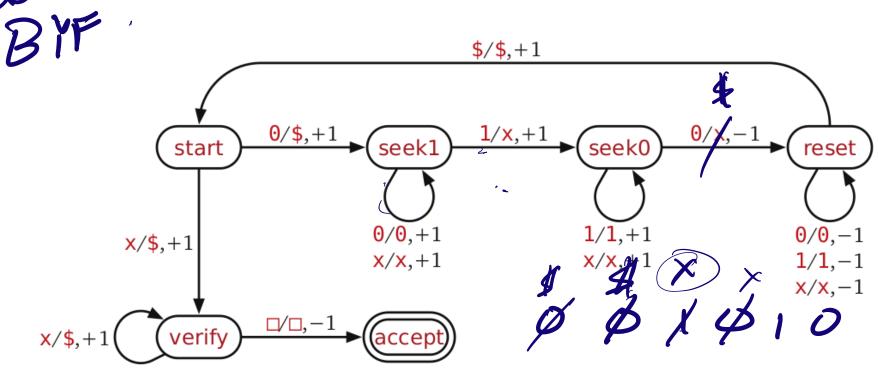
#### Pre-lecture brain teaser

You have the following Turing machine diagram that accepts a particular guage whose alphabet  $\Sigma = \{0,1\}$ . Please describe the language.



# ECE-374-B: Lecture 8 - Universal Turing Machines

Instructor: Nickvash Kani

September 23, 2025

University of Illinois Urbana-Champaign

#### Pre-lecture brain teaser

You have the following Turing machine diagram that accepts a particular language whose alphabet  $\Sigma = \{0, 1\}$ . Please describe the language. \$/\$,+10/\$, +11/x,+10/x, -1seek0 start seek1 reset 0/0, -11/1,+1x/x,+11/1,-1verify x/\$, +1

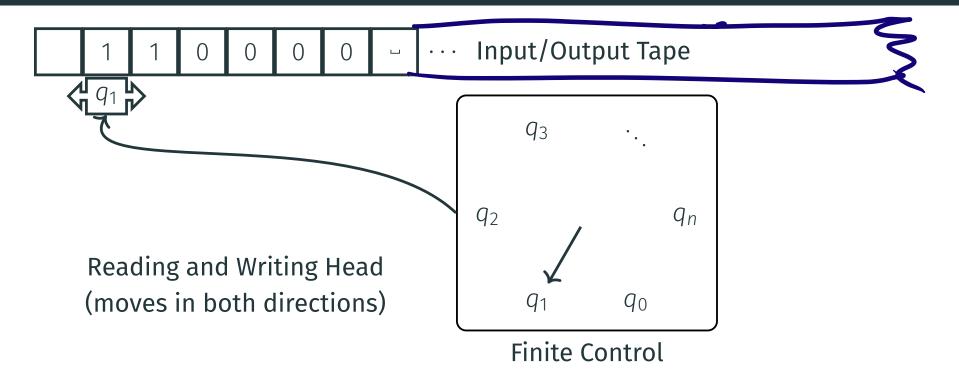
#### Pre-lecture brain teaser - code

Can simulate TM on turingmachine.io using the following code:

```
start state: start
table:
start:
    # Inductive case: start with the same symbol.
    0: {write: '$', R: seek1}
    # Base case: empty string.
    'x': {write: '$', R: verify}
seek1:
   [0,'x']: R
    1: {write: 'x', R: seek0}
seek0:
    [1,'x']: R
    0: {write: 'x', L: reset}
reset:
    [0,1,'x']: L
    '$': {R: start}
verify:
    x: {write: '$', R}
    ' ': {L: accept}
accept:
```

# Turing machine recap

# Turing machine



- Input written on (infinite) one sided tape.
- Special blank characters.
- Finite state control (similar to DFA).
- Ever step: Read character under head, write character out, move the head

#### **Transition function**

Current state

Scanned symbol

 $\delta: Q \times \Gamma = Q \times \Gamma \times \{L, R\}$  Direction to move on tape

Symbol to write

New State

 $\delta(q, a) = (p, b, L)$  means from state q, on reading a:

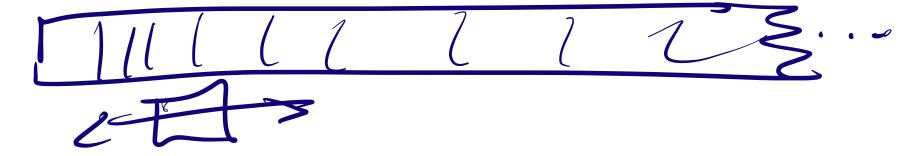
- go to state p
- write b
- move head Left

# Turing machine varients

# **Equivalent Turing Machines**

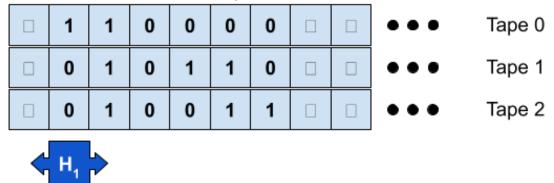
#### Several variations of a Turing machine:

- Standard Turing machine (single infinite tape)
- Multi-track tapes
- Doubly-Infinite Tape
- Multiple heads
- Multiple heads and tapes



#### Multi-track Tapes

Suppose we have a TM with multiple tracks:



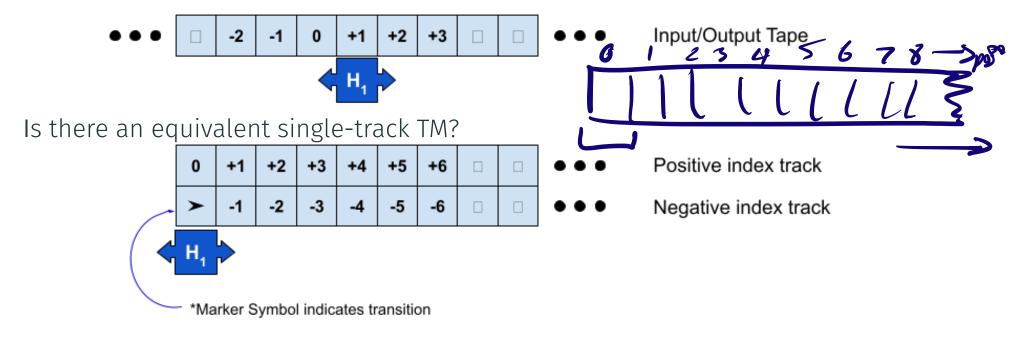
Is there an equivalent single-track TM?



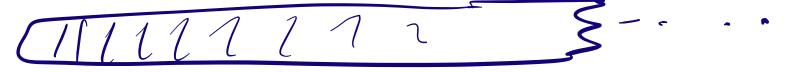
New transition function:  $\delta: Q \times \Gamma_1 \times \Gamma_2 \times \Gamma_3 \to Q \times \Gamma_1 \times \Gamma_2 \times \Gamma_3 \times \{-1, +1\}$ 

#### Infinite Bi-directional Tape

Suppose we have a TM with multiple tracks:

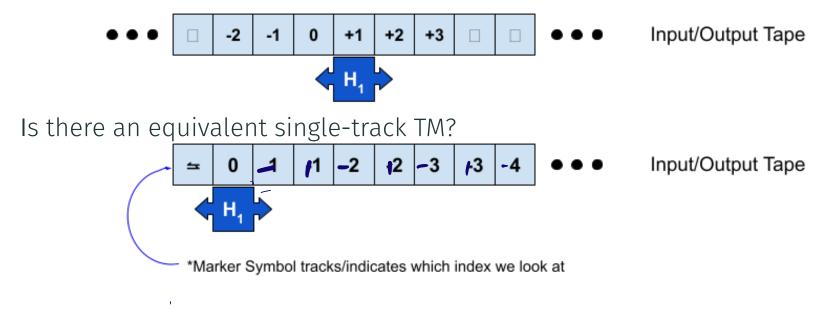


Can model as multiple tapes.



#### Infinite Bi-directional Tape

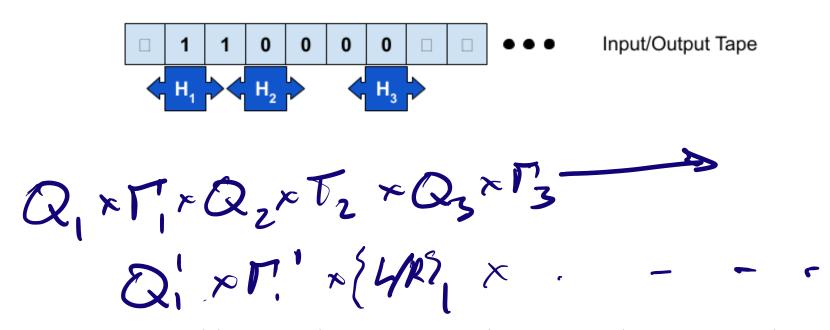
Suppose we have a TM with a bidirectional tape:



Or as single tape interleaved with positive and negative indexes.

#### Multiple Read/Write Heads

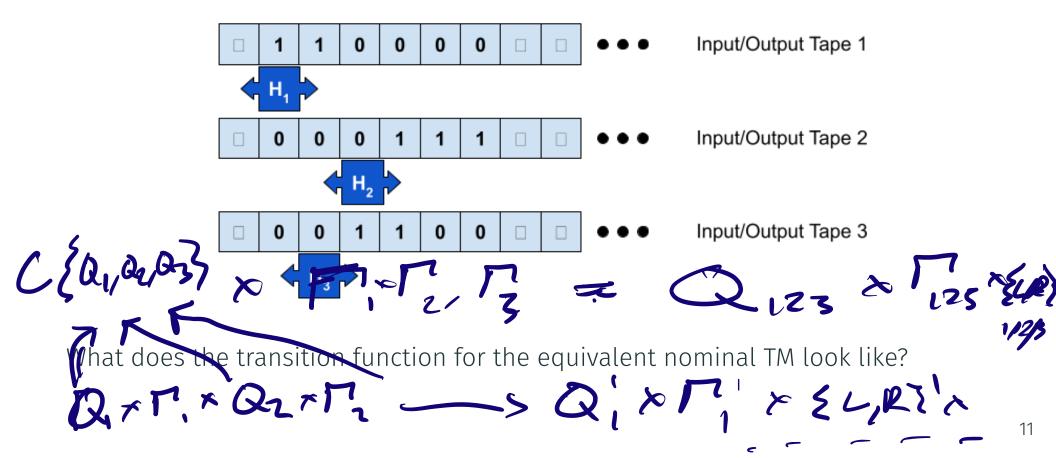
Suppose we have a TM with multiple heads:



What does the transition function for the equivalent nominal TM look like?

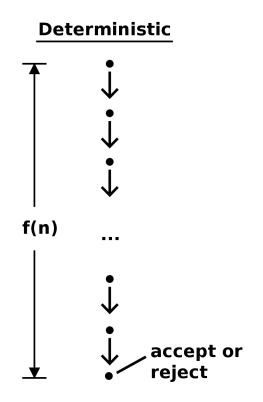
#### Multiple Read/Write Heads

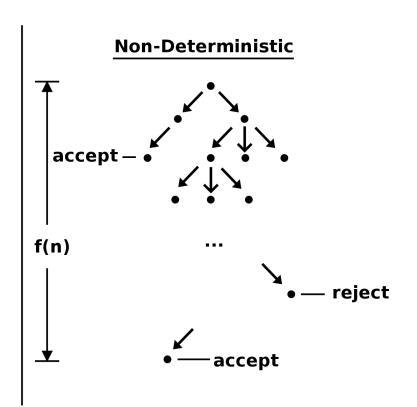
Suppose we have a TM with multiple heads and tracks:



# Determinism in Turing machines

#### Remember Non-determinism?





# Non-deterministic Turing machine?

What does a non-deterministic Turing machine look like?

# Non-deterministic Turing machine?

What does a non-deterministic Turing machine look like?

Is a NTM more powerful than a DTM?

#### Power of NTM

No. A DTM can simulate a NTM in the following ways:

- Multiplicity of configuration of states
  - 1. Have the store multiple configurations of the NTM.
  - 2. At every timestep, process each configuration. Add configurations to the set if multiple paths exist.
- Multiple Tapes Can simulate NTM with 3-tape DTM:

  1 First tape holds original input

  Compute Stars
  - 1. First tape holds original input

2. Second used to simulate a particular computation of NTM

3. Third tape encodes path in NTM computation tree.

Effectively this is a breadth-first search of non-deterministic computation tree.

#### Savitch's Theorem

Proved by Walter Savitch in 1970, states that for any function  $f \in \Omega(\log(n))$ :

$$NSPACE(f(n)) \subseteq DSPACE(f(n)^2)$$

#### Lemma

If a NTM can solve a problem using f(n) space, a DTM can solve the same problem int he square of that space bound.

⇒ Even though non-determinism significantly reduces time to solve problem, it reduces space requirements far less!

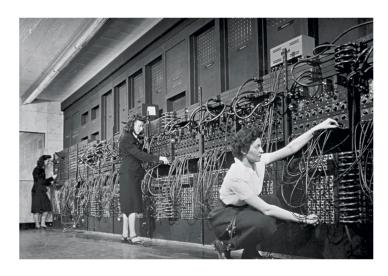
# Universal Turing Machine

# Special Purpose Machines?

We've seen that you need different DFAs for different languages.

We've seen that you need different TMs for different languages.

Early computers were no different.



# Universal Turing Machine

A single TM  $M_u$  that can compute anything computable!

#### Takes as input:

- the description of some other TM M
- · data w for M to run on

#### Outputs:

results of running M(w)

# Coding of TMs

Show how to represent every TM as a natural number

#### Lemma

If L over alphabet {0,1} is accepted by some TM M, then there is a one-tape TM M that accepts L, such that

- $\Gamma = \{0, 1, B\}$
- states numbered 1, . . . , k
- q<sub>1</sub> is a unique start state
- q<sub>2</sub> is a unique halt/accept state
- $q_3$  is a unique halt/reject state

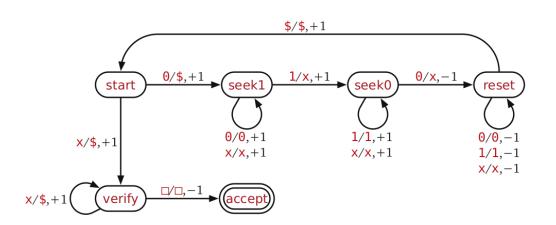
So to represent a TM, we need only list its set of transitions - everything else is implicit by the above.

# **Encoding Alphabet**

Consider the TM that recognizes the language  $L = \{0^n 1^n 0^n | n \ge 0\}$  with the state diagram shown below:

#### Input encoding:

- $\cdot \langle 0 \rangle = 001$
- $\cdot$   $\langle 1 \rangle = 010$
- $\langle \$ \rangle = 011$
- $\langle \mathbf{x} \rangle = 100$
- $\langle \square \rangle = 000$



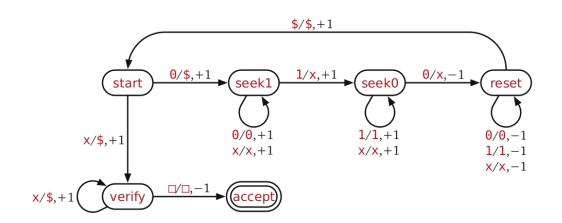
Example:  $\langle 001100 \rangle = [001 \cdot 001 \cdot 010 \cdot 010 \cdot 001 \cdot 001]$  (Putting · separators for the sake of legibility)

# **Encoding states**

Consider the TM that recognizes the language  $L = \{0^n 1^n 0^n | n \ge 0\}$  with the state diagram shown below:

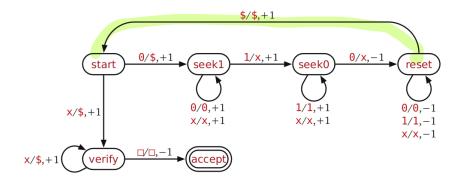
#### State encoding:

- $\langle \text{start} \rangle = 001$
- $\langle \text{seek1} \rangle = 010$
- $\langle \operatorname{seek} 0 \rangle = 011$
- $\langle \text{reset} \rangle = 100$
- $\langle \text{verify} \rangle = 101$
- $\langle \text{accept} \rangle = 110$
- $\langle \text{reject} \rangle = 000$



# **Encoding States and Alphabet**

Consider the TM that recognizes the language  $L = \{0^n 1^n 0^n | n \ge 0\}$  with the state diagram shown below:

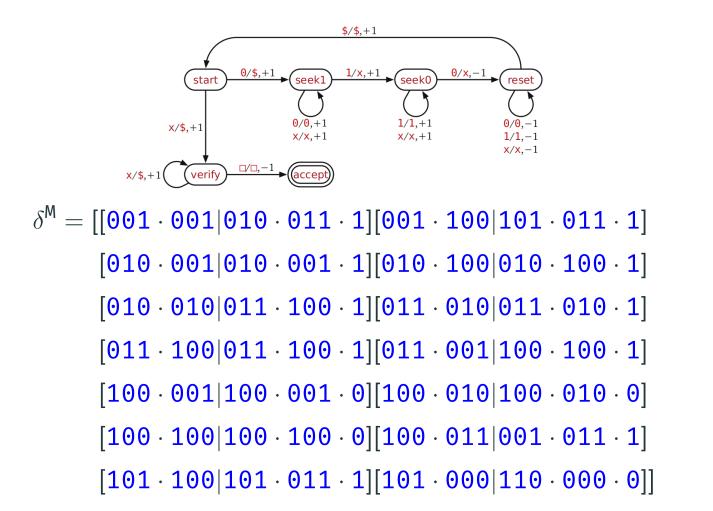


Now we need to encode a transition. Last thing we'll need is to encode the movement of the head whihe we'll describe as: [left, right] = [0, 1].

Example: How do we encode:  $\delta(\text{reset},\$) = (\text{start},\$,\text{right})$ 

Answer:  $[100 \cdot 011|001 \cdot 011 \cdot 1]$ 

#### Encoding machine through transitions



# Encoding machine through transitions

```
\delta^{\mathsf{M}} = 	exttt{[[001 \cdot 001 | 010 \cdot 011 \cdot 1][001 \cdot 100 | 101 \cdot 011 \cdot 1]}
                             [010 \cdot 001|010 \cdot 001 \cdot 1][010 \cdot 100|010 \cdot 100 \cdot 1]
                             [010 \cdot 010|011 \cdot 100 \cdot 1][011 \cdot 010|011 \cdot 010 \cdot 1]
                             [011 \cdot 100|011 \cdot 100 \cdot 1] [011 \cdot 001|100 \cdot 100 \cdot 1]
                             [100 \cdot 001|100 \cdot 001 \cdot 0][100 \cdot 010|100 \cdot 010 \cdot 0]
                             [100 \cdot 100 | 100 \cdot 100 \cdot 0][100 \cdot 011 | 001 \cdot 011 \cdot 1]
                             [101 \cdot 100|101 \cdot 011 \cdot 1][101 \cdot 000|110 \cdot 000 \cdot 0]]
\delta(\text{seek}0, X) = (\text{seek}0, X, \text{right})
```

#### Encoding initial state

Ok so now we've encoded the Turing machine (M) into a string, how do we make a machine  $M_u(M, w)$  which accepts if M(w) accepts, and rejects if M(w) rejects?

#### Encoding initial state

Ok so now we've encoded the Turing machine (M) into a string, how do we make a machine  $M_u(M, w)$  which accepts if M(w) accepts, and rejects if M(w) rejects?

Let's start with the encoding of w (let's say w = 001100):  $\langle 001100 \rangle = [001 \cdot 001 \cdot 010 \cdot 010 \cdot 001]$ 

#### Encoding initial state

Ok so now we've encoded the Turing machine (M) into a string, how do we make a machine  $M_u(M, w)$  which accepts if M(w) accepts, and rejects if M(w) rejects?

```
Let's start with the encoding of w (let's say w = 001100): \langle 001100 \rangle = [001 \cdot 001 \cdot 010 \cdot 010 \cdot 001]
```

Now let's add spaces next to each character so we can mark where M's head is:  $[[000 \cdot 001][000 \cdot 001][000 \cdot 010][000 \cdot 001][000 \cdot 001]]$ 

#### **Encoding states**

Padding used to mark state.

```
In the beginning,q = \langle \text{start} \rangle = 001 so our machine tapes initial string is: [[001 \cdot 001][000 \cdot 001][000 \cdot 010][000 \cdot 001][000 \cdot 001]]
```

Similarly intermediate configuration

```
M = \langle \text{state}, \text{tape string}, \text{head position} \rangle = (\text{seek1}, \$0\text{x}1\text{x}0, 3) \text{ would be marked as:}
[[000 \cdot 011] [000 \cdot 001] [000 \cdot 100] [010 \cdot 010] [000 \cdot 100] [000 \cdot 001]]
\text{reject \$ reject 0} \text{ reject x seek1 1 reject x reject 0}
```

The universal Turing machine

#### **UTM** introduction

Now that we are able to encode Turing machines, we want to construct a Turing machine such that:

$$L(M_u) = \{\langle M \rangle \# w | M \text{ accepts } w\}$$

 $M_u$  is a stored-program computer. It reads < M > and executes it on data w.

 $M_u$  simulates the run of M on w.

# Encodings

M: Turing machine

 $\langle M \rangle$ : a string uniquely describing M (i.e., it is a number.

w: An input string.

 $\langle M, w \rangle$ : A unique string encoding both M and input w.

$$L(M_u) = \{ \langle M, w \rangle M \text{ is a TM } \text{and } M \text{ accepts } w \}.$$

# *M<sub>u</sub>* Operational concept

We assume without a loss of generality that our universal turing machine  $(M_u)$  has two tapes and two heads:

- **Input tape:** which stores the encoding of  $\langle M \rangle = \langle \text{state}, \text{tape input}, \text{head position} \rangle$
- Machine tape: Encoding tape which stores M's encoding

**General Idea:** For any given configuration of M, our  $M_u$  will.

- Starting from leftmost of input tape, scan tape for first state which is not  $\langle \mathbf{reject} \rangle$
- $M_u$  scans machine tape for the transition function that matches the substring found in the input tape.
- Based on transition function,  $M_u$  writes the right half of this transition function into the current input tape cell.
- Based on head direction of the transition function,  $M_u$  moves the current state left or right

#### Simulation example I

Let's start with the configuration: M = (seek1, \$\$x1x0, 3):

- Input-Tape =  $[[000 \cdot 011][000 \cdot 011][000 \cdot 100][010 \cdot 010][000 \cdot 100][000 \cdot 001]]$
- Machine-Tape =  $\delta^M = [001 \cdot 001|010 \cdot 011 \cdot 1][001 \cdot 100|101 \cdot 011 \cdot 1][010 \cdot 001| \dots]$

First  $M_u$  searchers for none reject state:

- Input-Tape =  $[[000 \cdot 011][000 \cdot 011][000 \cdot 100][010 \cdot 010][000 \cdot 100][000 \cdot 001]]$
- Machine-Tape =  $\delta^M = [001 \cdot 001|010 \cdot 011 \cdot 1][001 \cdot 100|101 \cdot 011 \cdot 1][010 \cdot 001|...$

#### Simulation example II

- Input-Tape =  $[[000 \cdot 011][000 \cdot 011][000 \cdot 100][010 \cdot 010][000 \cdot 100][000 \cdot 001]]$
- Machine-Tape =  $\delta^M = [001 \cdot 001|010 \cdot 011 \cdot 1][001 \cdot 100|101 \cdot 011 \cdot 1][010 \cdot 001|...$

Then  $M_u$  searches for transition whose left side matches the input cell:

- Input-Tape =  $[[000 \cdot 011][000 \cdot 011][000 \cdot 100][010 \cdot 010][000 \cdot 100][000 \cdot 001]]$
- Machine-Tape =  $\delta^M = \dots 100 \cdot 1][010 \cdot 010|011 \cdot 100 \cdot 1][011 \cdot 010|011 \cdot 010 \cdot 1] \dots$

#### Simulation example III

- Input-Tape =  $[[000 \cdot 011][000 \cdot 011][000 \cdot 100][010 \cdot 010][000 \cdot 100][000 \cdot 001]]$
- Machine-Tape =  $\delta^M = \dots 100 \cdot 1][010 \cdot 010|011 \cdot 100 \cdot 1][011 \cdot 010|011 \cdot 010 \cdot 1] \dots$

Then  $M_u$  copies the right side of the transition function into the input tape:

- Input-Tape =  $[[000 \cdot 011][000 \cdot 011][000 \cdot 100][011 \cdot 100][000 \cdot 100][000 \cdot 001]]$
- Machine-Tape =  $\delta^M = \dots 100 \cdot 1][010 \cdot 010|011 \cdot 100 \cdot 1][011 \cdot 010|011 \cdot 010 \cdot 1] \dots$

# Simulation example IV

- Input-Tape =  $[[000 \cdot 011][000 \cdot 011][000 \cdot 100][011 \cdot 100][000 \cdot 100][000 \cdot 001]]$
- Machine-Tape =  $\delta^M = \dots 100 \cdot 1][010 \cdot 010|011 \cdot 100 \cdot 1][011 \cdot 010|011 \cdot 010 \cdot 1] \dots$

Then  $M_u$  move the state of the configuration according to the transition function:

- Input-Tape =  $[[000 \cdot 011][000 \cdot 011][000 \cdot 100][000 \cdot 100][011 \cdot 100][000 \cdot 001]]$
- Machine-Tape =  $\delta^M = \dots 100 \cdot 1][010 \cdot 010|011 \cdot 100 \cdot 1][011 \cdot 010|011 \cdot 010 \cdot 1] \dots$

# Simulation example V

```
• Input-Tape = [[000 \cdot 011][000 \cdot 011][000 \cdot 100][000 \cdot 100][011 \cdot 100][000 \cdot 001]]
```

```
• Machine-Tape = \delta^M = \dots 100 \cdot 1][010 \cdot 010|011 \cdot 100 \cdot 1][011 \cdot 010|011 \cdot 010 \cdot 1] \dots
```

#### Then we reset:

```
• Input-Tape = [[000 · 011][000 · 011][000 · 100][000 · 100][011 · 100][000 · 001]]
```

```
• Machine-Tape = \delta^M = [[001 \cdot 001|010 \cdot 011 \cdot 1][001 \cdot 100|101 \cdot 011 \cdot 1][010 \cdot 001| \dots]
```

#### What does this show?

- Every TM is encoded by a unique element of N (where N is a natural number)
- **Convention:** elements of N that do not correspond to any TM encoding represent the "null TM" that accepts nothing.
- Thus, every TM is a number, and vice versa
- Let <M> mean the number that encodes M. Conversely, let  $M_n$  be the TM with encoding n.

**Big Idea:** Every TM can be represent by a number (strings of 0's and 1's) and there exists a universal TM,  $M_u$ , that can simulate any other TM.