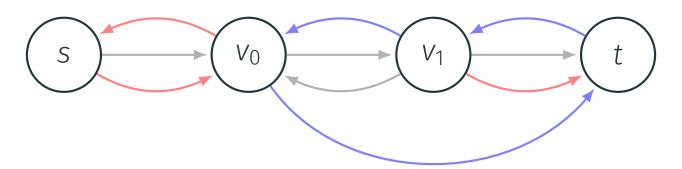
You have a graph  $\underline{G}(V,E)$ . Some of the edges are red, some are white and some are blue. You are given two distinct vertices u and v and want to find a walk  $[u \rightarrow v]$  such that:

- a white edge must be taken after a red edge only.
- a blue edge must be taken after a white edge only.
- and a red edge may be taken after a blue edge only.
- must start on red edge



# ECE-374-B: Lecture 17 - Bellman-Ford and Dynamic Programming on Graphs

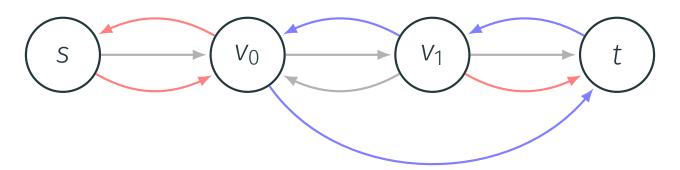
Instructor: Nickvash Kani

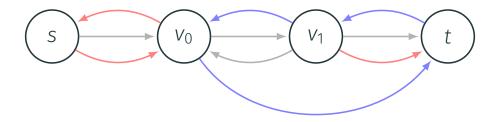
October 28, 2025

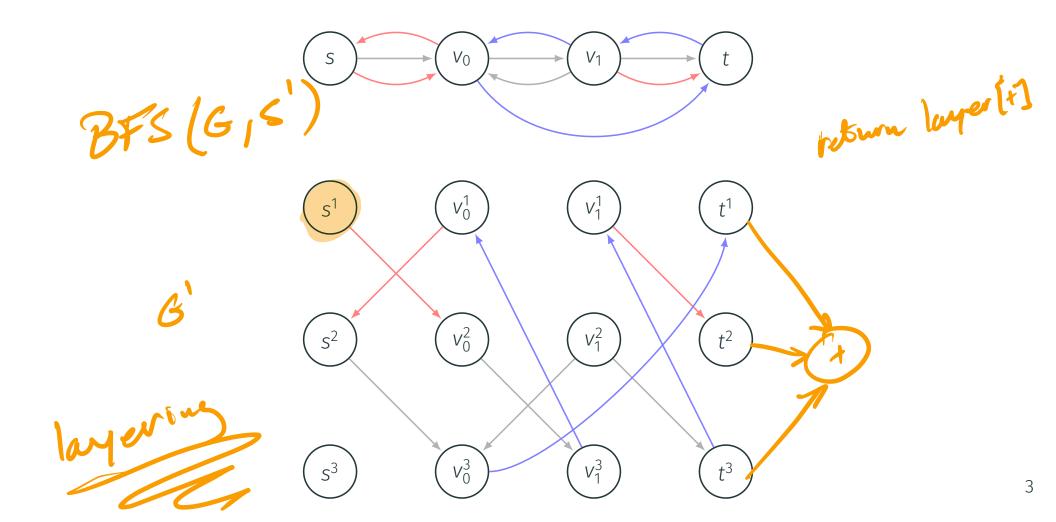
University of Illinois Urbana-Champaign

You have a graph  $\underline{G}(V,E)$ . Some of the edges are red, some are white and some are blue. You are given two distinct vertices  $\checkmark$  and  $\checkmark$  and want to find a walk  $[u \rightarrow v]$  such that:

- a white edge must be taken after a red edge only.
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# Shortest Paths with Negative Length Edges

negative edges

Why Dijkstra's algorithm fails with

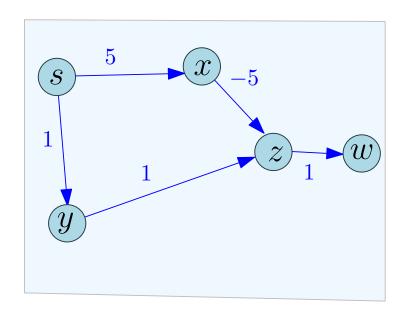
## Single-Source Shortest Paths with Negative Edge Lengths

# Single-Source Shortest Path Problems Input: A directed graph G — (V, E) with arbitrary (incl

**Input**: A <u>directed</u> graph G = (V, E) with arbitrary (including negative) edge lengths. For edge e = (u, v),  $\ell(e) = \ell(u, v)$  is its length.

- Given nodes s, t find shortest path from s to t.
- Given node s find shortest path from s to all other nodes.

## What are the distances computed by Dijkstra's algorithm?



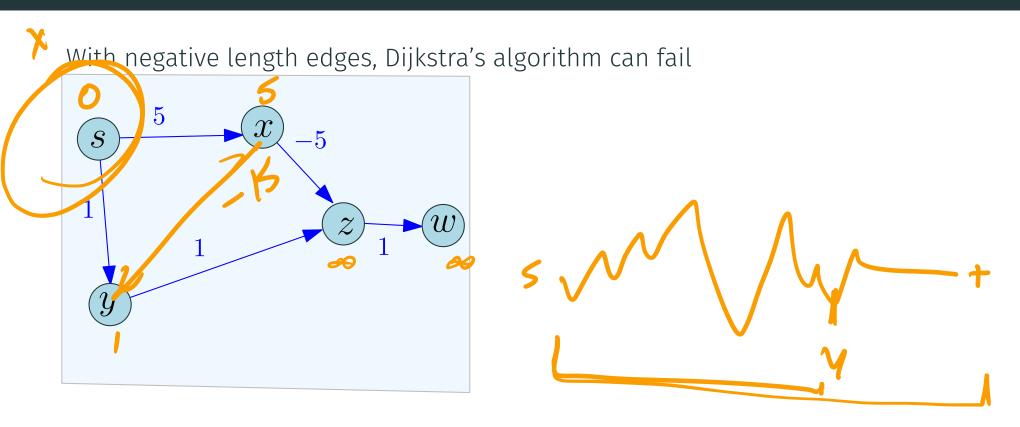
The distance as computed by Dijkstra algorithm starting from s:

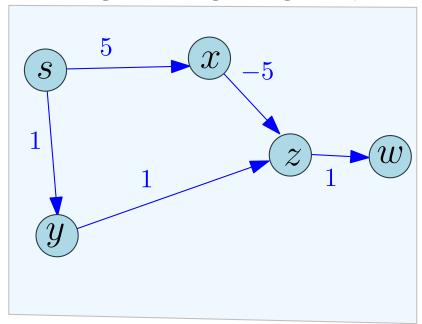
1. 
$$s = 0$$
,  $x = 5$ ,  $y = 1$ ,  $z = 0$ .

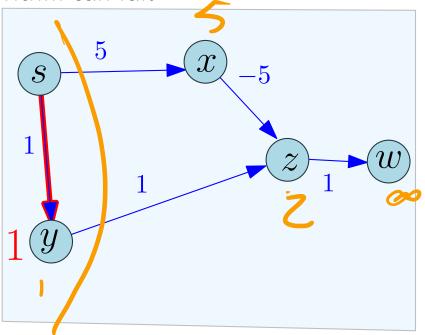
2. 
$$s = 0$$
,  $x = 1$ ,  $y = 2$ ,  $z = 5$ .

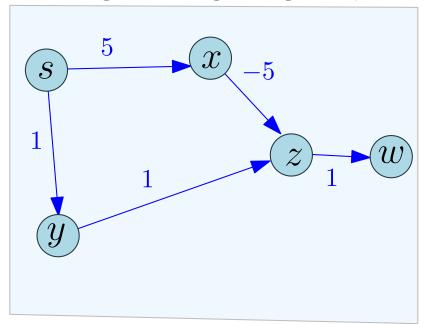
3. 
$$s = 0, x = 5, y = 1, z = 2$$
.

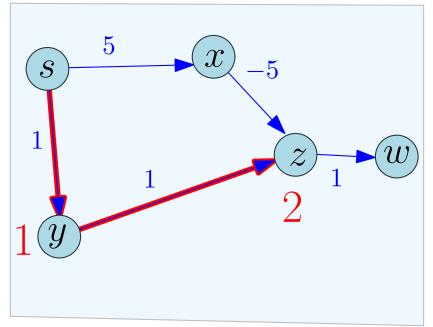
4. IDK.

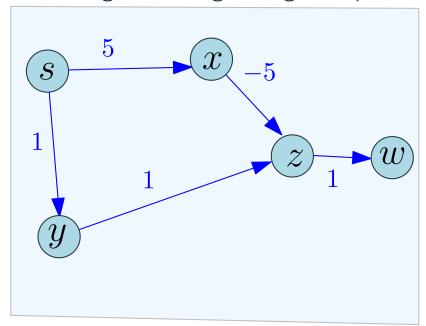


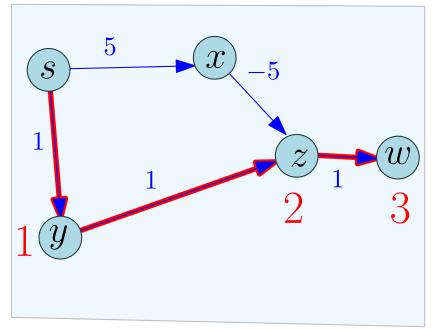


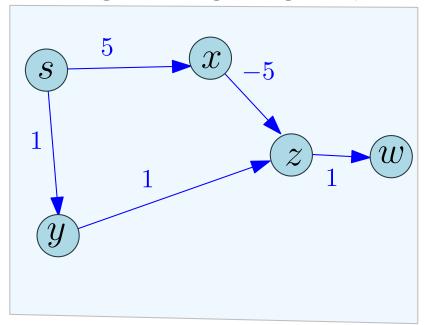


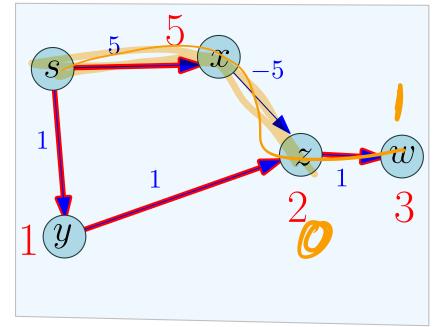


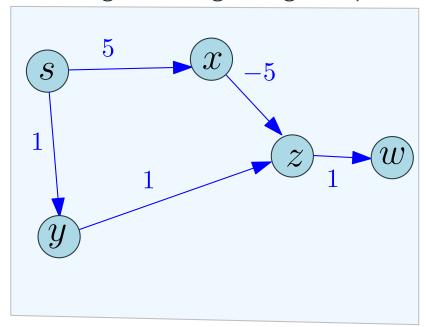


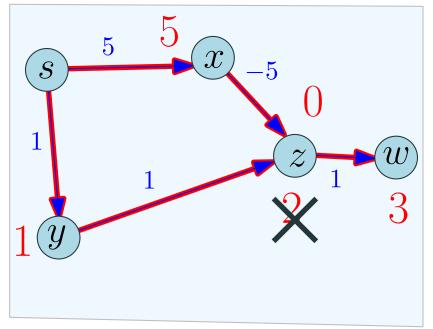


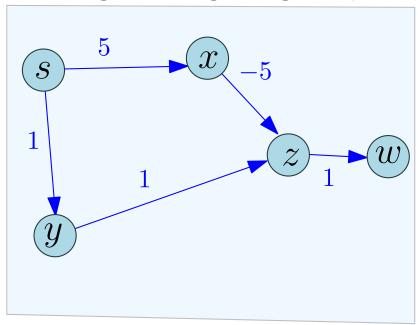


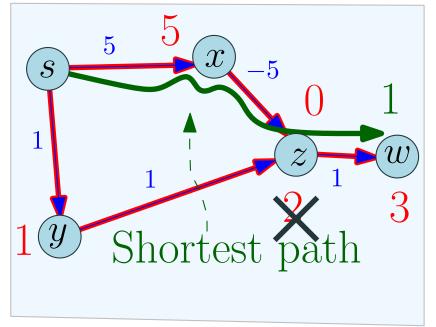




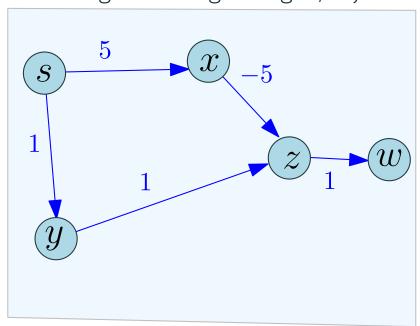


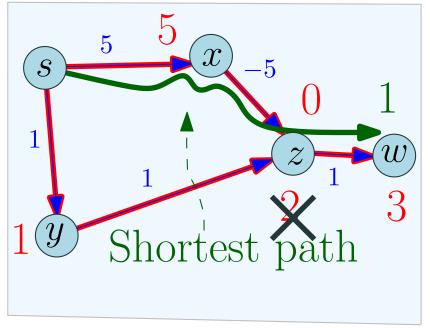






With negative length edges, Dijkstra's algorithm can fail





False assumption: Dijkstra's algorithm assumes that if  $s \to v_0 \to v_1 \to v_2 \dots \to v_k$  is a shortest path from s to  $v_k$  then  $dist(s, v_i) \le dist(s, v_{i+1})$  for  $0 \le i < k$ . Holds true only for non-negative edge lengths.

## Shortest Paths with Negative Lengths

#### Lemma

Let G be a directed graph with arbitrary edge lengths. If

 $s = v_0 \rightarrow v_1 \rightarrow v_2 \rightarrow ... \rightarrow v_k$  is a shortest path from s to  $v_k$  then for  $1 \le i < k$ :

• 
$$s = v_0 \rightarrow v_1 \rightarrow v_2 \rightarrow \ldots \rightarrow v_i$$
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- False:  $dist(s, v_i) \le dist(s, v_k)$  for  $1 \le i < k$ . Holds true only for non-negative edge lengths.

## Shortest Paths with Negative Lengths

#### Lemma

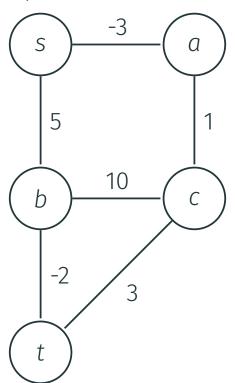
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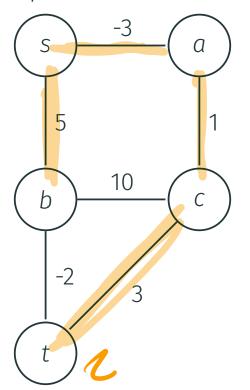
- $s = v_0 \rightarrow v_1 \rightarrow v_2 \rightarrow \ldots \rightarrow v_i$  is a shortest path from s to  $v_i$
- False:  $dist(s, v_i) \le dist(s, v_k)$  for  $1 \le i < k$ . Holds true only for non-negative edge lengths.

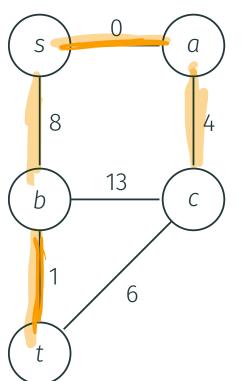
Cannot explore nodes in increasing order of distance! We need other strategies.

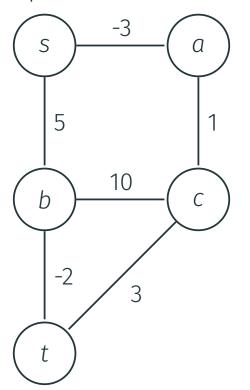
edge lengths!?

Why can't we just re-normalize the

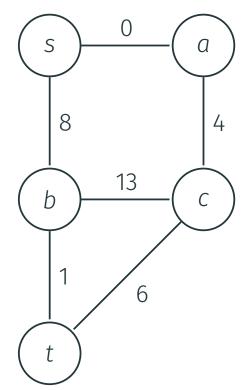




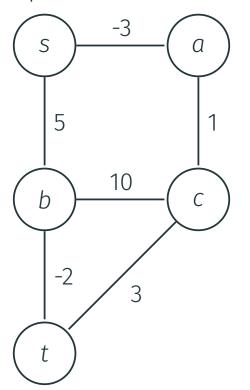




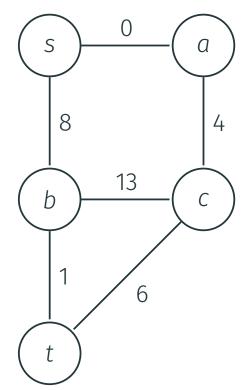
Shortest Path:  $s \rightarrow a \rightarrow c \rightarrow t$ 



Shortest Path:  $s \rightarrow b \rightarrow t$ 



Shortest Path:  $s \rightarrow a \rightarrow c \rightarrow t$ 



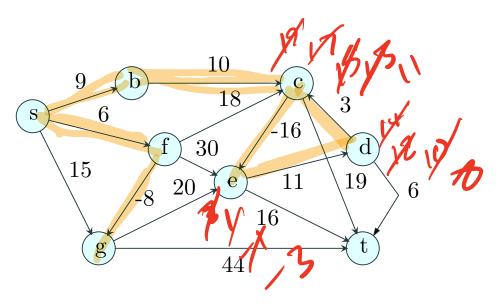
Shortest Path:  $s \rightarrow b \rightarrow t$ 

But wait! Things get worse: Negative cycles

## Negative Length Cycles

## Definition

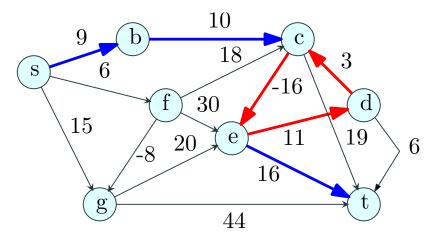
A cycle C is a negative length cycle if the sum of the edge lengths of C is negative.



## Negative Length Cycles

### Definition

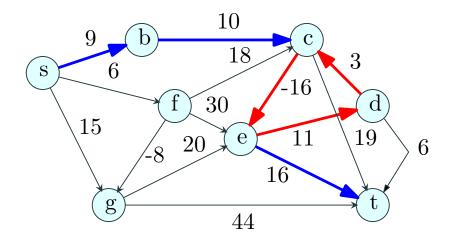
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## Negative Length Cycles

### Definition

A cycle C is a negative length cycle if the sum of the edge lengths of C is negative.



What is the shortest path distance between s and t?

Reminder: Paths have to be simple...

## Shortest Paths and Negative Cycles

Given G = (V, E) with edge lengths and s, t. Suppose

- G has a negative length cycle C, and
- s can reach C and C can reach t.

## Shortest Paths and Negative Cycles

Given G = (V, E) with edge lengths and s, t. Suppose

- G has a negative length cycle C, and
- s can reach C and C can reach t.

**Question:** What is the shortest distance from s to t?

Possible answers: Define shortest distance to be:

- · undefined that is \_\_\_\_\_, OR
- the length of a shortest <u>simple</u> path from s to t.

To Kally hand

## Really bad new about negative edges, and shortest path...

#### Lemma

If there is an efficient algorithm to find a shortest simple  $s \to t$  path in a graph with negative edge lengths, then there is an efficient algorithm to find the <u>longest</u> simple  $s \to t$  path in a graph with positive edge lengths.

Finding the  $s \to t$  longest path is difficult. **NP-HARD**!

with negative edges

Restating problem of Shortest path

## Alternatively: Finding Shortest Walks

Given a graph G = (V, E):

- A path is a sequence of <u>distinct</u> vertices  $v_1, v_2, ..., v_k$  such that  $(v_i, v_{i+1}) \in E$  for  $1 \le i \le k-1$ .
- A walk is a sequence of vertices  $v_1, v_2, ..., v_k$  such that  $(v_i, v_{i+1}) \in E$  for  $1 \le i \le k-1$ . Vertices are allowed to repeat.

Define dist(u, v) to be the length of a shortest walk from u to v.

- If there is a walk from u to v that contains negative length cycle then  $dist(u,v)=-\infty$
- Else there is a path with at most n-1 edges whose length is equal to the length of a shortest walk and dist(u, v) is finite

Helpful to think about walks

## Shortest Paths with Negative Edge Lengths - Problems

## Algorithmic Problems

<u>Input</u>: A directed graph G = (V, E) with edge lengths (could be negative). For edge e = (u, v),  $\ell(e) = \ell(u, v)$  is its length.

## Questions:

- Given nodes s, t, either find a negative length cycle C that s can reach or find a shortest path from s to t.
- Given node s, either find a negative length cycle C that s can reach or find shortest path distances from s to all reachable nodes.
- Check if G has a negative length cycle or not.

## Shortest Paths with Negative Edge Lengths - In Undirected Graphs

**Note**: With negative lengths, shortest path problems and negative cycle detection in undirected graphs cannot be reduced to directed graphs by bi-directing each undirected edge. Why?

Problem can be solved efficiently in undirected graphs but algorithms are different and significantly more involved than those for directed graphs. One need to compute *T*-joins in the relevant graph. Pretty painful stuff.

## Shortest path via number of hops

#### **Shortest Paths and Recursion**

• Compute the shortest path distance from s to t recursively?

What are the smaller sub-problems?



#### **Shortest Paths and Recursion**

- Compute the shortest path distance from s to t recursively?
- What are the smaller sub-problems?

#### Lemma

Let G be a directed graph with arbitrary edge lengths. If

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 is a shortest path from s to  $v_k$  then for  $1 \le i < k$ :

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$$s = v_0 \rightarrow v_1 \rightarrow v_2 \rightarrow \ldots \rightarrow v_i$$
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#### **Shortest Paths and Recursion**

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- What are the smaller sub-problems?

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•  $s = v_0 \rightarrow v_1 \rightarrow v_2 \rightarrow \ldots \rightarrow v_i$  is a shortest path from s to  $v_i$ 

Sub-problem idea: paths of fewer hops/edges

Single-source problem: fix source s.

Assume that all nodes can be reached by s in G

Assume G has no negative-length cycle (for now).



d(v, k): shortest walk length from s to v using at most k edges.

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Note: dist(s, v) = d(v, n - 1).

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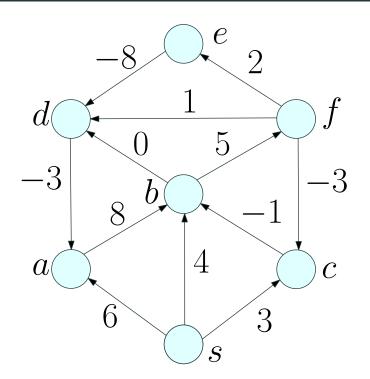
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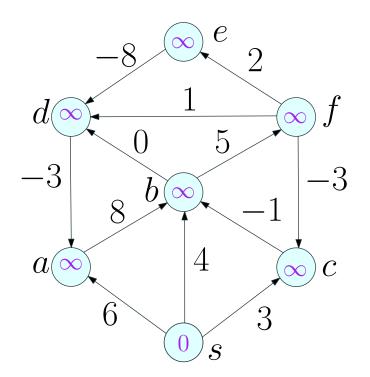
Note: dist(s, v) = d(v, n - 1). Recursion for d(v, k):

$$d(v,k) = \min \begin{cases} \min_{u \in V} (d(u,k-1) + \ell(u,v)). \end{cases}$$

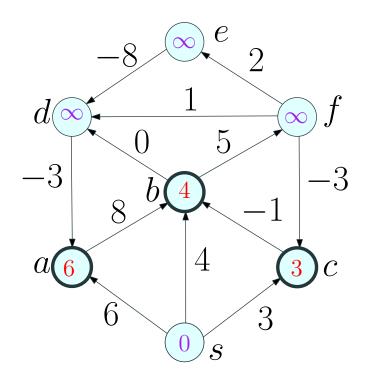
$$d(v,k-1) \text{ Shortest jeth seme a when we have a when we have a solution one fewer states and the seme a when we have a solution of the seme a when we have a when we have a whole a dorker have a dorker hav$$



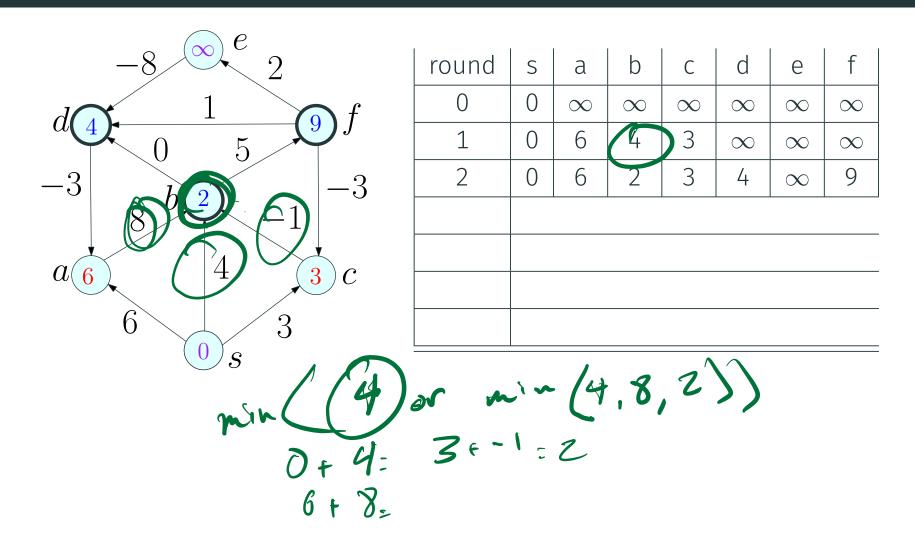
round	S	a	b	С	d	e	f

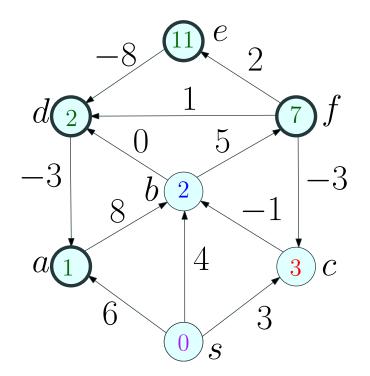


round	S	a	b	C	d	е	f
0	0	$\infty$	$\infty$	$\infty$	$\infty$	$\infty$	$\infty$

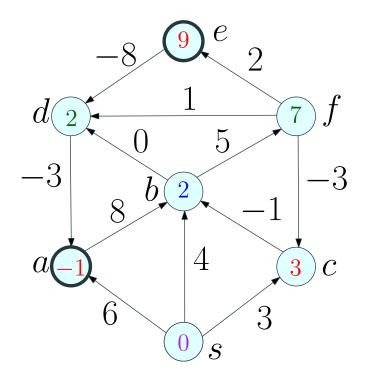


round	S	a	b	С	d	е	f
0	0	$\infty$	$\infty$	$\infty$	$\infty$	$\infty$	$\infty$
1	0	6	4	3	$\infty$	$\infty$	$\infty$

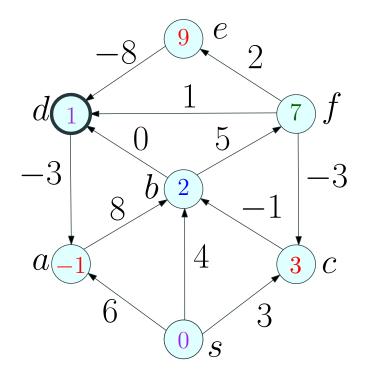




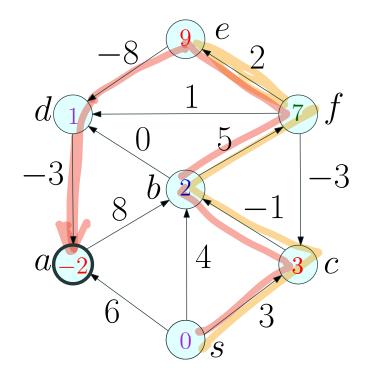
round	S	a	b	С	d	e	f
0	0	$\infty$	$\infty$	$\infty$	$\infty$	$\infty$	$\infty$
1	0	6	4	3	$\infty$	$\infty$	$\infty$
2	0	6	2	3	4	$\infty$	9
3	0	1	2	3	2	11	7



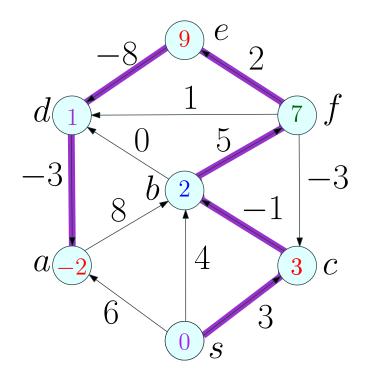
round	S	a	b	С	d	e	f
0	0	$\infty$	$\infty$	$\infty$	$\infty$	$\infty$	$\infty$
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round	S	a	b	С	d	e	f
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```
Create in(G) list from adj(G)
for each u \in V do
    d(u,0) \leftarrow \infty
d(s,0) \leftarrow 0
for k = 1 to n - 1 do
      for each v \in V do
           d(v, k) \leftarrow d(v, k-1)
            for each edge (u, v) \in in(v) do
                 d(v, k) = \min\{d(v, k), d(u, k - 1) + \ell(u, v)\}\
for each v \in V do
      dist(s, v) \leftarrow d(v, n-1)
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Running time: O(n(n+m))

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Running time: O(n(n+m)) Space:

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for each v \in V do
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```

Running time: O(n(n+m)) Space:  $O(m+n^2)$  (Space can be reduced to O(m+n)).

## Bellman-Ford Algorithm: Cleaner version

```
for each u \in V do
     d(u) \leftarrow \infty
d(s) \leftarrow 0
for k = 1 to n - 1 do
      for each v \in V do
            for each edge (u, v) \in in(v) do
                  d(v) = \min\{d(v), d(u) + \ell(u, v)\}\
for each v \in V do
            dist(s, v) \leftarrow d(v)
```

Running time: O(mn) Space: O(m+n)

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for each v \in V do
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```

relaxing relaxing

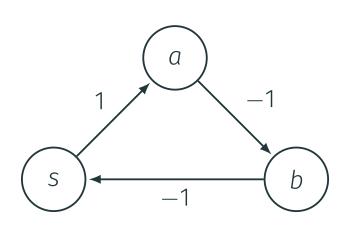
Running time: O(mn) Space: O(m+n) Do we need the in(V) list?

## Bellman-Ford Algorithm: Cleaner version

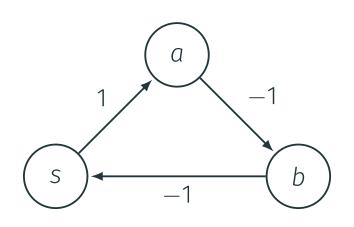
```
for each u \in V do
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            d(v) = \min\{d(v), d(u) + \ell(u, v)\}\
for each v \in V do
            dist(s, v) \leftarrow d(v)
```

Running time: O(mn) Space: O(n)

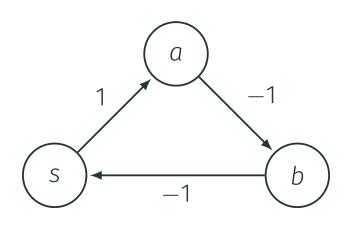
# Bellman-Ford: Detecting negative cycles



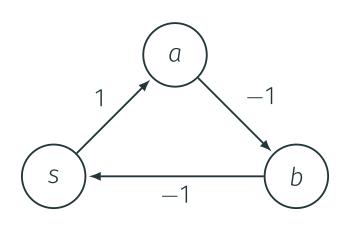
round	S	a	b



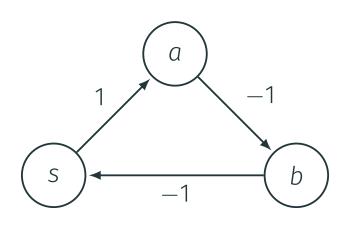
round	S	a	b
0	0	$\infty$	$\infty$
		_	



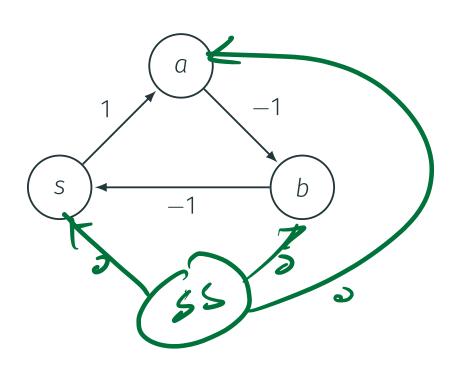
round	S	а	b
0	0	$\infty$	$\infty$
1	0	1	$\infty$



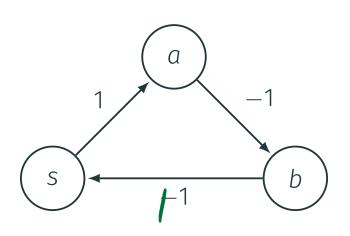
round	S	a	b
0	0	$\infty$	$\infty$
1	0	1	$\infty$
2	0	1	0



round	S	а	b
0	0	$\infty$	$\infty$
1	0	1	$\infty$
2	0	1	0
3	-1	1	0



round	S	a	b
0	0	$\infty$	$\infty$
1	0	1	$\infty$
2	0	1	0
3	-1	1	0
4	-1	0	0



round	S	а	b
0	0	$\infty$	$\infty$
1	0	1	$\infty$
2	0	1	0
3	-1	1	0
4	-1	0	0
5	-1	0	-1

# Negative cycles can not hide

#### Lemma restated

If G does not has a negative length cycle reachable from  $s \implies \forall v$ :

$$d(v,n)=d(v,n-1).$$

Also, d(v, n-1) is the length of the shortest path between s and v.

Put together are the following:

#### Lemma

G has a negative length cycle reachable from  $s \iff$  there is some node v such that d(v,n) < d(v,n-1).

#### Bellman-Ford: Negative Cycle Detection - final version

```
for each u \in V do
     d(u) \leftarrow \infty
d(s) \leftarrow 0
for k = 1 to n - 1 do
     for each v \in V do
          for each edge (u, v) \in in(v) do
                d(v) = \min\{d(v), d(u) + \ell(u, v)\}\
(* One more iteration to check if distances change *)
for each v \in V do
     for each edge (u,v) \in in(v) do
          if (d(v) > d(u) + \ell(u, v))
                Output ``Negative Cycle''
for each v \in V do
     dist(s, v) \leftarrow d(v)
```

# Variants on Bellman-Ford

# Finding the Paths and a Shortest Path Tree

How do we find a shortest path tree in addition to distances?

- For each v the d(v) can only get smaller as algorithm proceeds.
- If d(v) becomes smaller it is because we found a vertex u such that  $d(v) > d(u) + \ell(u, v)$  and we update  $d(v) = d(u) + \ell(u, v)$ . That is, we found a shorter path to v through u.
- For each v have a prev(v) pointer and update it to point to u if v finds a shorter path via u.
- At end of algorithm *prev*(*v*) pointers give a shortest path tree oriented towards the source *s*.

# Negative Cycle Detection

#### Negative Cycle Detection

Given directed graph G with arbitrary edge lengths, does it have a negative length cycle?

# **Negative Cycle Detection**

#### **Negative Cycle Detection**

Given directed graph G with arbitrary edge lengths, does it have a negative length cycle?

- Bellman-Ford checks whether there is a negative cycle *C* that is reachable from a specific vertex *s*. There may negative cycles not reachable from *s*.
- Run Bellman-Ford |V| times, once from each node u?

# Negative Cycle Detection

- Add a new node s' and connect it to all nodes of G with zero length edges. Bellman-Ford from s' will fill find a negative length cycle if there is one.
- · Negative cycle detection can be done with one Bellman-Ford invocation.

# Shortest Paths in DAGs

#### Shortest Paths in a DAG

#### Single-Source Shortest Path Problems

**Input** A directed acyclic graph G = (V, E) with arbitrary (including negative) edge lengths. For edge e = (u, v),  $\ell(e) = \ell(u, v)$  is its length.

- Given nodes s, t find shortest path from s to t.
- Given node s find shortest path from s to all other nodes.

#### Shortest Paths in a DAG

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- Given nodes s, t find shortest path from s to t.
- Given node s find shortest path from s to all other nodes.

#### Simplification of algorithms for DAGs

- No cycles and hence no negative length cycles! Hence can find shortest paths even for negative length edges
- Can order nodes using topological sort

# Algorithm for DAGs

- · Want to find shortest paths from s. Ignore nodes not reachable from s.
- Let  $s = v_1, v_2, v_{i+1}, \dots, v_n$  be a topological sort of G

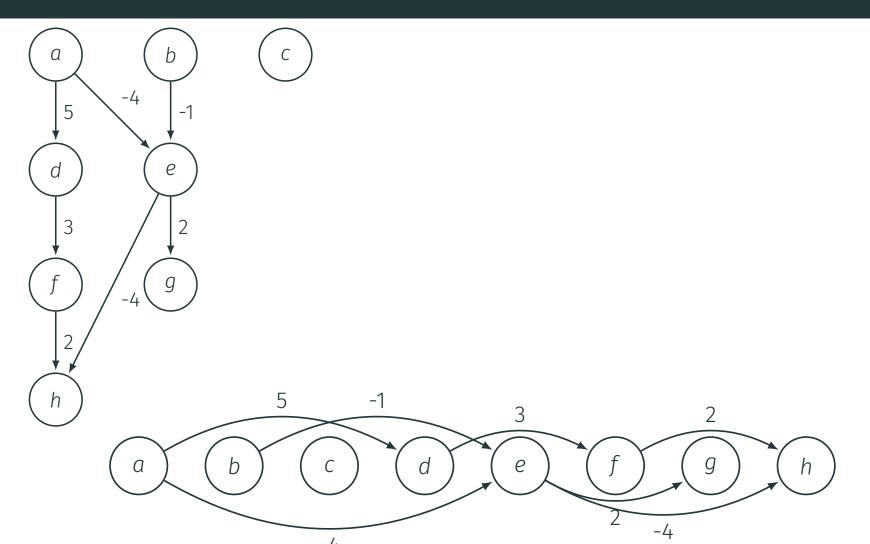
# Algorithm for DAGs

- Want to find shortest paths from s. Ignore nodes not reachable from s.
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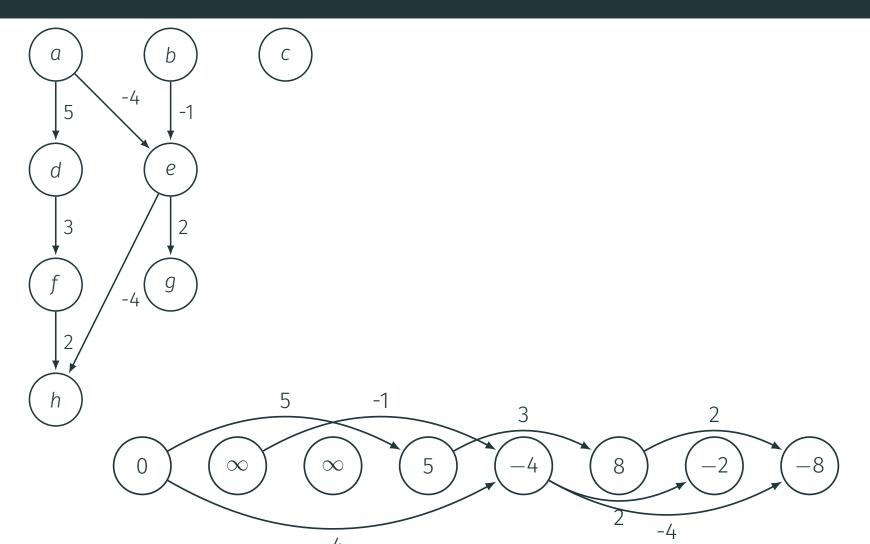
#### Observation:

- shortest path from s to  $v_i$  cannot use any node from  $v_{i+1}, \ldots, v_n$
- can find shortest paths in topological sort order.

# Shortest Paths for DAGs - Example



# Shortest Paths for DAGs - Example



# Algorithm for DAGs

```
for i=1 to n do d(s,v_i)=\infty d(s,s)=0 for i=1 to n-1 do for \ each \ edge \ (v_i,v_j) \ in \ Adj(v_i) \ do d(s,v_j)=\min\{d(s,v_j),d(s,v_i)+\ell(v_i,v_j)\} return d(s,\cdot) values computed
```

Correctness: induction on *i* and observation in previous slide.

Running time: O(m + n) time algorithm! Works for negative edge lengths and hence can find longest paths in a DAG.

# All Pairs Shortest Paths

#### Shortest Path Problems

#### Shortest Path Problems

**Input** A (undirected or directed) graph G = (V, E) with edge lengths (or costs). For edge e = (u, v),  $\ell(e) = \ell(u, v)$  is its length.

- Given nodes s, t find shortest path from s to t.
- Given node s find shortest path from s to all other nodes.
- Find shortest paths for all pairs of nodes.

# SSSP: Single-Source Shortest Paths

#### Single-Source Shortest Path Problems

**Input** A (undirected or directed) graph G = (V, E) with edge lengths. For edge e = (u, v),  $\ell(e) = \ell(u, v)$  is its length.

- Given nodes s, t find shortest path from s to t.
- Given node s find shortest path from s to all other nodes.

# SSSP: Single-Source Shortest Paths

#### Single-Source Shortest Path Problems

**Input** A (undirected or directed) graph G = (V, E) with edge lengths. For edge e = (u, v),  $\ell(e) = \ell(u, v)$  is its length.

- Given nodes s, t find shortest path from s to t.
- Given node s find shortest path from s to all other nodes.

Dijkstra's algorithm for non-negative edge lengths. Running time:  $O((m+n)\log n)$  with heaps and  $O(m+n\log n)$  with advanced priority queues.

Bellman-Ford algorithm for arbitrary edge lengths. Running time: O(nm).

# All-Pairs Shortest Paths - Using known algorithms...

#### All-Pairs Shortest Path Problem

**Input** A (undirected or directed) graph G = (V, E) with edge lengths. For edge e = (u, v),  $\ell(e) = \ell(u, v)$  is its length.

Find shortest paths for all pairs of nodes.

# All-Pairs Shortest Paths - Using known algorithms...

#### All-Pairs Shortest Path Problem

**Input** A (undirected or directed) graph G = (V, E) with edge lengths. For edge e = (u, v),  $\ell(e) = \ell(u, v)$  is its length.

Find shortest paths for all pairs of nodes.

Apply single-source algorithms *n* times, once for each vertex.

- Non-negative lengths.  $O(nm \log n)$  with heaps and  $O(nm + n^2 \log n)$  using advanced priority queues.
- Arbitrary edge lengths:  $O(n^2m)$ .  $\Theta(n^4)$  if  $m = \Omega(n^2)$ .

# All-Pairs Shortest Paths - Using known algorithms...

#### All-Pairs Shortest Path Problem

**Input** A (undirected or directed) graph G = (V, E) with edge lengths. For edge e = (u, v),  $\ell(e) = \ell(u, v)$  is its length.

• Find shortest paths for all pairs of nodes.

Apply single-source algorithms *n* times, once for each vertex.

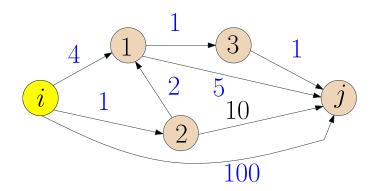
- Non-negative lengths.  $O(nm \log n)$  with heaps and  $O(nm + n^2 \log n)$  using advanced priority queues.
- Arbitrary edge lengths:  $O(n^2m)$ .  $\Theta(n^4)$  if  $m = \Omega(n^2)$ .

Can we do better?

All Pairs Shortest Paths: A recursive

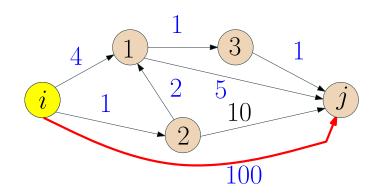
solution

- Number vertices arbitrarily as  $v_1, v_2, \ldots, v_n$
- dist(i,j,k): length of shortest walk from  $v_i$  to  $v_j$  among all walks in which the largest index of an intermediate node is at most k (could be  $-\infty$  if there is a negative length cycle).



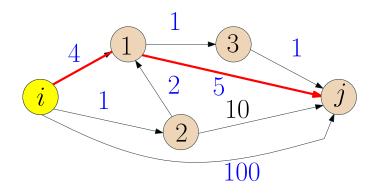
$$dist(i, j, 0) = 100$$
  
 $dist(i, j, 1) = 9$   
 $dist(i, j, 2) = 9$   
 $dist(i, j, 3) = 6$ 

- Number vertices arbitrarily as  $v_1, v_2, \ldots, v_n$
- dist(i, j, k): length of shortest walk from  $v_i$  to  $v_j$  among all walks in which the largest index of an intermediate node is at most k (could be  $-\infty$  if there is a negative length cycle).



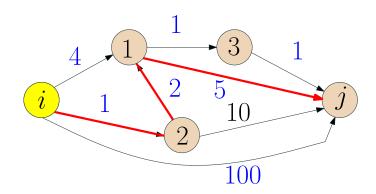
$$dist(i,j,0) = 100$$
  
 $dist(i,j,1) =$   
 $dist(i,j,2) =$   
 $dist(i,j,3) =$ 

- Number vertices arbitrarily as  $v_1, v_2, \ldots, v_n$
- dist(i, j, k): length of shortest walk from  $v_i$  to  $v_j$  among all walks in which the largest index of an intermediate node is at most k (could be  $-\infty$  if there is a negative length cycle).



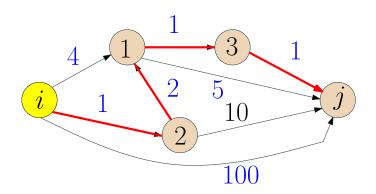
$$dist(i, j, 0) = 100$$
  
 $dist(i, j, 1) = 9$   
 $dist(i, j, 2) = 0$   
 $dist(i, j, 3) = 0$ 

- Number vertices arbitrarily as  $v_1, v_2, \ldots, v_n$
- dist(i, j, k): length of shortest walk from  $v_i$  to  $v_j$  among all walks in which the largest index of an <u>intermediate node</u> is at most k (could be  $-\infty$  if there is a negative length cycle).



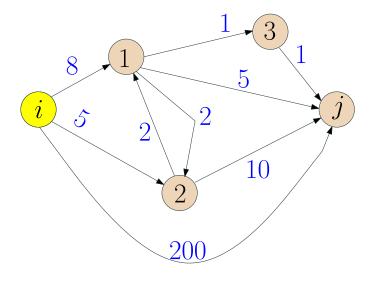
$$dist(i, j, 0) = 100$$
  
 $dist(i, j, 1) = 9$   
 $dist(i, j, 2) = 8$   
 $dist(i, j, 3) = 9$ 

- Number vertices arbitrarily as  $v_1, v_2, \ldots, v_n$
- dist(i, j, k): length of shortest walk from  $v_i$  to  $v_j$  among all walks in which the largest index of an intermediate node is at most k (could be  $-\infty$  if there is a negative length cycle).



dist(i, j, 0) =	100
dist(i, j, 1) =	9
dist(i, j, 2) =	8
dist(i, j, 3) =	5

# For the following graph, dist(i, j, 2) is...



- 1. 9
- 2. 10
- 3. 11
- 4. 12
- 5. 15

$$\operatorname{dist}(i, k, k-1) = k \qquad \operatorname{dist}(k, j, k-1)$$

$$\operatorname{dist}(i, j, k-1)$$

$$dist(i, j, k) = \min \begin{cases} dist(i, j, k - 1) \\ dist(i, k, k - 1) + dist(k, j, k - 1) \end{cases}$$

Base case:  $dist(i, j, 0) = \ell(i, j)$  if  $(i, j) \in E$ , otherwise  $\infty$ 

Correctness: If  $i \rightarrow j$  shortest walk goes through k then k occurs only once on the

36

If i can reach k and k can reach j and dist(k, k, k - 1) < 0 then G has a negative length cycle containing k and  $dist(i, j, k) = -\infty$ .

Recursion below is valid only if  $dist(k, k, k - 1) \ge 0$ . We can detect this during the algorithm or wait till the end.

$$dist(i, j, k) = \min \begin{cases} dist(i, j, k - 1) \\ dist(i, k, k - 1) + dist(k, j, k - 1) \end{cases}$$

Floyd-Warshall algorithm

#### Floyd-Warshall Algorithm - for All-Pairs Shortest Paths

$$d(i, j, k) = \min \begin{cases} d(i, j, k - 1) \\ d(i, k, k - 1) + d(k, j, k - 1) \end{cases}$$

```
for i = 1 to n do
      for j = 1 to n do
            d(i,j,0) = \ell(i,j)
 (* \ell(i,j) = \infty \text{ if } (i,j) \notin E, \text{ 0 if } i = j *)
for k = 1 to n do
      for i = 1 to n do
            for j = 1 to n do
                d(i, j, k) = \min \begin{cases} d(i, j, k - 1), \\ d(i, k, k - 1) + d(k, j, k - 1) \end{cases}
for i = 1 to n do
      if (dist(i, i, n) < 0) then
             Output \exists negative cycle in G
```

#### Floyd-Warshall Algorithm - for All-Pairs Shortest Paths

$$d(i, j, k) = \min \begin{cases} d(i, j, k - 1) \\ d(i, k, k - 1) + d(k, j, k - 1) \end{cases}$$

```
for i = 1 to n do
      for j = 1 to n do
           d(i,j,0) = \ell(i,j)
 (* \ell(i,j) = \infty \text{ if } (i,j) \notin E, 0 \text{ if } i = j *)
for k = 1 to n do
      for i = 1 to n do
            for j = 1 to n do
                d(i,j,k) = \min \begin{cases} d(i,j,k-1), \\ d(i,k,k-1) + d(k,j,k-1) \end{cases}
for i = 1 to n do
      if (dist(i, i, n) < 0) then
            Output \exists negative cycle in G
```

# Floyd-Warshall Algorithm - for All-Pairs Shortest Paths

$$d(i,j,k) = \min \begin{cases} d(i,j,k-1) \\ d(i,k,k-1) + d(k,j,k-1) \end{cases}$$

```
for i = 1 to n do
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 (* \ell(i,j) = \infty \text{ if } (i,j) \notin E, \text{ 0 if } i = j *)
for k = 1 to n do
      for i = 1 to n do
            for j = 1 to n do
                d(i, j, k) = \min \begin{cases} d(i, j, k - 1), \\ d(i, k, k - 1) + d(k, j, k - 1) \end{cases}
for i = 1 to n do
      if (dist(i, i, n) < 0) then
             Output \exists negative cycle in G
```

# Floyd-Warshall Algorithm: Finding the Paths

Question: Can we find the paths in addition to the distances?

# Floyd-Warshall Algorithm: Finding the Paths

Question: Can we find the paths in addition to the distances?

- Create a  $n \times n$  array Next that stores the next vertex on shortest path for each pair of vertices
- With array Next, for any pair of given vertices i, j can compute a shortest path in O(n) time.

# Floyd-Warshall Algorithm - Finding the Paths

```
for i = 1 to n do
    for i = 1 to n do
          d(i, j, 0) = \ell(i, j)
(* \ell(i,j) = \infty if (i,j) not edge, 0 if i = j *)
          Next(i, j) = -1
for k = 1 to n do
     for i = 1 to n do
          for i = 1 to n do
               if (d(i,j,k-1) > d(i,k,k-1) + d(k,j,k-1)) then
                    d(i, j, k) = d(i, k, k - 1) + d(k, j, k - 1)
                    Next(i, j) = k
for i = 1 to n do
     if (d(i, i, n) < 0) then
          Output that there is a negative length cycle in G
```

**Exercise:** Given *Next* array and any two vertices i, j describe an O(n) algorithm to find a i-j shortest path.

Summary of shortest path algorithms

# Summary of results on shortest paths

Single source		
No negative edges	Dijkstra	$O(n \log n + m)$
Edge lengths can be negative	Bellman Ford	O(nm)

#### All Pairs Shortest Paths

No negative edges	n * Dijkstra	$O(n^2 \log n + nm)$
No negative cycles	n * Bellman Ford	$O(n^2m) = O(n^4)$
No negative cycles	Johnson's <sup>1</sup>	$O(nm + n^2 \log n)$
No negative cycles	Floyd-Warshall	$O(n^3)$
Unweighted	Matrix multiplication <sup>2</sup>	$O(n^{2.38}), O(n^{2.58})$

# Summary of results on shortest paths

- (1): The algorithm for the case that there are no negative cycles, and doing all shortest paths, works by computing a potential function using **Bellman-Ford** and then doing **Dijkstra**. It is mentioned for the sake of completeness, but it outside the scope of the class.
- (2): https://resources.mpi-inf.mpg.de/departments/d1/teaching/ss12/AdvancedGraphAlgorithms/Slides14.pdf

# Fin