

The **B**ehavioral **C**oordination **O**perat**o**r **L**anguage

Gemoc Final Workshop, March 17th, 2016

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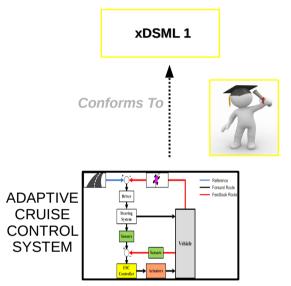






THALES

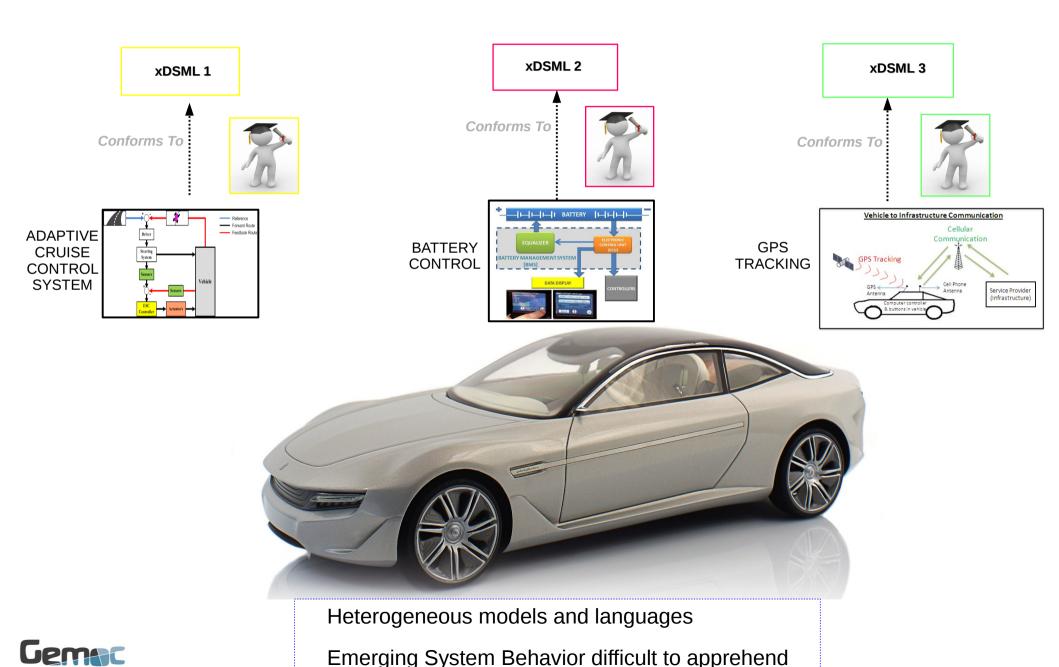
Discrete Time Behavior





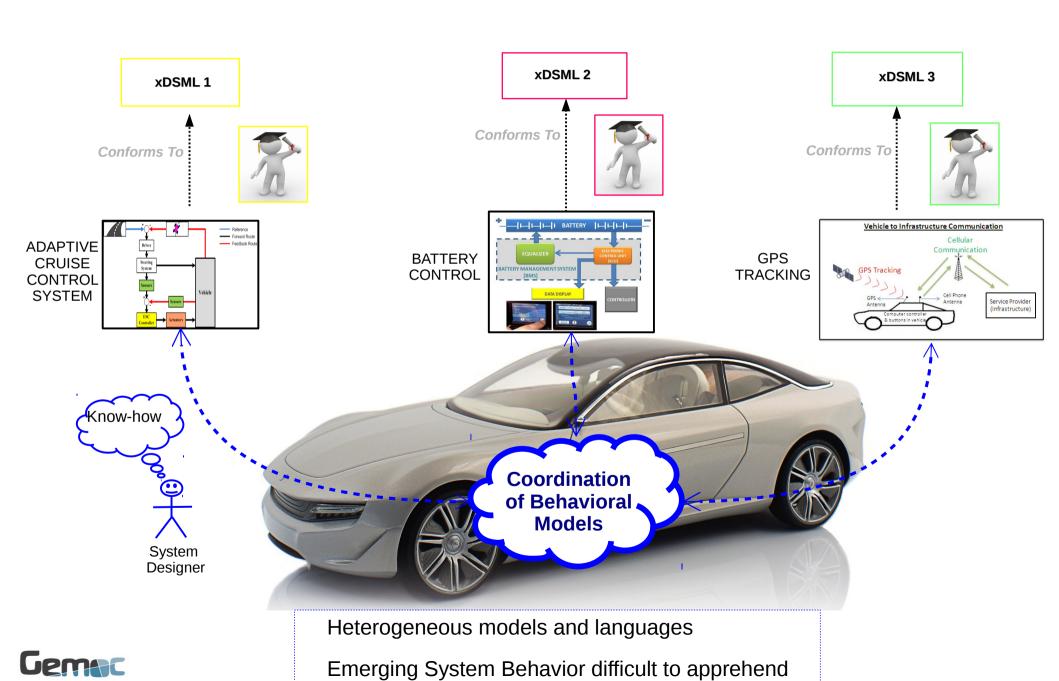


Discrete Time Behavior



Emerging System Behavior difficult to apprehend

Discrete Time Behavior



Outline

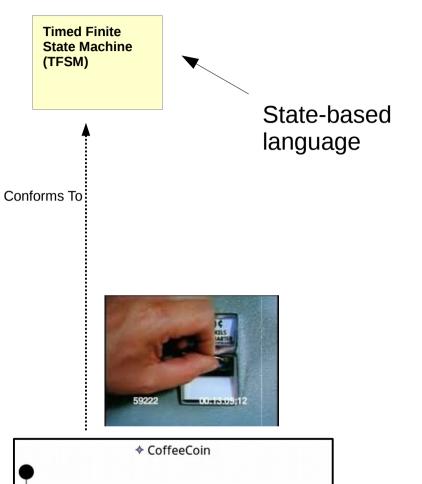
- State of the Art:
 - Coordination Languages and ADLs
 - Coordination Frameworks

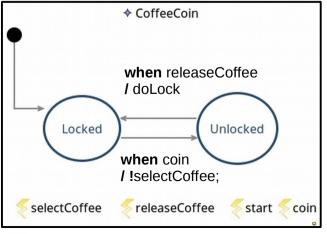
- Our proposal:
 - The **B**ehavioral **C**oordination **O**perator **L**anguage

Conclusion

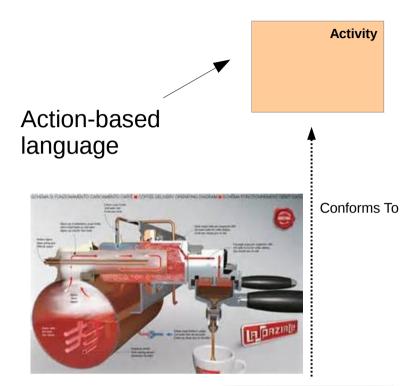


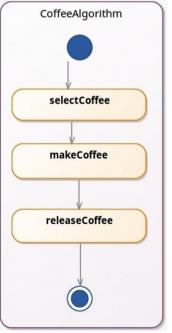
Running Example: the Coffee Machine 6



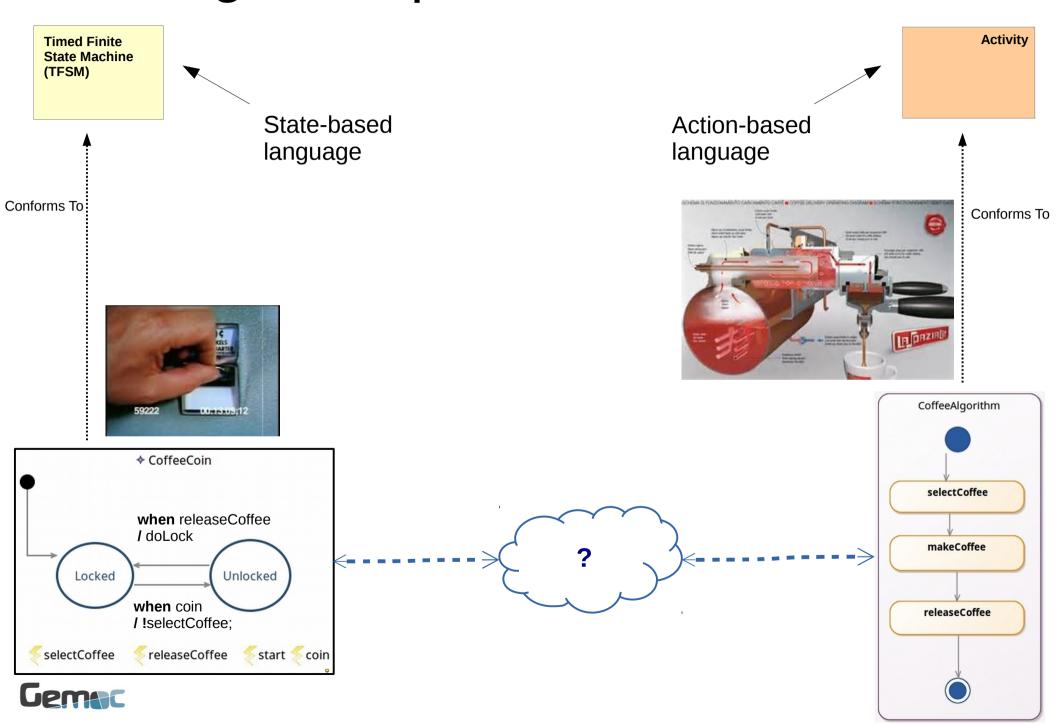




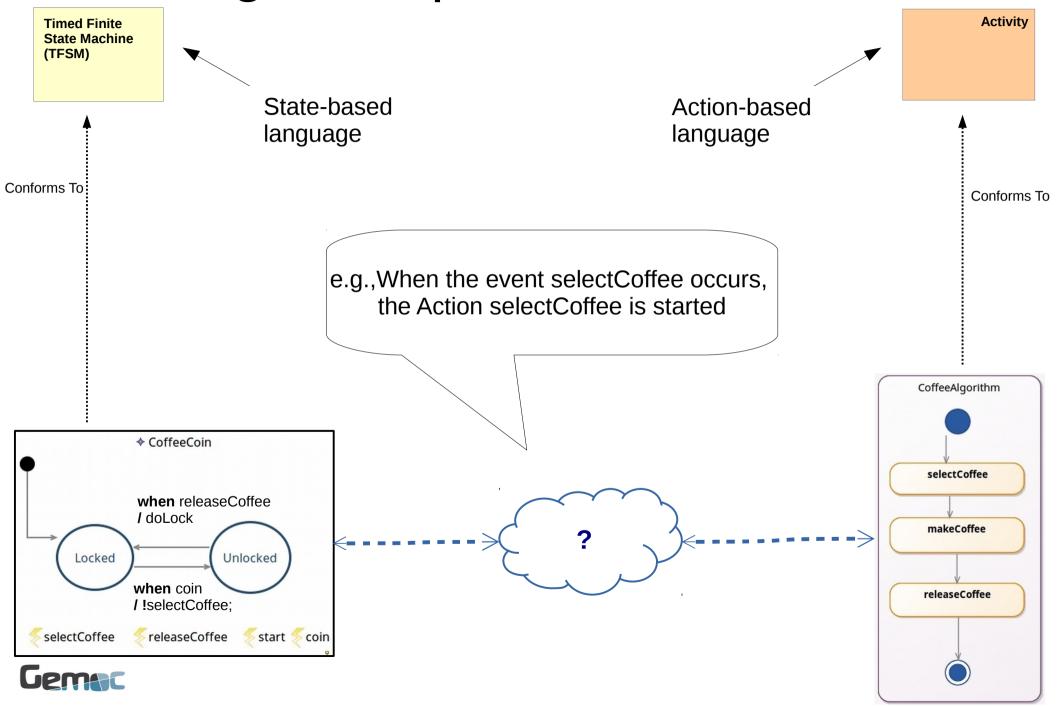


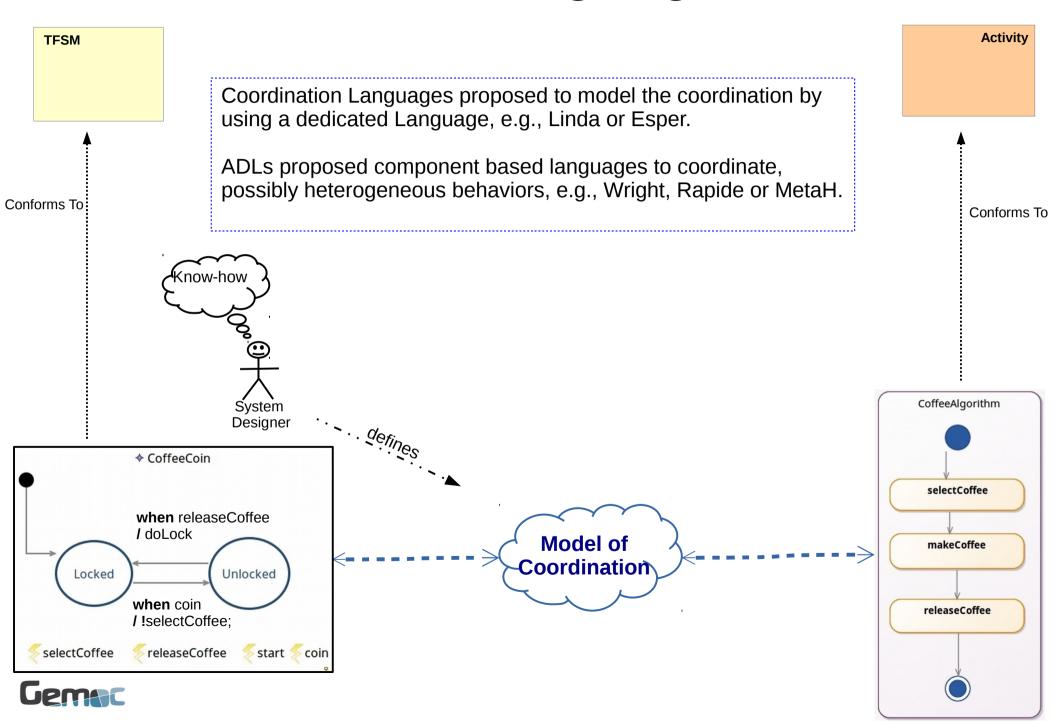


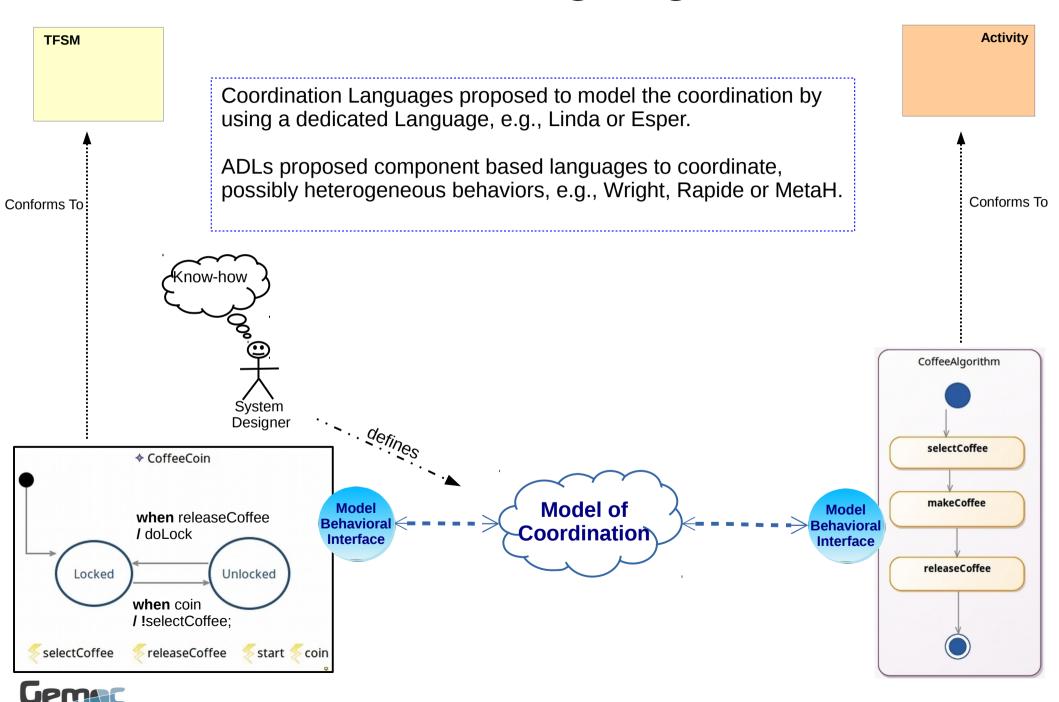
Running Example: the Coffee Machine⁷

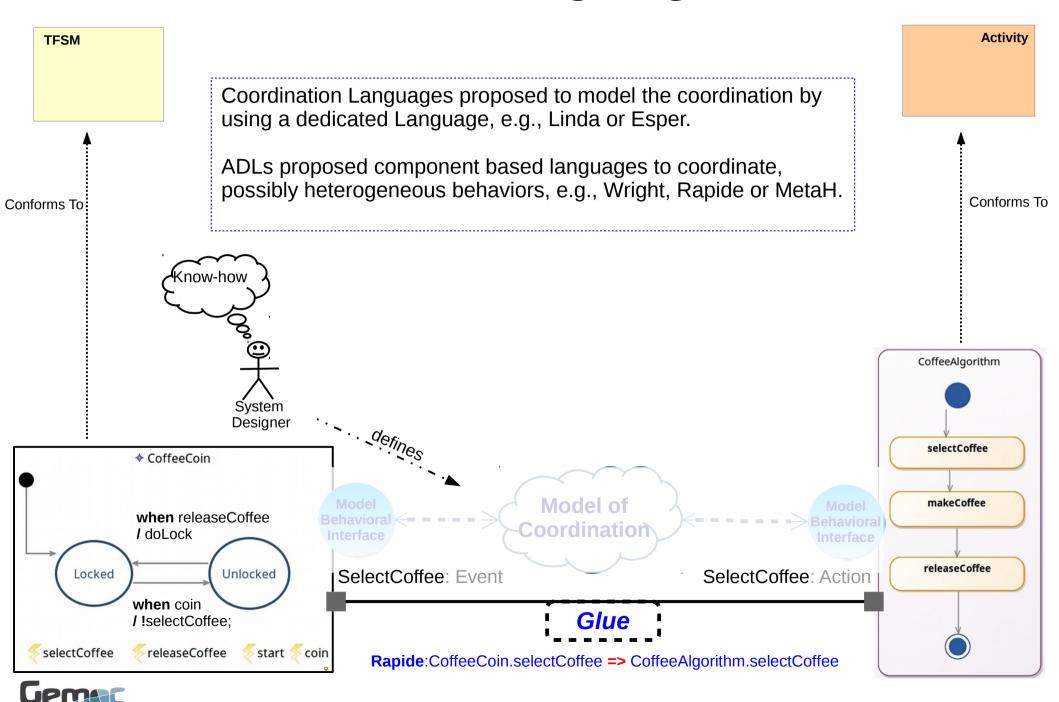


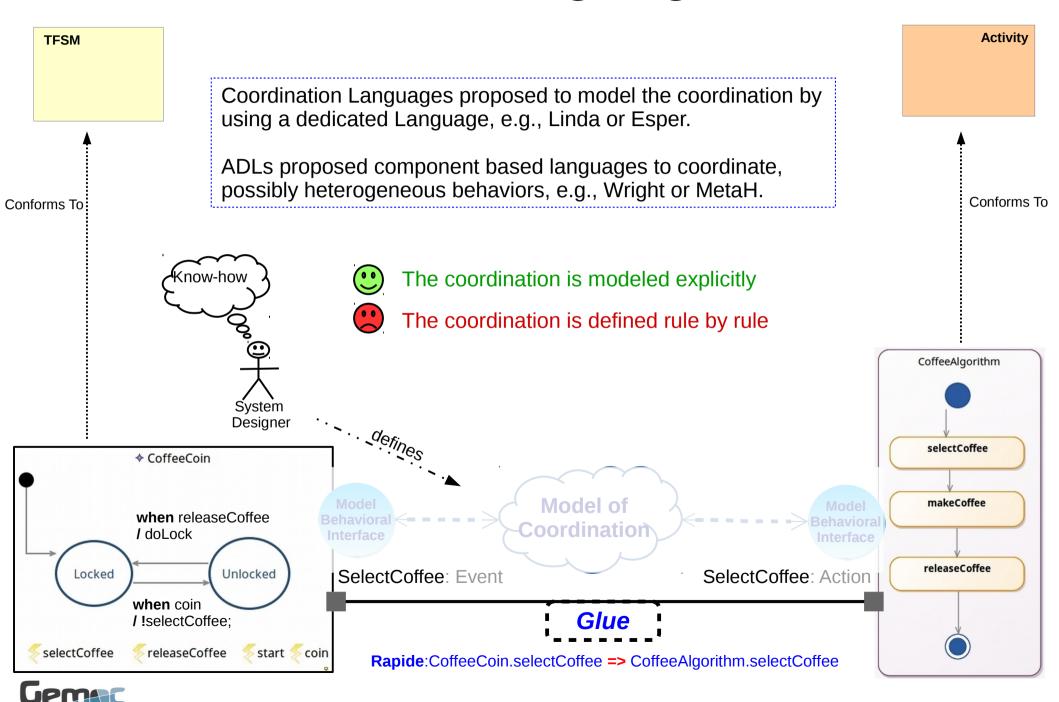
Running Example: the Coffee Machine



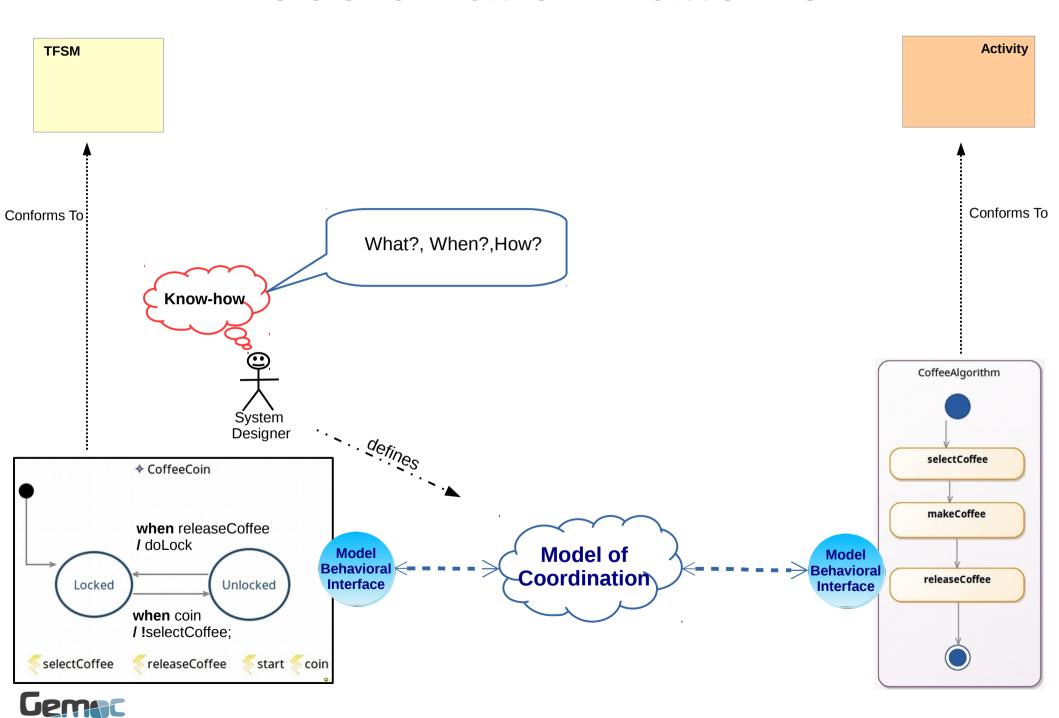


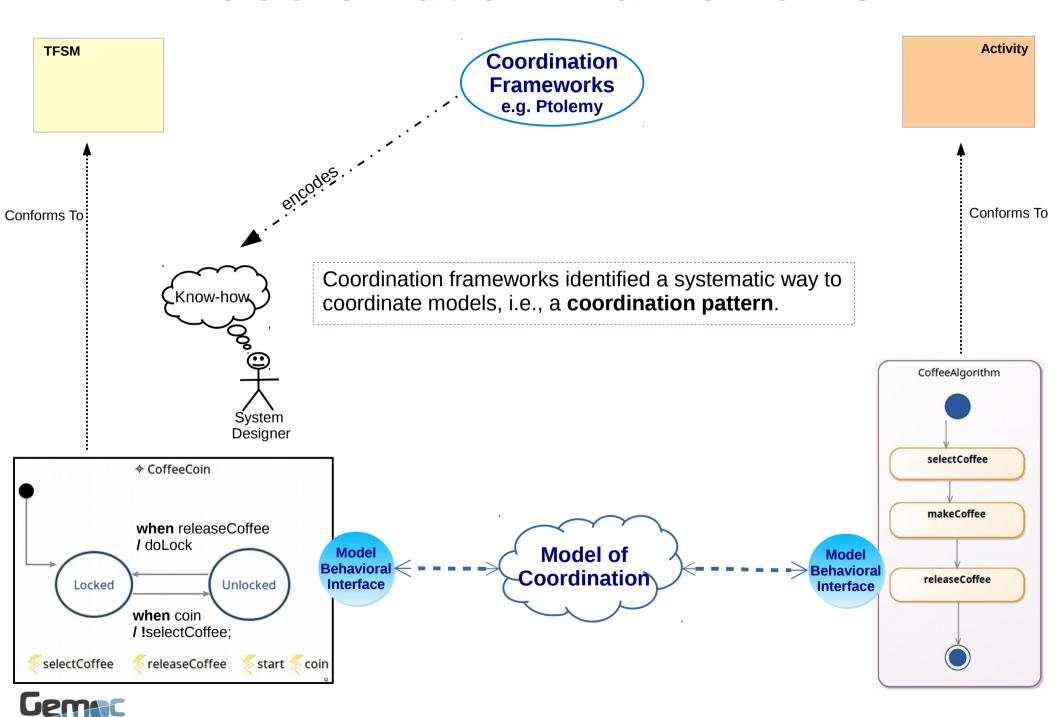


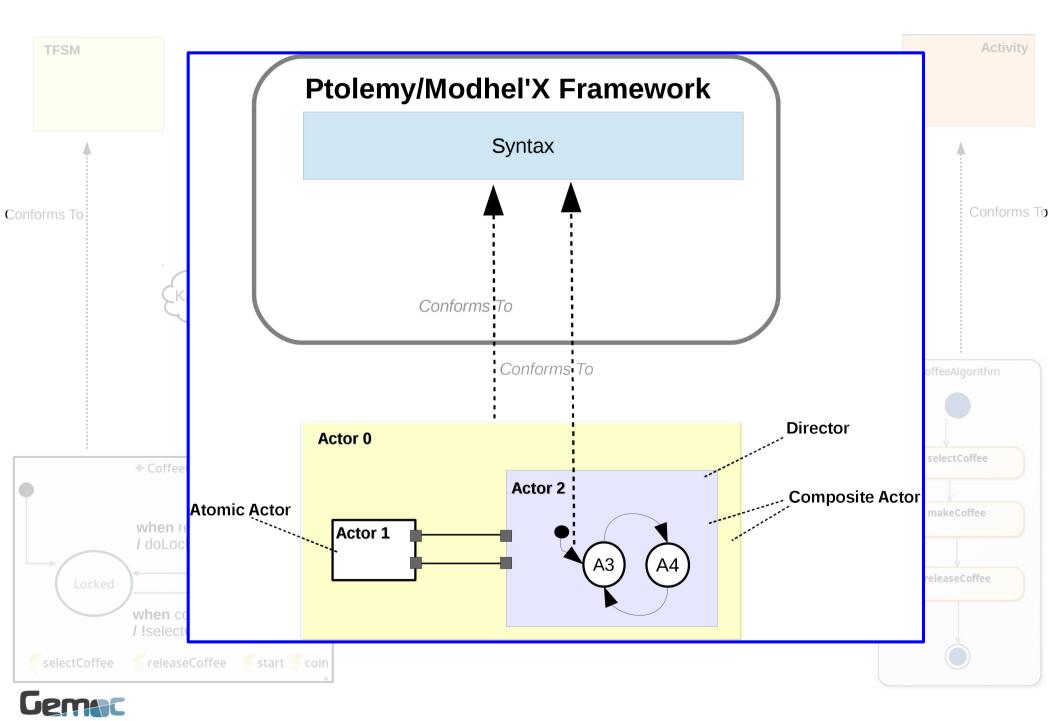


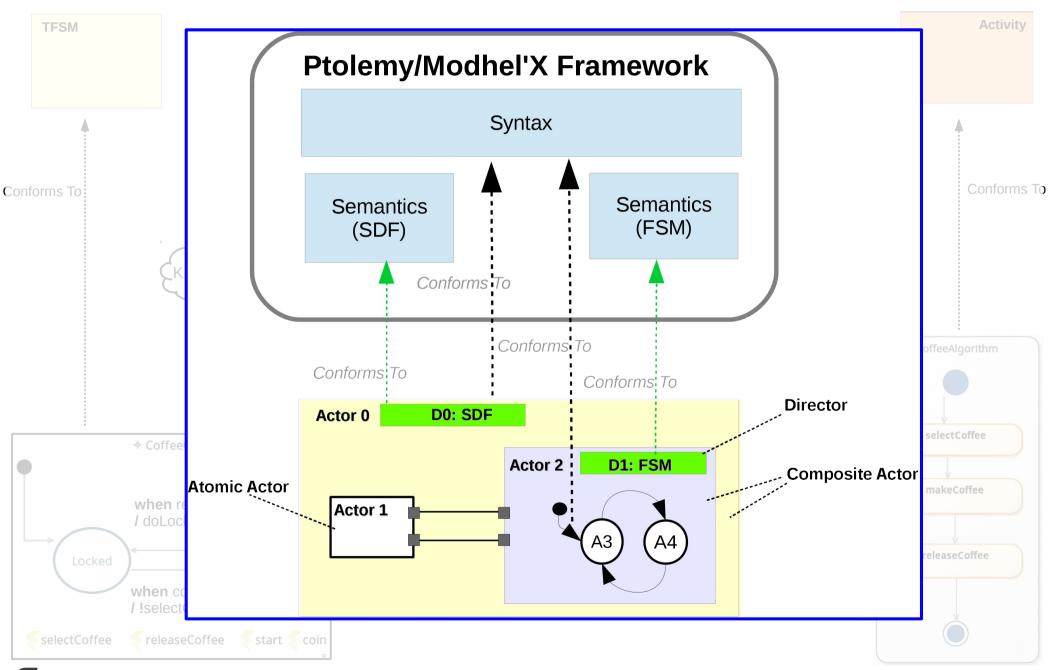


Coordination Patterns

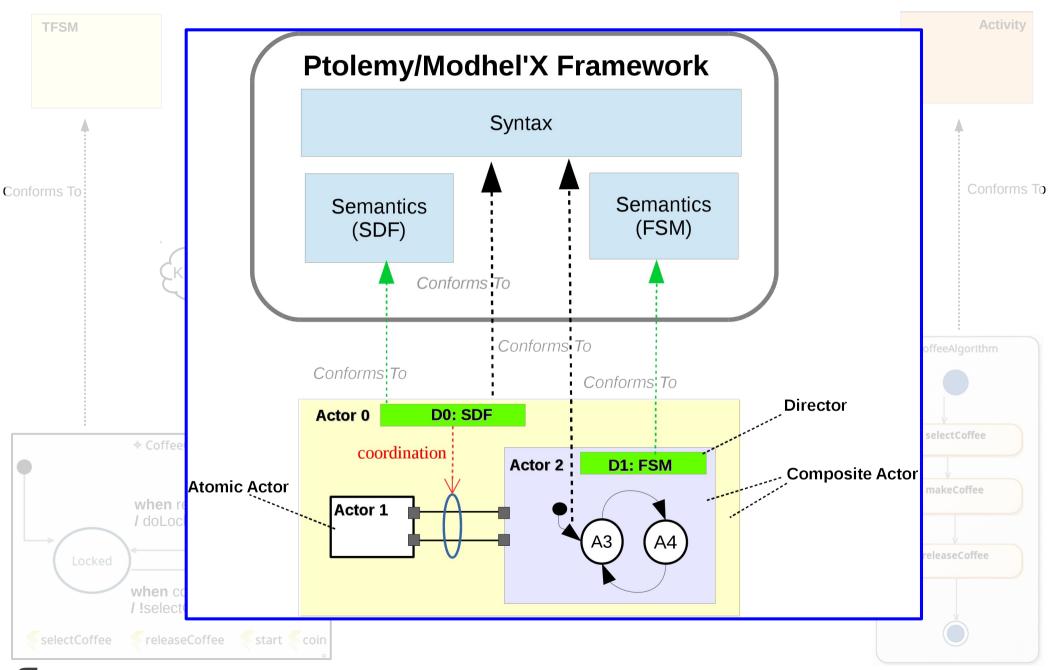




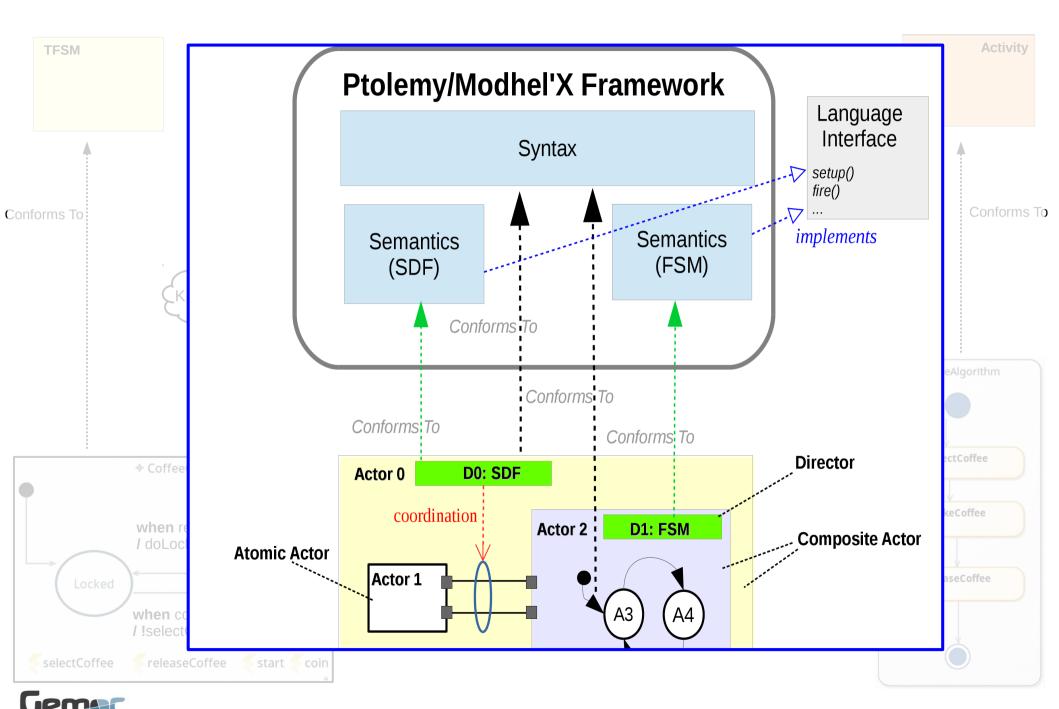


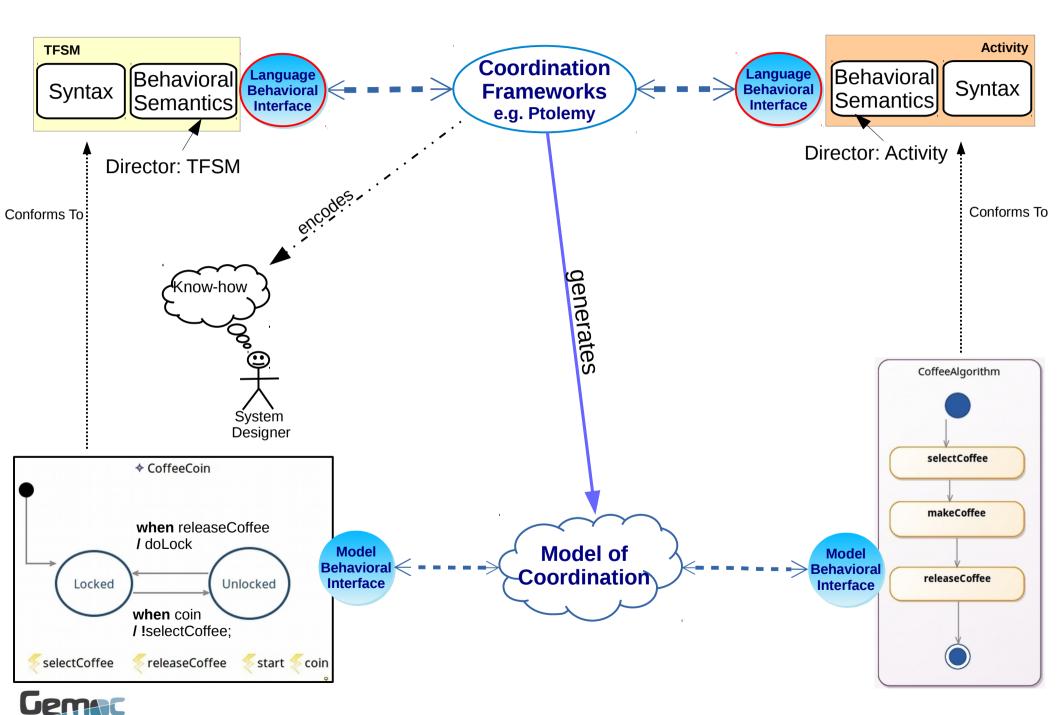


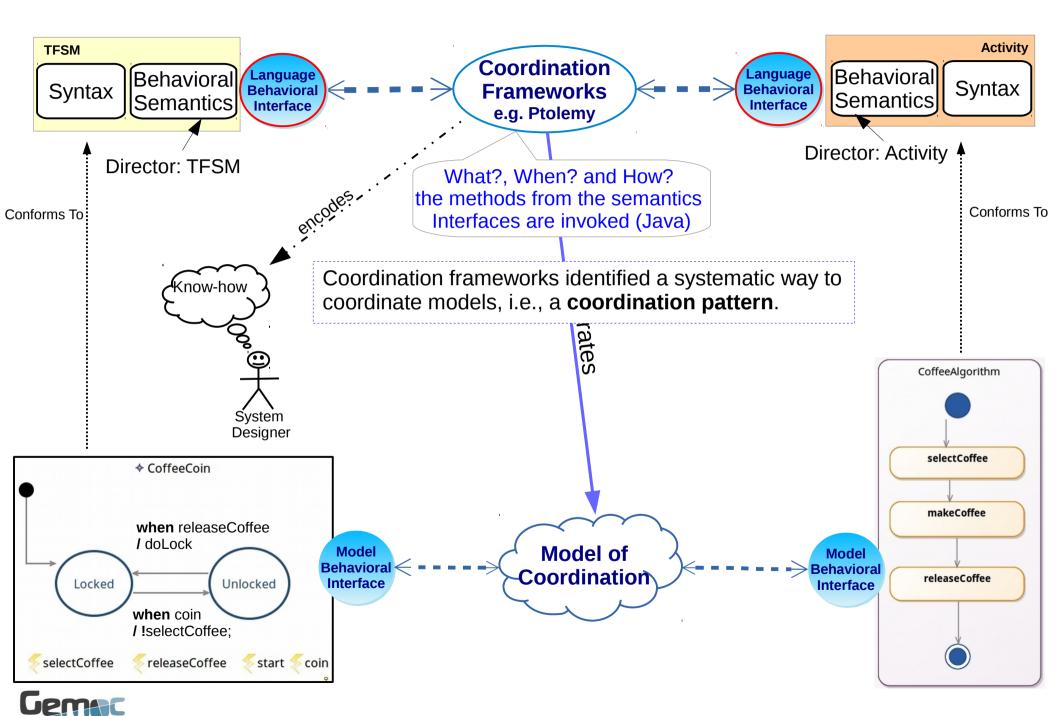


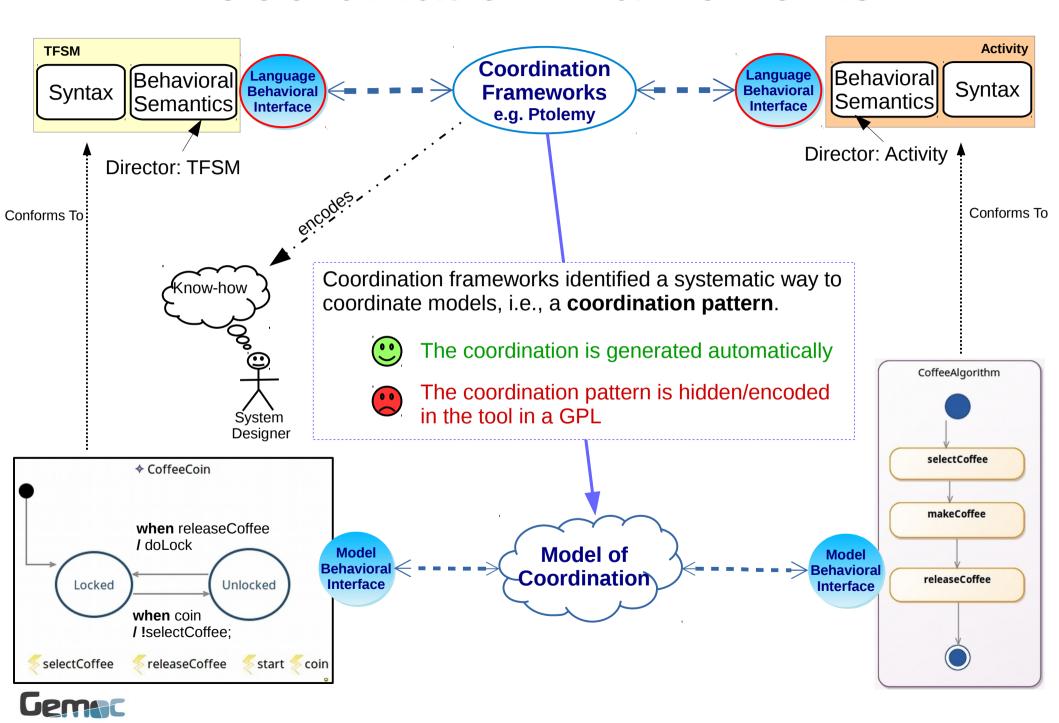












Take-Away Lessons

- Coordination Languages & ADLs:
 - The coordination is modeled explicitly
 - The coordination is defined rule by rule

- Coordination Frameworks:
 - The coordination is generated automatically based on a coordination pattern
 - The coordination pattern is hidden/encoded in the tool in a GPL



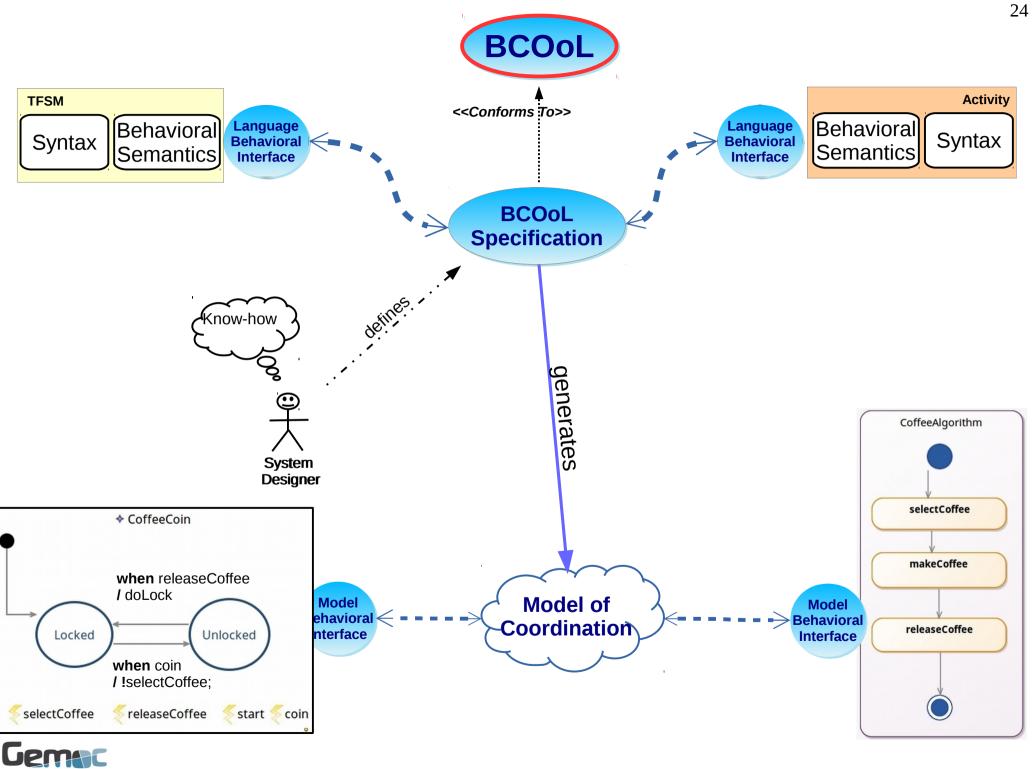
Outline

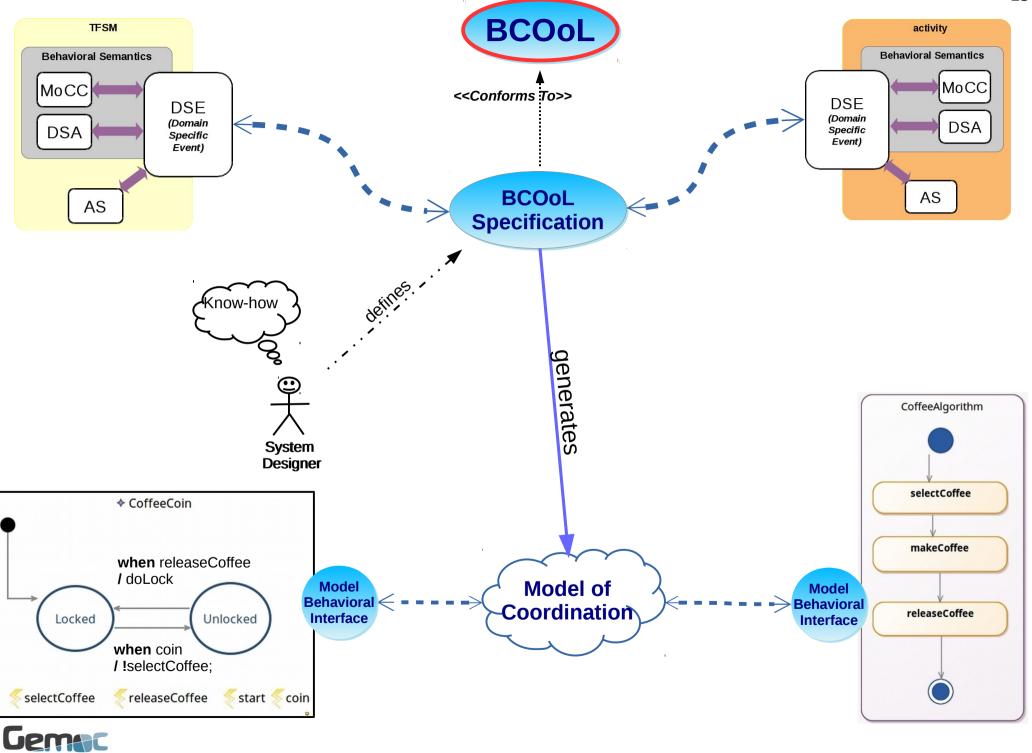
- State of the Art
 - Coordination Languages
 - Coordination Frameworks

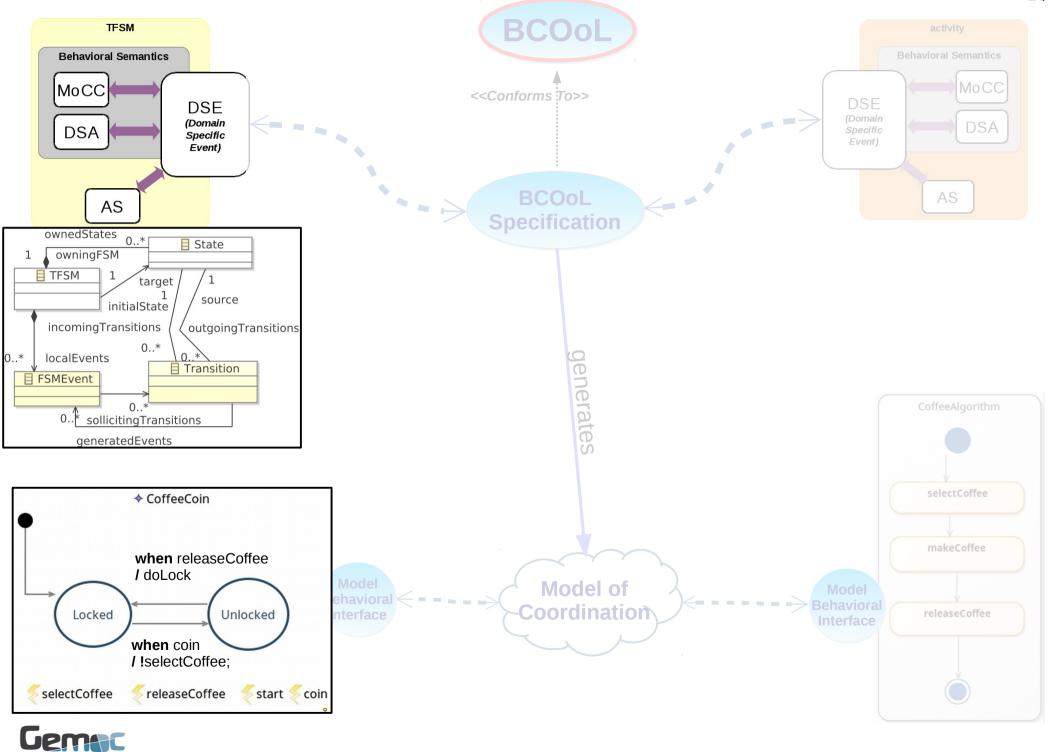
- Our proposal:
 - The <u>Behavioral Coordination Operator Language</u>

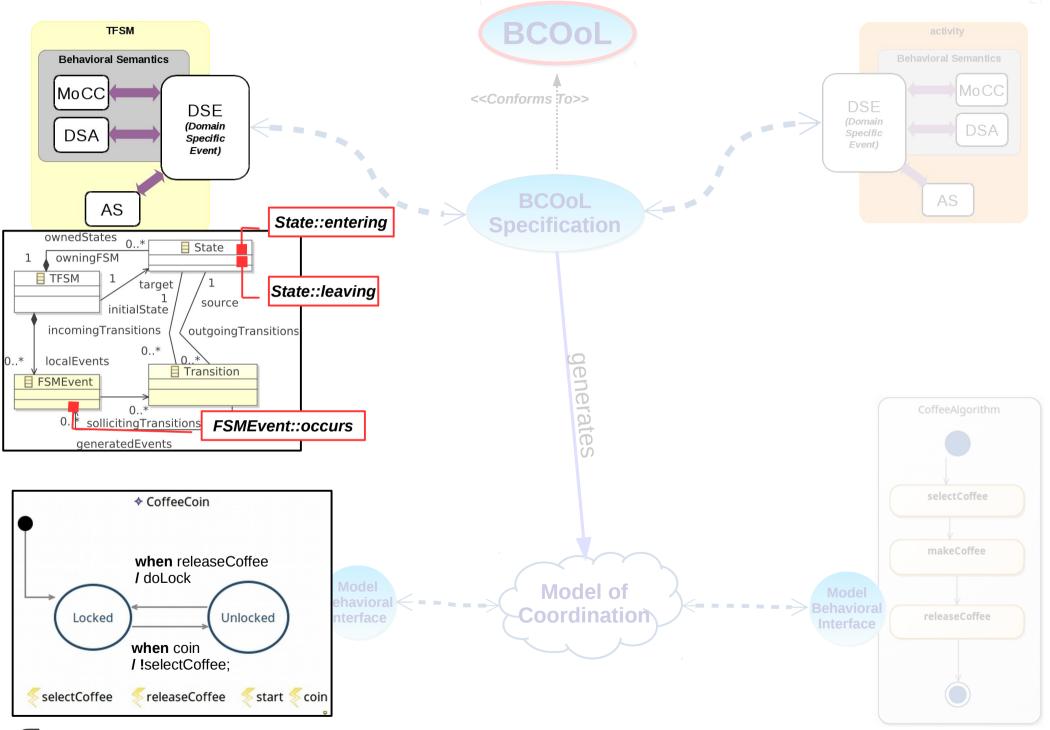
Conclusion



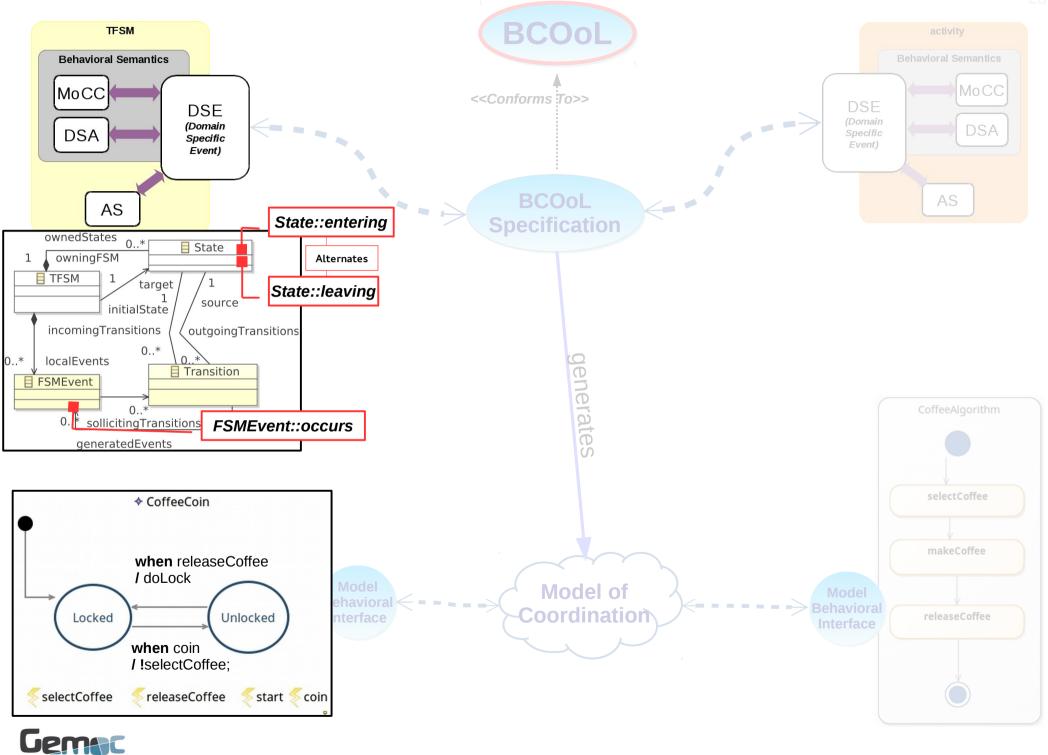


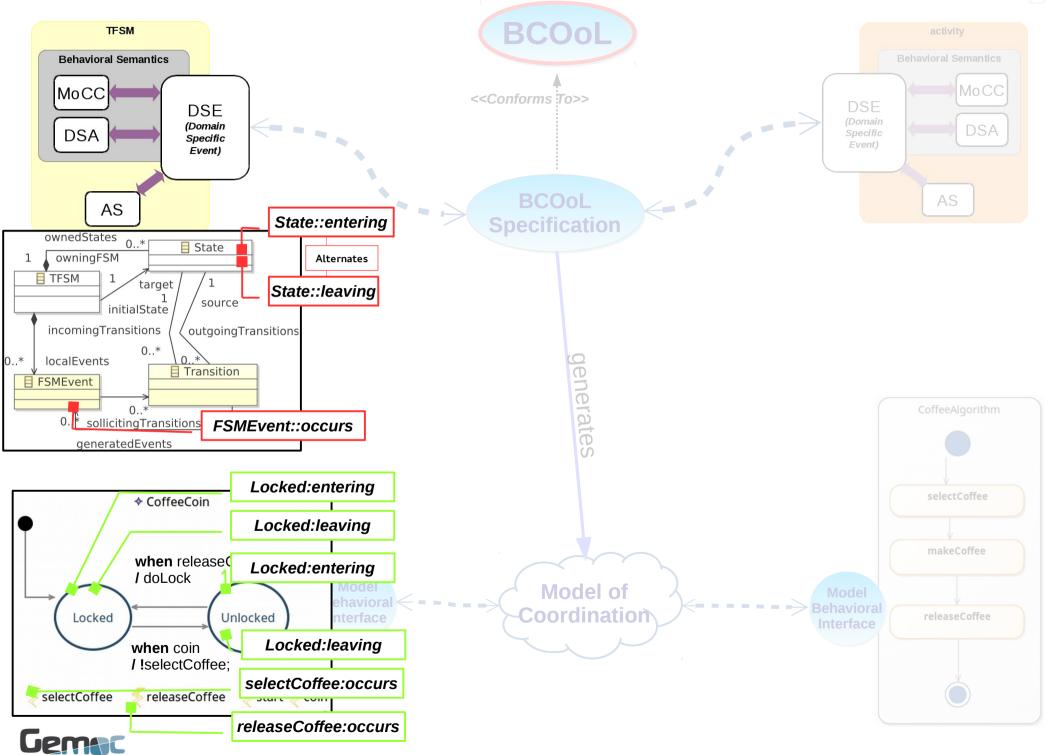


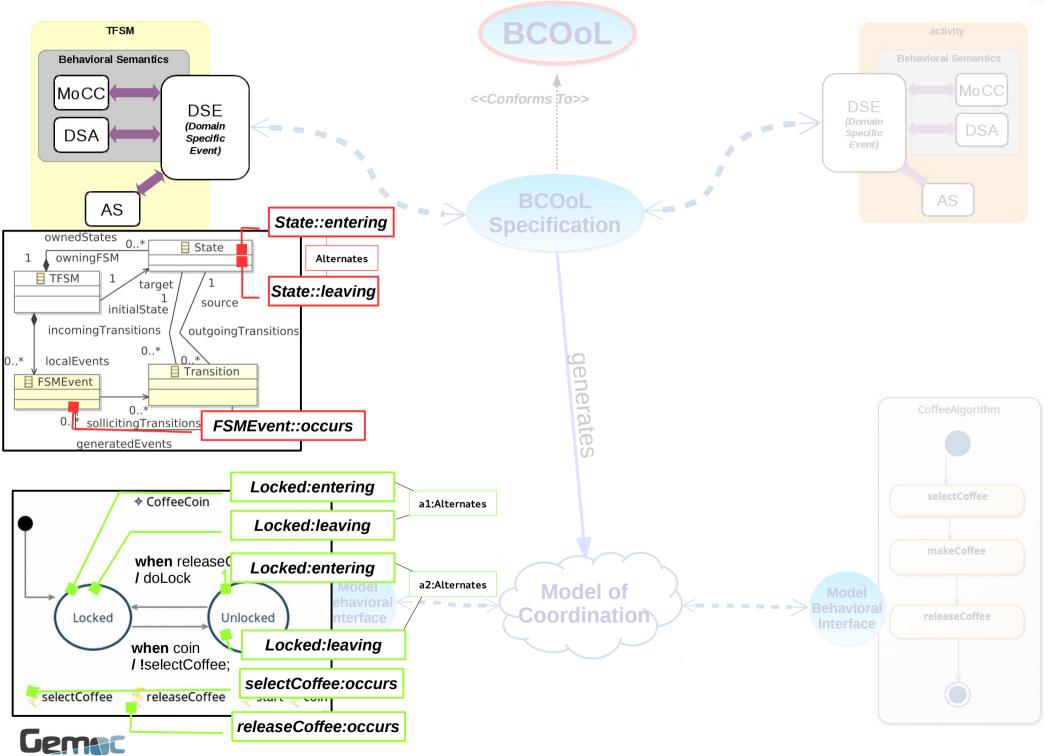


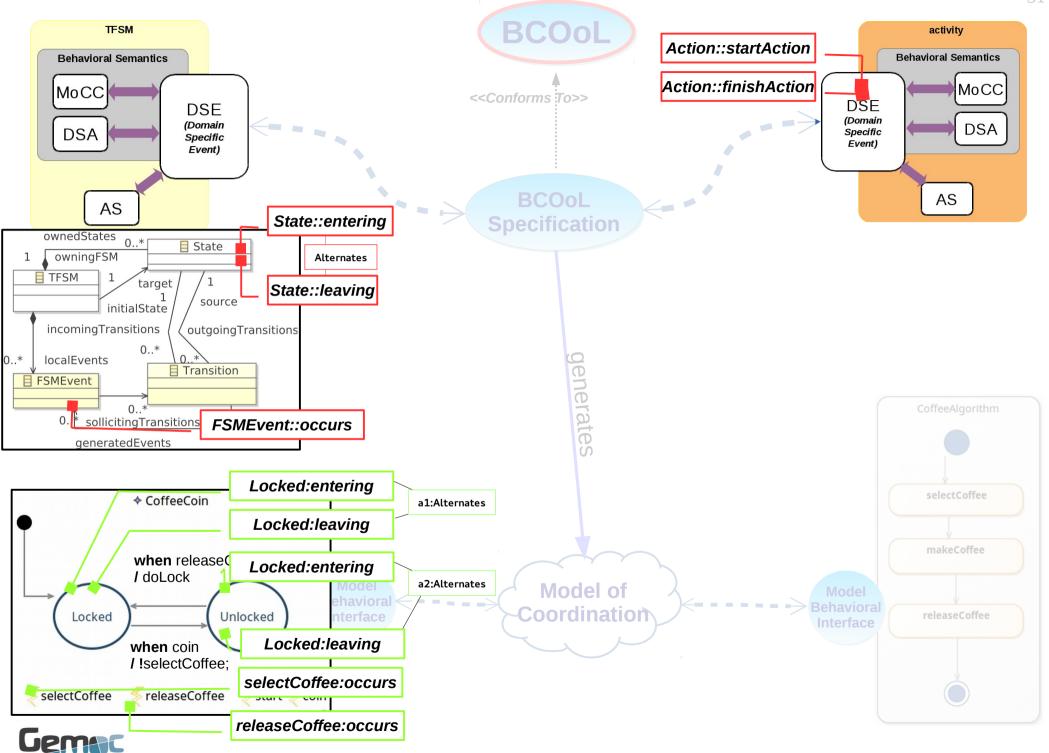


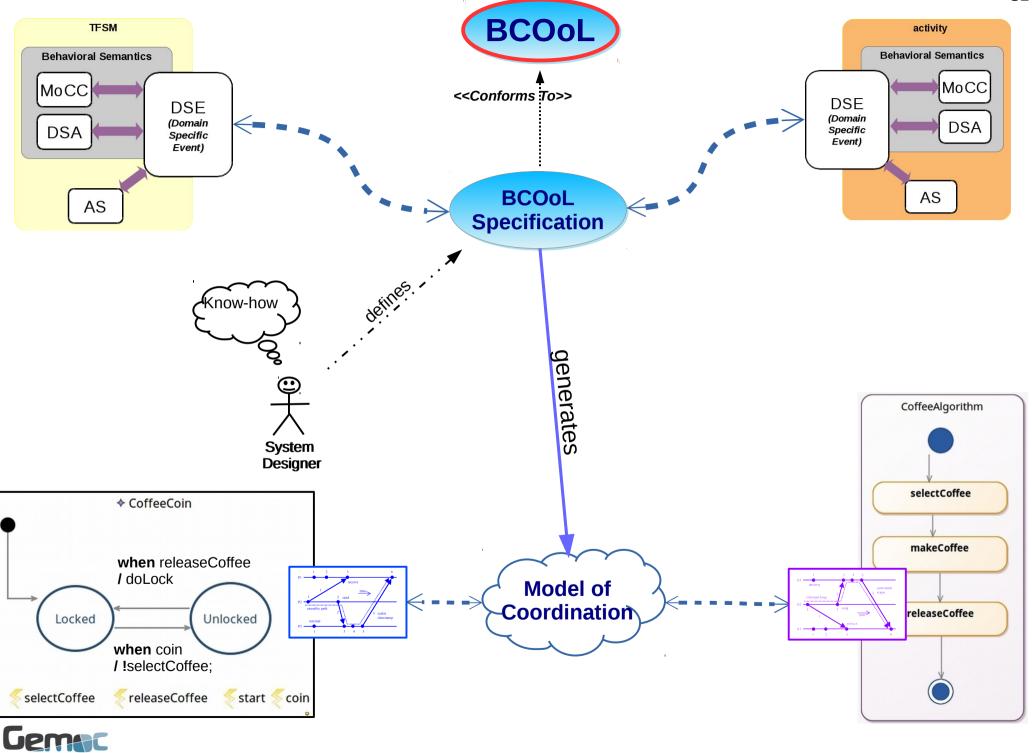
Gemac

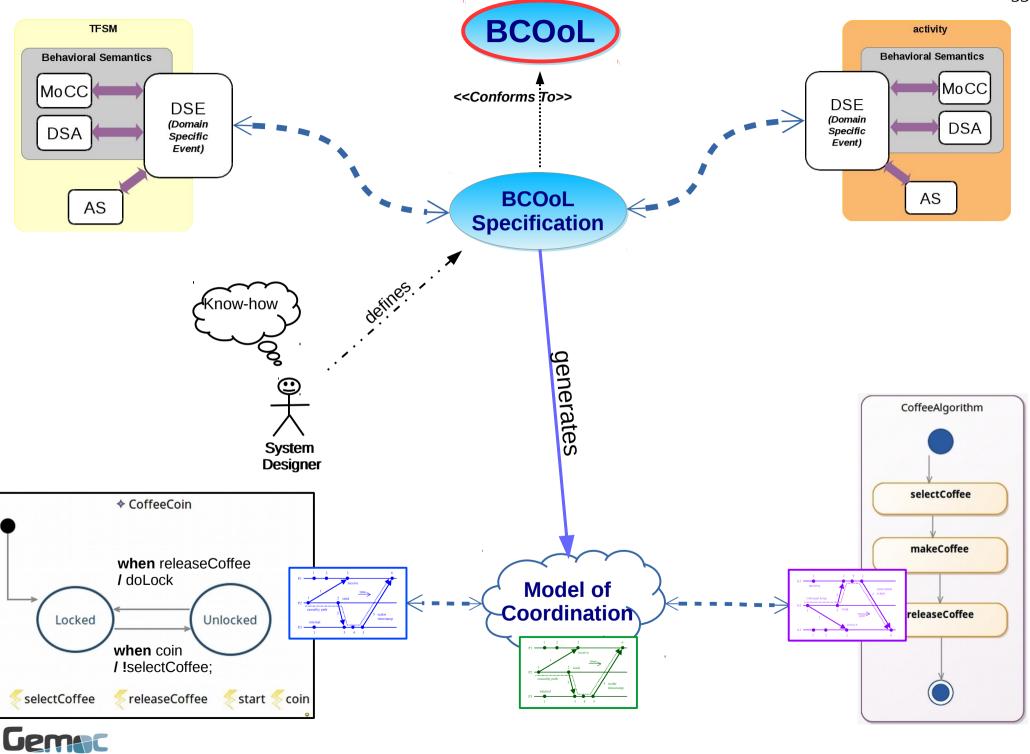


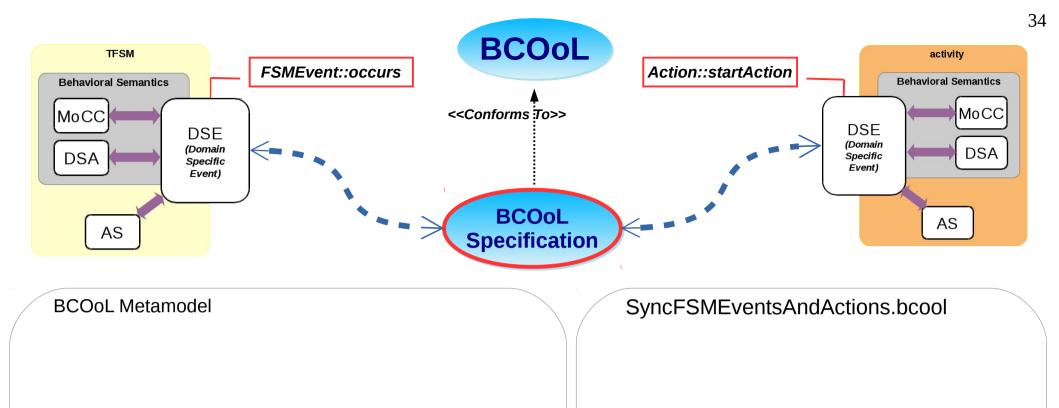




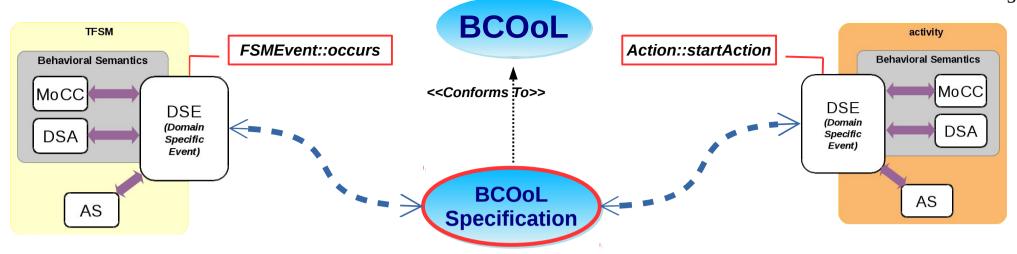


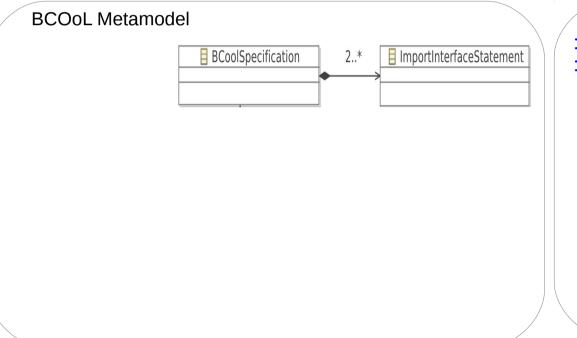








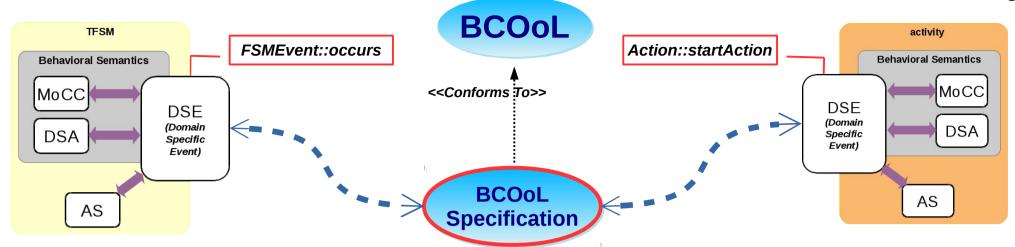


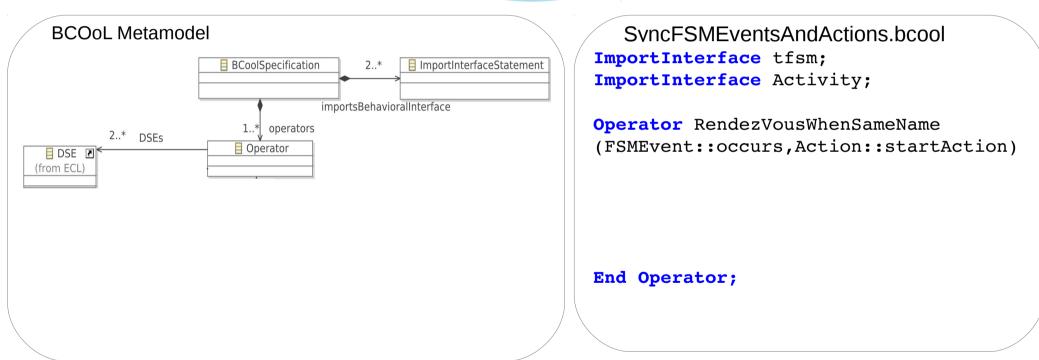


SyncFSMEventsAndActions.bcool

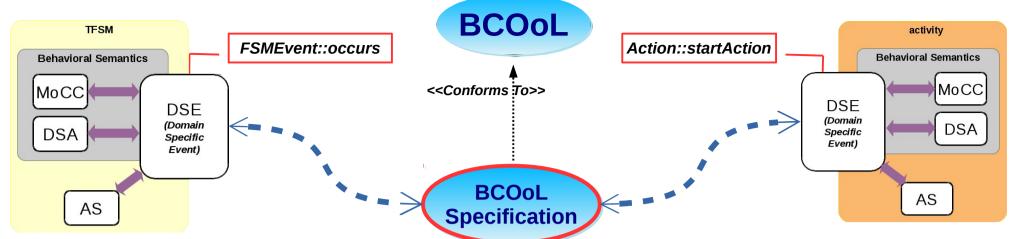
ImportInterface tfsm;
ImportInterface Activity;

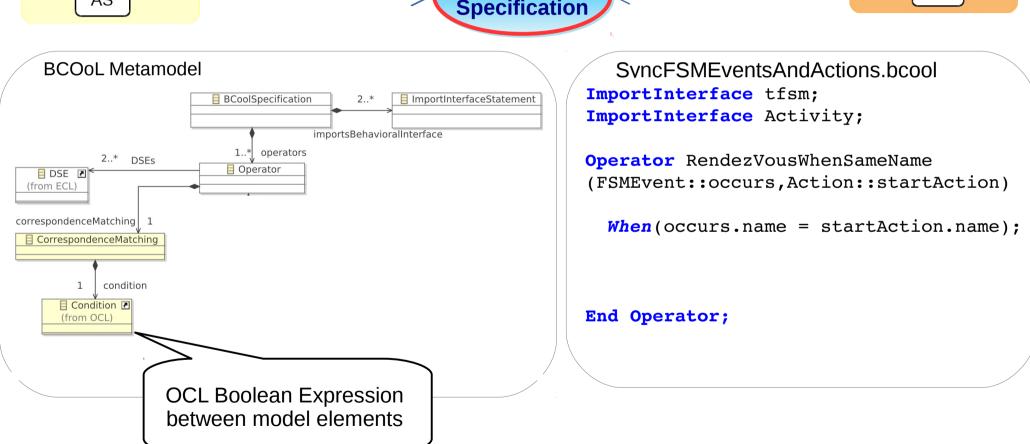




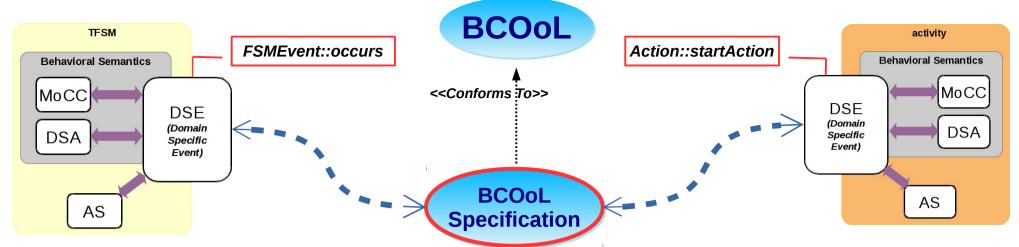


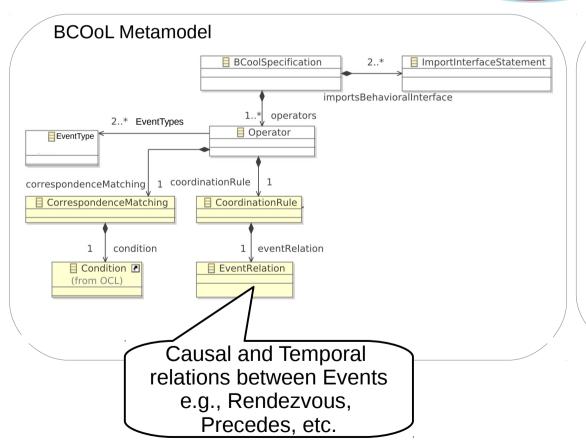












SyncFSMEventsAndActions.bcool

ImportInterface tfsm;
ImportInterface Activity;

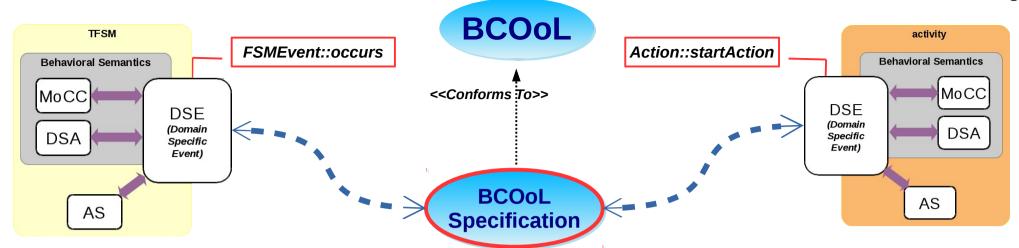
Operator RendezVousWhenSameName
(FSMEvent::occurs,Action::startAction)

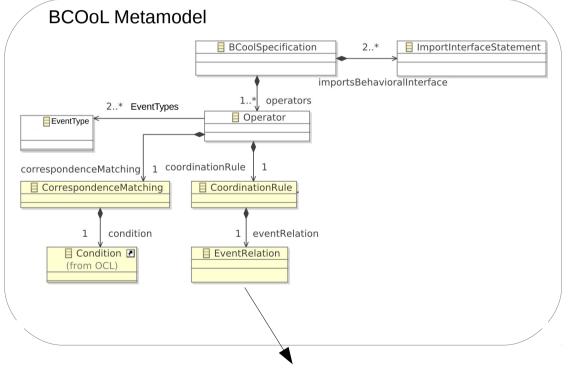
When(occurs.name = startAction.name);

CoordinationRule:

RendezVous (occurs, startAction)
End Operator;







SyncFSMEventsAndActions.bcool

ImportInterface tfsm;
ImportInterface Activity;

Operator RendezVousWhenSameName
(FSMEvent::occurs,Action::startAction)

When(occurs.name = startAction.name);

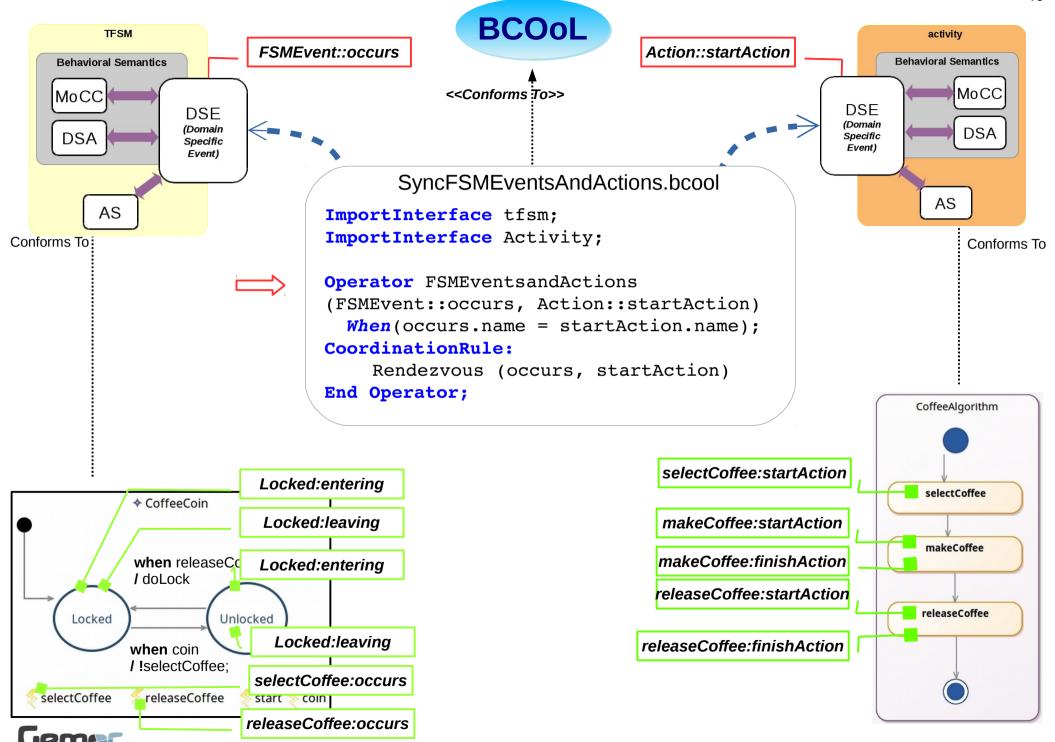
CoordinationRule:

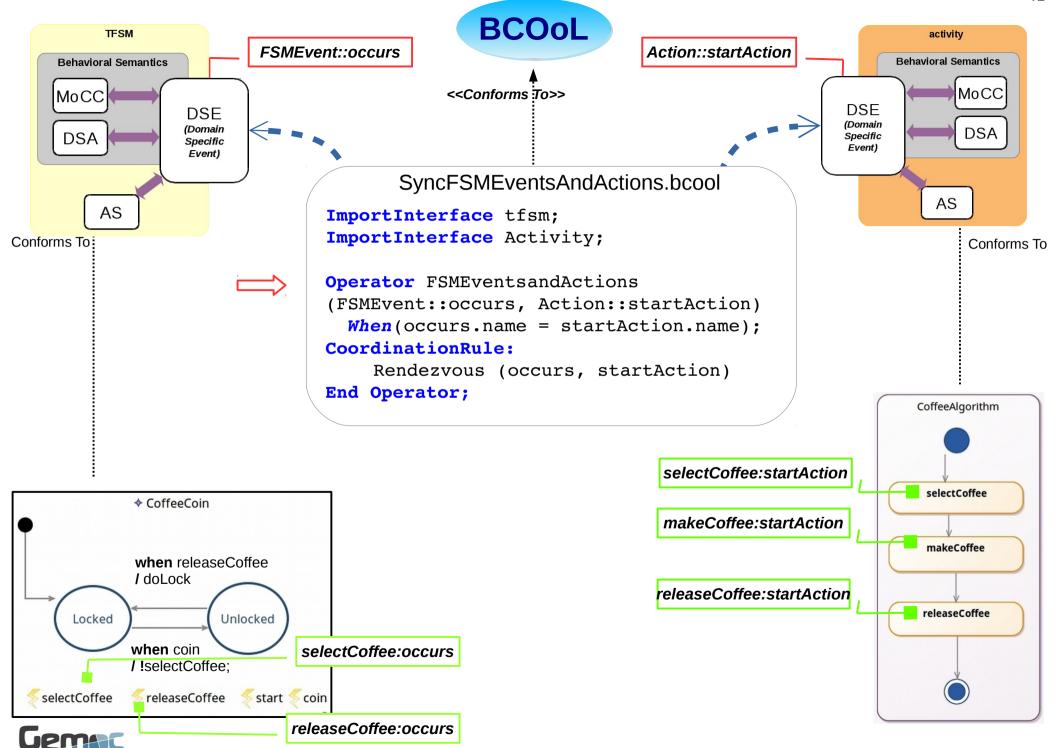
RendezVous (occurs, startAction)
End Operator;

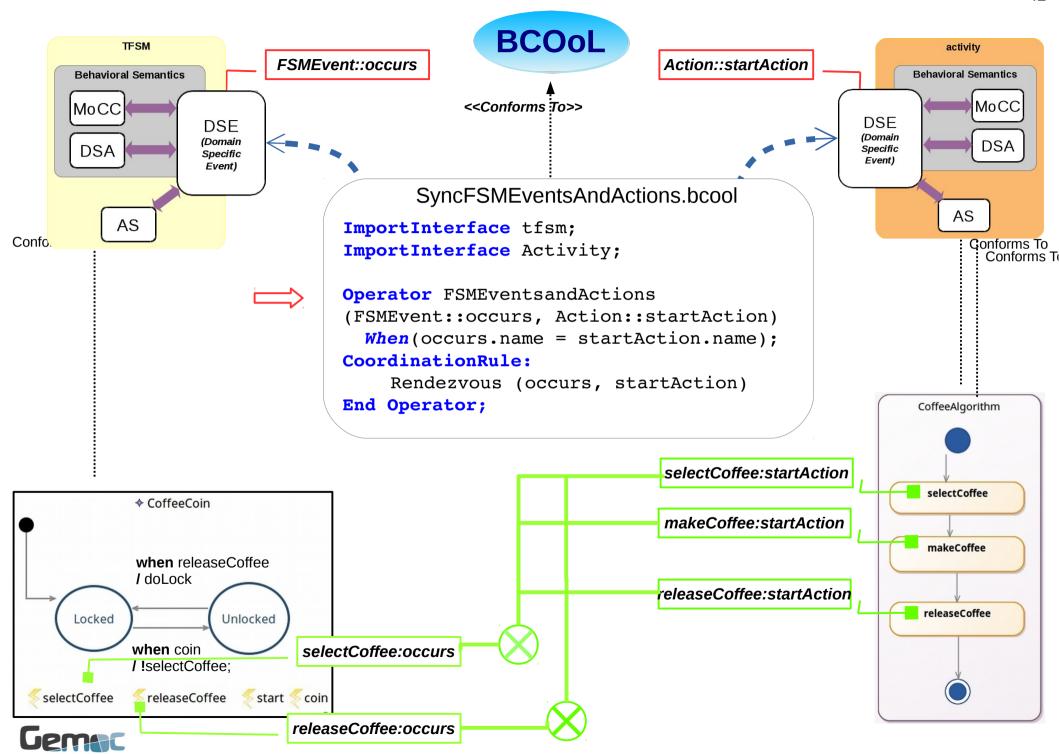
Defined in MoCCML

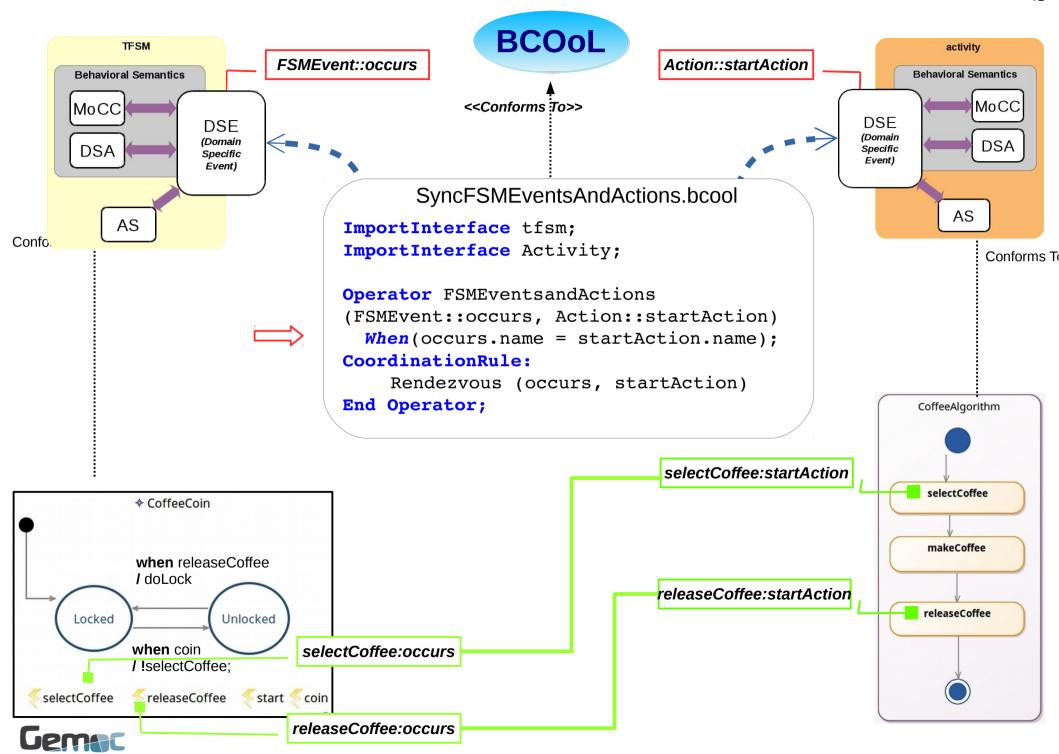
(Model of Concurrency and Communication Modeling Language)

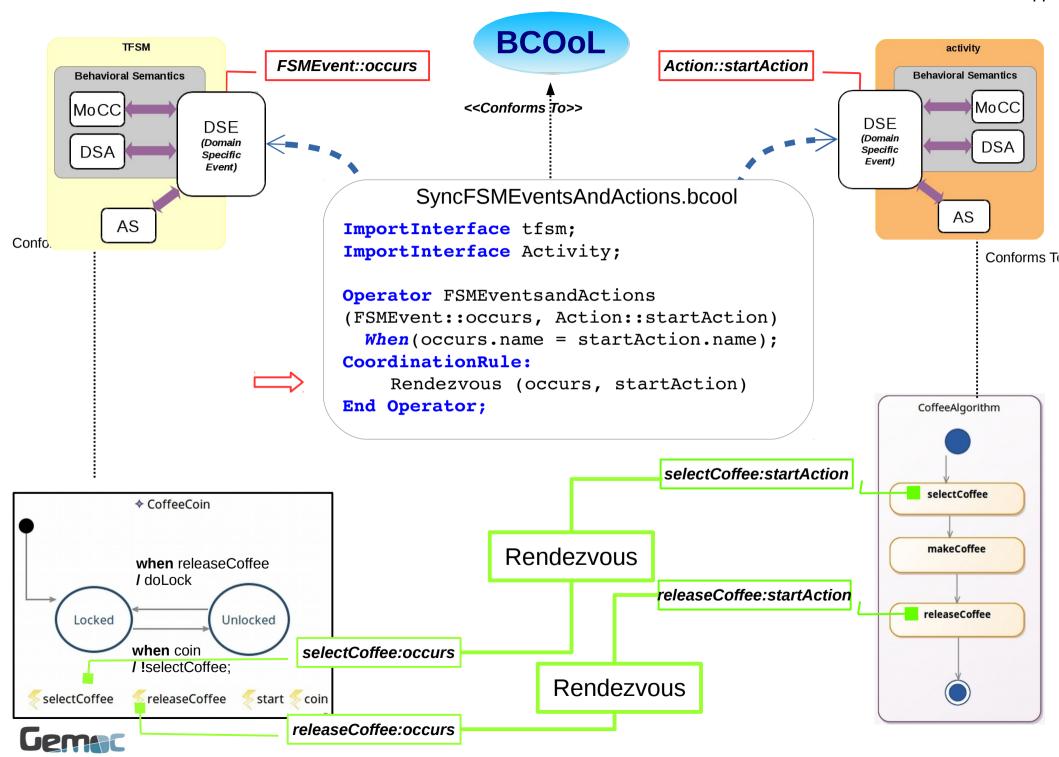


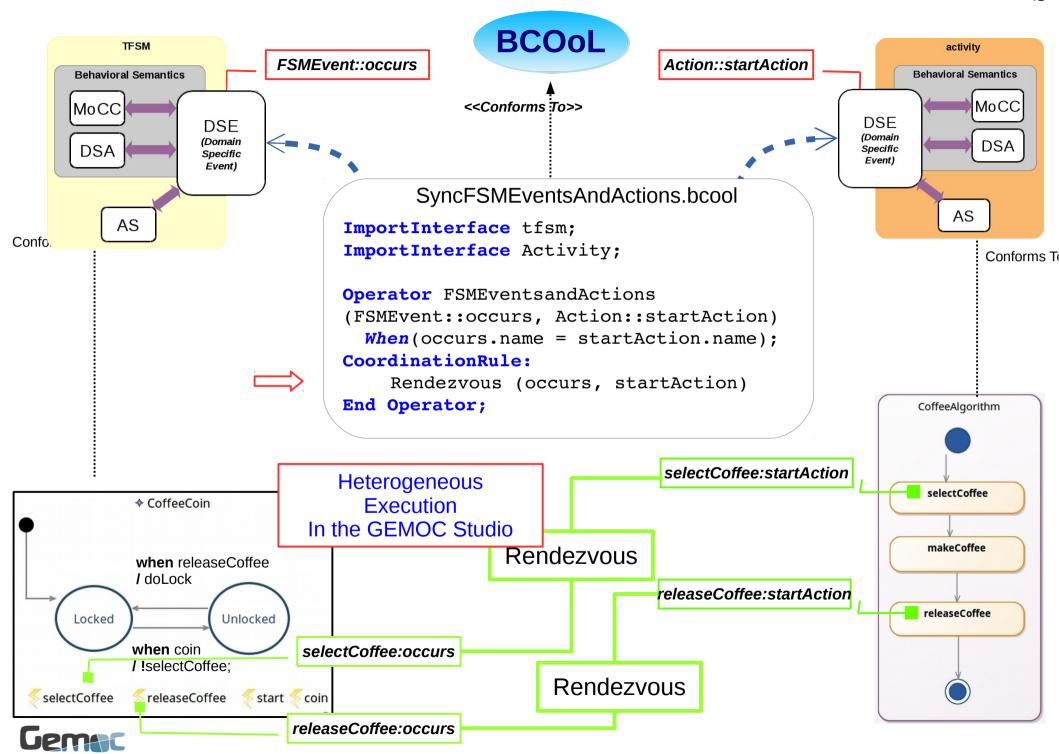




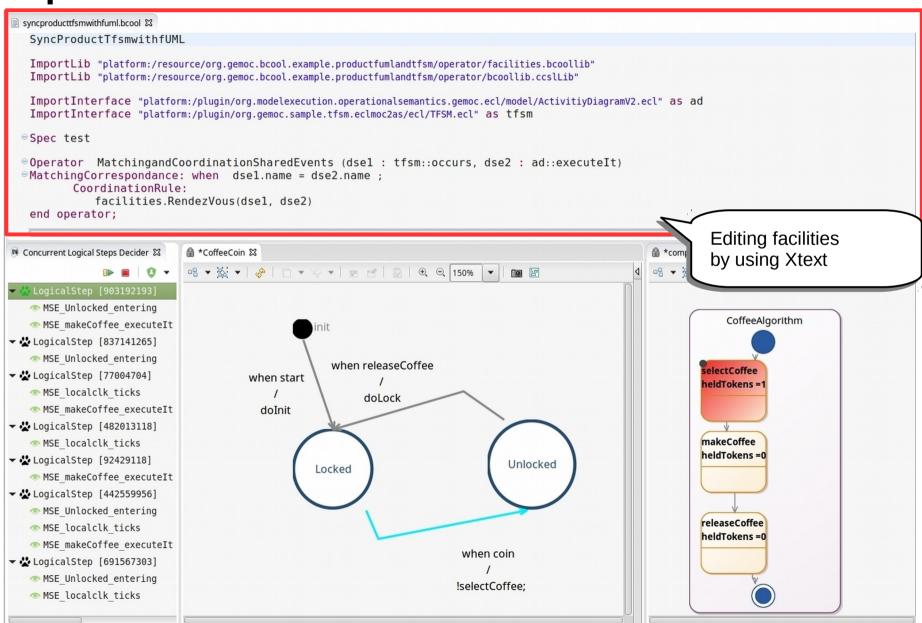






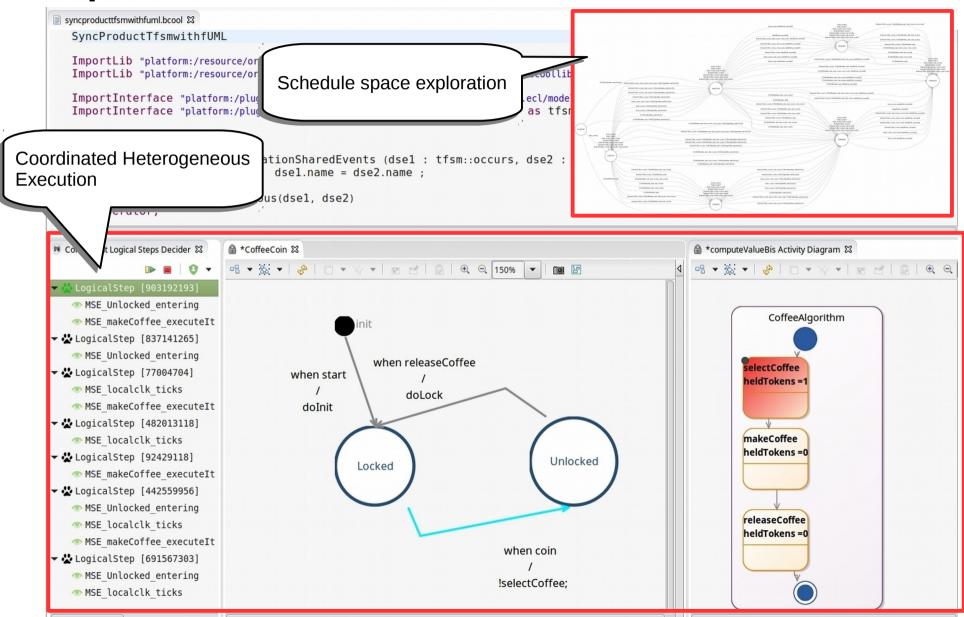


Implemented into the GEMOC studio





Implemented into the GEMOC studio





Conclusion

- BCOoL is a dedicated metalanguage to capture coordination patterns.
- It automates the coordination of models by relying on a formal language.
- It is associated to the GEMOC language/modeling workbench to execute and analyze the coordinated system.
- → Future work:
 - Using the explicit coordination to generate master on co-simulation bus
 - Understanding the interconnection with physical model (continuous time)





Thanks

http://timesquare.inria.fr/BCOoL

http://gemoc.org/ins



