Formal Methods

Lecture 6

(B. Pierce's slides for the book "Types and Programming Languages")

This Saturday, 10 November 2018, room 335 (FSEGA), we will recover the following activities:

- 1 Formal Methods course, 7.30-9.30
- 1 Programming Paradigms course, 9.30-11.30
- 1 Formal Methods course, 11.30-13.30

Programming in the

Continued

Lambda-Calculus,

Normal forms

Recall:

- A normal form is a term that cannot take an evaluation step.
- A stuck term is a normal form that is not a value.

Recursion in the

Lambda-Calculus

Divergence

omega =
$$(\lambda x. x x) (\lambda x. x x)$$

Note that omega evaluates in one step to itself!

So evaluation of omega never reaches a normal form: it diverges.

Divergence

omega =
$$(\lambda x. x x) (\lambda x. x x)$$

Being able to write a divergent computation does not seem very useful in itself. However, there are variants of omega that are *very* useful...

Iterated Application

Suppose f is some λ -abstraction, and consider the following term:

$$Y_f = (\lambda x. f(x x)) (\lambda x. f(x x))$$

Now the "pattern of divergence" becomes more interesting:

```
(\lambda x. f (x x)) (\lambda x. f (x x))
       f((\lambda x, f(x x)) (\lambda x, f(x x)))
   f (f ((\lambda x, f (x x)) (\lambda x, f (x x))))
f (f (f ((\underline{\lambda}x.\underline{f}(x\underline{x}))\underline{\lambda}x.\underline{f}(x\underline{x})))
```

 Y_f is still not very useful, since (like omega), all it does is diverge.

Delaying divergence

```
poisonpill = \lambda y. omega
```

Note that poisonpill is a value — it it will only diverge when we actually apply it to an argument. This means that we can safely pass it as an argument to other functions, return it as a result from functions, etc.

A delayed variant of omega

Here is a variant of omega in which the delay and divergence are a bit more tightly intertwined:

omegav =
$$\lambda y$$
. $(\lambda x$. $(\lambda y$. $(\lambda x \times y))$ $(\lambda x$. $(\lambda y$. $(\lambda y \times x \times y))$ y

Note that omegav is a normal form. However, if we apply it to any argument v, it diverges:

omegav v
$$= \frac{(\lambda y. \quad (\lambda x. \quad (\lambda y. \quad x \quad x \quad y)) \quad (\lambda x. \quad (\lambda y. \quad x \quad x \quad y)) \quad y) \quad v}{-\rightarrow} \\ \frac{(\lambda x. \quad (\lambda y. \quad x \quad x \quad y)) \quad (\lambda x. \quad (\lambda y. \quad x \quad x \quad y)) \quad v}{-\rightarrow} \\ (\lambda y. \quad (\lambda x. \quad (\lambda y. \quad x \quad x \quad y)) \quad (\lambda x. \quad (\lambda y. \quad x \quad x \quad y)) \quad y) \quad v$$

$$= \\ \text{omegav } v$$

Another delayed variant

Suppose f is a function. Define

$$Z_f = \lambda y. (\lambda x. f (\lambda y. x x y)) (\lambda x. f (\lambda y. x x y)) y$$

This term combines the "added f" from Y_f with the "delayed divergence" of omegav.

If we now apply Z_f to an argument v, something interesting happens:

$$Z_f \quad v \\ = \\ \frac{(\lambda y. \quad (\lambda x. \quad f \quad (\lambda y. \quad x \quad x \quad y)) \quad (\lambda x. \quad f \quad (\lambda y. \quad x \quad x \quad y)) \quad y) \quad v}{-\rightarrow} \\ \frac{(\lambda x. \quad f \quad (\lambda y. \quad x \quad x \quad y)) \quad (\lambda x. \quad f \quad (\lambda y. \quad x \quad x \quad y)) \quad v}{-\rightarrow} \\ f \quad (\lambda y. \quad (\lambda x. \quad f \quad (\lambda y. \quad x \quad x \quad y)) \quad (\lambda x. \quad f \quad (\lambda y. \quad x \quad x \quad y)) \quad y) \quad v \\ = \\ f \quad Z_f \quad v \\ \end{cases}$$

Since Z_f and v are both values, the next computation step will be the reduction of f Z_f — that is, before we "diverge," f gets to do some computation.

Now we are getting somewhere.

Recursion

Let

```
f = \lambda fct. \lambda n.

if n=0 then 1

else n * (fct (pred n))
```

f looks just the ordinary factorial function, except that, in place of a recursive call in the last time, it calls the function fct, which is passed as a parameter.

N.b.: for brevity, this example uses "real" numbers and booleans, infix syntax, etc. It can easily be translated into the pure lambda-calculus (using Church numerals, etc.).

We can use Z to "tie the knot" in the definition of f and obtain a real recursive factorial function:

$$Z_f$$
 3
 \longrightarrow^*
 f Z_f 3
 $=$
 $(\lambda \text{fct. } \lambda \text{n. } \dots)$ Z_f 3
 $\longrightarrow^-\longrightarrow^+$
 $3*(Z_f \text{ (pred 3))}$
 \longrightarrow^+
 $3*(Z_f \text{ 2)}$
 \longrightarrow^*
 $3*(Z_f \text{ 2)}$

A Generic Z

If we define

$$Z = \lambda f. Z_f$$

i.e.,

$$\lambda f$$
. λy . $(\lambda x$. f $(\lambda y$. x x $y)) $(\lambda x$. f $(\lambda y$. x x $y)) $y$$$

then we can obtain the behavior of Z_f for any f we like, simply by applying Z to f.

$$Z f \longrightarrow Z_f$$

For example:

```
fact = Z (\lambdafct.

\lambdan.

if n=0 then 1

else n * (fct (pred n)) )
```

Technical Note

The term \overline{Z} here is essentially the same as the fix:

```
Z = \lambda f. \lambda y. (\lambda x. f (\lambda y. x x y)) (\lambda x. f (\lambda y. x x y)) y

fix = \lambda f. (\lambda x. f (\lambda y. x x y)) (\lambda x. f (\lambda y. x x y))
```

Z is hopefully slightly easier to understand, since it has the property that Z f v \rightarrow * f (Z f) v, which fix does not (quite) share.

Testing booleans

Recall:

```
tru = \lambda t. \lambda f. t
fls = \lambda t. \lambda f. f
```

We showed last time that, if b is a boolean (i.e., it behaves like either tru or fls), then, for any values v and w, either

(if b behaves like fls).

A better way

A dummy "unit value," for forcing evaluation of thunks:

unit =
$$\lambda x$$
. x

A "conditional function":

```
test = \lambda b. \lambda t. \lambda f. b t f unit
```

If b is a boolean (i.e., it behaves like either tru or fls), then, for arbitrary terms s and t, either

b (
$$\lambda$$
dummy. s) (λ dummy. t) $-\stackrel{*}{\rightarrow}$ s

(if b behaves like tru) or

b (
$$\lambda$$
dummy. s) (λ dummy. t) $-\stackrel{*}{\rightarrow}$ t

(if b behaves like fls).

The Z Operator

we defined an operator Z that calculates the "fixed point" of a function it is applied to:

```
 \begin{array}{c} z\\ =\\ \lambda f. \ \lambda y. \ (\lambda x. \ f \ (\lambda y. \ x \ x \ y)) \ (\lambda x. \ f \ (\lambda y. \ x \ x \ y)) \ y \end{array}  That is, z \ f \ v \ \stackrel{*}{\longrightarrow} \ f \ (z \ f) \ v.
```

Factorial

As an example, we defined the factorial function in lambda-calculus as follows:

For the sake of the example, we used "regular" booleans, numbers, etc.

This could be translated "straightforwardly" into the pure lambda-calculus.

Let's do this.

Factorial

Factorial

A better version:

```
 \begin{array}{lll} \text{fact} &= & \\ & \text{fix } (\lambda \text{fct.} \\ & \lambda n. \\ & & \text{test (iszro n)} \\ & & & (\lambda \text{dummy. c1)} \\ & & & (\lambda \text{dummy. (times n (fct (prd n)))))} \end{array}
```

```
fact c6 -\stackrel{*}{\rightarrow}
```

```
fact c6
     (λs. λz.
            s ((\lambda s. \lambda z.
                   s ((\lambda s. \lambda z.
                             s ((\lambda s. \lambda z.
                                        s ((\lambda s. \lambda z.
                                                  s ((\lambda s. \lambda z.
                                                             s ((\lambda s. \lambda z. z)
                                                              s z))
                                                    s z))
                                         s z))
                               s z))
                   s z))
             s z))
```

If we enrich the pure lambda-calculus with "regular numbers," we can display church numerals by converting them to regular numbers:

```
realnat = \lambdan. n (\lambdam. succ m) 0
```

Now:

```
realnat (times c2 c2)
- \xrightarrow{*}
succ (succ (succ (succ zero))).
```

Alternatively, we can convert a few specific numbers to the form we want like this:

Now:

```
whack (fact c3) -\overset{*}{\rightarrow}^* \lambda \text{s. } \lambda \text{z. } \text{s (s (s (s (s z)))))}
```

A Larger Example

Head and tail functions for streams:

```
streamhd = \lambdas. fst (s unit)
streamtl = \lambdas. snd (s unit)
```

A stream of increasing numbers:

```
upfrom =
  fix
     (λr.
      λn.
         \lambdadummv.
            pair n (r (scc n)))
```

Some tests:

```
whack (streamhd (upfrom c0))
                    _→* c0
     whack (streamhd (streamtl (upfrom c0)))
                    -→* c2
whack (streamhd (streamtl (upfrom c0))))
```

Mapping over streams:

```
streammap =
  fix
   (\lambda sm.
    \lambda f.
    \lambda s.
    \lambda dummy.
        pair (f (streamhd s)) (sm f (streamtl s)))
```

Some tests:

```
evens = streammap double (upfrom c0);
whack (streamhd evens);
   /* yields c0 */
whack (streamhd (streamtl evens));
   /* yields c2 */
whack (streamhd (streamtl (streamtl evens)));
   /* yields c4 */
```

Equivalence of Lambda Terms

Representing Numbers

We have seen how certain terms in the lambda-calculus can be used to represent natural numbers.

```
c_0 = \lambda s. \quad \lambda z. \quad z
c_1 = \lambda s. \quad \lambda z. \quad s \quad z
c_2 = \lambda s. \quad \lambda z. \quad s \quad (s \quad z)
c_3 = \lambda s. \quad \lambda z. \quad s \quad (s \quad (s \quad z))
```

Representing Numbers

Other lambda-terms represent common operations on numbers:

$$scc = \lambda n. \lambda s. \lambda z. s (n s z)$$

In what sense can we say this representation is "correct"? In particular, on what basis can we argue that see on church numerals corresponds to ordinary successor on numbers?

The naive approach... doesn't work

One possibility:

For each n, the term $scc c_n$ evaluates to c_{n+1} .

Unfortunately, this is false.

E.g.:

```
scc c_2 = (\lambda n. \ \lambda s. \ \lambda z. \ s \ (n \ s \ z)) \ (\lambda s. \ \lambda z. \ s \ (s \ z))
-\rightarrow \lambda s. \ \lambda z. \ s \ ((\lambda s. \ \lambda z. \ s \ (s \ z)) \ s \ z)
\neq \lambda s. \ \lambda z. \ s \ (s \ (s \ z))
= c_3
```

A better approach

Recall the intuition behind the church numeral representation:

- a number *n* is represented as a term that "does something *n* times to something else"
- scc takes a term that "does something n times to something else" and returns a term that "does something n times to something else"

I.e., what we really care about is that $scc\ c_2$ behaves the same as c_3 when applied to two arguments.

```
scc c<sub>2</sub> v w = (\lambda n. \lambda s. \lambda z. s (n s z)) (\lambda s. \lambda z. s (s z)) v w -\rightarrow (\lambda s. \lambda z. s ((\lambda s. \lambda z. s (s z)) s z)) v w -\rightarrow (\lambda z. v ((\lambda s. \lambda z. s (s z)) v z)) w -\rightarrow v ((\lambda s. \lambda z. s (s z)) v w) -\rightarrow v ((\lambda z. v (v z)) w)
```

$$c_3 \vee w = (\lambda s. \lambda z. s (s (s z))) \vee w$$

 $-\rightarrow (\lambda z. \vee (\vee (\vee z))) w$

 $-\rightarrow V (V (V W))$

 $-\rightarrow V (V (V W))$

A general question

We have argued that, although scc c₂ and c₃ do not evaluate to the same thing, they are nevertheless "behaviorally equivalent."

What, precisely, does behavioral equivalence mean?

Intuition

Roughly,

"terms s and t are behaviorally equivalent" should mean:

"there is no 'test' that distinguishes s and t — i.e., no way to put them in the same context and observe different results."

To make this precise, we need to be clear what we mean by a *testing context* and how we are going to *observe* the results of a test.

Examples

```
tru = \lambdat. \lambdaf. t

tru' = \lambdat. \lambdaf. (\lambdax. x) t

fls = \lambdat. \lambdaf. f

omega = (\lambdax. x x) (\lambdax. x x)

poisonpill = \lambdax. omega

placebo = \lambdax. tru

Y_f = (\lambdax. f (x x)) (\lambdax. f (x x))
```

Which of these are behaviorally equivalent?

Observational equivalence

As a first step toward defining behavioral equivalence, we can use the notion of *normalizability* to define a simple notion of *test*.

Two terms s and t are said to be *observationally equivalent* if either both are normalizable (i.e., they reach a normal form after a finite number of evaluation steps) or both diverge.

I.e., we "observe" a term's behavior simply by running it and seeing if it halts.

Observational equivalence

Aside:

- Is observational equivalence a decidable property?
- Does this mean the definition is ill-formed?

Examples

- omega and tru are not observationally equivalent
- tru and fls are observationally equivalent

Behavioral Equivalence

This primitive notion of observation now gives us a way of "testing" terms for behavioral equivalence

Terms s and t are said to be *behaviorally equivalent* if, for every finite sequence of values v_1, v_2, \ldots, v_n , the applications

$$S V_1 V_2 \dots V_n$$

and

$$\mathsf{t} \; \mathsf{v}_1 \; \mathsf{v}_2 \; \ldots \; \mathsf{v}_n$$

are observationally equivalent.

Examples

These terms are behaviorally equivalent:

```
tru = \lambda t. \lambda f. t
tru' = \lambda t. \lambda f. (\lambda x. x) t
```

So are these:

```
omega = (\lambda x. x x) (\lambda x. x x)

Y_f = (\lambda x. f (x x)) (\lambda x. f (x x))
```

These are not behaviorally equivalent (to each other, or to any of the terms above):

```
fls = \lambda t. \lambda f. f
poisonpill = \lambda x. omega
placebo = \lambda x. tru
```

Given terms s and t, how do we *prove* that they are (or are not) behaviorally equivalent?

To prove that s and t are *not* behaviorally equivalent, it suffices to find a sequence of values $v_1 cdots v_n$ such that one of $v_1 cdots v_n cdots v_n$

and

$$t v_1 v_2 \dots v_n$$

diverges, while the other reaches a normal form.

Example:

the single argument unit demonstrates that fls is not behaviorally equivalent to poisonpill:

```
fls unit= (\lambda t. \ \lambda f. \ f) unit -\rightarrow^* \ \lambda f. \ f poisonpill unit diverges
```

Example:

the argument sequence $(\lambda x. x)$ poisonpill $(\lambda x. x)$ demonstrate that tru is not behaviorally equivalent to fls:

```
tru (\lambda x. x) poisonpill (\lambda x. x)
- \rightarrow * (\lambda x. x) (\lambda x. x)
- \rightarrow * \lambda x. x
fls (\lambda x. x) poisonpill (\lambda x. x)
- \rightarrow * poisonpill (\lambda x. x), which diverges
```

To prove that s and t *are* behaviorally equivalent, we have to work harder: we must show that, for *every* sequence of values $v_1 cdots v_n$, either both

and

$$t v_1 v_2 \dots v_n$$

diverge, or else both reach a normal form. How can we do this?

In general, such proofs require some additional machinery that we will not have time to get into in this course (so-called *applicative bisimulation*). But, in some cases, we can find simple proofs. *Theorem*: These terms are behaviorally equivalent:

```
tru = \lambdat. \lambdaf. t
tru' = \lambdat. \lambdaf. (\lambdax. x) t
```

Proof: Consider an arbitrary sequence of values $v_1 \dots v_n$.

- For the case where the sequence has just one element (i.e., n = 1), note that both tru v_1 and tru' v_1 reach normal forms after one reduction step.
- For the case where the sequence has more than one element (i.e., n > 1), note that both tru $v_1 \ v_2 \ v_3 \ \dots \ v_n$ and tru' $v_1 \ v_2 \ v_3 \ \dots \ v_n$ reduce (in two steps) to $v_1 \ v_3 \ \dots \ v_n$. So either both normalize or both diverge.

Theorem: These terms are behaviorally equivalent:

omega =
$$(\lambda x. x x) (\lambda x. x x)$$

 $Y_f = (\lambda x. f (x x)) (\lambda x. f (x x))$

Proof: Both

omega
$$v_1 \dots v_n$$

and

$$Y_f V_1 \dots V_n$$

diverge, for every sequence of arguments $v_1 \dots v_n$.

Lambda Calculus

Inductive Proofs about the

Two induction principles

Like before, we have two ways to prove that properties are true of the untyped lambda calculus.

- Structural induction on terms
- △ Induction on a derivation of $t \rightarrow t'$.

Let's look at an example of each.

Structural induction on terms

To show that a property P holds for all lambda-terms t, it suffices to show that

- P holds when t is a variable;
 - P holds when t is a lambda-abstraction λx. t₁, assuming that P holds for the immediate subterm t₁; and
- P holds when t is an application t₁ t₂, assuming that P holds for the immediate subterms t₁ and t₂.

N.b.: The variant of this principle where "immediate subterm" is replaced by "arbitrary subterm" is also valid. (Cf. *ordinary induction* vs. *complete induction* on the natural numbers.)

An example of structural induction on terms

Define the set of *free variables* in a lambda-term as follows:

$$FV (x) = \{x\}$$

 $FV (\lambda x. t_1) = FV (t_1) \setminus \{x\}$
 $FV (t_1 t_2) = FV (t_1) \cup FV (t_2)$

Define the size of a lambda-term as follows:

$$size(x) = 1$$

 $size(\lambda x. t_1) = size(t_1) + 1$
 $size(t_1 t_2) = size(t_1) + size(t_2) + 1$

Theorem: $|FV(t)| \leq size(t)$.

An example of structural induction on terms

```
Theorem: |FV(t)| \leq size(t).
Proof: By induction on the structure of t.
  If t is a variable, then |FV(t)| = 1 = size(t).
  \triangle If t is an abstraction \lambda x. t_1, then
            |FV (t)|
      = |FV(t_1) \setminus \{x\}| by defin
      \leq |FV(t_1)| by arithmetic
      \leq size(t<sub>1</sub>) by induction
                            hypothesis
      \leq size(t<sub>1</sub>) + 1 by arithmetic
```

by defn.

= size(t)

An example of structural induction on terms

```
Theorem: |FV(t)| \leq size(t).
```

Proof: By induction on the structure of t.

```
If t is an application t<sub>1</sub> t<sub>2</sub>, then
         |FV (t)|
   = |FV(t_1) \cup FV(t_2)|
                              by defn
   \leq max(|FV(t_1)|, |FV(t_2)|) by arithmetic
    \leq max(|size(t_1)|,
                               by IH and
        |size(t_2)|
                                arithmetic
   \leq |size(t_1)| + |size(t_2)| by arithmetic
   \leq |size(t_1)| + |size(t_2)| + by arithmetic
       size(t)
                                    by defn.
```

Induction on derivations

Recall that the reduction relation is defined as the smallest binary relation on terms satisfying the following rules:

$$(\lambda x. t_{12}) \ v_2 \longrightarrow [x \to v_2]t_{12}$$
 (E-AppAbs)
$$\frac{t_1 \longrightarrow t_1'}{t_1 \ t_2 \longrightarrow t_1' \ t_2}$$
 (E-App1)
$$\frac{t_2 \longrightarrow t_2'}{v_1 \ t_2 \longrightarrow v_1 \ t_1'}$$
 (E-App2)

Induction on derivations

Induction principle for the small-step evaluation relation.

To show that a property P holds for all derivations of $t \to t'$, it suffices to show that

- P holds for all derivations that use the rule E-AppAbs;
- P holds for all derivations that end with a use of E-App1 assuming that P holds for all subderivations; and
- P holds for all derivations that end with a use of E-App2 assuming that P holds for all subderivations.

Example

Theorem: if $t \rightarrow t'$ then $FV(t) \supseteq FV(t')$.

Induction on derivations

We must prove, for all derivations of $t \to t'$, that $FV(t) \supseteq FV(t')$.

There are three cases.

If the derivation of $t \to t'$ is just a use of E-AppAbs, then t is $(\lambda x. t_1) v$ and t' is $[x] \to v]t_1$. Reason as follows:

$$FV (t) = FV ((\lambda x. t_1) v)$$

$$= FV (t_1)/\{x\} \cup FV (v)$$

$$\supseteq FV ([x] \rightarrow v]t_1)$$

$$= FV (t')$$

If the derivation ends with a use of E-App1, then t has the form t_1 t_2 and t' has the form t_1' t_2 , and we have a subderivation of $t_1 - \rightarrow t_1'$

By the induction hypothesis, $FV(t_1) \supseteq FV(t_1')$. Now calculate:

$$FV (t) = FV (t_1 t_2)$$

$$= FV (t_1) \cup FV (t_2)$$

$$\supseteq FV (t_1') \cup FV (t_2)$$

$$= FV (t_1' t_2)$$

$$= FV (t')$$

If the derivation ends with a use of E-App2, the argument is similar to the previous case.

More About Bound Variables

Substitution

Our definition of evaluation is based on the "substitution" of values for free variables within terms.

$$(\lambda_{X,t_{12}})$$
 $v_2 \longrightarrow [x \rightarrow v_2]t_{12}$ (E-AppAbs)

But what is substitution, exactly? How do we define it?

Substitution

For example, what does

$$(\lambda_{X}, \chi (\lambda_{Y}, \chi_{Y})) (\lambda_{X}, \chi_{Y})$$

reduce to?

Note that this example is not a "complete program" — the whole term is not closed. We are mostly interested in the reduction behavior of closed terms, but reduction of open terms is also important in some contexts:

- program optimization
- alternative reduction strategies such as "full beta-reduction"

Formalizing Substitution

Consider the following definition of substitution:

```
 \begin{bmatrix} x \to s \\ x \to s \end{bmatrix} x = s \\ x \to s \end{bmatrix} y = y  if x \neq y  [x \to s](\lambda y.t_1) = \lambda y. ([x \to s]t_1)   [x \to s](t_1 t_2) = ([x \to s]t_1)([x \to s]t_2)
```

What is wrong with this definition?

Formalizing Substitution

It substitutes for free and bound variables!

$$[x \rightarrow y](\lambda x. x) = \lambda x.y$$

This is not what we want!

Substitution, take two

```
[x \rightarrow s]x = s
[x \rightarrow s]y = y
[x \rightarrow s](\lambda y.t_1) = \lambda y. ([x \rightarrow s]t_1)
[x \rightarrow s](\lambda x.t_1) = \lambda x. t_1
[x \rightarrow s](t_1 t_2) = ([x \rightarrow s]t_1)([x \rightarrow s]t_2)
```

What is wrong with this definition?

Substitution, take two

What is wrong with this definition? It suffers from *variable capture*!

$$[x \rightarrow y](\lambda y.x) = \lambda x. x$$

This is also not what we want.

Substitution, take three

```
[x \to s]x = s
[x \to s]y = y
[x \to s](\lambda y.t_1) = \lambda y. ([x \to s]t_1)
[x \to s](\lambda x.t_1) = \lambda x. t_1
[x \to s](t_1 t_2) = ([x \to s]t_1)([x \to s]t_2)
if x \neq y, y \notin FV (s)
```

What is wrong with this definition?

Substitution, take three

What is wrong with this definition?

Now substition is a partial function!

E.g.,
$$[x \rightarrow y](\lambda y.x)$$
 is undefined.

But we want an result for every substitution.

Bound variable names shouldn't matter

It's annoying that that the "spelling" of bound variable names is causing trouble with our definition of substitution.

Intuition tells us that there shouldn't be a difference between the functions $\lambda_{X.X}$ and $\lambda_{Y.Y}$. Both of these functions do exactly the same thing.

Because they differ only in the names of their bound variables, we'd like to think that these *are* the same function.

We call such terms alpha-equivalent.

Alpha-equivalence classes

In fact, we can create equivalence classes of terms that differ only in the names of bound variables.

When working with the lambda calculus, it is convenient to think about these *equivalence classes*, instead of raw terms.

For example, when we write $\lambda_{X.X}$ we mean not just this term, but the class of terms that includes $\lambda_{Y.Y}$ and $\lambda_{Z.Z}$.

We can now freely choose a different *representative* from a term's alpha-equivalence class, whenever we need to, to avoid getting stuck.