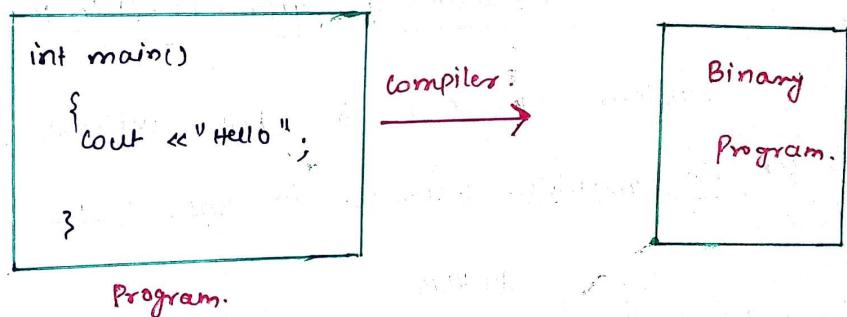


Program: A program is a file. It resides on your harddisk. We need a compiler to convert of our program to Binary program. and this Binary program exists on your file. If you are using Linux then it exists as .out file and in windows it might exist as .exe file.

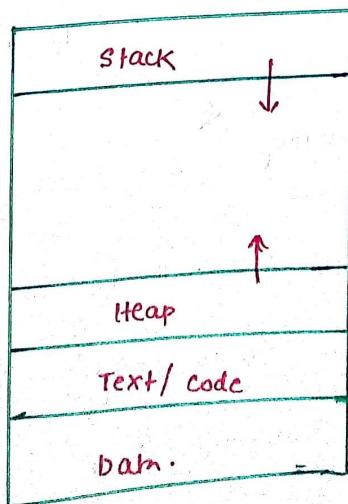
This Binary program is loaded into ram and run by the processor.

Process

Program →



process: A process is a program in execution. When a program goes to Ram and starts running then becomes a process.



process.

* Single Tasking System (MS-DOS).

In single tasking system better utilization of computer (you like to task more command) doesn't happen. We can't do multiple process in the Ram. that's why ~~Multi-tasking~~ System Programming came into picture.

* Multitasking System. (5-state Model)

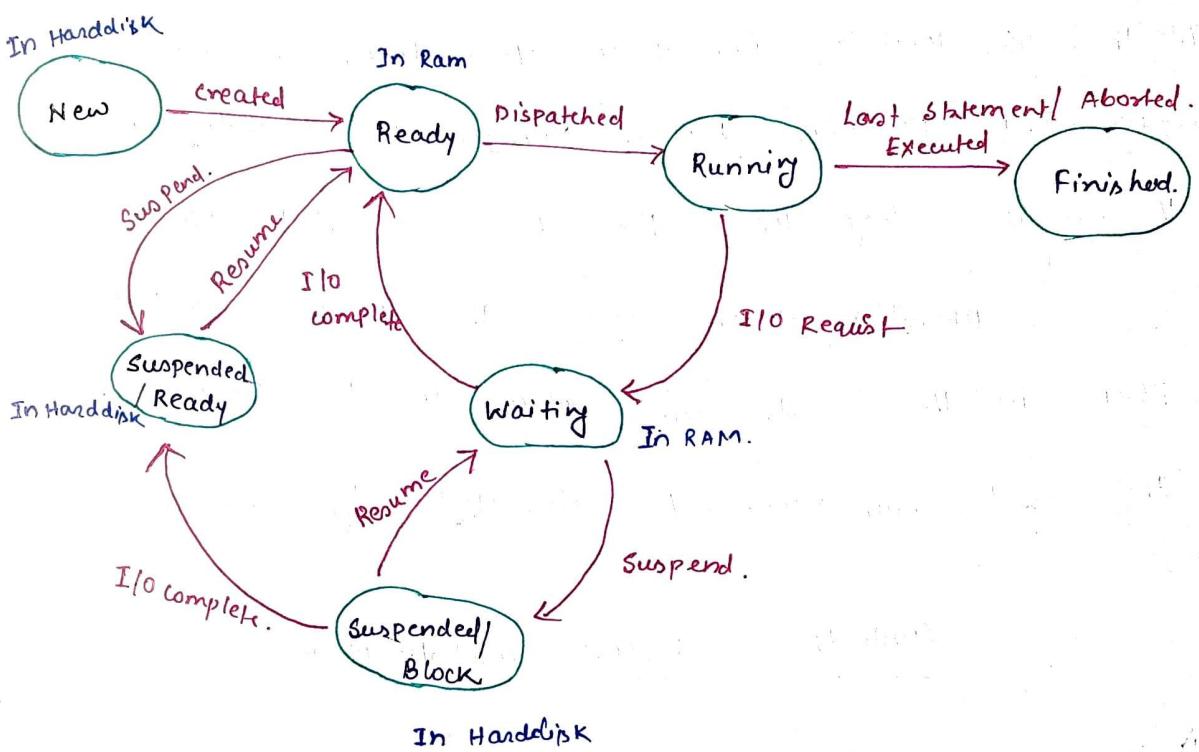
In this System, we can do better utilization of our computer. We can do multiple processes in RAM other than the OS.



In this 5 state Model first program will be in Harddisk and it goes in the Ram and then it is running if it find any higher priority or program will time out then it we return back to Ready area again. After this if program is Running and I/O Request happens then it will wait for it. again it goes to Ready State and Running State and then last statement happened and program finished. (if anything error msg. happened I/O i.e. then Aborted).

7 - States Model.
 (Multiprogramming system).

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In the 7 state model we are moving some of the waiting processes to the Harddisk bcz we want to run more processes, we want to increase the degree of multiprogramming.

If a program's is waiting for in the Ram then and if you all process I/O

Want to run some other process you take out one of the waiting process from waiting for I/O to Harddisk. So that you can run more processes. (Multiprogramming). If it's I/O

is completed then it moves to (suspended Ready state).

And if your RAM is free then it goes to Ready state as usual. Ready Process might return back to suspended / Ready (in Harddisk) bcz it might happen some higher priority task which has to run. This is about 7 states Model.

Q8. Process Control Block.

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This is the most central Datastructure of your operating system. All the OS module i.e. if it is I/O module, or memory management module, process Management module, all of the module they use the process control block.

Operating system stores the process control block in the most secure place in the memory. So they ~~can't~~ can never be corrupted by any user process.

Contents of process control block.

i) Process ID: It is a unique ID assigned to every process by operating system. It is of integer type. It can be of 32-bit, 64-bit (depends upon OS).

ii) process state: It might be ready, it might be running. We have talked this previously.

All the information related to that  stores in the process state.

iii) CPU Registers: When you have process in memory it might using some CPU Registers when it was running. One important Register is program counter. (which tells the next instruction to be executed.).

iv) Account information:

Account information is something like how much time CPU has consumed so far. More information related to system can also be stored in this field.

v) I/O Information:

What all I/O's it is using. What is the status of the I/O's.

vi) CPU scheduling Information:

All the CPU scheduling information will be kept here.

vii) Memory Information:

Where all memory blocks allocated for the process. Where were the memory blocks where the information is stored of Harddisk. All this informations are stored in Memory Information.

There are many more contents in process control.

Q9. Process Scheduler.

When we have movement from one process state to other process state. Process Schedulers do these things.

i) Long Term Scheduler:

Brings Process from Disk to RAM.

Basically it moves process to Ready state. Once the process is come into the RAM it is in Ready state.

ii) Short Term Scheduler:

Brings Process from Ready to Running state.

iii) Medium Term Scheduler:

Brings Process from Waitly state to

That we seen 2 extra steps in 7-state model. Suspended block state and it also resumes it and it also brings the process from Ready state to Suspend/Ready state.

10. Background for scheduling Algorithms.

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Queues in operating system: There are different Queue in OS.

The most important queue for scheduling perspective is Ready Queue.

Since there are multiple process in the Ready state. we put them all in a queue and it is called Ready Queue.

Job Queue: ~~Any~~ of jobs which are to be created as process.
Queue

I/O Queue: This queue is for I/O devices.

Here in Scheduling Algorithms we only Read about
Ready Queue we only focus about on Ready Queue.

Short Term Scheduler: It's job is to pick one of the processes from Ready Queue. Then Dispatcher comes into the picture.

Dispatcher: It makes the program jump to the line where to begin with. Exmpl. A program might gone in the waiting state then when it resumes it begins from the next line. This work is done by the Dispatcher.

* These algorithms are only for short term schedules
Or for the jobs in the Ready Queue.

When we are talking about scheduling Algorithms, we are

Q) When is short time scheduler called?

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- dr a) When some other process moves from running to waiting.
- b) When some other process moves from running to ready.
- c) When a new/existing process moves to ready state.
↳ (higher priority process).
- d) When a process terminates.

Different Times in scheduling Algorithms.

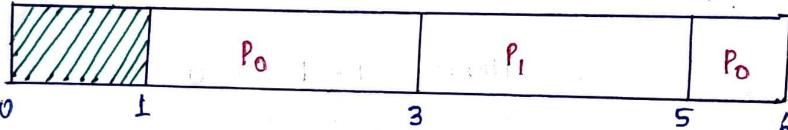
Time frame in CPU is scheduling are generally represented in DENT chart

Gantt

In DENT chart we represent the activity of CPU.

Example: of Gantt CHART.

Activity of CPU



Time →

CPU is free During this Time. P₀ is scheduled (1 to 3) Time. P₁ is scheduled (3 to 5) Time. P₀ is again scheduled. (5 to 6) Time.

When we Analysis Process P₀,

i) Arrival Time: (when P₀) is arrived : 1 Point of Time.

ii) Completion Time: (when process P₀ is completed) : 6 frames.

iii) Burst Time: (Time of CPU that the process takes) : 3 Difference b/w Two frames.

$$\text{Here for } P_0 \text{ CPU takes } 1 \rightarrow 3 = 2 \\ 5 \rightarrow 6 = 1 \quad \} = 3 \rightarrow (2+1)$$

iv) Turn Around Time: (Difference b/w completion time and Arrival Time).
= (completion Time - Arrival Time)
= (6 - 1) = 5 unit. time. for P₀

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v) Waiting Time: The Time that the process spends in ready Queue.

Here P_0 is waiting when P_1 starts processes. Hence $(3 \rightarrow 5 P_0)$ is waiting.

$$= 2 \text{ unit of Time.}$$

$$\text{Formula} = \text{Turn Around} - \text{Burst Time} \Rightarrow 5 - 3 = 2$$

$$= 2 \text{ units of Time for } P_0$$

vi) Response Time: Difference b/w Arrival Time and The first time when the process gets in CPU.

Difference
b/w Two
frames.

Here the process P_0 arrived at time 1 and gets into the CPU at time 1.

$$\text{Hence } 1 - 1 = 0$$

$$= 0 \text{ unit of Time.}$$

* Goals of a Scheduling Algorithms.

i) Max CPU utilization

ii) Max Throughput (No. of jobs finished per unit of time).

iii) Min Turnaround Time. (Discussed earlier).

iv) Min. waiting Time. (" " ")

v) Min. Response Time. (" " ")

vi) Fair CPU Allocation. (NO starvation)

→ (There is a job which is not picked by any short term scheduler for long time b/c there are many jobs)

11. FCFS Scheduling.

Abhishek Sharma Notes

NOW we will see Different Scheduling Algorithms.

FCFS: FCFS is the simplest scheduling algorithm. The idea is

the process comes first is scheduled first.
that

Example:

we have some processes like this

Process	Arrival Time	Burst Time
P ₀	0	2
P ₁	1	6
P ₂	2	4
P ₃	3	9
P ₄	4	12

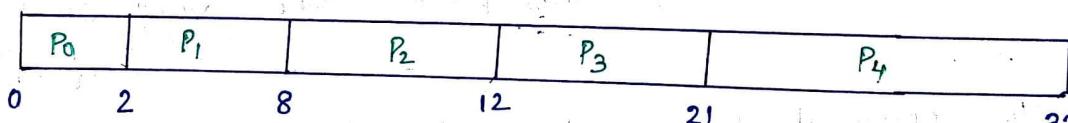
FCFS is non-preemptive process.

the process that takes

Time for CPU

When you assign process to a processor, you can't turn around back.

Let's draw Gantt chart for the processes



NOW From this information we will complete the Analysis of Algorithm.

Process	Arrival Time	Burst Time	Completion Time	Turn Around Time	Waiting Time	Avg. Waiting Time	Avg. Turn Around Time
P ₀	0	2	2	2	0	0	
P ₁	1	6	8	7	1	$(0+1+6+9+17)$	$\frac{29}{5}$
P ₂	2	4	12	10	6	$\frac{12}{5}$	5
P ₃	3	9	21	18	9	$\frac{21}{5}$	$\frac{74}{5}$
P ₄	4	12	33	29	17	$\frac{33}{5}$	

Avg. Waiting Time: How much time every process is spending in the ready queue waiting for the processor to get.

Avg. Turn Around Time: How much time every process is spending on your system.

* Some important points about FCFS Algorithm.

- i) Simple and easy to implement.
- ii) Non-preemptive. (If you assign a process to the processor you can't take it back).

and This causes certain problem.
i.e. convoy Effect.

- iii) Convoy Effect: (It might happens that when you using FCFS, it might happens that their is CPU Bond Process)

This process takes lot of time of CPU.

and along with CPU Bond process there might be multiple I/O Bond processes.

→ This process takes very small amount of time.

As CPU Bond process is scheduling before I/O Bond.

So it will execute process first and I/O Bond process have to wait for the CPU for execution.

This is 'convoy' effect. (Like in convoy, some V.I.P persons, small persons have to wait).

This problem occurs in FCFS scheduling.

- iv) Avg. waiting Time: Avg. waiting time for FCFS might not be good some time. (If

You have CPU Bond Process before I/O Bond Process) bcz you have to wait for more time.

12. Shortest Job First Algorithms.

Abhishek Sharma Notes

In FCFS Algo. we have some problem like convoy Effect.
(i.e. I/O Bound Processes have to wait for CPU Bound processes to finish).

The idea of shortest job first Algorithms is to consider the jobs in increasing order of their CPU Burst Time.

* we have all the jobs and their Burst Time and we have to consider them in their increasing order of their need CPU Burst Time. so that other jobs do not have to wait for too long.

* There are Two versions of shortest job first

i) preemptive

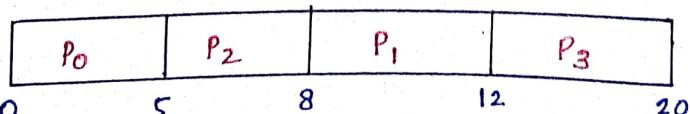
ii) non-preemptive.

Non-Preemptive Shortest Job First Algorithms:

Process	Arrival Time	Burst Time.
P ₀	0	5
P ₁	1	4
P ₂	2	3
P ₃	3	8

Granting quantum.

This is non-preemptive
(we can't go back)



and then P₃ it
filled and so on.

After P₀ we will find which Process has Least Burst Time. that is P₂(3)
So it is filled, after P₂ we will see which " " " " " " " " " " " " P₁(4).