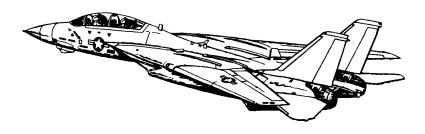
Pocket Checklist

F-14A/B AIRCRAFT

REV: 20210523



Procedures

Systems

AWG-9 Radar

TCS ALQ-100

LANTIRN

A/G Weapons

A/A Weapons



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PROCEDURES

PILOT - PRE-START

		1
1.	Parking Break	ENGAGED
2.	Ground Power	connected
3.	Compressed Air	connected
4.	ICS	HOT MIC
5.	TO RIO	"Begin Start-Up"
6.	ICS	Comm Check
7.	MASTER TEST	(a) LTS
	Selector	Warning Lights
		 RPM
8.	Ejection Seat	Armed
9.	RIO	Canopy Closed
10.	Oxygen	ON (FWD)
11	Emergency Wing Sweep	OVERSWEEP

PILOT - ENGINE START

1.	AIR SOURCE	OFF
2.	Hydraulics	(a) HYD TRANSFER PUMP SHUTOFF
		(b) Emerg. Hyd AUTO (LOW)
3.	L&R MASTER GEN	NORM
4.	RIO	"Ready to Start"
5.	Right Engine	(a) Engine CrankR
	Start-Up	(b) R Eng N2
		(c) R ThrottleIDLE
		(d) TIT< 890 C during start
		(e) R GEN CAUTIONextinguished
6.	Stabilized Parameters	• RPM
	eleis	• TIT approx 500 C
		• Fuel Flow
		• Oil Pressure25-35 psi
		• Hyd Pressure3000 psi
7.	Left Engine Start-	(a) Engine CrankL
	Up	(b) L Eng N2
	•	(c) L ThrottleIDLE
		(d) TIT < 890 C during start
		(e) L GEN Cautionextinguished
8.	Stabilized Param-	• RPM62-78%
	eters	• TIT approx 500 C
		• Fuel Flow950-1400 pph
		• NOZ 5 (100%)
		• Oil Pressure25-35 psi
		• Hyd Pressure
9.	HYD TRANSFER PUMP	NORM
10.	HYD PRESSURE	3000 psi
11.	AIR SOURCE	BOTH ENG
12.	Ground Power	disconnected
13.	Compressed Air	disconnected

1.3 PILOT - POST-START

1.	TO RIO	"Both Engines Running"
2.	Displays Control Panel	• VDI ON • HUD ON • HSD ON • HDS MODE TID (monitor INS)
3.	RIO	Select Align Quality INS GO NOW: shortest but least precise alignment INS GO COARSE: does not meet Launch Criteria for AIM-7 / AIM-54 INS GO MIN WPN LAUNCH: allows AIM-7 / AIM-54 launch INS GO FINE fine align (8 min)
4.	ACM Panel	• GUN RATE as required • SW COOL OFF • MSL PREP OFF • Missile MODE/STP NORM
5.	Gun Rounds	Set
6.	ANTI-SKID SPOILER BK	OFF
7.	Emergency Wing Sweep	(a) Handle
8.	AFCS Panel - SAS STAB AUG	• PITCH ON • ROLL ON • YAW ON
9.	WING/EXT TRANS	AUTO
10.	UHF 1 Function Selector	ВОТН
11.	TACAN Function Selector	T/R
12.	ARA-63 ICLS RE- CEIVER	ON

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13.	Radar Altimeter	(a) Control Knob one click CW to turn on (b) Display
14.	Standby ADI	erect at least 2 min before T/O
15.	KY-28 Crypt. Key	Set (refer to GROUND SETTINGS kb)
16.	RIO	set D/L frequency
17.	Lights	As desired

1.4 RIO - PRE-START

1.	Oxygen	ON (FWD)
2.	PILOT	• Ground Power connected • Compressed Air connected
3.	ICS	Comm Check
4.	Lights	As required
5.	LTS Test	Coordinate with Pilot
6.	Ejection Seats	ARMED
7.	Canopy	CLOSED
8.	TO PILOT	"Ready to Start"

1.5 RIO - POST-START - SHORE

1.	PILOT	Enginesstarted AIR SOURCEBOTH ENG
2.	INS STARTUP	(a) LIQUID COOLINGON (FWD) (b) WCS SwitchSTANDBY (c) IR/TV PowerSTBY/IR/TV (d) TID/DDDilluminated after 40 s
3.	Kneeboard	Retrieve Coordinates, Elevation, Magnetic Variation from GROUND SETTINGS Page
WAF	RNING Input Coords E	BEFORE selecting GND ALIGN if using ASH
4.	Start INS Align	(a) Nav Mode GND ALIGN (b) CAP • Category NAV • MESSAGE OWN AC (c) Keyboard
		 CLEAR, LAT, latitude, ENTER LONG, longitude, ENTER ALT, altitude, ENTER
		(d) CAP MESSAGEMAG HDG VAR (e) KeyboardHDG, mag var, ENTER (f) Align ProgressMonitor
5.	U/VHF Mode	T/R G

6.	Datalink	(a) Kneeboard TACTICAL DL (b) DL Power ON (FWD) (c) DL Mode TAC (AFT) (d) DL Freq. Set
7.	TACAN	T/R
8.	RWR Panel	(a) Display Type NORM (b) PWR ON (c) TEST SPL (d) MODE LMT
9.	DECM	STBY, then ACT
10.	IFF	(a) MASTER
11.	Altimeter	Reset
12.	CAP	Enter Data (WP, FP, etc.)
13.	Displays	• DDD
14.	Hand Control Panel	Set
15.	AN/ALE-39	Set (as required) • AUTO (CHAFF)/MAN • MAN
16.	Flare Mode	PILOT
17.	Complete INS Align	Duration Full Fine
		(a) Align CompleteCaret → Diamond(b) NAV ModeINS NAV
18.	Standby ADI	Erect at least 2 min before T/O
19.	TO PILOT	#Ready to Taxi"
Onc	e Airborne	
20.	IR/TV Power	ON
21.	WCS Switch	WCS XMT

1.6 RIO - POST-START - CARRIER

1.	PILOT	• Enginesstarted
		AIR SOURCE BOTH ENG
2.	INS STARTUP	(a) LIQUID COOLINGON (FWD)
		(b) WCS Switch STANDBY
		(c) IR/TV Power STBY/IR/TV
		(d) TID/DDD illuminated after 40 s
3.	Datalink	(a) Kneeboard TACTICAL DL
		(b) DL Power ON (FWD)
4.	Start INS Align	(a) DL FREQ
		(b) DL Mode CAINS/WAYPT
	HAME Made	(c) Nav ModeCVA
5.	U/VHF Mode	T/R G
6.	TACAN	T/R
7.	RWR Panel	(a) Display TypeNORM
		(b) PWRON
		(c) TEST SPL (d) MODE LMT
	DECM	STBY, then ACT
8.		<u> </u>
9.	IFF	(a) MASTER
10.	Altimeter	Reset
11.	CAP	Enter Data (WP, FP, etc.)
12.	Displays	• DDDSet
		• TID Set
		Multiple Display IndicatorSet
13.	Hand Control Panel	Set
14.	AN/ALE-39	Set (as required)
		AUTO (CHAFF)/MAN
		• MAN
15.	Flare Mode	PILOT
16.	Complete INS	Duration Full Fine9 min
	Align	Duration ASH much faster
		(a) Align CompleteCaret → Diamond (b) NAV ModeINS NAV

PROCEDURES F-14A/B REV: 20210523

17.	Datalink	(a) DL ModeTAC (AFT) (b) DL Freq.Set	
18.	Standby ADI	Erect at least 2 min before T/O	
19.	TO PILOT	"Ready to Taxi"	
Onc	Once Airborne		
20.	IR/TV Power	ON	
21.	WCS Switch	WCS XMT	

1.7 PRE-TAXI

1.	ANTI-SKID SPOILER BK	OFF
2.	HOOK BYPASS	As Required
3.	Nose Strut	RETRACTED
4.	HUD MODE	ТО
5.	Parking Brake	Released (IN)
6.	NWS	ENGAGED
7.	Path	verify clear

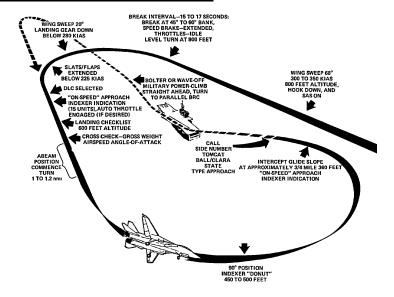
1.8 TAKEOFF - SHORE

	After Lining Up On Runway				
1.	(a) EM WING SWEEPFWD, then IN (b) MASTER RESETPRESS (c) WingsVerify thumb controller (d) WING SWEEPAUTO (e) WingsVerify at 20 deg				
2.	ANTI SKID SPOILER BK	BOTH (UP)			
3.	FLAPS	UP			
4.	Trim	0 deg			
5.	NWS	DISENGAGED			
6.	Takeoff	(a) Throttle .MIL (90% RPM) (b) Stick .Back at 130 KIAS (c) Rotation .approx 140 KIAS (d) GEAR .UP < 250 KIAS			

1.9 TAKEOFF - CARRIER

	Lineup	 Wait behind JBD until Catapult is clear Follow Taxi Directors Instructions to line up on Catapult
1.	Wing Sweep	(a) EM WING SWEEPFWD, then IN (b) MASTER RESETPRESS (c) WingsVerify thumb controller (d) WING SWEEPAUTO (e) WingsVerify at 20 deg
2.	FLAPS	DOWN
3.	Launch Bar Preparation	(a) Nose Strut KNEEL when directed (b) Throttle UP when directed (c) Taxi launch bar into shuttle (d) Throttle IDLE when directed
4.	Trim	2-3 deg nose up
5.	Speed Brakes	IN
6.	Final Checks	(a) Throttle MIL when directed (b) Control Wipeout • Stick Full Forward • Stick Full Aft • Stick Full Left • Stick Full Right • Rudder Full Left • Rudder Full Right (c) Eng. Inst Checked (d) Caution/Warnings None
7.	Catapult Shot	(a) Salute CAT SHOT (b) Gear UP < 250 KIAS (c) Flaps UP < 225 KIAS
8.	Clearing Turn	
		· ·

1.10 LANDING - OVERHEAD PATTERN



1.	Initial Approach	• WING SWEEP 68 deg
		• HOOKDOWN
		• SAS ON
		• HUDLDG
		Airspeed 300-350 KIAS
		• Altitude 800 ft
2.	Initial Break	Break Interval15-17 s
		• BANK 45-60 deg
		SPEED BRAKEEXTEND
		ThrottleIDLE
		• G3-4 G
		• Altitude 800 ft
3.	Break Turn	• Wing SweepAUTO < 280 KIAS
		• Landing GearDOWN < 280 KIAS
		• FLAPS DOWN < 225 KIAS
4.	Downwind	DLCSelected once flaps out
		• AOAON-SPEED
		LANDING CHECKLIST
		Altitude descend to 600 ft

5.	Final Turn	180 Deg Position • Abeam Pos 90 Deg Position	1-1.2 nmi
		• AOA • Altitude	
6.	Intercept Glides- lope	Distance Altitude AOA	360 ft

1.11 LANDING - CHECKLIST

1.	Wing Sweep	20 deg AUTO
2.	Wheels	• Lights
3.	SAS	ON
4.	FLAPS	DOWN
5.	DLC	Checked
6.	Hook	HOOKDOWN Transition LightOUT
7.	Harness	Locked
8.	Speedbrakes	EXT
9.	Brakes	Check
10.	Fuel	Check

After successfull airstart

- 10. BACK UP IGNITION OFF
- 11. **ENG MODE** PRI if possible

1.13 WINDMILL RESTART

- 1. Airspeed>450 kts
- 2. Throttle IDLE or above
- 3. BACK UP IGNITIONON

If no relight occurs

4. Throttle OFF then IDLE

If still no relight

- 5. **ENG MODE**SEC
- 6. Throttle OFF then IDLE

After successful airstart

- 7. BACK UP IGNITION OFF
- 8. **ENG MODE**PRI

1.14 AIRSTART - SPOOLDOWN

Immediately after engine loss before significant spooldown

1.	Throttle	IDLE or above
2.	Throttle	If no relight occurs OFF then IDLE
3.	ENG Mode Select	If still no relight occurs, SEC
4.	Throttle	If no start after mode switch OFF then IDLE
5.	ENG MODE SELECT	After successful airstart in SEC PRI if possible

1.15 AIRSTART

	AIROTAIRE	
•	Cross-Bleed Restart	With one ENG running, if Spooldown fails
		(a) Non-Running Throttle OFF
		(b) FUEL SHUT OFFcheck
		(c) Running throttle80%+
		(d) BACK UP IGNITIONON
		(e) ENG CRANK non-running eng
		(f) Non-Running ThrottleIDLE
		If no start occurs
		(g) Non-Running Throttle OFF then IDLE
		If still no start
		(h) ENG MODE SEC (i) Non-Running Throttle OFF then IDLE
		After successfull airstart
		(j) BACK UP IGNITIONOFF (k) ENG MODEPRI if possible

SYSTEMS F-14A/B REV: 20210523

2.6

- 2 SYSTEMS
- 2.1 AFCS
- 2.2 WING SWEEP
- 2.3 NAVIGATION
- 2.4 COMMUNICATION
- 2.5 DATALINK / IFF

	SHIPS
AB	Arleigh Burke
AK	Admiral Kuznetsov
GR	Grisha 5 (Albatros)
HP	Oliver Hazard Perry
J2	Type 054A Frigate, "Jiangkai II class"
KK	Krivak 3 (Rezky)
K۷	Kirov (Pyotr Velikiy)
L1	Type 052B Destroyer, "Luyang I class"
L2	Type 052C Destroyer, "Luyang II class"
N	Ship with Nav Radar
NE	Neustrashimy
NZ Nimitz (Vinson, Stenn	
TT	Tarantul 3 (Molniya)
TW	Tarawa
YU	Type 071 Amphibious Transport Dock, "Yuzhao class"
	AIRCRAFT
14	F-14A/B
15	F-15C/E
16	F-16C
17	JF-17
18 F/A-18C	
18	F/A-18C

RWR THREAT SYMBOLOGY

		KJ	KJ-2000
		M2	Mirage 2000-C Mirage 2000-5
21	MiG-21bis	S3	S-3B
23	MiG-23MLD	SH	SH-60B
24	Su-24M/MR	ТО	Tornado
25	MiG-25PD	TR	C-130
29	MiG-29A/G/S		C-17A AIR DEFENSE
	Su-27 Su-33	2	S-75 TR SNR (SA-2)
	J-11A	2	"Fan Song"
30	Su-30	3	S-125 TR SNR-125 (SA-
31	MiG-31		3) "Low Blow"
34	Su-34	6	Kub SA-6
37	AJS-37	7	HQ-7 TR
39	Su-25TM	8	OSA (SA-8)
50	A-50	10	S-300PS 30N6 TR (SA- 10)
52	B-52		Buk (SA-11)
AN	AN-26B AN-30M	12	S-300V
AP	AH-64D	15	Tor 9A331 (SA-15)
B1	B-1B	19	Tunguska 2C6M (SA-19)
BE	 Tu-95	A	Gepard
	Tu-142M		M-163 Vulcan ZSU-23-4 Shilka
BF	Tu-22M3	BB	S-300PS 64H6E SR (SA
BJ	Tu-160		10/Big Bird)
E2	E-2D	BF	Rapier Blindfire TR
E 3	E-3C	CS	S-300PS 5N66M SR
F4	F-4E		(SA-10/Clam Shell)
F5	F-5E	DE	Sborka (Dog Ear)
НХ	Ka-27	FF	S-125 P-19 SR (SA- 3/Flat Face)
IL	IL-76MD IL-78M	GR	Roland SR
KC	IL-76M KC-135		1 2.00.00

KJ	KJ-2000
M2	Mirage 2000-C Mirage 2000-5
S3	S-3B
SH SH-60B	
ТО	Tornado
TR	C-130 C-17A
	AIR DEFENSE
2	S-75 TR SNR (SA-2) "Fan Song"
3	S-125 TR SNR-125 (SA- 3) "Low Blow"
6	Kub SA-6
7	HQ-7 TR
8	OSA (SA-8)
10	S-300PS 30N6 TR (SA- 10)
11	Buk (SA-11)
12	S-300V
15	Tor 9A331 (SA-15)
19	Tunguska 2C6M (SA-19)
Α	Gepard M-163 Vulcan ZSU-23-4 Shilka
ВВ	S-300PS 64H6E SR (SA- 10/Big Bird)
BF	Rapier Blindfire TR
CS	S-300PS 5N66M SR (SA-10/Clam Shell)
DE	Sborka (Dog Ear)
FF	S-125 P-19 SR (SA- 3/Flat Face)
GR	Roland SR

НА	Hawk SR
HK	Hawk TR
HQ	HQ-7 SR
PT	Patriot
RO	Roland
RP	Rapier SR
S	1L13 55G6 EWR
SD	Buk TR (SA-11/Snow Drift)
SN	PRW-11 (Side Net)
	MISSILES
M	AIM-54 AIM-120 MICA-EM R-37 R-77 SD-10
	ATC
T	Airport ATC Radar

AWG-9 RADAR

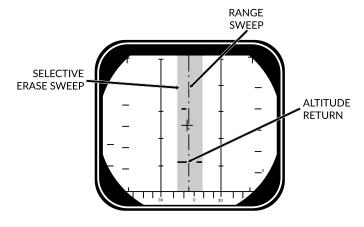
MAIN MODES - OVERVIEW

	Pu	Ise		Pulse Doppler		
	Pulse Search	P-STT	PD Search	RWS	TWS	PD-STT
Range	60 nm	50 nm	110 nm	90 nm	90 nm	90 nm
AIM-7	BRSIT	CW	BRS	SIT	-	PD
AIM-54	BRSIT	ACT	BRS	SIT	Multi TGT	PD/ACT

MAIN MODES

• Pulse	Basic Pulse w/o doppler filtering
	Cannot be notchedGround ClutterRudimentary Ground mapping
	Pulse Sub-Modes
	Pulse SearchPulse-STT
 Pulse Doppler 	 Doppler filter -> no ground returns
	 Susceptible to notching No ground clutter Greater range Advanced sub modes AIM-54 Guidance
	Pulse Doppler Sub-Modes
	PD SearchRWSTWSPD-STT

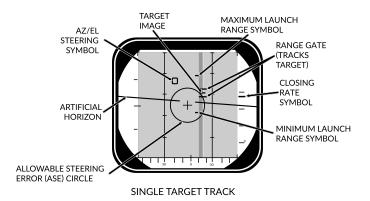
PULSE MODE - PULSE SEARCH 3.3



SEARCH (±10° SCAN)

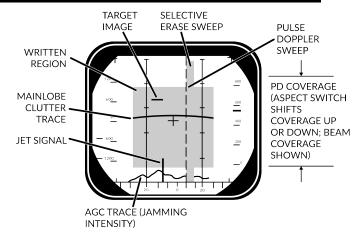
Pulse Search	Basic Mode, AWG-9 does not use pulse doppler filtering • Advantages
	All aspect target detectionCannot be notchedRudimentary ground mapping
	 Disadvantages
	Cannot discern ground returns and targetsLower range
• DDD	Range/Azimuth
	 Visual representation of radar and erase sweeps
• TID	No Information from PulseCannot guide AIM-54

3.4 PULSE MODE - PSTT



Pulse STT	Lock Target w/o doppler filtering • Advantages
	 Cannot be notched
	 Disadvantages
	 Susceptible to ground clutter
 Lock Target 	 Conditions
	Pulse Search Mode selectedRDR HCU Mode selected
	Lock Target
	(a) Hold HCU Half-action(b) Slew to desired Target(c) HCU Full-Action to lock
	Unlock Target
	(d) HCU Half-action
• DDD	 Track Indications
	ANT TRK light
	RDROT light
	 Tracking gates
	 Closure rate
	 Attack Symbology

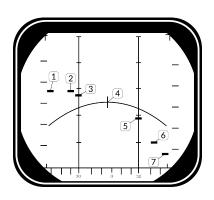
3.5 PULSE DOPPLER MODE - PULSE DOPPLER SEARCH



SEARCH (±40° SCAN)

Pulse Doppler Search	 "Early Warning" Mode, Longest Range, cannot display range Advantages Longest Range Doppler Filtering "Look Down Shoot Down"
	 Disadvantages
	Can be notchedNo range information
• DDD	Closure Rate/Azimuth
	 Visual representation of radar and erase sweeps
Doppler Filters	Main Lobe Clutter (MLC) Filter
	Own GS +/- 133 knotsRemoves main ground returnSource of notching
	Zero Doppler Filter
	 Negative own GS +/- 100 knots Removes Radar reflection from ground directly beneath own AC

MLC Switch	 IN: Enables MLC filter AUTO: Enables MLC filter if look-up angle less than 3 deg OUT: Disables MLC filter
Vc Switch	Changes closure rate DDD scale • X-4: -800 to 4000 knots • NORM: -200 to 1000 knots • VID: -50 to 250 knots
ASPECT Switch	Changes closure rate processing scale NOSE: -600 to 1800 knots BEAM: -1200 to 1200 knots TAIL: -1800 to 600 knots



	Look Angle	Line of Sight Rate	Target Heading
1	60 deg	1490	180 deg
2	45 deg	1500	120 deg
3	30 deg	1428	100 deg
4	0 deg	1200	90 deg
5	30 deg	672	80 deg
6	45 deg	210	60 deg
7	60 deg	-300	0 deg

3.6 PULSE DOPPLER MODE - RWS

 Range While Search 	FM Ranging, used for getting good A/A picture before selecting TWS • FM Ranging
	 Pulse Doppler with ranging TID shows momentary tracks with ranges Processing reduces max range
	Advantages
	Long RangeDoppler Filtering"Look Down Shoot Down"Signal Processing
	 Disadvantages
	 Can be notched
• DDD	 Closure Rate/Azimuth Visual representation of radar and erase sweeps
• TID	 Momentary Tracks Max concurrent tracks: 48 Cannot lock targets from TID
• Filtering	Same as Pulse Doppler Search

3.7 PULSE DOPPLER MODE - TWS

Track While Scan	Builds Track Files, high situational awareness, multi-target AIM-54 launch • Track Files
	 AWG-9 builds Trackfiles for contacts Can launch multiple AIM-54 Processing reduces max range Can lock targets from TID
	FM Ranging
	 Pulse Doppler with ranging TID shows momentary tracks with ranges Processing reduces max range
	Advantages
	Doppler FilteringMulti-Target AIM-54
	 Disadvantages
	Lowest RangeCan be notched
• DDD	 Closure Rate/Azimuth Visual representation of radar and erase sweeps
• TID	TracksfilesMax concurrent tracks: 24Max displayed tracks: 18
• Filtering	Same as Pulse Doppler Search
Scan Volume	Trackfiles require update every 2.5 s -> • 20 deg 4 bar (if selected) • 40 deg 2 bar (else)
TID Mode Selector	 GND STAB: Ground Stabilized, True North is up on TID A/C STAB: Aircraft Stabilized ATTAK: same as A/C STAB with superimposed attack steering symbology TV: Displays TCS on TID, dispays LANTIRN on TID if equipped

AWG-9 RADAR	F-14A/B REV: 2021052
TID Display Selector Buttons	 RID DISABLE: Not simulated ALT NUM: Enables display of track altitudes on left side of track symbols SYM ELEM: Enables display of all supplementary symbology of tracks and waypoints DATA LINK: Enables display of D/L contacts JAM STROBE: Enables display of jam strobes NON-ATTK: enables/disables display of targets not possible to engage (friendlies) LAUNCH ZONE: Enables display of weapon launch zones VEL VECTOR: Enables display of velocity vectors
Track Hold & Col-	• TRACK HOLD
lision Steering	 Normally: Tracks maintained for 14 s after last observation Track Hold: maintained for 2 min after last observation
	CLSN Button
	 begins collision steering to cur- rently tracked target enables Steering Centroid if in

enables Steering Centroid if in

- **TWS** - LD CLSN presents azimuth steer-
- ing only
- CLSN presents both azimuth and elevation steering
- TWS MAN: Manual azimuth/elevation control, target designation by RIO
- TWS AUTO: Automatic prioritization of targets and azimuth elevation control

3.8 PULSE DOPPLER MODE - TWS MAN

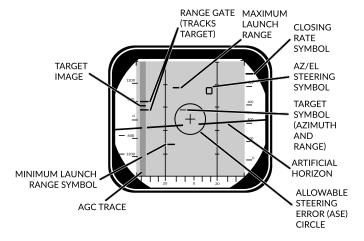
• TWS MAN	Target Selection: ManualScan Azimuth/Elevation: Manual
Target Selection	Conditions
	TWS MAN Radar Mode selectedTID CURSOR TID Mode selected
	 Hook Target
	(a) Hold HCU Half-Action(b) Slew TID Cursor over desired Tgt(c) HCU Full-Action to select Tgt
	 TID Symbology
	 Range (RA) Bearing (BR) Altitude (AL) Magnetic course (MC)
	 Lock Target
	(d) Press PD STT or Pulse STT but- tons
	Deselect Target
	(e) press HCU Half-Action
AIM-54 Launch	Automatically selects TWS AUTOPrevents selection of TWS MAN

AWG-9 RADAR F-14A/B REV: 20210523

3.9 PULSE DOPPLER MODE - TWS AUTO

TWS AUTOCentroid / Steer-	 Target Selection: prioritizes contacts based off range, aspect, closure Scan Azimuth/Elevation: Computed geometric center of targets in scan volume Steering Centroid
ing Cues	 facilitates steering cues HUD, VDI, TID, DDD Appears as X on TID Takes Gimbal limits into account Weights individual Tracks based on parameters
	 Illumination Centroid
	 Not Visible Controls azimuth and elevation of scan pattern Takes scan volume into account
Pilot Steering	Conditions
Cues	 A-A HUD Mode selected
	 Master Arm ON (UP)
	 AIM-54 or AIM-7 selected
	 TWS-AUTO selected

3.10 PULSE DOPPLER MODE - PDSTT



SINGLE TARGET TRACK

 Pulse STT Advantages Ground Clutter filtering Disadvantages Susceptible to notching Lock Target Conditions Pulse Doppler Mode selected (PD Search, RWS, TWS) RDR HCU Mode selected Lock Target Hold HCU Half-action Slew to desired Target HCU Full-Action to lock Unlock Target HCU Half-action Track Indications ANT TRK light RDROT light Tracking gates Closure rate Attack Symbology 		
Disadvantages Susceptible to notching Conditions Pulse Doppler Mode selected (PD Search, RWS, TWS) RDR HCU Mode selected Lock Target (a) Hold HCU Half-action (b) Slew to desired Target (c) HCU Full-Action to lock Unlock Target (d) HCU Half-action Track Indications ANT TRK light RDROT light RDROT light Tracking gates Closure rate Attack Symbology	Pulse STT	
- Susceptible to notching • Lock Target • Conditions - Pulse Doppler Mode selected (PD Search, RWS, TWS) - RDR HCU Mode selected • Lock Target (a) Hold HCU Half-action (b) Slew to desired Target (c) HCU Full-Action to lock • Unlock Target (d) HCU Half-action • DDD • Track Indications - ANT TRK light - RDROT light - Tracking gates - Closure rate - Attack Symbology		 Ground Clutter filtering
Lock Target Pulse Doppler Mode selected (PD Search, RWS, TWS) RDR HCU Mode selected Lock Target (a) Hold HCU Half-action (b) Slew to desired Target (c) HCU Full-Action to lock Unlock Target (d) HCU Half-action Track Indications ANT TRK light RDROT light Tracking gates Closure rate Attack Symbology		 Disadvantages
- Pulse Doppler Mode selected (PD Search, RWS, TWS) - RDR HCU Mode selected • Lock Target (a) Hold HCU Half-action (b) Slew to desired Target (c) HCU Full-Action to lock • Unlock Target (d) HCU Half-action • Track Indications - ANT TRK light - RDROT light - Tracking gates - Closure rate - Attack Symbology		 Susceptible to notching
Search, RWS, TWS) - RDR HCU Mode selected • Lock Target (a) Hold HCU Half-action (b) Slew to desired Target (c) HCU Full-Action to lock • Unlock Target (d) HCU Half-action • DDD • Track Indications - ANT TRK light - RDROT light - Tracking gates - Closure rate - Attack Symbology	 Lock Target 	Conditions
(a) Hold HCU Half-action (b) Slew to desired Target (c) HCU Full-Action to lock • Unlock Target (d) HCU Half-action • Track Indications - ANT TRK light - RDROT light - Tracking gates - Closure rate - Attack Symbology		Search, RWS, TWS)
(b) Slew to desired Target (c) HCU Full-Action to lock • Unlock Target (d) HCU Half-action • Track Indications - ANT TRK light - RDROT light - Tracking gates - Closure rate - Attack Symbology		Lock Target
(d) HCU Half-action Track Indications ANT TRK light RDROT light Tracking gates Closure rate Attack Symbology		(b) Slew to desired Target
Track Indications ANT TRK light RDROT light Tracking gates Closure rate Attack Symbology		 Unlock Target
 ANT TRK light RDROT light Tracking gates Closure rate Attack Symbology 		(d) HCU Half-action
 RDROT light Tracking gates Closure rate Attack Symbology 	• DDD	 Track Indications
		– RDROT light– Tracking gates

3.11 ACM MODES - OVERVIEW

3.12 ACM MODES - PLM

3.13 ACM MODES - VSL

3.14 ACM MODES - PAL

3.15 ACM MODES - MRL

3.16 TID SYMBOLOGY

GENERAL		
Center Dot		
Own AC		
TID Cursor		
TWS Steering Centroid	$ \times $	
ONBOARD SENSORS		
Unknown		
Hostile	🔨	
Friend	(·•)	
Angle-Tracked Radar Target	<u> </u>	
Angle-Tracked Radar Target with Altitude Difference Ranging		
TCS-Angle Tracked Target	•>	
TCS-Angle Tracked Target with Altitude Difference Ranging		
D/L TARGETS		
Unknown		
Hostile	🛂	
Friendly		

MANUAL REF POINTS

MANUAL REF POINTS	
Home base	•
Waypoint	·
Defended Point	
Fixed Point	\times
Hostile Area	
Surface Target	$ \bigoplus$
IP	
D/L REF POINTS	
Home Base	
Waypoint	1
Data Link Fixed Point	X
Surface Target	
POS SYMB MODIFIERS	
Mandatory Attack	
Data Link Destroy	
Do Not Attack	
Multiple Targets	$\langle \stackrel{\circ}{\downarrow} \rangle$
Data Link Challenge	
Track Extrapolated	

Altitude Numerics	4/^	
Firing Order Numerics	1,4,4	
Time-to-Impact (TTI)	^ <u>`</u> \ 6	
Velocity Vector		
Launch Zone Vectors		
Jamming Strobe		
Radar Antenna Scan Pattern Azimuth Lim- its	X-Y-)	
Data Link Jamming Strobe		
Data Link Pointer		
Data Link Priority Kill		
ATTACK DISPLAY SYMB		
Artificial Horizon		
Steering Guidance Symbol		
Allowable Steering Error Circle		
Breakaway Indication	$ \times $	

LANTIRN

- **UNGUIDED BOMB CCIP** 6.1
- 6.2 UNGUIDED BOMB CCRP
- 6.3 ZUNI ROCKETS
- 6.4 M61 GUN
- 6.5 TCS
- 6.6 GBU-12 PAVEWAY II
- 6.7 TALD DECOYS

A/A WEAPONS

- M61 GUN (MANUAL) 7.1
- M61 GUN (RTGS/NO RADAR) 7.2
- M61 GUN (RADAR) 7.3
- AIM-9 SIDEWINDER (SIL) 7.4
- AIM-9 SIDEWINDER (RADAR) 7.5
- **AIM-7 SPARROW** 7.6
- AIM-54 PHOENIX (SINGLE) 7.7
- **AIM-54 PHOENIX (MULTI)** 7.8

