

The difference between yolov4 and yolov4-tiny is: tiny is a compressed version of yolov4, which mainly runs the core version of small computing power cpu. The frame rate of the tiny version on jetso nano will be more than ten times higher than that of yolov4. We recommend using yolov4-tiny.

1. Insall CUDA, OpenCV, cuDNN

Input following command to download git clone https://github.com/AlexeyAB/darknet.git

2.Input following command

cd darknet
sudo vim Makefile #modify Makefile

3. Modify the content as shown below

```
GPU=1
CUDNN=1
OPENCV=1
```

```
File Edit
           Tabs
                Help
GPU=1
CUDNN=1
CUDNN HALF=0
OPENCV=1
OPENMP=0
LIBS0=0
ZED CAMERA=0
ZED_CAMERA_v2_8=0
# set GPU=1 and CUDNN=1 to speedup on GPU
# set CUDNN HALF=1 to further speedup 3 x times (Mixed-precision on Tensor Cores
) GPU: Volta, Xavier, Turing and higher
# set AVX=1 and OPENMP=1 to speedup on CPU (if error occurs then set AVX=0)
# set ZED CAMERA=1 to enable ZED SDK 3.0 and above
# set ZED CAMERA v2 8=1 to enable ZED SDK 2.X
USE CPP=0
DEBUG=0
ARCH= -gencode arch=compute 30,code=sm 30 \
      -gencode arch=compute 35,code=sm 35 \
      -gencode arch=compute 50,code=[sm 50,compute 50] \
```

4. Compile

Input following command in darknet directory.

make -j4

5. Copy the weight files yolov4.weights and yolov4-tiny.weights to the darknet directory.

```
ano@nano-desktop:~/darknet$ ls
                                                                                                                         yolov4-tiny.weights
             cmake
CMakeLists.txt
                                              darknet_video.py
                                                                                                  README .md
3rdparty
                                                                            LICENSE
                                                                                                  results
                                                                                                                         yolov4.weights
                                                                            Makefile
packup
                                              data
                                              image_yolov3.sh
                                                                            net_cam_v3.sh
                                                                                                  scripts
             DarknetConfig.cmake.in
darknet_images.py
                                             image yolov4.sh net cam v4.sh src include obj video yolov3.sh json_mjpeg_streams.sh predictions.jpg video_yolov4.sh
ouild.psl
ouild.sh
    darknet.py
@nano-desktop:~/darknet$
```



6. Test

Yolov4 image detection

./darknet detect cfg/yolov4.cfg yolov4.weights data/dog.jpg
./darknet detector test cfg/coco.data cfg/yolov4.cfg yolov4.weights data/dog.jpg

Yolov4-tiny image detection

./darknet detect cfg/yolov4-tiny.cfg yolov4-tiny.weights data/dog.jpg
./darknet detector test cfg/coco.data cfg/yolov4-tiny.cfg yolov4-tiny.weights
data/dog.jpg

Change the detection threshold

By default, YOLO only displays detected objects with a confidence of .25 or higher.

You can modify this setting with the following command.

For example, to display all detections, you can set the threshold to 0.1.

./darknet detect cfg/yolov4-tiny.cfg yolov4-tiny.weights data/dog.jpg -thresh 0.1





Yolov4 video detection

(Users need to to upload the video files to be detected to the data folder)

./darknet detector demo cfg/coco.data cfg/yolov4.cfg yolov4.weights data/123.mp4

Yolov4-tiny video detection

(Users need to to upload the video files to be detected to the data folder)
./darknet detector demo cfg/coco.data cfg/yolov4-tiny.cfg yolov4-tiny.weights
data/xxx.mp4

```
nx@nx-desktop:-/darknet-master$ ./darknet detector demo cfg/coco.data cfg/yolov4.cfg yolov4.weights data/123.mp4 CUDA-version: 10020 (10020), cuDNN: 8.0.0, GPU count: 1

OpenCV version: 4.1.1

Demo

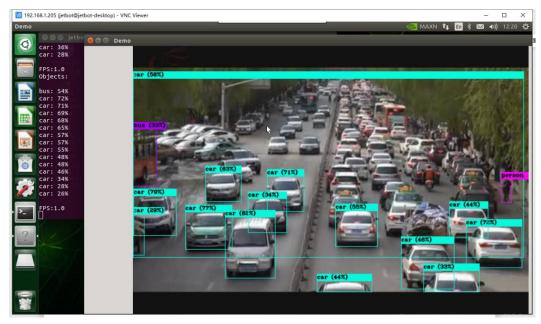
0 : compute_capability = 720, cudnn_half = 0, GPU: Xavier
net.optimized_memory = 0

mini_batch = 1, batch = 1, time_steps = 1, train = 0

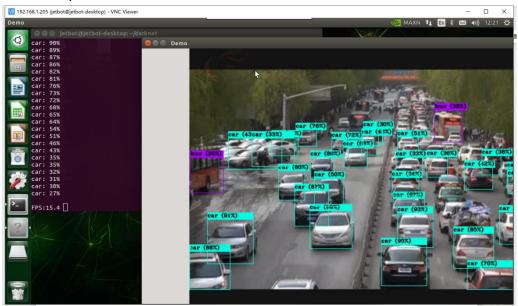
layer filters size/strd(dil) input output
0 conv 32 3 x 3/ 1 608 x 608 x 3 -> 608 x 608 x 32 0.639 8F
1 conv 64 3 x 3/ 2 608 x 608 x 32 -> 304 x 304 x 64 3.407 8F
2 conv 64 1 x 1/ 1 304 x 304 x 64 -> 304 x 304 x 64 0.757 8F
3 route 1 -> 304 x 304 x 64
4 conv 64 1 x 1/ 1 304 x 304 x 64 -> 304 x 304 x 64 0.757 8F
5 conv 32 1 x 1/ 1 304 x 304 x 64 -> 304 x 304 x 64 0.757 8F
5 conv 32 1 x 1/ 1 304 x 304 x 64 -> 304 x 304 x 64 0.757 8F
```

Yolov4 result as shown below.





Yolov4-tiny result as shown below.



Yolov4 camera detection in real time.

./darknet detector demo cfg/coco.data cfg/yolov4.cfg yolov4.weights /dev/video1

Yolov4 camera detection in real time.

./darknet detector demo cfg/coco.data cfg/yolov4-tiny.cfg yolov4-tiny.weights /dev/video1

Tip: Select the number corresponding to the USB camera for the video device.



