## Formal Methods

### Lecture 5

(B. Pierce's slides for the book "Types and Programming" Languages")

# Review (and more details)

**Operational Semantics** 

#### **Abstract Machines**

An abstract machine consists of:

- a set of states
- a transition relation on states, written -→

For the simple languages we are considering at the moment, the term being evaluated is the whole state of the abstract machine.

#### Operational semantics for Booleans

#### Syntax of terms and values

```
t ::= terms
    true constant true
    false constant false
    if t then t else t conditional

v ::= values
    true false false false value
```

#### **Evaluation Relation on Booleans**

The evaluation relation  $t \to t'$  is the smallest relation closed under the following rules:

```
if true then t2 else t3 \rightarrow t2 (E-IfTrue)

if false then t2 else t3 \rightarrow t3 (E-IfFalse)

t_1 \rightarrow t_1'
if t1 then t2 else t3 \rightarrow if t_1' then t2 else t3
```

#### Evaluation, more explicitly

 $\rightarrow$  is the smallest two-place relation closed under the following rules:

```
((if true then t2 else t3), t2) \in -\rightarrow

((if false then t2 else t3), t3) \in -\rightarrow

(t1, t'1) \in -\rightarrow

((if t1 then t2 else t3), (if t'1 then t2 else t3)) \in -\rightarrow
```

# Reasoning about Evaluation

#### **Derivations**

We can record the "justification" for a particular pair of terms that are in the evaluation relation in the form of a tree.

#### Terminology:

- These trees are called derivation trees (or just derivations).
- The final statement in a derivation is its conclusion.
- We say that the derivation is a witness for its conclusion (or a proof of its conclusion) — it records all the reasoning steps that justify the conclusion.

#### Observation

*Lemma:* Suppose we are given a derivation tree D witnessing the pair (t, t') in the evaluation relation. Then either

- 1. the final rule used in D is E-IfTrue and we have t = if true then  $t_2$  else  $t_3$  and  $t' = t_2$ , for some  $t_2$  and  $t_3$ , or
- 2. the final rule used in D is E-IfFalse and we have  $t = if false then t_2 else t_3 and t' = t_3$ , for some  $t_2$  and  $t_3$ , or
- 3. the final rule used in D is E-If and we have  $t = if t_1$  then  $t_2$  else  $t_3$  and  $t' = if t_1$  then  $t_2$  else  $t_3$ , for some  $t_1, t'$ ,  $t_2$ , and  $t_3$ ; moreover, the immediate subderivation of D witnesses  $(t_1, t'_1) \in -\rightarrow$ .

#### Induction on Derivations

We can now write proofs about evaluation "by induction on derivation trees."

Given an arbitrary derivation D with conclusion  $t \to t'$ , we assume the desired result for its immediate sub-derivation (if any) and proceed by a case analysis (using the previous lemma) of the final evaluation rule used in constructing the derivation tree.

#### Induction on Derivations — Example

Theorem: If  $t \to t'$ , i.e., if  $(t, t') \in \to$ , then size(t) > size(t'). Proof: By induction on a derivation D of  $t \to t'$ .

- 1. Suppose the final rule used in D is E-IfTrue, with t = if true then t<sub>2</sub> else t<sub>3</sub> and t' = t<sub>2</sub>. Then the result is immediate from the definition of *size*.
- 2. Suppose the final rule used in D is E-IfFalse, with t = if false then  $t_2$  else  $t_3$  and  $t' = t_3$ . Then the result is again immediate from the definition of *size*.
- 3. Suppose the final rule used in D is E-If, with t = if t₁ then t₂ else t₃ and t' = if t'₁ then t₂ else t₃, where (t₁, t₁') ∈ → is witnessed by a derivation D₁. By the induction hypothesis, size(t₁) > size(t₁'). But then, by the definition of size, we have size(t) > size(t').

#### Normal forms

A normal form is a term that cannot be evaluated any further — i.e., a term t is a normal form (or "is in normal form") if there is no t such that  $t \to t$ .

A normal form is a state where the abstract machine is halted — i.e., it can be regarded as a "result" of evaluation.

Recall that we intended the set of *values* (the boolean constants true and false) to be exactly the possible "results of evaluation." Did we get this definition right?

#### Values = normal forms

Theorem: A term  $\mathfrak{t}$  is a value iff it is in normal form. Proof:

The  $\Rightarrow$  direction is immediate from the definition of the evaluation relation.

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For the  $\Leftarrow$ = direction, it is convenient to prove the contrapositive: If t is *not* a value, then it is *not* a normal form. The argument goes by induction on t.

Note, first, that t must have the form if  $t_1$  then  $t_2$  else  $t_3$  (otherwise it would be a value). If  $t_1$  is true or false, then rule E-IfTrue or E-IfFalse applies to t, and we are done.

Otherwise, t<sub>1</sub> is not a value and so, by the induction hypothesis,

there is some t ${'}_1$  such that t ${_1} \longrightarrow {_t}{'_1}$  . But then rule E-If yields if  ${_t}_1$  then t\_2 else t\_3  $\longrightarrow$  if t\_1 then t\_2 else t\_3

i.e., t is not in normal form.

#### **Numbers**

#### New syntactic forms

```
succ t
      pred t
      iszero t
       nv
nv
       succ nv
```

```
terms
constant zero
successor
predecessor
zero test
```

values numeric value

numeric values zero value successor value New evaluation rules

$$t \rightarrow t'$$

$$\frac{t_1 - \rightarrow t_1'}{\text{succ } t_1 - \rightarrow \text{succ } t_1'}$$

$$\text{pred } 0 - \rightarrow 0$$

$$\text{pred } (\text{succ } \text{nv1}) - \rightarrow \text{nv1}$$

$$\frac{t_1 - \rightarrow t_1'}{\text{pred } t_1 - \rightarrow \text{pred } t_1'}$$

$$\text{iszero } 0 - \rightarrow \text{true}$$

$$\frac{t_1 - \rightarrow t_1'}{\text{succ } \text{nv1}} - \rightarrow \text{false (E-IszeroSucc)}$$

$$\frac{t_1 - \rightarrow t_1'}{\text{iszero } t_1 - \rightarrow \text{iszero } t_1'}$$
(E-Iszero)

#### Values are normal forms

Our observation a few slides ago that all values are in normal form still holds for the extended language.

Is the converse true? I.e., is every normal form a value?

#### Values are normal forms, but we have stuck terms

Is the converse true? I.e., is every normal form a value? No: some terms are *stuck*.

Formally, a stuck term is one that is a normal form but not a value. What are some examples?

Stuck terms model run-time errors.

#### Multi-step evaluation.

The *multi-step evaluation* relation,  $\stackrel{*}{-} \rightarrow$  , is the reflexive, transitive closure of single-step evaluation.

I.e., it is the smallest relation closed under the following rules:

$$t \xrightarrow{-\rightarrow t'} t$$

$$t \xrightarrow{-\rightarrow^* t'} t$$

$$t \xrightarrow{-\rightarrow^* t'} t' \xrightarrow{-\rightarrow^* t''} t'$$

#### Termination of evaluation

Theorem: For every t there is some normal form t' such that t' = t'.

First, recall that single-step evaluation strictly reduces the size of the term:

if 
$$t \rightarrow t'$$
, then  $size(t) > size(t')$ 

Now, assume (for a contradiction) that

$$t_0, t_1, t_2, t_3, t_4, \dots$$

is an infinite-length sequence such that

$$t_0 \longrightarrow t_1 \longrightarrow t_2 \longrightarrow t_3 \longrightarrow t_4 \longrightarrow \cdots$$

▲ Then

$$size(t_0) > size(t_1) > size(t_2) > size(t_3) > \dots$$

But such a sequence cannot exist — contradiction!

#### **Termination Proofs**

Most termination proofs have the same basic form:

```
Theorem: The relation R \subseteq X \times X is terminating — i.e., there are no infinite sequences x_0, x_1, x_2, etc. such that (x_i, x_{i+1}) \in R for each i.

Proof:
```

- 1. Choose
- a well-founded set (W, <) i.e., a set W with a partial order < such that there are no infinite descending chains  $w_0 > w_1 > w_2 > \dots$  in W
- $\Delta$  a function f from X to W
- 2. Show f(x) > f(y) for all  $(x, y) \in R$
- 3. Conclude that there are no infinite sequences  $x_0$ ,  $x_1$ ,  $x_2$ , etc. such that  $(x_i, x_{i+1}) \in R$  for each i, since, if there were, we could construct an infinite descending chain in W.

The Lambda Calculus

#### The lambda-calculus

- If our previous language of arithmetic expressions was the simplest nontrivial programming language, then the lambda-calculus is the simplest *interesting* programming language...
  - Turing complete
  - higher order (functions as data)
- Indeed, in the lambda-calculus, *all* computation happens by means of function abstraction and application.
- The base of programming language research
- The foundation of many real-world programming language designs (including ML, Haskell, Scheme, Lisp, ...)

#### **Intuitions**

Suppose we want to describe a function that adds three to any number we pass it. We might write

```
plus3 x = succ (succ (succ x))

That is, "plus3 x is succ (succ (succ x))."

O: What is plus3 itself?
```

#### **Intuitions**

Suppose we want to describe a function that adds three to any number we pass it. We might write

```
plus3 x = succ (succ (succ x))
```

That is, "plus3 x is succ (succ (succ x))."

Q: What is plus3 itself?

A: plus 3 is the function that, given x, yields succ (succ (succ x)).

```
plus3 = \lambda x. succ (succ (succ x))
```

This function exists independent of the name plus3.

 $\lambda x$ . t is written "fun  $x \rightarrow t$ " in OCaml.

So plus 3 (succ 0) is just a convenient shorthand for "the function that, given x, yields succ (succ (succ x)), applied to succ 0."

```
plus3 (succ 0)
=
(\lambda x. succ (succ (succ x)) (succ 0)
```

#### **Abstractions over Functions**

#### Consider the $\lambda$ -abstraction

```
g = \lambda f. f (f (succ 0))
```

Note that the parameter variable f is used in the *function* position in the body of g. Terms like g are called *higher-order* functions. If we apply g to an argument like plus3, the "substitution rule" yields a nontrivial computation:

```
g plus3
= (\lambda f. f (f (succ 0))) (\lambda x. succ (succ (succ x)))
i.e. (\lambda x. succ (succ (succ x)))
((\lambda x. succ (succ (succ x))) (succ 0))
i.e. (\lambda x. succ (succ (succ x)))
(succ (succ (succ (succ 0))))
i.e. succ (succ (succ (succ (succ (succ (succ 0))))))
```

#### **Abstractions Returning Functions**

Consider the following variant of g:

double = 
$$\lambda f$$
.  $\lambda y$ .  $f(f y)$ 

I.e., double is the function that, when applied to a function f, yields a *function* that, when applied to an argument y, yields f(y).

#### Example

```
double plus3 0
          (\lambda f. \lambda y. f (f y))
             (\lambda x. \text{ succ } (\text{succ } (\text{succ } x)))
          (\lambda v. (\lambda x. succ (succ (succ x)))
                     ((\lambda x. succ (succ (succ x))) v))
             0
i .e.
          (\lambda x. \text{ succ } (\text{succ } (\text{succ } x)))
                     ((\lambda x. succ (succ (succ x))) 0)
i .e.
          (\lambda x. succ (succ (succ x)))
                     (succ (succ (succ 0)))
i .e.
          succ (succ (succ (succ (succ (succ 0)))))
```

#### The Pure Lambda-Calculus

As the preceding examples suggest, once we have  $\lambda$ -abstraction and application, we can throw away all the other language primitives and still have left a rich and powerful programming language.

In this language — the "pure lambda-calculus"— everything is a function.

- Variables always denote functions
- Functions always take other functions as parameters
- The result of a function is always a function

#### **Syntax**

```
t ::= terms
x variable

$\lambda x. t abstraction
t t application
```

#### Terminology:

- terms in the pure  $\lambda$ -calculus are often called  $\lambda$ -terms
- $\lambda$  terms of the form  $\lambda x$ . t are called  $\lambda$ -abstractions or just abstractions

### Syntactic conventions

Since  $\lambda$ -calculus provides only one-argument functions, all multi-argument functions must be written in curried style.

The following conventions make the linear forms of terms easier to read and write:

Application associates to the left

**E.g.**, 
$$t u v$$
 **means**  $(t u) v$ , **not**  $t (u v)$ 

Bodies of  $\lambda$ - abstractions extend as far to the right as possible

```
E.g., \lambda x. \lambda y. x y means \lambda x. (\lambda y. x y), not \lambda x. (\lambda y. x) y
```

#### Scope

The  $\lambda$ -abstraction term  $\lambda x$ . t binds the variable x. The scope of this binding is the body t.

Occurrences of x inside t are said to be *bound* by the abstraction. Occurrences of x that are *not* within the scope of an abstraction binding x are said to be *free*.

$$\lambda x$$
.  $\lambda y$ .  $x y z$   $\lambda x$ .  $(\lambda y$ .  $z y) y$ 

#### **Values**

ν ..– λx. t values abstraction value

# **Operational Semantics**

## Computation rule:

$$(\lambda x. t_{12}) v_2 \longrightarrow [x \rightarrow v_2]t_{12}$$
 (E-AppAbs)

Notation:  $[x \rightarrow v_2]t_{12}$  is "the term that results from substituting free occurrences of x in  $t_{12}$  with  $v_2$ ."

# **Operational Semantics**

### Congruence rules:

$$\frac{t_1 \xrightarrow{-} t_1'}{t_1 \ t_2 \xrightarrow{-} t_1'} t_2 \tag{E-App1}$$

$$\frac{t_2 \xrightarrow{-} t_2'}{v_1 \quad t_2 \xrightarrow{-} v_1 \quad t_2'} \tag{E-App2}$$

## **Terminology**

A term of the form  $(\lambda x. t) v$ 

- that is, a  $\lambda$ -abstraction applied to a *value*
- is called a redex (short for "reducible expression").

## Alternative evaluation strategies

Strictly speaking, the language we have defined is called the *pure*, *call-by-value lambda-calculus*.

The evaluation strategy we have chosen — *call by value* — reflects standard conventions found in most mainstream languages.

#### Some other common ones:

- Call by name (cf. Haskell)
- Normal order (leftmost/outermost)
- Full (non-deterministic) beta-reduction

# Programming in the

Lambda-Calculus

# Multiple arguments

Above, we wrote a function double that returns a function as an argument.

double = 
$$\lambda f$$
.  $\lambda y$ .  $f(f y)$ 

This idiom — a  $\lambda$ -abstraction that does nothing but immediately yield another abstraction — is very common in the  $\lambda$ -calculus.

In general,  $\lambda x$ .  $\lambda y$ . t is a function that, given a value v for x, yields a function that, given a value u for y, yields t with v in place of x and u in place of y.

That is,  $\lambda x$ .  $\lambda y$ . t is a two-argument function.

(Recall the discussion of currying in OCaml.)

# Syntactic conventions

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Application associates to the left

 $^{\scriptscriptstyle \Delta}$  Bodies of  $\lambda\text{-}$  abstractions extend as far to the right as possible

E.g., 
$$\lambda x$$
.  $\lambda y$ .  $x$   $y$  means  $\lambda x$ .  $(\lambda y$ .  $x$   $y)$ , not  $\lambda x$ .  $(\lambda y$ .  $x)$   $y$ 

## The "Church Booleans"

```
tru = \lambda t. \lambda f. t
fls = \lambda t. \lambda f. f
```

```
tru v w
= (\lambda t. \lambda f. t)_{v} \text{ w} \text{ by definition}
- \rightarrow (\lambda f._{v})_{w} \text{ reducing the underlined redex}
- \rightarrow v \text{ reducing the underlined redex}
fls v w
= (\lambda t. \lambda f. f)_{v} \text{ by definition}
- \rightarrow (\lambda f._{f})_{w} \text{ reducing the underlined redex}
- \rightarrow w \text{ reducing the underlined redex}
```

#### **Functions on Booleans**

not = 
$$\lambda b$$
. b fls tru

That is, not is a function that, given a boolean value v, returns fls if v is tru and tru if v is fls.

### **Functions on Booleans**

and = 
$$\lambda b$$
.  $\lambda c$ .  $b$   $c$  fls

That is, and is a function that, given two boolean values v and w, returns w if v is tru and fls if v is fls

Thus and v w yields tru if both v and w are tru and fls if either v or w is fls.

#### **Pairs**

```
pair = \lambda f. \lambda s. \lambda b. b f s
fst = \lambda p. p tru
snd = \lambda p. p fls
```

That is, pair v w is a function that, when applied to a boolean value b, applies b to v and w.

By the definition of booleans, this application yields v if b is tru and w if b is fls, so the first and second projection functions fst and snd can be implemented simply by supplying the appropriate boolean.

## Example

```
fst (pair v w)

= fst ((\underline{\lambda}f, \underline{\lambda}s, \underline{\lambda}b, \underline{b}, \underline{f}, \underline{s}), \underline{v}, \underline{w}) by definition

--> fst ((\underline{\lambda}s, \underline{\lambda}b, \underline{b}, \underline{v}, \underline{s}), \underline{w}) reducing

--> fst (\underline{\lambda}b, \underline{b}, \underline{v}, \underline{w}) reducing

--> (\underline{\lambda}b, \underline{b}, \underline{v}, \underline{w}) by definition

--> (\underline{\lambda}b, \underline{b}, \underline{v}, \underline{w}) reducing

reducing

reducing as

-->* v before.
```

#### Church numerals

Idea: represent the number n by a function that "repeats some action n times."

```
c_0 = \lambda s. \quad \lambda z. \quad z
c_1 = \lambda s. \quad \lambda z. \quad s \quad z
c_2 = \lambda s. \quad \lambda z. \quad s \quad (s \quad z)
c_3 = \lambda s. \quad \lambda z. \quad s \quad (s \quad (s \quad z))
```

That is, each number n is represented by a term  $c_n$  that takes two arguments, s and z (for "successor" and "zero"), and applies s, n times, to z.

## **Functions on Church Numerals**

#### Successor:

```
scc = \lambda n. \lambda s. \lambda z. s (n s z)
```

#### Addition:

```
plus = \lambda m. \lambda n. \lambda s. \lambda z. m s (n s z)
```

#### Multiplication:

```
times = \lambda m. \lambda n. m (plus n) c_0
```

#### Zero test:

```
iszro = \lambda m. m (\lambda x. fls) tru
```

What about predecessor?

## Predecessor

```
zz = pair c_0 c_0

ss = \lambda p. pair (snd p) (scc (snd p))

prd = \lambda m. fst (m ss zz)
```