# USING PARTIAL MODEL SYNTHESIS TO SUPPORT MODEL INTEGRATION IN LARGE-SCALE SOFTWARE DEVELOPMENT

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September 2013



#### Motivation

- Global software engineering projects
  - Highly distributed
  - Involve many stakeholders which produce heterogeneous models reflecting different concerns
- GEMOC initiative:
  - Find ways to support collaboration and interoperability at the integration points between models
- Key challenge:
  - Management of dependencies between models!

# **GEMOC Approach**

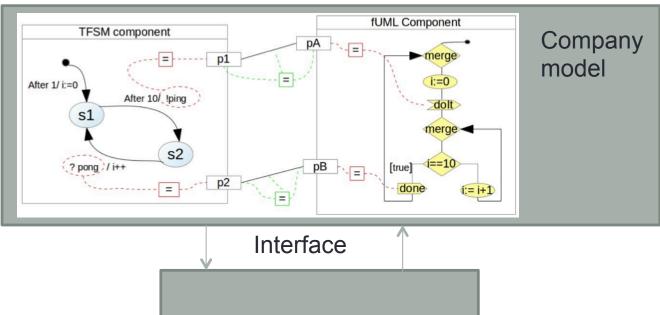
Clearly define interface specifications early in the development lifecycle:

- E.g., a set of operation signatures or detailed interaction scenarios, properties, invariants
- ☑These are useful for guiding model development
- ★Not well suited for dynamic techniques such as testing, simulation, model-checking

# Our proposal

Automatic synthesis of partial models from interface specifications that act as model stubs and can be used as temporary stand-ins for the models to allow simulation and other analysis.

Partial model: a set of possible models admissible by the specification



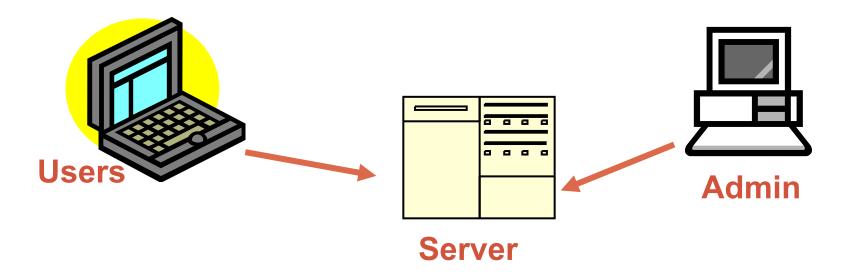
Model developed by subcontractor

#### **Outline**

- Motivation
- Illustration: Web-mail system
- Classical approach:
  - Synthesis from Scenarios
  - Synthesis from Global Properties
- Partial modeling approach:
  - Synthesis from Scenarios
  - Synthesis from Global Properties
  - Merge
- Status
- Connection to GEMOC

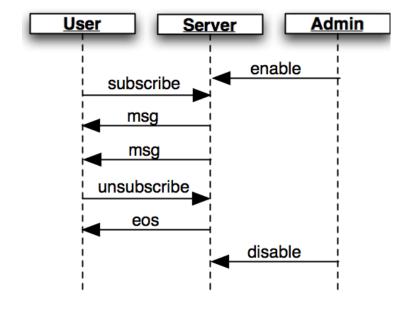
# Web-mail System

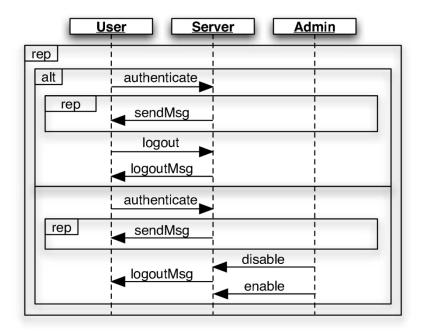
A toy example to illustrate our approach...



Description consists of a set of scenarios and FLTL properties

#### Web-mail Scenarios





#### Web-mail Properties

#### Expressed in FLTL

fluent Registered = <enable, disable> initially TRUE fluent LoggedIn = <authenticate, {logout, disable}> initially FALSE



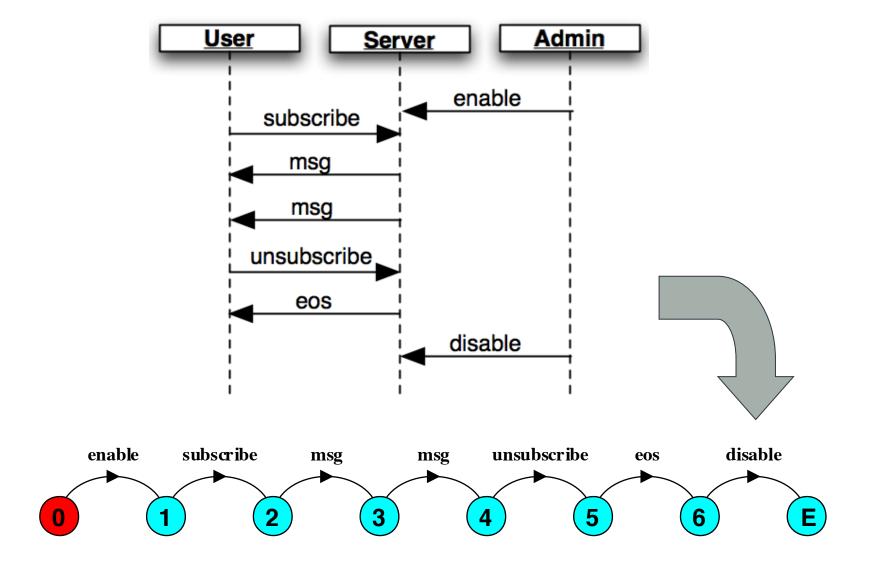
#### Properties

LegalAccess: [](LoggedIn -> Registered)

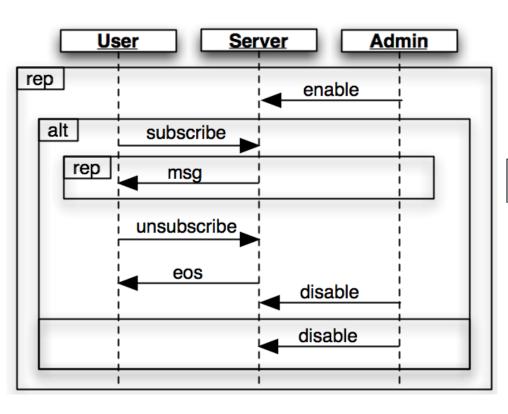
PrivateAccess: [](sendMsg ->LoggedIn)

Logouts are ack'd: [](logout -> X logoutMsg)

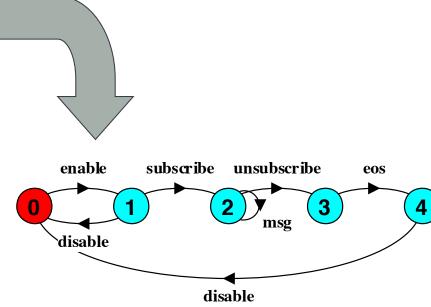
# (classical) Synthesis from Scenarios



# Synthesis from Complex Scenario Specifications

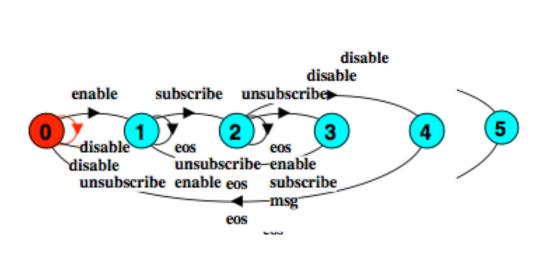


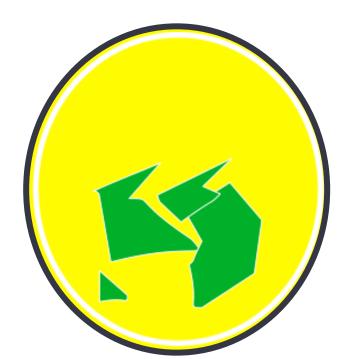
 Support for repetitions, alternatives, references, triggers, symbolic instances, preemption, broadcasting...



## Scenarios are Partial Specifications

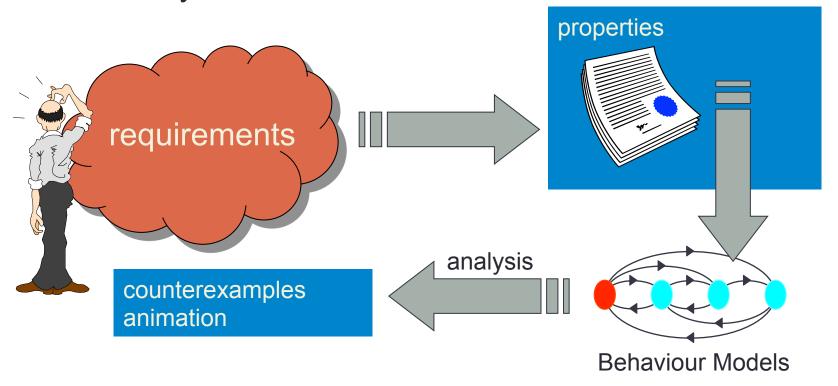
- A model synthesised from scenarios
  - Describes behaviour that the system must be capable of exhibiting
  - Does not describe all the required behaviour
- Elaboration = "adding behaviour"
  - i.e., preserving trace inclusion or simulation





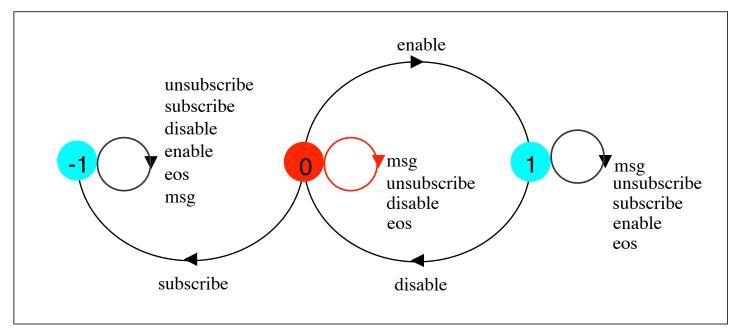
## Synthesis from Declarative Specifications

 Build models automatically from assertions about the intended system behaviour.



# FLTL Safety Properties to LTS

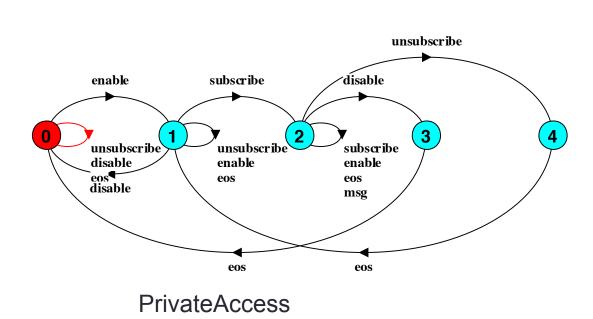
- 1. Apply FLTL to Büchi construction [Gianna'03]
- Remove accepting state and all transitions leading to it.

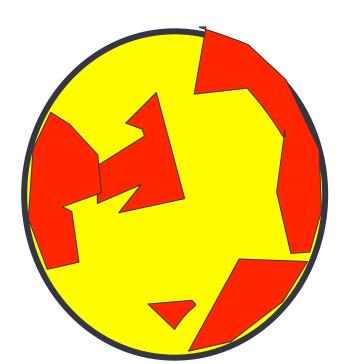


constraint LegalAccess = [](Subscribed -> Enabled)

# Models Synthesized from Properties are Partial too!

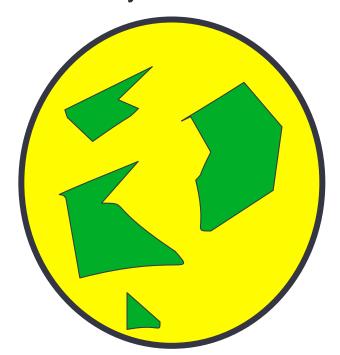
- A model synthesized from a property P
  - describes all behaviour that does not violate P, or alternatively
  - describes behaviour that the system may exhibit
- Not all described traces are required to be provided by the system
- Elaboration = "removing behaviour"
  - i.e., preserving trace inclusion or simulation



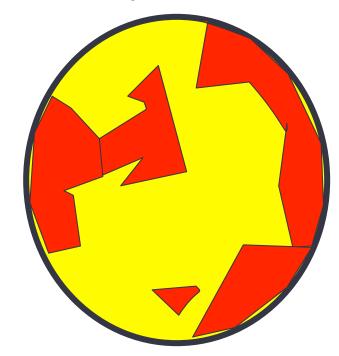


# Scenarios and Properties are Complementary

- Scenarios...
  - describe traces we know we want.
  - provide a lower bound to intended system behaviour.

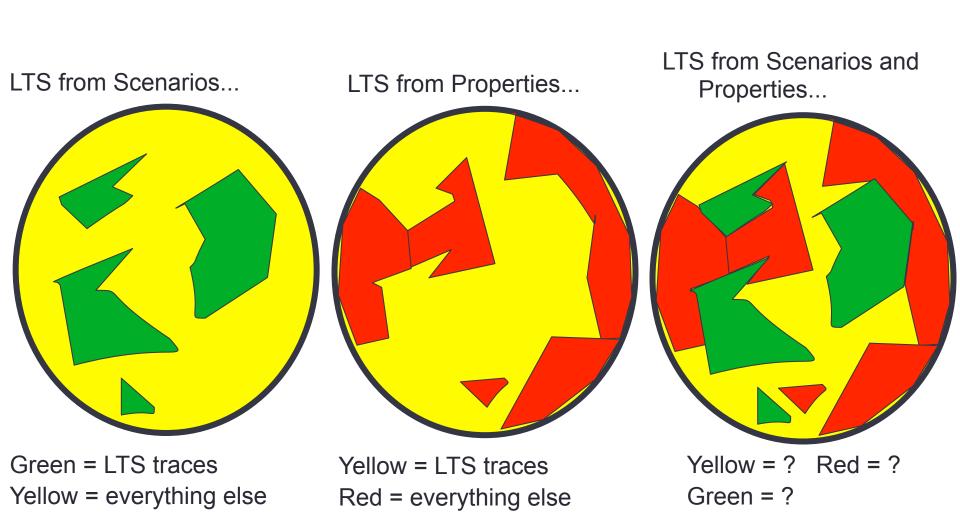


- Properties...
  - describe what we know we don't want.
  - provide an upper bound to intended system behaviour



# LTS are Not Expressive Enough...

2 valued behaviour models cannot capture the "middle ground"



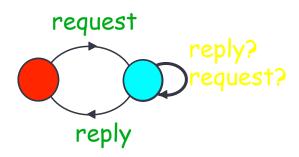
#### **Outline**

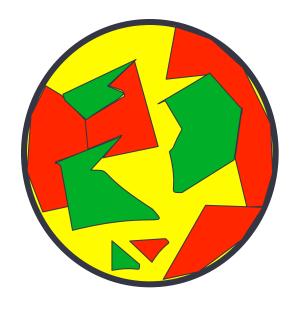
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# Modal Transition Systems (MTS)

- Larsen et. al. 1988 -

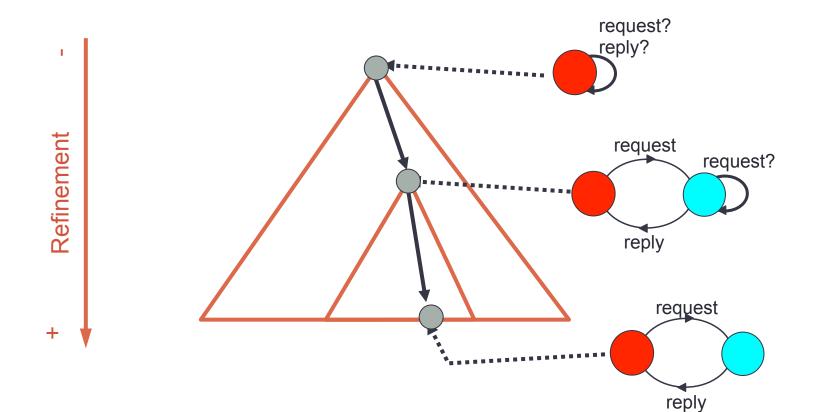
- Extension of LTS:
  - Required transitions
  - Possible transitions
- They describe
  - Explicitly what we do not know
  - Implicitly what we prohibit



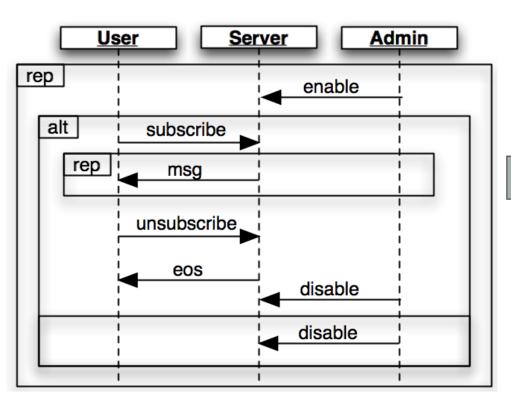


#### MTS Refinement

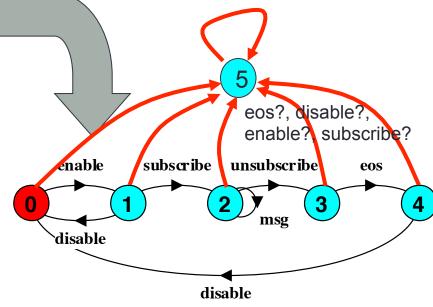
- Intuitive semantics: "more defined than", "has more information than"
- Refinement is inclusion of implementations



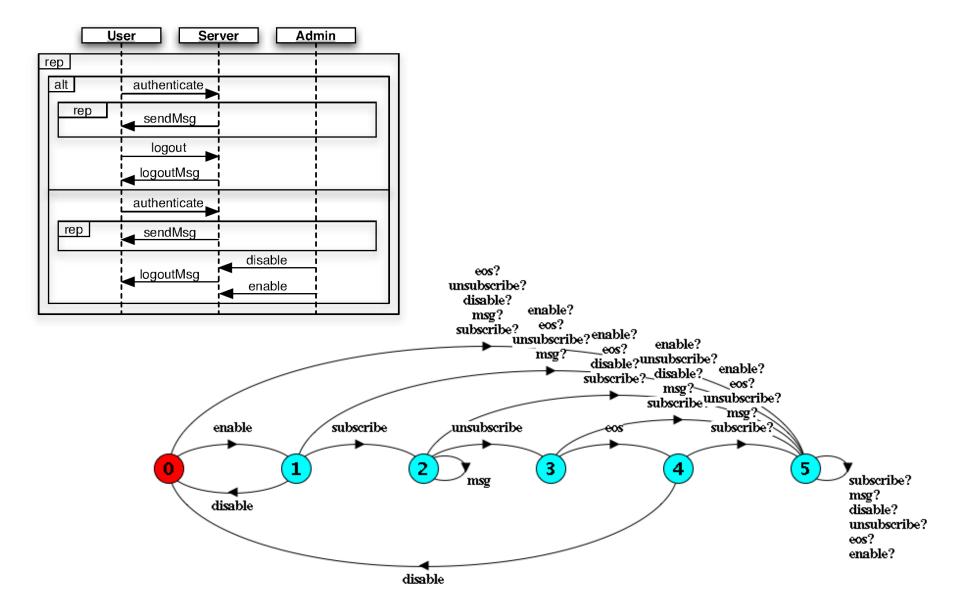
# Synthesis of MTS from Scenarios



- 1. Synthesize LTS as usual
- Add sink state
- 3. For all state s and label e, if e is not enabled on s, add a may-transition (s, e, sink)

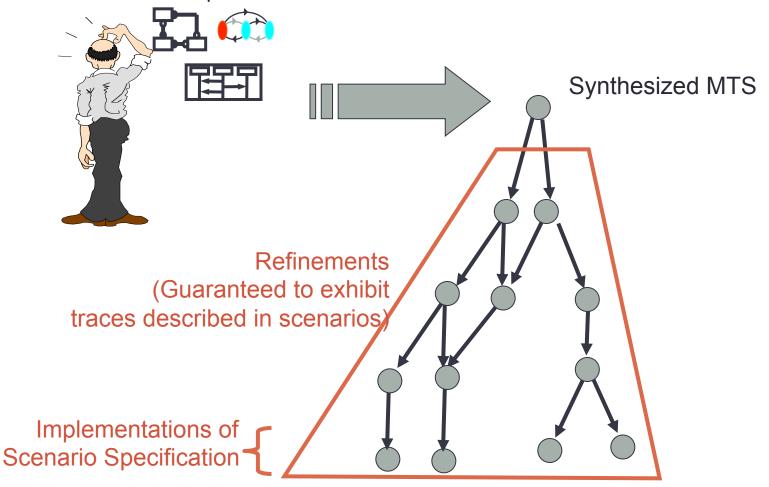


# Synthesis of MTS from Complex Scenario



## MTS Synthesis from Scenarios

- From architectural specifications
  - Structural descriptions + scenarios

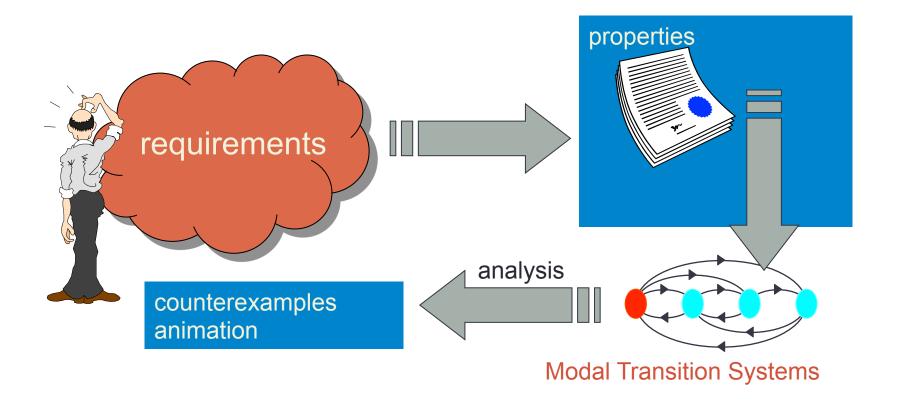


#### Note

 All of the above observations apply to synthesis from architectural descriptions, not just from scenarios

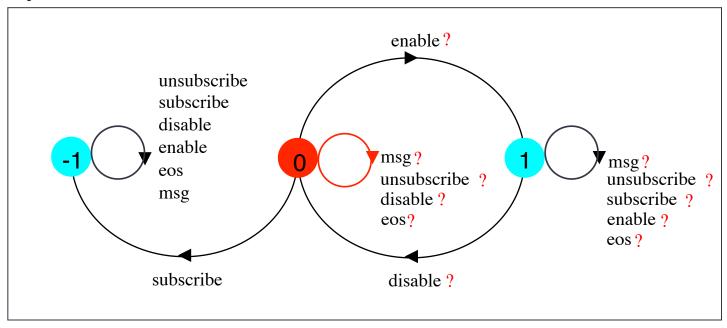
#### Synthesis of MTS from Declarative Specifications

 Build MTS models automatically from assertions about the intended system behaviour.



# FLTL Safety Properties to MTS

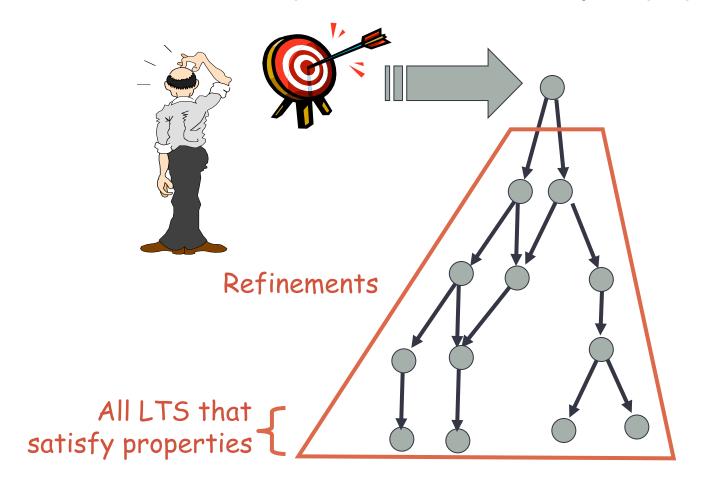
- 1. Apply FLTL to Büchi construction [Gianna'03]
- 2. Remove accepting state and all transitions leading to it.
- If a state has more than one outgoing transition, make them all may-transitions



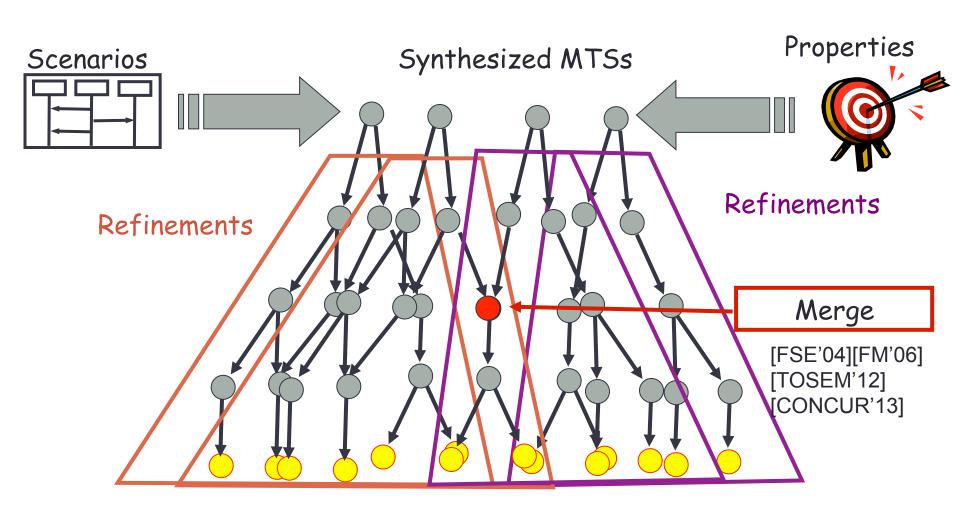
constraint LegalAccess = [](Subscribed -> Enabled)

# Synthesis from Safety Properties

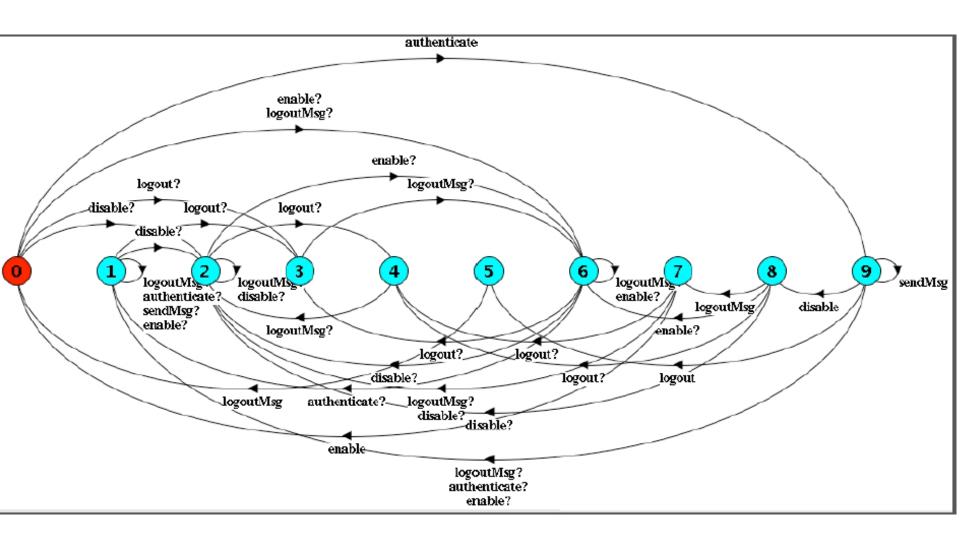
Synthesis characterises all implementations that satisfy the properties



# Synthesis from heterogeneous specifications



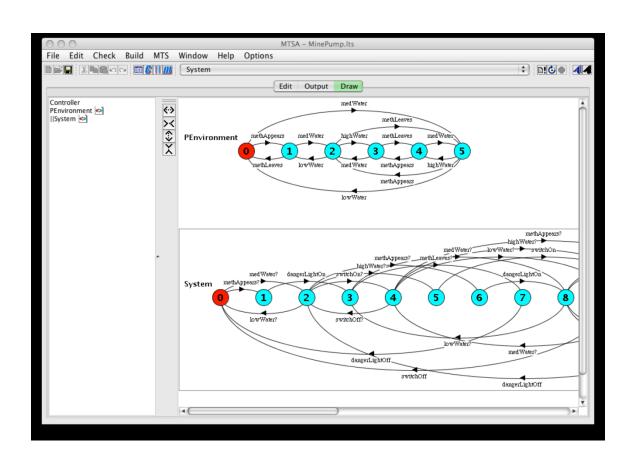
# Resulting Model



## **Tool Support**

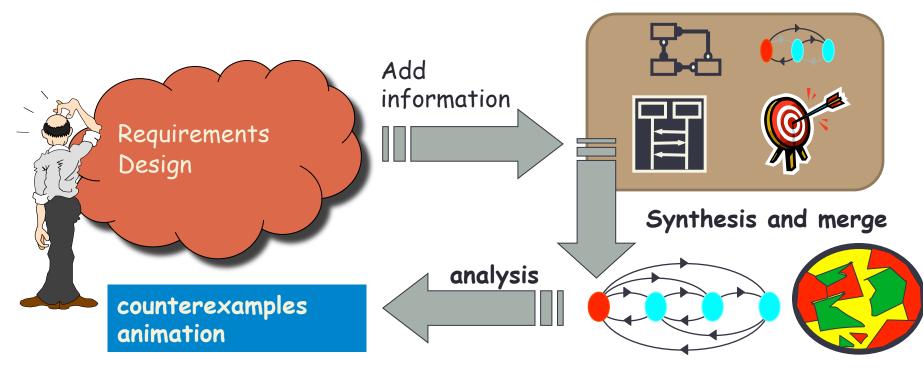
http://sourceforge.net/projects/mtsa/

- Synthesis (Process Algebra, Scenarios, Properties)
- FLTL Model Checking
- Animation
- Composition
  - Parallel
  - Merge
- Others
  - Minimization
  - Hiding
  - Determinization



# Summarizing

 Partial behaviour models are the foundations for techniques and tools to develop support for the iterative construction and elaboration of behaviour models



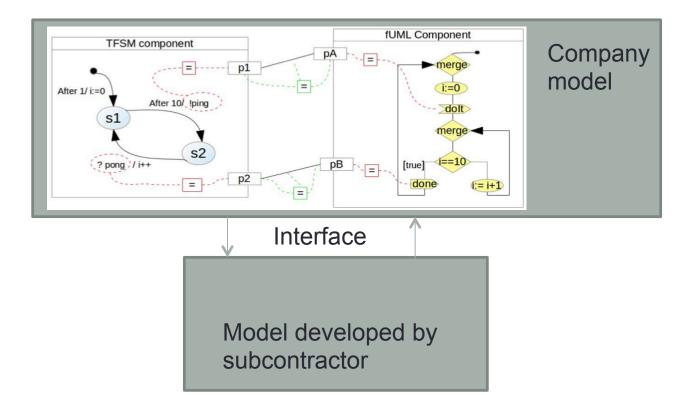
Partial Behaviour Models (e.g., MTS)

#### Status of this work

- Toolset for MTS synthesis, verification, animation (mature)
- Recent progress in merging partial models over different vocabularies [CONCUR'13]
  - Requires DMTSs
- Toolset for DMTS analysis (prototype)
- Novel scenario-based specification languages [FSE'11]
- Support for inconsistency resolution [SoSym'11]

# Why Relevant to GEMOC?

- We propose to synthesize partial models to construct behavior of missing components, given their contracts, however partial
- The resulting behavioral models can be used, together with existing ones, in testing, animation, verification



# Challenges

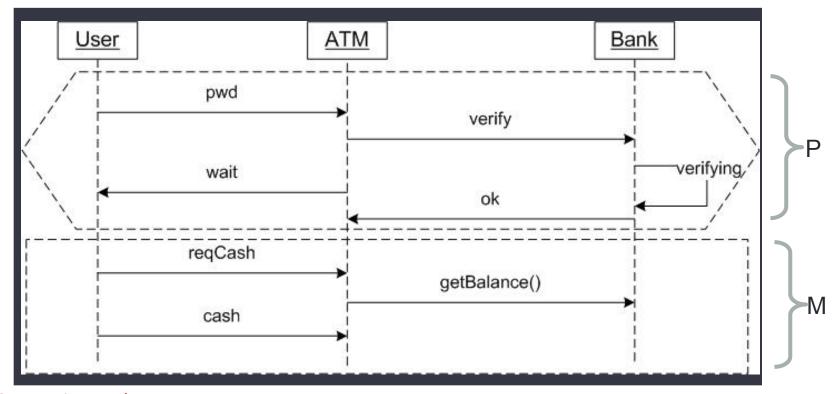
- Synthesis to produce a model complying to an assumed meta-model
- Scalability to "large" models
- Timing issues
- Handling relationships between models

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# QUESTIONS?

#### **Existential Triggered Scenarios**

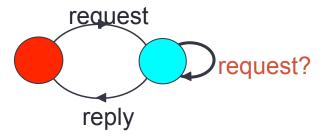


#### Tree-based Semantics:

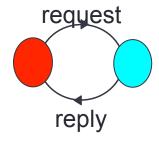
When the Prechart holds then, there must exist an execution branch where the Mainchart is next.

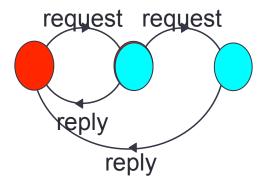
# Modal Transition Systems [Larsen88]

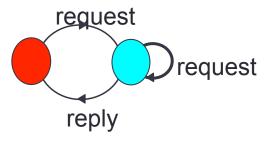
- Extend LTS with an extra set of transitions
  - Required or Must transitions
  - Possible or May transitions



- An LTS L is an implementation of an MTS M if
  - all required behaviour in M is in L, and
  - all behaviour in L is possible in M







## MTS are Sufficiently Expressive

 Modal Transistion Systems can distinguish required behaviour of scenarios, proscribed behaviour from properties and the rest...

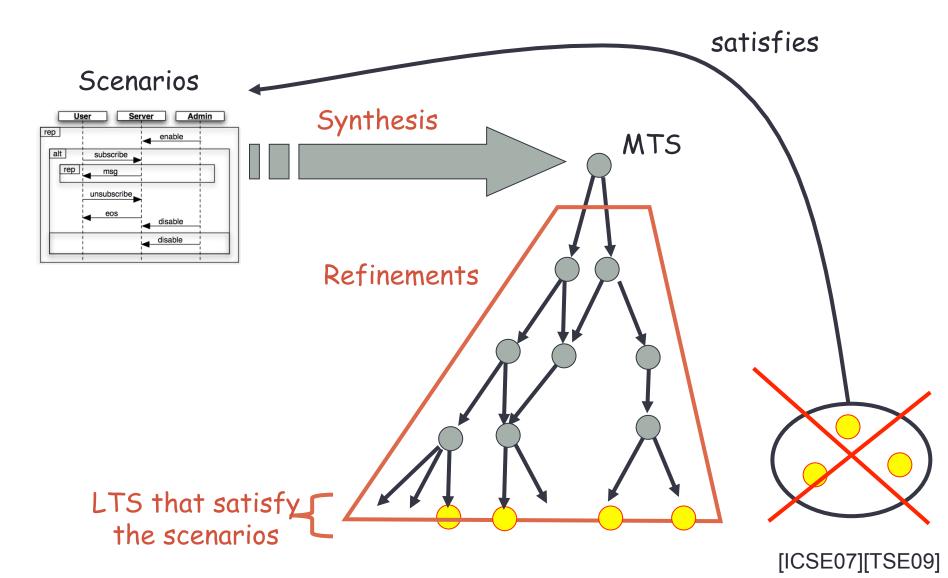


Green = MTS required traces

Yellow = MTS possible traces

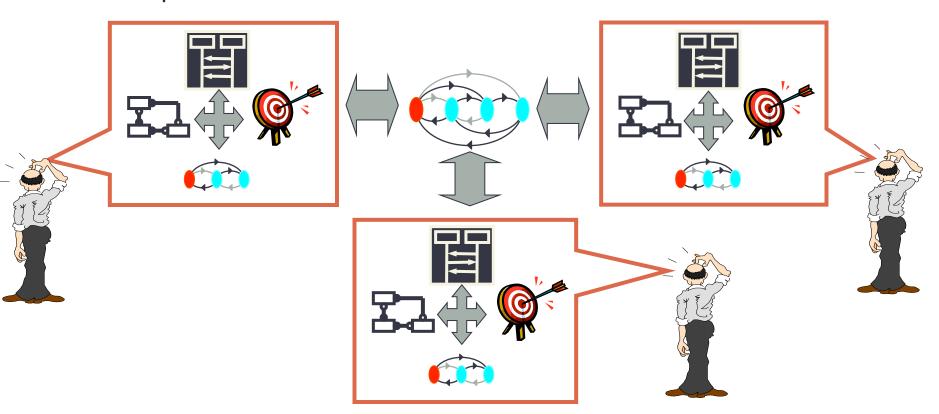
Red = everything else

# Synthesis from Scenarios



# MTS Merging

- Merging MTS resulting from...
  - Heterogeneous notations
  - Multiple stakeholders



#### **Problems**

(D)MTS merge

FSE'11 paper. Language: CSSL

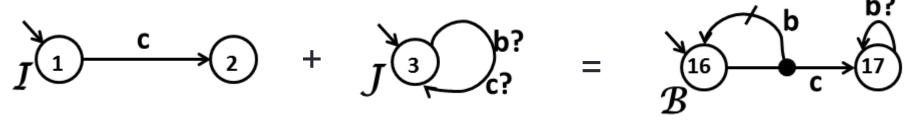
General synthesis of partial models from specs (CSSL?)

Model repair problem

- MTSs over different vocabularies are NOT closed under merge
- What is the 'right' language for capturing properties of behavioural models that come from scenarios?
- This is synthesis w.r.t. safety properties only what about richer behaviours such as liveness? Timing? Probabilities? Hybrid models? Richer metamodels?
- How to "fix" a behavioral model if it has been determined to be incorrect
  - E.g., some of the sensors fail?
  - E.g., new sensors with new parameters/behavior are detected?
  - E.g., testing determined that that the original properties were "a bit" wrong?

# (D)MTS Merge

#### Example:



- Merge of (D)MTSs is defined when they are ...
  - ... Consistent and
  - · ... Compatible
    - each model does not have loops consisting entirely of non-observable operations
    - (Youssef Zaky's masters thesis had a different compatibility condition)
- CONCUR'13 paper forthcoming (with Shoham Ben-David and Sebastian Uchitel)
  - See poster
- Development of DMTSA (on top of MTSA) in progress