# Variational Auto-Encoders (Part 2)

#### What we'll learn about Variational Auto-Encoders:

Part 1 (previous): The "simple" explanation of a VAE, as a regularized AE

- What is a VAE
- How to train VAEs
- How do different terms of training loss influence what VAE learns
- How does a VAE relate to the basic AE

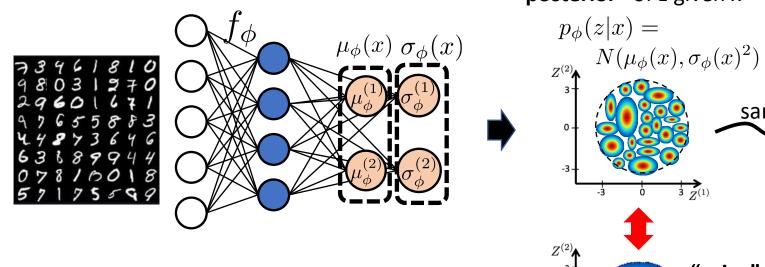
Part 2 (this video): Applications of VAE for...

- Generation of new data points
- Modifying data via interpolating between 2 inputs
- Modifying specific feature of an input
- Compression => Reconstruction

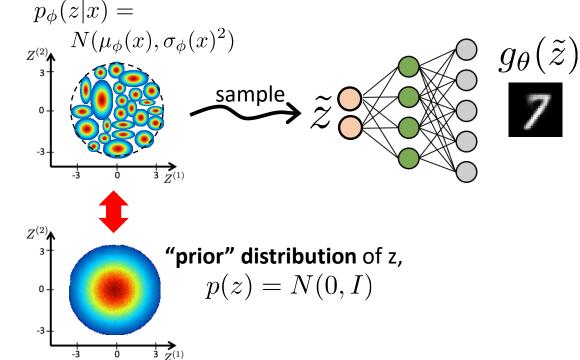
Part 3: The probabilistic derivation of a VAE (Optional, non-assessed. To be published at a later date)

Derivation of VAE as a probabilistic model for Density Estimation

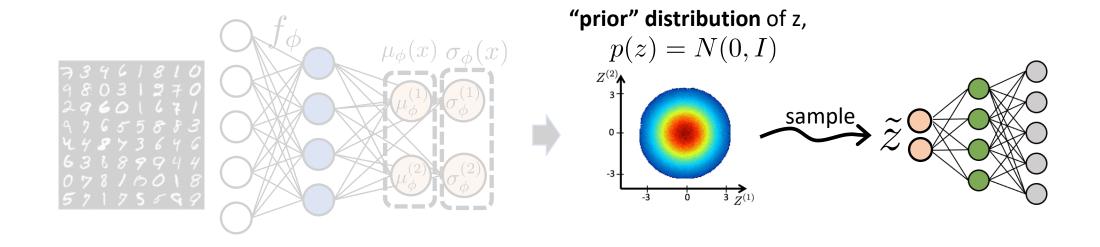
#### VAE: Training



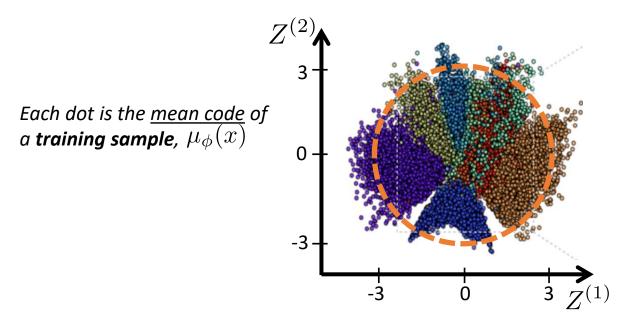
Predicted "conditional" or "posterior" of z given x

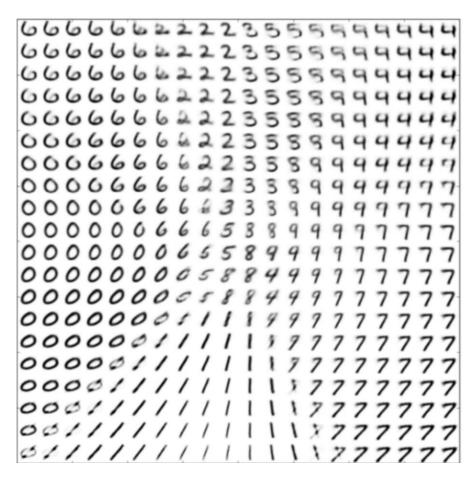


## VAE: Generating new data by sampling from prior



#### Generating (synthesizing) new data with VAE

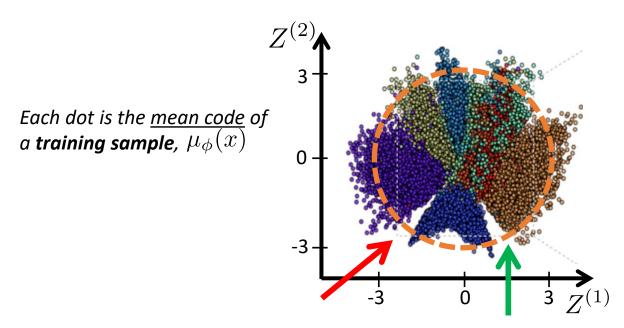




Values of z were sampled on a grid, under the area (-3,+3) covered by the prior.

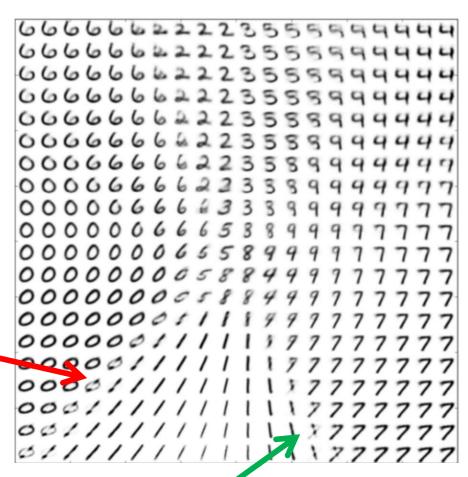
Images from: Cloudera Fast Forward (link)

## Generating (synthesizing) new data with VAE



Even for VAE, some "gaps" can still be left in space of Z. Why?

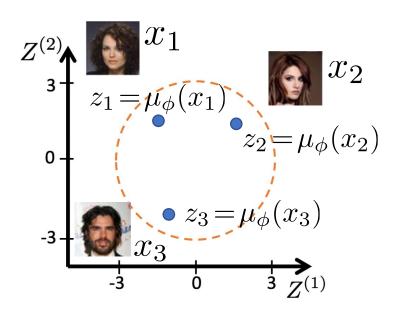
- 1. Reconstruction loss encourages separation of dissimilar data, "opposing" the regularizer.
- 2. SGD optimization does not find global optimum.



Values of z were sampled on a grid, under the area (-3,+3) covered by the prior.

Images from: Cloudera Fast Forward (link)

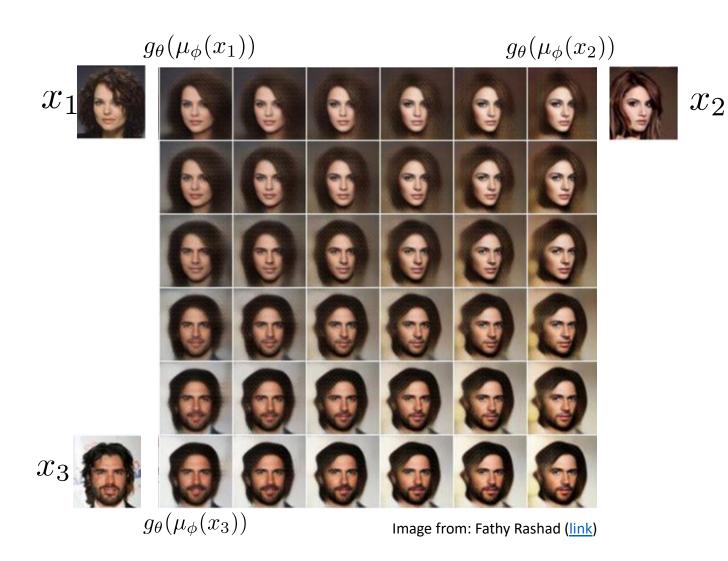
#### Interpolating between different inputs with VAE



#### Algorithm:

- **1. Encode** inputs x and get  $\mu_{\phi}(x)$  as z. E.g.  $z_1 = \mu_{\phi}(x_1), z_2 = \mu_{\phi}(x_2), z_3 = \mu_{\phi}(x_3)$
- 2. Create **new z** code by **interpolation** E.g.  $z = z_1 + \alpha(z_2 z_1) + \beta(z_3 z_1)$
- **3. Decode z** with decoder.

Can be for 2 or more inputs.



#### Interpolating between inputs: basic AE vs VAE

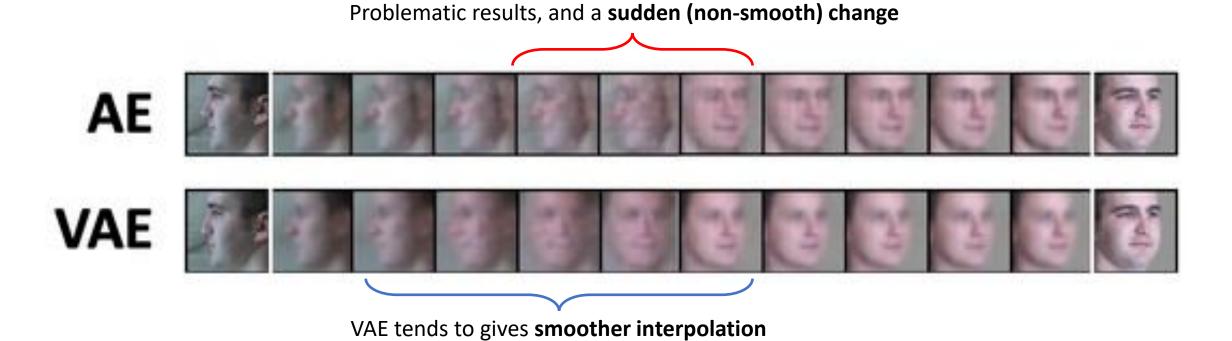
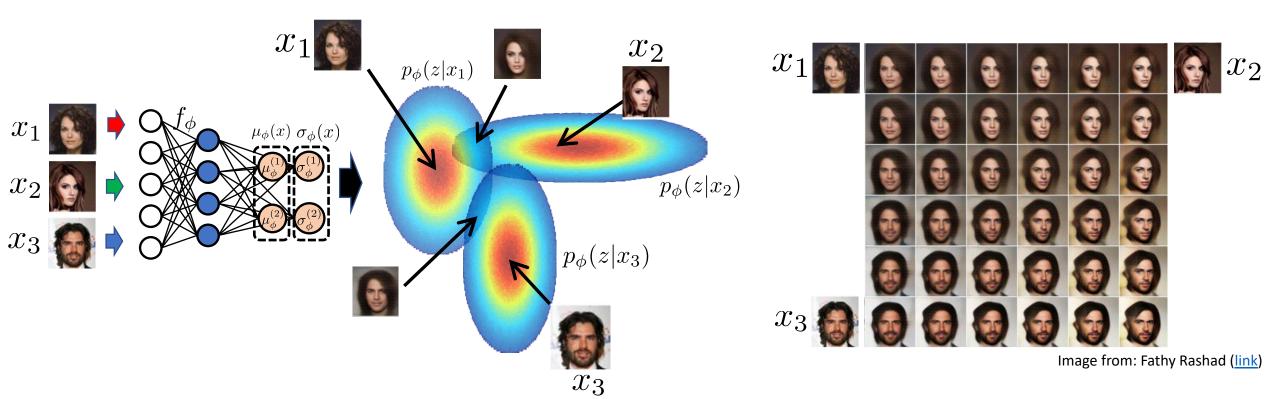
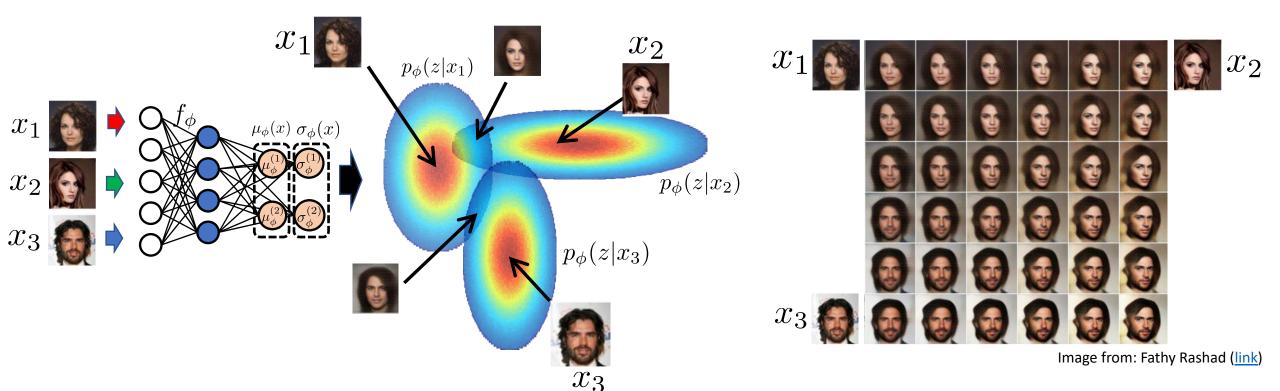


Image from: Yan et al, "Semantics-Guided Representation Learning with Applications to Visual Synthesis", 2020

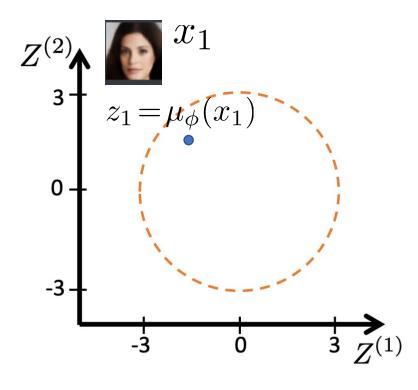
## Interpolation with a VAE gives "smoothly" changing output

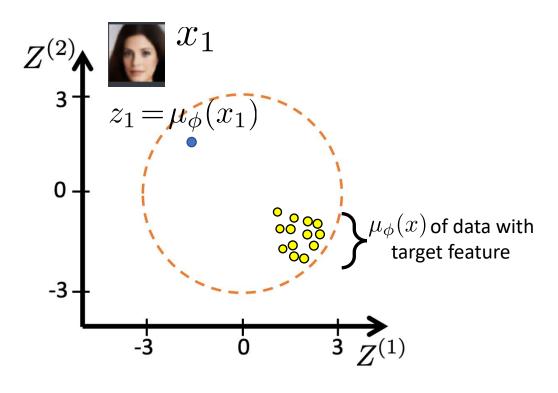


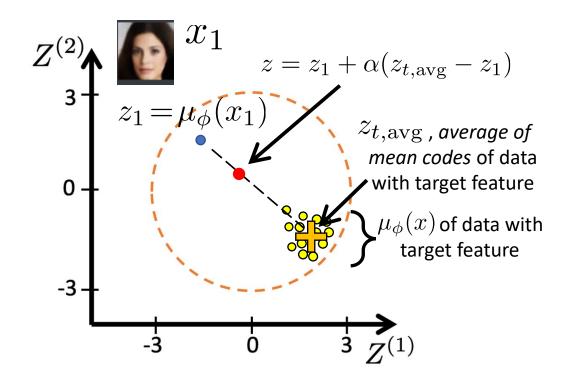
## Interpolation with a VAE gives "smoothly" changing output



**Smoothness**: No *sudden* changes between 2 nearby z values. Thanks to training with Gaussian distribution  $p_{\phi}(y|z)$  for encoding. In VAE, values of z between 2 training datapoints are associated with probability  $p_{\phi}(z|x_1)$  code of one training image  $x_1$ , and probability  $p(z|x_2)$  code of another training image  $x_2$ , where the 2 Gaussians predicted by encoder overlap. Therefore, decoding such intermediate values z leads to an image that has characteristics of both images that their p(z|x) overlap at that value of z. As we move in space of Z, Gaussians p(z|x) vary smoothly, and so characteristics in decoded images will vary smoothly.







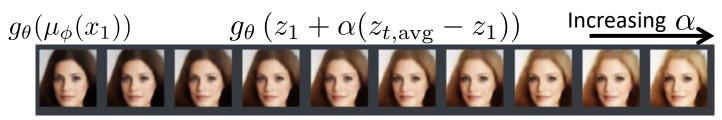
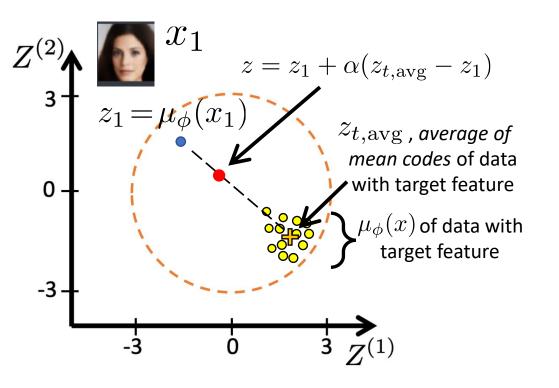


Image from: Steven Flores (link)



#### Algorithm:

- **1. Encode** original input x and use predicted  $\mu_{\phi}(x)$  as its code: E.g.  $z_1 = \mu_{\phi}(x_1)$
- 2. Identify all training samples that have the desired "target" characteristic. E.g. blondes. Assume these are  $x_{t,1}, x_{t,2}, ...$
- **3. Encode** all training samples with the target characteristic. Use mean of the Gaussian predicted by encoder as the code. E.g.  $z_{t,1} = \mu_{\phi}(x_{t,1}), \ z_{t,2} = \mu_{\phi}(x_{t,2}), \ldots$
- 4. Compute **average** value of codes of all samples with target characteristic:  $z_{t,\text{avg}} = average(z_{t,1}, z_{t,2}, ...)$
- 5. Create **new z** code by **interpolation** E.g.  $z=z_1+lpha(z_{t,\mathrm{avg}}-z_1)$
- **6. Decode z** with decoder.

Possible with more than 1 target features, similarly to algo on Slide 7.

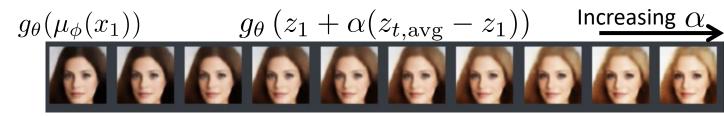


Image from: Steven Flores (link)

#### **Requirement:**

\*Need\* to know which data have the target characteristic (e.g. blonde hair)

#### Altering specific features of data with basic Auto-Encoder

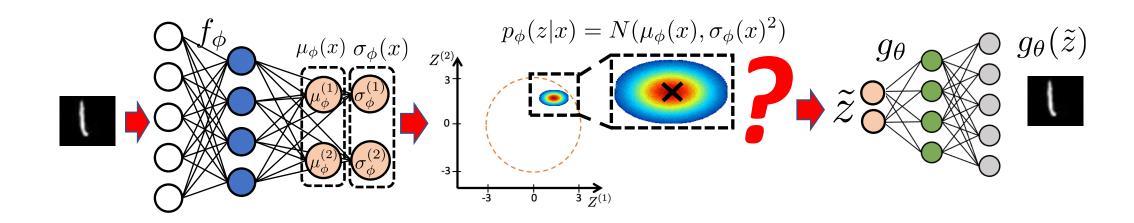
The same procedure can be done via a basic (deterministic) Auto-Encoder.

What issues do you expect and why?

#### Using VAEs for Compression and Reconstruction

After a VAE is trained, we may consider using it for compression and reconstruction.

Q: If we want **the best possible reconstruction of x, which code z** should we give as input to the decoder?

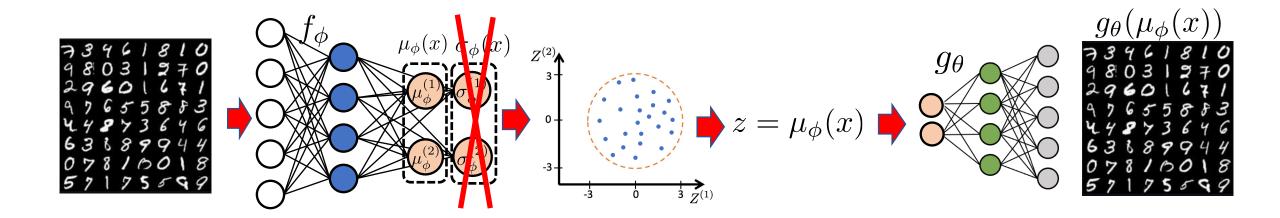


A: The predicted mean  $\mu_{\phi}(x)$  by the encoder. This is the value of z that is most likely to be the correct encoding of x according to encoder.

#### Using VAEs for Compression and Reconstruction

After a VAE is trained, we may consider using it for compression and reconstruction.

To get the best possible reconstruction from a VAE, we simply decode  $z=\mu_\phi(x)$  . We do not use the predicted standard deviation, nor sample.



#### Reconstruction with VAE vs basic AE

**VAE's** capacity is used to optimize **both reconstruction and regularization** losses.

These two losses have **competing** goals!

Therefore its reconstructions may not be as good as those from a basic AE of similar capacity.

It is not what VAE is made for!



From: Steven Flores, Variational Autoencoders for Image Generation

#### In this video:

What we can use VAEs for:

- Generation of new data points
- Modifying data via interpolating between 2 inputs
- Modifying specific feature of an input

What VAE is not ideal for:

Compression => Reconstruction

#### Next weeks:

- Generative Adversarial Networks
- Probabilistic derivation of VAEs (non-assessed, optional, if time allows)

## Thank you very much