

# Formal Methods

## Lecture 11

(B. Pierce's slides for the book “Types and Programming Languages”)

Developing an algorithmic  
subtyping relation

## Subtype relation

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$$S <: S \quad (\text{S-REFL})$$

$$\frac{S <: U \quad U <: T}{S <: T} \quad (\text{S-TRANS})$$

$$\{l_i : T_i \mid i \in 1..n+k\} <: \{l_i : T_i \mid i \in 1..n\} \quad (\text{S-RCDWIDTH})$$

$$\frac{\text{for each } i \quad S_i <: T_i}{\{l_i : S_i \mid i \in 1..n\} <: \{l_i : T_i \mid i \in 1..n\}} \quad (\text{S-RCDDEPTH})$$

$$\frac{\{k_j : S_j \mid j \in 1..n\} \text{ is a permutation of } \{l_i : T_i \mid i \in 1..n\}}{\{k_j : S_j \mid j \in 1..n\} <: \{l_i : T_i \mid i \in 1..n\}} \quad (\text{S-RCDPERM})$$

$$\frac{T_1 <: S_1 \quad S_2 <: T_2}{S_1 \rightarrow S_2 <: T_1 \rightarrow T_2} \quad (\text{S-ARROW})$$

$$S <: \text{Top} \quad (\text{S-TOP})$$

## Issues

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For a given subtyping statement, there are multiple rules that could be used last in a derivation.

1. The conclusions of `S-RcdWidth`, `S-RcdDepth`, and `S-RcdPerm` overlap with each other.
2. `S-Refl` and `S-Trans` overlap with every other rule.

## Step 1: simplify record subtyping

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Idea: combine all three record subtyping rules into one “macro rule” that captures all of their effects

$$\frac{\{l_i \mid i \in 1 \dots n\} \subseteq \{k_j \mid j \in 1 \dots m\} \quad k_j = l_i \text{ implies } S_j <: T_i}{\{k_j : S_j \mid j \in 1 \dots m\} <: \{l_i : T_i \mid i \in 1 \dots n\}} \quad (\text{S-Rcd})$$

## Simpler subtype relation

---

$$S <: S \quad (\text{S-Ref1})$$

$$\frac{S <: U \quad U <: T}{S <: T} \quad (\text{S-Trans})$$

$$\frac{\{l_i \mid i \in 1..n\} \subseteq \{k_j \mid j \in 1..m\} \quad k_j = l_i \text{ implies } S_j <: T_i}{\{k_j : S_j \mid j \in 1..m\} <: \{l_i : T_i \mid i \in 1..n\}} \quad (\text{S-Rcd})$$

$$\frac{T_1 <: S_1 \quad S_2 <: T_2}{S_1 \rightarrow S_2 <: T_1 \rightarrow T_2} \quad (\text{S-Arrow})$$

$$S <: \text{Top} \quad (\text{S-Top})$$

## Step 2: Get rid of reflexivity

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Observation: S-Ref1 is unnecessary.

Lemma:  $S <: S$  can be derived for every type  $S$  without using S-Ref1.

## Even simpler subtype relation

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$$\frac{S <: U \quad U <: T}{S <: T} \quad (\text{S-TRANS})$$

$$\frac{\{l_i \mid i \in 1..n\} \subseteq \{k_j \mid j \in 1..m\} \quad k_j = l_i \text{ implies } S_j <: T_i}{\{k_j : S_j \mid j \in 1..m\} <: \{l_i : T_i \mid i \in 1..n\}} \quad (\text{S-RCD})$$

$$\frac{T_1 <: S_1 \quad S_2 <: T_2}{S_1 \rightarrow S_2 <: T_1 \rightarrow T_2} \quad (\text{S-ARROW})$$

$$S <: \text{Top} \quad (\text{S-TOP})$$



## Step 3: Get rid of transitivity

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Observation: S-Trans is unnecessary.

Lemma: If  $S <: T$  can be derived, then it can be derived without using S-Trans.

## “Algorithmic” subtype relation

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$$\vdash_{\Delta} S <: \text{Top} \quad (\text{SA-Top})$$

$$\frac{\vdash_{\Delta} T_1 <: S_1 \quad \vdash_{\Delta} S_2 <: T_2}{\vdash_{\Delta} S_1 \rightarrow S_2 <: T_1 \rightarrow T_2} \quad (\text{SA-Arrow})$$

$$\frac{\{l_i : i \in 1..n\} \subseteq \{k_j : j \in 1..m\} \text{ for each } k_j = l_i, \vdash_{\Delta} S_j <: T_i}{\vdash_{\Delta} \{k_j : S_j : j \in 1..m\} <: \{l_i : T_i : i \in 1..n\}} \quad (\text{SA-Rcd})$$

## Soundness and completeness

---

Theorem:  $S <: T$  iff  $\vdash^A S <: T$ .

Proof: (*Homework*)

Terminology:

- △ The algorithmic presentation of subtyping is *sound* with respect to the original if  $\vdash^A S <: T$  implies  $S <: T$ .  
(Everything validated by the algorithm is actually true.)
- △ The algorithmic presentation of subtyping is *complete* with respect to the original if  $S <: T$  implies  $\vdash^A S <: T$ .  
(Everything true is validated by the algorithm.)

## Subtyping Algorithm (pseudo-code)

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The algorithmic rules can be translated directly into code:

```
subtype(S, T) =  
  if T = Top, then true  
  else if S = S1→S2 and T = T1→T2  
    then subtype(T1, S1) ∧ subtype(S2, T2)  
  else if S = {kj:Sj j ∈ 1..m} and T = {li:Ti i ∈ 1..n}  
    then {li i ∈ 1..n} ⊆ {kj j ∈ 1..m}  
      ∧ for all i ∈ 1..n there is some j ∈ 1..m with kj = li  
        and subtype(Sj, Ti)  
  else false.
```

## Decision Procedures

---

Recall: A *decision procedure* for a relation  $R \subseteq U$  is a total function  $p$  from  $U$  to  $\{true, false\}$  such that  $p(u) = true$  iff  $u \in R$ .

Is our *subtype* function a decision procedure?

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Is our *subtype* function a decision procedure?

Since *subtype* is just an implementation of the algorithmic subtyping rules, we have

1. if  $subtype(S, T) = true$ , then  $\vdash^A S <: T$   
(hence, by soundness of the algorithmic rules,  $S <: T$ )
2. if  $subtype(S, T) = false$ , then not  $\vdash^A S <: T$   
(hence, by completeness of the algorithmic rules, not  $S <: T$ )

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Q: What's missing?

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(hence, by completeness of the algorithmic rules, not  $S <: T$ )

Q: What's missing?

A: How do we know that *subtype* is a *total* function?

Prove it!



## Decision Procedures (take 1)

---

A *decision function* for a relation  $R \subseteq U$  is a *total* function  $p$  from  $U$  to  $\{true, false\}$  such that  $p(u) = true$  iff  $u \in R$ .

## Decision Procedures (take 1)

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A *decision function* for a relation  $R \subseteq U$  is a *total function*  $p$  from  $U$  to  $\{true, false\}$  such that  $p(u) = true$  iff  $u \in R$ .

Example:

$$\begin{aligned}U &= \{1, 2, 3\} \\ R &= \{(1, 2), (2, 3)\}\end{aligned}$$

Note that, for now, we are saying absolutely nothing about *computability*. We'll come back to this in a moment.

## Decision Procedures (take 1)

---

A *decision function* for a relation  $R \subseteq U$  is a *total function*  $p$  from  $U$  to  $\{true, false\}$  such that  $p(u) = true$  iff  $u \in R$ .

Example:

$$\begin{aligned}U &= \{1, 2, 3\} \\ R &= \{(1, 2), (2, 3)\}\end{aligned}$$

The function  $p$  whose graph is

$$\begin{aligned}\{ & ((1, 2), true), ((2, 3), true), \\ & ((1, 1), false), ((1, 3), false), \\ & ((2, 1), false), ((2, 2), false), \\ & ((3, 1), false), ((3, 2), false), ((3, 3), false)\}\end{aligned}$$

is a decision function for  $R$ .

## Decision Procedures (take 1)

---

A *decision function* for a relation  $R \subseteq U$  is a *total* function  $p$  from  $U$  to  $\{true, false\}$  such that  $p(u) = true$  iff  $u \in R$ .

Example:

$$\begin{aligned}U &= \{1, 2, 3\} \\ R &= \{(1, 2), (2, 3)\}\end{aligned}$$

The function  $p'$  whose graph is

$$\{((1, 2), true), ((2, 3), true)\}$$

is *not* a decision function for  $R$ .

## Decision Procedures (take 1)

---

A *decision function* for a relation  $R \subseteq U$  is a *total function*  $p$  from  $U$  to  $\{true, false\}$  such that  $p(u) = true$  iff  $u \in R$ .

Example:

$$\begin{aligned}U &= \{1, 2, 3\} \\ R &= \{(1, 2), (2, 3)\}\end{aligned}$$

The function  $p''$  whose graph is

$$\{((1, 2), true), ((2, 3), true), ((1, 3), false)\}$$

is also *not* a decision function for  $R$ .

## Decision Procedures (take 2)

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Of course, we want a decision procedure to be a *procedure*.

A *decision procedure* for a relation  $R \subseteq U$  is a *computable* total function  $p$  from  $U$  to  $\{true, false\}$  such that  $p(u) = true$  iff  $u \in R$ .

## Example

---

$$U = \{1, 2, 3\}$$

$$R = \{(1, 2), (2, 3)\}$$

## Example

---

$$\begin{aligned}U &= \{1, 2, 3\} \\ R &= \{(1, 2), (2, 3)\}\end{aligned}$$

The function

$p(x, y) =$  *if  $x = 2$  and  $y = 3$  then true  
else if  $x = 1$  and  $y = 2$  then true  
else false*

whose graph is

$\{ ((1, 2), \text{true}), ((2, 3), \text{true}),$   
 $((1, 1), \text{false}), ((1, 3), \text{false}),$   
 $((2, 1), \text{false}), ((2, 2), \text{false}),$   
 $((3, 1), \text{false}), ((3, 2), \text{false}), ((3, 3), \text{false}) \}$

is a decision procedure for  $R$ .



## Example

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$$\begin{aligned}U &= \{1, 2, 3\} \\ R &= \{(1, 2), (2, 3)\}\end{aligned}$$

The recursively defined partial function

$$\begin{aligned}p(x, y) = & \text{ if } x = 2 \text{ and } y = 3 \text{ then true} \\ & \text{ else if } x = 1 \text{ and } y = 2 \text{ then true} \\ & \text{ else if } x = 1 \text{ and } y = 3 \text{ then false} \\ & \text{ else } p(x, y)\end{aligned}$$

whose graph is

$$\{ ((1, 2), \text{true}), ((2, 3), \text{true}), ((1, 3), \text{false}) \}$$

is *not* a decision procedure for  $R$ .

## Subtyping Algorithm

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This recursively defined *total* function is a decision procedure for the subtype relation:

*subtype*(S, T) =

- if  $T = \text{Top}$ , then *true*
- else if  $S = S_1 \rightarrow S_2$  and  $T = T_1 \rightarrow T_2$   
then  $\text{subtype}(T_1, S_1) \wedge \text{subtype}(S_2, T_2)$
- else if  $S = \{k_j : S_j \mid j \in 1..m\}$  and  $T = \{l_i : T_i \mid i \in 1..n\}$   
then  $\{l_i \mid i \in 1..n\} \subseteq \{k_j \mid j \in 1..m\}$   
 $\wedge$  for all  $i \in 1..n$  there is some  $j \in 1..m$  with  $k_j = l_i$   
and  $\text{subtype}(S_j, T_i)$
- else *false*.

To show this, we need to prove:

1. that it returns *true* whenever  $S <: T$ , and
2. that it returns either *true* or *false* on all inputs.

## Subtyping Algorithm

---

But this recursively defined *partial* function is not:

$\text{subtype}(S, T) =$

if  $T = \text{Top}$ , then *true*

else if  $S = S_1 \rightarrow S_2$  and  $T = T_1 \rightarrow T_2$

then  $\text{subtype}(T_1, S_1) \wedge \text{subtype}(S_2, T_2)$

else if  $S = \{k_j : S_j \mid j \in 1..m\}$  and  $T = \{l_i : T_i \mid i \in 1..n\}$

then  $\{l_i \mid i \in 1..n\} \subseteq \{k_j \mid j \in 1..m\}$

$\wedge$  for all  $i \in 1..n$  there is some  $j \in 1..m$  with  $k_j = l_i$

and  $\text{subtype}(S_j, T_i)$  else

$\text{subtype}(T, S)$

# Algorithmic Typing

## Algorithmic typing

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- △ How do we implement a type checker for the lambda-calculus with subtyping?
- △ Given a context  $\Gamma$  and a term  $t$ , how do we determine its type  $T$ , such that  $\Gamma \vdash t : T$ ?

## Issue

---

For the typing relation, we have just one problematic rule to deal with: subsumption.

$$\frac{\Gamma \vdash t : S \quad S \leq T}{\Gamma \vdash t : T} \quad (\text{T-Sub})$$

Where is this rule really needed?

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For the typing relation, we have just one problematic rule to deal with: subsumption.

$$\frac{\Gamma \vdash t : S \quad S \leqslant T}{\Gamma \vdash t : T} \quad (\text{T-Sub})$$

Where is this rule really needed?

For applications. E.g., the term

$$(\lambda r : \{x : \text{Nat}\}. r.x) \{x=0, y=1\}$$

is not typable without using subsumption.

Where else??

## Issue

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For the typing relation, we have just one problematic rule to deal with: subsumption.

$$\frac{\Gamma \vdash t : S \quad S <: T}{\Gamma \vdash t : T} \quad (\text{T-Sub})$$

Where is this rule really needed?

For applications. E.g., the term

$(\lambda r : \{x : \text{Nat}\}. r.x) \{x=0, y=1\}$

is not typable without using subsumption.

Where else?? *Nowhere else!*

But we *conjectured* that applications were the only critical uses of subsumption.



## Plan

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1. Investigate how subsumption is used in typing derivations by looking at examples of how it can be “pushed through” other rules
2. Use the intuitions gained from this exercise to design a new, algorithmic typing relation that
  - △ omits subsumption
  - △ compensates for its absence by enriching the application rule
3. Show that the algorithmic typing relation is essentially equivalent to the original, declarative one

$$\frac{\frac{\Gamma, x:S_1 \vdash s_2 : S_2 \quad S_2 \leqslant T_2}{\Gamma, x:S_1 \vdash s_2 : T_2} \text{ (T-Sub)}}{\Gamma \vdash \lambda x:S_1. s_2 : S_1 \rightarrow T_2} \text{ (T-Abs)}$$

## Example (T-Abs)

---

$$\begin{array}{c}
 \vdots \qquad \qquad \qquad \vdots \\
 \hline
 \Gamma, x:S_1 \vdash s_2 : S_2 \qquad S_2 <: T_2 \\
 \hline
 \Gamma, x:S_1 \vdash s_2 : T_2 \quad (\text{T-SUB}) \\
 \hline
 \Gamma, x:S_1 \vdash s_2 : T_2 \quad (\text{T-ABS}) \\
 \hline
 \Gamma \vdash \lambda x:S_1. s_2 : S_1 \rightarrow T_2
 \end{array}$$

becomes

$$\begin{array}{c}
 \vdots \qquad \qquad \qquad \vdots \\
 \hline
 \Gamma, x:S_1 \vdash s_2 : S_2 \qquad \hline \hline S_1 <: S_1 \quad (\text{S-REFL}) \qquad \hline \hline S_2 <: T_2 \\
 \hline
 \Gamma \vdash \lambda x:S_1. s_2 : S_1 \rightarrow S_2 \quad (\text{T-ABS}) \qquad \hline \hline S_1 \rightarrow S_2 <: S_1 \rightarrow T_2 \quad (\text{S-ARROW}) \\
 \hline
 \Gamma \vdash \lambda x:S_1. s_2 : S_1 \rightarrow T_2 \quad (\text{T-SUB})
 \end{array}$$

## Example (T-Sub with T-Rcd)

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$$\frac{\begin{array}{c} \vdots \\ \hline \Gamma \vdash t_i : S_i \end{array} \quad \begin{array}{c} \vdots \\ \hline S_i <: T_i \end{array}}{\hline \text{for each } i \quad \Gamma \vdash t_i : T_i} \text{ (T-SUB)}$$
$$\frac{\text{for each } i \quad \Gamma \vdash t_i : T_i}{\Gamma \vdash \{l_i = t_i \mid i \in 1..n\} : \{l_i : T_i \mid i \in 1..n\}} \text{ (T-RCD)}$$

## Intuitions

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These examples show that we do not need  $T\text{-Sub}$  to “enable”  $T\text{-Abs}$  or  $T\text{-Rcd}$ : given any typing derivation, we can construct a derivation *with the same conclusion* in which  $T\text{-Sub}$  is never used immediately before  $T\text{-Abs}$  or  $T\text{-Rcd}$ .

What about  $T\text{-App}$ ?

We’ve already observed that  $T\text{-Sub}$  is required for typechecking some applications. So we expect to find that we *cannot* play the same game with  $T\text{-App}$  as we’ve done with  $T\text{-Abs}$  and  $T\text{-Rcd}$ . Let’s see why.

$$\begin{array}{c}
\vdots \\
\hline
\Gamma \vdash s_1 : S_{11} \rightarrow S_{12} \\
\hline
\Gamma \vdash s_1 : T_{11} \rightarrow T_{12} \quad (T\text{-SUB})
\end{array}
\quad
\begin{array}{c}
\vdots \\
\hline
T_{11} <: S_{11} \quad S_{12} <: T_{12} \\
\hline
S_{11} \rightarrow S_{12} <: T_{11} \rightarrow T_{12} \quad (S\text{-ARROW})
\end{array}
\quad
\begin{array}{c}
\vdots \\
\hline
\Gamma \vdash s_2 : T_{11} \\
\hline
\Gamma \vdash s_1 \ s_2 : T_{12} \quad (T\text{-APP})
\end{array}$$

## Example (T-App on the left)

---

$$\begin{array}{c}
 \vdots \qquad \qquad \qquad \vdots \qquad \qquad \qquad \vdots \\
 \hline \Gamma \vdash s_1 : S_{11} \rightarrow S_{12} \qquad \frac{T_{11} <: S_{11} \quad S_{12} <: T_{12}}{S_{11} \rightarrow S_{12} <: T_{11} \rightarrow T_{12}} \text{(S-ARROW)} \qquad \vdots \\
 \hline \Gamma \vdash s_1 : T_{11} \rightarrow T_{12} \qquad \Gamma \vdash s_2 : T_{11} \\
 \hline \Gamma \vdash s_1 \ s_2 : T_{12} \text{(T-APP)}
 \end{array}$$

becomes

$$\begin{array}{c}
 \vdots \qquad \qquad \qquad \vdots \qquad \qquad \qquad \vdots \\
 \hline \Gamma \vdash s_1 : S_{11} \rightarrow S_{12} \qquad \frac{\Gamma \vdash s_2 : T_{11} \quad T_{11} <: S_{11}}{\Gamma \vdash s_2 : S_{11}} \text{(T-SUB)} \qquad \vdots \\
 \hline \Gamma \vdash s_1 \ s_2 : S_{12} \qquad S_{12} <: T_{12} \\
 \hline \Gamma \vdash s_1 \ s_2 : T_{12} \text{(T-SUB)}
 \end{array}$$

## Example (T-App on the right)

---

$$\frac{\frac{\vdots}{\Gamma \vdash s_1 : T_{11} \rightarrow T_{12}} \quad \frac{\frac{\vdots}{\Gamma \vdash s_2 : T_2} \quad T_2 <: T_{11}}{\Gamma \vdash s_2 : T_{11}} \text{ (T-SUB)}}{\Gamma \vdash s_1 \ s_2 : T_{12}} \text{ (T-APP)}$$



## Example (T-App on the right)

---

$$\frac{\frac{\vdots}{\Gamma \vdash s_1 : T_{11} \rightarrow T_{12}} \quad \frac{\frac{\vdots}{\Gamma \vdash s_2 : T_2} \quad \frac{\vdots}{T_2 <: T_{11}}}{\Gamma \vdash s_2 : T_{11}} \text{ (T-SUB)}}{\Gamma \vdash s_1 \ s_2 : T_{12}} \text{ (T-APP)}$$

becomes

$$\frac{\frac{\vdots}{\Gamma \vdash s_1 : T_{11} \rightarrow T_{12}} \quad \frac{\frac{\vdots}{T_2 <: T_{11}} \quad \frac{\vdots}{T_{12} <: T_{12}}}{T_{11} \rightarrow T_{12} <: T_2 \rightarrow T_{12}} \text{ (S-REFL) (S-ARROW)}}{\frac{\Gamma \vdash s_1 : T_{11} \rightarrow T_{12} \quad T_{11} \rightarrow T_{12} <: T_2 \rightarrow T_{12}}{\Gamma \vdash s_1 : T_2 \rightarrow T_{12}} \text{ (T-SUB)}} \quad \frac{\vdots}{\Gamma \vdash s_2 : T_2} \text{ (T-APP)}$$

## Intuitions

---

So we've seen that uses of subsumption can be "pushed" from one of immediately before  $T\text{-App}$ 's premises to the other, but cannot be completely eliminated.

## Example (nested uses of T-Sub)

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$$\frac{\frac{\frac{\cdot}{\Gamma \vdash s : S} \quad \frac{\frac{\cdot}{S <: U}}{\Gamma \vdash s : U} \text{ (T-Sub)}}{\Gamma \vdash s : T} \quad \frac{\frac{\cdot}{U <: T}}{\Gamma \vdash s : T} \text{ (T-Sub)}$$

## Example (nested uses of T-Sub)

---

$$\begin{array}{c}
 \begin{array}{c} \vdots \\ \hline \Gamma \vdash s : S \end{array} \quad \begin{array}{c} \vdots \\ \hline S <: U \end{array} \\
 \hline \Gamma \vdash s : U \quad (T\text{-SUB})
 \end{array}
 \quad
 \begin{array}{c} \vdots \\ \hline U <: T \end{array}$$

$$\hline \Gamma \vdash s : T \quad (T\text{-SUB})$$

becomes

$$\begin{array}{c} \vdots \\ \hline \Gamma \vdash s : S \end{array}
 \quad
 \begin{array}{c} \vdots \\ \hline S <: U \end{array}
 \quad
 \begin{array}{c} \vdots \\ \hline U <: T \end{array}$$

$$\hline S <: T \quad (S\text{-TRANS})$$

$$\hline \Gamma \vdash s : T \quad (T\text{-SUB})$$

## Summary

---

What we've learned:

- ▲ Uses of the  $T\text{-Sub}$  rule can be “pushed down” through typing derivations until they encounter either
  1. a use of  $T\text{-App}$  or
  2. the root for the derivation tree.
- ▲ In both cases, multiple uses of  $T\text{-Sub}$  can be collapsed into a single one.

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What we've learned:

- ▲ Uses of the  $T\text{-Sub}$  rule can be “pushed down” through typing derivations until they encounter either
  1. a use of  $T\text{-App}$  or
  2. the root for the derivation tree.
- ▲ In both cases, multiple uses of  $T\text{-Sub}$  can be collapsed into a single one.

This suggests a notion of “normal form” for typing derivations, in which there is

- ▲ exactly one use of  $T\text{-Sub}$  before each use of  $T\text{-App}$
- ▲ one use of  $T\text{-Sub}$  at the very end of the derivation
- ▲ no uses of  $T\text{-Sub}$  anywhere else.

## Algorithmic Typing

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The next step is to “build in” the use of subsumption in application rules, by changing the T-App rule to incorporate a subtyping premise.

$$\frac{\Gamma \vdash t_1 : T_{11} \rightarrow T_{12} \quad \Gamma \vdash t_2 : T_2 \quad \vdash T_2 <: T_{11}}{\Gamma \vdash t_1 \ t_2 : T_{12}}$$

Given any typing derivation, we can now

1. normalize it, to move all uses of subsumption to either just before applications (in the right-hand premise) or at the very end
2. replace uses of T-App with T-Sub in the right-hand premise by uses of the extended rule above

This yields a derivation in which there is just *one* use of subsumption, at the very end!

## Minimal Types

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But... if subsumption is only used at the very end of derivations, then it is actually *not needed* in order to show that any term is typable!

It is just used to give *more* types to terms that have already been shown to have a type.

In other words, if we dropped subsumption completely (after refining the application rule), we would still be able to give types to exactly the same set of terms — we just would not be able to give as many types to some of them.



## Minimal Types

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If we drop subsumption, then the remaining rules will assign a *unique, minimal* type to each typable term.

For purposes of building a typechecking algorithm, this is enough.

# Final Algorithmic Typing Rules

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$$\frac{x:T \in \Gamma}{\Gamma \vdash x : T} \quad (\text{TA-VAR})$$

$$\frac{\Gamma, x:T_1 \vdash t_2 : T_2}{\Gamma \vdash \lambda x:T_1. t_2 : T_1 \rightarrow T_2} \quad (\text{TA-ABS})$$

$$\frac{\Gamma \vdash t_1 : T_1 \quad T_1 = T_{11} \rightarrow T_{12} \quad \Gamma \vdash t_2 : T_2 \quad \vdash T_2 <: T_{11}}{\Gamma \vdash t_1 \ t_2 : T_{12}} \quad (\text{TA-APP})$$

$$\frac{\text{for each } i \quad \Gamma \vdash t_i : T_i}{\Gamma \vdash \{l_1=t_1 \dots l_n=t_n\} : \{l_1:T_1 \dots l_n:T_n\}} \quad (\text{TA-RCD})$$

$$\frac{\Gamma \vdash t_1 : R_1 \quad R_1 = \{l_1:T_1 \dots l_n:T_n\}}{\Gamma \vdash t_1.l_i : T_i} \quad (\text{TA-PROJ})$$

## Soundness of the algorithmic rules

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Theorem: If  $\Gamma \vdash^A t : T$ , then  $\Gamma \vdash t : T$ .

## Completeness of the algorithmic rules

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Theorem [Minimal Typing]: If  $\Gamma \vdash t : T$ , then  $\Gamma \vdash^A t : S$  for some  $S \leq T$ .

## Completeness of the algorithmic rules

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Theorem [Minimal Typing]: If  $\Gamma \vdash t : T$ , then  $\Gamma \vdash^A t : S$  for some  $S \leq T$ .

Proof: Induction on typing derivation.

(N.b.: All the messing around with transforming derivations was just to build intuitions and decide what algorithmic rules to write down and what property to prove: the proof itself is a straightforward induction on typing derivations.)

# Meets and Joins

## Adding Booleans

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Suppose we want to add booleans and conditionals to the language we have been discussing.

For the *declarative* presentation of the system, we just add in the appropriate syntactic forms, evaluation rules, and typing rules.

$$\Gamma \vdash \text{true} : \text{Bool} \quad (\text{T-True})$$
$$\Gamma \vdash \text{false} : \text{Bool} \quad (\text{T-False})$$
$$\frac{\Gamma \vdash t_1 : \text{Bool} \quad \Gamma \vdash t_2 : T \quad \Gamma \vdash t_3 : T}{\Gamma \vdash \text{if } t_1 \text{ then } t_2 \text{ else } t_3 : T} \quad (\text{T-If})$$

## A Problem with Conditional Expressions

---

For the *algorithmic* presentation of the system, however, we encounter a little difficulty.

What is the minimal type of

```
if true then {x=true,y=false} else  
{x=true,z=true}
```

?



## The Algorithmic Conditional Rule

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More generally, we can use subsumption to give an expression

if  $t_1$  then  $t_2$  else  $t_3$

any type that is a possible type of both  $t_2$  and  $t_3$ .

So the *minimal* type of the conditional is the *least common supertype* (or *join*) of the minimal type of  $t_2$  and the minimal type of  $t_3$ .

$$\frac{\Gamma \vdash t_1 : \text{Bool} \quad \Gamma \vdash t_2 : T_2 \quad \Gamma \vdash t_3 : T_3}{\Gamma \vdash \text{if } t_1 \text{ then } t_2 \text{ else } t_3 : T_2 \vee T_3} \quad (\text{T-If})$$

Does such a type exist for every  $T_2$  and  $T_3$ ??

## Existence of Joins

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Theorem: For every pair of types  $S$  and  $T$ , there is a type  $J$  such that

1.  $S \leq J$

2.  $T \leq J$

3. If  $K$  is a type such that  $S \leq K$  and  $T \leq K$ , then  $J \leq K$ .

I.e.,  $J$  is the smallest type that is a supertype of both  $S$  and  $T$ .

## Examples

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What are the joins of the following pairs of types?

1.  $\{x:\text{Bool}, y:\text{Bool}\}$  and  $\{y:\text{Bool}, z:\text{Bool}\}$ ?
2.  $\{x:\text{Bool}\}$  and  $\{y:\text{Bool}\}$ ?
3.  $\{x:\{a:\text{Bool}, b:\text{Bool}\}\}$  and  $\{x:\{b:\text{Bool}, c:\text{Bool}\}, y:\text{Bool}\}$ ?
4.  $\{\}$  and  $\text{Bool}$ ?
5.  $\{x:\{\}\}$  and  $\{x:\text{Bool}\}$ ?
6.  $\text{Top} \rightarrow \{x:\text{Bool}\}$  and  $\text{Top} \rightarrow \{y:\text{Bool}\}$ ?
7.  $\{x:\text{Bool}\} \rightarrow \text{Top}$  and  $\{y:\text{Bool}\} \rightarrow \text{Top}$ ?

## Meets

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To calculate joins of arrow types, we also need to be able to calculate *meets* (greatest lower bounds)!

Unlike joins, meets do not necessarily exist.

E.g.,  $\text{Bool} \rightarrow \text{Bool}$  and  $\{\}$  have *no* common subtypes, so they certainly don't have a greatest one!

## Existence of Meets

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Theorem: For every pair of types  $S$  and  $T$ , if there is any type  $N$  such that  $N <: S$  and  $N <: T$ , then there is a type  $M$  such that

1.  $M <: S$
2.  $M <: T$
3. If  $O$  is a type such that  $O <: S$  and  $O <: T$ , then  $O <: M$ .

I.e.,  $M$  (when it exists) is the largest type that is a subtype of both  $S$  and  $T$ .

*Jargon:* In the simply typed lambda calculus with subtyping, records, and booleans...

- △ The subtype relation *has joins*
- △ The subtype relation *has bounded meets*

## Examples

---

What are the meets of the following pairs of types?

1.  $\{x:\text{Bool}, y:\text{Bool}\}$  and  $\{y:\text{Bool}, z:\text{Bool}\}$ ?
2.  $\{x:\text{Bool}\}$  and  $\{y:\text{Bool}\}$ ?
3.  $\{x:\{a:\text{Bool}, b:\text{Bool}\}\}$  and  $\{x:\{b:\text{Bool}, c:\text{Bool}\}, y:\text{Bool}\}$ ?
4.  $\{\}$  and  $\text{Bool}$ ?
5.  $\{x:\{\}\}$  and  $\{x:\text{Bool}\}$ ?
6.  $\text{Top} \rightarrow \{x:\text{Bool}\}$  and  $\text{Top} \rightarrow \{y:\text{Bool}\}$ ?
7.  $\{x:\text{Bool}\} \rightarrow \text{Top}$  and  $\{y:\text{Bool}\} \rightarrow \text{Top}$ ?

# Calculating Joins

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$$S \vee T = \begin{cases} \text{Bool} & \text{if } S = T = \text{Bool} \\ M_1 \rightarrow J_2 & \text{if } S = S_1 \rightarrow S_2 \quad T = T_1 \rightarrow T_2 \\ & S_1 \wedge T_1 = M_1 \quad S_2 \vee T_2 = J_2 \\ \{j_l : J_l \mid l \in 1..q\} & \text{if } S = \{k_j : S_j \mid j \in 1..m\} \\ & T = \{l_i : T_i \mid i \in 1..n\} \\ & \{j_l \mid l \in 1..q\} = \{k_j \mid j \in 1..m\} \cap \{l_i \mid i \in 1..n\} \\ & S_j \vee T_i = J_l \quad \text{for each } j_l = k_j = l_i \\ \text{Top} & \text{otherwise} \end{cases}$$

## Calculating Meets

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$S \wedge T =$

$\left\{ \begin{array}{ll} S & \text{if } T = \text{Top} \\ T & \text{if } S = \text{Top} \\ \text{Bool} & \text{if } S = T = \text{Bool} \\ J_1 \rightarrow M_2 & \text{if } S = S_1 \rightarrow S_2 \quad T = T_1 \rightarrow T_2 \\ & S_1 \vee T_1 = J_1 \quad S_2 \wedge T_2 = M_2 \\ \{m_l : M_l \mid l \in 1..q\} & \text{if } S = \{k_j : S_j \mid j \in 1..m\} \\ & T = \{l_i : T_i \mid i \in 1..n\} \\ & \{m_l \mid l \in 1..q\} = \{k_j \mid j \in 1..m\} \cup \{l_i \mid i \in 1..n\} \\ & S_j \wedge T_i = M_l \quad \text{for each } m_l = k_j = l_i \\ & M_l = S_j \quad \text{if } m_l = k_j \text{ occurs only in } S \\ & M_l = T_i \quad \text{if } m_l = l_i \text{ occurs only in } T \\ \text{fail} & \text{otherwise} \end{array} \right.$