## 7.vanilla

## September 29, 2021

```
[1]: import sys
     import warnings
    if not sys.warnoptions:
        warnings.simplefilter('ignore')
[2]: import tensorflow as tf
    import numpy as np
    import matplotlib.pyplot as plt
    import seaborn as sns
    import pandas as pd
    from sklearn.preprocessing import MinMaxScaler
    from datetime import datetime
    from datetime import timedelta
    from tqdm import tqdm
    sns.set()
    tf.compat.v1.random.set_random_seed(1234)
[3]: df = pd.read_csv('../dataset/GOOG-year.csv')
    df.head()
[3]:
             Date
                                                           Close
                                                                   Adj Close \
                         Open
                                     High
                                                  Low
    0 2016-11-02 778.200012 781.650024 763.450012 768.700012 768.700012
    1 2016-11-03 767.250000
                               769.950012 759.030029 762.130005 762.130005
    2 2016-11-04 750.659973
                               770.359985 750.560974 762.020020 762.020020
    3 2016-11-07 774.500000
                               785.190002 772.549988 782.520020 782.520020
    4 2016-11-08 783.400024 795.632996 780.190002 790.510010 790.510010
        Volume
    0 1872400
    1 1943200
    2 2134800
    3 1585100
    4 1350800
[4]: minmax = MinMaxScaler().fit(df.iloc[:, 4:5].astype('float32')) # Close index
    df_log = minmax.transform(df.iloc[:, 4:5].astype('float32')) # Close index
```

```
df_log = pd.DataFrame(df_log)
df_log.head()
```

```
[4]: 0
0 0.112708
1 0.090008
2 0.089628
3 0.160459
4 0.188066
```

## 0.1 Split train and test

I will cut the dataset to train and test datasets,

- 1. Train dataset derived from starting timestamp until last 30 days
- 2. Test dataset derived from last 30 days until end of the dataset

So we will let the model do forecasting based on last 30 hours, and we will going to repeat the experiment for 10 times. You can increase it locally if you want, and tuning parameters will help you by a lot.

```
[5]: test_size = 30
simulation_size = 10

df_train = df_log.iloc[:-test_size]
df_test = df_log.iloc[-test_size:]
df.shape, df_train.shape, df_test.shape
```

```
[5]: ((252, 7), (222, 1), (30, 1))
```

```
[6]: class Model:
         def __init__(
             self,
             learning_rate,
             num_layers,
             size,
             size_layer,
             output_size,
             forget_bias = 0.1,
         ):
             def lstm cell(size layer):
                 return tf.nn.rnn_cell.BasicRNNCell(size_layer)
             rnn_cells = tf.nn.rnn_cell.MultiRNNCell(
                 [lstm_cell(size_layer) for _ in range(num_layers)],
                 state_is_tuple = False,
             self.X = tf.placeholder(tf.float32, (None, None, size))
```

```
self.Y = tf.placeholder(tf.float32, (None, output_size))
        drop = tf.contrib.rnn.DropoutWrapper(
            rnn_cells, output_keep_prob = forget_bias
        self.hidden_layer = tf.placeholder(
            tf.float32, (None, num_layers * size_layer)
        self.outputs, self.last_state = tf.nn.dynamic_rnn(
            drop, self.X, initial_state = self.hidden_layer, dtype = tf.float32
        )
        self.logits = tf.layers.dense(self.outputs[-1], output_size)
        self.cost = tf.reduce_mean(tf.square(self.Y - self.logits))
       self.optimizer = tf.train.AdamOptimizer(learning_rate).minimize(
            self.cost
        )
def calculate_accuracy(real, predict):
   real = np.array(real) + 1
   predict = np.array(predict) + 1
   percentage = 1 - np.sqrt(np.mean(np.square((real - predict) / real)))
   return percentage * 100
def anchor(signal, weight):
   buffer = []
   last = signal[0]
   for i in signal:
        smoothed_val = last * weight + (1 - weight) * i
       buffer.append(smoothed_val)
       last = smoothed_val
   return buffer
size_layer = 128
timestamp = 5
```

```
[7]: num_layers = 1
    size_layer = 128
    timestamp = 5
    epoch = 300
    dropout_rate = 0.8
    future_day = test_size
    learning_rate = 0.01
```

```
[8]: def forecast():
    tf.reset_default_graph()
    modelnn = Model(
        learning_rate, num_layers, df_log.shape[1], size_layer, df_log.
    shape[1], dropout_rate
    )
    sess = tf.InteractiveSession()
    sess.run(tf.global_variables_initializer())
```

```
date_ori = pd.to_datetime(df.iloc[:, 0]).tolist()
   pbar = tqdm(range(epoch), desc = 'train loop')
   for i in pbar:
       init_value = np.zeros((1, num_layers * size_layer))
       total_loss, total_acc = [], []
       for k in range(0, df_train.shape[0] - 1, timestamp):
           index = min(k + timestamp, df_train.shape[0] - 1)
           batch_x = np.expand_dims(
               df_train.iloc[k : index, :].values, axis = 0
           batch_y = df_train.iloc[k + 1 : index + 1, :].values
           logits, last_state, _, loss = sess.run(
               [modelnn.logits, modelnn.last_state, modelnn.optimizer, modelnn.
→cost],
               feed_dict = {
                   modelnn.X: batch_x,
                   modelnn.Y: batch_y,
                   modelnn.hidden_layer: init_value,
               },
           init_value = last_state
           total_loss.append(loss)
           total_acc.append(calculate_accuracy(batch_y[:, 0], logits[:, 0]))
       pbar.set_postfix(cost = np.mean(total_loss), acc = np.mean(total_acc))
   future_day = test_size
   output_predict = np.zeros((df_train.shape[0] + future_day, df_train.
\rightarrowshape[1]))
   output_predict[0] = df_train.iloc[0]
   upper_b = (df_train.shape[0] // timestamp) * timestamp
   init_value = np.zeros((1, num_layers * size_layer))
   for k in range(0, (df_train.shape[0] // timestamp) * timestamp, timestamp):
       out_logits, last_state = sess.run(
           [modelnn.logits, modelnn.last_state],
           feed_dict = {
               modelnn.X: np.expand_dims(
                   df_{train.iloc[k : k + timestamp], axis = 0
               modelnn.hidden_layer: init_value,
           },
       init_value = last_state
       output_predict[k + 1 : k + timestamp + 1] = out_logits
```

```
if upper_b != df_train.shape[0]:
    out_logits, last_state = sess.run(
        [modelnn.logits, modelnn.last_state],
        feed_dict = {
            modelnn.X: np.expand_dims(df_train.iloc[upper_b:], axis = 0),
            modelnn.hidden_layer: init_value,
        },
    )
    output_predict[upper_b + 1 : df_train.shape[0] + 1] = out_logits
    future day -= 1
    date_ori.append(date_ori[-1] + timedelta(days = 1))
init_value = last_state
for i in range(future_day):
    o = output_predict[-future_day - timestamp + i:-future_day + i]
    out_logits, last_state = sess.run(
        [modelnn.logits, modelnn.last_state],
        feed_dict = {
            modelnn.X: np.expand_dims(o, axis = 0),
            modelnn.hidden_layer: init_value,
        },
    )
    init value = last state
    output_predict[-future_day + i] = out_logits[-1]
    date_ori.append(date_ori[-1] + timedelta(days = 1))
output_predict = minmax.inverse_transform(output_predict)
deep_future = anchor(output_predict[:, 0], 0.3)
return deep_future[-test_size:]
```

```
[9]: results = []
for i in range(simulation_size):
    print('simulation %d'%(i + 1))
    results.append(forecast())
```

WARNING: Logging before flag parsing goes to stderr.

W0812 22:23:09.113305 140115879184192 deprecation.py:323] From <ipython-input-6-35b560f11ea1>:12: BasicRNNCell.\_\_init\_\_ (from tensorflow.python.ops.rnn\_cell\_impl) is deprecated and will be removed in a future version.

Instructions for updating:
This class is equivalent as tf.keras.layers.SimpleRNNCell, and will be replaced by that in Tensorflow 2.0.

W0812 22:23:09.116059 140115879184192 deprecation.py:323] From <ipython-input-6-35b560f11ea1>:16: MultiRNNCell.\_\_init\_\_ (from

tensorflow.python.ops.rnn\_cell\_impl) is deprecated and will be removed in a future version.

Instructions for updating:

This class is equivalent as tf.keras.layers.StackedRNNCells, and will be replaced by that in Tensorflow 2.0.

simulation 1

W0812 22:23:09.445186 140115879184192 lazy\_loader.py:50]

The TensorFlow contrib module will not be included in TensorFlow 2.0.

For more information, please see:

- \* https://github.com/tensorflow/community/blob/master/rfcs/20180907-contribsunset.md
  - \* https://github.com/tensorflow/addons
  - \* https://github.com/tensorflow/io (for I/O related ops)

If you depend on functionality not listed there, please file an issue.

W0812 22:23:09.448605 140115879184192 deprecation.py:323] From <ipython-input-6-35b560f11ea1>:27: dynamic\_rnn (from tensorflow.python.ops.rnn) is deprecated and will be removed in a future version.

Instructions for updating:

Please use `keras.layers.RNN(cell)`, which is equivalent to this API W0812 22:23:09.640925 140115879184192 deprecation.py:506] From

/usr/local/lib/python3.6/dist-packages/tensorflow/python/ops/init\_ops.py:1251: calling VarianceScaling.\_\_init\_\_ (from tensorflow.python.ops.init\_ops) with dtype is deprecated and will be removed in a future version.

Instructions for updating:

Call initializer instance with the dtype argument instead of passing it to the constructor

W0812 22:23:09.647897 140115879184192 deprecation.py:506] From

/usr/local/lib/python3.6/dist-

packages/tensorflow/python/ops/rnn\_cell\_impl.py:459: calling Zeros.\_\_init\_\_ (from tensorflow.python.ops.init\_ops) with dtype is deprecated and will be removed in a future version.

Instructions for updating:

Call initializer instance with the dtype argument instead of passing it to the constructor

W0812 22:23:09.740828 140115879184192 deprecation.py:323] From <ipython-input-6-35b560f11ea1>:29: dense (from tensorflow.python.layers.core) is deprecated and will be removed in a future version.

Instructions for updating:

Use keras.layers.dense instead.

train loop: 100%| | 300/300 [00:52<00:00, 5.77it/s, acc=76.9, cost=0.129]

simulation 2

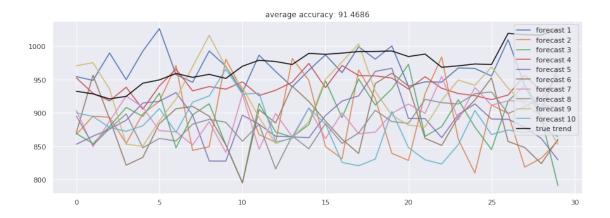
train loop: 100% | 300/300 [00:49<00:00, 6.03it/s, acc=78, cost=0.11]

simulation 3

```
cost=0.154
     simulation 4
                            | 300/300 [00:50<00:00, 6.11it/s, acc=82.7,
     train loop: 100%|
     cost=0.075]
     simulation 5
     train loop: 100%
                            | 300/300 [00:52<00:00, 5.65it/s, acc=76.3,
     cost=0.121
     simulation 6
     train loop: 100%|
                            | 300/300 [00:48<00:00, 6.15it/s, acc=77,
     cost=0.123
     simulation 7
     train loop: 100%|
                            | 300/300 [00:52<00:00, 5.65it/s, acc=80.2,
     cost=0.0896]
     simulation 8
     train loop: 100%
                            | 300/300 [00:50<00:00, 5.99it/s, acc=75.1,
     cost=0.15]
     simulation 9
     train loop: 100%|
                           | 300/300 [00:52<00:00, 5.58it/s, acc=87.2,
     cost=0.0367]
     simulation 10
                            | 300/300 [00:52<00:00, 5.69it/s, acc=76.7,
     train loop: 100%
     cost=0.121
[10]: accuracies = [calculate accuracy(df['Close'].iloc[-test_size:].values, r) for r__
      →in results]
      plt.figure(figsize = (15, 5))
      for no, r in enumerate(results):
          plt.plot(r, label = 'forecast %d'%(no + 1))
      plt.plot(df['Close'].iloc[-test_size:].values, label = 'true trend', c = __
      →'black')
      plt.legend()
      plt.title('average accuracy: %.4f'%(np.mean(accuracies)))
      plt.show()
```

| 300/300 [00:52<00:00, 5.77it/s, acc=73.7,

train loop: 100%|



[]: