

GENERAL QUALIFYING EXAM SOLUTIONS: STELLAR ASTROPHYSICS

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1 Stellar Astrophysics

1.1 Question 1

Sketch out a Hertzsprung-Russell diagram. Indicate where on the main sequence different spectral classes lie. Draw and describe the post main-sequence tracks of both low- and high-mass stars.

1.1.1 Short answer

Answer.

1.1.2 Additional context

Evolution of a $9 M_{\odot}$ star: Figure 1 shows the calculated evolutionary path on the HRD of a $9 M_{\odot}$ star of solar composition. Letters mark critical points in the course of evolution. Specifically, the various points mark the following events:

- A: Beginning of steady hydrogen burning, ZAMS.
- C-C0: Exhaustion of hydrogen in the core, and ignition of hydrogen burning in a shell surrounding the hydrogen-exhausted core.
- E: Arrival on the Hayashi line, that is, the envelope is (almost) fully convective.
- F: Ignition of helium burning in the center.
- J: Exhaustion of helium in the core.
- JK: Ignition of helium burning in a shell surrounding the helium-exhausted core.
- L: Back to the Hayashi line (fully convective envelope).
- LM: Early asymptotic giant branch phase (E-AGB).

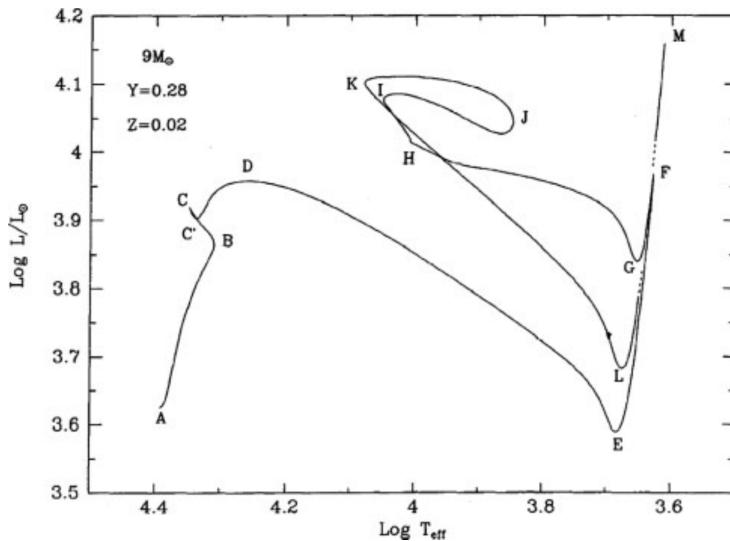


Figure 1: The evolutionary track in the HRD diagram of a $9 M_{\odot}$ star with solar composition from the ZAMS all the way to the AGB phase (hydrogen and helium burning in two separate shells). What happens at the labeled points. Source: Renzini et al. (1992, *Astrophys. J.*, 400, 280). Figure taken from Gregg & Renzini (2011).

Before disclosing what happens at points BDGHI and K (not mentioned in the previous list) it is necessary to introduce a few concepts in the language of stellar model makers. The **core** is the innermost part of the star, where nuclear reactions have greatly altered the original composition. By **envelope** one means the outer part of the star, over (most of) which nuclear burning is negligible and whose composition may still be close to the original one.

Next is the concept of **thermal equilibrium**. *A star is said to be in thermal equilibrium (TE) when the total rate of nuclear energy generation (L_N) is almost perfectly equal to its surface luminosity (L_S).* TE means that the envelope is able to transfer outside and radiate into space quite precisely the same amount of energy which per unit time is produced by nuclear reactions in the core. If $L_S \simeq L_N$ the star is in TE and its evolution proceeds on a nuclear timescale. Conversely, if $L_S \neq L_N$ the star is out of TE, and its evolution proceeds on a thermal timescale, which usually is much shorter than the nuclear

timescale. TE is often broken when the core runs out of fuel or when a new fuel is ignited. A dramatic example of breaking TE is the helium ignition in a degenerate core, called a **helium flash**. At flash peak $L_N \simeq 10^{10} L_\odot$ while $L_S \simeq 2000 L_\odot$ (and decreases!). The energy that does not escape the star is used to expand the helium core, hence relieving its degeneracy.

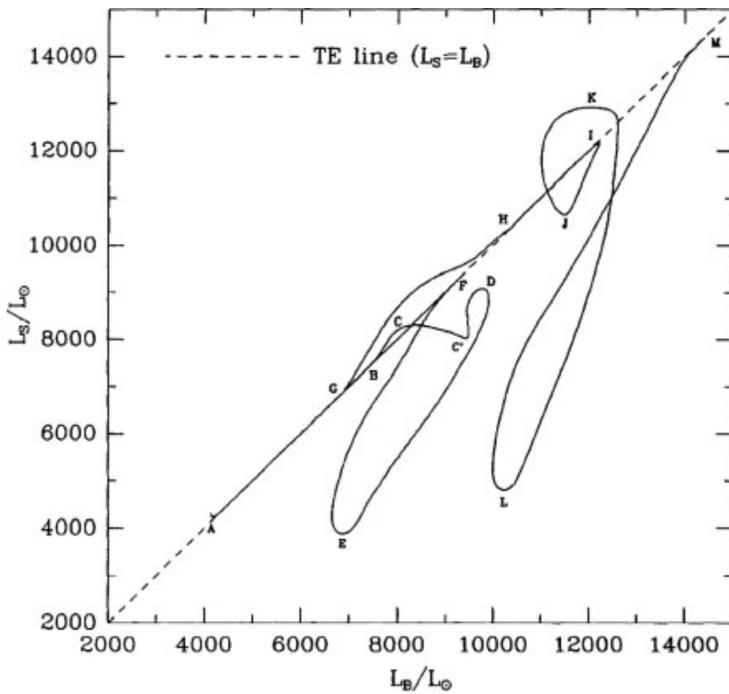


Figure 2: The luminosity radiated from the star's surface as a function of the luminosity released by the stellar core and entering the envelope from its base, for the same track shown in Figure 1. Labels of relevant points along the sequence are the same as in Figure 1. Source: Renzini et al. (1992, *Astrophys. J.*, 400, 280). Figure taken from Gregg & Renzini (2011).

Evolutionary phases in TE and those out of TE can be easily identified by plotting L_S versus L_N , or, equivalently, versus the luminosity impinging at the base of the envelope (L_B), as shown in Figure 2 relative to the evolution of the same $9 M_\odot$ star model whose HRD is shown in Figure 1. Letter labels in this figure mark the same events as in Figure 1, so that one can identify those phases that are in TE and those which are out of it.

Thus, phase AB (which is most of the main sequence phase) proceeds in strict TE, but as hydrogen approaches exhaustion in the core, nuclear burning starts to fall short of keeping in pace with the rate at which energy is being radiated away, the star starts departing from TE and begins to contract (point B). At point B, as the core is running out of fuel the envelope starts losing more energy than it receives, and contracts until at point C hydrogen is effectively exhausted over the central regions, and nuclear energy generation quickly shifts to a shell surrounding a hydrogen-exhausted helium core. The quick readjustment from core to shell burning leaves the star at point C', somewhat out of TE, but then the structure tends to approach again TE, until at point D this tendency is reverted and a major excursion away from TE begins. In stars a little less massive than the one considered here, TE is actually well restored shortly after point C', and yet (as here at point D) TE is broken and stars undergo an extensive loop in the $L_S - L_B$ diagram, as shown in Figure 2. The journey across the HRD from point D to point E takes place on a thermal timescale, and the star expands to red giant dimensions. Clearly, a thermal instability erupts at point D. This is indeed a quite severe thermal instability, suffice to say from Figure 2 that at the peak of the instability the core releases $\sim 7000 L_\odot$ but the envelope radiates away only $\sim 4000 L_\odot$, and $\sim 3000 L_\odot$ are absorbed for its expansion.

The physical origin of this thermal instability is actually quite easy to understand. During phase C'D the luminosity provided by the hydrogen burning shell steadily increases as the shell moves out in the mass coordinate thanks to its own burning, and sits on a progressively more massive helium core. In response to the increasing luminosity impinging on its base (L_B) the envelope slowly expands. By expanding the envelope cools, and by cooling heavy metal ions begin to recombine. Besides being scattered by free electrons, photons now begin to be absorbed by such heavy ions via bound-bound and bound-free transitions: *radiative opacity increases*. This opacity increase is the key factor that determines the onset of the thermal instability. At any point within the star the luminosity transmitted outwards by the radiation field is:

$$L_r = 4\pi r^2 \frac{4acT^3}{3\kappa\rho} \frac{dT}{dr} = 4\pi r^2 F_r \text{ [erg s}^{-1}\text{]},$$

where r is the distance from the center, T the temperature, ρ the density, κ the opacity, and F_r the

radiative energy flux. During phase C'D the envelope slowly expands, hence r^2 increases while the flux F_r decreases, but their product still increases and the star is approaching TE. However, as this trend continues the increase in opacity accelerates and eventually the flux drops faster than r^2 increases, and their product L_r starts to decrease. The decrease happens first near the stellar surface, and then (very quickly) through the whole envelope. At this point the envelope is transferring outwards and radiating away less energy than it receives from the stellar core, that is, $\Delta L = L_B - L_S > 0$. But as the envelope expands more ions recombine, opacity increases further, the flux drops even more, the thermal imbalance $L_B - L_S$ increases and expansion accelerates: the stellar envelope is in a thermal runaway, as it becomes more and more unable to radiate away the energy it receives from the stellar interior.

At point E the surface luminosity starts to rise again, $L_B - L_S$ begins to drop, and TE is rapidly restored. What relieves the instability and saves the star from literally falling apart is convection. As the expanding envelope cools, and opacity increases, eventually the radiative gradient ∇_{rad}^1 exceeds the adiabatic gradient ∇_{ad} , first near the photosphere, where hydrogen is only partly ionized, and then rapidly through the whole envelope. Thus, convection replaces radiative transfer in carrying out energy through the envelope, and the thermal instability is quenched since it was intimately related to the radiative mode of energy transfer. Most of the energy flux in the envelope being now carried by convective motions, the envelope ceases to absorb energy, and the surface luminosity L_S starts to increase again: the star now ascends the Hayashi line, until at point F the helium burning reactions ignite in the core.

Following helium ignition, the helium core initiates a very slow expansion, which will last through a major fraction of the helium burning phase. This is because the helium burning core works like a breeder reactor during this stage, that is, it produces more new fuel than it burns. As triple- reactions produce fresh ^{12}C , the $^{12}\text{C}(\alpha, \gamma)^{16}\text{O}$ reactions release an increasing amount of energy, and the inner core is forced to expand slightly. Such a modest expansion of the core is sufficient to cause a decrease of temperature and density in the surrounding hydrogen burning shell and the stellar luminosity correspondingly starts to decrease. The star now evolves along the **Hayashi line** from F to G, burning helium in the core and hydrogen in the shell, until thermal stability is broken again at point G. As the envelope contracts it heats up gradually, and in particular near its base, heavy ions start losing electrons. Hence opacity decreases along with the radiative gradient. As ∇_{rad} drops below ∇_{ad} a radiative region appears at the base of the envelope and grows outwards in mass. As this growth progresses the envelope becomes more and more transparent to radiation, until it starts radiating away more energy than it receives from the core: $L_B - L_S$ turns increasingly negative, the envelope starts deflating, but the more it contracts the more “transparent” it becomes, and the more energy it loses into space. The thermal instability bringing the star in its envelope deflation from point G to point H is precisely the reverse analog of the thermal instability that causes the runaway expansion from point D to point E. As envelope inflation can be ascribed to a runaway recombination of heavy elements in the envelope, envelope deflation is due to a runaway ionization of such heavy elements. A comparison of the three figures (Figures 1-3) helps in visualizing the onset of the thermal instability and of its results.

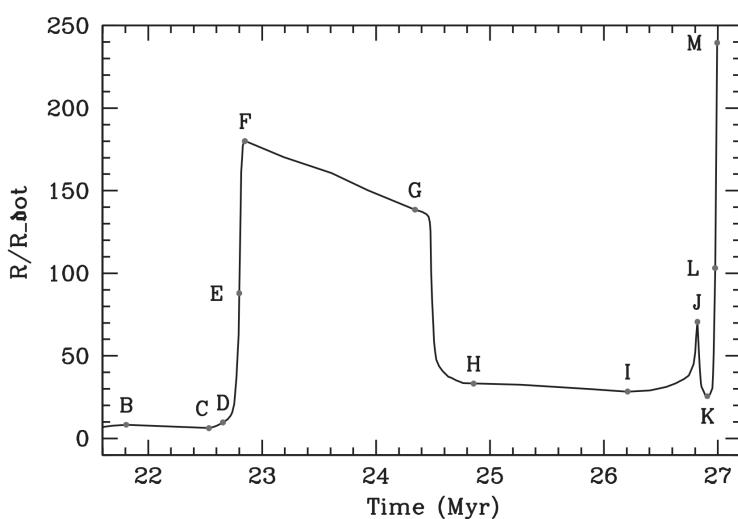


Figure 3: The stellar radius as a function of time for the same track shown in Figure 1. Labels of relevant points along the sequence are the same as in Figure 1. Source: Renzini et al. (1992, *Astrophys. J.*, 400, 280). Figure taken from Greggio & Renzini (2011).

Thus, in this star, the core helium burning phase in thermal equilibrium is spent in two distinct locations in the HRD: part on the Hayashi line as a red giant (F-G) and part as a blue giant (H-I) separated by a runaway contraction out of TE (G-H). This first blue loop (also called the **Cepheid blue loop**)

¹Temperature gradients are defined as $\nabla T(\rho, T, X_i) = (\partial \log T / \partial \log P)$.

continues after point I when TE is broken again. Here the envelope is slowly expanding in response to the slowly increasing luminosity from the core and shell burning, when the envelope turns unstable again due to the same physical process already described for the DE phase.

However, the journey towards the Hayashi line is suddenly interrupted and inverted at point J, which marks the start of the so-called **second blue loop**. What happens at point J and after is a rather complex series of interconnected events: helium is exhausted in the core, the core contracts and helium burning rapidly shifts from the helium-exhausted CO core to a shell surrounding it; helium shell ignition is quite violent and causes expansion of the helium buffer above this shell: when the expansion front breaks through the hydrogen burning shell temperature and density in the shell drop; burning in the hydrogen shell (which was still providing most of the stellar luminosity) is effectively shut off completely causing a sudden drop of the luminosity impinging on the base of the envelope: L_B drops below L_S and the envelope stops expanding and contracts. In the meantime the strength of the helium burning shell steadily increases until it leads L_B to exceed L_S again, contraction stops and the star resumes at point K its runaway expansion that was temporarily stopped at J. The rest, from K to L to M is quite similar to the DEF phase, with convection replacing radiative transfer in the envelope and TE being rapidly restored, shortly before point M. Figure 3 clearly illustrates the dramatic effects of the envelope thermal instabilities on the overall structure of the star. Those phases which are in TE are nearly flat in this plot, that is, the stellar radius changes quite slowly with time. With one exception, those phases which are out of TE are instead nearly vertical, that is, the radius varies very rapidly during such runaway inflations or deflations. The exception is phase BC, which is only modestly out of TE, and contraction is relatively slow.

What happens past point M is still an open issue. A $9 M_\odot$ star lies between two domains: massive stars that eventually undergo core collapse and supernova explosion, and intermediate-mass stars, which shedding all their hydrogen-rich envelope die as a white dwarf. One believes that in a $9 M_\odot$ star carbon is ignited in the central core under only mildly degenerate conditions, and the star keeps ascending along the Hayashi line as a super asymptotic giant branch star experiencing a few thermal pulses in its deeper regions, where hydrogen and helium are still burning in two separate shells. Thus, if the envelope is completely lost in a wind the star leaves an ONeMg white dwarf. If instead mass loss is less severe then the core keeps growing in mass thanks to the active burning shells until electron captures in the core trigger a core collapse and we have a supernova explosion. Clearly the fate critically depends on the strength of the mass loss process.

Evolution of a Solar-composition star: Figure 1.4 shows stellar evolutionary tracks of solar composition, covering a wide range of initial masses, from a $0.8 M_\odot$ star, whose MS evolutionary lifetime is longer than one Hubble time, up to a $20 M_\odot$ model. The evolutionary tracks of stars with mass greater than $20 M_\odot$ are heavily affected by mass loss.

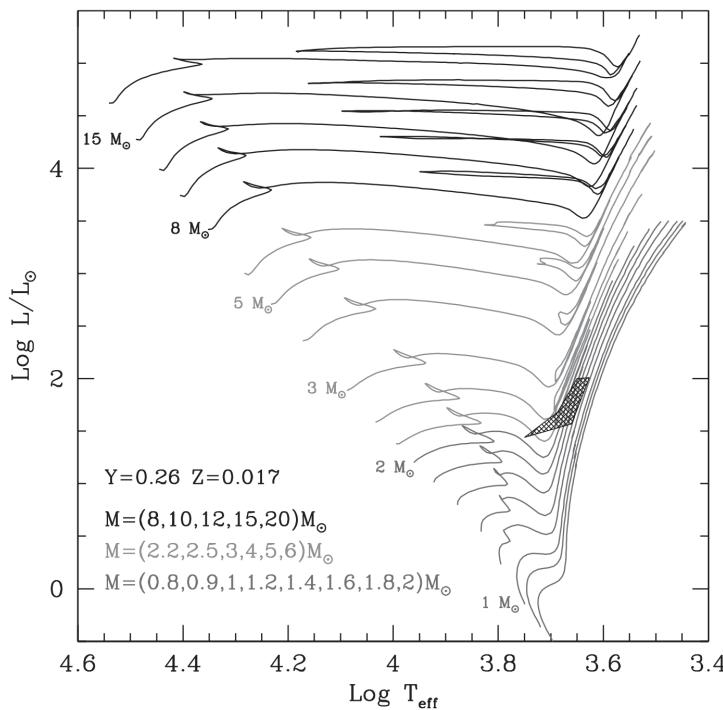


Figure 4: Evolutionary tracks of solar composition star. The shaded area shows the location of low-mass ($0.55 \leq M/M_\odot \leq 2$) core helium burning models. Drawn using the YZVAR database (Bertelli, G. et al. 2008, Astron. Astrophys., 484, 815; 2009, Astron. Astrophys., 508, 355). Figure taken from Greggio & Renzini (2011).

Different gray shades in Figure 4 pertain to the different mass ranges as customarily distinguished in

stellar evolution: low-mass stars, up to $\lesssim 2.2 M_{\odot}$, intermediate-mass stars, up to $\lesssim 8 M_{\odot}$, and high-mass stars. These ranges correspond to different physical behavior during the evolution of the stars, and the mass limits depend on chemical composition. Low-mass stars develop an **electron degenerate helium core** after their MS evolution; intermediate mass stars ignite helium under non-degenerate conditions, but develop a **CO degenerate core** after central helium burning; massive stars experience all successive nuclear burnings up to the production of an **iron core**.

During their MS evolution, stars with mass below $\sim 1 M_{\odot}$ burn hydrogen through the **p-p chain**, whose reaction rate is not extremely sensitive to temperature, so that these stars possess a radiative core. As evolution proceeds hydrogen is progressively depleted in the inner core, more in the center than in the periphery, leading to a smooth hydrogen profile from a central minimum up to the initial abundance in the outer layers. On the HRD, the stellar track climbs to higher luminosities and temperatures until the central hydrogen is severely depleted; at this point the effective temperature starts decreasing, producing the turnoff (TO), that is, the maximum temperature point on the MS, which is easily recognizable on the CMD of globular clusters. Shortly after the TO, hydrogen is completely exhausted in the center and the hydrogen shell burning phase starts as a natural progression from the previous core hydrogen burning phase. During shell hydrogen burning, the track forms the subgiant branch (SGB), evolving at (almost) constant luminosity and decreasing temperature until the external convection penetrates deeply inside, and the star becomes almost fully convective at the base of the red giant branch (RGB).

The MS stars (with $M \gtrsim 1 M_{\odot}$) have a convective core, since at least part of the hydrogen burning occurs through the CNO cycle, whose energy generation rate is extremely sensitive to temperature. Because of central mixing, the hydrogen profile is characterized by an inner plateau; as evolution proceeds, the extension of the convective core progressively decreases, leaving behind a gradient of hydrogen abundance. In stars with a convective core, the fuel depletion affects a sizable central region, which starts rapid contraction when approaching fuel exhaustion. This happens at the local minimum effective temperature point during the MS evolution of stars with $M > 1 M_{\odot}$ (Figure 4), which signals the beginning of the overall contraction phase. The evolutionary behavior across this phase and the following runaway expansion has been already described in detail in the previous section.

As already mentioned, the helium core of low-mass stars is (electron) degenerate: this implies that central helium ignition is delayed because core contraction does not lead to an efficient increase of the central temperature. The (almost) fully convective star climbs along the RGB, while the hydrogen burning shell progresses outward, thereby increasing the mass of the helium core. When the core reaches a critical limit, a helium flash occurs off-center, since neutrino losses induce a temperature inversion in the innermost layers. This event is not catastrophic for the star because local expansion removes the degeneracy; instead, a sequence of flashes occurring at progressively inner locations totally remove the core degeneracy. During this phase, which lasts 1 Myr, the star moves downward along the Hayashi line to settle on the core helium burning locus, either the red clump, or the horizontal branch (HB). The maximum luminosity reached on the RGB (RGB Tip, or TRGB) is a very important feature in the color-magnitude diagram (CMD) of stellar populations because it is virtually independent of mass, and then of evolutionary lifetime. This is because on the one hand the critical mass for helium ignition under degenerate conditions is almost constant ($0.5 M_{\odot}$), and on the other, along the RGB there exists a core mass-luminosity relation. The evolutionary lifetimes of low-mass stars range from 1 Gyr up to the Hubble time, as seen in Figure 4, and all of them experience the helium flash at almost the same luminosity; therefore, the CMD of a stellar population with stars older than 1 Gyr will show a prominent TRGB feature whose luminosity is known, thus allowing us to determine the distance of the stellar population. The TRGB luminosity depends slightly on metallicity, being higher for higher metal content. However, by a fortunate combination, the absolute magnitude in the I-band of the TRGB does not depend much on metallicity, for metal-poor populations. This is because the effective temperature at the TRGB also depends on metallicity: the higher Z , the cooler the TRGB stars, and the higher the bolometric correction (in absolute value). The trend with metallicity of the bolometric correction to the I-band largely compensates that of the tip luminosity, so that the I-band absolute magnitude of the TRGB ($M_{I,TRGB}$) is almost independent of age and weakly dependent on metallicity of the parent stellar population. This makes $M_{I,TRGB}$ a very effective distance indicator in galaxies.

The luminosity of core helium burning low-mass stars, being fixed by the mass of their hydrogen-exhausted core, is also largely independent of their total mass, thereby providing another distance indicator. However, evolution during the core helium burning phase spreads the red clump stars over 0.6 magnitudes, as can be seen from the vertical size of the hatched region in Figure 4. In addition, the core mass at helium ignition is not a monotonic function of the total mass, and as the latter increases beyond the limit of the low-mass stars regime (M_{Hef}), it decreases, reaches a minimum of about $0.326 M_{\odot}$, and then increases. As a result, stars with mass just above M_{Hef} start their core helium burning evolution at fainter luminosities, have the longest helium burning lifetimes, and cover a wider range of luminosities, compared to stars with $M < M_{Hef}$. Therefore, the core helium burners of a composite stellar population

Z, Y	a	H burning lifetime			Lifetime up to first pulse or C ignition				
		b	c	$\left\langle \frac{\Delta t_{\text{TO}}}{t_{\text{TO}}} \right\rangle$	a	b	c	$\left\langle \frac{\Delta t_{\text{tot}}}{t_{\text{tot}}} \right\rangle$	
0.0001, 0.23	0.8751	-3.240	9.754	0.041	0.8130	-3.194	9.809	0.022	
0.0001, 0.40	0.8248	-3.007	9.288	0.049	0.7784	-2.992	9.371	0.023	
0.001, 0.26	0.8192	-3.168	9.705	0.040	0.7679	-3.147	9.776	0.031	
0.001, 0.40	0.7590	-2.951	9.310	0.049	0.7363	-2.976	9.409	0.032	
0.004, 0.26	0.8085	-3.230	9.796	0.040	0.7534	-3.211	9.875	0.042	
0.017, 0.26	0.8071	-3.423	10.029	0.038	0.7260	-3.369	10.104	0.053	
0.04, 0.26	0.7466	-3.516	10.213	0.049	0.6694	-3.457	10.281	0.063	
0.04, 0.40	0.7649	-3.361	9.767	0.073	0.7324	-3.371	9.866	0.063	
0.04, 0.46	0.7362	-3.243	9.554	0.082	0.7427	-3.303	9.669	0.068	
0.07, 0.40	0.7322	-3.420	9.855	0.079	0.7065	-3.437	9.948	0.066	

Table 1: Coefficients of $\log t$ for various chemical compositions, resulting from the least square fit of the hydrogen burning and the total lifetimes as a function of M_0 . The fit covers the range $0.6 \leq M_0/M_\odot \leq 20$; columns 5 and 9 report the average relative accuracy on the evolutionary lifetimes at the TO and at the first thermal pulse or central carbon ignition. The YZVAR database (Bertelli, G. et al. 2008, Astron. Astrophys., 484, 815; 2009, Astron. Astrophys., 508, 355) has been used to derive the coefficients. Table taken from Greggio & Renzini (2011).

with a sizable component at ages just below 1 Gyr are spread over a wide magnitude range, which limits the use of this feature for distance determinations.

The effective temperature of low mass core helium burning stars depends on the mass of their envelope, a dependence which is very pronounced when the envelope is thinner than for example $0.2 M_\odot$ for $Z \lesssim 0.1 Z_\odot$. Below this threshold, the lower the envelope mass, the hotter the core helium burning stars. In a coeval and homogeneous stellar population the core helium burning stars all have virtually the same core mass and then luminosity; a spread of their envelope masses produces a feature on the HRD at about constant (bolometric) magnitude extending over a temperature range. The observational counterpart of this locus is the horizontal branch: a prominent feature in the HRD of globular clusters whose age is old enough to host core helium burning stars with low-mass envelopes. The existence of wide HBs in globular clusters was explained as due to a dispersion of mass lost during the RGB phase, but recently it became apparent that other effects are also at play. Evolutionary tracks during the core helium burning phase exhibit a wide variety of morphologies, depending on their mass, envelope mass, metallicity and helium abundance. At central helium exhaustion, a rapid core contraction leads to shell helium ignition; the model star expands and moves again towards the Hayashi line to start the asymptotic giant branch (AGB) evolutionary stage. However, if the envelope mass is small enough, the shell helium burning phase is entirely spent at high effective temperatures, as an AGB manqué star. The hot HB stars and their AGB manqué progeny are likely responsible for the UV emission from elliptical galaxies which host old stellar populations.

The evolution of intermediate and high-mass stars during the hydrogen and helium burning stages is very similar to what has already been described for the $9 M_\odot$ star. But, following helium exhaustion, intermediate-mass stars behave similarly to low-mass stars. We only notice here that for stars with mass in the vicinity of M_{Hef} the core helium burning phase is spent in a red clump, which becomes a wider and wider blue loop as the model mass grows. Thus, the core helium burning phase of intermediate-mass stars is spent part in the blue and part in the red. The very occurrence of the loop, its extension and the fraction of lifetime spent on each side of the loop, are sensitive to a number of parameters describing the input physics of the models, like metallicity, opacity, convection and others. Therefore, the blue-to-red ratio in stellar populations with stars in this mass range is difficult to interpret. The luminosity of intermediate mass core helium burners is instead a more robust prediction of the models, and can be effectively used as an age indicator of stellar populations.

Dependence on chemical composition: The evolutionary tracks of given mass are very sensitive to the (initial) helium content (Y) and metallicity (Z), which control the energy generation rates and the opacity. We briefly illustrate some dependencies relevant to the interpretation of the HR diagram and of the spectral energy distribution of stellar populations.

At a given initial mass, evolutionary lifetimes become shorter as Y increases, because stars with higher molecular weight are more compact, hotter, brighter, hence faster in consuming the hydrogen fuel, of which less is available. Instead, lifetimes become longer as Z increases, because the hydrogen burning models get fainter due to the higher opacity, while the hydrogen fuel reservoir remains virtually unchanged. Table 1.2 lists the values of the coefficients of the following relation:

$$\log t = a \log^2 M_0 + b \log M_0 + c [\text{yr}],$$

adopted to describe the evolutionary lifetimes (in years) as a function of initial mass (in M_{\odot}). The parabolic fit over the whole considered mass range is a rather drastic approximation; nevertheless these analytic relations can be useful to estimate evolutionary lifetimes and their dependence on composition. As mentioned previously, the values of mass defining the low, intermediate and high-mass range depend somewhat on chemical composition. For example M_{He} decreases with Y increasing and with Z decreasing. Therefore, an extended RGB on the HRD of a stellar population traces the presence of evolved stars with mass lower than $2.1 M_{\odot}$ for solar composition, or with mass lower than $1.5 M_{\odot}$ if $Z = 0.001$, $Y = 0.4$. However, evolutionary lifetimes at given mass also depend on composition, and, by and large, an extended and well populated RGB is developed in stellar populations older than 1 Gyr almost irrespective of chemical composition.

At fixed initial mass, zero age main sequence models are hotter and brighter for a higher helium content, and/or a lower metallicity. Indeed, the locus of the corresponding stars on the HRD (ZAMS) is used to infer the composition of the target stellar population, and is virtually the only way to estimate the helium content of these stars, if Z is known from spectroscopy. The puzzling composition of multiple stellar populations in some galactic globular clusters has been derived from ZAMS fitting.

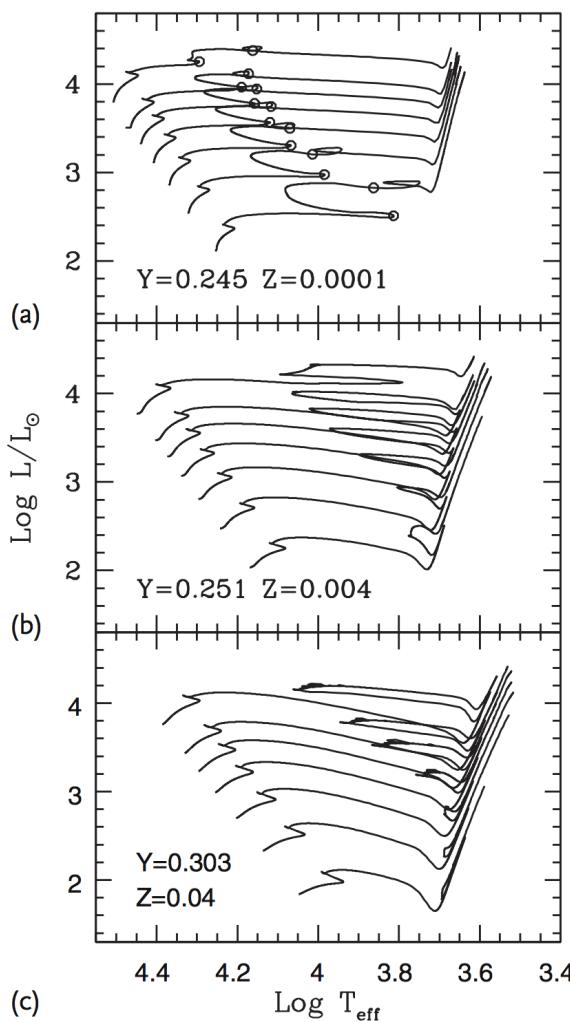


Figure 5: a-c) Evolutionary tracks of intermediate-mass stars ($M/M_{\odot} = 3, 4, 5, 6, 7, 8, 10$) for different compositions, as labeled. In (a), the open circles mark start and the end of the core helium burning phase. Drawn using the BaSTI database (Pietrinferni, A. et al. 2004, *Astrophys. J.*, 612, 168). the Figure taken from Gregg & Renzini (2011).

Figure 5 shows some evolutionary tracks of intermediate-mass stars for three different initial compositions. The described trend of the ZAMS with metal content is readily visible, together with some other properties already mentioned: at very low metallicity (Figure 5a) the entire core helium burning phase occurs in the blue part of the HRD, and the thermal runaway in the envelope which brings the model star to the Hayashi track is delayed to the very latest stages. As metallicity increases, the luminosity decrease associated with the thermal runaway gets more and more pronounced: this reflects the progressively higher opacity, and then radiative energy trapping in the envelope. At the same time, at higher metallicity it is more difficult to produce extended blue loops: the 3 and $4 M_{\odot}$ tracks at $Z \sim 2 Z_{\odot}$ do not present a blue loop at all, and the loop of the $5 M_{\odot}$ track is just alluded to. The models in Figure 5 are computed adopting classical recipes for the input physics, and even slight modifications of the assumptions lead to dramatic variations of the tracks shape. For example, intermediate-mass models with $Z = 0.04$, $Y = 0.40$ which adopt a modest overshooting from the convective core lack the loops completely, and the core helium

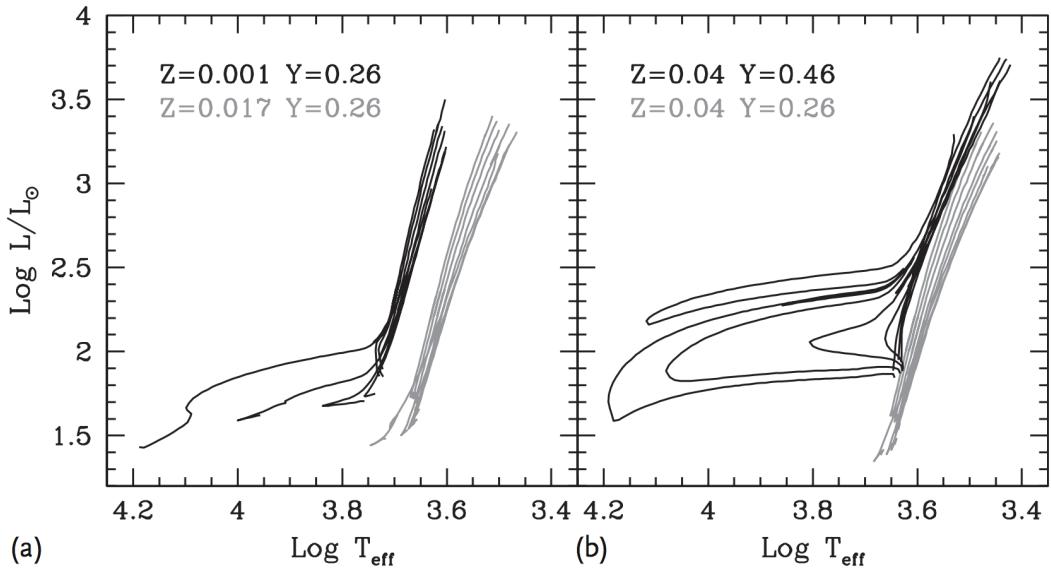


Figure 6: (a,b) Evolutionary tracks of low-mass stars during the core helium burning and early AGB phases. The chemical composition is labeled. Initial model masses are $M/M_{\odot} = 0.55, 0.6, 0.65, 0.7, 1, 1.2, 1.4, 1.6$ except for the ($Z = 0.04, Y = 0.46$) set, for which the $1.6 M_{\odot}$ track ignites helium under non-degenerate conditions. Drawn using the YZVAR database (Bertelli, G. et al. 2008, Astron. Astrophys., 484, 815; 2009, Astron. Astrophys., 508, 355). Figure taken from Greggio & Renzini (2011).

burning phase is totally spent close to the Hayashi line.

Figure 6 illustrates the effect of chemical composition on core helium burners of low-mass. The gray tracks in Figure 6a show that at solar composition this evolutionary phase is completely spent in the red, even for masses as low as $0.55 M_{\odot}$. Conversely, at low metallicity (black lines), low-mass core helium burners are blue, opening the possibility of producing extended HBs in old stellar populations. The tracks in Figure 1.6b show the effect of enhancing the helium abundance: at high metallicity the core helium burning phase is completely spent close to the Hayashi line for a solar helium abundance, but if the helium abundance is high, a blueward excursion occurs during the core helium burning phase which is very wide for low-mass stars. Therefore the production of blue HB stars in old stellar populations can be achieved either assuming heavy mass loss on the RGB, or a high helium content, or both. Actually, the existence of multiple stellar populations with different helium content in NGC 2808 has been first suggested on the basis of its HB stars distribution, and confirmed later from the multiple MSs. Mass loss and helium abundance have indeed an important impact on the HRD of stellar populations, as well as on their spectral energy distribution, since stars in the core helium burning phase provide an important contribution to the total light.

- How does metallicity affect this diagram?
- Elaborate on the life sequence of low-mass stars.
- Elaborate on the life sequence of high-mass stars.
- Which direction does radius increase?
- What's the functional form for how radius increases as a function of temperature and luminosity?
- Why can you use the tip of the red giant branch for distance determination?
- How can you use the H-R diagram to determine ages? Which of the two techniques is more accurate?

1.2 Question 2

Sketch a plot of radius versus mass for various “cold” objects made of normal matter, including planets, brown dwarfs and white dwarfs. Explain the mass-size relationship for rocky and gaseous objects. Why is there an upper mass limit?

1.2.1 Short answer

Answer.

1.2.2 Additional context

Additional context.

1.2.3 Follow-up Questions

- How do you calculate the Chandrasekhar mass limit?
- Why is Saturn smaller than Jupiter? Or, why do we see a range of radii in extrasolar planets (e.g., hot Jupiters)?

1.3 Question 3

Describe the physical conditions that lead to the formation of absorption lines in stars' spectra. What leads to emission lines?

1.3.1 Short answer

Answer.

1.3.2 Additional context

If an absorber X is in a level ℓ and there is radiation present with photons having an energy equal to $E_u - E_\ell$, where E_ℓ and E_u are the energies of levels ℓ (for “lower”) and u (for “upper”), the absorber can absorb a photon and undergo an upward transition:

$$\text{absorption : } X_\ell + h\nu \rightarrow X_u, \quad h\nu = E_u - E_\ell.$$

Suppose that we have number density n_ℓ of absorbers X in level ℓ . The rate per volume at which the absorbers absorb photons will obviously be proportional to both the density of photons of the appropriate energy and the number density n_ℓ , so we can write the rate of change of n_ℓ due to photo-absorption by level ℓ as

$$\left(\frac{dn_u}{dt} \right)_{\ell \rightarrow u} = - \left(\frac{dn_\ell}{dt} \right)_{\ell \rightarrow u} = n_\ell B_{\ell u} u_\nu, \quad \nu = \frac{E_u - E_\ell}{h},$$

where u_ν is the **radiation energy density per unit frequency**, and the proportionality constant $B_{\ell u}$ is the **Einstein B coefficient** for the transition $\ell \rightarrow u$.

An absorber X in an excited level u can decay to a lower level ℓ with emission of a photon. There are two ways this can happen:

$$\text{spontaneous emission : } X_u \rightarrow X_\ell + h\nu, \quad \nu = (E_u - E_\ell)/h,$$

$$\text{stimulated emission : } X_u + h\nu \rightarrow X_\ell + 2h\nu, \quad \nu = (E_u - E_\ell)/h.$$

Spontaneous emission is a random process, independent of the presence of a radiation field, with a probability per unit time $A_{u\ell}$ – the **Einstein A coefficient**.

Stimulated emission occurs if photons of the identical frequency, polarization, and direction of propagation are already present, and the rate of stimulated emission is proportional to the density of these photons. Thus the total rate of depopulation of level u due to emission of photons can be written

$$\left(\frac{dn_\ell}{dt} \right)_{u \rightarrow \ell} = - \left(\frac{dn_u}{dt} \right)_{u \rightarrow \ell} = n_u (A_{u\ell} + B_{u\ell} u_\nu), \quad \nu = \frac{E_u - E_\ell}{h},$$

where the coefficient $B_{u\ell}$ is the **Einstein B coefficient** for the downward transition $u \rightarrow \ell$. Thus we now have three coefficients characterizing radiative transitions between levels u and ℓ : $A_{u\ell}$, $B_{u\ell}$ and $B_{\ell u}$. We will now see that they are not independent of one another.

In TE, the radiation field becomes the “blackbody” radiation field, with intensity given by the **blackbody spectrum**

$$B_\nu(T) = \frac{2h\nu^2}{c^2} \frac{1}{\exp(h\nu/k_B T) - 1} [\text{erg s}^{-1} \text{cm}^{-2} \text{Hz}^{-1} \text{sr}^{-1}],$$

with specific energy density

$$(u_\nu)_{\text{LTE}} = \frac{4\pi}{c} B_\nu(T) = \frac{8\pi h\nu^3}{c^3} \frac{1}{e^{h\nu/k_B T} - 1} [\text{erg s}^{-2} \text{cm}^{-1} \text{Hz}^{-1} \text{sr}^{-1}].$$

If we place absorbers X into a blackbody radiation field, then the net rate of change of level u is

$$\begin{aligned} \frac{dn_u}{dt} &= \left(\frac{dn_u}{dt} \right)_{\ell \rightarrow u} + \left(\frac{dn_u}{dt} \right)_{u \rightarrow \ell} \\ &= n_\ell B_{\ell u} \frac{8\pi h\nu^3}{c^3} \frac{1}{\exp(h\nu/k_B T) - 1} - n_u \left(A_{u\ell} + B_{u\ell} \frac{8\pi h\nu^3}{c^3} \frac{1}{\exp(h\nu/k_B T) - 1} \right). \end{aligned}$$

If the absorbers are allowed to come to equilibrium with the radiation field, levels ℓ and u must be populated according to $n_u/n_\ell = (g_u/g_\ell)e^{(E_\ell E_u)/k_B T}$, with $dn_u/dt = 0$. From the equation above, it is easy to show that $B_{u\ell}$ and $B_{\ell u}$ must be related to $A_{u\ell}$ by

$$B_{u\ell} = \frac{c^3}{8\pi h\nu^3} A_{u\ell} [\text{s}^{-1}],$$

$$B_{\ell u} = \frac{g_u}{g_\ell} B_{u\ell} = \frac{g_u}{g_\ell} \frac{c^3}{8\pi h\nu^3} A_{u\ell} [\text{s}^{-1}].$$

Thus the strength of stimulated emission ($B_{u\ell}$) and absorption ($B_{\ell u}$) are both determined by $A_{u\ell}$ and the ratio g_u/g_ℓ .

Rather than discussing absorption and stimulated emission in terms of the radiation energy density u_ν , it is helpful to characterize the intensity of the radiation field by a dimensionless quantity, the photon occupation number n_γ :

$$n_\gamma \equiv \frac{c^2}{2h\nu^3} I_\nu \text{ [dimensionless]},$$

$$\bar{n}_\gamma \equiv \frac{c^2}{2h\nu^3} \bar{I}_\nu = \frac{c^3}{8\pi h\nu^3} u_\nu \text{ [dimensionless]},$$

where the bar denotes averaging over directions. With this definition of n_γ , we can rewrite equations for $(dn_u/dt)_{\ell \rightarrow u}$ and $(dn_\ell/dt)_{u \rightarrow \ell}$ as simply

$$\left(\frac{dn_\ell}{dt} \right)_{u \rightarrow \ell} = n_u A_{u\ell} (1 + \bar{n}_\gamma),$$

$$\left(\frac{dn_u}{dt} \right)_{\ell \rightarrow u} = n_\ell \frac{g_u}{g_\ell} A_{u\ell} \bar{n}_\gamma.$$

If the radiation field depends on frequency in the vicinity of the transition frequency $\nu_{u\ell}$, then n_γ needs to be averaged over the emission and absorption profiles in the above two equations.

From the first of the above two equations, we immediately see that the photon occupation number n_γ determines the relative importance of stimulated and spontaneous emission: stimulated emission is unimportant when $\bar{n}_\gamma \ll 1$, but should otherwise be included in analyses of level excitation.

Absorption cross section: Having determined the rate at which photons are absorbed by an absorber exposed to electromagnetic radiation, it is useful to recast this in terms of an absorption cross section. The photon density per unit frequency is just $u_\nu/h\nu$. Let $\sigma_{\ell u}(\nu)$ be the cross section for absorption of photons of frequency ν with resulting $\ell \rightarrow u$ transition. The absorption rate is then

$$\left(\frac{dn_u}{dt} \right)_{\ell \rightarrow u} = n_\ell \int \sigma_{\ell u}(\nu) c \frac{u_\nu}{h\nu} d\nu \approx n_\ell u_\nu \frac{c}{h\nu} \int \sigma_{\ell u}(\nu) d\nu [\text{s}^{-1}],$$

where we have assumed that u_ν (and $h\nu$) do not vary appreciably over the line profile of $\sigma_{\ell u}$. Thus

$$B_{\ell u} = \frac{c}{h\nu} \int \sigma_{\ell u}(\nu) d\nu [\text{s}^{-1}],$$

and, using our equation that relates $B_{\ell u}$ to $A_{u\ell}$, we obtain the integral over the absorption cross section:

$$\int \sigma_{\ell u}(\nu) d\nu = \frac{g_u}{g_\ell} \frac{c^2}{8\pi\nu_{\ell u}^2} A_{u\ell} [\text{Hz cm}^2].$$

Thus we may relate the monochromatic absorption cross section $\sigma_{\ell u}(\nu)$ to a normalized line profile ϕ_ν :

$$\sigma_{\ell u}(\nu) = \frac{g_u}{g_\ell} \frac{c^2}{8\pi\nu_{\ell u}^2} A_{u\ell} \phi_\nu [\text{cm}^2], \quad \int \phi_\nu d\nu = 1.$$

Intrinsic line profile: The intrinsic line profile is characterized by a normalized profile function ϕ_ν^{intr} :

$$\sigma_\nu^{\text{intr}} = \frac{\pi e^2}{m_e c^2} f_{\ell u} \phi_\nu^{\text{intr}} [\text{cm}^2], \quad \int \phi_\nu^{\text{intr}} d\nu = 1.$$

The intrinsic line profile of an absorption line is normally described by the **Lorentz line profile** function:

$$\phi_\nu^{\text{intr}} = \frac{4\gamma_{u\ell}}{16\pi^2(\nu - \nu_{u\ell})^2 + \gamma_{u\ell}^2} [\text{erg s}^{-1} \text{cm}^{-2} \text{sr}^{-1}],$$

where $\nu_{u\ell} \equiv (E_u - E_\ell)/h$. The Lorentz profile provides an accurate (but not exact)² approximation to the actual line profile. The Lorentz line profile has a **full width at half maximum** (FWHM) of

$$(\Delta\nu)_{\text{FWHM}}^{\text{intr}} = \frac{\gamma_{u\ell}}{2\pi} [\text{Hz}].$$

²The line profile is more accurately given by the **Kramers-Heisenberg formula**; Lee (2003) discusses application of this formula to the Lyman α line.

The intrinsic width of the absorption line reflects the uncertainty in the energies of levels u and ℓ due to the finite lifetimes of these levels³ against transitions to all other levels, including both radiative and collisional transitions. If the primary process for depopulating levels u and ℓ is spontaneous decay (as is often the case in the ISM), then

$$\gamma_{u\ell} \equiv \gamma_{\ell u} = \sum_{E_j < E_u} A_{uj} + \sum_{E_j < E_\ell} A_{\ell j}.$$

In the case of a **resonance line**, where ℓ is the ground state, the second sum vanishes.

Doppler broadening; The voigt line profile: Atoms and ions are generally in motion, and the velocity distribution is often approximated by a Gaussian, this being of course the correct form if the velocities are entirely due to thermal motions:

$$p_v = \frac{1}{\sqrt{2\pi}} \frac{1}{\sigma_v} e^{-(v-v_0)^2/2\sigma_v^2} = \frac{1}{\sqrt{\pi}} \frac{1}{b} e^{-(v-v_0)^2/b^2},$$

where $p_v dv$ is the probability of the velocity along the line of sight being in the interval $[v, v + dv]$, σ_v is the one-dimensional velocity dispersion, and b is the the **broadening parameter**, $b \equiv \sqrt{2}\sigma_v$.

The width of the velocity distribution is also sometimes specified in terms of the FWHM; for a Gaussian distribution of velocities, this is just

$$(\Delta v)_{\text{FWHM}} = \sqrt{8 \ln 2} \sigma_v = 2\sqrt{\ln 2} b [\text{m s}^{-1}].$$

If the velocity dispersion is entirely due to thermal motion with kinetic temperature $T = 10^4 T_4$ K, then

$$\begin{aligned} \sigma_v &= \left(\frac{k_B T}{M} \right)^{1/2} = 9.12 \left(\frac{T_4}{M/\text{amu}} \right)^{1/2} [\text{km s}^{-1}] \\ b &= \left(\frac{2k_B T}{M} \right)^{1/2} = 12.90 \left(\frac{T_4}{M/\text{amu}} \right)^{1/2} [\text{km s}^{-1}] \\ (\Delta v)_{\text{FWHM}}^{\text{therm}} &= \left[\frac{(8 \ln 2) k_B T}{M} \right]^{1/2} = 21.47 \left(\frac{T_4}{M/\text{amu}} \right)^{1/2} [\text{km s}^{-1}]. \end{aligned}$$

The intrinsic absorption line profile ϕ_ν^{intr} must be convolved with the velocity distribution of the absorbers to obtain the line profile

$$\phi_\nu = \int p_v(v) \frac{4\gamma_{u\ell}}{16\pi^2[\nu - (1-v/c)\nu_{u\ell}]^2 + \gamma_{u\ell}^2} dv [\text{erg s}^{-1} \text{cm}^{-2} \text{sr}^{-1}],$$

where $p_v dv$ is the probability of the absorber having radial velocity in the interval $[v, v + dv]$. If the absorbers have a **Maxwellian** (i.e., Gaussian) one-dimensional velocity distribution p_v , then the absorption line will have a so-called **Voigt line profile**:

$$\phi_\nu^{\text{Voigt}} \equiv \frac{1}{\sqrt{2\pi}} \int \frac{e^{-v^2/2\sigma_v^2}}{\sigma_v} p_v(v) \frac{4\gamma_{u\ell}}{16\pi^2[\nu - (1-v/c)\nu_{u\ell}]^2 + \gamma_{u\ell}^2} dv [\text{erg s}^{-1} \text{cm}^{-2} \text{sr}^{-1}].$$

Unfortunately, the Voigt line profile cannot be obtained analytically except for limiting cases.⁵ However, if, as is generally the case, the one-dimensional velocity dispersion $\sigma_v \gg (\Delta v)_{\text{FWHM}}^{\text{intr}}$, the central core of the line profile is well-approximated by treating the intrinsic line profile as a δ -function, so that the central core of the line has a Maxwellian profile:

$$\phi_\nu \approx \frac{1}{\pi} \frac{c}{\nu_{u\ell}} \frac{1}{b} e^{-v^2/b^2} [\text{erg s}^{-1} \text{cm}^{-2} \text{sr}^{-1}], \quad b \equiv \sqrt{2}\sigma_v.$$

Selection rules for radiative transitions: Some energy levels are connected by strong radiative transitions; in other cases, radiative transitions between the levels may be extremely slow. The strong transitions always satisfy what are referred to as the **selection rules for electric dipole transitions**. Here, we summarize the selection rules for the strong electric dipole transitions, and we also give the selection rules for **inter-system** and **forbidden transitions** that do not satisfy the electric dipole selection rules but nevertheless are strong enough to be astrophysically important. We will use the ion NII as an example; the first nine energy levels of NII are shown in Figure 7.

Allowed: Electric dipole transitions: The strongest transitions are electric dipole transitions. These are transitions satisfying the following selection rules:

³The **Heisenberg uncertainty principle** $\Delta E \Delta t \geq \hbar$ implies that an energy level u has a width $\Delta E_u \approx \hbar/\tau_u$, where τ_u is the level lifetime.

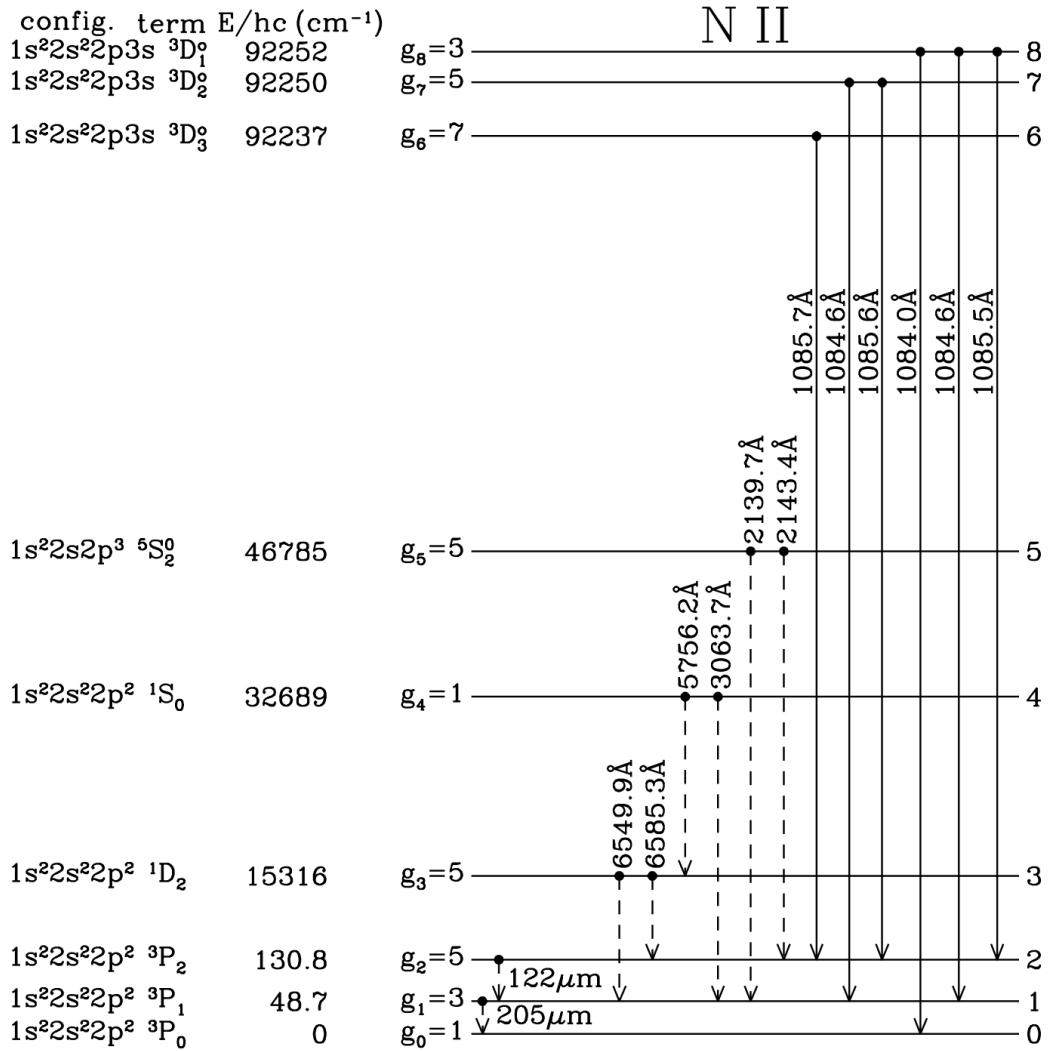


Figure 7: First nine energy levels of NII. Forbidden transitions are indicated by broken lines, and allowed transitions by solid lines; forbidden decays are not shown from levels that have permitted decay channels. Fine-structure splitting is not to scale. Hyperfine splitting is not shown. Figure taken from Draine (2015).

1. Parity must change.
2. $\Delta L = 0, \pm 1$.
3. $\Delta J = 0, \pm 1$, but $\Delta J = 0 \rightarrow 0$ is forbidden.
4. Only one single-electron wave function $n\ell$ changes, with $\Delta\ell = \pm 1$.
5. $\Delta S = 0$: Spin does not change.

An allowed transition is denoted *without* square brackets, for example,

$$\text{NII } 1084.0\text{\AA} \ ^3P_0 - \ ^3D_1^o.$$

This is a transition between the $\ell = 1s^2 2s^2 2p^2 3P_0$ and $u = 1s^2 2s^2 2p^3 3s 3D_1^o$ levels of NII, with a wavelength $\lambda_{ul} = 1084.0 \text{\AA}$. The transition has $A_{ul} = 2.18 \times 10^8 \text{ s}^{-1}$. This decay is very fast – the lifetime of the $^3D_1^o$ level against this decay is only $1/A_{ul} = 4.6 \text{ ns}$!

Spin-Forbidden or inter-system transitions: These are transitions that fulfill the electric dipole selection rules 1 to 4 but have $\Delta S \neq 0$. These transitions are considerably weaker than allowed transitions. Such transitions are sometimes referred to as **semi-forbidden**, or **inter-combination**, or **inter-system transitions**; the latter is the terminology that we will use. An inter-system transition is denoted with a single right bracket – for example,

$$\text{NII}] 2143.4\text{\AA} \ ^3P_2 - \ ^5S_2^o.$$

This is a transition between the $\ell = 1s^2 2s^2 2p^2 3P_2$ and $u = 1s^2 2s^2 2p^3 {}^5S_2^o$ levels of NII, with a wavelength $\lambda_{ul} = 2143.4 \text{ \AA}$ and $A_{ul} = 1.27 \times 10^2 \text{ s}^{-1}$.

Forbidden transitions: Forbidden transitions are those that fail to fulfill at least one of the selection rules 1 to 4. The transition probabilities vary widely, depending on the values of the electric quadrupole or magnetic dipole matrix elements between the upper and lower states. A forbidden transition is denoted with two square brackets – for example,

$$[\text{NII}] 6549.9 \text{\AA} \, {}^3P_1 - {}^1D_2^o.$$

This is a transition between the $\ell = 1s^2 2s^2 2p^2 3P_1$ and $u = 1s^2 2s^2 2p^2 {}^1D_2^o$ levels of NII, with a wavelength $\lambda_{ul} = 6549.9 \text{ \AA}$ and $A_{ul} = 9.20 \times 10^{-4} \text{ s}^{-1}$. This fails rule 1 (parity is unchanged) and it fails rule 4 (single electron wave functions are unchanged). This is an example of a **magnetic dipole transition**.

Another example of a forbidden transition is the **electric quadrupole transition**

$$[\text{NII}] 5756.2 \text{\AA} \, {}^1D_2 - {}^1S_0^o.$$

This is a transition between the $\ell = 1s^2 2s^2 2p^2 1D_2$ and $u = 1s^2 2s^2 2p^2 {}^1S_0^o$ levels of NII, with a wavelength $\lambda_{ul} = 5756.2 \text{ \AA}$ and $A_{ul} = 1.17 \text{ s}^{-1}$. This fails rules 1 (parity is unchanged) and 4 (single electron wave functions are unchanged) and it fails rules 2 and 3 ($\Delta L = -2$ and $\Delta J = -2$), yet its transition probability is three orders of magnitude larger than the magnetic dipole transition [NII] 6549.9\AA!

We see then that there is a hierarchy in the transition probabilities: very roughly speaking, inter-system lines are $\sim 10^6$ times weaker than permitted transitions, and forbidden lines are $\sim 10^2 - 10^6$ times weaker than inter-system transitions.

Despite being very “weak,” forbidden transitions are important in astrophysics for the simple reason that every atom and ion has excited states that can only decay via forbidden transitions. At high densities, such excited states would be depopulated by collisions, but at the very low densities of interstellar space, collisions are sufficiently infrequent that there is time for forbidden radiative transitions to take place.

1.3.3 Follow-up Questions

- Why aren’t emission and absorption lines delta functions?
- How does this relate to population levels and excitation temperatures?
- Are there emission lines in the Sun? Why is there emission from the Calcium doublet?
- Write down the heat transfer equation. What do solutions look like?

1.4 Question 4

Describe these important sources of stellar opacity: electron scattering, free-free, bound-free, and the H⁻ ion.

1.4.1 Short answer

Answer.

1.4.2 Additional context

Electron scattering: If an EM wave passes an electron, the electric field makes the electron oscillate. The oscillating electron represents a classical dipole that radiates in other directions, (i.e., the electron scatters part of the energy of the incoming wave). The weakening of the original radiation due to scattering is equivalent to that by absorption, and we can describe it by way of a cross section at frequency ν per unit mass (κ_ν). This can be calculated classically giving the result

$$\kappa_\nu = \frac{8\pi}{3} \frac{e_e^2}{\mu_e m_u} = 0.20(1+X) \text{ [cm}^2 \text{ g}^{-1}\text{]},$$

where r_e is the classical electron radius, X the mass fraction of hydrogen, and the constant is in $\text{cm}^2 \text{ g}^{-1}$. The term $\mu_e m_u$ arises because κ_ν is taken per unit mass; and μ_e is replaced by (4.30). Since κ_ν does not depend on the frequency, we immediately obtain the **Rosseland mean for electron scattering**:

$$\kappa_{\text{sc}} = 0.20(1+X) \text{ [cm}^2 \text{ g}^{-1}\text{]}.$$

The Thomson scattering just described neglects the exchange of momentum between electron and radiation. If this becomes important, then κ_ν will be reduced compared to the value given above, though this effect plays a role only at temperatures sufficiently high for the scattered photons to be very energetic. In fact, during the scattering process the electron must obtain such a large momentum that its velocity is comparable to c , say $v \gtrsim 0.1c$ for the equation above to become a bad approximation. The momentum of the photon is $h\nu/c$, which after scattering is partly transferred to the electron, $m_e v \sim h\nu/c$. Therefore relativistic corrections (**Compton scattering**) become important if the average energy of the photons is $h\nu \gtrsim 0.1 m_e c^2$. For $h\nu$ we take the frequency at which the Planck function has a maximum; then according to Wien's law this is at $h\nu = 4.965 k_B T$, and the full Compton scattering cross section has to be taken into account if $T > 0.1 m_e c^2/(4.965 \text{ K})$, or roughly $T > 10^8 \text{ K}$. In fact even at $T = 10^8 \text{ K}$ Compton scattering reduces the opacity by only 20% of that given by the equation above.

Free-free: If during its thermal motion a free electron passes an ion, the two charged particles form a system which can absorb and emit radiation. This mechanism is only effective as long as the electron and ion are sufficiently close. Now, the mean thermal velocity of the electrons is $v \sim \sqrt{T}$, and the time during which they form a system able to absorb or emit is proportional to $1/v \sim 1/\sqrt{T}$; therefore, if in a mass element the numbers of electrons and ions are fixed, the number of systems temporarily able to absorb is proportional to $1/\sqrt{T}$.

The absorption properties of such a system have been derived classically; the absorption coefficient per system is proportional to $Z^2 \nu^{-3}$, where Z is the charge number of the ion. We therefore expect the absorption coefficient κ_ν of a given mixture of (fully ionized) matter to be

$$\kappa_\nu \sim Z^2 \rho T^{-1/2} \nu^{-3} \text{ [cm}^2 \text{ g}^{-1}\text{]}.$$

Here the factor ρ appears because for a given mass element the probability that two particles are accidentally close together is proportional to the density.

For the determination of the Rosseland mean κ of this absorption coefficient we make use of a simple theorem: a factor ν^α contained in κ_ν gives a factor T^α in κ . With this and the above equation for κ_ν we find

$$\kappa_{\text{ff}} \sim \rho T^{-7/2} \text{ [cm}^2 \text{ g}^{-1}\text{]}.$$

All opacities of this form are called **Kramers opacities** and give only a classical approximation. One normally multiplies the Kramers formula by a correction factor g , the so-called **Gaunt factor**, in order to take care of the quantum-mechanical correction. In the equation for κ_{ff} , we have still omitted the factor Z^2 which appears in κ_ν . In general, one has a mixture of different ions, and therefore one has to add the contributions of the different chemical species. The (weighted) sum over the values of Z^2 is taken into the constant of proportionality in κ_{ff} , which then depends on the chemical composition. For a fully ionized mixture a good approximation is given by

$$\kappa_{ff} = 3.8 \times 10^{22}(1 + X)[(X + Y) + B]\rho T^{-7/2} [\text{cm}^2 \text{g}^{-1}],$$

with the numerical constant in cgs. The mass fractions of H and He are X and Y , respectively. Here the factor $(1 + X)$ arises, since ν_{ff} must be proportional to the electron density which is proportional to $(1 + X)\rho$. The term $(X + Y)$ in the brackets can be understood in the following way: there are X/m_u hydrogen ions and $Y/(4m_u)$ helium ions. The former have the charge number 1, the latter the charge number 2. But since $\kappa_\nu \sim Z^2$, when adding the contributions of H and He to the total absorption coefficient, we obtain the factor $X/m_u + 4Y/(4m_u) = (XY)m_u$. Correspondingly the term B gives the contribution of the heavier elements:

$$B = \sum_i \frac{X_i Z_i^2}{A_i} \text{ [dimensionless]},$$

where the summation extends over all elements higher than helium and A_i is the atomic mass number.

Bound-free: We first consider a (neutral) hydrogen atom in its ground state, with an ionization energy of χ_0 (i.e., a photon of energy $h\nu > X_0$ can ionize the atom). Energy conservation then demands that

$$h\nu = \chi_0 + \frac{1}{2}m_e v_e^2 \text{ [eV]},$$

where v_e is the velocity of the electron released (relative to the ion, which is assumed to be at rest before and after ionization).

If we define an absorption coefficient a_ν per ion ($a_\nu = \kappa_\nu \rho / n_{\text{ion}}$), we expect $a_\nu = 0$ for $\nu < \chi_0/h$ and $a_\nu > 0$ for $\nu \geq \chi_0/h$. Classical considerations similar to those which lead to the Kramers dependence of κ_ν for freefree transitions give a $a_\nu \sim \nu^{-3}$ for $\nu \geq \chi_0/h$. Quantum-mechanical corrections can again be taken into account by a Gaunt factor. But if we have neutral hydrogen atoms in different stages of excitation, the situation is different: an atom in the first excited stage has an absorption coefficient $a_\nu = 0$ for $h\nu < \chi_1$, where χ_1 is the energy necessary to ionize a hydrogen atom from the first excited state, while $a_\nu \sim \nu^{-3}$ for $h\nu \geq \chi_1$. The absorption coefficient κ_ν for a mixture of hydrogen atoms in different states of excitation is a superposition of the a_ν for different stages of excitation. The resulting κ_ν is a saw-tooth function. In order to obtain κ_ν for a certain value of the temperature T , one has to determine the relative numbers of atoms in the different stages of excitation by the Boltzmann formula; then their absorption coefficients a_ν , weighted with their relative abundances, are to be summed.

If there are ions of different chemical species with different degrees of ionization, one has to sum the functions a_ν for all species in all stages of excitation and all degrees of ionization before carrying out the Rosseland integration. An important source of opacity are bound-free transitions of neutral hydrogen atoms, in which case the opacity must be proportional to the number of neutral hydrogen atoms and κ can be written in the form

$$\kappa_{bf} = X(1 - x)\tilde{\kappa}(T) [\text{cm}^2 \text{g}^{-1}].$$

Here $\tilde{\kappa}(T)$ is obtained by Rosseland integration over (weighted) sums of functions a_ν for the different stages of excitation, while x is the degree of ionization.

H⁻ ion: Hydrogen atom has a bound state for a second electron in the field of the proton, though it has a very low ionization potential, $E_{H^-} = 0.75 \text{ eV}$. The number density of negative hydrogen ions will be proportional to the electron density, which, in all but the most metal-poor stars, will be set by ionization of the metals (which have much lower ionization potentials than hydrogen and helium). Thus, the H⁻ opacity will scale as $\kappa_{H^-} \propto \rho X Z$ at low temperatures; H⁻ is of course easily ionized at higher temperatures, and at very low temperatures even metals will not be ionized, so there will be no electrons to form H⁻ by combining with H.

1.5 Question 5

Describe the processes that can cause pulsations in a star's luminosity, and provide at least one example of a class of stellar pulsation.

1.5.1 Short answer

Classifications of stellar pulsations include:

Some classifications of stellar pulsations include:

- Cepheids:
- RR Lyrae variables:
- Mira variables:

For a star to begin and continue to pulsate, there must be some mechanism which converts radiant energy into energy of motion in a timely way, overcoming friction and building up the motion. Such a mechanism can exist in a star: it is the thermodynamic effect of an ionization zone in a star. In a star of moderate surface temperature, the layers below the surface have temperatures up to a few tens of thousands of degrees. The helium tends to be singly-ionized; it has lost one of its two electrons but not the second. If the star contracts, it heats slightly which causes the helium to lose its second electron. This requires energy which comes from the radiation flowing outward through the gas; it is absorbed by the opacity of the gas. The energy then becomes stored in the form of ionization energy. When the star subsequently expands and cools, the electrons recombine with the helium atoms, and release the stored-up ionization energy. This is the 'push' which maintains the pulsation in all of the pulsating stars in the Cepheid instability strip.

1.5.2 Additional context

Variable stars are those that change brightness. Their variability may be due to geometric processes such as rotation, or eclipse by a companion star, or physical processes such as vibration, flares, or cataclysmic explosions. In each case, variable stars provide unique information about the properties of stars, and the processes that go on within them.

Variable stars are stars which change in brightness. The change may be as small as a few parts in a million, or it may be a factor of a thousand or more. It may occur in a second or less, or it may take years, decades, or centuries. These are extremes, but astronomers have developed an array of techniques for discovering, measuring, and analyzing the full range of possible variable stars. Why? Because the variations provide important and often unique information about the nature and evolution of the stars. This information can be used to deduce even more fundamental knowledge about our universe in general. The variations may be due to the rotation of a spotted star, or to an eclipse of a star by a companion star, or even by an unseen planet. The variations may be due to the vibrations of a star; if they are complex enough (as they are in our Sun), they may provide an internal 'picture' of the star. The variations may be due to eruptions on a star (flares), an accretion disc (dwarf novae), major explosions on a star (novae), or to the total disruption of a star in a supernova. SNe are the most violent events in our Universe, yet we owe our existence to them, because they help to recycle the atoms, created in stars, into space where some of them became part of our Sun, our planet, and our biosphere. Also, the elements heavier than iron were mostly created in SNe explosions. SNe may be dramatic and extreme, but they represent only one of the many roles that variable stars play in modern astrophysics, and in our understanding of the Universe and the processes which govern it.

Classification of variable stars: The earliest classification scheme dates back nearly two centuries: Pigott divided variables according to the nature of their light curve into novae, long-period variables, and short-period variables. A century later, Pickering devised a more detailed scheme: (Ia) normal novae, primarily nearby ones in our own galaxy; (Ib) novae in nebulae: now known to be primarily SNe in distant galaxies; (IIa) long-period variables, cool, large-amplitude pulsating variables; (IIb) U Geminorum stars, dwarf novae; (IIc) R Coronae Borealis stars, stars which suddenly and unpredictably decline in brightness; (III) irregular variables, a motley collection; (IVa) short-period variables, such as Cepheids and later including the cluster-type or RR Lyrae stars; (IVb) Beta Lyrae type eclipsing variables; and (V) Algol type eclipsing variables.

Pickering's classification scheme contains some hints as to the nature and cause of the variability. Classification and explanation go hand in hand (in principle), and in the late nineteenth and early twentieth centuries, progress was made in understanding the physical nature and the physical processes in variable stars, and in stars in general.

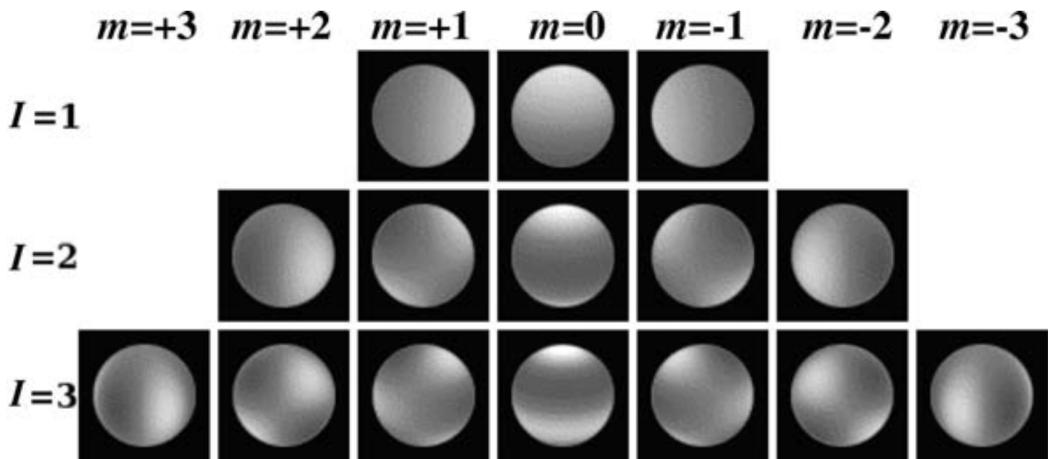


Figure 8: Illustration of non-radial pulsation modes. When the light-coloured regions are moving downward, the dark-coloured regions are moving upward. In radial pulsation, all parts of the star move in and out in unison. (Source: Whole Earth Telescope). Figure taken from Percy (2007).

Pulsating variable stars: Pulsation is the astronomer's word for *vibration or oscillation*. Every physical object has natural patterns or modes of vibration, each with a corresponding period – the time required for one vibration.

Pulsation modes: Stars are, to a first approximation, spherical. The simplest form of pulsation is radial pulsation – a simple, spherically symmetric in-and-out expansion and contraction. A star has an infinite number of modes of radial pulsation. The simplest is called the **fundamental mode**. In this mode, all parts of the star expand together and contract together, in unison. The next simplest mode is the **first overtone**. In this mode, there is a nodal sphere in the star, where the material remains at rest. When the part of the star outside this sphere is expanding, the part inside is contracting, and vice versa. In the **second overtone mode**, there are two nodal spheres, where the material remains at rest. The large-amplitude pulsating stars – **Cepheids**, **RR Lyrae variables**, and **Mira variables** – pulsate primarily in radial modes. Radial pulsation produces substantial changes in luminosity (and therefore brightness), temperature (and therefore colour), and radial velocity; these are observed, and provide direct evidence for the radial pulsation. Through techniques such as the **Baade-Wesselink method**, they can be used to determine the average radius of the star.

It is less easy to tell which radial mode a star is pulsating in. Most, but not all, large-amplitude variables pulsate in the fundamental mode. If the radius and mass of the star can be estimated, the observed period can be compared with the theoretical or expected period for each mode. If the star pulsates in two or more radial modes, then the period ratio can be used to deduce the modes.

In **non-radial pulsations**, the star changes shape, not volume (Figure 8). There is a triply-infinite set of modes, corresponding to the three different co-ordinate axes on the star. These are chosen to be: the distance from the centre, the angular distance ('latitude') above or below the star's equator, and the angular distance ('longitude') around the star's equator. Non-radial modes can be divided into (i) **p (pressure) modes**, in which the motion is primarily radial and the restoring force is pressure (as it is in radial modes), and (ii) **g (gravity) modes**, in which the motion is primarily horizontal, and the restoring force is buoyancy or gravity (as it is in water waves). A wide assortment of stars pulsate non-radially. Non-radial pulsation tends to produce smaller amplitudes than radial modes in the brightness and colour variation, but, if they can be observed, their relative amplitudes and phases (along with the periods themselves) can be used to identify the precise non-radial mode. Non-radial pulsation also produces characteristic absorption line profile variations. With modern high S/R spectrographs, these can and have been observed and studied over time. Also, there are often very close non-radial periods, whose differences are a clue to the mode identification. In non-rotating stars, these close periods are actually identical or degenerate, but in a rotating star, they become different; the difference is proportional to the amount of rotation. The situation is complicated by the fact that many of these non-radially pulsating stars rotate rapidly, and the theory of rapidly rotating pulsating stars is not well understood.

Modelling stellar pulsation: The theory of stellar pulsation begins with a model of the star which gives the physical properties of the star as a function of distance from the centre. The first models of stars were primitive (and so were the deductions from stellar pulsation theory). Now, with improved understanding of the physics of stars, and powerful computers to implement this knowledge, the models are much more detailed and accurate.

The simplest level of modelling is the **linear adiabatic theory** (LAT) of radial pulsation of a spherically symmetric, non-rotating, non-magnetic star. This was formulated by Arthur Eddington, early in the twentieth century. It assumes that the pulsations are infinitesimally small, and that there is no transfer of energy between parts of the star. It provides reasonable estimates of the periods of the radial modes and their dependence on the physical properties of the star. For instance, it shows that the period of any mode is approximately inversely proportional to the square root of the mean density of the star. Alternatively, the period times the square root of the density is approximately constant; we call it the **Q-value**, or **pulsation constant**. It is this relationship which leads to the period-luminosity relation; since both period and luminosity are related to the radius of the star, and since the temperatures of pulsating stars are about the same, period and luminosity will be related to each other. The LAT also shows that the relative amplitude of pulsation tends to be largest in the outer layers, where the density is lowest. Corresponding calculations can be done for non-radial pulsation. The LAT assumes that the pulsation takes the form of a standing wave in the star (i.e., a wave which is perfectly reflected from the centre and the surface).

The next level of complexity is the **linear non-adiabatic theory** (LNAT). This also assumes that the pulsations are infinitesimally small, but it allows for the possibility that any layer of the star may gain or lose energy. In particular, the amplitude of the infinitesimal pulsations can increase or decrease, and we can tell what modes may be unstable, and grow. We cannot tell what the eventual amplitudes may be (i.e., which mode(s) may grow to become observable). The LNAT gives periods which are slightly more realistic than the LAT, though they are about the same in most cases.

The next level of complexity is the **non-linear, non-adiabatic theory**, which amounts to a full, time-dependent, hydrodynamical model of the star. This includes the equation which relates the motion of a layer in the star to the forces acting on it. The calculation begins with the static, ‘equilibrium’ model of the star. Infinitesimal random motions are imposed on the model (such as from the round-off errors in the calculations), to see if they grow or decay. After several hundred cycles, the model (usually) reaches some constant, stable amplitude in one or more modes. The non-linear theory accurately predicts the amplitudes of Cepheids and RR Lyrae stars, which pulsate in one or two radial modes. It has not been able to explain stars like Delta Scuti stars, which can and do pulsate in many radial and non-radial modes. An ongoing problem in stellar pulsation is: what determines what mode(s) a star will pulsate in, and with what amplitude?

These models are non-rotating and non-magnetic. Non-linear analysis of rotating magnetic models is at the frontier of present research. But we know that all stars rotate (some of them very rapidly) and that many of them have significant magnetic fields. In reality, there is no such thing as a truly spherically symmetric star; for most of them, however, that is a reasonable approximation.

Non-linear effects: The pulsation waves in a star are not reflected perfectly from the surface, but move outward in an atmosphere of decreasing density. In many variables, such as Mira stars, this creates **shock waves** as the atmospheric layers pile up against each other. In Mira stars, this creates layers of higher density where gases condense into dust. The dust absorbs the star’s radiation and is pushed outward, carrying gas along with it. The result is mass loss which has a profound effect on the star and the space around it. In the largest, most luminous supergiants, the outward radiation pressure almost balances or perhaps even exceeds gravity; the star borders on instability; and non-linear effects may be significant.

The instability strip(s): Normally, stars are stable. The inward pull of gravity is balanced by the outward pressure of the hot gas in the star. If the star begins to contract, its internal pressure and temperature increase and reverse the contraction. If the star begins to expand, its internal pressure and temperature decrease and gravity restores the initial balance. Furthermore, if a star expands or contracts, the energy of motion is dissipated by friction. Eventually the star returns to rest.

For a star to begin and continue to pulsate, there must be some mechanism which converts radiant energy into energy of motion in a timely way, overcoming friction and building up the motion. Such a mechanism can exist in a star: it is the thermodynamic effect of an ionization zone in a star.

In a star of moderate surface temperature, the layers below the surface have temperatures up to a few tens of thousands of degrees. The helium tends to be singly-ionized; it has lost one of its two electrons but not the second. If the star contracts, it heats slightly which causes the helium to lose its second electron. This requires energy which comes from the radiation flowing outward through the gas; it is absorbed by the opacity of the gas. The energy then becomes stored in the form of ionization energy. When the star subsequently expands and cools, the electrons recombine with the helium atoms, and release the stored-up ionization energy. This is the ‘push’ which maintains the pulsation in all of the pulsating stars in the Cepheid instability strip (Figure 9). If there is sufficient mass in the ionization zone to store up significant radiant energy during the pulsation cycle, then the star will pulsate. This mechanism is referred to as **self-exciting**, in contrast to the pulsations of the Sun and other Sun-like stars, which are excited by the turbulence in their convection zones.

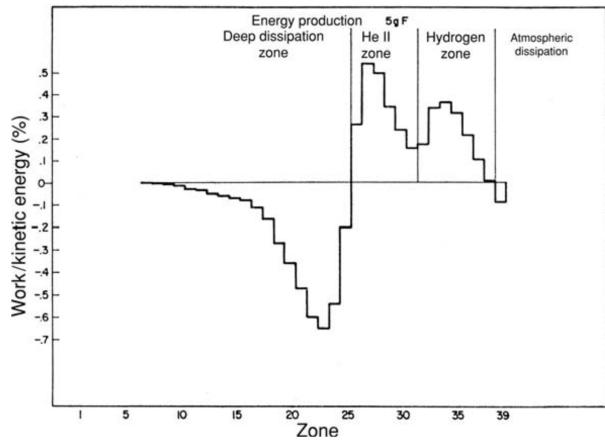


Figure 9: Diagram showing the zones in an unstable star which convert radiant energy into kinetic energy, and vice versa, in a model of a pulsating RR Lyrae star, expressed as the fractional energy production (positive) or dissipation (negative) per period. The centre of the star is at the left, the atmosphere at the right. The two energizing zones (the hydrogen zone and the ionized helium (He II) zone) are shown, along with the principal dissipation zone, deeper in the star. (From Christy, 1966.) Figure taken from Percy (2007).

But what about the other types of pulsating stars? The Beta Cephei stars were a real mystery, because they are much hotter than the Cepheid instability strip. Only in the 1980s was it realized that the ionization of iron, at temperatures near 150,000 K deep within the star had sufficient effect to maintain the pulsation. This realization came about as a result of physicists' recalculation of the opacity of iron at these temperatures. This solved the long-standing mystery of the Beta Cephei stars, and some other nagging problems in pulsation theory as well.

Figure 10 shows the location of various types of pulsating variable stars in the HR diagram. There is a misconception often included in astronomy textbooks that pulsation is something that happens only in evolved stars such as giants and supergiants. In fact, the Cepheid instability strip extends from the top of the HR diagram to the bottom, at approximately constant temperature. That is because the instability mechanism occurs at a particular temperature – the temperature at which there is a helium ionization zone in the outer layers of the star. So supergiant Cepheids pulsate, main-sequence Delta Scuti stars pulsate, and white dwarfs pulsate – all as a result of the same mechanism.

The Cepheid instability strip is not exactly vertical: its temperature is cooler at its high-luminosity end. That is because more luminous stars have outer regions of lower density; at lower density, ionization can occur at a lower temperature because there is lots of ‘room’ for the electrons that are released.

Stars can evolve into the instability strip in different ways (figure 6.4). Massive young stars can evolve quickly from left to right in the HR diagram; old low-mass stars can evolve slowly to the same position. So there may be Population I and II stars in the same region of the instability strip.

Stars can evolve into the instability strip in different ways (Figure 11). Massive young stars can evolve quickly from left to right in the HR diagram; old low-mass stars can evolve slowly to the same position. So there may be Population I and II stars in the same region of the instability strip.

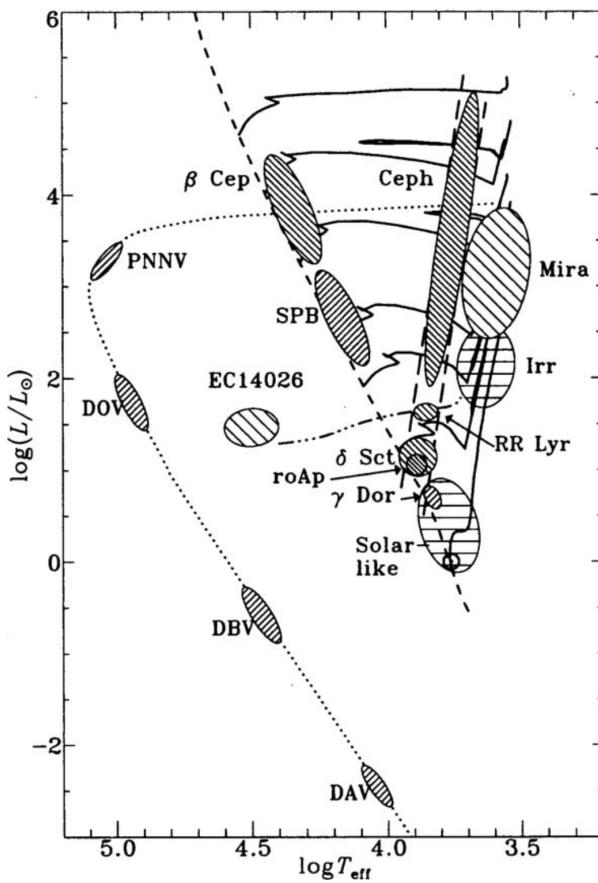


Figure 10: The location of various types of pulsating star on the HR diagram. The main instability regions are the Cepheid strip, including its intersection with the main sequence (dashed line), the region of the coolest stars (Miras and their relatives), and the region of the Beta Cephei and SPB stars. There are also instability regions along the white dwarf cooling track (dotted line) at the bottom of the diagram, including the nuclei of planetary nebulae (PNNV) and the DOV, DBV, and DAV pulsating white dwarfs. (From J. Christensen-Dalsgaard, private communication.) Figure taken from Percy (2007).

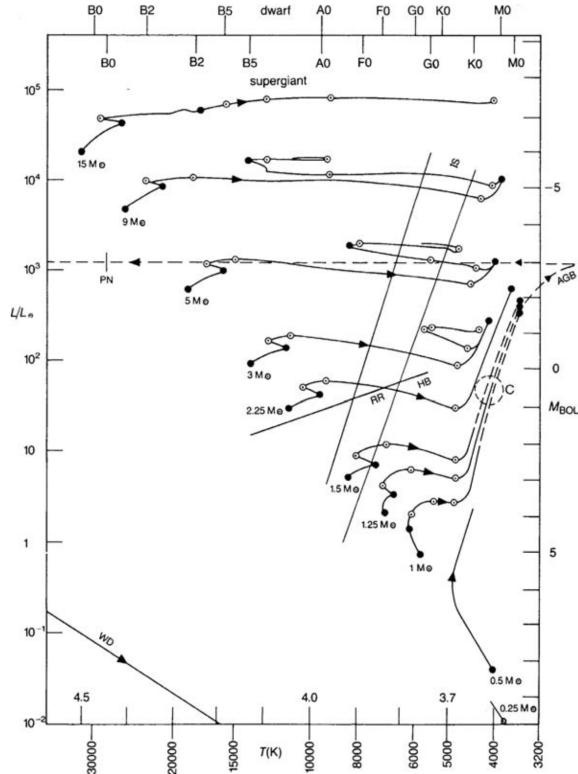


Figure 11: Evolution tracks on the HR diagram, showing the changes which take place in a star as it evolves. The tracks are marked by the mass of the star in solar units. The Cepheid pulsation instability strip is marked IS, and the horizontal branch where RR Lyrae (RR) variables are found is marked HB. The time scales for evolution depend on the mass: the more massive the star, the faster the evolution. (From Kaler, 1997.) Figure taken from Percy (2007).

1.5.3 Follow-up Questions

- What about the instability strip? RR Lyrae?
- What is the period-luminosity relation?
- What is the form of the period-luminosity relation?

- How would you derive the time scale of pressure waves in a star?
- How would you order-of-magnitude estimate the period for a pulsation?

1.6 Question 6

Briefly describe the sources of thermal energy for stars and planets.

1.6.1 Short answer

The sources of thermal energy of stars include:

- gravitational energy:
- rotational energy:
- nuclear energy:

The sources of thermal energy of planets include:

- radioactive decay:
- differentiation:
- solar radiation:
- accretion/impact:
- tidal heating:

1.6.2 Additional context

Stars:

One of the great mysteries of the late nineteenth and early twentieth centuries was the source of the energy required to sustain the luminosity of the sun. By then, the defining Solar parameters of mass, radius, and luminosity were known with sufficient precision to attempt to relate them. For instance, it was clear that if the Sun derived its energy from chemical processes typically yielding less than $10^{12} \text{ erg g}^{-1}$, it could shine no longer than about 10,000 years at its current luminosity. It is said that Lord Kelvin, in noting that the liberation of gravitational energy could only keep the sun shining for about 10 million years, found it necessary to reject Charles Darwin's theory of evolution because there would have been insufficient time for natural selection to provide the observed diversity of species.

Gravitational energy: It is generally conceded that the Sun has shone at roughly its present luminosity for at least the past 2 billion years and has been in existence for nearly 5 billion years. With this in mind, let us begin our study of the sources of stellar energy with an inventory of the stores of energy available to the sun. Perhaps the most obvious source of energy is that suggested by Lord Kelvin, namely gravitation:

$$E_p \leq -\frac{3}{5} \frac{GM^2}{R} [\text{J}].$$

The right-hand side of the inequality is the gravitational potential energy for a uniform density sphere, which provides a sensible upper limit for the energy. Remember that the gravitational energy is considered negative by convention; a rather larger magnitude of energy may be available for a star that is more centrally concentrated than a uniform-density sphere. We may acquire a better estimate of the gravitational potential energy by using the results for a polytrope. Chandrasekhar obtains the following result for the gravitational potential energy of a polytrope:

$$E_p = -\frac{3}{5-n} \frac{GM^2}{R} [\text{J}].$$

For a star in convective equilibrium (that is, $n = 3/2$) the factor multiplying GM^2/R becomes $6/7$ or nearly unity. Note that for a polytrope of index 5, $U_g \rightarrow -\infty$ implying an infinite central concentration of material. This is also one of the polytropes for which there exists an analytic solution. Thus, one has the picture of a mass point surrounded by a massless envelope of infinite extent. This equation also tells us that as the polytropic index increases, so does the central concentration.

It is not at all obvious that the total gravitational energy would be available to permit the star to shine. Some energy must be provided in the form of heat, to provide the pressure which supports the star. We may use the Virial theorem [equation (1.2.35)] to estimate how much of the gravitational energy can be utilized by the luminosity. Consider a star with no mass motions, so that the macroscopic kinetic energy T in equation (1.2.35) is zero. Let us also assume that the equilibrium state is good enough that we can replace the time averages by the instantaneous values. Then the **Virial theorem becomes**

$$2E_k + E_p = 0 \text{ [J].}$$

Recall that E_k is the total internal kinetic energy of the gas which includes all motions of the particles making up the gas. Now we know from thermodynamics that not all the internal kinetic energy is available to do work, and it is therefore not counted in the internal energy of the gas.

For simplicity, let us assume that γ is constant through out the star. Remembering that the total energy E is the sum of the internal energy and the gravitational energy, we can express the Virial theorem in the following ways:

$$\begin{aligned} E_k &= -\frac{E_p}{3(\gamma - 1)} \text{ [J]} \\ E_{\text{tot}} &= -(3\gamma - 4)E_{\text{th}} \text{ [J]} \\ E_{\text{tot}} &= \frac{3\gamma - 4}{3(\gamma - 1)} E_p \text{ [J].} \end{aligned}$$

It is clear that for $\gamma > 4/3$ (that is, $n < 3$), the total energy of the star will be negative. This simply says that the star is gravitationally bound and can be in equilibrium. So we can look for the physically reasonable polytropes to have indices less than or equal to 3. The case of $n = 3$ is an interesting one for it represents radiation dominated gas. In the limit of complete radiation dominance, the total energy of the configuration will be zero.

Rotational energy: Stars do rotate, and we should not forget to count the rotational energy in the inventory of energies. We may place a reasonable upper limit on the magnitude of the rotational energy that we can expect by noting that (1) the moment of inertia of the star will always be less than that of a sphere of uniform density and (2) there is a limit to the angular velocity ω_c at which the star can rotate. Thus, for a centrally condensed star

$$\begin{aligned} \omega^2 &= \frac{8GM}{27R^3} \text{ [km}^2 \text{s}^{-2} \text{kpc}^{-2}\text]} \\ I_z &< \frac{2}{5}MR^2 \text{ [kg km}^2\text]}, \end{aligned}$$

which implies that the rotational energy must be bounded by

$$E_{\text{rot}} = \frac{1}{2}I_z\omega^2 < \frac{8}{135}\frac{GM^2}{R} \text{ [J].}$$

One may quibble that we have used the angular velocity limit for a centrally condensed star and the moment of inertia for a uniform-density star, but the fact remains that it is extremely difficult for a star to have more than about 10 percent of the magnitude of its gravitational energy stored in the form of rotational energy.

Nuclear energy: Of course, the ultimate upper limit for stored energy is the energy associated with the rest mass itself. It is also the common way of estimating the energy available from nuclear sources. Indeed, that fraction of the rest mass which becomes energy when four hydrogen atoms are converted to one helium atom provides the energy to sustain the solar luminosity. Below in Table 2 is a short table giving the mass loss for a few common elements involved in nuclear fusion processes.

Form of Energy	Amount, erg	$\%M_\odot$	Lifetime for constant L_\odot , years
Chemical (10^{12} erg/g)	1.98×10^{45}	10^{-7}	14,000
Rotational ($8 \Omega/81$)	2.21×10^{47}	10^{-5}	1.4 million
Gravitational [$3GM^2/(5R)$]	2.24×10^{48}	10^{-4}	14 million
Nuclear ($0.0106M_\odot c^2$)	1.89×10^{52}	1	140 billion
Rest mass energy ($M_\odot c^2$)	1.78×10^{54}	100	1.4×10^{13}

Table 2: Possible sources of Solar energy. Table taken from Kippenhahn, Weigert & Weiss (2012).

Clearly most of the energy to be gained from nuclear fusion occurs by the conversion of hydrogen to helium and less than one-half of that energy can be obtained by all other fusion processes that carry helium to iron. Nevertheless, 0.7% of mc^2 is a formidable supply of energy. Table 2 is a summary of the energy that one could consider as being available to the Sun. All these entries are generous upper limits. For example, the sun rotates at less than 0.5% of its critical velocity, it was never composed of 100% hydrogen and will begin to change significantly when a fraction of the core hydrogen is consumed,

and not all the gravitational energy could ever be converted to energy for release. In any event, only nuclear processes hold the promise of providing the solar luminosity for the time required to bring about agreement with the age of the solar system as derived from rocks and meteorites. However, the time scales of Table 2 are interesting because they provide an estimate of how long the various energy sources could be expected to maintain some sort of equilibrium configuration.

Planets:

1.6.3 Follow-up Questions

- Why do different nuclear reaction pathways have different temperature sensitivities?
- If I assume a constant core temperature on the main sequence, how does stellar radius depend on mass?
- What are some other thermal sources, like say for neutron stars?

1.7 Question 7

Describe the process by which supernovae produce light. Why are Type Ia supernovae generally brighter than Type II events?

1.7.1 Short answer

Answer.

1.7.2 Additional context

Additional context.

1.7.3 Follow-up Questions

- When a star goes supernova, how much of the luminous energy generated at the rebound is available for heating the gas? As in, where does the heat come from?
- Are there cases where the rebound shock wave can't blow up the star? Why, and what happens then?

1.8 Question 8

Describe the condition for a star's envelope to become convective. Why are low mass stars convective in their outer envelopes while high mass stars are convective in their inner cores?

1.8.1 Short answer

The radiation pressure gradient is given by

$$\frac{dP_{\text{rad}}}{dr} = -\frac{\kappa\rho}{c} F_{\text{rad}} \text{ [P m]},$$

where F_{rad} is the outward radiative flux. The radiation pressure may also be expressed as

$$\frac{dP_{\text{rad}}}{dr} = \frac{4}{3} a T^3 \frac{dT}{dr} \text{ [P m].}$$

Equating the two, we have

$$\frac{dT}{dr} = -\frac{3}{4ac} \frac{\kappa\rho}{T^3} F_{\text{rad}} \text{ [K m}^{-1}\text{].}$$

If we use the expression for the radiative flux written in terms of the local radiative luminosity of the star at radius r ,

$$F_{\text{rad}} = \frac{L_r}{4\pi r^2} \text{ [erg s}^{-1} \text{ cm}^{-2}\text{]},$$

the temperature gradient for radiative transport becomes

$$\frac{dT}{dr} = -\frac{3}{4ac} \frac{\kappa\rho}{T^3} \frac{L_r}{4\pi r^2} \text{ [K m}^{-1}\text{].}$$

As either the flux or the opacity increases, the temperature gradient must become steeper (i.e., more negative) if radiation transport is to carry all of the required luminosity outward. The same situation holds as the density increases or the temperature increases.

We now consider a situation where a hot convective bubble of gas rises and expands **adiabatically**, meaning that the bubble does not exchange heat with its surroundings. After it has travelled some distance, it finally **thermalizes**, giving up any excess heat as it loses its identity and dissolves into the surrounding gas. Differentiating the **ideal gas law**

$$P = \frac{\rho k_B T}{\mu m_H} \text{ [P]}$$

yields an expression involving the bubble's **temperature gradient**

$$\frac{dP}{dr} = -\frac{P}{\mu} \frac{d\mu}{dr} + \frac{P}{\rho} \frac{d\rho}{dr} + \frac{P}{T} \frac{dT}{dr}.$$

Using the adiabatic relationship between pressure and density

$$PV^\gamma = K \text{ [P m}^3\text{]}$$

and recalling that $V \equiv 1/\rho$ is the **specific volume**, we have that

$$P = K\rho^\gamma \text{ [P].}$$

Differentiating and re-writing, we obtain

$$\frac{dP}{dr} = \gamma \frac{P}{\rho} \frac{d\rho}{dr} \text{ [P m}^{-1}\text{].}$$

If we assume for simplicity that the mean molecular weight μ is constant, we can combine equations for dP/dr to give the **adiabatic temperature gradient**

$$\left(\frac{dT}{dr} \right)_{\text{ad}} = \left(1 - \frac{1}{\gamma} \right) \frac{T}{P} \frac{dP}{dr} \text{ [K m}^{-1}\text{].}$$

Using the equation of **hydrostatic equilibrium**

$$\frac{dP}{dr} = -\frac{GM_r\rho}{r^2} = -\rho g \text{ [P m}^{-1}\text{]}, \quad g \equiv \frac{GM_r}{r^2} \text{ [m s}^{-2}\text{]}$$

and the ideal gas law, we finally obtain

$$\left(\frac{dT}{dr}\right)_{\text{ad}} = \left(1 - \frac{1}{\gamma}\right) \frac{\mu m_H}{k} \frac{GM_r}{r^2} [\text{K m}^{-1}].$$

If the star's actual temperature gradient is *steeper* than the adiabatic temperature gradient,

$$\left|\frac{dT}{dr}\right|_{\text{act}} > \left|\frac{dT}{dr}\right|_{\text{ad}} [\text{K m}^{-1}],$$

the temperature gradient is said to be **super-adiabatic** (recall that $dT/dr < 0$). In the deep interior of a star, if the actual temperature gradient is just *slightly* larger than the adiabatic temperature gradient, this may be sufficient to carry nearly all of the luminosity by convection. Consequently, it is often the case that either radiation or convection dominates the energy transport in the deep interior of stars, while the other energy transport mechanism contributes very little to the total energy outflow. The particular mechanism in operation is determined by the temperature gradient. However, near the surface of the star, the situation is much more complicated: both radiation and convection can carry significant amounts of energy simultaneously.

In general, convection will occur when

1. the stellar opacity is large, implying that an unachievable steep temperature gradient would be necessary for radiative transport;
2. a region exists where ionization is occurring, causing a large specific heat and a low adiabatic temperature gradient; and
3. the temperature dependence of the nuclear energy generation rate is large, causing a steep radiative flux gradient and a large temperature gradient.

In the atmosphere of many stars, the first two conditions can occur simultaneously, whereas the third condition would occur only deep in stellar interiors. In particular, the third condition can occur when the highly temperature-dependent CNO cycle or triple alpha processes are occurring.

1.8.2 Additional context

Three different energy transport mechanisms operate in stellar interiors. **Radiation** allows the energy produced by nuclear reactions and gravitation to be carried to the surface via photons, the photons being absorbed and re-emitted in nearly random directions as they encounter matter. This suggests that the opacity of the material must play an important role, as one would expect. **Convection** can be a very efficient transport mechanism in many regions of a star, with hot, buoyant mass elements carrying excess energy outward while cool elements fall inward. Finally, **conduction** transports heat via collisions between particles. Although conduction can play an important role in some stellar environments, it is generally insignificant in most stars throughout the majority of their lifetimes.

Radiative transport of energy: basic estimates Rough estimates show important features of the radiative transfer in stellar interiors and justify an enormous simplification of the formalism. Let us first estimate the mean free path ℓ_{mfp} of a photon at an “average” point inside a star like the Sun:

$$\ell_{\text{mfp}} = \frac{1}{\kappa\rho} [\text{m}].$$

where κ is a mean absorption coefficient (i.e., a radiative cross section per unit mass averaged over frequency). Typical values for stellar material are of order $\kappa \approx 1 \text{ cm}^2 \text{ g}^{-1}$; for the ionized hydrogen in stellar interiors, a lower limit is certainly the value for electron scattering, $\kappa \approx 0.4 \text{ cm}^2 \text{ g}^{-1}$. Using this and the mean density of matter in the Sun, $\bar{\rho}_\odot = 1.4 \text{ g cm}^{-3}$, we obtain a mean free path of only

$$\ell_{\text{mfp}} = \frac{1}{\kappa\rho} = \frac{1}{1 \text{ cm}^2 \text{ g}^{-1} \cdot 0.4 \text{ g cm}^{-3}} \approx 2 [\text{cm}],$$

i.e., stellar matter is very opaque.

The typical temperature gradient in the star can be roughly estimated by averaging between centre ($T_c \approx 10^7 \text{ K}$) and surface ($T_0 \approx 10^4 \text{ K}$):

$$\frac{\Delta T}{\Delta r} \approx \frac{T_c - T_0}{R_\odot} \approx 1.4 \times 10^{-4} [\text{K cm}^{-1}].$$

The radiation field at a given point is emitted from a small, nearly isothermal surrounding, the differences of temperature being only of order $\Delta T = \ell_{\text{mfp}}(dT/dr) \approx 3 \times 10^{-4} \text{ K}$. Since the energy density of radiation is $u \sim T^4$, the relative anisotropy of the radiation at a point with $T = 10^7 \text{ K}$ is $\Delta T/T \sim 10^{-10}$. The situation in stellar interiors must obviously be very close to TE, and the radiation very close to that of

a blackbody. Nevertheless, the small remaining anisotropy can easily be the carrier of the stars' huge luminosity: this fraction of 10^{-10} of the flux emitted from 1 cm^2 of a blackbody of $T = 10^7\text{ K}$ is still 10^3 times larger than the flux at the solar surface ($6 \times 10^{10}\text{ erg cm}^{-2}\text{ s}^{-1}$). Radiative transport of energy occurs via the non-vanishing net flux (i.e., via the surplus of the outwards-going radiation emitted from somewhat hotter material below over the inwards-going radiation emitted from less-hot material above).

Diffusion of radiative energy: The above estimates have shown that for radiative transport in stars, the mean free path ℓ_{mfp} of the “transporting particles” (i.e., photons) is very small compared to the characteristic length R (stellar radius) over which the transport extends: $\ell_{\text{mfp},\odot}/R_\odot \approx 3 \times 10^{-11}$. In this case, the transport can be treated as a diffusion process, which yields an enormous simplification of the formalism. We derive the corresponding equation by analogy to those for particle diffusion.

The diffusive flux j of particles (per unit area and time) between places of different particle density n is given by

$$\vec{j} = -D\nabla n \quad [??],$$

where D is the coefficient of diffusion,

$$D = \frac{1}{3}v\ell_{\text{mfp}} \quad [\text{s}^{-1}],$$

determined by the average values of mean velocity v and mean free path ℓ_{mfp} of the particles.

In order to obtain the corresponding diffusive flux of radiative energy \vec{F} ; we replace n by the energy density of radiation U ;

$$u = aT^4 = \frac{4\sigma}{c}T^4 \quad [\text{erg cm}^{-3}].$$

Here, $a = 7.57 \times 10^{-15}\text{ erg cm}^3\text{ K}^{-4}$ is the **radiation density constant**. Owing to the spherical symmetry of the problem, \vec{F} has only a radial component $F_r = |\vec{F}| = F$ and ∇U reduces to the derivative in the radial direction

$$\frac{\partial u}{\partial r} = 4aT^3 \frac{\partial T}{\partial r} \quad [\text{erg cm}^{-4}].$$

Using this result along with the equation for \vec{j} , this immediately gives us

$$F = -\frac{4ac}{3} \frac{T^3}{\kappa\rho} \frac{\partial T}{\partial r} \quad [\text{erg s}^{-1}\text{ cm}^{-2}].$$

Note that this can be interpreted formally as an **equation for heat conduction** by writing

$$\vec{F} = -k_{\text{rad}}\nabla T \quad [\text{erg s}^{-1}\text{ cm}^{-2}],$$

where

$$k_{\text{rad}} = \frac{4ac}{3} \frac{T^3}{\kappa\rho} \quad [\text{erg cm}^{-1}\text{ K}^{-1}\text{ s}^{-1}]$$

represents the **coefficient of conduction** for this radiative transport.

We solve F for the gradient of the temperature and replace it by the usual local luminosity $L = 4\pi r^2 F$; then

$$\frac{\partial T}{\partial r} = -\frac{3}{16\pi ac} \frac{\kappa\rho L}{r^2 T^3} \quad [\text{K cm}^{-1}]$$

Of course, this neat and simple equation becomes invalid when one approaches the surface of the star. Because of the decreasing density, the mean free path of the photons will there become comparable with (and finally larger than) the remaining distance to the surface; hence the whole diffusion approximation breaks down, and one has to solve the far more complicated full set of transport equations for radiation in the stellar atmosphere (these equations indeed yield our simple diffusion approximation as the proper limiting case for large optical depths).

The Rosseland mean for κ_ν : The above equations are independent of the frequency ν ; F and L are quantities integrated over all frequencies, so that the quantity must represent a “proper mean” over ν . We shall now prescribe a method for this averaging.

In general the absorption coefficient depends on the frequency ν . Let us denote this by adding a subscript ν to all quantities that thus become frequency dependent: κ_ν , ℓ_ν , D_ν , u_ν etc.

For the diffusive energy flux \vec{F}_ν of radiation in the interval $[\nu, \nu + d\nu]$, we write now

$$\vec{F}_\nu = -D_\nu \nabla u_\nu \text{ [erg s}^{-1} \text{ cm}^{-2}\text]},$$

$$D_\nu = \frac{1}{3} c \ell_\nu = \frac{c}{3 \kappa_\nu \rho} \text{ [m}^2 \text{ s}^{-1}\text]},$$

while the energy density in the same interval is given by

$$u_\nu = \frac{4\pi}{c} B(\nu, T) = \frac{8\pi h}{c^3} \frac{\nu^3}{e^{h\nu/k_B T} - 1} \text{ [erg cm}^{-3}\text]}.$$

$B(\nu, T)$ denotes here the **Planck function** for the intensity of blackbody radiation (differing from the usual formula for the energy density simply by the factor $4\pi/c$). From this equation for u_ν , we have

$$\nabla u_\nu = \frac{4\pi}{c} \frac{\partial B}{\partial T} \nabla T,$$

which together with D_ν is inserted into \vec{F}_ν , the latter then being integrated over all frequencies to obtain the total flux F :

$$\vec{F} = - \left[\frac{4\pi}{3\rho} \int_0^\infty \frac{1}{\kappa_\nu} \frac{\partial B}{\partial T} d\nu \right] \nabla T \text{ [m}^2 \text{ s}^{-1}\text]}.$$

We have thus regained $\vec{F} = -k_{\text{rad}} \nabla T$ with

$$k_{\text{rad}} = \frac{4\pi}{3\rho} \int_0^\infty \frac{1}{\kappa_\nu} \frac{\partial B}{\partial T} d\nu \text{ [erg cm}^{-1} \text{ K}^{-1} \text{ s}^{-1}\text]}.$$

Equating this expression for k_{rad} with that in the averaged form, we have immediately the proper formula for averaging the absorption coefficient:

$$\frac{1}{\kappa} = \frac{\pi}{acT^3} \int_0^\infty \frac{\partial B}{\partial T} d\nu \text{ [cm}^2 \text{ g}^{-1}\text]}.$$

This is the so-called **Rosseland mean**. Since

$$\int_0^\infty \frac{\partial B}{\partial T} d\nu = \frac{acT^3}{\pi},$$

the Rosseland mean is formally the harmonic mean of with the weighting function $\partial B/\partial T$, and it can simply be calculated, once the function κ_ν is known from atomic physics.

In order to see the physical interpretation of the Rosseland mean, we rewrite $\vec{F}_\nu = -D_\nu \nabla u_\nu$ as

$$\vec{F}_\nu = - \left(\frac{1}{\kappa_\nu} \frac{\partial B(\nu, T)}{\partial T} \right) \frac{4\pi}{3\rho} \nabla T \text{ [m}^2 \text{ s}^{-1}\text]}.$$

This shows that, for a given point in the star (ρ and ∇T given), the integrand in $1/\kappa$ is at all frequencies proportional to the net flux \vec{F}_ν of energy. The Rosseland mean therefore favours the frequency ranges of maximum energy flux. One could say that an average *transparency* is evaluated rather than an *opacity* – which is plausible, since it is to be used in an equation describing the transfer of energy rather than its blocking.

One can also easily evaluate the frequency where the weighting function $\partial B/\partial T$ has its maximum. One finds that, for given a temperature, $\partial B/\partial T \sim x^4 e^x (e^x - 1)^{-2}$ with $x = h\nu/k_B T$. Differentiation with respect to x shows that the maximum of $\partial B/\partial T$ is close to $x = 4$.

The way we have defined the Rosseland mean κ , which is a kind of weighted harmonic mean value, has the uncomfortable consequence that the opacity κ of a mixture of two gases having the opacities κ_1, κ_2 is not the sum of the opacities: $\kappa \neq \kappa_1 \kappa_2$. Therefore, in order to find κ for a mixture containing the weight fractions X of hydrogen and Y of helium, the mean opacities of the two single gases are of no use. Rather one has to add the frequency-dependent opacities $\kappa_\nu = X_{\kappa_\nu, \text{H}} + Y_{\kappa_\nu, \text{He}}$ before calculating the Rosseland mean. For any new abundance ratio X/Y the averaging over the frequency has to be carried out separately.

In the above we have characterized the energy flux due to the diffusion of photons by F_ν . Since in the following we shall encounter other mechanisms for energy transport, from now on we shall specify this radiative flux by the vector \vec{F}_{rad} . Correspondingly we shall use κ_{rad} instead of κ , etc.

Conductive transport of energy: In heat conduction, energy transfer occurs via collisions during the random thermal motion of the particles (electrons and nuclei in completely ionized matter, otherwise

atoms or molecules). A basic estimate shows that in “ordinary” stellar matter (i.e., in a non-degenerate gas), conduction has no chance of taking over an appreciable part of the total energy transport. Although the collisional cross sections of these charged particles are rather small at the high temperatures in stellar interiors ($10^{-18} - 10^{-20} \text{ cm}^2$ per particle), the large density ($\rho = 1.4 \text{ g cm}^{-3}$ in the Sun) results in mean free paths several orders of magnitude less than those for photons; and the velocity of the particles is only a few per cent of c . Therefore the coefficient of diffusion is much smaller than that for photons. The situation becomes quite different, however, for the cores of evolved stars where the electron gas is highly degenerate. The density can be as large as 10^6 g cm^{-3} . But degeneracy makes the electrons much faster, since they are pushed up close to the Fermi energy; and degeneracy increases the mean free path considerably, since the quantum cells of phase space are filled up such that collisions in which the momentum is changed become rather improbable. Then the coefficient of diffusion (which is proportional to the product of mean free path and particle velocity) is large, and heat conduction can become so efficient that it short-circuits the radiative transfer.

The energy flux \vec{F}_{cd} due to heat conduction may be written as

$$\vec{F}_{\text{cd}} = -k_{\text{cd}} \nabla T [\text{m}^2 \text{s}^{-1}].$$

The sum of the conductive flux \vec{F}_{cd} and the radiative flux \vec{F}_{rad} is

$$\vec{F} = \vec{F}_{\text{rad}} + \vec{F}_{\text{cd}} = -(k_{\text{rad}} + k_{\text{cd}}) \nabla T [\text{m}^2 \text{s}^{-1}],$$

On the other hand, we can just as well write the conductive coefficient k_{cd} formally in analogy to k_{rad} as

$$k_{\text{cd}} = \frac{4ac}{3} \frac{T^3}{\kappa_{\text{cd}} \rho} [\text{cm}^2 \text{g}^{-1}],$$

hence defining the **conductive opacity** κ_{cd} . Then the flux becomes

$$\vec{F} = -\frac{4ac}{3} \frac{T^3}{\rho} \left(\frac{1}{\kappa_{\text{rad}}} + \frac{1}{\kappa_{\text{cd}}} \right) \nabla T,$$

which shows that we arrive formally at the same type of equation as in the pure radiative case if we replace $1/\kappa$ by $1/\kappa_{\text{rad}} + 1/\kappa_{\text{cd}}$. Again the result is plausible, since the mechanism of transport that provides the largest flux will dominate the sum (i.e., the mechanism for which the stellar matter has the highest “transparency”).

The basic equation for energy transport which, if we define properly, holds for radiative and conductive energy transport, can be rewritten in a convenient form. Starting with

$$\frac{\partial T}{\partial r} = -\frac{3}{16\pi ac} \frac{\kappa \rho L}{r^2 T^3} [\text{K cm}^{-1}],$$

we can transform to the independent variable mass m using the fact that $\partial r / \partial m = (4\pi r^2 \rho)^{-1}$:

$$\frac{\partial T}{\partial m} = -\frac{3}{64\pi^2 ac} \frac{\kappa L}{r^4 T^3} [\text{K g}^{-1}].$$

Assuming hydrostatic equilibrium, we can divide this by $\partial P / \partial r = -(Gm\rho)/r^2$ and obtain

$$\frac{(\partial T / \partial m)}{(\partial P / \partial m)} = \frac{3}{16\pi ac G} \frac{\kappa L}{m T^3} [\text{K P g}^{-2}].$$

We call the ratio of the derivatives on the left $(dT/dP)_{\text{rad}}$, and we mean by this the variation of T in the star with depth, where the depth is expressed by the pressure, which increases monotonically inwards. In this sense, in a star which is in hydrostatic equilibrium and transports the energy by radiation (and conduction), $(dT/dP)_{\text{rad}}$ is a gradient describing the temperature variation with depth. If we use the customary abbreviation

$$\nabla_{\text{rad}} \equiv \left(\frac{d \ln T}{d \ln P} \right)_{\text{rad}} [\text{K P}^{-1}],$$

which can be written in the form

$$\nabla_{\text{rad}} = \frac{3}{16\pi ac G} \frac{\kappa L P}{m T^4} [\text{K P}^{-1}],$$

in which conduction effects are now included. ∇_{rad} means a spatial derivative (connecting P and T in two neighbouring mass shells), while ∇_{ad} describes the thermal variation of one and the same mass element during its adiabatic compression. Only in special cases $(d \ln T / d \ln P)$ and ∇_{ad} will have the same value, and we then speak of an **adiabatic stratification**.

Transport of energy by convection: Convective transport of energy means an exchange of energy between hotter and cooler layers in a dynamically unstable region through the exchange of macroscopic mass elements (“blobs”, “bubbles”, “convective elements”), the hotter of which move upwards while the cooler ones descend. The moving mass elements will finally dissolve in their new surroundings and thereby deliver their excess (or deficiency) of heat. Owing to the high density in stellar interiors, convective transport can be very efficient. However, this energy transfer can operate only if it finds a sufficient driving mechanism in the form of the buoyancy forces.

A thorough theoretical treatment of convective motions and transport of energy is extremely difficult. It is the prototype of the many astrophysical problems in which the bottleneck preventing decisive progress is the difficulty involved in solving the well-known hydrodynamic equations. For simplifying assumptions, solutions are available that may even give reasonable approximations for certain convective flows in the laboratory. Unfortunately, convection in stars proceeds under rather malicious conditions: turbulent motion transports enormous fluxes of energy in a very compressible gas, which is stratified in density, pressure, temperature, and gravity over many powers of ten. Nevertheless, large efforts have been made over many years to solve this notorious problem, and they have partly arrived at promising results. None of the so-called Reynolds stress models, however, have reached a stage where it could provide a procedure easy enough to be handled in everyday stellar-structure calculations, and at the same time would describe the full properties of convection accurately enough. On the other hand, full two- and three-dimensional hydrodynamical simulations have also made large progress, thanks to the impressive advances in supercomputer technology and efficient numerical algorithms. They give valuable hints to the true nature of convection and often serve as numerical experiments to test the dynamical methods. Nevertheless, these numerical simulations are still limited in their size and thus can follow convection in most cases only for a limit time and only for thin convection zones. But even if these restrictions can be foreseen to get relaxed with time, such full hydrodynamical simulations will never be used in full stellar evolution models, as they would unnecessarily follow the star’s evolution on a dynamical timescale, which is so much shorter than the dominant nuclear one. Therefore, we limit ourselves exclusively to the description of the old so-called **mixing-length** theory. The reason for this is not that we believe it to be sufficient, but it does provide at least a simple method for treating convection locally, at any given point of a star. Moreover, empirical tests of the resulting stellar models show a surprisingly good agreement with observations. And, finally, even this poor approximation shows without any doubt that in the very deep interior of a star, a detailed theory is normally not necessary.

Note that in the following we are dealing only with convection in stars that are in hydrostatic equilibrium. We furthermore assume that the convection is time independent, which means that it is fully adjusted to the present state of the star. Otherwise, a convection theory for rapidly changing regions (time-dependent convection) has to be developed.

The gradient ∇_{rad} is what would be maintained in a star if the whole luminosity L had to be transported outwards by radiation only. If convection contributes to the energy transport, the actual gradient ∇ will be different (namely smaller). In the following, we will estimate ∇ in the case of convection.

The basic picture: The mixing-length theory goes back to Ludwig Prandtl, who in 1925 modelled a simple picture of convection in complete analogy to molecular heat transfer: the transporting “particles” are macroscopic mass elements (“blobs”) instead of molecules; their mean free path is the **mixing length** after which the blobs dissolve in their new surroundings. Prandtl’s theory was adapted for stars afterwards.

The total energy flux $L/4\pi r^2$ at a given point in the star consists of the radiative flux F_{rad} (in which the conductive flux may already be incorporated) plus the convective flux F_{con} . Their sum defines the gradient ∇_{rad} that would be necessary to transport the whole flux by radiation:

$$F_{\text{rad}} + F_{\text{con}} = \frac{4acG}{3} \frac{mT^4}{\kappa P r^2} \nabla_{\text{rad}} [\text{erg s}^{-1} \text{cm}^{-2}].$$

However, part of the flux is transported by convection. If the actual gradient of the stratification is ∇ , then the radiative flux is only

$$F_{\text{rad}} = \frac{4acG}{3} \frac{mT^4}{\kappa P r^2} \nabla [\text{erg s}^{-1} \text{cm}^{-2}].$$

Note that ∇ is not yet known; in fact, we hope to obtain it as the result of this consideration. The first step is to derive an expression for F_{con} .

Consider a convective element (a blob) with an excess temperature ΔT over its surroundings. It moves radially with velocity v and remains in complete balance of pressure, that is, $\Delta T = 0$. This gives a local flux of convective energy

$$F_{\text{con}} = \rho v c_P \Delta T [\text{erg s}^{-1} \text{cm}^{-2}],$$

which we can take immediately as the correct equation for the average convective flux, if we consider $v\Delta T$ replaced by the proper mean over the whole concentric sphere. One should be aware that this “proper mean” comprises most of the difficulties for a strict treatment. We adopt the following simple model. All elements may have started their motion as very small perturbations only, that is, with initial values that can be approximated by $\Delta T_0 = 0$ and $v_0 = 0$. Because of differences in temperature gradients and buoyancy forces, ΔT and v increase as the element rises (or sinks) until, after moving over a distance ℓ_m , the element mixes with the surroundings and loses its identity. ℓ_m is called the **mixing length**. The elements passing at a given moment through a sphere of constant r will have different values of v and ΔT since they have started their motion at quite different distances, from zero to ℓ_m . We assume, therefore, that the “average” element has moved $\ell_m/2$ when passing through the sphere. Then,

$$\begin{aligned}\frac{\Delta T}{T} &= \frac{1}{T} \frac{\partial(\Delta T)}{\partial r} \frac{\ell_m}{2} \\ &= (\nabla - \nabla_e) \frac{\ell_m}{2} \frac{1}{H_P} \text{ [dimensionless].}\end{aligned}$$

The density difference is simply $\Delta\rho/\rho = -\delta\Delta T/T$ and the (radial) buoyancy force (per unit mass), $k_r = -g\Delta\rho/\rho$. On average, half of this value may have acted on the element over the whole of its preceding motion ($\ell_m/2$); such that the work done is

$$\frac{1}{2}k_r \frac{\ell_m}{2} = g\delta(\nabla - \nabla_e) \frac{\ell_m^2}{8H_P} \text{ [J].}$$

Let us suppose that half of this work goes into the kinetic energy of the element $v^2/2$ per unit mass), while the other half is transferred to the surroundings, which have to be “pushed aside”. Then, we have for the average velocity v of the elements passing our sphere

$$v^2 = g\delta(\nabla - \nabla_e) \frac{\ell_m^2}{8H_P} \text{ [m}^2 \text{s}^{-2}\text{].}$$

Inserting this and $\Delta T/T$ into F_{conv} , we obtain for the average convective flux

$$F_{\text{conv}} = \rho c_P T \sqrt{g\delta} \frac{\ell_m^2}{4\sqrt{2}} H_P^{-3/2} (\nabla - \nabla_e)^{3/2} \text{ [erg s}^{-1} \text{cm}^{-2}\text{].}$$

Finally, we shall consider the change of temperature T_e inside the element (diameter d , surface S , volume V) when it moves with velocity v . This change has two causes, one being the adiabatic expansion (or compression), and the other being the radiative exchange of energy with the surroundings. The total energy loss λ per unit time is given by

$$\lambda = Sf = \frac{8acT^3}{3\kappa\rho} \Delta T \frac{S}{d}.$$

The quantity λ is a sort of “luminosity” of the blob, and it determines the rate by which the thermal energy of the blob of volume V changes:

$$\rho V c_P \frac{\partial T}{\partial t} = -\lambda.$$

The corresponding temperature decrease per unit length over which the element rises is $\lambda/\rho V c_P v$, and the total change per unit length is then

$$\left(\frac{dT}{dr} \right)_e = \left(\frac{dT}{dr} \right)_{\text{ad}} - \frac{\lambda}{\rho V c_P v}.$$

Multiplying this by H_P/T , we have

$$\nabla_e - \nabla_{\text{ad}} = \frac{\lambda H_P}{\rho V c_P v T}.$$

Here, λ may be replaced by the equation we have for λ above, with the average ΔT given by the equation for $\Delta T/T$ also provided above. The resulting equation then contains a “form factor” $\ell_m S/Vd$, which would be $6/\ell_m$ for a sphere of diameter ℓ_m : In the literature, one often finds

$$\frac{\ell_m S}{Vd} \approx \frac{9/2}{\ell_m},$$

which we will use in the following.

This equation along with that of $(\nabla_e - \nabla_{\text{ad}})$ and λ then becomes

$$\frac{\nabla_e - \nabla_{\text{ad}}}{\nabla - \nabla_e} = \frac{6acT^3}{\kappa\rho^2 c_P \ell_m v}.$$

Let us now summarize what we have achieved and describe what is still lacking. To start with the latter, we have obviously not yet used any physics that could determine the mixing length ℓ_m . Since we do not know a reasonable approach for this, we shall simply treat it as a free parameter and make (more or less) plausible assumptions for its value (This is typical for all versions of the mixing-length approach and in fact also for many others that seem to be less arbitrary at a first glance.). In any case, the heat transfer mainly operates via the largest possible elements, and they can scarcely move over much more than their own diameter before differential forces destroy their identity.

Now, however, the prospect looks quite favourable: we have obtained the five equations which we can solve for the five quantities F_{rad} , F_{con} , v , ∇_e , and ∇ :

$$\begin{aligned} F_{\text{rad}} + F_{\text{con}} &= \frac{4acG}{3} \frac{mT^4}{\kappa P r^2} \nabla_{\text{rad}} \quad [\text{erg s}^{-1} \text{cm}^{-2}] \\ F_{\text{rad}} &= \frac{4acG}{3} \frac{mT^4}{\kappa P r^2} \nabla \quad [\text{erg s}^{-1} \text{cm}^{-2}] \\ v^2 &= g\delta(\nabla - \nabla_e) \frac{\ell_m^2}{8H_P} \quad [\text{m}^2 \text{s}^{-2}] \\ F_{\text{conv}} &= \rho c_P T \sqrt{g\delta} \frac{\ell_m^2}{4\sqrt{2}} H_P^{-3/2} (\nabla - \nabla_e)^{3/2} \quad [\text{erg s}^{-1} \text{cm}^{-2}] \\ \frac{\nabla_e - \nabla_{\text{ad}}}{\nabla - \nabla_e} &= \frac{6acT^3}{\kappa\rho^2 c_P \ell_m v}, \end{aligned}$$

if the usual local quantities (P , T , ρ , L , m , c_P , ∇_{ad} , ∇_{rad} , and g) are given.

1.8.3 Follow-up Questions

- How do we know that the Sun's outer envelope is convective?
- How far into the surface of the Sun does the convective zone permeate? How can we measure this?

1.9 Question 9

What is Eddington's luminosity limit? Explain why this limit is important for the properties and lifetimes of massive stars.

1.9.1 Short answer

Answer.

1.9.2 Additional context

Sir Arthur Stanley Eddington observed that radiation and gravitation both obey inverse-square laws and so there would be instances when the two forces could be in balance irrespective of distance. Thus there should exist a maximum luminosity for a star of a given mass, where the force of radiation on the surface material would exactly balance the force of gravity.

There exists a gradient of the radiation pressure

$$\frac{dP_{\text{rad}}}{dr} = \frac{a}{3} T^3 \frac{dT}{dr} [\text{P m}^{-1}],$$

which exerts, just like the gas pressure gradient, an outward acceleration ($dP_{\text{rad}}/dr < 0$)

$$g_{\text{rad}} = -\frac{1}{\rho} \frac{dP_{\text{rad}}}{dr} [\text{m s}^{-2}]$$

Using

$$F = -\frac{4ac}{3} \frac{T^3}{\kappa\rho} \frac{\partial T}{\partial r} [\text{erg s}^{-1} \text{cm}^{-2}]$$

we see that we can rewrite this as

$$g_{\text{rad}} = \frac{\kappa F_{\text{rad}}}{c} = \frac{\kappa L_r}{4\pi r^2 c} [\text{m s}^{-2}].$$

In case that radiation pressure completely dominates over gas pressure, a star can no longer be in hydrostatic equilibrium if $g_{\text{rad}} > g$. The sum of both accelerations can be written as

$$g + g_{\text{rad}} = -\frac{Gm}{r^2} \left[1 - \frac{\kappa L_r}{4\pi c G m} \right] = -\frac{Gm}{r^2} [1 - \Gamma_r] [\text{m s}^{-2}],$$

where Γ_r can be understood as the ratio of the luminosity relative to the critical luminosity at which the bracket changes sign, and thus the star becomes unbound. For $m = M$ this critical luminosity is called the **Eddington luminosity** and is

$$L_E = \frac{4\pi c GM}{\kappa} [\text{J s}^{-1}].$$

Expressed in Solar units it is

$$\frac{L_E}{L_\odot} = 1.3 \times 10^4 \frac{1}{\kappa} \frac{M}{M_\odot}$$

and grows linearly with stellar mass. Since $L \propto M^3$, stars obviously reach a limit, where radiation pressure is able to drive a strong stellar wind, and which depends on the opacity.

For hot, massive stars electron scattering is the dominating opacity source, which can be approximated by

$$\begin{aligned} \kappa_\nu &= \frac{8\pi}{3} \frac{e_e^2}{\mu_e m_u} \\ &= 0.20(1 + X) [\text{cm}^2 \text{g}^{-1}], \end{aligned}$$

and is $\kappa_{\text{sc}} = 0.20(1 + X)$. For a mass fraction of hydrogen of 0.70 this simplifies to

$$\frac{L_E}{L_\odot} = 3.824 \times 10^4 \frac{M}{M_\odot}.$$

For $M \approx 200 M_\odot$ the luminosity of massive main-sequence stars reach the Eddington limit and disperse. This is a rough estimate for an upper limit. In reality the instability of this mechanism occurs at lower mass. However, the Eddington limit can become quite important in other situations.

Any object that has a luminosity greater than L_E will be forced into instability by its own radiation pressure. This effectively provides a mass-luminosity relationship for super-massive stars since these

radiation-dominated configurations will radiate near their limit. It is worth noting that **magnetars**, the source for **soft gamma repeaters**, are class of gamma-ray bursts that *exceed the Eddington luminosity by far*, but are characterized by a comparably soft gamma spectrum. In a magnetar, the decaying magnetic field is the source of free energy (rather than rotation, as in pulsars).

Limiting masses for super-massive stars: Any star with a mass less than about half a million solar masses can come to equilibrium burning hydrogen via the CNO cycle, albeit with a short lifetime. More massive stars are destined to continue to contract. Of course, more massive stars will produce nuclear energy at an ever-increasing rate as their central temperatures rise. However, the rate of energy production cannot increase without bound. This is suggested by the declining exponents of the temperature dependence shown in Table 3. The nuclear reactions that involve β decay set a limit on how fast the CNO cycle can run, and β decay is independent of temperature. So there is a maximum rate at which energy can be produced by the CNO cycle operating in these stars.

Proton-Proton			CNO Cycle			Triple- α Process		
T_6	ϵ_0 (cgs)	v	ϵ_0 (cgs)	v	T_8	ϵ_0 (cgs)	v	
10	7×10^{-2}	4.60	3×10^{-4}	22.9	0.8	2×10^{-12}	49	
20	1	3.54	4.5×10^2	18	1.0	4×10^{-8}	41	
40	9	2.72	3×10^7	14.1	2.0	15	19	
80	43	2.08	2×10^{11}	11.1	3.0	6×10^3	12	
100	—	—	2×10^{12}	10.2	4.0	10^5	7.9	

Table 3: Table taken from Collins (2003).

If the nuclear energy produced is sufficient to bring the total energy above the binding energy curve, the star will explode. However, should the energy not be produced at a rate sufficient to catch the binding energy that is rising due to the relativistic collapse, the star will continue an unrestrained collapse to the Schwarzschild radius and become a black hole. Which scenario is played out will depend on the star's mass. For these stars, the temperature gradient will be above the adiabatic gradient, so convection will exist. However, the only energy transportable by convection is the kinetic energy of the gas, which is an insignificant fraction of the internal energy. Therefore, unlike normal main sequence stars, although it is present, convection will be a very inefficient vehicle for the transport of energy. This is why the star remains with a structure of a polytrope of index $n = 3$ in the presence of convection. The pressure support that determines the density distribution comes entirely from radiation and is not governed by the mode of energy transport.

The star will radiate at the Eddington luminosity, and that will set the time scale for collapse. The total energy of these stars is small compared to the gravitational energy. So most of the energy derived from gravitational contraction must go into supporting the star, and very little is available to supply the Eddington luminosity. This can be seen from the relativistic Virial theorem which indicates that any change in the gravitational energy is taken up by the kinetic energy. Relativistic particles (in this case, photons) are much more difficult to bind by gravitation than ordinary matter; thus little of the gravitational energy resulting from collapse will be available to let the star shine. The collapse will proceed very quickly on a time scale that is much nearer to the dynamical time scale than the Kelvin-Helmholtz time scale. The onset of nuclear reactions will slow the collapse, but will not stop it for the massive stars.

A dynamical analysis shows that stars more massive than about $7.5 \times 10^5 M_\odot$ will undergo collapse to a black hole. Here the collapse proceeds so quickly and the gravity is so powerful that the nuclear reactions, being limited by β decay at the resulting high temperatures, do not have the time to produce sufficient energy to arrest the collapse. For less massive stars, this is not the case. Stars in the narrow range of $5 \times 10^5 M \leq M \leq 7.5 \times 10^5 M_\odot$ will undergo explosive nuclear energy generation resulting in the probable destruction of the star.

Nothing has been said about the role of chemical composition in the evolution of these stars. Clearly, if there is no carbon present, the CNO cycle is not available for the stabilization of the star. Model calculations show that the triple-alpha process cannot stop the collapse. For stars with low metal abundance, only the pp-cycle is available as an energy source. This has the effect of lowering the value of the maximum stable mass. Surprisingly, there is no range at which an explosion occurs. If the star cannot stabilize before reaching R_m , it will continue in a state of unrestrained gravitational collapse to a black hole. Thus, it seems unlikely that stars more massive than about a half million solar masses could exist.

In addition, it seems unlikely that black holes exist with masses greater than a few solar masses and less than half a million solar masses. If they do, they must form by accretion and not as a single entity.

1.9.3 Follow-up Questions

- Draw a force diagram of what's happening.
- What particles experience gravity the most?
- What particles experience photon pressure the most?

1.10 Question 10

Explain why we know what the Sun's central temperature ought to be, and how we know what it actually is.

1.10.1 Short answer

The hydrostatic condition

$$\frac{\partial P}{\partial r} = -\frac{Gm\rho}{r^2} \text{ [P m}^{-1}\text{]}$$

together with an equation of state for a perfect gas

$$P = \frac{\rho k_B T}{\mu m_H} \text{ [P]}$$

enables us to estimate the pressure and the temperature in the interior of a star of given mass and radius. Let us replace the left-hand side of the equation for hydrostatic equilibrium by an average pressure gradient $(P_0 - P_c)/r$ where P_0 and P_c are the pressures at the surface and at the centre, respectively. On the right-hand side, we can replace m and r by rough mean values $M/2$ and $R/2$, and obtain

$$P_c \approx \frac{2GM^2}{\pi R^4} \text{ [P].}$$

From the equation of state for a perfect gas (our assumption of a perfect gas turns out to be fully justified for these values of P and T), and with the mean density

$$\bar{\rho} = \frac{3M}{4\pi R^3} \text{ [g cm}^{-3}\text{]},$$

we find with P_c that

$$\begin{aligned} T_c &= \frac{P_c \mu m_H}{\bar{\rho} k_B} \text{ [K]} \\ &= \frac{\left(\frac{2GM^2}{\pi R^4}\right) \mu m_H}{\left(\frac{3M}{4\pi R^3}\right) k_B} \text{ [K]} \\ &= \left(\frac{2GM^2}{\pi R^4} \mu m_H\right) \cdot \left(\frac{3M}{4\pi R^3} k_B\right)^{-1} \text{ [K]} \\ &= \left(\frac{2GM^2 \mu m_H}{\pi R^4}\right) \cdot \left(\frac{4\pi R^3}{3M k_B}\right) \text{ [K]} \\ &= \frac{8G\mu m_H}{3k_B} \left(\frac{M}{R}\right) \text{ [K].} \end{aligned}$$

Therefore,

$$T_c \propto \frac{M}{R} \text{ [K].}$$

With the mass and the radius of the Sun ($M_\odot = 1.989 \times 10^{33}$ g, $R_\odot = 6.96 \times 10^{10}$ cm) and with $\mu = 0.5$, we find that

$$\begin{aligned} T_c &= \frac{8G\mu m_H}{3k_B} \left(\frac{1.989 \times 10^{33} \text{ g}}{6.96 \times 10^{10} \text{ cm}}\right) \text{ [K]} \\ &= 3.1 \times 10^7 \text{ [K].} \end{aligned}$$

Modern numerical solutions give $T_c = 1.6 \times 10^7$ K.

1.10.2 Additional context

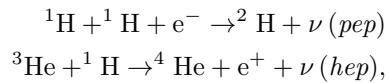
Although the Sun is a very ordinary star of average mass and in a quiet state of MS hydrogen burning, it is a unique object for stellar evolution theorists. For no other star so many quantities are known with comparable accuracy obtained by so many different and independent methods. From Kepler's laws and known distances within the solar system we can derive its mass and radius as well as the total luminosity. This yields the effective temperature by application of the Stefan-Boltzmann law. Neutrino experiments on Earth allow the determination of conditions in the innermost energy producing core. And the art

Quantity	Value	Method
Mass	$(1.9891 \pm 0.0004) \times 10^{33} \text{ g}$	Kepler's third law
Radius	$695,508 \pm 26 \text{ km}$	Angular diameter plus distance
Luminosity	$(3.846 \pm 0.01) \times 10^{33} \text{ erg s}^{-1}$	Solar constant
Effective temp.	$5,779 \pm 2 \text{ K}$	Stefan-Boltzmann law
Z/X	0.0245 ± 0.001 0.0165	Meteorites and solar spectrum (new determination)
Age	$4.57 \pm 0.02 \text{ Gyr}$	Radioactive decay in meteorites
Depth of conv. env.	$0.713 \pm 0.001 R_\odot$	Helioseismology
Env. helium content	0.246 ± 0.002	Helioseismology

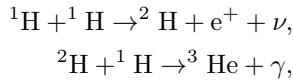
Table 4: Solar quantities and how they are derived. Table taken from Kippenhahn, Weigert & Weiss (2012).

of (helio-)seismology has returned with high accuracy the run of the sound speed throughout most of the solar interior, the helium content of the outer convective envelope, and its depth. These quantities restrict the modelling of the present Sun and allow a comparison with stellar evolution theory at a degree of precision which is almost unique in astrophysics. Table 4 summarizes the fundamental solar parameters and the method to derive them. Note that the rather large uncertainty in the solar mass is the result of the uncertainty in Newton's constant of gravity G. Kepler's third law returns their combination, GM_\odot , with a precision of 10^{-7} !

Solar neutrinos: Some of the nuclear reactions of the pp chain, as well as of the CNO cycle, produce neutrinos. In addition, there are also neutrinos due to the very rare *pep* and *hep* reactions



the latter one being the trivial way to produce ${}^4\text{He}$ after the **pp-chain**,



but it is occurring in only 10^{-8} of all cases. However, the energy of the emitted neutrino is close to 10 MeV, and it is therefore necessary to consider this reaction. The neutrinos leave the star practically without interacting with the stellar matter. The energy spectrum of neutrinos from β decay is continuous, since the electrons can take part of the energy away, while neutrinos released after an inverse β decay are essentially monochromatic. Therefore most reactions of the pp chain have a continuous spectrum, while the pep-reaction and the electron capture on ${}^7\text{Be}$ have a line spectrum. Since ${}^7\text{Be}$ can decay into ${}^7\text{Li}$ either in the ground state or in an excited state, this reaction gives two spectral lines. The neutrino spectrum of the Sun as predicted from the reactions of the pp chain, computed from our standard solar model, is given in Figure 12.

Since the solar neutrinos can leave the Sun almost unimpeded they can in principle be measured in terrestrial laboratories and thus be used to learn directly about conditions in the innermost solar core. This difficult task indeed has been undertaken since 1964, when John Bahcall and Raymond Davies began to plan for an underground neutrino detector in a mine in Homestead, North Dakota. Forty years later the experiments finally have confirmed the standard solar model, and R. Davies received the Nobel Prize for his work. The time in between, however, was characterized by the **solar neutrino problem**.

The solar neutrino problem consisted in the fact that since the first results from the so-called chlorine experiment by Davies there was a lack of neutrinos compared to solar model predictions. The chlorine experiment is sensitive to neutrinos with energies above 0.814 MeV and therefore, as can be seen in Figure 12 mainly to the ${}^8\text{B}$ neutrinos, with some contribution from pep, hep, and ${}^7\text{Be}$ neutrinos. The experiment is based on the reaction ${}^{37}\text{Cl} + \nu \rightarrow {}^{37}\text{Ar}$, where the decays of radioactive argon nuclei are counted. The rate of neutrino captures is commonly measured in solar neutrino units (SNU). One SNU corresponds to 10^{-36} captures per second and per target nucleus. The predicted counts amount to 7.5 SNU for the chlorine experiment, the measurements averaged over several decades to only 2.5 ± 0.2 SNU. The deficit could indicate that the solar centre is cooler than in the models.

To improve the experimental evidence, additional experiments were started. First, another kind of radiochemical detector using gallium in the detector fluid measured, due to a much lower energy threshold, the majority of neutrinos, including those from the pp-reaction. Later, electron-scattering detectors were developed, which are sensitive to the highest energies only, but which provide directional information about the neutrino source (for these detectors the *hep*-neutrinos have to be taken into account.). All

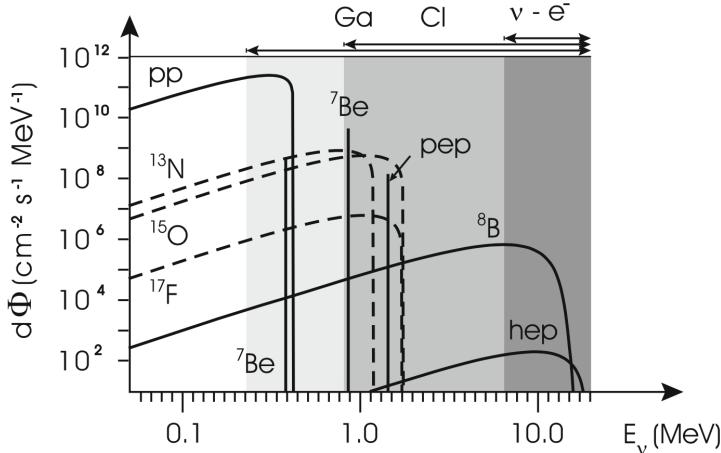


Figure 12: The neutrino spectrum of the Sun as predicted from the theoretical standard solar model. The solid lines belong to reactions of the pp chain while the broken lines are due to reactions of the CNO cycle. The neutrinos from most of the reactions have continuous spectra, while mono-energetic neutrinos come from ${}^7\text{Be}$ and from the pep-reaction. The flux for the continuum sources is given in $\text{cm}^2 \text{s}^{-1} \text{MeV}^{-1}$ and for the line sources in $\text{cm}^2 \text{s}^{-1}$. The sensitivity of the three types of neutrino experiments is indicated above the figure and by the shaded regions. Figure taken from Kippenhahn, Weigert & Weiss (2012).

experiments confirmed that the solar neutrino flux was of the right order of magnitude, and therefore that indeed the Sun shines by the nuclear fusion of hydrogen, but they also consistently measured a deficit of neutrinos. This deficit, however, varied between different kinds of detectors.

With more and more experimental data it became evident that even hypothetical changes to the solar centre cannot solve the problem and that the solution is most likely to be found in the properties of neutrinos. All nuclear reactions emit electron neutrinos, and these are the only ones that were measured in terrestrial experiment, with the exception of the electron-scattering Sudbury Neutrino Observatory (SNO) experiment in Canada, where heavy water (with a high percentage of deuterium isotopes) was used as the detector. Here also reactions with the two other types (flavours) of neutrinos, muon and tau neutrinos can be detected. Summing these and the electron neutrinos up, the total number of detections is completely consistent with the solar model prediction, within a few percent. What created the apparent solar neutrino deficit is the fact that neutrinos can change their flavour, both while travelling through vacuum and more efficiently in the presence of electrons in the solar interior. A similar effect was also confirmed for muon neutrinos arising in the Earth's upper atmosphere from high-energy cosmic radiation, when measured before or after they have travelled through the Earth's interior. The modelling of the solar interior, together with sophisticated experiments, has therefore resulted in new knowledge about fundamental properties of neutrinos. In particular, these so-called **neutrino oscillations** are possible only if neutrinos have mass.

1.11 Question 11

Which have higher central pressure, high-mass or low-mass main-sequence stars? Roughly, what is their mass-radius relation? Derive this.

1.11.1 Short answer

Answer.

1.11.2 Additional context

Additional context.

1.11.3 Follow-up Questions

- How would we actually know the central pressure?
- What properties can we measure to test models of stellar structure?

1.12 Question 12

Sketch the SED of an O, A, G, M, and T star. Give defining spectral characteristics, such as the Balmer lines and Balmer jump and Calcium doublets, and describe physically.

1.12.1 Short answer

Answer.

1.12.2 Additional context

Additional context.

1.12.3 Follow-up Questions

- Are there emission lines?
- What molecular lines are in the Sun?
- What important lines are there are much longer wavelengths than those in the optical?
- What if the A star had a protoplanetary disk?
- What is the significance of a λF_λ (or νF_ν) spectrum?
- How can the relative height of the stellar vs disk bumps change? (i.e., total energy of the system cannot change; dust bump can't be higher than star bump without extinction.)

1.13 Question 13

What can be learned about young stars (T Tauri and pre-main-sequence stars) from an analysis of their spectral features?

1.13.1 Short answer

Answer.

1.13.2 Additional context

Additional context.

1.13.3 Follow-up Questions

- How does the spectrum change as planets start to form?

1.14 Question 14

Sketch the spectral energy distribution (SED) of a T Tauri star surrounded by a protoplanetary disk. How would the SED change: (a) if the disk develops a large inner hole, (b) if the dust grains in the disk grow in size by agglomeration (with the same total mass)?

1.14.1 Short answer

Answer.

1.14.2 Additional context

Additional context.

1.15 Question 15

What are the primary origins of the heat lost to space by infrared luminosity of Jupiter, Earth, and Io?

1.15.1 Short answer

Answer.

1.15.2 Additional context

Additional context.

1.16 Question 16

Explain the observational problem of radius inflation for hot Jupiters and describe two possible solutions.

1.16.1 Short answer

Answer.

1.16.2 Additional context

Additional context.

1.17 Question 17

Explain the effects of an atmosphere on a planet's surface temperature and the position of the habitable zone. What special considerations must one make for habitability around M-type stars?

1.17.1 Short answer

Answer.

1.17.2 Additional context

Additional context.

1.18 Question 18

Explain the process of nuclear fusion and give two examples of important fusion processes that affect the lives of stars.

1.18.1 Short answer

Answer.

1.18.2 Additional context

Additional context.

1.19 Question 19

What is Fermi's Paradox? Explain its logic and assess the current state of the Paradox in light of modern knowledge.

1.19.1 Short answer

Answer.

1.19.2 Additional context

Additional context.

1.19.3 Follow-up Questions

- What percentage of stars have planets?

1.20 Question 20

The so-called r- and s- processes are mechanisms that produce elements heavier than iron. Describe these mechanisms and evidence for them from abundance patterns. Where is the r-process thought to act?

1.20.1 Short answer

Answer.

1.20.2 Additional context

Additional context.

1.21 Resources

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- Understanding Variable Stars, Percy (2007)