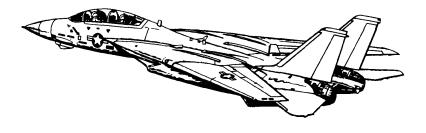
Pocket Checklist

F-14A/B AIRCRAFT

REV: 20210819



Procedures

Systems

AWG-9 Radar

TCS LANTIRN

A/G Weapons

A/A Weapons



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PROCEDURES

1.1 PILOT - PRE-START

| 1. | Parking Break | ENGAGED | |
|-----|-------------------------|--|--|
| 2. | Ground Power | connected | |
| 3. | Compressed Air | connected | |
| 4. | ICS | HOT MIC | |
| 5. | TO RIO | "Begin Start-Up" | |
| 6. | ICS | Comm Check | |
| 7. | MASTER TEST Selector | (a) LTS Warning Lights Caution Lights Checked Advisory Lights Checked (b) FIRE DET/EXT L FIRE GO illuminated R FIRE GO illuminated (c) INST RPM EGT 96% EGT FF 10500 pph AOA 18 ± 5 Wing Sweep 45 ± 2.5 | |
| | | • FUEL QTY | |
| 8. | Ejection Seat | Armed | |
| 9. | RIO | Canopy Closed | |
| 10. | Oxygen | ON (FWD) | |
| 11 | Emergency Wing Sweep | OVERSWEEP | |

PILOT - ENGINE START

| 1. | AIR SOURCE | OFF |
|-----|--------------------------|--|
| 2. | Hydraulics | (a) HYD TRANSFER PUMP SHUTOFF (b) Emerg. Hyd AUTO (LOW) |
| 3. | L&R MASTER GEN | NORM |
| 4. | RIO | "Ready to Start" |
| 5. | Right Engine Start-Up | (a) Engine Crank R (b) R Eng N2 20% (c) R Throttle IDLE (d) TIT < 890 C during start |
| 6. | Stabilized Parameters | RPM |
| 7. | Left Engine Start- Up | (a) Engine Crank L (b) L Eng N2 20% (c) L Throttle IDLE (d) TIT < 890 C during start |
| 8. | Stabilized Parameters | • RPM |
| 9. | HYD TRANSFER PUMP | NORM |
| 10. | HYD PRESSURE | 3000 psi |
| 11. | AIR SOURCE | BOTH ENG |
| 12. | Ground Power | disconnected |
| 13. | Compressed Air | disconnected |

1.3 PILOT - POST-START

| 1. | TO RIO | "Both Engines Running" | |
|-----|------------------------------|--|--|
| 2. | Displays Control Panel | • VDI ON • HUD ON • HSD ON • HDS MODE TID (monitor INS) | |
| 3. | RIO | Select Align Quality INS GO NOW: shortest but least precise alignment INS GO COARSE: does not meet Launch Criteria for AIM-7 / AIM-54 INS GO MIN WPN LAUNCH: allows AIM-7 / AIM-54 launch INS GO FINE fine align (8 min) | |
| 4. | ACM Panel | • GUN RATE | |
| 5. | Gun Rounds | Set | |
| 6. | ANTI-SKID SPOILER BK | OFF | |
| 7. | Emergency Wing Sweep | (a) Handle | |
| 8. | AFCS Panel - SAS STAB AUG | • PITCH | |
| 9. | WING/EXT TRANS | AUTO | |
| 10. | UHF 1 Function Selector | ВОТН | |
| 11. | TACAN Function Selector | T/R | |
| 12. | ARA-63 ICLS RE- CEIVER | ON | |

| PROCEDURES | F-14A/B | REV: 20210819 | |
|------------|---------|---------------|--|
| | | | |

| 13. | Radar Altimeter | (a) Control Knob one click CW to turn on (b) Display 6000 ft (warm up) (c) Display 0 ft (ready) | | |
|-----|------------------|---|--|--|
| 14. | Standby ADI | erect at least 2 min before T/O | | |
| 15. | KY-28 Crypt. Key | Set (refer to GROUND SETTINGS kb) | | |
| 16. | RIO | set D/L frequency | | |
| 17. | Lights | As desired | | |

1.4 RIO - PRE-START

| 1. | Oxygen | ON (FWD) | |
|----|-----------------------|---|--|
| 2. | PILOT | • Ground Power connected • Compressed Air connected | |
| 3. | ICS | Comm Check | |
| 4. | Lights | As required | |
| 5. | LTS Test | Coordinate with Pilot | |
| 6. | Ejection Seats | ARMED | |
| 7. | Canopy | CLOSED | |
| 8. | TO PILOT | "Ready to Start" | |

1.5 RIO - POST-START - SHORE

| 5. | U/VHF Mode | T/R G |
|-----|----------------------|---|
| | | (d) CAP MESSAGE MAG HDG VAR (e) Keyboard HDG, mag var, ENTER (f) Align Progress Monitor |
| | | CLEAR, LAT, latitude, ENTER LONG, longitude, ENTER ALT, altitude, ENTER |
| | | (c) Keyboard |
| | | Category NAV MESSAGE OWN AC |
| 4. | Start INS Align | (a) Nav Mode GND ALIGN (b) CAP |
| WAI | RNING Input Coords B | EFORE selecting GND ALIGN if using ASH |
| 3. | Kneeboard | Retrieve Coordinates, Elevation, Magnetic Variation from GROUND SETTINGS Page |
| | | (d) TID/DDD illuminated after 40 s |
| | | (c) IR/TV Power STBY/IR/TV |
| ۷. | INS STARTUP | (a) LIQUID COOLING ON (FWD) (b) WCS Switch STANDBY |
| 2. | INS STARTUP | • AIR SOURCEBOTH ENG |
| 1. | PILOT | • Enginesstarted |

| 6. | Datalink | (a) Kneeboard TACTICAL DL (b) DL Power ON (FWD) (c) DL Mode TAC (AFT) (d) DL Freq. Set |
|-----|-----------------------|--|
| 7. | TACAN | T/R |
| 8. | RWR Panel | (a) Display Type NORM (b) PWR ON (c) TEST SPL (d) MODE LMT |
| 9. | DECM | STBY, then ACT |
| 10. | IFF | (a) MASTER |
| 11. | Altimeter | Reset |
| 12. | CAP | Enter Data (WP, FP, etc.) |
| 13. | Displays | • DDD |
| 14. | Hand Control Panel | Set |
| 15. | AN/ALE-39 | Set (as required) • AUTO (CHAFF)/MAN • MAN |
| 16. | Flare Mode | PILOT |
| 17. | Complete INS Align | Duration Full Fine |
| | | (a) Align Complete Caret → Diamond (b) NAV Mode |
| 18. | Standby ADI | Erect at least 2 min before T/O |
| 19. | TO PILOT | "Ready to Taxi" |
| Onc | e Airborne | |
| 20. | IR/TV Power | ON |
| 21. | WCS Switch | WCS XMT |

1.6 RIO - POST-START - CARRIER

| 1. | PILOT | • Engines started • AIR SOURCE |
|-----|-----------------------|--|
| 2. | INS STARTUP | (a) LIQUID COOLING ON (FWD) (b) WCS Switch STANDBY (c) IR/TV Power STBY/IR/TV (d) TID/DDD illuminated after 40 s |
| 3. | Datalink | (a) Kneeboard |
| 4. | Start INS Align | (a) DL FREQ Set (b) DL Mode CAINS/WAYPT (c) Nav Mode CVA |
| 5. | U/VHF Mode | T/R G |
| 6. | TACAN | T/R |
| 7. | RWR Panel | (a) Display Type NORM (b) PWR ON (c) TEST SPL (d) MODE LMT |
| 8. | DECM | STBY, then ACT |
| 9. | IFF | (a) MASTER |
| 10. | Altimeter | Reset |
| 11. | CAP | Enter Data (WP, FP, etc.) |
| 12. | Displays | • DDD |
| 13. | Hand Control Panel | Set |
| 14. | AN/ALE-39 | Set (as required) • AUTO (CHAFF)/MAN • MAN |
| 15. | Flare Mode | PILOT |
| 16. | Complete INS Align | Duration Full Fine |

| PR | OCEDURES | F-14A/B | REV: 20210819 |
|---------|-------------|---------------------------------------|---------------|
| 17. | Datalink | \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ | TAC (AFT) |
| 18. | Standby ADI | Erect at least 2 min bet | fore T/O |
| 19. | TO PILOT | "Ready to Taxi" | |

| | (b) DL Freq. Set |
|---------------------|---------------------------------|
| 18. Standby ADI | Erect at least 2 min before T/O |
| 19. TO PILOT | "Ready to Taxi" |
| Once Airborne | |
| 20. IR/TV Power | ON |
| 21. WCS Switch | WCS XMT |
| | |

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1.7 PRE-TAXI

| 1. | ANTI-SKID SPOILER BK | OFF |
|----|-------------------------|---------------|
| 2. | HOOK BYPASS | As Required |
| 3. | Nose Strut | RETRACTED |
| 4. | HUD MODE | ТО |
| 5. | Parking Brake | Released (IN) |
| 6. | NWS | ENGAGED |
| 7. | Path | verify clear |

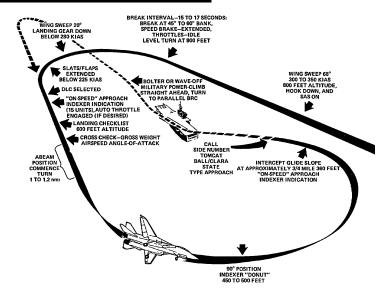
1.8 TAKEOFF - SHORE

| | | After Lining Up On Runway |
|----|-------------------------|--|
| 1. | Wing Sweep | (a) EM WING SWEEP FWD, then IN (b) MASTER RESET PRESS (c) Wings Verify thumb controller (d) WING SWEEP AUTO (e) Wings Verify at 20 deg |
| 2. | ANTI SKID SPOILER BK | BOTH (UP) |
| 3. | FLAPS | UP |
| 4. | Trim | 0 deg |
| 5. | NWS | DISENGAGED |
| 6. | Takeoff | (a) Throttle MIL (90% RPM) (b) Stick Back at 130 KIAS (c) Rotation approx 140 KIAS (d) GEAR UP < 250 KIAS |

1.9 TAKEOFF - CARRIER

| | Lineup | Wait behind JBD until Catapult is clear Follow Taxi Directors Instructions to line up on Catapult |
|----|---------------------------|--|
| 1. | Wing Sweep | (a) EM WING SWEEP FWD, then IN (b) MASTER RESET PRESS (c) Wings Verify thumb controller (d) WING SWEEP AUTO (e) Wings Verify at 20 deg |
| 2. | FLAPS | DOWN |
| 3. | Launch Bar Preparation | (a) Nose Strut KNEEL when directed (b) Throttle UP when directed (c) Taxi launch bar into shuttle (d) Throttle IDLE when directed |
| 4. | Trim | 2-3 deg nose up |
| 5. | Speed Brakes | IN |
| 6. | Final Checks | (a) ThrottleMIL when directed (b) Control Wipeout |
| | | Stick Full Forward Stick Full Aft Stick Full Left Stick Full Right Rudder Full Left Rudder Full Right |
| | | (c) Eng. Inst |
| 7. | Catapult Shot | (a) Salute CAT SHOT (b) Gear UP < 250 KIAS |
| 8. | Clearing Turn | |

1.10 LANDING - OVERHEAD PATTERN



| 1. | Initial Approach | WING SWEEP68 deg |
|----|------------------|--------------------------------|
| | | • HOOKDOWN |
| | | • SASON |
| | | • HUDLDG |
| | | Airspeed300-350 KIAS |
| | | • Altitude800 ft |
| 2. | Initial Break | • Break Interval 15-17 s |
| | | • BANK 45-60 deg |
| | | SPEED BRAKE EXTEND |
| | | ThrottleIDLE |
| | | • G 3-4 G |
| | | • Altitude800 ft |
| 3. | Break Turn | • Wing Sweep AUTO < 280 KIAS |
| | | • Landing Gear DOWN < 280 KIAS |
| | | • FLAPS DOWN < 225 KIAS |
| 4. | Downwind | DLC Selected once flaps out |
| | | • AOA ON-SPEED |
| | | LANDING CHECKLIST |
| | | Altitudedescend to 600 ft |

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| 5. | Final Turn | 180 Deg Position • Abeam Pos | 1-1.2 nmi |
|----|-------------------|-------------------------------|------------|
| | | • AOA | DONUT |
| | | Altitude | 400-500 ft |
| 6. | Intercept Glides- | Distance | 3/4 Mile |
| | lope | Altitude | 360 ft |
| | | • AOA | ON-SPEED |

1.11 LANDING - CHECKLIST

| 1. | Wing Sweep | 20 deg AUTO |
|-----|-------------|--|
| 2. | Wheels | • Lights 3 DOWN • Transition Light OUT |
| 3. | SAS | ON |
| 4. | FLAPS | DOWN |
| 5. | DLC | Checked |
| 6. | Hook | HOOKDOWN Transition LightOUT |
| 7. | Harness | Locked |
| 8. | Speedbrakes | EXT |
| 9. | Brakes | Check |
| 10. | Fuel | Check |

1.12 AIRSTART

| • Spooldown | Before significant spooldown (a) Non-Running ENGIDLE or above If no relight occurs (b) Non-Running ENG OFF then IDLE If still no relight occurs (c) ENG MODE |
|---------------------|--|
| Cross-Bleed Restart | With one ENG running, if Spooldown fails (a) Non-Running ENG OFF (b) FUEL SHUT OFF check (c) Running throttle 80%+ (d) BACK UP IGNITION ON (e) ENG CRANK non-running eng (f) Non-Running ENG IDLE If no start occurs (g) Non-Running ENG OFF then IDLE If still no start (h) ENG MODE SEC (i) Non-Running ENG OFF then IDLE |
| Windmill Restart | (a) Airspeed |
| Post Restart | (a) BACK UP IGNITION OFF (b) ENG MODE PRI |

SYSTEMS

2.1 AFCS - SAS

| • | SAS | Stability Augmentation System |
|---|---------------------------|---|
| | | Not Fly-by-Wire Automatic control surface commands generated by analog computer to im- |
| | | prove stability |
| • | Control | Three individual channels (Pitch, Roll, Yaw) |
| • | Autopilot Emer- | Paddle on Stick |
| | gency Disengage Paddle | Disengages Autopilot ModesDeactivates Pitch, Roll SAS Channels |

2.2 AFCS - AUTOPILOT

| Attitude Hold | Basic Attitude Hold |
|-----------------------------------|--|
| | Maintains existing pitch & roll |
| | Attitude can be changed with stick input If engaged outside limits will automati- |
| | cally move within range |
| | • Limits |
| | - Pitch: 30 deg |
| | - Roll: 60 deg |
| | Engagement |
| | (a) SAS Switches ON (FWD) |
| | (b) Alt. Hold Mode OFF |
| | (c) VEC/PCD/ACLOFF |
| | (d) Heading ModeOFF |
| | (e) Autopilot Switch ENGAGE (FWD) |

| Altitude Hold | Barometric Altitude Hold |
|-----------------------------------|---|
| | Maintains current barometric altitude |
| | • Limits |
| | Vertical velocity: < 100 ft/s |
| | Engagement |
| | (a) SAS Switches |
| Heading Hold | Magnetic Heading Hold |
| | Maintains current magneatic heading |
| | • Limits |
| | Bank angle < 5 deg |
| | Engagement |
| | (a) SAS Switches ON (FWD) (b) Autopilot Switch ENGAGE (FWD) (c) Heading Mode HDG (FWD) |
| Ground Track | Autopilot follows ground track |
| | Similar to heading hold |
| | Compensates for wind drift |
| | Uses INS data instead of magnetic bearing |
| | • Limits |
| | Bank angle < 5 deg |
| | • Engagement |
| | (a) SAS Switches |
| • VEC/PCD | Datalink Vector / Precision Course Direction |
| | Allows Link 4 controller to remotely direct the aircraft Not Modelled in DCS |
| | |

| S | STEMS | F-14A/B REV: 20210819 |
|------------|-----------------------------|---|
| • | ACL | Automatic Carrier Landing |
| | | See relevant section |
| • | Autopilot Emer- | Paddle on Stick |
| | gency Disengage | Disengages Autopilot Modes |
| | Paddle | - Deactivates Pitch, Roll SAS Channels |
| 2.3 | APC / AUTOTHROT | TLE |
| • | APC | Approach Power Compensator |
| | | Automatic throttle control |
| - | | Maintains ON SPEED AoA |
| • | Conditions | Engagement is inhibited / APC is disengaged if |
| | | conditions not met • Throttles |
| | | Landing Gear Handle Down |
| | | Weight on Wheels No |
| • | Engage | Throttle Mode AUTO (FWD) |
| • | | |
| 2.4 2.5 | Disengage ACLS WING-SWEEP | Cage/Seam Button |
| 2.4 | ACLS | In Flight Limited between 20 deg & 68 deg |
| 2.4 | ACLS WING-SWEEP | |
| 2.4 | ACLS WING-SWEEP | In Flight Limited between 20 deg & 68 deg On Ground can Oversweep to 75 deg |
| 2.4 | ACLS WING-SWEEP | In Flight Limited between 20 deg & 68 deg On Ground can Oversweep to 75 deg Hydromechanically Controlled |
| 2.4 | ACLS WING-SWEEP | In Flight Limited between 20 deg & 68 deg On Ground can Oversweep to 75 deg Hydromechanically Controlled Automatically through CADC Manually with emergency wing-sweep |
| 2.4 | ACLS WING-SWEEP | In Flight Limited between 20 deg & 68 deg On Ground can Oversweep to 75 deg Hydromechanically Controlled Automatically through CADC Manually with emergency wing-sweep handle 15 deg / s at 1 g loading |
| 2.4 | ACLS WING-SWEEP Overview | In Flight Limited between 20 deg & 68 deg On Ground can Oversweep to 75 deg Hydromechanically Controlled Automatically through CADC Manually with emergency wing-sweep handle 15 deg / s at 1 g loading Mechanically linked to ensure symmetry |
| 2.4 | ACLS WING-SWEEP Overview | In Flight Limited between 20 deg & 68 deg On Ground can Oversweep to 75 deg Hydromechanically Controlled Automatically through CADC Manually with emergency wing-sweep handle 15 deg / s at 1 g loading Mechanically linked to ensure symmetry AUTO CADC controls wing position as function |
| 2.4 | ACLS WING-SWEEP Overview | In Flight Limited between 20 deg & 68 deg On Ground can Oversweep to 75 deg Hydromechanically Controlled Automatically through CADC Manually with emergency wing-sweep handle 15 deg / s at 1 g loading Mechanically linked to ensure symmetry AUTO CADC controls wing position as function of current Mach via wing-sweep program |
| 2.4 | ACLS WING-SWEEP Overview | In Flight Limited between 20 deg & 68 deg On Ground can Oversweep to 75 deg Hydromechanically Controlled Automatically through CADC Manually with emergency wing-sweep handle 15 deg / s at 1 g loading Mechanically linked to ensure symmetry AUTO CADC controls wing position as function of current Mach via wing-sweep program MAN Pilot manually chooses desired wing |
| 2.4 | ACLS WING-SWEEP Overview | In Flight Limited between 20 deg & 68 deg On Ground can Oversweep to 75 deg Hydromechanically Controlled Automatically through CADC Manually with emergency wing-sweep handle 15 deg / s at 1 g loading Mechanically linked to ensure symmetry AUTO CADC controls wing position as function of current Mach via wing-sweep program MAN Pilot manually chooses desired wing sweep angle with thumb controller |

| • Emergency Mode | Emergency Wing-Sweep Handle |
|-------------------------------|--|
| | Moved with wing sweep program by spi- |
| | der detent under normal operation |
| | Can be forced out of spider detent and |
| | moved manually |
| Oversweep | Selected via Emergency Wing-Sweep Han- dle |
| | (a) Em. Wing-Sweep |
| | (b) HZ TAIL AUTHIlluminated |
| | (c) Em. Wing-Sweep |
| Return to CADC | After Emergency Mode / Oversweep |
| Control | (a) Em. Wing-SweepSpider Detent |
| | (Fwd on startup) |
| | (b) MASTER RESET Press |

| Indicated Mach | Max Forward Wing Position |
|----------------|---------------------------|
| 0.4 | 20 deg |
| 0.7 | 25 deg |
| 0.8 | 50 deg |
| 0.9 | 60 deg |
| 1.0 | 68 deg |

- 2.6 NAVIGATION
- 2.7 COMMUNICATION
- 2.8 DATALINK / IFF

2.9 RWR THREAT SYMBOLOGY

| | SHIPS | |
|----------|--|--|
| AB | Arleigh Burke | |
| AK | Admiral Kuznetsov | |
| GR | Grisha 5 (Albatros) | |
| HP | Oliver Hazard Perry | |
| J2 | Type 054A Frigate, "Jiangkai II class" | |
| KK | Krivak 3 (Rezky) | |
| ΚV | Kirov (Pyotr Velikiy) | |
| L1 | Type 052B Destroyer, "Luyang I class" | |
| L2 | Type 052C Destroyer, "Luyang II class" | |
| N | Ship with Nav Radar | |
| NE | Neustrashimy | |
| NZ | Nimitz (Vinson, Stennis) | |
| SV | Slava (Moscow) | |
| TC | Ticonderoga | |
| TT | Tarantul 3 (Molniya) | |
| TW | Tarawa | |
| YU | Type 071 Amphibious Transport Dock, "Yuzhao class" | |
| AIRCRAFT | | |
| 14 | F-14A/B | |
| 15 | F-15C/E | |
| 16 | F-16C | |
| 17 | JF-17 | |
| 18 | F/A-18C | |
| 19 | | |

| 21 | MiG-21bis |
|------------|--|
| 23 | MiG-23MLD |
| 24 | Su-24M/MR |
| 25 | MiG-25PD |
| 29 | MiG-29A/G/S Su-27 Su-33 J-11A |
| 30 | Su-30 |
| 31 | MiG-31 |
| 34 | Su-34 |
| 37 | AJS-37 |
| 39 | Su-25TM |
| 50 | A-50 |
| 52 | B-52 |
| AN | AN-26B AN-30M |
| AP | AH-64D |
| B1 | B-1B |
| BE | Tu-95 Tu-142M |
| BF | Tu-22M3 |
| BJ | Tu-160 |
| E2 | E-2D |
| E 3 | E-3C |
| F4 | F-4E |
| F5 | F-5E |
| НХ | Ka-27 |
| IL | IL-76MD IL-78M |
| KC | KC-135 |
| | |

| KJ | KJ-2000 |
|-----|---|
| M2 | Mirage 2000-C Mirage 2000-5 |
| S3 | S-3B |
| SH | SH-60B |
| ТО | Tornado |
| TR | C-130 C-17A |
| | AIR DEFENSE |
| 2 | S-75 TR SNR (SA-2) "Fan Song" |
| 3 | S-125 TR SNR-125 (SA- 3) "Low Blow" |
| 6 | Kub SA-6 |
| 7 | HQ-7 TR |
| 8 | OSA (SA-8) |
| 10 | S-300PS 30N6 TR (SA- 10) |
| _11 | Buk (SA-11) |
| 12 | S-300V |
| 15 | Tor 9A331 (SA-15) |
| 19 | Tunguska 2C6M (SA-19) |
| Α | Gepard M-163 Vulcan ZSU-23-4 Shilka |
| ВВ | S-300PS 64H6E SR (SA- 10/Big Bird) |
| BF | Rapier Blindfire TR |
| CS | S-300PS 5N66M SR (SA-10/Clam Shell) |
| DE | Sborka (Dog Ear) |
| FF | S-125 P-19 SR (SA- 3/Flat Face) |
| GR | Roland SR |

| НА | Hawk SR |
|-----|---|
| HK | Hawk TR |
| HQ | HQ-7 SR |
| PT | Patriot |
| RO | Roland |
| RP | Rapier SR |
| S | 1L13 55G6 EWR |
| SD | Buk TR (SA-11/Snow Drift) |
| SN | PRW-11 (Side Net) |
| | MISSILES |
| M | AIM-54 AIM-120 MICA-EM R-37 R-77 SD-10 |
| ATC | |
| Т | Airport ATC Radar |
| | |

AWG-9 RADAR

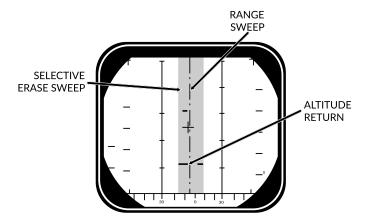
MAIN MODES - OVERVIEW

| | Pulse | | Pulse Doppler | | | |
|--------|-----------------|-------|---------------|-------|--------------|--------|
| | Pulse Search | P-STT | PD Search | RWS | TWS | PD-STT |
| Range | 60 nm | 50 nm | 110 nm | 90 nm | 90 nm | 90 nm |
| AIM-7 | BRSIT | CW | BRS | SIT | - | PD |
| AIM-54 | BRSIT | ACT | BRS | SIT | Multi TGT | PD/ACT |

MAIN MODES

| • Pulse | Basic Pulse w/o doppler filtering |
|-----------------------------------|--|
| | Cannot be notchedGround ClutterRudimentary Ground mapping |
| | Pulse Sub-Modes |
| | Pulse SearchPulse-STT |
| Pulse Doppler | Doppler filter -> no ground returns |
| | Susceptible to notching No ground clutter Greater range Advanced sub modes AIM-54 Guidance |
| | Pulse Doppler Sub-Modes |
| | PD SearchRWSTWSPD-STT |

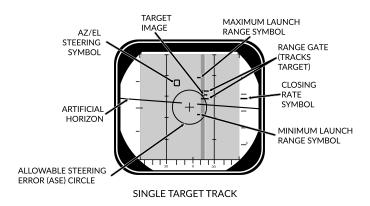
PULSE MODE - PULSE SEARCH 3.3



SEARCH (±10° SCAN)

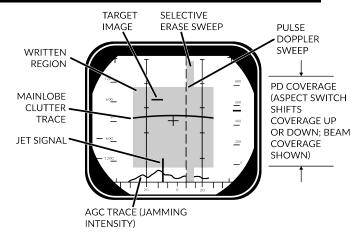
| Pulse Search | Basic Mode, AWG-9 does not use pulse doppler filtering • Advantages |
|--------------|--|
| | All aspect target detection Cannot be notched Rudimentary ground mapping |
| | Disadvantages |
| | Cannot discern ground returns and targetsLower range |
| • DDD | Range/Azimuth |
| | Visual representation of radar and erase sweeps |
| • TID | No Information from Pulse Cannot guide AIM-54 |

3.4 PULSE MODE - PSTT



| Pulse STT | Lock Target w/o doppler filtering |
|---------------------------------|--|
| | Advantages |
| | Cannot be notched |
| | Disadvantages |
| | Susceptible to ground clutter |
| Lock Target | Conditions |
| | Pulse Search Mode selectedRDR HCU Mode selected |
| | Lock Target |
| | (a) Hold HCU Half-action |
| | (b) Slew to desired Target |
| | (c) HCU Full-Action to lock |
| | Unlock Target |
| | (d) HCU Half-action |
| • DDD | Track Indications |
| | ANT TRK light |
| | RDROT light |
| | Tracking gates |
| | Closure rate |
| | Attack Symbology |

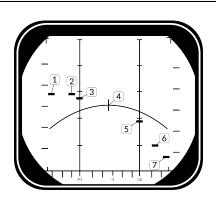
3.5 PULSE DOPPLER MODE - PULSE DOPPLER SEARCH



SEARCH (±40° SCAN)

| Pulse Doppler Search | "Early Warning" Mode, Longest Range, cannot display rangeAdvantages |
|--|---|
| | Longest RangeDoppler Filtering"Look Down Shoot Down" |
| | Disadvantages |
| | Can be notchedNo range information |
| • DDD | Closure Rate/Azimuth Visual representation of radar and erase sweeps |
| Doppler Filters | Main Lobe Clutter (MLC) Filter |
| | Own GS +/- 133 knotsRemoves main ground returnSource of notching |
| | Zero Doppler Filter |
| | Negative own GS +/- 100 knots Removes Radar reflection from ground directly beneath own AC |

| MLC Switch | IN: Enables MLC filter AUTO: Enables MLC filter if look-up angle less than 3 deg OUT: Disables MLC filter |
|---------------|---|
| Vc Switch | Changes closure rate DDD scale • X-4: -800 to 4000 knots • NORM: -200 to 1000 knots • VID: -50 to 250 knots |
| ASPECT Switch | Changes closure rate processing scale NOSE: -600 to 1800 knots BEAM: -1200 to 1200 knots TAIL: -1800 to 600 knots |



| | Look Angle | Line of Sight Rate | Target Heading |
|---|------------|--------------------|----------------|
| 1 | 60 deg | 1490 | 180 deg |
| 2 | 45 deg | 1500 | 120 deg |
| 3 | 30 deg | 1428 | 100 deg |
| 4 | 0 deg | 1200 | 90 deg |
| 5 | 30 deg | 672 | 80 deg |
| 6 | 45 deg | 210 | 60 deg |
| 7 | 60 deg | -300 | 0 deg |

3.6 PULSE DOPPLER MODE - RWS

| Range While Search | FM Ranging, used for getting good A/A picture before selecting TWS • FM Ranging |
|--------------------|--|
| | Pulse Doppler with ranging TID shows momentary tracks with ranges Processing reduces max range |
| | Advantages |
| | Long RangeDoppler Filtering"Look Down Shoot Down"Signal Processing |
| | Disadvantages |
| | Can be notched |
| • DDD | Closure Rate/Azimuth Visual representation of radar and erase sweeps |
| • TID | Momentary Tracks Max concurrent tracks: 48 Cannot lock targets from TID |
| • Filtering | Same as Pulse Doppler Search |

3.7 PULSE DOPPLER MODE - TWS

| Track While Scan | Builds Track Files, high situational awareness, multi-target AIM-54 launch • Track Files |
|-------------------|---|
| | AWG-9 builds Trackfiles for contacts Can launch multiple AIM-54 Processing reduces max range Can lock targets from TID |
| | FM Ranging |
| | Pulse Doppler with ranging TID shows momentary tracks with ranges Processing reduces max range |
| | Advantages |
| | Doppler FilteringMulti-Target AIM-54 |
| | Disadvantages |
| | Lowest RangeCan be notched |
| • DDD | Closure Rate/Azimuth Visual representation of radar and erase sweeps |
| • TID | Tracksfiles |
| | Max concurrent tracks: 24 |
| Pitta autorio | Max displayed tracks: 18 |
| • Filtering | Same as Pulse Doppler Search |
| Scan Volume | Trackfiles require update every 2.5 s -> • 20 deg 4 bar (if selected) • 40 deg 2 bar (else) |
| TID Mode Selector | GND STAB: Ground Stabilized, True North is up on TID A/C STAB: Aircraft Stabilized ATTAK: same as A/C STAB with superimposed attack steering symbology TV: Displays TCS on TID, dispays LANTIRN on TID if equipped |

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|--|
| RID DISABLE: Not simulated ALT NUM: Enables display of track altitudes on left side of track symbols SYM ELEM: Enables display of all supplementary symbology of tracks and waypoints DATA LINK: Enables display of D/L contacts JAM STROBE: Enables display of jam strobes NON-ATTK: enables/disables display of targets not possible to engage (friendlies) LAUNCH ZONE: Enables display of weapon launch zones VEL VECTOR: Enables display of velocity vectors TRACK HOLD |
| Normally: Tracks maintained for 14 s after last observation Track Hold: maintained for 2 min after last observation CLSN Button |
| begins collision steering to currently |
| tracked target - enables Steering Centroid if in TWS - LD CLSN presents azimuth steering only - CLSN presents both azimuth and elevation steering |
| TWS MAN: Manual azimuth/elevation control, towart designation by PIO |
| target designation by RIOTWS AUTO: Automatic prioritization of targets and azimuth elevation control |
| |

3.8 PULSE DOPPLER MODE - TWS MAN

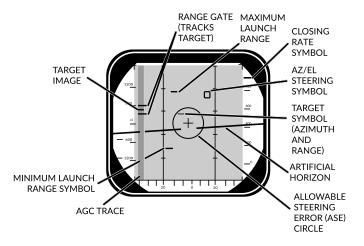
| • TWS MAN | Target Selection: Manual |
|--------------------------------------|---|
| | Scan Azimuth/Elevation: Manual |
| Target Selection | • Conditions |
| | TWS MAN Radar Mode selected |
| | TID CURSOR TID Mode selected |
| | Hook Target |
| | (a) Hold HCU Half-Action |
| | (b) Slew TID Cursor over desired Tgt |
| | (c) HCU Full-Action to select Tgt |
| | TID Symbology |
| | - Range (RA) |
| | Bearing (BR) |
| | Altitude (AL) |
| | – Magnetic course (MC) |
| | Lock Target |
| | (d) Press PD STT or Pulse STT buttons |
| | Deselect Target |
| | (e) press HCU Half-Action |
| AIM-54 Launch | Automatically selects TWS AUTO |
| | Prevents selection of TWS MAN |

3.9 PULSE DOPPLER MODE - TWS AUTO

| TWS AUTO | Target Selection: prioritizes contacts based off range, aspect, closure Scan Azimuth/Elevation: Geometric center of targets in scan volume |
|---------------------------------------|---|
| Centroid / Steer- | Steering Centroid |
| ing Cues | facilitates steering cues HUD, VDI, TID, DDD Appears as X on TID Takes Gimbal limits into account Weights individual Tracks based on parameters |
| | Illumination Centroid |
| | Not Visible Controls azimuth and elevation of scan pattern Takes scan volume into account |
| Pilot Steering | Conditions |
| Cues | A-A HUD Mode selectedMaster Arm ON (UP)AIM-54 or AIM-7 selectedTWS-AUTO selected |

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3.10 PULSE DOPPLER MODE - PDSTT



SINGLE TARGET TRACK

| Lock Target with doppler filtering • Advantages - Ground Clutter filtering • Disadvantages |
|---|
| Ground Clutter filtering |
| • |
| Disadvantages |
| |
| Susceptible to notching |
| Conditions |
| Pulse Doppler Mode selected (PD Search, RWS, TWS) |
| RDR HCU Mode selected |
| Lock Target |
| (a) Hold HCU Half-action |
| (b) Slew to desired Target |
| (c) HCU Full-Action to lock |
| Unlock Target |
| (d) HCU Half-action |
| Track Indications |
| ANT TRK light |
| RDROT light |
| Tracking gates |
| Closure rate |
| Attack Symbology |
| _ |

3.11 ACM MODES - OVERVIEW

| | PLM | VSL | PAL | MRL |
|----------------------------|-----------|----------|------------|------|
| Range | 5 nm | 5 nm | 15 nm | 5 nm |
| Description | Boresight | Vertical | Horizontal | RIO |
| Weapons Gun + All Missiles | | | | |

| • PLM | Pilot Lockon Mode Highest Priority ACM Search Pattern - Small Boresight - Range: 5 nm |
|-------|--|
| • VSL | Vertical Scan Lockon HI Search Pattern Width: 5 deg Vertical: +15 to +55 deg Range: 5 nm |
| | LO Search Pattern Width: 5 deg Vertical: -15 to +25 deg Range: 5 nm RIO/PILOT Controlled |
| • PAL | Pilot Automatic Lockon Search Pattern Width: +/- 20 deg Vertical: 8-bar Range: 15 nm |
| • MRL | Manual Rapid Lockon RIO Controlled Search Pattern HCU Controlled Range: 5 nm |

3.12 TID SYMBOLOGY

| GENERAL | | |
|-----------------------|---------|---|
| Center Dot | • | Basic Component of Symbols |
| | | Marks coordinates of symbol |
| Own AC | | Symbol representing own aircraft |
| | | Ground Stabilized: Moves Aircraft Stabilized: Stationary Outside TID: line drawn from TID center towards symbol |
| TID Cursor | | Hook Cursor |
| | | Controlled by HCU in TID mode |
| | | Half-Action |
| | | Enables display of symbolEnables HCU stick to move cursor |
| | | • Full-Action |
| | | Hooks closest symbol If no symbol near, cursor dropped at location |
| TWS Steering Centroid | X | Steering centroid of TWS tracks |
| | | Selected by WCS for weapons engagement |
| ONBOARD SENS | ORS | Symbol Above Dot |
| Unknown | • | Unknown Sensor Track All Returns in RWS |
| Hostile | <u></u> | Sensor Track designated Hos- tile by RIO |
| Friend | • | Sensor Track designated Friendly by RIO |
| Angle-Tracked Radar | | Radar Angle Tracking |
| Target | \• | Jamming Target |

| Angle-Tracked Radar Target with Altitude Difference Ranging | \bigcirc | Radar Angle Tracking Jamming Target Alt. diff. ranging |
|---|------------|--|
| TCS-Angle Tracked Target | •> | TCS Angle Tracking |
| TCS-Angle Tracked Target with Altitude Difference Ranging | \bigcirc | TCS Angle Tracking Alt. diff. ranging |
| D/L TARGETS | S | Symbol Below Dot |
| Unknown | | D/L Track designated Un- known by Source |
| Hostile | • | D/L Track designated Hostile by Source |
| Friendly | | D/L Track designated Friendly by Source |
| MANUAL REF PO | INTS | |
| Home base | | Waypoint Representing Home Base Carrier Airfield |
| Waypoint | • | Nav Waypoint Supplanted by Number 1, 2, or 3 |
| Defended Point | | Waypoint to Defend |
| Fixed Point | \times | Generic Waypoint |
| Hostile Area | | Waypoint Indicating Hostile Area |
| Surface Target | | Waypoint Indicating Surface Target |
| IP | | Initial Point Waypoint for A/G engagement |
| D/L REF POIN | TS | |
| Home Base | | D/L Waypoint Representing Home Base |

AWG-9 RADAR REV: 20210819 Waypoint • D/L Generic Waypoint Data Link Fixed • D/L Waypoint Representing **Point Fixed Point** • D/L Waypoint Representing a Surface Target **Surface Target** POS SYMB MODIFIERS Additional Symbology on TWS Mandatory Attack **Track** - Horizontal bar through center dot Selected by RIO - Only 1 target can be designated - Guaranteed WCS priority number **Data Link Destroy** Additional Symbology on D/L **Track** - Horizontal bar through center dot Selected by Source - No effect on WCS prioritization **Do Not Attack** Additional Symbology on TWS or D/L Track Vertical bar through center dot If Set by RIO - Removes WCS prioritization **Multiple Targets** Additional Symbology on TWS or D/L Track Horizontal bar on left side of symbol • Indicates Multiple Targets

| Data Link Challenge | | Additional Symbology on D/L Track |
|----------------------|----------------|--|
| | | Small V with center at center dot |
| | | Command to Visually Identify |
| Track Extrapolated | \\ \hat{\chi}\ | Additional Symbology on TWS or D/L Track |
| | | Small X with center at center dot |
| | | No Update within 8 seconds |
| | | Track deleted after 14 seconds |
| | | Or after 2 min if track hold |
| Altitude Numerics | 4/•\ | Altitude to Nearest Ten Thousand |
| | | example: 35000-45000 |
| Firing Order Numer- | /__ | Indicates AIM-54 Prioritization |
| ics | | Numbers 1-6Only in TWS |
| Time-to-Impact (TTI) | ^\116 | After AIM-54 Launch |
| | | Prioritization replaced with estimated TTI |
| | | Flashes after Pitbull |
| Velocity Vector | | Additional Symbology from center Dot |
| | | Direction represents track heading |
| | | Length represents speed |
| | | Varies with Mode |
| | | Ground Stabilized: true heading and ground speed Aircraft Stabilized: relative heading and velocity |

| Launch Zone Vectors | | Additional Symbology for AIM-54 Selected manually by RIO Or 60 seconds from max launch TUMR Time-Until-Minimum-Range Max: 180 seconds, 1.5 inches TUOR Time-Until-Optimal-Range Start of bar is 8 seconds from optimum TUIR |
|---|------|---|
| Jamming Strobe | | Time-Until-In-RangeLine from own AC towards |
| Radar Antenna Scan Pattern Azimuth Limits | | Jammer Limits of Current Scan Azimuth Single Line in STT |
| Data Link Jamming Strobe | | Line from D/L point towards Jammer |
| Data Link Pointer | | Additional Symbology on D/L Track — Circle — Indicates operator concern |
| Data Link Priority Kill | | Additional Symbology on D/L Track Square Indicates target must be destroyed No effect on WCS prioritization |

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ATTACK DISPLAY SYMBOLOGY

| Artificial Horizon | | Represents Pitch and Roll |
|------------------------------------|---|---|
| Steering Guidance Symbol | | Represents Steering Error Should be placed as near as possible to center of ASE circle |
| Allowable Steering Error Circle | | Indicates Allowable Steering Error for Missile Launch Size Varies with Geometry, Mode, Missile |
| Breakaway Indica- tion | X | Appears when Target Range Less than Minimum for Se- lected Weapon |

TCS/ALQ-100

5 LANTIRN

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A/G WEAPONS

M61 GUN 6.1

| 1. P | ilot Conditions (a) | MASTER ARMON |
|-------------|---------------------|--|
| | (b) | HUD |
| | (c) | WEAPON SELECTORGUNS |
| | (d) | Stations verify selected |
| | (e) | Wing SweepBOMB |
| 2. E | mployment (a) | Dive |
| | (b) | Pipperon target |
| | (c) | TRIGGER FIRE |
| • N | ote: TCS • | TCS slaved to radar impact point |
| | • | Rio can select NAR or WIDE |

| 6.2 | ZUNI ROCKETS | | |
|-----|------------------|--|------------------------------|
| 1. | RIO Conditions | (a) WPN TYP (b) Attack Mode | Pilot Attack |
| | | STP-SGL single rock STP-PRS single pair RPL-SGL set numbe press RPL-PRS set numbe | per press r of rocket per |
| | | (d) Mechanical Fuze (e) Electronic Fuze (f) Delivery Options | INST |
| | | • INTERVAL | |
| | | (g) Stations | Armed |
| 2. | Pilot Conditions | (a) MASTER ARM | A/G OFF |
| | | (d) Stations | • |
| 3. | Employment | (a) Dive | 20-30 deg |

(c) TRIGGER FIRE

UNGUIDED BOMB - CCIP

| 1. RIO Conditions | (a) WPN TYP MK-82 (b) Attack Mode Pilot Attack (c) Deliver Mode STP-PRS |
|---------------------|---|
| | STP-SGL single bomb per press STP-PRS single pair per press RPL-SGL set number of bomb per press RPL-PRS set number of pairs per press |
| | (d) Mechanical Fuze NOSE (e) Electronic Fuze INST (f) Delivery Options set • INTERVAL 010 msec • QTY 01 |
| 2. Pilot Conditions | (g) Stations Armed (a) MASTER ARM ON (b) HUD A/G (c) WEAPON SELECTOR OFF (d) Stations verify selected (e) Wing Sweep BOMB |
| 3. Employment | (a) Dive 40 deg (b) Pipper on target (c) STORE RELEASE Press and Hold |

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6.4 UNGUIDED BOMB - CCRP

| 1. RIO Conditions | (a) WPN TYP MK-82 (b) Attack Mode Target Attack (c) Deliver Mode STP-PRS |
|---------------------|---|
| | STP-SGL single bomb per press STP-PRS single pair per press RPL-SGL set number of bomb per press RPL-PRS set number of pairs per press |
| | (d) Mechanical Fuze NOSE (e) Electronic Fuze INST (f) Delivery Options set |
| | • INTERVAL |
| | (g) Stations Armed |
| 2. Pilot Conditions | (a) MASTER ARM |
| | (c) WEAPON SELECTOR OFF |
| | (d) Stations verify selected |
| | (e) Wing SweepBOMB |
| 3. Designation | (a) Slew Diamond |
| 4. Employment | (a) Flight Path |
| | When Solution Cue meets Velocity Vector |
| | (c) STORE RELEASE Press and Hold |

6.5 GBU-10 / 12 / 16 / 24

| 1. LANTIRN PREP | (a) Target Pod PowerPOD |
|---------------------|---|
| | Warm up takes approx. 8 min |
| | Automatically switches to STANDBY |
| | (b) Laser Codeas desired |
| | MUST BE SET ON THE GROUND |
| | • Default: 1688 |
| | (c) LANTIRN ModeOPERATE |
| | STANDBY caution will flash for 30 s |
| | Then switches to OPER |
| | (d) VIDEO SwitchFLIR |
| | (e) TID ModeTV |
| 2. RIO Conditions | (a) WPN TYPGBU-12 |
| | (b) Attack ModeManual |
| | (c) Deliver ModeSTP-SGL |
| | STP-SGL single bomb per press |
| | STP-PRS single pair per press |
| | RPL-SGL set number of bomb per press |
| | RPL-PRS set number of pairs per press |
| | (d) Mechanical Fuze NOSE |
| | (e) Electronic FuzeINST |
| | (f) Delivery Options set (not necessary for STP-SGL) |
| | (g) StationsArmed |
| 3. Pilot Conditions | (a) MASTER ARMON |
| 5. Phot Conditions | (a) MASTER ARM |
| | (c) WEAPON SELECTOR OFF |
| | (d) VDI Mode |
| | (e) Stations verify selected |
| | (f) Wing SweepBOMB |
| 4. Slew LANTIRN | Slave to WYPTLeft-4-Way RIGHT |
| | QSNO (Snowplow) S4 HAT Down |
| | Toggle FOV LANTIRN Toggle FOV |
| | SlewLANTIRN Stick |
| | Area Track Left-4-Way UP |
| | Point Track Left-4-Way Down |
| | Undesignate LANTIRN Undesignate |

| A/G WEAPONS | F-14A/B | REV: 20210819 |
|-------------|---------|---------------|
| | | |

| 4. | Designate | (a) DesignateTrigger Full-Action Time-to-Go calculated Slant Range calculated |
|----|------------|---|
| | | Once Time-to-Realease (TREL) is 0 |
| | | (b) Auto-LaseIf selected: lases 10s to impact (c) Manual Lase Trigger Full-Action (d) While Lasing L blinks |
| 5. | Employment | Once Time-to-Realease (TREL) is 0 |
| | | (a) STORE RELEASE Press and Hold |
| | | (b) Flight Path Gentle right-hand turn (to prevent masking) |

6.6 TALD DECOYS

| 1. RIO Conditions | (a) WPN TYP TALD (b) Deliver Mode STP-SGL |
|---------------------|---|
| | STP (Step) single bomb per press RPL (Ripple) multiple bombs per press SGL (Single) single bomb per press |
| | • PRS (Pairs) a pair of bombs per press |
| | (c) Delivery Options set (not necessary for STP-SGL) |
| | (d) StationsArmed |
| 2. Pilot Conditions | (a) MASTER ARMON |
| | (b) HUD |
| | (c) WEAPON SELECTOR OFF |
| | (d) HSD ModeTID |
| | (e) Stations verify selected |
| 3. Employment | (a) Flight Path High / Fast |
| | (b) RWR Monitor to locate emitters |
| | (c) STORE RELEASE Press and Hold |

6.7 SELECTIVE ORNANCE JETTISON

7 A/A WEAPONS

7.1 M61 GUN (MANUAL)

| 1. | Conditions | • MASTER ARMON |
|----|-------------------|---|
| | | • HUD |
| | | • Gun Rate HIGH |
| | | Gunsight Leadas required |
| | | WEAPON SELECTOR |
| 2. | Gun Mode | (a) Gun Mode MANUAL |
| | | Press CAGE/SEAM to select |
| | | No ranging |
| | | No lead information |
| 3. | Employment | (a) Pipper on target |
| | | (b) Trigger FIRE |

7.2 M61 GUN (RTGS/NO RADAR)

| 1. | Conditions | MASTER ARM ON HUD A/A Gun Rate HIGH WEAPON SELECTOR GUNS |
|----|------------|--|
| 2. | Gun Mode | (a) Gun Mode |
| 3. | Employment | (a) Pipper on target (b) Trigger FIRE |

7.3 M61 GUN (RTGS/RADAR)

| 1. Conditions | MASTER ARM ON HUD A/A Gun Rate HIGH WEAPON SELECTOR GUNS |
|---------------|--|
| 2. Radar Lock | (a) Gun ModeRTGS • Real-Time Gunsight Mode • Selected automatically with guns |
| | (b) Radar STT • RIO STT lock • ACM Modes |
| 3. Employmen | t (a) Pipperon target (b) Trigger |

7.4 AIM-9 SIDEWINDER (SIL)

| 1. Conditions | MASTER ARM ON |
|---------------|--|
| | • HUD |
| | SW COOLON WEAPON SELECTORSW |
| | |
| 2. IR Lock | (a) MODE/STPas desired |
| | • NORM |
| | Uncage seeker with CAGE/SEAM |
| | 4.5 sec search time |
| | 40 deg track limit |
| | • BRSIT |
| | Seeker slaved to ADL |
| | 2.5 deg FOV |
| | (b) CAGE/SEAM press to uncage (if using NORM) |
| | (c) Tone high pitched |
| 3. Employment | (a) TriggerFIRE |

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7.5 AIM-9 SIDEWINDER (RADAR)

| 1. Condition | • MASTER ARMON |
|--------------|--|
| | • HUD |
| | • SW COOLON |
| | WEAPON SELECTORSW |
| 2. Radar/IR | ck (a) MODE/STPNORM |
| | • NORM |
| | Uncage seeker with CAGE/SEAM4.5 sec search time |
| | 40 deg track limit |
| | BRSIT |
| | Seeker slaved to ADL |
| | 2.5 deg FOV |
| | (b) RadarSTT |
| | RIO STT lock |
| | ACM Modes |
| | (c) CAGE/SEAM press to slave to radar (d) Tone high pitched |
| 3. Employm | (a) Steering center T-shaped cue with ASE (b) TriggerFIRE |

7.6 AIM-7 SPARROW

| 1. Conditions | MASTER ARM ON HUD A/A MSL PREP ON WEAPON SELECTOR SP |
|-------------------|---|
| 2. RIO Conditions | (a) LIQUID COOLING ON (FWD) (b) MSL SPD GATE NOSE QTR • NOSE QTR Standard Operation • All Others Not Simulated |
| | (c) MSL OPTIONSas desired |
| | • NORM |
| | WCS uses dedicated CW antenna for AIM-7 guidance |
| | SP PD |
| | WCS uses PD from main flood antenna for AIM-7F/M guidance |
| 3. Radar Lock | (a) MODE/STPNORM |
| | • NORM |
| | Used for normal STT engagementWCS can use CS or PD |
| | BRSIT |
| | Boresight flood mode |
| | Tracks strongest return |
| | (b) Radar STT |
| 4. Employment | (a) Target<20 deg from ADL |
| | (b) Steering center T-shaped cue with ASE |
| | (c) Trigger FIRE |
| | (d) Radar Maintain Lock |

7.7 AIM-54 PHOENIX - PD-STT

| WEAPON SELECTOR (a) LIQUID COOLING (b) MSL SPD GATE NOSE NORM NORM NORM NORM NORM NORM NOR NORM NORM | | • TID TTI appears (d) Radar Maintain Lock |
|--|-------------------|--|
| WEAPON SELECTOR ON (I | 5. Employment | (a) Target |
| RIO Conditions (a) LIQUID COOLING | | Follows ADLDoes not require any radar data(b) RadarSTT |
| RIO Conditions (a) LIQUID COOLING | | _ |
| RIO Conditions (a) LIQUID COOLING | | Used for STT engagement |
| RIO Conditions (a) LIQUID COOLING | 4. Hadar Lock | |
| WEAPON SELECTOR 2. RIO Conditions (a) LIQUID COOLING ON (I (b) MSL SPD GATE NOSE | | NORM AIM-54 uses SARH all the way to the target PH ACT Must be selected before launch WCS commands active at first guidance command If no target detected by seeker reverts back to SARH |
| WEAPON SELECTOR | 2. RIO Conditions | the contract of the contract o |
| • HUD | 1. Conditions | MASTER ARM ON HUD A/A MSL PREP ON WEAPON SELECTOR PH |

7.8 AIM-54 PHOENIX - TWS / MULTI

| 1. Conditions | MASTER ARMON |
|-------------------|---|
| | • HUD |
| | • MSL PREP ON |
| | WEAPON SELECTORPH |
| 2. RIO Conditions | (a) LIQUID COOLING ON (FWD) (b) MSL SPD GATE NOSE QTR |
| | NOSE QTR Standard Operation |
| | All Others Not Simulated |
| | (c) MSL OPTIONSas desired |
| | • NORM |
| | AIM-54 uses SARH until active |
| | PH ACT |
| | Must be selected before launch |
| | WCS commands active at first guid- |
| | ance command |
| | If no target detected by seeker re- |
| | verts back to SARH |
| | (d) WCS Mode TWS MAN/AUTO |
| 3. Radar Track | (a) MODE/STPNORM |
| | • NORM |
| | Used for TWS engagement |
| | BRSIT |
| | AIM-54 active at launch |
| | - Follows ADL |
| | Does not require any radar data |
| | (b) Radar TWS |
| | WCS will automatically build trackfiles |
| | Track priorities to the right of contact |
| | symbol |
| 4. Employment | (a) TriggerPress and Hold |
| | (3-4 seconds) |
| | TID TTI appears |
| | WCS MODE switches to TWS AUTO |
| | Priority automatically collapses by one |
| | Repeat for remaining targets |
| | (b) RadarMaintain Track |
| | (until active) |
| | · · · |

