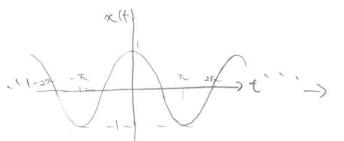
E933200 signals and systems

Solutions to Midtern Exam I

1

$$\chi(t) = \cos(t).$$



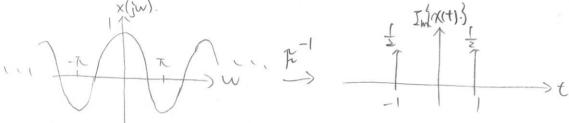
$$(jw) = \pi S(w-1) + \pi S(w+1)$$

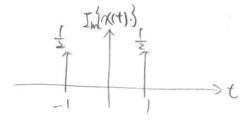
$$x(jw) = \pi \delta(w-1) + \pi \delta(w+1)$$

$$x(jw) = j \cos(w)$$

(6)

$$X(jw) = j \cos(w)$$
 $\chi(t) = \mathcal{F}^{-1} \{j \cos(w)\} = j \mathcal{K}^{-1} \{\cos(w)\} = \frac{1}{2} (S(t-1) + S(t+1))$
 $\chi(jw)$.





$$=\sum_{k=-\infty}^{\infty}a_k^{*}\cdot\int_{T}^{\infty}\chi(t)e^{-jkwt}dt=\sum_{k=-\infty}^{\infty}a_k^{*}a_k=\sum_{k=-\infty}^{\infty}|a_k|^2$$

$$Q_0 = \frac{1}{2\pi} \int_{\frac{\pi}{2}}^{\frac{\pi}{2}} |dt| = \frac{\pi}{2\pi} = \frac{1}{2}$$

kto ak = I Size -jwkt dt

$$= \frac{1}{2\pi} \frac{1}{jwk} \left(e^{-jwk} \frac{\pi}{2} - e^{+jwk} \frac{\pi}{2} \right)$$

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=
$$\frac{1}{2\pi i j w k}$$
 $\frac{1}{2} \sin \frac{w k \pi}{2} = \frac{\sin(\frac{k\pi}{2})}{\pi k}$

$$\chi(t) = \begin{cases} 1 & |t| < \frac{\pi}{2} \\ 0 & \frac{\pi}{2} < |t| < \pi \end{cases}$$
where the period $\tau = 2\pi$ and $w = \frac{2\pi}{\tau} = 1$

$$q_k = \frac{1}{\tau} \int_{\tau} \chi(t) e^{-jkw} dt$$

where the period
$$T=2\pi$$
 and $w=\frac{2\pi}{T}=1$

$$Q_{k}=\frac{1}{2}\int_{T}^{\infty}x(t)e^{-jkw\epsilon}dt$$

$$Q_{k}=\frac{1}{2}\int_{T}^{\infty}x(t)dt=\frac{\pi}{2\pi}=\frac{1}{2}$$

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$$(\frac{2}{1} - \frac{1}{4})/2 = \frac{1}{2} \frac{1}{2} \frac{1}{(2k-1)^2}$$

$$\chi(t) \times u(t) = \int_{-\infty}^{\infty} \chi(t)u(t-\tau)d\tau = \int_{-\infty}^{t} \chi(t)d\tau$$

$$u(\tau) = \int_{-\infty}^{\infty} \chi(t)u(t-\tau)d\tau = \int_{-\infty}^{t} \chi(t)d\tau$$

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(b)
$$U(jw) = \frac{1}{2} \left[\frac{1 + S9n(t)}{2} \right]$$

= $\frac{1}{2} \left[2\pi \delta(w) + \frac{2}{jw} \right]$
= $\pi \delta(w) + \frac{1}{jw}$

$$= \mathcal{K} \left\{ \int_{-\infty}^{t} \chi(\tau) d\tau \right\}$$

$$= \mathcal{K} \left\{ \chi(\tau) + \chi(t) \right\} = \chi(jw) \cdot U(jw) = \chi(jw) \left(\pi \delta(w) + \frac{1}{jw} \right)$$

$$= \frac{\chi(jw)}{jw} + \pi \chi(jw) \cdot \delta(w)$$

= X(jw) + T X(0) S(w).

4.
$$X(jw) = \int_{-\infty}^{\infty} X(t) \cdot e^{jwt} dt$$

$$D(jw) = \frac{dX(jw)}{dw} = \frac{d}{dw} \left(\int_{-\infty}^{\infty} X(t) e^{jwt} dt \right)$$

$$= \int_{-\infty}^{\infty} X(t) \left(\frac{d}{dw} \cdot e^{jwt} \right) dt$$

$$= \int_{-\infty}^{\infty} (X(t) \cdot -jt) e^{jwt} dt$$

$$d(t) = \bigcap_{i=1}^{n-1} \{ D(j\omega) \} = -jt \times (t)$$

5.
$$Y(t) = X(t) * h(t) \Rightarrow Y(jw) = F\{x(t) * h(t)\} = X(jw) \cdot H(jw)$$

 $X(jw) = F\{sinc(\frac{t}{n})\} = \pi \cdot Yect(\frac{w}{n})$

$$\left(\mathcal{F}\left\{ \operatorname{sinc}\left(\frac{\operatorname{wt}}{\pi}\right) \right\} = \frac{\pi}{\operatorname{w}} \operatorname{vect}\left(\frac{\operatorname{w}}{\operatorname{zw}}\right), \text{ for } 1, \text{ for } 1 \right\} = \pi \operatorname{vect}\left(\frac{\operatorname{w}}{\operatorname{z}}\right)$$

$$H(Ju) = \mathcal{H} \left\{ \text{STNC}(t) \right\} = \text{Vect}\left(\frac{\omega}{2\pi}\right)$$
 $\mathcal{L} = \mathcal{L}$

$$Y(j\omega)=X(j\omega)\cdot H(j\omega)=\pi\cdot \text{Vect}(\frac{\omega}{z})$$

$$\Rightarrow y(t)=T_1^{-1}\left\{\pi\cdot \text{Vect}(\frac{\omega}{z})\right\}=\text{Sinc}(\frac{t}{\pi})$$

6.
$$X(t) = Yect(\frac{t}{2}) = \begin{cases} 1, |t| \le 1 \\ 0, |t| > 1 \end{cases}$$

$$\xrightarrow{1}$$

(a)
$$X(j\omega) = \int_{-\infty}^{\infty} \text{ rect}(\frac{t}{2}) \cdot e^{j\omega t} dt$$

$$= \int_{-1}^{1} e^{j\omega t} dt = \frac{1}{-j\omega} e^{j\omega t} \Big|_{-1}^{1}$$

$$= \frac{1}{-j\omega} \left(e^{j\omega} - e^{j\omega} \right) = \frac{1}{j\omega} \left(e^{j\omega} - e^{j\omega} \right)$$

$$= \frac{1}{j\omega} (2j \sin(\omega)) = \frac{2\sin\omega}{\omega}$$

(b)
$$\int_{0}^{\infty} \frac{\sin \omega}{w} dw = \frac{1}{z} \int_{-\infty}^{\infty} \frac{\sin \omega}{w} dw$$

$$X(t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} X(jw) e^{jwt} dw$$

$$= \frac{1}{2\pi} \int_{-\infty}^{\infty} \frac{25\overline{n}w}{w} e^{jwt} dw$$

Letting t=0,

$$X(0) = \frac{1}{2\pi} \int_{-\infty}^{\infty} \frac{25 \text{In}(w)}{w} dw$$

$$\Rightarrow 1 = \frac{1}{2\pi} \int_{-\infty}^{\infty} \frac{25\pi w}{w} dw$$