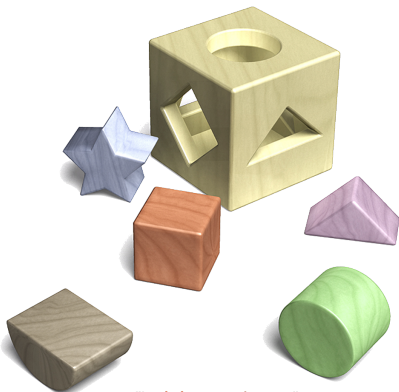


Visualizing Dynamic Programming On Tree Decompositions

Martin Rübke

International Center for Computational Logic
Technische Universität Dresden
Germany

- ▶ **WHAT is this about?**
- ▶ **WHO benefits from visualization?**



"Logic is everywhere ..."



About me

Martin Röbbke

- **born in Dresden**
- **studying Computer Science Bachelor**
 - **started studying physics at the TU Dresden**
 - **did like logic and visualization more, so switched the faculty** 😊



How did I get to work with my supervisor Johannes Fichte?



Motivation

Previous work:

- ▶ **Boolean formulas are very expressive!**
 - ▷ Problem with huge instances
- ▶ Customized algorithms, data-structures, hardware

Why visualization?

→ trace and document the customization

Outlook:

- ▶ Improve and streamline the visualization process
- ▶ Implement debug-output in existing solvers
- ▶ Even more dynamic possibilities

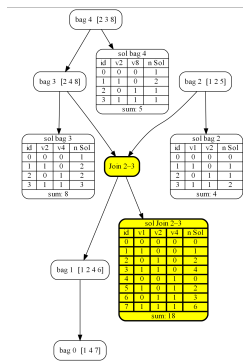


Figure: Example of a #SAT run with DP



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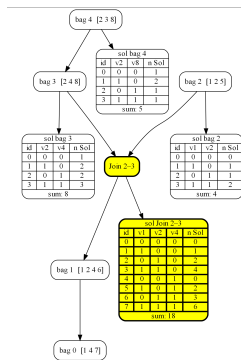


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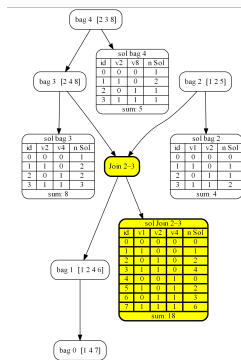


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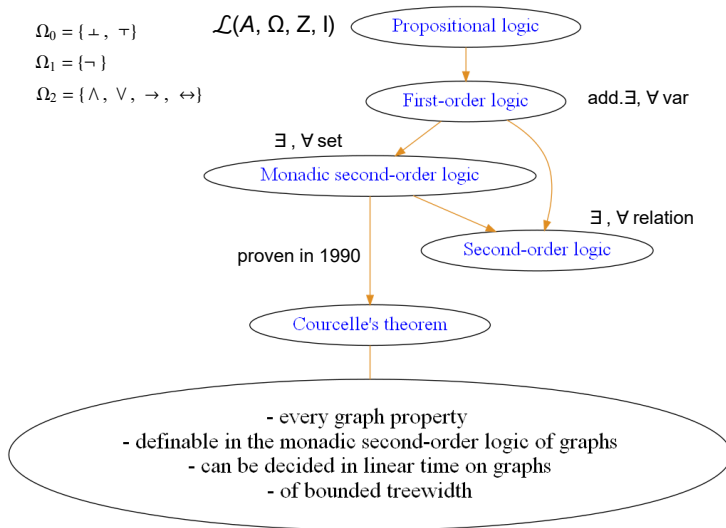
Background

$$\Omega_0 = \{ \perp, \top \}$$

$$\Omega_1 = \{ \neg \}$$

$$\Omega_2 = \{ \wedge, \vee, \rightarrow, \leftrightarrow \}$$

$\mathcal{L}(A, \Omega, Z, I)$



Example: Vertex-Cover problem

For this graph **G** we want to compute a set of vertices so that from every edge **(u, v)** there is at least one of **u** or **v** in that “cover” of **G**.

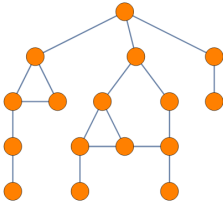


Figure: Example undirected graph **G**

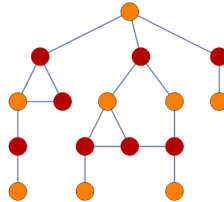


Figure: Minimal VC of **G**

$$\exists S : \forall x, y \in E : (x \in S \vee y \in S)$$

Finding the smallest of these sets is the optimization version of a NP-complete decision problem.



Courcelle's theorem

► statement:

Every graph property definable in MSOL is decidable in linear time on graphs of bounded treewidth.

Courcelle, Bruno (Bordeaux I University 1990)

► drawback: still expensive ($2^{k \cdot tw}$, $2^{2^{\#quant}}$, large constants)

► usage:

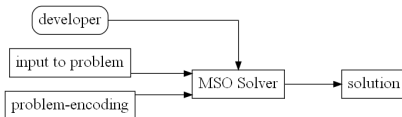


Figure: Implementation of the theorem



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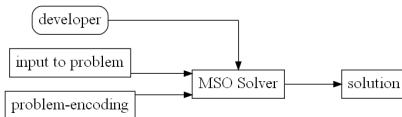


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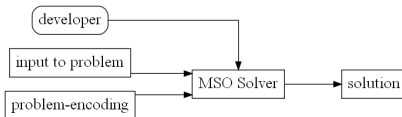


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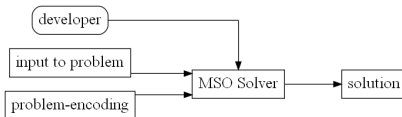


Figure: Implementation of the theorem



(Weighted) Model-Counting

The #SAT Problem

Input: A boolean formula \mathbf{F}

Question: How many assignments do the occurring variables satisfy in \mathbf{F}

The Weighted Model Counting Problem

- ▶ $w(lit) \in [0, 1]$, $w(\neg lit) = 1 - w(lit)$
- ▶ $w(assignment) = \prod_{lit} w(lit)$
- ▶ $WMC(formula) = \sum_{satisfying\ assignments} w(assignment)$



Graphs for Boolean Formulas

Transforming the formula into CNF-form

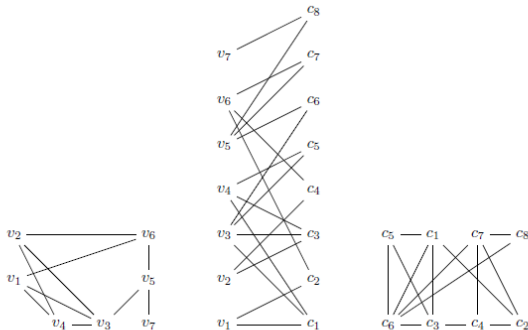


Figure 2.1: The primal (left), incidence (middle) and dual (right) graph for the SAT formula in Example [2.1](#)



Tree Decompositions

Parameterized Complexity and its Applications in Practice

From Foundations to Implementations

Johannes K. Fichte

TU Dresden, Germany

Jakarta, Indonesia

Summer 2019 (May 6th - May 16th)

pages 162-174

Backup: VC tree vs graph - example



gpuSAT1

graphic / github

- ▶ **OpenCL**
- ▶ **Incidence + Primal Graph**



gpuSAT2

graphic / github

- ▶ **OpenCL**
- ▶ **Only primal graph - simpler solving DP**
- ▶ **adapted memory-management**
- ▶ **improved precision handling**
- ▶ **customized tree decompositions**



graphic / github

- ▶ **using databases for intermediate results**
- ▶ **SAT**
- ▶ **#SAT**
- ▶ **Vertex Cover**



TODO - DA

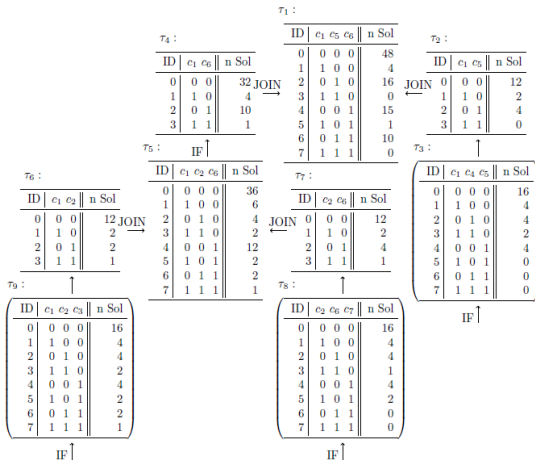


Figure:



TODO - presentation_gpusat



Creating Visualization for:

Improving

- ▶ **documentation**
- ▶ **debugging complex ds and parallel sync**
- ▶ **hotspots**

Generalizing the underlying graph



Outlook

- ▶ customizable output and interactive visualization
- ▶ ref. impl. in CUDA of gpuSAT2



Further Information



References



