



# Deep Learning - MAI

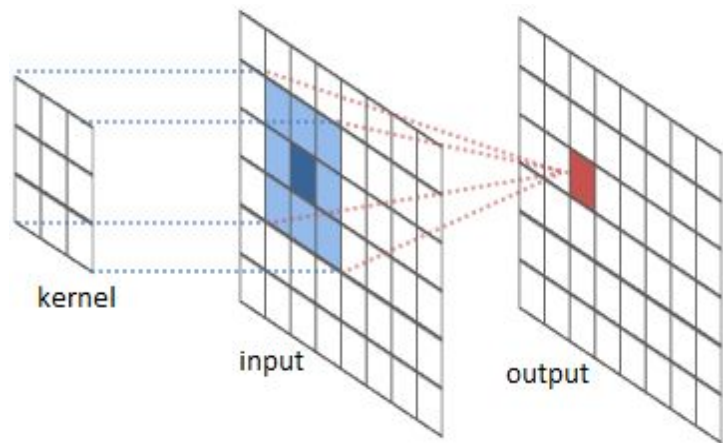
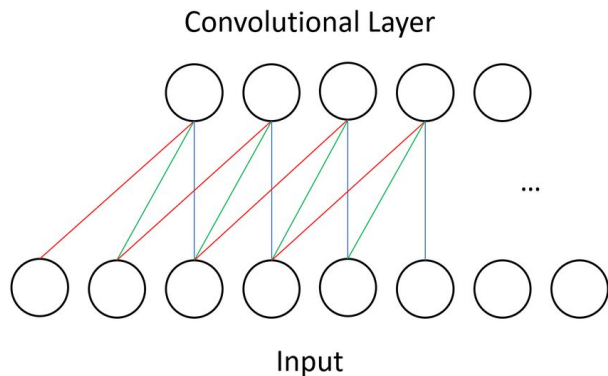
Convolutional neural networks

THEORY

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# Spatial Connectivity

- ❖ Some data has spatial correlations that can be exploited
  - 1D, 2D, 3D, ...
- ❖ Near-by data points are more relevant than far-away.
- ❖ Sparsify connectivity to reduce complexity and ease the learning



# Weight Sharing

- ❖ Sparse connectivity is nice, but we want to apply filters everywhere.
- ❖ Each filter will get convolved all over the image: 2D activations matrix
- ❖ In static we have sets of neurons sharing weights
- ❖ In this context, what is a neuron?



# Convolution in Action

Kernel size 3x3  
(neuron input = 9)

1 0 1  
0 1 0  
1 0 1

Detect 'X'

1 <sub>x1</sub>	1 <sub>x0</sub>	1 <sub>x1</sub>	0	0
0 <sub>x0</sub>	1 <sub>x1</sub>	1 <sub>x0</sub>	1	0
0 <sub>x1</sub>	0 <sub>x0</sub>	1 <sub>x1</sub>	1	1
0	0	1	1	0
0	1	1	0	0

Image

Filter convolution  
process

4		

Convolved  
Feature

Activations (pre-func.)

# Image Transformations

- ❖ Convolving filters transform the image
- ❖ Let the model learn the kernels it needs

**Edge detection**

$$\begin{bmatrix} -1 & -1 & -1 \\ -1 & 8 & -1 \\ -1 & -1 & -1 \end{bmatrix}$$



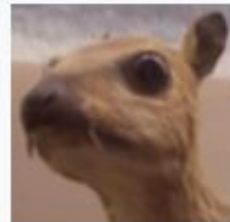
**Sharpen**

$$\begin{bmatrix} 0 & -1 & 0 \\ -1 & 5 & -1 \\ 0 & -1 & 0 \end{bmatrix}$$



**Gaussian blur**  
 $3 \times 3$

$$\frac{1}{16} \begin{bmatrix} 1 & 2 & 1 \\ 2 & 4 & 2 \\ 1 & 2 & 1 \end{bmatrix}$$



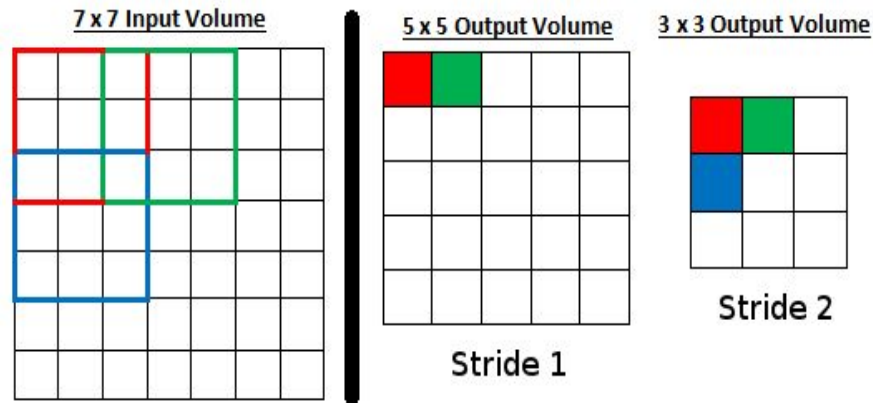
# Convolution Details

**Kernel size:** Size of the receptive field of convolutional neurons

**Stride:** Steps size of convolution

**Padding:** Allows focus on border

- ❖ Most common fill: Zeros
- ❖ Valid (no padding): Internal only. May skip data. Reduces dimensionality
- ❖ Same: Keep dimensionality with stride 1

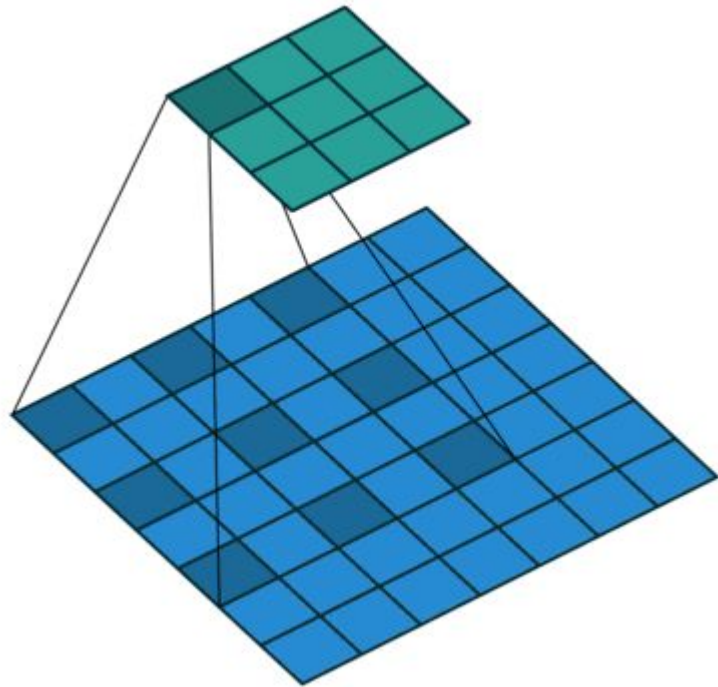


$$OutputSize = \frac{InputSize - KernelSize + 2 * Padding}{Stride} + 1$$

# Dilated/Atrous Convolutions

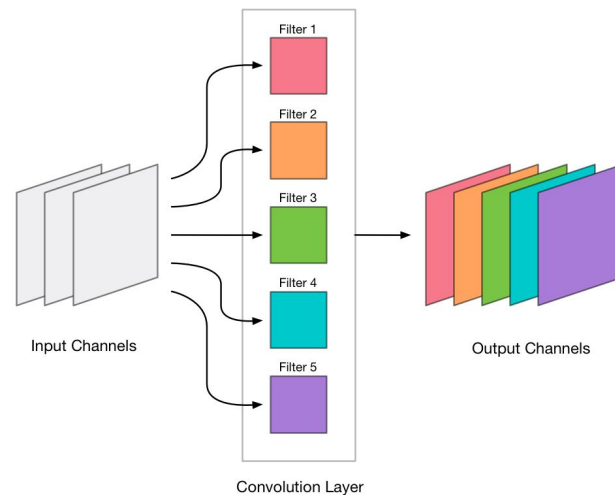
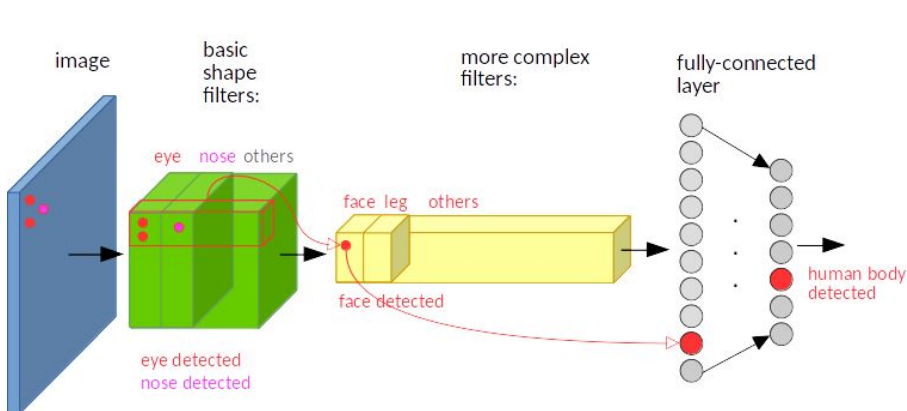
Sparsify the kernel

- ❖ Increases perceptive field without added complexity
- ❖ Loses details, gains context
- ❖ Another hyperparam :(
- ❖ Used for
  - Down/Upsampling (segmentation)
  - High Resolution inputs



# Output Volumes

- ❖ Typically, conv filters are full depth ( $N*N*input\_depth$ )
- ❖ Each conv filter (often 3D) convolved generates a 2D plane of data
- ❖ Depth provides all the *views* on a part of the input
- ❖ Output volume: New representation of input with different dimensions



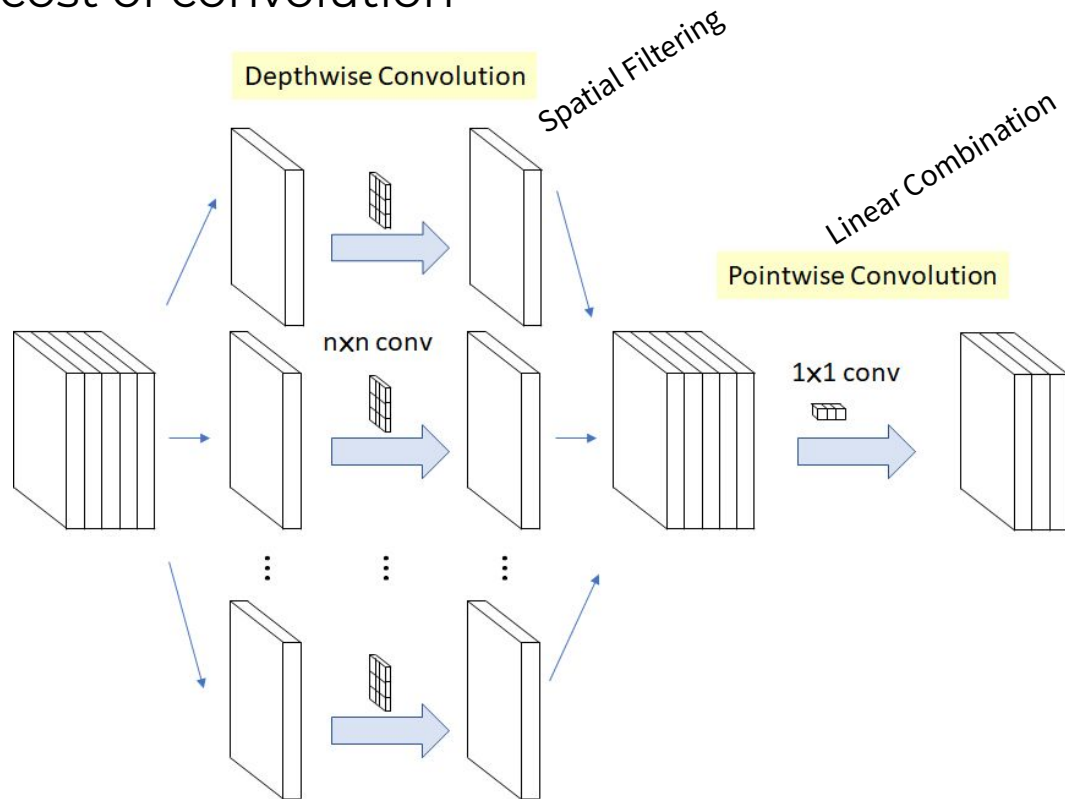


# Depth-wise Separable Convolutions

Decreasing the complexity and cost of convolution

1. Depth-wise convolutions
  - Filters:  $N \times N \times 1$
2. Point-wise convolution
  - Filters:  $1 \times 1 \times \text{input\_depth}$

Params:  $N \times N + N$

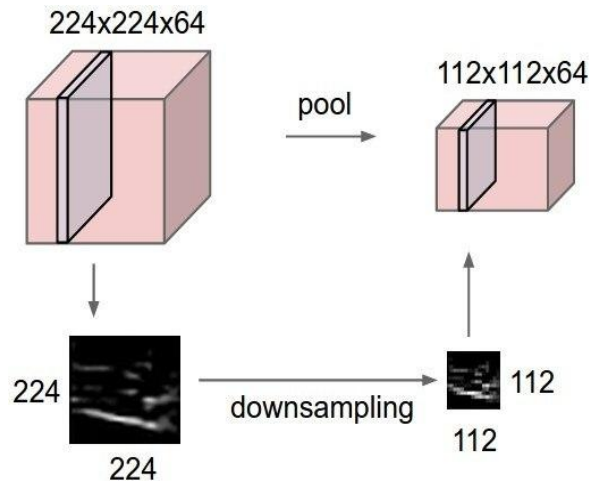
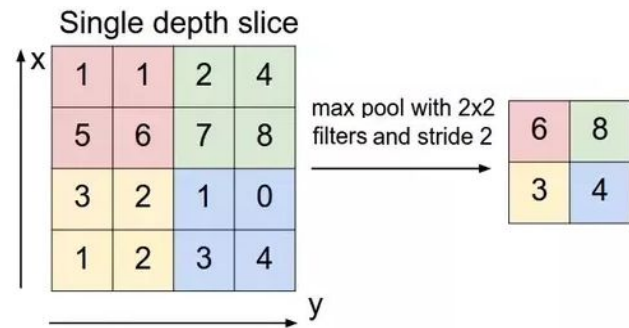


# To Pool Or Not To Pool

- ❖ Operation: **Max** or Avg
- ❖ Dimensionality reduction (along x and y only)
- ❖ Rarely applied full depth
- ❖ Parameter free layer
- ❖ Hyperparams: Size & Stride
- ❖ Loss in spatial precision / Robust to invariance

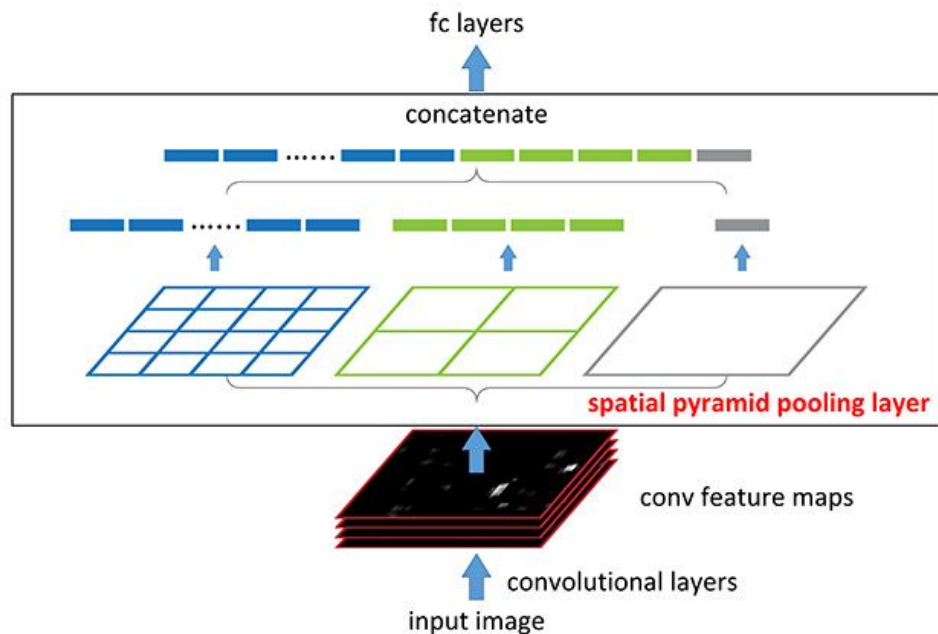
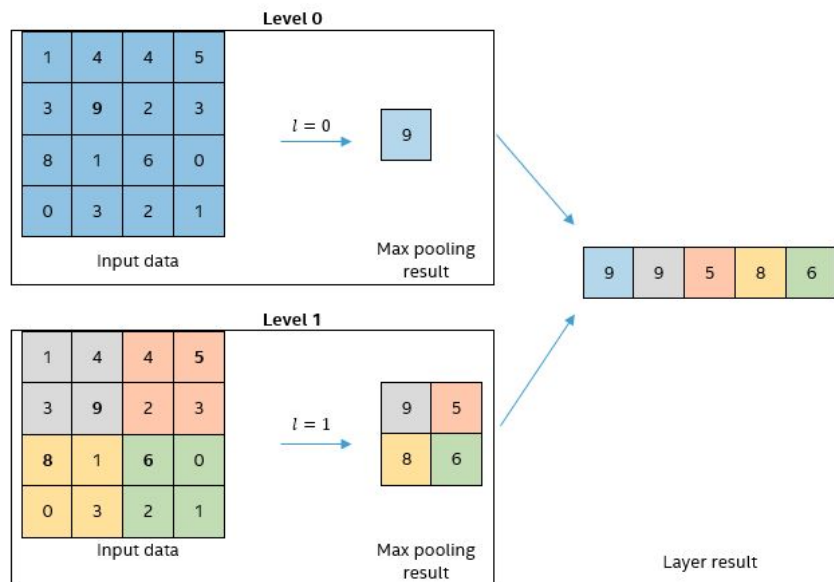
Other means to reduce complexity

- ❖ Depth-wise separable convs, bigger conv. strides



# Spatial Pyramid Pooling (SPP)

- ❖ Multi-scale Pool (by powers of 2)
- ❖ Often used between conv and fc



More alternatives: Atrous spatial PP, Global average pooling, Pyramid pooling module, Adaptive PP

# Practical Tips XI

## Convolutional

- Small/big filters (**3x3**, 5x5, 7x7)
  - Cheap/Expensive
  - Local/General
  - Bigger/Smaller outputs (stride)
- Kernel Size = input size: fc
- Kernel size = 1x1: Alter depth)

## Pooling

- 2x2, stride 1 is the least invasive

## Hyperparameters incomplete list #4

- ☐ Kernel size (conv & pool)
- ☐ Stride (conv & pool)
- ☐ Padding (conv & pool)
- ☐ Num. filters
- ☐ Dilatation rate

# The Challenge

## ImageNet Large-Scale Visual Recognition Challenge 2012 (ILSVRC'12)

- ❖ Image Classification: 1,000 classes
- ❖ Training: 1.2M
- ❖ Living things + Human-made objects
  - 120 breeds of dogs
- ❖ DANGER! When using a new test set (2019) performance drops +10%



# Data Augmentation for CNNs

Apply what is safe for each case

- ❖ Problem specific
- ❖ Limited impact
- ❖ Computation
- ❖ Train/Val/Test

Geometry based



Color based



Noise / occlusion



Weather



# Advanced image regularization/augmentation

Increase training variance, attention to all input regions, noisy!

- ❖ MixUp (merge two samples), AdaMixup (manifold intrusion)
- ❖ CutOut (remove a patch)
- ❖ CutMix (merge samples w/ patch)
- ❖ Auto/DeepAugment (learn  $\langle op., mag. \rangle$  from the data. Danger!)



More data is always better than more augmentation!

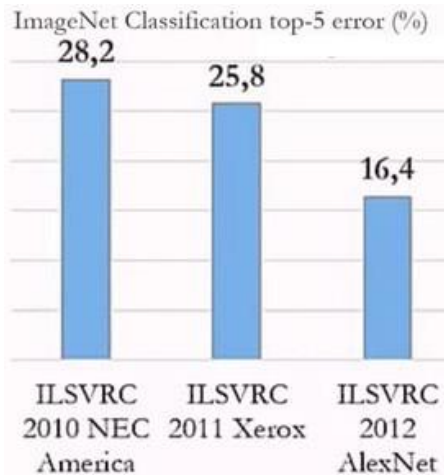
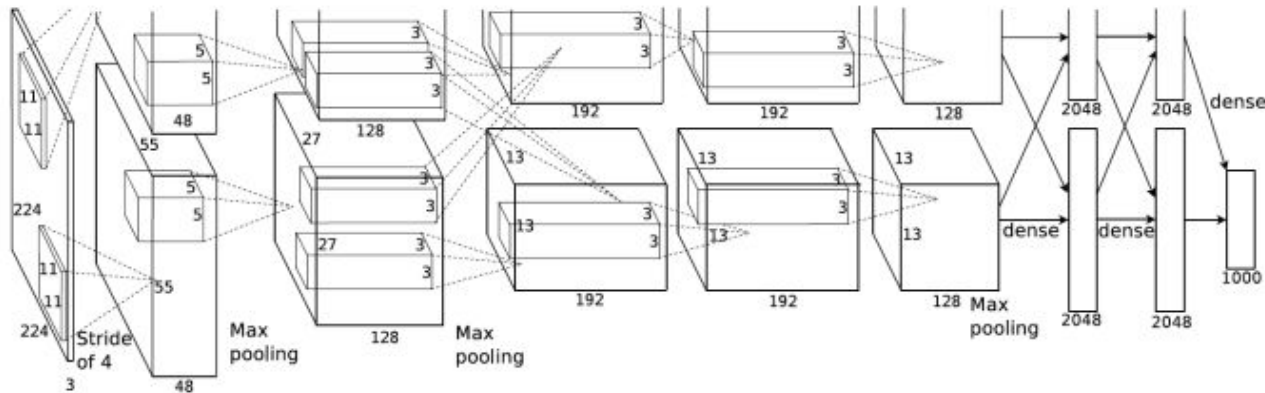




# CNNs Big Bang

## AlexNet (2012)

- ❖ Breakthrough in ILSVRC
- ❖ 5 convs+pools, ReLU, 2 dense, and dropout
- ❖ 62M parameters



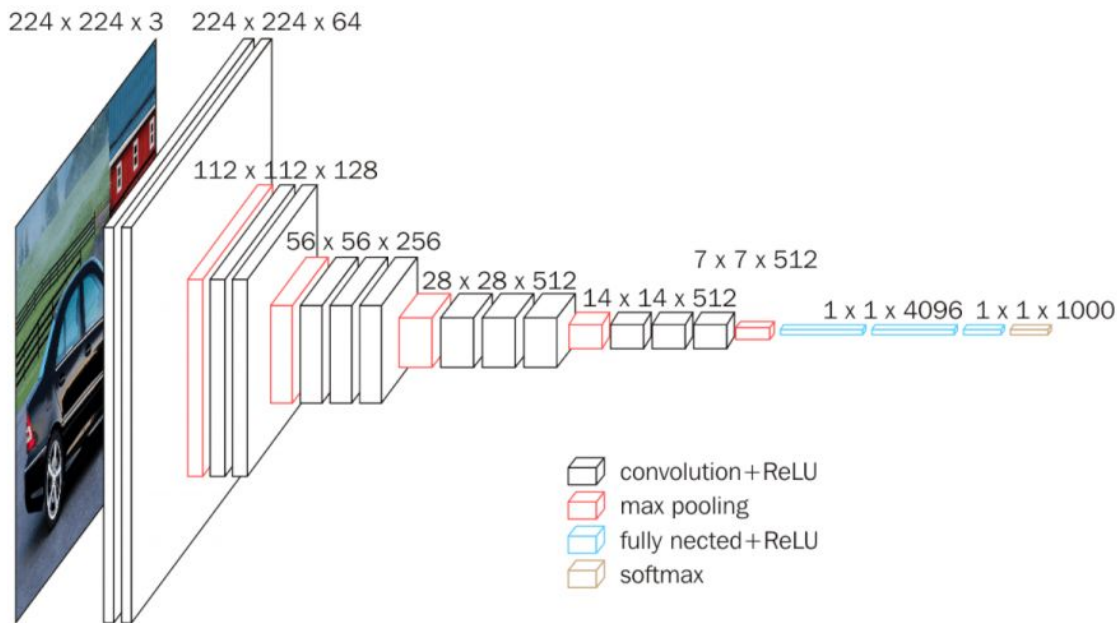
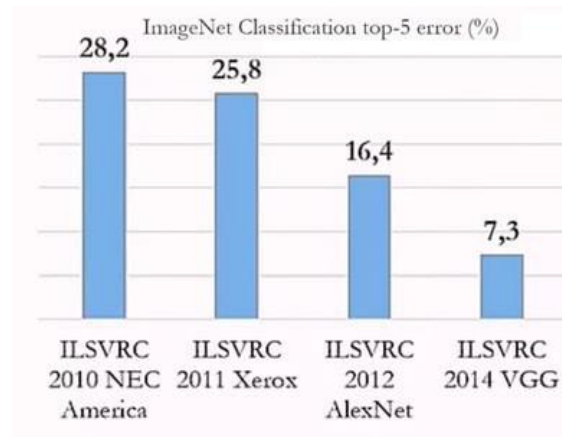
On the shoulders of giants



# A new Standard for CNNs

VGG 11/13/16/19 (2014)

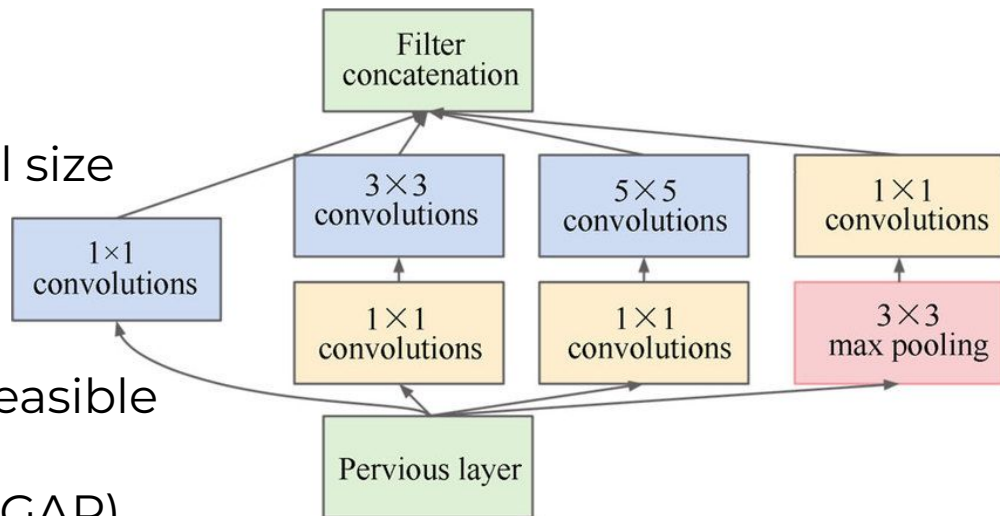
- ❖ Prototype of (conv-pool)\*+dense\* architecture
- ❖ 133-144M parameters
- ❖ 3x3 convs only



# The Inception Family

GoogLeNet (2014)

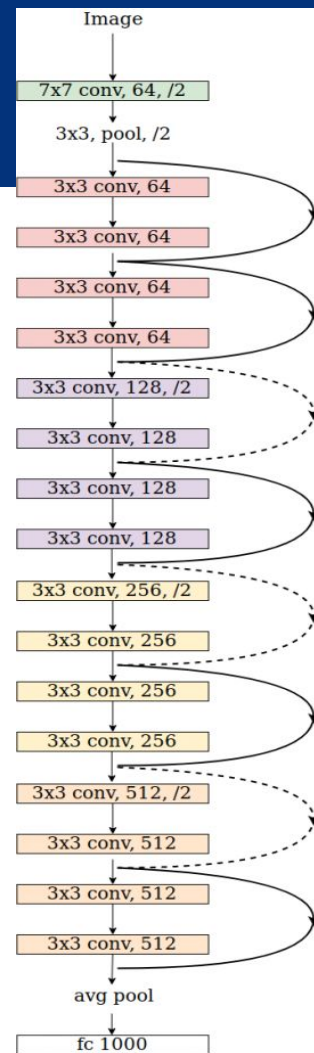
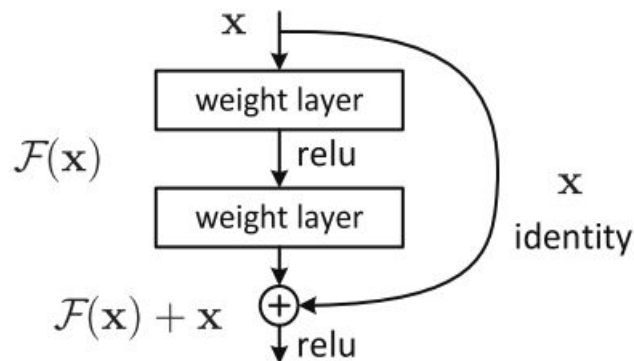
- ❖ The Inception block
- ❖ Let the model decide the kernel size
- ❖ Better scale adaptation
- ❖ Bottleneck 1x1 conv to make it feasible
- ❖ No FC: Global Average Pooling (GAP)



# The Skipped Connection

## ResNet (2015)

- ❖ Residual blocks / Skip connections
- ❖ Deeper should never be worse
  - Learning the identity is hard
  - Learning to cancel out is easy
- ❖ Shallow ensemble of nets
- ❖ Train up to 1K layers (do not!)
- ❖ ILSVRC'12 human level

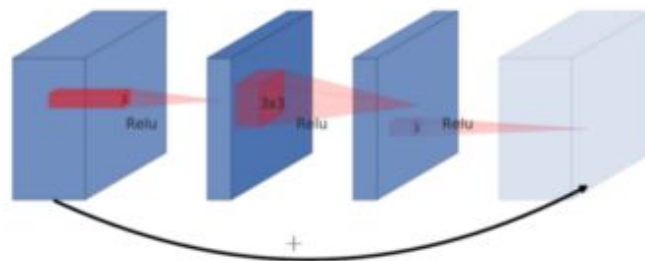


# Inverted Residuals and Linear Bottlenecks

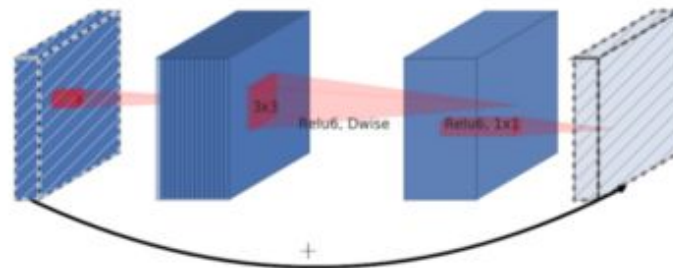
1. Upsample depth
2. Depth-wise conv
3. Point-wise conv

- ❖ Linear act at end
- ❖ Non-linear mid
- ❖ Residual link
- ❖ Efficient

(a) Residual block



(b) Inverted residual block



*Sponsored by:*  
The manifold hypothesis

# EfficientNet

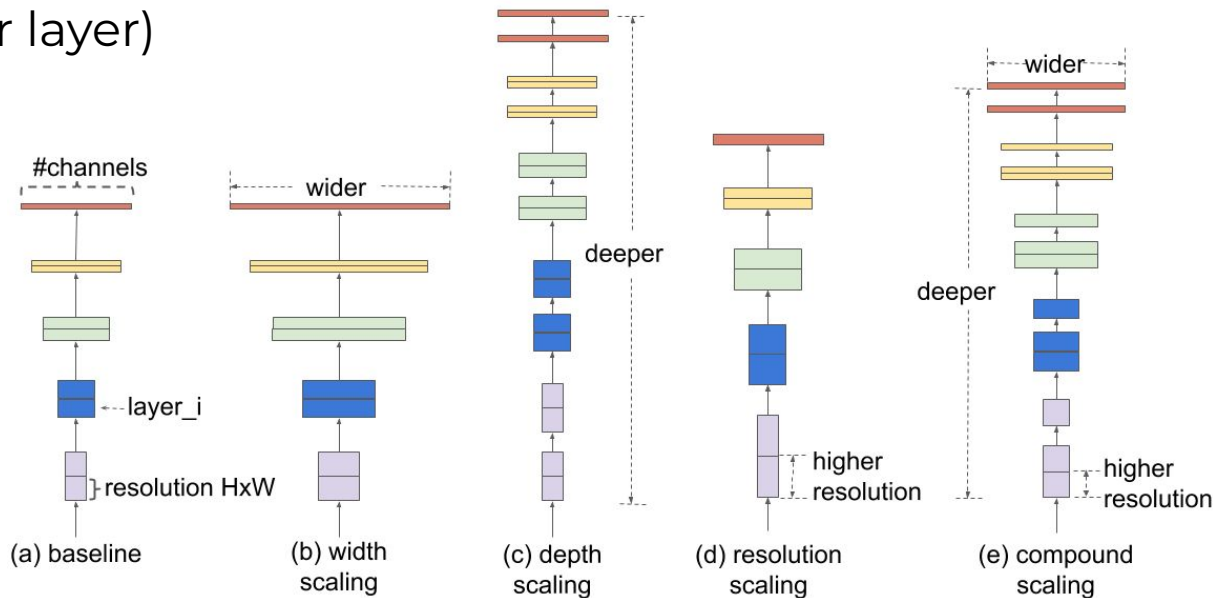
Should I go deeper, wider or bigger?

❖ Find a balance between them (they are all related!)

- Width (neurons per layer)
- Depth (layers)
- Resolution (input)

❖ Choose a size

- EfficientNetB0-B7



# Noisy Student

A semi-supervised training paradigm

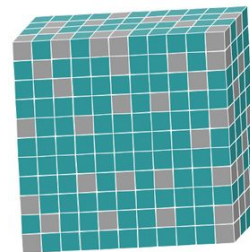
1. Train model A (teacher) with the labeled data
  2. Use A to generate pseudo-labels for an unlabeled data set
  3. Train model B (student) with both labeled and pseudo-labeled data
- ❖ Iterate, re-labeling the unlabeled data each time
  - ❖ Highly regularized (noise!) student to guarantee improvement
  - ❖ Each student has more capacity than the previous



# Spatial Dropout

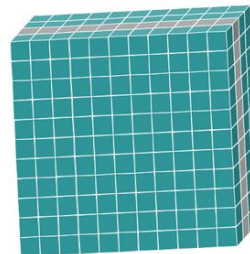
Standard Dropout is suboptimal for spatially related data

- ❖ Consecutive inputs can be strongly redundant



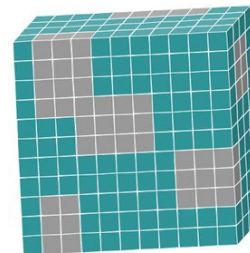
Spatial Dropout

- ❖ Drop entire feature maps, aka channels



Cutout

- ❖ Drop connected components along width, height and/or depth





# Visualizing CNNs

Biases everywhere



# The Basics

- ❖ NN are representation learning techniques
- ❖ CNNs build hierarchically complex features
  - From Gabor filters to dog faces
  - Induced by convolution
  - Tend to focus on the “non obvious for humans”
    - Backgrounds, textures
- ❖ The closer to the loss, more classifier (task) and less representation (data)

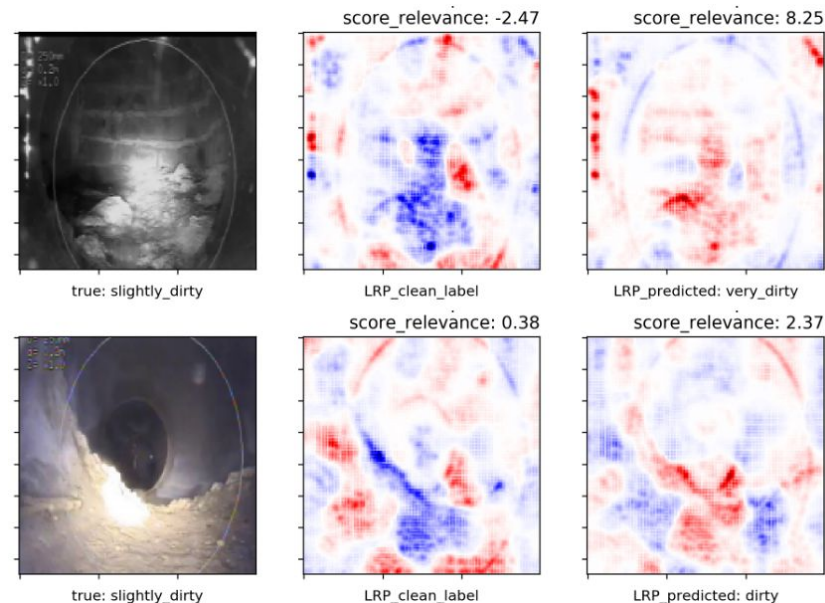
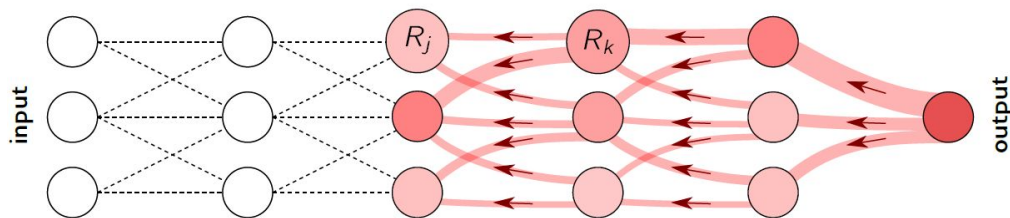
# Ways of Looking at CNNs

- ❖ *Attribution: **Where*** is the network looking?
  - Grounded. Instance based.
  - Explainability in practice.
- ❖ *Feature Visualization: **What*** is the network seeing?
  - Uncontextualized. Maximization based.
  - Diagnosys & Insight
- ❖ *Exemplification: **Which*** samples cause a maximum activation?
  - Samples from a distribution



# Attribution

- ❖ Finding the importance of pixels
- ❖ Layerwise Relevance Propagation (LRP)
  - Backpropagate *an* output. Find the relevance of each neuron
    - Weighted by CNN parameters



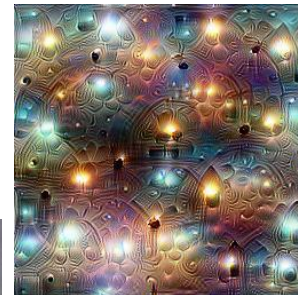
# Feature Visualization

## ❖ Optimizing the input to maximize the output

- A neuron
- A channel
- A layer (DeepDream)



Low level



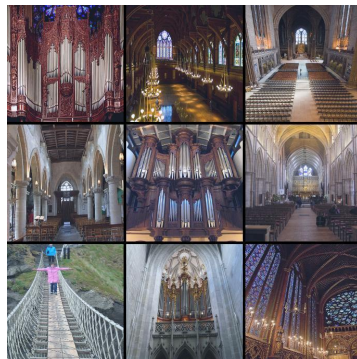
High level



# Exemplification

## ❖ Finding images within a dataset maximizing outputs

- Subjective
- Partial
- Stochastic



# Bias in DL

*“All models are wrong, some are useful” - George Box*

-

*“All DL models are biased, some are usefully biased”*

- ❖ Bias is what makes ML work. Is a form of generalization.
  - *Identification*: What bias?
    - Bonus track: Human bias (Pareidolia)
  - *Appreciation*: Desirable bias?
  - *Mitigation*: Altering dataset or model?



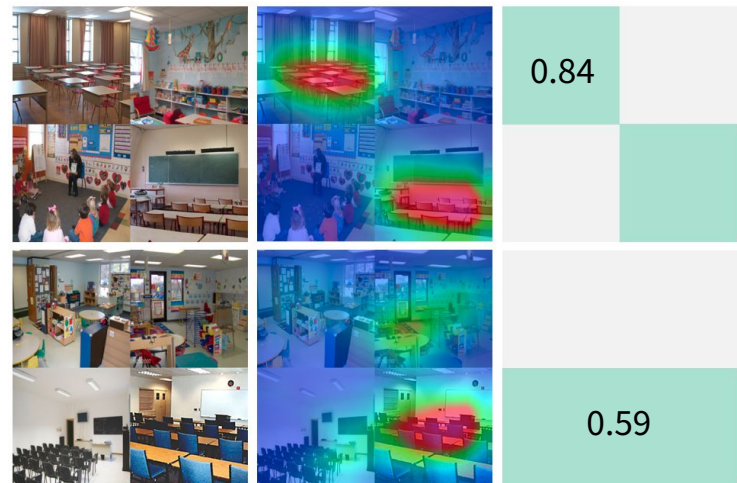
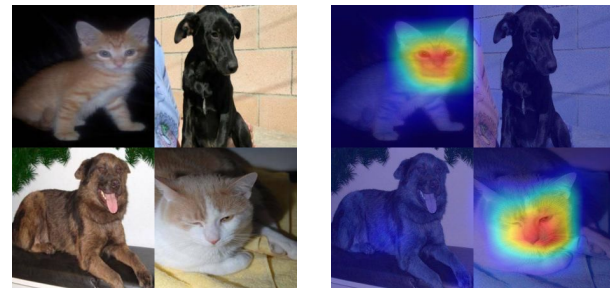


# Bias Detection through XAI Attribution

Focus & Mosaics: An eye-tracking game

*Why is this mosaic of class “cat”?*

- ❖ Identification: Many examples needed
- ❖ Appreciation: Expert decision
- ❖ Mitigation:
  - Shared bias:
    - + target samples without bias
    - + non-target samples with bias
  - Missing bias: + target samples with bias



Target class: **Classroom**  
Outer class: Kindergarten

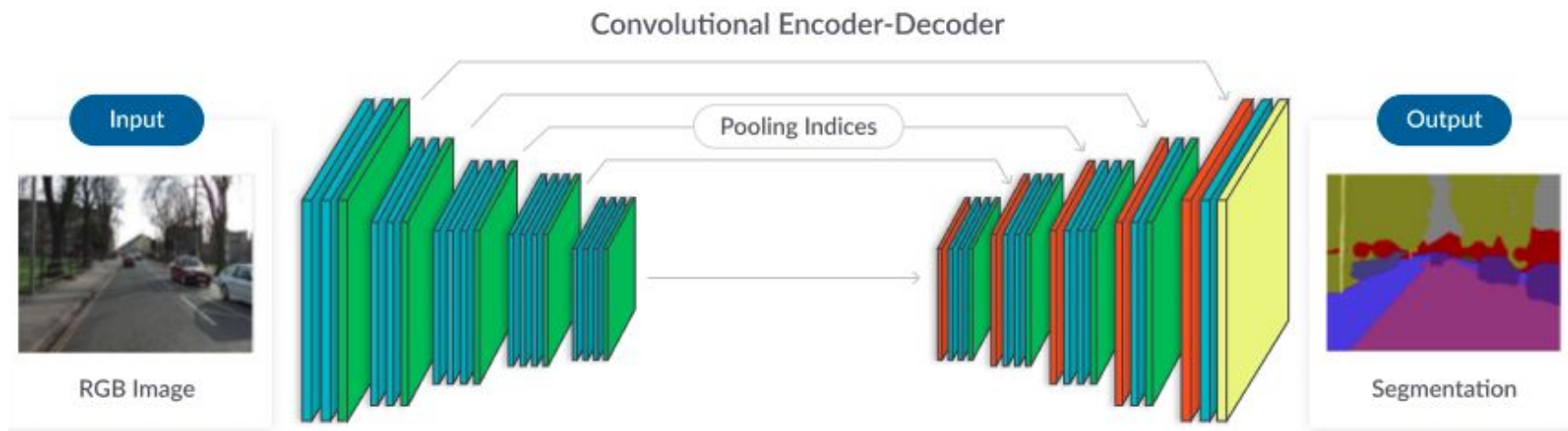


# Playing with CNNs



# Encoder-Decoder CNNs

- ❖ Pixel-wise classification task (image reconstruction loss)
- ❖ Bottlenecking makes it cheaper



● Conv + Batch Normalisation + ReLU

● Pooling

● Upsampling

● Softmax

# Automatic Image Colorization

- ◆ Another pixel-wise classification application



(a) *Colorado National Park, 1941*



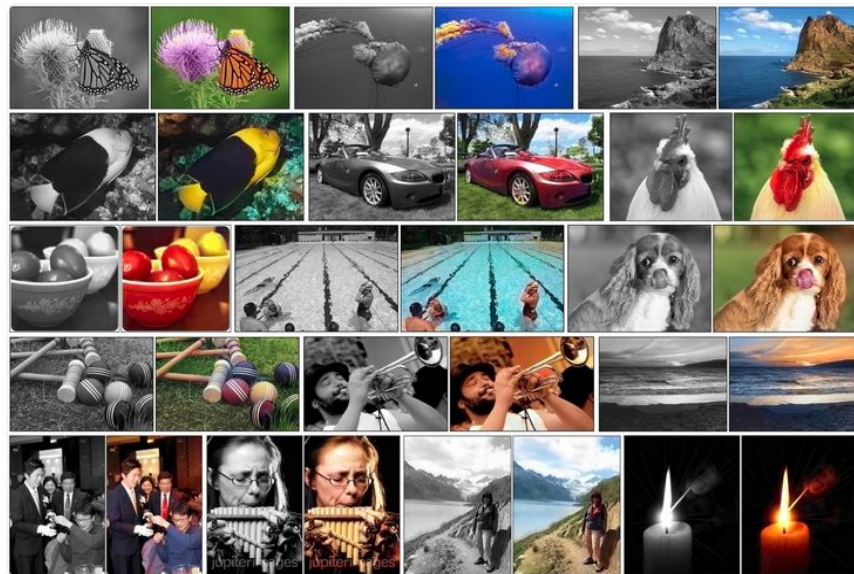
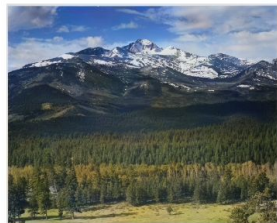
(b) *Textile Mill, June 1937*



(c) *Berry Field, June 1909*



(d) *Hamilton, 1936*



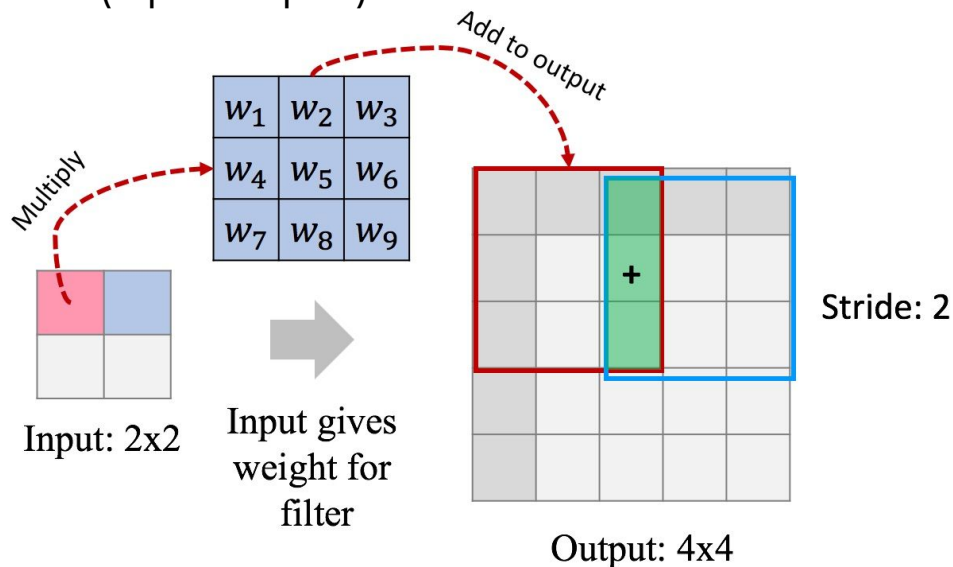
# Transposed Convolution ~~Deconvolution~~

❖ Reverse effect of regular convolution (upsample)

❖ Learnt interpolation

❖ Applications

- Segmentation
- GANs
- Super-Resolution
- Conv. Autoencoders



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# Faster Segmentation

- ❖ ~~Pixel-wise classification~~ Object detection (bounding box)
  - Can be done with a “regular” CNN
- ❖ R-CNN: Propose crops (SVM). Extract features (CNN). Classify crops (SVM)
- ❖ Fast R-CNN: Extract features. Propose crops. Classify/Bounding Box (CNN)
- ❖ Faster R-CNN: Propose crops through a specific sub-net (RPN)
- ❖ YOLO v? (no regions, faster, less accurate)
  - Divide into grid. Predict class and bounding box for each cell.



# Better Segmentation

- ❖ Mask R-CNN
  - Faster R-CNN for object detection
  - FCN for instance segmentation (pixel classification)
- ❖ Xception
  - Depth-wise separable Convs (inverted order & w/o non-linearity)
  - Skip connections
  - Atrous SPP



# Style Transfer

- ❖ What do the correlation of activations intra-layer tell us?
  - What if we force it on another image?

- ❖ Gram matrix represents the *style*

- Channel-wise ( $c \times c$ )
- Several mid layers

- ❖ Activations represents the *content*

- One mid layer



- ❖ Optimize the **input** to minimize 2 losses
- ❖ Use a pre-trained net frozen
- ❖ Improved and extended



# Image Generation

- ❖ StyleGAN2 + pix2pixHD
  - Pixel-wise generative models
- ❖ Flow-edge Guided Video Completion
- ❖ <https://colab.research.google.com/drive/1KznIbRyNdiNBrrVbD7uolccdf9rngVUE?usp=sharing>



# Handwritten Generation

- ❖ <https://github.com/sjvasquez/handwriting-synthesis>
- ❖ <https://arxiv.org/abs/1308.0850>
- ❖ <https://www.calligrapher.ai/>





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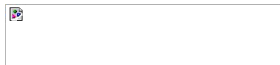


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