# ARNAV THAREJA

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#### **EDUCATION**

University of Washington | Seattle, WA Bachelor of Science, Computer Science

Cumulative GPA: 3.97

Coursework: Data Structures & Parallelism, The Hardware/Software Interface, System & Software Tools, Discrete Math, Probability and Statistics, Linear Algebra, Differential Equations

Planned Coursework: Algorithms, Operating Systems, Distributed Systems, Autonomous Robotics, Computer Vision,

Databases, Systems Programming

#### **EXPERIENCE**

**Personal Robotics Lab** May 2021 - Present Undergraduate Researcher Seattle, WA

- Working on multi-agent autonomous navigation and task allocation with MuSHR cars
- Designed and implemented algorithms for non-holonomic multi-agent navigation with optimal task allocation in C++
- Built ROS (Robot Operating System) wrappers around algorithms to enable easy interfacing with existing systems
- Sped up robot trajectory comparison framework by 50x by directly analyzing ROS bags through the rosbag Python API
- Demonstrated and tested system capabilities and translation to real-world environments on physical robots

**Husky Robotics** October 2020 - Present Seattle, WA

Software Engineer, Autonomous Navigation Subteam

- Created robot pathfinding and autonomous navigation algorithms for a prototype Mars rover using C++
- Integrated ROS2 into codebase using nodes and topics for navigation plan visualization
- Defined and implemented a navigation algorithm to locate targets based on approximate GPS coordinates
- Designed patterns for driving between two posts given GPS coordinates of the center
- Leveraged Docker for CI (continuous integration)

Mathnasium May 2019 - June 2020 Instructor Renton, WA

- Taught K-12 students topics in math up to calculus and helped develop an intuitive understanding of math concepts
- Contributed to smooth operation of the center and interacted with parents and prospective customers

## **PROJECTS**

**Chess** | Personal Project

github.com/arnavthareja/chess

Expected Graduation: June 2024

- Built a chess game in Java that can be played in the terminal
- Implemented a minimax algorithm with alpha-beta pruning for automated gameplay with informed move selection
- Used a heuristic-based iterative deepening depth first search algorithm and memoization to improve runtime

**Angles** | DubHacks 2020 - Newsprint Track Finalist (Top 3 out of 70+ Projects)

devpost.com/software/angles-sqdzlt

- Developed a Chrome Extension that suggests news articles of opposite bias when a news website is visited
- Leveraged Google Cloud NLP with JavaScript to extract keywords from news articles to use in our opposite bias algorithm
- Selected as a finalist in the Newsprint track and recognized as one of the top 3 projects out of over 70 projects

#### Yearbook 2020 | Personal Project

yearbook-hhs.web.app

- Designed and developed a web application for students and graduates to sign yearbooks virtually during COVID-19
- Utilized JavaScript, HTML, CSS, and Google Firebase for user authentication, cloud storage, and NoSQL database

## **CL-CBS ROS Wrapper** | Personal Robotics Lab

github.com/arnavthareja/clcbs\_ros

- Created a ROS wrapper and defined a ROS API around the Car-Like Conflict-Based Search (CL-CBS) algorithm using C++
- Extended CL-CBS functionality to allow for parameter reconfiguration and restriction of allowed motion primitives

## **SKILLS**

Languages Tools

Java, C++, Python, C, JavaScript, HTML, CSS

ROS (Robot Operating System), Docker, GDB (GNU Debugger), Linux, CMake, Git, GitHub, LaTeX