

Advance

1.Learning goals

In this lesson, we mainly learn how to control robot advance.

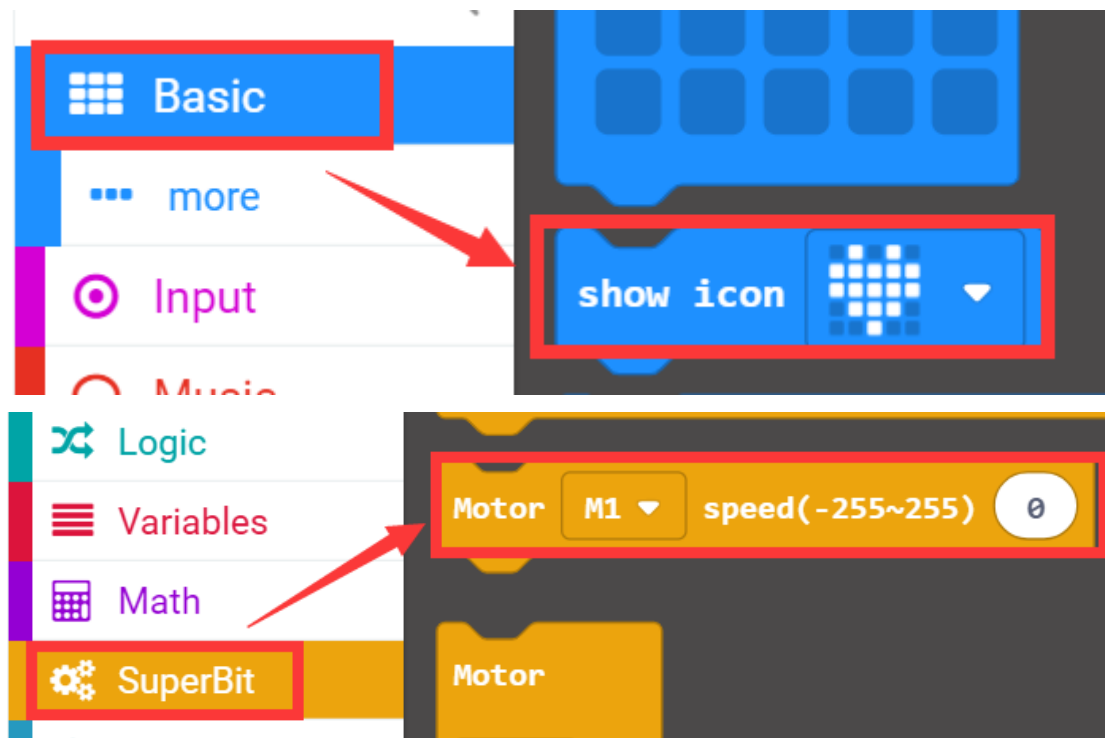
2.Programming method

Mode 1 online programming: First, we need to connect the micro:bit to the computer by USB cable. The computer will pop up a USB flash drive and click on the URL in the USB flash drive: <http://microbit.org/> to enter the programming interface. Add the Yahboom package <https://github.com/lzty634158/SuperBit> to program.

Mode 2 offline programming: We need to open the offline programming software. After the installation is complete, enter the programming interface, click **【New Project】**, add Yahboom package: <https://github.com/lzty634158/SuperBit>, you can program.

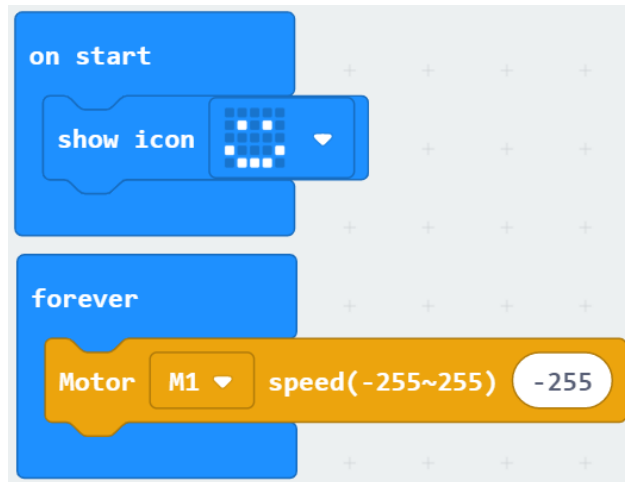
3.Looking for blocks

The following is the location of the building blocks required for this programming.



4.Combine building block

The summary program is shown below:



5.Assembly steps

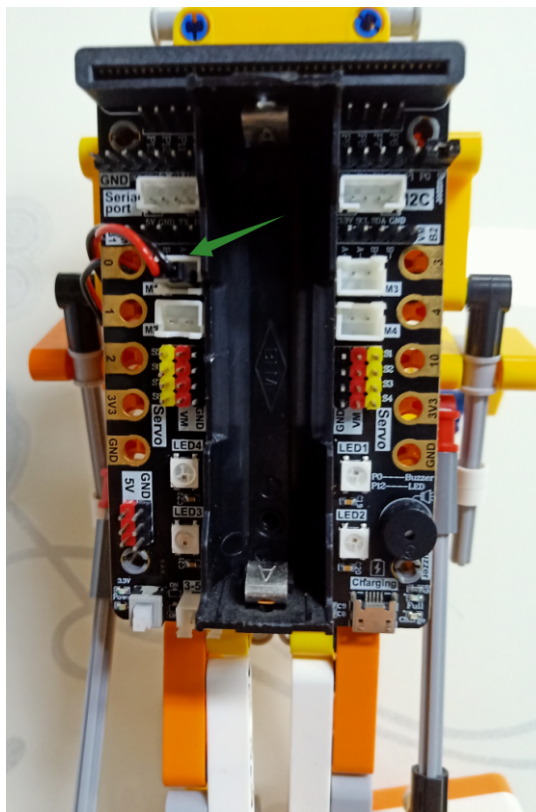
Please refer to **Assembly instructions** folder for building blocks assembly steps.

6.About wiring:

As shown below,

Building block motor connect to M1 interface of super:bit.

The black wiring of the motor is near the battery side.



7. Experimental phenomena

After the program is successfully downloaded, the micro:bit dot matrix will display the smile pattern and the car will advance.