

Assembler, Linker & Loader

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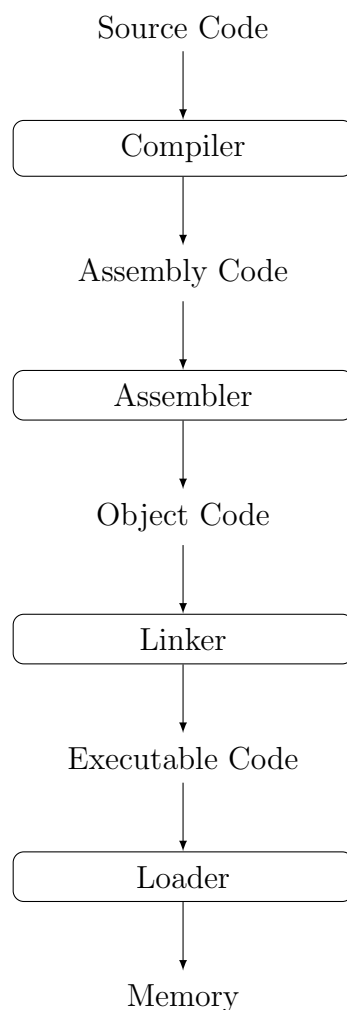
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1 Introduction

This document is in with the reference to the project given in CS-244(System Programming Lab) course under the guidance of Prof. Santosh Biswas on Assembler, Linker, Loader and it's working for a programming language.

A computer will not understand any program written in a language, other than its machine language. This document covers how a normal source code is loaded into the memory. It is done in various steps. Below is the flow chart showing exection of a source code.



A basic overview of the process of assembler, linker & loader

The programs written in other languages must be translated into the machine language. Such translation is performed with the help of software. A program which translates an assembly language program into a machine language program is called an assembler.

In high level languages, some built in header files or libraries are stored. These libraries are predefined and these contain basic functions which are essential for executing the program. These functions are linked to the libraries by a program called Linker. Usually a longer program is divided into smaller subprograms called modules. And these modules must be combined to execute the program. The process of combining the modules is done by the linker.

Loader is a program that loads machine codes of a program into the system memory. In Computing, a loader is the part of an Operating System that is responsible for loading programs. It is one of the essential stages in the process of starting a program. Because it places programs into memory and prepares them for execution.

2 Terminologies used & their details

2.1 Assembly Language

Lets try to understand a assembly language with a simple Example. This will give us an insight to the underlying algorithms and data structures which is explained later in this section. Assembly language program (8085 micro-processor) to add two 8 bit numbers. Problem - Write an assembly language program to add two 8 bit numbers stored at address 2050 and address 2051 in 8085 microprocessor. Starting address of program is taken as 2000.

Algorithm

1. First add contents of memory location 2050 and 2051 using ADD instruction and storing at 3050.
2. The carry generated is recovered using ADC command and is stored at memory location 3051.

Explanation

1. LHLD 2050 moves the contents of 2050 memory location (3B) in L register and contents of 2051 memory location (F9) in H register.
2. MOV A, L copies contents of L register (3B) to A (Accumulator).
3. ADD H adds contents of A (Accumulator) and H register (F9). The result is stored in A itself. For all arithmetic instructions A is by default an operand and A stores the result as well.
4. MOV L, A copies contents of A (34) to L.
5. MVI A 00 moves immediate data (i.e., 00) to A.
6. ADC A adds contents of A(00), contents of register specified (i.e A) and carry (1) As ADC is also an arithmetic operation, A is by default an operand and A stores the result as well.
7. MOV H, A copies contents of A (01) to H.
8. SHLD 3050 moves the contents of L register (34) in 3050 memory location and contents of H register (01) in 3051 memory location.
9. HLT stops executing the program and halts any further execution.

Consider another problem which might further clear the understanding of assembly language programming. Add the contents of memory locations 200h and 2001h and place the result in the memory locations 2002h 2003h. The machine language code/ assembly language code will look something like this

```
LXI H,2000H ;HL Points 2000H
MOV A,M ;Get the first operand
INX H ;HL points to 2001H
ADD M ;Add second operand
INX H ;HL points to 2002H
MOV M,A ;Store lower byte of result at 2002H
MVI A,00 ;Initialize higher byte result with 00H
ADC A ;Add carry in the higher byte
INX H ;HL points 2003h
MOV M,A ;Store the higher nbyte of result at 2003H
HLT ;Terminate the program
```

2.2 Compiling Assembly Language

We used the 8085 instruction set for converting the programming file to the assembly language.

With the help of scanning which will be explained in the next section with the use of regex python expressions, each lines of code was converted to the equivalent assembly 8085 instruction. Below is the list of several operations which our program handles.

The 8085 programming model

8085 processor has a set of seven 8-bit registers including the accumulator and six others, namely, B, C, D, E, H and L. Depending upon applications, the registers other than the accumulator can be used either as independent byte-registers or as 16-bit register pairs. A 16-bit special-purpose register called program counter is available in the microprocessor. It stores the address of the next instruction to be fetched. A 16-bit stack pointer stores the address of the last byte entered into the stack.

8085 is pronounced as "eighty-eighty-five" microprocessor. It is an 8-bit microprocessor designed by Intel in 1977 using NMOS technology.

It has the following configuration:

1. 8-bit data bus.
2. 16-bit address bus, which can address upto 64KB.
3. A 16-bit program counter.

4. A 16-bit stack pointer.
5. Six 8-bit registers arranged in pairs: BC, DE, HL.
6. Requires +5V supply to operate at 3.2 MHZ single phase clock.

Addition of two numbers in our programming language:

```
var a = 0
var b = 4
var c = a + b
```

Assembly file generated by our program gives:

```
MVI D, =0
MOV #a,D
MVI D, =4
5
MOV #b,D
MOV D,#a
MOV #c,D
END
a DS 1
b DS 1
c DS 1
=0
=4
```

Use of jump instruction(unconditional) :

```
var c = 0
JUMP here
c = c + 20
here:
var c = 10
```

Assembly file generated by our program gives:

```
MVI D, =0
MOV #c,D
JMP here
LDA #c
ADI 20
STA #c
```

```

MVI D, =10
MOV #c,D
END
c DS 1
c DS 1
=0
=10

```

Similarly for the array indexing and declaration

```

var c = 5
var a[5]
a[1] = 1
a[3] = c

```

Assembly file generated by our program gives:

```

MVI D, =5
MOV #c,D
MVI A, 1
STA #a+1
LDA #c
STA #a+3
END
c DS 1
=5
6
a DS 5

```

2.3 Scanning and Parsing the code

Scanning is the process of recognizing the lexical components in a source strings. A Scanner simply turns an input String (say a file) into a list of tokens. These tokens represent things like identifiers, parentheses, operators etc.

The goals of parsing are to check the validity of a source string, and to determine its syntactic structure. For the invalid string, the parser issues diagnostic messages reporting the cause and nature of error(s) in the string. For a valid string (code statement in this case), it builds a parse tree to reflect the sequence of derivations or reductions performed during the parsing. A parser converts this list of tokens into a Tree-like object to represent how the tokens fit together to form a cohesive whole (sometimes referred to as a sentence).

In terms of programming language parsers, the output is usually referred to as an Abstract Syntax Tree (AST). Each node in the AST represents a different construct of the language, e.g. an IF statement would be a node with 2 or 3 sub nodes, a CONDITION node, a THEN node and potentially an ELSE node.

Parse trees and Abstract syntax trees

A parse tree depicts the steps in parsing, so it is useful for understanding the process of parsing. However it is a poor intermediate representation of a source string because it contains too much information as far as subsequent processing in the compiler is concerned. An abstract syntax tree (AST) represents the structure of a source string in a more economical manner. The word abstract implies that it is a representation designed by a compiler designer for his own purposes. Below is the diagram representing the process of parsing and scanning of programming code lines.

In our case, we have scanned the code lines using regex library in python for

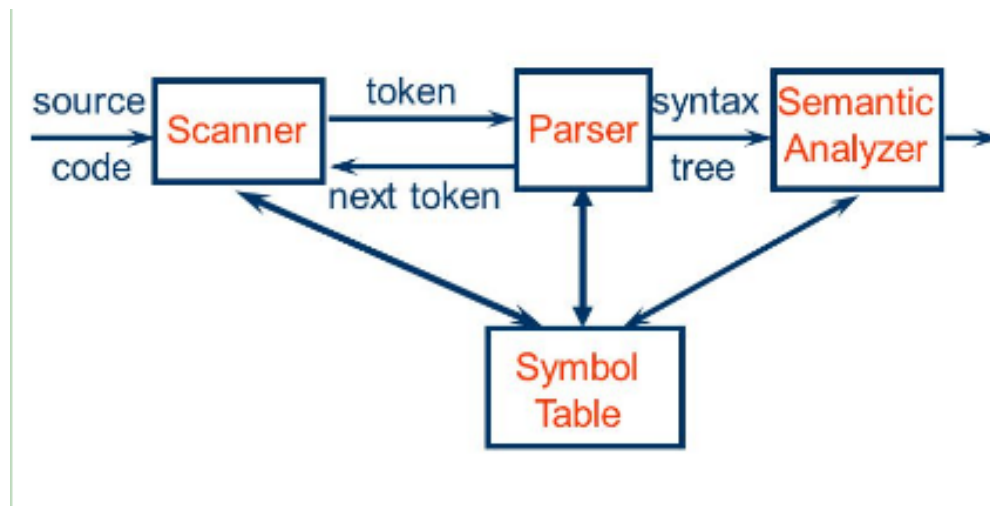


Figure 1: Scanning and parsing of code lines.

all types of statements available in the language which we designed according to the syntax so defined for each. For a given programming statement, it first tokenizes and checks against all defined regexes. Definition of some regexes can be seen in the table below. One of the most important uses of the theory of formal languages is in the definition of programming languages and in the construction of interpreters and compilers for them. The basic problem here is to define a programming language precisely and to use this definition as the starting point for the writing of efficient and reliable translation programs. Both regular and context-free languages are important in achieving this. As

Operation	Regex Definition
Addition	<code>\s*(\w+) \s* = \s*(\w+) \s* \+ \s*(\w+) \s*</code>
Extern	Variable extern <code>\s+(\w+) \s*</code>
Loop	<code>\s*loop \s+(\w+) \s*</code>
Macro	<code>\s*macro \s*</code>
Minimum of a list e.g., min(2,3,0,1)	<code>\s*(\w+) \s* = \s*min \s* \((.*) \) \s* \</code>

Table 1: Some regex definitions in python.

we have seen, regular languages are used in the recognition of certain simple patterns that occur in programming languages, but as we argue in the introduction to this chapter, we need context-free languages to model more complicated aspects.

As with most other languages, we can define a programming language by a grammar.

It is traditional in writing on programming languages to use a convention for specifying grammars called the Backus-Naur form or BNF. This form is in essence the same as the notation we have used here, but the appearance is different. In BNF, variables are enclosed in triangular brackets. Terminal symbols are written without any special marking. BNF also uses subsidiary symbols such as —, much in the way we have done.

Many parts of C-like programming languages are susceptible to definition by restricted forms of context-free grammars. For example, the while statement in C can be defined as Here the keyword while is a terminal symbol. All other terms are variables, which still have to be defined.

Unfortunately, not all features of a typical programming language can be expressed by an s- grammar. The rules for above are not of this type, so that parsing becomes less obvious. The question then arises what grammatical rules we can permit and still parse efficiently. In compilers, extensive use has been made of what are called LL and LR grammars. These grammars have the ability to express the less obvious features of a programming language, yet allow us to parse in linear time.

In connection with this, the issue of ambiguity takes on added significance. The specification of a programming language must be unambiguous, otherwise a program may yield very different results when processed by different compilers or run on different systems. As Example 5.11 shows, a naive approach can easily introduce ambiguity in the grammar. To avoid such mistakes we must be able to recognize and remove ambiguities. A related question is whether a language is or is not inherently ambiguous. What we need for this

purpose are algorithms for detecting and removing ambiguities in context-free grammars and for deciding whether or not a context-free language is inherently ambiguous. Unfortunately, these are very difficult tasks, impossible in the most general sense, as we will see later.

Those aspects of a programming language that can be modeled by a context-free grammar are usually referred to as its syntax. However, it is normally the case that not all programs that are syntactically correct in this sense are in fact acceptable programs. For C, the usual BNF definition allows constructs such as

```
char a, b, c; followed by  
c = 3.2;
```

This combination is not acceptable to C compilers since it violates the constraint, a character variable cannot be assigned a real value. Context-free grammars cannot express the fact that type clashes may not be permitted. Such rules are part of programming language semantics, since they have to do with how we interpret the meaning of a particular construct. Programming language semantics are a complicated matter. Nothing as elegant and concise as context-free grammars exists for the specification of programming language semantics, and consequently some semantic features may be poorly defined or ambiguous. It is an ongoing concern both in programming languages and in formal language theory to find effective methods for defining programming language semantics. Several methods have been proposed, but none of them has been as universally accepted and are as successful for semantic definition as context-free languages have been for syntax.

3 Assembler

3.1 What is an assembler?

An assembler is a type of computer program that interprets software programs written in assembly language into machine language, code and instructions that can be executed by a computer. It serves as the bridge between symbolically coded instructions written in assembly language and the computer processor, memory and other computational components.

An assembler works by assembling and converting the source code of assembly language into object code or an object file that constitutes a stream of zeros and ones of machine code, which are directly executable by the processor. Assemblers are classified based on the number of times it takes them to read the source code before translating it; there are both single-pass and multi-pass assemblers. Moreover, some high-end assemblers provide enhanced functionality by enabling the use of control statements, data abstraction services and providing support for object-oriented programming structures. It enables software and application developers to access, operate and manage a computer's hardware architecture and components. It is sometimes referred to as the compiler of assembly language. It also provides the services of an interpreter.

3.2 Data Structure

- Op code table (OPTAB)

It is used to look up mnemonic operation codes and translate them to their machine language equivalents. It is usually organized as a hash table, with mnemonic operation code as the key. The hash table organization is particularly appropriate, since it provides fast retrieval with a minimum of searching. In most cases, OPTAB is a static table that is, entries are not normally added to or deleted from it. In such cases it is possible to design a special hashing function or other data structure to give optimum performance for the particular set of keys being stored. Most of the time, however, a general purpose hashing method is used.

- Symbol Table (SYMTAB)

It includes the name and value (address) for each label in the source program, together with flags to indicate error conditions (e.g., a symbol defined in two different places). This table may also contain other information about the data area or instruction labeled for example,

its type or length. During Pass 1 of the assembler, labels are entered into SYMTAB as they are encountered in the source program, along with their assigned addresses (from LOCCTR). During Pass 2, symbols used as operands are looked up in SYMTAB to obtain the addresses to be inserted in the assembled instructions. It is usually organized as a hash table for efficiency of insertion and retrieval. Since entries are rarely deleted from this table, efficiency of deletion is not an important consideration. Because SYMTAB is used heavily throughout the assembly, similar characteristics for example, labels that start or end with the same characters (like LOOP1, LOOP2) or are of the same length. It is important that the hashing function used perform well with such non-random keys. Division of the entire key by a prime table length often gives good results.

- Location Counter (LOCCTR)
This is a variable that is used to help in the assignment of addresses. LOCCTR is initialized to the beginning address specified in the START statement. After each source statement is processed, the length of the assembled instructions or data area to be generated is added to LOCCTR. Thus whenever we reach a label in the source program, the current value of LOCCTR gives the address to be associated with that label.

3.3 Pass 1 Assembler

A single pass assembler scans the program only once and creates the equivalent binary program. It substitutes all of the symbolic instructions with machine code in one pass. The reason for using single pass assemblers is:

- It is necessary or desirable to avoid a second pass over the source program.
- The external storage for the intermediate file between two passes is slow or is inconvenient to use.

Algorithm for pass 1 assembler is given below:

Loop until the end of the program

1. Read in a line of assembly code
2. Assign an address to this line
 - Increment N (word addressing or byte addressing)

3. Save address values assigned to labels

- In symbol tables

4. Process assembler directives

- Constant declaration
- Space reservation

Following is the pseudocode of pass 1 assembler

```
begin
  if starting address is given
    LOCCTR = starting address;
  else
    LOCCTR = 0;
  while OP CODE != END do          ;; or EOF
    begin
      read a line from the code
      if there is a label
        if this label is in SYMTAB, then error
      else insert (label, LOCCTR) into SYMTAB
      search OPTAB for the op code
      if found
        LOCCTR += N                ;; N is the length of this instruction (4 for MIPS)
      else if this is an assembly directive
        update LOCCTR as directed
      else error
      write line to intermediate file
    end
    program size = LOCCTR - starting address;
  end
```

After Pass 1 and before Pass 2 codes are displayed below:

```
var a = 0
loop 3
a = a + 1
endloop
```

Assembly code produced is:

```

MVI D, =0
MOV #a,D
PUSH E
MVI E, 3
LDA #a
ADI 1
STA #a
MOV A,E
SUI 1
MOV E,A
JNZ loop0
POP E
END
a DS 1
=0

```

The symbols table and literals table are shown below:

Symbols Table

```

a : #23
loop : %6

```

Literals Table

```

0: 24

```

3.4 Pass 2 Assembler

Two pass translation of an assembly language program can handle forward references easily. LC processing is performed in the first pass and symbols defined in the program are entered into the symbol table. The second pass synthesizes the target form using the address information found in the symbol table. In effect, the first pass performs the analysis of the source program while the second pass performs synthesis of target program. The first pass constructs an intermediate representation (IR) of the source program for use by the second pass.

Consider an assembler instruction like the following:-

```

JMP LATER
...
...
LATER:

```

This is known as a forward reference. If the assembler is processing the file one line at a time, then it doesn't know where LATER is when it first encounters the jump instruction. So, it doesn't know if the jump is a short jump, a near jump or a far jump. There is a large difference amongst these instructions. They are 2, 3, and 5 bytes long respectively. The assembler would have to guess how far away the instruction is in order to generate the correct instruction. If the assembler guesses wrong, then the addresses for all other labels later in the program would be wrong, and the code would have to be regenerated. Or, the assembler could always choose the worst case. But this would mean generating inefficiency in the program, since all jumps would be considered far jumps and would be 5 bytes long, where actually most jumps are short jumps, which are only 2 bytes long.

So, what is to be done to allow the assembler to generate the correct instruction? Answer: scan the code twice. The first time, just count how long the machine code instructions will be, just to find out the addresses of all the labels. Also, create a table that has a list of all the addresses and where they will be in the program. This table is known as the symbol table. On the second scan, generate the machine code, and use the symbol table to determine how far away jump labels are, and to generate the most efficient instruction.

This is known as a two-pass assembler. Each pass scans the program, the first pass generates the symbol table and the second pass generates the machine code.

The two pass assembler performs two passes over the source program.

In the first pass, it reads the entire source program, looking only for label definitions. All the labels are collected, assigned address, and placed in the symbol table in this pass, no instructions are assembled and at the end the symbol table should contain all the labels defined in the program. To assign address to labels, the assembler maintains a Location Counter (LC).

In the second pass the instructions are again read and are assembled using the symbol table. Basically, the assembler goes through the program one line at a time, and generates machine code for that instruction. Then the assembler proceeds to the next instruction. In this way, the entire machine code program is created. For most instructions this process works fine, for example for instructions that only reference registers, the assembler can compute the machine code easily, since the assembler knows where the registers are.

Algorithm of Pass 2 Assembler is given below:

Loop until the end of the program

1. Read in a line of assembly code

2. Assign an address to this line
 - Increment N (word addressing or byte addressing)
3. Save address values assigned to labels
 - In symbol tables
4. Process assembler directives
 - Constant declaration
 - Space reservation

Once Again perform the loop until the end of the program

1. Read in a line of code
2. Translate opcode using opcode table
3. Change labels to address using the symbol table
4. Process assembler directives
5. Produce object program

3.5 Difference between Pass 1 and Pass 2 Assembler

The difference between one pass and two pass assemblers are:-

A one pass assembler passes over the source file exactly once, in the same pass collecting the labels, resolving future references and doing the actual assembly. The difficult part is to resolve future label references (the problem of forward referencing) and assemble code in one pass. The one pass assembler prepares an intermediate file, which is used as input by the two pass assembler.

A two pass assembler does two passes over the source file (the second pass can be over an intermediate file generated in the first pass of the assembler). In the first pass all it does is looks for label definitions and introduces them in the symbol table (a dynamic table which includes the label name and address for each label in the source program). In the second pass, after the symbol table is complete, it does the actual assembly by translating the operations into machine codes and so on.

4 Linker

4.1 What is a Linker?

In high level languages, some built in header files or libraries are stored. These libraries are predefined and these contain basic functions which are essential for executing the program. These functions are linked to the libraries by a program called Linker. If linker does not find a library of a function then it informs to compiler and then compiler generates an error. The compiler automatically invokes the linker as the last step in compiling a program. Computer programs typically are composed of several parts or modules; these parts/modules need not all be contained within a single object file, and in such cases refer to each other by means of symbols. Typically, an object file can contain three kinds of symbols:

- defined "external" symbols, sometimes called "public" or "entry" symbols, which allow it to be called by other modules.
- undefined "external" symbols, which reference other modules where these symbols are defined.
- local symbols, used internally within the object file to facilitate relocation.

For most compilers, each object file is the result of compiling one input source code file. When a program comprises multiple object files, the linker combines these files into a unified executable program, resolving the symbols as it goes along. Linkers can take objects from a collection called a library. Some linkers do not include the whole library in the output; they include only its symbols that are referenced from other object files or libraries. Libraries exist for diverse purposes, and one or more system libraries are usually linked in by default. The linker also takes care of arranging the objects in a programs address space. This may involve relocating code that assumes a specific base address to another base. Since a compiler seldom knows where an object will reside, it often assumes a fixed base location (for example, zero). Relocating machine code may involve retargeting of absolute jumps, loads and stores. The executable output by the linker may need another relocation pass when it is finally loaded into memory (just before execution). This pass is usually omitted on hardware offering virtual memory: every program is put into its own address space, so there is no conflict even if all programs load at the same base address. This pass may also be omitted if the executable is a position independent executable. Not built in libraries, it also links the user defined functions to the user defined libraries. Usually a longer program is

divided into smaller subprograms called modules. And these modules must be combined to execute the program. The process of combining the modules is done by the linker.

4.2 Tasks of a Linker

- Searches the program to find library routines used by program, e.g. `printf()`, math routines.
- Determines the memory locations that code from each module will occupy and relocates its instructions by adjusting absolute references.
- Resolves references among files

4.3 Linking Requirements

- All program units are translated separately.
- Hence, all sub program calls and common variable reference require linking.
- Programs are nested in main program.
- Procedure reference do not require linking, they can be handled using relocation.
- Build in functions require linking.
- Linker processes all object modules being linked and builds a table of all public definition and load time address.
- Name Table (NTAB)
 - Symbol : Symbol Name for external reference or object module.
 - Linked Address : For public definition contains link-address. For object module contains link-origin.
- Most information in NTAB is derived from LINKTAB entries with `type=PD`.

4.4 Algorithm of a Linker

1. program-linked-origin := `link origin` from linker command.
2. For each object module
 - t-origin := translated origin of object module. OM-size := size of the object module;
 - Relocation-factor := program-linked-origin - t-origin.
 - Read the machine language program in work-area .
 - Read LINKTAB of the object module.
 - For each LINKTAB entry with type = PD
 - name := symbol;
 - linked-address := translated-address + relocation-factor;
 - enter(name, linked-address) in NTAB.
 - Enter (object module name, program-linked-origin) in NTAB;
 - program-linked-origin := program-linked-origin + OM-size ;
3. for each object module
 - t-origin := translated origin of the object module.
 - For each LINKTAB entry with type=EXT
 - address-in-work-area := address of work-area + program-linked-origin
 - `link-origin` + translated address
 - t-origin ;
 - Search symbol in NTAB and copy its linked address. Add the linked address to the operand address in the word with the address address-in-work-area.

Example

- While linking program P and program Q with linked-origin = 900, NTAB contains above information:
- Work-area = 300.
- When LINKTAB of alpha is processed during linking, address-in-work-area := 300 + 900 - 900 + 518 = 518. i.e 518.
- Hence linked address of ALPHA is 973, is copied from NTAB entry of ALPHA and added to word in address 518.

Symbol	Linked Address
P	900
A	940
Q	942
Alpha	973

Table 2: NTAB Information

4.5 Relocation

As the compiler has no information on the layout of objects in the final output, it cannot take advantage of shorter or more efficient instructions that place a requirement on the address of another object. For example, a jump instruction can reference an absolute address or an offset from the current location, and the offset could be expressed with different lengths depending on the distance to the target.

By generating the most conservative instruction (usually the largest relative or absolute variant, depending on platform) and adding relaxation hints, it is possible to substitute shorter or more efficient instructions during the final link. This step can be performed only after all input objects have been read and assigned temporary addresses; the linker relaxation pass subsequently reassigns addresses, which may in turn allow more relaxations to occur. In general, the substituted sequences are shorter, which allows this process to always converge on the best solution given a fixed order of objects; if this is not the case, relaxations can conflict, and the linker needs to weigh the advantages of either option.

While instruction relaxation typically occurs at link-time, inner-module relaxation can already take place as part of the optimising process at compile-time. In some cases, relaxation can also occur at load-time as part of the relocation process or combined with dynamic dead-code elimination techniques. Consider a program consisting of 2 different files and one of them having extern variable to use variable of another file.

First file contains:

```
global a = 5
```

While 2nd file contains

```
extern a
```

```
a = a + 2
```

Output given by linker:

```
MVI D, ='5'
```

```
MOV @A,D
```

```
END
a DS 1
='5'
LDA @4
ADI 2
STA @4
END
```

5 Loader

5.1 What is a Loader?

Loader is a program that loads machine codes of a program into the system memory. In Computing, a loader is the part of an Operating System that is responsible for loading programs. It is one of the essential stages in the process of starting a program. Because it places programs into memory and prepares them for execution. Loading a program involves reading the contents of executable file into memory. Once loading is complete, the operating system starts the program by passing control to the loaded program code. All operating systems that support program loading have loaders. In many operating systems the loader is permanently resident in memory. In computer systems a loader is the part of an operating system that is responsible for loading programs and libraries. It is one of the essential stages in the process of starting a program, as it places programs into memory and prepares them for execution. Loading a program involves reading the contents of the executable file containing the program instructions into memory, and then carrying out other required preparatory tasks to prepare the executable for running. Once loading is complete, the operating system starts the program by passing control to the loaded program code. All operating systems that support program loading have loaders, apart from highly specialized computer systems that only have a fixed set of specialized programs. Embedded systems typically do not have loaders, and instead the code executes directly from ROM. In order to load the operating system itself, as part of booting, a specialized boot loader is used. In many operating systems the loader is permanently resident in memory, although some operating systems that support virtual memory may allow the loader to be located in a region of memory that is pageable. In the case of operating systems that support virtual memory, the loader may not actually copy the contents of executable files into memory, but rather may simply declare to the virtual memory subsystem that there is a mapping between a region of memory allocated to

contain the running programs code and the contents of the associated executable file. (See memory-mapped file.) The virtual memory subsystem is then made aware that pages with that region of memory need to be filled on demand if and when program execution actually hits those areas of unfilled memory. This may mean parts of a programs code are not actually copied into memory until they are actually used, and unused code may never be loaded into memory at all. It is the part of the OS that brings an executable file residing on disk into memory and starts it running. The main task of the loader is to bring binary executable image into main memory and bind the relocatable addresses into absolute addresses.

The binary image of a program consists of following parts :-

- Header It shows the type of file (executable or library file).
- Text It shows the actual code of the program
- List of shared libraries - libraries that have been used in the object file.

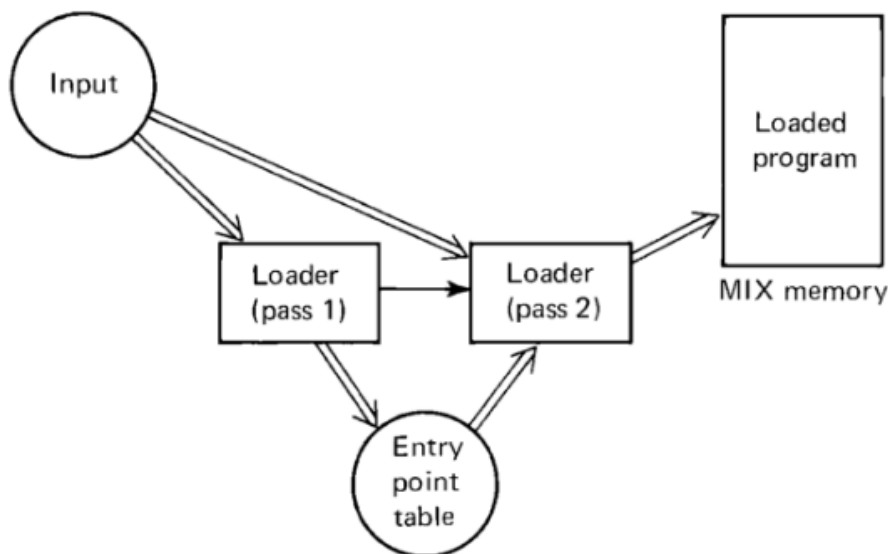


Figure 2: Functioning of a Loader

5.2 Execution of Loader

The steps on how loading is executed are shown below:

- Read executable files header to determine the size of text and data segments.
- Create a new address space for the program.
- Copies instructions and data into address space.
- Copies arguments passed to the program on the stack.
- Initializes the machine registers including the stack ptr.
- Jumps to a startup routine that copies the programs arguments from the stack to registers and calls the programs main routine

5.3 Design of an absolute Loader

An absolute object file consists of three parts

1. The start address of the program
2. The object instructions
3. The address of the first executable instruction. This is placed in the object file by assembler in response to the END directive. It is either the address specified by the END or, in the absence of such an address is identical to the first address of the program.

The loader reads the first item and loads the rest of object file into successive memory locations.

6 References

- Systems Programming and Operating Systems by Dhananjay Dhamdhere
- 2-pass Assembler explanation
- wiki-assembler
- Linker and Loader by John R. Levine