

13th European Conference on Evolutionary Computation in Combinatorial Optimisation

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| Email of contact author | mostepha-redouane.khouadjia@inria.fr | | |
| Confirm email | mostepha-redouane.khouadjia@inria.fr | | |
| List of authors | First name | Last name | Affiliation |
| | Mostepha Redouane | Khouadjia | INRIA-Saclay/LRI |
| | Marc | Schoenauer | INRIA-Saclay/LRI |
| | Vincent | Vidal | ONERA |
| | Johann | Dréo | THALES |
| | Pierre | Savéant | THALES |
| | | | |
| | | | |
| | | | |
| Other authors | | | |
| Abstract | <div>Most real-world Planning problems are multi-objective, trying to minimize both the makespan of the solution plan, and some cost of the actions involved in the plan. But most, if not all existing approaches are based on single-objective planners, and use an aggregation of the objectives to remain in the single-objective context. DAE is an evolutionary planner that won the temporal deterministic satisficing track at the last International Planning Competitions (IPC). Like all Evolutionary Algorithms (EA), it can easily be turned into a Pareto-based</div> | | |



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