

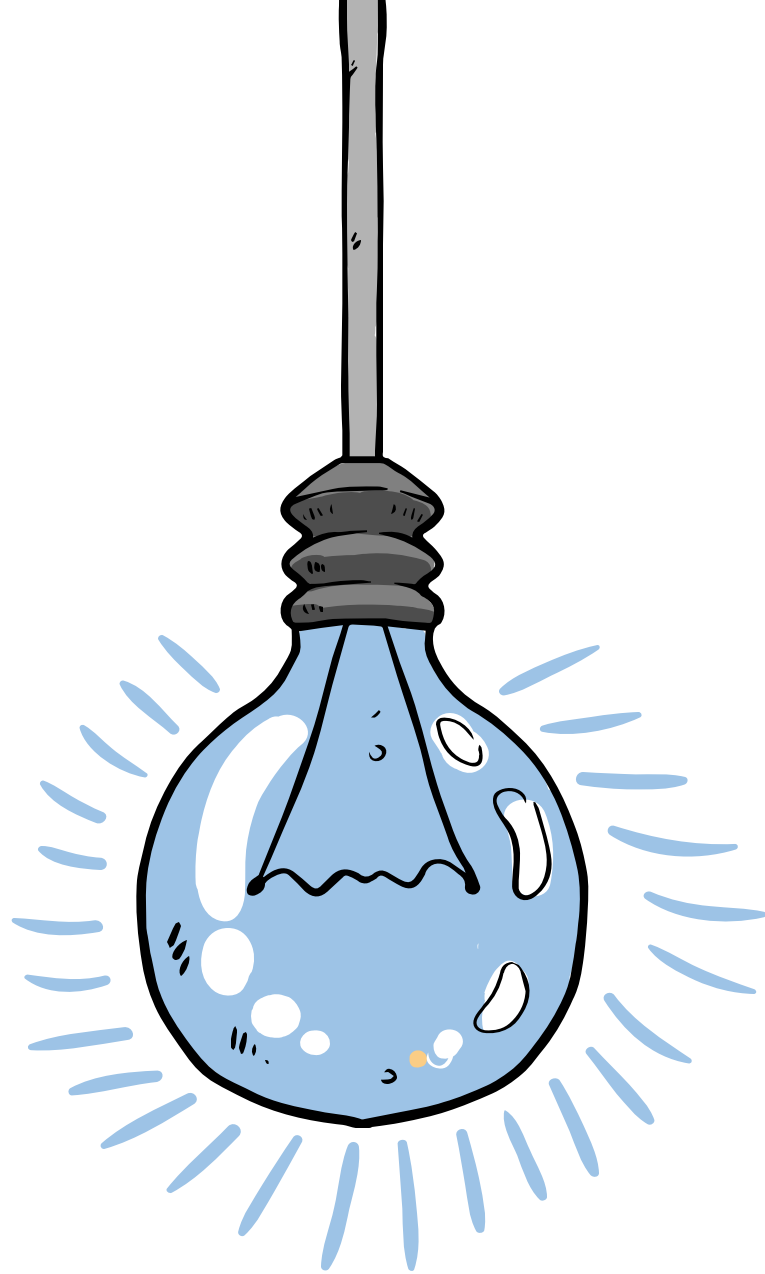
物聯網

第21組

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B0844143陳亭妤





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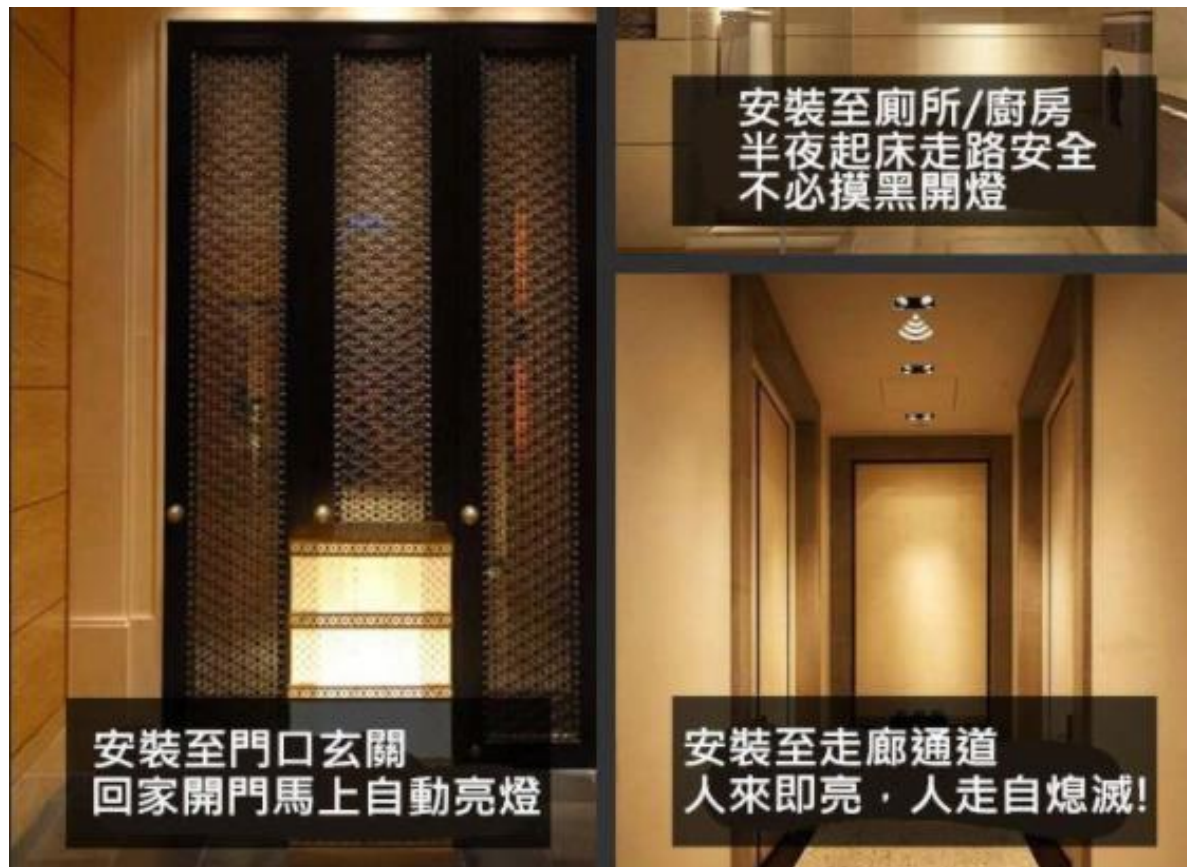
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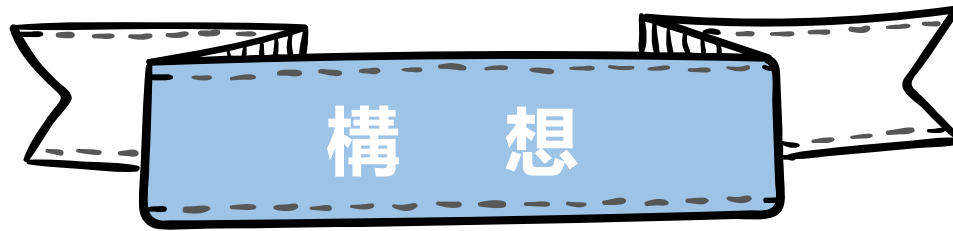
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偵測到屋內有人
紅外線



判斷白天或晚上
感光



打開燈(晚上)
RGB LED

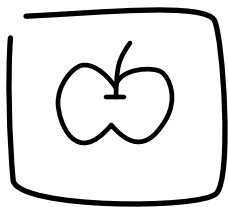


偵測溫溼度
溫濕

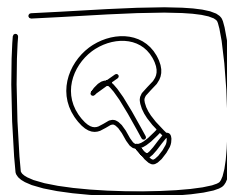


是否需開電風扇
電風扇

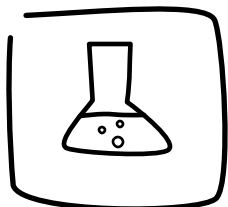
構 想



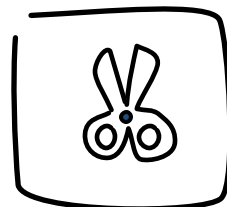
顯示溫濕度



屋內有幾個人



電燈是否打開



風扇是否打開



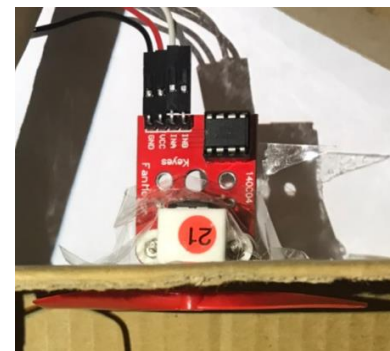
使用到的設備

使用的設備

紅外線



電風扇



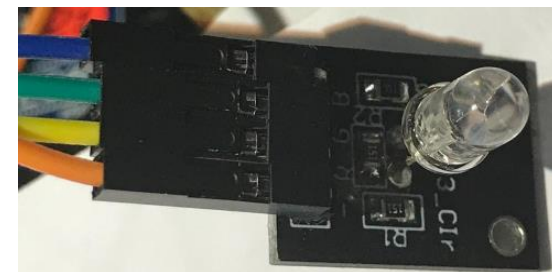
光敏電阻

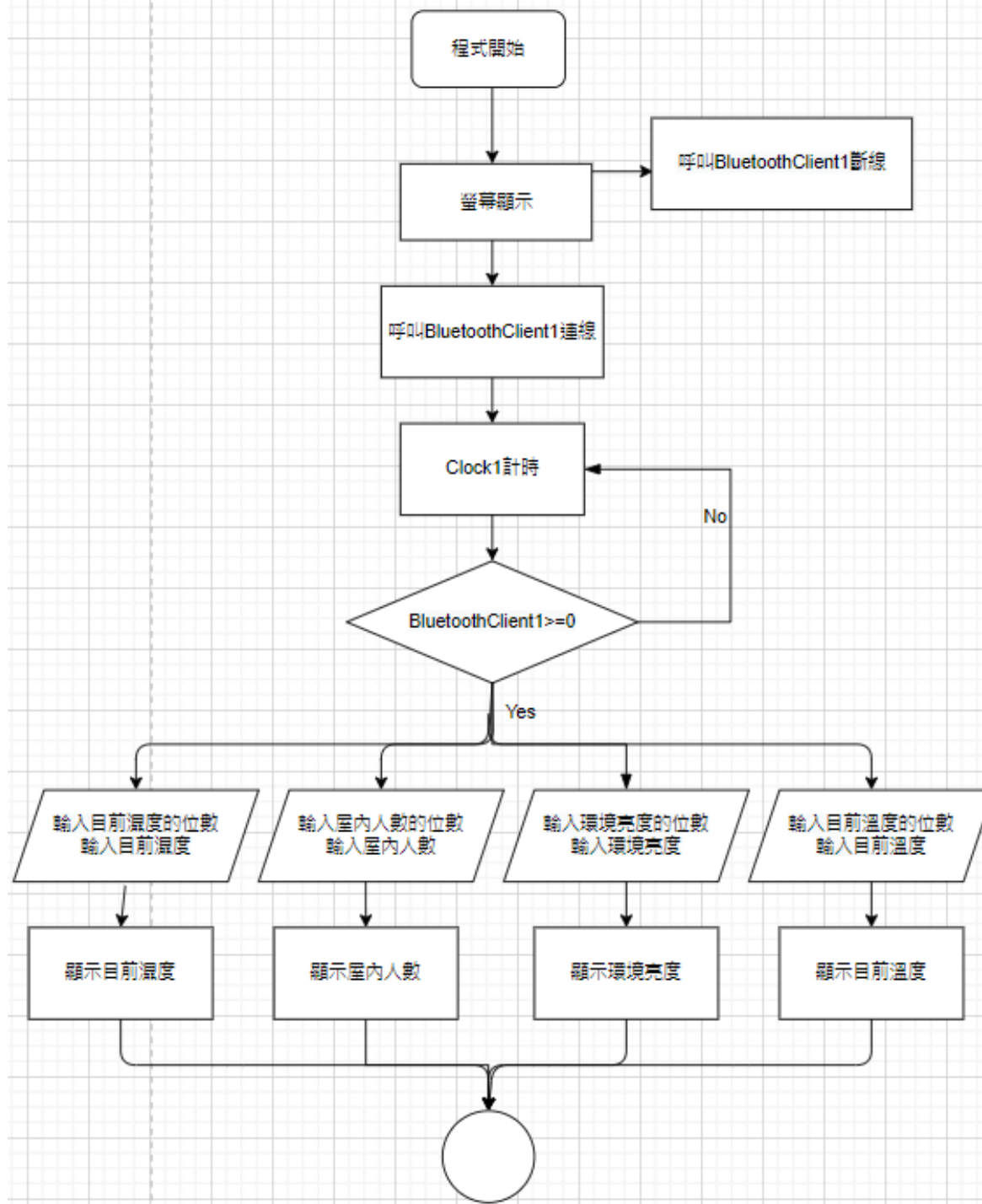
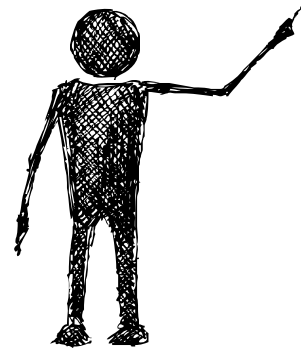


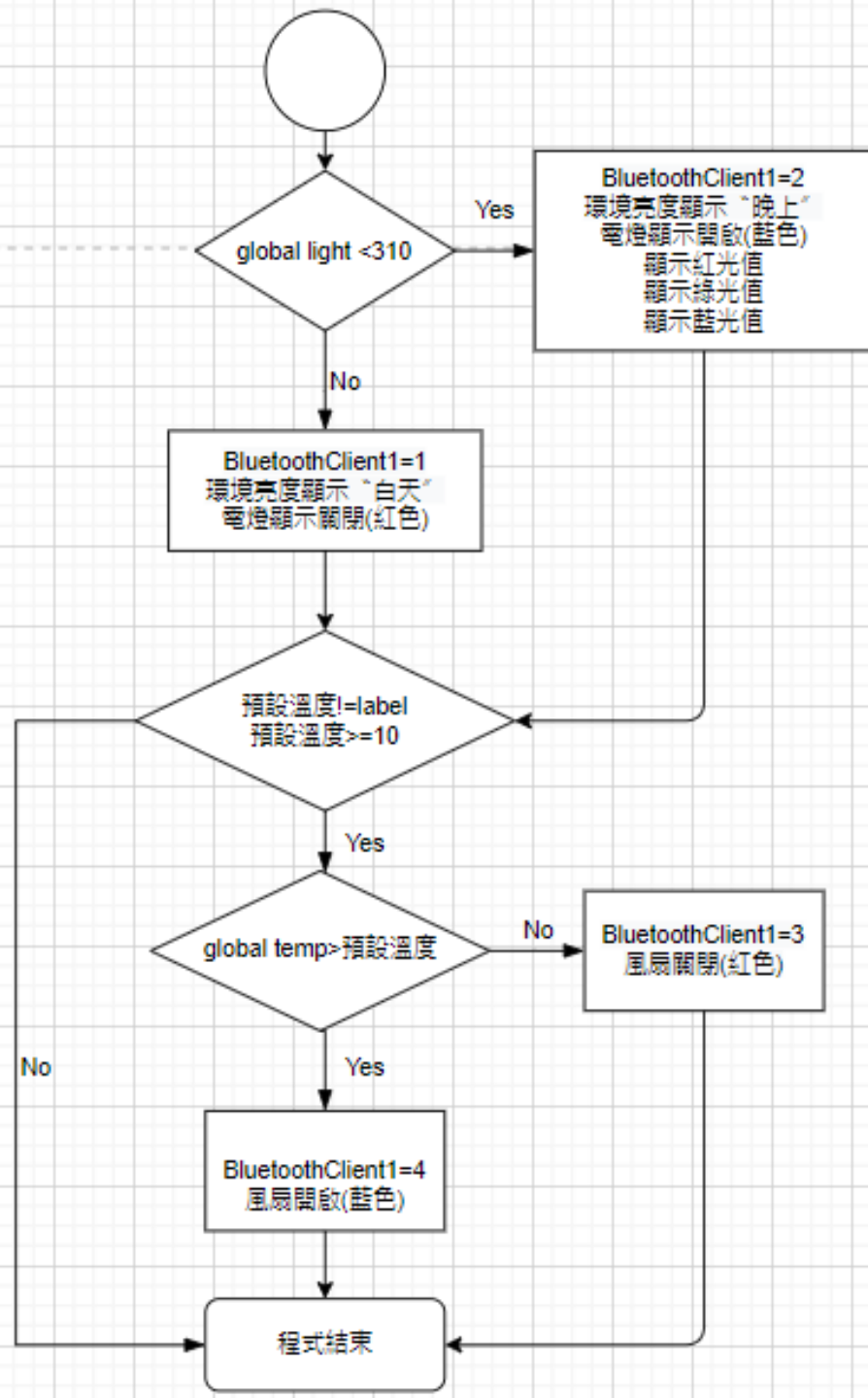
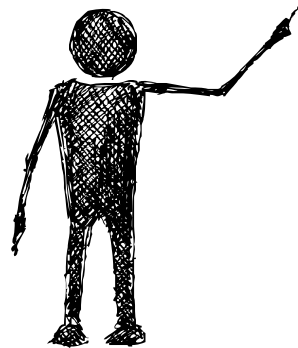
溫濕感測器



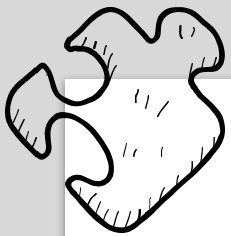
RGB燈











全域變數

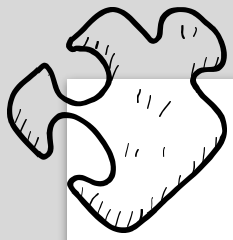
```
#include <SoftwareSerial.h>
#include <Wire.h>
#include "SimpleDHT.h"

SimpleDHT11 dht11;

SoftwareSerial BT(12,11);
//RGB的PORT
const int rpin =4;
const int gpin =5;
const int bpin =6;
String data1;
int rValue,gValue,bValue =-1;
int Comma1, Comma2;
```

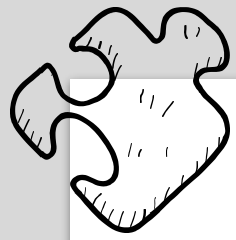
```
//紅外線的port
const int SensorIn=2;
const int SensorOut=3;
int StateIn;
int StateOut;
int n = 0;
int digits =0;
//感光的port
const int pinLS =A2;
int lightval =0;
int lightdigits = 0;

//溫溼度
int pinDHT11=10;
int templength =0;
int humilength =0;
byte humidity =0;
byte temperature = 0;
//風扇
int INA = 9;
int INB = 8;
```



Void setup()

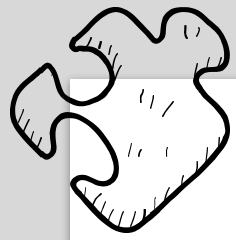
```
void setup() {  
    Serial.begin(9600);  
    //RGD的INOUT  
    pinMode(rpin, OUTPUT);  
    pinMode(gpin, OUTPUT);  
    pinMode(bpin, OUTPUT);  
    //紅外線INOUT  
    pinMode(SensorIn, INPUT);  
    pinMode(SensorOut, INPUT);  
    //溫濕  
    pinMode(pinDHT11, INPUT);  
    //風扇output  
    pinMode(INA, OUTPUT);  
    pinMode(INB, OUTPUT);  
    //感光  
    pinMode(pinLS, INPUT);  
    BT.begin(9600);  
}
```



紅外線副程式

```
void infrared()
{
    StateIn = digitalRead(SensorIn);
    StateOut = digitalRead(SensorOut);
    if(StateIn == LOW)
    {
        n = n+1;
        digits = (int) (log10(n))+1; //計算幾位
        BT.print(digits);
        BT.print(n);
        delay(200);
    }
    else if (StateOut == LOW)
    {
        n=n-1;
        if(n<0) //數值小於0，顯示0人
        {
            n=0;
            BT.print(1);
            BT.print(0);
        }
    }
}
```

```
    }else
    {
        digits=(int) (log10(n))+1;
        BT.print(digits);
        BT.print(n);
        delay(200);
    }
else
{ digits=(int) (log10(n))+1;
  BT.print(digits);
  BT.print(n);
  delay(200);
}
}
```

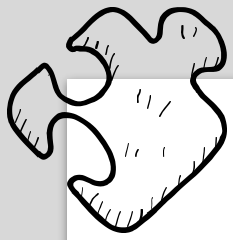



感光副程式

```
void readlight()
{
    //感光
    lightval = analogRead(pinLS);
    lightdigits = (int)(log10(lightval))+1;
    BT.print(lightdigits);
    BT.print(lightval);
    delay(200);
}
```

溫溼度副程式

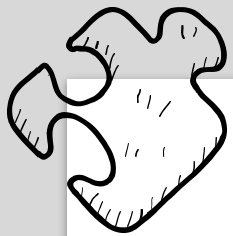
```
void readtempandhumi()
{
    if( isnan(humidity) || isnan(temperature))
    {
        return;
    }
    if( dht11.read(pinDHT11 , &temperature , &humidity , NULL))
    {
        return;
    }
    templength = (int)(log10(temperature))+1;
    humilength = (int)(log10(humidity))+1;
}
```



主程式

```
void loop() {  
  
    readlight(); //感光  
    delay(100);  
    readtempandhumi(); //溫濕  
    delay(100);  
    BT.print(templength);  
    BT.print(int(temperature));  
    delay(200);  
    BT.print(humilength);  
    BT.print(int(humidity));  
    delay(200);  
    infrared(); //紅外線  
  
    delay(100);  
}
```

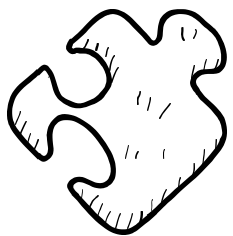
```
//RGB及風扇  
char data3 = BT.read();  
switch(data3)  
{  
    case '3':  
        digitalWrite(INA, LOW);  
        digitalWrite(INB, HIGH);  
        break;  
    case '4':  
        digitalWrite(INA, LOW);  
        digitalWrite(INB, LOW);  
        break;  
    default:  
        break;  
}
```



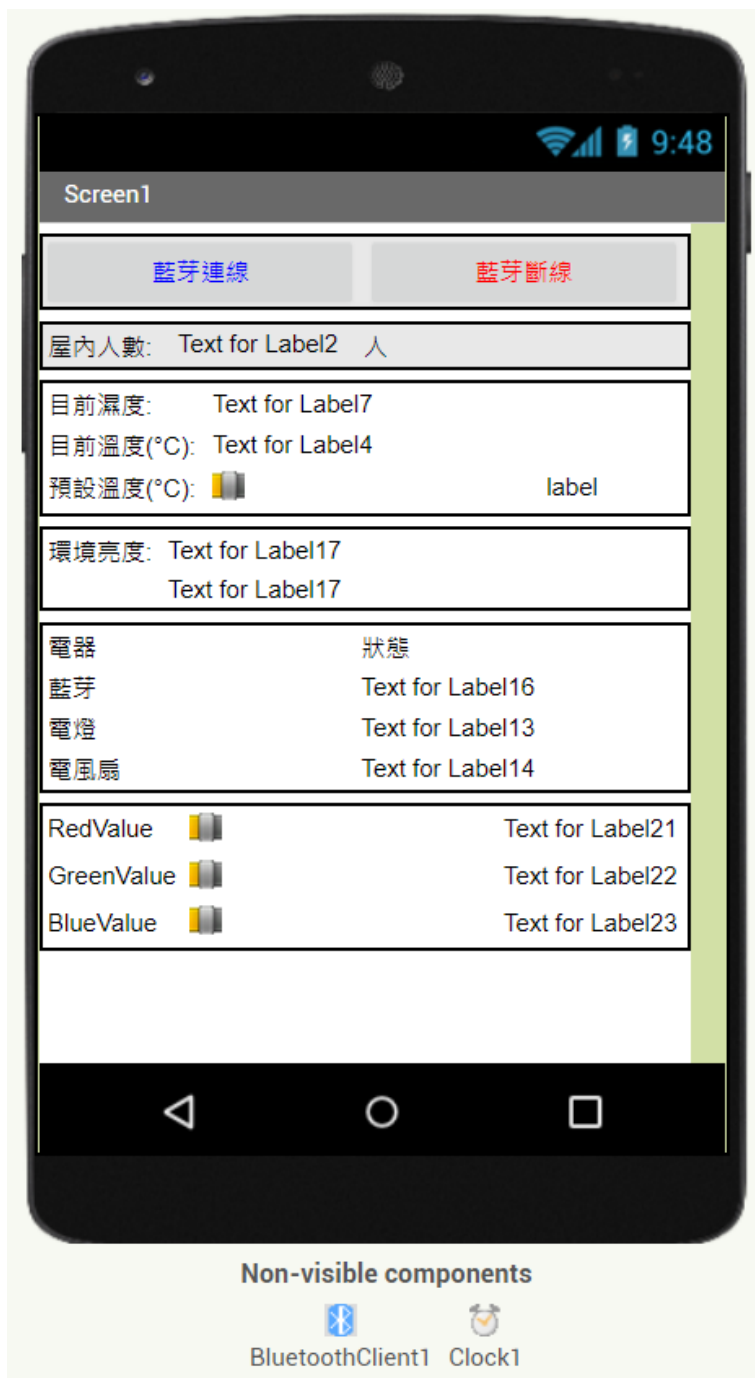
主程式

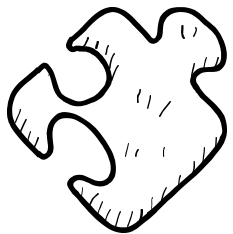
```
char data = BT.read();
switch(data)
{
    case '1':
        analogWrite(rpin, 0);
        analogWrite(gpin, 0);
        analogWrite(bpin, 0);
        break;
    case '2':
        data1 = BT.readString();
        Comma1 = data1.indexOf(",");
        Comma2 = data1.indexOf(",", Comma1 + 1);
        rValue = data1.substring(0, Comma1).toInt();
        gValue = data1.substring(Comma1+1, Comma2).toInt();
        bValue = data1.substring(Comma2+1).toInt();
        analogWrite(rpin, rValue);
        analogWrite(gpin, gValue);
        analogWrite(bpin, bValue);
        break;
}
delay(200);
}
```





手機操作介面



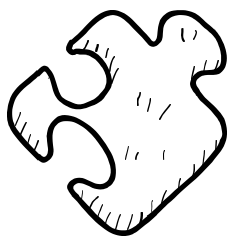


藍芽按鈕設定

```
when Screen1.Initialize
do
  set 藍芽狀態.TextColor to [red]
  set 藍芽狀態.Text to "請連接藍芽"
```

```
when ListPicker1.BeforePicking
do
  set 藍芽狀態.TextColor to [red]
  set 藍芽狀態.Text to "請連接藍芽"
  set ListPicker1.Elements to BluetoothClient1.AddressesAndNames
```

```
when ListPicker1.AfterPicking
do
  if
    call BluetoothClient1.Connect
    address ListPicker1.Selection
  then
    set Button1.Enabled to true
    set ListPicker1.Enabled to false
    set 藍芽狀態.TextColor to [blue]
    set 藍芽狀態.Text to "藍芽連接成功!"
    set Clock1.TimerEnabled to true
    set 紅光設定.ThumbPosition to "256"
    set 綠光設定.ThumbPosition to "256"
    set 藍光設定.ThumbPosition to "256"
    set 顯示電風扇狀態.Text to "關閉"
    set 顯示電風扇狀態.TextColor to [red]
```

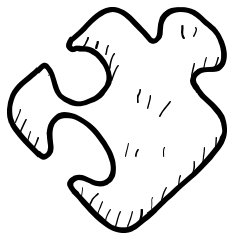


藍芽斷線按鈕設定

```
when Button1 .Click
do
  call BluetoothClient1 .Disconnect
  set Button1 . Enabled to false
  set ListPicker1 . Enabled to true
  set 藍芽狀態 . TextColor to red
  set 藍芽狀態 . Text to "請連接藍芽"
  set Clock1 . TimerEnabled to false
  set 顯示屋內人數 . Text to "--"
  set 顯示目前溫度 . Text to "--"
  set 顯示目前濕度 . Text to "--"
  set 顯示電風扇狀態 . Text to "--"
  set 顯示電燈狀態 . Text to "--"
```

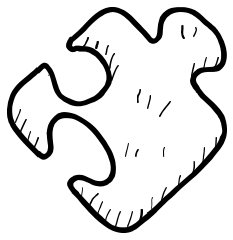
宣告全域變數

```
initialize global lightlength to ""
initialize global light to create empty list
initialize global templength to ""
initialize global temp to create empty list
initialize global humilength to ""
initialize global humi to create empty list
initialize global length to ""
initialize global count to ""
```



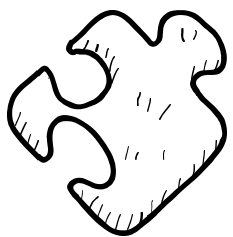
Sliders 設置

```
when 溫度設定 .PositionChanged  
  thumbPosition  
do set 預設溫度 . Text to round get thumbPosition  
  
when 紅光設定 .PositionChanged  
  thumbPosition  
do set 顯示紅光值 . Text to round get thumbPosition  
  
when 綠光設定 .PositionChanged  
  thumbPosition  
do set 顯示綠光值 . Text to round get thumbPosition  
  
when 藍光設定 .PositionChanged  
  thumbPosition  
do set 顯示藍光值 . Text to round get thumbPosition
```

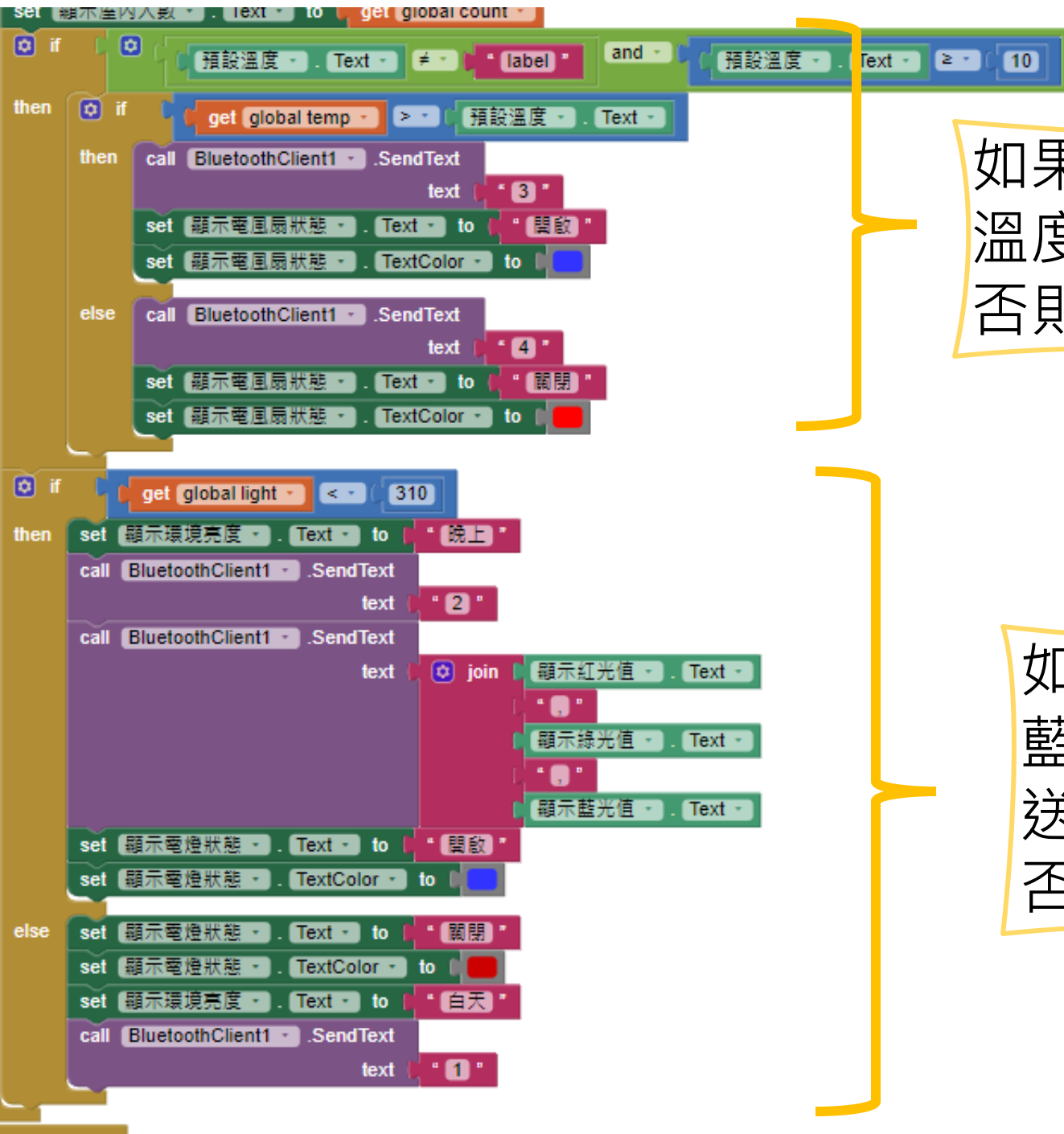



主程式

```
when Clock1.Timer
do
  if
  then
    set global lightlength to call BluetoothClient1.ReceiveText
    numberOfBytes 1
    set global light to call BluetoothClient1.ReceiveText
    numberOfBytes get global lightlength
    set Label17.Text to get global light
    set global templength to call BluetoothClient1.ReceiveText
    numberOfBytes 1
    set global temp to call BluetoothClient1.ReceiveText
    numberOfBytes get global templength
    set 顯示目前溫度.Text to get global temp
    set global humilength to call BluetoothClient1.ReceiveText
    numberOfBytes 1
    set global humi to call BluetoothClient1.ReceiveText
    numberOfBytes get global humilength
    set 顯示目前濕度.Text to get global humi
    set global length to call BluetoothClient1.ReceiveText
    numberOfBytes 1
    set global count to call BluetoothClient1.ReceiveText
    numberOfBytes get global length
    set 顯示屋內人數.Text to get global count
    if
```



主程式

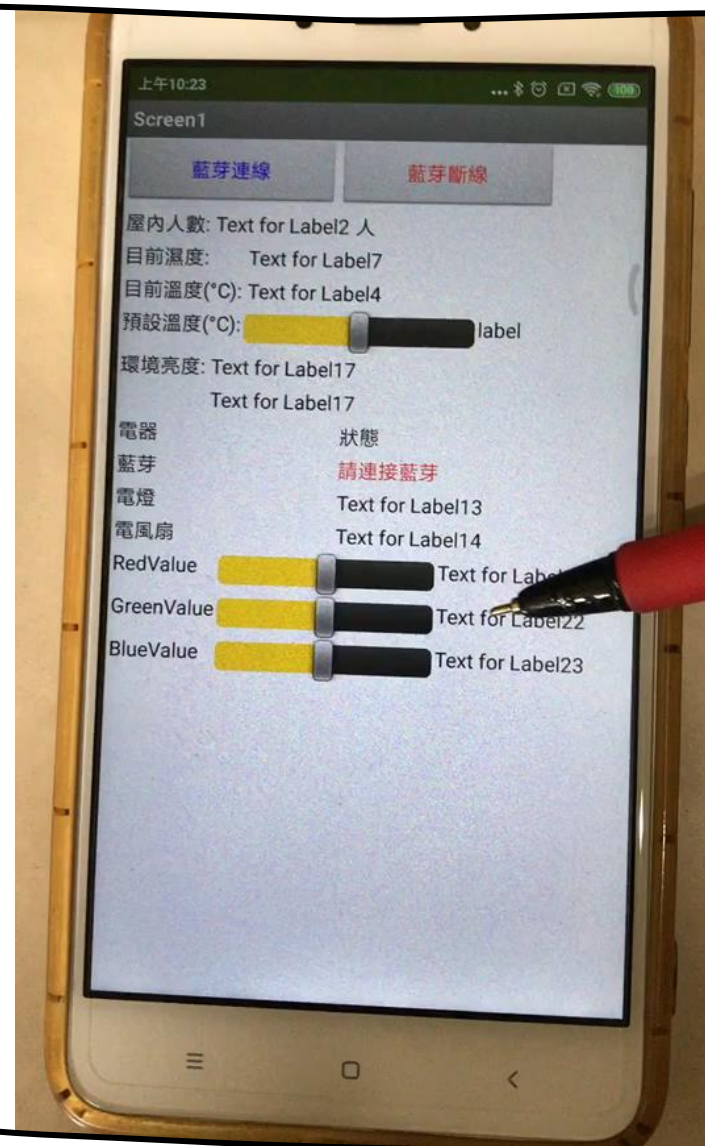


如果現在溫度 > 預設溫度，藍芽傳送3。否則傳送4。

如果光敏值 < 310，藍芽傳送4，並傳送RGB值。否則傳送1。

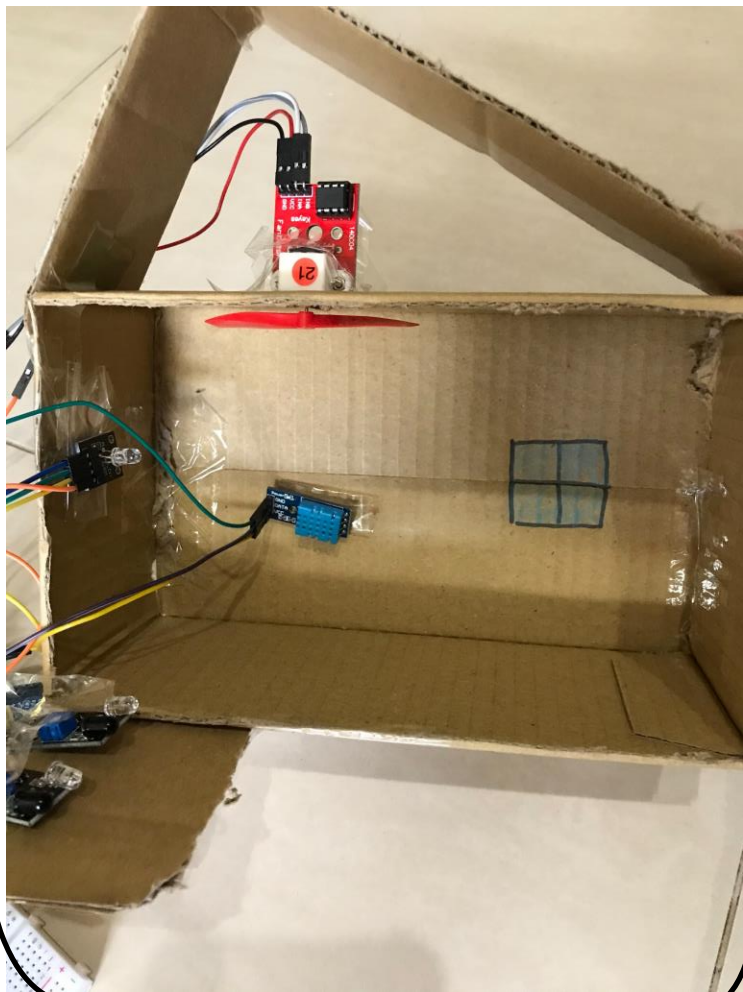


影片



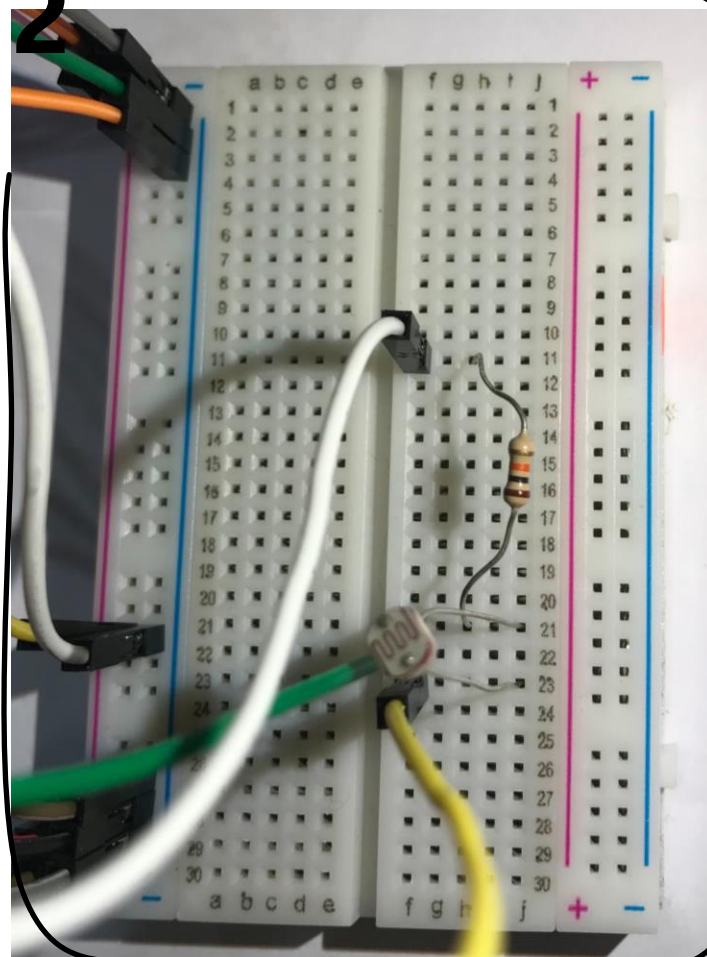
元件擺放

01



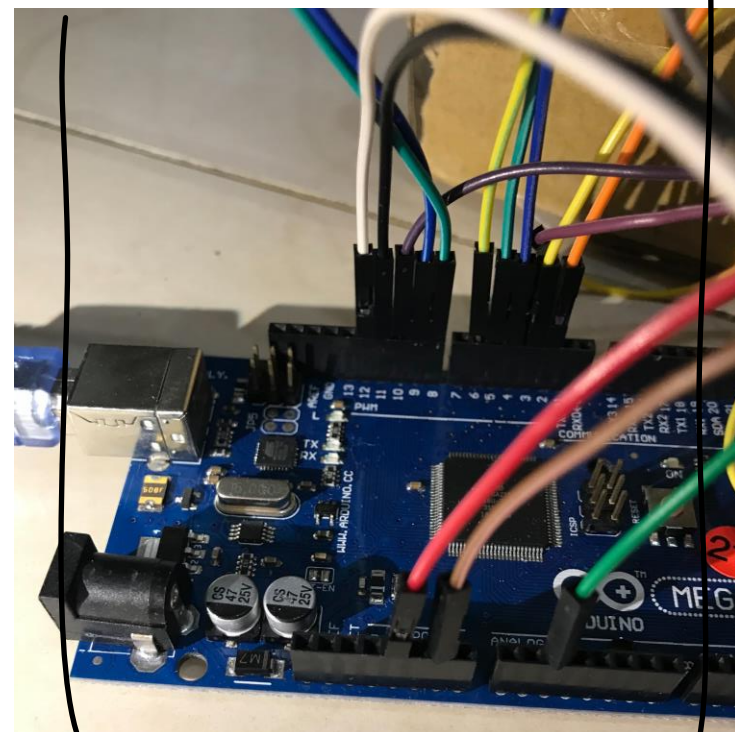
■ 房 子

02



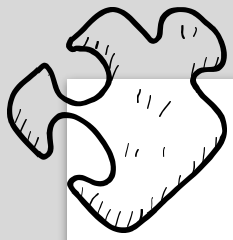
■ 麵 包 板

03



■ M e g a 板





全域宣告

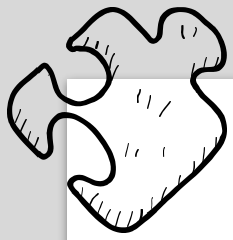
```
#include <SoftwareSerial.h>
#include <Wire.h>
#include <IRremote.h>
const byte IR_RECEIVE_PIN = 3;
int fantime=0;
int digits =0;
int INA = 9;
int INB = 8;
SoftwareSerial BT(12,11);
```

setup

```
void setup() {

    Serial.begin(9600);
    pinMode(INA,OUTPUT);
    pinMode(INB,OUTPUT);
    IrReceiver.begin(IR_RECEIVE_PIN );
    BT.begin(9600);

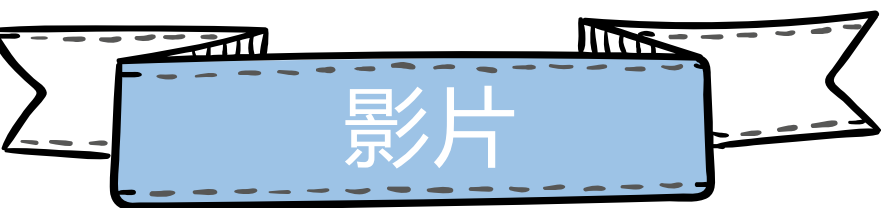
}
```



主程式

```
void loop() {  
  if (IrReceiver.decode())  
  {  
    switch(IrReceiver.decodedIRData.command)  
    {  
      case 2:  
        digitalWrite(INA, LOW);  
        digitalWrite(INB, HIGH);  
        delay (fantime*1000);  
        digitalWrite(INA, LOW);  
        digitalWrite(INB, LOW);  
        break;  
      case 10:  
        Serial.println("fan is turned on");  
        break;  
      case 23:  
        fantime++;  
        Serial.println("fantime:");  
        Serial.println(fantime);  
        digits = (int)(log10(fantime))+1;  
        break;
```

```
      case 24:  
        fantime--;  
        if(fantime < 0)  
        {  
          fantime = 0;  
        }  
        Serial.println("fantime:");  
        Serial.println(fantime);  
        digits = (int)(log10(fantime))+1;  
        break;  
      default:  
        break;  
    }  
    IrReceiver.resume();  
    delay(200);  
    BT.print(digits);  
    BT.print(fantime);  
  }  
}
```



謝謝聆聽