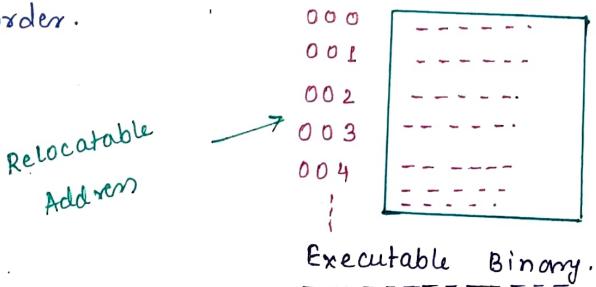


Address Binding: Mapping of Relocatable Addresses to Physical Addresses.

Q) What is Relocatable address and physical Address?

Relocatable Address: When we produced a Binary of a program, it contains Relocatable Addresses. These are in sequential order.



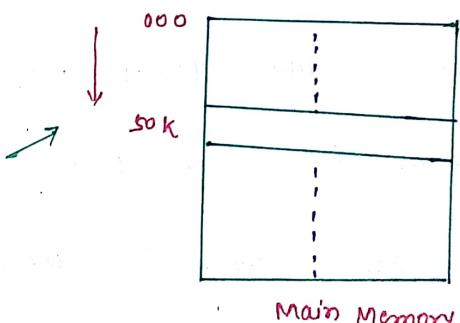
To run this Binary File we have to bring it in Main Memory.

Physical Addresses: The Addresses in the main Memory are

called Physical Addresses.

It is the actual Addresses in Ram.

physical Addresses



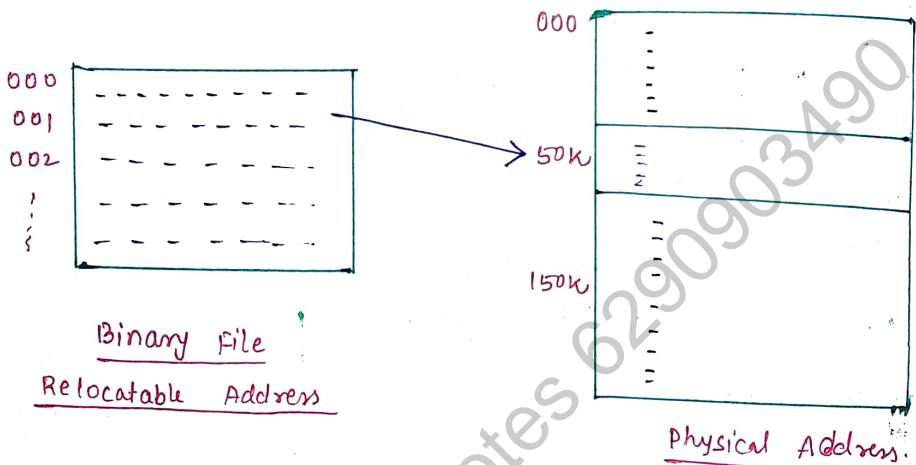
Main Memory.

* Address Binding can happen at different stages!

↳ Compile Time: compile Time Address Binding is that means your compiler knows where this program is going to be loaded in physical memory and it used to have in very very old days. Ex. .com file and MS-DOS.

They used to use compile Time Address Binding.

ii) Load Time Binding: your loader has the executable file which has all the relative addresses. It puts it in the main memory with some base location and all the relative addresses. They are recomputed with reference to base Address.



If our Binary file program went into the main memory at 50K Then counting starts from there onwards like $(50K+1, 50K+2, \dots)$ and so on. Base Address is in our Main Memory. so all the addresses are readjusted according to Base Addresses.

* Problem with Load Time Binding.

Once a program is located in main memory, it can't be moved to other location in the main memory.

Q) Why we need to move our Program's location in the main memory ??

A): your program might be doing I/O. and when it does I/O. it waits for the I/O. So we can do that move this program to another location and bring other program for work.

iii) Run Time Binding: Run Time Binding Happens in all of the modern Operating Systems. In Run Time Binding your process can be moved to a different section of memory at runtime. The Addresses Generated by CPU is not physical Addresses. CPU Generates Logical Addresses and These addresses are converted to Physical Addresses at RUN TIME.

To Implement Run Time Binding Hardwares support is required. In compile Time Binding, Load Time Binding we could do it through Software.

* There are some Memory Management unit which converts these Logical Addresses into Physical Addresses.

27/09/2021. 34. Runtime Binding.

Runtime Binding: As we discussed above, The addresses generated by CPU is Logical Addresses in Run Time Binding. And These Logical Addresses are converted to physical Address During Runtime.

Purpose of Runtime Binding: Your process can move to different location while it is being Run.

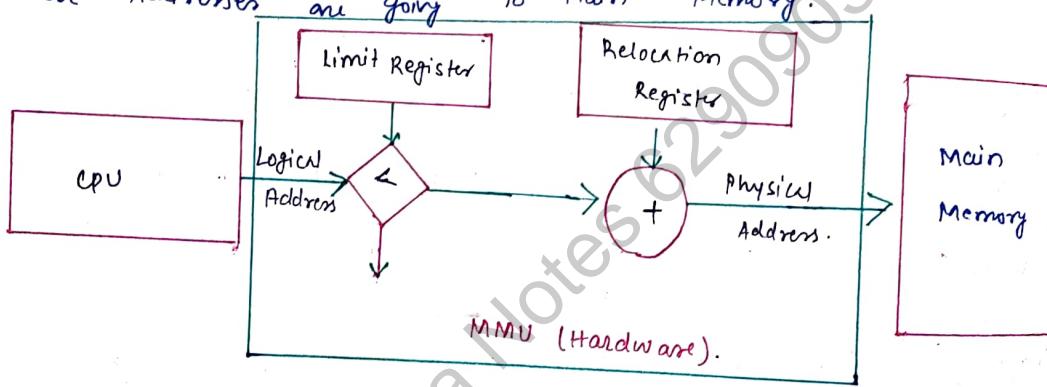
Working.

Runtime Binding Happens In our Hardware. In Hardware we have MMU (Memory Management unit) which have two registers Limit Register and Relocation Register.

When a process is loaded into Memory. These Registers are located by the operating system. (Limit & Relocation Register).

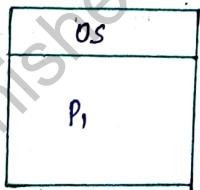
CPU generates the logical Addresses and after the generation of Logical Addresses These 2 Register converts these Addresses into physical Addresses. Hardware helps you in doing security Also. It provides you security. Your process cannot access beyond its Limit.

After converting the Logical Addresses to Physical Addresses. These Addresses are going to Main Memory.



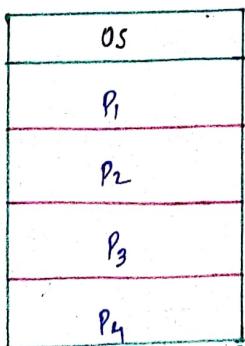
35. Evolution of Memory Management.

* Single Tasking System:



It is the Initial system. At a time only one process can be run (Ex. Process P₁) After completion of one process another process can be run.

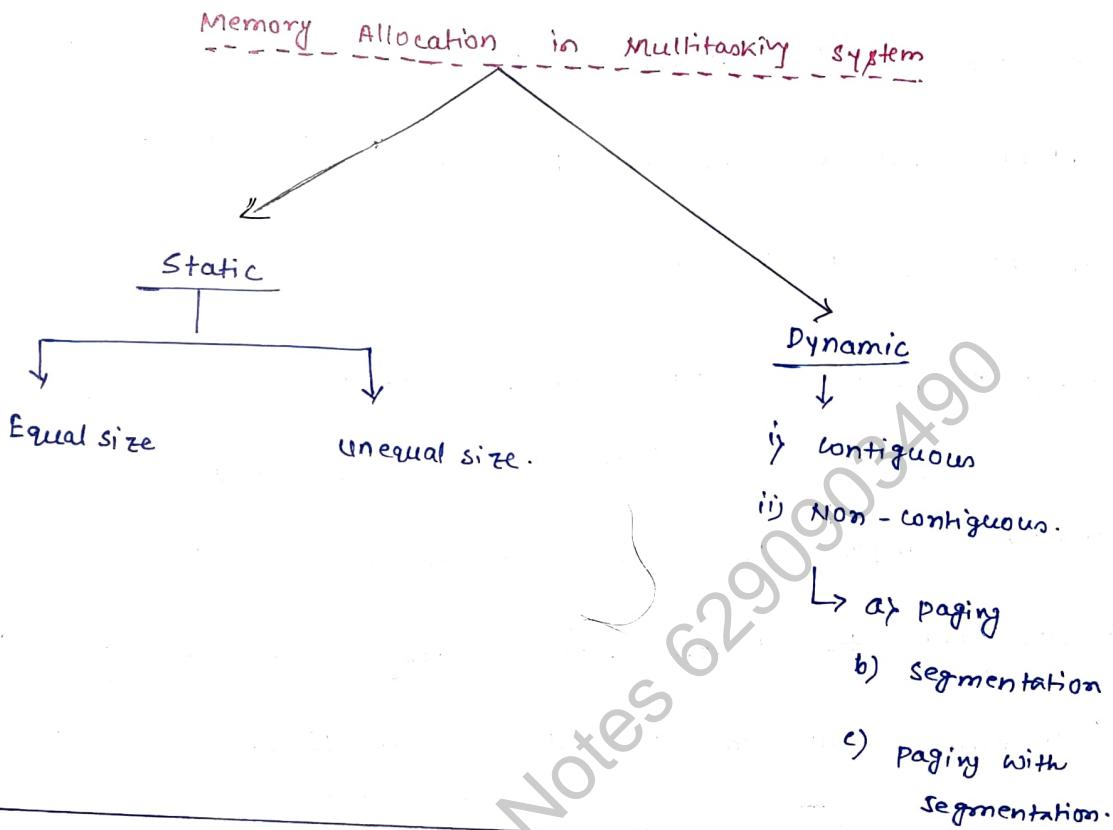
* Multi-tasking System:



You can run multiple processes at a Time. CPU can be utilised in a proper way.

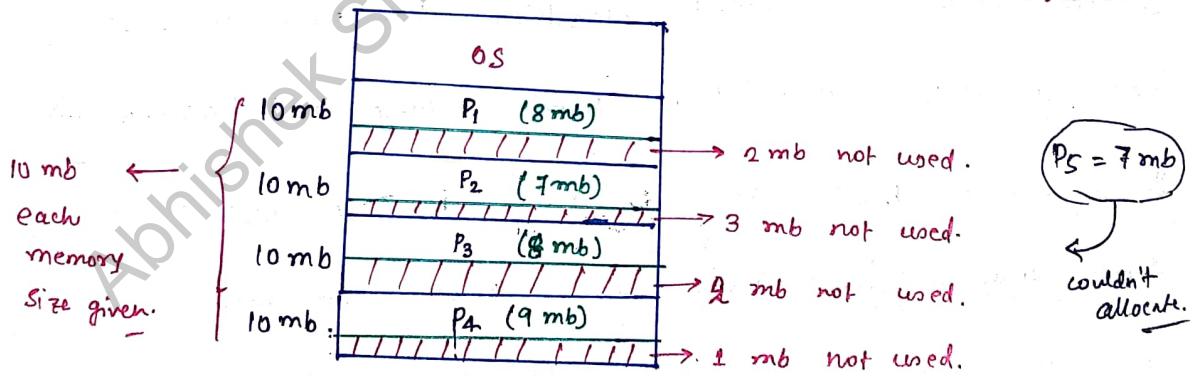
You might have multiple processes available in memory. So that CPU can be utilized better.

Abhishek Sharma notes



Equal size Partition:

Static Memory Allocation in Multitasking system



We have 10 mb memory for each process and $P_1 = 8 \text{ mb}$, $P_2 = 7 \text{ mb}$, $P_3 = 6 \text{ mb}$, $P_4 = 9 \text{ mb}$. Consumes the memory space

Now a process $P_5 = 7 \text{ mb}$ wants to access the memory but it can't allocate. Even though we have total $(2+3+2+1) = 8 \text{ mb}$ memory which is free but we can't assign $P_5 = 7 \text{ mb}$.
(but in different areas)

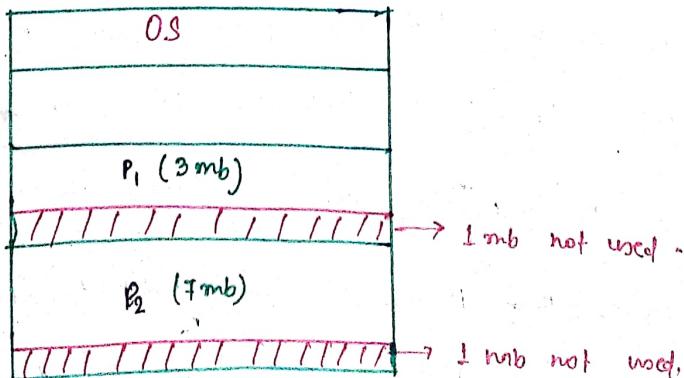
This is called External Fermentation.

External Fermentation: There is a process waiting for some memory for allocation. But there is memory available but in different parts. So that it is not allocated to the process. is called External fermentation.

Internal Fermentation: When more memory is allocated than needed. Little in our Equal size memory example. we allocate 10 mb memory for each process but the process ^{is} consuming less memory than needed. This is Internal Fermentation.

Unequal Size Partition

The idea is to better utilize the memory. In this type of memory allocation we have unequal memory slots rather than fixed memory slot (Equal partition). If a process need 3 mb and the memory slot is of 4 mb than it goes there. If a process has need 7 mb and the slot is of greater than 7 mb then it goes there.



The unequal size partition is better than

equal size partition. Bcz. Here Memory is better utilized.

Still it has also Internal Fermentation and External Fermentation.

* Both of the Static Memory Allocation in Multitasking System

has Internal Fermentation and External fermentation.

→ (Equal size and unequal size).

Dynamic Memory Allocation in Multitasking System.

In dynamic Memory Allocation we need memory Empty initially.

When processes came we allocate them into memory accordingly

to their sizes. During Runtime you allocate memory according to the process size.

Contiguous Dynamic Memory Allocation.

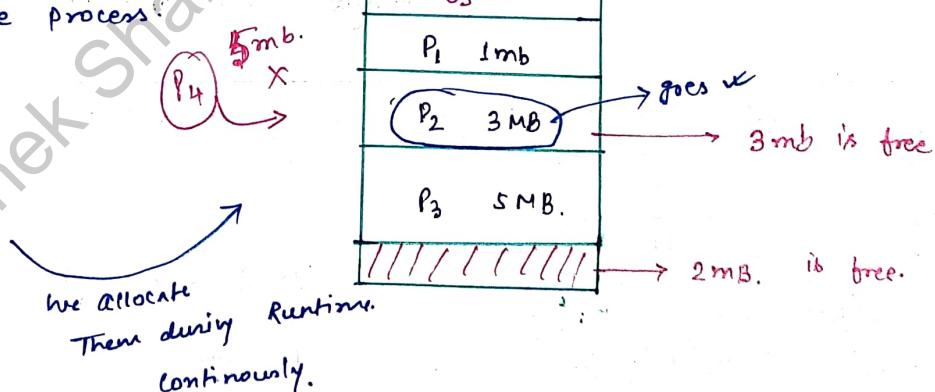
We allocate memory dynamically contiguous (one by one).

We have three processes:

$$P_1 = 1 \text{ mb}$$

$$P_2 = 3 \text{ MB}$$

$$P_3 = 5 \text{ MB}$$



Let's assume, At a time P_2 goes from the memory and

① The memory space is now empty i.e. (3 MB) we have

another (2 MB) free memory. Now we have $(3+2) = 5 \text{ mb}$ free on different spaces. and a process $P_4 = 5 \text{ mb}$ want to come but if it is not allowed. and not allocated.

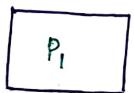
In Contiguous Dynamic Memory Allocation we don't have Internal Fermentation. But we have External Fermentation.

TO Avoid External Fermentation we have non-contiguous Dynamic Memory Allocation. In which we use Paging and Segmentation to avoid External Fermentation.

We divide the processes into pages and these pages are loaded separately at different location. Or we divide the processes into segments and these segments are loaded at different locations.

These pages and segments do not have to be at contiguous location. We will study in the next lect. about Paging and Segmentation.

36. Dynamic partitioning.



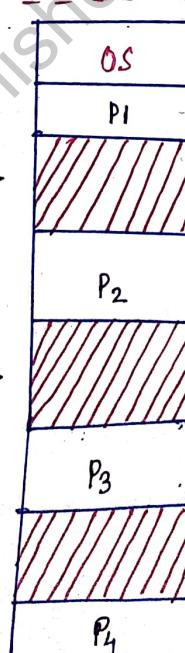
\Rightarrow P_1 Process is running and occupying memory.



↪ Hole

\Rightarrow Process Left The memory and There is a hole.

Example:



If a process $P_5 = 5\text{mb}$ came and we have to allocate.

How will be the allocate?

There are no continuous memory.

How will we allocate?

A: There are 2 ways to allocate memory.

There are 2 ways to allocate memory in non-contiguous dynamic memory allocation.

i) Bitmap

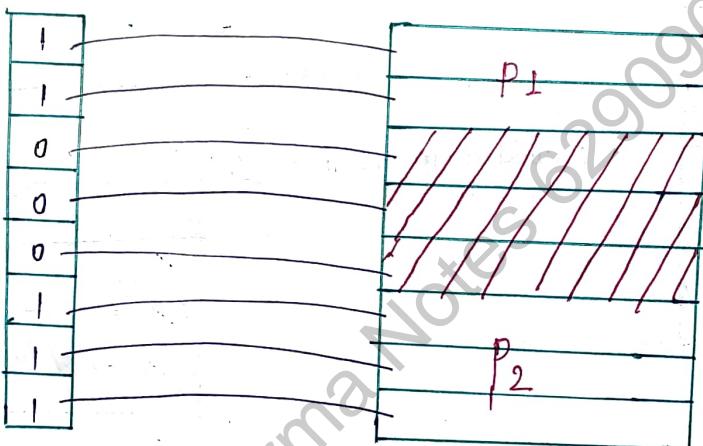
ii) Linked List.

Bitmap:

We use Bitmap. Where every entry has '1' and '0'.

'1' means the particular slot of memory is occupied.

'0' means there is a hole. (Memory is free).



The problem with this Bitmap approach is that it consumes lots of memory. Ex. You have 32 bits size memory and 1 bit of it is occupied by this Bitmap.

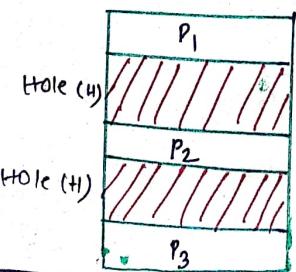
So every 32 bit you need 1 bit for Bitmap.

That is why Bitmap is not used in Dynamic Memory Allocation.

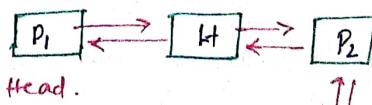
Linked List:

This is the other way to manage memory in

Dynamic partitioning is Linked List.



H = Hole.



Linked List.

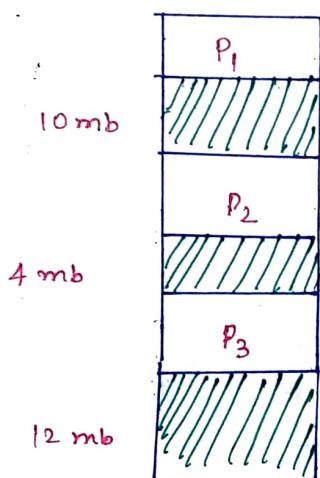


- Algorithms:-

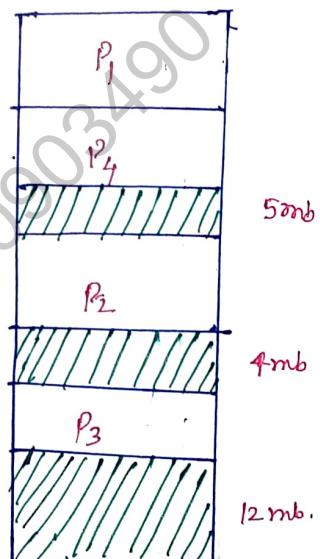
These algorithms (first, Best, Next, worst fit) are about how we allocate memory in the Linked List Representation to the process.

i) First fit Algorithm:-

This is the Best Algo. in all algorithms.



When a process $P_4 = 5\text{mb}$
Allocated in the Memory.



In this Algo. we Traverse from the Linked List from Head. and as soon as we find a hole that can accommodate the process we allocate memory to the process.

ii) Best Fit Algorithm:-

Instead of allocating the 1st node, we traverse the whole list and we find the hole that is best fit for the process having size closest or equal to the waiting process.

Example. In the above Example, (in first fit) if a process $P_4 = 3\text{ MB}$ comes we allocate memory.

After P_2 's hole that is of (4mb Hole).

The disadvantages of Best fit Algorithms is Abhishek Sharma Notes that we have to traverse through the whole list to find the hole.

iii) Next Fit Algorithm:

We start searching \wedge from the point where we stopped last time.

Ex: If we have 2 processes $P_4 = 8\text{mb}$ and $P_5 = 3\text{mb}$.

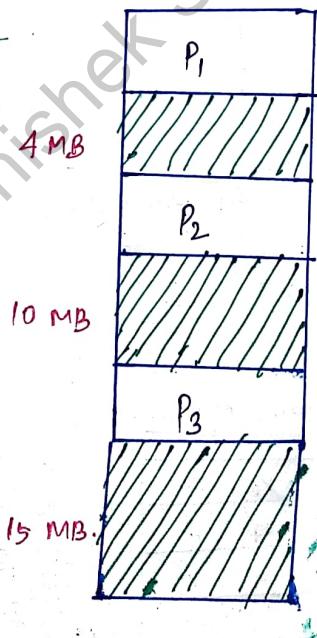
Then we allocate P_4 in P_1 's after Hole and we now start searching for P_5 from P_1 's Hole after this point.

That's how next fit algo works. It starts from the search point of last search. It's not begin from the beginning.

iv) Worst Fit Algorithm:

Always allocates the biggest slot to process request in the memory.

Example.



Whatever request it might come, it always assign to this hole bcz. its size is biggest.

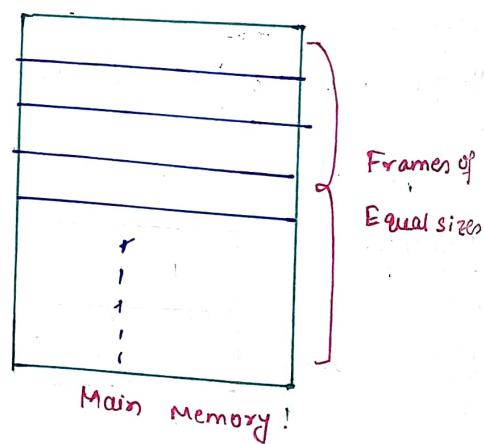
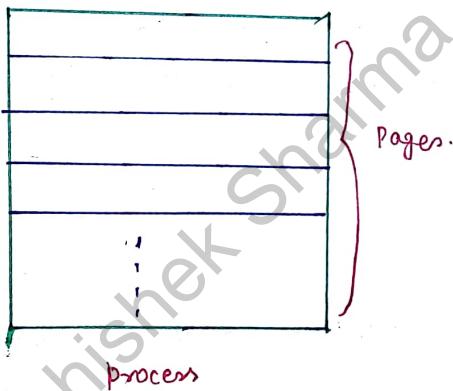
After Analysis, First-fit Algorithm is the best Algorithm. bcz in Best fit and worst fit Algo. we need to traverse the whole list.

3.8. Paging in Memory Management.

Abhishek Sharma Notes

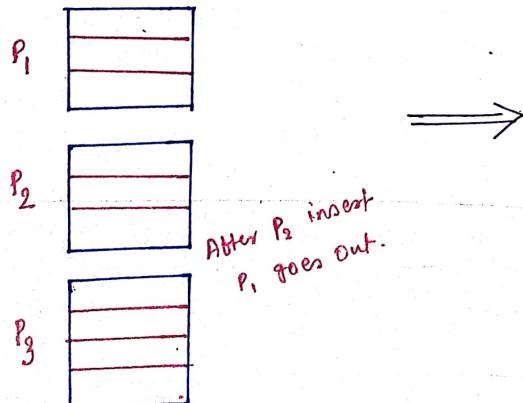
Paging: The most popular idea of Memory Management is Paging. This idea creates abstraction where programmers do not worry for anything. They see their programs as contiguous. Memory location and internally your program is stored in different memory locations.

In Paging your main memory is divided into slots of equal sizes. and all these slots are called frames. Similarly your process is divided into slots of equal sizes and all these slots are called pages.

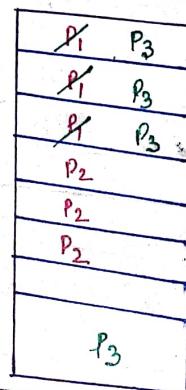


* Page size is always equal to frame size.

Example of Paging:



Main Memory



We can insert in different locations as well in Paging.

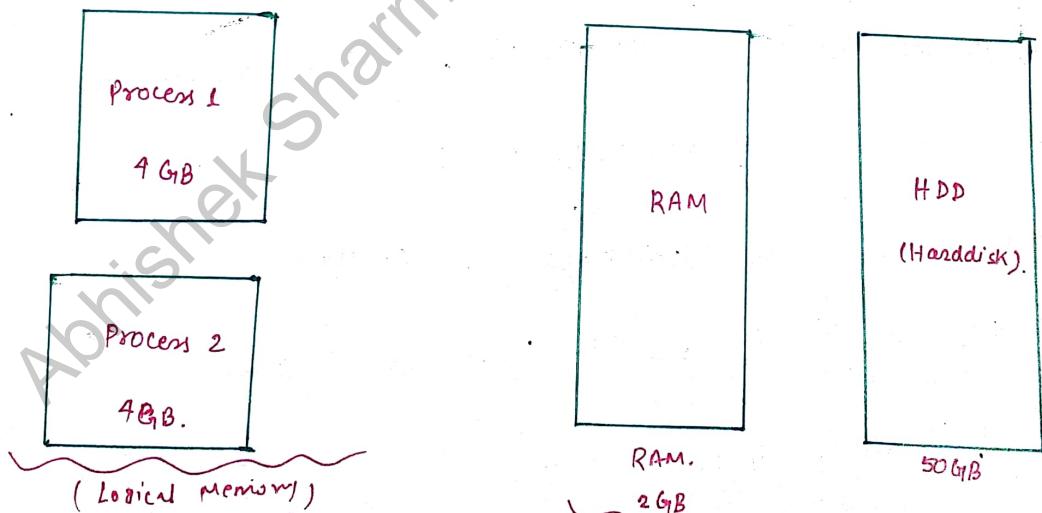
To convert Logical Addresses to physical Addresses we use Page Table. These page tables are mapping b/w pages and frames. Page no. is generated by the Logical Addresses is passed to the page table and page table tells you the frame no. in the Main Memory. (Physical memory).

39. Virtual Memory.

Virtual memory is very closely related to paging.

The Idea of virtual memory is some pages of the process may be present in the memory and some pages of the process may not be present in the memory. We will talk about valid and invalid bit.

Virtual Memory and Related Concepts.



A process assumes that it has 4 GB of Main memory. (Physical Memory) It doesn't know that it has 2 GB of memory only.

* Whenever a page is not present and later required by the process then **Page fault** happens.

Idea of Virtual Memory:

Whenever there is shortage of physical memory happens.

Virtual Memory compensates the shortage of physical memory by transferring pages from Harddisk.

When a page is required and it is not in the memory . It is loaded from the Harddisk.

* Page Fault is a really costly operation.

OS has to run some code to bring that page from Harddisk to Ram. There are many things involved.

* Harddisk access is really really slow in compared to normal RAM Access.

* Performance Impact of Page Fault:

$$\begin{aligned}\text{Avg. Access Time} &= 0.99 \times 10 \text{ ns} + 0.01 \times 50,000,000 \text{ ns} \\ &= 50,009,9 \text{ ns.} \\ &= 50,009,9 \times 10^{-6} = 50 \mu\text{s.}\end{aligned}$$

* Page fault increases the Avg. Access Time.

Advantages of Virtual Memory:

1) The Degree of Multiprogramming goes High.

Disadvantages of Virtual Memory:

2) If you have very few pages allocated to individual processes Then there are going to many page faults.

TLB: Translation Lookaside Buffer.

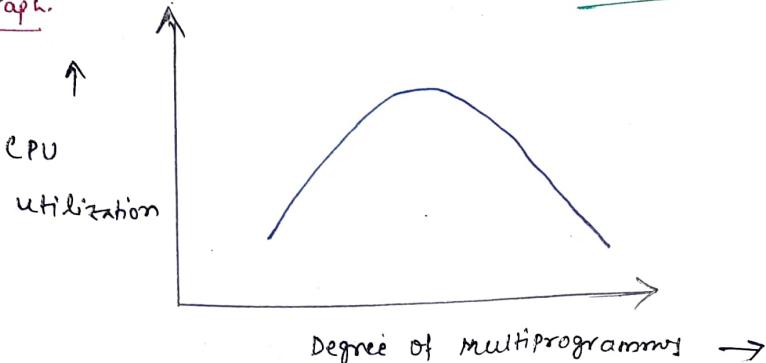
It is an associate cache present in your CPU.

Purpose of TLB: CPU Generates Logical Address and every page may contain multiple logical addresses. So when a CPU Generates a Logical Address This address has to be converted into physical addresses. We look these physical addresses in Page table to find the frame no. in the memory. and this look up is very frequent if might happen very frequently for the same page no.

So the idea of this TLB is to optimize this lookup. we have the cache of this page table in our processor. and this cache is very fast bcz most of the time you need to access the same page no.

Demand Paging: You only keep working set part of the memory process in memory. and in pure Demand Paging Environment you need to keep the minimal part in the Memory of process and you will fetch the which part is demanded. This is part from the memory called Demand paging.

Thrashing: Thrashing is when the page fault and swapping happens very frequently at a higher rate, and the OS has to spend more time swapping these pages. This state of OS is called thrashing.

Thrashiy Graph.

After a certain time graph decreases bcz as you increase degree of multiprogramming page fault happens and this situation is called Thrashiy.

Page Replacement Algorithms:

Page Replacement:

When page fault occurs . you need to bring the page from Harddisk to RAM and your RAM may not have space for accomodate this page. For TO accomodate this page we need to move one of the existing page from RAM to Harddisk.

Q How did you decide which page to move to bring a new require page ??

A To decide this Particular page (which has to move from RAM to Harddisk) we ~~use~~ need Page Replacement Algorithm.

* PAGE Replacement can be Local or Global.

Local Page Replacement : A process has fixed working state allocated to RAM and when page fault occurs you need to Replace one of the processes pages to Bring a new Page.

This is called Local Strategy for page Replacement Algorithm.

* Local Strategy is the most popular strategy for page Replacement Algo.

Global Page Replacement: You can pick pages of other processes and you move them to disk to bring a new page.

Algorithm for Page Replacement

It doesn't matter you have Global or Local Page Replacement. You need to follow the following Algos.

i) First in First Out (suffers from Belady's Anomaly).

ii) Optimal (you remove that page which is accessed latest from RAM to Harddisk in time).

iii) Least Recently Used. (This is the most popular page replacement algorithm).

If it's not feasible for OS to know which page has access latest in future.

Idea: If a page is being accessed now, it is very possible that it is going to access in near future also.

Most popularly used.

You replace the page which is accessed earliest in time.

41. Segmentation in Memory Management

Segmentation is an alternate of paging.

In paging, we divide our process into small size equal partitions and these equal partition may be there at non-contiguous location. Advantages of paging are our process can be loaded into non-contiguous location also we get to implement virtual memory where we maintain page table and we map these pages.

To frames with main memory.

Segmentation is an alternate to implement both the ideas.

Non-contiguous Allocation of process in main memory and implementing Virtual memory.

Idea: idea of segmentation is to bring the related items together into main memory. and These related items might be of different sizes. Not of the same size as pages.

In segmentation, we divide our process according to user's view. User's view is related items together.

Advantages of Segmentation:

- 1) Your process can be loaded into non-contiguous memory location.
- 2) We can implement virtual memory.

Q How we can load our process into non-contiguous Memory location?

Let's see with the help of Example:

Logical view

Segment 0
Segment 1
Segment 2
Segment 3

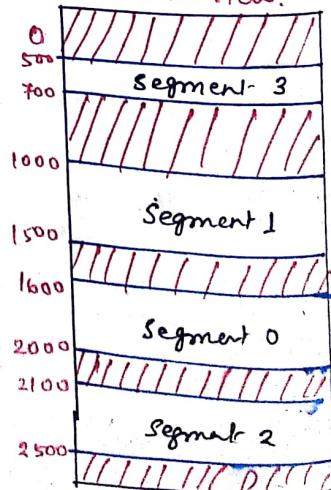
Segment table

	Base	Limit
0	1600	400
1	1000	500
2	2100	400
3	500	200

If the limit is crossed then it will give us error or segmentation fault.

Simple Segmentation: All segments are present.

Physical view



Q. How can we implement virtual memory with use of Segmentation?

Let's see with the help of Example:

We can add Absent (0) present (1) Bit in our segment table.

Then all the segments don't need to present in your main memory.

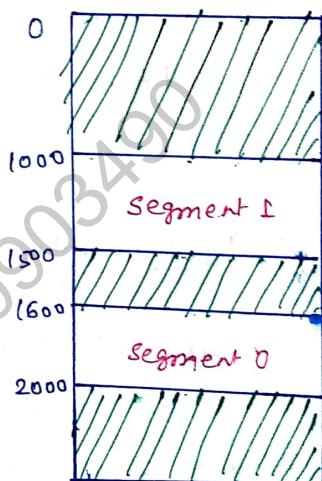
Logical view

Segment 0
Segment 1
Segment 2
Segment 3.

Segment Table.

	Base	Limit	Absent/ Present Bit
0	1600	400	1
1	1000	1500	1
2	/ / / / /	/ / / / /	0
3	/ / / / /	/ / / / /	0

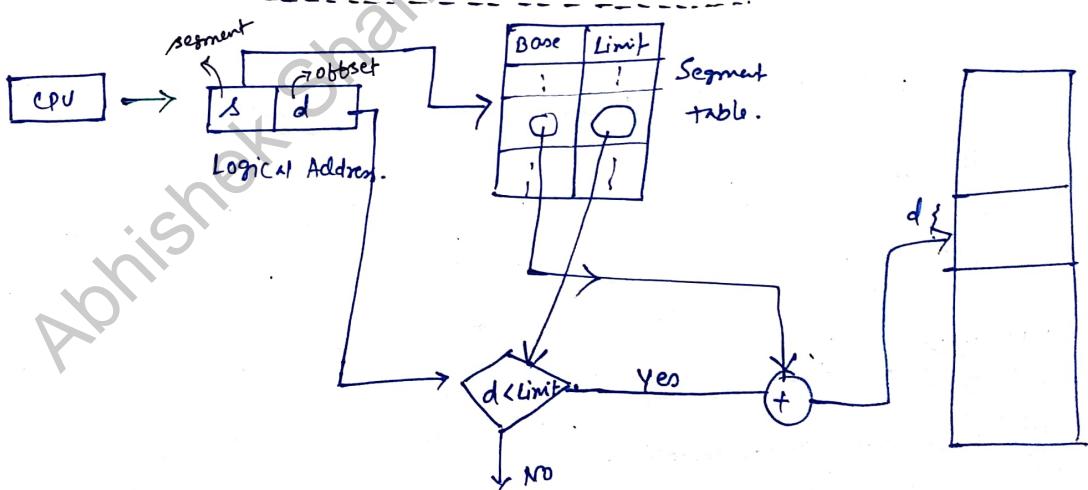
Physical view.



Virtual Memory Segmentation!

All segments need not to be present.

Working of The Segmentation

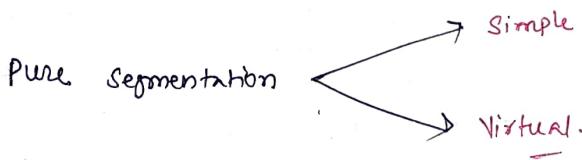


Error or Segmentation fault.

This is how we access particular process through segmentation.

Overview of Segmentation:

Segmentation can be of pure segmentation. All the example we discussed are of pure segmentation. Where we divide our process into segments and we are loading the individual segments as a whole.



* Segmentation with paging: This is implemented in the ~~Architecture~~ Architecture that we generally use. We will talk about it further Lect.

Advantages of Segmentation Over Paging:

- i) No internal fragmentation.
- ii) user view
- iii) Segment table is smaller than page table.
Therefore easier to implement sharing and protection.

Disadvantages:

- i) External fragmentation.

4.2. Segmentation with paging.

Abhishek Sharma Notes.

Ph: 6290903490.

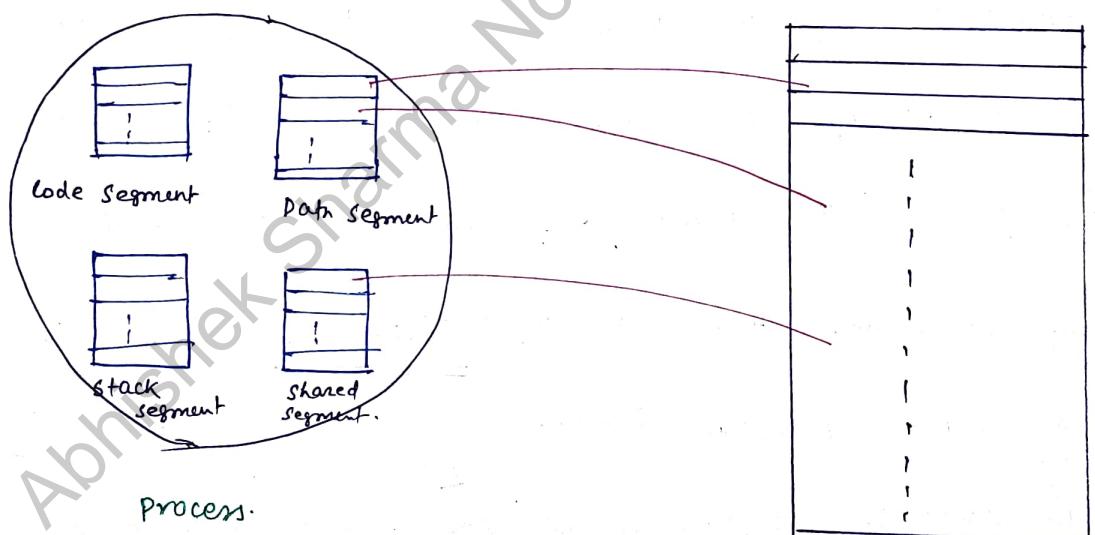
Idea of Segmentation with paging:

In Paging does better memory utilization bcz in segmentation you have External fragmentation (disadvantage).

In Segmentation has the advantages of user view and sharing and production is easier in Segmentation. bcz you do it at the segment level..

So the idea of segmentation with paging is to take the advantages of both the things (above upper mentioned)..

Example Diagram of segmentation with paging.



A Process is divided into some segments and each individual segment has some pages.

- Q1 How we will map these segment pages (Logical Address) to our physical memory Address ??

Q How we will map now
Logical Address to physical
Memory Address ??

Abhishek Sharma notes.
Ph. 6290903490

A Now we have Both Segment table and Page table.
For a single process we have our own segment table.
When we switch context from one process to other processes there is a register in CPU which is set for context switching. named Segment Base Register.
This Register gives us base address of the segment table. That is how we will figure out where is the segment table of our process. Using this segment table we go to the page Table and using this page table we go to the frame no. And once we go to the frame no. We add the offset (d) to go to the actual physical Address.



The last bits of the virtual Address are called offset. Which is the location difference b/w the byte address we want and the start of the page.

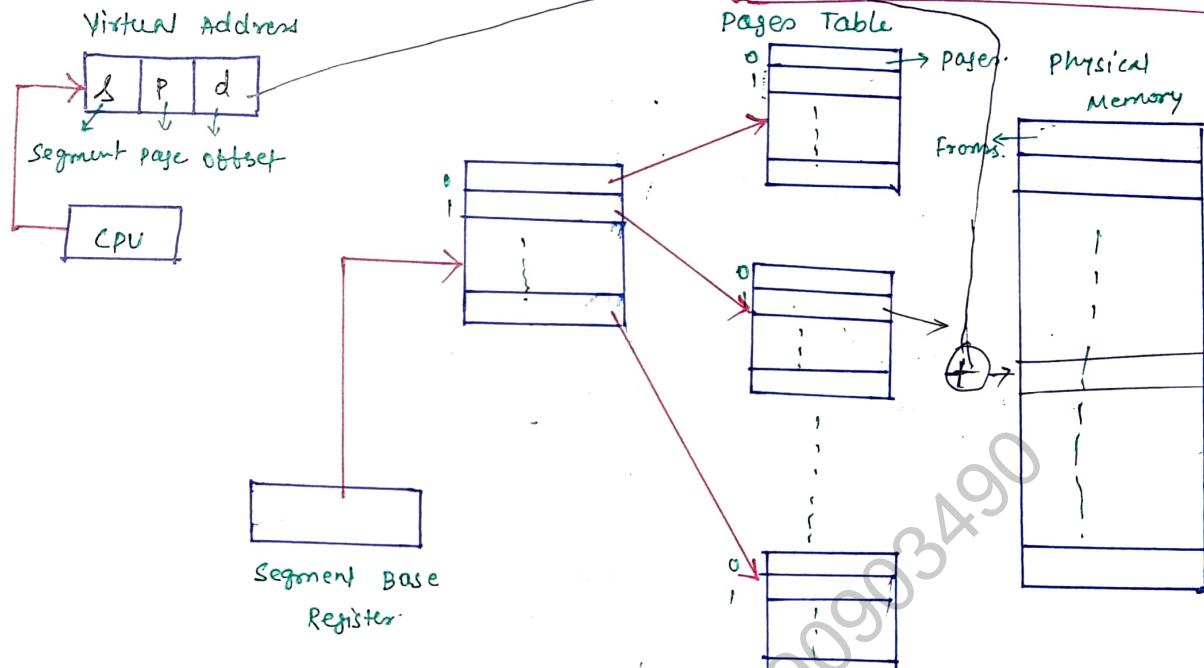
Disadvantages:

Segmentation with paging causes too lookups.
We generally use segmentation with paging.

* Working of Segmentation with paging.

Abhishek Sharma Notes.

Ph: 6290903490.



Single process

The end of operating system.

Thank you for supporting me guys.
😊

Date: 28/09/2021

12:40 AM.

Join the group and share the group with your near and dear once.

Thank you

Abhishek Sharma.

3rd year undergraduate at
NIT Durgapur.

Best of Luck!
If you like my notes then please
go to the group and share your thoughts.