Optimization Notes

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The problem we are trying to optimize is as follows.

$$\max_{c_1(s), c_2(s), l_1(s), l_2(s), x'(s), R'(s)} \sum_{s} P(s_{-}, s) \left[\sum_{i} \alpha_i \left(\frac{\psi c_i(s)^{1-\sigma}}{1-\sigma} + (1-\psi) \log(1-l_i(s)) \right) + \beta V(x'(s), R'(s), s) \right]$$

subject to the constraints

$$\psi c_2(s)^{-\sigma}(c_2(s) - c_1(s)) + x'(s) + \left(\frac{-(1 - \psi)l_2(s)}{1 - l_2(s)} + R'(s)\frac{(1 - \psi)l_1(s)}{1 - l_1(s)}\right) = \frac{\psi c_2(s)^{-\sigma}}{\beta \mathbb{E}[\psi c_2^{-\sigma}]}$$
(1)

$$\frac{\sum_{s} P(s_{-}, s) \psi c_{2}(s)^{-\sigma}}{\sum_{s} P(s_{-}, s) \psi c_{1}(s)^{-\sigma}} = R$$
 (2)

$$\frac{(1-\psi)}{\theta_1(1-l_1(s))\psi c_1(s)^{-\sigma}} = \frac{(1-\psi)}{\theta_2(1-l_2(s))\psi c_2(s)^{-\sigma}}$$
(3)

$$n_1c_1(s) + n_2c_2(s) + g(s) = \theta_1l_1(s) + \theta_2l_2(s) \tag{4}$$

$$R'(s) = \frac{\psi c_2(s)^{-\sigma}}{\psi c_1(s)^{-\sigma}} \tag{5}$$

conditional on s_- , R and x. For s=2, given a guess of $z=(c_1(1),c_1(2),c_2(1))$ it is possible to find the variables $c_2(2), l_1, l_2, x', R'$ such that the equations above our satisfied and their derivatives with respect to z. Taking derivatives we can the perform an unconstrained optimization. From now on ∇ will refer to the vector of partial derivatives with respect to z, $u_{c,i}(s)$ will refer to $\psi c_i(s)^{-\sigma}$ and $u_{l,i}(s)=-\frac{1-\psi}{1-l_i(s)}$. Also, for the purposes of these notes, we will denote $P_s=P(s_-,s)$. These notes will follow same order as the computations in the code. To begin with, taking equation (2) we can solve for $c_2(2)$ as

$$c_2(2) = \left(\frac{P(s_{-}, 1)c_1(1)^{-\sigma} + P(s_{-}, 2)c_1(2)^{-\sigma} - P(s_{-}, 1)c_2(1)^{-\sigma}}{P(s_{-}, 2)}\right)^{-1/\sigma}$$
(6)

Taking derivatives we obtain

$$\nabla c_2(2) = c_2(s)^{1+\sigma} \begin{bmatrix} \frac{RP_1}{P_2} c_1(1)^{-\sigma-1} \\ Rc_1(2)^{-\sigma-1} \\ \frac{-P_1}{P_2} c_2(1)^{-\sigma-1} \end{bmatrix}$$
 (7)

We compute R'(s) directly from equation (5). Taking derivatives we obtain

$$\nabla R'(s) = \sigma c_2(s)^{-\sigma} c_1(s)^{\sigma - 1} \nabla c_1(s) - \sigma c_2(s)^{-\sigma - 1} c_1(s)^{\sigma} \nabla c_2(s). \tag{8}$$

The wage equation, equation (3), gives us the following relationship between l_1 and l_2

$$l_1(s) = 1 - (1 - l_2(s))\frac{\theta_2}{\theta_1}R'(s)$$
(9)

substituting into the resource constraint, equation (4), we quickly obtain

$$l_2(s) = \frac{n_1 c_1(s) + n_2 c_2(s) + g(s) + n_1 \theta_2 R'(s) - \theta_1 n_1}{\theta_2(n_2 + R(s)n_1)}$$
?? (10)

which, when differentiated, gives us

$$\nabla l_2(s) = \frac{n_1 \nabla R'(s)}{n_2 + R'(s)n_2} - \frac{n_1 l_2(s) \nabla R'(s)}{n_2 + R'(s)n_1} + \frac{n_1 \nabla c_1(s)}{\theta_2(n_2 + R'(s)n_1)} + \frac{n_2 \nabla c_2(s)}{\theta_2(n_2 + R'(s)n_1)}$$
(11)

we then also get

$$\nabla l_1(s) = \nabla l_2(s) \frac{\theta_2}{\theta_1} R'(s) - (1 - l_2(s)) \frac{\theta_2}{\theta_1} \nabla R'(s)$$
(12)

Finally, rearranging equation (1),

$$x'(s) = \frac{\psi c_2(s)^{-\sigma} x}{\beta \sum_{s'} P_{s'} \psi c_2(s')^{-\sigma}} + \frac{(1 - \psi)l_2(s)}{1 - l_2(s)} - R'(s) \frac{(1 - \psi)l_1(s)}{1 - l_1(s)} + \psi c_1(s)c_2(s)^{-\sigma} - \psi c_2(s)^{1-\sigma}$$
(13)

Taking the gradient,

$$\nabla x'(s) = \left(\frac{-\sigma\psi c_2(s)^{-\sigma-1}}{\beta\mathbb{E}[\psi c_2^{-\sigma}]} + \frac{\sigma\psi c_2(s)^{-2\sigma-1}\beta P_s}{(\beta\mathbb{E}[\psi c_2^{-\sigma}])^2} - \sigma\psi c_2(s)^{-\sigma-1}c_1(s) - (1-\sigma)\psi c_2(s)^{-\sigma}\right)\nabla c_2(s)$$

$$+ \frac{\sigma\psi c_2(s)^{-\sigma}c_2(s^{-})^{-\sigma-1}\beta P_{s^{-}}}{(\beta\mathbb{E}[\psi c_2^{-\sigma}])^2}\nabla c_2(s^{-}) + \psi c_2(s)^{-\sigma}\nabla c_1(s) + \frac{1-\psi}{(1-l_2(s))^2}\nabla l_2(s)$$

$$- R'(s)\frac{1-\psi}{(1-l_1(s))^2}\nabla l_1(s) - \frac{(1-\psi)l_1(s)}{1-l_1(s)}\nabla R'(s)$$
(14)

With the notation that s^- is 2 when s=1 and 1 when s=2. The FOC necessary conditions that the optimizer must satisfy can then be written as

$$\sum_{s} P_{s} \left[\sum_{i} \alpha_{i} \left(u_{c,i}(s) \nabla c_{i}(s) + u_{l,i}(s) \nabla l_{i}(s) \right) + \beta \left(V_{x}(x'(s), R'(s)) \nabla x'(s) + V_{R}(x'(s), R'(s)) \nabla R'(s) \right) \right]$$
(15)