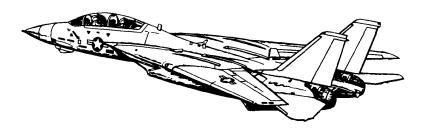
Pocket Checklist

F-14A/B AIRCRAFT

REV: 20210823



Procedures

Systems

AWG-9 Radar

TCS LANTIRN

A/G Weapons

A/A Weapons



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PROCEDURES

1.1 PILOT - PRE-START

1.	Parking Break	ENGAGED
2.	Ground Power	connected
3.	Compressed Air	connected
4.	ICS	HOT MIC
5.	TO RIO	"Begin Start-Up"
6.	ICS	Comm Check
7.	MASTER TEST Selector	 (a) LTS Warning Lights Caution Lights Checked Advisory Lights Checked (b) FIRE DET/EXT L FIRE GO illuminated R FIRE GO illuminated (c) INST RPM EGT 96% EGT FF 10500 pph AOA 18 ± 5 Wing Sweep 45 ± 2.5
		• FUEL QTY
8.	Ejection Seat	Armed
9.	RIO	Canopy Closed
10.	Oxygen	ON (FWD)
11	Emergency Wing Sweep	OVERSWEEP

PILOT - ENGINE START

1.	AIR SOURCE	OFF
2.	Hydraulics	(a) HYD TRANSFER PUMP SHUTOFF (b) Emerg. Hyd AUTO (LOW)
3.	L&R MASTER GEN	NORM
4.	RIO	"Ready to Start"
5.	Right Engine Start-Up	(a) Engine Crank R (b) R Eng N2 20% (c) R Throttle IDLE (d) TIT < 890 C during start
6.	Stabilized Parameters	 RPM
7.	Left Engine Start- Up	(a) Engine Crank L (b) L Eng N2 20% (c) L Throttle IDLE (d) TIT < 890 C during start
8.	Stabilized Parameters	 RPM
9.	HYD TRANSFER PUMP	NORM
10.	HYD PRESSURE	3000 psi
11.	AIR SOURCE	BOTH ENG
12.	Ground Power	disconnected
13.	Compressed Air	disconnected

1.3 PILOT - POST-START

	_ <u></u>	
1.	TO RIO	"Both Engines Running"
2.	Displays Control Panel	• VDI ON • HUD ON • HSD ON • HDS MODE TID (monitor INS)
3.	RIO	 Select Align Quality INS GO NOW: shortest but least precise alignment INS GO COARSE: does not meet Launch Criteria for AIM-7 / AIM-54 INS GO MIN WPN LAUNCH: allows AIM-7 / AIM-54 launch INS GO FINE fine align (8 min)
4.	ACM Panel	• GUN RATE
5.	Gun Rounds	Set
6.	ANTI-SKID SPOILER BK	OFF
7.	Emergency Wing Sweep	(a) Handle
8.	AFCS Panel - SAS STAB AUG	• PITCH
9.	WING/EXT TRANS	AUTO
10.	UHF 1 Function Selector	ВОТН
11.	TACAN Function Selector	T/R
12.	ARA-63 ICLS RE- CEIVER	ON

	OCEDURES		F-14A/B	 REV: 20210823	
40	Deden Altimates	1	(a) O a matural 1/m a la	and allaly OM to turn an	

13.	Radar Altimeter	(a) Control Knob one click CW to turn on (b) Display 6000 ft (warm up) (c) Display 0 ft (ready)
14.	Standby ADI	erect at least 2 min before T/O
15.	KY-28 Crypt. Key	Set (refer to GROUND SETTINGS kb)
16.	RIO	set D/L frequency
17.	Lights	As desired

1.4 RIO - PRE-START

1.	Oxygen	ON (FWD)
2.	PILOT	• Ground Power connected • Compressed Air connected
3.	ICS	Comm Check
4.	Lights	As required
5.	LTS Test	Coordinate with Pilot
6.	Ejection Seats	ARMED
7.	Canopy	CLOSED
8.	TO PILOT	"Ready to Start"

1.5 RIO - POST-START - SHORE

1.	PILOT	• Engines started • AIR SOURCEBOTH ENG
2.	INS STARTUP	(a) LIQUID COOLING ON (FWD) (b) WCS Switch STANDBY (c) IR/TV Power STBY/IR/TV (d) TID/DDD illuminated after 40 s
3.	Kneeboard	Retrieve Coordinates, Elevation, Magnetic Variation from GROUND SETTINGS Page
WA	RNING Input Coords E	BEFORE selecting GND ALIGN if using ASH
4.	Start INS Align	(a) Nav Mode GND ALIGN (b) CAP • Category NAV
		MESSAGE OWN AC (c) Keyboard
		 CLEAR, LAT, latitude, ENTER LONG, longitude, ENTER ALT, altitude, ENTER
		(d) CAP MESSAGE MAG HDG VAR (e) Keyboard HDG, mag var, ENTER (f) Align Progress
5.	U/VHF Mode	T/R G

6.	Datalink	(a) Kneeboard TACTICAL DL (b) DL Power ON (FWD) (c) DL Mode TAC (AFT) (d) DL Freq. Set
7.	TACAN	T/R
8.	RWR Panel	(a) Display Type NORM (b) PWR ON (c) TEST SPL (d) MODE LMT
9.	DECM	STBY, then ACT
10.	IFF	(a) MASTER
11.	Altimeter	Reset
12.	CAP	Enter Data (WP, FP, etc.)
13.	Displays	• DDD
14.	Hand Control Panel	Set
15.	AN/ALE-39	Set (as required) • AUTO (CHAFF)/MAN • MAN
16.	Flare Mode	PILOT
17.	Complete INS Align	 Duration Full Fine
		(a) Align Complete Caret → Diamond(b) NAV Mode
18.	Standby ADI	Erect at least 2 min before T/O
19.	TO PILOT	"Ready to Taxi"
Onc	e Airborne	
20.	IR/TV Power	ON
21.	WCS Switch	WCS XMT

PROCEDURES F-14A/B REV: 20210823

1.6 RIO - POST-START - CARRIER

1.	PILOT	• Engines started • AIR SOURCE
2.	INS STARTUP	(a) LIQUID COOLING
3.	Datalink	(a) Kneeboard
4.	Start INS Align	(a) DL FREQ Set (b) DL Mode CAINS/WAYPT (c) Nav Mode CVA
5.	U/VHF Mode	T/R G
6.	TACAN	T/R
7.	RWR Panel	(a) Display Type NORM (b) PWR ON (c) TEST SPL (d) MODE LMT
8.	DECM	STBY, then ACT
9.	IFF	(a) MASTER
10.	Altimeter	Reset
11.	CAP	Enter Data (WP, FP, etc.)
12.	Displays	• DDD
13.	Hand Control Panel	Set
14.	AN/ALE-39	Set (as required) • AUTO (CHAFF)/MAN • MAN
15.	Flare Mode	PILOT
16.	Complete INS Align	Duration Full Fine
		(a) Align Complete Caret → Diamond (b) NAV Mode

PR	OCEDURES	F-14A/B REV: 20210823
17.	Datalink	(a) DL Mode TAC (AFT) (b) DL Freq. Set
18.	Standby ADI	Erect at least 2 min before T/O
19.	TO PILOT	"Ready to Taxi"
Onc	e Airborne	
20	IR/TV Power	ON

WCS XMT

WCS Switch

21.

PROCEDURES F-14A/B REV: 20210823

1.7 PRE-TAXI

1.	ANTI-SKID SPOILER BK	OFF
2.	HOOK BYPASS	As Required
3.	Nose Strut	RETRACTED
4.	HUD MODE	ТО
5.	Parking Brake	Released (IN)
6.	NWS	ENGAGED
7.	Path	verify clear

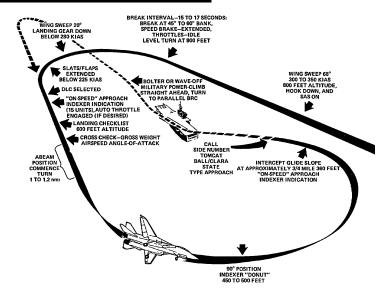
1.8 TAKEOFF - SHORE

		After Lining Up On Runway
1.	Wing Sweep	(a) EM WING SWEEP
2.	ANTI SKID SPOILER BK	BOTH (UP)
3.	FLAPS	UP
4.	Trim	0 deg
5.	NWS	DISENGAGED
6.	Takeoff	(a) Throttle MIL (90% RPM) (b) Stick Back at 130 KIAS (c) Rotation approx 140 KIAS (d) GEAR UP < 250 KIAS

1.9 TAKEOFF - CARRIER

	Lineup	 Wait behind JBD until Catapult is clear Follow Taxi Directors Instructions to line up on Catapult
1.	Wing Sweep	(a) EM WING SWEEP FWD, then IN (b) MASTER RESET PRESS (c) Wings Verify thumb controller (d) WING SWEEP AUTO (e) Wings Verify at 20 deg
2.	FLAPS	DOWN
3.	Launch Bar Preparation	(a) Nose Strut KNEEL when directed (b) Throttle UP when directed (c) Taxi launch bar into shuttle (d) Throttle IDLE when directed
4.	Trim	2-3 deg nose up
5.	Speed Brakes	IN
6.	Final Checks	(a) Throttle
		 Stick Full Forward Stick Full Aft Stick Full Left Stick Full Right Rudder Full Left Rudder Full Right
		(c) Eng. Inst
7.	Catapult Shot	(a) SaluteCAT SHOT
	· 	(b) Gear UP < 250 KIAS (c) Flaps UP < 225 KIAS

1.10 LANDING - OVERHEAD PATTERN



1.	Initial Approach	WING SWEEP68 deg
		• HOOKDOWN
		• SAS ON
		• HUDLDG
		• Airspeed300-350 KIAS
		• Altitude800 ft
2.	Initial Break	Break Interval 15-17 s
		• BANK45-60 deg
		SPEED BRAKE EXTEND
		ThrottleIDLE
		• G 3-4 G
		• Altitude800 ft
3.	Break Turn	• Wing Sweep AUTO < 280 KIAS
		• Landing Gear DOWN < 280 KIAS
		• FLAPS DOWN < 225 KIAS
4.	Downwind	DLC Selected once flaps out
		• AOA ON-SPEED
		LANDING CHECKLIST
		Altitudedescend to 600 ft

PROCEDURES F-14A/B REV: 20210823

5.	Final Turn	180 Deg Position • Abeam Pos	1-1.2 nmi
		• AOA	DONUT
		Altitude	400-500 ft
6.	Intercept Glides-	Distance	3/4 Mile
	lope	Altitude	360 ft
		• AOA	ON-SPEED

1.11 LANDING - CHECKLIST

1.	Wing Sweep	20 deg AUTO
2.	Wheels	• Lights 3 DOWN • Transition Light OUT
3.	SAS	ON
4.	FLAPS	DOWN
5.	DLC	Checked
6.	Hook	HOOK DOWN Transition Light OUT
7.	Harness	Locked
8.	Speedbrakes	EXT
9.	Brakes	Check
10.	Fuel	Check

1.12 AIRSTART

• Spooldown	Before significant spooldown (a) Non-Running ENGIDLE or above If no relight occurs (b) Non-Running ENG OFF then IDLE If still no relight occurs (c) ENG MODE SEC (d) Non-Running ENG OFF then IDLE
Cross-Bleed Restart	With one ENG running, if Spooldown fails (a) Non-Running ENG
Windmill Restart	(a) Airspeed
Post Restart	(a) BACK UP IGNITION OFF (b) ENG MODE PRI

SYSTEMS F-14A/B REV: 20210823

2 SYSTEMS

2.1 AFCS - SAS

• SAS	Stability Augmentation System
	Not Fly-by-Wire
	 Automatic control surface commands generated by analog computer to im- prove stability
• Controls	Three individual Switches
	- Pitch
	– Roll
	- Yaw
 Autopilot Emer- 	Paddle on Stick
gency Disengage Paddle	Disengages Autopilot ModesDeactivates Pitch, Roll SAS Channels

2.2 AFCS - AUTOPILOT

 Attitude Hold 	Basic Attitude Hold
	 Maintains existing pitch & roll Attitude can be changed with stick input If engaged outside limits will automatically move within range
	• Limits
	Pitch: 30 degRoll: 60 deg
	 Engagement
	(a) SAS Switches ON (FWD) (b) Alt. Hold Mode OFF (c) VEC/PCD/ACL OFF
	(d) Heading ModeOFF (e) Autopilot Switch ENGAGE (FWD)

 Altitude Hold 	Barometric Altitude Hold
	 Maintains current barometric altitude
	• Limits
	Vertical velocity: < 100 ft/s
	 Engagement
	(a) SAS Switches ON (FWD) (b) Autopilot Switch ENGAGE (FWD) (c) Alt. Hold Mode ALT (FWD) (d) A/P REF Light Wait until appears (e) NWS Button Press
 Heading Hold 	 Magnetic Heading Hold
	 Maintains current magneatic heading
	• Limits
	Bank angle < 5 deg
	 Engagement
	(a) SAS Switches ON (FWD) (b) Autopilot Switch ENGAGE (FWD) (c) Heading Mode HDG (FWD)
Ground Track	Autopilot follows ground track
	 Similar to heading hold
	 Compensates for wind drift
	 Uses INS data instead of mag. bearing
	• Limits
	Bank angle < 5 deg
	Engagement
	(a) SAS Switches
• VEC/PCD	Datalink Vector / Precision Course Direction
	 Allows Link 4 controller to remotely di- rect the aircraft
	- Not Modelled in DCS

~	YSTEMS	F-14A/B REV: 20210823
•	ACL	Automatic Carrier Landing
		 See relevant section
•	Autopilot Emer-	Paddle on Stick
	gency Disengage	 Disengages Autopilot Modes
	Paddle	- Deactivates Pitch, Roll SAS Channels
2.3	APC / AUTOTHROT	TLE
•	APC	Approach Power Compensator
		 Automatic throttle control
		- Maintains ON SPEED AoA
•	Conditions	Engagement is inhibited / APC is disengaged if
		conditions not met
		• Throttles
		Landing Gear HandleDown Maintage Missale No. 100 No
		Weight on Wheels No
•	Engage	Throttle Mode AUTO (FWD)
		<u> </u>
	Disengage ACLS WING-SWEEP	Cage/Seam Button
2.4 2.5	ACLS	In Flight Limited between 20 deg & 68 deg
	ACLS WING-SWEEP	
	ACLS WING-SWEEP	 In Flight Limited between 20 deg & 68 deg On Ground can Oversweep to 75 deg Hydromechanically Controlled
	ACLS WING-SWEEP	 In Flight Limited between 20 deg & 68 deg On Ground can Oversweep to 75 deg
	ACLS WING-SWEEP	 In Flight Limited between 20 deg & 68 deg On Ground can Oversweep to 75 deg Hydromechanically Controlled Automatically through CADC Manually with emergency wing-sweep handle 15 deg/s at 1g loading
	ACLS WING-SWEEP Overview	 In Flight Limited between 20 deg & 68 deg On Ground can Oversweep to 75 deg Hydromechanically Controlled Automatically through CADC Manually with emergency wing-sweep handle 15 deg/s at 1g loading Mechanically linked to ensure symmetry
	ACLS WING-SWEEP	 In Flight Limited between 20 deg & 68 deg On Ground can Oversweep to 75 deg Hydromechanically Controlled Automatically through CADC Manually with emergency wing-sweep handle 15 deg/s at 1g loading Mechanically linked to ensure symmetry AUTO CADC controls wing position as function
	ACLS WING-SWEEP Overview	In Flight Limited between 20 deg & 68 deg On Ground can Oversweep to 75 deg Hydromechanically Controlled Automatically through CADC Manually with emergency wing-sweep handle 15 deg/s at 1g loading Mechanically linked to ensure symmetry AUTO CADC controls wing position as function of current Mach via wing-sweep program
	ACLS WING-SWEEP Overview	In Flight Limited between 20 deg & 68 deg On Ground can Oversweep to 75 deg Hydromechanically Controlled Automatically through CADC Manually with emergency wing-sweep handle 15 deg/s at 1g loading Mechanically linked to ensure symmetry AUTO CADC controls wing position as function of current Mach via wing-sweep program MAN Pilot manually chooses desired wing
	ACLS WING-SWEEP Overview	In Flight Limited between 20 deg & 68 deg On Ground can Oversweep to 75 deg Hydromechanically Controlled Automatically through CADC Manually with emergency wing-sweep handle 15 deg/s at 1g loading Mechanically linked to ensure symmetry AUTO CADC controls wing position as function of current Mach via wing-sweep program MAN Pilot manually chooses desired wing sweep angle with thumb controller
	ACLS WING-SWEEP Overview	In Flight Limited between 20 deg & 68 deg On Ground can Oversweep to 75 deg Hydromechanically Controlled Automatically through CADC Manually with emergency wing-sweep handle 15 deg/s at 1g loading Mechanically linked to ensure symmetry AUTO CADC controls wing position as function of current Mach via wing-sweep program MAN Pilot manually chooses desired wing

• Emergency Mode	 Emergency Wing-Sweep Handle
	 Moved with wing sweep program by spider detent under normal operation Can be forced out of spider detent and moved manually
 Oversweep 	 Selected via Emergency Wing-Sweep Han- dle
	(a) Em. Wing-Sweep
	(b) HZ TAIL AUTHIlluminated (c) Em. Wing-Sweep75 deg
Return to CADC	After Emergency Mode / Oversweep
Control	(a) Em. Wing-SweepSpider Detent (Fwd on startup)
	(b) MASTER RESET Press

Indicated Mach	Max Forward Wing Position
0.4	20 deg
0.7	25 deg
0.8	50 deg
0.9	60 deg
1.0	68 deg

- 2.6 NAVIGATION
- 2.7 COMMUNICATION
- 2.8 DATALINK / IFF

2.9 ALR-67 RWR - OVERVIEW

 PWR Switch 	Set to ON to Operate
VOL Knob	Sets RIO Audio Level
TEST Switch	 Springloaded to Center BIT – Initiates Build In Test SPL – Holds BIT status page while held
MODE Switch	 Springloaded to Center OFST – Separates overlapping symbols LMT – Displays 6 highest threats
DISPLAY TYPE Selector	 Changes Priority of Display NORM – Normal threat symbology AI – Airborne Interceptor prioritized AAA – Anti-aircraft artillery prioritized UNK – Unknown prioritized FRIEND – Friendly threats prioritized Indicated by Letter in Display Center
• Display	Outer Band
	 Critical Band Imminent threat to own aircraft Blinking indicates engaging own aircraft
	Middle Band
	Lethal BandPotentially threatening emittersNot actively engaging own aircraft
	Inner Band
	Non-Lethal BandNot currently within capability of emitter
	Inner Circle
	 N, I, A, U, or F – Prioritization type O – Offset L – Limit B – BIT Failure T – Thermal overload

SYSTEMS

F-14A/B

REV: 20210823

Alert Tones

- Short Tone New emitter / emitter moved
- Slow Warbling Threat in critical band
- Fast Warbling Threat actively engaging own aircraft
- **4-Tone Sequence** New threat capable of silently engaging own aircraft

2.10 ALR-67 RWR - THREAT SYMBOLOGY

•	SHIPS	
AB	Arleigh Burke	
AK	Admiral Kuznetsov	
GR	Grisha 5 (Albatros)	
HP	Oliver Hazard Perry	
J2	Type 054A Frigate, "Jiangkai II class"	
KK	Krivak 3 (Rezky)	
ΚV	Kirov (Pyotr Velikiy)	
L1	Type 052B Destroyer, "Luyang I class"	
L2	Type 052C Destroyer, "Luyang II class"	
N	Ship with Nav Radar	
NE	Neustrashimy	
NZ	Nimitz (Vinson, Stennis)	
SV	Slava (Moscow)	
TC	Ticonderoga	
TT	Tarantul 3 (Molniya)	
TW	Tarawa	
YU	Type 071 Amphibious Transport Dock, "Yuzhao class"	
AIRCRAFT		
14	F-14A/B	
15	F-15C/E	
16	F-16C	
17	JF-17	
18	F/A-18C	
19		

21	MiG-21bis
23	MiG-23MLD
24	Su-24M/MR
25	MiG-25PD
29	MiG-29A/G/S Su-27 Su-33 J-11A
30	Su-30
31	MiG-31
34	Su-34
37	AJS-37
39	Su-25TM
50	A-50
52	B-52
AN	AN-26B AN-30M
AP	AH-64D
B1	B-1B
BE	Tu-95 Tu-142M
BF	Tu-22M3
BJ	Tu-160
E2	E-2D
E 3	E-3C
F4	F-4E
F5	F-5E
НХ	Ka-27
IL	IL-76MD IL-78M
КС	KC-135

KJ	KJ-2000
M2	Mirage 2000-C Mirage 2000-5
S3	S-3B
SH	SH-60B
ТО	Tornado
TR	C-130 C-17A
	AIR DEFENSE
2	S-75 TR SNR (SA-2) "Fan Song"
3	S-125 TR SNR-125 (SA- 3) "Low Blow"
6	Kub SA-6
7	HQ-7 TR
_ 8	OSA (SA-8)
10	S-300PS 30N6 TR (SA- 10)
11	Buk (SA-11)
12	S-300V
15	Tor 9A331 (SA-15)
19	Tunguska 2C6M (SA-19)
Α	Gepard M-163 Vulcan ZSU-23-4 Shilka
ВВ	S-300PS 64H6E SR (SA- 10/Big Bird)
BF	Rapier Blindfire TR
CS	S-300PS 5N66M SR (SA-10/Clam Shell)
DE	Sborka (Dog Ear)
FF	S-125 P-19 SR (SA- 3/Flat Face)
GR	Roland SR

НА	Hawk SR	
HK	Hawk TR	
HQ	HQ-7 SR	
PT	Patriot	
RO	Roland	
RP	Rapier SR	
S	1L13 55G6 EWR	
SD	Buk TR (SA-11/Snow Drift)	
SN	PRW-11 (Side Net)	
	MISSILES	
M	AIM-54 AIM-120 MICA-EM R-37 R-77 SD-10	
ATC		
	Airport ATC Radar	

- 2.11 ALE-39 COUNTERMEASURES DISPENSER
- 2.12 ALQ-100 / ALQ-126 DECM

AWG-9 RADAR

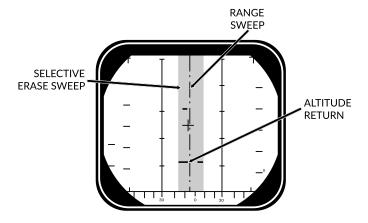
MAIN MODES - OVERVIEW

	Pulse		Pulse Doppler			
	Pulse Search	P-STT	PD Search	RWS	TWS	PD-STT
Range	60 nm	50 nm	110 nm	90 nm	90 nm	90 nm
AIM-7	BRSIT	CW	BRS	SIT	-	PD
AIM-54	BRSIT	ACT	BRS	SIT	Multi TGT	PD/ACT

MAIN MODES

• Pulse	Basic Pulse w/o doppler filtering
	Cannot be notchedGround ClutterRudimentary Ground mapping
	Pulse Sub-Modes
	Pulse SearchPulse-STT
 Pulse Doppler 	Doppler filter -> no ground returns
	 Susceptible to notching No ground clutter Greater range Advanced sub modes AIM-54 Guidance
	Pulse Doppler Sub-Modes
	PD SearchRWSTWSPD-STT

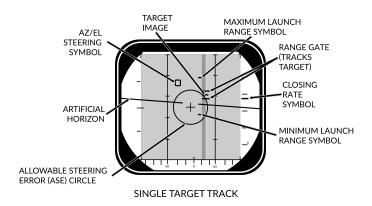
PULSE MODE - PULSE SEARCH 3.3



SEARCH (±10° SCAN)

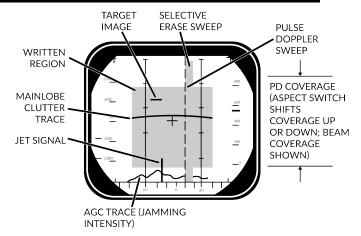
Pulse Search	Basic Mode - AWG-9 does not use pulse doppler filtering • Advantages
	All aspect target detectionCannot be notchedRudimentary ground mapping
	Disadvantages
	Cannot discern ground returns and targetsLower range
• DDD	Range/Azimuth
	 Visual representation of radar and erase sweeps
• TID	No Information from PulseCannot guide AIM-54

3.4 PULSE MODE - PSTT



Pulse STT	Lock Target w/o doppler filtering • Advantages
	 Cannot be notched
	 Disadvantages
	 Susceptible to ground clutter
 Lock Target 	 Conditions
	Pulse Search Mode selectedRDR HCU Mode selected
	Lock Target
	(a) Hold HCU Half-action(b) Slew to desired Target(c) HCU Full-Action to lock
	Unlock Target
	(d) HCU Half-action
• DDD	 Track Indications
	 ANT TRK light RDROT light Tracking gates Closure rate Attack Symbology

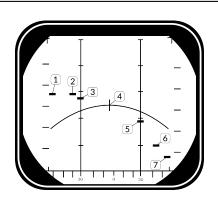
3.5 PULSE DOPPLER MODE - PULSE DOPPLER SEARCH



SEARCH (±40° SCAN)

 Pulse Doppler Search 	"Early Warning" Mode - Longest Range, cannot display rangeAdvantages
	Longest RangeDoppler Filtering"Look Down Shoot Down"
	 Disadvantages
	Can be notchedNo range information
• DDD	 Closure Rate/Azimuth Visual representation of radar and erase sweeps
 Doppler Filters 	Main Lobe Clutter (MLC) Filter
	Own GS +/- 133 knotsRemoves main ground returnSource of notching
	Zero Doppler Filter
	 Negative own GS +/- 100 knots Removes Radar reflection from ground directly beneath own AC

MLC Switch	 IN: Enables MLC filter AUTO: Enables MLC filter if look-up angle less than 3 deg OUT: Disables MLC filter
• Vc Switch	Changes closure rate DDD scale • X-4: -800 to 4000 knots • NORM: -200 to 1000 knots • VID: -50 to 250 knots
ASPECT Switch	 Changes closure rate processing scale NOSE: -600 to 1800 knots BEAM: -1200 to 1200 knots TAIL: -1800 to 600 knots



	Look Angle	Line of Sight Rate	Target Heading
1	60 deg	1490	180 deg
2	45 deg	1500	120 deg
3	30 deg	1428	100 deg
4	0 deg	1200	90 deg
5	30 deg	672	80 deg
6	45 deg	210	60 deg
7	60 deg	-300	0 deg

3.6 PULSE DOPPLER MODE - RWS

 Range While Search 	FM Ranging, used for getting good A/A picture before selecting TWS • FM Ranging
	 Pulse Doppler with ranging TID shows momentary tracks with ranges Processing reduces max range
	Advantages
	Long RangeDoppler Filtering"Look Down Shoot Down"Signal Processing
	 Disadvantages
	 Can be notched
• DDD	 Closure Rate/Azimuth Visual representation of radar and erase sweeps
• TID	 Momentary Tracks Max concurrent tracks: 48 Cannot lock targets from TID
 Filtering 	Same as Pulse Doppler Search

3.7 PULSE DOPPLER MODE - TWS

Track While Scan	Builds Track Files, high situational awareness, multi-target AIM-54 launch • Track Files
	 AWG-9 builds Trackfiles for contacts Can launch multiple AIM-54 Processing reduces max range Can lock targets from TID
	FM Ranging
	 Pulse Doppler with ranging TID shows momentary tracks with ranges Processing reduces max range
	 Advantages
	Doppler FilteringMulti-Target AIM-54
	 Disadvantages
	Lowest RangeCan be notched
• DDD	 Closure Rate/Azimuth Visual representation of radar and erase sweeps
• TID	TracksfilesMax concurrent tracks: 24Max displayed tracks: 18
• Filtering	Same as Pulse Doppler Search
Scan Volume	Trackfiles require update every 2.5 s -> • 20 deg 4 bar (if selected) • 40 deg 2 bar (else)
• TID Mode Selector	 GND STAB: Ground Stabilized, True North is up on TID A/C STAB: Aircraft Stabilized ATTAK: same as A/C STAB with superimposed attack steering symbology TV: Displays TCS on TID, dispays LANTIRN on TID if equipped

Selector
Buttons

RID DISABLE: Not simulated

- ALT NUM: Enables display of track altitudes on left side of track symbols
- SYM ELEM: Enables display of all supplementary symbology of tracks and waypoints
- DATA LINK: Enables display of D/L contacts
- JAM STROBE: Enables display of jam strobes
- NON-ATTK: enables/disables display of targets not possible to engage (friendlies)
- LAUNCH ZONE: Enables display of weapon launch zones
- VEL VECTOR: Enables display of velocity vectors

• TRACK HOLD & CLSN Steering Buttons

TRACK HOLD

- Normally: Tracks maintained for 14 s after last observation
- Track Hold: maintained for 2 min after last observation

CLSN Button

- begins collision steering to currently tracked target
- enables Steering Centroid if in TWS
- LD CLSN presents azimuth steering only
- CLSN presents both azimuth and elevation steering

TWS AUTO / MAN

- TWS MAN: Manual azimuth/elevation control, target designation by RIO
- TWS AUTO: Automatic prioritization of targets and azimuth elevation control

3.8 PULSE DOPPLER MODE - TWS MAN

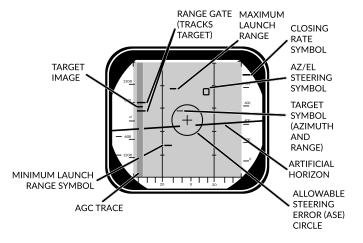
TWS MAN	Target Selection: Manual
	Scan Azimuth/Elevation: Manual
 Target Selection 	 Conditions
	 TWS MAN Radar Mode selected
	 TID CURSOR TID Mode selected
	Hook Target
	(a) Hold HCU Half-Action
	(b) Slew TID Cursor over desired Tgt
	(c) HCU Full-Action to select Tgt
	TID Symbology
	- Range (RA)
	Bearing (BR)
	Altitude (AL)
	– Magnetic course (MC)
	Lock Target
	(d) Press PD STT or Pulse STT buttons
	Deselect Target
	(e) press HCU Half-Action
AIM-54 Launch	Automatically selects TWS AUTO
	 Prevents selection of TWS MAN

3.9 PULSE DOPPLER MODE - TWS AUTO

TWS AUTO	 Target Selection: prioritizes contacts based off range, aspect, closure Scan Azimuth/Elevation: Geometric center of targets in scan volume
 Centroid / Steer- 	Steering Centroid
ing Cues	 facilitates steering cues HUD, VDI, TID, DDD Appears as X on TID Takes Gimbal limits into account Weights individual Tracks based on parameters
	 Illumination Centroid
	 Not Visible Controls azimuth and elevation of scan pattern Takes scan volume into account
 Pilot Steering 	 Conditions
Cues	A-A HUD Mode selectedMaster Arm ON (UP)AIM-54 or AIM-7 selectedTWS-AUTO selected

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3.10 PULSE DOPPLER MODE - PDSTT



SINGLE TARGET TRACK

 Pulse Doppler 	Lock Target with doppler filtering			
STT	 Advantages 			
	 Ground Clutter filtering 			
	 Disadvantages 			
	 Susceptible to notching 			
Lock Target	Conditions			
	 Pulse Doppler Mode selected (PD 			
	Search, RWS, TWS)			
	 RDR HCU Mode selected 			
	 Lock Target 			
	(a) Hold HCU Half-action			
	(b) Slew to desired Target			
	(c) HCU Full-Action to lock			
	Unlock Target			
	(d) HCU Half-action			
DDD	Track Indications			
	ANT TRK light			
	RDROT light			
	Tracking gates			
	 Closure rate 			
	 Attack Symbology 			

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3.11 ACM MODES - OVERVIEW

	PLM	VSL	PAL	MRL
Range	5 nm	5 nm	15 nm	5 nm
Description	Boresight	Vertical	Horizontal	RIO
Weapons		Gun +	- All Missiles	

• PLM	Pilot Lockon Mode Highest Priority ACM Search Pattern - Small Boresight - Range: 5 nm
• VSL	 Vertical Scan Lockon HI Search Pattern Width: 5 deg Vertical: +15 to +55 deg Range: 5 nm
	 LO Search Pattern Width: 5 deg Vertical: -15 to +25 deg Range: 5 nm RIO/PILOT Controlled
• PAL	Pilot Automatic Lockon Search Pattern Width: +/- 20 deg Vertical: 8-bar Range: 15 nm
• MRL	Manual Rapid Lockon RIO Controlled Search Pattern HCU Controlled Range: 5 nm

3.12 TID SYMBOLOGY

GENERAL		
Center Dot	•	Basic Component of Symbols Marks coordinates of sym-
Own AC		Symbol representing own aircraft
		 Ground Stabilized: Moves Aircraft Stabilized: Stationary Outside TID: line drawn from TID center towards symbol
TID Cursor		Hook Cursor
		 Controlled by HCU in TID mode
		Half-Action
		Enables display of symbolEnables HCU stick to move cursor
		• Full-Action
		Hooks closest symbolIf no symbol near, cursor dropped at location
TWS Steering Cen- troid	X	Steering centroid of TWS tracks
		 Selected by WCS for weapons engagement
ONBOARD SENS	ORS	Symbol Above Dot
Unknown	•	 Unknown Sensor Track All Returns in RWS
Hostile	•	Sensor Track designated Hos- tile by RIO
Friend	•	 Sensor Track designated Friendly by RIO
Angle-Tracked Radar		Radar Angle Tracking
Target		 Jamming Target

Angle-Tracked Radar Target with Altitude Difference Ranging		 Radar Angle Tracking Jamming Target Alt. diff. ranging
TCS-Angle Tracked Target	•>	TCS Angle Tracking
TCS-Angle Tracked Target with Altitude Difference Ranging		TCS Angle Tracking Alt. diff. ranging
D/L TARGET	S	Symbol Below Dot
Unknown		D/L Track designated Un- known by Source
Hostile	•	D/L Track designated Hostile by Source
Friendly		D/L Track designated Friendly by Source
MANUAL REF PO	DINTS	
Home base		 Waypoint Representing Home Base Carrier Airfield
Waypoint	••	 Nav Waypoint Supplanted by Number 1, 2, or 3
Defended Point		Waypoint to Defend
Fixed Point	X	Generic Waypoint
Hostile Area		Waypoint Indicating Hostile Area
Surface Target		Waypoint Indicating Surface Target
IP		Initial Point
		 Waypoint for A/G engage- ment
D/L REF POIN	TS	
Home Base		 D/L Waypoint Representing Home Base

AWG-9 RADAR REV: 2021082 Waypoint • D/L Generic Waypoint Data Link Fixed • D/L Waypoint Representing **Point Fixed Point** • D/L Waypoint Representing a Surface Target **Surface Target** POS SYMB MODIFIERS Additional Symbology on TWS **Mandatory Attack Track** - Horizontal bar through center dot Selected by RIO - Only 1 target can be designated - Guaranteed WCS priority number **Data Link Destroy** Additional Symbology on D/L **Track** - Horizontal bar through center dot Selected by Source - No effect on WCS prioritization **Do Not Attack** Additional Symbology on TWS or D/L Track Vertical bar through center dot If Set by RIO - Removes WCS prioritization **Multiple Targets** Additional Symbology on TWS or D/L Track Horizontal bar on left side of symbol • Indicates Multiple Targets

Data Link Challenge		 Additional Symbology on D/L Track
		 Small V with center at center dot
		 Command to Visually Identify
Track Extrapolated	\\ \hat{\chi}\	Additional Symbology on TWS or D/L Track
		 Small X with center at center dot
		No Update within 8 seconds
		 Track deleted after 14 seconds
		 Or after 2 min if track hold
Altitude Numerics	4/•	 Altitude to Nearest Ten Thousand
		- example: 35000-45000
Firing Order Numer-	/	 Indicates AIM-54 Prioritization
ics		Numbers 1-6Only in TWS
Time-to-Impact (TTI)	 ∕•\ 6	After AIM-54 Launch
		 Prioritization replaced with estimated TTI
		Flashes after Pitbull
Velocity Vector		 Additional Symbology from center Dot
		Direction represents track heading
		Length represents speedVaries with Mode
		 Ground Stabilized: true heading and ground speed Aircraft Stabilized: relative heading and velocity

Launch Zone Vectors		Additional Symbology for AIM-54 Selected manually by RIO Or 60 seconds from max launch TUMR Time-Until-Minimum-Range Max: 180 seconds, 1.5 inches TUOR Time-Until-Optimal-Range Start of bar is 8 seconds from optimum TUIR
Jamming Strobe		 Time-Until-In-Range Line from own AC towards Jammer
Radar Antenna Scan Pattern Azimuth Limits		Limits of Current Scan Azimuth Single Line in STT
Data Link Jamming Strobe		 Line from D/L point towards Jammer
Data Link Pointer	$\overline{\odot}$	 Additional Symbology on D/L Track — Circle — Indicates operator concern
Data Link Priority Kill		 Additional Symbology on D/L Track Square Indicates target must be destroyed No effect on WCS prioritization

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ATTACK DISPLAY SYMBOLOGY

Artificial Horizon		Represents Pitch and Roll
Steering Guidance Symbol		Represents Steering Error Should be placed as near as possible to center of ASE circle
Allowable Steering Error Circle		 Indicates Allowable Steering Error for Missile Launch Size Varies with Geometry, Mode, Missile
Breakaway Indica- tion	X	Appears when Target Range Less than Minimum for Se- lected Weapon

OVERVIEW

5 LANTIRN

5.1 **OVERVIEW**

• LANTIRN	Low Altitude Navigation and Targeting Infra-Red for Night Only Targeting Pod – Nav pod was deleted Incomplete Integration – Own control panel, supplants TCS feed
Master Modes	 A/G – Allows bomb release guidance A/A – Optimized for air targets
FOV Levels Overview	 Wide FOV – 5.9 deg Slew – 8.5 deg/s Narrow
	FOV – 1.7 degSlew – 1.8 deg/s
	Expanded
	− FOV − 0.8 deg
	− Slew − 0.7 deg/s
	 Digital Zoom – Degraded quality

5.2 OVERVIEW - STARTUP

1.	Power Switch	POD
2.	Pod Startup Sequence	8 min startup sequenceMODE Switch shows STBY when complete
3.	MODE Switch	Press
4.	Initialization	30 sec initialization
	Sequence	 MODE Switch shows OPER when ready
5.	VIDEO Switch	FLIR
6.	TID MODE	TV

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5.3 OVERVIEW - POINTING MODES

Sensor Modes	Contrast Lock
Overview	Area TrackPoint Track
	Q Designation
	Directional Q – QSNO / QADL / QHUDLocation Q – QWp / QDES
Directional Q	Do Not Allow Weapon GuidanceQSNO
	 Pod slaved to ground 15 nm in front along own aircraft heading
	• QADL
	Pod slaved to ADLIn A/A mode
	• QHUD
	Pod slaved to HUDIn A/G mode
Location Q	Allow Weapon GuidanceQWp
	Pod slaved to WCS waypointCycled with QWp+ / QWp-
	• QDES
	 Designate targets for engagement LANTIRN Trigger Second Detent to designate Coordinates can be manually added to WCS for navigation

5.4 OVERVIEW - LASING/DESIGNATION

 A/G Designation 	Trigger Second Detent (a) DesignateTrigger Full-Action
	Laser Fires
	 Slant Range calculated
	Time-to-Go calculated
Steering Cues	 Automatically activated when QDES se- lected/designated
	 QDES remains even if new Q selected
	 Cues still point towards QDES even if pod at
	another point
 Manual Lase 	(a) LaseTrigger Half-Action Hold
Latched Lase	Effect – Lases for 60 sec
	(a) Activate Latch Lase Button Press
	(b) ExtendLatch Lase Button Press
	(c) Deactivate Trigger Half-Action
Auto Lase	Effect – Fires from -10 to +4 sec TIMP
	(a) Laser Mode Slider AFT Short
	(b) Cycle A/MRight 4-Way Depress
 Laser Notes 	Always at current Pod location
	Can point to different location than QDES

5.5 CONTROLS - PANEL

Power Switch	 OFF – Disables power to system IMU – Only powers LANTIRN IMU Not Simulated in DCS
	POD – Powers whole system
 MODE Switch 	• STBY – Standby
	OPER – Operational
 LASER Switch 	ARM – Arms laser
	 Indicated by LASER ARMED light
	SAFE – Inhibits laser use
 VIDEO Switch 	FLIR – Displays LANTIRN FLIR on TID
	• TCS – Displays TCS video on TID
• Indicator Lights	Indicate Error States
IBIT Button	Initiates Build-In-Test

5.6 CONTROLS - STICK

Master Mode	 A/G Mode – Side 2-Way FWD A/A Mode – Side 2-Way AFT
• Slew	Center Slew Hat
• WHOT/BHOT	Center Slew Hat Depress
• Contrast Track	 Point Track – Left 4-Way Up Area Track – Left 4-Way Down
Q Select	 QADL/QHUD – Right 4-Way Up QDES – Right 4-Way Right QSNO – Right 4-Way Down
 Declutter 	Right 4-Way Depress
• Zoom Level	FOV Button
Cycle Gain Control Mode	Slider FWD short
Manual Gain Control	(a) SliderFWD long (b) GainRight 4-Way Up/Down LevelRight 4-Way Left/Right

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•	Laser Code	(a) Slider AFT short (b) Select Digit Right 4-Way Left/Right (c) Change Digit Right 4-Way Up/Down
•	Focus Control	(a) Slider AFT hold (b) Right 4-Way Up/Down
•	Manual Lase	Trigger Half-Action
•	Latched Laser	Latched Laser Fire Button
•	Designate QDES	Trigger Full-Action

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5.7 DISPLAY

Top Left	Own Aircraft Datablock
	Lat – deg:min.dec
	Long – deg:min.dec
	ALT – Altitude (ft)
	 KGS – Knots Ground Speed
	DIVE – Dive Angle (deg)
Mid Left	Sensor Mode – WHOT / BHOT
	 Gain Control – Auto / Manual
Bottom Left	Pod Info Datablock
	- SRA - Slant Range
	AZ – Pod LoS Azimuth L/R
	EL – Pod LoS Elevation
	- Time – UTC Time
	- IBIT - Codes
Bottom Center	Master Mode – A/A / A/G
	 Track Mode – AREA / POINT / Q
	Current Weapon
	Laser Code
	• L
	 Steady – Laser Armed
	 Flashing – Laser Firing
Bottom Right	
	Q Datablock
	Q DatablockTTG – Time-To-Go
	- TTG - Time-To-Go
	TTG – Time-To-GoB/R – Bearing and Range
	 TTG – Time-To-Go B/R – Bearing and Range ELEV – Elevation (ft) of Q
Mid Center	 TTG – Time-To-Go B/R – Bearing and Range ELEV – Elevation (ft) of Q Lat – deg:min:dec
Mid Center	 TTG – Time-To-Go B/R – Bearing and Range ELEV – Elevation (ft) of Q Lat – deg:min:dec Long – deg:min:dec
Mid Center	 TTG – Time-To-Go B/R – Bearing and Range ELEV – Elevation (ft) of Q Lat – deg:min:dec Long – deg:min:dec Crosshair
Mid Center	 TTG – Time-To-Go B/R – Bearing and Range ELEV – Elevation (ft) of Q Lat – deg:min:dec Long – deg:min:dec Crosshair Bounding Box – Indicates currently
Mid Center	 TTG – Time-To-Go B/R – Bearing and Range ELEV – Elevation (ft) of Q Lat – deg:min:dec Long – deg:min:dec Crosshair Bounding Box – Indicates currently tracked target in point mode
Mid Center	- TTG - Time-To-Go - B/R - Bearing and Range - ELEV - Elevation (ft) of Q - Lat - deg:min:dec - Long - deg:min:dec • Crosshair - Bounding Box - Indicates currently tracked target in point mode - Zoom Boxes - Indicates next zoom lev-

LANTIRN	F-14A/B REV: 20210823
 Mid Right 	Bomb Rlease Cue
	 Only shown if current Q is QDES, with valid weapon selected TREL – Time to release TIMP – Time to Impact (after release)
Top Center	Steering Guidance to Q
	 Relative bearing L/R to commanded heading

6 A/G WEAPONS

6.1 A/G WEAPON SETTINGS - OVERVIEW

• WPN TYPE	Selects Weapon Type
	 Configures WCS for selected weapon Refer to Kneeboard for list of mounted weapons Mk-81 / 82 / 83 have both L and H option referring to high and low drag
DLVY MODE	 STP-SGL – Single weapon per press STP-PRS Single pair per press RPL-SGL – QTY of weapons per press RPL-PRS – QTY of pairs per press
DLVY OPTNS	 INTERVAL – Interval in ms QTY – Number of stores to be released
MECH FUZE	 NOSE – Arms nose fuze SAFE – Inhibits arming of fuzes NOSE/TAIL – Arms both fuzes
• ELEC FUZE	 SAFE – Inhibits electrical bomb fuzing VT – Sets air-burst mode at preset burst height for compatible stores INST – Sets instantaneous burst mode DLY 1 – Sets preset time delay 1 DLY 2 – Sets preset time delay 2
• STA SEL	 Selects Stations for Employment/Jettison Set to SEL to activate a pylon Stations 1 & 8 should be set to B for selection Station 1 & 8 SW was used for Sidewinder jettison, is now inoperable
• TANK JETT	Allows Drop Tank Jettison
SEL JETT	 JETT – Selective jettison SAFE – Inhibits jettison AUX – Backup mode
• JETT OPTIONS	 MER TER – Jettisons ejector racks WPNS – Jettisons weapons only

ATTK MODE CCMPTR TGT Computer Target – Similar to CCRP CMPTR IP Computer initial point - Extended CMPTR TGT mode using known IP - For use when target hard to spot visually but close to landmark CMPTR PLT Computer Pilot – similar to CCIP MAN - Manual - HUD displays pipper Backup mode D/L BOMB Data-Link Bomb – Automatic mode steered by D/L cues - Not Implemented in DCS SELECTIVE ORNANCE JETTISON 6.2 1. **Pilot Conditions** • MASTER ARMON 2. **RIO Conditions** Desired Stations Selected • JETT OPTIONS As Desired **Jettison** (a) SEL JETT Guard Flipped 3. (b) SEL JETT SwitchJETT M61 GUN 6.3 • MASTER ARM ON 1. **Pilot Conditions** WEAPON SELECTOR GUNS • Wing SweepBOMB 2. **Employment** (b) **Pipper**on target (c) TRIGGER FIRE **Note: TCS** • TCS slaved to radar impact point Rio can select NAR or WIDE

6.4 FFAR / ZUNI ROCKETS

1. RIO Conditions	WPN TYP Attack Mode Attack Mode Deliver Mode Mechanical Fuze Electronic Fuze Delivery Options Stations Attack Attack Pilot Attack RPL-SGL NOSE INST As Desired
2. Pilot Conditions	 MASTER ARM ON HUD A/G WEAPON SELECTOR OFF Stations verify selected Wing Sweep BOMB
3. Employment	(a) Dive 20-30 deg (b) Pipper on target (c) TRIGGER FIRE

6.5 UNGUIDED BOMB - CCIP

1.	RIO Conditions	WPN TYP MK-8X Attack Mode Pilot Attack Deliver Mode STP-PRS Mechanical Fuze NOSE Electronic Fuze INST Delivery Options As Desired Stations Armed
2.	Pilot Conditions	 MASTER ARM
3.	Employment	(a) Dive 40 deg (b) Pipper on target (c) STORE RELEASE Press and Hold

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6.6 UNGUIDED BOMB - CCRP

1. RIO Conditions	WPN TYP MK-8X Attack Mode Target Attack Deliver Mode STP-PRS Mechanical Fuze NOSE Electronic Fuze INST Delivery Options As Desired Stations Armed
2. Pilot Conditions	 MASTER ARM ON HUD A/G WEAPON SELECTOR OFF Stations verify selected Wing Sweep BOMB
3. Designation	(a) Slew Diamond VSL HI/LO (b) Designate
4. Employment	(a) Flight Path
	(c) STORE RELEASE Press and Hold

6.7 LASER GUIDED BOMB

1. LANTIRN PREP	 (a) Target Pod Power
	 (b) Laser Code
	(c) LANTIRN ModeOPERATE
	 STANDBY caution will flash for 30 s Then switches to OPER
	(d) VIDEO Switch
2. RIO Conditions	WPN TYP GBU-XX Attack Mode
3. Pilot Conditions	• MASTER ARM ON • HUD A/G • WEAPON SELECTOR OFF • VDI Mode TV • Stations verify selected • Wing Sweep BOMB
4. Slew LANTIRN	Refer to LANTIRN Control Section Slave to WYPT Left-4-Way RIGHT QSNO (Snowplow) S4 HAT Down Toggle FOV LANTIRN Toggle FOV Slew LANTIRN Stick Area Track Left-4-Way UP Point Track Left-4-Way Down Undesignate LANTIRN Undesignate

4. Designate	Refer to LANTIRN Designation Section (a) DesignateTrigger Full-Action
	 Slant Range calculated
	Time-to-Go calculated
	Once Time-to-Realease (TREL) is 0
	(b) Auto-Lase If selected: lases 10s to impact
	(c) Manual Lase Trigger Full-Action
	(d) While LasingL blinks
5. Employment	Once Time-to-Realease (TREL) is 0
	(a) STORE RELEASE Press and Hold
	(b) Flight Path Gentle right-hand turn
	(to prevent masking)

6.8 TALD DECOYS

1.	RIO Conditions	WPN TYPTALD Deliver ModeSTP-SGL Delivery OptionsAs Desired StationsArmed
2.	Pilot Conditions	• MASTER ARM ON • HUD
3.	Employment	(a) Flight Path High / Fast (b) RWR Monitor to locate emitters (c) STORE RELEASE Press and Hold

A/A WEAPONS

M61 GUN - OVERVIEW

• GUN RATE	Cycles Gun Rate
Button	– HIGH – 6000 rpm
	– LOW – 4000 rpm
A/A Gun Modes	• RTGS
	 Real-Time Gunsight Mode Selected automatically with guns If No WCS Data Available displays bullet location at 2000 ft with diamond and 1000 ft with pipper If WCS Data Available pipper displays bullet location at targets current range out to 4000 ft
	MANUAL
	Fixed manual pipperAdjust with GUN ELEV knobPress CAGE/SEAM to select
• CAGE/SEAM Button	Cycles RTGS / MANUAL Gun Modes
ROUNDS Knob	Allows selection of remaining gun rounds

M61 GUN - MANUAL

1.	Pilot Conditions	• MASTER ARM	ON
		• HUD	A/A
		• Gun Rate	HIGH
		Gunsight Lead	as required
		WEAPON SELECTOR	GUNS
2.	Employment	(a) Gun Mode	MANUAL
		(b) Pipper	on target
		(c) Trigger	FIRE

M61 GUN - RTGS / NO RADAR

1.	Pilot Conditions	• MASTER ARM	ON
		• HUD	A / A
		• Gun Rate	HIGH
		WEAPON SELECTOR	GUNS
2.	Employment	(a) Gun Mode	RTGS
		(b) Pipper	on target
		(c) Trigger	FIRE

M61 GUN - RTGS / RADAR

1.	Pilot Conditions	• MASTER ARM	ON
		• HUD	A/A
		• Gun Rate	HIGH
		WEAPON SELECTOR	GUNS
2.	Employment	(a) Gun Mode	RTGS
		(b) Radar	STT
		(c) Pipper	on target
		(d) Trigger	FIRE

7.5 AIM-9 SIDEWINDER - OVERVIEW

Missile Preparation	MSL PREP
	 AIM-9 seeker must be cooled
	 Either press SW COOL button
	Or activation of ACM
 Seeker Head 	• SEAM
Modes	 Sidewinder Expanded Acquisition Mode
	 Double-D search pattern invisible to pilot
	- 4.5 sec search time
	 Allows AIM-9 to be uncaged and track target
	 40 deg track limit
	 Allows WCS to slave AIM-9 to radar
	track
	Boresight
	 AIM-9 locked to ADL
	2.5 deg FOV
	 Selected if MODE/STP set to BRSIT
	 And ACM not active
MODE/STP	• NORM
Switch	 Allows SEAM seeker mode
	BRSIT
	 Forces Boresight seeker mode
	 Overridden if ACM active
CAGE/SEAM Button	Uncages Seeker
	 Starts 4.5 second search
	If no IR source found cages again
	Slaves Seeker
	- If radar STT locked
	- II Iauai STT IUUNGU

7.6 AIM-9 SIDEWINDER - SILENT

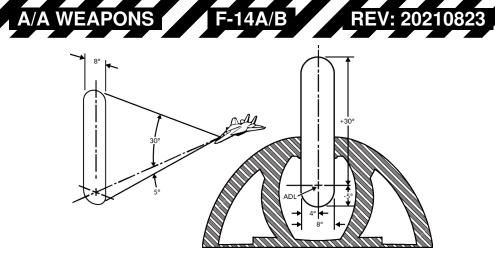
1.	Pilot Conditions	MASTER ARM	ON
		• HUD	
		• SW COOL	ON
		• MODE/STP	As Desired
		WEAPON SELECTOR	SW
2.	Employment	(a) CAGE/SEAM	Uncage Seeker
		(b) IR-Lock	Good Tone
		(c) Trigger	FIRE

7.7 AIM-9 SIDEWINDER - RADAR

1.	Pilot Conditions	MASTER ARMON
		• HUD
		• SW COOLON
		• MODE/STPNORM
		WEAPON SELECTORSW
2.	Employment	(a) Radar STT
		(b) CAGE/SEAM Slave Seeker
		(c) IR-LOCKGood Tone
		(d) Steering center T-shaped cue with ASE
		(e) TriggerFIRE

7.8 AIM-7 SPARROW - OVERVIEW

• Missile	MSL PREP
Preparation	 AIM-7 must be tuned to AWG-9
	 Either press MSL PREP button
	Or activation of ACM
 Launch Modes 	 Normal
	 Standard operation, STT target designated before launch AIM-7 uses SARH all the way to target WCS can use CS or PD for guidance set with MSL OPTIONS Switch
	 Boresight
	 Uses CS flood antenna of AWG-9 Missile will track strongest return in Flood area Automatically activated if STT broken
	 Selected if MODE/STP set to BRSIT Or if no STT available
	- Shown Below
MSL SPD GATE	NOSE QTR
Switch	 Standard setting in DCS
	All Others
	Not simulated
MSL OPTIONS	NORM
Switch	WCS uses dedicated CW antenna for AIM-7 guidance
	• SP PD
	 WCS uses PD from main flood antenna for AIM-7F/M guidance
MODE/STP	• NORM
Switch	 Sets normal launch mode logic
	• BRSIT
	Forces Boresight launch mode



AIM-7 SPARROW - STT 7.9

1. Pilot Conditions	 MASTER ARM ON HUD A/A MSL PREP ON MODE/STP NORM WEAPON SELECTOR SP
2. RIO Conditions	MSL SPD GATE NOSE QTR MSL OPTIONS As Desired
3. Employment	(a) RadarSTT (b) Steering
	Target < 20 deg from ADLASE center T-shaped cue within
	(c) Trigger
	(d) Radar Maintain Lock (until impact)

7.10 AIM-54 PHOENIX - OVERVIEW

Missile	Weapon Cooling
Preparation	 AIM-54 requires liquid cooling
	 RIO enabled LIQUID COOLING switch
	MSL PREP
	 AIM-54 must be tuned to AWG-9
	 Either press MSL PREP button
	- Or activation of ACM
Launch Modes	PDSTT SARH
	- AIM-54 uses SARH all the way to targe
	Faster update rate than TWSSlightly increased effective range as
	compared to a TWS launch
	• TWS SARH/ARH
	 Allows 6 AIM-54 launches at 6 target
	Missile is initially SARH guided
	 When within AIM-54 seeker range AW
	9 sends activation command
	 Not Fire and Forget: Requires automatic activation command
	ACM Active
	Activated when BRSIT selected
	Or when ACM active with no radar trace.
	 Missile commanded active before
	launch
MSL SPD GATE	NOSE QTR
Switch	 Standard setting in DCS
	All Others
	 Not simulated
MSL OPTIONS	• NORM

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- WCS immediately sends AIM-54 activa-

Reverts to SARH if no target detectedMust be selected before launch

tion command on launch

A/	A WEAPONS	F-14A/B REV: 20210823
•	TGTS Switch	 SMALL – 6nm activation range NORM – 10nm activation range LARGE – 13nm activation range
•	Missile Next Launch Button	 Selects Hooked Track as Next Target for AIM-54 TWS Engagement
MODE/STP Switch		NORM Normal operation
		BRSIT Commanded active before launch Missile follows ADL and locks strongest return
TWS Symbology	TWS Symbology	Refer to TID Symbology Section • Pre-Launch
		 Prioritization numbers assigned to tracks automatically or manually Blinking indicates optimal launch parameters
	Post-Launch	
		 Target prioritization number replaced with TTI Other prioritization numbers collapsed by one Tracks under missile attack brightened

Launch To Eject

(LTE) Time

- TTI blinks when missile active

• Normal Operation – 3-4 seconds

• When in ACM – 1 second

7.11 AIM-54 PHOENIX - PD-STT

1. Pilot Conditions	 MASTER ARM
2. RIO Conditions	WEAPON SELECTORPH LIQUID COOLINGON (FWD) MSL SPD GATENOSE QTR MSL OPTIONSAs Desired TGTS SwitchAs Desired
3. Employment	(a) RadarSTT
	Target < 20 deg from ADLASE center T-shaped cue within
	(c) TriggerPress and Hold

7.12 AIM-54 PHOENIX - TWS / MULTI

1. Pilot Conditions	• MASTER ARMON
	• HUD
	• MSL PREPON
	• MODE/STPNORM
	WEAPON SELECTORPH
2. RIO Conditions	• LIQUID COOLING ON (FWD)
	MSL SPD GATE NOSE QTR
	MSL OPTIONS As Desired
	TGTS Switch As Desired
	WCS Mode TWS MAN/AUTO
4. Employment	(a) Radar TWS
	(b) TriggerPress and Hold
	(until weapon release)
	(c) Repeatfor remaining targets
	(d) RadarMaintain Track
	(until active)

