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$_O riginal_A lgorithm/wu_c omponents_i llus.pngFiguredescribingthethreeplancomponentswhenpushinganobject, aspublish$
$_n avigation_2 010, Wuet.al.describetwoversionsoftheiralgorithm:$
$anaivebutlocallyoptimalbaselineone, andanoptimizedone, builtuponthelogicfoundationofthefirst, butthatlosesitslocalo$
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$_O riginal_A lgorithm/algo1.pngMainloopthatevaluatesallplanscontainingthemanipulationofanobstacleeverytimeanewo$
$_O riginal_A lgorithm/algo2.pngSubroutineforevaluatingallpossibleplansforeachmanipulationdirectionallowedonanobst$
$_n avigation_2 010$
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$_O riginal_A lgorithm/algo3.pngMainloop$
$_O riginal_A lgorithm/algo4.pngSubroutine$
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