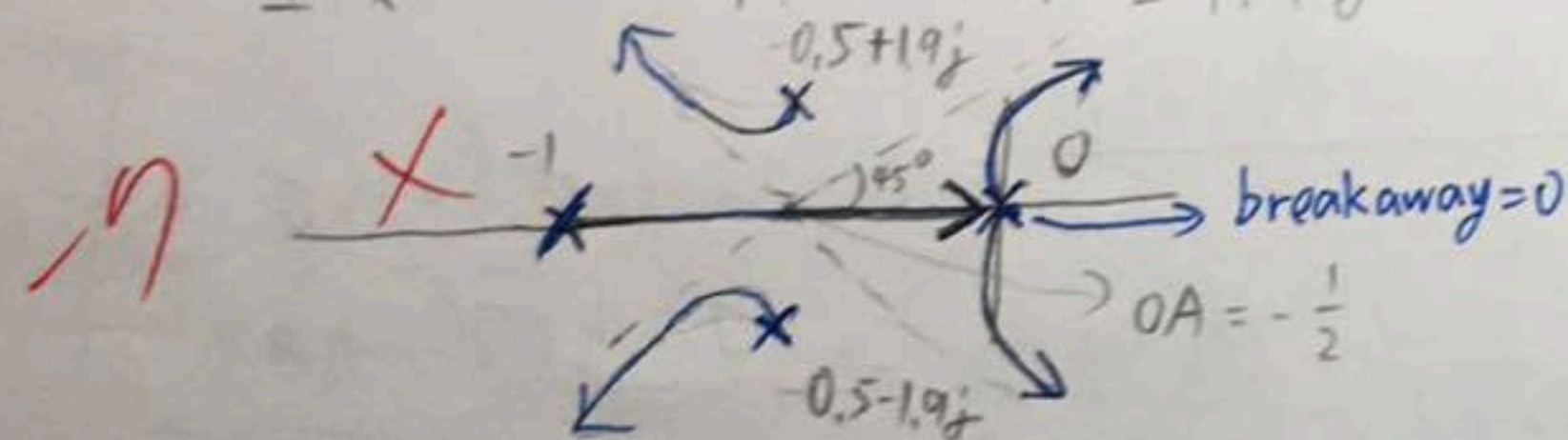


院系 College	I 學院 I 科 系 3 年 班 College Department Year Class	評閱成績 Score	of Instructor
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1. (a) 極點: $0, -1, -0.5 \pm 1.9j$



$$OA = \frac{0 - 1 - 0.5 + 1.9j - 0.5 - 1.9j}{4 - 0} = -\frac{1}{2}$$

$$\phi_{asy} = \frac{2\pi l + \pi}{4 - 0} = \frac{\pi}{4}, \frac{3\pi}{4}, \frac{5\pi}{4}, \frac{7\pi}{4} = \pm 45^\circ, \pm 135^\circ$$

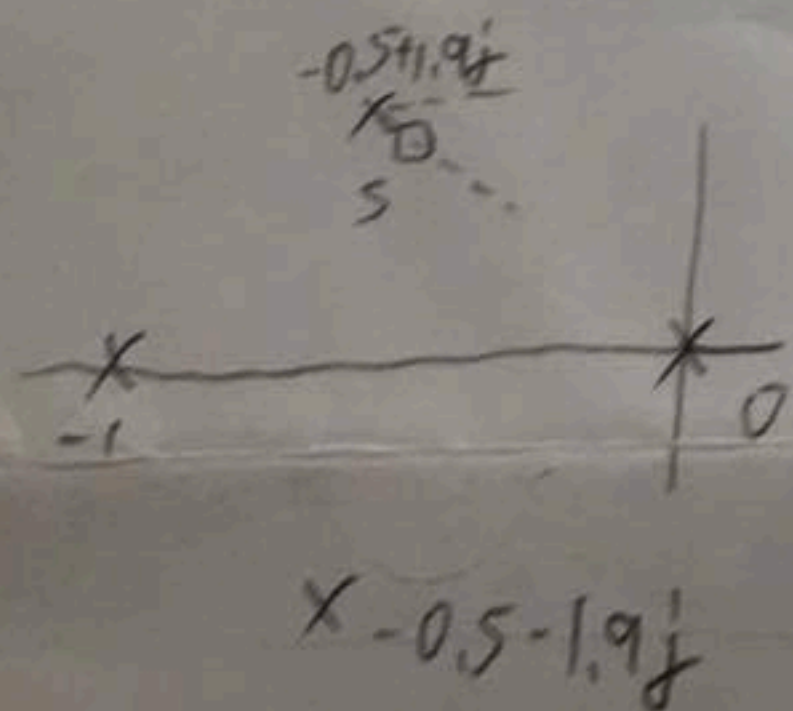
breakaway point: $\frac{k}{s(s+1)(s^2+s+4)} = -1 \Rightarrow k = -s(s^3+s^2+4s+s^2+s+4) = -(s^4+2s^3+5s^2+4s)$

$$\frac{dk}{ds} = 0 \Rightarrow \frac{d(-s^4-2s^3-5s^2-4s)}{ds} = 0 \Rightarrow -4s^3-6s^2-10s-4 = 0$$

$$s = -0.75 \pm 1.392j, 0$$

↑
breakaway point

(b) $\angle s$ at $-0.5 + 1.9j$



$$\angle G(s) = \angle k - \angle(s) - \angle(s+1) - \angle(s+0.5-1.9j) - \angle(s+0.5+1.9j)$$

$$-180^\circ = 0^\circ - (180^\circ - \tan^{-1} \frac{1.9}{0.5}) - \tan^{-1} \frac{1.9}{0.5} - \angle dep - 90^\circ$$

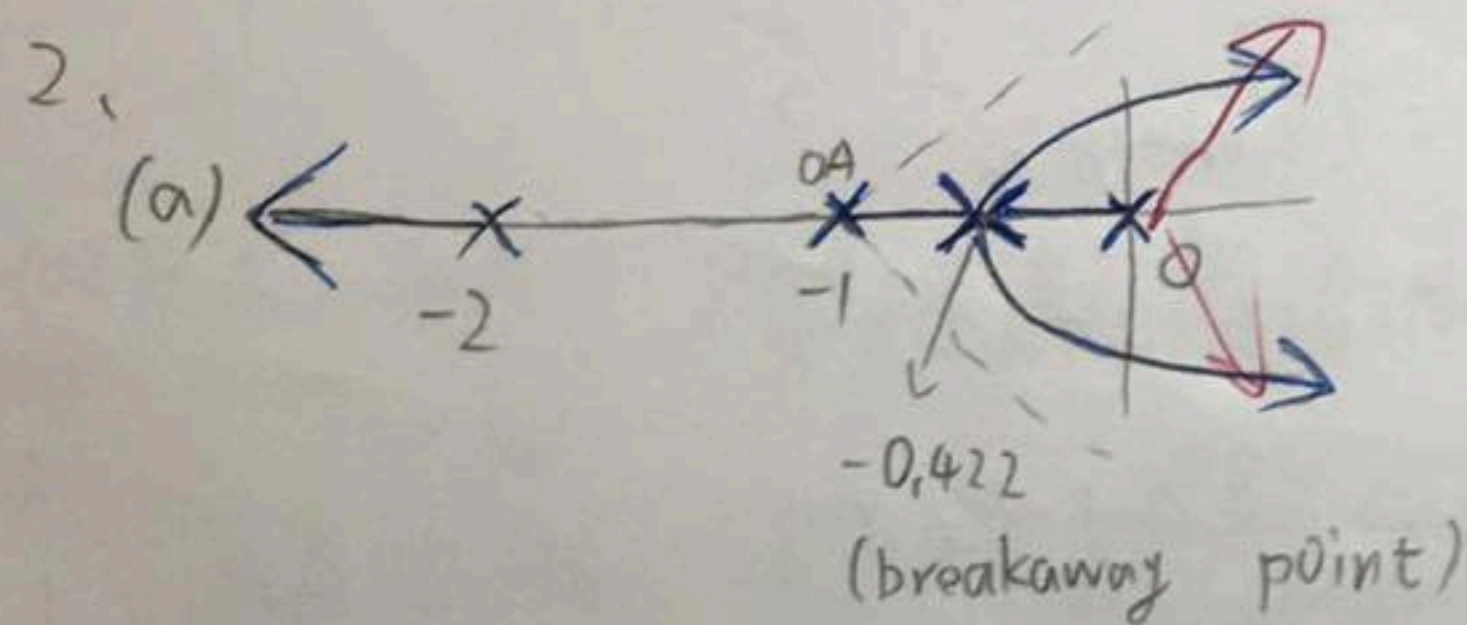
$$\therefore \angle dep = -90^\circ$$

(c) $\angle j\omega$ at $G(s) = -1 \Rightarrow \frac{k}{s^4+5s^2+s(2s^2+4)} = -1 \Rightarrow \frac{k}{(s^4+2s^3+5s^2+4s)} = -1$

(c) $\sum j\omega \text{ 帶入 } G(s) = -1 \Rightarrow \frac{k}{s^4 + 5s^2 + s(2s^2 + 4)} = -1 \Rightarrow \frac{k}{(w^4 - 5w^2) + jw(-2w^2 + 4)} = -1 \dots ①$

$\therefore w = 0 \text{ or } \pm\sqrt{2}$ 再代回 ① 式 $\Rightarrow \frac{k}{(4-10)+0} = -1 \Rightarrow k = 6$

故 $0 < k < 6$ (系統穩定)



$OA = \frac{-2}{3} = -1$

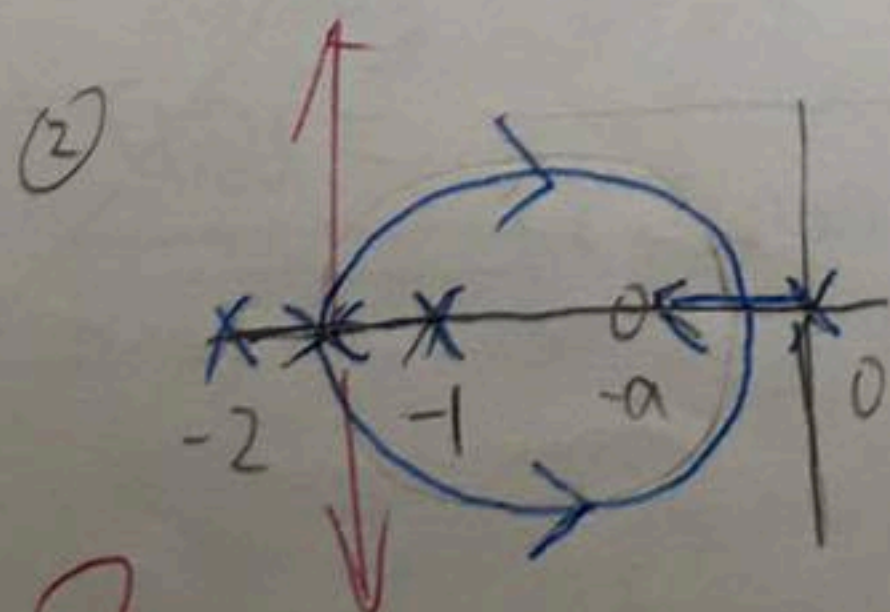
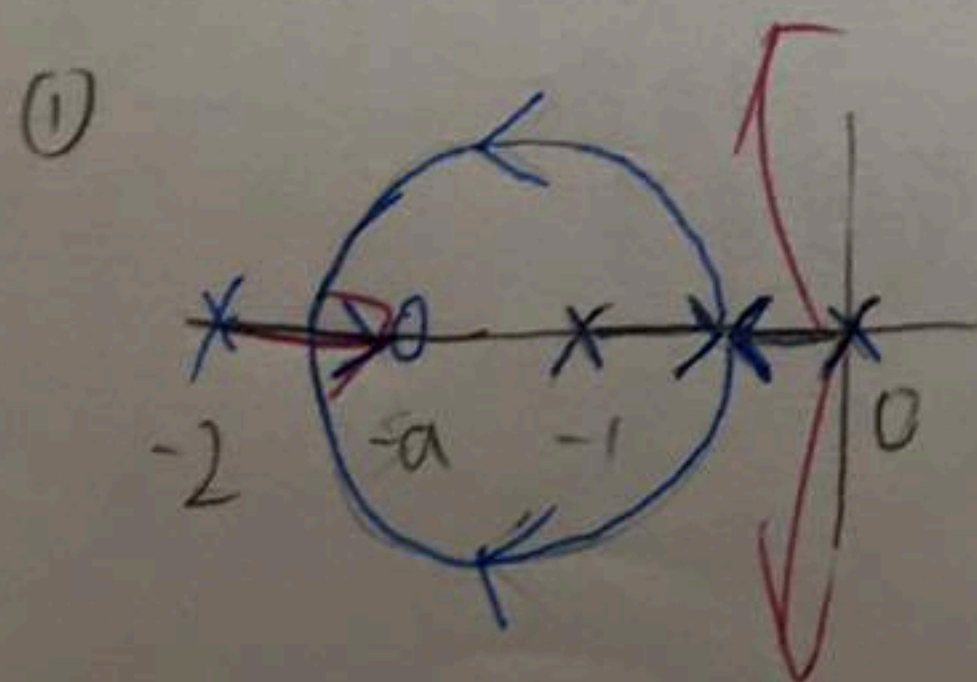
$\phi_{asy} = \frac{2\pi l + \pi}{3 - 0} = \frac{\pi}{3} \cdot \pi = \frac{5\pi}{3} = \pm 60^\circ, 180^\circ$

breakaway point: $\frac{1}{s+2} + \frac{1}{s+1} + \frac{1}{s} = 0$

$\Rightarrow s^2 + s + s^2 + 2s + s^2 + 3s + 2 = 0 \Rightarrow 3s^2 + 6s + 2 = 0$
 $\therefore s = -0.422, -1.5$

\therefore root-locus 上 poles 會往右半平面跑, \therefore 當 k 大時, 系統不穩定

(b) 畫出 root locus 來: 分兩種情形 ① $s \in [-2, -1]$ ② $s \in [-1, 0]$

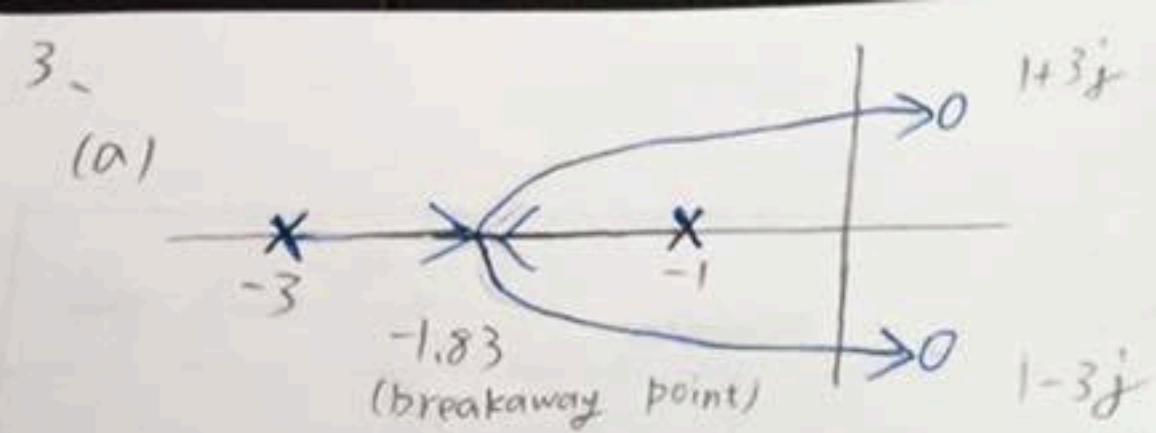


由此 2 種情形來看, 發現 k 增大, root-locus 都不會跑到右半平面, \therefore 會使系統穩定

(續寫轉背頁)

學號:

姓名:



$$k = \frac{s^2 + 4s + 3}{-(s^2 - 2s + 10)} \Rightarrow \frac{dk}{ds} = 0$$

$$\Rightarrow \frac{d\left(\frac{\sigma^2 + 4\sigma + 3}{-\sigma^2 + 2\sigma - 10}\right)}{d\sigma} = 0 \Rightarrow \frac{(-\sigma^2 + 2\sigma - 10)(2\sigma + 4) - (\sigma^2 + 4\sigma + 3)(-2\sigma + 2)}{(-\sigma^2 + 2\sigma - 10)^2} = 0 \Rightarrow 6\sigma^2 - 14\sigma - 46 = 0$$

$$\sigma = 4.17, -1.83$$

(b) $\hat{s} = j\omega$ 帶入 $G(s) = -1 \Rightarrow \frac{k(-\omega^2 - 2j\omega + 10)}{(-\omega^2 + 4j\omega + 3)} = \frac{k(-\omega^2 + 10) + jk(-2\omega)}{(-\omega^2 + 3) + j(4\omega)} = -1 \dots (1)$

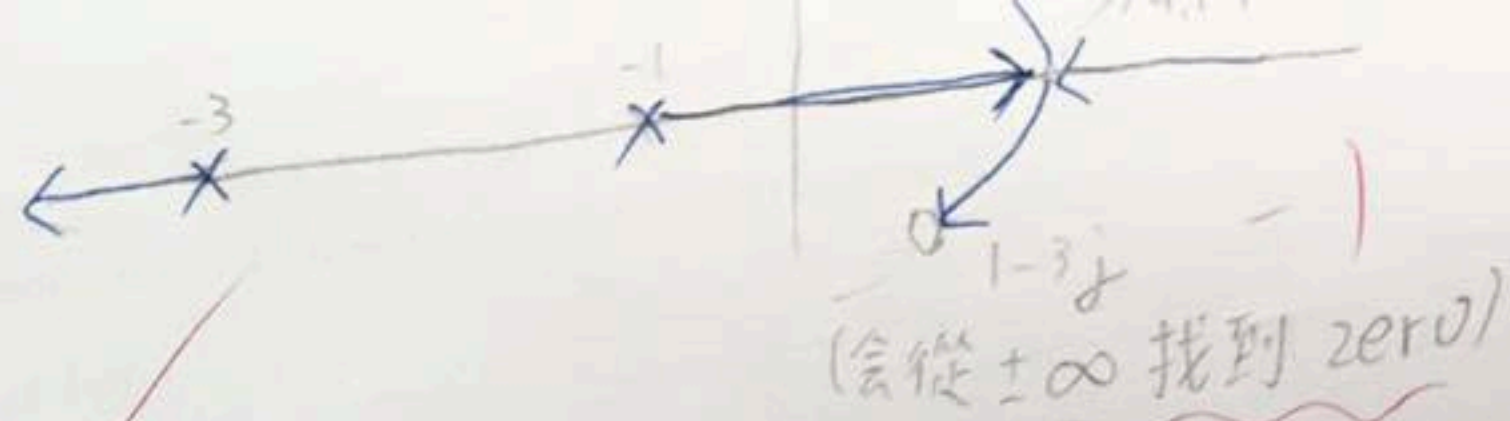
$$\therefore \frac{k(-\omega^2 + 10)}{-\omega^2 + 3} = \frac{k(-2\omega)}{4\omega} \Rightarrow -2\omega^2 + 20 = \omega^2 - 3 \Rightarrow 3\omega^2 = 23 \Rightarrow \omega = \pm 2.7689$$

(帶回 (1) 式)

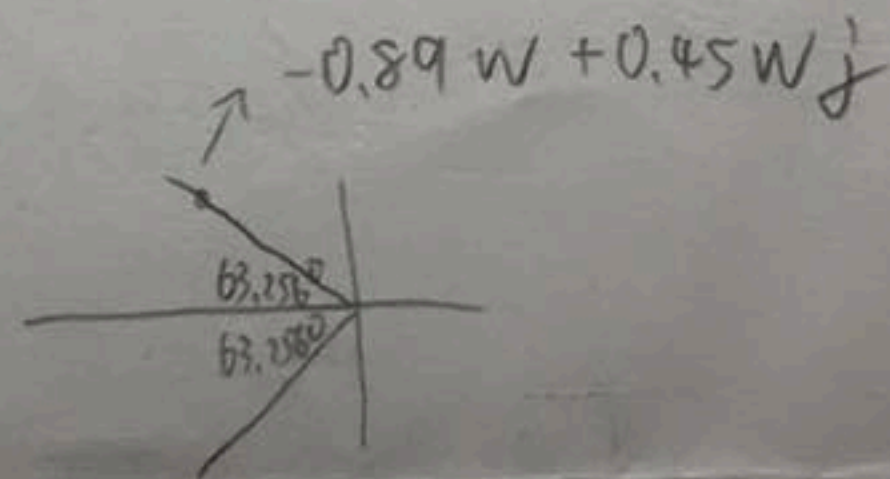
$$\Rightarrow \frac{k}{-2} = -1 \Rightarrow k = 2$$

(c) $\frac{0.45}{0.89} = 0.45 = \cos \theta \Rightarrow \theta = 63.256^\circ$

$$\therefore s = -0.89\omega + 0.45j\omega \text{ 帶入 } G(s) = -1 \Rightarrow \frac{k(0.89^2\omega^2 - 2 \cdot 0.89 \cdot 0.45j\omega^2 - 0.45^2\omega^2 + 2 \cdot 0.89\omega - 2 \cdot 0.45j\omega + 10)}{0.89^2\omega^2 - 2 \cdot 0.89 \cdot 0.45j\omega^2 - 0.45^2\omega^2 - 4 \cdot 0.89\omega + 4 \cdot 0.45j\omega + 3} = -1$$



(\because 有 zero 點存在, pole 即使往 $+\infty$ or $-\infty$ 跑, 最後要回到 zero)



$$\Rightarrow \frac{k(0.5896w^2 - 0.801jw^2 + 1.78w - 0.9jw + 10)}{0.5896w^2 - 0.801jw^2 - 3.56w + 1.8jw + 3} = -1$$

$$\Rightarrow \frac{k(0.5896w^2 + 1.78w + 10)}{0.5896w^2 - 3.56w + 3} = \frac{k(-0.801w^2 - 0.9jw)}{-0.801w^2 + 1.8jw} \Rightarrow$$

$$\Rightarrow \frac{-0.5896 \cdot 0.801 w^3 - 1.78 \cdot 0.801 w^2 - 8.81w + 0.5896 \cdot 1.8 w^2 + 1.78 \cdot 1.8 w + 18}{-0.5896 \cdot 0.801 w^3 + 3.56 \cdot 0.801 w^2 - 3 \cdot 0.801 w - 0.5896 \cdot 0.9 w^2 + 3.56 \cdot 0.9 w - 2.7} = -5$$

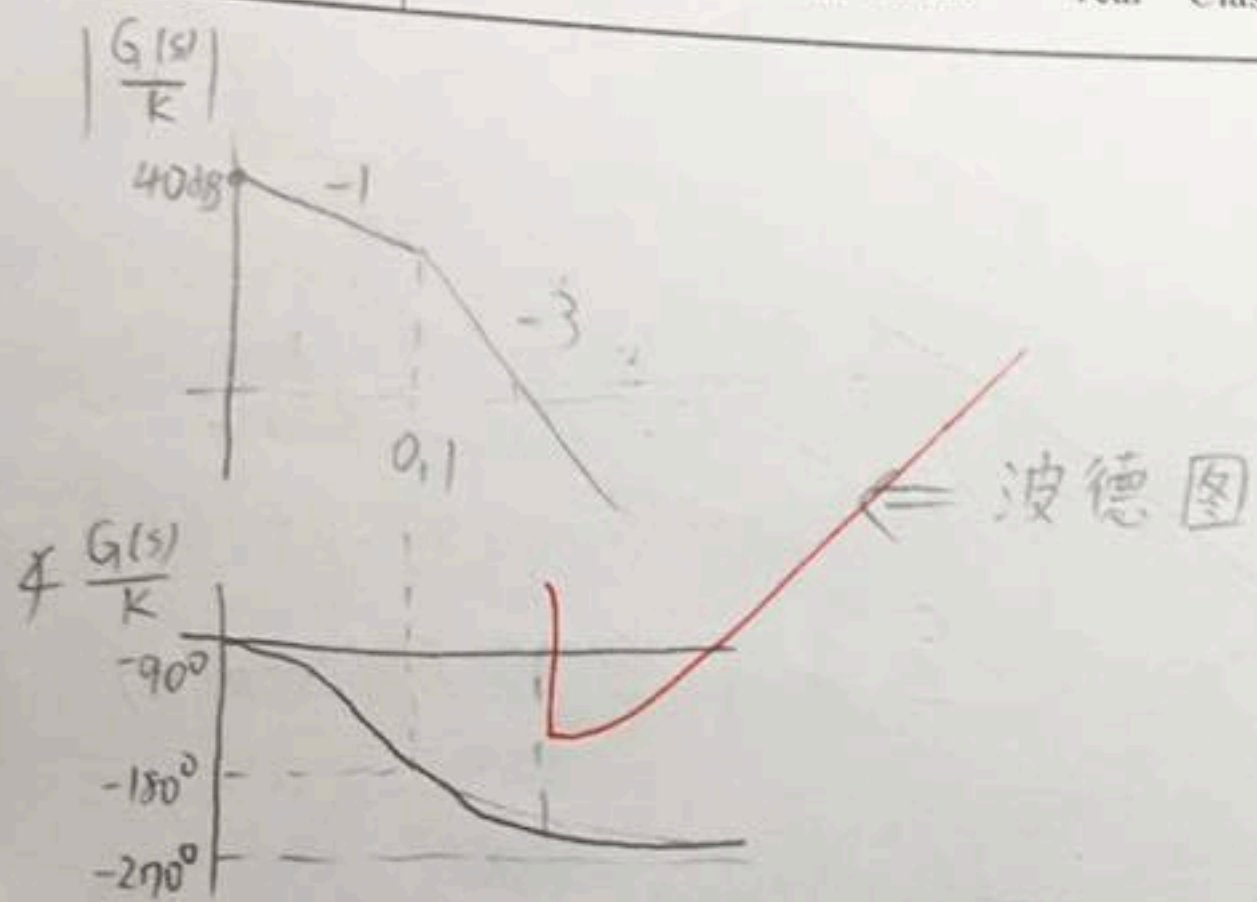
$$\Rightarrow -2.68542 w^2 - 5.607 w + 20.7 = 0 \quad w = 1.922, -4.01 \text{ (負不合)} \text{ 代回 } G(s) = -1$$

$$\therefore k: (-9.3728) = -1 \quad \therefore k = 0.10669$$

4. (a) s 在 0 & $\sqrt{0.01} = 0.1$ 會有轉折, 令 $s = jw$, $w = 0.1$ 帶入

$$G(s) = \frac{10}{0.1s^2 + s(0.01s^2 + 1)} = \frac{10}{-0.1w^2 + jw(-0.01w^2 + 1)} = 100 \Rightarrow \text{轉成dB} \quad 40 \text{ dB}$$

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$$(b) G(j\omega) = \frac{K \cdot 10}{-0.1\omega^2 + j\omega(-0.01\omega^2 + 1)}$$

$$\therefore -20 \log |G(j\omega)| = 10 \text{ dB} \quad \therefore |G(j\omega)| = 0.31622$$

$$\therefore \angle G(j\omega) = 0 \quad \therefore \omega_{pc} = 0 \text{ or } \pm 10 \quad (\omega_{pc} = 10)$$

$$\therefore \frac{|K \cdot 10|}{|-0.1\omega_{pc}^2 + j\omega_{pc}(-0.01\omega_{pc}^2 + 1)|} = 0.31622 \Rightarrow \therefore K = 0.31622$$

$$(c) \angle G(s) = -(180^\circ - 45^\circ) = -135^\circ$$

$$\therefore 0^\circ - (180^\circ - \tan^{-1} \frac{-0.01\omega^3 + \omega}{0.1\omega^2}) = -135^\circ \Rightarrow \omega_{gc} = 6.18$$

$$|G(j\omega)| = 1 = \frac{|10K|}{\sqrt{(-0.1\omega^2)^2 + (-0.01\omega^3 + \omega)^2}} \Rightarrow \therefore K = 0.5401$$

$$|G(j\omega)| = 1 = \frac{|10K|}{\sqrt{(1-0.1\omega^2)^2 + (-0.01\omega^3 + \omega)^2}} \Rightarrow \therefore \underline{K = 0.5401}$$

5. (a) 先求 GM - PM 才能畫出 Nichols Chart

(b)

$$(c) G(s) = \frac{1000}{s(s^2 + 11s + 10)} \quad s = j\omega \quad \frac{1000}{-11\omega^2 + j\omega(-\omega^2 + 10)}$$

' $G(s) = -1 \Rightarrow$ 虛部 = 0 $\Rightarrow \omega = 0$ or $\pm \sqrt{10}$ 帶回原 $G(s)$
(不合) (負不合)

(b) $\underline{GM} = -20 \log |G(s)| = -20 \log 9.0909 = \underline{-19 \text{ (dB)}}$

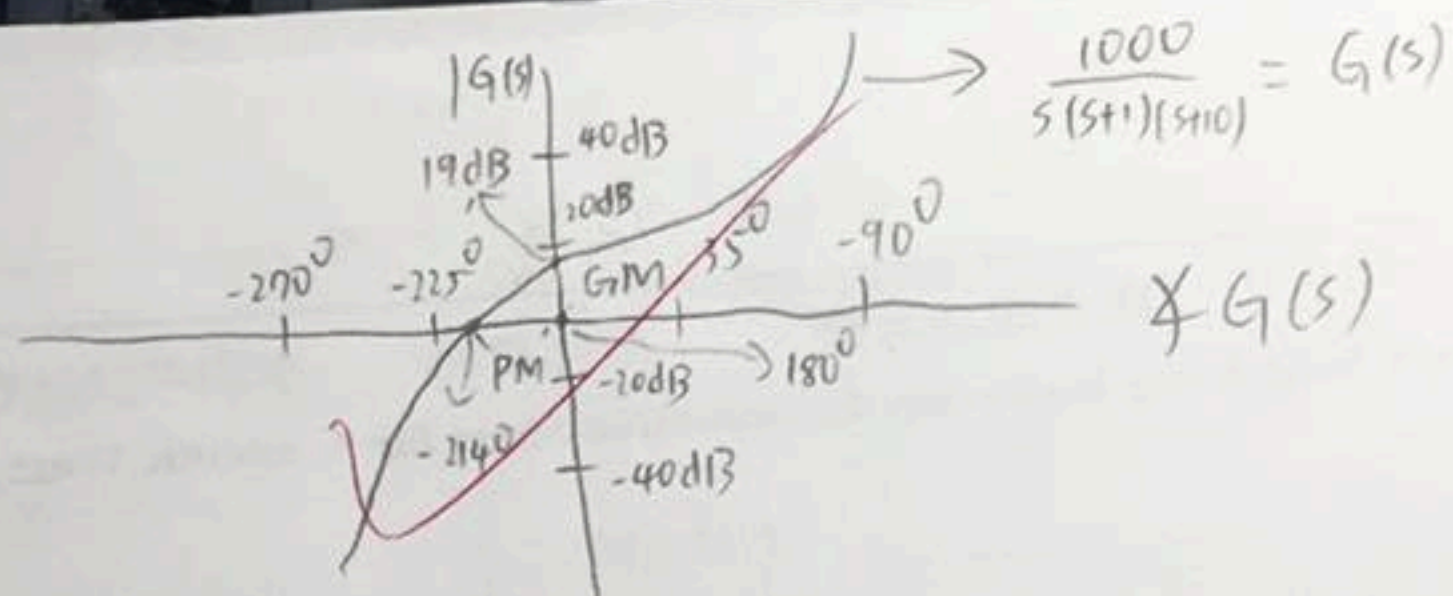
再求 PM: 先求 $\omega_{gc} \Rightarrow \frac{1000}{\sqrt{(1-11\omega^2)^2 + (-\omega^3 + 10\omega)^2}} = 1 \Rightarrow \omega_{gc} = 8.664$

$\angle G(j\omega_{gc}) = 0^\circ - \left(180^\circ + \tan^{-1} \frac{\omega^3 - 10\omega}{11\omega^2} \right) = -214^\circ$
(續寫轉背頁)

$\therefore \underline{PM} = 180^\circ - 214^\circ = \underline{-34^\circ}$

3.

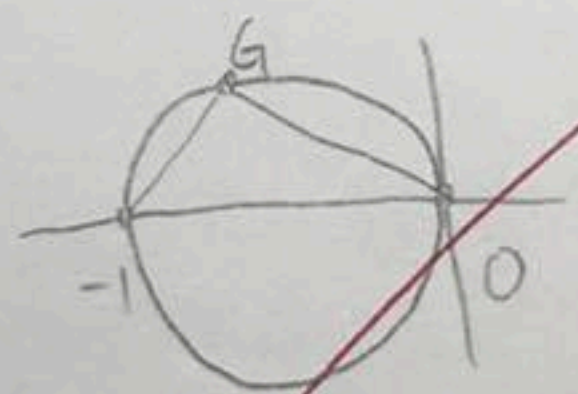
Nichols Chart



(d) 由 (a) 題的 Nichols Chart 可看出 $GM < 0$ & $PM < 0$, \therefore 交在 19dB 的位置 (即 $GM = -19dB$) & 交在 -214° (即 $PM = -34^\circ$), \therefore 對於一個系統, 只要 GM or $PM < 0$, 就會不穩定, 故此系統不穩定

$$6. (a) |M| = \frac{|G - (-0)|}{|G - (-1)|}$$

\Rightarrow 图示



表示一個集合: G , (G 到 0 的距離) \div (G 到 -1 的距離) 呈一個常數 (constant)

\Rightarrow 而此常數用 M 來表示

$$(b) \hat{s} = x + jy \Rightarrow |M| = \frac{|x + jy|}{|1 + x + jy|} = \frac{\sqrt{x^2 + y^2}}{\sqrt{(1+x)^2 + y^2}}$$

$$\Rightarrow [(1 + 2x + x^2) + y^2] M^2 = x^2 + y^2$$

呈 - 个常数 (constant)

\Rightarrow 而此常数用 M 来表示

$$(b) \text{ 令 } s = x + jy \Rightarrow |M| = \frac{|x + jy|}{|1 + x + jy|} = \frac{\sqrt{x^2 + y^2}}{\sqrt{(1+x)^2 + y^2}}$$

$$\Rightarrow [(1 + 2x + x^2) + y^2] M^2 = x^2 + y^2$$

$$\Rightarrow (1 - M^2)x^2 - 2M^2x + (1 - M^2)y^2 = M^2$$

$$\Rightarrow x^2 - \frac{2M^2}{1-M^2}x + y^2 = \frac{M^2}{1-M^2}$$

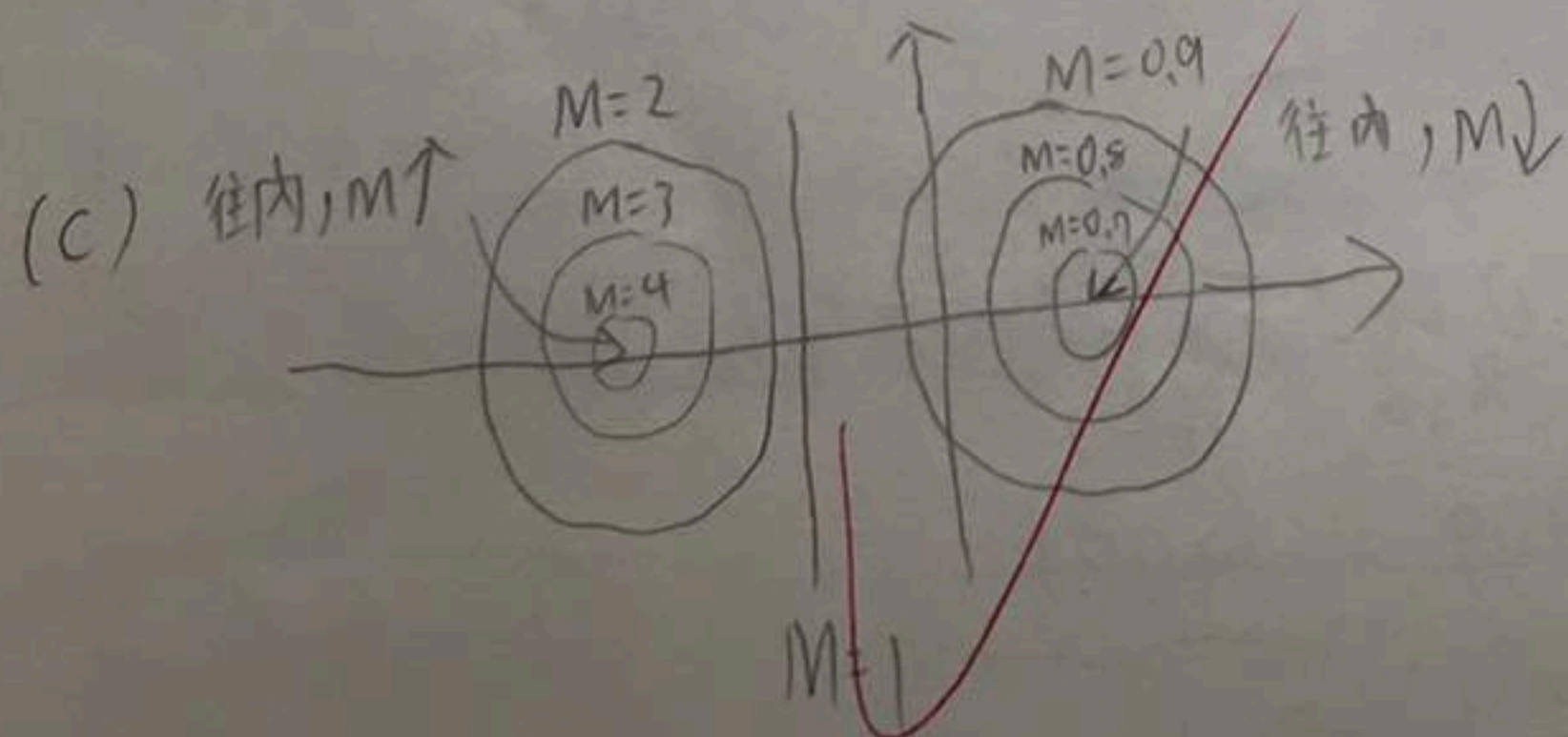
同除 $1-M^2$

$$\Rightarrow x^2 - \frac{2M^2}{1-M^2}x + \left(\frac{M^2}{1-M^2}\right)^2 + y^2 = \frac{M^2}{1-M^2} + \left(\frac{M^2}{1-M^2}\right)^2$$

同加 $\left(\frac{M^2}{1-M^2}\right)^2$

$$\Rightarrow \left(x - \frac{M^2}{1-M^2}\right)^2 + y^2 = \frac{M^2 - M^4 + M^4}{(1 - 2M^2 + M^4)} = \left(\frac{M}{1-M^2}\right)^2$$

\therefore 由上式：圆的方程式可得知 圆心在 $\left(\frac{M^2}{1-M^2}, 0\right)$
半径 $\left|\frac{M}{1-M^2}\right|$



4.