

Selected Tutorial Solutions, Week 12

91. Here is how the 2-PDA recogniser for B operates:

- (a) Push a \$ symbol onto stack 1 and also onto stack 2.
- (b) As long as we find an **a** in input, consume it and push an **a** onto stack 1.
- (c) As long as we find a **b** in input, consume it and push a **b** onto stack 2.
- (d) As long as we find a **c** in input, consume it and pop both stacks.
- (e) If the top of each stack has a \$ symbol, pop these.
- (f) If we got to this point and the input has been exhausted, accept.

If the 2-PDA got stuck at any point, that meant reject.

92. To simulate M running on input $x_1x_2\cdots x_n$, the 2-PDA P first pushes a \$ symbol onto stack 1 and also onto stack 2. It then runs through its input, pushing $x_1, x_2, \dots, x_{n-1}, x_n$ onto stack 1. It then pops each symbol from stack 1, pushing it to stack 2. That is, it pushes $x_n, x_{n-1}, \dots, x_2, x_1$ onto stack 2, in that order. Note that x_1 is on top.

P is now ready to simulate M . Note that it has consumed all of its input already, but it is not yet in a position to accept or reject.

For each state of M , P has a corresponding state. Assume P is in the state that corresponds to some M state q .

For each M -transition $\delta(q, a) = (r, b, R)$, P has a transition that pops a off stack 2 and pushes b onto stack 1. If stack 2 now has \$ on top, P pushes a blank symbol onto stack 2. Then P goes to the state corresponding to r .

For each M -transition $\delta(q, a) = (r, b, L)$, P has a transition that first pops a off stack 2, replacing it by b . It then pops the top element off stack 1 and transfers it to the top of stack 2, unless it happens to be \$. And then of course P goes to the state corresponding to r .

If this seems mysterious, try it out for a simple Turing machine and draw some diagrams along to way, with snapshots of the Turing machine's tape and tape head next to the 2-PDA's corresponding pair of stacks. The invariant is that what sits on top of the 2-PDA's stack 2 is exactly what is under the Turing machine's tape head at the corresponding point in its computation.

93. Assume that H is a decider for the language

$$\text{Halt}_{TM} = \{\langle M, w \rangle \mid M \text{ is a Turing machine and } M \text{ halts when run on input } w\}$$

Here is a decider for A_{TM} :

On input x :

- if x is not of the required form $\langle M, w \rangle$, reject;
- else run H on $\langle M, w \rangle$;
- if H rejects, reject;
- else run M on w and accept x if M accepts w ;
- else reject.

Since H halts for all input, the above Turing machine also halts, and it accepts if and only if M accepts w . Since we know that A_{TM} is undecidable, we conclude that $Halt_{TM}$ is undecidable as well.

94. Yes, $\{\langle G \rangle \mid G \text{ is a context-free grammar over } \{0, 1\} \text{ and } L(G) \cap 1^* \neq \emptyset\}$ is decidable. Since 1^* is regular, the intersection $L(G) \cap 1^*$ is context-free, and we can build a context-free grammar G' for it. We then run the emptiness decider from Lecture 21 on G' . If that decider accepts, we reject, and vice versa.
95. Let A and B be decidable languages, let M_A be a decider for A and M_B a decider for B . We construct a decider for $A \cup B$ as a Turing machine which implements this routine:

On input w :

- (1) Run M_A on input w and accept if M_A accepts.
- (2) Run M_B on input w and accept if M_B accepts; else reject.

96. Let M_A and M_B be recognisers for A and B , respectively. We want to construct a recogniser for $A \cup B$ but we can't use the construction from the last question. The reason is that there could be some string $w \in B$, which should obviously be accepted by the recogniser we construct, but for which M_A fails to terminate. That is, step (1) above never terminates.

Instead we construct a recogniser for $A \cup B$ by alternating the recognisers for A and B :

On input w :

- (1) Let M_A take a single execution step; accept if M_A accepts; go to step (4) if M_A rejects.
- (2) Let M_B take a single execution step; accept if M_B accepts; go to step (5) if M_B rejects.
- (3) Go to step (1).
- (4) Run M_B alone; accept if M_B accepts; reject if it rejects.
- (5) Run M_A alone; accept if M_A accepts; reject if it rejects.

Note that this machine may fail to terminate on w , which will happen if both of M_A and M_B fail to terminate. That's okay, of course, as we are constructing a recogniser, not a decider.

97. This is easy enough. Let M be a decider for A . We get a decider for A^c simply by swapping the 'reject' and 'accept' states in M .

The construction won't work if all we know about M is that it is a recogniser for A . Namely, M may fail to terminate for some string $w \in A^c$.

98. We just show the case for concatenation. Let M_A and M_B be recognisers for A and B , respectively. We want to construct a recogniser for $A \circ B$. It will make our task easier if we utilise nondeterminism. We can construct a nondeterministic Turing machine to implement this routine:

On input w :

- (1) Split w nondeterministically so that $w = xy$.
- (2) Run M_A on x ; reject w if M_A rejects x .
- (2) Run M_B on y ; reject w if M_B rejects y .
- (3) Otherwise accept w .

This makes good use of the nondeterministic Turing machine's bias towards acceptance.

99. Assume \mathcal{B} is countable. Then we can enumerate \mathcal{B} :

| Element | | | | | | | | |
|----------|---|---|---|---|---|---|---|-----|
| b_1 | 0 | 0 | 1 | 0 | 1 | 1 | 1 | ... |
| b_2 | 1 | 0 | 1 | 1 | 1 | 0 | 1 | ... |
| b_3 | 1 | 0 | 1 | 1 | 1 | 0 | 1 | ... |
| b_4 | 0 | 1 | 0 | 0 | 1 | 0 | 0 | ... |
| \vdots | | | | | | | | |

However, the infinite sequence which has

$$i\text{'th bit} = \begin{cases} 0 & \text{if the } i\text{th bit of } b_i \text{ is 1} \\ 1 & \text{if the } i\text{th bit of } b_i \text{ is 0} \end{cases}$$

is different from each of the b_i . Hence no enumeration can exist, and \mathcal{B} is uncountable. This should not be surprising, because the set \mathcal{B} is really the same as (or is isomorphic to) $\mathbb{N} \rightarrow \Sigma$.