

Case Study : Laminar Heated Channel Flow Using FVM and SIMPLE

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% Finite Volume Method with SIMPLE algorithm

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clear,clc,close all

global Fw Fe Fs Fn DF aW aE aS aN aP bP dU dV

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% CHANNEL FLOW PROBLEM WITH CONSTANT TEMPERATURE OR HEAT FLUX WALLS

% Geometry

H = 0.01; % Height of channel in y-direction(m)

L = 10*H; % Length of cavity in x-direction (m)

% Grid geometry

Nx = 200; % Number of main grid points in x-direction within domain

dx = L/Nx; % Grid spacing in x-direction

Ny = 40; % Number of main grid points in y-direction within domain

dy = H/Ny; % Grid spacing in y-direction

dz = 0.01; % Width in z-direction for flux calculations (m)

x = dx/2:dx:L-dx/2; % x-locations of main grid points (m)

xu = 0:dx:L; % x-locations of u-velocities (m)
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y = dy/2:dy:H-dy/2; % y-locations of main grid points (m)

yv = 0:dy:H; % y-locations of v-velocities (m)

iu = 1:Nx+1; Ju = 2:Ny+1; % Interior node numbers for u

lv = 2:Nx+1; jv = 1:Ny+1; % Interior node numbers for v

lp = 2:Nx+1; Jp = 2:Ny+1; % Interior node numbers for p

iF = 2:Nx; jF = 2:Ny; % Node numbers for face flow (or advection)

% Properties (air at STP)

rho = 1.2; % Density (kg/m^3)

mu = 1.8e-5; % Absolute viscosity (N-s/m^2)

nu = mu/rho; % Kinematic viscosity (m^2/s)

kt = 0.025; % Thermal conductivity (W/m-K)

cp = 1006; % Specific heat (J/kg-K)

alpha = kt/(rho*cp); % Thermal diffusivity (m^2/s)

Pr = nu/alpha; % Prandtl number

% Boundary conditions

Re = 100; % Reynolds number

U = Re*nu/(2*H); % Average velocity(m/s)

Ti = 20; % Inlet temperature (deg. C)

Tw = 100; % Wall temperature (deg. C)

qw = 100; % Wall heat flux (W/m^2)

BC_N = 1; % BC_N = 0 for Tw, BC_N = 1 for qw

BC_S = 1; % BC_S = 0 for Tw, BC_S = 1 for symmetry

% Solution controls

alphaU = 0.3; % Velocity relaxation (under)

alphaP = 0.2; % Pressure relaxation (under)

NmaxSIM = 1e+4; % Iteration max for SIMPLE algorithm (-)

NmaxGSI = 1e+1; % Iteration max for numerical method (-)

err = 1e-5; % Convergence criteria (-)

div = 1e+1; % Divergence criteria (-)

% Initialize u, v, p, T, F, a, and residual matrices

u = zeros(Nx+1,Ny+2); v = zeros(Nx+2,Ny+1);

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uStar = zeros(Nx+1,Ny+2); vStar = zeros(Nx+2,Ny+1);

uPrime = zeros(Nx+1,Ny+2); vPrime = zeros(Nx+2,Ny+1);

dU = zeros(Nx+1,Ny+2); dV = zeros(Nx+2,Ny+1);

T = zeros(Nx+2,Ny+2);

p = zeros(Nx+2,Ny+2);

pPrime = zeros(Nx+2,Ny+2);

Fe = zeros(Nx+1,Ny+1); Fw = zeros(Nx+1,Ny+1); % Flow coefficients

Fn = zeros(Nx+1,Ny+1); Fs = zeros(Nx+1,Ny+1);

DF = zeros(Nx+1,Ny+1);

aE = zeros(Nx+1,Ny+1); aW = zeros(Nx+1,Ny+1); % Coefficients for

aN = zeros(Nx+1,Ny+1); aS = zeros(Nx+1,Ny+1); % discretized equations

aP = zeros(Nx+1,Ny+1); bP = zeros(Nx+1,Ny+1);

ures = zeros(NmaxSIM,1); % Residual for u

vres = zeros(NmaxSIM,1); % Residual for v

pres = zeros(NmaxSIM,1); % Residual for pPrime

% Inlet velocity for uniform flow at inlet

u(:,Ju) = U;

% Initialize to inear pressure drop for fully developed flow

p1 = 12*mu*U*L/(2*H)^2;

p(lp,Jp) = ones(Nx,Ny).*linspace(p1,0,Nx)';

% Initialize temperature to inlet and wall temperatures

T(:,Jp) = Ti; T(:,1) = Tw; T(:,Ny+2) = Tw;

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% SIMPLE algorithm

% Constant diffusion coefficients

Dx = (mu/dx)*dy*dz;

Dy = (mu/dy)*dx*dz;

for n = 1:NmaxSIM

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% Initial guess

uOld = u;

vOld = v;

pStar = p;

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% STEP 1a: solve x-momentum as uStar

% Setup coefficients

FVM_u(Nx,Ny,dx,dy,dz,rho,Dx,Dy,iF,Ju,alphaU,uOld,vOld,pStar,BC_S);

% Use previous calculation as initial guess in numerical method

[uStar,ures(n)] = FVM_GS_ext_mesh(Nx,Ny+1,alphaU,NmaxGSI,err,uOld);

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% STEP 1b: solve y-momentum as vStar

% Setup coefficients

FVM_v(Nx,Ny,dx,dy,dz,rho,Dx,Dy,lv,jF,alphaU,u,v,pStar)

% Use previous calculation as initial guess in numerical method

[vStar,vres(n)] = FVM_GS_ext_mesh(Nx+1,Ny,alphaU,NmaxGSI,err,vOld);

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% STEP 2: Solve pressure correction equation (PCE)

% Setup coefficients

FVM_pcorr(Nx,Ny,dx,dy,dz,rho,lp,jp,uStar,vStar)

% Use numerical method to calculate pressure correction

pPrime(:, :) = 0;

[pPrime,pres(n)] = FVM_GS_ext_mesh(Nx+1,Ny+1,1,NmaxGSI,err,pPrime);

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% STEP 3: calculate corrected pressure and velocity

% p corrections with under-relaxation

p(lp,jp) = pStar(lp,jp) + pPrime(lp,jp)*alphaP;

% u corrections

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[illegible]

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% POST PROCESSING

figure('Name','Convergence Plot for Scaled Residuals',...
'Position',[100 100 500 300])

% Convergence plot

nlist = 10:n;

semilogy(nlist,ures(nlist),'-b',nlist,vres(nlist),'-r',...
nlist,pres(nlist),'-g')

legend('u residual','v residual','p residual')

xlabel('Iteration')

ylabel('Scaled Residual')

FVM_Vplot(Nx,Ny,x,xu,y,H,u(iu,Ju),v(lv,jv),p(lp,Jp),U)

FVM_Tplot(Nx,Ny,x,y,L,H,rho,cp,u(iu,Ju),T(lp,Jp),U,Ti,Tw,qw,BC_N)

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Figure 1 convergence plot for scaled residuals

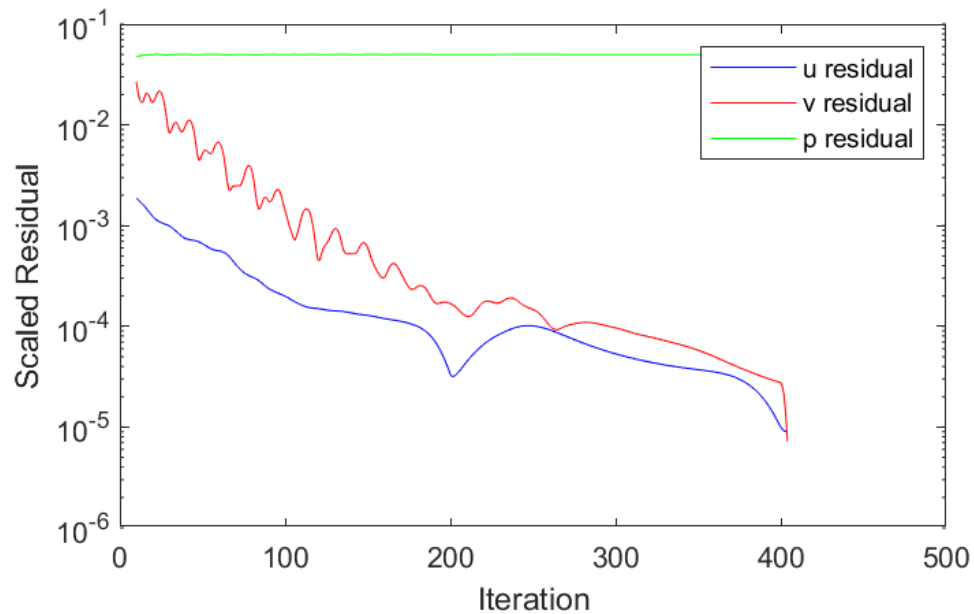


Figure 2 velocity and contour plots

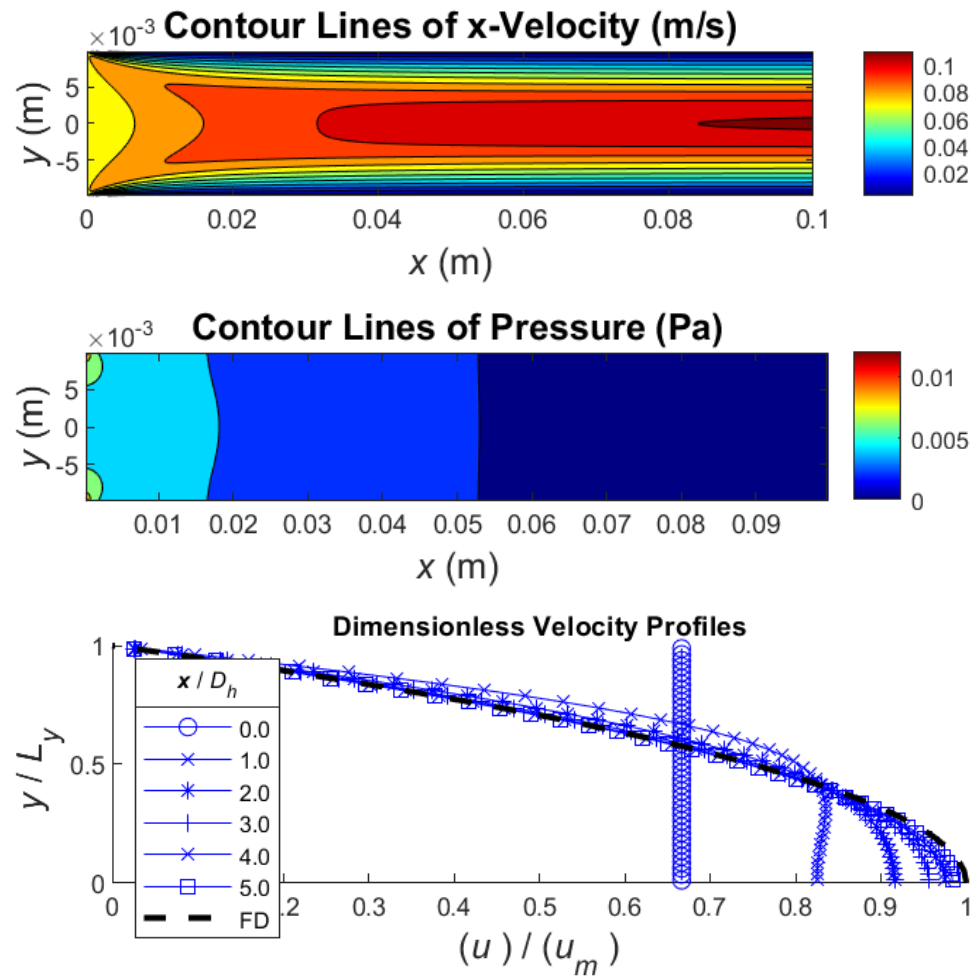


Figure 3 constant surface heat flux

