Lecture 11. Kernel Methods

COMP90051 Statistical Machine Learning

Semester 2, 2018 Lecturer: Ben Rubinstein



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This lecture

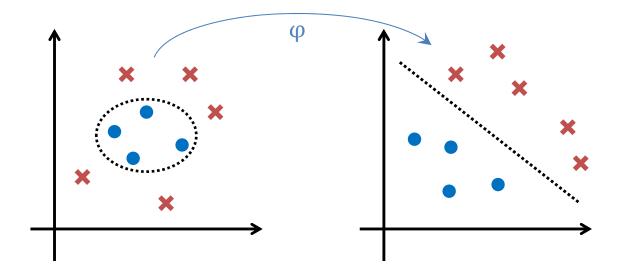
- Kernelisation
 - Basis expansion on dual formulation of SVMs
 - "Kernel trick"; Fast computation of feature space dot product
- Modular learning
 - Separating "learning module" from feature transformation
 - Representer theorem
- Constructing kernels
 - Overview of popular kernels and their properties
 - * Mercer's theorem
 - Learning on unconventional data types

Kernelising the SVM

Feature transformation by basis expansion; sped up by direct evaluation of kernels – the 'kernel trick'

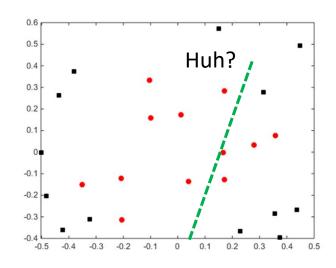
Handling non-linear data with the SVM

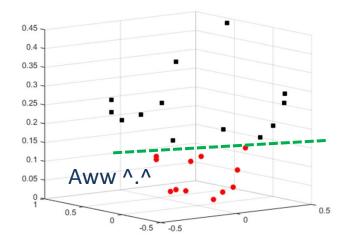
- Method 1: Soft-margin SVM (deck #10)
- Method 2: Feature space transformation (deck #4)
 - Map data into a new feature space
 - * Run hard-margin or soft-margin SVM in new space
 - Decision boundary is non-linear in original space



Feature transformation (Basis expansion)

- Consider a binary classification problem
- Each example has features $[x_1, x_2]$
- Not linearly separable
- Now 'add' a feature $x_3 = x^2 + x_2^2$
- Each point is now $[x_1, x_2, x_1^2 + x_2^2]$
- Linearly separable!





Naïve workflow

- Choose/design a linear model
- Choose/design a high-dimensional transformation $\varphi(x)$
 - Hoping that after adding <u>a lot</u> of various features some of them will make the data linearly separable
- For each training example, and for each new instance compute $\varphi(x)$
- Train classifier/Do predictions
- Problem: impractical/impossible to compute $\varphi(x)$ for high/infinite-dimensional $\varphi(x)$

Hard-margin SVM's dual formulation

s.t.
$$\lambda_i \geq 0$$
 and $\sum_{i=1}^n \lambda_i y_i = 0$

• Making predictions: classify instance x as sign of

$$s = b^* + \sum_{i=1}^n \lambda_i^* y_i \mathbf{x}_i' \mathbf{x}_i'$$

Note: b^* found by solving for it in $y_j(b^* + \sum_{i=1}^n \lambda_i^* y_i(x_i' x_j)) = 1$ for any support vector j

Hard-margin SVM in *feature space*

• Training: finding λ that solve

$$\underset{\lambda}{\operatorname{argmax}} \sum_{i=1}^{n} \lambda_{i} - \frac{1}{2} \sum_{i=1}^{n} \sum_{j=1}^{n} \lambda_{i} \lambda_{j} y_{i} y_{j} \varphi(x_{i})' \varphi(x_{j})$$

s.t.
$$\lambda_i \geq 0$$
 and $\sum_{i=1}^n \lambda_i y_i = 0$

• Making predictions: classify new instance x as sign of

$$s = b^* + \sum_{i=1}^n \lambda_i^* y_i \varphi(x_i)' \varphi(x)$$

Note: b^* found by solving for it in $y_j(b^* + \sum_{i=1}^n \lambda_i^* y_i \varphi(x_i)' \varphi(x_j)) = 1$ for support vector j

Observation: Kernel representation

- Both parameter estimation and computing predictions depend on data <u>only in a form of a dot product</u>
 - * In original space $u'v = \sum_{i=1}^m u_i v_i$
 - * In transformed space $\varphi(\boldsymbol{u})'\varphi(\boldsymbol{v}) = \sum_{i=1}^l \varphi(\boldsymbol{u})_i \varphi(\boldsymbol{v})_i$

• Kernel is a function that can be expressed as a dot product in some feature space $K(\boldsymbol{u}, \boldsymbol{v}) = \varphi(\boldsymbol{u})' \varphi(\boldsymbol{v})$

Kernel as shortcut: Example

- For some $\varphi(x)$'s, kernel is faster to compute directly than first mapping to feature space then taking dot product.
- For example, consider two vectors $\mathbf{u}=[u_1]$ and $\mathbf{v}=[v_1]$ and transformation $\varphi(\mathbf{x})=[x_1^2,\sqrt{2c}x_1,c]$, some c
 - * So $\varphi(\boldsymbol{u}) = \begin{bmatrix} u_1^2, \sqrt{2c}u_1, c \end{bmatrix}'$ and $\varphi(\boldsymbol{v}) = \begin{bmatrix} v_1^2, \sqrt{2c}v_1, c \end{bmatrix}'$
 - * Then $\varphi(u)'\varphi(v) = (u_1^2v_1^2 + 2cu_1v_1 + c^2)$ +5 operations = 9 ops.
- This can be <u>alternatively computed directly</u> as

$$\varphi(\boldsymbol{u})'\varphi(\boldsymbol{v})=(u_1v_1+c)^2$$
 3 operations

* Here $K(\boldsymbol{u}, \boldsymbol{v}) = (u_1 v_1 + c)^2$ is the corresponding kernel

More generally: The "kernel trick"

- Consider two training points x_i and x_j and their dot product in the transformed space.
- $k_{ij} \equiv \varphi(x_i)' \varphi(x_j)$ can be computed as:
 - 1. Compute $\varphi(x_i)'$
 - 2. Compute $\varphi(x_i)$
 - 3. Compute $k_{ij} = \varphi(\mathbf{x}_i)' \varphi(\mathbf{x}_j)$
- However, for some transformations φ , there's a "shortcut" function that gives exactly the same answer $K(x_i, x_j) = k_{ij}$
 - * Doesn't involve steps 1 3 and no computation of $\varphi(x_i)$ and $\varphi(x_i)$
 - * Usually k_{ij} computable in O(m), but computing $\varphi(x)$ requires O(l), where $l \gg m$ (impractical) and even $l = \infty$ (infeasible)

feature mapping is

implied by kernel

Kernel hard-margin SVM

• Training: finding λ that solve

$$\underset{\lambda}{\operatorname{argmax}} \sum_{i=1}^{n} \lambda_{i} - \frac{1}{2} \sum_{i=1}^{n} \sum_{j=1}^{n} \lambda_{i} \lambda_{j} y_{i} y_{j} K(\boldsymbol{x}_{i}, \boldsymbol{x}_{j})$$

s.t.
$$\lambda_i \geq 0$$
 and $\sum_{i=1}^n \lambda_i y_i = 0$

• Making predictions: classify new instance x based on the sign of

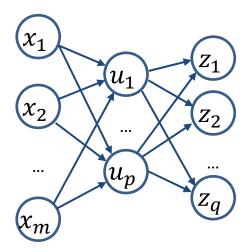
$$s = b^* + \sum_{i=1}^{n} \lambda_i^* y_i K(x_i, x_j)$$
 feature mapping is implied by kernel

• Here b^* can be found by noting that for support vector j we have $y_j\left(b^* + \sum_{i=1}^n \lambda_i^* y_i K\left(\boldsymbol{x}_i, \boldsymbol{x}_j\right)\right) = 1$

Approaches to non-linearity

ANNs

- Elements of $u = \varphi(x)$ are transformed input x
- This φ has weights learned from data



SVMs

- Choice of kernel K determines features ϕ
- Don't learn φ weights
- But, don't even need to compute φ so can support v high dim. φ
- Also support arbitrary data types

Any method that uses a feature space transformation arphi(x) uses kernels

When poll is active, respond at **PollEv.com/bipr**

Text **BIPR** to **+61 427 541 357** once to join

Answers to this poll are anonymous

True

False

Support vectors are points from the training set True **False**

Feature mapping $\varphi(x)$ makes data linearly separable True **False**

Modular Learning

Kernelisation beyond SVMs; Separating the "learning module" from feature space transformation

Modular learning

- All information about feature mapping is concentrated within the kernel
- In order to use a different feature mapping, simply change the kernel function
- Algorithm design decouples into choosing a "learning method" (e.g., SVM vs logistic regression) and choosing feature space mapping, i.e., kernel

Kernelised perceptron (1/3)

When classified correctly, weights are unchanged

When misclassified:
$$\mathbf{w}^{(k+1)} = -\eta(\pm \mathbf{x})$$

($\eta > 0$ is called *learning rate*)

$$\begin{array}{ll} \underline{\text{If } y = 1, \, \text{but } s < 0} & \underline{\text{If } y = -1, \, \text{but } s \geq 0} \\ w_i \leftarrow w_i + \eta x_i & w_i \leftarrow w_i - \eta x_i \\ w_0 \leftarrow w_0 + \eta & w_0 \leftarrow w_0 - \eta \end{array}$$

Suppose weights are initially set to 0

First update: $\mathbf{w} = \eta y_{i_1} \mathbf{x}_{i_1}$

Second update: $\mathbf{w} = \eta y_{i_1} \mathbf{x}_{i_1} + \eta y_{i_2} \mathbf{x}_{i_2}$

Third update $\mathbf{w} = \eta y_{i_1} \mathbf{x}_{i_1} + \eta y_{i_2} \mathbf{x}_{i_2} + \eta y_{i_3} \mathbf{x}_{i_3}$

etc.

Kernelised perceptron (2/3)

- Weights always take the form $\mathbf{w} = \sum_{i=1}^{n} \alpha_i y_i \mathbf{x}_i$, where $\boldsymbol{\alpha}$ some coefficients
- Perceptron weights are always a linear combination of data!
- Recall that prediction for a new point x is based on sign of $w_0 + w'x$
- Substituting w we get $w_0 + \sum_{i=1}^n \alpha_i y_i x_i' x$
- The dot product $x_i'x$ can be replaced with a kernel

Kernelised perceptron (3/3)

Choose initial guess $\mathbf{w}^{(0)}$, k=0

Set $\alpha = 0$

For t from 1 to T (epochs)

For each training example $\{x_i, y_i\}$

Predict based on $w_0 + \sum_{j=1}^n \alpha_j y_j x_i' x_j$

If misclassified, update $\alpha_i \leftarrow \alpha_i + 1$

Representer theorem

• Theorem: For any training set $\{x_i, y_i\}_{i=1}^n$, any empirical risk function E, monotonic increasing function g, then any solution

$$f^* \in \arg\min_f E(\mathbf{x}_1, y_1, f(\mathbf{x}_1), ..., \mathbf{x}_n, y_n, f(\mathbf{x}_n)) + g(\|f\|)$$

has representation for some coefficients

$$f^*(\mathbf{x}) = \sum_{i=1}^n \alpha_i \, k(\mathbf{x}, \mathbf{x}_i)$$

Aside: f sits in a reproducing kernel Hilbert space (RKHS)

- Tells us when a (decision-theoretic) learner is kernelizable
- The dual tells us the form this linear kernel representation takes
- SVM is but one example!
 - Ridge regression
 - * Logistic regression
 - Principal component analysis (PCA)
 - Canonical correlation analysis (CCA)
 - Linear discriminant analysis (LDA)
 - * and many more ...

Constructing Kernels

An overview of popular kernels and kernel properties

Polynomial kernel

- Function $K(\boldsymbol{u}, \boldsymbol{v}) = (\boldsymbol{u}'\boldsymbol{v} + c)^d$ is called *polynomial kernel*
 - * Here $oldsymbol{u}$ and $oldsymbol{v}$ are vectors with m components
 - * $d \ge 0$ is an integer and $c \ge 0$ is a constant
- Without the loss of generality, assume c=0
 - * If it's not, add \sqrt{c} as a dummy feature to \boldsymbol{u} and \boldsymbol{v}

•
$$(u'v)^d = (u_1v_1 + \dots + u_mv_m)(u_1v_1 + \dots + u_mv_m)\dots(u_1v_1 + \dots + u_mv_m)$$

- $=\sum_{i=1}^{l} (u_1 v_1)^{a_{i1}} \dots (u_m v_m)^{a_{im}}$
 - * Here $0 \le a_{ij} \le d$ and l are integers

•
$$= \sum_{i=1}^{l} (u_1^{a_{i1}} \dots u_m^{a_{im}}) (v_1^{a_{i1}} \dots v_m^{a_{im}})$$

- $=\sum_{i=1}^{l}\varphi(\mathbf{u})_{i}\varphi(\mathbf{v})_{i}$
- Feature map $\varphi \colon \mathbb{R}^m o \mathbb{R}^l$, where $\varphi_i(\pmb{x}) = \left(x_1^{a_{i1}} \dots x_m^{a_{im}}\right)$

Identifying new kernels

• Method 1: Let $K_1(u, v)$, $K_2(u, v)$ be kernels, c > 0 be a constant, and f(x) be a real-valued function. Then each of the following is also a kernel:

*
$$K(u, v) = K_1(u, v) + K_2(u, v)$$

*
$$K(\boldsymbol{u}, \boldsymbol{v}) = cK_1(\boldsymbol{u}, \boldsymbol{v})$$

*
$$K(\boldsymbol{u}, \boldsymbol{v}) = f(\boldsymbol{u})K_1(\boldsymbol{u}, \boldsymbol{v})f(\boldsymbol{v})$$

* See Bishop for more identities

Prove these!

Method 2: Using Mercer's theorem (coming up!)

Radial basis function kernel

- Function $K(\boldsymbol{u}, \boldsymbol{v}) = \exp(-\gamma \|\boldsymbol{u} \boldsymbol{v}\|^2)$ is the <u>radial basis function kernel</u> (aka Gaussian kernel)
 - * Here $\gamma > 0$ is the spread parameter

•
$$\exp(-\gamma \|\mathbf{u} - \mathbf{v}\|^2) = \exp(-\gamma (\mathbf{u} - \mathbf{v})'(\mathbf{u} - \mathbf{v}))$$

- = $\exp(-\gamma(u'u 2u'v + v'v))$
- = $\exp(-\gamma u'u) \exp(2\gamma u'v) \exp(-\gamma v'v)$
- $= f(\mathbf{u}) \exp(2\gamma \mathbf{u}' \mathbf{v}) f(\mathbf{v})$

Power series expansion

- $= f(\boldsymbol{u}) \left(\sum_{d=0}^{\infty} r_d (\boldsymbol{u}' \boldsymbol{v})^d \right) f(\boldsymbol{v})$
- Here, each $(u'v)^d$ is a polynomial kernel. Using kernel identities, we conclude that the middle term is a kernel, and hence the whole expression is a kernel

Mercer's Theorem

- Question: given $\varphi(u)$, is there a good kernel to use?
- Inverse question: given some function $K(\boldsymbol{u}, \boldsymbol{v})$, is this a valid kernel? In other words, is there a mapping $\varphi(\boldsymbol{u})$ implied by the kernel?

• Mercer's theorem:

- * Consider a finite sequences of objects $x_1, ..., x_n$
- * Construct $n \times n$ matrix of pairwise values $K(x_i, x_j)$
- * $K(x_i, x_j)$ is a valid kernel if this matrix is positivesemidefinite, and this holds for all possible sequences $x_1, ..., x_n$

Data comes in a variety of shapes

- So far in COMP90051 data has been vectors of numbers
- But what if we wanted to do machine learning on ...
- Graphs
 - * Facebook, Twitter, ...



- Sequences of variable lengths
 - * "science is organized knowledge", "wisdom is organized life"*, ...
 - * "CATTC", "AAAGAGA"
- Songs, movies, etc.

Handling arbitrary data structures

- Kernels are powerful approach to deal with many data types
- Could define similarity function on variable length strings
 K("science is organized knowledge", "wisdom is organized life")
- However, not every function on two objects is a valid kernel
- Remember that we need that function $K(m{u}, m{v})$ to imply a dot product in some feature space

A large variety of kernels

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This lecture

- Kernels
 - Nonlinearity by basis expansion
 - Kernel trick to speed up computation
- Modular learning
 - Separating "learning module" from feature transformation
 - Representer theorem
- Constructing kernels
 - * An overview of popular kernels and their properties
 - * Mercer's theorem
 - * Extending machine learning beyond conventional data structure

Next lecture: Ensemble methods