

INTRODUCTION TO EECS II

DIGITAL

COMMUNICATION

SYSTEMS

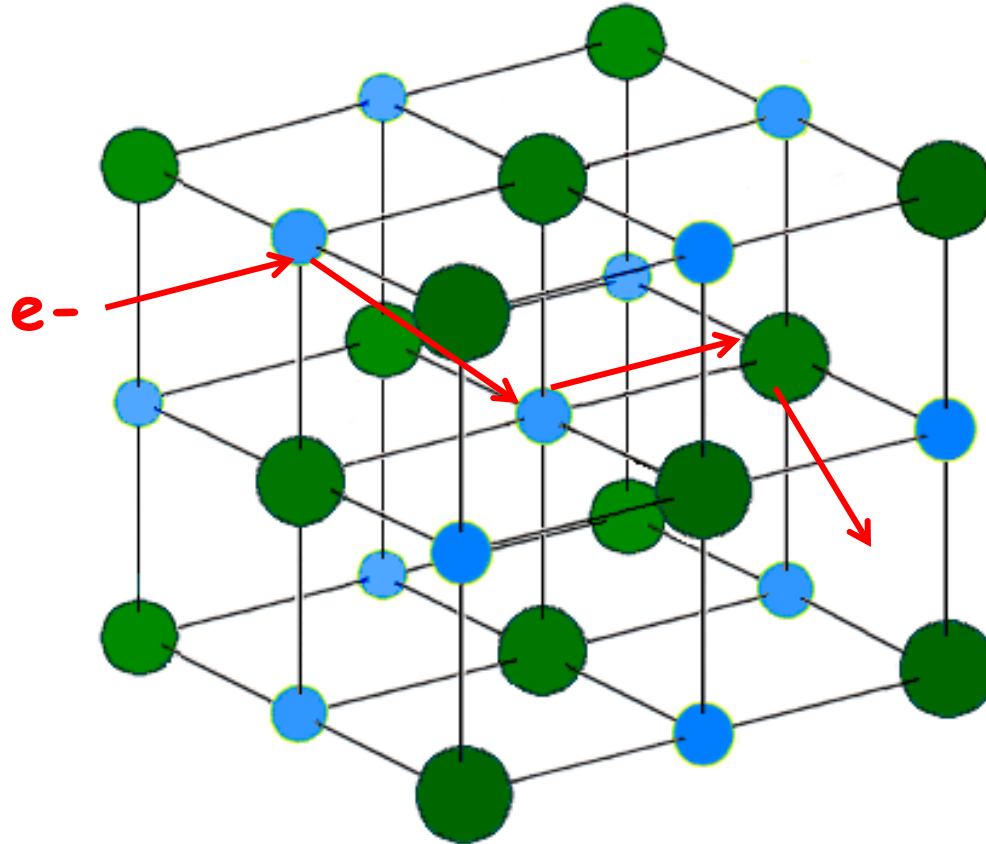
6.02 Fall 2010

Lecture #4

- Signals and Noise
 - Noise sources and bit errors
- Analyzing Noise:
 - PDF, CDF, and Noise + Noisefree decomposition
- Computing Bit Error Rates:
 - The No ISI case, the impact of the Noise PDF.

Noise Can Be Due to Fundamental Processes

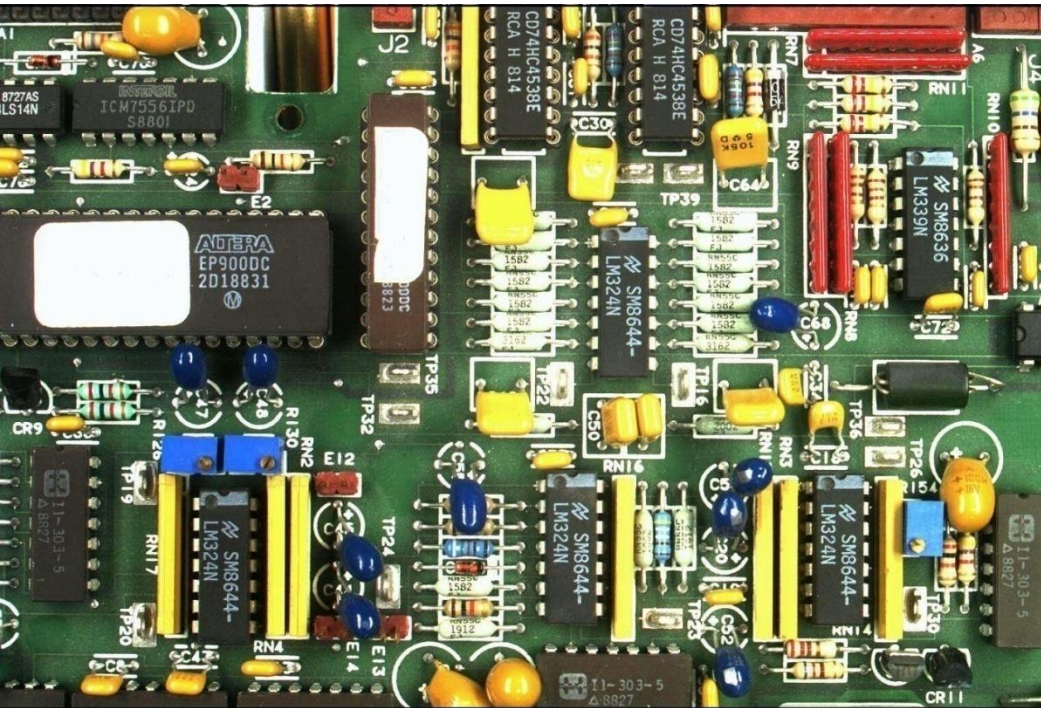
Electron Moving Through Crystal with Vibrating Atoms



http://www4.nau.edu/meteorite/Meteorite/Images/Sodium_chloride_crystal.png

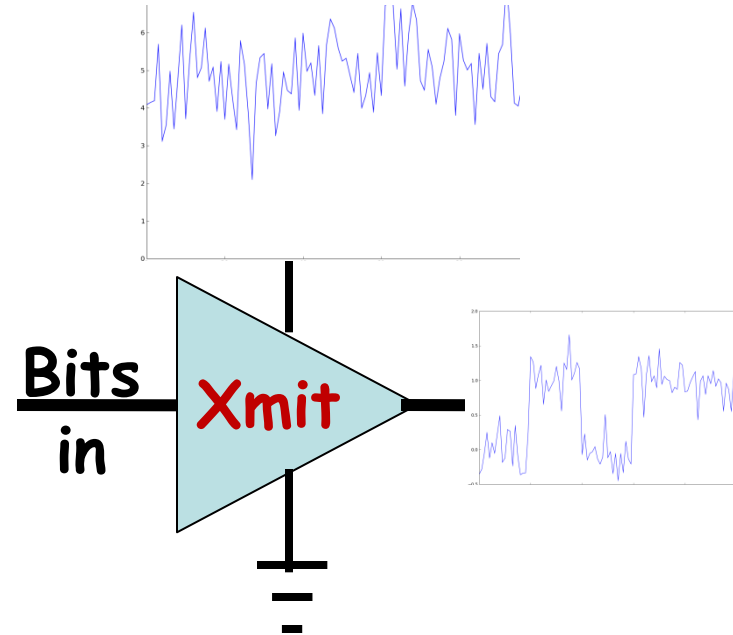
Randomized path leads to noisy current flow

Effect of Many Interactions Can Be Modeled as Noise

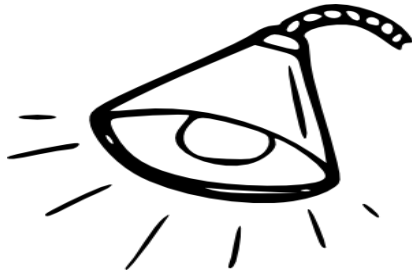


<http://www.imageteck.net/PCB%20Board%203.JPG>

Many components connected by thin wires (that have inductance and resistance) to single power supply - 1000's of devices switching on and off creates "noisy" power supply.



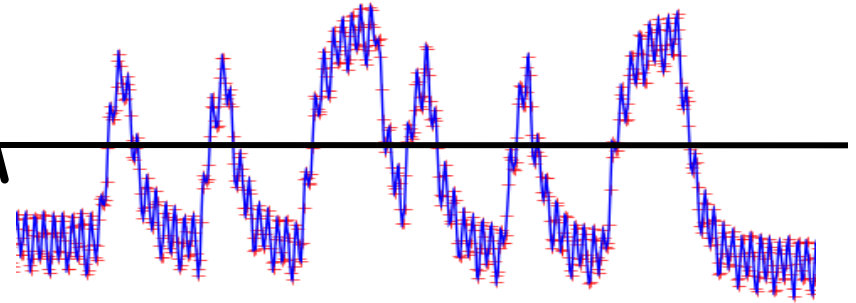
6.02 IR Transceiver Noise Source - Room Light



http://www.clipart.com/cliparts/0/6/b/6/11954240371585298002ryanlerch_lamp_outline.svg.med.png

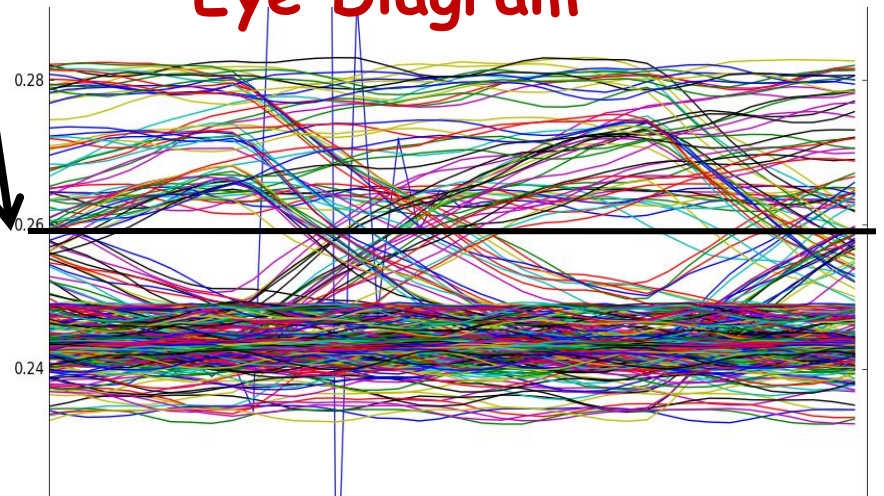
20 Samples/bit

Receiver Waveform

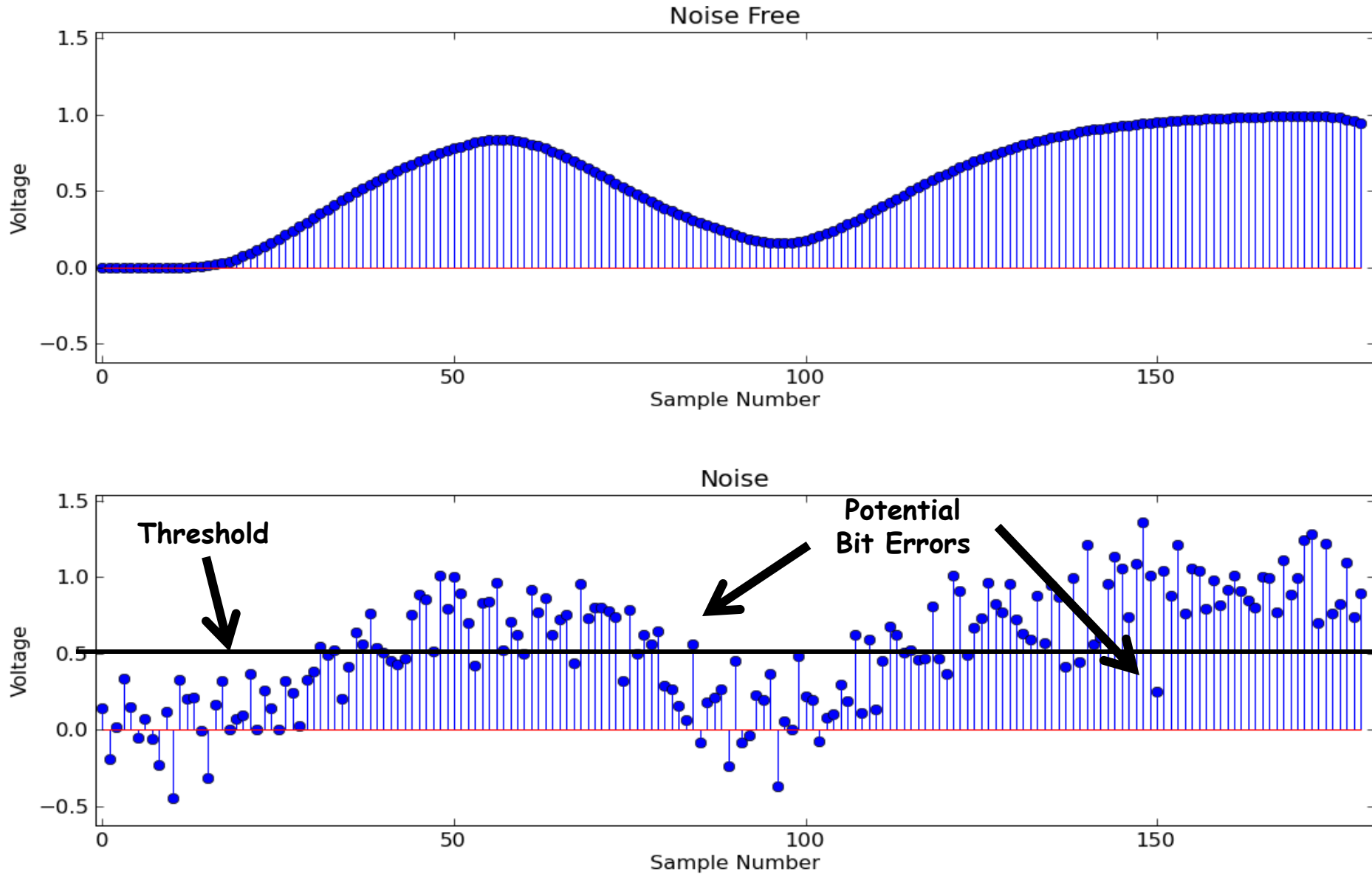


Threshold

Eye Diagram



Noisy Signal Can Cause Bit Errors



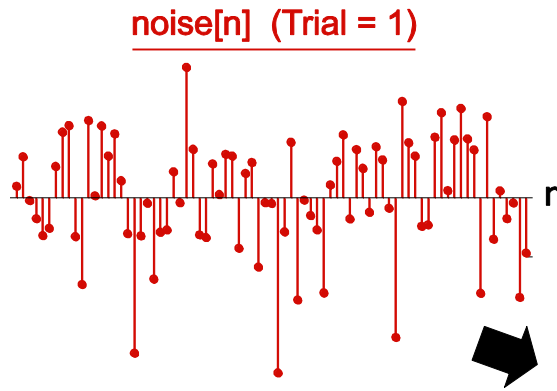
Key Noise Questions For A Channel

- For a given Transmission Scheme:
 - What's the Bit Error Rate (BER)?
 - BER: Fraction of erroneously received bits
- If the Signal is increased:
 - How much is BER reduced?
- If ISI is reduced:
 - Is BER reduced significantly?

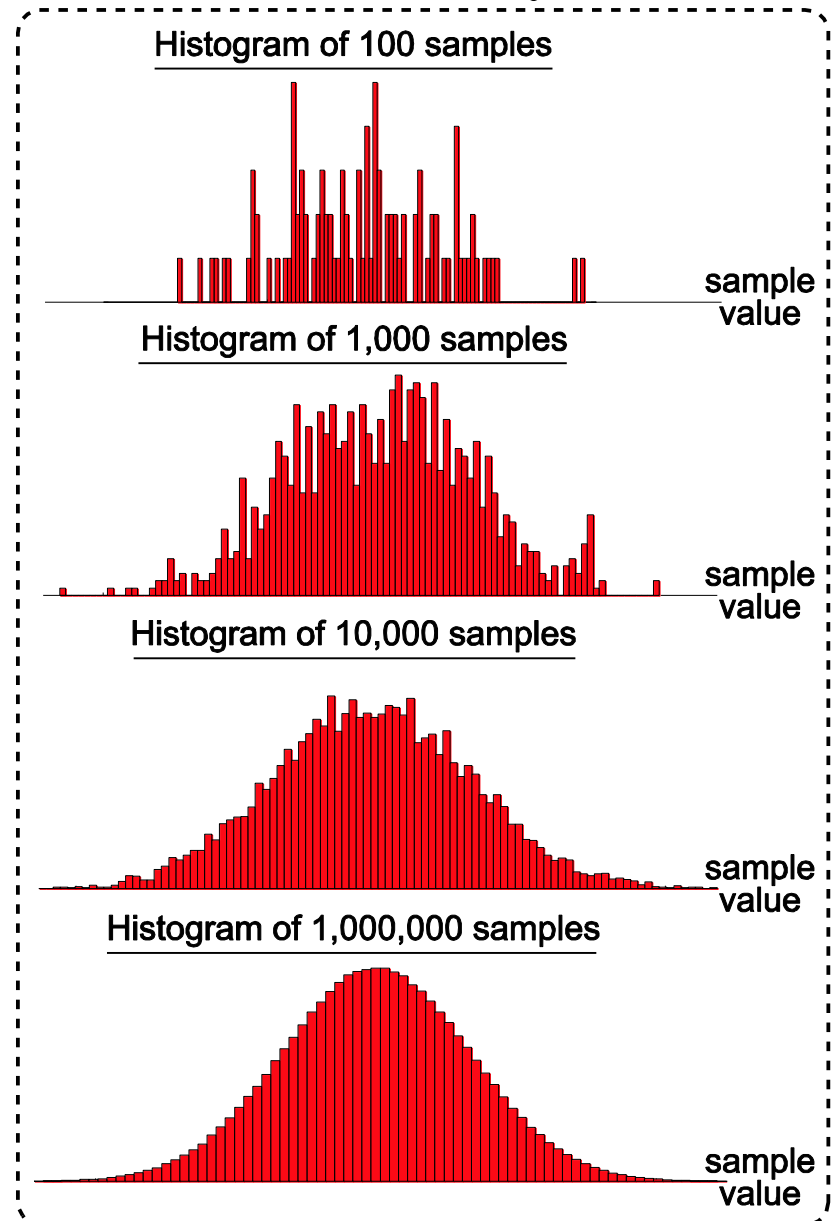
To Answer these questions

- Need to Characterize the Noise
 - What "shape" (probability density function)?
 - How "big" (variance)?

Experiment to see Noise "Shape"



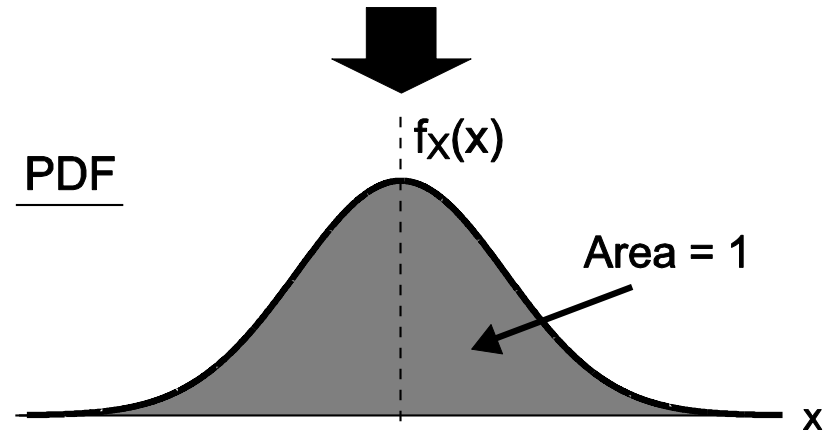
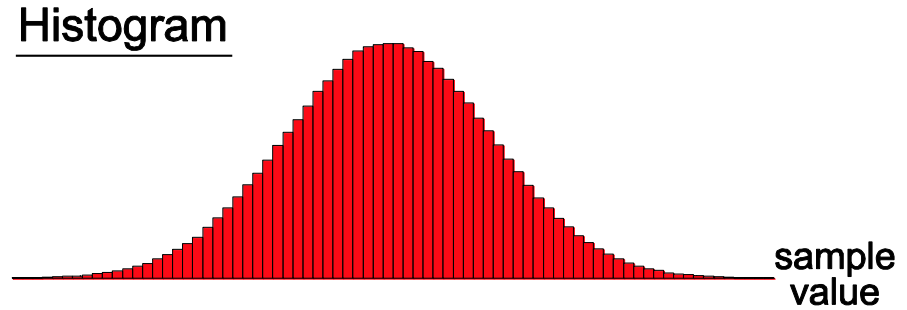
- Create histograms of sample values from trials of increasing lengths
- Assumption of independence and stationarity implies histogram should converge to a shape known as a probability density function (PDF)



"Shape" = Probability Density Function PDF

- Define X as a random variable whose PDF has the same shape as the histogram we just obtained
- Denote PDF of X as $f_X(x)$
 - Scale $f_X(x)$ such that its overall area is 1

$$\Rightarrow \int_{-\infty}^{\infty} f_X(x) = 1$$

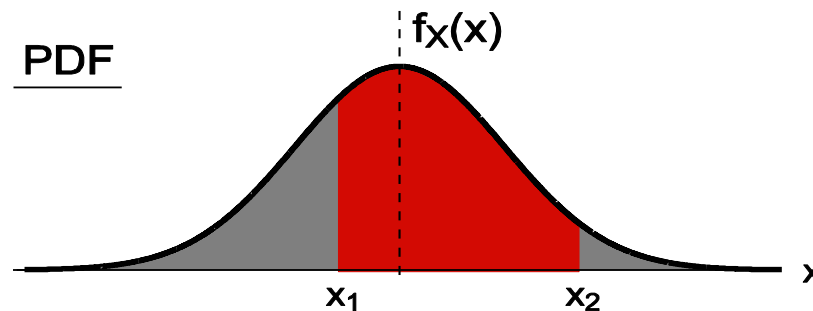


This shape is referred to as a Gaussian PDF

PDF \rightarrow Probability and PDF \rightarrow CDF

- The *probability* that random variable X takes on a value in the range of x_1 to x_2 is calculated from the PDF of X as:

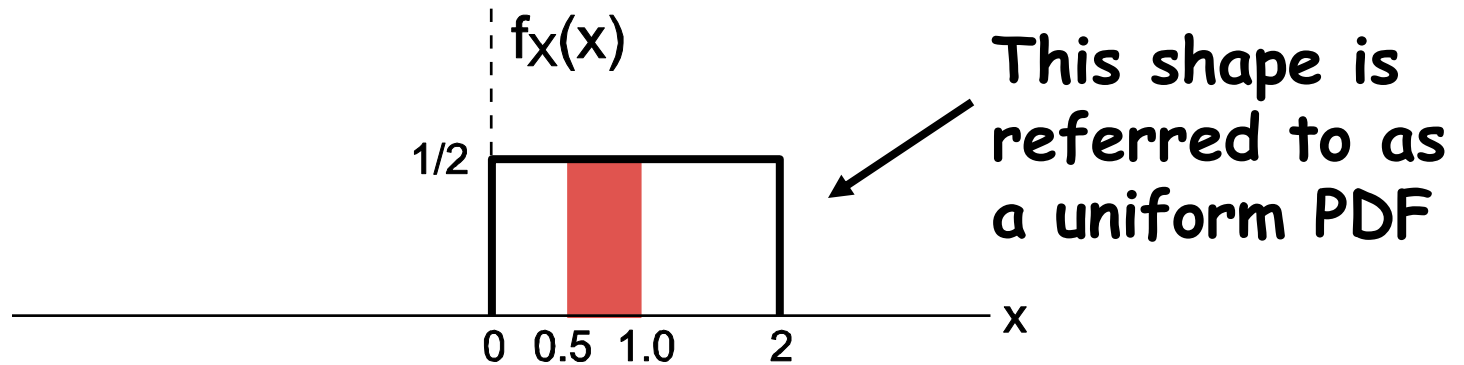
$$\text{Prob}(x_1 \leq x \leq x_2) = \int_{x_1}^{x_2} f_X(x) dx$$



- The *probability* that random variable X takes on a value less than x_1 is the cumulative distribution function **CDF(x_1)**

$$\text{CDF}(x_1) = \text{Prob}(x \leq x_1) = \int_{-\infty}^{x_1} f_X(x) dx$$

Example Probability Calculation



- Verify that overall area is 1:

$$\int_{-\infty}^{\infty} f_X(x) dx = \int_0^2 0.5 dx = 1$$

- Probability that x takes on a value between 0.5 and 1.0:

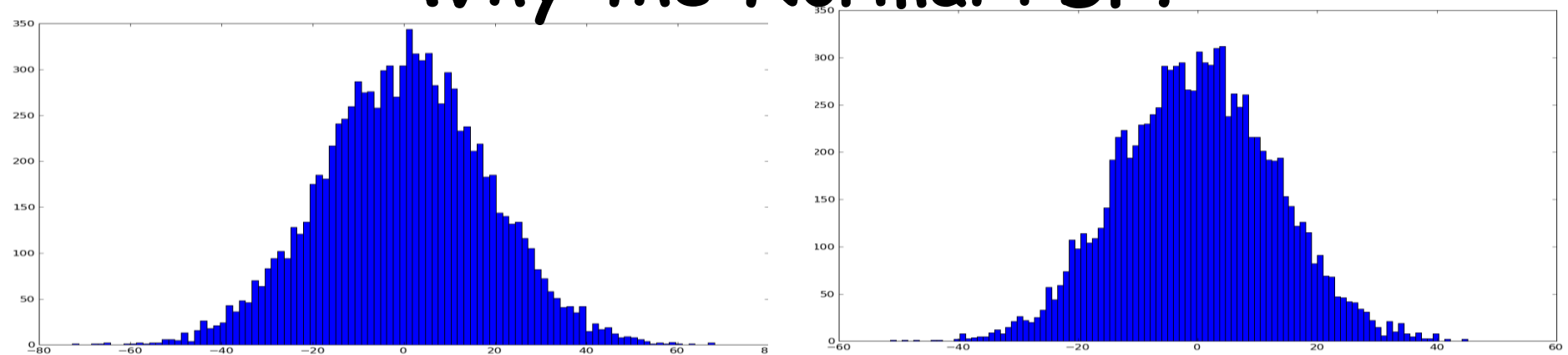
$$\text{Prob}(0.5 \leq x \leq 1.0) = \int_{0.5}^{1.0} 0.5 dx = 0.25$$

Noise Modeled Using Normal (Gaussian) PDF

$$f_X(x) = \frac{1}{\sqrt{2\pi} \sigma} e^{-\frac{x^2}{2\sigma^2}}$$

σ = standard deviation

Why the Normal PDF?

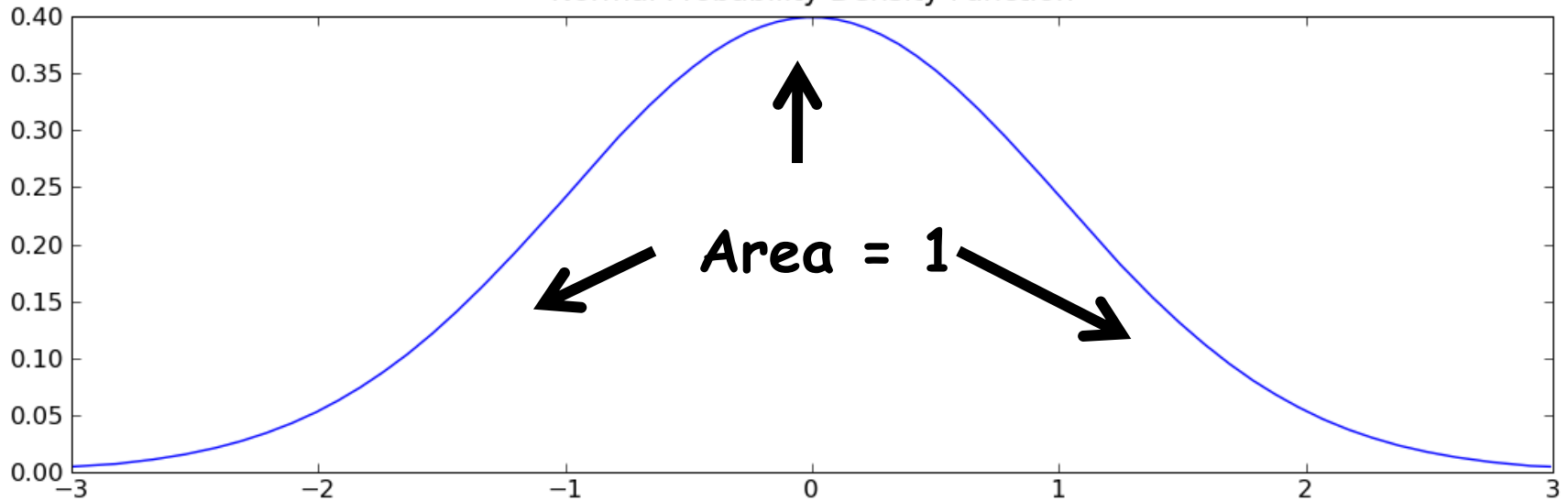


Histogram for 10,000 trials of sums of 1000 uniformly (right) or triangularly (left) distributed $[-1,1]$ random variables

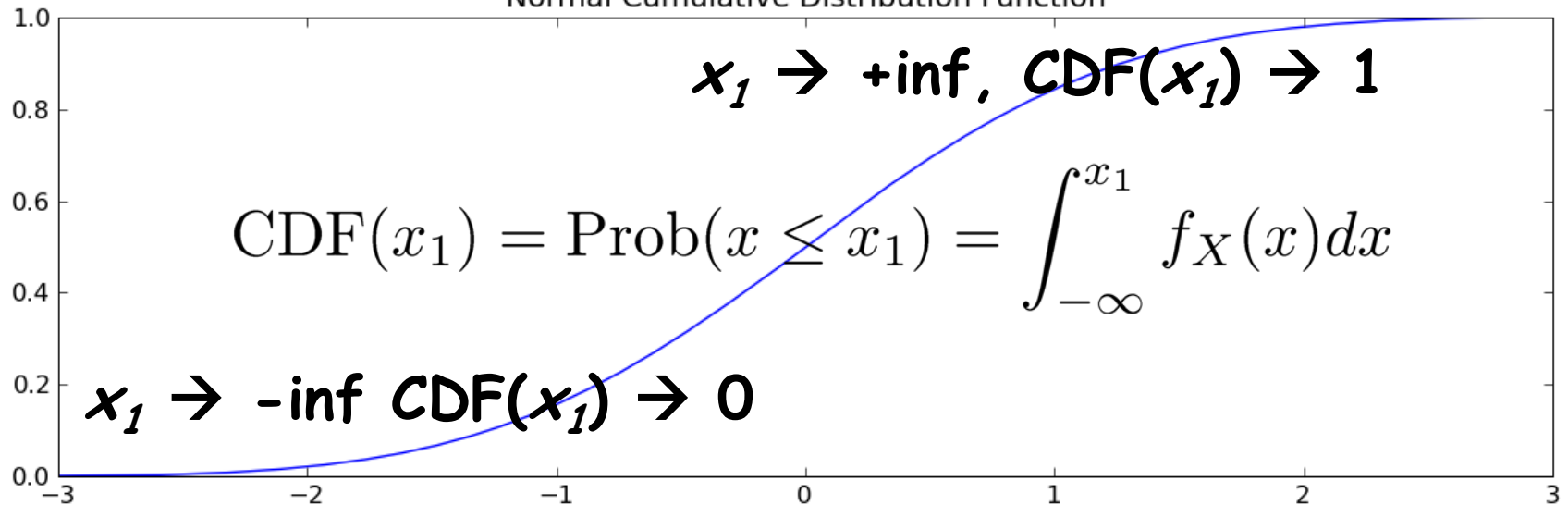
Key Point: Sums of Noise from many sources well approximated by the Normal(Gaussian) PDF

Unit Normal (Gaussian) PDF and CDF

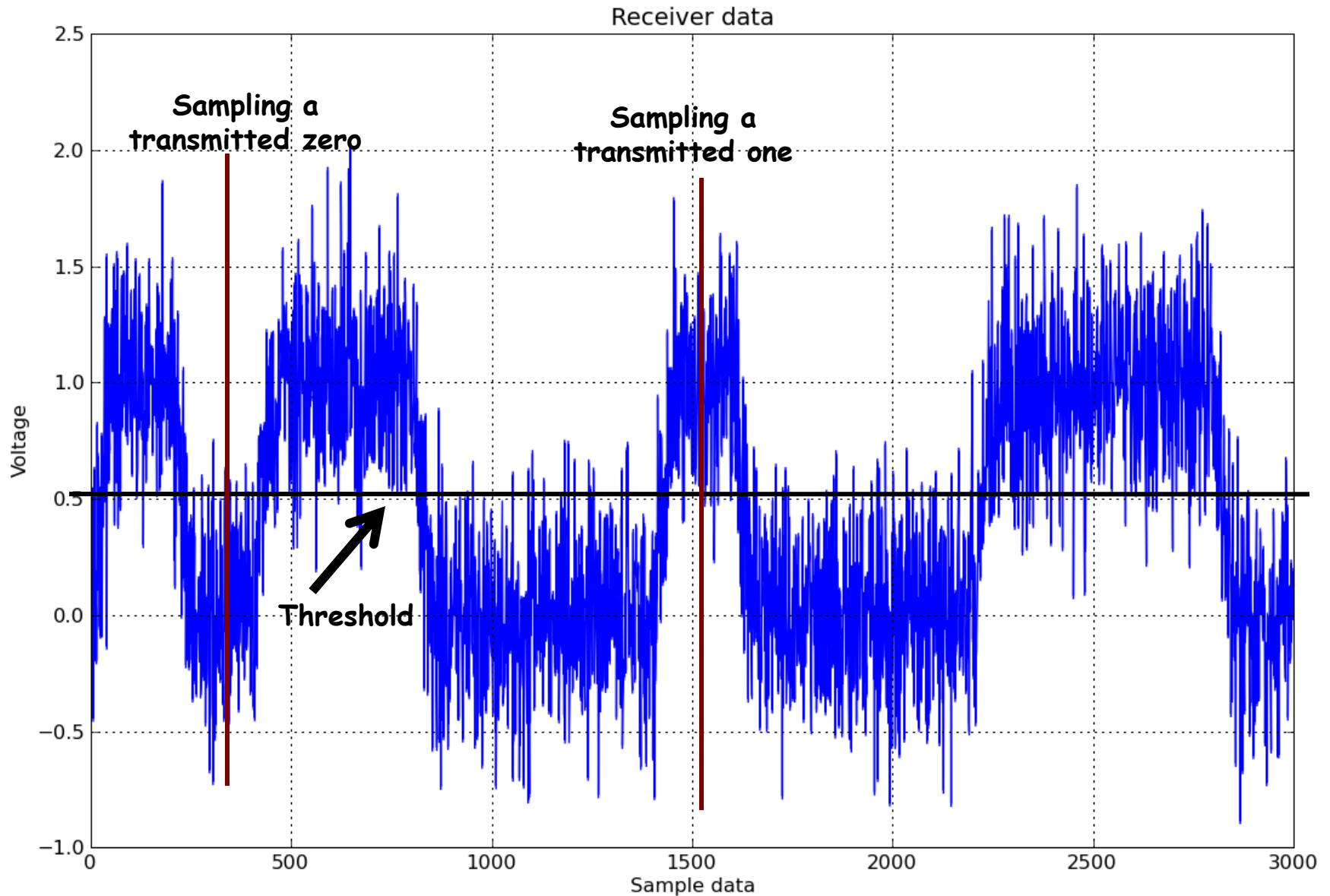
Normal Probability Density Function



Normal Cumulative Distribution Function

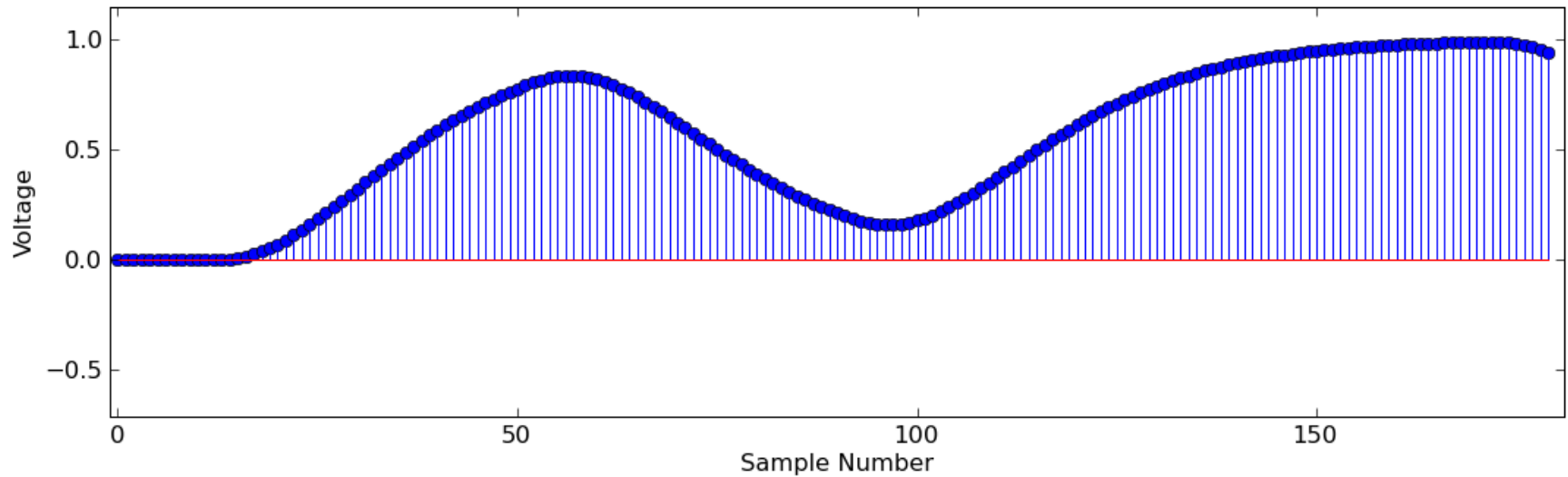


Estimating Probability of Bit Error

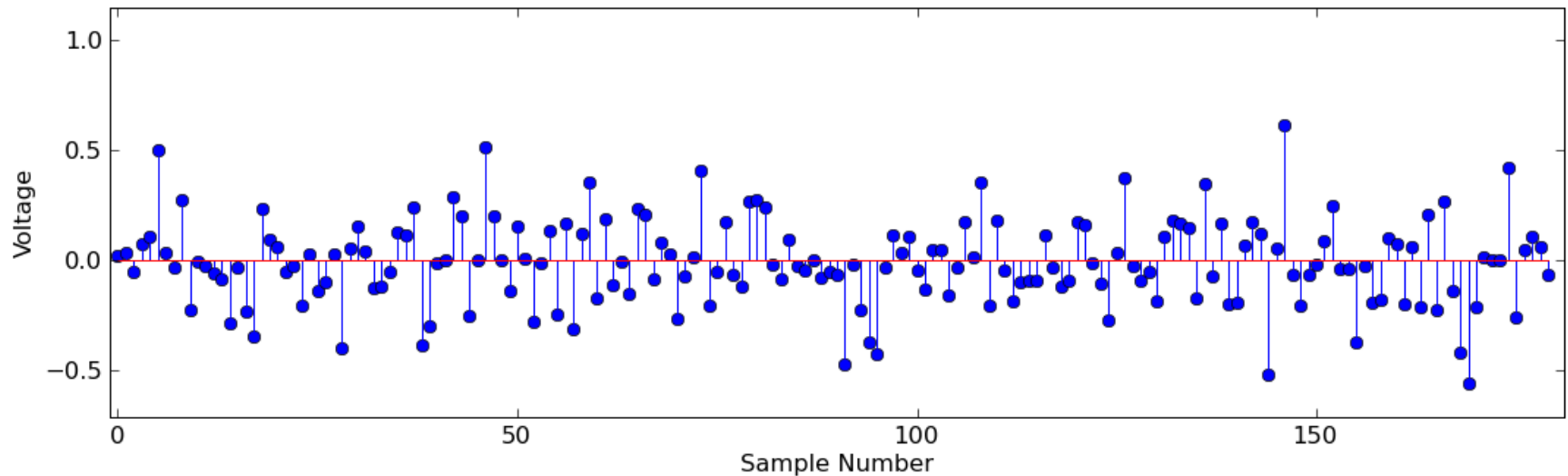


Decompose Into Noisefree + Noise

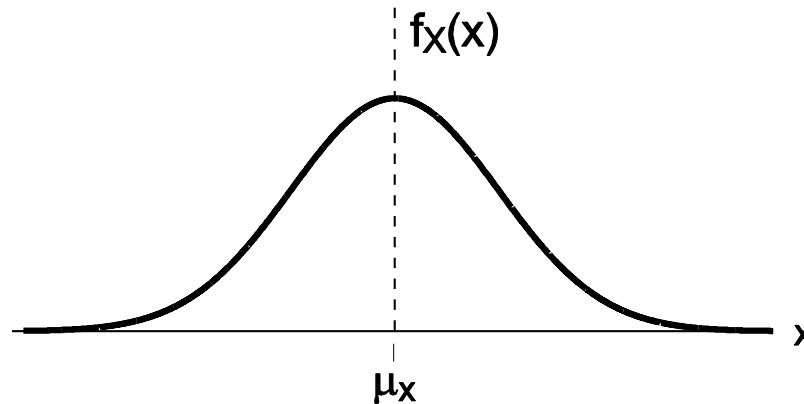
Noise Free



Noise



Mean and Variance



- The mean of random variable X , μ_x , corresponds to its average value

- Computed as

$$\mu_X = \int_{-\infty}^{\infty} x f_X(x) dx$$

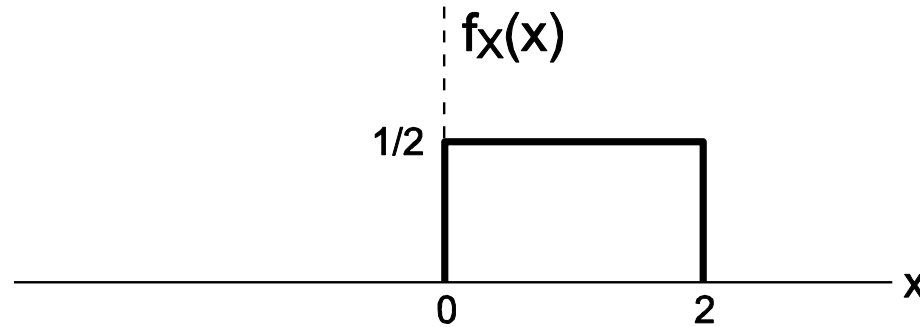
- The variance of random variable x , σ_x^2 , gives an indication of its variability

- Computed as

$$\sigma_X^2 = \int_{-\infty}^{\infty} (x - \mu_x)^2 f_X(x) dx$$

- The standard deviation of a random variable X , is denoted σ_X

Example Mean and Variance Calculation



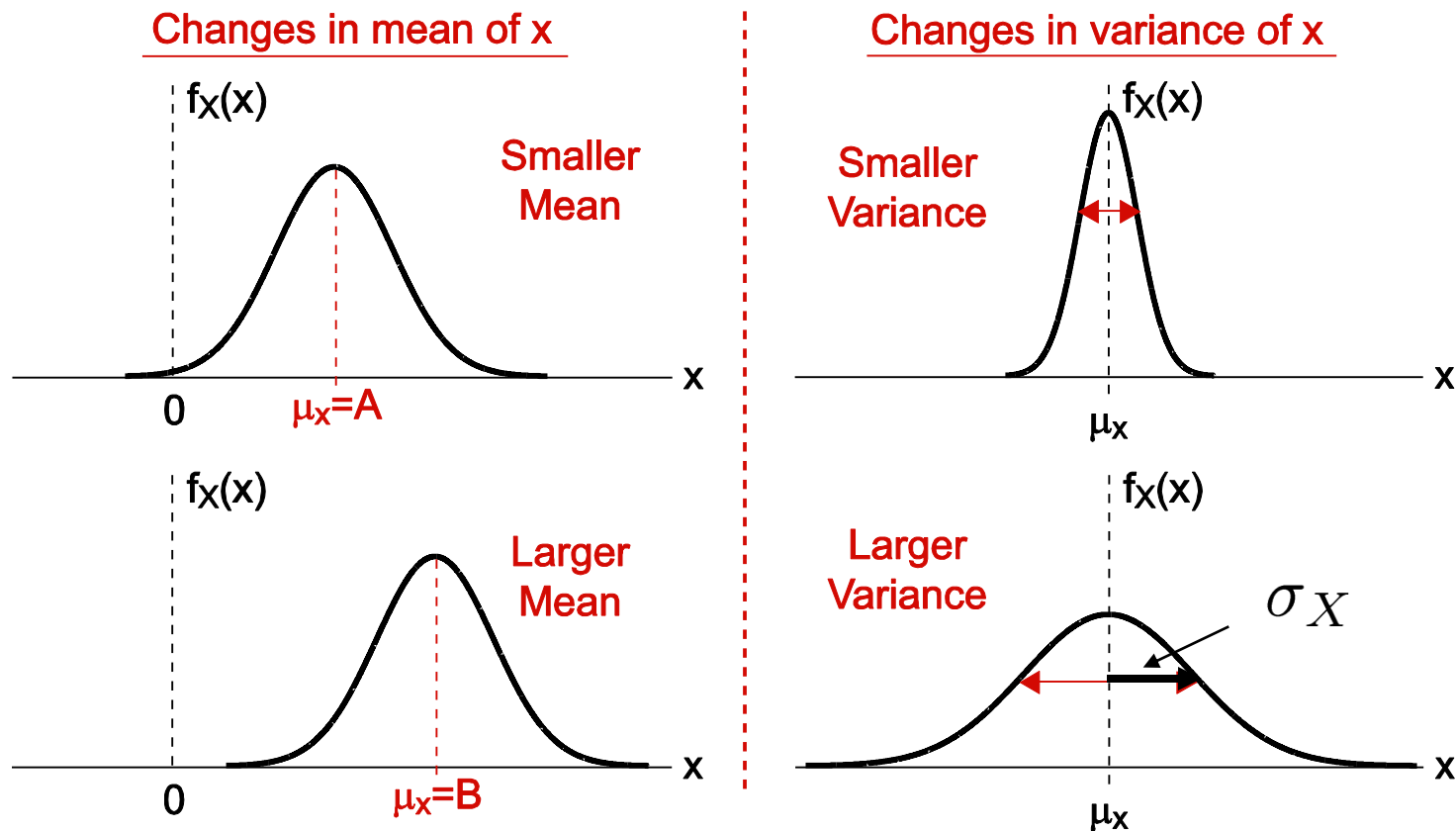
- **Mean:**

$$\mu_X = \int_{-\infty}^{\infty} x f_X(x) dx = \int_0^2 x \frac{1}{2} dx = \frac{1}{4} x^2 \Big|_0^2 = 1$$

- **Variance:**

$$\begin{aligned} \sigma_X^2 &= \int_{-\infty}^{\infty} (x - \mu_x)^2 f_X(x) dx = \int_0^2 (x - 1)^2 \frac{1}{2} dx \\ &= \frac{1}{6} (x - 1)^3 \Big|_0^2 = \frac{1}{6} + \frac{1}{6} = \frac{1}{3} \end{aligned}$$

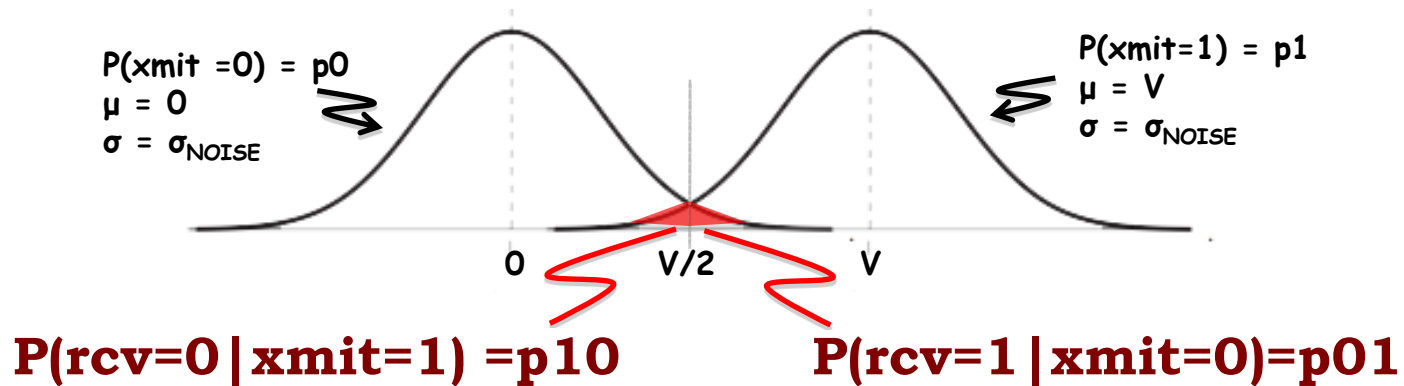
Visualizing Mean and Variance from PDF



- Changes in mean shift the *center of mass* of PDF
- Changes in variance narrow or broaden the PDF
 - Variance tells us how "big" the noise is!

Summary

- Assume Gaussian PDF for noise and no inter-symbol interference (ISI next time) yields the following picture:



- We can estimate the bit-error rate (BER) as

$$P(\text{bit error}) = p_0 * p_{01} + p_1 * p_{10}$$