Setting up the Mediapipe environment

1.Instructions before use

This tutorial is applicable to self built images. If you are using the YAHBOOM version of the image, this tutorial can be ignoredThe environment configuration for this tutorial is shown in the following figure

```
😰 🖨 📵 jtop MAXN|CPU 30.9%|GPU 0.0%
jtop 4.2.0 - (c) 2023, Raffaello Bonghi [raffaello@rnext.it]
Website: https://rnext.it/jetson_stats
Platform
                                           Serial Number: [s|XX CLICK TO READ XX
K]Machine: aarch64
                                           Hardware
 System: Linux
                                           Model: NVIDIA Jetson Nano Developer
 Distribution: Ubuntu 18.04 Bionic Beaver 699-level Part Number: 699-13448-000
 Release: 4.9.253-tegra
                                            P-Number: p3448-0000
 Python: 3.6.9
                                            BoardIDs: p3448
                                           Module: NVIDIA Jetson Nano (4 GB ram
Libraries
                                            SoC: tegra210
 CUDA: 10.2.300
                                           CUDA Arch BIN: 5.3
 cuDNN: 8.2.1.32
                                           Codename: Porg
 TensorRT: 8.2.1.8
                                           L4T: 32.7.1
 VPI: 1.2.3
                                           Jetpack: 4.6.1
 Vulkan: 1.2.70
 OpenCV: 4.1.1 with CUDA: NO
                                          Hostname: yahboom
                                          Interfaces
                                           wlan0: 192.168.2.68
                                            docker0: 172.17.0.1
1ALL 2GPU 3CPU 4MEM 5ENG 6CTRL 7INFO Quit
                                                                   (c) 2023, RB
```

2. Environmental construction

- 1. Directly set up bazel and mediapipe-0.8-cp36-cp36m-Linux in the attachment of the environment_ Transfer two files aarch64.whl to Jetson Nano B01
- 2. Run the following command on Jetson Nano B01

```
sudo chmod +x bazel
mv bazel /usr/local/bin
```

Enter the following command: bazel -- version

The results are shown in the figure:

```
jetson@yahboom:~$ bazel --version
bazel 5.4.0- (@non-git)
```

3. install mediapipe

```
pip3 install opencv-contrib-python==3.4.18.65
pip3 install mediapipe-0.8-cp36-cp36m-linux_aarch64.whl
pip3 uninstall opencv-contrib-python #Because Jetson Nano BO1 already comes with
it
```

4. Verify if the installation was successful

```
python3
import mediapipe as mp
```

If there are no errors reported, it indicates successful installation

```
jetson@yahboom:~

jetson@yahboom:~

python 3.6.9 (default, Mar 10 2023, 16:46:00)

[GCC 8.4.0] on linux

Type "help", "copyright", "credits" or "license" for more information.ser

>>> import mediapipe as mp
>>> Import mediapipe as mp
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```