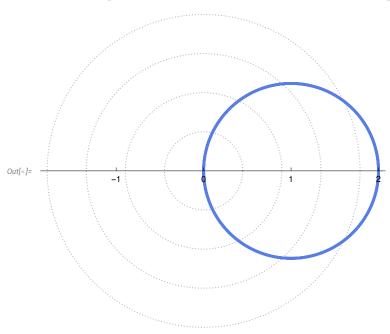
# Problem 1.

**Problem Statement.** Find length of a curve defined in polar coordinates  $\rho = 2 \cos \theta$ .



#### First derivative:

$$ln[\cdot]:= d\rho[\theta] = Simplify[D[\rho[\theta], \theta]]$$

Out[
$$\bullet$$
]=  $-2 Sin[\theta]$ 

### **Arc Length:**

$$l[a_, b_] = l[a_, b_] = l[a_, b_] = l[a_, b_]$$

$$Out[\bullet] = -2 a + 2 b$$

### Full curve length:

$$ln[\circ]:= L = l[0, 2\pi]$$

Out[
$$\circ$$
]=  $4\pi$ 

## Problem 2.

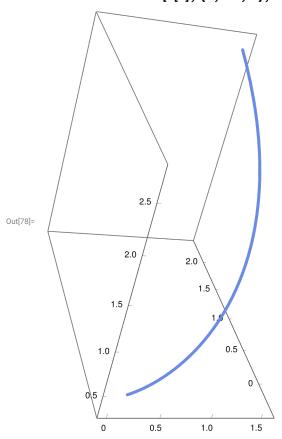
Problem Statement. Find tangent Frenet's basis equations (lines and planes) of curve

$$r(t) = e^t \left\{ \cos t, \sin t, 1 \right\} \text{ at point } M(1, 0, 1)$$

In[76]:= Clear[r, t]

 $r[t] = \{ Exp[t] Cos[t], Exp[t] Sin[t], Exp[t] \};$ 

ParametricPlot3D[r[t], {t, -1, 1}, PlotTheme → "Business"]



#### First derivative:

$$\begin{array}{ll} & \text{In[79]:=} & \text{dr[t_] = Simplify[D[r[t], t]]} \\ & \text{Out[79]:=} & \left\{ e^{t} \left( \text{Cos[t] - Sin[t]} \right), \, e^{t} \left( \text{Cos[t] + Sin[t]} \right), \, e^{t} \right\} \end{array}$$

### **Normalized First Derivative:**

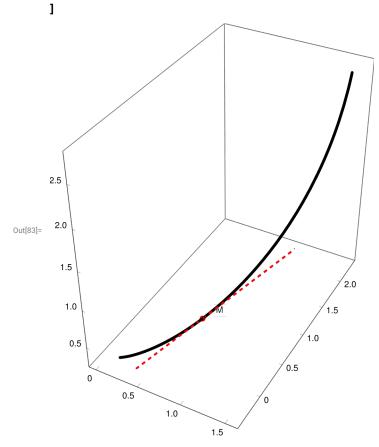
$$In[80]:=$$
 Clear[ $\tau$ ]

$$\tau[t_] = Assuming[t \in Reals, Simplify[\frac{dr[t]}{Sqrt[dr[t].dr[t]]}]]$$

Out[81]= 
$$\left\{\frac{\operatorname{Cos}[t] - \operatorname{Sin}[t]}{\sqrt{3}}, \frac{\operatorname{Cos}[t] + \operatorname{Sin}[t]}{\sqrt{3}}, \frac{1}{\sqrt{3}}\right\}$$

### **Tangent Line Equation:**

```
\ln[82]:= \  \, \boldsymbol{t\tau[t_{,}} \ \boldsymbol{u_{,}} = \boldsymbol{r[t] + \tau[t]} \, \boldsymbol{u;}
        Show[
           \label{eq:parametricPlot3D} ParametricPlot3D[r[t], \{t, -1, 1\}, PlotTheme \rightarrow "Business", PlotStyle \rightarrow Black],
          ListPointPlot3D[\{r[0]\} \rightarrow \{"M"\}, PlotStyle \rightarrow Red],
          \label{eq:parametricPlot3D[ltau], u, -5, 5}, \ PlotStyle \rightarrow \{Red, Dashed\}]
```



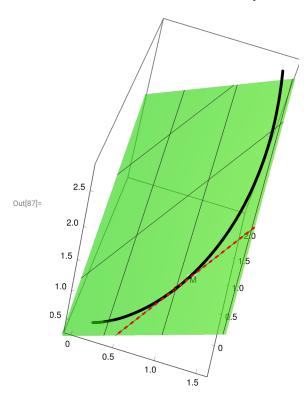
### **Second Derivative**

In[84]:= 
$$d2r[t] = Simplify[D[dr[t], t]]$$
Out[84]:=  $\left\{-2 e^{t} Sin[t], 2 e^{t} Cos[t], e^{t}\right\}$ 

#### **Plane Equation**

```
In[85]:= πτ[t_, u_, v_] = r[t] + dr[t] u + d2r[t] v;
Print["Parametric plane equation is ", πτ[0, u, v]]
Show[
ParametricPlot3D[r[t], {t, -1, 1}, PlotTheme → "Business", PlotStyle → Black],
ListPointPlot3D[{r[0]} → {"M"}, PlotStyle → Red],
ParametricPlot3D[lτ[0, u], {u, -5, 5}, PlotStyle → {Red, Dashed}],
ParametricPlot3D[πτ[0, u, v], {u, -5, 5}, {v, -5, 5},
PlotStyle → Directive[Green, Opacity[0.6], Specularity[White, 20]]]
]
```

Parametric plane equation is  $\{1+u, u+2v, 1+u+v\}$ 



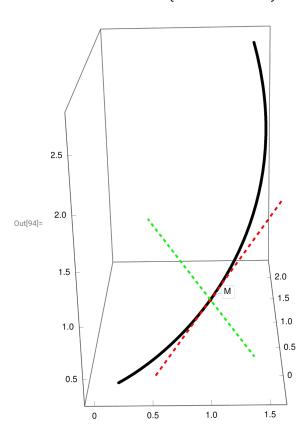
#### **Binormal**

Out[89]= 
$$\left\{e^{2t} \left(-\cos[t] + \sin[t]\right), -e^{2t} \left(\cos[t] + \sin[t]\right), 2e^{2t}\right\}$$

$$||S[t]| = Assuming[t \in Reals, Simplify[\frac{B[t]}{Sqrt[B[t].B[t]]}]]$$

Out[90]= 
$$\left\{\frac{-\cos[t] + \sin[t]}{\sqrt{6}}, -\frac{\cos[t] + \sin[t]}{\sqrt{6}}, \sqrt{\frac{2}{3}}\right\}$$

```
\label{eq:continuous_series} \begin{split} & \log[0] \\ & \text{Out}[91] = \left\{-1, -1, 2\right\} \\ & \log[2] = \left\{\beta[t_{-}, u_{-}] = r[0] + \beta[0] \, u; \\ & \text{Print} \Big[ \text{"Binormal line is ", } l\beta[0, u] \Big] \\ & \text{Show}[ \\ & \text{ParametricPlot3D}[r[t], \{t, -1, 1\}, \text{PlotTheme} \rightarrow \text{"Business", PlotStyle} \rightarrow \text{Black}], \\ & \text{ListPointPlot3D}[\{r[0]\} \rightarrow \{\text{"M"}\}, \text{PlotStyle} \rightarrow \text{Red}], \\ & \text{ParametricPlot3D}[l\tau[0, u], \{u, -5, 5\}, \text{PlotStyle} \rightarrow \{\text{Red, Dashed}\}], \\ & \text{ParametricPlot3D}[l\beta[0, u], \{u, -5, 5\}, \text{PlotStyle} \rightarrow \{\text{Green, Dashed}\}] \\ & \text{Binormal line is } \left\{1 - u, -u, 1 + 2 \, u\right\} \end{split}
```



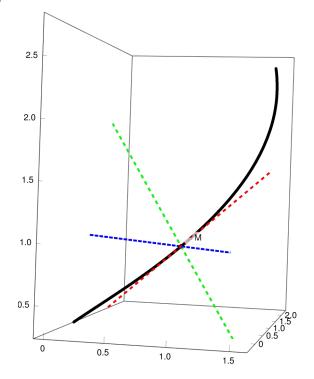
#### Main normal

```
In[95]:= V[t_] = Cross[dr[t], B[t]]

Out[95]:= \left\{3 e^{3t} \cos[t] + 3 e^{3t} \sin[t], -3 e^{3t} \cos[t] + 3 e^{3t} \sin[t], 0\right\}
```

```
 \begin{split} & \text{In}[96] = \text{ $v[t_{-}] = \text{Assuming}[t \in \text{Reals, Simplify}[\frac{V[t]}{\text{Sqrt}[V[t].V[t]]}]]} \\ & \text{Out}[96] = \left\{ \frac{\text{Cos}[t] + \text{Sin}[t]}{\sqrt{2}}, \frac{-\text{Cos}[t] + \text{Sin}[t]}{\sqrt{2}}, 0 \right\} \\ & \text{In}[97] = \text{ $V[0]$} \\ & \text{Out}[97] = \left\{ 3, -3, 0 \right\} \\ & \text{In}[98] = \text{ $V[t_{-}, u_{-}] = r[0] + V[0] u;} \\ & \text{Print}["\text{Binormal line is ", $lv[0, u]]} \\ & \text{Show}[ \\ & \text{ParametricPlot3D}[r[t], \{t, -1, 1\}, \text{PlotTheme} \rightarrow "\text{Business", PlotStyle} \rightarrow \text{Black}], \\ & \text{ListPointPlot3D}[\{r[0]\} \rightarrow \{"\text{M"}\}, \text{PlotStyle} \rightarrow \text{Red}], \\ & \text{ParametricPlot3D}[l\tau[0, u], \{u, -5, 5\}, \text{PlotStyle} \rightarrow \text{Red, Dashed}], \\ & \text{ParametricPlot3D}[l\tau[0, u], \{u, -5, 5\}, \text{PlotStyle} \rightarrow \text{Green, Dashed}], \\ & \text{ParametricPlot3D}[lv[0, u], \{u, -5, 5\}, \text{PlotStyle} \rightarrow \text{Blue, Dashed}] \\ & \text{Binormal line is } \left\{ 1 + 3u, -3u, 1 \right\} \\ \end{aligned}
```

Out[100]=



#### **Planes**

-2 + x + y + z

Out[102]=

### Problem 3.

Problem Statement. Find curvature and torsion of curve with radius-vector

$$f(t) = \left\{ a \cos^2 t, \, a \cos t \sin t, \, b \, t \right\}.$$

$$ln[\cdot]:= u[t_] = \{a Cos[t]^2, a Cos[t] Sin[t], b t\};$$

$$du[t_] = Simplify[D[u[t], t]]$$

$$Out[*]= \left\{-2 \text{ a Cos[t] Sin[t], a Cos[2 t], b}\right\}$$

$$ln[\cdot]:= d2u[t] = Simplify[D[du[t], t]]$$

$$Out[*]=$$
  $\left\{-2 \text{ a Cos}[2 \text{ t}], -2 \text{ a Sin}[2 \text{ t}], 0\right\}$ 

$$ln[\cdot]:= dud2u[t] = Simplify[Cross[du[t], d2u[t]]]$$

$$out[*] = \{2 \text{ a b Sin}[2 t], -2 \text{ a b Cos}[2 t], 2 a^2\}$$

$$lo(n) = dud2uLen[t] = Simplify[Sqrt[dud2u[t].dud2u[t]]]$$

Out[•]= 2 
$$\sqrt{a^2(a^2+b^2)}$$

$$ln[\cdot]:= d3u[t] = Simplify[D[d2u[t], t]]$$

$$Out[\cdot] = \{4 \text{ a Sin}[2 \text{ t}], -4 \text{ a Cos}[2 \text{ t}], 0\}$$

$$los_{0} = \frac{1}{2} dud2ud3u[t] = Simplify[Det[{du[t], d2u[t], d3u[t]}]$$

```
 \begin{aligned} &\text{In}[119] = \text{ } \text{x}[\texttt{t}\_] = \text{a} \text{Cos}[\texttt{t}]^2; \text{ } \text{y}[\texttt{t}\_] = \text{a} \text{Cos}[\texttt{t}] \text{Sin}[\texttt{t}]; \text{ } \text{z}[\texttt{t}\_] = \text{b} \text{ } \text{t}; \\ &\text{torsion} = \text{Simplify} \Big[ \Big( \text{D}[x[\texttt{t}], \{\texttt{t}, \, 3\}], (\text{D}[y[\texttt{t}], \, \texttt{t}] \times \text{D}[z[\texttt{t}], \, \{\texttt{t}, \, 2\}] - \text{D}[y[\texttt{t}], \, \{\texttt{t}, \, 2\}] \times \text{D}[z[\texttt{t}], \, \{\texttt{t}, \, 2\}] \times \text{D}[z[\texttt{t}], \, \{\texttt{t}, \, 2\}] \times \text{D}[z[\texttt{t}], \, \{\texttt{t}, \, 2\}] \times \text{D}[y[\texttt{t}], \,
```