Find the regular expression for the language containing all binary strings that do not contain the subsequence 111000

## ECE-374-B: Lecture 3 - NFAs

Instructer: Nickvash Kani

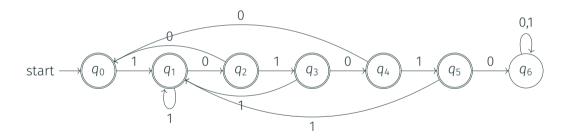
September 04, 2025

University of Illinois at Urbana-Champaign

Find the regular expression for the language containing all binary strings that **do not** contain the subsequence 111000

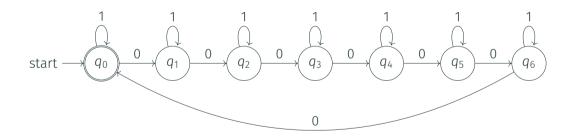
Find the regular expression for the language containing all binary strings that **do not** contain the substring 101010

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Find the regular expression for the language contains all binary strings whose  $\#_0(w)\%7 = 0$  (number of 0's divisible by 7).

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Show that the following string(w) is a member of the language that:

- · does not contain the subsequence 111000 or
- does not contain the substring 101010 or
- or has a number of 0's divisible by 7

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w = 1001110110111001 10000101111110010 0101010011001111 10010010111111100

You have 30 seconds.

Show that the following string(w) is a member of the language that:

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- · does not contain the substring 101010 or
- or has a number of 0's divisible by 7

w = 1001110110111001 10000101111110010 0101010011001111 10010010111111100

You have 30 seconds. Pray, choose a strategy and hope you get lucky.

Does luck allow us to solve unsolvable problems?

Does luck allow us to solve unsolvable problems? New example: Consider two machines:  $M_1$  and  $M_2$ 

- $M_1$  is a classic deterministic machine.
- $\cdot$   $M_2$  is a "lucky" machine that will always make the right choice.

## Lucky machine programs

**Problem:** Find shortest path from a to b

Program on  $M_1$  (Dijkstra's algorithm):

```
Initialize for each node v, \operatorname{Dist}(s,v) = d'(s,v) = \infty

Initialize X = \emptyset, d'(s,s) = 0

for i = 1 to |V| do

Let v be node realizing d'(s,v) = \min_{u \in V - X} d'(s,u)

\operatorname{Dist}(s,v) = d'(s,v)

X = X \cup \{v\}

Update d'(s,u) for each u in V - X as follows:

d'(s,u) = \min \Big( d'(s,u), \operatorname{Dist}(s,v) + \ell(v,u) \Big)
```

# Lucky machine programs

**Problem:** Find shortest path from a to b

Program on  $M_2$  (Blind luck):

```
Initialize path = []
path += a
While(notatb)
    take an outgoing edge (u,v) from current node u to v
    current = v
    path += v
return path
```

Does luck allow us to solve unsolvable problems? Consider two machines:  $M_1$  and  $M_2$ 

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## Question:

Does luck allow us to solve unsolvable problems? Consider two machines:  $M_1$  and  $M_2$ 

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**Question:** Are there problems which  $M_2$  can solve that  $M_1$  cannot.

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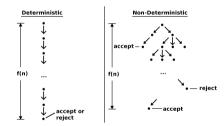
The notion was first posed by **Robert W. Floyd** in 1967.

# Non-determinism in computing

In computer science, a nondeterministic machine is a theoretical device that can have more than one output for the same input.

A machine that is capable of taking multiple states concurrently. Whenever it reaches a choice, it takes both paths.

If there is a path for the string to be accepted by the machine, then the string is part of the language.



## Non-determinism in media

Placeholder slide for youtube.

# Why non-determinism?

- Non-determinism adds power to the model; richer programming language and hence (much) easier to "design" programs
- Fundamental in theory to prove many theorems
- Very important in practice directly and indirectly
- Many deep connections to various fields in Computer Science and Mathematics

Many interpretations of non-determinism. Hard to understand at the outset. Get used to it and then you will appreciate it slowly.

(NFA) Introduction

Non-deterministic finite automata

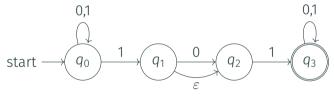
# Non-deterministic Finite State Automata by example

When you come to a fork in the road, take it.

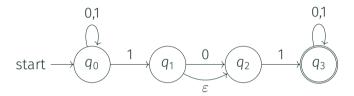
# Non-deterministic Finite State Automata by example

When you come to a fork in the road, take it.

Today we'll talk about automata whose logic is not deterministic.

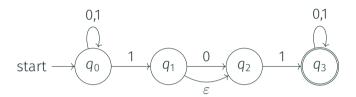


## NFA acceptance: Informal



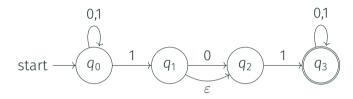
**Informal definition:** An NFA N accepts a string w iff some accepting state is reached by N from the start state on input w.

# NFA acceptance: Informal



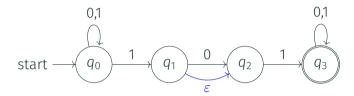
**Informal definition:** An NFA *N* accepts a string *w* iff some accepting state is reached by *N* from the start state on input *w*.

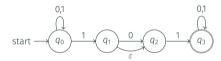
The language accepted (or recognized) by a NFA N is denote by L(N) and defined as:  $L(N) = \{w \mid N \text{ accepts } w\}$ .



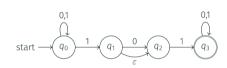
• Is 010110 accepted?

# NFA acceptance: Wait! what about the $\epsilon$ ?!

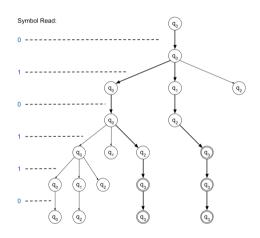


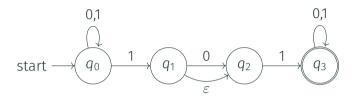


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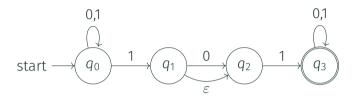


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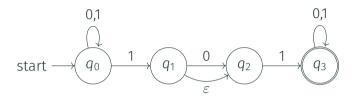




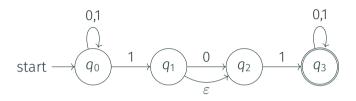
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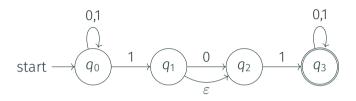
- Is 010110 accepted?
- Is 010 accepted?



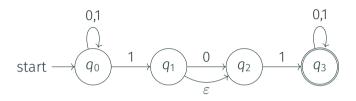
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- Is 010110 accepted?
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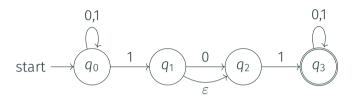


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### NFA acceptance: Example



- Is 010110 accepted?
- Is 010 accepted?
- Is 101 accepted?
- Is 10011 accepted?
- What is the language accepted by N?

**Comment:** Unlike DFAs, it is easier in NFAs to show that a string is accepted than to show that a string is **not** accepted.

Formal definition of NFA

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 $\mathcal{P}(Q)$ ?

### Reminder: Power set

Q: a set. Power set of Q is:  $\mathcal{P}(Q) = 2^Q = \{X \mid X \subseteq Q\}$  is set of all subsets of Q.

Example 
$$Q = \{1, 2, 3, 4\}$$

$$\mathcal{P}(Q) = \left\{ \begin{array}{c} \{1, 2, 3, 4\}, \\ \{2, 3, 4\}, \{1, 3, 4\}, \{1, 2, 4\}, \{1, 2, 3\}, \\ \{1, 2\}, \{1, 3\}, \{1, 4\}, \{2, 3\}, \{2, 4\}, \{3, 4\}, \\ \{1\}, \{2\}, \{3\}, \{4\}, \\ \{\} \end{array} \right\}$$

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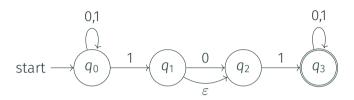
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- $s \in Q$  is the start state,
- $A \subseteq Q$  is the set of accepting/final states.

 $\delta(q,a)$  for  $a \in \Sigma \cup \{\varepsilon\}$  is a subset of Q — a set of states.



- $\cdot Q =$
- $\cdot$   $\Sigma =$
- ·  $\delta =$

· s =

Extending the transition function to

strings

• NFA 
$$N = (Q, \Sigma, \delta, s, A)$$

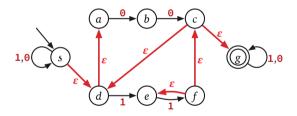
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- $\delta^*(q, w)$ : set of states reachable on input w starting in state q.

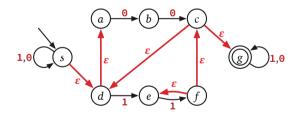
#### Definition

For NFA  $N=(Q,\Sigma,\delta,s,A)$  and  $q\in Q$  the  $\epsilon \operatorname{reach}(q)$  is the set of all states that q can reach using only  $\varepsilon$ -transitions.



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### Definition

For  $X \subseteq Q$ :  $\epsilon$ reach $(X) = \bigcup_{x \in X} \epsilon$ reach(x).

 $\epsilon$ reach(q): set of all states that q can reach using only  $\varepsilon$ -transitions.

#### Definition

Inductive definition of  $\delta^*: Q \times \Sigma^* \to \mathcal{P}(Q)$ :

• if 
$$w = \varepsilon$$
,  $\delta^*(q, w) = \epsilon \operatorname{reach}(q)$ 

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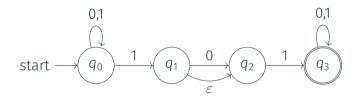
• if 
$$w = a$$
 where  $a \in \Sigma$ :  $\delta^*(q, a) = \epsilon \operatorname{reach}\left(\bigcup_{p \in \epsilon \operatorname{reach}(q)} \delta(p, a)\right)$ 

 $\epsilon$ reach(q): set of all states that q can reach using only  $\epsilon$ -transitions.

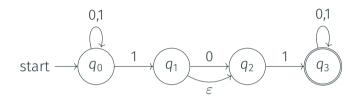
#### Definition

Inductive definition of  $\delta^*: Q \times \Sigma^* \to \mathcal{P}(Q)$ :

- if  $w = \varepsilon$ ,  $\delta^*(q, w) = \epsilon \operatorname{reach}(q)$
- if w = a where  $a \in \Sigma$ :  $\delta^*(q, a) = \epsilon \operatorname{reach}\left(\bigcup_{p \in \epsilon \operatorname{reach}(q)} \delta(p, a)\right)$
- if w = ax:  $\delta^*(q, w) = \epsilon \operatorname{reach}\left(\bigcup_{p \in \epsilon \operatorname{reach}(q)} \left(\bigcup_{r \in \delta^*(p, a)} \delta^*(r, x)\right)\right)$

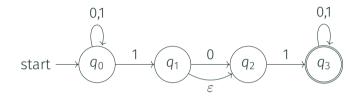


Find  $\delta^*$  ( $q_0, 11$ ):



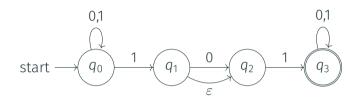
Find 
$$\delta^*$$
 ( $q_0, 11$ ):

$$\delta^*(q, w) = \epsilon \operatorname{reach}\left(\bigcup_{p \in \epsilon \operatorname{reach}(q)} \left(\bigcup_{r \in \delta^*(p, a)} \delta^*(r, x)\right)\right)$$



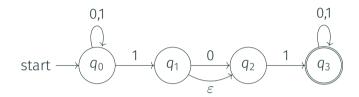
We know 
$$w = 11 = ax$$
 so  $a = 1$  and  $x = 1$ 

$$\delta^*(q_0, 11) = \epsilon \operatorname{reach} \left( \bigcup_{p \in \epsilon \operatorname{reach}(q_0)} \left( \bigcup_{r \in \delta^*(p, 1)} \delta^*(r, 1) \right) \right)$$



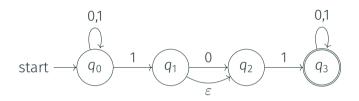
$$\epsilon$$
reach $(q_0) = \{q_0\}$ 

$$\delta^*(q_0, 11) = \epsilon \operatorname{reach} \left( \bigcup_{p \in \{q_0\}} \left( \bigcup_{r \in \delta^*(p, 1)} \delta^*(r, 1) \right) \right)$$



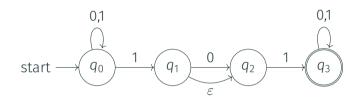
Simplify:

$$\delta^*(q_0, 11) = \epsilon \operatorname{reach}\left(\bigcup_{r \in \delta^*(\{q_0\}, 1)} \delta^*(r, 1)\right)$$



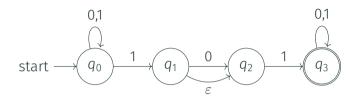
Need 
$$\delta^*(q_0, 1) = \epsilon \operatorname{reach}\left(\bigcup_{p \in \epsilon \operatorname{reach}(q)} \delta(p, a)\right) = \epsilon \operatorname{reach}(\delta(q_0, 1))$$
:
$$= \epsilon \operatorname{reach}(\{q_0, q_1\}) = \{q_0, q_1, q_2\}$$

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$$\delta^*(q_0, 11) = \epsilon \operatorname{reach}\left(\bigcup_{r \in \{q_0, q_1, q_2\}} \delta^*(r, 1)\right)$$



### Simplify

$$\delta^*(q_0, 11) = \epsilon \operatorname{reach}(\delta^*(q_0, 1) \cup \delta^*(q_1, 1) \cup \delta^*(q_2, 1))$$

### Transition for strings: w = ax

$$\delta^*(q, w) = \epsilon \operatorname{reach}\left(\bigcup_{p \in \epsilon \operatorname{reach}(q)} \left(\bigcup_{r \in \delta^*(p, a)} \delta^*(r, x)\right)\right)$$

$$\cdot R = \epsilon \operatorname{reach}(q) \implies \delta^*(q, w) = \epsilon \operatorname{reach}\left(\bigcup_{p \in R} \bigcup_{r \in \delta^*(p, a)} \delta^*(r, x)\right)$$

- $N = \bigcup_{p \in R} \delta^*(p, a)$ : All the states reachable from q with the letter a.
- $\cdot \delta^*(q, w) = \epsilon \operatorname{reach}\left(\bigcup_{r \in N} \delta^*(r, x)\right)$

# Formal definition of language accepted by N

#### Definition

A string w is accepted by NFA N if  $\delta_N^*(s, w) \cap A \neq \emptyset$ .

#### Definition

The language L(N) accepted by a NFA  $N = (Q, \Sigma, \delta, s, A)$  is

$$\{w \in \Sigma^* \mid \delta^*(s, w) \cap A \neq \emptyset\}.$$

# Formal definition of language accepted by N

#### Definition

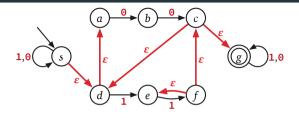
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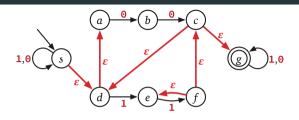
$$\{w \in \Sigma^* \mid \delta^*(s, w) \cap A \neq \emptyset\}.$$

Important: Formal definition of the language of NFA above uses  $\delta^*$  and not  $\delta$ . As such, one does not need to include  $\varepsilon$ -transitions closure when specifying  $\delta$ , since  $\delta^*$  takes care of that.



### What is:

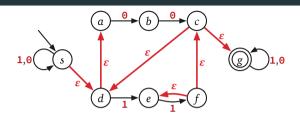
• 
$$\delta^*(s, \epsilon) =$$



### What is:

• 
$$\delta^*(s, \epsilon) =$$

• 
$$\delta^*(s,0) =$$



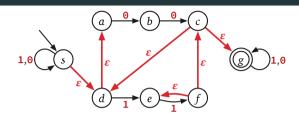
### What is:

• 
$$\delta^*(s, \epsilon) =$$

• 
$$\delta^*(s, 0) =$$

• 
$$\delta^*(b, 0) =$$

# Example



## What is:

- $\delta^*(s, \epsilon) =$
- $\delta^*(s, 0) =$
- $\delta^*(b, 0) =$
- $\delta^*(b,00) =$

# Constructing generalized NFAs

#### DFAs and NFAs

- Every DFA is a NFA so NFAs are at least as powerful as DFAs.
- NFAs prove ability to "guess and verify" which simplifies design and reduces number of states
- Easy proofs of some closure properties

# Example

 $L = \{ bitstrings that have a 1 three positions from the end \}$ 

# A simple transformation

#### Theorem

For every NFA N there is another NFA N' such that L(N) = L(N') and such that N' has the following two properties:

- N' has single final state f that has no outgoing transitions
- The start state s of N is different from f

# A simple transformation

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Why couldn't we say this for DFA's?

# A simple transformation

**Hint:** Consider the L =  $0^* + 1^*$ .

Closure Properties of NFAs

# Closure properties of NFAs

Are the class of languages accepted by NFAs closed under the following operations?

- union
- intersection
- concatenation
- · Kleene star
- complement

### Closure under union

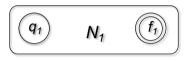
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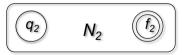
For any two NFAs  $N_1$  and  $N_2$  there is a NFA N such that  $L(N) = L(N_1) \cup L(N_2)$ .

#### Closure under union

#### Theorem

For any two NFAs  $N_1$  and  $N_2$  there is a NFA N such that  $L(N) = L(N_1) \cup L(N_2)$ .





#### Closure under concatenation

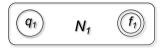
#### Theorem

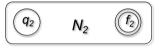
For any two NFAs  $N_1$  and  $N_2$  there is a NFA N such that  $L(N) = L(N_1) \cdot L(N_2)$ .

#### Closure under concatenation

#### Theorem

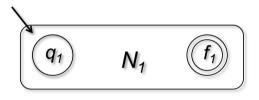
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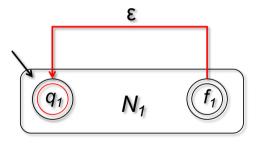
#### Theorem

For any NFA  $N_1$  there is a NFA N such that  $L(N) = (L(N_1))^*$ .



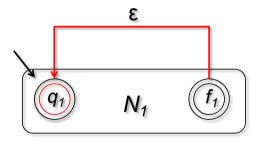
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#### Theorem

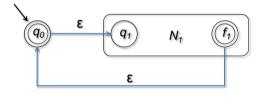
For any NFA  $N_1$  there is a NFA N such that  $L(N) = (L(N_1))^*$ .



Does not work! Why?

#### Theorem

For any NFA  $N_1$  there is a NFA N such that  $L(N) = (L(N_1))^*$ .



#### **Transformations**

All these examples are examples of language transformations.

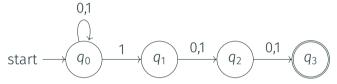
A language transformation is one where you take one class or languages, perform some operation and get a new language that belongs to that same class (closure).

Tomorrow's lab will go over more examples of language transformations.

Last thought

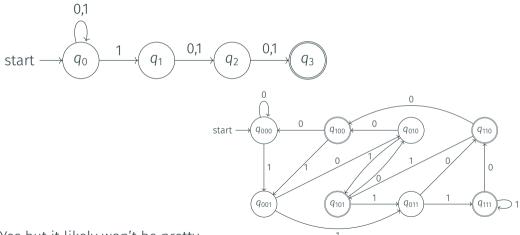
# Equivalence

Do all NFAs have a corresponding DFA?



# Equivalence

Do all NFAs have a corresponding DFA?



Yes but it likely won't be pretty.