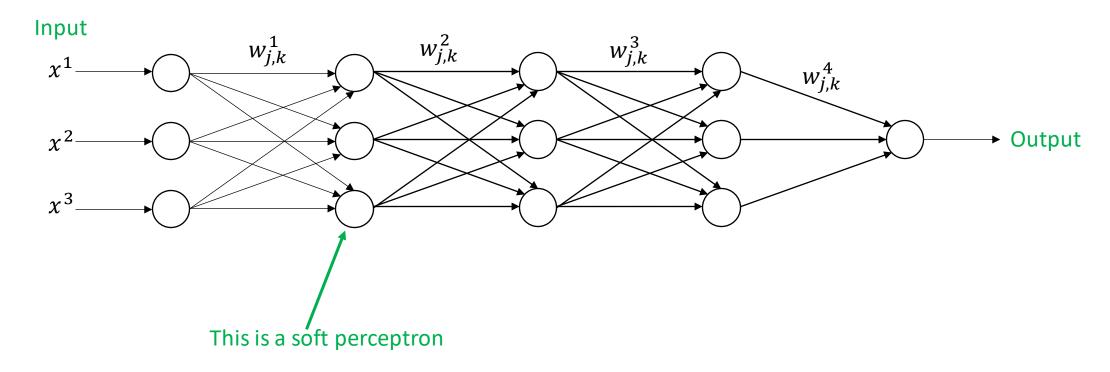
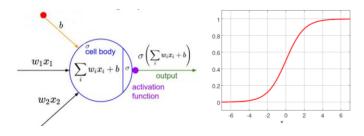
Neural Computation

Neural Networks,
Computation Graphs
and
Backpropagation

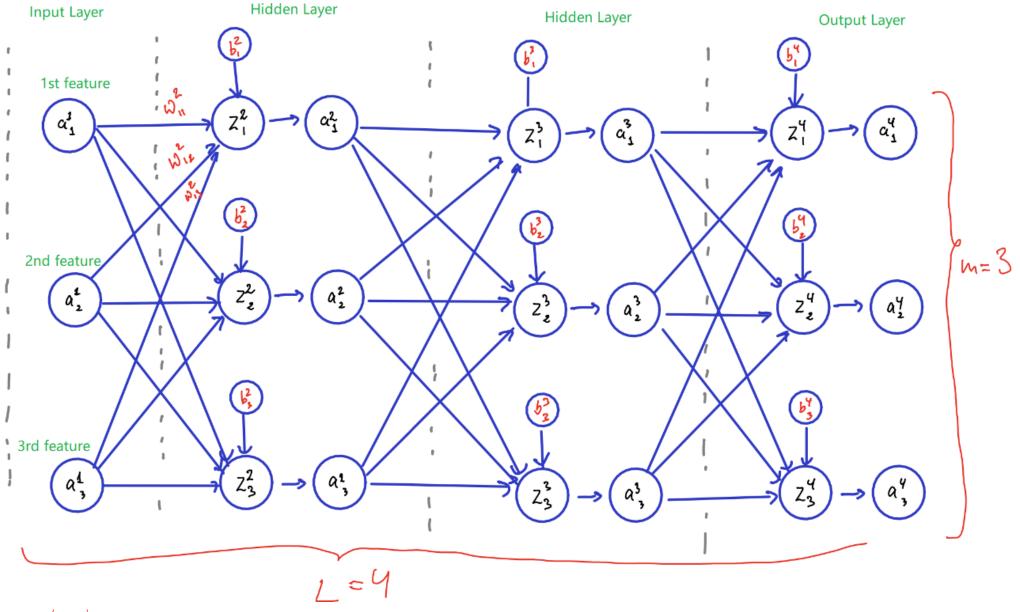
Multi-Layer-Perceptron (MLP) aka Feed-Forward-Net





In the this video:

- Compute derivatives for MLP
- Efficient algorithm (backpropagation)



L: number of layers (superscript 1 is "input layer", superscript L is "output layer")

m: "width" of network (can vary between layers)

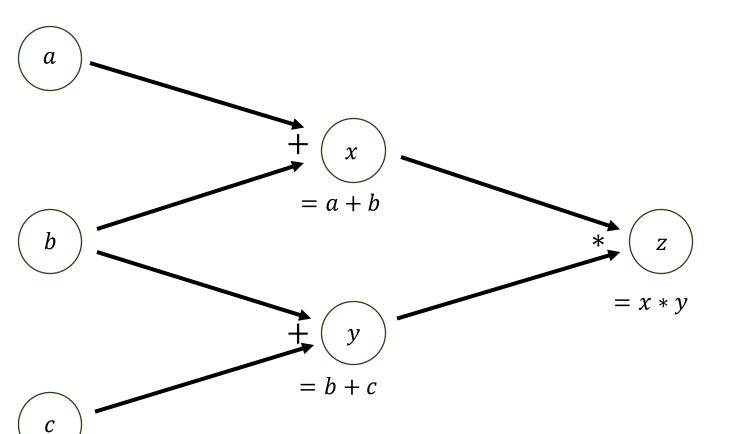
 ω_{jk}^{ℓ} : "weight" of connection between k-th unit in layer $\ell-1$, to j-th unit in layer l

 b_j^ℓ : "bias" of j-th unit in layer I

 $z_j^\ell = \sum_k \omega_{jk}^\ell a_k^{\ell-1} + b_j^\ell$: weighted input to unit j in layer ℓ

 $a_j^\ell = \sigma(z_j^\ell)$: "activation" of unit j in layer ℓ , where σ is an "activation function"

Computation Graphs



$$z = (a+b) * (b+c)$$

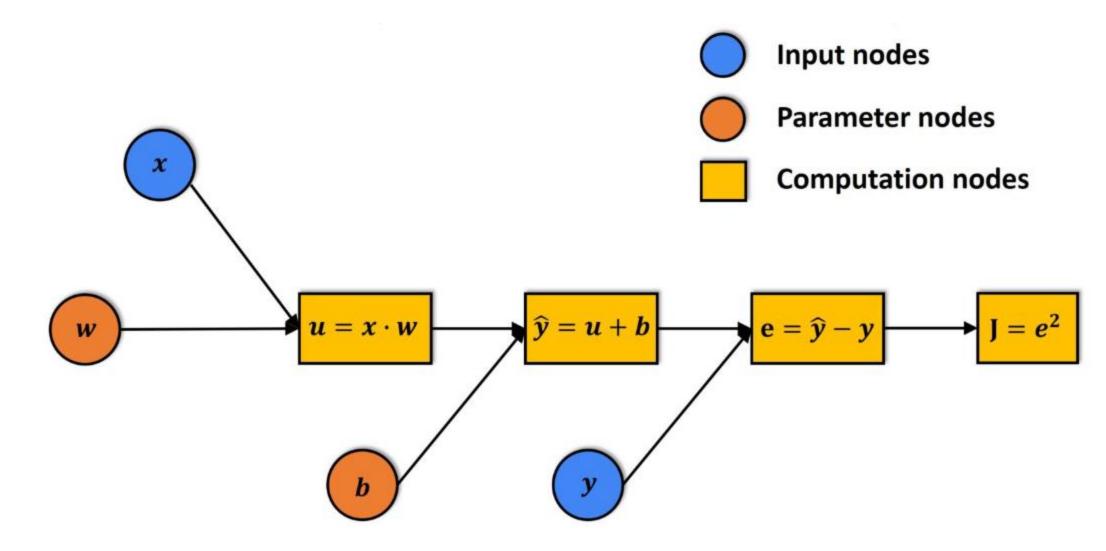
Directed acyclic graph Nodes:

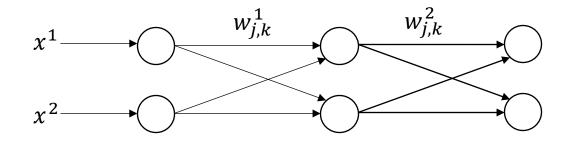
Inputs, outputs or intermediate results

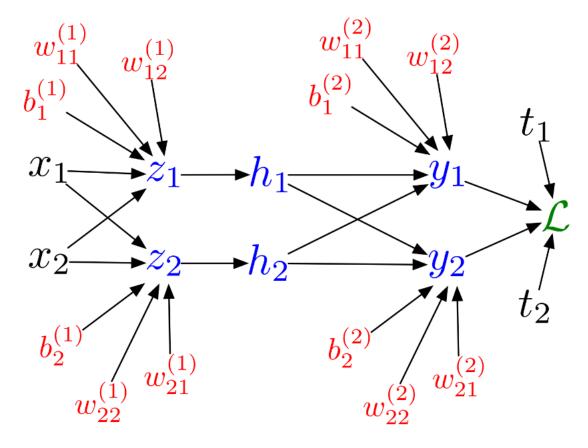
Edges:

• Indicate computation

Computation Graph for Linear Regression







Roger Grosse: CSC 311 Spring 2020: Introduction to Machine Learning

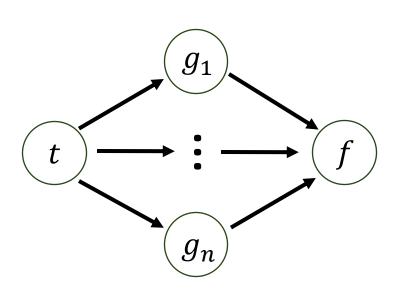
Chain Rule in Computation Graph

Consider

$$f = f(g_1, ..., g_n),$$
 where all
$$g_i = g_i(t) \text{ are functions of } t$$

We can compute the derivative as

$$\frac{\partial f}{\partial t} = \sum_{i=1}^{n} \frac{\partial f}{\partial g_i} \frac{\partial g_i}{\partial t}$$



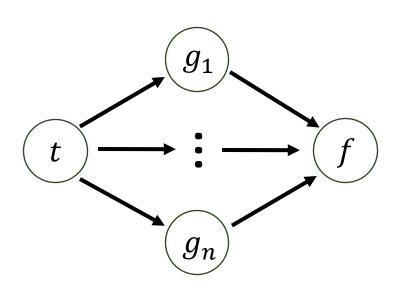
Chain Rule in Computation Graph

Consider

$$f=f(g_1,\ldots,g_n),$$
 where all $g_i=g_i(t)$ are functions of t (aka successors)

We can compute the derivative as

$$\frac{\partial f}{\partial t} = \sum_{i=1}^{n} \frac{\partial f}{\partial g_i} \frac{\partial g_i}{\partial t}$$



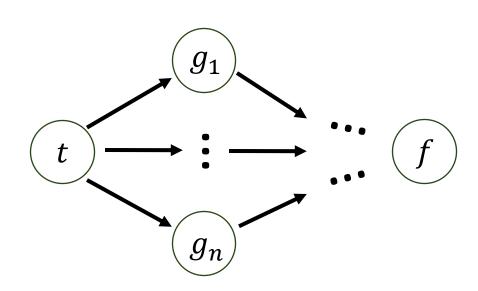
Chain Rule in Computation Graph

Consider

$$f = f(g_1, \dots, g_n),$$
 where all
$$g_i = g_i(t) \text{ are successors of } t$$

We can compute the derivative as

$$\frac{\partial f}{\partial t} = \sum_{i=1}^{n} \frac{\partial f}{\partial g_i} \frac{\partial g_i}{\partial t}$$



Computation Graphs

$$\frac{\partial f}{\partial t} = \sum_{i=1}^{n} \frac{\partial f}{\partial g_i} \frac{\partial g_i}{\partial t}$$

$$\frac{\partial z}{\partial a} = \frac{\partial z}{\partial x} \frac{\partial x}{\partial a}$$

$$\frac{\partial z}{\partial b} = \frac{\partial z}{\partial x} \frac{\partial x}{\partial b} + \frac{\partial z}{\partial y} \frac{\partial y}{\partial b}$$

$$= a + b$$

$$= a + b$$

$$= x * y$$

$$= b + c$$

$$z = (a+b) * (b+c)$$

Computation Graphs

$$\frac{\partial z}{\partial a} = \begin{pmatrix} \frac{\partial z}{\partial x} \end{pmatrix} \frac{\partial x}{\partial a} = (b+c) * 1$$

$$a$$

$$\frac{\partial z}{\partial b} = \begin{pmatrix} \frac{\partial z}{\partial x} \\ \frac{\partial z}{\partial b} \end{pmatrix} \frac{\partial x}{\partial b} + \begin{pmatrix} \frac{\partial z}{\partial y} \\ \frac{\partial y}{\partial b} \\ \frac{\partial z}{\partial c} \end{pmatrix} \frac{\partial x}{\partial b} + \begin{pmatrix} \frac{\partial z}{\partial y} \\ \frac{\partial y}{\partial c} \\ \frac{\partial z}{\partial c} \end{pmatrix} \frac{\partial y}{\partial c} = (a+b) * 1$$

$$= (b+c) * 1 + (a+b) * 1$$

$$= b+c$$

$$\frac{\partial f}{\partial t} = \sum_{i=1}^{n} \frac{\partial f}{\partial g_i} \frac{\partial g_i}{\partial t}$$

$$z = (a+b) * (b+c)$$

- Networks have millions to billions of parameters
- Deriving equation for each parameter is
 - too difficult by hand

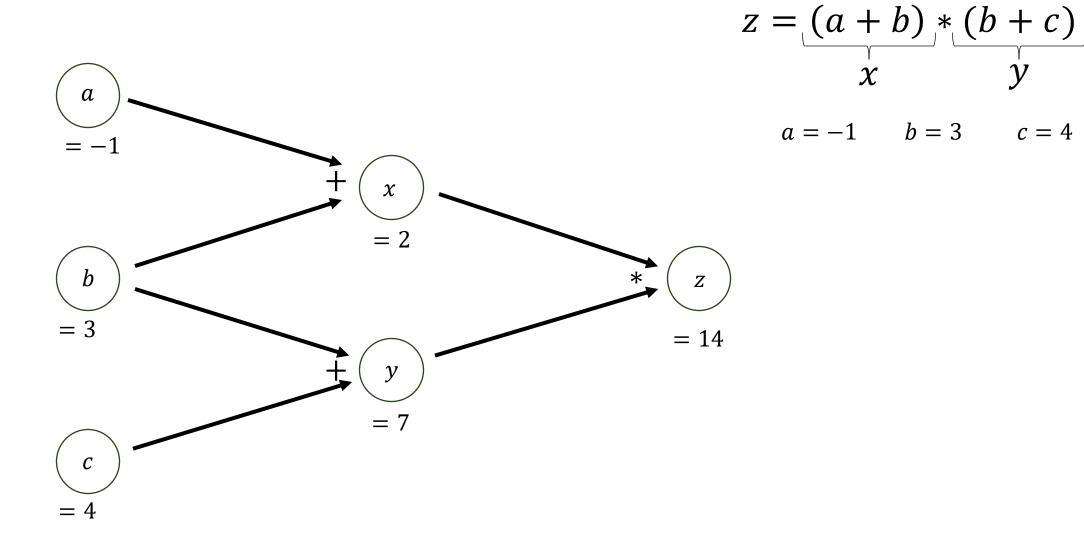
= x * y

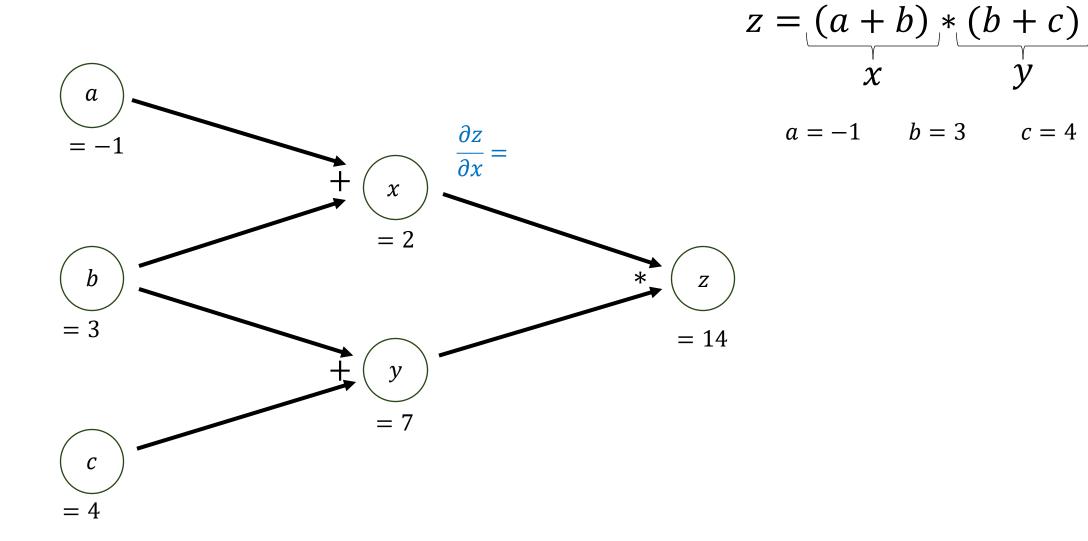
- computationally inefficient
- Need efficient algorithm to compute gradient

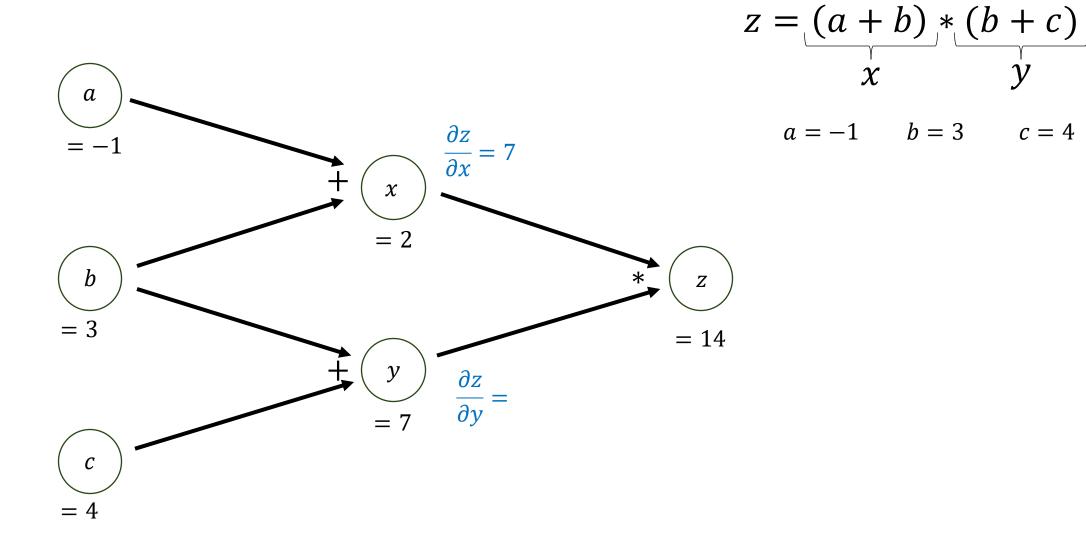
Backpropagation Algorithm

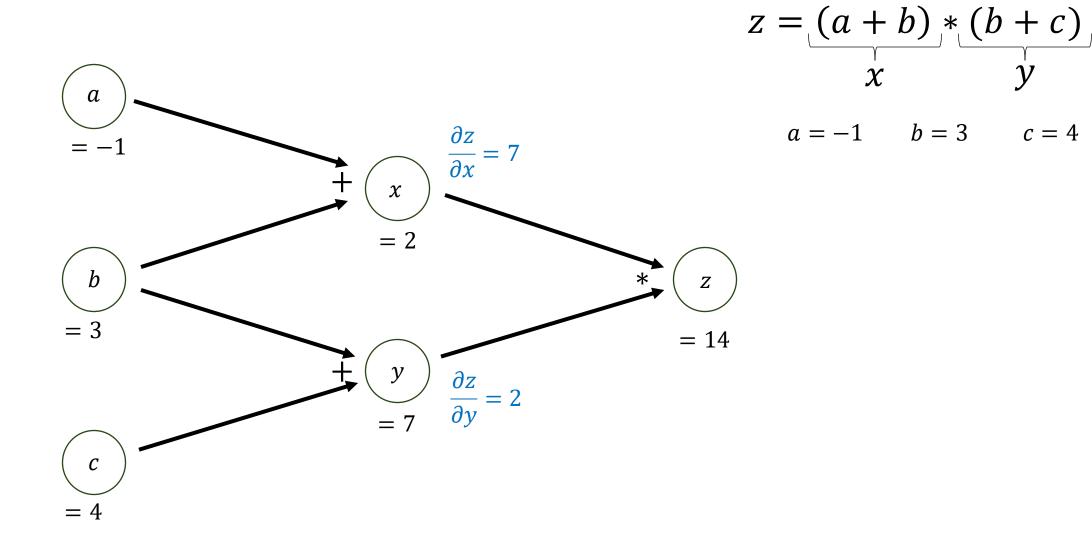
- Forward pass:
 - Move forward through graph to compute all intermediate results
- Backward pass:
 - Move backward through graph compute all gradients
 - Use result from successor nodes.

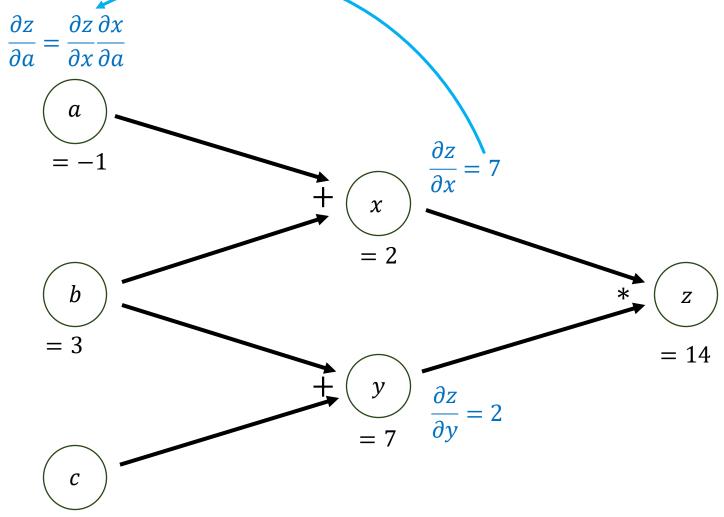
Forward Pass







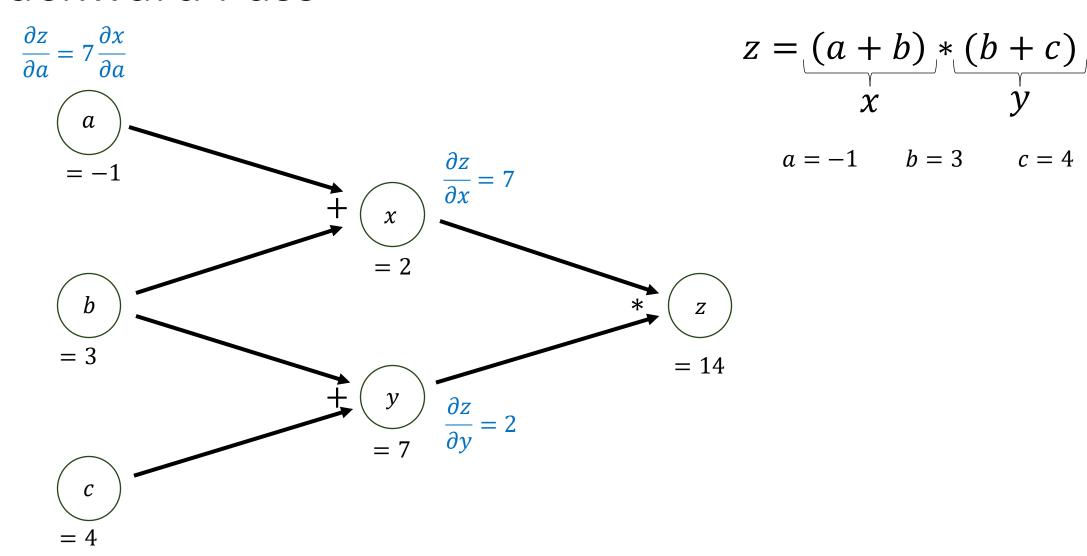


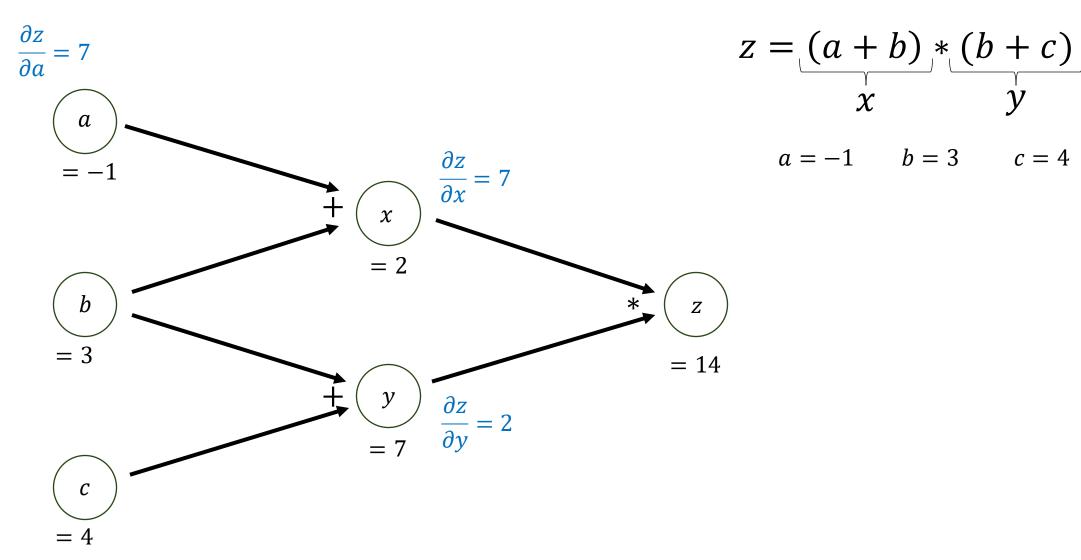


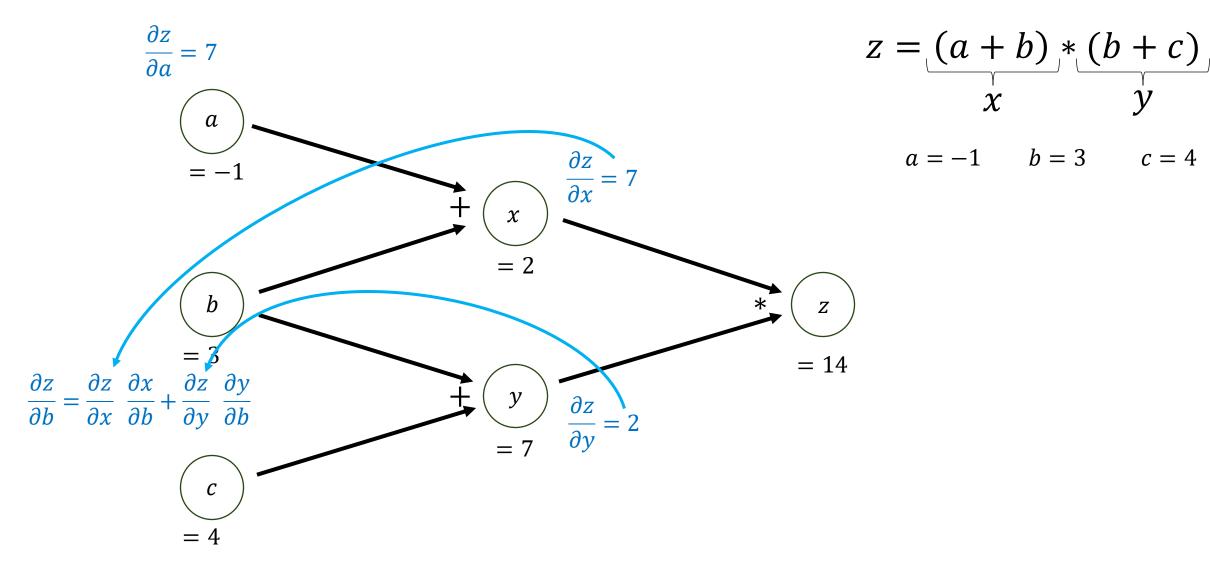
$$z = (a+b) * (b+c)$$

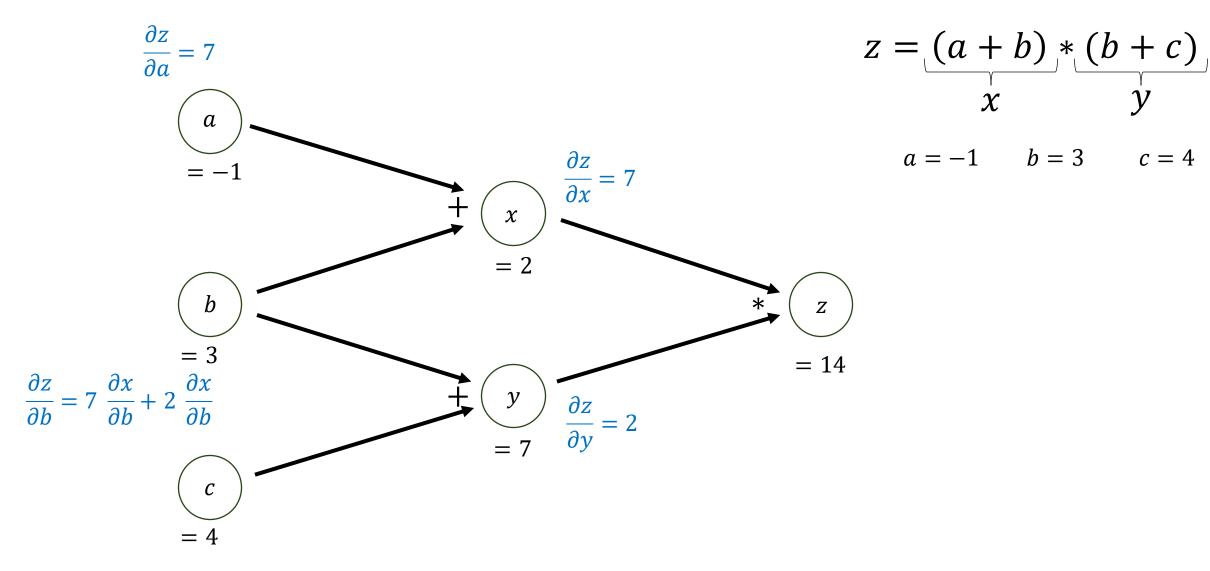
$$x$$

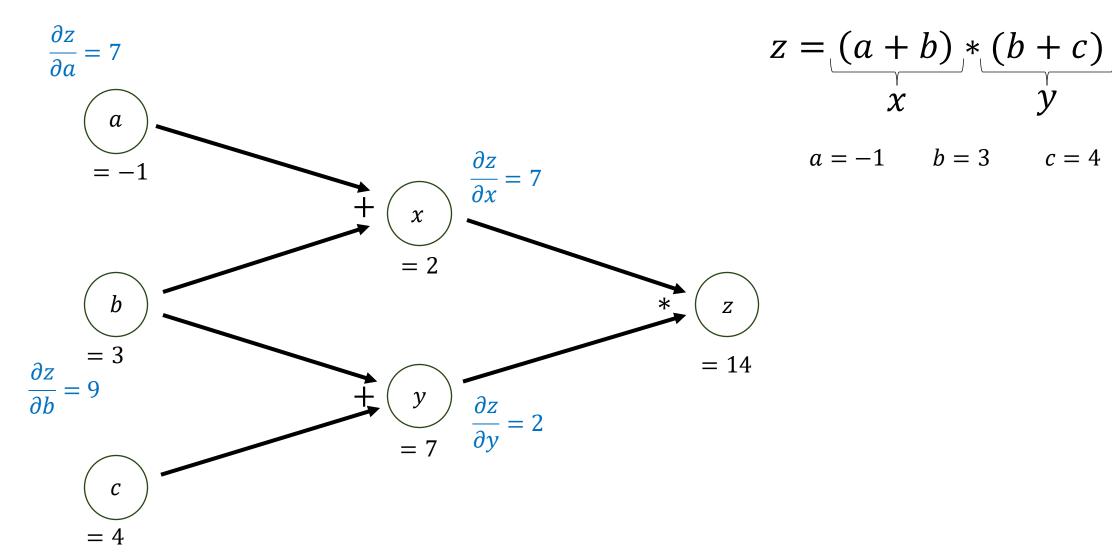
$$a = -1$$
 $b = 3$ $c = 4$

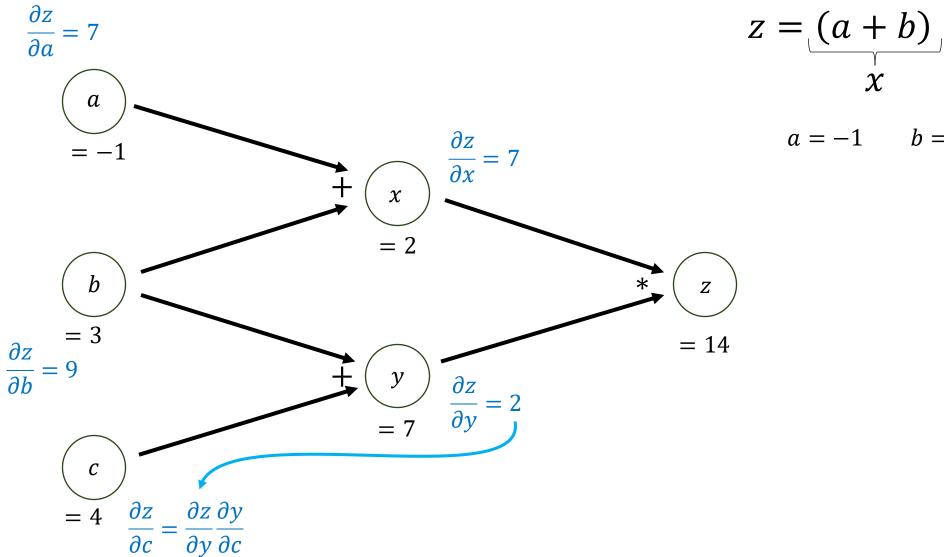








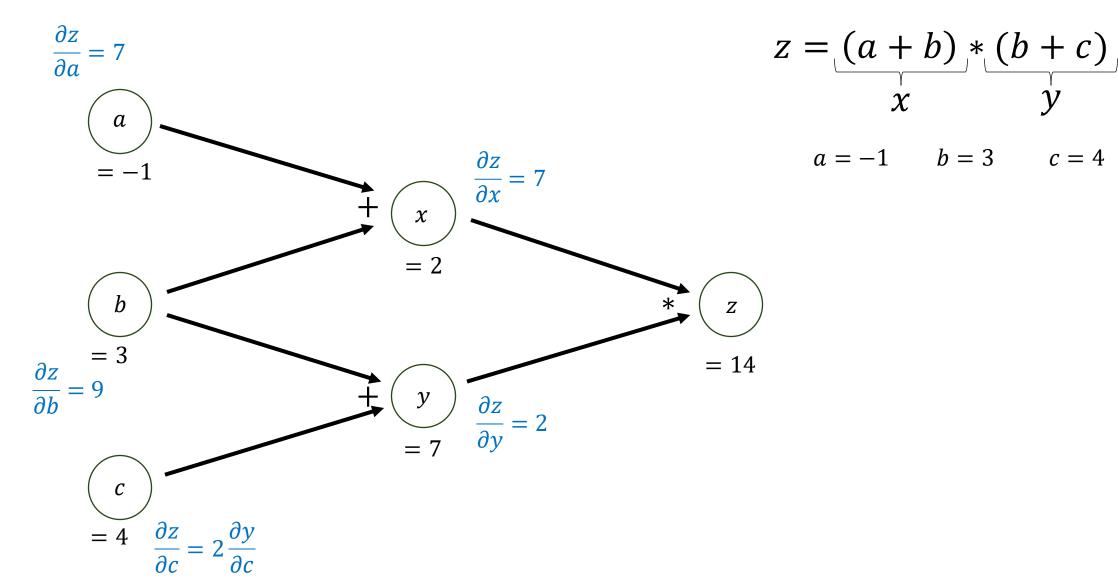


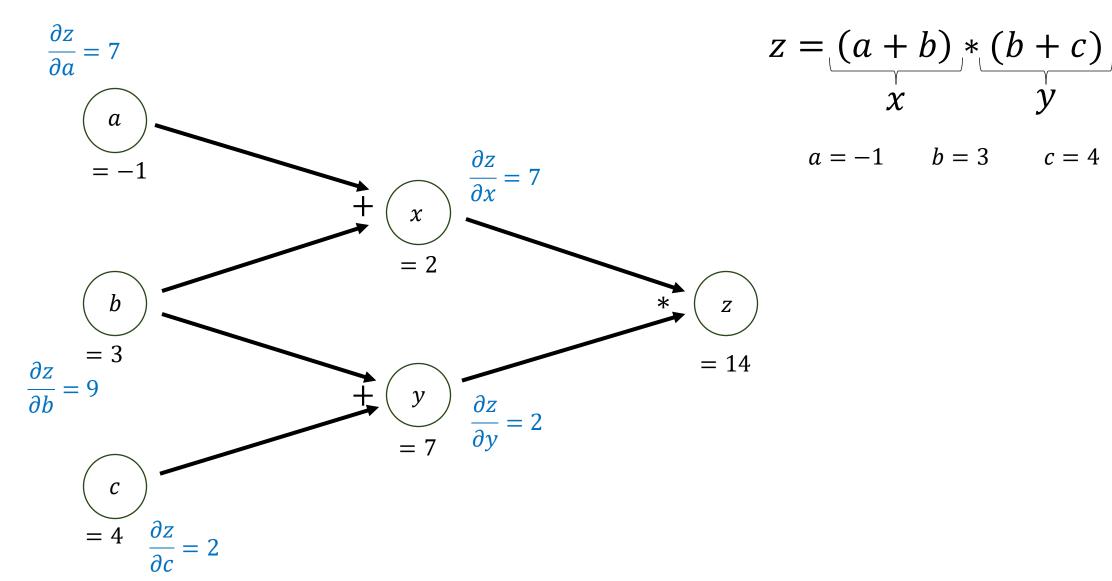


$$z = (a+b) * (b+c)$$

$$x$$

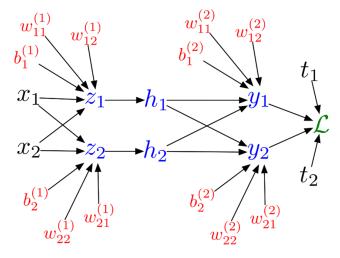
$$a = -1$$
 $b = 3$ $c = 4$





Summary

- Computation Graphs
 - Directed and acyclic
 - Nodes: variables
 - Edges: computation
 - Enable calc. of gradients
- Backpropagation
 - Efficient computation of gradients
 - Forward pass to compute values
 - Backward pass to compute gradients
 - Use successor results



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