Algorithms and Datastructures

Graphs, Depth-/Breadth-first Search, Graph-Connectivity

Albert-Ludwigs-Universität Freiburg

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Structure

Feedback
- Exercises
- Lecture

Graphs
- Introduction
- Implementation
- Application example

Feedback from the exercises

The upcoming exercise sheet 12 and 13 will be merged together (finding largest connected component + Dijkstra)

Some people were asking for more solution sheets for the exercises

We are working on it.

Feedback from the lecture

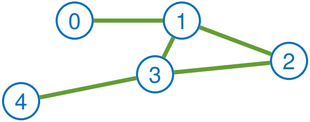
Code in the lecture will be a litte bit different from exercise sheet.

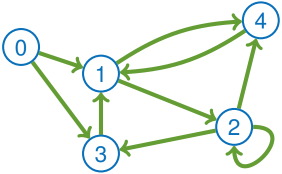
One person asked for additional explanations regarding proofs.

Graphs - Overview:

- Besides arrays, lists and trees the most common datastructure
  (Trees are a special type of graph)
- Representation of graphs in the computer
- Breadth first search (BFS)
- Depth first search (DFS)
- Connected components of a graph

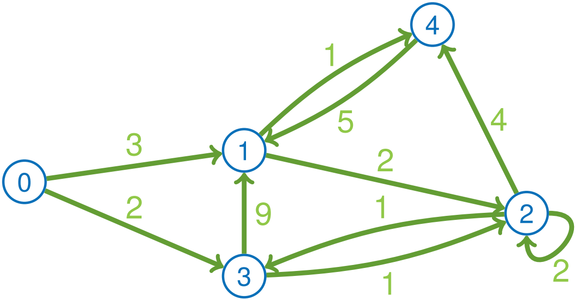
Terminology:





- Each Graph $G = (V, E)$ consists of:
  - A set of vertices (nodes) $V = \{v_1, v_2, \dots\}$
  - A set of edges (arcs) $E = \{e_1, e_2, \dots\}$
- Each edge connects two vertices ($u, v \in V$)
  - Undirected edge: $e = \{u, v\}$ (set)
  - Directed edge: $e = (u, v)$ (tuple)
- Self-loops are also possible: $e = (u, u)$ or $e = \{u, u\}$

Weighted graph:



- Each edge is marked with a real number named weight
- The weight is also named length or cost of the edge depending on the application

Example: Road network

- Intersections: vertices
- Roads: edges
- Travel time: costs of the edges

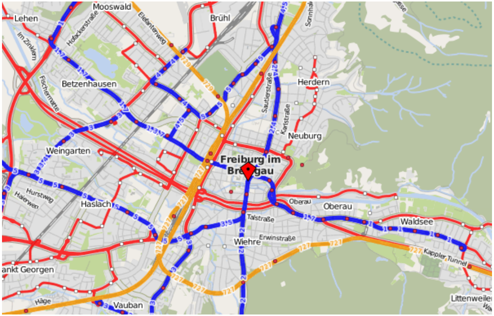


Abbildung: Map of Freiburg © OpenStreetMap

How to represent this graph computationally?

- Two classic variants
  1. Adjacency matrix with space consumption $\Theta(|V|^2)$

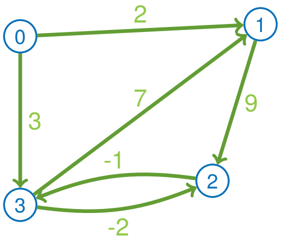


Abbildung: Weighted graph with $|V| = 4$, $|E| = 6$

end-vertice

start-vertice	0	1	2	3
0		2		3
1			9	
2				-1
3		7	-2	

Abbildung: Adjacency matrix

How to represent this graph computationally?

- Two classic variants
  2. Adjacency list / fields with space consumption $\Theta(|V| + |E|)$
     - Each list item stores the target vertice and the cost of the edge

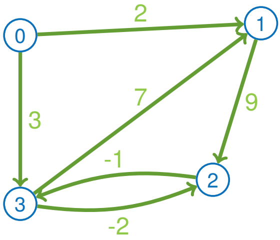


Abbildung: Weighted graph with $|V| = 4$, $|E| = 6$

start-vertice		
0	1, 2	3, 3
1	2, 9	
2	3, -1	
3	1, 7	2, -2

Abbildung: Adjacency list

Graph: Arrangement

- Graph is fully defined through the adjacency matrix / list
- The arrangement is not relevant for visualisation of the graph

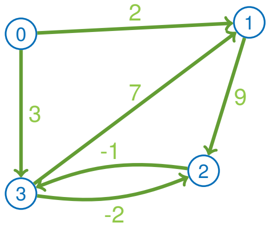


Abbildung: Weighted graph with $|V| = 4$, $|E| = 6$

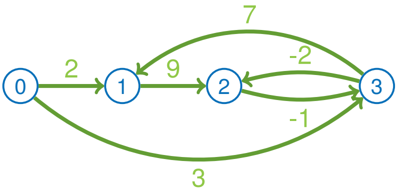


Abbildung: Same graph ordered by number - outer planar graph

```python
class Graph:
    def __init__(self):
        self.vertices = []
        self.edges = []

    def addVertice(self, vert):
        self.vertices.append(vert)

    def addEdge(self, fromVert, toVert):
        self.edges.append((fromVert, toVert))

    ...
```

```
...

def toString(self):
    return '{'
        + ', '.join( \
            [str(len(self.vertices)), \
                str(len(self.edges))] \
            + ["(%s, %s)" % tup \
                for tup in self.edges]) \
        + '}'
```

Degree of a vertex: Directed graph: $G = (V, E)$

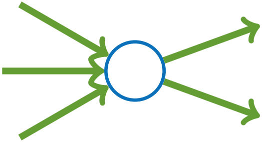


Abbildung: Vertex with in- / outdegree of 3 / 2

- Indegree of a vertex u is the number of edge heads adjacent to the vertex

$$\deg^{+}(u) = |\{(v,u):\ (v,u) \in E\}|$$

- Outdegree of a vertex u is the number of edge tails adjacent to the vertex

$$\deg^{-}(u) = |\{(u,v):\ (u,v) \in E\}|$$

Degree of a vertex: Undirected graph: $G = (V, E)$

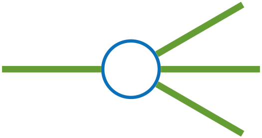


Abbildung: Vertex with degree of 4

- Degree of a vertex u is the number of vertices adjacent to the vertex

$$\deg(u) = |\{\{v, u\} : \{v, u\} \in E\}|$$

Paths in a graph: $G = (V, E)$

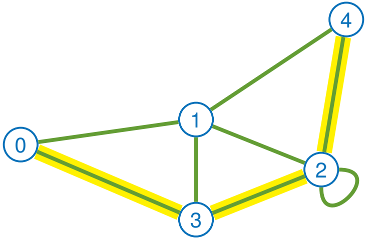


Abbildung: Undirected path of length 3

$P = (0, 3, 2, 4)$

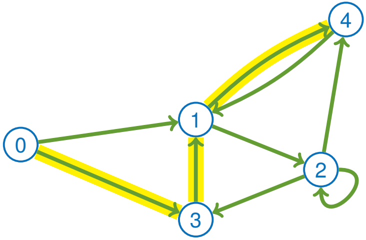


Abbildung: Directed path of length 3

$P = (0, 3, 1, 4)$

- A path of G is a sequence of edges $u_1, u_2, \ldots, u_i \in V$ with
  - Undirected graph: $\{u_1, u_2\}, \{u_2, u_3\}, \ldots, \{u_{i-1}, u_i\} \in E$
  - Directed graph: $(u_1, u_2), (u_2, u_3), \ldots, (u_{i-1}, u_i) \in E$

Paths in a graph: $G = (V, E)$

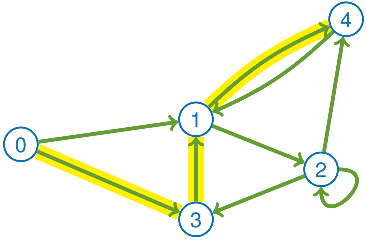


Abbildung: Directed path of length 3

$P = (0, 3, 1, 4)$

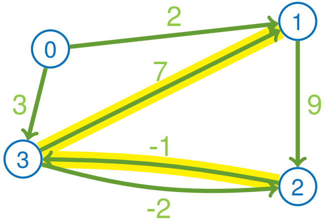


Abbildung: Weighted path with cost 6

$P = (2, 3, 1)$

- The length of a path is: (also costs of a path)
  - Without weights: number of edges taken
  - With weights: sum of weigths of edges taken

Shortest path in a graph: $G = (V, E)$

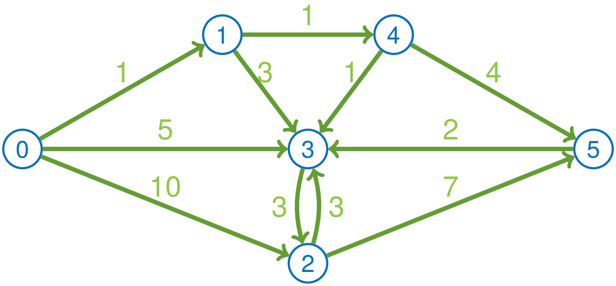


Abbildung: Shortest path from 0 to 2 with cost / distance $d(0, 2) = ?$

- The shortest path between two vertices u, v is the path $P = (u, \ldots, v)$ with the shortest length $d(u, v)$ or lowest costs

Shortest path in a graph: $G = (V, E)$

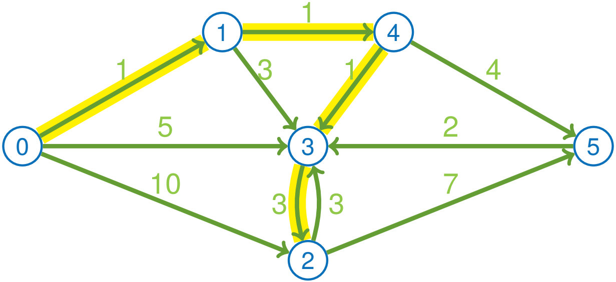


Abbildung: Shortest path from 0 to 2 with cost / distance $d(0,2) = 6$
$P = (0,1,4,3,2)$

- The shortest path between two vertices u, v is the path $P = (u, \ldots, v)$ with the shortest length $d(u, v)$ or lowest costs

Diameter of a graph: $G = (V, E)$ $\qquad d = \max_{u,v \in V} d(u, v)$

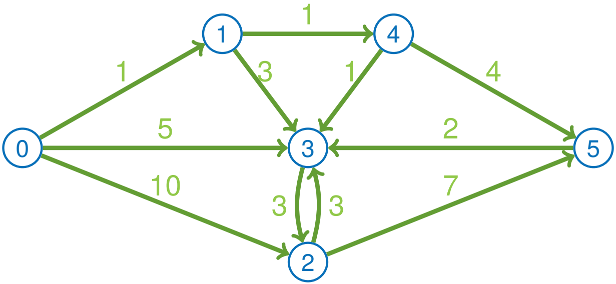


Abbildung: Diameter of graph is $d = ?$

- The diameter of a graph is the length / the costs of the longest shortest path

Diameter of a graph: $G = (V, E)$

$$d = \max_{u,v \in V} d(u,v)$$

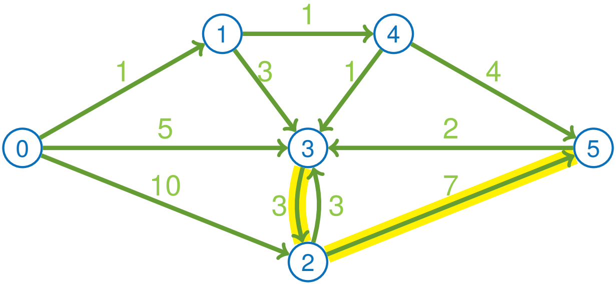


Abbildung: Diameter of graph is $d = 10$, $P = (3, 2, 5)$

- The diameter of a graph is the length / the costs of the longest shortest path

Connected components: $G = (V, E)$

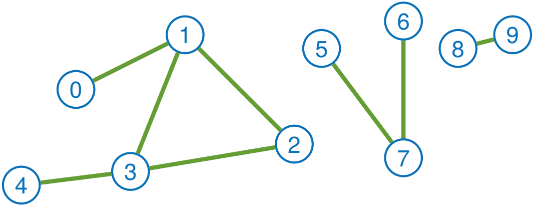


Abbildung: Three connected components

- Undirected graph:
  - All connected components are a partition of V

$$V = V_1 \cup \cdots \cup V_k$$

  - Two vertices u, v are in the same connected component if a path between u and v exists

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Connected components: $G = (V, E)$

- Directed graph:
  - Named strongly connected components
  - Direction of edge has to be regarded
  - Not part of this lecture

Graph Exploration: (Informal definition)

- Let $G = (V, E)$ be a graph and $s \in V$ a start vertex
- We visit each reachable vertex connected to s
- Breadth-first search: in sequence of the smallest distance to s
- Depth-first search: in sequence of the largest distance to s
- Not a problem on its own but is often used as subroutine of other algorithms

Idea:

1. We start with all vertices unmarked and mark visited vertices
2. Mark the start vertex s (level 0)
3. Mark all unmarked connected vertices (level 1)
4. Mark all unmarked vertices connected to a level 1-vertex (level 2)
5. Iteratively mark reachable vertices for all levels
6. All connected nodes are now marked and in the same connected component as the start vertex s

- The marked vertices create a „spanning tree“ containing all reachable nodes

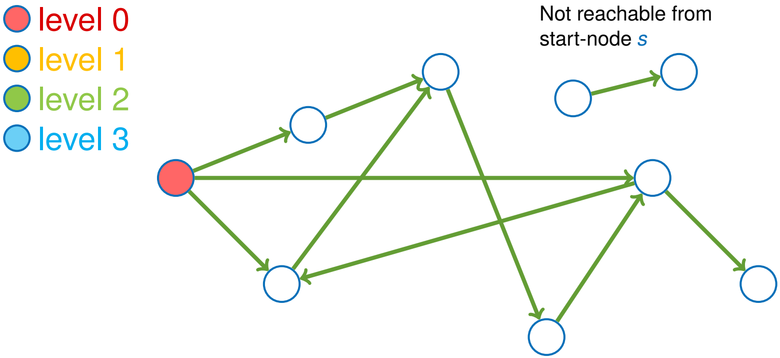
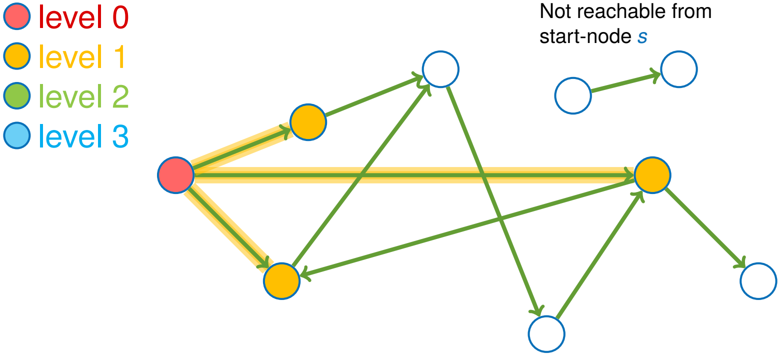


Abbildung: spanning tree of a breadth-first search

- The marked vertices create a „spanning tree“ containing all reachable nodes



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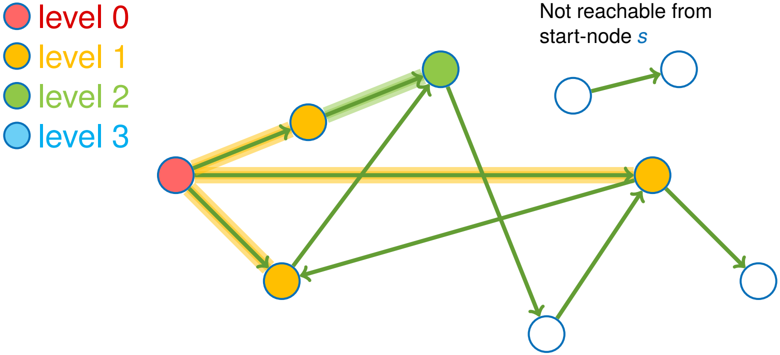

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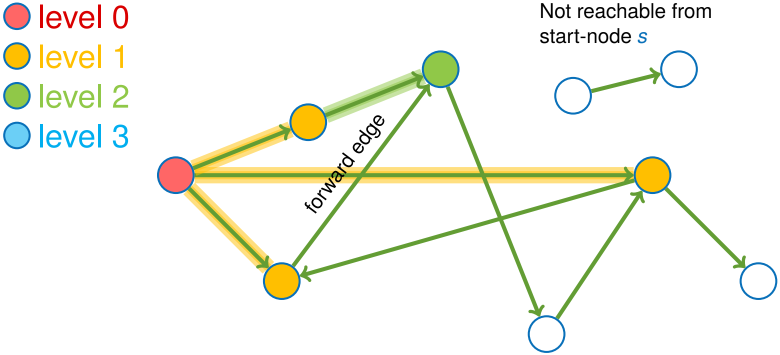

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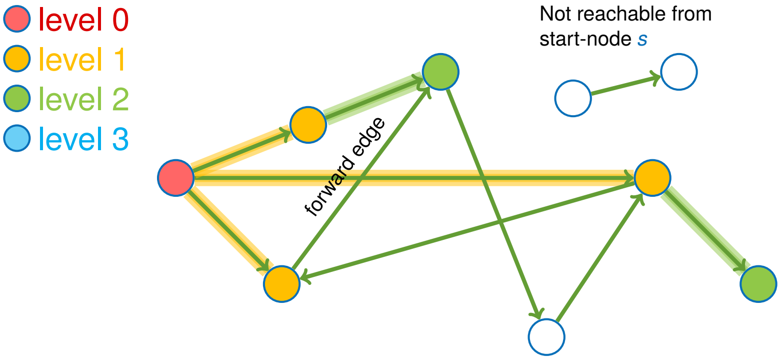

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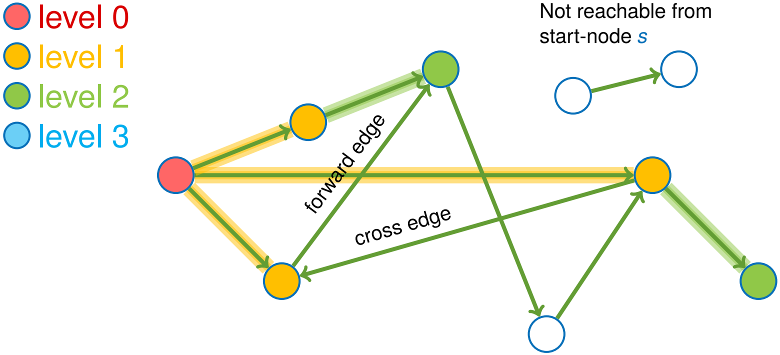

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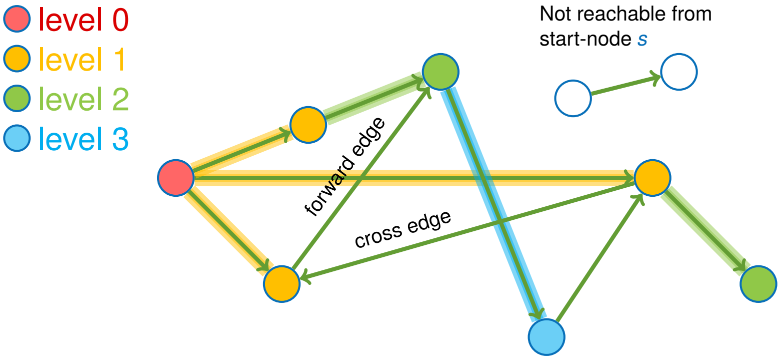

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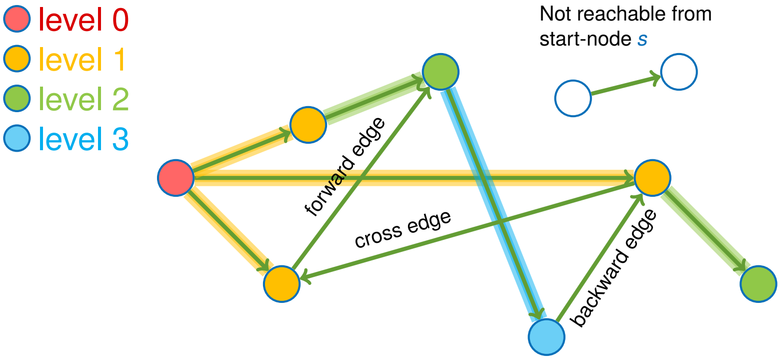

Abbildung: spanning tree of a breadth-first search

Idea:

1. We start with all vertices unmarked and mark visited vertices
2. Mark the start vertex s
3. Pick an unmarked connected vertex and start a recursive depth-first search with the vertex as start vertex (continue on step 2)
4. If no unmarked connected vertex exists go one vertex back (reduce the recursion level by one)

Depth-first search:

- Search starts with long paths (searching with depth)
- Marks like breadth-first search all connected vertices
- If the graph is acyclic we get a topological sorting
    - Each newly visited vertex gets marked by an increasing number
    - The numbers increase with path from the start vertex

- The marked vertices create a different spanning tree containing all reachable nodes

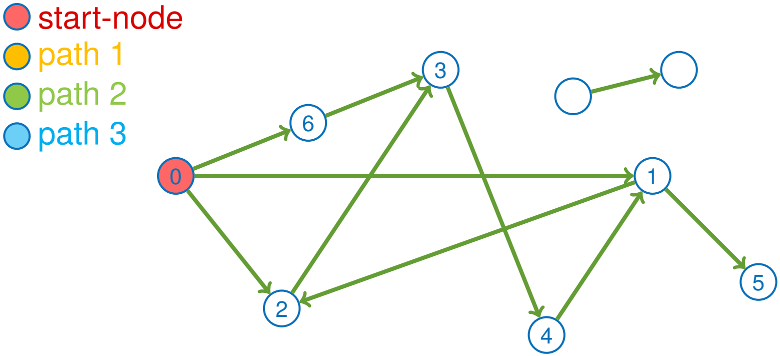

Abbildung: spanning tree of a depth-first search

- The marked vertices create a different spanning tree containing all reachable nodes

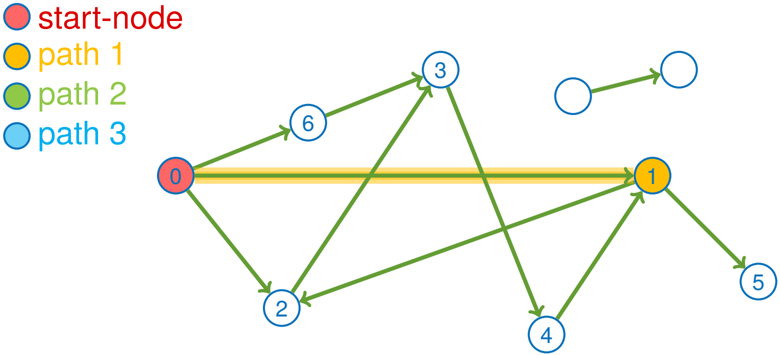

Abbildung: spanning tree of a depth-first search

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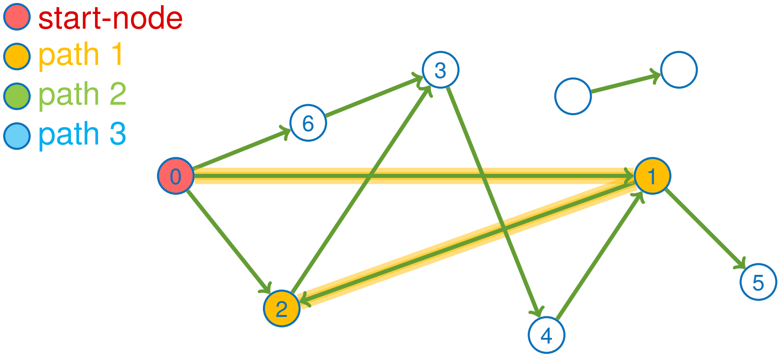

Abbildung: spanning tree of a depth-first search

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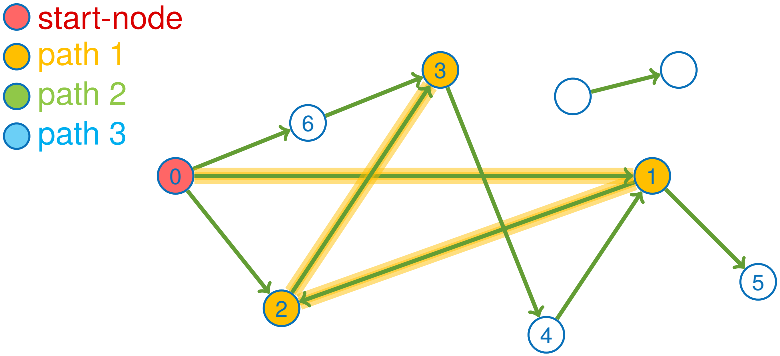

Abbildung: spanning tree of a depth-first search

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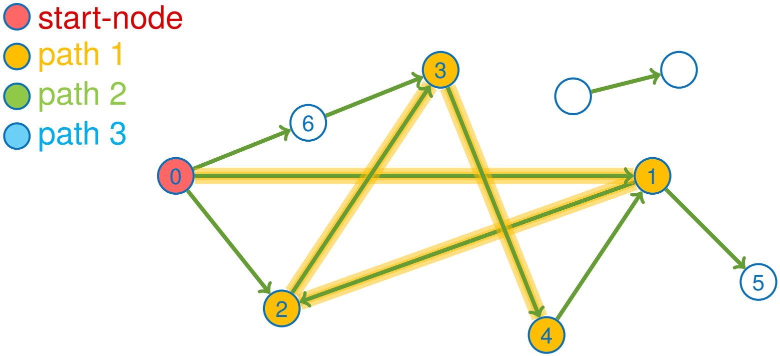

Abbildung: spanning tree of a depth-first search

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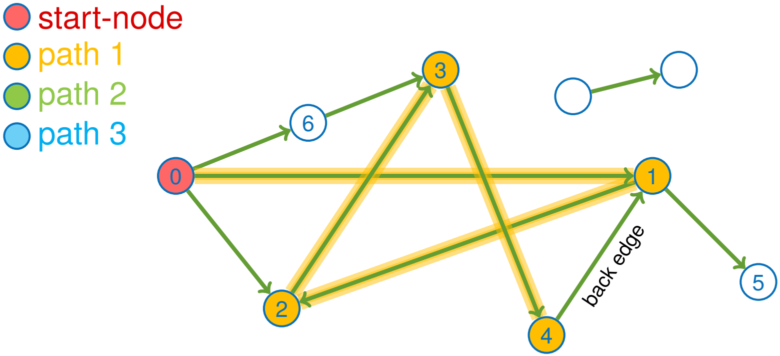

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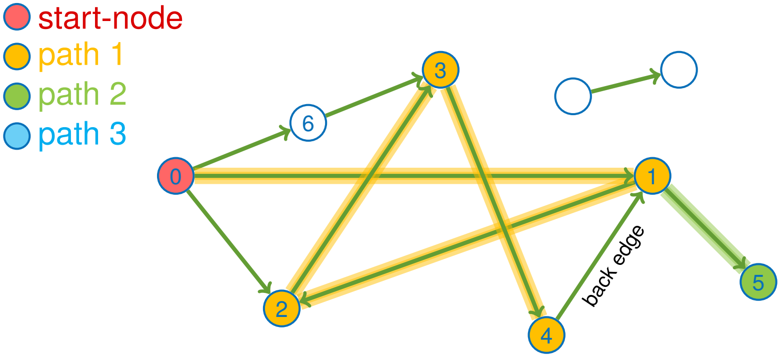

Abbildung: spanning tree of a depth-first search

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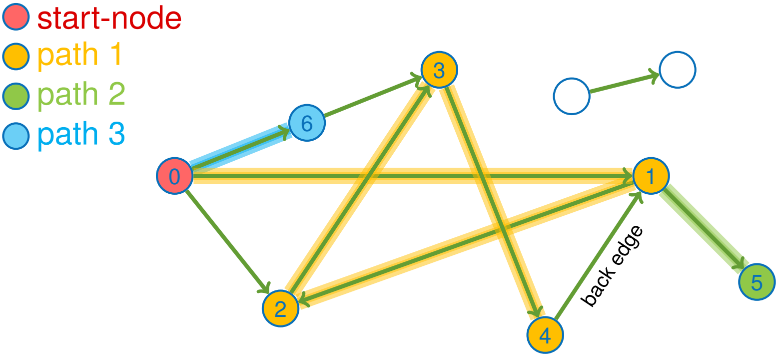

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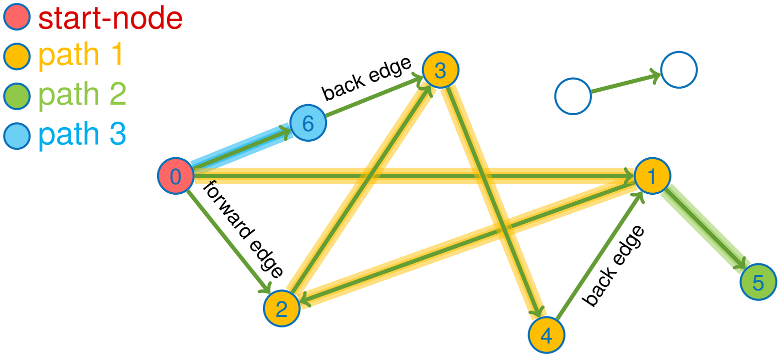

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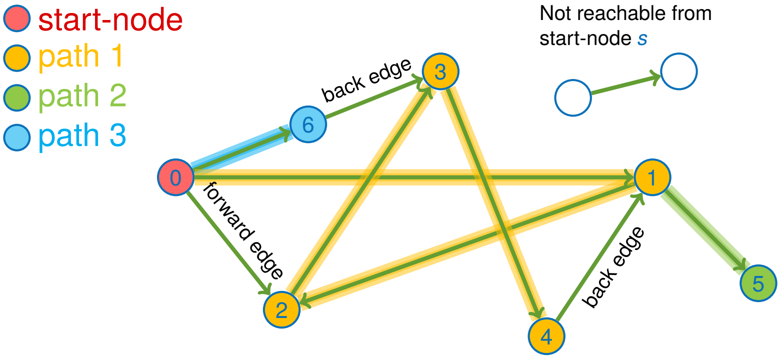

Abbildung: spanning tree of a depth-first search

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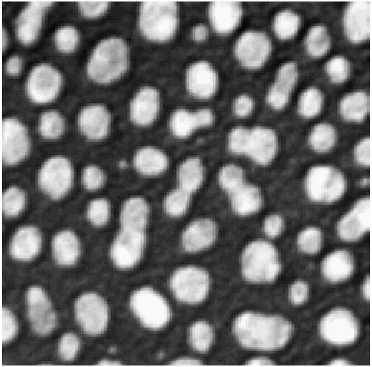
Runtime complexity:

- Constant costs for each visited vertex and edge
- We get a runtime complexity of $\Theta(|V'| + |E'|)$
- Let V' and E' be the reachable vertices and edges
- All vertices of V' are in the same connected component as our start vertex s
- This can only be improved by a constant factor

Application example

Image processing

- Connected component labeling
- Counting of objects in an image



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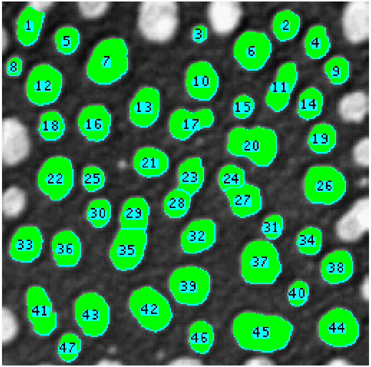
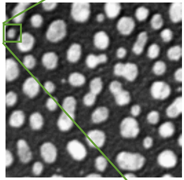


Application example

Image processing

What's object, what's background?



	A	B	C	D	E	F	G	H	I	J	K	L	M	N	O	P	Q	R	S	T	U
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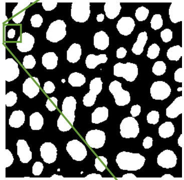
52	48	56	64	80	88	104	112	112	120	112	104	88	72	56	32	32	32	64	88	128	168
53	40	48	48	56	64	72	72	80	80	80	72	64	48	40	24	32	32	72	104	144	184
54	48	48	48	48	48	56	56	56	64	56	56	48	40	32	24	40	48	88	128	160	200

UNI FREIBURG

Convert to black white using threshold:

```python
value = 255 if value > 100 else 0
```

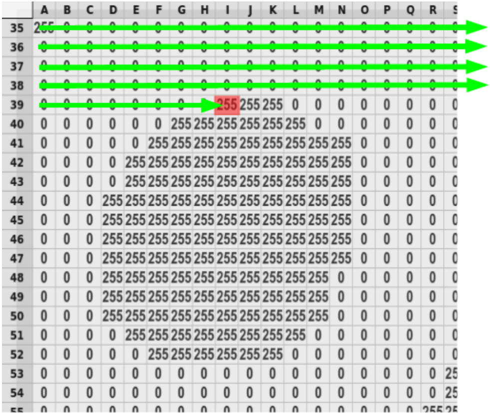


	A	B	C	D	E	F	G	H	I	J	K	L	M	N	O	P
35	255	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
36	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
37	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
38	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
39	0	0	0	0	0	0	0	0	255	255	255	0	0	0	0	0
40	0	0	0	0	0	0	255	255	255	255	255	255	0	0	0	0
41	0	0	0	0	0	255	255	255	255	255	255	255	255	255	0	0
42	0	0	0	0	255	255	255	255	255	255	255	255	255	255	0	0
43	0	0	0	0	255	255	255	255	255	255	255	255	255	255	0	0
44	0	0	0	255	255	255	255	255	255	255	255	255	255	255	0	0
45	0	0	0	255	255	255	255	255	255	255	255	255	255	255	0	0
46	0	0	0	255	255	255	255	255	255	255	255	255	255	255	0	0
47	0	0	0	255	255	255	255	255	255	255	255	255	255	255	0	0
48	0	0	0	255	255	255	255	255	255	255	255	255	255	0	0	0
49	0	0	0	255	255	255	255	255	255	255	255	255	255	0	0	0
50	0	0	0	255	255	255	255	255	255	255	255	255	255	0	0	0
51	0	0	0	0	255	255	255	255	255	255	255	255	0	0	0	0
52	0	0	0	0	0	255	255	255	255	255	255	0	0	0	0	0
53	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
54	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
55	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
56	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
57	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
58	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0

Interpret image as graph:

- Each white pixel is a node
- Edges between adjacent pixels (normally 4 or 8 neighbors)
- Edges are not saved externally, algorithm works directly on array
- Breadth- / depth-first search find all connected components (particles)

Find connected components:

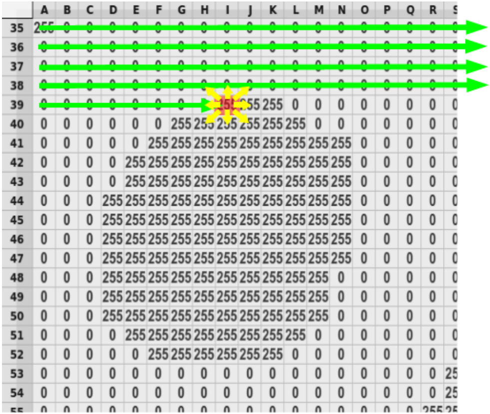


	A	B	C	D	E	F	G	H	I	J	K	L	M	N	O	P	Q	R	S
35	255	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
36	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
37	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
38	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
39	0	0	0	0	0	0	0	0	255	255	255	0	0	0	0	0	0	0	0
40	0	0	0	0	0	0	255	255	255	255	255	255	0	0	0	0	0	0	0
41	0	0	0	0	0	255	255	255	255	255	255	255	255	255	0	0	0	0	0
42	0	0	0	0	255	255	255	255	255	255	255	255	255	255	0	0	0	0	0
43	0	0	0	0	255	255	255	255	255	255	255	255	255	255	0	0	0	0	0
44	0	0	0	255	255	255	255	255	255	255	255	255	255	255	0	0	0	0	0
45	0	0	0	255	255	255	255	255	255	255	255	255	255	255	0	0	0	0	0
46	0	0	0	255	255	255	255	255	255	255	255	255	255	255	0	0	0	0	0
47	0	0	0	255	255	255	255	255	255	255	255	255	255	255	0	0	0	0	0
48	0	0	0	255	255	255	255	255	255	255	255	255	255	0	0	0	0	0	0
49	0	0	0	255	255	255	255	255	255	255	255	255	255	0	0	0	0	0	0
50	0	0	0	255	255	255	255	255	255	255	255	255	255	0	0	0	0	0	0
51	0	0	0	0	255	255	255	255	255	255	255	255	0	0	0	0	0	0	0
52	0	0	0	0	0	255	255	255	255	255	255	0	0	0	0	0	0	0	0
53	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	25
54	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	25
55	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	255	25

- Search pixel-by-pixel for non-zero intensity
- Label found pixel as component 1

UNI FREIBURG

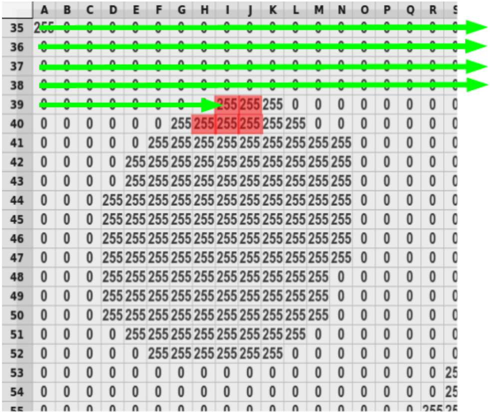
Find connected components:



	A	B	C	D	E	F	G	H	I	J	K	L	M	N	O	P	Q	R	S
35	255	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
36	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
37	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
38	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
39	0	0	0	0	0	0	0	0	255	255	255	0	0	0	0	0	0	0	0
40	0	0	0	0	0	0	255	255	255	255	255	255	0	0	0	0	0	0	0
41	0	0	0	0	0	255	255	255	255	255	255	255	255	255	0	0	0	0	0
42	0	0	0	0	255	255	255	255	255	255	255	255	255	255	0	0	0	0	0
43	0	0	0	0	255	255	255	255	255	255	255	255	255	255	0	0	0	0	0
44	0	0	0	255	255	255	255	255	255	255	255	255	255	255	0	0	0	0	0
45	0	0	0	255	255	255	255	255	255	255	255	255	255	255	0	0	0	0	0
46	0	0	0	255	255	255	255	255	255	255	255	255	255	255	0	0	0	0	0
47	0	0	0	255	255	255	255	255	255	255	255	255	255	255	0	0	0	0	0
48	0	0	0	255	255	255	255	255	255	255	255	255	255	0	0	0	0	0	0
49	0	0	0	255	255	255	255	255	255	255	255	255	255	0	0	0	0	0	0
50	0	0	0	255	255	255	255	255	255	255	255	255	255	0	0	0	0	0	0
51	0	0	0	0	255	255	255	255	255	255	255	255	0	0	0	0	0	0	0
52	0	0	0	0	0	255	255	255	255	255	255	0	0	0	0	0	0	0	0
53	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	25
54	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	25
55	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	255	25

- Search pixel-by-pixel for non-zero intensity
- Label found pixel as component 1
- Check neighbors of all new labeled pixels

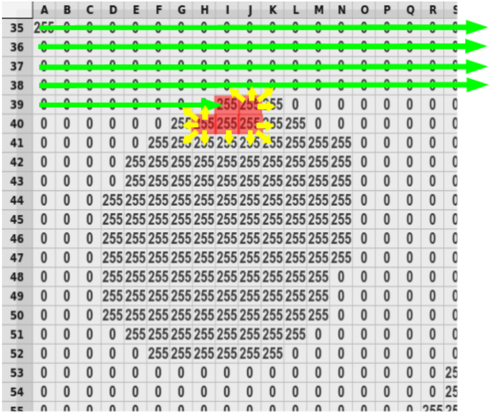
Find connected components:



	A	B	C	D	E	F	G	H	I	J	K	L	M	N	O	P	Q	R	S
35	255	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
36	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
37	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
38	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
39	0	0	0	0	0	0	0	0	255	255	255	0	0	0	0	0	0	0	0
40	0	0	0	0	0	0	255	255	255	255	255	255	0	0	0	0	0	0	0
41	0	0	0	0	0	255	255	255	255	255	255	255	255	255	0	0	0	0	0
42	0	0	0	0	255	255	255	255	255	255	255	255	255	255	0	0	0	0	0
43	0	0	0	0	255	255	255	255	255	255	255	255	255	255	0	0	0	0	0
44	0	0	0	255	255	255	255	255	255	255	255	255	255	255	0	0	0	0	0
45	0	0	0	255	255	255	255	255	255	255	255	255	255	255	0	0	0	0	0
46	0	0	0	255	255	255	255	255	255	255	255	255	255	255	0	0	0	0	0
47	0	0	0	255	255	255	255	255	255	255	255	255	255	255	0	0	0	0	0
48	0	0	0	255	255	255	255	255	255	255	255	255	255	0	0	0	0	0	0
49	0	0	0	255	255	255	255	255	255	255	255	255	255	0	0	0	0	0	0
50	0	0	0	255	255	255	255	255	255	255	255	255	255	0	0	0	0	0	0
51	0	0	0	0	255	255	255	255	255	255	255	255	0	0	0	0	0	0	0
52	0	0	0	0	0	255	255	255	255	255	255	0	0	0	0	0	0	0	0
53	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	25
54	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	25

- Search pixel-by-pixel for non-zero intensity
- Label found pixel as component 1
- Check neighbors of all new labeled pixels
- Label non-zero pixels as component 1

Find connected components:



	A	B	C	D	E	F	G	H	I	J	K	L	M	N	O	P	Q	R	S
35	255	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
36	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
37	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
38	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
39	0	0	0	0	0	0	0	[illegible]	255	255	255	0	0	0	0	0	0	0	0
40	0	0	0	0	0	0	255	255	255	255	255	255	0	0	0	0	0	0	0
41	0	0	0	0	0	255	255	255	255	255	255	255	255	255	0	0	0	0	0
42	0	0	0	0	255	255	255	255	255	255	255	255	255	255	0	0	0	0	0
43	0	0	0	0	255	255	255	255	255	255	255	255	255	255	0	0	0	0	0
44	0	0	0	255	255	255	255	255	255	255	255	255	255	255	0	0	0	0	0
45	0	0	0	255	255	255	255	255	255	255	255	255	255	255	0	0	0	0	0
46	0	0	0	255	255	255	255	255	255	255	255	255	255	255	0	0	0	0	0
47	0	0	0	255	255	255	255	255	255	255	255	255	255	255	0	0	0	0	0
48	0	0	0	255	255	255	255	255	255	255	255	255	255	0	0	0	0	0	0
49	0	0	0	255	255	255	255	255	255	255	255	255	255	0	0	0	0	0	0
50	0	0	0	255	255	255	255	255	255	255	255	255	255	0	0	0	0	0	0
51	0	0	0	0	255	255	255	255	255	255	255	255	0	0	0	0	0	0	0
52	0	0	0	0	0	255	255	255	255	255	255	0	0	0	0	0	0	0	0
53	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	25
54	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	25
55	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	255	25

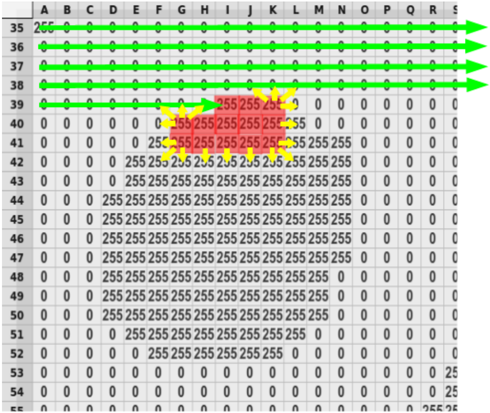
- Search pixel-by-pixel for non-zero intensity
- Label found pixel as component 1
- Check neighbors of all new labeled pixels
- Label non-zero pixels as component 1

Find connected components:

	A	B	C	D	E	F	G	H	I	J	K	L	M	N	O	P	Q	R	S
35	255	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
36	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
37	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
38	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
39	0	0	0	0	0	0	0	[illegible]	255	255	255	0	0	0	0	0	0	0	0
40	0	0	0	0	0	0	255	255	255	255	255	255	0	0	0	0	0	0	0
41	0	0	0	0	0	255	255	255	255	255	255	255	255	255	0	0	0	0	0
42	0	0	0	0	255	255	255	255	255	255	255	255	255	255	0	0	0	0	0
43	0	0	0	0	255	255	255	255	255	255	255	255	255	255	0	0	0	0	0
44	0	0	0	255	255	255	255	255	255	255	255	255	255	255	0	0	0	0	0
45	0	0	0	255	255	255	255	255	255	255	255	255	255	255	0	0	0	0	0
46	0	0	0	255	255	255	255	255	255	255	255	255	255	255	0	0	0	0	0
47	0	0	0	255	255	255	255	255	255	255	255	255	255	255	0	0	0	0	0
48	0	0	0	255	255	255	255	255	255	255	255	255	255	0	0	0	0	0	0
49	0	0	0	255	255	255	255	255	255	255	255	255	255	0	0	0	0	0	0
50	0	0	0	255	255	255	255	255	255	255	255	255	255	0	0	0	0	0	0
51	0	0	0	0	255	255	255	255	255	255	255	255	0	0	0	0	0	0	0
52	0	0	0	0	0	255	255	255	255	255	255	0	0	0	0	0	0	0	0
53	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	25
54	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	25
55	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	255	25

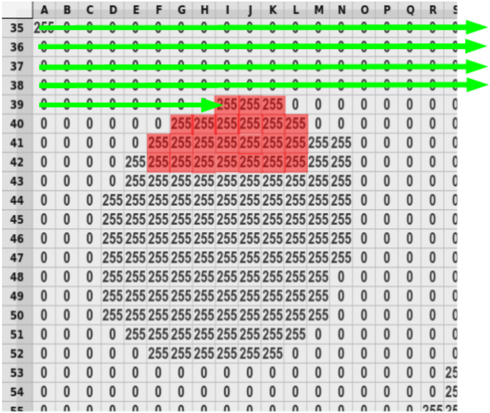
- Search pixel-by-pixel for non-zero intensity
- Label found pixel as component 1
- Check neighbors of all new labeled pixels
- Label non-zero pixels as component 1

Find connected components:



- Search pixel-by-pixel for non-zero intensity
- Label found pixel as component 1
- Check neighbors of all new labeled pixels
- Label non-zero pixels as component 1

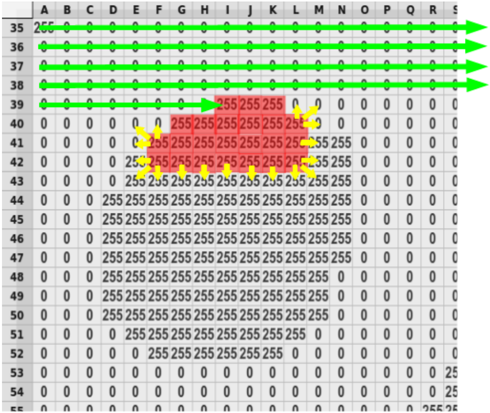
Find connected components:



	A	B	C	D	E	F	G	H	I	J	K	L	M	N	O	P	Q	R	S
35	255	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
36	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
37	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
38	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
39	0	0	0	0	0	0	0	0	255	255	255	0	0	0	0	0	0	0	0
40	0	0	0	0	0	0	255	255	255	255	255	255	0	0	0	0	0	0	0
41	0	0	0	0	0	255	255	255	255	255	255	255	255	255	0	0	0	0	0
42	0	0	0	0	255	255	255	255	255	255	255	255	255	255	0	0	0	0	0
43	0	0	0	0	255	255	255	255	255	255	255	255	255	255	0	0	0	0	0
44	0	0	0	255	255	255	255	255	255	255	255	255	255	255	0	0	0	0	0
45	0	0	0	255	255	255	255	255	255	255	255	255	255	255	0	0	0	0	0
46	0	0	0	255	255	255	255	255	255	255	255	255	255	255	0	0	0	0	0
47	0	0	0	255	255	255	255	255	255	255	255	255	255	255	0	0	0	0	0
48	0	0	0	255	255	255	255	255	255	255	255	255	255	0	0	0	0	0	0
49	0	0	0	255	255	255	255	255	255	255	255	255	255	0	0	0	0	0	0
50	0	0	0	255	255	255	255	255	255	255	255	255	255	0	0	0	0	0	0
51	0	0	0	0	255	255	255	255	255	255	255	255	0	0	0	0	0	0	0
52	0	0	0	0	0	255	255	255	255	255	255	0	0	0	0	0	0	0	0
53	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	25
54	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	25
55	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	255	25

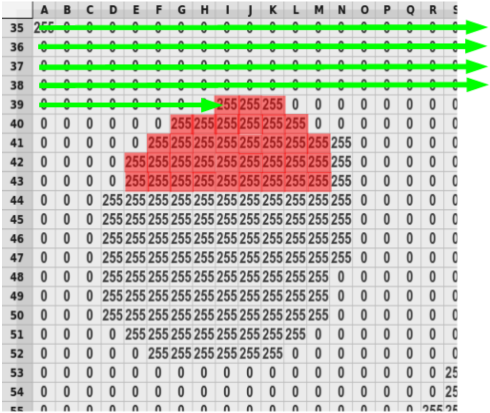
- Search pixel-by-pixel for non-zero intensity
- Label found pixel as component 1
- Check neighbors of all new labeled pixels
- Label non-zero pixels as component 1

Find connected components:



- Search pixel-by-pixel for non-zero intensity
- Label found pixel as component 1
- Check neighbors of all new labeled pixels
- Label non-zero pixels as component 1

Find connected components:



	A	B	C	D	E	F	G	H	I	J	K	L	M	N	O	P	Q	R	S
35	255	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
36	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
37	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
38	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
39	0	0	0	0	0	0	0	0	255	255	255	0	0	0	0	0	0	0	0
40	0	0	0	0	0	0	255	255	255	255	255	255	0	0	0	0	0	0	0
41	0	0	0	0	0	255	255	255	255	255	255	255	255	255	0	0	0	0	0
42	0	0	0	0	255	255	255	255	255	255	255	255	255	255	0	0	0	0	0
43	0	0	0	0	255	255	255	255	255	255	255	255	255	255	0	0	0	0	0
44	0	0	0	255	255	255	255	255	255	255	255	255	255	255	0	0	0	0	0
45	0	0	0	255	255	255	255	255	255	255	255	255	255	255	0	0	0	0	0
46	0	0	0	255	255	255	255	255	255	255	255	255	255	255	0	0	0	0	0
47	0	0	0	255	255	255	255	255	255	255	255	255	255	255	0	0	0	0	0
48	0	0	0	255	255	255	255	255	255	255	255	255	255	0	0	0	0	0	0
49	0	0	0	255	255	255	255	255	255	255	255	255	255	0	0	0	0	0	0
50	0	0	0	255	255	255	255	255	255	255	255	255	255	0	0	0	0	0	0
51	0	0	0	0	255	255	255	255	255	255	255	255	0	0	0	0	0	0	0
52	0	0	0	0	0	255	255	255	255	255	255	0	0	0	0	0	0	0	0
53	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	25
54	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	25
55	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	255	25

- Search pixel-by-pixel for non-zero intensity
- Label found pixel as component 1
- Check neighbors of all new labeled pixels
- Label non-zero pixels as component 1

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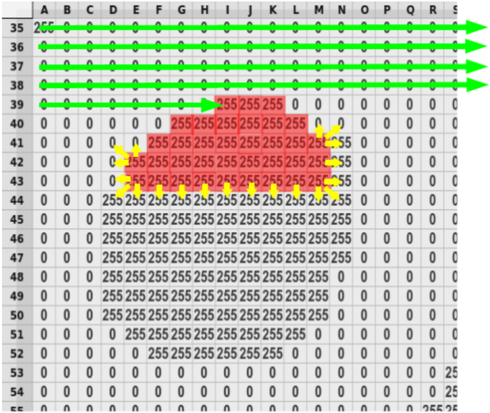
Find connected components:



	A	B	C	D	E	F	G	H	I	J	K	L	M	N	O	P	Q	R	S
35	255	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
36	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
37	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
38	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
39	0	0	0	0	0	0	0	[illegible]	255	255	255	0	0	0	0	0	0	0	0
40	0	0	0	0	0	0	255	255	255	255	255	255	0	0	0	0	0	0	0
41	0	0	0	0	0	255	255	255	255	255	255	255	255	255	0	0	0	0	0
42	0	0	0	0	255	255	255	255	255	255	255	255	255	255	0	0	0	0	0
43	0	0	0	0	255	255	255	255	255	255	255	255	255	255	0	0	0	0	0
44	0	0	0	255	255	255	255	255	255	255	255	255	255	255	0	0	0	0	0
45	0	0	0	255	255	255	255	255	255	255	255	255	255	255	0	0	0	0	0
46	0	0	0	255	255	255	255	255	255	255	255	255	255	255	0	0	0	0	0
47	0	0	0	255	255	255	255	255	255	255	255	255	255	255	0	0	0	0	0
48	0	0	0	255	255	255	255	255	255	255	255	255	255	0	0	0	0	0	0
49	0	0	0	255	255	255	255	255	255	255	255	255	255	0	0	0	0	0	0
50	0	0	0	255	255	255	255	255	255	255	255	255	255	0	0	0	0	0	0
51	0	0	0	0	255	255	255	255	255	255	255	255	0	0	0	0	0	0	0
52	0	0	0	0	0	255	255	255	255	255	255	0	0	0	0	0	0	0	0
53	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	25
54	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	25
55	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	255	25

- Search pixel-by-pixel for non-zero intensity
- Label found pixel as component 1
- Check neighbors of all new labeled pixels
- Label non-zero pixels as component 1

Find connected components:

	A	B	C	D	E	F	G	H	I	J	K	L	M	N	O	P	Q	R	S
35	255	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
36	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
37	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
38	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
39	0	0	0	0	0	0	0	0	255	255	255	0	0	0	0	0	0	0	0
40	0	0	0	0	0	0	255	255	255	255	255	255	0	0	0	0	0	0	0
41	0	0	0	0	0	255	255	255	255	255	255	255	255	255	0	0	0	0	0
42	0	0	0	0	255	255	255	255	255	255	255	255	255	255	0	0	0	0	0
43	0	0	0	0	255	255	255	255	255	255	255	255	255	255	0	0	0	0	0
44	0	0	0	255	255	255	255	255	255	255	255	255	255	255	0	0	0	0	0
45	0	0	0	255	255	255	255	255	255	255	255	255	255	255	0	0	0	0	0
46	0	0	0	255	255	255	255	255	255	255	255	255	255	255	0	0	0	0	0
47	0	0	0	255	255	255	255	255	255	255	255	255	255	255	0	0	0	0	0
48	0	0	0	255	255	255	255	255	255	255	255	255	255	0	0	0	0	0	0
49	0	0	0	255	255	255	255	255	255	255	255	255	255	0	0	0	0	0	0
50	0	0	0	255	255	255	255	255	255	255	255	255	255	0	0	0	0	0	0
51	0	0	0	0	255	255	255	255	255	255	255	255	0	0	0	0	0	0	0
52	0	0	0	0	0	255	255	255	255	255	255	0	0	0	0	0	0	0	0
53	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	25
54	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	25
55	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	255	25

- Search pixel-by-pixel for non-zero intensity
- Label found pixel as component 1
- Check neighbors of all new labeled pixels
- Label non-zero pixels as component 1

Find connected components:

- Search pixel-by-pixel for non-zero intensity
- Label found pixel as component 2
- ...

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Result of connected component labeling:

	A	B	C	D	E	F	G	H	I	J	K	L	M	N	O	P	Q	R	S	T	U	V	W	X
35	255	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
36	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
37	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
38	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
39	0	0	0	0	0	0	0	0	255	255	255	0	0	0	0	0	0	0	0	0	0	0	0	0
40	0	0	0	0	0	0	255	255	255	255	255	255	0	0	0	0	0	0	0	0	0	0	0	0
41	0	0	0	0	0	255	255	255	255	255	255	255	255	255	0	0	0	0	0	0	0	0	0	0
42	0	0	0	0	255	255	255	255	255	255	255	255	255	255	0	0	0	0	0	0	0	0	0	0
43	0	0	0	0	255	255	255	255	255	255	255	255	255	255	0	0	0	0	0	0	0	0	0	0
44	0	0	0	255	255	255	255	255	255	255	255	255	255	255	0	0	0	0	0	0	0	0	0	0
45	0	0	0	255	255	255	255	255	255	255	255	255	255	255	0	0	0	0	0	0	0	0	0	0
46	0	0	0	255	255	255	255	255	255	255	255	255	255	255	0	0	0	0	0	0	0	0	0	25
47	0	0	0	255	255	255	255	255	255	255	255	255	255	255	0	0	0	0	0	0	0	0	255	25
48	0	0	0	255	255	255	255	255	255	255	255	255	255	0	0	0	0	0	0	0	0	255	255	25
49	0	0	0	255	255	255	255	255	255	255	255	255	255	0	0	0	0	0	0	0	0	255	255	25
50	0	0	0	255	255	255	255	255	255	255	255	255	255	0	0	0	0	0	0	0	255	255	255	25
51	0	0	0	0	255	255	255	255	255	255	255	255	0	0	0	0	0	0	0	255	255	255	255	25
52	0	0	0	0	0	255	255	255	255	255	255	0	0	0	0	0	0	0	0	255	255	255	255	25
53	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	255	255	255	255	255	25
54	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	255	255	255	255	255	25
55	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	255	255	255	255	255	255	25
56	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	255	255	255	255	255	255	25
57	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	255	255	255	255	255	255	25
58	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	255	255	255	255	255	255	25
59	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	255	255	255	255	255	255	255	25
60	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	255	255	255	255	255	255	255	25
61	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	255	255	255	255	255	255	255	25
62	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	255	255	255	255	255	255	255	25
63	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	255	255	255	255	255	255	255	25
64	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	255	255	255	255	255	255	25
65	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	255	255	255	255	255	255	25
66	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	255	255	255	255	255	255	25

$\Rightarrow$

	A	B	C	D	E	F	G	H	I	J	K	L	M	N	O	P	Q	R	S	T	U	V	W	
35	10	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	
36	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	
37	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	
38	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	
39	0	0	0	0	0	0	0	0	13	13	13	0	0	0	0	0	0	0	0	0	0	0	0	
40	0	0	0	0	0	0	13	13	13	13	13	13	0	0	0	0	0	0	0	0	0	0	0	
41	0	0	0	0	0	13	13	13	13	13	13	13	13	13	0	0	0	0	0	0	0	0	0	
42	0	0	0	0	13	13	13	13	13	13	13	13	13	13	0	0	0	0	0	0	0	0	0	
43	0	0	0	0	13	13	13	13	13	13	13	13	13	13	0	0	0	0	0	0	0	0	0	
44	0	0	0	13	13	13	13	13	13	13	13	13	13	13	0	0	0	0	0	0	0	0	0	
45	0	0	0	13	13	13	13	13	13	13	13	13	13	13	0	0	0	0	0	0	0	0	0	
46	0	0	0	13	13	13	13	13	13	13	13	13	13	13	0	0	0	0	0	0	0	0	0	1
47	0	0	0	13	13	13	13	13	13	13	13	13	13	13	0	0	0	0	0	0	0	0	17	1
48	0	0	0	13	13	13	13	13	13	13	13	13	13	0	0	0	0	0	0	0	0	17	17	1
49	0	0	0	13	13	13	13	13	13	13	13	13	13	0	0	0	0	0	0	0	0	17	17	1
50	0	0	0	13	13	13	13	13	13	13	13	13	13	0	0	0	0	0	0	0	17	17	17	1
51	0	0	0	0	13	13	13	13	13	13	13	13	0	0	0	0	0	0	0	17	17	17	17	1
52	0	0	0	0	0	13	13	13	13	13	13	0	0	0	0	0	0	0	0	17	17	17	17	1
53	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	17	17	17	17	17	1
54	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	17	17	17	17	17	1
55	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	17	17	17	17	17	17	1
56	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	17	17	17	17	17	17	1
57	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	17	17	17	17	17	17	1
58	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	17	17	17	17	17	17	1
59	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	17	17	17	17	17	17	17	1
60	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	17	17	17	17	17	17	17	1
61	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	17	17	17	17	17	17	17	1
62	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	17	17	17	17	17	17	17	1
63	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	17	17	17	17	17	17	17	1
64	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	17	17	17	17	17	17	1
65	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	17	17	17	17	17	17	1
66	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	17	17	17	17	17	17	1

Abbildung: Result: particle indices instead of intensities

Further Literature

- **General**

[CRL01] Thomas H. Cormen, Ronald L. Rivest, and Charles E. Leiserson.
Introduction to Algorithms.
MIT Press, Cambridge, Mass, 2001.

[MS08] Kurt Mehlhorn and Peter Sanders.
Algorithms and data structures, 2008.
https://people.mpi-inf.mpg.de/~mehlhorn/ftp/Mehlhorn-Sanders-Toolbox.pdf.

Further Literature

- **Graph-Search**

[Wika] Breadth-first search
https://en.wikipedia.org/wiki/Breadth-first_search

[Wikb] Depth-first search
https://en.wikipedia.org/wiki/Depth-first_search

- **Graph-Connectivity**

[Wik] Connectivity (graph theory)
https://en.wikipedia.org/wiki/Connectivity_(graph_theory)