An Intro to OSQAT - closed-system simulation

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August 5, 2020

0.1 Close System Examples

This notebook will get you started with OSQAT by introducing you to the functionality for solving closed system equations.

0.1.1 Define the Hamiltonin

Let start with a 2-level system with Hamiltonian

$$H(s) = -\sigma_z$$

and initial state

$$|\phi(0)\rangle = |+\rangle$$
,

where s is the dimensionless annealing parameter and is usually chosen as

$$s = t/t_f$$
,

where t_f is the total evolution time. We use a constant Hamiltonian in this tutorial so we can trivially confirm the simulation result. However, the syntax will be the same for time dependent Hamiltonians. Let's first define the Hamiltonian by:

```
using QuantumAnnealingTools, OrdinaryDiffEq, Plots
# define the Hamiltonian
H = DenseHamiltonian([(s)->1.0], [-σz], unit=:ħ)
u0 = PauliVec[1][1]
# define total evolution time in (ns)
tf = 10
annealing = Annealing(H, u0)

Annealing with hType QTBase.DenseHamiltonian{Complex{Float64}} and uType Ar
ray{Complex{Float64},1}
u0 with size: (2,)
```

In this example, we use the DenseHamiltonian object. The syntax is the same for other type of Hamiltonians.

0.1.2 Schrodinger equation

We start with the Schrodinger equation $\left\{ \left(\frac{\phi}{\phi} \right) \right\} = -i t_f H(s) \left\{ \frac{\phi}{\phi} \right\}$

To solve the this differential equation, we need to choose a proper algorithm. OSQAT rely on OrdinaryDiffEq.jl as the low level solver, which support a large collection of algorithms. We do not guarantee compatibilities to every solver in this list. Users can try specific algorithms if they are interested. We provide a list of algorithms we tested and recommended here:

- The default Tsitouras 5/4 Runge-Kutta method(Tsit5()).
 This is the default method in OrdinaryDiffEq and works well in most cases.
- 2. A second order A-B-L-S-stable one-step ESDIRK method(TRBDF2()).

 This is the method widely used in large scale classical circuit simulations. Because this method has order of 2, it is recommended to use smaller error tolerance comparing with other higher order methods.
- 3. A simple linear exponential method(LinearExponential()).

 This method simply discretize the Hamiltonian and do matrix exponential for each interval.
- 4. Adaptive exponential Rosenbrock methods(Exprb32()/Exprb43()).

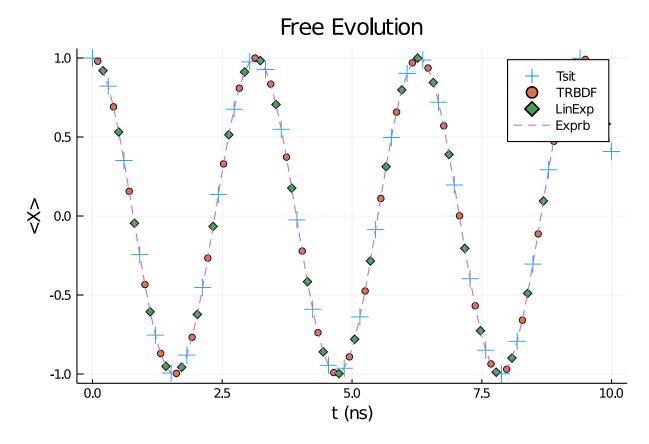
 This method belongs to the adaptive exponential Runge-Kutta method family.

It is important to notice that, method 3 and 4 are exponential methods which would preserve the norm of the state vectors. To solve our the Schrodinger equation we use the command solve schrodinger.

```
sol_tsit = solve_schrodinger(annealing, tf, alg=Tsit5(), abstol=1e-6, reltol=1e-6);
sol_trbdf = solve_schrodinger(annealing, tf, alg=TRBDF2(), abstol=1e-6, reltol=1e-6);
# LinearExponential is a fixed step size method, user need to specify the time steps
using keyword argument `tstops`.
sol_linexp = solve_schrodinger(annealing, tf, alg=LinearExponential(), abstol=1e-6,
reltol=1e-6, tstops=range(0,tf,length=100));
# Even though Exprb method is an adaptive method, it tends to jump a lot of middle
points. So if you want accurate evolution in the middle,
# it is better to manually add more points for the algorithm.
sol_exprb32 = solve_schrodinger(annealing, tf, alg=Exprb32(),
tstops=range(0,tf,length=100));
retcode: Success
Interpolation: 3rd order Hermite
t: 101-element Array{Float64,1}:
 0.0
 0.02155449821897047
 0.10101010101010101
 0.20202020202020202
 0.30303030303030304
 0.404040404040403
 0.5050505050505051
```

```
0.6060606060606061
 0.7070707070707071
 0.8080808080808081
 9.1919191919192
 9.2929292929292
 9.3939393939394
 9.4949494949495
 9.5959595959595
 9.6969696969697
 9.7979797979798
 9.89898989899
u: 101-element Array{Array{Complex{Float64},1},1}:
 [0.7071067811865475 + 0.0im, 0.7071067811865475 + 0.0im]
 [0.7069425279158157 + 0.015240151705153755im, 0.7069425279158157 - 0.01524
0151705153755im]
 [0.7035025277139556 + 0.0713035307686447im, 0.7035025277139556 - 0.0713035
307686447im]
 [0.6927265103834769 + 0.14188016708451748im, 0.6927265103834769 - 0.141880]
16708451748im]
 [0.6748855338844382 + 0.21101042472460332im, 0.6748885838844382 - 0.211010
42472460332im]
 [0.6501705946090355 + 0.2779895643827896im, 0.6501705946090355 - 0.2779895
 [0.6188245268432399 + 0.3421347760418987im, 0.6188245268432399 - 0.3421347
760418987im]
 [0.5811699339461844 + 0.40279213979047235im, 0.5811699339461844 - 0.402792
13979047235im]
 [0.5375906807055341 + 0.45934329212317915im, 0.5375906807055341 - 0.459343
29212317915im]
 [0.48853103007846754 + 0.5112117297661226im, 0.48853103007846754 - 0.51121
17297661226im]
 [-0.6880224515362771 + 0.16317201408946222im, -0.6880224515362771 - 0.1631
7201408946222iml
 [-0.7009694825372761 + 0.0929611991716103im, -0.7009694825372761 - 0.09296
11991716103im]
 802703553061978im]
 [-0.7053665829045693 - 0.04957805685514289im, -0.7053665829045693 + 0.0495
7805685514289im]
 [-0.6967718266103273 - 0.12045340029284536im, -0.6967718266103273 + 0.1204
5340029284536im]
 [-0.6810739217040739 - 0.19010079740662192im, -0.6810739217040739 + 0.1901
0079740662192im]
  \hbox{ $[-0.6584328984097478-0.25781023698010735im,-0.6584328984097478+0.2578] }
1023698010735im]
 9146404983027im]
 [-0.5933131681105249 - 0.38468101661851273im, -0.5933131681105249 + 0.3846
8101661851273im]
We plot the observable \langle X \rangle during the evolution.
t_list = range(0,tf,length=100)
tsit = []
trbdf = []
linexp = []
```

```
exprb32 = []
for s in t_list
    push!(tsit, real(sol_tsit(s)'*\sigmax*sol_tsit(s)))
    push!(trbdf, real(sol_trbdf(s)'*\sigmax*sol_trbdf(s)))
    push!(linexp, real(sol_linexp(s)'*\sigmax*sol_linexp(s)))
    push!(exprb32, real(sol_exprb32(s)'*\sigmax*sol_exprb32(s)))
end
scatter(t_list[1:3:end], tsit[1:3:end], label="Tsit", marker=:+, markersize=8)
scatter!(t_list[2:3:end], trbdf[2:3:end], label="TRBDF")
scatter!(t_list[3:3:end], linexp[3:3:end], label="LinExp", marker=:d)
plot!(t_list, exprb32, label="Exprb", linestyle=:dash)
xlabel!("t (ns)")
ylabel!("<X>")
title!("Free Evolution")
```



0.1.3 Other close system equations

The package also contains several other close system tools.

Von Neumann equation Von Neumann equation is the "Schrodinger" equation for density matrices

$$\dot{\rho} = -it_f[H(s), \rho]$$
.

Even though Von Neumann equation is equivalent to the Schrodinger equation, it is sometimes numerically more stable than the Schrodinger equation. Users is encouraged to try to solve them using different algorithms.

```
annealing = Annealing(H, u0)
```

```
sol tsit = solve von neumann(annealing, tf, alg=Tsit5(), abstol=1e-6, reltol=1e-6)
retcode: Success
Interpolation: specialized 4th order "free" interpolation
t: 78-element Array{Float64,1}:
 0.025416471135423512
 0.07162657822452011
 0.12691325854682373
 0.19490751014915958
 0.2726355853793798
 0.3605272018981224
 0.4567317871059021
 0.5605609353632346
 0.6707029681719032
 8.93912030993445
 9.07904338542158
 9.218966473882144
 9.358889575316146
 9.498812680456844
 9.63873579857098
 9.778658911125072
 9.91858201811912
10.0
u: 78-element Array{Array{Complex{Float64},2},1}:
+ 0.0im 0.499999999999999 + 0.0im]
.4993541420867104 - 0.025405526573483335im 0.49999999999999 + 0.0im]
[0.4999999999999 + 0.0im 0.49487840083247414 + 0.07138184906644161im; 0
.49487840083247414 - 0.07138184906644161im 0.499999999999999 + 0.0im]
 [0.4999999999999 + 0.0im 0.4839793174578459 + 0.12555484945742712im; 0.
4839793174578459 - 0.12555484945742712im 0.49999999999999 + 0.0im]
 [0.49999999999999 + 0.0im 0.46248968537194657 + 0.19000865966633518im; 0
.46248968537194657 - 0.19000865966633518im 0.49999999999999 + 0.0im]
 [0.4999999999999 + 0.0im 0.427493339167494 + 0.25932497858582826im; 0.4
27493339167494 - 0.25932497858582826im 0.499999999999999 + 0.0im]
 37555502540351415 - 0.3300885061538326im 0.49999999999999 + 0.0im]
[0.499999999999 + 0.0im 0.30550378150848995 + 0.39581237672432157im; 0
.30550378150848995 - 0.39581237672432157im 0.4999999999999999 + 0.0im
73361827963109 - 0.450294326336122im 0.499999999999999 + 0.0im]
[0.4999999999999 + 0.0im 0.1136919542765893 + 0.48690259218729237im; 0.
1136919542765893 - 0.48690259218729237im 0.49999999999999 + 0.0im]
821075428516711 + 0.4128134549525757im 0.499999999999999 + 0.0im]
[0.4999999999999 + 0.0im 0.3851552754690851 - 0.31883384596677317im; 0.
3851552754690851 + 0.31883384596677317im 0.49999999999999 + 0.0im]
 [0.4999999999999 + 0.0im 0.45823633996555163 - 0.200047638132882im; 0.4
5823633996555163 + 0.200047638132882im 0.499999999999999 + 0.0im]
 [0.4999999999999 + 0.0im 0.495664718569642 - 0.06569688565511998im; 0.4
95664718569642 + 0.06569688565511998im 0.499999999999999 + 0.0im]
 .49452831997779884 - 0.07376535766452093im 0.49999999999999 + 0.0im]
 [0.4999999999999 + 0.0im 0.4549155549065751 + 0.20748835723339634im; 0.
```

As shown below, the solution given by the solver is the density matrix instead of state vector:

Recommended algorithm Only explicit methods are supported for solving equations w.r.t. density matrices. Vectorization is needed for implicit methods. This can be done by setting vectorize keyword argument to be true. For example, in the following block, we solve the Von Neumann equation with TRBDF2 method:

```
sol_bdf = solve_von_neumann(annealing, tf, alg=TRBDF2(), reltol=1e-6, vectorize=true)
sol_bdf(0.5 * tf)

4-element Array{Complex{Float64},1}:
    0.4999999999999 + 0.0im
    -0.4214558175232074 + 0.26894060674187487im
    -0.4214558175232074 - 0.26894060674187487im
    0.4999999999999 + 0.0im
```

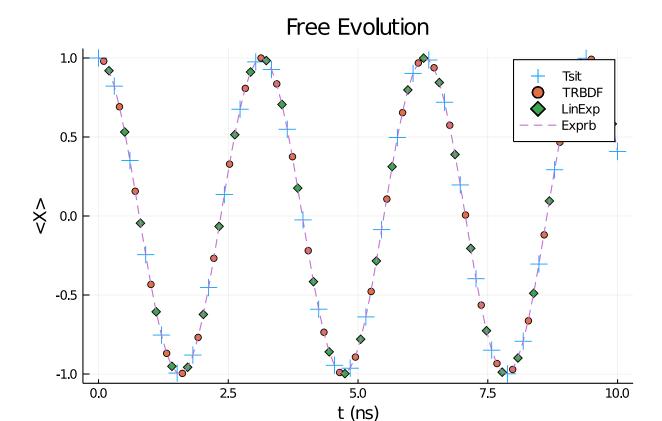
As shown above, the solution given by the solver becomes a vectorized version of the density matrix.

Side note: TRBDF2 can actually work without vectorizing the Von Neumann equation. However, this is not generally true for other algorithms/solvers. For example, we will run into error for LinearExponential method if no vectorization is performed:

```
sol_linexp = solve_von_neumann(annealing, tf, alg=LinearExponential(),
tstops=range(0,tf,length=100));
Error: MethodError: no method matching Array{T,2} where T(::QuantumAnnealin
gTools.var"#35#39")
Closest candidates are:
  Array{T,2} where T(!Matched::LinearAlgebra.SymTridiagonal{T,V} where V<:A
bstractArray{T,1}) where T at D:\Julia-1.5.0\share\julia\stdlib\v1.5\Linear
Algebra\src\tridiag.jl:141
  Array{T,2} where T(!Matched::LinearAlgebra.Tridiagonal{T,V} where V<:Abst
ractArray{T,1}) where T at D:\Julia-1.5.0\share\julia\stdlib\v1.5\LinearAlg
ebra\src\tridiag.j1:582
  Array{T,2} where T(!Matched::LinearAlgebra.LowerTriangular{T,S} where S<:
AbstractArray{T,2}) where T at D:\Julia-1.5.0\share\julia\stdlib\v1.5\Linea
rAlgebra\src\triangular.jl:34
sol_linexp = solve_von_neumann(annealing, tf, alg=LinearExponential(),
tstops=range(0,tf,length=100), vectorize=true);
```

```
retcode: Success
Interpolation: 3rd order Hermite
t: 100-element Array{Float64,1}:
 0.10101010101010101
 0.20202020202020202
 0.30303030303030304
 0.404040404040403
 0.5050505050505051
 0.6060606060606061
 0.7070707070707071
 0.8080808080808081
 0.90909090909091
 9.1919191919192
 9.2929292929292
 9.3939393939394
 9.4949494949495
 9.5959595959595
 9.6969696969697
 9.7979797979798
 9.89898989899
10.0
u: 100-element Array{Array{Complex{Float64},1},1}:
[0.499999999999 + 0.0im, 0.499999999999 + 0.0im, 0.499999999999
.4898316129998498 + 0.10032442826134269im, 0.49999999999999 + 0.0im]
0.45974003637613875 + 0.19656830607416487im, 0.499999999999999 + 0.0im
[0.4999999999999 + 0.0im, 0.410949201315085 - 0.28481705345448277im, 0.
410949201315085 + 0.28481705345448277im, 0.49999999999999 + 0.0im]
[0.499999999999 + 0.0im, 0.3454436041885337 - 0.3614812807397302im, 0.
3454436041885337 + 0.3614812807397302im, 0.499999999999999 + 0.0im
[0.49999999999999 + 0.0im, 0.2658875900455196 - 0.4234427818014917im, 0.
2658875900455196 + 0.4234427818014917im, 0.49999999999999 + 0.0im]
 [0.49999999999999 + 0.0im, 0.1755169842460251 - 0.4681813625521424im, 0.
1755169842460251 + 0.4681813625521424im, 0.49999999999999 + 0.0im]
[0.4999999999999 + 0.0im, 0.07800747996287927 - 0.493877346180042im, 0.
07800747996287927 + 0.493877346180042im, 0.499999999999999 + 0.0im]
-0.02267486530094263 + 0.49948558586167846im, 0.49999999999999 + 0.0im
0.1224349433425395 + 0.4847779745911619im, 0.49999999999999 + 0.0im]
.4467497876359766 - 0.22453201831188785im, 0.49999999999999 + 0.0im]
[0.49999999999999 + 0.0im, 0.4827164308971524 + 0.1303259273587371im, 0.
4827164308971524 - 0.1303259273587371im, 0.49999999999999 + 0.0im]
[0.49999999999999 + 0.0im, 0.49904928423555467 + 0.030819018543436303im,
0.49904928423555467 - 0.030819018543436303im, 0.49999999999999 + 0.0im
.4950840325569366 + 0.06994140910192062im, 0.49999999999999 + 0.0im]
[0.4999999999999 + 0.0im, 0.4709819567157834 - 0.16785707148694098im, 0
.4709819567157834 + 0.16785707148694098im, 0.49999999999999 + 0.0im]
0.42772337365073343 + 0.25894539121759863im, 0.499999999999999 + 0.0im
[0.4999999999999 + 0.0im, 0.36706776341652236 - 0.3395014831490315im, 0
```

```
.36706776341652236 + 0.3395014831490315im, 0.4999999999999 + 0.0im]
 [0.4999999999999 + 0.0im, 0.2914822048875151 - 0.4062488452093284im, 0.
2914822048875151 + 0.4062488452093284im, 0.49999999999999 + 0.0im]
 [0.4999999999999 + 0.0im, 0.20404103090669592 - 0.45647262536381406im,
0.20404103090669592 + 0.45647262536381406im, 0.499999999999999 + 0.0im
We can again plot the \langle X \rangle for different methods
sol_tsit = solve_von_neumann(annealing, tf, alg=Tsit5(), reltol=1e-6);
sol_trbdf = solve_von_neumann(annealing, tf, alg=TRBDF2(), reltol=1e-6);
# LinearExponential is a fixed step size method, user need to specify the time steps
using keyword argument `tstops`.
sol_linexp = solve_von_neumann(annealing, tf, alg=LinearExponential(),
tstops=range(0,tf,length=100), vectorize=true);
# Even though Exprb method is an adaptive method, it tends to jump a lot of middle
points. So if you want accurate evolution in the middle,
# it is better to manually add more points for the algorithm.
sol_exprb32 = solve_von_neumann(annealing, tf, alg=Exprb32(),
tstops=range(0,tf,length=100), vectorize=true);
t_list = range(0,tf,length=100)
tsit = []
trbdf = []
linexp = []
exprb32 = []
for s in t_list
    push!(tsit, real(tr(sol_tsit(s)*σx)))
    push!(trbdf, real(tr(sol_trbdf(s)*σx)))
   push!(linexp, real(tr(\sigmax*reshape(sol_linexp(s),2,2))))
    push!(exprb32, real(tr(\sigmax*reshape(sol_exprb32(s),2,2))))
end
scatter(t_list[1:3:end], tsit[1:3:end], label="Tsit", marker=:+, markersize=8)
scatter!(t list[2:3:end], trbdf[2:3:end], label="TRBDF")
scatter!(t_list[3:3:end], linexp[3:3:end], label="LinExp", marker=:d)
plot!(t_list, exprb32, label="Exprb", linestyle=:dash)
xlabel!("t (ns)")
vlabel!("<X>")
title!("Free Evolution")
```



Unitary Lastly, we can also solve the unitary

$$U(s) = T_{+} \exp \left\{ -it_{f} \int_{0}^{s} H(s') ds' \right\}$$

using solve_unitary. The ODE form of the problem is

$$\dot{U} = -it_f H(s) U .$$

Again, although this is in principle equivalent to Schrondinger/Von Neumann equation, the unitary becomes handy in certain cases, e.g. the Redfeild equation.

Again we plot the $\langle X \rangle$ obtained by multiplying the unitary with the initial state.

```
sol_tsit = solve_unitary(annealing, tf, alg=Tsit5(), reltol=1e-6);
sol_trbdf = solve_unitary(annealing, tf, alg=TRBDF2(), reltol=1e-6, vectorize=true);
# LinearExponential is a fixed step size method, user need to specify the time steps using keyword argument `tstops`.
sol_linexp = solve_unitary(annealing, tf, alg=LinearExponential(), tstops=range(0,tf,length=100), vectorize=true);
# Even though Exprb method is an adaptive method, it tends to jump a lot of middle points. So if you want accurate evolution in the middle,
# it is better to manually add more points for the algorithm.
```

```
sol_exprb32 = solve_unitary(annealing, tf, alg=Exprb32(), tstops=range(0,tf,length=100),
vectorize=true);
t_list = range(0,tf,length=100)
tsit = []
trbdf = []
linexp = []
exprb32 = []
for s in t_list
    state_tsit = sol_tsit(s) * u0
    state_trbdf = reshape(sol_trbdf(s), 2, 2) * u0
    state_linexp = reshape(sol_linexp(s), 2, 2) * u0
    state_exprb32 = reshape(sol_exprb32(s), 2, 2) * u0
    push!(tsit, real(state_tsit' * \sigma x * state_tsit))
    push!(trbdf, real(state_trbdf' * \sigma x * state_trbdf))
    push!(linexp, real(state_linexp' * \sigma x * state_linexp))
    push!(exprb32, real(state_exprb32' * \sigma x * state_exprb32))
end
scatter(t_list[1:3:end], tsit[1:3:end], label="Tsit", marker=:+, markersize=8)
scatter!(t_list[2:3:end], trbdf[2:3:end], label="TRBDF")
scatter!(t_list[3:3:end], linexp[3:3:end], label="LinExp", marker=:d)
plot!(t_list, exprb32, label="Exprb", linestyle=:dash)
xlabel!("t (ns)")
vlabel!("<X>")
title!("Free Evolution")
```



