MIR: Installation and Usage

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1 Introduction

MIR is a task-based runtime system library. MIR is written using C99 and scales well for medium-grained task-based programs. MIR provides a direct interface for writing task-based programs. A subset of OpenMP 3.0 tasks is also supported. MIR is flexible - the user can experiment with different scheduling policies. Locality-aware scheduling and data distribution support for NUMA systems is also present. MIR supports extensive performance analysis and profiling features. Users can quickly solve performance problems using detailed thread-based and task-based performance information provided by MIR.

2 Requirements

Building MIR as a basic task-based runtime system requires:

- Machine with x86 architecture
- Linux kernel later than January 2012
- GCC and Binutils
- Scons a build system

2.1 Optional requirements

Extended features of MIR such as profiling and locality-aware scheduling require these additional software:

• libnuma - for data-distribution and locality-aware scheduling on NUMA systems

- PAPI for reading hardware performance counters during thread-based profiling
- Paraver for visualizing thread execution traces
- Python 2.X and 3.X for executing profiling scripts
- Intel Pin sources for profiling instructions executed by tasks during task-based profiling
- R for executing profiling scripts
- These R packages:
 - igraph for task graph processing
 - RColorBrewer for colors
 - gdata, plyr for data structure transformations
- Graphviz for task graph plotting

3 Directory Structure

The MIR source repository is structured as shown below. Directories are shown using /. Nesting is shown using indentation and +.

```
/ src - Core source files

+/ arch - Architecture-based source files

+/ scheduling - Scheduling policy source files

/ scripts - Various profiling and testing scripts

+/ task-graph - Scripts for task-based profiling

/ test - programs for testing

+/ omp - OpenMP programs

+/ bots - BOTS programs written using MIR programming interface

+/ with-data-footprint - Programs where tasks have explicit data foot-
```

4 Building

print

Building the basic MIR library is simple. Follow below steps:

1. Set MIR_ROOT environment variable to the MIR source repository path

```
$ export MIR ROOT=<<MIR source repository path>>
```

- 2. Ensure MIR_ROOT/src/SConstruct matches your build intention
- 3. Build

```
$ cd $MIR_ROOT/src
$ scons
```

4.1 Data-distribution and locality-aware scheduling on NUMA systems

Follow below steps to enable support for NUMA systems.

- 1. Install libnuma and numactl
- 2. Create an empty file called HAVE LIBNUMA

```
$ touch $MIR_ROOT/src/HAVE_LIBNUMA
```

3. Clean and rebuild MIR

```
$ cd $MIR_ROOT/src
$ scons —c
$ scons
```

5 Task-based Programming Interface

MIR provides a direct task-based programming interface and supports a subset of OpenMP 3.0 tasks.

5.1 Direct task-based programming

MIR provides a basic interface for task-based programming. Look at mir_public_int.h in MIR_ROOT/src for interface details and programs in MIR_ROOT/test for interface usage details. A simple example program is shown below.

```
#include "mir public int.h"
void foo(int id)
   printf(stderr, "Hello from task %d\n", id);
struct foo wrapper arg t
   int id;
void foo_wrapper(void* arg)
   struct foo _wrapper_arg_t* farg = (struct foo _wrapper_arg_t*)(arg);
   foo(farg->id);
}
int main(int argc, char *argv[])
   // Initialize the runtime system
   mir_create();
   // Create as many tasks as there are threads
   int num_workers = mir_get_num_threads();
   for(int i=0; i<num_workers; i++)</pre>
         struct foo wrapper arg t arg;
         arg.id = i;
         mir task create((mir tfunc t) foo wrapper, &arg, sizeof(struct
    foo_wrapper_arg_t), 0, NULL, NULL);
   // Wait for tasks to finish
   mir_task_wait();
   // Release runtime system resources
   mir destroy();
   return 0;
```

5.2 OpenMP 3.0 task-based programming subset

MIR also supports a subset of OpenMP 3.0 tasks. Only the task and taskwait constructs are supported. These two constructs are sufficient for

writing most task based programs. Note that the constructs are supported by intercepting GCC translated calls to GNU libgomp interfaces. Therefore OpenMP 3.0 task support is restricted to programs compiled using GCC.

The parallel construct is deprecated. MIR creates a team of threads during initialization - when mir_create is called. Threads are released when mir_destroy is called.

Tips to write OpenMP 3.0 task programs supported by MIR:

- Initialize and release the runtime system explicitly by calling mir_create and mir_destroy.
- Do not think in terms of threads. Think in terms of tasks.
- Do not use the parallel construct to share work.
- Do not use barriers to synchronize threads.
- Use the task construct to parallelize work. Use clauses shared, first-private and private to indicate the data environment.
- Use taskwait to synchronize tasks.
- Use mir_lock instead of the critical construct or use native locks such as pthread lock.
- Use gcc atomic builtins for flushing and atomic operations.
- Look at examples in MIR ROOT/test/omp.

A simple set of steps we use often when producing MIR supported OpenMP programs is as follows:

- 1. When parallel execution is required, create a parallel block with default(none) followed immediately by a single block.
- 2. Use the task construct within the single block to parallelize work.
- Synchronize tasks using the taskwait construct explicitly. Do not rely on implicit barriers and taskwaits.
- 4. Parallelizing work inside a master task context is helpful while interpreting profiling results.
- 5. Compile and link with the native OpenMP implementation (libgomp) and check if the program runs correctly.
- 6. Comment out the parallel and single blocks, initialize the MIR runtime system right in the beginning of the program and release it at the end of the program, include mir_public_int.h, compile and link with the appropriate MIR library (opt/debug/prof) to produce the executable.

The directly-programmed example shown previously written using the OpenMP 3.0 task subset supported by MIR is shown below.

```
int main(int argc, char *argv[])
   // Initialize the runtime system
   mir create();
//#pragma omp parallel default(none)
//#pragma omp single
// Master task context: helpful for interpreting profiling results.
#pragma omp task
   // Now parallelize the work involved
   // Work in this case: create as many tasks as there are threads
  int num_workers = mir_get_num_threads();
   for(int i=0; i<num workers; i++)
      #pragma omp task firstprivate(i)
         foo(i);
   // Wait for tasks to finish
   #pragma omp taskwait
// Wait for master task to finish
#pragma omp taskwait
//}
//}
   // Release runtime system resources
  mir_destroy();
   return 0;
```

Look at test programs in MIR ROOT/test for advanced usage examples.

6 Testing

MIR does not have a dedicated test case (unit testing) suite yet. The fib program (Fibonacci number calculation) is recommended for testing.

```
$ cd $MIR_ROOT/test/fib
$ scons -c
```

```
$ scons
$ echo "Executing verbose build"
$ ./fib—verbose
$ echo "Executing debug build"
$ ./fib—debug
$ echo "Executing optimized (production) build"
$ ./fib—opt
```

Other test programs in MIR ROOT/test can also be used for testing.

6.1 Compiling and linking

Look at SConstruct - the scons build file - of each test program to understand how to compile and link with the MIR library. Observing scons build messages is also recommended.

6.2 Configuration

MIR has several configurable options which can be set using the environment variable MIR_CONF. Set the -h flag to see available configuration options.

```
$ cd $MIR_ROOT/test/fib
$ scons
$ MIR_CONF="-h" ./fib-opt 3
```

6.3 Core binding

MIR creates and binds one worker thread per core (including hardware threads) by default. Binding is id-based - worker thread 0 is bound to core 0, worker 1 to core 1 and so on. The binding scheme can be changed to a specific mapping using the environment variable MIR_WORKER_CORE_MAP. Ensure MIR_WORKER_EXPLICIT_BIND is defined in mir_defines.h to enable explicit binding support. An example is shown below.

```
$ cd $MIR_ROOT/src

$ grep "EXPLICIT_BIND" mir_defines.h

#define MIR_WORKER_EXPLICIT_BIND

$ cd $MIR_ROOT/test/fib

$ cat /proc/cpuinfo | grep -c Core

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$ export MIR_WORKER_CORE_MAP="0,2,3,1"
```

```
$ scons
$ ./fib—debug 10 3
MIR_DBG: Starting initialization ...
MIR_DBG: Architecture set to firenze
MIR_DBG: Memory allocation policy set to system
MIR_DBG: Task scheduling policy set to central—stack
MIR_DBG: Reading worker to core map ...
MIR_DBG: Binding worker 0 to core 3
MIR_DBG: Binding worker 3 to core 0
MIR_DBG: Binding worker 2 to core 2
MIR_DBG: Worker 2 is initialized!
MIR_DBG: Worker 3 is initialized!
MIR_DBG: Binding worker 1 to core 1
...
```

7 Profiling

MIR supports detailed thread-based and task-based profiling.

7.1 Thread-based profiling

Thread states and events are main performance indicators in thread-based profiling.

Enable the -r flag to get detailed per-thread state and event information in files with *-prv-*.rec extension. Each rec file represents a worker thread. The rec files can be inspected individually or combined and visualized using Paraver.

```
$ rm *.rec *.prv *.pcf
$ MIR_CONF="-r" ./fib-opt
$ $MIR_ROOT/scripts/mirtoparaver.py *-config.rec
$ wxparaver *-paraver.prv
```

A set of files matching the pattern *-state-time*.rec are also created when -r is enabled. These files contain thread state duration information which can be aggregated for analysis without Paraver.

```
$ $MIR_ROOT/scripts/get-state-stats.sh <<Unix time>>
$ cat state-file-acc.info
```

Hardware performance counters can be read during thread events. This process is not fully automated and needs work from the user.

First install PAPI. Then set the PAPI_ROOT environment variable and create a file called HAVE_PAPI in MIR_ROOT/src. Next enable the preprocessor definition MIR_RECORDER_USE_HW_PERF_COUNTERS in MIR_ROOT/src/mir_defines.h. Next enable PAPI hardware performance counters of interest in MIR_ROOT/src/mir_recorder.c. Rebuild MIR.

Performance counter readings will be now be added to .rec files produced by enabling thread-based profiling (-r flag). The readings can either be viewed on Paraver or aggregated for analysis outside Paraver.

```
$ $MIR_ROOT/scripts/get-event-counts.sh <<.prv file>>
$ cat event-counts-*.txt
```

7.2 Task-based profiling

Task are first-class citizens in task-based profiling.

Enable the -i flag in MIR_CONF to get basic task-based information in a file called mir-stats.

```
$ MIR_CONF="-i" ./fib-opt
$ cat mir-stats
```

Enable the -g flag to generate and plot the fork-join task graph that unfolded during execution.

```
$ MIR_CONF="-g" ./fib-opt
$ Rscript ${MIR_ROOT}/scripts/task-graph/mir-fork-join-graph-plot.R mir-
task-graph color
```

MIR can also generate an instruction-level profile of tasks. Instruction-level task profiling support is restricted to programs compiled using GCC. To enable instruction-level profiling support, first get PIN sources and set the below environment variables.

```
$ export PIN_ROOT=<<Pin source path>>
$ export LD_LIBRARY_PATH=$LD_LIBRARY_PATH:$PIN_ROOT
```

Next, edit PIN_ROOT/source/tools/Config/makefile.unix.config and add-fopenmp (note the -) to variables tool LDFLAGS NOOPT, TOOL CXXFLAGS NOOPT.

Next build mir_outline_function_profiler.so - the Pin tool which profiles tasks.

```
$ cd $MIR_ROOT/scripts/task-graph
$ make PIN_ROOT=$PIN_ROOT
```

View profiling options options using -h.

```
$ $PIN_ROOT/intel64/bin/pinbin -t $MIR_ROOT/scripts/task-graph/obj-intel64/mir_outline_function_profiler.so -h -- echo
```

Look at MIR_ROOT/docs/ATG.pdf for more information on instruction-level profiling. Also, the file MIR_ROOT/test/fib/profile-test.sh shows how to automate instruction-level profiling.