Algorithmns and Datastructures

Levenshtein distance, Dynamic programming

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Algorithmns and Datastructures, February 2017

Structure

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Introduction

Edit distance

Edit distance:

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- Measurement for similarity of two words / strings

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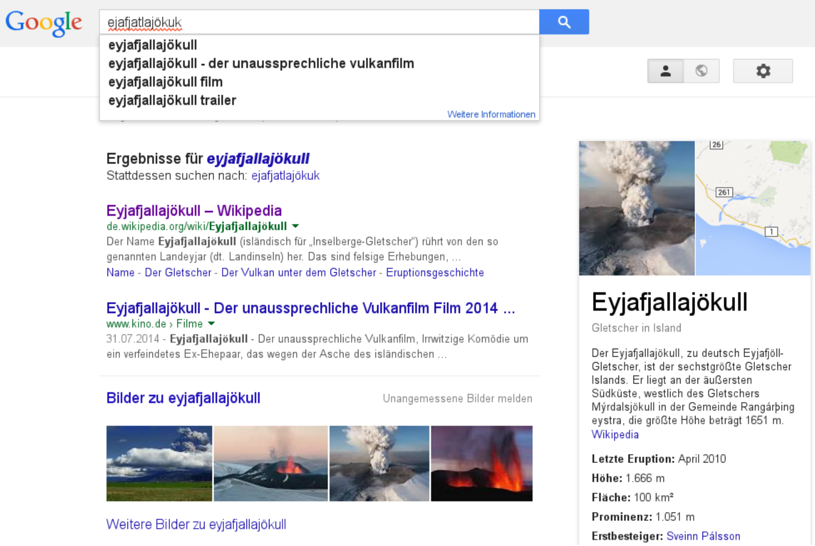
- Algorithm for efficient calculation
- General principle: dynamic programming

Introduction

Motivation: Error tolerant string comparison



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- Bioinformatics: Similarity of DNA-sequences

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Google-Scholar entry:

[HTML] Gapped **BLAST** and PSI-**BLAST**: a new generation of protein database search programs
SF Altschul, TL Madden, AA Schäffer… - Nucleic acids …, 1997 - Oxford Univ Press
Abstract The **BLAST** programs are widely used tools for searching protein and DNA databases for sequence similarities. For protein comparisons, a variety of definitional, algorithmic and statistical refinements described here permits the execution time of the **...**
Zitiert von: $\boxed{58805}$ Ähnliche Artikel Alle 135 Versionen Zitieren Speichern

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Definition of edit distance: (*Levenshtein-distance*)

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- Edit distance $\mathrm{ED}(x, y)$ of x and y:
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Edit distance
Example

1 2 3 4 5
DOOF

B L OED

1 2 3 4 5
DOOF
$\downarrow$ `replace(1, B)`
BOOF

B L O E D

Edit distance
Example

1 2 3 4 5
DOOF
$\downarrow$ `replace(1, B)`
BOOF
$\downarrow$ `replace(2, L)`
BLOF

BLOED

1 2 3 4 5
DOOF

↓ `replace(1, B)`

BOOF

↓ `replace(2, L)`

BLOF

↓ `insert(4, E)`

BLOEF

BLOED

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```
1 2 3 4 5
DOOF
   ↓      replace(1, B)
BOOF
   ↓      replace(2, L)
BLOF
   ↓      insert(4, E)
BLOEF
   ↓      replace(5, D)
BLOED
```

Edit distance

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1 2 3 4 5
DOOF
↓ `replace(1, B)`
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↓ `insert(4, E)`
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$$\underbrace{\texttt{replace(1, B)}\ \texttt{replace(2, L)}\ \texttt{insert(4, E)}\ \texttt{replace(5, D)}}_{\text{ED}=4}$$

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DOOF
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1 2 3 4 5
B LOED

DOOF

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DOOF	
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BLOF	
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BLOEF	
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BLOED	
	ED=4

1 2 3 4 5	
BLOED	
↓	`replace(5, F)`
BLOEF	
DOOF	

Edit distance
Example

1 2 3 4 5 DOOF		1 2 3 4 5 B LOED	
↓	`replace(1, B)`	↓	`replace(5, F)`
BOOF		B LOEF	
↓	`replace(2, L)`	↓	`delete(4)`
B LOF		B LOF	
↓	`insert(4, E)`		
B LOEF			
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B LOED		DOOF	

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↓	`replace(2, L)`	↓	`delete(4)`
B LOF		B LOF	
↓	`insert(4, E)`	↓	`replace(2, O)`
B LOEF		B OOF	
↓	`replace(5, D)`		
B LOED		DOOF	

ED=4

Edit distance

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ED=4

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B L O F	
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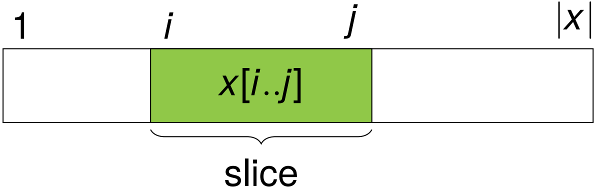

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- $\mathrm{ED}(x,y) = \mathrm{ED}(y,x)$
- $\mathrm{ED}(x,\varepsilon) = |x|$
- $\mathrm{ED}(x,y) \geq \mathrm{abs}(|x| - |y|)$

$$\mathrm{abs}(x) = \begin{cases} x & \text{if } x \geq 0 \\ -x & \text{else} \end{cases}$$

Trivial facts:

- $\mathrm{ED}(x,y) = \mathrm{ED}(y,x)$
- $\mathrm{ED}(x,\varepsilon) = |x|$
- $\mathrm{ED}(x,y) \geq \mathrm{abs}(|x| - |y|)$ $\qquad \mathrm{abs}(x) = \begin{cases} x & \text{if } x \geq 0 \\ -x & \text{else} \end{cases}$
- $\mathrm{ED}(x,y) \leq \mathrm{ED}(x[1..n-1], y[1..m-1]) + 1$ $\qquad n = |x|,\ m = |y|$

Solutions based on examples:

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- Searching biggest substrings can yield the solution but doesn't have to

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Recursive approach:

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Recursive approach:

- Dividing in two halves? Not a good idea:

$\mathrm{ED}(GRAU, RAUM) = 2$ but $\mathrm{ED}(GR, RA) + \mathrm{ED}(AU, UM) = 4$

Edit distance

Solving examples

Solutions based on examples:

- From VERIEN to FERIEN?
- From MEXIKO to AMERIKA?
- From AAEBEAABEAREEAEBA to RBEAAEEBAAAEBBAEAE?
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- Finding "smaller" sub problems?
  Let's try it!

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Terminology:

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- Let $\sigma_1, \ldots, \sigma_k$ be a sequence of k operations where $k = \mathrm{ED}(x, y)$ for $x \rightarrow y$ (transform x into y)
  (We do not know this sequence but we assume it exists)

Edit distance

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BOOF		AUDOOF	
$\downarrow$	`replace(2, L)`	$\downarrow$	`delete(1)`
BLOF		UDOOF	
$\downarrow$	insert(4, E)	$\downarrow$	`delete(1)`
BLOEF		DOOF	
$\downarrow$	`replace(5, D)`	$\downarrow$	`insert(4, O)`
BLOED		DOOOF	

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1	2	3	4	5
D	O	O	F	
B	L	O	E	D

1	2	3	4	5	6	7
S	A	U	D	O	O	F
D	O	O	O	F		

Consider the last operation:

Consider the last operation:

- Solve blue part recursively

Edit distance

Recursive approach

Consider the last operation:

- Solve blue part recursively

DOOF
↓↓↓↓
BLOE
↓insert
BLOED

Figure: Case 1a

DOOF
↓↓↓↓↓↓
BLOEDF
↓delete
BLOED

Figure: Case 1b

DOOF
↓↓↓↓↓
BLOEF
↓replace
BLOED

Figure: Case 1c

Consider the last operation:

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Consider the last operation:

- Solve blue part recursively

W I N T E R
↓ ↓ ↓ ↓ ↓ ↓
S O M M E R
↓nothing
S O M M E R

Figure: Case 2

Display of solution:

- Alignment
- Example:

_	_	_	B	L	O	E	D
S	A	U	B	L	O	E	D

Dynamic programming:

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- Instances of Bellman's principle of optimality:

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  - Shortest paths

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Figure: Richard Bellman (1920 - 1984)

- Optimal solutions consist of optimal partial solutions
  - Shortest paths: Each partial path has to be optimal
  - Edit distance: Each partial alignment has to be optimal

- Always solvable through dynamic programming (Caching of optimal partial solutions)

Case analysis:

Edit distance

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  - $\sigma_1, \ldots, \sigma_{k-1}$: $x \to z$ and σ_k: $z \to y$
    Example:

$$x = \mathrm{DOOF},\ z = \mathrm{SAUBLOEF},\ y = \mathrm{SAUBLOED}$$

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    Example:

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  - Let $n = |x|$, $m = |y|$, $m' = |z|$
  - We note $m' \in \{m-1, m, m+1\}$ why?

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  - Case 1c: $\sigma_k = \texttt{replace}(m', y[m])$ [then $m' = m$]
- Case 2: σ_k does nothing at the outer end:
  - Then $z[m'] = y[m]$ and $x[n'] = z[m']$ and with that $\sigma_1, \ldots, \sigma_{k-1}$: $x[1..n-1] \to y[1..m-1]$ and $x[n] = y[m]$

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- Case 1a (`insert`): $\sigma_1, \ldots, \sigma_{k-1}$: $x \qquad \rightarrow y[1..m-1]$

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This results in the recursive formula:

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- Case 2 (`nothing`): $\sigma_1,\dots,\sigma_k$: $x[1..n-1] \rightarrow y[1..m-1]$

This results in the recursive formula:

- For $|x| > 0$ and $|y| > 0$ is $\mathrm{ED}(x,y)$ the minimum of
  - $\mathrm{ED}(x, y[1..m-1]) + 1$ and
  - $\mathrm{ED}(x[1..n-1], y) + 1$ and

Edit distance

Case analysis:

- Case 1a (`insert`): $\sigma_1, \ldots, \sigma_{k-1}: x \rightarrow y[1..m-1]$
- Case 1b (`delete`): $\sigma_1, \ldots, \sigma_{k-1}: x[1..n-1] \rightarrow y$
- Case 1c (`replace`): $\sigma_1, \ldots, \sigma_{k-1}: x[1..n-1] \rightarrow y[1..m-1]$
- Case 2 (`nothing`): $\sigma_1, \ldots, \sigma_k: x[1..n-1] \rightarrow y[1..m-1]$

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Edit distance

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  - $\mathrm{ED}(x[1..n-1], y[1..m-1]) + 0$ if $x[n] = y[m]$

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- Case 1b (`delete`): $\sigma_1,\ldots,\sigma_{k-1}: x[1..n-1] \to y$
- Case 1c (`replace`): $\sigma_1,\ldots,\sigma_{k-1}: x[1..n-1] \to y[1..m-1]$
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  - $\mathrm{ED}(x[1..n-1], y[1..m-1]) + 0$ if $x[n] = y[m]$
- For $|x| = 0$ is $\mathrm{ED}(x,y) = |y|$

Edit distance

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This results in the recursive formula:

- For $|x| > 0$ and $|y| > 0$ is $\mathrm{ED}(x, y)$ the minimum of
  - $\mathrm{ED}(x, y[1..m-1]) + 1$ and
  - $\mathrm{ED}(x[1..n-1], y) + 1$ and
  - $\mathrm{ED}(x[1..n-1], y[1..m-1]) + 1$ if $x[n] \neq y[m]$
  - $\mathrm{ED}(x[1..n-1], y[1..m-1]) + 0$ if $x[n] = y[m]$
- For $|x| = 0$ is $\mathrm{ED}(x, y) = |y|$
- For $|y| = 0$ is $\mathrm{ED}(x, y) = |x|$

```python
def edit_distance(x, y):
    if len(x) == 0:
        return len(y)
    if len(y) == 0:
        return len(x)

    ed1 = edit_distance(x, y[:-1]) + 1
    ed2 = edit_distance(x[:-1], y) + 1
    ed3 = edit_distance(x[:-1], y[:-1])
    if x[-1] != y[-1]:
        ed3 += 1

    return min(ed1, ed2, ed3)
```

Recursive program:

Recursive program:

- The algorithm results in the following recursive formular:

$$\begin{aligned} T(n,m) &= T(n-1,m) + T(n,m-1) + T(n-1,m-1) + 1 \\ &\geq T(n-1,m-1) + T(n-1,m-1) + T(n-1,m-1) \\ &= 3 \cdot T(n-1,m-1) \end{aligned}$$

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$$\begin{aligned} T(n,m) &= T(n-1,m) + T(n,m-1) + T(n-1,m-1) + 1 \\ &\geq T(n-1,m-1) + T(n-1,m-1) + T(n-1,m-1) \\ &= 3 \cdot T(n-1,m-1) \end{aligned}$$

- This results in $T(n,n) \geq 3^n$

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- The algorithm results in the following recursive formular:

$$
\begin{aligned}
T(n,m) &= T(n-1,m) + T(n,m-1) + T(n-1,m-1) + 1 \\
&\geq T(n-1,m-1) + T(n-1,m-1) + T(n-1,m-1) \\
&= 3 \cdot T(n-1,m-1)
\end{aligned}
$$

- This results in $T(n,n) \geq 3^n$

$\Rightarrow$ The runtime is at least exponential

Dynamic programming:

Dynamic programming:

- We create a table with all possible combination of substrings and save calculated entries
- This results in a runtime and space consumption of $O(n \cdot m)$

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Visualization on the next slide:

Edit distance

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Visualization on the next slide:

- Operations always refer to the last position (indices are omitted)

Dynamic programming:

- We create a table with all possible combination of substrings and save calculated entries
- This results in a runtime and space consumption of $O(n \cdot m)$

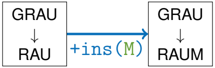
Visualization on the next slide:

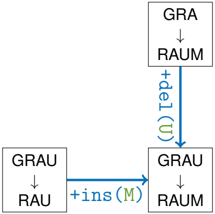
- Operations always refer to the last position (indices are omitted)
- We also display the replaced character on a `replace` operation to visualize operations without costs
  $\Rightarrow$ `repl(A, A)`

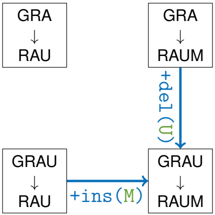
GRAU

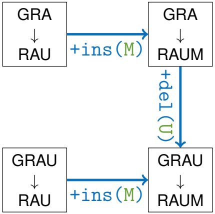
↓

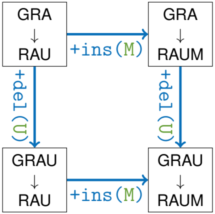
RAUM

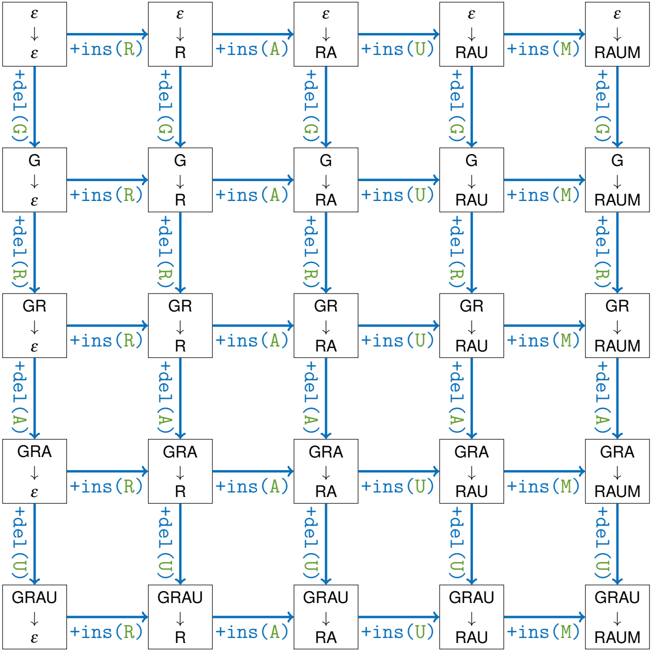

GRAU
↓
RAU
+ins(M)
GRAU
↓
RAUM


GRA
↓
RAUM
+del(U)
GRAU
↓
RAU
+ins(M)
GRAU
↓
RAUM

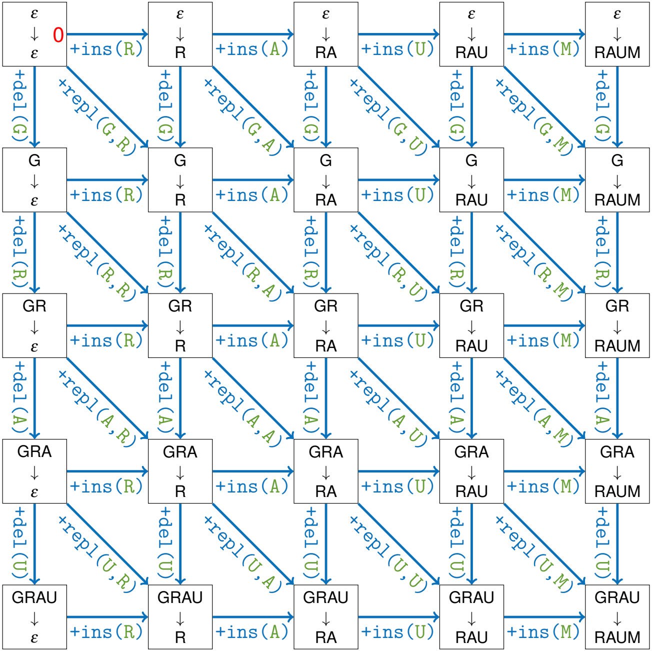

GRA
RAU
GRA
RAUM
+del(U)
GRAU
RAU
+ins(M)
GRAU
RAUM

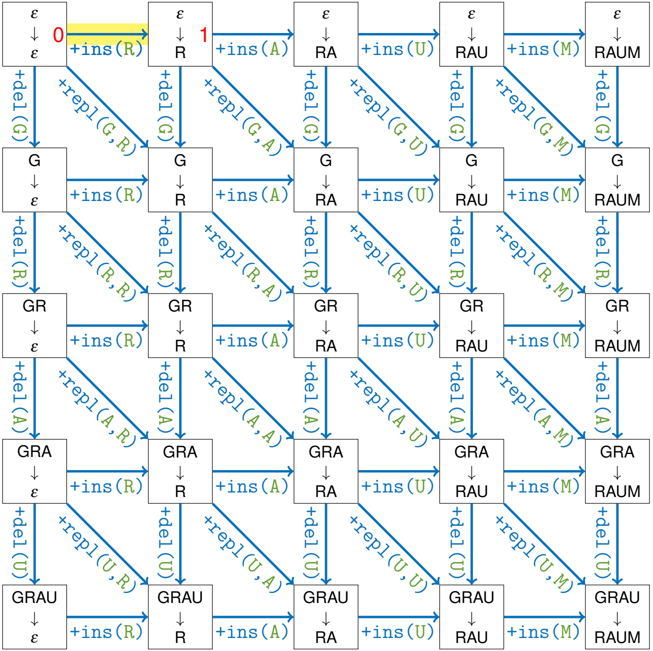

GRA
↓
RAU
+ins(M)
GRA
↓
RAUM
+del(U)
GRAU
↓
RAU
+ins(M)
GRAU
↓
RAUM

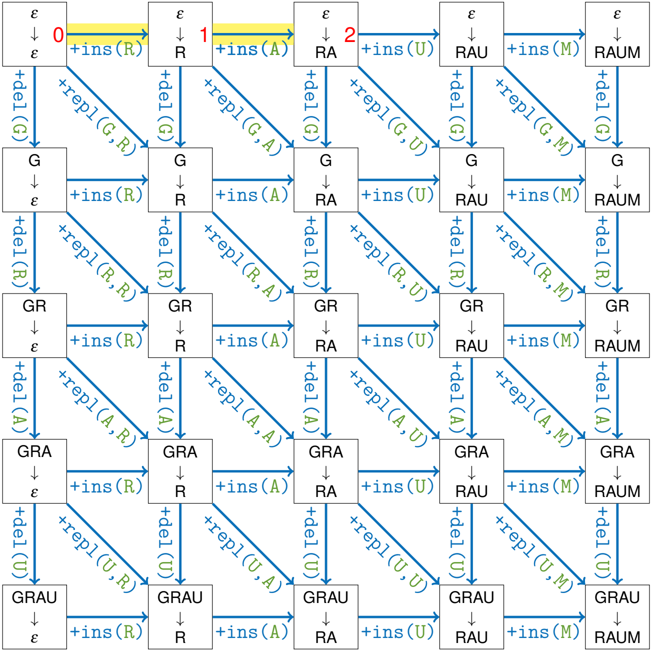

GRA
↓
RAU
+ins(M)
GRA
↓
RAUM
+del(U)
+del(U)
GRAU
↓
RAU
+ins(M)
GRAU
↓
RAUM

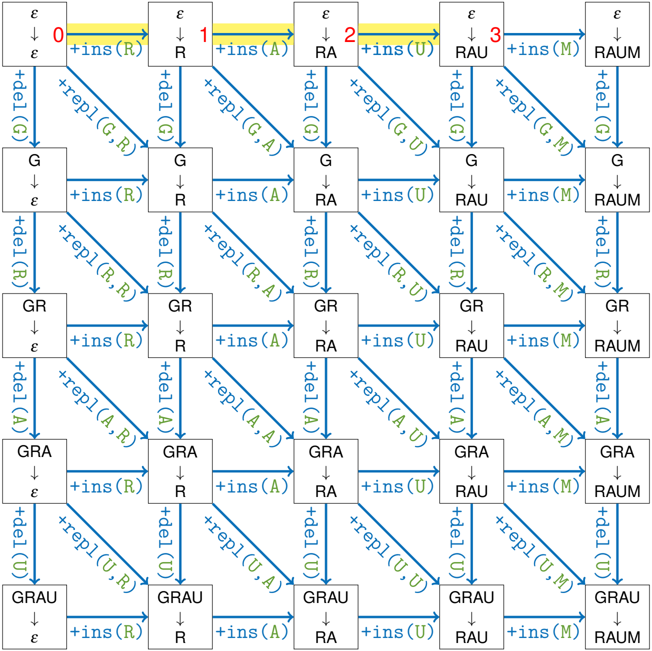

ε ↓ ε
+ins(R)
ε ↓ R
+ins(A)
ε ↓ RA
+ins(U)
ε ↓ RAU
+ins(M)
ε ↓ RAUM
+del(G)
G ↓ ε
G ↓ R
G ↓ RA
G ↓ RAU
G ↓ RAUM
+del(R)
GR ↓ ε
GR ↓ R
GR ↓ RA
GR ↓ RAU
GR ↓ RAUM
+del(A)
GRA ↓ ε
GRA ↓ R
GRA ↓ RA
GRA ↓ RAU
GRA ↓ RAUM
+del(U)
GRAU ↓ ε
GRAU ↓ R
GRAU ↓ RA
GRAU ↓ RAU
GRAU ↓ RAUM

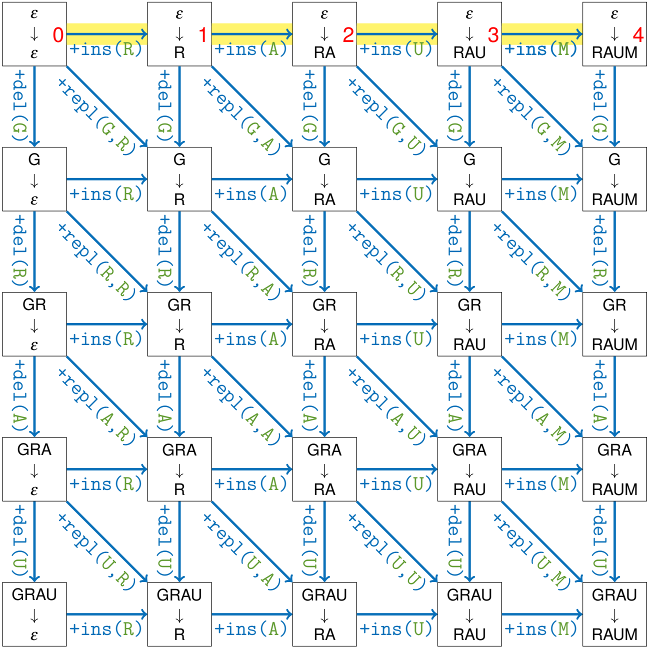
Fast algorithm:
We can determine the edit distance for all combination of partial strings from the top left to bottom right.

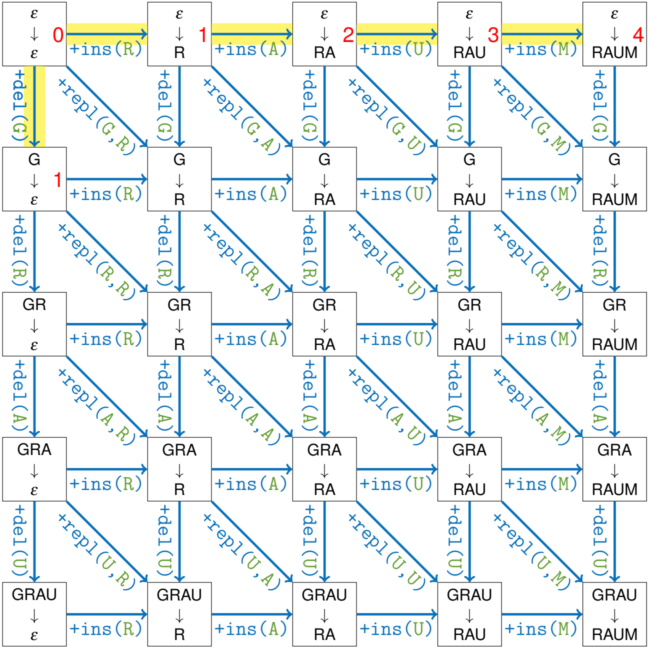

ε ↓ ε
0
+ins(R)
ε ↓ R
+ins(A)
ε ↓ RA
+ins(U)
ε ↓ RAU
+ins(M)
ε ↓ RAUM
+del(G)
+repl(G,R)
+repl(G,A)
+repl(G,U)
+repl(G,M)
G ↓ ε
G ↓ R
G ↓ RA
G ↓ RAU
G ↓ RAUM
+del(R)
+repl(R,R)
+repl(R,A)
+repl(R,U)
+repl(R,M)
GR ↓ ε
GR ↓ R
GR ↓ RA
GR ↓ RAU
GR ↓ RAUM
+del(A)
+repl(A,R)
+repl(A,A)
+repl(A,U)
+repl(A,M)
GRA ↓ ε
GRA ↓ R
GRA ↓ RA
GRA ↓ RAU
GRA ↓ RAUM
+del(U)
+repl(U,R)
+repl(U,A)
+repl(U,U)
+repl(U,M)
GRAU ↓ ε
GRAU ↓ R
GRAU ↓ RA
GRAU ↓ RAU
GRAU ↓ RAUM

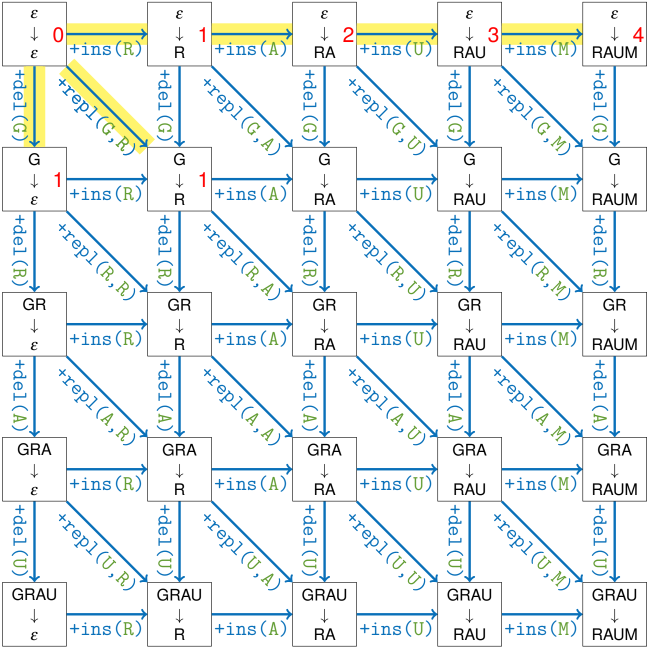

ε ↓ ε
0
+ins(R)
ε ↓ R
1
+ins(A)
ε ↓ RA
+ins(U)
ε ↓ RAU
+ins(M)
ε ↓ RAUM
+del(G)
+repl(G,R)
+repl(G,A)
+repl(G,U)
+repl(G,M)
G ↓ ε
G ↓ R
G ↓ RA
G ↓ RAU
G ↓ RAUM
+del(R)
+repl(R,R)
+repl(R,A)
+repl(R,U)
+repl(R,M)
GR ↓ ε
GR ↓ R
GR ↓ RA
GR ↓ RAU
GR ↓ RAUM
+del(A)
+repl(A,R)
+repl(A,A)
+repl(A,U)
+repl(A,M)
GRA ↓ ε
GRA ↓ R
GRA ↓ RA
GRA ↓ RAU
GRA ↓ RAUM
+del(U)
+repl(U,R)
+repl(U,A)
+repl(U,U)
+repl(U,M)
GRAU ↓ ε
GRAU ↓ R
GRAU ↓ RA
GRAU ↓ RAU
GRAU ↓ RAUM

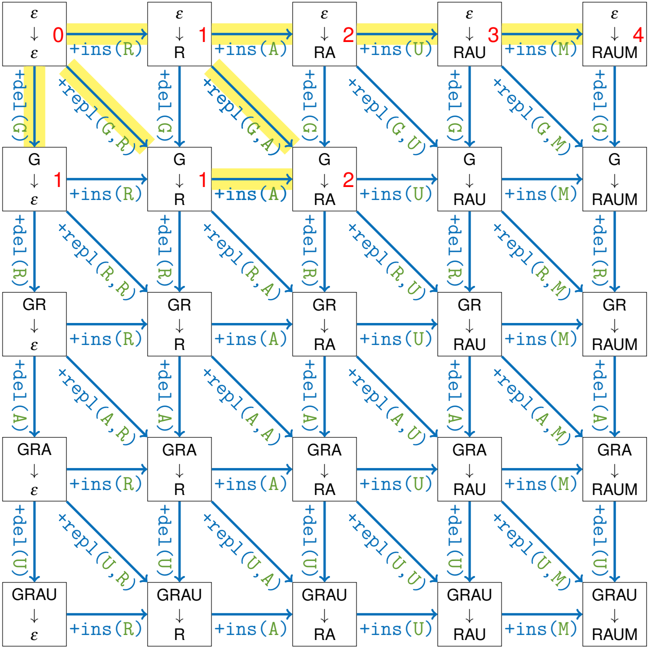

0
1
2
ε → ε
ε → R
ε → RA
ε → RAU
ε → RAUM
G → ε
G → R
G → RA
G → RAU
G → RAUM
GR → ε
GR → R
GR → RA
GR → RAU
GR → RAUM
GRA → ε
GRA → R
GRA → RA
GRA → RAU
GRA → RAUM
GRAU → ε
GRAU → R
GRAU → RA
GRAU → RAU
GRAU → RAUM
+ins(R)
+ins(A)
+ins(U)
+ins(M)
+del(G)
+del(R)
+del(A)
+del(U)
+repl(G,R)
+repl(G,A)
+repl(G,U)
+repl(G,M)
+repl(R,R)
+repl(R,A)
+repl(R,U)
+repl(R,M)
+repl(A,R)
+repl(A,A)
+repl(A,U)
+repl(A,M)
+repl(U,R)
+repl(U,A)
+repl(U,U)
+repl(U,M)

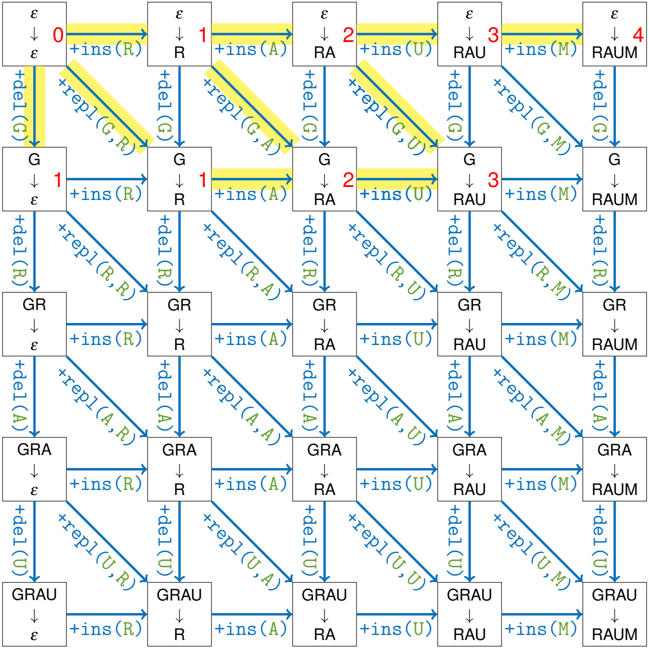

ε ↓ ε
ε ↓ R
ε ↓ RA
ε ↓ RAU
ε ↓ RAUM
0
1
2
3
+ins(R)
+ins(A)
+ins(U)
+ins(M)
+del(G)
+del(R)
+del(A)
+del(U)
+repl(G,R)
+repl(G,A)
+repl(G,U)
+repl(G,M)
+repl(R,R)
+repl(R,A)
+repl(R,U)
+repl(R,M)
+repl(A,R)
+repl(A,A)
+repl(A,U)
+repl(A,M)
+repl(U,R)
+repl(U,A)
+repl(U,U)
+repl(U,M)
G ↓ ε
G ↓ R
G ↓ RA
G ↓ RAU
G ↓ RAUM
GR ↓ ε
GR ↓ R
GR ↓ RA
GR ↓ RAU
GR ↓ RAUM
GRA ↓ ε
GRA ↓ R
GRA ↓ RA
GRA ↓ RAU
GRA ↓ RAUM
GRAU ↓ ε
GRAU ↓ R
GRAU ↓ RA
GRAU ↓ RAU
GRAU ↓ RAUM

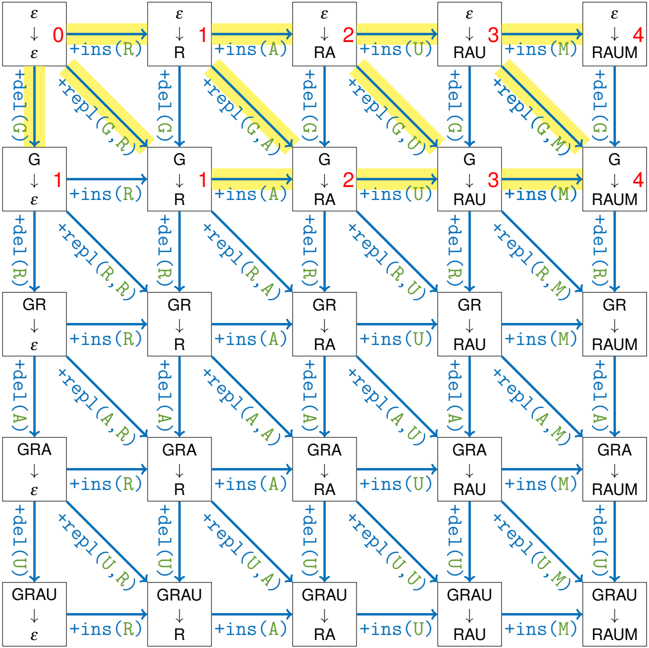

ε ↓ ε
ε ↓ R
ε ↓ RA
ε ↓ RAU
ε ↓ RAUM
0
1
2
3
4
G ↓ ε
G ↓ R
G ↓ RA
G ↓ RAU
G ↓ RAUM
GR ↓ ε
GR ↓ R
GR ↓ RA
GR ↓ RAU
GR ↓ RAUM
GRA ↓ ε
GRA ↓ R
GRA ↓ RA
GRA ↓ RAU
GRA ↓ RAUM
GRAU ↓ ε
GRAU ↓ R
GRAU ↓ RA
GRAU ↓ RAU
GRAU ↓ RAUM
+ins(R)
+ins(A)
+ins(U)
+ins(M)
+del(G)
+del(R)
+del(A)
+del(U)
+repl(G,R)
+repl(G,A)
+repl(G,U)
+repl(G,M)
+repl(R,R)
+repl(R,A)
+repl(R,U)
+repl(R,M)
+repl(A,R)
+repl(A,A)
+repl(A,U)
+repl(A,M)
+repl(U,R)
+repl(U,A)
+repl(U,U)
+repl(U,M)


ε → ε
0
+ins(R)
ε → R
1
+ins(A)
ε → RA
2
+ins(U)
ε → RAU
3
+ins(M)
ε → RAUM
4
+del(G)
+repl(G,R)
+repl(G,A)
+repl(G,U)
+repl(G,M)
G → ε
1
G → R
G → RA
G → RAU
G → RAUM
+del(R)
+repl(R,R)
+repl(R,A)
+repl(R,U)
+repl(R,M)
GR → ε
GR → R
GR → RA
GR → RAU
GR → RAUM
+del(A)
+repl(A,R)
+repl(A,A)
+repl(A,U)
+repl(A,M)
GRA → ε
GRA → R
GRA → RA
GRA → RAU
GRA → RAUM
+del(U)
+repl(U,R)
+repl(U,A)
+repl(U,U)
+repl(U,M)
GRAU → ε
GRAU → R
GRAU → RA
GRAU → RAU
GRAU → RAUM

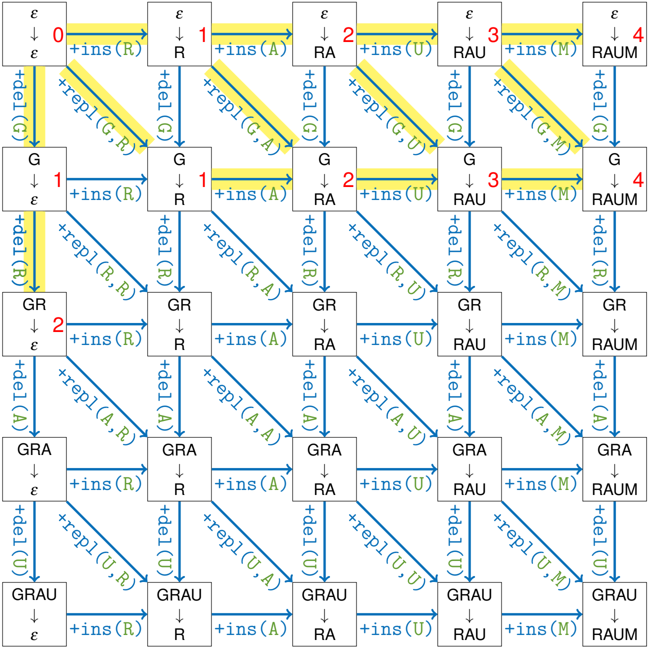

ε ↓ ε 0
ε ↓ R 1
ε ↓ RA 2
ε ↓ RAU 3
ε ↓ RAUM 4
+ins(R)
+ins(A)
+ins(U)
+ins(M)
+del(G)
+repl(G,R)
+repl(G,A)
+repl(G,U)
+repl(G,M)
G ↓ ε 1
G ↓ R 1
G ↓ RA
G ↓ RAU
G ↓ RAUM
+del(R)
+repl(R,R)
+repl(R,A)
+repl(R,U)
+repl(R,M)
GR ↓ ε
GR ↓ R
GR ↓ RA
GR ↓ RAU
GR ↓ RAUM
+del(A)
+repl(A,R)
+repl(A,A)
+repl(A,U)
+repl(A,M)
GRA ↓ ε
GRA ↓ R
GRA ↓ RA
GRA ↓ RAU
GRA ↓ RAUM
+del(U)
+repl(U,R)
+repl(U,A)
+repl(U,U)
+repl(U,M)
GRAU ↓ ε
GRAU ↓ R
GRAU ↓ RA
GRAU ↓ RAU
GRAU ↓ RAUM

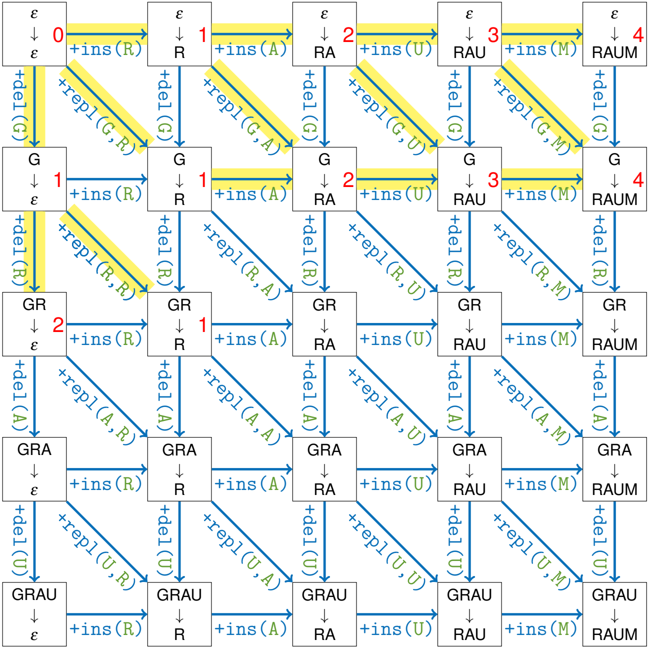



ε → ε 0
ε → R 1
ε → RA 2
ε → RAU 3
ε → RAUM 4
+ins(R)
+ins(A)
+ins(U)
+ins(M)
+del(G)
+repl(G,R)
+repl(G,A)
+repl(G,U)
+repl(G,M)
G → ε 1
G → R 1
G → RA 2
G → RAU 3
G → RAUM
+del(R)
+repl(R,R)
+repl(R,A)
+repl(R,U)
+repl(R,M)
GR → ε
GR → R
GR → RA
GR → RAU
GR → RAUM
+del(A)
+repl(A,R)
+repl(A,A)
+repl(A,U)
+repl(A,M)
GRA → ε
GRA → R
GRA → RA
GRA → RAU
GRA → RAUM
+del(U)
+repl(U,R)
+repl(U,A)
+repl(U,U)
+repl(U,M)
GRAU → ε
GRAU → R
GRAU → RA
GRAU → RAU
GRAU → RAUM

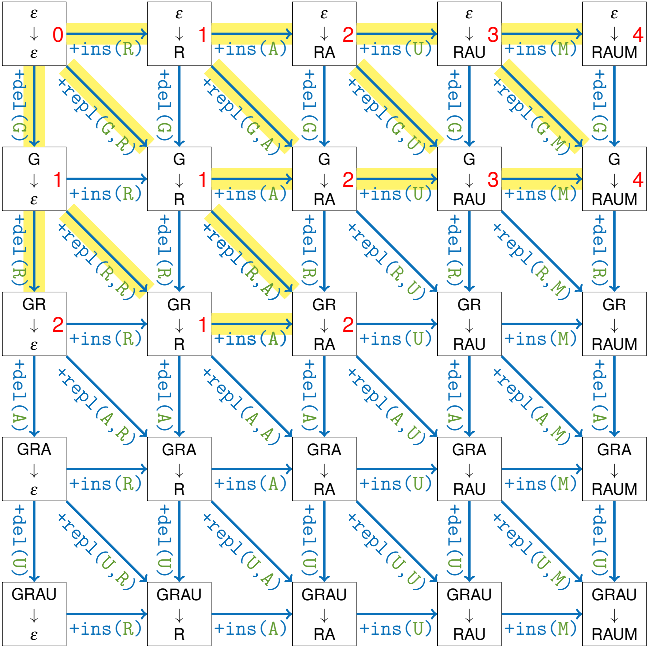


ε → ε 0
ε → R 1
ε → RA 2
ε → RAU 3
ε → RAUM 4
G → ε 1
G → R 1
G → RA 2
G → RAU 3
G → RAUM 4
GR → ε
GR → R
GR → RA
GR → RAU
GR → RAUM
GRA → ε
GRA → R
GRA → RA
GRA → RAU
GRA → RAUM
GRAU → ε
GRAU → R
GRAU → RA
GRAU → RAU
GRAU → RAUM
+ins(R)
+ins(A)
+ins(U)
+ins(M)
+del(G)
+del(R)
+del(A)
+del(U)
+repl(G,R)
+repl(G,A)
+repl(G,U)
+repl(G,M)
+repl(R,R)
+repl(R,A)
+repl(R,U)
+repl(R,M)
+repl(A,R)
+repl(A,A)
+repl(A,U)
+repl(A,M)
+repl(U,R)
+repl(U,A)
+repl(U,U)
+repl(U,M)


ε ↓ ε
0
ε ↓ R
1
ε ↓ RA
2
ε ↓ RAU
3
ε ↓ RAUM
4
+ins(R)
+ins(A)
+ins(U)
+ins(M)
+del(G)
+repl(G,R)
+repl(G,A)
+repl(G,U)
+repl(G,M)
G ↓ ε
1
G ↓ R
1
G ↓ RA
2
G ↓ RAU
3
G ↓ RAUM
4
+del(R)
+repl(R,R)
+repl(R,A)
+repl(R,U)
+repl(R,M)
GR ↓ ε
2
GR ↓ R
GR ↓ RA
GR ↓ RAU
GR ↓ RAUM
+del(A)
+repl(A,R)
+repl(A,A)
+repl(A,U)
+repl(A,M)
GRA ↓ ε
GRA ↓ R
GRA ↓ RA
GRA ↓ RAU
GRA ↓ RAUM
+del(U)
+repl(U,R)
+repl(U,A)
+repl(U,U)
+repl(U,M)
GRAU ↓ ε
GRAU ↓ R
GRAU ↓ RA
GRAU ↓ RAU
GRAU ↓ RAUM



ε → ε 0
ε → R 1
ε → RA 2
ε → RAU 3
ε → RAUM 4
G → ε 1
G → R 1
G → RA 2
G → RAU 3
G → RAUM 4
GR → ε 2
GR → R 1
GR → RA
GR → RAU
GR → RAUM
GRA → ε
GRA → R
GRA → RA
GRA → RAU
GRA → RAUM
GRAU → ε
GRAU → R
GRAU → RA
GRAU → RAU
GRAU → RAUM
+ins(R)
+ins(A)
+ins(U)
+ins(M)
+del(G)
+del(R)
+del(A)
+del(U)
+repl(G,R)
+repl(G,A)
+repl(G,U)
+repl(G,M)
+repl(R,R)
+repl(R,A)
+repl(R,U)
+repl(R,M)
+repl(A,R)
+repl(A,A)
+repl(A,U)
+repl(A,M)
+repl(U,R)
+repl(U,A)
+repl(U,U)
+repl(U,M)


ε ↓ ε 0
ε ↓ R 1
ε ↓ RA 2
ε ↓ RAU 3
ε ↓ RAUM 4
G ↓ ε 1
G ↓ R 1
G ↓ RA 2
G ↓ RAU 3
G ↓ RAUM 4
GR ↓ ε 2
GR ↓ R 1
GR ↓ RA 2
GR ↓ RAU
GR ↓ RAUM
GRA ↓ ε
GRA ↓ R
GRA ↓ RA
GRA ↓ RAU
GRA ↓ RAUM
GRAU ↓ ε
GRAU ↓ R
GRAU ↓ RA
GRAU ↓ RAU
GRAU ↓ RAUM
+ins(R)
+ins(A)
+ins(U)
+ins(M)
+del(G)
+del(R)
+del(A)
+del(U)
+repl(G,R)
+repl(G,A)
+repl(G,U)
+repl(G,M)
+repl(R,R)
+repl(R,A)
+repl(R,U)
+repl(R,M)
+repl(A,R)
+repl(A,A)
+repl(A,U)
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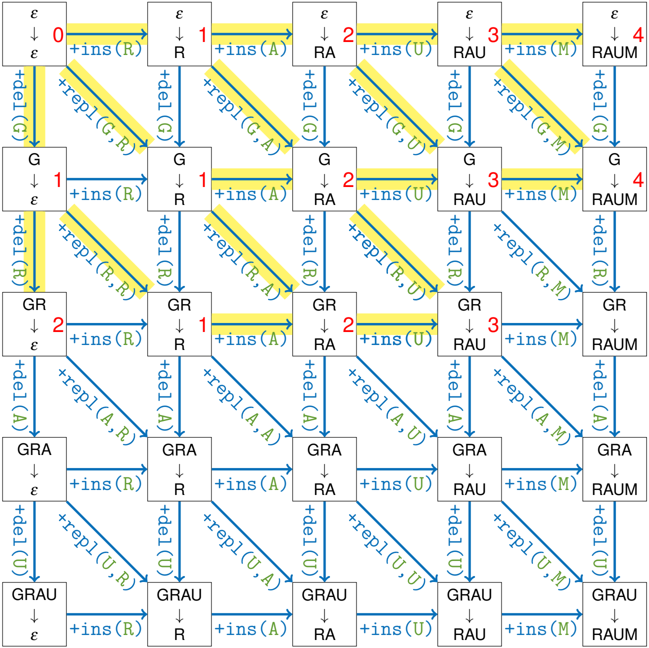
+repl(U,A)
+repl(U,U)
+repl(U,M)


ε ↓ ε 0
ε ↓ R 1
ε ↓ RA 2
ε ↓ RAU 3
ε ↓ RAUM 4
G ↓ ε 1
G ↓ R 1
G ↓ RA 2
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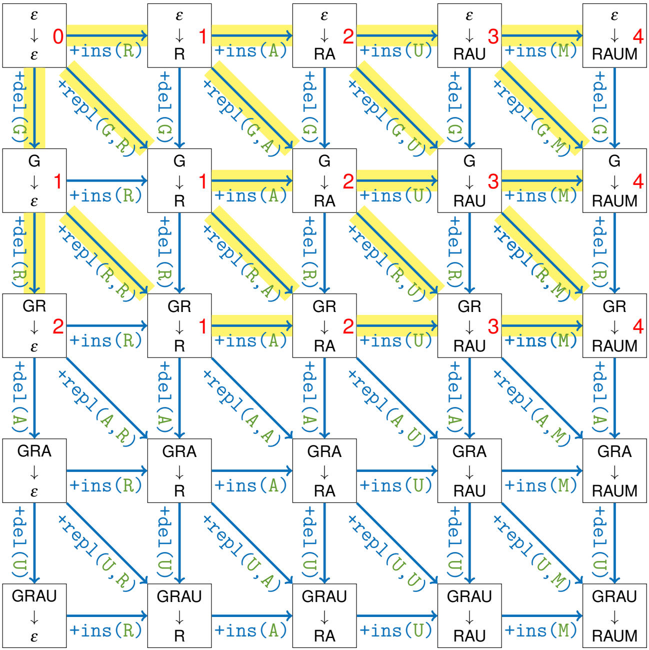
G ↓ RAUM 4
GR ↓ ε 2
GR ↓ R 1
GR ↓ RA 2
GR ↓ RAU 3
GR ↓ RAUM
GRA ↓ ε
GRA ↓ R
GRA ↓ RA
GRA ↓ RAU
GRA ↓ RAUM
GRAU ↓ ε
GRAU ↓ R
GRAU ↓ RA
GRAU ↓ RAU
GRAU ↓ RAUM
+ins(R)
+ins(A)
+ins(U)
+ins(M)
+del(G)
+del(R)
+del(A)
+del(U)
+repl(G,R)
+repl(G,A)
+repl(G,U)
+repl(G,M)
+repl(R,R)
+repl(R,A)
+repl(R,U)
+repl(R,M)
+repl(A,R)
+repl(A,A)
+repl(A,U)
+repl(A,M)
+repl(U,R)
+repl(U,A)
+repl(U,U)
+repl(U,M)


ε → ε 0
ε → R 1
ε → RA 2
ε → RAU 3
ε → RAUM 4
G → ε 1
G → R 1
G → RA 2
G → RAU 3
G → RAUM 4
GR → ε 2
GR → R 1
GR → RA 2
GR → RAU 3
GR → RAUM 4
GRA → ε
GRA → R
GRA → RA
GRA → RAU
GRA → RAUM
GRAU → ε
GRAU → R
GRAU → RA
GRAU → RAU
GRAU → RAUM
+ins(R)
+ins(A)
+ins(U)
+ins(M)
+del(G)
+del(R)
+del(A)
+del(U)
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+repl(G,A)
+repl(G,U)
+repl(G,M)
+repl(R,R)
+repl(R,A)
+repl(R,U)
+repl(R,M)
+repl(A,R)
+repl(A,A)
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+repl(U,A)
+repl(U,U)
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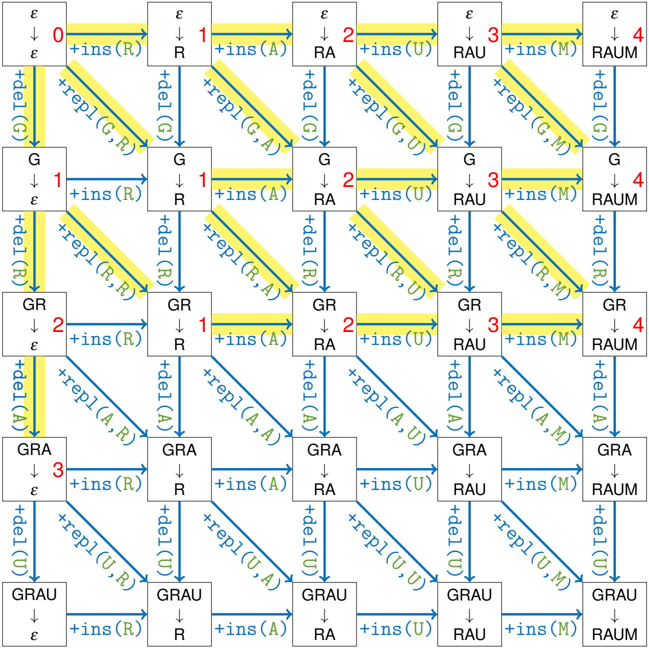
ε ↓ ε 0
ε ↓ R 1
ε ↓ RA 2
ε ↓ RAU 3
ε ↓ RAUM 4
G ↓ ε 1
G ↓ R 1
G ↓ RA 2
G ↓ RAU 3
G ↓ RAUM 4
GR ↓ ε 2
GR ↓ R 1
GR ↓ RA 2
GR ↓ RAU 3
GR ↓ RAUM 4
GRA ↓ ε 3
GRA ↓ R
GRA ↓ RA
GRA ↓ RAU
GRA ↓ RAUM
GRAU ↓ ε
GRAU ↓ R
GRAU ↓ RA
GRAU ↓ RAU
GRAU ↓ RAUM
+ins(R)
+ins(A)
+ins(U)
+ins(M)
+del(G)
+del(R)
+del(A)
+del(U)
+repl(G,R)
+repl(G,A)
+repl(G,U)
+repl(G,M)
+repl(R,R)
+repl(R,A)
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+repl(A,A)
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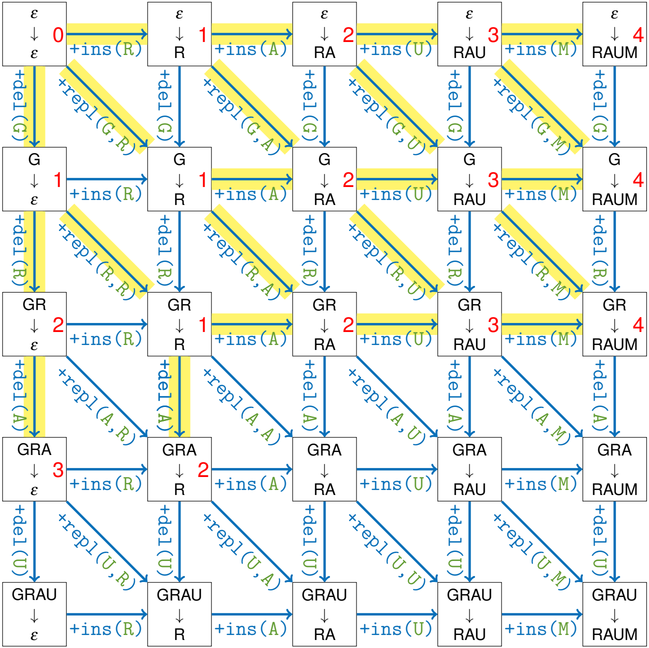
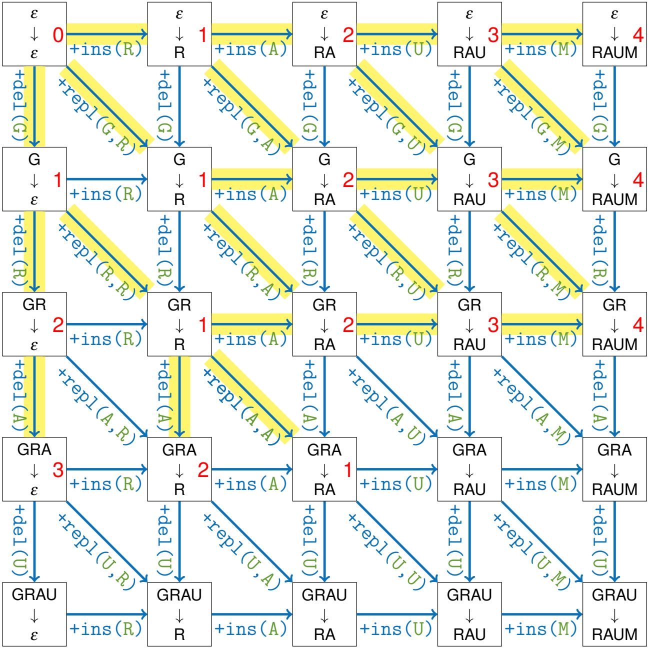
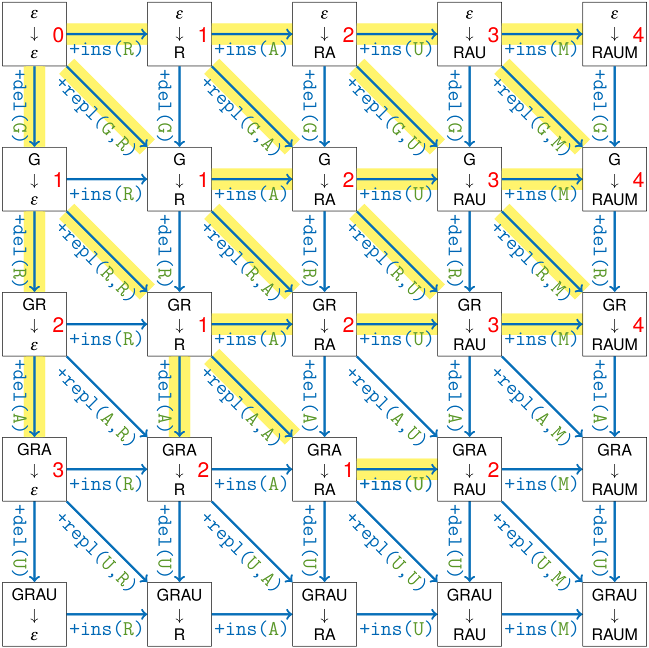
+repl(U,A)
+repl(U,U)
+repl(U,M)

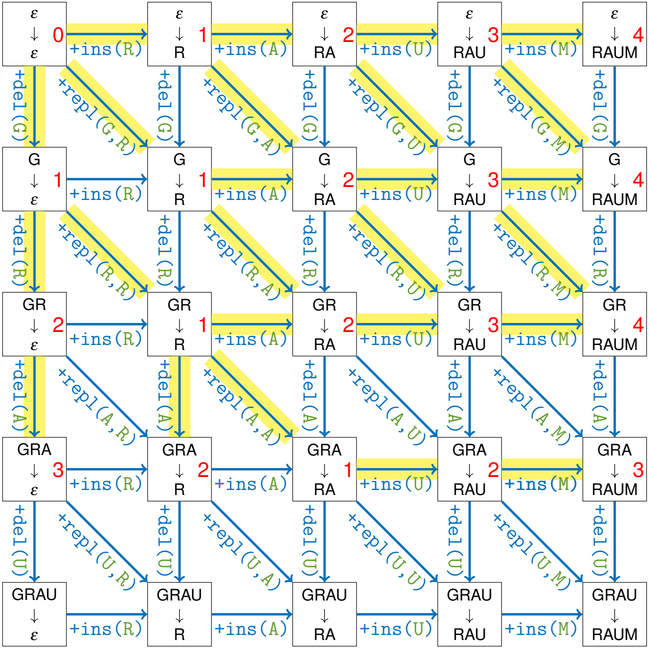


ε ↓ ε 0
+ins(R)
ε ↓ R 1
+ins(A)
ε ↓ RA 2
+ins(U)
ε ↓ RAU 3
+ins(M)
ε ↓ RAUM 4
+del(G)
+repl(G,R)
+repl(G,A)
+repl(G,U)
+repl(G,M)
G ↓ ε 1
G ↓ R 1
G ↓ RA 2
G ↓ RAU 3
G ↓ RAUM 4
+del(R)
+repl(R,R)
+repl(R,A)
+repl(R,U)
+repl(R,M)
GR ↓ ε 2
GR ↓ R 1
GR ↓ RA 2
GR ↓ RAU 3
GR ↓ RAUM 4
+del(A)
+repl(A,R)
+repl(A,A)
+repl(A,U)
+repl(A,M)
GRA ↓ ε 3
GRA ↓ R 2
GRA ↓ RA
GRA ↓ RAU
GRA ↓ RAUM
+del(U)
+repl(U,R)
+repl(U,A)
+repl(U,U)
+repl(U,M)
GRAU ↓ ε
GRAU ↓ R
GRAU ↓ RA
GRAU ↓ RAU
GRAU ↓ RAUM

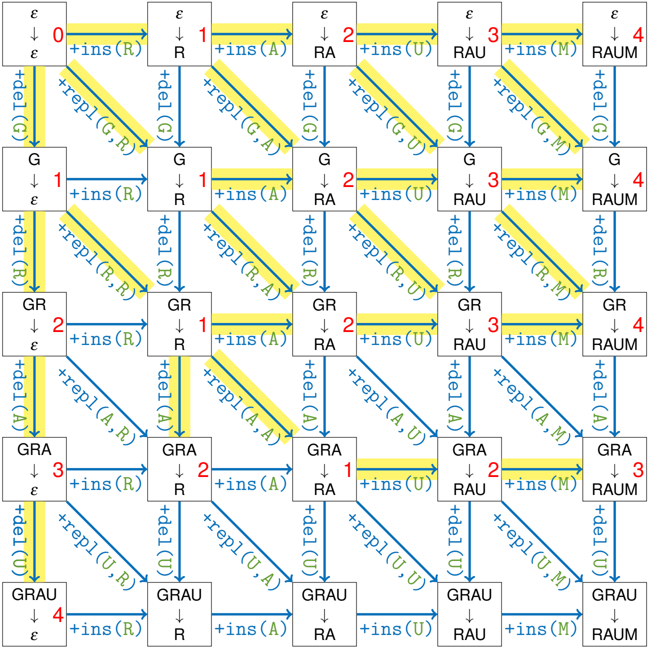

ε → ε 0
ε → R 1
ε → RA 2
ε → RAU 3
ε → RAUM 4
G → ε 1
G → R 1
G → RA 2
G → RAU 3
G → RAUM 4
GR → ε 2
GR → R 1
GR → RA 2
GR → RAU 3
GR → RAUM 4
GRA → ε 3
GRA → R 2
GRA → RA 1
GRA → RAU
GRA → RAUM
GRAU → ε
GRAU → R
GRAU → RA
GRAU → RAU
GRAU → RAUM
+ins(R)
+ins(A)
+ins(U)
+ins(M)
+del(G)
+del(R)
+del(A)
+del(U)
+repl(G,R)
+repl(G,A)
+repl(G,U)
+repl(G,M)
+repl(R,R)
+repl(R,A)
+repl(R,U)
+repl(R,M)
+repl(A,R)
+repl(A,A)
+repl(A,U)
+repl(A,M)
+repl(U,R)
+repl(U,A)
+repl(U,U)
+repl(U,M)

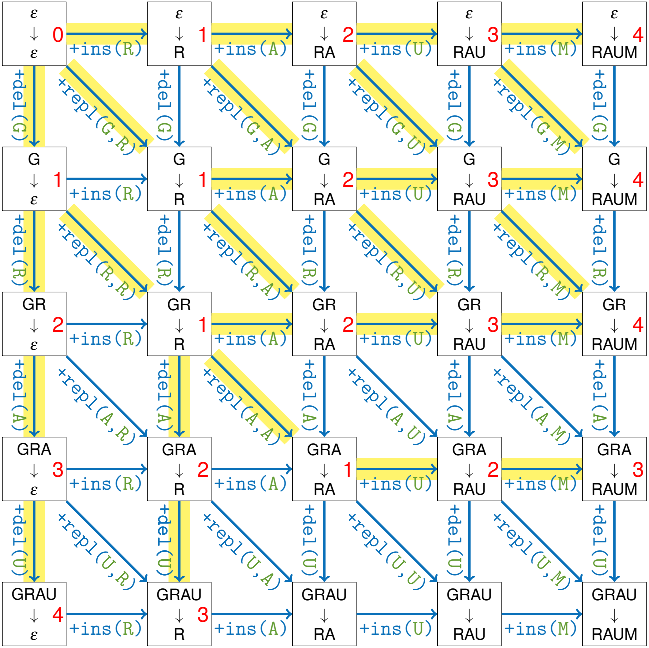


ε ↓ ε 0
ε ↓ R 1
ε ↓ RA 2
ε ↓ RAU 3
ε ↓ RAUM 4
G ↓ ε 1
G ↓ R 1
G ↓ RA 2
G ↓ RAU 3
G ↓ RAUM 4
GR ↓ ε 2
GR ↓ R 1
GR ↓ RA 2
GR ↓ RAU 3
GR ↓ RAUM 4
GRA ↓ ε 3
GRA ↓ R 2
GRA ↓ RA 1
GRA ↓ RAU 2
GRA ↓ RAUM
GRAU ↓ ε
GRAU ↓ R
GRAU ↓ RA
GRAU ↓ RAU
GRAU ↓ RAUM
+ins(R)
+ins(A)
+ins(U)
+ins(M)
+del(G)
+del(R)
+del(A)
+del(U)
+repl(G,R)
+repl(G,A)
+repl(G,U)
+repl(G,M)
+repl(R,R)
+repl(R,A)
+repl(R,U)
+repl(R,M)
+repl(A,R)
+repl(A,A)
+repl(A,U)
+repl(A,M)
+repl(U,R)
+repl(U,A)
+repl(U,U)
+repl(U,M)



ε ↓ ε 0
ε ↓ R 1
ε ↓ RA 2
ε ↓ RAU 3
ε ↓ RAUM 4
+ins(R) +ins(A) +ins(U) +ins(M)
+del(G) +repl(G,R) +repl(G,A) +repl(G,U) +repl(G,M)
G ↓ ε 1
G ↓ R 1
G ↓ RA 2
G ↓ RAU 3
G ↓ RAUM 4
+del(R) +repl(R,R) +repl(R,A) +repl(R,U) +repl(R,M)
GR ↓ ε 2
GR ↓ R 1
GR ↓ RA 2
GR ↓ RAU 3
GR ↓ RAUM 4
+del(A) +repl(A,R) +repl(A,A) +repl(A,U) +repl(A,M)
GRA ↓ ε 3
GRA ↓ R 2
GRA ↓ RA 1
GRA ↓ RAU 2
GRA ↓ RAUM 3
+del(U) +repl(U,R) +repl(U,A) +repl(U,U) +repl(U,M)
GRAU ↓ ε
GRAU ↓ R
GRAU ↓ RA
GRAU ↓ RAU
GRAU ↓ RAUM


ε ↓ ε 0
ε ↓ R 1
ε ↓ RA 2
ε ↓ RAU 3
ε ↓ RAUM 4
G ↓ ε 1
G ↓ R 1
G ↓ RA 2
G ↓ RAU 3
G ↓ RAUM 4
GR ↓ ε 2
GR ↓ R 1
GR ↓ RA 2
GR ↓ RAU 3
GR ↓ RAUM 4
GRA ↓ ε 3
GRA ↓ R 2
GRA ↓ RA 1
GRA ↓ RAU 2
GRA ↓ RAUM 3
GRAU ↓ ε 4
GRAU ↓ R
GRAU ↓ RA
GRAU ↓ RAU
GRAU ↓ RAUM
+ins(R)
+ins(A)
+ins(U)
+ins(M)
+del(G)
+del(R)
+del(A)
+del(U)
+repl(G,R)
+repl(G,A)
+repl(G,U)
+repl(G,M)
+repl(R,R)
+repl(R,A)
+repl(R,U)
+repl(R,M)
+repl(A,R)
+repl(A,A)
+repl(A,U)
+repl(A,M)
+repl(U,R)
+repl(U,A)
+repl(U,U)
+repl(U,M)


ε ↓ ε 0
ε ↓ R 1
ε ↓ RA 2
ε ↓ RAU 3
ε ↓ RAUM 4
G ↓ ε 1
G ↓ R 1
G ↓ RA 2
G ↓ RAU 3
G ↓ RAUM 4
GR ↓ ε 2
GR ↓ R 1
GR ↓ RA 2
GR ↓ RAU 3
GR ↓ RAUM 4
GRA ↓ ε 3
GRA ↓ R 2
GRA ↓ RA 1
GRA ↓ RAU 2
GRA ↓ RAUM 3
GRAU ↓ ε 4
GRAU ↓ R 3
GRAU ↓ RA
GRAU ↓ RAU
GRAU ↓ RAUM
+ins(R)
+ins(A)
+ins(U)
+ins(M)
+del(G)
+del(R)
+del(A)
+del(U)
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+repl(G,A)
+repl(G,U)
+repl(G,M)
+repl(R,R)
+repl(R,A)
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+repl(R,M)
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+repl(A,A)
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+repl(U,U)
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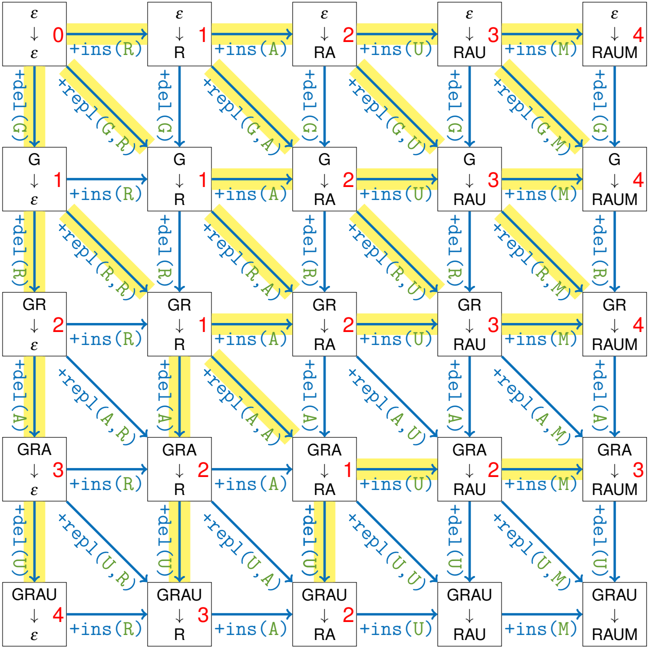

ε ↓ ε 0
ε ↓ R 1
ε ↓ RA 2
ε ↓ RAU 3
ε ↓ RAUM 4
G ↓ ε 1
G ↓ R 1
G ↓ RA 2
G ↓ RAU 3
G ↓ RAUM 4
GR ↓ ε 2
GR ↓ R 1
GR ↓ RA 2
GR ↓ RAU 3
GR ↓ RAUM 4
GRA ↓ ε 3
GRA ↓ R 2
GRA ↓ RA 1
GRA ↓ RAU 2
GRA ↓ RAUM 3
GRAU ↓ ε 4
GRAU ↓ R 3
GRAU ↓ RA 2
GRAU ↓ RAU
GRAU ↓ RAUM
+ins(R)
+ins(A)
+ins(U)
+ins(M)
+del(G)
+del(R)
+del(A)
+del(U)
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+repl(G,A)
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+repl(G,M)
+repl(R,R)
+repl(R,A)
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+repl(A,R)
+repl(A,A)
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+repl(U,A)
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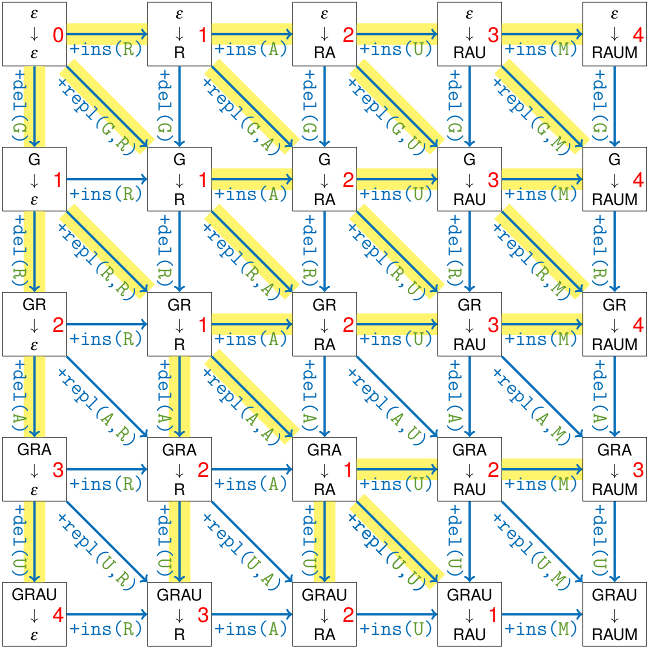

ε ↓ ε 0
ε ↓ R 1
ε ↓ RA 2
ε ↓ RAU 3
ε ↓ RAUM 4
G ↓ ε 1
G ↓ R 1
G ↓ RA 2
G ↓ RAU 3
G ↓ RAUM 4
GR ↓ ε 2
GR ↓ R 1
GR ↓ RA 2
GR ↓ RAU 3
GR ↓ RAUM 4
GRA ↓ ε 3
GRA ↓ R 2
GRA ↓ RA 1
GRA ↓ RAU 2
GRA ↓ RAUM 3
GRAU ↓ ε 4
GRAU ↓ R 3
GRAU ↓ RA 2
GRAU ↓ RAU 1
GRAU ↓ RAUM
+ins(R)
+ins(A)
+ins(U)
+ins(M)
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+del(R)
+del(A)
+del(U)
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+repl(G,U)
+repl(G,M)
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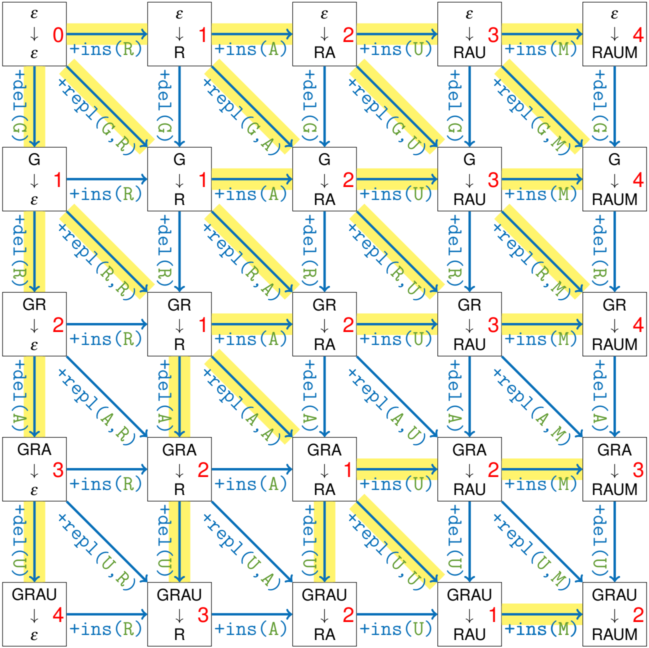
ε ↓ ε 0
ε ↓ R 1
ε ↓ RA 2
ε ↓ RAU 3
ε ↓ RAUM 4
G ↓ ε 1
G ↓ R 1
G ↓ RA 2
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G ↓ RAUM 4
GR ↓ ε 2
GR ↓ R 1
GR ↓ RA 2
GR ↓ RAU 3
GR ↓ RAUM 4
GRA ↓ ε 3
GRA ↓ R 2
GRA ↓ RA 1
GRA ↓ RAU 2
GRA ↓ RAUM 3
GRAU ↓ ε 4
GRAU ↓ R 3
GRAU ↓ RA 2
GRAU ↓ RAU 1
GRAU ↓ RAUM 2
+ins(R)
+ins(A)
+ins(U)
+ins(M)
+del(G)
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+del(A)
+del(U)
+repl(G,R)
+repl(G,A)
+repl(G,U)
+repl(G,M)
+repl(R,R)
+repl(R,A)
+repl(R,U)
+repl(R,M)
+repl(A,R)
+repl(A,A)
+repl(A,U)
+repl(A,M)
+repl(U,R)
+repl(U,A)
+repl(U,U)
+repl(U,M)

How to get the sequence of operations?

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How to get the sequence of operations?

- We save at each recursion the most efficient previous entry (the highlighted arrows in our image)

How to get the sequence of operations?

- We save at each recursion the most efficient previous entry (the highlighted arrows in our image)
- There can be more than one arrows to the three previous entries

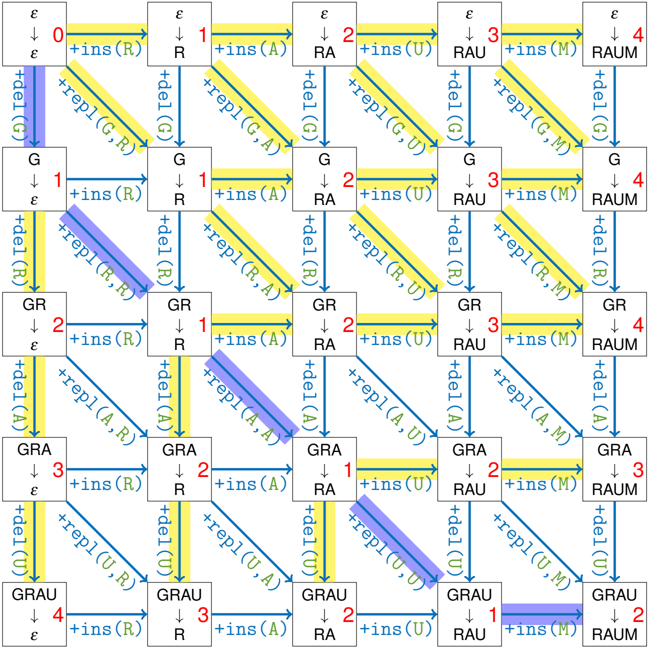
Edit distance

How to get the sequence of operations?

- We save at each recursion the most efficient previous entry (the highlighted arrows in our image)
- There can be more than one arrows to the three previous entries
- If we follow the highlighted path from (n,m) to $(1,1)$ we get the optimum operations to transform x into y

How to get the sequence of operations?

- We save at each recursion the most efficient previous entry (the highlighted arrows in our image)
- There can be more than one arrows to the three previous entries
- If we follow the highlighted path from (n,m) to $(1,1)$ we get the optimum operations to transform x into y
  - If we can follow more than one path there exist more than one ideal sequence



ε ↓ ε 0
ε ↓ R 1
ε ↓ RA 2
ε ↓ RAU 3
ε ↓ RAUM 4
G ↓ ε 1
G ↓ R 1
G ↓ RA 2
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G ↓ RAUM 4
GR ↓ ε 2
GR ↓ R 1
GR ↓ RA 2
GR ↓ RAU 3
GR ↓ RAUM 4
GRA ↓ ε 3
GRA ↓ R 2
GRA ↓ RA 1
GRA ↓ RAU 2
GRA ↓ RAUM 3
GRAU ↓ ε 4
GRAU ↓ R 3
GRAU ↓ RA 2
GRAU ↓ RAU 1
GRAU ↓ RAUM 2
+ins(R)
+ins(A)
+ins(U)
+ins(M)
+del(G)
+del(R)
+del(A)
+del(U)
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+repl(A,R)
+repl(A,A)
+repl(A,U)
+repl(A,M)
+repl(U,R)
+repl(U,A)
+repl(U,U)
+repl(U,M)

Edit distance

General principle:

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- Recursive computation of …
  - … the same reoccuring partial problems
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  - … the same reoccuring partial problems
  - … a limited number of partial problems
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- In a order that unsolved partial problems consist of already solved partial problems
- The "path" to our solution normally gets computed while searching the best solution
- Dijkstra algorithm is basically dynamic programming!

Additional applications:

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Additional applications:

- *Edit distance*: global alignment with $O(n^2)$ space and time consumption

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_	_	_	B	L	O	E	D
S	A	U	B	L	O	E	D

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_	_	_	B	L	O	E	D
S	A	U	B	L	O	E	D

  - Solution in $O(n^3)$ time or $O(n^2)$ affine

$O(n^2)$ space consumption might be problematic:

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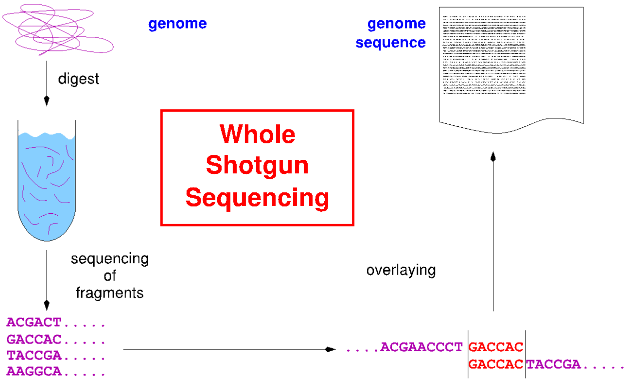
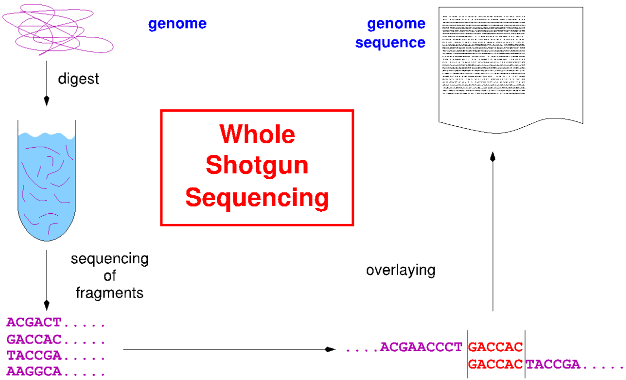
Hirschberg algorithm:

- Divide-and-conquer approach
- $O(n)$ space and $O(n^2)$ time consumption

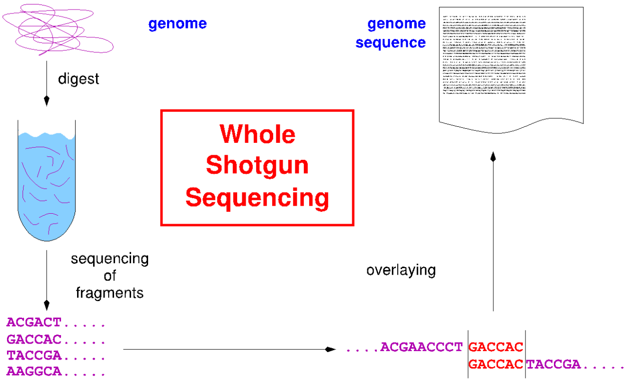
Edit distance

Additional applications (III)





- Sequencing: $O(n^2)$ is too much



- Sequencing: $O(n^2)$ is too much
- Index: suffixtree, suffixarray, burrow-wheeler-transform

Further Literature

- **General**

[CRL01] Thomas H. Cormen, Ronald L. Rivest, and Charles E. Leiserson.
Introduction to Algorithms.
MIT Press, Cambridge, Mass, 2001.

[MS08] Kurt Mehlhorn and Peter Sanders.
Algorithms and data structures, 2008.
https://people.mpi-inf.mpg.de/~mehlhorn/ftp/Mehlhorn-Sanders-Toolbox.pdf.

Further Literature

- **Dynamic programming**

  [Wik] Dynamic programming
  https://en.wikipedia.org/wiki/Dynamic_programming

- **Edit distance**

  [Wik] Levenshtein distance
  https://en.wikipedia.org/wiki/Levenshtein_distance