## 02 TimeGAN TF2

September 29, 2021

Time-series Generative Adversarial Network (TimeGAN)

## 1 Imports & Settings

[66]: import warnings

Adapted from the excellent paper by Jinsung Yoon, Daniel Jarrett, and Mihaela van der Schaar: Time-series Generative Adversarial Networks,

Neural Information Processing Systems (NeurIPS), 2019.

- Last updated Date: April 24th 2020
- Original code author: Jinsung Yoon (jsyoon0823@gmail.com)

```
warnings.filterwarnings('ignore')

import pandas as pd
import numpy as np
from sklearn.preprocessing import MinMaxScaler
import tensorflow as tf
from pathlib import Path
from tqdm import tqdm

from tensorflow.keras.models import Sequential, Model
from tensorflow.keras.layers import GRU, Dense, RNN, GRUCell, Input
from tensorflow.keras.losses import BinaryCrossentropy, MeanSquaredError
from tensorflow.keras.optimizers import Adam
from tensorflow.keras.callbacks import TensorBoard
from tensorflow.keras.utils import plot_model

import matplotlib.pyplot as plt
import seaborn as sns
```

```
[68]: gpu_devices = tf.config.experimental.list_physical_devices('GPU')
if gpu_devices:
    print('Using GPU')
    tf.config.experimental.set_memory_growth(gpu_devices[0], True)
else:
    print('Using CPU')
```

```
Using CPU
```

```
[69]: sns.set_style('white')
```

## 2 Experiment Path

```
[5]: results_path = Path('time_gan')
    if not results_path.exists():
        results_path.mkdir()

[6]: experiment = 0

[7]: log_dir = results_path / f'experiment_{experiment:02}'
    if not log_dir.exists():
        log_dir.mkdir(parents=True)

[8]: hdf_store = results_path / 'TimeSeriesGAN.h5'
```

## 3 Prepare Data

#### 3.1 Parameters

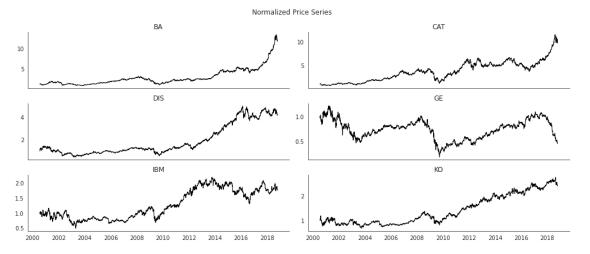
## 3.2 Plot Series

[12]: select\_data()

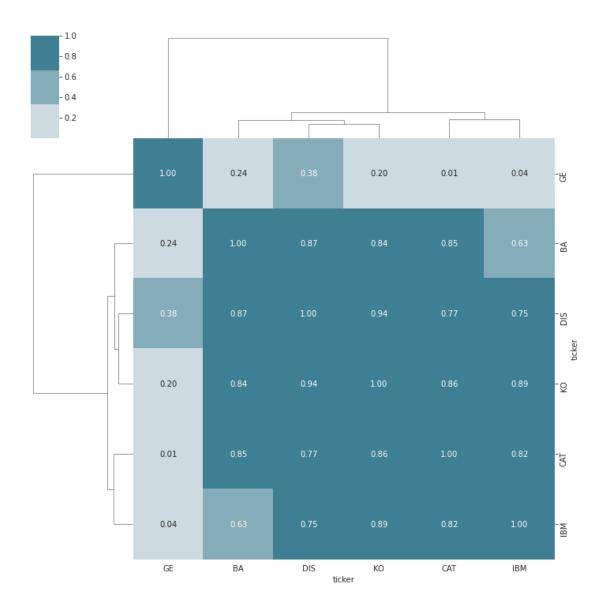
```
rot=0,
lw=1,
color='k')

for ax in axes.flatten():
    ax.set_xlabel('')

plt.suptitle('Normalized Price Series')
plt.gcf().tight_layout()
sns.despine();
```



## 3.3 Correlation



## 3.4 Normalize Data

```
[15]: scaler = MinMaxScaler()
scaled_data = scaler.fit_transform(df).astype(np.float32)
```

## 3.5 Create rolling window sequences

```
[16]: data = []
    for i in range(len(df) - seq_len):
        data.append(scaled_data[i:i + seq_len])

        n_windows = len(data)
```

#### 3.6 Create tf.data.Dataset

#### 3.7 Set up random series generator

```
[18]: def make_random_data():
    while True:
        yield np.random.uniform(low=0, high=1, size=(seq_len, n_seq))
```

We use the Python generator to feed a tf.data.Dataset that continues to call the random number generator as long as necessary and produces the desired batch size.

## 4 TimeGAN Components

The design of the TimeGAN components follows the author's sample code.

#### 4.1 Network Parameters

```
[20]: hidden_dim = 24
num_layers = 3
```

### 4.2 Set up logger

```
[21]: writer = tf.summary.create_file_writer(log_dir.as_posix())
```

## 4.3 Input place holders

```
[22]: X = Input(shape=[seq_len, n_seq], name='RealData')
Z = Input(shape=[seq_len, n_seq], name='RandomData')
```

#### 4.4 RNN block generator

We keep it very simple and use a very similar architecture for all four components. For a real-world application, they should be tailored to the data.

### 4.5 Embedder & Recovery

## 4.6 Generator & Discriminator

# 5 TimeGAN Training

#### 5.1 Settings

```
[26]: train_steps = 10000 gamma = 1
```

### 5.2 Generic Loss Functions

```
[27]: mse = MeanSquaredError()
bce = BinaryCrossentropy()
```

## 6 Phase 1: Autoencoder Training

### 6.1 Architecture

[29]: autoencoder.summary()

```
Model: "Autoencoder"
```

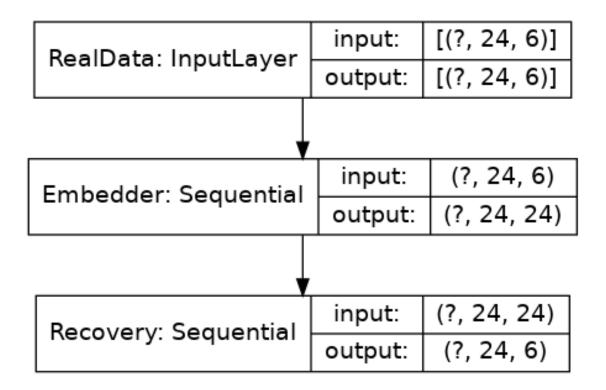
Layer (type)	Output Shape	Param #
RealData (InputLayer)	[(None, 24, 6)]	0
Embedder (Sequential)	(None, 24, 24)	10104
Recovery (Sequential)	(None, 24, 6)	10950

Total params: 21,054 Trainable params: 21,054 Non-trainable params: 0

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```
[30]: plot_model(autoencoder, to_file=(results_path / 'autoencoder.png').as_posix(), show_shapes=True)
```

[30]:



## 6.2 Autoencoder Optimizer

```
[31]: autoencoder_optimizer = Adam()
```

### 6.3 Autoencoder Training Step

```
[32]: Otf.function
   def train_autoencoder_init(x):
        with tf.GradientTape() as tape:
            x_tilde = autoencoder(x)
            embedding_loss_t0 = mse(x, x_tilde)
            e_loss_0 = 10 * tf.sqrt(embedding_loss_t0)

        var_list = embedder.trainable_variables + recovery.trainable_variables
        gradients = tape.gradient(e_loss_0, var_list)
        autoencoder_optimizer.apply_gradients(zip(gradients, var_list))
        return tf.sqrt(embedding_loss_t0)
```

#### 6.4 Autoencoder Training Loop

#### 6.5 Persist model

```
[34]: | # autoencoder.save(log_dir / 'autoencoder')
```

## 7 Phase 2: Supervised training

### 7.1 Define Optimizer

```
[35]: supervisor_optimizer = Adam()
```

### 7.2 Train Step

```
[36]: Otf.function
   def train_supervisor(x):
        with tf.GradientTape() as tape:
            h = embedder(x)
            h_hat_supervised = supervisor(h)
            g_loss_s = mse(h[:, 1:, :], h_hat_supervised[:, :-1, :])

        var_list = supervisor.trainable_variables
        gradients = tape.gradient(g_loss_s, var_list)
        supervisor_optimizer.apply_gradients(zip(gradients, var_list))
        return g_loss_s
```

### 7.3 Training Loop

100% | 10000/10000 [03:04<00:00, 54.31it/s]

### 7.4 Persist Model

```
[38]: # supervisor.save(log_dir / 'supervisor')
```

## 8 Joint Training

#### 8.1 Generator

### 8.1.1 Adversarial Architecture - Supervised

## [40]: adversarial\_supervised.summary()

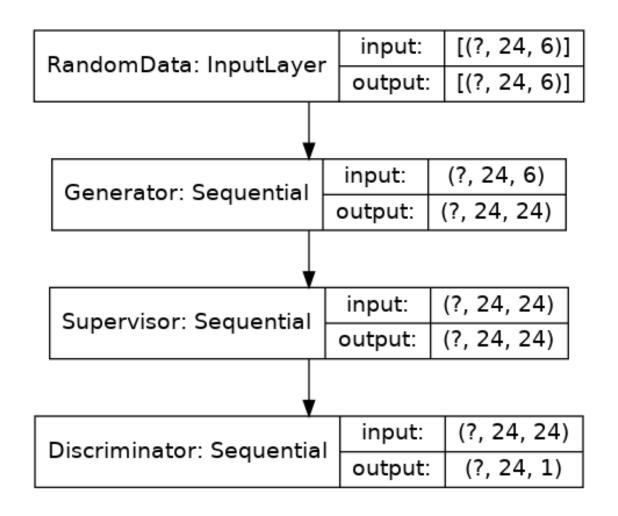
Model: "AdversarialNetSupervised"

Layer (type)	Output Shape	Param #
RandomData (InputLayer)	[(None, 24, 6)]	0
Generator (Sequential)	(None, 24, 24)	10104
Supervisor (Sequential)	(None, 24, 24)	7800
Discriminator (Sequential)	(None, 24, 1)	10825

Total params: 28,729 Trainable params: 28,729 Non-trainable params: 0

```
[41]: plot_model(adversarial_supervised, show_shapes=True)
```

[41]:



### 8.1.2 Adversarial Architecture in Latent Space

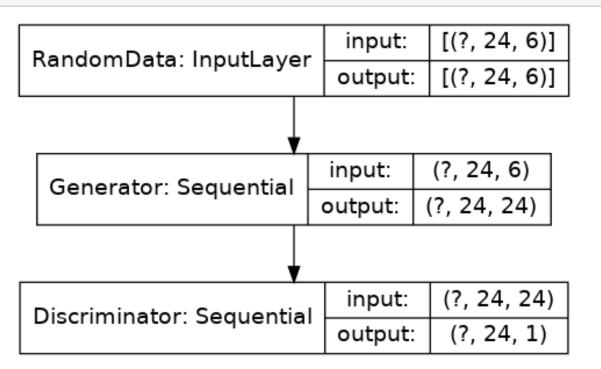
Discriminator (Sequential) (None, 24, 1) 10825

Total params: 20,929 Trainable params: 20,929 Non-trainable params: 0

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[44]: plot\_model(adversarial\_emb, show\_shapes=True)

[44]:



#### 8.1.3 Mean & Variance Loss

[46]: synthetic\_data.summary()

Model: "SyntheticData"

Layer (type)	Output Shape	Param #
RandomData (InputLayer)	[(None, 24, 6)]	0
Generator (Sequential)	(None, 24, 24)	10104

```
Supervisor (Sequential) (None, 24, 24) 7800

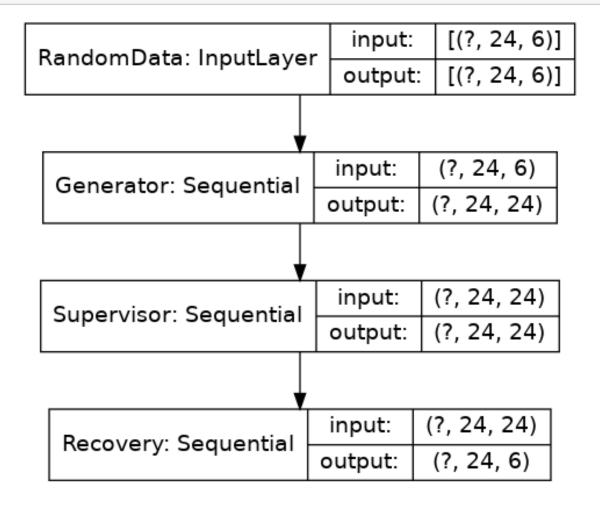
Recovery (Sequential) (None, 24, 6) 10950
```

Total params: 28,854 Trainable params: 28,854 Non-trainable params: 0

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#### [47]: plot\_model(synthetic\_data, show\_shapes=True)

[47]:



```
return g_loss_mean + g_loss_var
```

## 8.2 Discriminator

## 8.2.1 Architecture: Real Data

[50]: discriminator\_model.summary()

Model: "DiscriminatorReal"

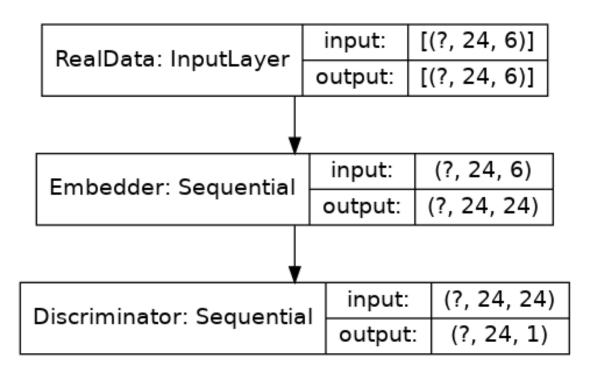
tput Shape 	Param #
None, 24, 6)]	0
one, 24, 24)	10104
one, 24, 1)	10825
	one, 24, 24)

Total params: 20,929 Trainable params: 20,929 Non-trainable params: 0

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[51]: plot\_model(discriminator\_model, show\_shapes=True)

[51]:



## 8.3 Optimizers

```
[52]: generator_optimizer = Adam()
  discriminator_optimizer = Adam()
  embedding_optimizer = Adam()
```

#### 8.4 Generator Train Step

## 8.5 Embedding Train Step

### 8.6 Discriminator Train Step

```
return (discriminator_loss_real +
    discriminator_loss_fake +
    gamma * discriminator_loss_fake_e)
```

```
[56]: @tf.function
    def train_discriminator(x, z):
        with tf.GradientTape() as tape:
            discriminator_loss = get_discriminator_loss(x, z)

        var_list = discriminator.trainable_variables
        gradients = tape.gradient(discriminator_loss, var_list)
        discriminator_optimizer.apply_gradients(zip(gradients, var_list))
        return discriminator_loss
```

## 8.7 Training Loop

```
[57]: step_g_loss_u = step_g_loss_s = step_g_loss_v = step_e_loss_t0 = step_d_loss = 0
      for step in range(train_steps):
          # Train generator (twice as often as discriminator)
         for kk in range(2):
             X = next(real series iter)
             Z_ = next(random_series)
              # Train generator
             step_g_loss_u, step_g_loss_s, step_g_loss_v = train_generator(X_, Z_)
              # Train embedder
             step_e_loss_t0 = train_embedder(X_)
         X_ = next(real_series_iter)
         Z = next(random series)
         step_d_loss = get_discriminator_loss(X_, Z_)
         if step_d_loss > 0.15:
             step_d_loss = train_discriminator(X_, Z_)
         if step % 1000 == 0:
             print(f'{step:6,.0f} | d_loss: {step_d_loss:6.4f} | g_loss_u:__
       f'g loss s: {step g loss s:6.4f} | g loss v: {step g loss v:6.4f}_u
       \rightarrow | e_loss_t0: {step_e_loss_t0:6.4f}')
         with writer.as_default():
             tf.summary.scalar('G Loss S', step_g_loss_s, step=step)
             tf.summary.scalar('G Loss U', step_g_loss_u, step=step)
             tf.summary.scalar('G Loss V', step_g_loss_v, step=step)
             tf.summary.scalar('E Loss TO', step_e_loss_t0, step=step)
             tf.summary.scalar('D Loss', step_d_loss, step=step)
```

```
0 | d_loss: 2.1271 | g_loss_u: 0.6151 | g_loss_s: 0.0003 | g_loss_v: 0.3934
| e_loss_t0: 0.0329
1,000 | d loss: 0.5845 | g loss u: 2.8059 | g loss s: 0.0004 | g loss v: 0.0681
| e loss t0: 0.0094
2,000 | d loss: 1.3358 | g loss u: 1.3916 | g loss s: 0.0001 | g loss v: 0.0490
| e loss t0: 0.0079
3,000 | d loss: 1.2601 | g loss u: 1.0959 | g loss s: 0.0002 | g loss v: 0.0492
| e loss t0: 0.0072
4,000 | d_loss: 1.0254 | g_loss_u: 1.4230 | g_loss_s: 0.0001 | g_loss_v: 0.0293
| e_loss_t0: 0.0067
5,000 | d_loss: 0.9681 | g_loss_u: 1.5861 | g_loss_s: 0.0001 | g_loss_v: 0.0175
| e_loss_t0: 0.0058
6,000 | d_loss: 1.4235 | g_loss_u: 1.3382 | g_loss_s: 0.0001 | g_loss_v: 0.0303
| e loss t0: 0.0052
7,000 | d_loss: 1.3194 | g_loss_u: 1.4435 | g_loss_s: 0.0001 | g_loss_v: 0.0450
| e_loss_t0: 0.0049
8,000 | d_loss: 1.3595 | g_loss_u: 1.4879 | g_loss_s: 0.0001 | g_loss_v: 0.0275
| e_loss_t0: 0.0048
9,000 | d_loss: 1.4149 | g_loss_u: 1.3156 | g_loss_s: 0.0001 | g_loss_v: 0.0771
| e_loss_t0: 0.0043
```

## 8.8 Persist Synthetic Data Generator

```
[58]: synthetic_data.save(log_dir / 'synthetic_data')
```

WARNING:tensorflow:From /opt/conda/envs/ml4t-dl/lib/python3.8/site-packages/tensorflow/python/training/tracking/tracking.py:111:

Model.state\_updates (from tensorflow.python.keras.engine.training) is deprecated and will be removed in a future version.

Instructions for updating:

This property should not be used in TensorFlow 2.0, as updates are applied automatically.

WARNING:tensorflow:From /opt/conda/envs/ml4t-dl/lib/python3.8/site-packages/tensorflow/python/training/tracking/tracking.py:111: Layer.updates (from tensorflow.python.keras.engine.base\_layer) is deprecated and will be removed in a future version.

Instructions for updating:

This property should not be used in TensorFlow 2.0, as updates are applied automatically.

INFO:tensorflow:Assets written to: time\_gan/experiment\_00/synthetic\_data/assets

## 9 Generate Synthetic Data

```
[59]: generated_data = []
for i in range(int(n_windows / batch_size)):
    Z_ = next(random_series)
    d = synthetic_data(Z_)
```

```
generated_data.append(d)
[60]: len(generated_data)
[60]: 35
[61]: | generated_data = np.array(np.vstack(generated_data))
      generated_data.shape
[61]: (4480, 24, 6)
[62]: np.save(log_dir / 'generated_data.npy', generated_data)
     9.1 Rescale
[63]: generated_data = (scaler.inverse_transform(generated_data
                                                  .reshape(-1, n_seq))
                        .reshape(-1, seq_len, n_seq))
      generated_data.shape
[63]: (4480, 24, 6)
     9.2 Persist Data
[64]: with pd.HDFStore(hdf_store) as store:
          store.put('data/synthetic', pd.DataFrame(generated_data.reshape(-1, n_seq),
                                                    columns=tickers))
```

#### 9.3 Plot sample Series

sns.despine()
fig.tight\_layout()

