### **ARCOS Group**

uc3m | Universidad Carlos III de Madrid

# Lesson 3 (I)

Fundamentals of assembler programming

Computer Structure

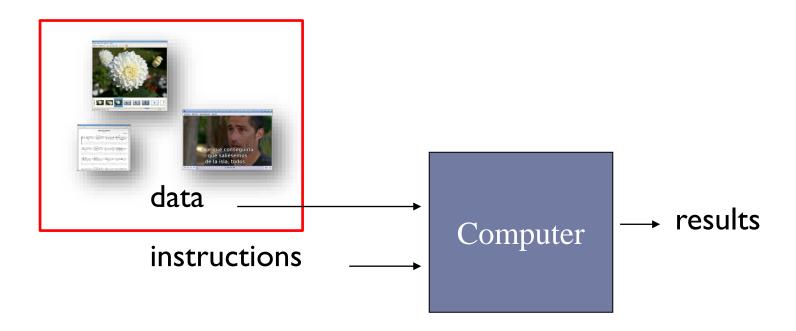
Bachelor in Computer Science and Engineering



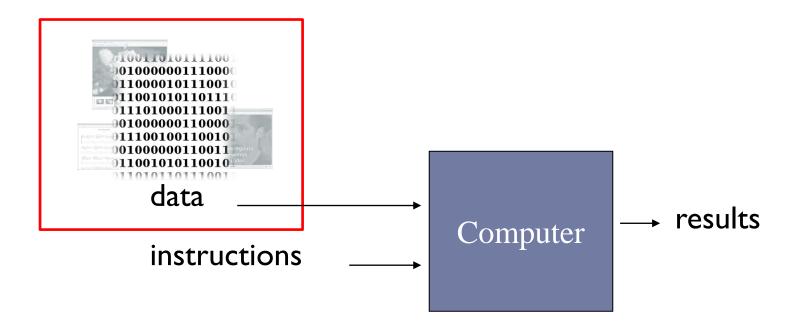
### Contents

- Basic concepts on assembly programming
  - Motivations and goals
  - MIPS32 introduction
- MIPS32 assembly language, memory model and data representation
- Instruction formats and addressing modes
- Procedure calls and stack convention

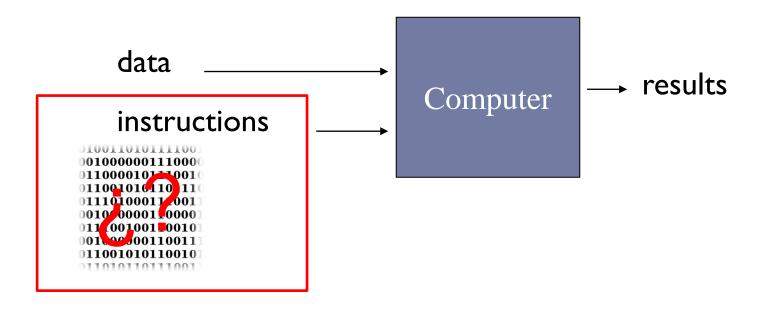
Data representation...



Binary data representation.

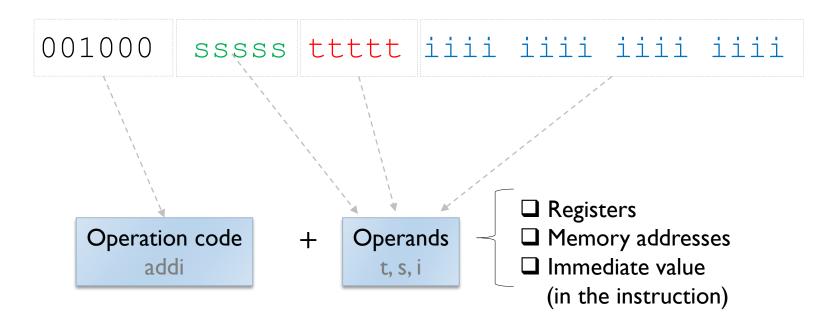


What about the instructions?



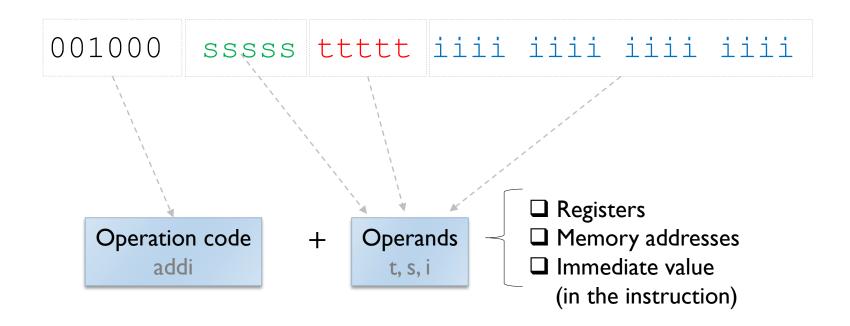
### Machine instruction

- Machine instruction: elementary operation that can be executed directly by the processor.
- Example of instruction in MIPS:
  - Sum of a register (s) with an immediate value (i) and the result of the sum is stored in register (t).



## Properties of machine instructions

- Perform a single, simple task
- Operate on a fixed number of operands
- Include all the information necessary for its execution



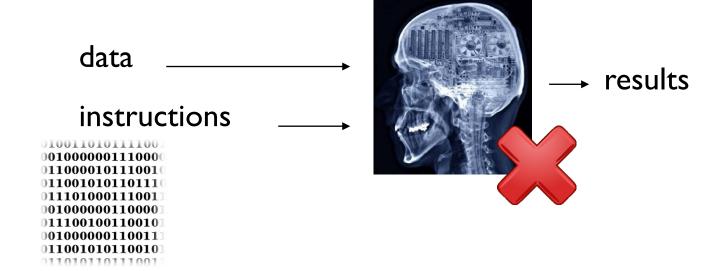
### Information contained in a machine instruction

- ▶ The operation to be performed.
- Where the operands are located:
  - In registers
  - In memory
  - In the instruction itself (immediate)
- Where to leave the results (as operand)
- A reference to the next instruction to be executed
  - Implicitly: the following instruction
    - A program is a consecutive sequence of machine instructions.
  - Explicitly in branching instructions (as operand)



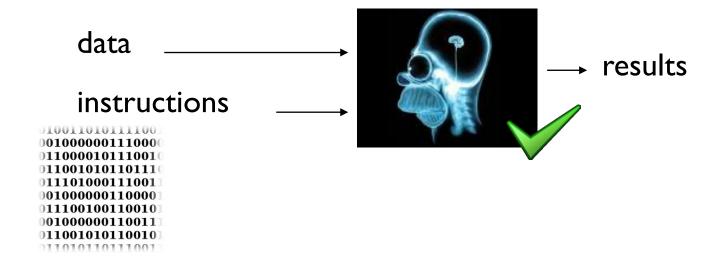
### Machine instructions

▶ There are not complex instructions...



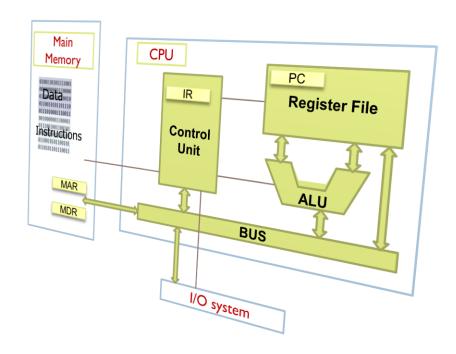
### Machine instructions

but very simple tasks...

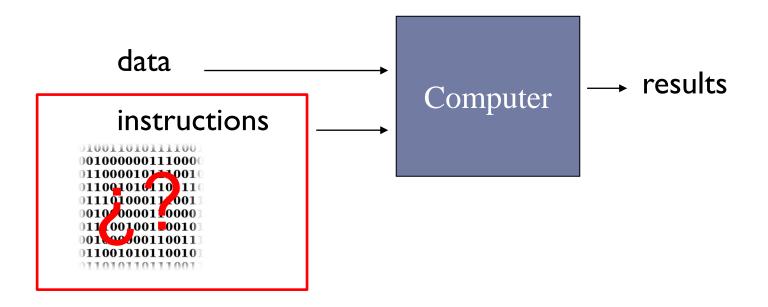


### Machine instructions

- ... performed by the processor:
  - Data transfers
  - Arithmetic
  - Logical
  - Conversion
  - Input/Output
  - System Control
  - Flow control

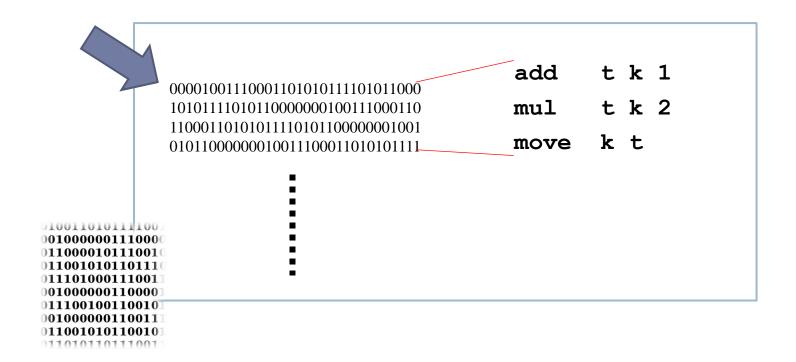


What about the instructions?



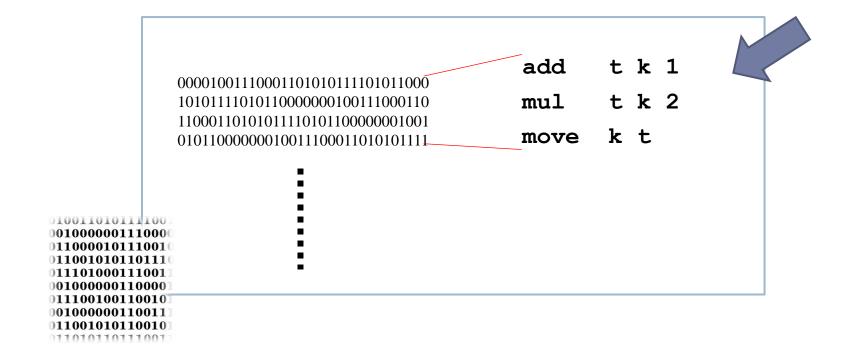
## Definition of program

Program: Ordered sequence of machine instructions that are executed by default in order.



## Assembly language definition

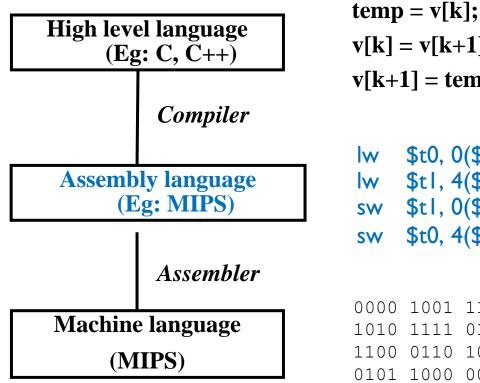
▶ **Assembly language**: programmer-readable language that is the most direct representation of architecture-specific machine code.



## Assembly language definition

- Assembly language: programmer-readable language that is the most direct representation of architecture-specific machine code.
  - Uses symbolic codes to represent instructions
    - ▶ add addition
    - ▶ 1w Load a memory data
  - Uses symbolic codes for data and references
    - \$t0 − register
  - ▶ There is an assembly instruction per machine instruction
    - add \$t1, \$t2, \$t3

# Languages levels



```
v[k] = v[k+1];
v[k+1] = temp;
     $t0, 0($2)
     $t1, 4($2)
     $t1, 0($2)
     $t0, 4($2)
0000 1001 1100 0110 1010 1111 0101 1000
1010 1111 0101 1000 0000 1001 1100 0110
1100 0110 1010 1111 0101 1000 0000 1001
0101 1000 0000 1001 1100 0110 1010 1111
```

### Instruction sets

- Instruction Set Architecture (ISA)
  - Instruction set of a processor
  - Boundary between hardware and software

## Examples:

- ▶ 80×86
- ARM
- MIPS
- RISC-V
- PowerPC
- Etc.

# Characteristics of an instruction set (1/2)

### Operations:

Arithmetic, logic, transfer, control, control, etc.

### Operands:

Registers, memory, the instruction itself

## Type and size of operands:

- bytes: 8 bits
- integers: 16, 32, 64 bits
- floating-point numbers: single precision, double precision, etc.

## Memory addressing:

- Most of them use byte addressing
- They provide instructions for accessing multi-byte elements from a given position

# Characteristics of an instruction set (2/2)

### Addressing modes:

They specify where and how to access operands (register, memory or the instruction itself)

#### Flow control instructions:

- Unconditional jumps
- Conditional jumps
- Procedure calls

## Format and coding of the instruction set:

- Fixed or variable length instructions
  - ▶ 80x86: variable (from I up to I8 bytes)
  - ▶ MIPS, ARM: fixed

# Programming model of a computer

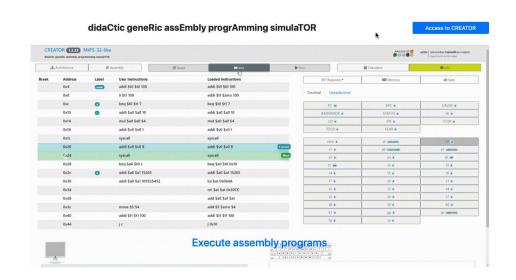
- ▶ A computer offers a programming model that consists of:
  - Instruction set (assembly language)
    - ▶ ISA: Instruction Set Architecture
    - An instruction includes:
      - □ Operation code
      - □ Other elements: registers, memory address, numbers
  - Storing elements
    - Registers
    - Memory
    - Registers of I/O controllers
  - Execution modes

# Motivation to learn assembly

```
#include <stdio.h>
#define PI 3.1416
 #define RADIUS 20
 int main ()
    register int I;
     I=2*PI*RADIUS;
     printf("long: %d\n",l);
      return (0);
```

- Understand how high level languages are executed
  - ▶ C, C++, Java, ...
- Analyze the execution time of high level instructions.
- Useful in specific domains:
  - Compilers
  - Operating Systems
  - Games
  - Embedded systems
  - Etc.

## Motivation to use CREATOR simulator



https://creatorsim.github.io/

- CREATOR: didaCtic geneRic assEmbly progrAmming simulaTOR
- CREATOR can simulate MIPS32 and RISC-V architectures
- CREATOR can be executed from Firefox, Chrome, Edge or Safari

## Goals

- Know how the elements of a highlevel assembly language are represented.:
  - Data types (int, char, ...)
  - ▶ Control structures (if, while, ...)
- Be able to write small programs in assembler

```
.data
PI: .word 3.14156
RADIO: .word 20

.text

li $a0 2
la $t0 PI
lw $t0 ($t0)
la $t1 RADIO
lw $t1 ($t1)
mul $a0 $a0 $t0
mul $a0 $a0 $t1

li $v0 1
syscall
```

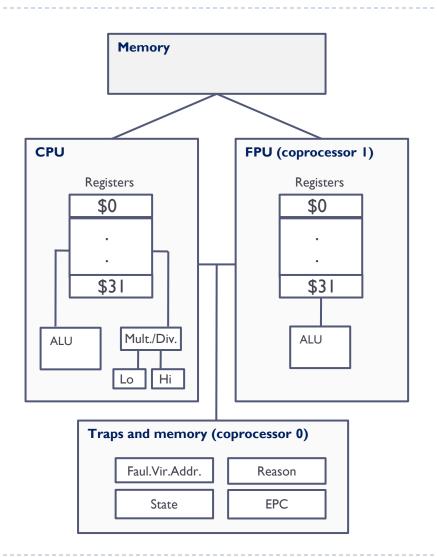
# Example assembler: MIPS 32

- RISC (Reduced Instruction Set Computer) Processor
- Examples of RISC processors:
  - MIPS, ARM, RISC-V



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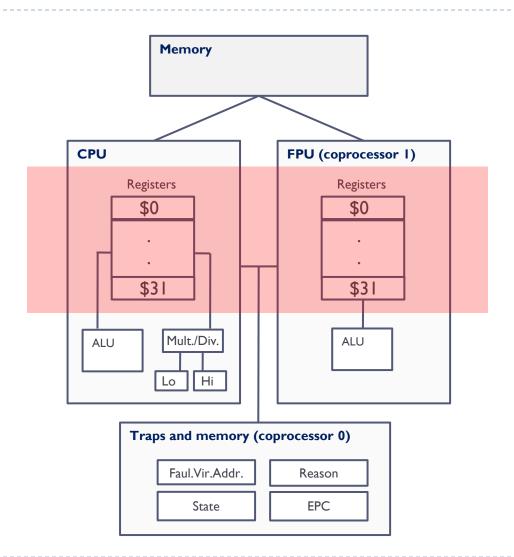


#### MIPS 32

- 32 bits processor
- RISC type
- CPU + auxiliary coprocessors

#### Coprocessor 0

- exceptions, interrupts and virtual memory system
- Coprocessor I
  - FPU (floating point unit)



#### ▶ MIPS 32

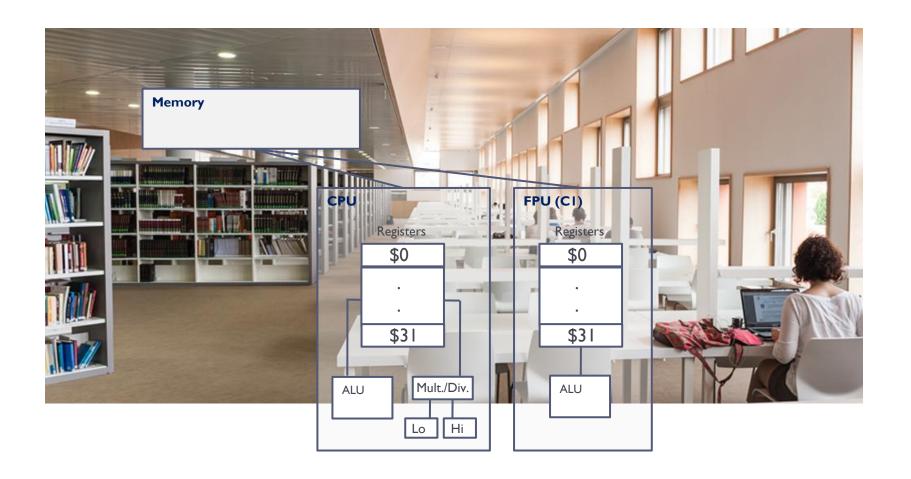
- 32 bits processor
- RISC type
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#### Coprocessor 0

exceptions, interrupts and virtual memory system

#### Coprocessor I

FPU (floating point unit)



# Register File (integers)

Symbolic name	Number	Usage
\$zero	\$0	Constant 0
\$at	<b>\$</b> I	Reserved for assembler
\$v0, \$v1	\$2, \$3	Results of functions
\$a0,, \$a3	\$4,, \$7	Function arguments
\$t0,, \$t7	\$8,, \$15	Temporary (NO preserved across calls)
\$s0,, \$s7	\$16,, \$23	Saved temporary (preserved across calls)
\$t8, \$t9	\$24, \$25	Temporary (NO preserved across calls)
\$k0, \$k1	\$26, \$27	Reserved for operating system
\$gp	\$28	Pointer to global area
\$sp	\$29	Stack pointer
\$fp	\$30	Frame pointer
\$ra	\$31	Return address (used by function calls)

### ▶ There are 32 registers

- Size: 4 bytes (I word)
- Used a \$ at the beginning

#### Use convention:

- Reserved
- Arguments
- Results
- Temporary
- Pointers

# Register File (floating point)

Symbolic name	Usage
\$f0\$f3	Results (like \$v)
\$f4\$f11	Temporals (like \$t)
\$f12\$f15	Arguments (like \$a)
\$f16\$f19	Temporals (like \$t)
\$f20\$f31	Reserved (like \$sv)

### ▶ There are 32 registers

- Size: 4 bytes (I word)
- Used a \$ at the beginning

#### Can be used:

- Simple precision (32 registers)
- Double precision (16 registers)
  - Two consecutives registers are combined into a single double
  - $\rightarrow$  E.g.: \$f0' = (\$f0, \$f1)

## Data transfer

### Copy data:

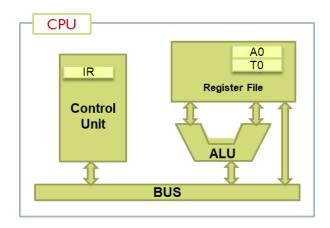
- Between registers
- Between registers and memory (later)

### Examples:

Immediate load (store a value in a register)

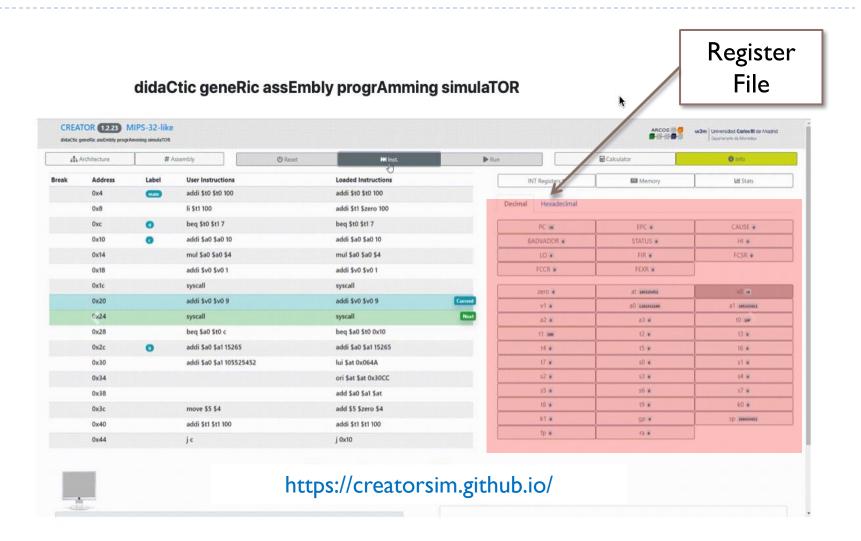
```
▶ li $t0 5
# $t0 ← 5
```

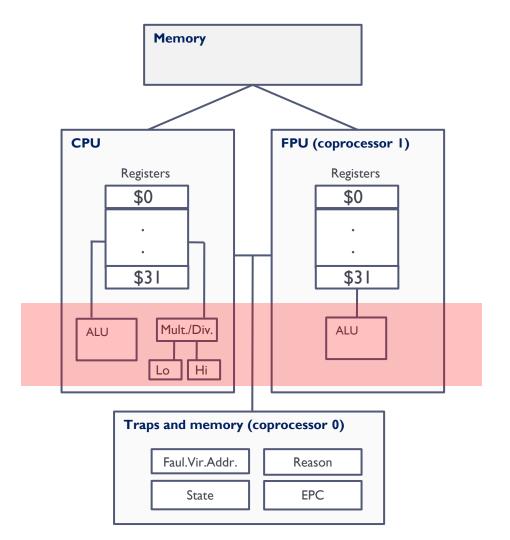
- Register to register
  - ▶ move \$a0 \$t0 # \$a0 ← \$t0



```
move a0 t0 \# BR[a0] = BR[t0]
li t0 \# BR[t0] = IR(li,t0,1)
```

### **CREATOR**





#### ▶ MIPS 32

- 32 bits processor
- RISC type
- CPU + auxiliary coprocessors

#### Coprocessor 0

exceptions, interrupts and virtual memory system

#### Coprocessor I

FPU (floating point unit)

## Arithmetic instructions

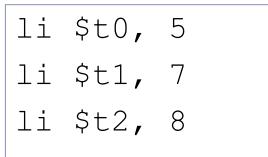
- Integer operations (ALU) or floating-point operations (FPU)
- Examples (ALU):
  - Addition add \$t0, \$t1, \$t2 \$t0 = \$t1 + \$t2 Add with overflow addi \$t0, \$t1, 5 \$t0 = \$t1 + 5 Add with overflow addu \$t0, \$t1, \$t2 \$t0 = \$t1 + \$t2 Add without overflow
  - Subtraction sub \$t0 \$t1 | I
  - Multiplication mul \$t0 \$t1 \$t2
  - Division div \$t0, \$t1, \$t2 \$t0 = \$t1 / \$t2 Integer division rem \$t0, \$t1, \$t2 \$t0 = \$t1 % \$t2 Remainder



# Example

```
int a = 5;
int b = 7;
int c = 8;
int d;
```

$$d = a * (b + c)$$





add \$t1, \$t1, \$t2 mul \$t3, \$t1, \$t0



# Example

```
int a = 5;
int b = 7;
int c = 8;
int d;
```

$$d=-(a*(b-10)+c)$$

```
li $t0, 5
li $t1, 7
li $t2, 8
li $t3 10
```



```
sub $t4, $t1, $t3
mul $t4, $t4, $t0
add $t4, $t4, $t2
li $t5, -1
mul $t4, $t4, $t5
```

## Types of arithmetic operations

- Pure binary or two's complement arithmetic
- Examples:
  - Signed sum (ca2) add \$t0 \$t1 \$t2
  - Immediate signed sumaddi \$t0 \$t1 -5
  - Unsigned sum (binary)addu \$t0 \$t1 \$t2
  - Immediate unsigned sum addiu \$t0 \$t1 2

Without overflow:

```
li $t0 0x7FFFFFFF
li $t1 5
addu $t0 $t0 $t1
```

With overflow:

```
li $t0 0x7FFFFFFF
li $t1 1
add $t0 $t0 $t1
```

## Exercise

```
li $t1 5
li $t2 7
li $t3 8
li $t0 10
sub $t4 $t2 $t0
mul $t4 $t4 $t1
add $t4 $t4 $t3
li $t0 -1
mul $t4 $t4 $t0
```



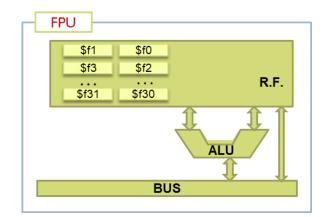
# Exercise (solution)

```
li $t1 5
                                  li $t1 5
li $t2 7
                                  li $t2 7
li $t3 8
                                  li $t3 8
li
  $t0 10
                                  addi $t4 $t2 -10
sub $t4 $t2 $t0
                                 mul $t4 $t4 $t1
mul $t4 $t4 $t1
                                 add $t4 $t4 $t3
add $t4 $t4 $t3
                                 mul $t4 $t4 -1
li $t0 -1
mul $t4 $t4 $t0
```

### Arithmetic: IEEE 754

- ▶ IEEE 754 floating point arithmetic on the FPU
- Examples:
  - Simple precision add add.s \$f0 \$f1 \$f4

    f0 = f1 + f4
  - Double precision add add.d \$f0 \$f2 \$f4
     (f0,f1) = (f2,f3) + (f4,f5)

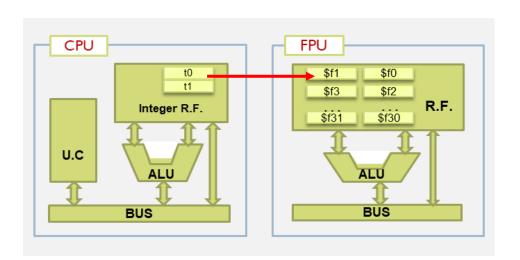


- Load the float value 8.0 in register \$f4: li.s \$f4, 8.0
- Load the double value 12.4 in registers (\$f2, \$f3): li.d \$f2, 12.4
- ▶ Others: add.s, sub.s, mul.s, div.s, abs.s, bclt, bclf, ...

### Data transfer: IEEE 754

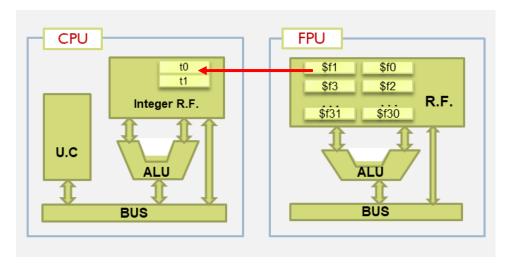
### mtc1 \$t0 \$f1

Move To Coprocessor I (FPU)



### mfc1 \$t0 \$f1

Move From Coprocessor I (FPU)



## Conversion operations

- cvt.s.w \$f2 \$f1
  - Convert from integer (\$f1) to single precision (\$f2)
- cvt.w.s \$f2 \$f1
  - Convert from single precision (\$f1) to integer (\$f2)
- cvt.d.w \$f2 \$f0
  - Convert from integer (\$f0) to double precision (\$f2)
- cvt.w.d \$f2 \$f0
  - Convert from double precision (\$f0) to integer (\$f2)
- cvt.d.s \$f2 \$f0
  - Convert from single precision (\$f0) to double f2)
- cvt.s.d \$f2 \$f0
  - Convert from double precision (\$f0) to single (\$f2)



```
float PI = 3,1415;
int radio = 4;
float longitud;

longitud = PI * radio;
```

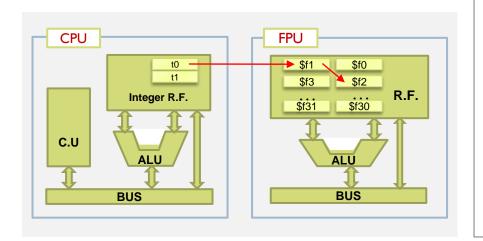
```
.text
.globl main
main:

li.s     $f0     3.1415
     li     $t0     4
```



```
float PI = 3,1415;
int radio = 4;
float longitud;

longitud = PI * radio;
```



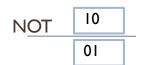
```
.text
.globl main
main:
```

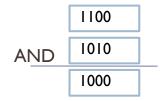
```
li.s $f0 3.1415
li $t0 4
```

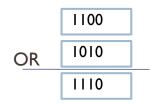
## Logical instructions

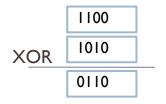
### Boolean operations:

- NOT not \$t0 \$t1 (\$t0 = ! \$t1)
- AND
  and \$t0 \$t1 \$t2 (\$t0 = \$t1 & \$t2)
- or \$t0 \$t1 \$t2 (\$t0 = \$t1 | \$t2)
  ori \$t0 \$t1 80 (\$t0 = \$t1 | 80)
- > XOR
  xor \$t0 \$t1 \$t2 (\$t0 = \$t1 ^ \$t2)









li \$t0, 5 li \$t1, 8

and \$t2, \$t1, \$t0

What is the value of \$t2?



## Example (solution)

li \$t0, 5 li \$t1, 8

and \$t2, \$t1, \$t0

What is the value of \$t2?

000 .... 0101 \$t0 <u>000 ..... 1000</u> \$t1 and 000 ..... 0000 \$t2



## Exercise

li \$t0, 5
li \$t1, 0x007FFFFF

and \$t2, \$t1, \$t0

What does an "and" with 0x007FFFFF allow to do?



## Exercise (solution)

li \$t0, 5 li \$t1, 0x007FFFFF

and \$t2, \$t1, \$t0

What does an "and" with 0x007FFFFF allow to do?



Obtain the 23 least significant bits

The constant used for bit selection is called a mask.

### Shift instructions

- Bits movement
- Examples:
  - Shift right logical srl \$t0 \$t0 4 (\$t0 = \$t0 >> 4 bits)



Shift left logical
sll \$t0 \$t0 5 (\$t0 = \$t0 << 5 bits)</p>



Shift right arithmetic sra \$t0 \$t0 2 (\$t0 = \$t0 >> 2 bits)



li \$t0, 5

li \$t1, 6

sra \$t0, \$t1, 1



• What is the value of \$t0?

srl \$t0, \$t1, 1



• What is the value of \$t0?

# Example (solution)

li \$t0, 5 li \$t1, 6

sra \$t0, \$t1, 1

srl \$t0, \$t1, 1



• What is the value of \$t0?

000 .... 0110 \$t1 shift one bit to right (/2) 000 .... 0011 \$t0



• What is the value of \$t0?

000 .... 0110 \$t1 Shit one bit to left (x2) 000 .... 1100 \$t0

### Rotations

- Bits movement
- Example:
  - Rotate left rol \$t0 \$t0 4 rotate 4 bits
  - Rotate rightror \$t0 \$t0 5rotate 5 bits







# Exercise (solution)

Make a program that detects the sign of a stored number \$t0 and leaves in \$t1 a 1 if it is negative and a 0 if it is positive.



```
li $t0 -3

move $t1 $t0

rol $t1 $t1 1

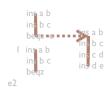
and $t1 $t1 0x00000001
```

## Comparison instructions

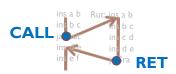
```
> seq $t0, $t1, $t2
       if (\$t I == \$t2) \$t0 = I; else \$t0 = 0 # set if equal
sneq $t0, $t1, $t2
       if (\$t \mid !=\$t2) \$t0 = \mid ; else \$t0 = 0 # set if no equal
sge $t0, $t1, $t2
       ▶ sgt $t0, $t1, $t2
       if (t | > t) t0 = 1; else t0 = 0 # set if greater than
▶ sle $t0, $t1, $t2
       if (t < -t = t ) t < -t = t ; else t < -t = t  set if less or equal
▶ slt $t0, $t1, $t2
       if (\$t \ | \ \$t2) \$t0 = \ \ \ \ ; else \$t0 = \ \ \ # set if less than
```

### Branch instructions

- Change the sequence of instructions to be executed
- Several types:
  - Conditional branches:
    - Branch if value match condition
    - ▶ E.g.: bne \$t0 \$t1 etiqueta1
  - Unconditional branches:
    - Always branch E.g.: j etiqueta2
  - Function calls:
    - Branch with return
    - ► E.g.: jal subrutina l ..... jr \$ra







56

### Branch instructions

- Change the sequence of instructions to be executed
- Several types:
  - Conditional branches:
    - Branch if value match condition
    - ▶ E.g.: bne \$t0 \$t1 etiqueta1

```
ins a b
ins b c
beque a sab
ins b c
ins a b
ins a c
ins d c
beqz
e2
```

```
▶ beq $t0 $t1
                 etiq1
                        # go to etiq1 if $t1 = $t0
▶ bne $t0
           $t1
                  etiq1  # go to etiq1 if $t1 != $t0
                 etiq1 # go to etiq1 if $t1 = 0
begz
     $t1
                  etiq1 # go to etiq1 if $t1 != 0
bnez
     $t1
     $t0
                 etiq1 # go to etiq1 if $t1 > $t0
bgt
           $t1
▶ bge $t0 $t1 etiq1 # go to etiq1 if $t1 >= $t0
▶ blt $t0
                 etiq1 # go to etiq1 if $t1 < $t0
           $t1
▶ ble $t0
                        # go to etiq1 if $t1 <= $t0
            $t1
                  etiq1
```

# Control flow structures if...(1/2)

```
int b1 = 4;
int b2 = 2;

if (b2 == 8) {
   b1 = 0;
}
```

```
li $t0 4
      li $t1 2
      li $t2 8
      bneq $t0 $t2 end1
      li $t0 0
end1:
```



# Control flow structures if-else ...(2/2)

```
int a = 1;
int b = 2;

if (a < b)
{
    // action 1
}
else
{
    // action 2
}</pre>
```



```
li $t1 1
      li $t2 2
      blt $t1 $t2 then1
else1:
      # action 2
      b end1
then1:
      # action 1
end1:
```

# Control flow structures while

```
int i;
                                    li $t0 0
                                    li $t1 10
i=0;
                            while2:
                                    bge $t0 t1 end2
while (i < 10)
                                    # action
                                    addi $t0 $t0 1
   /* action */
                                    b(while2)
   i = i + 1;
                            end2:
```

### Exercise

▶ Calculate I + 2 + 3 + .... + I0 and result in \$tI

```
i=0;
s = 0;
while (i < 10)
  s = s + i;
  i = i + 1;
```



## Exercise (solution)

▶ Calculate I + 2 + 3 + .... + I0 and result in \$tI

```
i=0;
s=0;
while (i < 10)
{
    s = s + i;
    i = i + 1;
}</pre>
```

```
li $t0 0
li $t1 0
li $t2 10
while: bge $t0 t2 end
add $t1 $t1 $t0
addi $t0 $t0 1
b while
end: ...
```

### Exercise

▶ Calculate the number of I's of a register (\$t0). Result in \$t3.

```
i = 0;
n = 45; # number
s = 0;
while (i < 32)
 b = last bit of n
  s = s + b;
  shift n 1 bit to right
  i = i + 1;
```

## Exercise (solution)

▶ Calculate the number of I's of a register (\$t0). Result in \$t3.

```
i = 0;
n = 45;  # number
s=0;
while (i < 32)
{
  b = last bit of n
  s = s + b;
  shift n 1 bit to right
  i = i + 1;
}</pre>
```

```
i = 0;
n = 45; # number
s = 0;
while (i < 32)
  b = n & 1;
  s = s + b;
  n = n >> 1;
  i = i + 1;
```



## Exercise (solution)

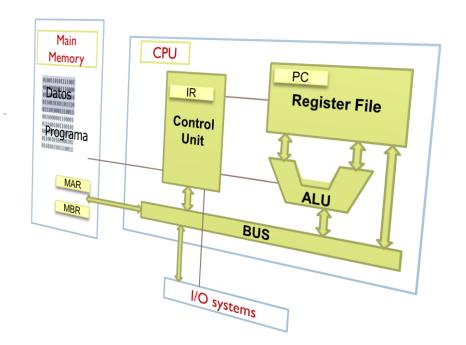
▶ Calculate the number of I's of a register (\$t0). Result in \$t3

```
i = 0;
n = 45;  # number
s=0;
while (i < 32)
{
   b = last bit of n
   s = s + b;
   shift n 1 bit to right
   i = i + 1;
}</pre>
```

```
li $t0 0 #i
       li $t1 45
                   #n
       li $t2 32
       li $t3 0 #s
while1: bge $t0 t2 end1
       and $t4 $t1 1
       add $t3 $t3 $t4
       srl $t1 $t1 1
       addi $t0 $t0 1
       b while1
end1: ...
```

## Types of instructions

- Data transfer
- Arithmetic
- Logical
- Shifting
- Rotation
- Comparison
- Branches
- Conversion
- Input/output
- System calls



## Typical faults

- 1) Poorly designed program
  - Does not do what is requested
  - Incorrectly does what is requested
- 2) Programming directly in assembler
  - Do not code in pseudo-code the algorithm to be implemented
- 3) Write unreadable code
  - Do not tabulate the code
  - Do not comment the assembly code or make reference to the algorithm initially proposed.

Calculate the number of I's of a int in C/Java

### Another solution:

```
int count[256] = \{0,1,1,2,1,2,2,3,1, ... 8\};
int i;
int c = 0;
for (i = 0; i < 4; i++) {
     c = count[n \& 0xFF];
     s = s + c;
     n = n >> 8;
}
printf("There is %d\n", c);
```

 Obtain the 16 first bits of a register (\$t0) and store them in the 16 last bits of other register (\$t1)

## Solution

 Obtain the 16 first bits of a register (\$t0) and store them in the 16 last bits of other register (\$t1)



Shift 16 bits to right

## Compilation process

### High level language

### Assembly language

### Binary language

```
#include <stdio.h>
#define PI 3.1416
#define RADIO 20
int main ()
 int I;
 I=2*PI*RADIO:
 printf("long: %d\n".l) :
 return (0);
```



```
.data
  PI: .word 3.14156
  RADIO: .word 20
.text
  li $a0 2
  la $t0 PI
  lw $t0 ($t0)
  la $t1 RADIO
  lw $t1 ($t1)
  mul $a0 $a0 $t0
  mul $a0 $a0 $t1
  li $v0 1
  syscall
```



Determine if the number stored in \$t2 is even. If \$t2 is even the program stores 1 in \$t1, else stores 0 in \$t1

### Solution

Determine if the number stored in \$t2 is even. If \$t2 is even the program stores 1 in \$t1, else stores 0 in \$t1

```
li $t2 9

li $t1 2

rem $t1 $t2 $t1 # remainder

beq $t1 $0 then # cond.

else: li $t1 0

b end # uncond.

then: li $t1 1

end: ...
```

Determine if the number stored in \$12 is even. If \$12 is even the program stores I in \$11, else stores 0 in \$11. In this case, analyze the last bit

### Solution

Determine if the number stored in \$12 is even. If \$12 is even the program stores I in \$11, else stores 0 in \$11. In this case, analyze the last bit

```
li $t2 9
li $t1 1
and $t1 $t2 $t1  # get the last bit
beq $t1 $0 then  # cond.
else: li $t1 0
b end  # uncond.
then: li $t1 1
end: ...
```

- ► Calculate a<sup>n</sup>
  - a in \$t0
  - ▶ n in \$tl
  - Result in \$t2

```
a=8
n=4;
i=0;
p = 1;
while (i < n)
{
   p = p * a
   i = i + 1;
}</pre>
```

## Solution

#### Calculate a<sup>n</sup>

- a in \$t0
- ▶ n in \$tl
- Result in \$t2

```
a=8
n=4;
i=0;
p = 1;
while (i < n)
{
   p = p * a
   i = i + 1;
}</pre>
```

```
li $t0 8
        li $t1 4
        li
            $t2 1
        li $t4 0
while: bge $t4 $t1 end
        mul $t2 $t2 $t0
        addi $t4 $t4 1
        b while
end:
       move $t2 $t4
```