

Image from: <http://www.kirrk.com/modularity/wp-content/uploads/2009/12/EncapsulatingDesign1.jpg>

Example of Hill Climbing Application: Software Module Clustering (Problem Formulation)

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Hill Climbing Applications

Hill-Climbing is applicable to any optimisation problem, but its success depends on the shape of the objective function for the problem instance in hands.

Simple algorithm — not difficult to implement.
Could be attempted first to see if the retrieved solutions are good enough, before a more complex algorithm is investigated.

Applications

- Hill-climbing has been successfully applied to software module clustering.
- Software Module Clustering:
 - Software is composed of several units, which can be organised into modules.
 - Well modularised software is easier to develop and maintain.
 - As software evolves, modularisation tends to degrade.

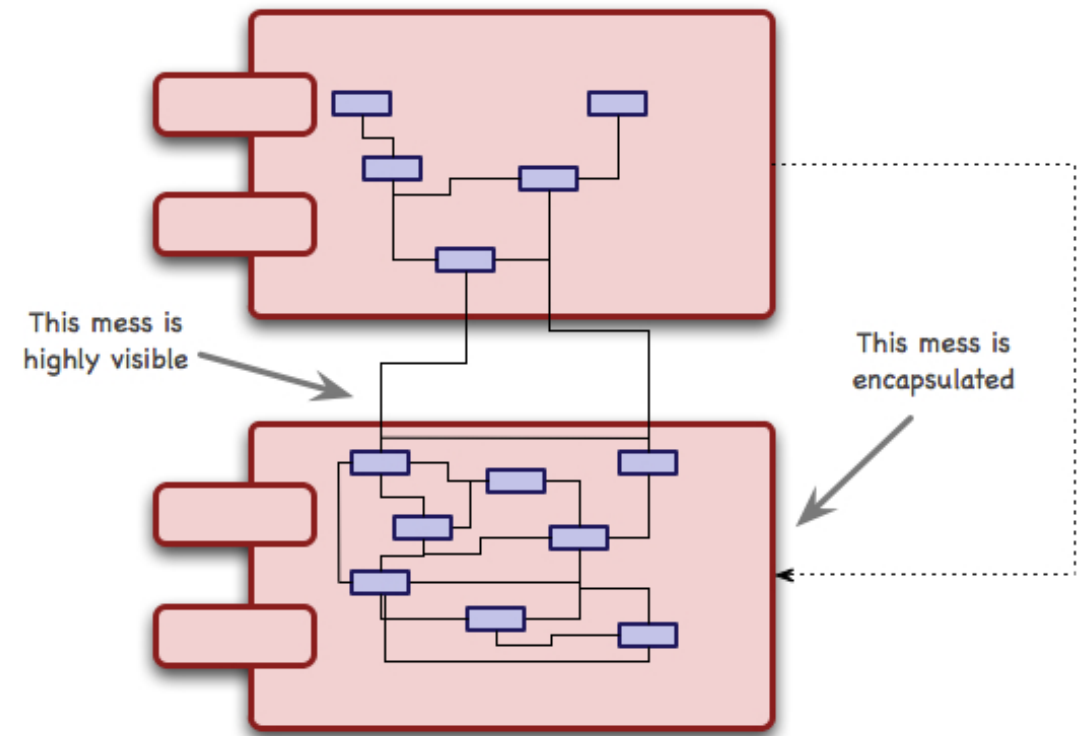


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Problem: **find** an allocation of units into modules that **maximises** the quality of modularisation.

Applying Hill-Climbing (and Simulated Annealing)

- We need to specify:
 - Optimisation problem formulation:
 - Design variable and search space
 - Constraints
 - Objective function
 - Algorithm-specific operators:
 - Representation.
 - Initialisation procedure.
 - Neighbourhood operator.
 - Strategy to deal with constraints, e.g.:
 - Representation, initialisation and neighbourhood operators that ensure only feasible solutions to be generated.
 - Modification in the objective function.

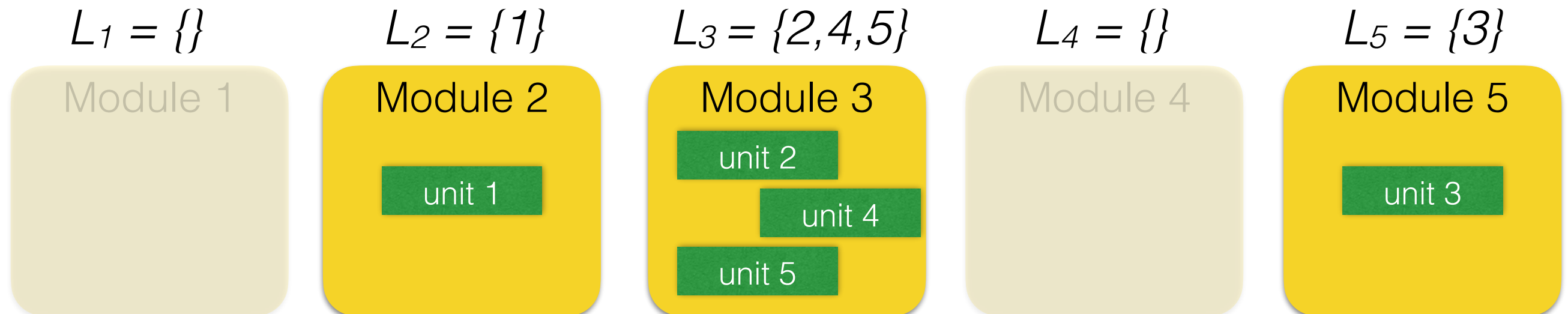
Formulation Optimisation Problems

- **Design variables** represent a candidate solution.
 - Design variables define the **search space** of candidate solutions.
- **Objective function** defines our goal.
 - Can be used to evaluate the quality of solutions.
 - Function to be optimised (maximised or minimised).
- [Optional] Solutions must satisfy certain **constraints**.

Design Variable

Design variable: allocation of units into modules.

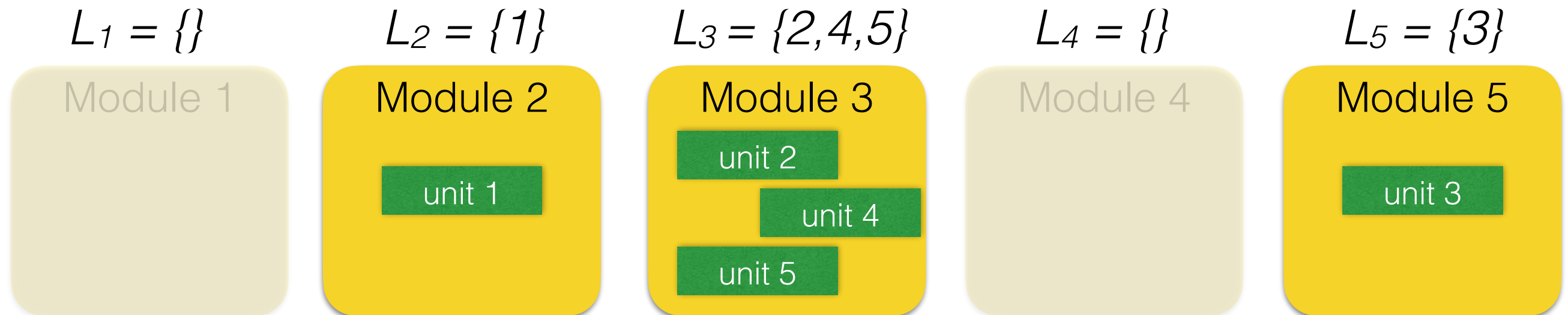
- Consider that we have N units, identified by natural numbers in $\{1, 2, \dots, N\}$.
- This means that we have at most N modules.
- Our design variable is a list L of N modules, where each module L_i , $i \in \{1, 2, \dots, N\}$, is a set containing a minimum of 0 and a maximum of N units.



Design Variable

Design variable: allocation of units into modules.

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Search space: all possible allocations.

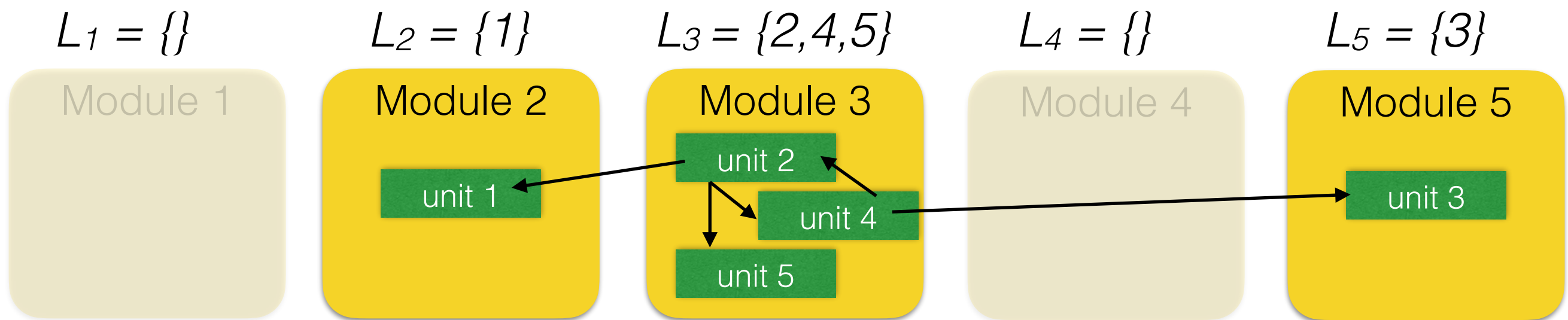
Constraints and Objective Function

Constraints: N/A

Objective function: quality of modularisation (to be maximised).

How to compute quality?

What does good quality mean?



A unit can make use of (depend on) another unit — this information can be retrieved from the current source code being refactored.

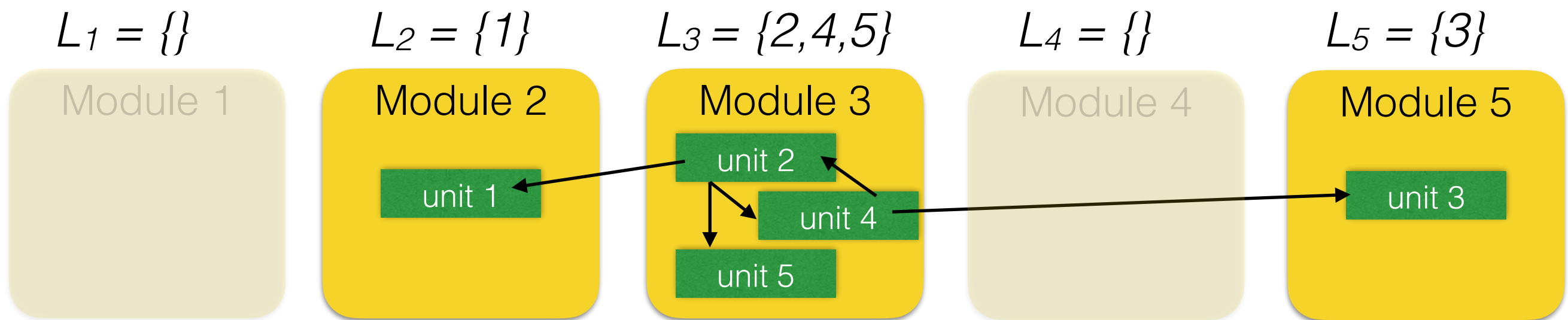
Constraints and Objective Function

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Lots of connections inside a module (high cohesion) and few connections between modules (low coupling).

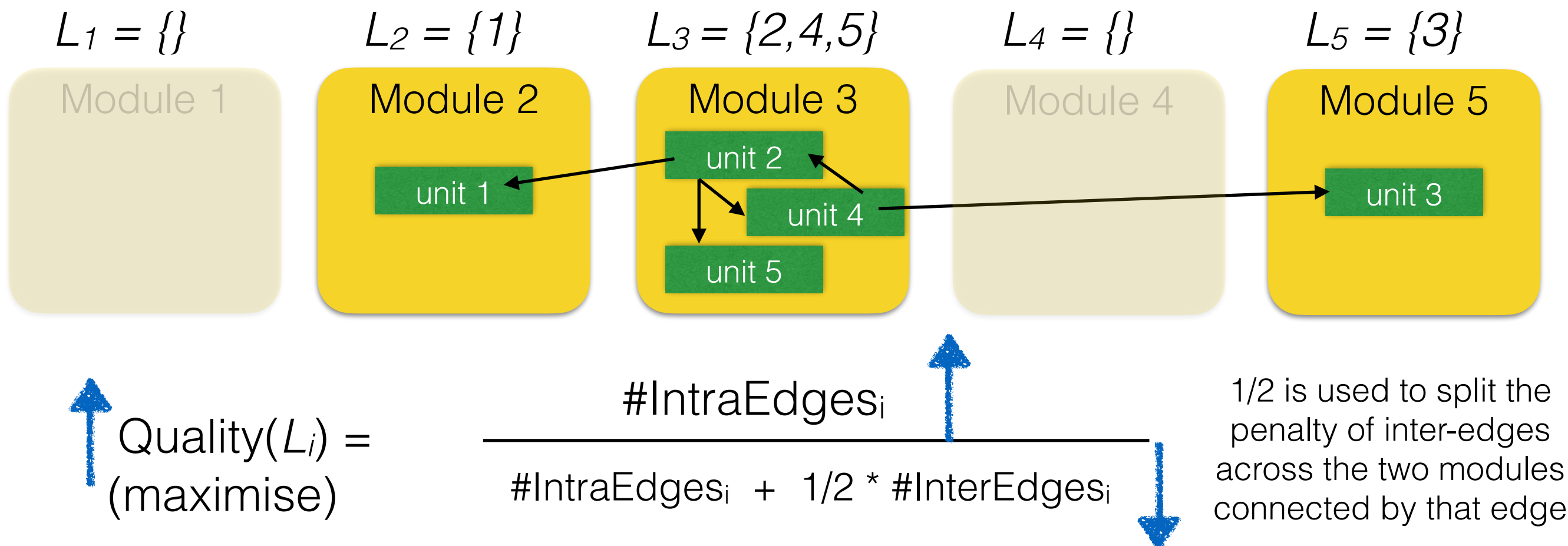
Quality of a Module L_i

Constraints: N/A

Objective function: quality of modularisation (to be maximised).

How to compute quality?

What does good quality mean?



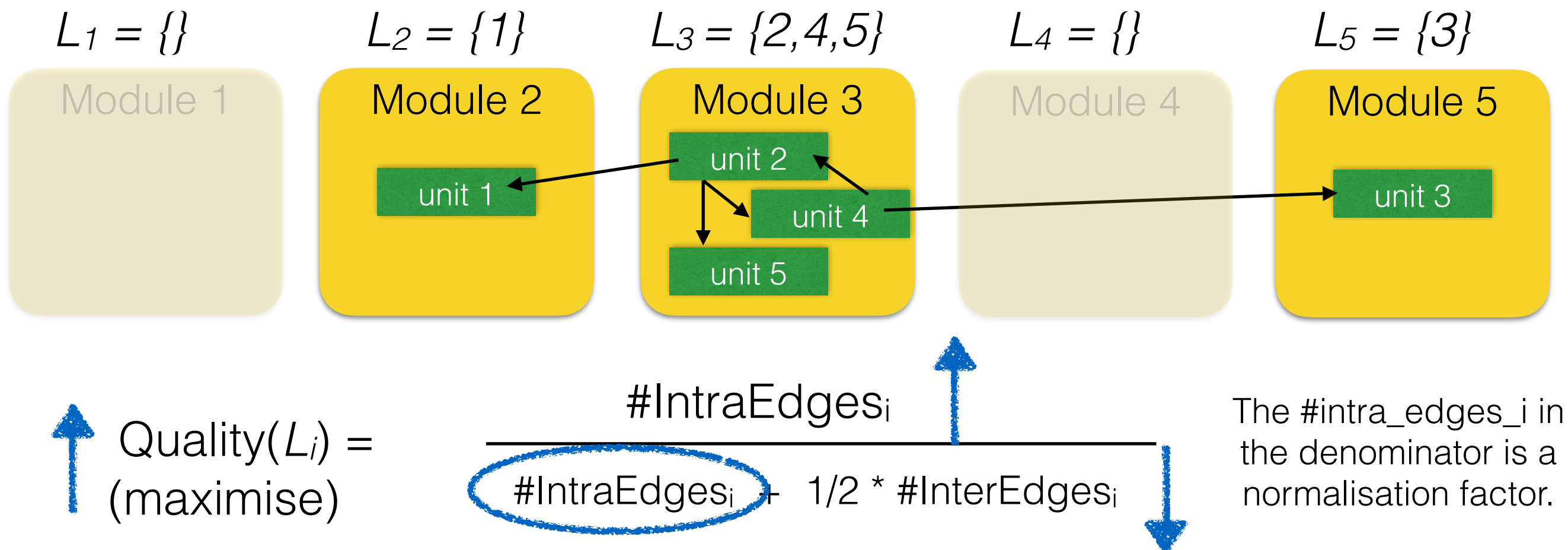
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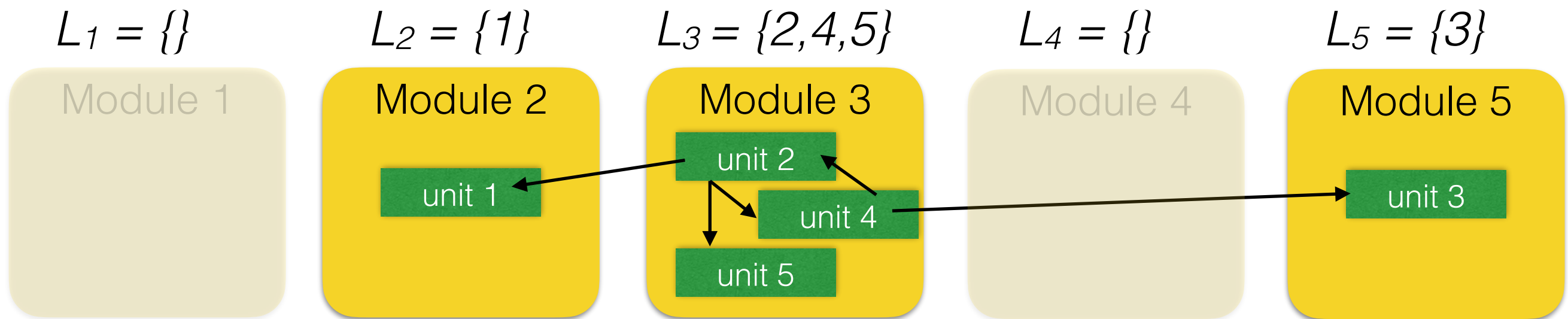
Intra Edges

Constraints: N/A

Objective function: quality of modularisation (to be maximised).

How to compute quality?

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$$\#IntraEdges_i = \sum_{j=1}^{size(L_i)} \sum_{j'=1}^{size(L_i)} D_{L_{ij}, L_{ij'}} \quad D_{a,b} = \begin{cases} 1, & \text{if unit } a \text{ depends on unit } b \\ 0, & \text{otherwise (incl. diagonal)} \end{cases}$$

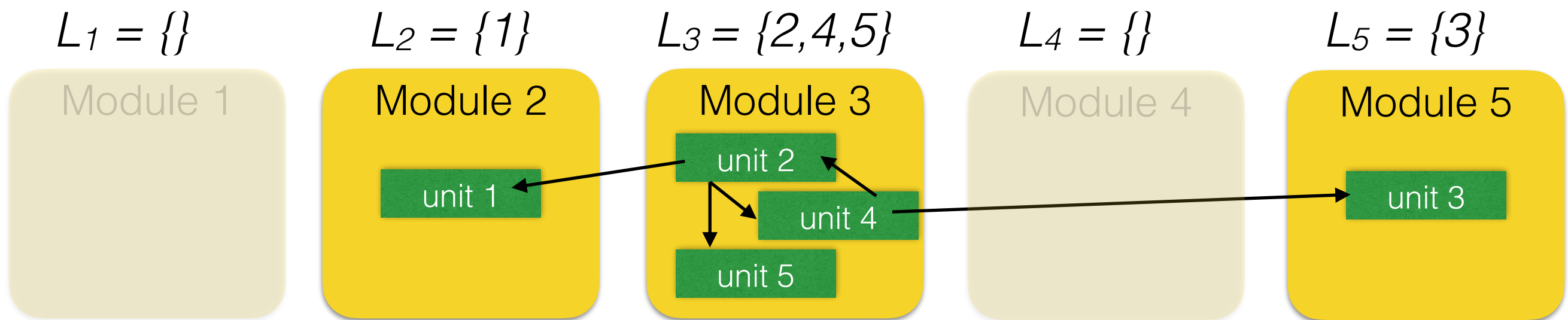
Inter Edges

Constraints: N/A

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$$\#InterEdges_i = \sum_{j=1}^{size(L_i)} \sum_{i' \in \{1,2,\dots,N\} | i' \neq i} \sum_{j'=1}^{size(L_{i'})} (D_{L_{ij}, L_{i'j'}} + D_{L_{i'j'}, L_{ij}})$$

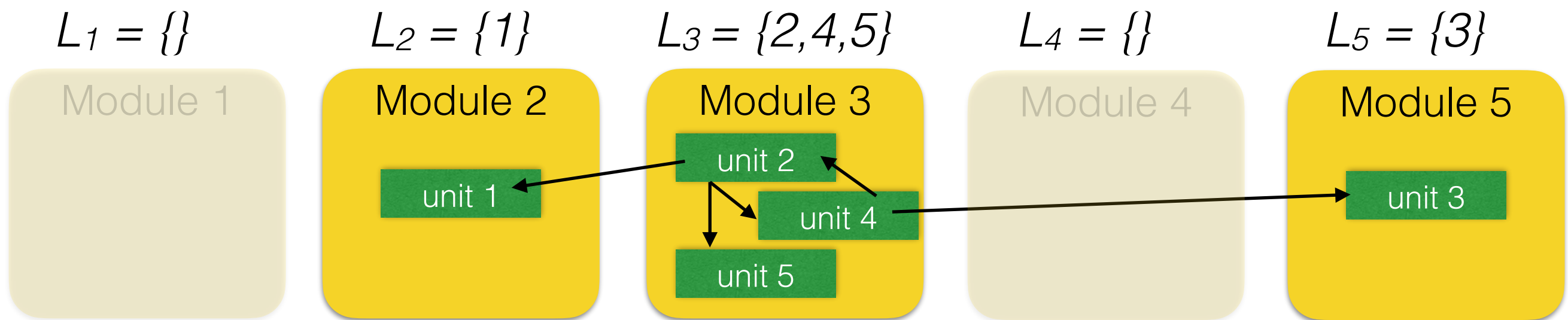
Quality of a Module L_i

Constraints: N/A

Objective function: quality of modularisation (to be maximised).

How to compute quality?

What does good quality mean?



$$\text{Quality}(L_i) = \frac{\# \text{IntraEdges}_i}{\# \text{IntraEdges}_i + 1/2 * \# \text{InterEdges}_i}$$

(maximise)

This is the quality of a **single** module.

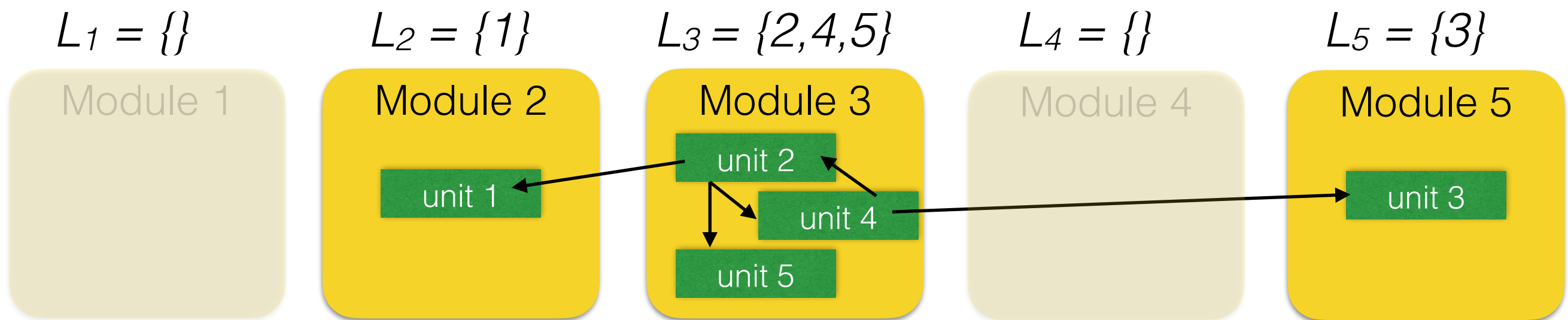
Quality of a Solution L

Constraints: N/A

Objective function: quality of modularisation (to be maximised).

How to compute quality?

What does good quality mean?



Quality(L) = sum of the qualities of the non-empty modules
(maximise)

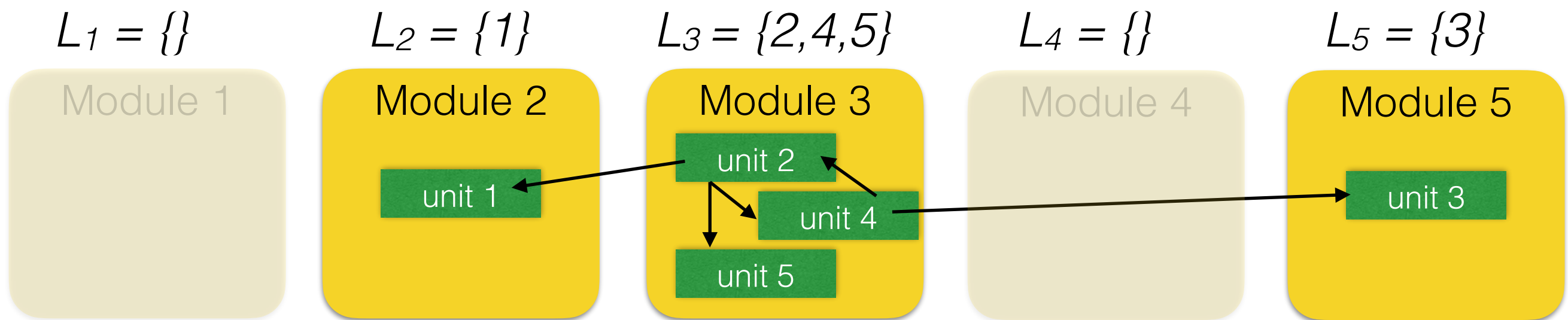
Quality of a Solution L

Constraints: N/A

Objective function: quality of modularisation (to be maximised).

How to compute quality?

What does good quality mean?



$$\uparrow \text{Quality}(L) = \sum_{\substack{i \in \{1,2,\dots,N\} \\ L_i \neq \{\}}} \text{Quality}(L_i) \uparrow$$

(maximise)

Problem Formulation

Hill-Climbing (assuming maximisation)

1. current_solution = generate initial solution randomly
2. Repeat:
 - 2.1 generate neighbour solutions (differ from current solution by a single element)
 - 2.2 best_neighbour = get highest quality neighbour of current_solution
 - 2.3 If $\text{quality}(\text{best_neighbour}) \leq \text{quality}(\text{current_solution})$
 - 2.3.1 Return current_solution
 - 2.4 current_solution = best_neighbour

Until a maximum number of iterations

Design variable —>
what is a candidate solution for us?

Problem Formulation

Hill-Climbing (assuming maximisation)

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Until a maximum number of iterations

Design variable —>
what is a candidate solution for us?

Objective —>
what is quality for us?

Are there any constraints that
need to be satisfied?

Simulated Annealing would also require a problem formulation to be able to solve a problem.

Summary

- Software Module Clustering problem formulation.

Next

- Representation, initialisation and neighbourhood operators.