN F-14A/B REV: 20220214

4.2.4 OVERVIEW - LASING/DESIGNATION

(a) DesignateTrigger Full-Action	
Laser FiresSlant Range calculated	
Automatically activated when QDES selected/designated	
QDES remains even if new Q selected	
 Cues still point towards QDES even if pod at another point 	
(a) LaseTrigger Half-Action Hold	
• Effect – Lases for 60 sec	
(a) ActivateLatch Lase Button Press	
(b) Extend Latch Lase Button Press	
(c) DeactivateTrigger Half-Action	
• Effect – Fires from -10 to +4 sec TIMP	
(a) Laser ModeSlider AFT Short	
(b) Cycle A/M Right 4-Way Depress	
Always at current Pod location	
Can point to different location than QDES	

4.2.5 CONTROLS - PANEL

• Power Switch	 OFF - Disables power to system IMU - Only powers LANTIRN IMU (Not Simulated in DCS) POD - Powers whole system
• MODE Switch	STBY – StandbyOPER – Operational
• LASER Switch	ARM – Arms laserSAFE – Inhibits laser use
• VIDEO Switch	 FLIR – Displays LANTIRN FLIR on TID TCS – Displays TCS video on TID
• Indicator Light	Indicate Error States
• IBIT Button	Initiates Build-In-Test

4.2.6 CONTROLS - STICK

•	Master Mode	A/G Mode – Side 2-Way FWDA/A Mode – Side 2-Way AFT
•	Slew	Center Slew Hat
•	WHOT/BHOT	Center Slew Hat Depress
•	Contrast Track	 Point Track – Left 4-Way Up Area Track – Left 4-Way Down
•	Q Select	 QADL/QHUD – Right 4-Way Up QDES – Right 4-Way Right QSNO – Right 4-Way Down
•	Declutter	Right 4-Way Depress
•	Zoom Level	FOV Button
•	Cycle Gain Control Mode	Slider FWD short
•	Manual Gain Control	(a) Slider
•	Laser Code	(a) Slider AFT short (b) Select Digit Right 4-Way Left/Right (c) Change Digit Right 4-Way Up/Down
•	Focus Control	(a) Slider AFT hold (b) Right 4-Way Up/Down
•	Manual Lase	Trigger Half-Action
•	Latched Laser	Latched Laser Fire Button
•	Designate QDES	Trigger Full-Action

4.2.7 DISPLAY

. T I . ft		
• Top Left	Own Aircraft Datablock	
	- Lat - deg:min.dec	
	- Long - deg:min.dec	
	- ALT - Altitude (ft)	
	 KGS – Knots Ground Speed 	
	DIVE – Dive Angle (deg)	
 Mid Left 	 Sensor Mode – WHOT / BHOT 	
	Gain Control – Auto / Manual	
 Bottom Left 	Pod Info Datablock	
	- SRA – Slant Range	
	AZ - Pod LoS Azimuth L/R	
	- EL - Pod LoS Elevation	
	- Time - UTC Time	
	- IBIT - Codes	
 Bottom Center 	 Master Mode – A/A / A/G 	
	 Track Mode – AREA / POINT / Q 	
	Current WeaponLaser Code	
	• L	
	- Steady - Laser Armed	
	 Flashing – Laser Firing 	
Bottom Right	Q Datablock	
	- TTG - Time-To-Go	
	- B/R - Bearing and Range	
	- ELEV – Elevation (ft) of Q	
	- Lat - deg:min:dec	
	- Long - deg:min:dec	
Mid Center	Crosshair	
	 Bounding Box – Indicates currently 	
	tracked target in point mode	
	- Zoom Boxes - Indicates next zoom lev-	
	els	
	 FLIR Pointing Cue – Shows Pod LoS, 	
	screen center indicates straight down	

TCS - LANTIRN	F-14A/B REV: 20220214
 Mid Right 	Bomb Rlease Cue
	 Only shown if current Q is QDES, with valid weapon selected TREL - Time to release
	- TIMP - Time to Impact (after release)
Top Center	Steering Guidance to Q
	- Relative bearing L/R to commanded

heading

Chapter 5

A/G WEAPONS

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	5.1.1 A/G WEAPON SETTINGS - OVERVIEW
	5.1.2 SELECTIVE ORNANCE JETTISON
5.2	UNGUIDED
	5.2.1 M61 GUN
	5.2.2 FFAR / ZUNI ROCKETS
	5.2.3 UNGUIDED BOMB - CCIP
	5.2.4 UNGUIDED BOMB - CCRP
5.3	GUIDED
	5.3.1 LASER GUIDED BOMB
	5.3.2 TALD DECOYS

5.1 SETTINGS

5.1.1 A/G WEAPON SETTINGS - OVERVIEW

• WPN TYPE	Selects Weapon Type
	 Configures WCS for selected weapon Refer to Kneeboard for list of mounted weapons Mk-81 / 82 / 83 have both L and H option refering to high and low drag
• DLVY MODE	 STP-SGL – Single weapon per press STP-PRS Single pair per press RPL-SGL – QTY of weapons per press RPL-PRS – QTY of pairs per press
• DLVY OPTNS	 INTERVAL – Interval in ms QTY – Number of stores to be released
• MECH FUZE	 NOSE – Arms nose fuze SAFE – Inhibits arming of fuzes NOSE/TAIL – Arms both fuzes
• ELEC FUZE	 SAFE - Inhibits electrical bomb fuzing VT - Sets air-burst mode at preset burst height for compatible stores INST - Sets instantaneous burst mode DLY 1 - Sets preset time delay 1 DLY 2 - Sets preset time delay 2
• STA SEL	Selects Stations for Employment/Jettison
	 Set to SEL to activate a pylon Stations 1 & 8 should be set to B for selection Station 1 & 8 SW was used for Sidewinder jettison, is now inoperable
 TANK JETT 	 Allows Drop Tank Jettison
• SEL JETT	 JETT – Selective jettison SAFE – Inhibits jettison AUX – Backup mode
• JETT OPTIONS	 MERTER – Jettisons ejector racks WPNS – Jettisons weapons only

A/G WEAPONS F-14A/B REV: 20220214

ATTK MODE

- CCMPTRTGT
 - Computer Target Similar to CCRP
- CMPTR IP
 - Computer initial point
 - Extended CMPTR TGT mode using known IP
 - For use when target hard to spot visually but close to landmark
- CMPTR PLT
 - Computer Pilot similar to CCIP
- MAN
 - Manual HUD displays pipper
 - Backup mode
- D/L BOMB
 - Data-Link Bomb Automatic mode steered by D/L cues
 - Not Implemented in DCS

5.1.2 SELECTIVE ORNANCE JETTISON

1.	Pilot Conditions	MASTER ARM ON
2.	RIO Conditions	Desired Stations
3.	Jettison	(a) SEL JETT GuardFlipped (b) SEL JETT SwitchJETT

5.2 UNGUIDED

5.2.1 M61GUN

1.	Pilot Conditions	• MASTER ARM	ON
		• HUD	A/G
		WEAPON SELECTOR	GUNS
		Wing Sweep	ВОМВ
2.	Employment	(a) Dive	20-30 deg
		(b) Pipper	on target
		(c) TRIGGER	FIRE
•	Note: TCS	TCS slaved to radar impact p	oint
		Rio can select NAR or WIDE	

5.2.2 FFAR/ZUNI ROCKETS

1.	RIO Conditions	• WPN TYP	LAU-10
		Attack Mode	Pilot Attack
		Deliver Mode	RPL-SGL
		Mechanical Fuze	NOSE
		Electronic Fuze	INST
		Delivery Options	As Desired
		• Stations	Armed
2.	Pilot Conditions	• MASTER ARM	ON
		• HUD	A/G
		WEAPON SELECTOR	OFF
		• Stations	verify selected
		Wing Sweep	ВОМВ
3.	Employment	(a) Dive	20-30 deg
		(b) Pipper	on target
		(c) TRIGGER	FIRE

5.2.3 UNGUIDED BOMB - CCIP

1.	RIO Conditions	• WPN TYP	MK-8X
		Attack Mode	Pilot Attack
		Deliver Mode	STP-PRS
		Mechanical Fuze	NOSE
		Electronic Fuze	INST
		Delivery Options	As Desired
		• Stations	Armed
2.	Pilot Conditions	• MASTER ARM	ON
		• HUD	A/G
		WEAPON SELECTOR	OFF
		• Stations	verify selected
		Wing Sweep	ВОМВ
3.	Employment	(a) Dive	40 deg
		(b) Pipper	on target
		(c) STORE RELEASE	_
		5-5	

5.2.4 UNGUIDED BOMB - CCRP

1.	RIO Conditions	WPN TYP
		Mechanical FuzeNOSE
		• Electronic FuzeINST
		Delivery Options As Desired
		StationsArmed
2.	Pilot Conditions	• MASTER ARM ON
		• HUD A/G
		WEAPON SELECTOR OFF
		• Stationsverify selected
		Wing Sweep BOMB
3.	Designation	(a) Slew DiamondVSL HI/LO
	•	(b) DesignatePAL
4.	Employment	(a) Flight Path Straight, Level (b) Vel Vector on Bomb Fall Line
		When Solution Cue meets Velocity Vector
		(c) STORE RELEASEPress and Hold

5.3 GUIDED

5.3.1 LASER GUIDED BOMB

1.	LANTIRN	(a) Target Pod PowerPOD		
٠.	PREP			
TRE		Warm up takes approx. 8 min		
		Automatically switches to STANDBY		
		(b) Laser Codeas desired		
		 MUST BE SET ON THE GROUND 		
		• Default: 1688		
		(c) LANTIRN ModeOPERATE		
		 STANDBY caution will flash for 30 s 		
		 Then switches to OPER 		
		(d) VIDEO SwitchFLIR		
		(e) TID ModeTV		
2.	RIO Conditions	• WPN TYPGBU-XX		
		Attack Mode		
		Deliver ModeSTP-SGL		
		Mechanical Fuze NOSE		
		Electronic FuzeINST		
		Delivery Options As Desired		
		Stations Armed		
3.	Pilot Conditions	• MASTER ARM ON		
		• HUDA/G		
		WEAPON SELECTOR OFF		
		• VDI ModeTV		
		• Stationsverify selected		
		Wing SweepBOMB		
4.	Slew LANTIRN	Refer to LANTIRN Control Section		
		• Slave to WYPT Left-4-Way RIGHT		
		QSNO (Snowplow)		
		Toggle FOV LANTIRN Toggle FOV Slew LANTIRN Stick		
		Area TrackLeft-4-Way UP		
		Point Track Left-4-Way Down		
		Undesignate LANTIRN Undesignate		
		,		

4. Designate	Refer to LANTIRN Designation Section (a) DesignateTrigger Full-Action • Slant Range calculated • Time-to-Go calculated
	Once Time-to-Realease (TREL) is 0
	(b) Auto-Lase If selected: lases 10s to impact (c) Manual LaseTrigger Full-Action (d) While LasingL blinks
5. Employment	Once Time-to-Realease (TREL) is 0
	(a) STORE RELEASE Press and Hold
	(b) Flight PathGentle right-hand turn
	(to prevent masking)

5.3.2 TALD DECOYS

1.	RIO Conditions	• WPN TYPTALD
		Deliver ModeSTP-SGL
		Delivery Options As Desired
		• StationsArmed
2.	Pilot Conditions	• MASTER ARM ON
		• HUD A/G
		WEAPON SELECTOR OFF
		• HSD ModeTID
		Stationsverify selected
3.	Employment	(a) Flight PathHigh / Fast
		(b) RWR Monitor to locate emitters
		(c) STORE RELEASEPress and Hold

Chapter 6

A/A WEAPONS

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6.1	M61 GUN
	6.1.1 M61 GUN - OVERVIEW
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	6.1.3 M61 GUN - RTGS / NO RADAR
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6.2	AIM-9 SIDEWINDER
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	6.4.2 AIM-54 - PD-STT
	6.4.3 AIM-54 - TWS / MULTI

6.1 M61 GUN

6.1.1 M61 GUN - OVERVIEW

• GUN RATE	Cycles Gun Rate
Button	- HIGH - 6000 rpm
	- LOW - 4000 rpm
A/A Gun Modes	• RTGS
	 Real-Time Gunsight Mode Selected automatically with guns If No WCS Data Available displays bullet location at 2000 ft with diamond and 1000 ft with pipper If WCS Data Available pipper displays bullet location at targets current range out to 4000 ft
	• MANUAL
	 Fixed manual pipper Adjust with GUN ELEV knob Press CAGE/SEAM to select
CAGE/SEAM Button	Cycles RTGS / MANUAL Gun Modes
ROUNDS Knob	Allows selection of remaining gun rounds

6.1.2 M61 GUN - MANUAL

1.	Pilot Conditions	• MASTER ARM	ON
		• HUD	A/A
		• Gun Rate	HIGH
		Gunsight Lead	as required
		WEAPON SELECTOR	GUNS
2.	Employment	(a) Gun Mode	MANUAL
		(b) Pipper	on target
		(c) Trigger	FIRE

6.1.3 M61 GUN - RTGS / NO RADAR

1.	Pilot Conditions	• MASTER ARM	ON
		• HUD	A/A
		• Gun Rate	HIGH
		WEAPON SELECTOR	GUNS
2.	Employment	(a) Gun Mode	RTGS
		(b) Pipper	on target
		(c) Trigger	FIRE

6.1.4 M61 GUN - RTGS / RADAR

1.	Pilot Conditions	• MASTER ARM	ON
		• HUD	A/A
		• Gun Rate	HIGH
		WEAPON SELECTOR	GUNS
2.	Employment	(a) Gun Mode	RTGS
		(b) Radar	STT
		(c) Pipper	on target
		(d) Trigger	FIRE

6.2 AIM-9 SIDEWINDER

6.2.1 AIM-9 - OVERVIEW

 Missile 	MSL PREP
Preparation	 AIM-9 seeker must be cooled
	 Either press SW COOL button
	 Or activation of ACM
 Seeker Head 	• SEAM
Modes	 Sidewinder Expanded Acquisition Mode
	 Double-D search pattern invisible to pilot
	- 4.5 sec search time
	 Allows AIM-9 to be uncaged and
	track target
	- 40 deg track limit
	- Allows WCS to slave AIM-9 to rada
	track
	Boresight
	 AIM-9 locked to ADL
	- 2.5 deg FOV
	 Selected if MODE/STP set to BRSIT
	- And ACM not active
 MODE/STP 	• NORM
Switch	 Allows SEAM seeker mode
	• BRSIT
	- Forces Boresight seeker mode
	- Overridden if ACM active
• CAGE/SEAM	Uncages Seeker
B	- Starts 4.5 second double-D search
Button	
Button	– If no IR source found cages again
Button	If no IR source found cages againSlaves Seeker

6.2.2 AIM-9-SILENT

1.	Pilot Conditions	• MASTER ARM	ON
		• HUD	A/A
		• SW COOL	ON
		• MODE/STP	As Desired
		• WEAPON SELECTOR	SW
2.	Employment	(a) CAGE/SEAM	Uncage Seeker
		(b) IR-Lock	Good Tone
		(c) Trigger	FIRE

6.2.3 AIM-9-RADAR

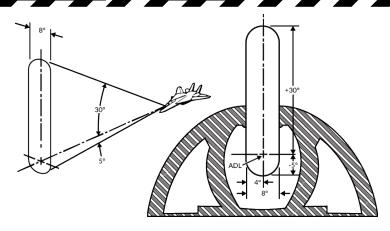
1.	Pilot Conditions	MASTER ARM	ON
		• HUD	A/A
		• SW COOL	ON
		• MODE/STP	NORM
		• WEAPON SELECTOR	SW
2.	Employment	(a) Radar	STT
		(b) CAGE/SEAM	Slave Seeker
		(c) IR-LOCK	Good Tone
		(d) Steering center T-sh	aped cue with ASE
		(e) Trigger	FIRE

6.3 AIM-7 SPARROW

6.3.1 AIM-7 - OVERVIEW

Missile Preparation	MSL PREP
	 AIM-7 must be tuned to AWG-9
	 Either press MSL PREP button
	 Or activation of ACM
 Launch Modes 	Normal
	 Standard operation, STT target designated before launch AIM-7 uses SARH all the way to target WCS can use CS or PD for guidance set with MSL OPTIONS Switch
	Boresight
	 Uses CS flood antenna of AWG-9 Missile will track strongest return in Flood area
	Automatically activated if STT brokenSelected if MODE/STP set to BRSIT
	– Or if no STT available
	- Shown Below
• MSL SPD	NOSE QTR
GATE Switch	 Standard setting in DCS
	All Others
	- Not simulated
• MSL OPTIONS	• NORM
Switch	 WCS uses dedicated CW antenna for AIM-7 guidance
	• SP PD
	 WCS uses PD from main flood antenna for AIM-7F/M guidance
MODE/STP	• NORM
Switch	- Sets normal launch mode logic
	• BRSIT

- Forces Boresight launch mode



6.3.	2 AIM-7 - STT	
1.	Pilot Conditions	MASTER ARM ON HUD A/A MSL PREP ON MODE/STP NORM WEAPON SELECTOR SP
2.	RIO Conditions	MSL SPD GATE
3. Employment	Employment	(a) RadarSTT
		Target < 20 deg from ADLASE center T-shaped cue within
	(c) TriggerPress and Hold (until weapon release)	
		(d) Radar Maintain Lock (until impact)

6.4 AIM-54 PHOENIX

6.4.1 AIM-54 - OVERVIEW

iquid cooling JID COOLING switch
uned to AWG-9 PREP button CM
H all the way to target e than TWS d effective range as VS launch
launches at 6 targets SARH guided -54 seeker range ivation command get: Requires auto- ommand
RSIT selected tive with no radar ed active before
in DCS

- Not simulated

A/A WEAPONS	F-14A/B REV: 20220214
• MSL OPTIONS Switch	NORM Normal guidance (SARH or SARH/ARH) PH ACT WCS immediately sends AIM-54 activation command on launch Reverts to SARH if no target detected Must be selected before launch
• TGTS Switch	 SMALL – 6nm activation range NORM – 10nm activation range LARGE – 13nm activation range
 Missile Next Launch Button 	 Selects Hooked Track as Next Target for AIM-54 TWS Engagement
MODE/STP Switch	NORM Normal operation BRSIT Commanded active before launch Missile follows ADL and locks strongest return
TWS Symbology	Refer to TID Symbology Section • Pre-Launch - Prioritization numbers assigned to tracks automatically or manually - Blinking indicates optimal launch parameters • Post-Launch - Target prioritization number replaced with TTI - Other prioritization numbers collapsed by one - Tracks under missile attack brightened - TTI blinks when missile active

• Normal Operation – 3-4 seconds

• When in ACM - I second

Launch To Eject

(LTE) Time

6.4.2 AIM-54 - PD-STT • MASTER ARM ON • HUD A/A • MSL PREP ON • MODE/STP NORM • WEAPON SELECTOR PH

(b) Steering

(a) **Radar**STT

(until impact)

6.4.3 AIM-54-TWS/MULTI

Employment

3.

1. Pilot Conditions	• MASTER ARM ON
	• HUDA/A
	• MSL PREP ON
	• MODE/STPNORM
	WEAPON SELECTOR PH
2. RIO Conditions	• LIQUID COOLING ON (FWD)
	MSL SPD GATE NOSE QTR
	MSL OPTIONSAs Desired
	TGTS Switch As Desired
	WCS ModeTWS MAN/AUTO
4. Employment	(a) Radar TWS
	(b) TriggerPress and Hold
	(until weapon release)
	(c) Repeat for remaining targets
	(d) Radar Maintain Track
	(until active)

