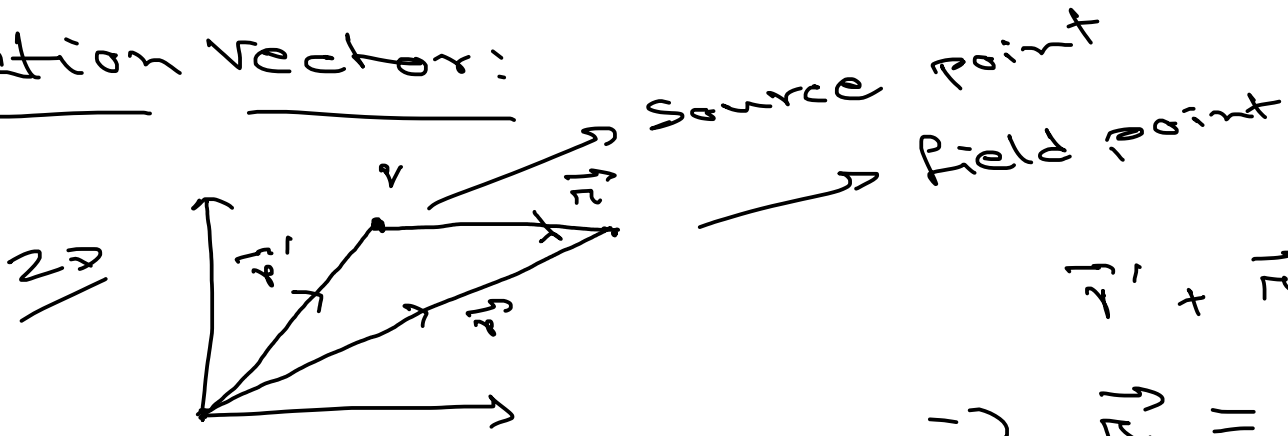


# Separation Vector:



$$\vec{r}_1 + \vec{r}_2 = \vec{r}$$

$$\Rightarrow \vec{r}_2 = \vec{r} - \vec{r}_1$$

$$r = |\vec{r} - \vec{r}_1|$$

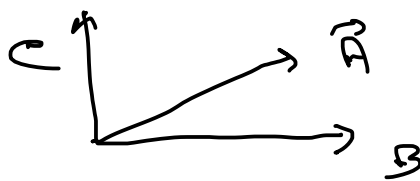
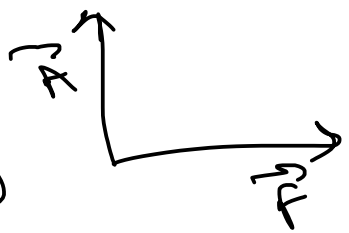
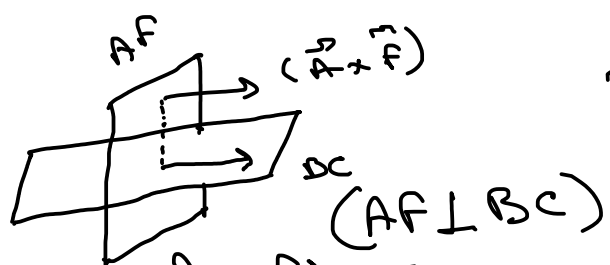
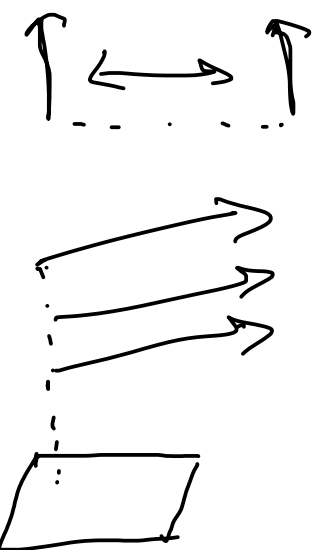
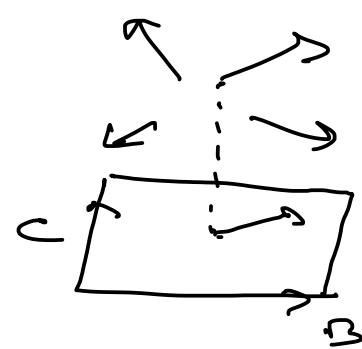
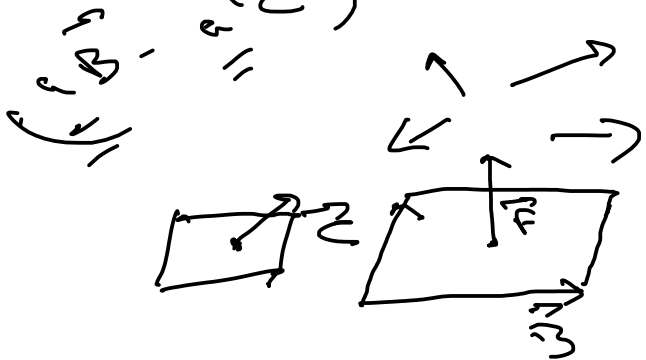
$$r = |\vec{r}_2|$$

⑦  $\vec{A} \times (\vec{B} \times \vec{C})$

$$= \vec{B} (\vec{A} \cdot \vec{C}) - \vec{C} (\vec{A} \cdot \vec{B})$$

$\vec{A} \cdot \vec{B}$  lies on BC plane

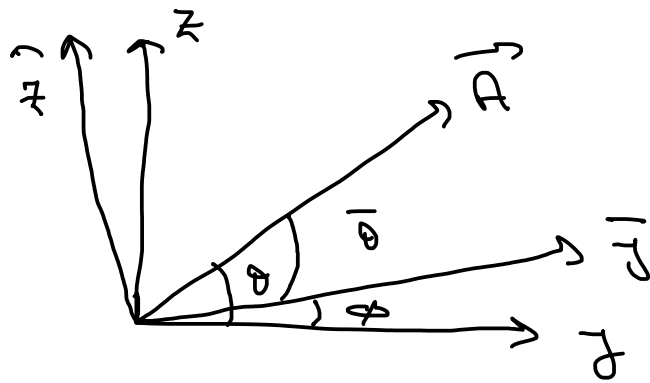
$\vec{A} \cdot (\vec{B} \times \vec{C})$   
 $\rightarrow$  volume of parallelepiped.



(Added after class. I think this will help to visualize)

# Vector transformation:

## Cartesian



$(x, y, z)$   $\xrightarrow[\text{about } x\text{-axis.}]{\text{Rotate by } \phi}$   $(\bar{x}, \bar{y}, \bar{z})$   
 $x = \bar{x}$

$$\begin{cases} A = \hat{x} A_x + \hat{y} A_y + \hat{z} A_z \\ A = \hat{\bar{x}} A_x + \hat{\bar{y}} A_y + \hat{\bar{z}} A_z \end{cases}$$

$$\begin{aligned} A_y &= A \cos \theta \\ A_z &= A \sin \theta \end{aligned}$$

$$\bar{A}_y = A \cos \theta = A \cos (\theta - \phi)$$

$$\begin{aligned} &= A (\cos \theta \cos \phi + \sin \theta \sin \phi) \\ &= A_y \cos \phi + A_z \sin \phi \end{aligned}$$

$$\bar{A}_z = A \sin \theta = A \sin (\theta - \phi)$$

$$= -A_y \sin \phi + A_z \cos \phi$$

In matrix notation:

$$\begin{pmatrix} 1 \\ A_y \\ A_z \end{pmatrix} = \begin{pmatrix} \cos \phi & \sin \phi \\ -\sin \phi & \cos \phi \end{pmatrix} \begin{pmatrix} A_y \\ A_z \end{pmatrix} \quad \checkmark$$

More generally,

$$\begin{pmatrix} 1 \\ A_y \\ A_z \end{pmatrix} = \begin{pmatrix} R_{xx} & R_{xy} & R_{xz} \\ R_{yx} & R_{yy} & R_{yz} \\ R_{zx} & R_{zy} & R_{zz} \end{pmatrix} \begin{pmatrix} A_x \\ A_y \\ A_z \end{pmatrix}$$

Compactly,

$$A_i = \sum_{j=1}^3 R_{ij} A_j \quad | \quad i, j \equiv x, y, z$$

new definition of vector: A vector is any set of three components that transforms as

$$\vec{A}_i = \sum_{j=1}^3 R_{ij} A_j$$

under change of coordinates.

