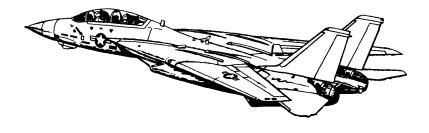
Pocket Checklist

F-14A/B AIRCRAFT

REV: 20220126



Procedures

Systems

AWG-9 Radar

TCS LANTIRN

A/G Weapons

A/A Weapons



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1 PROCEDURES

1.1 PILOT - PRE-START

1.	Parking Brake	ENGAGED
2.	Ground Power	connected
3.	Compressed Air	connected
4.	ICS	HOT MIC
5.	TO RIO	"Begin Start-Up"
6.	ICS	Comm Check
7.	MASTER TEST Selector	(a) LTS • Warning Lights
		• FUEL QTY
8.	Ejection Seat	Armed
9.	RIO	Canopy Closed
10.	Oxygen	ON (FWD)
11	Emergency Wing Sweep	OVERSWEEP

PILOT - ENGINE START

1.	AIR SOURCE	OFF
2.	Hydraulics	(a) HYD TRANSFER PUMP SHUTOFF (b) Emerg. HydAUTO (LOW)
3.	L&R MASTER GEN	NORM
4.	RIO	"Ready to Start"
5.	Right Engine Start-Up	(a) Engine Crank R (b) R Eng N2 20% (c) R Throttle IDLE (d) TIT < 890 C during start
6.	Stabilized Parameters	• RPM
7.	Left Engine Start-Up	(a) Engine Crank L (b) L Eng N2 20% (c) LThrottle IDLE (d) TIT < 890 C during start
8.	Stabilized Parameters	• RPM
9.	HYD TRANSFER PUMP	NORM
10.	HYD PRESSURE	3000 psi
11.	AIR SOURCE	BOTH ENG
12.	Ground Power	disconnected
13.	Compressed Air	disconnected

1.3 PILOT - POST-START

	TORIO	#D # E .
1.	TO RIO	"Both Engines Running"
2.	Displays Control Panel	• VDION
	ranei	• HUD
		• HDS MODE
		(monitor INS)
3.	RIO	Select Align Quality INS GO NOW: shortest but least precise alignment INS GO COARSE: does not meet Launch Criteria for AIM-7 / AIM-54 INS GO MIN WPN LAUNCH: allows AIM-7 /
		• INS GO FINE fine align (8 min)
4.	ACM Panel	GUN RATE
5.	Gun Rounds	Set
6.	ANTI-SKID SPOILER BK	OFF
7.	Emergency Wing Sweep	(a) Handle
8.	AFCS Panel - SAS STAB AUG	• PITCH ON • ROLL ON • YAW ON
9.	WING/EXT TRANS	AUTO
10.	UHF1 Function Selector	ВОТН
11.	TACAN Function Selector	T/R
12.	ARA-63 ICLS RECEIVER	ON

						_
PR	O	CE	D	UR	B	S

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13.	Radar Altimeter	(a) Control Knob one click CW to turn on
		(b) Display 6000 ft (warm up)
		(c) Display 0 ft (ready)
14.	Standby ADI	erect at least 2 min before T/O
15.	KY-28 Crypt. Key	Set (refer to GROUND SETTINGS kb)
16.	RIO	set D/L frequency
17.	Lights	As desired

1.4 RIO - PRE-START

1.	Oxygen	ON (FWD)
2.	PILOT	• Ground Powerconnected • Compressed Airconnected
3.	ICS	Comm Check
4.	Lights	As required
5.	LTS Test	Coordinate with Pilot
6.	Ejection Seats	ARMED
7.	Canopy	CLOSED
8.	TO PILOT	"Ready to Start"

1.5 RIO - POST-START - SHORE

1.	PILOT	• Enginesstarted
		• AIR SOURCEBOTH ENG
2.	INS STARTUP	(a) LIQUID COOLINGON (FWD)
		(b) WCS SwitchSTANDBY
		(c) IR/TV Power STBY/IR/TV
		(d) TID/DDD illuminated after 40 s
3.	Kneeboard	Retrieve Coordinates, Elevation, Magnetic Variation from GROUND SETTINGS Page
WA	RNING Input Coords	BEFORE selecting GND ALIGN if using ASH
4.	Start INS Align	(a) Nav Mode
		Category NAV MESSAGE OWN AC
		(c) Keyboard
		CLEAR, LAT, latitude, ENTER
		 LONG, longitude, ENTER
		• ALT, altitude, ENTER
		(d) CAP MESSAGEMAG HDG VAR
		(e) Keyboard HDG , mag var, ENTER
		(f) Align ProgressMonitor
5.	U/VHF Mode	T/R G

6.	Datalink	(a) Kneeboard TACTICAL DL (b) DL Power ON (FWD) (c) DL Mode TAC (AFT) (d) DL Freq. Set
7.	TACAN	T/R
8.	RWR Panel	(a) Display Type NORM (b) PWR ON (c) TEST SPL (d) MODE LMT
9.	DECM	STBY, then ACT
10.	IFF	(a) MASTER STBY (b) CODE as required
11.	Altimeter	Reset
12.	CAP	Enter Data (WP, FP, etc.)
13.	Displays	• DDD
14.	Hand Control Panel	Set
15.	AN/ALE-39	Set (as required) • AUTO (CHAFF)/MAN • MAN
16.	Flare Mode	PILOT
17.	Complete INS Align	• Duration Full Fine
		(a) Align Complete Caret → Diamond (b) NAV Mode
18.	Standby ADI	Erect at least 2 min before T/O
19.	TO PILOT	"Ready to Taxi"
Onc	e Airborne	
20.	IR/TV Power	ON
21.	WCS Switch	WCS XMT

1.6 RIO - POST-START - CARRIER

1.	PILOT	• Enginesstarted • AIR SOURCEBOTH ENG
2.	INS STARTUP	(a) LIQUID COOLING ON (FWD) (b) WCS Switch STANDBY (c) IR/TV Power STBY/IR/TV (d) TID/DDD illuminated after 40 s
3.	Datalink	(a) Kneeboard
4.	Start INS Align	(a) DL FREQ Set (b) DL Mode CAINS/WAYPT (c) Nav Mode CVA
5.	U/VHF Mode	T/R G
6.	TACAN	T/R
7.	RWR Panel	(a) Display Type NORM (b) PWR ON (c) TEST SPL (d) MODE LMT
8.	DECM	STBY, then ACT
9.	IFF	(a) MASTER
10.	Altimeter	Reset
11.	CAP	Enter Data (WP, FP, etc.)
12.	Displays	• DDD
13.	Hand Control Panel	Set
14.	AN/ALE-39	Set (as required) • AUTO (CHAFF)/MAN • MAN
15.	Flare Mode	PILOT
16.	Complete INS Align	 Duration Full Fine
		(b) NAV ModeINS NAV

PR	OCEDURES	F-14A/B REV:	20220126
17.	Datalink	(a) DL Mode	• •
18.	Standby ADI	Erect at least 2 min before T/O	
19.	TO PILOT	"Ready to Taxi"	
_			

		(b) DL Freq Set
18.	Standby ADI	Erect at least 2 min before T/O
19.	TO PILOT	"Ready to Taxi"
Once Airborne		
20.	IR/TV Power	ON
21.	WCS Switch	WCS XMT

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1.7 PRE-TAXI

1.	ANTI-SKID SPOILER BK	OFF
2.	HOOK BYPASS	As Required
3.	Nose Strut	RETRACTED
4.	HUD MODE	то
5.	Parking Brake	Released (IN)
6.	NWS	ENGAGED
7.	Path	verify clear

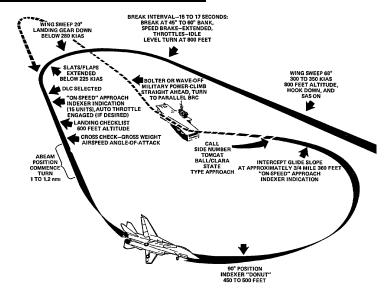
1.8 TAKEOFF - SHORE

	After Lining Up On Runway		
1.	Wing Sweep	(a) EM WING SWEEP FWD, then IN (b) MASTER RESET PRESS (c) Wings Verify thumb controller (d) WING SWEEP AUTO (e) Wings Verify at 20 deg	
2.	ANTI SKID SPOILER BK	BOTH (UP)	
3.	FLAPS	UP	
4.	Trim	0 deg	
5.	NWS	DISENGAGED	
6.	Takeoff	(a) Throttle MIL (90% RPM) (b) Stick Back at 130 KIAS (c) Rotation approx 140 KIAS (d) GEAR UP < 250 KIAS	

1.9 TAKEOFF - CARRIER

	Lineup	 Wait behind JBD until Catapult is clear Follow Taxi Directors Instructions to line up on Catapult
1.	Wing Sweep	(a) EMWING SWEEP FWD, then IN (b) MASTER RESET PRESS (c) Wings Verify thumb controller (d) WING SWEEP AUTO (e) Wings Verify at 20 deg
2.	FLAPS	DOWN
3.	Launch Bar Preparation	(a) Nose Strut
4.	Trim	2-3 deg nose up
5.	Speed Brakes	IN
6.	Final Checks	(a) Throttle
		(c) Eng. Inst
7.	Catapult Shot	(a) Salute CAT SHOT (b) Gear UP < 250 KIAS
8.	Clearing Turn	

1.10 LANDING - OVERHEAD PATTERN



1.	Initial Approach	• WING SWEEP68 deg
		• HOOK DOWN
		• SASON
		• HUDLDG
		• Airspeed300-350 KIAS
		• Altitude 800 ft
2.	Initial Break	• Break Interval15-17 s
		• BANK 45-60 deg
		SPEED BRAKE EXTEND
		• ThrottleIDLE
		• G 3-4 G
		• Altitude800 ft
3.	Break Turn	• Wing Sweep AUTO < 280 KIAS
		• Landing Gear DOWN < 280 KIAS
		• FLAPS DOWN < 225 KIAS
4.	Downwind	• DLCSelected once flaps out
		• AOA ON-SPEED
		 LANDING CHECKLIST
		Altitude descend to 600 ft

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5.	Final Turn	180 Deg Position • Abeam Pos	1-1.2 nmi
		• AOA	DONUT
		Altitude	400-500 ft
6.	Intercept Glides-	• Distance	3/4 Mile
	lope	Altitude	360 ft
		• AOA	ON-SPEED

1.11 LANDING - CHECKLIST

1.	Wing Sweep	20 deg AUTO
2.	Wheels	• Lights
3.	SAS	ON
4.	FLAPS	DOWN
5.	DLC	Checked
6.	Hook	HOOKDOWN Transition LightOUT
7.	Harness	Locked
8.	Speedbrakes	EXT
9.	Brakes	Check
10.	Fuel	Check

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1.12 AERIAL REFUELING

1.13 AIRSTART

• Spooldown	Before significant spooldown (a) Non-Running ENGIDLE or above
	If no relight occurs (b) Non-Running ENG OFF then IDLE If still no relight occurs (c) ENG MODE SEC (d) Non-Running ENG OFF then IDLE
 Cross-Bleed Restart 	With one ENG running, if Spooldown fails (a) Non-Running ENG OFF (b) FUEL SHUT OFF check (c) Running throttle 80%+ (d) BACK UP IGNITION ON (e) ENG CRANK non-running eng (f) Non-Running ENG IDLE If no start occurs
	(g) Non-Running ENG OFF then IDLE If still no start (h) ENG MODE SEC (i) Non-Running ENG OFF then IDLE
Windmill Restart	(a) Airspeed >450 kts (b) Throttle IDLE or above (c) BACK UP IGNITION ON If no relight occurs
	(d) Throttle OFF then IDLE If still no relight SEC (e) ENG MODE SEC (f) Throttle OFF then IDLE
Post Restart	(a) BACK UP IGNITION OFF (b) ENG MODE PRI

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2 SYSTEMS

2.1 AFCS - SAS

· SAS	Stability Augmentation System
	- Not Fly-by-Wire
	 Automatic control surface commands generated by analog computer to im- prove stability
· Controls	Three individual Switches
	- Pitch
	- Roll
	- Yaw
 Autopilot Emer- 	Paddle on Stick
gency Disengage	 Disengages Autopilot Modes
Paddle	 Deactivates Pitch, Roll SAS Channels

2.2 AFCS - AUTOPILOT

 Attitude Hold 	Basic Attitude Hold
	 Maintains existing pitch & roll Attitude can be changed with stick input If engaged outside limits will automatically move within range
	• Limits
	Pitch: 30 degRoll: 60 deg
	Engagement
	(a) SAS Switches ON (FWD) (b) Alt. Hold Mode OFF (c) VEC/PCD/ACL OFF (d) Heading Mode OFF
	(e) Autopilot Switch ENGAGE (FV

 Altitude Hold 	Barometric Altitude Hold
	 Maintains current barometric altitude
	• Limits
	 Vertical velocity: < 100 ft/s
	Engagement
	(a) SAS SwitchesON (FWD) (b) Autopilot Switch ENGAGE (FWD) (c) Alt. Hold ModeALT (FWD) (d) A/P REF Light Wait until appears (e) NWS ButtonPress
 Heading Hold 	Magnetic Heading Hold
	 Maintains current magneatic heading
	• Limits
	- Bank angle < 5 deg
	• Engagement
	(a) SAS SwitchesON (FWD) (b) Autopilot Switch ENGAGE (FWD) (c) Heading Mode
Ground Track	Autopilot follows ground track
	- Similar to heading hold
	Compensates for wind driftUses INS data instead of mag. bearing
	• Limits
	- Bank angle < 5 deg
	• Engagement
	(a) SAS SwitchesON (FWD) (b) Autopilot Switch ENGAGE (FWD) (c) Heading ModeGT (AFT) (d) A/P REF Light Wait until appears (e) NWS ButtonPress
· VEC/PCD	Vector / Precision Course Direction
	 Allows Link 4 controller to remotely direct the aircraft Not Modelled in DCS
• ACL	Automatic Carrier Landing
	- See relevant section
·	

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- Autopilot Emergency Disengage Paddle
- Paddle on Stick
 - Disengages Autopilot Modes
 - Deactivates Pitch, Roll SAS Channels

2.3 APC/AUTOTHROTTLE

· APC	Approach Power Compensator
	Automatic throttle controlMaintains ON SPEED AoA
 Conditions 	Engagement is inhibited / APC is disengaged if conditions not met • Throttles
· Engage	Throttle Mode AUTO (FWD)
· Disengage	Cage/Seam Button

2.4 ACLS

2.5 WING-SWEEP

· Overview	 In Flight Limited between 20 deg & 68 deg On Ground can Oversweep to 75 deg Hydromechanically Controlled
	 Automatically through CADC Manually with emergency wing-sweep handle
	15 deg/s at 1g loadingMechanically linked to ensure symmetry
CADC Modes	• AUTO
	 CADC controls wing position as function of current Mach via wing-sweep pro- gram
	• MAN
	 Pilot manually chooses desired wing sweep angle with thumb controller
	• BOMB
	- Sets wing sweep to 55 deg or further aft

Emergency Mode	 Emergency Wing-Sweep Handle Moved with wing sweep program by spider detent under normal operation Can be forced out of spider detent and moved manually
· Oversweep	 Selected via Emergency Wing-Sweep Handle
	(a) Em. Wing-Sweep
Return to CADC	After Emergency Mode / Oversweep
Control	(a) Em. Wing-Sweep Spider Detent (Fwd on startup)
	(b) MASTER RESET Press

Indicated Mach	Max Forward Wing Position
0.4	20 deg
0.7	25 deg
0.8	50 deg
0.9	60 deg
1.0	68 deg

2.6 NAVIGATION - OVERVIEW

Pilot Cockpit Interface		
• HUD	Heads Up Display • Displays WRITE ME information	
· VDI	Vertical Display Indicator • placeholder	
• HSD	Horizontal Situation Display • NAV Mode Information	
	 Diamond - Current heading Chevron - TACAN TO bearing + - TACAN FROM bearing House - ADF bearing RNG - Range to Waypoint (nm) MODE - NAV STEER mode W - Wind heading / speed (kts) TAS - True AirSpeed (kts) GS - GroundSpeed (kts) 	
	TID Mode Information	
	Overhead ViewWaypoint Coordinates	
• BDHI	placeholder	
Standby Mag- netic Compass	• placeholder	
 Tacan Control Panel 	• placeholder	
STEER CMD Selectors	• placeholder	

2.7 NAVIGATION - INS

· Contributing	IMU – Inertial Measurement Unit
Subsystems	 4 Gimbals - No gimbal-lock, corrects platform attitude errors 2 Gyros - Source for aircraft attitude data 3 Accelerometers - Source for aircraft acceleration data
	CSDC – Computer Signal Data Converter
	 Processes sensor signals including IMU data
CSDC Data	(a) INS – Primary nav mode
Modes	Velocity Data – IMUPitch/Roll Data – IMU
	(b) IMU/AM - Backup mode selected by RIO or automatically when CSDC determines IMU velocity data unreliable.
	 Velocity Data – Calculated from true airspeed & stored wind Pitch/Roll Data – IMU
	(c) AHRS/AM – Further degraded mode selected by RIO or automatically when CSDC detects total INS failure
	 Heading - Mag heading & MAG VAR Velocity Data - Calculated from true airspeed & stored wind Pitch/Roll Data - AHRS

2.8 NAVIGATION - ALIGNMENT

 Ground Align 	(a)
· Carrier Align D/L	
 Carrier Align Handset 	
Reinitialization	
 Automatic Stored Heading 	
Catapult Align	

2.9 NAVIGATION - WAYPOINT

- Reference Point Types
- Navigation Waypoint Used for navigation. Maximum of 3 stored simultaneously
- Fixed Point (FP) Arbitrary point to establish current position relative to external references
- Initial Point (IP) Starting point for A/G attack run
- Surface Target (ST) Enemy surface target
- **Defended Point (DP)** Area to protect (i.e friendly forces)
- Hostile Area (HA) Area with known ground or air hostiles
- Home Base (HB) Airfield / CV
- 2.10 NAVIGATION TACAN
- 2.11 NAVIGATION VOR/ADF

2.12 COMMS - OVERVIEW

• ARC-159 UHF1	 Air-to-Air & Air-to-Surface Communica- tion Pilot Controlled
	 Frequency
	Range - 225.000 - 399.975 MHzSteps - 25 kHz
	– Channels – 20
• ARC-182 V/UHF 2	 Air-to-Air & Air-to-Surface Communica- tion RIO Controlled Frequency
	 Band 1 - 30 - 88 MHz Band 2 - 108 - 156 MHz Band 3 - 156 - 174 MHz Band 4 - 225 - 399.975 MHz Steps - 25 kHz Channels - 20
• ARA-50 UHF ADF	 UHF Automatic Direction Finder LoS bearing to UHF Transmitter Bearing displayed on BDHI, Pilot HSD 5 min Warmup
KY-28 Voice Se- curity Equipment	Voice CipheringIntegrated with UHF 1 and V/UHF 22 min Warmup

2.13 COMMS - ARC-159 UHF 1

• ARC-159 UHF1	 Air-to-Air & Air-to-Surface Communication Pilot Controlled Frequency
	 Range - 225.000 - 399.975 MHz Steps - 25 kHz Channels - 20
VOL Knob	Controls Pilot UHF 1 Audio Level
BRT/TEST Knob	 Controls Radio FREQ Display Turn past max to display 888.888

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 SQL Switch 	 Toggles radio squelch (noise attenuation)
READ Switch	 Displays Frequency of Selected Preset Channel
LOAD Button	 Saves Displayed Frequency to Selected Preset Channel
TONE Button	 Steady 1.020 kHz Test Tone
Mode Selector	Frequency Selection Method
	- GUARD - 243.000 MHz
	 MANUAL – Manual tuning
	- PRESET - Preset channels
 Function Selector 	 Selects Transceivers to Energize
	 ADF – Not simulated
	- BOTH - Main & Guard
	- MAIN - Main
	- OFF - Secures UHF 1 radio
· CHAN SEL	 Selects from 20 preset Channels

2.14 COMMS - ARC-182 V/UHF 2

• ARC-182 V/UHF 2	 Air-to-Air & Air-to-Surface Communication RIO Controlled Frequency
	 Band 1 - 30 - 88 MHz Band 2 - 108 - 156 MHz Band 3 - 156 - 174 MHz Band 4 - 225 - 399.975 MHz Steps - 25 kHz Channels - 20
· VOL Knob	Controls RIO UHF 2 Audio Level
BRT/TEST Knob	Controls Radio FREQ Display
• SQL Switch	Toggles radio squelch (noise attenuation)

SYSIEMS	F-14A/B REV: 20220126
• Mode Selector	Transceiver Settings
	 OFF - Secures V/UHF radio unless frequency mode set to 243
	 T/R - Energizes transmitter and main receiver
	 T/R & G - Energizes transmitter, main, and guard receiver
	 DF - Automatic direction finding from 108 - 399.975 MHz
	- TEST - BIT
• CHAN SEL	Selects Frequency Tuning Mode
Outer Dial	- 243 - Selects UHF Guard
	- MAN - Manual Select frequency
	 G – Tunes Tranceiver to guard frequecy in last selected band
	 PRESET – Allows selection between 40 preset channels (31-40 are Have Quick and not simulated)
	 READ - Displays frequency of selected preset channel
	 LOAD - Saves displayed frequency to selected preset channel

2.15 COMMS - KY-28 VOICE SECURITY EQUIPMENT

CHAN SEL

Inner Dial

•	KY-28 Voice Security Equipment	Voice CipheringIntegrated with UHF 1 and V/UHF 22 min Warmup
•	ZEROIZE Switch	Lift Guard to Erase Preloaded CodesCodes loaded via ground crew
•	Power-Mode Switch	 Selects Mode P/OFF - Removes power from system C - Transmit / Receive in secure mode DELAY - Between PTT and trans.

• Selects one of 40 Preset Channels

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Radio-Select Switch

• Selects Radio Mode

- RELAY Acts as relay for other stations (not simulated)
- RAD-2 Secure voice for V/UHF 2
- RAD-1 Secure voice for UHF1

2.16 LINK 4 DATALINK - OVERVIEW

•	· Link 4	Modes – Mutually exclusive
		- Link 4A - AWACS / Surface Ship
		 Link 4C - Fighter to Fighter
	• Data Speed – up to 5000 bit/s!	
· Link 4A	Network - AWACS / Surface Ship	
		 Additionally used for ACLS
•	Link 4C	Network - Fighter to Fighter
		- Up to four F-14s
		- Unique to F-14
Basic Op	Basic Operation	(a) Power Switch As Desired
		• Link 4A ON
		• Link 4CAUX
		(b) Mode SwitchTAC
		(c) FrequencySet

2.17 LINK 4 DATALINK - CONTROL PANEL

• Test Switch	Controls Test / Anti-Jam Modes
	- TEST - Initiates BIT
	- NORM - Normal Operation
	A-J - Anti-Jam (not simulated)
• Frequency	Selects Datalink Frequency
Thumbwheels	- First Digit - Fixed as 3
	- Allowable Range - 300.0 - 324.9 MHz
• Power Switch	Controls System Power
	- ON - Enables Link 4A
	 OFF – Disables system
	- AUX - Enables Link 4C

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2.18 LINK 4 DATALINK - REPLY/ANTENNA PANEL

• ANTENNA	Selects Antenna
Switch	Shared with UHF1 - Mutually exclusiveUHF1 LWR / DL UPRUHF1 UPR / DL LWR
• REPLY Switch	• Sets Reply Mode
	 NORM – Own Aircraft replies to datalink messages CANC – Receive only
 MODE Switch 	 Controls Overall Mode
	TAC - Normal airborne modeCAINS/WAYPT - Enables CV align
- Address Thumbwheels	 Sets Two Least Significant Bits of Aircraft D/L Address

2.19 ALR-67 RWR - CONTROLS / OVERVIEW

DIAMP C : I	
• PWR Switch	Set to ON to Operate
· VOL Knob	Sets RIO Audio Level
• TEST Switch	 Springloaded to Center BIT – Initiates Build In Test SPL – Holds BIT status page while held
• MODE Switch	 Springloaded to Center OFST - Separates overlapping symbols LMT - Displays 6 highest threats
• DISPLAY TYPE	Changes Priority of Display
Selector	 NORM - Normal threat symbology AI - Airborne Interceptor prioritized AAA - Anti-aircraft artillery prioritized UNK - Unknown prioritized FRIEND - Friendly threats prioritized
	 Indicated by Letter in Display Center
· Display	Outer Band Critical Band Imminent threat to own aircraft Blinking indicates engaging own aircraft craft
	Middle Band
	 Lethal Band Potentially threatening emitters Not actively engaging own aircraft Inner Band
	- Non-Lethal Band
	Not currently within capability of emitter
	Inner Circle
	 N, I, A, U, F - Prioritization type O - Offset L - Limit B - BIT Failure T - Thermal overload

SYSTEMS

F-14A/B

REV: 20220126

Alert Tones

- Short Tone New emitter / emitter moved
- Slow Warbling Threat in critical band
- Fast Warbling Threat actively engaging own aircraft
- **4-Tone Sequence** New threat capable of silently engaging own aircraft

2.20 ALR-67 RWR - THREAT SYMBOLOGY

SHIPS		
Arleigh Burke		
Admiral Kuznetsov		
AK Admiral Kuznetsov GR Grisha 5 (Albatros)		
· · · · · · · · · · · · · · · · · · ·		
Oliver Hazard Perry		
Type 054A Frigate, "Jiangkai II class"		
Krivak 3 (Rezky)		
Kirov (Pyotr Velikiy)		
Type 052B Destroyer, "Luyang I class"		
Type 052C Destroyer, "Luyang II class"		
Ship with Nav Radar		
Neustrashimy		
Nimitz (Vinson, Stennis)		
Slava (Moscow)		
Ticonderoga		
Tarantul 3 (Molniya)		
Tarawa		
Type 071 Amphibious Transport Dock, "Yuzhao class"		
AIRCRAFT		
F-14A/B		
F-15C/E		
F-16C		
JF-17		
F/A-18C		

21	MiG-21bis
23	MiG-23MLD
24	Su-24M/MR
25	MiG-25PD
29	MiG-29A/G/S Su-27 Su-33 J-11A
30	Su-30
31	MiG-31
34	Su-34
37	AJS-37
39	Su-25TM
50	A-50
52	B-52
AN	AN-26B AN-30M
AP	AH-64D
B1	B-1B
BE	Tυ-95 Tυ-142M
BF	Tu-22M3
BJ	Tu-160
E2	E-2D
E 3	E-3C
F4	F-4E
F5	F-5E
нх	Ka-27
IL	IL-76MD IL-78M

KJ	KJ-2000
M2	Mirage 2000-C
	Mirage 2000-5
S3	S-3B
SH	SH-60B
TO	Tornado
TR	C-130 C-17A
	AIR DEFENSE
2	S-75 TR SNR (SA-2) "Fan Song"
3	S-125 TR SNR-125 (SA-3) "Low Blow"
6	Kub SA-6
7	HQ-7TR
8	OSA (SA-8)
10	S-300PS 30N6 TR (SA- 10)
11	Buk (SA-11)
12	S-300V
15	Tor 9A331 (SA-15)
19	Tunguska 2C6M (SA-19)
Α	Gepard
	M-163 Vulcan ZSU-23-4 Shilka
ВВ	S-300PS 64H6E SR (SA- 10/Big Bird)
BF	Rapier Blindfire TR
CS	S-300PS 5N66M SR (SA-10/Clam Shell)
DE	Sborka (Dog Ear)
FF	S-125 P-19 SR (SA-3/Flat Face)
GR	Roland SR

НА	Hawk SR
НК	Hawk TR
HQ	HQ-7 SR
PT	Patriot
RO	Roland
RP	Rapier SR
S	1L13 55G6 EWR
SD	Buk TR (SA-11/Snow Drift)
SN	PRW-11 (Side Net)
	MISSILES
M	AIM-54 AIM-120 MICA-EM R-37 R-77 SD-10
	ATC
T	Airport ATC Radar

2.21 ALE-39 CMS DISPENSER

	Programmer		
• CHAFF Section	B QTY – Number of cartridges to eject in burst		
	 Options – 1-4 cartridges, C continuous, R random (4-6 cartridges) 		
	BINTV – Time in seconds between each car- tridge ejection		
	 Options1, .2, .5, .7, 1 seconds, R random 		
	S QTY – How many salvos of bursts		
	- Options - 1, 2, 4, 6, 8, 10, 15 salvos		
	• S INT – Time in seconds between salvos		
	- Options - 2, 4, 6, 8, 10 seconds		
WARNING R & C burst settings have special INTV behavior			
- JAMMER Section	Jammer cartridges not implemented in DCS		
• FLARE Section	QTY – Number of cartridges to eject in burst		
	- Options - 2, 3, 4, 6, 8, 10 cartridges		
	INTV – Time in seconds between each car- tridge ejection		
	- Options - 2, 4, 6, 8, 10 seconds		
	Control Panel		
• PWR/MODE Switch	 AUTO (CHAFF) / MAN – Enables power to system and allows automatic chaff ejection program initiation MAN – Enables power to system OFF – Disables system 		

2.22 ALQ-100 / ALQ-126 DECM

3 AWG-9 RADAR

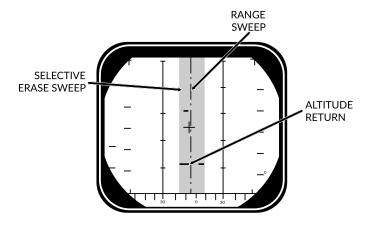
3.1 MAIN MODES - OVERVIEW

	Pulse		Pulse Doppler			
	Pulse Search	P-STT	PD Search	RWS	TWS	PD-STT
Range	60 nm	50 nm	110 nm	90 nm	90 nm	90 nm
AIM-7	BRSIT	CW	BRSIT		-	PD
AIM-54	BRSIT	ACT	BRSIT		Multi TGT	PD/ACT

3.2 MAIN MODES

· Pulse	Basic Pulse w/o doppler filtering
	- Cannot be notched
	- Ground Clutter
	 Rudimentary Ground mapping
	Pulse Sub-Modes
	Pulse SearchPulse-STT
 Pulse Doppler 	 Doppler filter> no ground returns
	 Susceptible to notching
	 No ground clutter
	- Greater range
	 Advanced sub modes
	- AIM-54 Guidance
	 Pulse Doppler Sub-Modes
	- PD Search
	- RWS
	- TWS
	- PD-STT

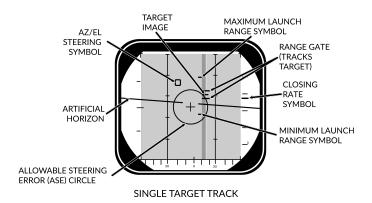
3.3 PULSE MODE - PULSE SEARCH



SEARCH (±10° SCAN)

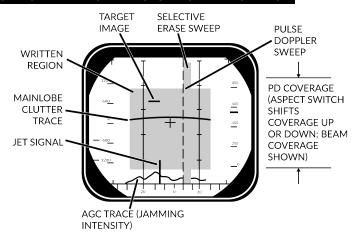
• Pulse Search	Basic Mode - AWG-9 does not use pulse doppler filtering • Advantages
	• Advantages
	 All aspect target detection
	- Cannot be notched
	 Rudimentary ground mapping
	Disadvantages
	 Cannot discern ground returns and targets
	- Lower range
· DDD	Range/Azimuth
	 Visual representation of radar and erase
	sweeps
· TID	No Information from Pulse
	Cannot guide AIM-54

3.4 PULSE MODE - PSTT



Pulse STT	Lock Target w/o doppler filtering		
	Advantages		
	- Cannot be notched		
	 Disadvantages 		
	- Susceptible to ground clutter		
 Lock Target 	• Conditions		
	Pulse Search Mode selectedRDR HCU Mode selected		
	• Lock Target		
	(a) Hold HCU Half-action		
	(b) Slew to desired Target		
	(c) HCU Full-Action to lock		
	 Unlock Target 		
	(d) HCU Half-action		
· DDD	Track Indications		
	- ANT TRK light		
	- RDROT light		
	– Tracking gates		
	- Closure rate		
	- Attack Symbology		

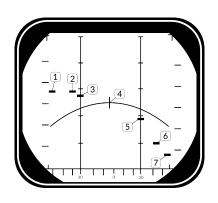
3.5 PULSE DOPPLER MODE - PULSE DOPPLER SEARCH



SEARCH (±40° SCAN)

 Pulse Doppler Search 	"Early Warning" Mode - Longest Range, cannot display range • Advantages	
	Longest RangeDoppler Filtering"Look Down Shoot Down"	
	Disadvantages	
	Can be notchedNo range information	
· DDD	Closure Rate/Azimuth	
	 Visual representation of radar and erase sweeps 	
Doppler Filters	Main Lobe Clutter (MLC) Filter	
	Own GS +/- 133 knotsRemoves main ground returnSource of notching	
	Zero Doppler Filter	
	 Negative own GS +/- 100 knots Removes Radar reflection from ground directly beneath own AC 	

• MLC Switch	 IN: Enables MLC filter AUTO: Enables MLC filter if look-up angle less than 3 deg OUT: Disables MLC filter
• Vc Switch	Changes closure rate DDD scale • X-4: -800 to 4000 knots • NORM: -200 to 1000 knots • VID: -50 to 250 knots
ASPECT Switch	 Changes closure rate processing scale NOSE: -600 to 1800 knots BEAM: -1200 to 1200 knots TAIL: -1800 to 600 knots



	Look Angle	Line of Sight Rate	Target Heading
1	60 deg	1490	180 deg
2	45 deg	1500	120 deg
3	30 deg	1428	100 deg
4	0 deg	1200	90 deg
5	30 deg	672	80 deg
6	45 deg	210	60 deg
7	60 deg	-300	0 deg

3.6 PULSE DOPPLER MODE - RWS

 Range While Search 	FM Ranging, used for getting good A/A picture before selecting TWS • FM Ranging			
	 Pulse Doppler with ranging TID shows momentary tracks with ranges Processing reduces max range 			
	Advantages			
	 Long Range Doppler Filtering "Look Down Shoot Down" Signal Processing 			
	Disadvantages			
	- Can be notched			
• DDD	 Closure Rate/Azimuth Visual representation of radar and erase sweeps 			
· TID	 Momentary Tracks Max concurrent tracks: 48 Cannot lock targets from TID 			
• Filtering	Same as Pulse Doppler Search			

3.7 PULSE DOPPLER MODE - TWS

Track While Scan	Builds Track Files, high situational awareness, multi-target AIM-54 launch • Track Files		
	 AWG-9 builds Trackfiles for contacts Can launch multiple AIM-54 Processing reduces max range Can lock targets from TID 		
	FM Ranging		
	 Pulse Doppler with ranging TID shows momentary tracks with ranges Processing reduces max range 		
	Advantages		
	Doppler FilteringMulti-Target AIM-54		
	 Disadvantages 		
	- Lowest Range		
• DDD	- Can be notched • Closure Rate/Azimuth		
	Visual representation of radar and erase sweeps		
· TID	Tracksfiles		
	Max concurrent tracks: 24		
	Max displayed tracks: 18		
• Filtering	Same as Pulse Doppler Search		
Scan Volume	Trackfiles require update every 2.5 s -> • 20 deg 4 bar (if selected) • 40 deg 2 bar (else)		
• TID Mode Selector	 GND STAB: Ground Stabilized, True North is up on TID A/C STAB: Aircraft Stabilized ATTAK: same as A/C STAB with superimposed attack steering symbology TV: Displays TCS on TID, dispays LANTIRN on TID if equipped 		

AWG-9 RADAR	F-14A/B	REV: 20220126

Selector Buttons	 RID DISABLE: Not simulated ALT NUM: Enables display of track altitudes on left side of track symbols SYM ELEM: Enables display of all supplementary symbology of tracks and waypoints DATA LINK: Enables display of D/L contacts JAM STROBE: Enables display of jam strobes NON-ATTK: enables/disables display of targets not possible to engage (friendlies) LAUNCH ZONE: Enables display of weapon launch zones VEL VECTOR: Enables display of velocity vectors
TRACK HOLD CLSN Steering	• TRACK HOLD
Buttons	 Normally: Tracks maintained for 14 s after last observation Track Hold: maintained for 2 min after last observation
	CLSN Button
	 begins collision steering to currently tracked target enables Steering Centroid if in TWS LD CLSN presents azimuth steering only CLSN presents both azimuth and elevation steering
• TWS AUTO / MAN	 TWS MAN: Manual azimuth/elevation control, target designation by RIO TWS AUTO: Automatic prioritization of targets and azimuth elevation control

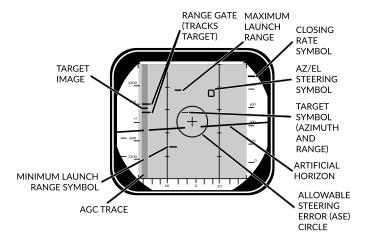
3.8 PULSE DOPPLER MODE - TWS MAN

• TWS MAN	 Target Selection: Manual
	 Scan Azimuth/Elevation: Manual
 Target Selection 	 Conditions
	TWS MAN Radar Mode selectedTID CURSOR TID Mode selected
	 Hook Target
	(a) Hold HCU Half-Action(b) Slew TID Cursor over desired Tgt(c) HCU Full-Action to select Tgt
	TID Symbology
	 Range (RA) Bearing (BR) Altitude (AL) Magnetic course (MC)
	 Lock Target
	(d) Press PD STT or Pulse STT buttons
	 Deselect Target
	(e) press HCU Half-Action
AIM-54 Launch	 Automatically selects TWS AUTO
	 Prevents selection of TWS MAN

3.9 PULSE DOPPLER MODE - TWS AUTO

• TWS AUTO	 Target Selection: prioritizes contacts based off range, aspect, closure Scan Azimuth/Elevation: Geometric center of targets in scan volume
· Centroid / Steer-	Steering Centroid
ing Cues	 facilitates steering cues HUD, VDI, TID, DDD Appears as X on TID Takes Gimbal limits into account Weights individual Tracks based on parameters
	 Illumination Centroid
	 Not Visible Controls azimuth and elevation of scan pattern Takes scan volume into account
 Pilot Steering 	 Conditions
Cues	 A-A HUD Mode selected Master Arm ON (UP) AIM-54 or AIM-7 selected TWS-AUTO selected

3.10 PULSE DOPPLER MODE - PDSTT



SINGLE TARGET TRACK

 Pulse Doppler STT 	Lock Target with doppler filtering • Advantages		
	Ground Clutter filteringDisadvantagesSusceptible to notching		
Lock Target	Conditions		
	 Pulse Doppler Mode selected (PD Search, RWS, TWS) 		
	 RDR HCU Mode selected 		
	• Lock Target		
	(a) Hold HCU Half-action		
	(b) Slew to desired Target		
	(c) HCU Full-Action to lock		
	Unlock Target		
	(d) HCU Half-action		
DDD	Track Indications		
	- ANT TRK light		
	- RDROT light		
	- Tracking gates		
	– Closure rate		
	– Attack Symbology		

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3.11 ACM MODES - OVERVIEW

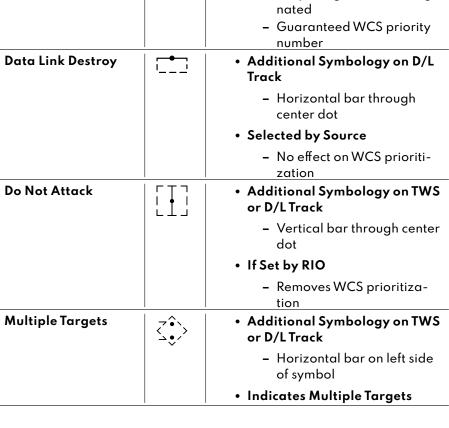
	PLM	VSL	PAL	MRL
Range	5 nm	5 nm	15 nm	5 nm
Description	Boresight	Vertical	Horizontal	RIO
Weapons		Gun +	All Missiles	

• PLM	Pilot Lockon Mode Highest Priority ACM Search Pattern - Small Boresight - Range: 5 nm
· VSL	 Vertical Scan Lockon HI Search Pattern Width: 5 deg Vertical: +15 to +55 deg Range: 5 nm
	• LO Search Pattern - Width: 5 deg - Vertical: -15 to +25 deg - Range: 5 nm
	RIO/PILOT Controlled
· PAL	Pilot Automatic LockonSearch Pattern
	Width: +/- 20 degVertical: 8-barRange: 15 nm
• MRL	 Manual Rapid Lockon RIO Controlled Search Pattern
	HCU ControlledRange: 5 nm

3.13 TID SYMBOLOGY

GENERAL		
Center Dot	•	Basic Component of Symbols
		 Marks coordinates of symbol
Own AC		Symbol representing own air- craft
		 Ground Stabilized: Moves Aircraft Stabilized: Stationary Outside TID: line drawn from TID center towards symbol
TID Cursor		Hook Cursor
		 Controlled by HCU in TID mode
		Half-Action
		 Enables display of symbol Enables HCU stick to move cursor
		• Full-Action
		 Hooks closest symbol If no symbol near, cursor dropped at location
TWS Steering Cen- troid	$ \times $	Steering centroid of TWS tracks
		 Selected by WCS for weapons engagement
ONBOARD SENS	ORS	Symbol Above Dot
Unknown	•	 Unknown Sensor Track All Returns in RWS
Hostile	·	Sensor Track designated Hos- tile by RIO
Friend		 Sensor Track designated Friendly by RIO
Angle-Tracked		Radar Angle Tracking
Radar Target		- Jamming Target

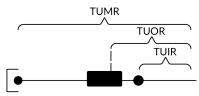
Angle-Tracked Radar Target with Altitude Difference Ranging		 Radar Angle Tracking Jamming Target Alt. diff. ranging
TCS-Angle Tracked Target	•>	TCS Angle Tracking
TCS-Angle Tracked Target with Altitude Difference Ranging		TCS Angle Tracking Alt. diff. ranging
D/L TARGETS		Symbol Below Dot
Unknown		D/L Track designated Un- known by Source
Hostile		D/L Track designated Hostile by Source
Friendly		D/L Track designated Friendly by Source
MANUAL REF PO	NTS	
Home base		Waypoint Representing Home Base Carrier Airfield
Waypoint	•	 Nav Waypoint Supplanted by Number 1, 2, or 3
Defended Point		Waypoint to Defend
Fixed Point	X	Generic Waypoint
Hostile Area		Waypoint Indicating Hostile Area
Surface Target		Waypoint Indicating Surface Target
IP	+	Initial Point Waypoint for A/G engagement
D/L REF POINT	5	



Data Link Challenge		 Additional Symbology on D/L Track
		 Small V with center at center dot
		 Command to Visually Identify
Track Extrapolated	Ŷ	 Additional Symbology on TWS or D/L Track
		 Small X with center at center dot
		 No Update within 8 seconds
		 Track deleted after 14 seconds
		 Or after 2 min if track hold
Altitude Numerics	4/^\	 Altitude to Nearest Ten Thousand
		- example: 35000-45000
Firing Order Numerics	/ •\4	 Indicates AIM-54 Prioritiza- tion
		Numbers 1-6Only in TWS
Time-to-Impact (TTI)	<i>^</i> .\II6	After AIM-54 Launch
		 Prioritization replaced with estimated TTI
		 Flashes after Pitbull
Velocity Vector		 Additional Symbology from center Dot
		Direction represents track headingLength represents speed
		Varies with Mode
		 Ground Stabilized: true heading and ground speed Aircraft Stabilized: relative heading and velocity

Launch Zone Vectors





- Additional Symbology for AIM-54
 - Selected manually by RIO
 - Or 60 seconds from max launch
- TUMR
 - Time-Until-Minimum-Range
 - Max: 180 seconds, 1.5 inches
- TUOR
 - Time-Until-Optimal-Range
 - Start of bar is 8 seconds from optimum
- TUIR

imuth

- Time-Until-In-Range

Radar Antenna Scan Pattern Azimuth Limits

Jamming Strobe



• Line from own AC towards Jammer

Limits of Current Scan Az-

• Single Line in STT

Data Link Jamming Strobe



 Line from D/L point towards Jammer

Data Link Pointer



- Additional Symbology on D/L Track
 - Circle
 - Indicates operator concern

Data Link Priority Kill		 Additional Symbology on D/L Track
		 Square Indicates target must be destroyed No effect on WCS prioritization
ATTACK DISPLAY SYM	BOLOGY	
Artificial Horizon		Represents Pitch and Roll
Steering Guidance Symbol		 Represents Steering Error Should be placed as near as possible to center of ASE circle
Allowable Steering Error Circle		 Indicates Allowable Steering Error for Missile Launch Size Varies with Geometry, Mode, Missile
Breakaway Indica- tion	X	Appears when Target Range Less than Minimum for Se- lected Weapon

4 TCS

4.1 **OVERVIEW**

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TCS - LANTIRN

5 LANTIRN

5.1 OVERVIEW

· LANTIRN	Low Altitude Navigation and Targeting Infra-Red for Night
	 Only Targeting Pod – Nav pod was deleted Incomplete Integration – Own control panel, supplants TCS feed
 Master Modes 	 A/G – Allows bomb release guidance A/A – Optimized for air targets
• FOV Levels Overview	WideFOV - 5.9 degSlew - 8.5 deg/s
	 Narrow FOV - 1.7 deg Slew - 1.8 deg/s
	• Expanded
	FOV - 0.8 degSlew - 0.7 deg/sDigital Zoom - Degraded quality

5.2 OVERVIEW - STARTUP

1.	Power Switch	POD
2.	Pod Startup Sequence	 8 min startup sequence MODE Switch shows STBY when complete
3.	MODE Switch	Press
4.	Initialization Sequence	30 sec initializationMODE Switch shows OPER when ready
5.	VIDEO Switch	FLIR
6.	TID MODE	TV

5.3 OVERVIEW - POINTING MODES

 Sensor Modes 	Contrast Lock
Overview	Area TrackPoint Track
	• Q Designation
	Directional Q - QSNO / QADL / QHUDLocation Q - QWp / QDES
• Directional Q	Do Not Allow Weapon GuidanceQSNO
	 Pod slaved to ground 15 nm in front along own aircraft heading
	• QADL
	 Pod slaved to ADL
	- In A/A mode
	• QHUD
	 Pod slaved to HUD
	- In A/G mode
• Location Q	Allow Weapon GuidanceQWp
	 Pod slaved to WCS waypoint
	Cycled with QWp+ / QWp-
	• QDES
	 Designate targets for engagement LANTIRN Trigger Second Detent to designate
	 Coordinates can be manually added to WCS for navigation

5.4 OVERVIEW - LASING/DESIGNATION

A/G Designation	(a) DesignateTrigger Full-Action	
	Laser Fires	
	Slant Range calculated	
	Time-to-Go calculated	
Steering Cues	 Automatically activated when QDES selected/designated 	
	 QDES remains even if new Q selected 	
	 Cues still point towards QDES even if pod at another point 	
Manual Lase	(a) LaseTrigger Half-Action Hold	
 Latched Lase 	• Effect – Lases for 60 sec	
	(a) ActivateLatch Lase Button Press	
	(b) Extend Latch Lase Button Press	
	(c) DeactivateTrigger Half-Action	
Auto Lase	• Effect – Fires from -10 to +4 sec TIMP	
	(a) Laser ModeSlider AFT Short	
	(b) Cycle A/M Right 4-Way Depress	
• Laser Notes	Always at current Pod location	
	 Can point to different location than QDES 	

5.5 CONTROLS - PANEL

• Power Switch	 OFF - Disables power to system IMU - Only powers LANTIRN IMU (Not Simulated in DCS) POD - Powers whole system
• MODE Switch	STBY – StandbyOPER – Operational
• LASER Switch	ARM – Arms laserSAFE – Inhibits laser use
VIDEO Switch	 FLIR - Displays LANTIRN FLIR on TID TCS - Displays TCS video on TID
· Indicator Light	Indicate Error States
· IBIT Button	Initiates Build-In-Test

5.6 CONTROLS - STICK

•	Master Mode	 A/G Mode – Side 2-Way FWD A/A Mode – Side 2-Way AFT
•	Slew	Center Slew Hat
•	WHOT/BHOT	Center Slew Hat Depress
•	Contrast Track	 Point Track - Left 4-Way Up Area Track - Left 4-Way Down
•	Q Select	 QADL/QHUD - Right 4-Way Up QDES - Right 4-Way Right QSNO - Right 4-Way Down
•	Declutter	Right 4-Way Depress
•	Zoom Level	FOV Button
•	Cycle Gain Control Mode	Slider FWD short
•	Manual Gain Control	(a) Slider FWD long (b) Gain Right 4-Way Up/Down Level Right 4-Way Left/Right
•	Laser Code	(a) Slider AFT short (b) Select Digit Right 4-Way Left/Right (c) Change Digit Right 4-Way Up/Down
•	Focus Control	(a) Slider AFT hold (b) Right 4-Way Up/Down
•	Manual Lase	Trigger Half-Action
•	Latched Laser	Latched Laser Fire Button
•	Designate QDES	Trigger Full-Action

5.7 DISPLAY

· Top Left	Own Aircraft Datablock
	- Lat - deg:min.dec
	- Long - deg:min.dec
	- ALT - Altitude (ft)
	- KGS - Knots Ground Speed
	- DIVE - Dive Angle (deg)
· Mid Left	Sensor Mode – WHOT / BHOT
	Gain Control – Auto / Manual
Bottom Left	Pod Info Datablock
	- SRA - Slant Range
	- AZ - Pod LoS Azimuth L/R
	- EL - Pod LoS Elevation
	- Time - UTC Time
	- IBIT - Codes
Bottom Center	Master Mode – A/A / A/G
	 Track Mode – AREA / POINT / Q
	Current Weapon
	Laser Code
	• L
	- Steady - Laser Armed
	- Flashing - Laser Firing
Bottom Right	• Q Datablock
3	- TTG - Time-To-Go
	- B/R - Bearing and Range
	- ELEV - Elevation (ft) of Q
	- Lat - deg:min:dec
	- Long - deg:min:dec
Mid Center	• Crosshair
	- Bounding Box - Indicates currently
	tracked target in point mode
	- Zoom Boxes - Indicates next zoom lev-
	els
	- FLIR Pointing Cue - Shows Pod LoS,
	screen center indicates straight down
	1

 Only shown if current Q is QDES, v valid weapon selected TREL - Time to release TIMP - Time to Impact (after release) 	
valid weapon selected	is QDES , with
•	is QDES , with
 Only shown if current Q is QDES, v 	is QDES , with
Mid Right Bomb Rlease Cue	

heading

- Relative bearing L/R to commanded

6 A/GWEAPONS

6.1 A/G WEAPON SETTINGS - OVERVIEW

• WPN TYPE	Selects Weapon Type
	 Configures WCS for selected weapon Refer to Kneeboard for list of mounted weapons Mk-81 / 82 / 83 have both L and H option refering to high and low drag
• DLVY MODE	 STP-SGL – Single weapon per press STP-PRS Single pair per press RPL-SGL – QTY of weapons per press RPL-PRS – QTY of pairs per press
• DLVY OPTNS	 INTERVAL – Interval in ms QTY – Number of stores to be released
• MECH FUZE	 NOSE - Arms nose fuze SAFE - Inhibits arming of fuzes NOSE/TAIL - Arms both fuzes
• ELEC FUZE	 SAFE - Inhibits electrical bomb fuzing VT - Sets air-burst mode at preset burst height for compatible stores INST - Sets instantaneous burst mode DLY 1 - Sets preset time delay 1 DLY 2 - Sets preset time delay 2
· STA SEL	Selects Stations for Employment/Jettison
	 Set to SEL to activate a pylon Stations 1 & 8 should be set to B for selection Station 1 & 8 SW was used for Sidewinder jettison, is now inoperable
 TANK JETT 	Allows Drop Tank Jettison
· SEL JETT	 JETT - Selective jettison SAFE - Inhibits jettison AUX - Backup mode
· JETT OPTIONS	 MERTER – Jettisons ejector racks WPNS – Jettisons weapons only

ATTK MODE

- CCMPTRTGT
 - Computer Target Similar to CCRP
- CMPTR IP
 - Computer initial point
 - Extended CMPTR TGT mode using known IP
 - For use when target hard to spot visually but close to landmark
- CMPTR PLT
 - Computer Pilot similar to CCIP
- MAN
 - Manual HUD displays pipper
 - Backup mode
- D/L BOMB
 - Data-Link Bomb Automatic mode steered by D/L cues
 - Not Implemented in DCS

6.2 SELECTIVE ORNANCE JETTISON

1.	Pilot Conditions	MASTER ARM	ON
2.	RIO Conditions	Desired Stations JETT OPTIONS	
3.	Jettison	(a) SEL JETT Guard(b) SEL JETT Switch	

6.3 M61 GUN

1.	Pilot Conditions	• MASTER ARM	ON
		• HUD	
		WEAPON SELECTOR	-
		Wing Sweep	ВОМВ
2.	Employment	(a) Dive	20-30 deg
		(b) Pipper	on target
		(c) TRIGGER	FIRE
•	Note: TCS	TCS slaved to radar impact p	oint
		Rio can select NAR or WIDE	

6.4 FFAR/ZUNI ROCKETS

1.	RIO Conditions	• WPN TYP	LAU-10
		Attack Mode	Pilot Attack
		Deliver Mode	RPL-SGL
		Mechanical Fuze	NOSE
		Electronic Fuze	INST
		Delivery Options	As Desired
		• Stations	Armed
2.	Pilot Conditions	• MASTER ARM	ON
		• HUD	A/G
		WEAPON SELECTOR	OFF
		• Stations	verify selected
		Wing Sweep	ВОМВ
3.	Employment	(a) Dive	20-30 deg
		(b) Pipper	on target
		(c) TRIGGER	FIRE

6.5 UNGUIDED BOMB - CCIP

1.	RIO Conditions	• WPN TYP MK-8X
		Attack ModePilot Attack
		Deliver ModeSTP-PRS
		Mechanical Fuze NOSE
		Electronic FuzeINST
		Delivery Options As Desired
		StationsArmed
2.	Pilot Conditions	• MASTER ARM ON
		• HUD
		WEAPON SELECTOR OFF
		Stationsverify selected
		• Wing Sweep BOMB
3.	Employment	(a) Dive 40 deg
		(b) Pipper on target
		(c) STORE RELEASEPress and Hold

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6.6 UNGUIDED BOMB - CCRP

1.	RIO Conditions	• WPNTYP MK-8X	
		Attack Mode Target Attack	
		Deliver ModeSTP-PRS	
		Mechanical Fuze NOSE	
		Electronic FuzeINST	
		Delivery Options As Desired	
		StationsArmed	
2.	Pilot Conditions	• MASTER ARM ON	
		• HUD A/G	
		WEAPON SELECTOR OFF	
		Stationsverify selected	
		Wing SweepBOMB	
3.	Designation	(a) Slew DiamondVSL HI/LO	
		(b) DesignatePAL	
4.	Employment	(a) Flight PathStraight, Level	
		(b) Vel Vector on Bomb Fall Line	
		When Solution Cue meets Velocity Vector	
		(c) STORE RELEASE Press and Hold	

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6.7 LASER GUIDED BOMB

	To a contract of the contract
l. LANTIRN PREP	(a) Target Pod PowerPOD
T KET	Warm up takes approx. 8 minAutomatically switches to STANDBY
	(b) Laser Code as desired
	MUST BE SET ON THE GROUND
	• Default: 1688
	(c) LANTIRN ModeOPERATE
	• STANDBY caution will flash for 30 s
	 Then switches to OPER
	(d) VIDEO SwitchFLIR
	(e) TID ModeTV
2. RIO Conditions	• WPN TYPGBU-XX
	Attack Mode
	Deliver ModeSTP-SGL
	Mechanical FuzeNOSE
	• Electronic FuzeINST
	Delivery Options As Desired
3. Pilot Conditions	• StationsArmed
3. Pilot Conditions	• MASTER ARMON • HUDA/G
	WEAPON SELECTOR OFF
	• VDI Mode
	• Stationsverify selected
	Wing SweepBOMB
4. Slew LANTIRN	Refer to LANTIRN Control Section
	Slave to WYPTLeft-4-Way RIGHT
	QSNO (Snowplow)S4 HAT Down
	Toggle FOV LANTIRN Toggle FOV
	SlewLANTIRN Stick
	Area Track Left-4-Way UP
	Point Track Left-4-Way Down
	Undesignate LANTIRN Undesignate

4. Designate	Refer to LANTIRN Designation Section (a) DesignateTrigger Full-Action • Slant Range calculated • Time-to-Go calculated
	Once Time-to-Realease (TREL) is 0
	(b) Auto-Lase If selected: lases 10s to impact (c) Manual LaseTrigger Full-Action (d) While LasingL blinks
5. Employment	Once Time-to-Realease (TREL) is 0
	(a) STORE RELEASEPress and Hold
	(b) Flight PathGentle right-hand turn
	(to prevent masking)

6.8 TALD DECOYS

1.	RIO Conditions	• WPN TYPTALD • Deliver ModeSTP-SGL
		Delivery Options As Desired
		StationsArmed
2.	Pilot Conditions	• MASTER ARM ON
		• HUD A/G
		WEAPON SELECTOR OFF
		• HSD ModeTID
		Stationsverify selected
3.	Employment	(a) Flight PathHigh / Fast
		(b) RWR Monitor to locate emitters
		(c) STORE RELEASE Press and Hold

7 A/AWEAPONS

7.1 M61 GUN - OVERVIEW

GUN RATE Button	 Cycles Gun Rate
	- HIGH - 6000 rpm
	- LOW - 4000 rpm
A/A Gun Modes	• RTGS
	 Real-Time Gunsight Mode Selected automatically with guns If No WCS Data Available displays bullet location at 2000 ft with diamond and 1000 ft with pipper If WCS Data Available pipper displays bullet location at targets current range out to 4000 ft
	• MANUAL
	Fixed manual pipperAdjust with GUN ELEV knobPress CAGE/SEAM to select
CAGE/SEAM But- ton	Cycles RTGS / MANUAL Gun Modes
ROUNDS Knob	Allows selection of remaining gun rounds

7.2 M61 GUN - MANUAL

1.	Pilot Conditions	• MASTER ARM	ON
		• HUD	A/A
		• Gun Rate	HIGH
		Gunsight Lead	as required
		WEAPON SELECTOR	GUNS
2.	Employment	(a) Gun Mode	MANUAL
		(b) Pipper	on target
		(c) Trigger	FIRE

7.3 M61 GUN - RTGS / NO RADAR

1. Pilot Conditions	• MASTER ARM	ON	
		• HUD	A/A
		• Gun Rate	HIGH
	WEAPON SELECTOR	GUNS	
2.	Employment	(a) Gun Mode	RTGS
		(b) Pipper	on target
	(c) Trigger	FIRE	

7.4 M61 GUN - RTGS / RADAR

1.	Pilot Conditions	• MASTER ARM	ON
		• HUD	A/A
		• Gun Rate	HIGH
		WEAPON SELECTOR	GUNS
2.	Employment	(a) Gun Mode	RTGS
		(b) Radar	STT
		(c) Pipper	on target
		(d) Trigger	FIRE

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7.5 AIM-9 SIDEWINDER - OVERVIEW

· Missile Prepara-	MSL PREP
tion	 AIM-9 seeker must be cooled
	 Either press SW COOL button
	- Or activation of ACM
 Seeker Head 	• SEAM
Modes	 Sidewinder Expanded Acquisition Mode
	 Double-D search pattern invisible to pilot
	 4.5 sec search time
	 Allows AIM-9 to be uncaged and track target
	 40 deg track limit
	 Allows WCS to slave AIM-9 to radar
	track
	 Boresight
	 AIM-9 locked to ADL
	- 2.5 deg FOV
	 Selected if MODE/STP set to BRSIT
	- And ACM not active
 MODE/STP 	• NORM
Switch	 Allows SEAM seeker mode
	• BRSIT
	- Forces Boresight seeker mode
	- Overridden if ACM active
· CAGE/SEAM But-	Uncages Seeker
ton	 Starts 4.5 second double-D search
	 If no IR source found cages again
	Slaves Seeker
	– If radar STT locked

7.6 AIM-9 SIDEWINDER - SILENT

1. Pile	Pilot Conditions	• MASTER ARM	ON
		• HUD	A/A
		• SW COOL	ON
		• MODE/STP	As Desired
		• WEAPON SELECTOR	SW
2.	Employment	(a) CAGE/SEAM	Uncage Seeker
		(b) IR-Lock	Good Tone
		(c) Trigger	FIRE

7.7 AIM-9 SIDEWINDER - RADAR

1.	Pilot Conditions	• MASTER ARM	ON
		• HUD	A/A
		• SW COOL	ON
		• MODE/STP	NORM
		WEAPON SELECTOR	SW
2.	Employment	(a) Radar	STT
		(b) CAGE/SEAM	Slave Seeker
		(c) IR-LOCK	Good Tone
		(d) Steering center T-sho	aped cue with ASE
		(e) Trigger	FIRE

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7.8 AIM-7 SPARROW - OVERVIEW

Missile Preparation

- MSL PREP
 - AIM-7 must be tuned to AWG-9
 - Either press MSL PREP button
 - Or activation of **ACM**

Launch Modes

- Normal
 - Standard operation, STT target designated before launch
 - AIM-7 uses SARH all the way to target
 - WCS can use CS or PD for guidance set with **MSL OPTIONS** Switch
- Boresight
 - Uses CS flood antenna of AWG-9
 - Missile will track strongest return in Flood area
 - Automatically activated if STT broken
 - Selected if **MODE/STP** set to **BRSIT**
 - Or if no STT available
 - Shown Below

• MSL SPD

GATE Switch

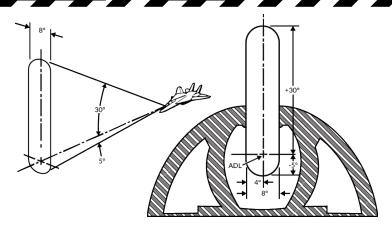
- NOSE QTR
 - Standard setting in DCS
- All Others
 - Not simulated

• MSL OPTIONS
Switch

- NORM
 - WCS uses dedicated CW antenna for AIM-7 guidance
- SP PD
 - WCS uses PD from main flood antenna for AIM-7F/M guidance

MODE/STP Switch

- NORM
 - Sets normal launch mode logic
- BRSIT
 - Forces Boresight launch mode



7.9 AIM-7 SPARROW - STT

$\overline{}$	Dil i C livi	MACTED ADM
١.	Pilot Conditions	• MASTER ARM ON
		• HUD
		• MSL PREP ON
		• MODE/STPNORM
		WEAPON SELECTORSP
2.	RIO Conditions	MSL SPD GATE NOSE QTR
		MSL OPTIONS As Desired
3.	Employment	(a) Radar STT
		(b) Steering
		• Target < 20 deg from ADL
		ASE center T-shaped cue within
		(c) TriggerPress and Hold
		(until weapon release)
		(d) Radar Maintain Lock (until impact)

7.10 AIM-54 PHOENIX - OVERVIEW

•	Missile Prepara-	 Weapon Cooling
	tion	AIM-54 requires liquid coolingRIO enabled LIQUID COOLING switch
		MSL PREP
		 AIM-54 must be tuned to AWG-9 Either press MSL PREP button Or activation of ACM
•	Launch Modes	• PDSTT SARH
		 AIM-54 uses SARH all the way to target Faster update rate than TWS Slightly increased effective range as compared to a TWS launch
		• TWS SARH/ARH
		 Allows 6 AIM-54 launches at 6 targets Missile is initially SARH guided When within AIM-54 seeker range AWG-9 sends activation command Not Fire and Forget: Requires automatic activation command
		ACM Active
		 Activated when BRSIT selected Or when ACM active with no radar track Missile commanded active before launch
•	MSL SPD	NOSE QTR
	GATE Switch	 Standard setting in DCS
		All Others
		 Not simulated
•	MSL OPTIONS	• NORM
	Switch	 Normal guidance (SARH or SARH/ARH)
		• PH ACT
		 WCS immediately sends AIM-54 acti- vation command on launch

Reverts to SARH if no target detectedMust be selected before launch

A/	A WEAPONS	F-14A/B REV: 20220126
•	TGTS Switch	 SMALL - 6nm activation range NORM - 10nm activation range LARGE - 13nm activation range
•	Missile Next Launch Button	 Selects Hooked Track as Next Target for AIM-54 TWS Engagement
•	MODE/STP Switch	NORM Normal operation BRSIT
		 Commanded active before launch Missile follows ADL and locks strongest return
•	TWS Symbology	Refer to TID Symbology Section • Pre-Launch
		 Prioritization numbers assigned to tracks automatically or manually Blinking indicates optimal launch parameters

7.12	AIM-54 PHOENIX	- TWS / MULTI
1.	Pilot Conditions	MASTER ARM ON HUD A/A MSL PREP ON MODE/STP NORM WEAPON SELECTOR PH
2.	RIO Conditions	 LIQUID COOLING ON (FWD) MSL SPD GATE NOSE QTR MSL OPTIONS As Desired TGTS Switch As Desired WCS Mode TWS MAN/AUTO
4.	Employment	(a) Radar

