### **Implementation Note: Unrolling Parameters**

### **Advanced optimization**

Let's say we've implemented a cost function that takes the parameters theta and returns the cost function and returns derivatives, then we can pass this to an advanced optimization algorithm by fminunc (the function fminunc takes the costFunction and initial theta values). Both routines assume that theta and the initial value of theta are parameters vector ( $\mathbb{R}^{n+1}$ ), and it also assumes that, our cost function will return as a second value the gradient which is also a vector ( $\mathbb{R}^{n+1}$ ).

For NNs, our parameters are matrices e.g.

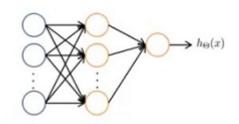
## Neural Network (L=4):

$$\Theta^{(1)},\Theta^{(2)},\Theta^{(3)}$$
 - matrices (Theta1, Theta2, Theta3)  $D^{(1)},D^{(2)},D^{(3)}$  - matrices (D1, D2, D3)

"Unroll" into vectors

# Example

$$s_1 = 10, s_2 = 10, s_3 = 1$$
  
 $\Theta^{(1)} \in \mathbb{R}^{10 \times 11}, \Theta^{(2)} \in \mathbb{R}^{10 \times 11}, \Theta^{(3)} \in \mathbb{R}^{1 \times 11}$   
 $D^{(1)} \in \mathbb{R}^{10 \times 11}, D^{(2)} \in \mathbb{R}^{10 \times 11}, D^{(3)} \in \mathbb{R}^{1 \times 11}$ 



We can use the thetaVec = [ Theta1(:); Theta2(:); Theta3(:)]; notation to unroll the theta matrices into a long vector.

And we can also use the DVec = [D1(:); D2(:); D3(:)]; notation to unroll the D matrices into a big long vector.

To go back the theta matrices we can use:

```
Theta1 = resape(thetaVec(1:110), 10, 11);
Theta2 = resape(thetaVec(111:220), 10, 11);
Theta3 = resape(thetaVec(221:231), 1, 11);
```

**Video Question:** Suppose D1 is a  $10 \times 6$  matrix and D2 is a  $1 \times 11$  matrix. You set:

Which of the following would get D2 back from DVec?

- reshape(DVec(60:71), 1, 11)
- reshape(DVec(61:72), 1, 11)

```
reshape(DVec(61:71), 1, 11)
```

reshape(DVec(60:70), 11, 1)

### **Summary**

With neural networks, we are working with sets of matrices:

```
\Theta^{(1)}, \Theta^{(2)}, \Theta^{(3)}, \dots

D^{(1)}, D^{(2)}, D^{(3)}, \dots
```

In order to use optimizing functions such as "fminunc()", we will want to "unroll" all the elements and put them into one long vector:

```
thetaVector = [ Theta1(:); Theta2(:); Theta3(:); ]
deltaVector = [ D1(:); D2(:); D3(:) ]
```

If the dimensions of Theta1 is 10 x 11, Theta2 is 10 x 11 and Theta3 is 1 x 11, then we can get back our original matrices from the "unrolled" versions as follows:

```
Theta1 = reshape(thetaVector(1:110),10,11)
Theta2 = reshape(thetaVector(111:220),10,11)
Theta3 = reshape(thetaVector(221:231),1,11)
```

To summarize:

#### Learning Algorithm

- $\rightarrow$  Have initial parameters  $\Theta^{(1)}, \Theta^{(2)}, \Theta^{(3)}$ .
- → Unroll to get initialTheta to pass to
- fminunc(@costFunction, initialTheta, options)

```
function [jval, gradientVec] = costFunction (thetaVec) From thetaVec, get \Theta^{(1)}, \Theta^{(2)}, \Theta^{(3)}. Use forward prop/back prop to compute D^{(1)}, D^{(2)}, D^{(3)} and J(\Theta). Unroll D^{(1)}, D^{(2)}, D^{(3)} to get gradientVec.
```