



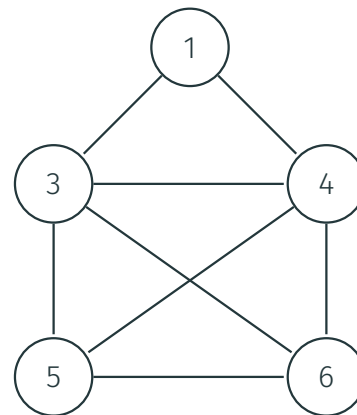
# Pre-lecture brain teaser

Consider the following algorithm which takes in a undirected graph  $(G)$  and a vertex  $s$

```
FindClique ( $G, s$ )  
   $C = s$   
  for each vertex  $v \in V$   
    flag = 1  
    for each vertex  $u \in C$   
      if  $(u, v) \notin E$   
        flag = 0  
    if flag == 1  
       $C = C \cup \{v\}$   
  return  $C$ 
```

The algorithm is a represents a greedy algorithm which finds a clique depending on a start vertex  $s$ .

- How fast is this algorithm?



# ECE-374-B: Lecture 20 - P/NP and NP-completeness

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**Instructor:** Nickvash Kani

November 11, 2025

University of Illinois Urbana-Champaign

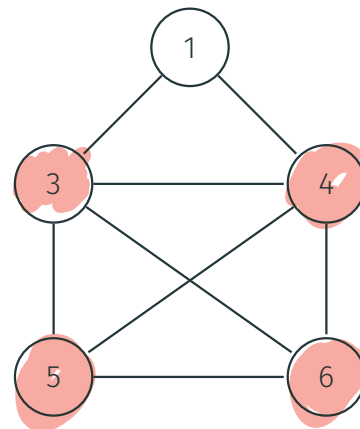
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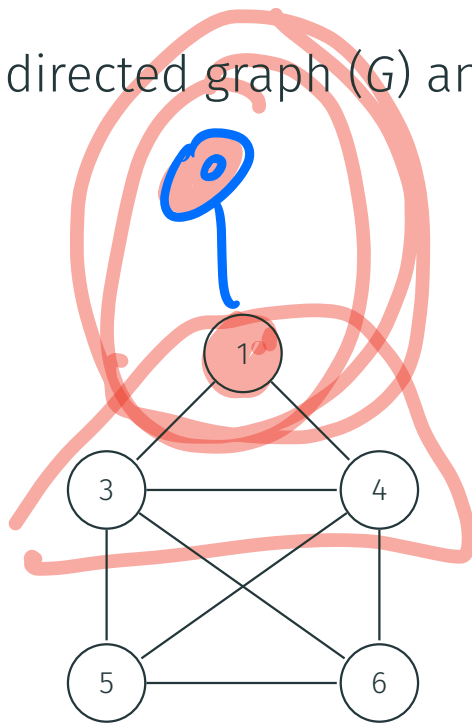
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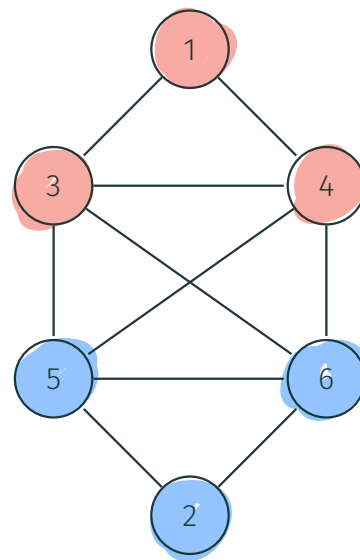


The Clique-problem is NP-complete. But this algorithm provides us with the maximal clique containing  $s$ . If we run it  $|V|$  times, does that solve the clique-problem.

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# The Satisfiability Problem (SAT)

---

# Propositional Formulas

## Definition

Consider a set of boolean variables  $x_1, x_2, \dots, x_n$ .

- A literal is either a boolean variable  $x_i$  or its negation  $\neg x_i$ .

- A clause is a disjunction of literals.

For example,  $x_1 \vee x_2 \vee \neg x_4$  is a clause.

- A formula in conjunctive normal form (CNF) is propositional formula which is a conjunction of clauses

- $(x_1 \vee x_2 \vee \neg x_4) \wedge (x_2 \vee \neg x_3) \wedge x_5$  is a CNF formula.

$$\begin{aligned} [x_1, \dots, x_5] &= [1, 1, 0, 0, 1] \\ (x_1 \vee x_2) \wedge (\bar{x}_1 \vee x_2) \wedge (x_1 \vee \bar{x}_2) \wedge (\bar{x}_1 \vee \bar{x}_2) \\ [x_1, x_2] &= [0, 0] = [1, 1] \end{aligned}$$



# Propositional Formulas

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  - $(x_1 \vee x_2 \vee \neg x_4) \wedge (x_2 \vee \neg x_3) \wedge x_5$  is a CNF formula.
- A formula  $\varphi$  is a 3CNF:  
A CNF formula such that every clause has **exactly** 3 literals.
  - $(x_1 \vee x_2 \vee \neg x_4) \wedge (x_2 \vee \neg x_3 \vee x_1)$  is a 3CNF formula, but  $(x_1 \vee x_2 \vee \neg x_4) \wedge (x_2 \vee \neg x_3) \wedge x_5$  is not.

## Problem: SAT

**Instance:** A CNF formula  $\varphi$ .

**Question:** Is there a truth assignment to the variable of  $\varphi$  such that  $\varphi$  evaluates to true?

## Problem: 3SAT

**Instance:** A 3CNF formula  $\varphi$ .

**Question:** Is there a truth assignment to the variable of  $\varphi$  such that  $\varphi$  evaluates to true?

# Satisfiability

## SAT

Given a CNF formula  $\varphi$ , is there a truth assignment to variables such that  $\varphi$  evaluates to true?

## Example

- $(x_1 \vee x_2 \vee \neg x_4) \wedge (x_2 \vee \neg x_3) \wedge x_5$  is satisfiable; take  $x_1, x_2, \dots, x_5$  to be all true
- $(x_1 \vee \neg x_2) \wedge (\neg x_1 \vee x_2) \wedge (\neg x_1 \vee \neg x_2) \wedge (x_1 \vee x_2)$  is not satisfiable.

## 3SAT

Given a 3CNF formula  $\varphi$ , is there a truth assignment to variables such that  $\varphi$  evaluates to true?

# Importance of SAT and 3SAT

- SAT and 3SAT are basic constraint satisfaction problems.
- Many different problems can be reduced to them because of the simple yet powerful expressiveness of logical constraints.
- Arise naturally in many applications involving hardware and software verification and correctness.
- As we will see, it is a fundamental problem in theory of NP-Completeness.

$$SAT \leq_P 3SAT$$

How **SAT** is different from **3SAT**?

In **SAT** clauses might have arbitrary length: 1, 2, 3, ... variables:

$$(x \vee y \vee z \vee w \vee u) \wedge (\neg x \vee \neg y \vee \neg z \vee w \vee u) \wedge (\neg x)$$

In **3SAT** every clause must have exactly 3 different literals.

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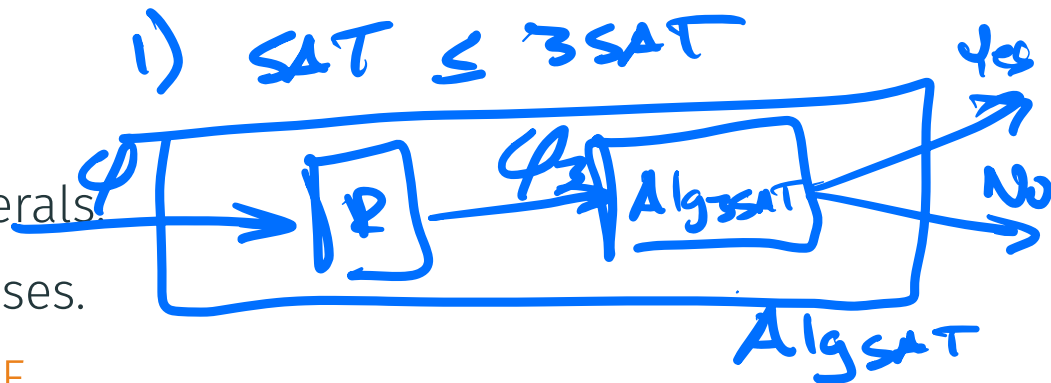
In **3SAT** every clause must have exactly 3 different literals.

$$3SAT \subseteq SAT$$

To reduce from an instance of **SAT** to an instance of **3SAT**, we must make all clauses to have exactly 3 variables...

Basic idea

- Pad short clauses so they have 3 literals.
- Break long clauses into shorter clauses.
- Repeat the above till we have a **3CNF**.



$$SAT \leq_P 3SAT$$

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$\langle 3 \text{ literals} \rangle$   
**SAT**  
 $(\neg x)$

$\langle 3 \text{ literals} \rangle$   
**3 SAT**  
 $(a \vee \neg x) \vee (\neg a \vee \neg x)$   
 repeat for  
 3 literals

$$SAT \leq_P 3SAT$$

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$\gg$  1. + literals  
**SAT**

$\gg$  3 literals  
**3 SAT**

$(x \vee y \vee z \vee w \vee u)$

$(x \vee y \vee z \vee a)$

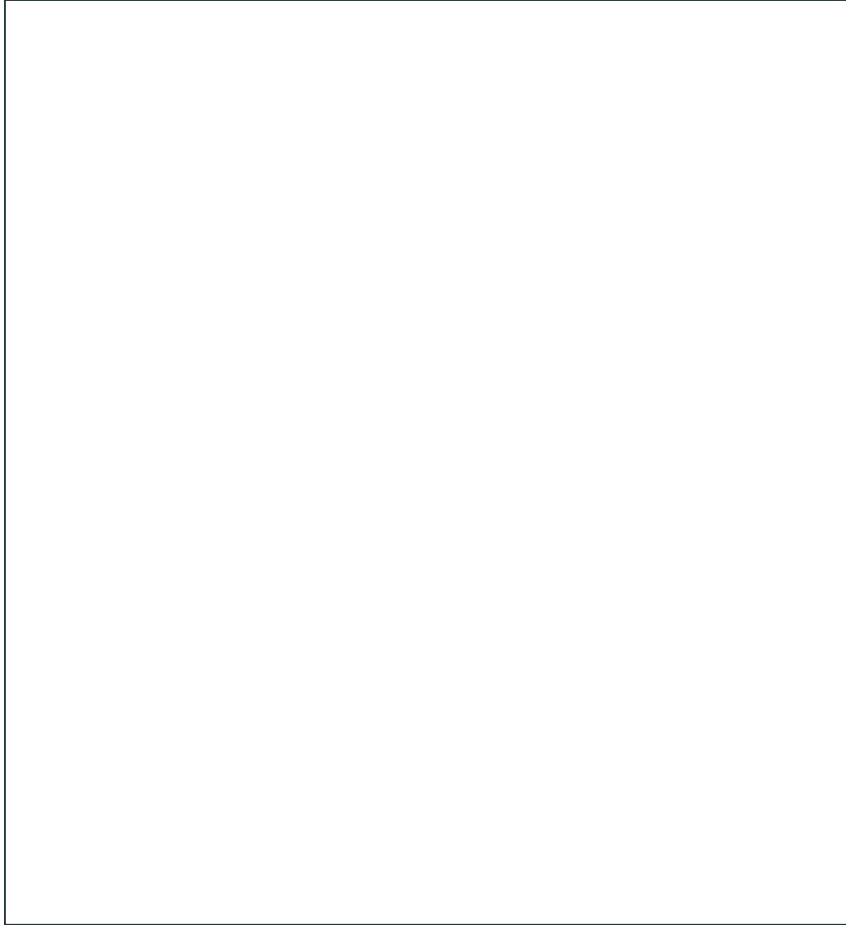
$\wedge (\neg a \vee w \vee u)$



# Overview of Complexity Classes

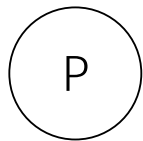
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# Algorithmic Complexity Space



This represents all problems that exist.

# Algorithmic Complexity Space



All problems solvable in a polynomial amount of time.

Most of the problems we discussed in the second part of the course.

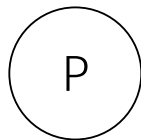
P problems:

- Longest whatever subsequence
- Various shortest path problems
- Graph connectivity

# Algorithmic Complexity Space

Undecidable (*uncomputable*)

Decidable (*computable*)



Set of all problems that can be computed by a **TM** (or not).

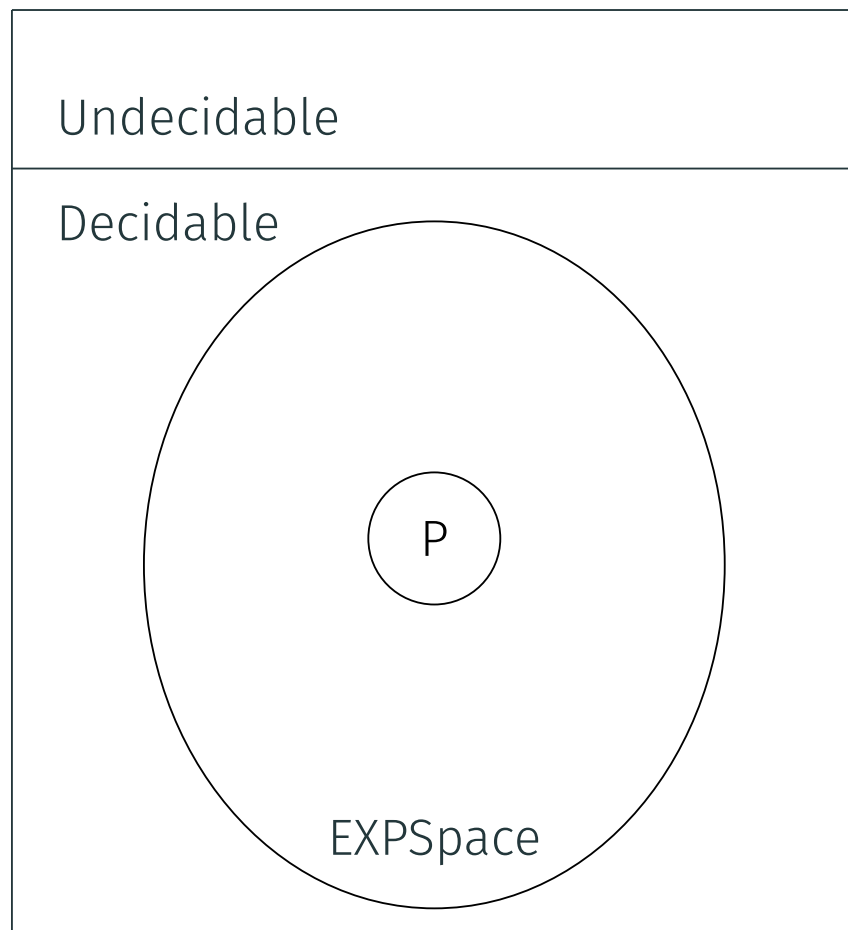
Decidable problems:

- Anything you can compute

Undecidable problems:

- Halting problem
- TM equivalence
- All non-trivial programs (Rice's theorem)

# Algorithmic Complexity Space



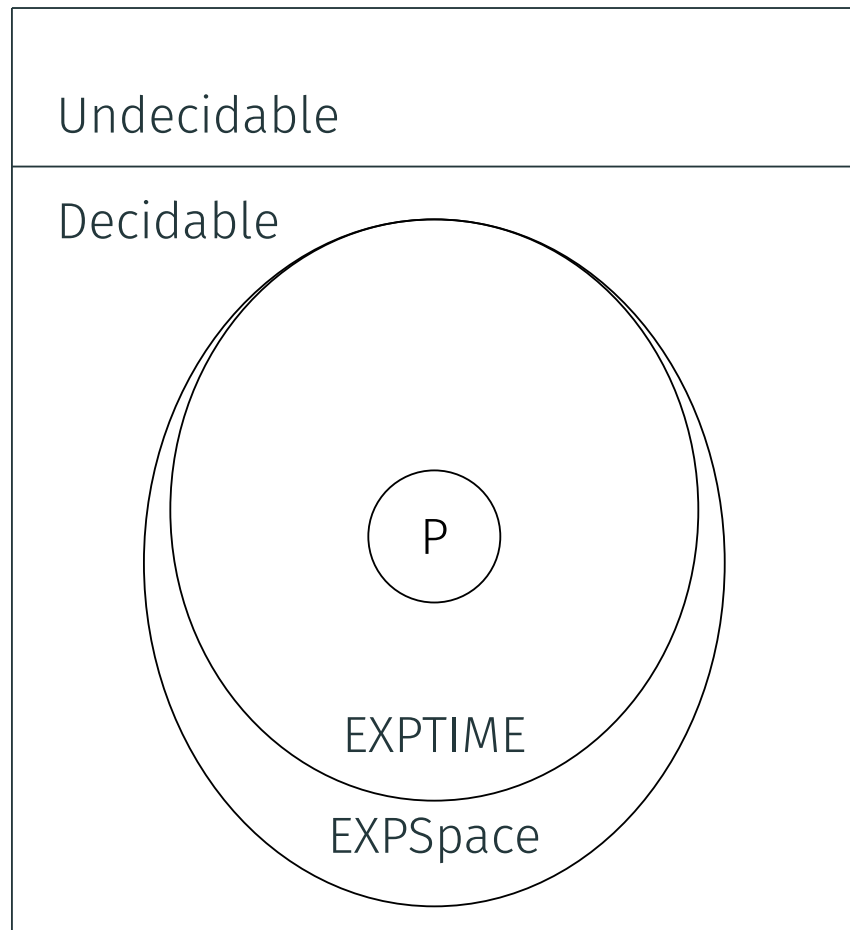
Set of all decision problem solvable by a **TM** in  $O^{p(n)}$  space.

EXPSPACE problems:

- Given regular expressions  $r_1$  and  $r_2$ , does  $L(r_1) \equiv L(r_2)$
- Convertibility and reachability for Petri Nets

Equivalent to NEXPSPACE (Savitch's theorem), and

# Algorithmic Complexity Space

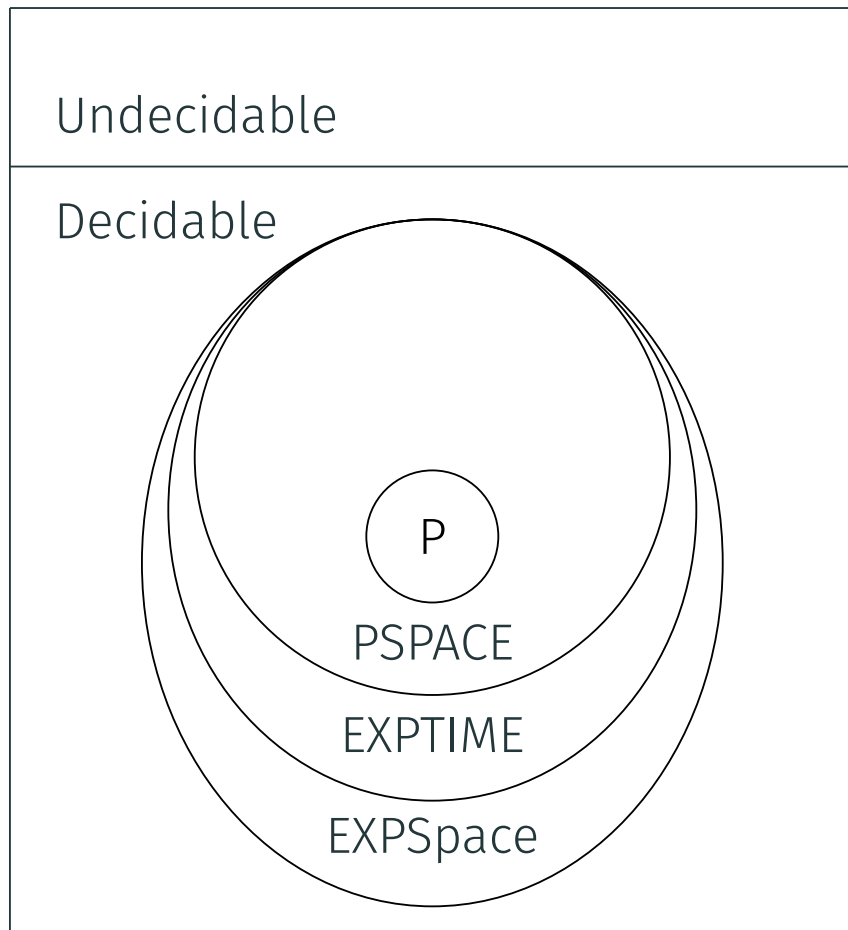


Set of all decision problem solvable by a **TM** in  $O^{p(n)}$  time.

EXPSPACE problems:

- Succinct circuits

# Algorithmic Complexity Space

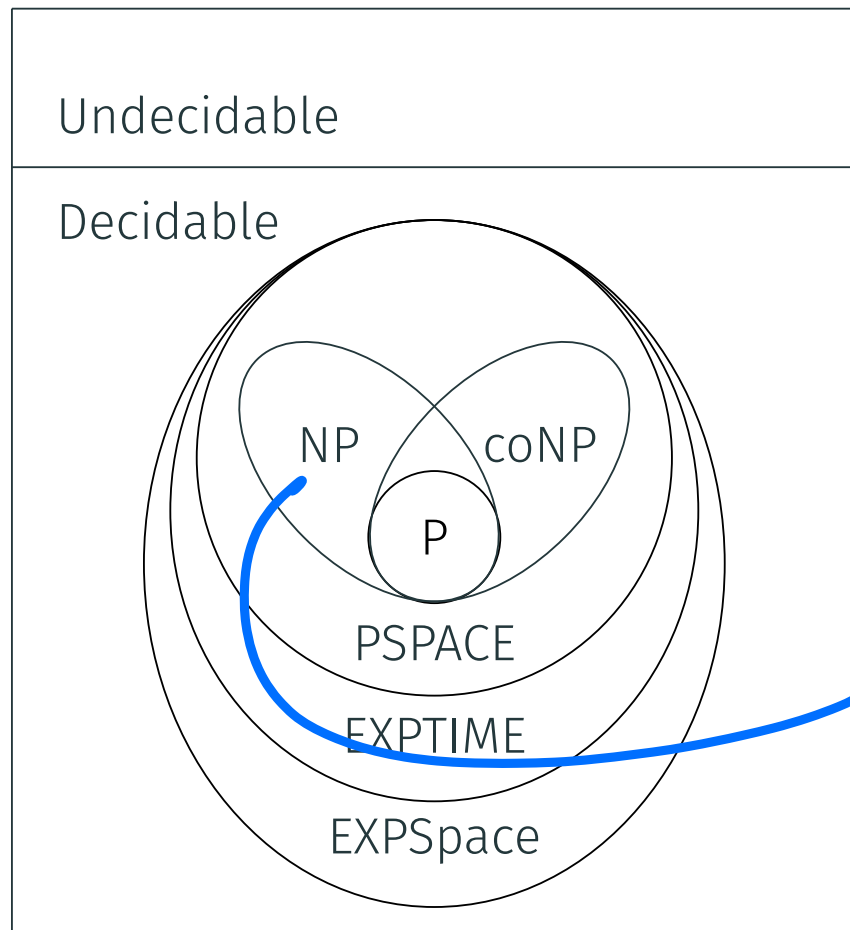


Set of all decision problem solvable by a **TM** using a polynomial amount of space.

PSPACE problems:

- Given a regular expression  $r_1$ , is  $L(r_1) = \Sigma^*$
- Quantified boolean problem
- Reconfiguration problems
- Various puzzle problems

# Algorithmic Complexity Space



Set of all decision problem solvable by a **NTM** in a polynomial amount of time.

Alternatively, NP contains the problems whose YES instances are checkable in a polynomial amount of time by a **TM** (**DTM**). coNP is same for NO instances.

NP problems:

- SAT, 3SAT, ...

- Integer factorization

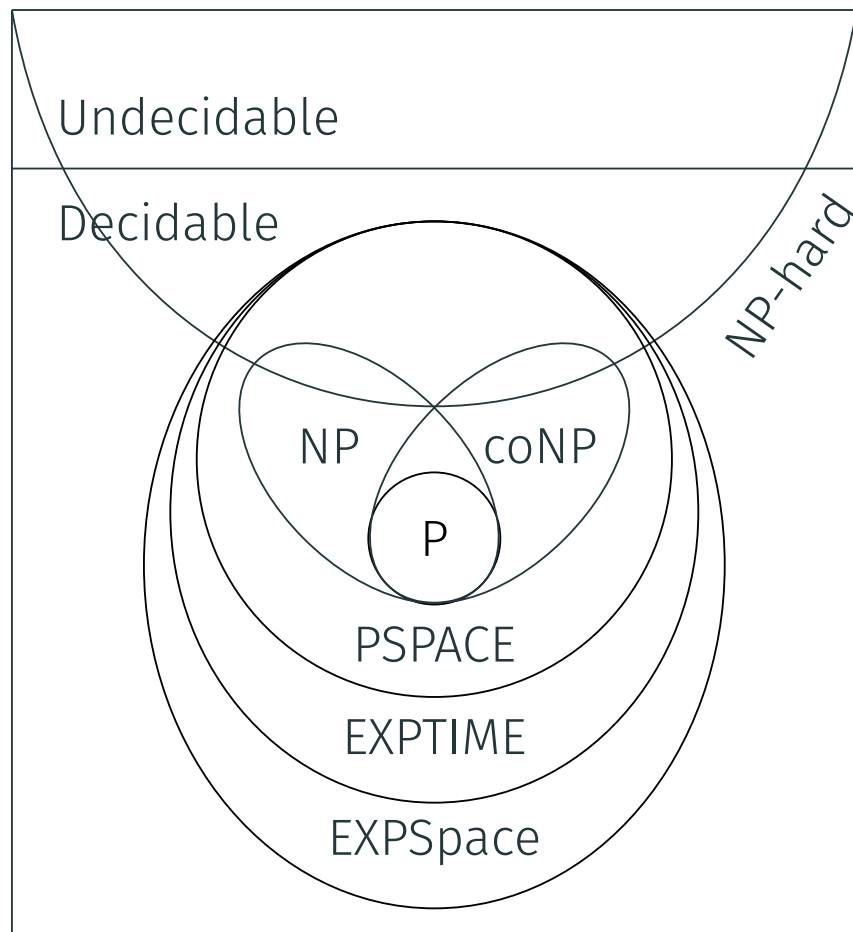
coNP problems:

- Tautology (opposite of SAT)
- Integer factorization

*Non-deterministic polynomial time*



# Algorithmic Complexity Space

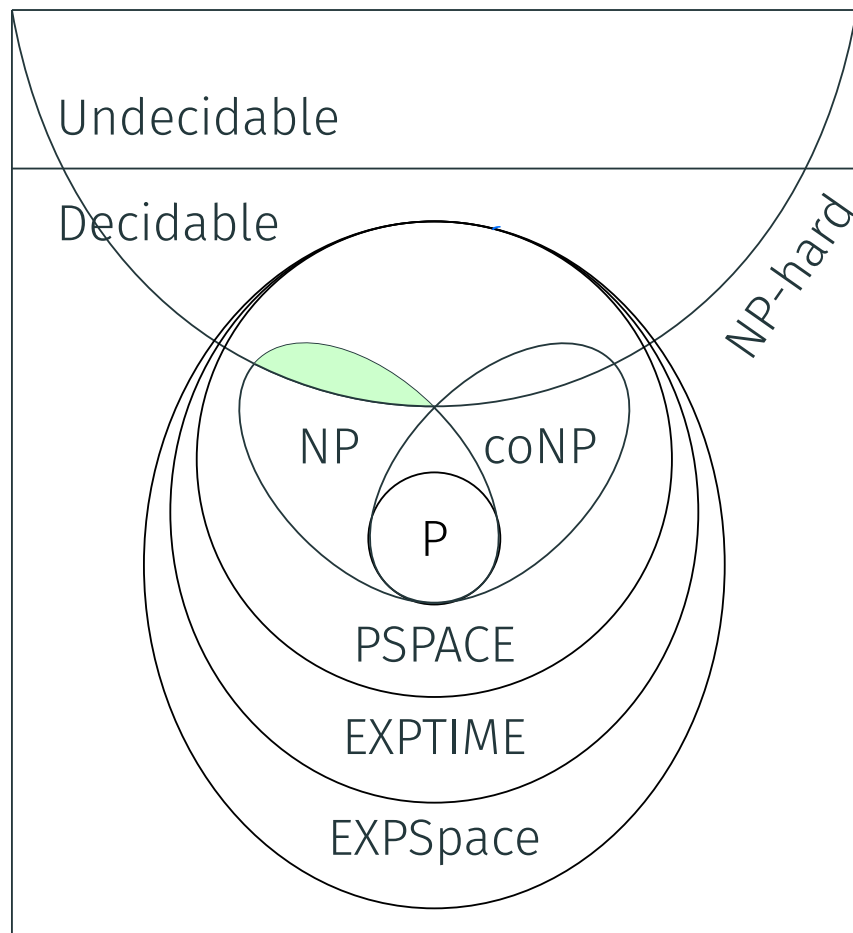


Class of problems that are at least as hard as the hardest problems in NP.

NP-hard problems:

- SAT, 3SAT, ...
- Clique, Independent set
- Hamiltonian path/cycle
- 3+ Coloring

# Algorithmic Complexity Space



The intersection of NP-hard and NP is called **NP-complete**. These are all the NP problems which all other NP problems can reduce to.

NP-complete problems:

- 3+ SAT, SAT
- Clique, Independent set
- 3+ Coloring

# Non-deterministic polynomial time - NP

---

# P and NP and Turing Machines

- P: set of decision problems that have polynomial time algorithms.
- NP: set of decision problems that have polynomial time non-deterministic algorithms.
- Many natural problems we would like to solve are in  $NP$ .
- Every problem in  $NP$  has an exponential time algorithm
- $P \subseteq NP$
- Some problems in  $NP$  are in  $P$  (example, shortest path problem)

**Big Question:** Does every problem in  $NP$  have an efficient algorithm? Same as asking whether  $P = NP$ .

efficient  
polynomial

# Problems with no known deterministic polynomial time algorithms

## Problems

- Independent Set
- Vertex Cover
- Set Cover
- SAT

There are of course undecidable problems (no algorithm at all!) but many problems that we want to solve are of similar flavor to the above.

**Question:** What is common to above problems?

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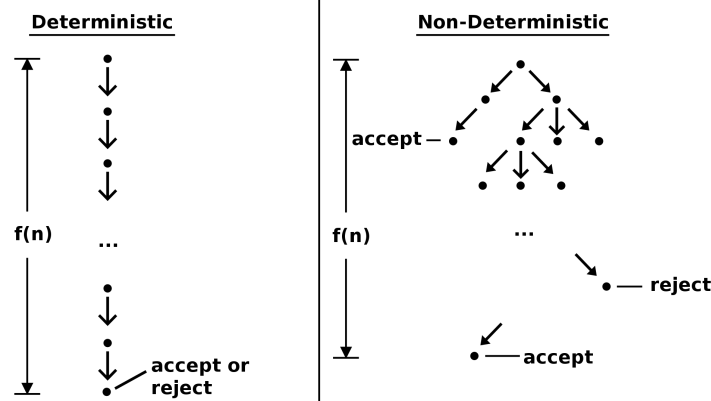
They can all be solved via a non-deterministic computer in polynomial time!

# Non-determinism in computing

Non-determinism is a special property of algorithms.

An algorithm that is capable of taking multiple states concurrently. Whenever it reaches a choice, it takes both paths.

If there is a path for the string to be accepted by the machine, then the string is part of the language.



# Problems with no known deterministic polynomial time algorithms

## Problems

- **Independent Set** & **Vertex Cover** - Can build algorithm to check all possible collection of vertices
- **Set Cover** - Can check all possible collection of sets
- **SAT** -Can build a non-deterministic algorithm that checks every possible boolean assignment.

But we don't have access to a non-deterministic computer. So how can a deterministic computer verify that a algorithm is in NP?



# Efficient Checkability

Above problems share the following feature:

## **Checkability**

For any YES instance  $I_X$  of  $X$  there is a proof/certificate/solution that is of length  $\text{poly}(|I_X|)$  such that given a proof one can efficiently check that  $I_X$  is indeed a YES instance.

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Examples:

- **SAT** formula  $\varphi$ : proof is a satisfying assignment.
- **Independent Set** in graph  $G$  and  $k$ : a subset  $S$  of vertices.
- **Homework**

## Definition

An algorithm  $C(\cdot, \cdot)$  is a certifier for problem  $X$  if the following two conditions hold:

- For every  $s \in X$  there is some string  $t$  such that  $C(s, t) = \text{"yes"}$
- If  $s \notin X$ ,  $C(s, t) = \text{"no"}$  for every  $t$ .

The string  $s$  is the problem instance. (Example: particular graph in independent set problem) The string  $t$  is called a **certificate** or **proof** for  $s$ .

*truth assignment*

# Efficient (polynomial time) Certifiers

## Definition (Efficient Certifier.)

A certifier  $C$  is an efficient certifier for problem  $X$  if there is a polynomial  $p(\cdot)$  such that the following conditions hold:

- For every  $s \in X$  there is some string  $t$  such that  $C(s, t) = \text{"yes"}$  **and**  $|t| \leq p(|s|)$ .
- If  $s \notin X$ ,  $C(s, t) = \text{"no"}$  for every  $t$ .
- $C(\cdot, \cdot)$  runs in polynomial time.

## Example: Independent Set

- **Problem:** Does  $G = (V, E)$  have an independent set of size  $\geq k$ ?
  - **Certificate:** Set  $S \subseteq V$ .
  - **Certifier:** Check  $|S| \geq k$  and no pair of vertices in  $S$  is connected by an edge.

↳ runs in poly time

∴ IS is in NP

## Example: SAT

- **Problem:** Does formula  $\varphi$  have a satisfying truth assignment?
  - **Certificate:** Assignment  $a$  of 0/1 values to each variable.
  - **Certifier:** Check each clause under  $a$  and say “yes” if all clauses are true.

↳ show that this runs in poly time

↳  $\therefore$  SAT is in NP

# Why is it called Nondeterministic Polynomial Time

A certifier is an algorithm  $C(I, c)$  with two inputs:

- $I$ : instance.
- $c$ : proof/certificate that the instance is indeed a YES instance of the given problem.

One can think about  $C$  as an algorithm for the original problem, if:

- Given  $I$ , the algorithm guesses (non-deterministically, and who knows how) a certificate  $c$ .
- The algorithm now verifies the certificate  $c$  for the instance  $I$ .

NP can be equivalently described using Turing machines.

# Polynomial-time reductions

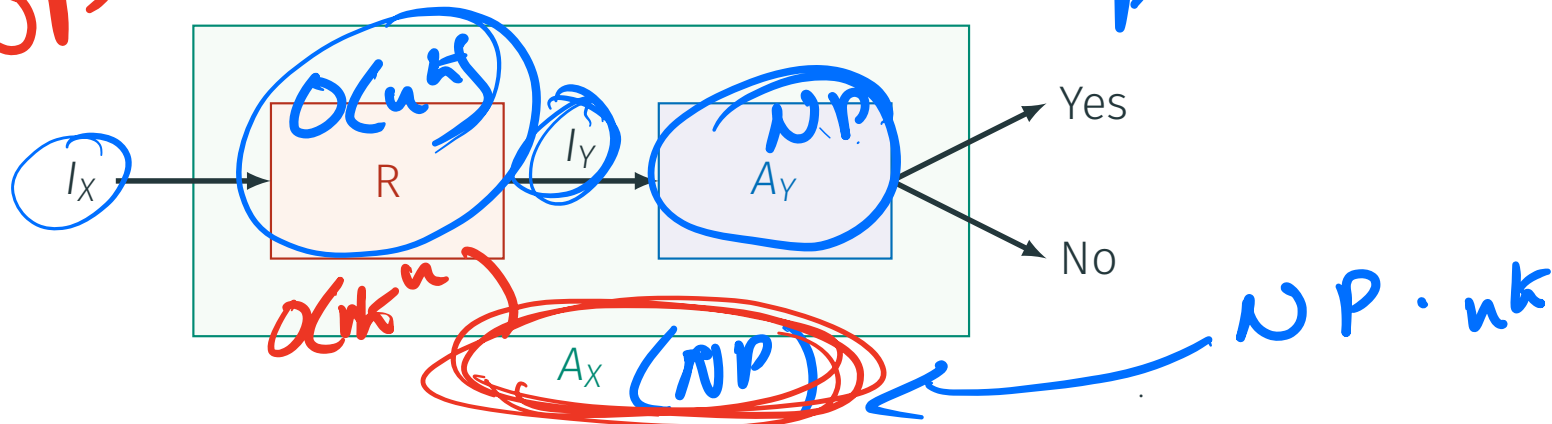
We say that an algorithm is efficient if it runs in polynomial-time.

To find efficient algorithms for problems, we are only interested in **polynomial-time** reductions. Reductions that take longer are not useful.

If we have a polynomial-time reduction from problem  $X$  to problem  $Y$  (we write  $X \leq_P Y$ ), and a poly-time algorithm  $A_Y$  for  $Y$ , we have a polynomial-time/efficient algorithm for  $X$ .

$X \leq_{\text{Exp}} \text{NP}$

$X \leq_P \text{NP}$





# Polynomial-time Reduction

A polynomial time reduction from a decision problem  $X$  to a decision problem  $Y$  is an algorithm  $\mathcal{A}$  that has the following properties:

- given an instance  $I_X$  of  $X$ ,  $\mathcal{A}$  produces an instance  $I_Y$  of  $Y$
- $\mathcal{A}$  runs in time polynomial in  $|I_X|$ .
- Answer to  $I_X$  YES  $\iff$  answer to  $I_Y$  is YES.

## Lemma

*If  $X \leq_P Y$  then a polynomial time algorithm for  $Y$  implies a polynomial time algorithm for  $X$ .*

Such a reduction is called a Karp reduction. Most reductions we will need are Karp reductions. Karp reductions are the same as mapping reductions when specialized to polynomial time for the reduction step.

## Review question: Reductions again...

Let  $X$  and  $Y$  be two decision problems, such that  $X$  can be solved in polynomial time, and  $X \leq_P Y$ . Then

(A)  $Y$  can be solved in polynomial time.

(B)  $Y$  can NOT be solved in polynomial time.

(C) If  $Y$  is hard then  $X$  is also hard.

(D) None of the above.

(E) All of the above.

*Maybe maybe not*



# Cook-Levin Theorem

---

# “Hardest” Problems

## Question

What is the hardest problem in NP? How do we define it?

## Towards a definition

- Hardest problem must be in NP.
- Hardest problem must be at least as “difficult” as every other problem in NP.

$$X \leq_p Y$$

where  $X$  is in NP  
 $Y$  is specific problem  
 $X$  all problems in NP

# NP-Complete Problems

## Definition

A problem  $X$  is said to be **NP-Complete** if

- $X \in NP$ , and
- (Hardness) For any  $Y \in NP$ ,  $Y \leq_P X$ .

if it NP-hard  
it is in NP

# Solving NP-Complete Problems

## Lemma

*Suppose  $X$  is NP-Complete. Then  $X$  can be solved in polynomial time if and only if  $P = NP$ .*

## Proof.

$\Rightarrow$  Suppose  $X$  can be solved in polynomial time

- Let  $Y \in NP$ . We know  $Y \leq_P X$ .
- We showed that if  $Y \leq_P X$  and  $X$  can be solved in polynomial time, then  $Y$  can be solved in polynomial time.
- Thus, every problem  $Y \in NP$  is such that  $Y \in P$ ;  $NP \subseteq P$ .
- Since  $P \subseteq NP$ , we have  $P = NP$ .

$\Leftarrow$  Since  $P = NP$ , and  $X \in NP$ , we have a polynomial time algorithm for  $X$ .  $\square$

# NP-Hard Problems

## Definition

A problem  $Y$  is said to be **NP-Hard** if

- (**Hardness**) For any  $X \in NP$ , we have that  $X \leq_P Y$ .

An NP-Hard problem need not be in NP!

**Example:** Halting problem is NP-Hard (why?) but not NP-Complete.

# Consequences of proving NP-Completeness

If  $X$  is NP-Complete

- Since we believe  $P \neq NP$ ,
- and solving  $X$  implies  $P = NP$ .

$X$  is **unlikely** to be efficiently solvable.

At the very least, many smart people before you have failed to find an efficient algorithm for  $X$ .



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(This is proof by mob opinion — take with a grain of salt.)

# NP-Complete Problems

## Question

Are there any problems that are NP-Complete?

## Answer

Yes! Many, many problems are NP-Complete.

# Cook-Levin Theorem

Theorem (Cook-Levin)  
*SAT* is NP-Complete.

$$NP \leq_p SAT$$

# Cook-Levin Theorem

Theorem (Cook-Levin)  
*SAT* is NP-Complete.

$$X \leq_p \text{SAT}$$

Need to show

- *SAT* is in NP.
- every NP problem  $X$  reduces to *SAT*.

Steve Cook won the Turing award for his theorem.

# Proving that a problem $X$ is NP-Complete

To prove  $X$  is NP-Complete, show

- Show that  $X$  is in NP.
- Give a polynomial-time reduction from a known NP-Complete problem such as SAT to  $X$

$$\text{SAT} \leq X$$

# Proving that a problem $X$ is NP-Complete

To prove  $X$  is NP-Complete, show

- Show that  $X$  is in NP.
- Give a polynomial-time reduction from a known NP-Complete problem such as **SAT** to  $X$

**SAT**  $\leq_P X$  implies that every NP-complete problem  $Y \leq_P X$ . Why?

## 3-SAT is NP-Complete

- 3-SAT is in  $NP$
- $SAT \leq_P 3-SAT$  as we saw

# NP-Completeness via Reductions

- SAT is NP-Complete due to Cook-Levin theorem
- $\text{SAT} \leq_P \text{3-SAT}$
- $\text{3-SAT} \leq_P \text{Independent Set}$
- $\text{Independent Set} \leq_P \text{Vertex Cover}$
- $\text{Independent Set} \leq_P \text{Clique}$
- $\text{3-SAT} \leq_P \text{3-Color}$
- $\text{3-SAT} \leq_P \text{Hamiltonian Cycle}$



# NP-Completeness via Reductions

- SAT is NP-Complete due to Cook-Levin theorem
- $SAT \leq_P 3\text{-SAT}$
- $3\text{-SAT} \leq_P \text{Independent Set}$
- $\text{Independent Set} \leq_P \text{Vertex Cover}$
- $\text{Independent Set} \leq_P \text{Clique}$
- $3\text{-SAT} \leq_P 3\text{-Color}$
- $3\text{-SAT} \leq_P \text{Hamiltonian Cycle}$

Hundreds and thousands of different problems from many areas of science and engineering have been shown to be NP-Complete.

A surprisingly frequent phenomenon!

## Reducing 3-SAT to Independent Set

---

# Independent Set

Problem: **Independent Set**

**Instance:** A graph  $G$ , integer  $k$ .

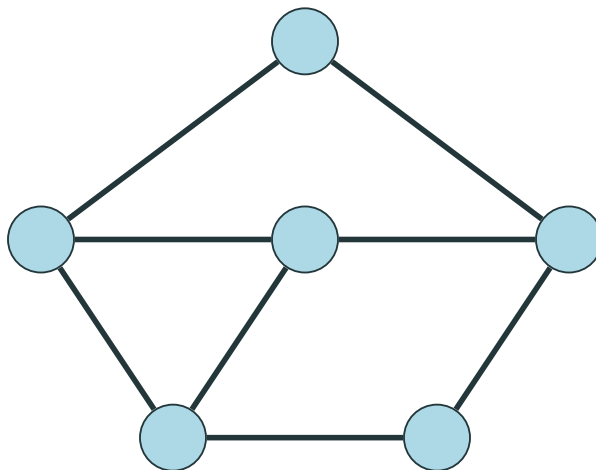
**Question:** Is there an independent set in  $G$  of size  $k$ ?

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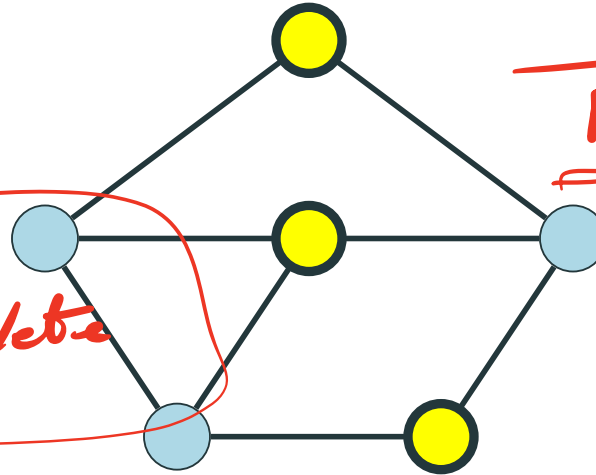
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$\exists \text{ SAT} \in \text{NP-complete}$   
 $\exists \text{ SAT} \in \text{NP}$   
 $\exists \text{ SAT} \in \text{NP-hard}$



$\text{NP-complete} \leq_p \text{IS}$

NP-hard

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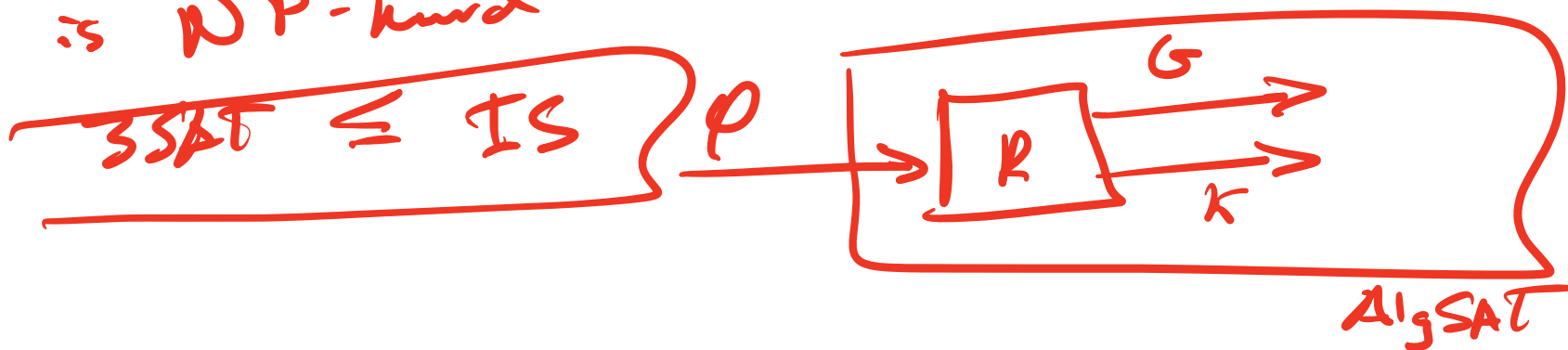
# Interpreting 3SAT

There are two ways to think about 3SAT

- Find a way to assign 0/1 (false/true) to the variables such that the formula evaluates to true, that is each clause evaluates to true.
- Pick a literal from each clause and find a truth assignment to make all of them true. You will fail if two of the literals you pick are in **conflict**, i.e., you pick  $x_i$  and  $\neg x_i$

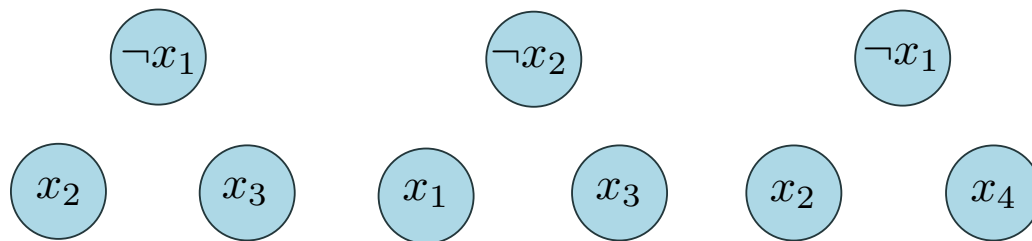
We will take the second view of 3SAT to construct the reduction.

IS is NP-hard



# The Reduction

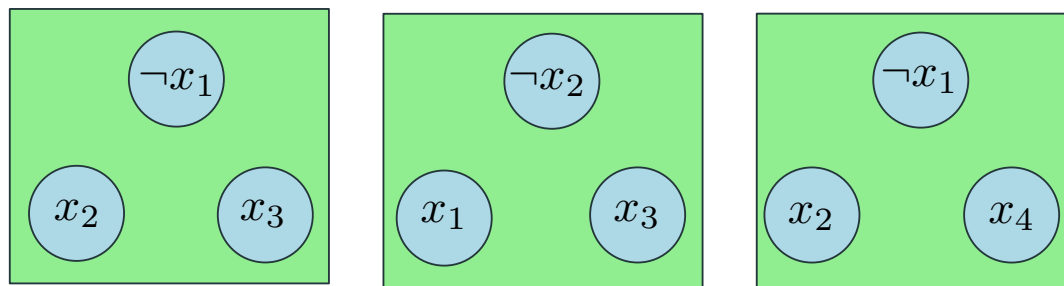
- $G_\varphi$  will have one vertex for each literal in a clause
- 2- Connect the 3 literals in a clause to form a triangle; the independent set will pick at most one vertex from each clause, which will correspond to the literal to be set to true
- 4- Connect 2 vertices if they label complementary literals; this ensures that the literals corresponding to the independent set do not have a conflict
- 5- Take  $k$  to be the number of clauses



**Figure 1:** Graph for  $\varphi = (\neg x_1 \vee x_2 \vee x_3) \wedge (x_1 \vee \neg x_2 \vee x_3) \wedge (\neg x_1 \vee x_2 \vee x_4)$

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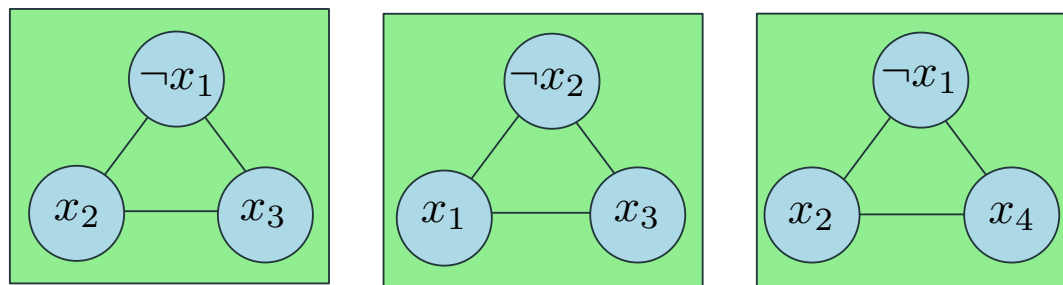


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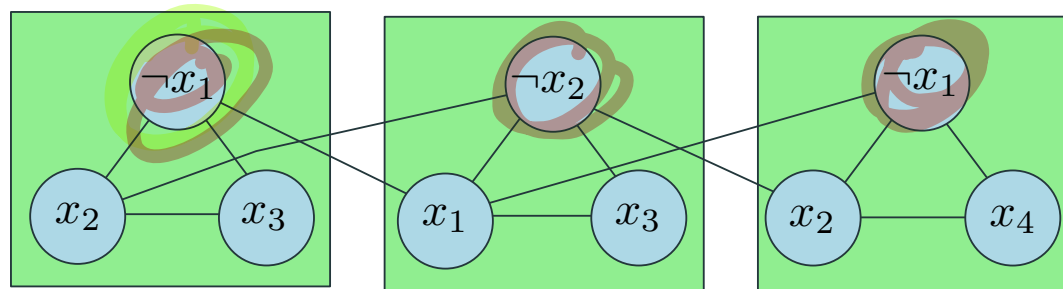


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*$k = \# \text{ clauses}$*

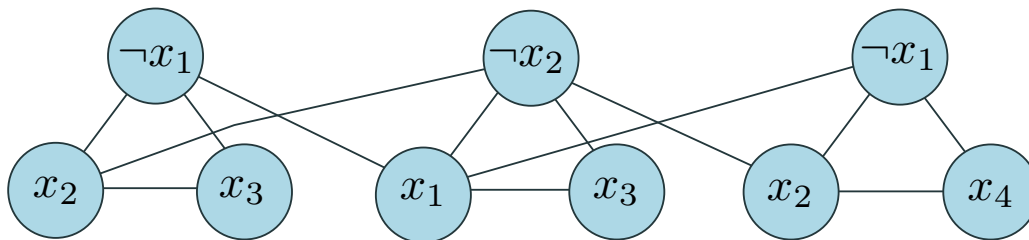


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*NP-hard*



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## Lemma

$\varphi$  is satisfiable iff  $G_\varphi$  has an independent set of size  $k$  ( $=$  number of clauses in  $\varphi$ ).

## Proof.

$\Rightarrow$  Let  $a$  be the truth assignment satisfying  $\varphi$

- 2- Pick one of the vertices, corresponding to true literals under  $a$ , from each triangle. This is an independent set of the appropriate size. Why?

□

### Lemma

$\varphi$  is satisfiable iff  $G_\varphi$  has an independent set of size  $k$  (= number of clauses in  $\varphi$ ).

### Proof.

$\Leftarrow$  Let  $S$  be an independent set of size  $k$

- $S$  must contain exactly one vertex from each clause triangle
- $S$  cannot contain vertices labeled by conflicting literals
- Thus, it is possible to obtain a truth assignment that makes in the literals in  $S$  true; such an assignment satisfies one literal in every clause □

## Other NP-Complete problems

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# Graph Coloring

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## Problem: Graph Coloring

**Instance:**  $G = (V, E)$ : Undirected graph, integer  $k$ .

**Question:** Can the vertices of the graph be colored using  $k$  colors so that vertices connected by an edge do not get the same color?

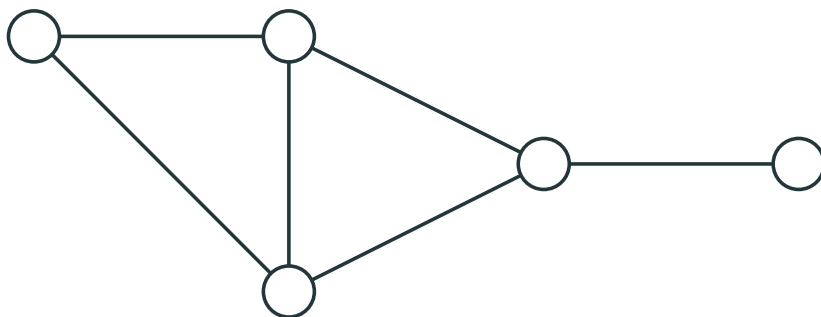


# Graph 3-Coloring

## Problem: 3 Coloring

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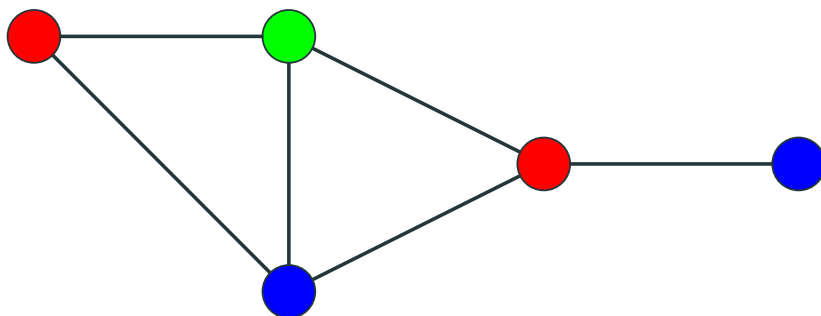


# Graph 3-Coloring

## Problem: 3 Coloring

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# Graph Coloring

**Observation:** If  $G$  is colored with  $k$  colors then each color class (nodes of same color) form an independent set in  $G$ . Thus,  $G$  can be partitioned into  $k$  independent sets iff  $G$  is  $k$ -colorable.

Graph 2-Coloring can be decided in polynomial time.

$G$  is 2-colorable iff  $G$  is bipartite! There is a linear time algorithm to check if  $G$  is bipartite using Breadth-first-Search

# Hamiltonian Cycle

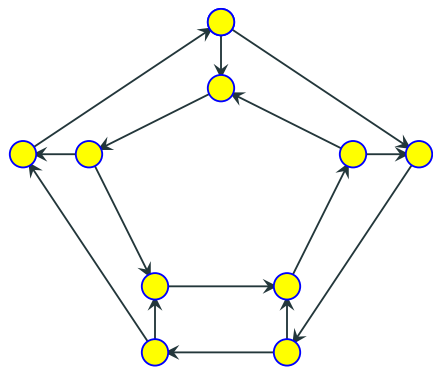
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# Directed Hamiltonian Cycle

**Input** Given a directed graph  $G = (V, E)$  with  $n$  vertices

**Goal** Does  $G$  have a **Hamiltonian cycle**?

- 2- A Hamiltonian cycle is a cycle in the graph that visits every vertex in  $G$  exactly once



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