

Keras 1장

Neural networks foundations

오세진

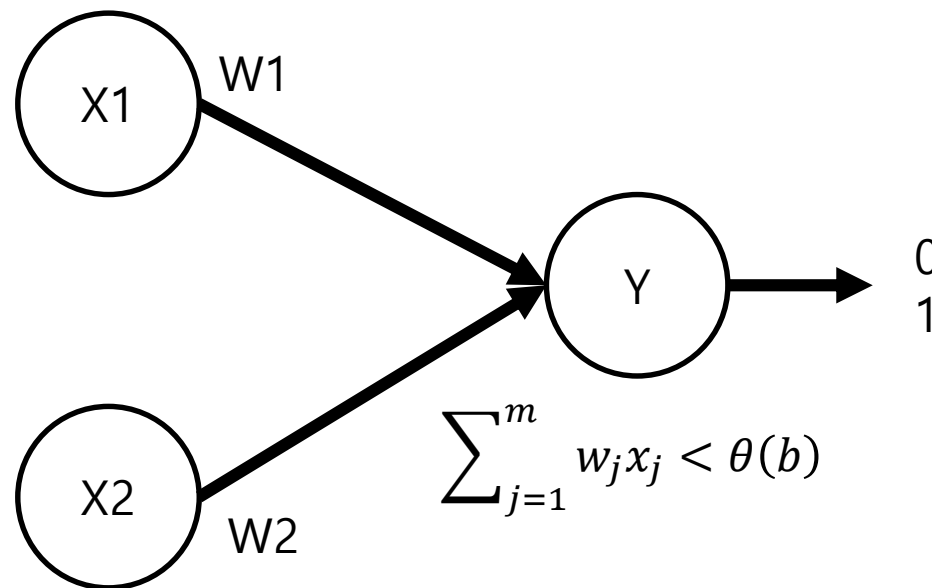
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3. Backpropagation

Perceptron

정의

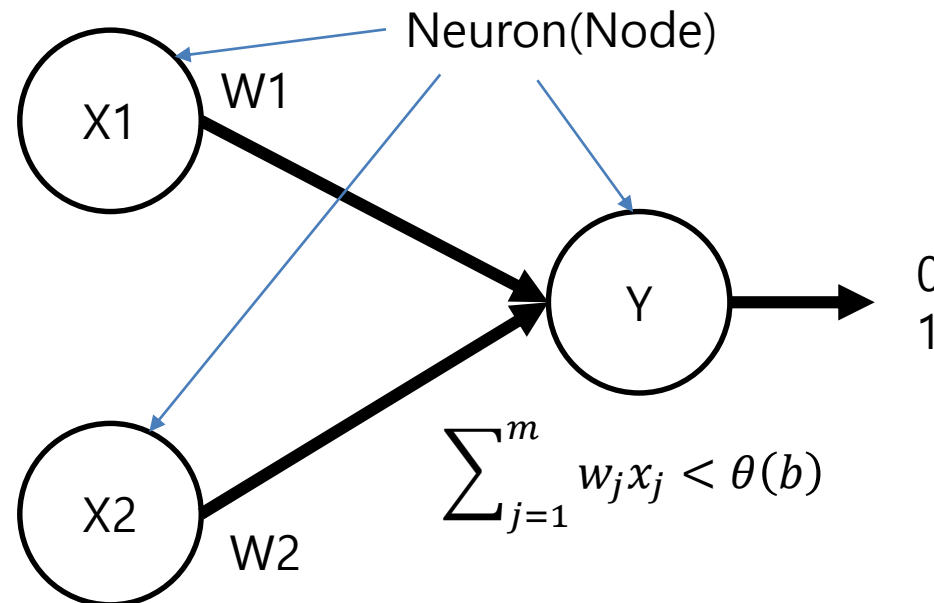
- Simple algorithm which, given an input vector x outputs either 1 (yes) or 0 (no)



Perceptron

정의

- Simple algorithm which, given an input vector x outputs either 1 (yes) or 0 (no)



Perceptron

정의

- Simple algorithm which, given an input vector x outputs either 1 (yes) or 0 (no)

$$f(x) = \begin{cases} 1 & wx + b > 0 \\ 0 & \text{otherwise} \end{cases}$$

입력별 가중치

$$wx = \sum_{j=1}^m w_j x_j$$

b : bias

w : weight

Perceptron

정의

- Simple algorithm which, given an input vector x outputs either 1 (yes) or 0 (no)

$$f(x) = \begin{cases} 1 & wx + b > 0 \\ 0 & \text{otherwise} \end{cases}$$

입력 벡터

$$wx = \sum_{j=1}^m w_j x_j$$

b : bias

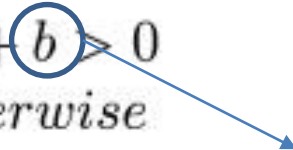
w : weight

$$\begin{bmatrix} x_1 \\ \cdot \\ \cdot \\ \cdot \\ x_m \end{bmatrix}$$

Perceptron

정의

- Simple algorithm which, given an input vector x outputs either 1 (yes) or 0 (no)

$$f(x) = \begin{cases} 1 & wx + b > 0 \\ 0 & \text{otherwise} \end{cases}$$


Activation 강도 조절

$$wx = \sum_{j=1}^m w_j x_j$$

b : bias

w : weight

Perceptron

-Simple and multilayer

AND

| x1 | x2 | y |
|----|----|---|
| 0 | 0 | 0 |
| 0 | 1 | 0 |
| 1 | 0 | 0 |
| 1 | 1 | 1 |

NAND

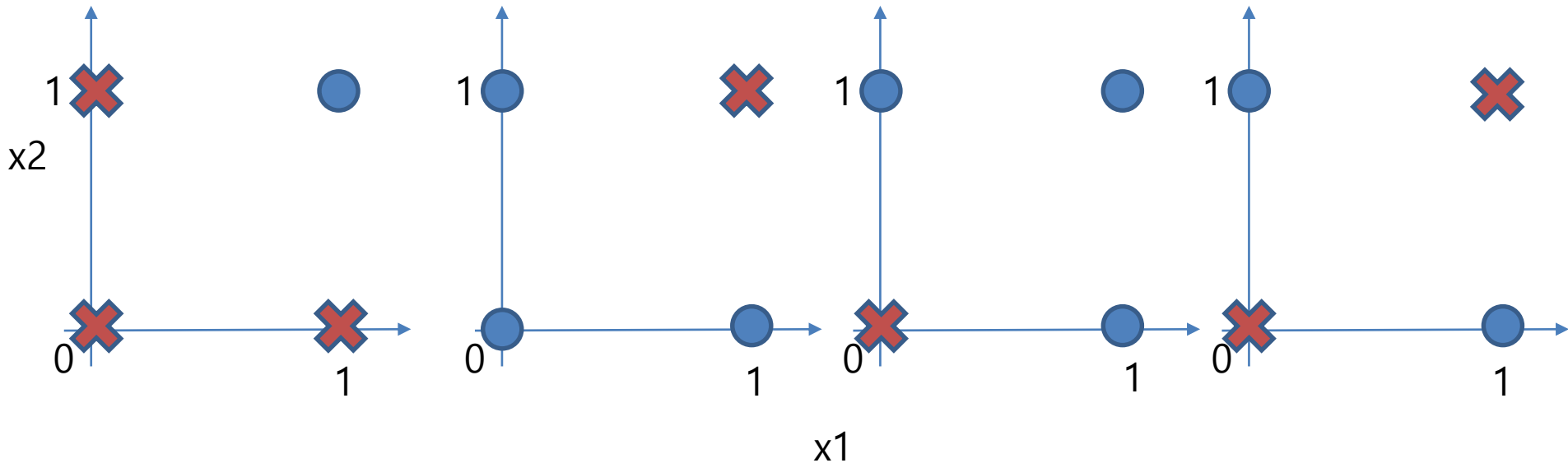
| x1 | x2 | y |
|----|----|---|
| 0 | 0 | 1 |
| 0 | 1 | 1 |
| 1 | 0 | 1 |
| 1 | 1 | 0 |

OR

| x1 | x2 | y |
|----|----|---|
| 0 | 0 | 0 |
| 0 | 1 | 1 |
| 1 | 0 | 1 |
| 1 | 1 | 1 |

XOR

| x1 | x2 | y |
|----|----|---|
| 0 | 0 | 0 |
| 0 | 1 | 1 |
| 1 | 0 | 1 |
| 1 | 1 | 0 |



Perceptron

- Simple and multilayer

Simple

AND

| x1 | x2 | y |
|----|----|---|
| 0 | 0 | 0 |
| 0 | 1 | 0 |
| 1 | 0 | 0 |
| 1 | 1 | 1 |

NAND

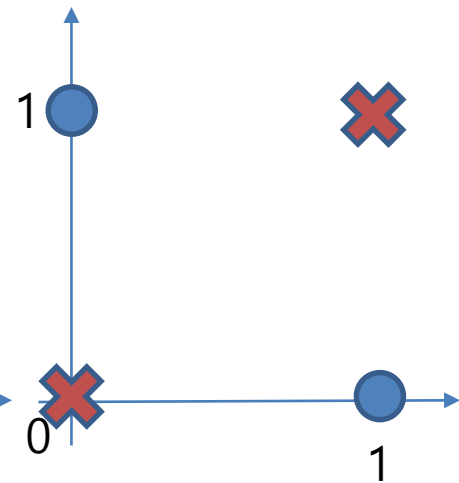
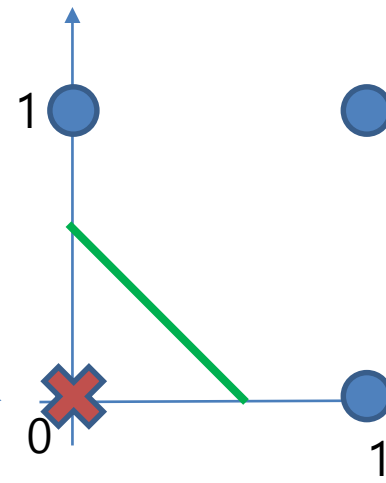
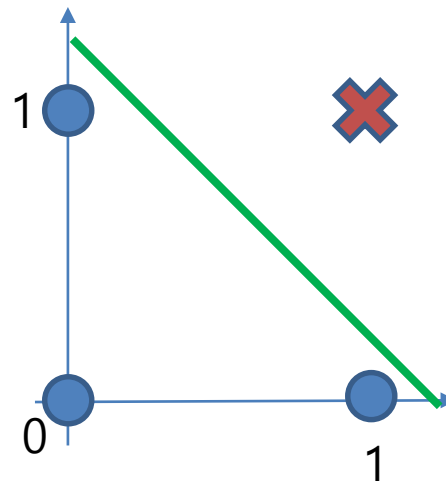
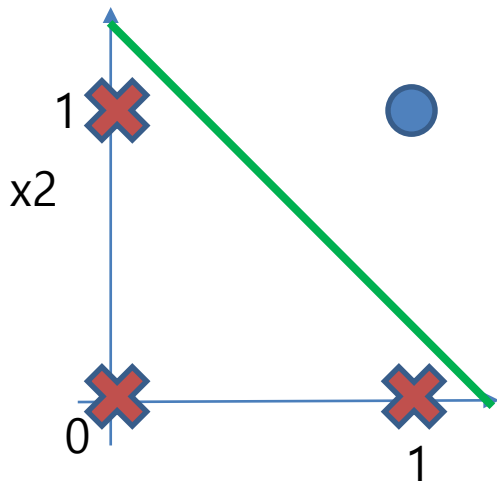
| x1 | x2 | y |
|----|----|---|
| 0 | 0 | 1 |
| 0 | 1 | 1 |
| 1 | 0 | 1 |
| 1 | 1 | 0 |

OR

| x1 | x2 | y |
|----|----|---|
| 0 | 0 | 0 |
| 0 | 1 | 1 |
| 1 | 0 | 1 |
| 1 | 1 | 1 |

XOR

| x1 | x2 | y |
|----|----|---|
| 0 | 0 | 0 |
| 0 | 1 | 1 |
| 1 | 0 | 1 |
| 1 | 1 | 0 |



x1

Perceptron

-Single and multilayer

Simple

Multilayer

AND

| x1 | x2 | y |
|----|----|---|
| 0 | 0 | 0 |
| 0 | 1 | 0 |
| 1 | 0 | 0 |
| 1 | 1 | 1 |

NAND

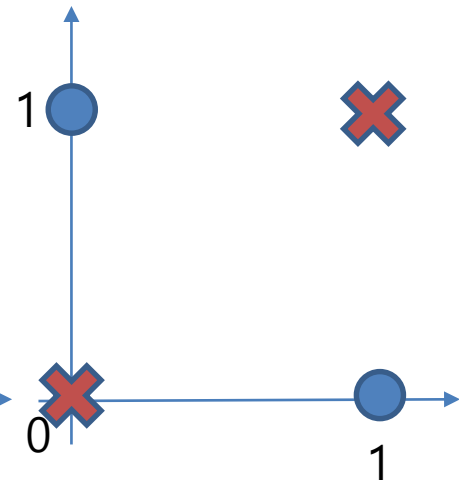
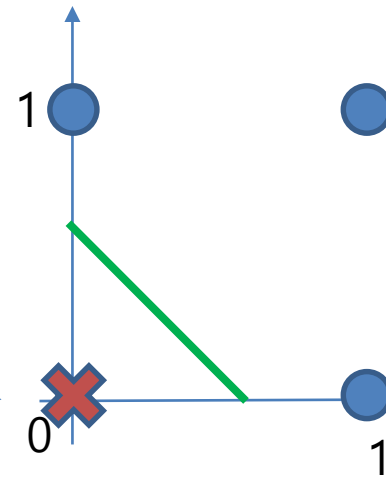
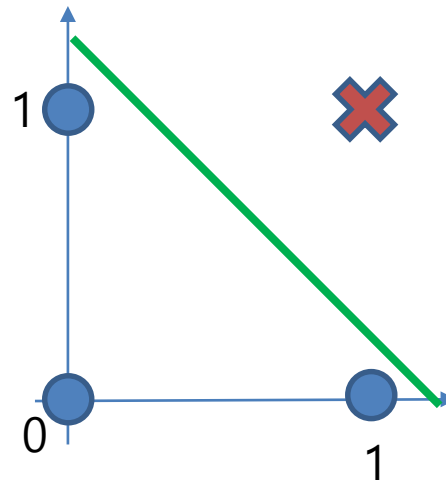
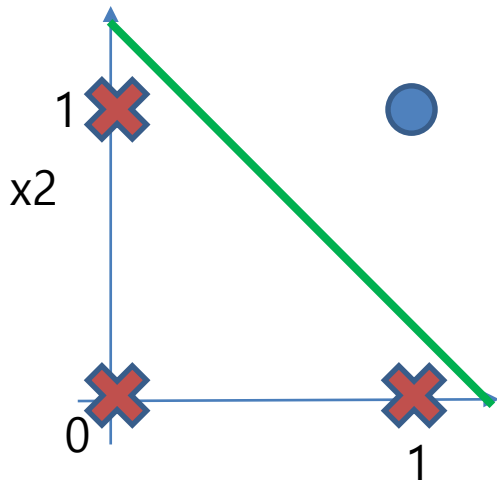
| x1 | x2 | y |
|----|----|---|
| 0 | 0 | 1 |
| 0 | 1 | 1 |
| 1 | 0 | 1 |
| 1 | 1 | 0 |

OR

| x1 | x2 | y |
|----|----|---|
| 0 | 0 | 0 |
| 0 | 1 | 1 |
| 1 | 0 | 1 |
| 1 | 1 | 1 |

XOR

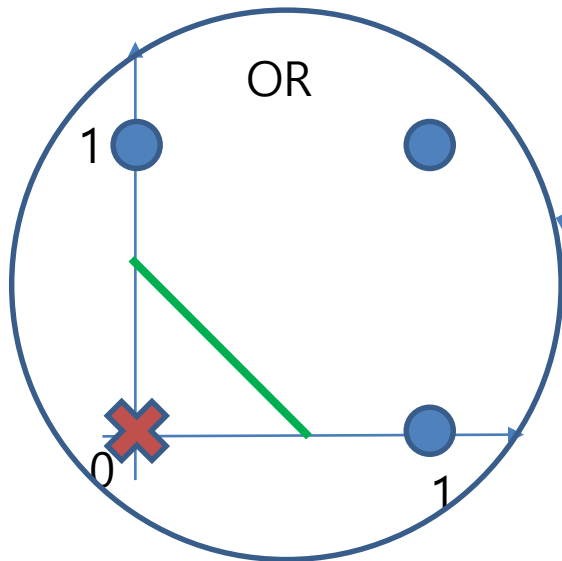
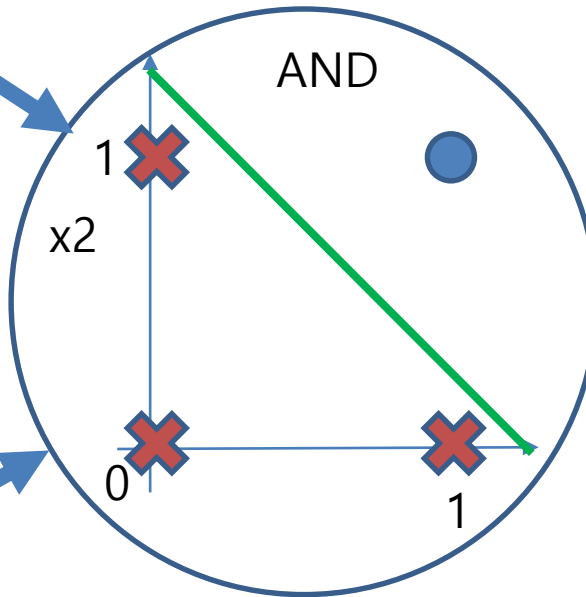
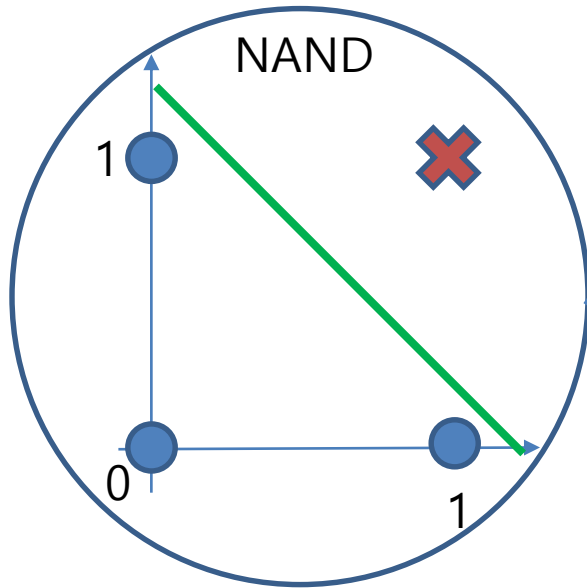
| x1 | x2 | y |
|----|----|---|
| 0 | 0 | 0 |
| 0 | 1 | 1 |
| 1 | 0 | 1 |
| 1 | 1 | 0 |



x_1

Perceptron

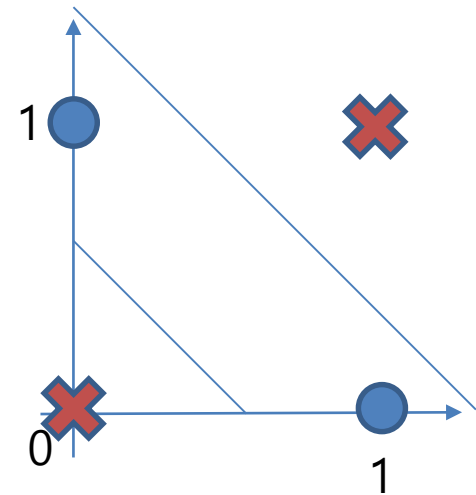
-Single and multilayer



Multilayer

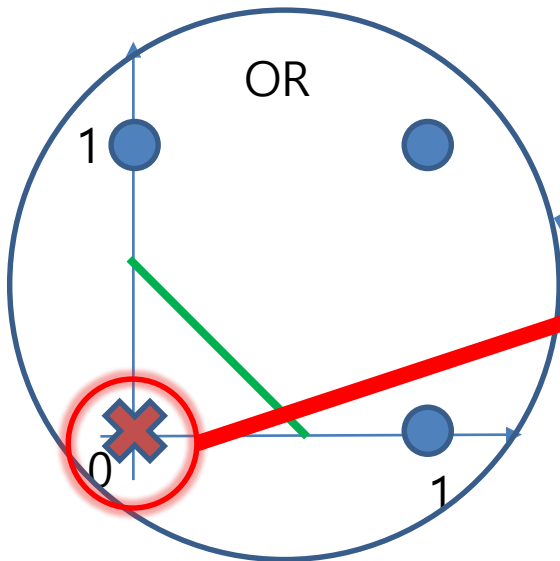
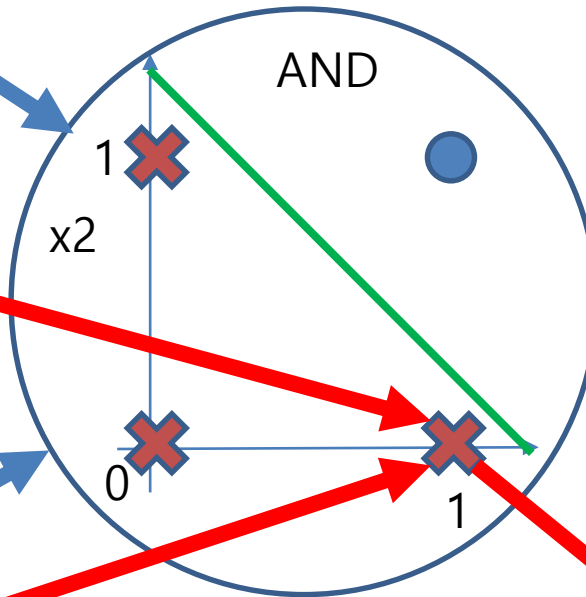
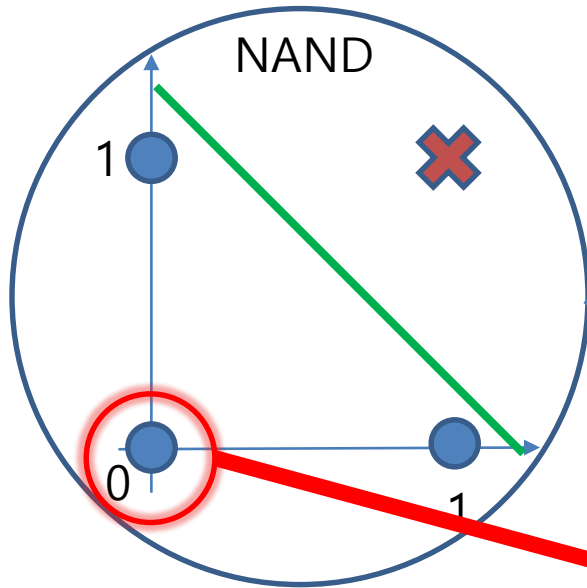
XOR

| x1 | x2 | y |
|----|----|---|
| 0 | 0 | 0 |
| 0 | 1 | 1 |
| 1 | 0 | 1 |
| 1 | 1 | 0 |



Perceptron

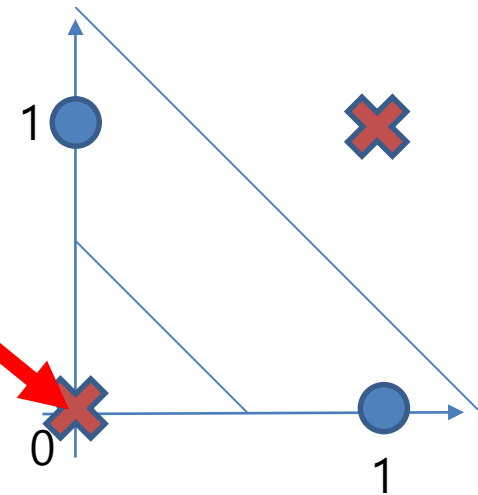
-Single and multilayer



Multilayer

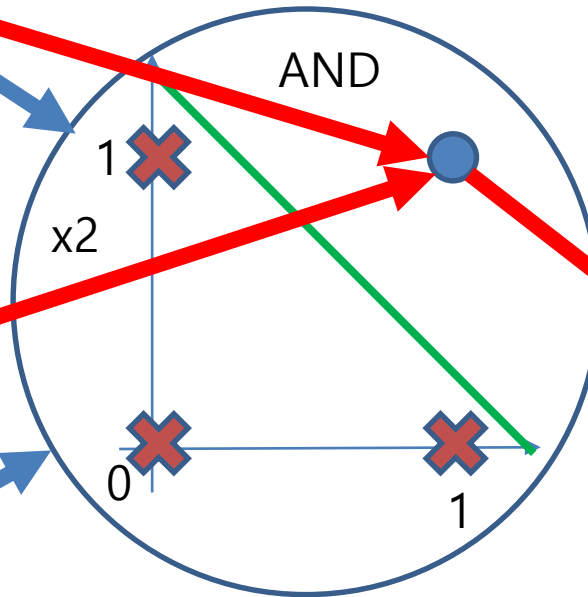
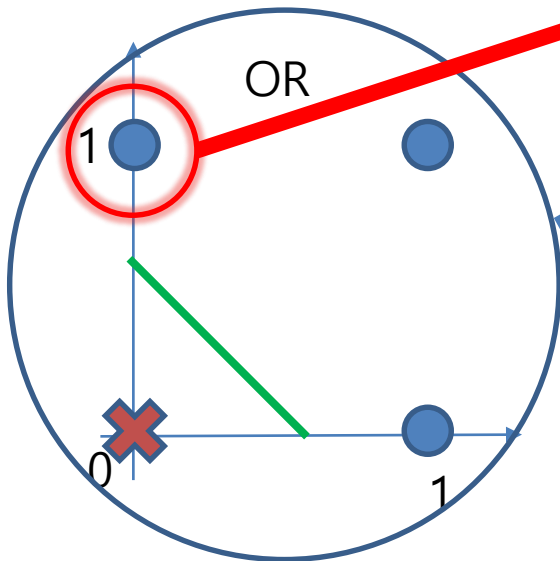
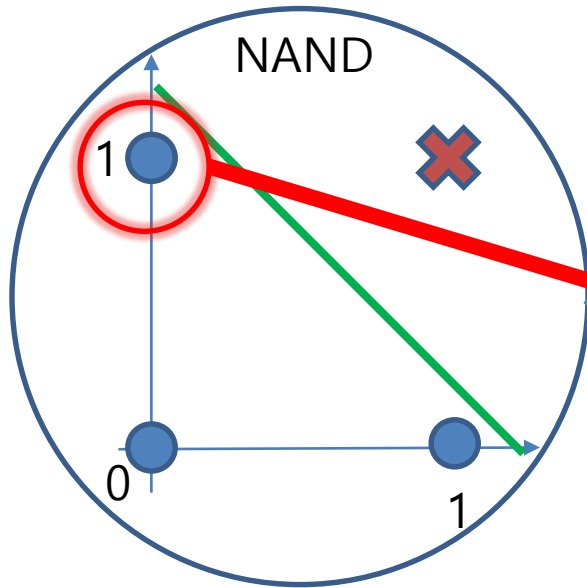
XOR

| x1 | x2 | y |
|----|----|---|
| 0 | 0 | 0 |
| 0 | 1 | 1 |
| 1 | 0 | 1 |
| 1 | 1 | 0 |



Perceptron

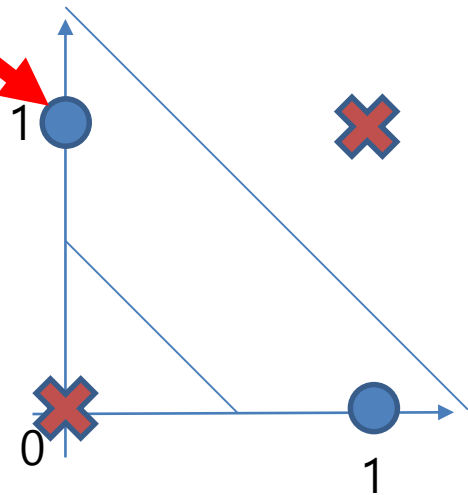
-Single and multilayer



Multilayer

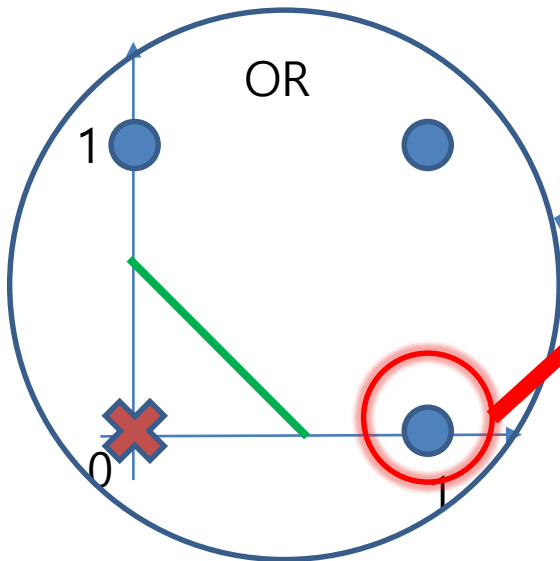
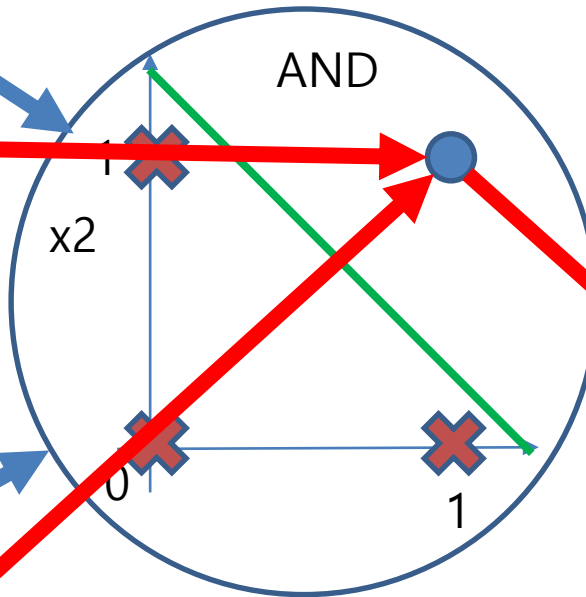
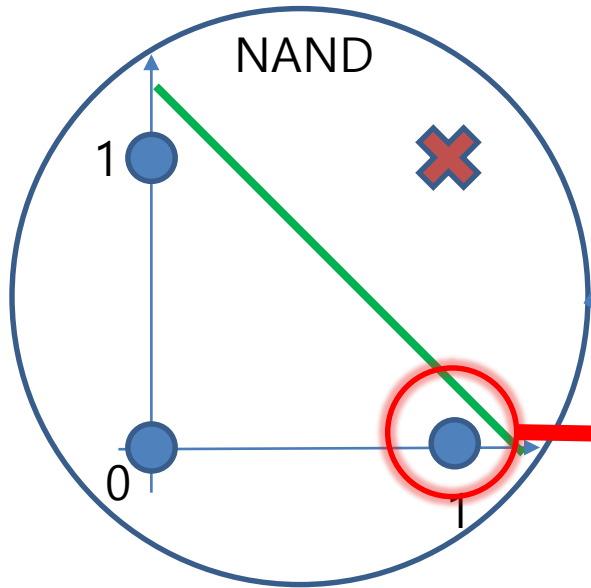
XOR

| x1 | x2 | y |
|----|----|---|
| 0 | 0 | 0 |
| 0 | 1 | 1 |
| 1 | 0 | 1 |
| 1 | 1 | 0 |



Perceptron

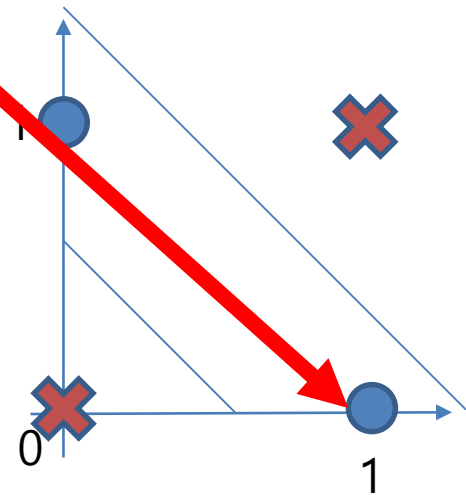
-Single and multilayer



Multilayer

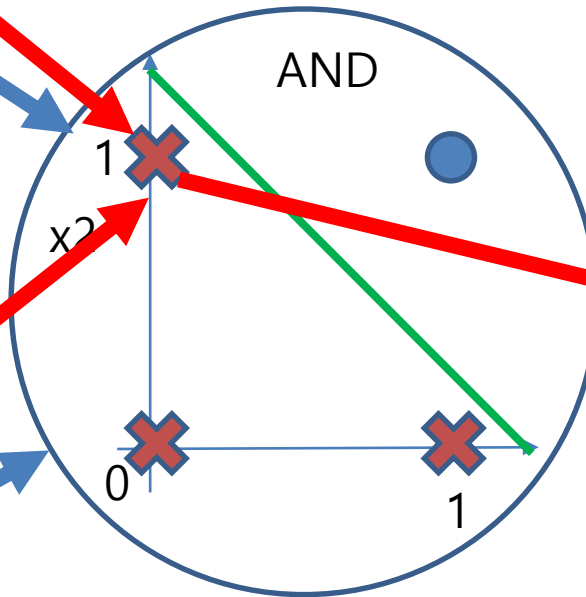
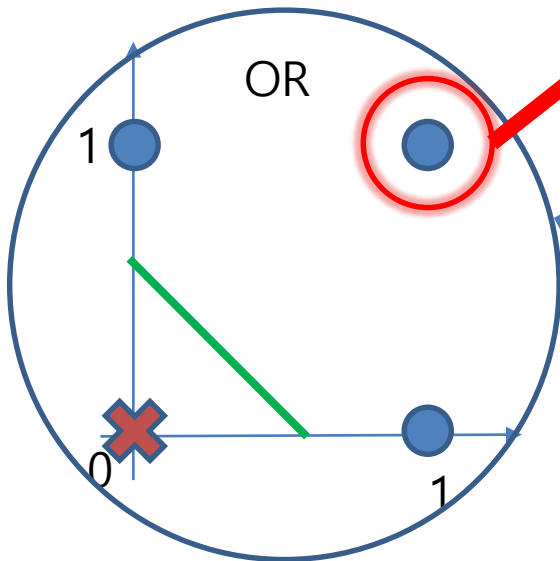
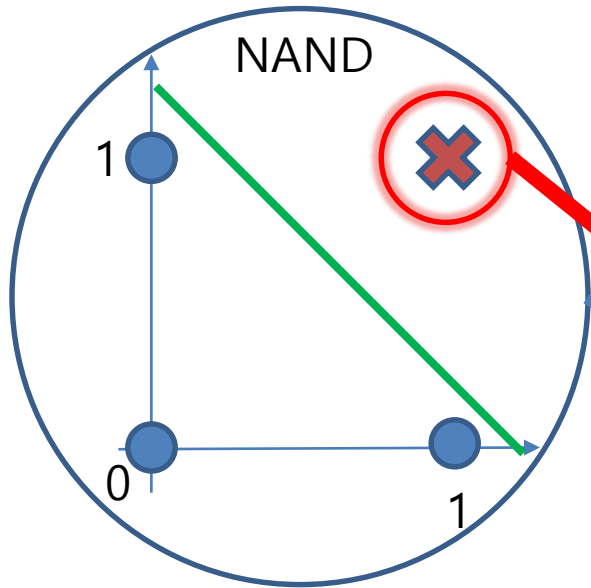
XOR

| x1 | x2 | y |
|----|----|---|
| 0 | 0 | 0 |
| 0 | 1 | 1 |
| 1 | 0 | 1 |
| 1 | 1 | 0 |



Perceptron

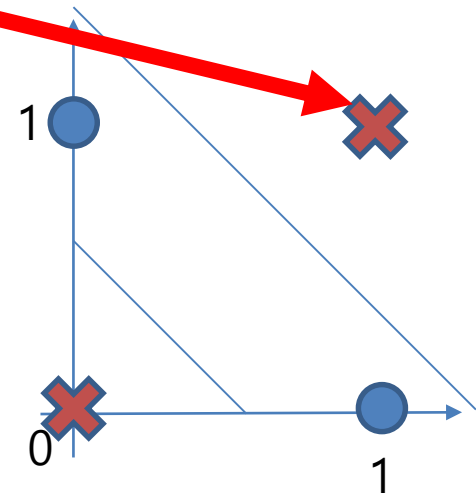
-Single and multilayer



Multilayer

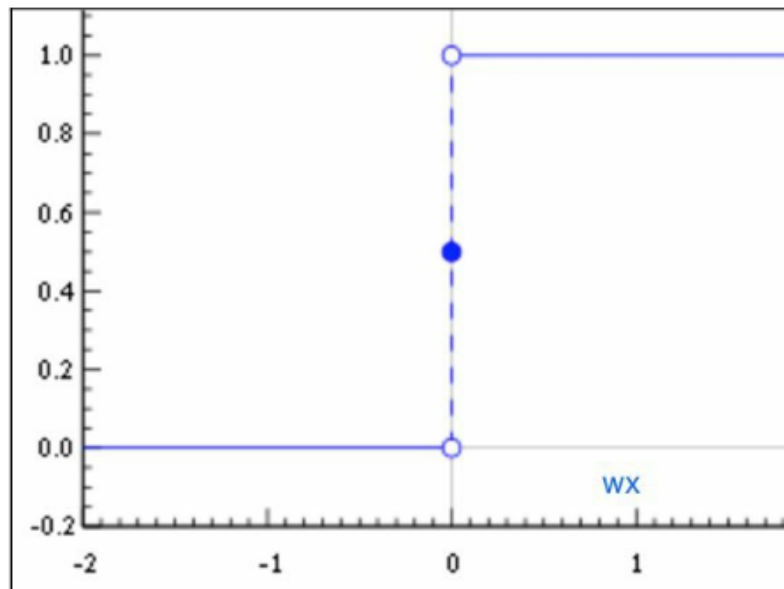
XOR

| x1 | x2 | y |
|----|----|---|
| 0 | 0 | 0 |
| 0 | 1 | 1 |
| 1 | 0 | 1 |
| 1 | 1 | 0 |



Problems in training the perceptron and a solution

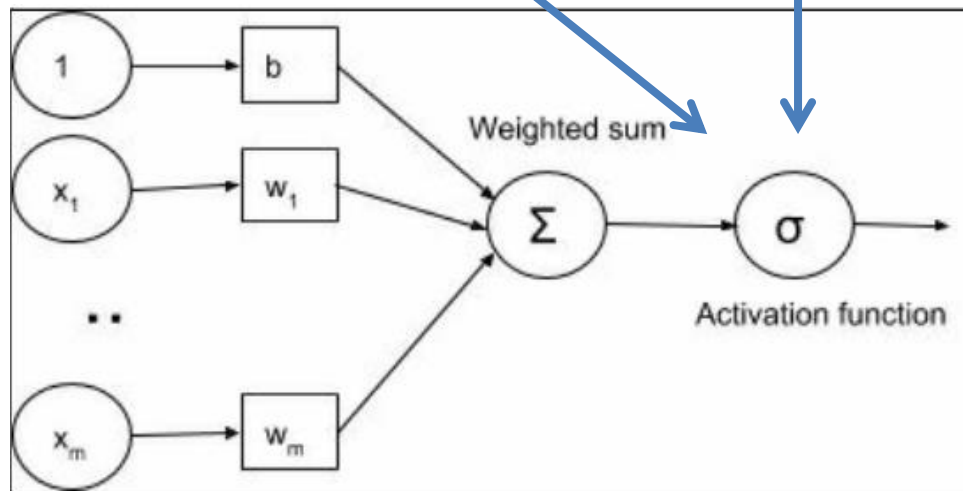
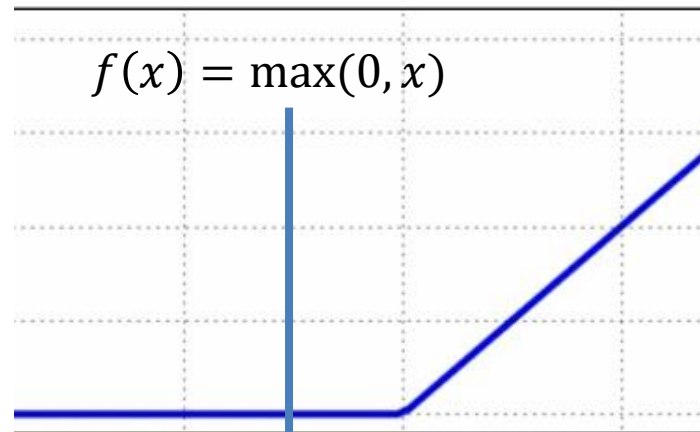
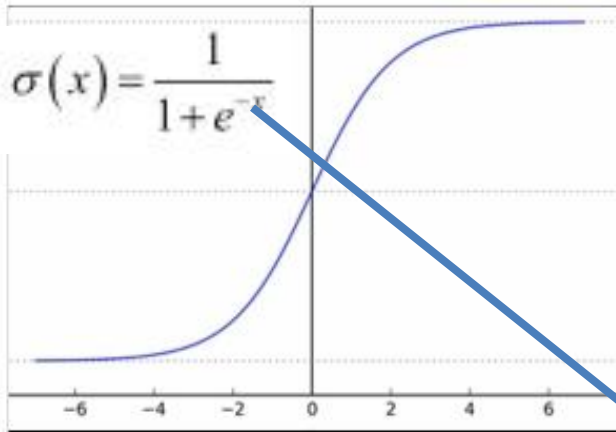
- So far, we need to adjust parameters for single neuron (weight and bias)
- Ideally, providing a set of training set and let the computer adjust the weight and the bias such a way that the errors produced in the output are minimized
- A big output jump cannot progressively learn without knowing whether improving (Perceptron only returns 0 or 1, Need to use nonlinear $f(x)$)
- Stacking layers is useless (ex. $h(x)=ax$, $y(x)=h(h(h(x)))=a^3x=bx$)



Activation F(x)

-Sigmoid and ReLU

- A neuron can use the sigmoid for computing the nonlinear function
- ReLU : Rectified linear unit



One-hot encoding

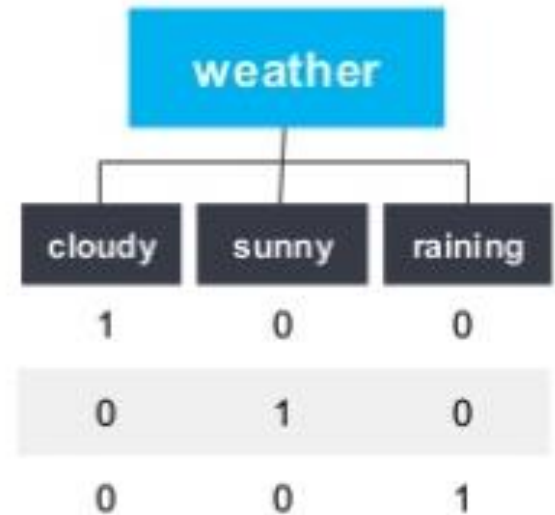
-Transform categorical into numerical variables



One-hot encoding

| day | temperature [F] | weather | bike rentals |
|-----|-----------------|---------|--------------|
| 3 | 76 | Cloudy | 543 |
| 4 | 72 | Raining | 173 |
| 5 | 78 | Sunny | 674 |
| 6 | 68 | Raining | 124 |

| day | temperature [F] | cloudy | sunny | raining | bike rentals |
|-----|-----------------|--------|-------|---------|--------------|
| 3 | 76 | 1 | 0 | 0 | 543 |
| 4 | 72 | 0 | 0 | 1 | 173 |
| 5 | 78 | 0 | 1 | 0 | 674 |
| 6 | 68 | 0 | 0 | 1 | 124 |



One-hot encoding

- Transform categorical into numerical variables
- Usually in bioinformatics.....

| | A | B | C | D | E | F | G | H | I |
|----|---------|---------|-------|-------|-----|--------|-------|------|------|
| 1 | sym | KATOIII | SKGT2 | NCC59 | AGS | SNU638 | NUGC3 | IM95 | YCC3 |
| 2 | A1CF | 1 | 1 | 0 | 0 | 0 | 0 | 0 | 0 |
| 3 | A2ML1 | 0 | 0 | 1 | 1 | 0 | 0 | 0 | 0 |
| 4 | AACS | 0 | 0 | 1 | 1 | 0 | 0 | 0 | 0 |
| 5 | AADAC | 0 | 0 | 0 | 0 | 1 | 0 | 0 | 0 |
| 6 | AADACL4 | 0 | 1 | 0 | 0 | 0 | 0 | 0 | 0 |
| 7 | AADAT | 0 | 0 | 0 | 0 | 0 | 1 | 0 | 0 |
| 8 | AAR2 | 0 | 0 | 1 | 0 | 0 | 0 | 1 | 1 |
| 9 | AARS | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 1 |
| 10 | AASDH | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| 11 | AATK | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| 12 | ABAT | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| 13 | ABCA10 | 0 | 0 | 1 | 0 | 0 | 0 | 0 | 0 |
| 14 | ABCA12 | 0 | 0 | 1 | 1 | 1 | 0 | 1 | 0 |
| 15 | ABCA13 | 0 | 0 | 0 | 1 | 0 | 0 | 0 | 0 |

1 = 돌연변이
0 = 돌연변이 없음.

Objective f(x)

- Optimizer that optimize parameters
- Loss f(x), Cost f(x)

MSE

Mean squared error between the predictions and the true values

$$MSE = \frac{1}{n} \sum_{i=1}^n (\Upsilon - Y)^2$$

Binary cross-entropy

Binary logarithmic loss. Predicting p while the target is t

Suitable for binary labels prediction $0 < p < 1, t \in (0,1)$

$$-t \log(p) - (1 - t) \log(1 - p)$$

Categorical cross-entropy

Multiclass logarithmic loss. If the target is $t(i,j)$ and the prediction is $p(i,j)$

$$L_i = -\sum_j t_{i,j} \log(p_{i,j})$$

Performance

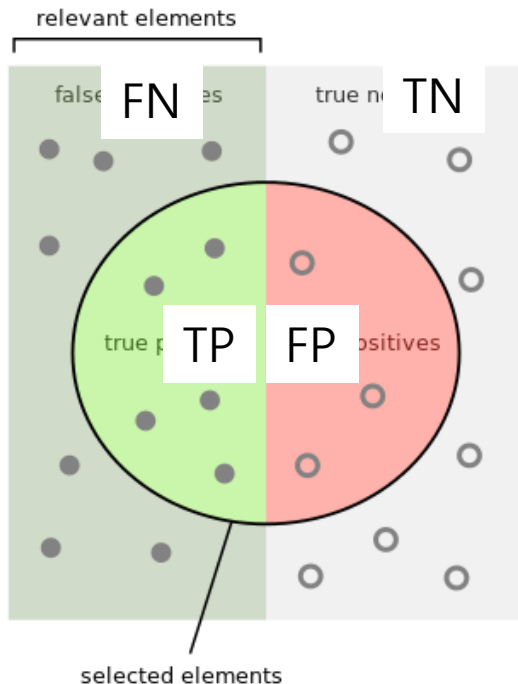
Accuracy

The proportion of correct predictions with respect to the target (Average of precision)

$$\frac{\sum \text{True positive} + \sum \text{True negative}}{\sum \text{Total population}}$$

Precision & Recall

How many selected items are relevant for multilabel classification



Key Metrics:

$$\text{Accuracy} = \frac{TP + TN}{TP + TN + FP + FN}$$

$$\text{Recall} = \frac{TP}{TP + FN}$$

$$\text{Precision} = \frac{TP}{TP + FP}$$

Performance

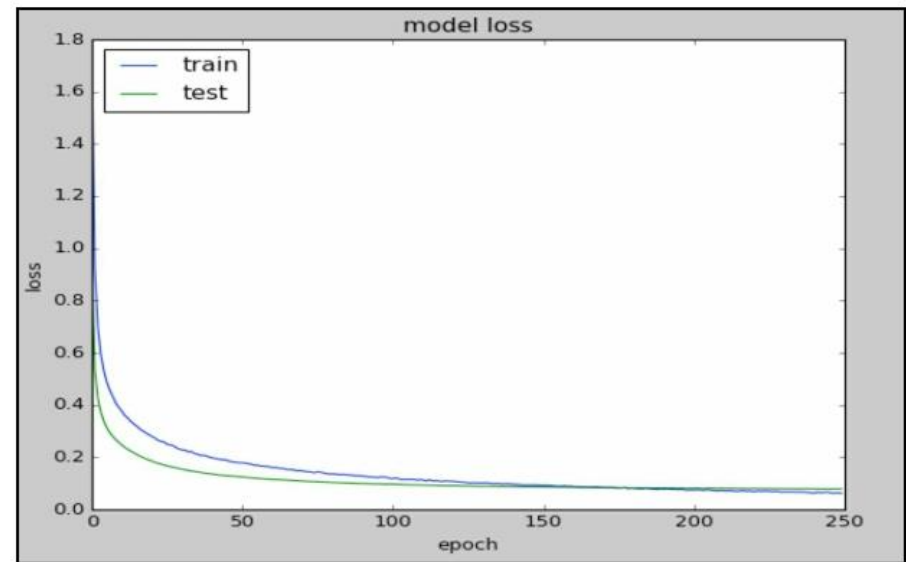
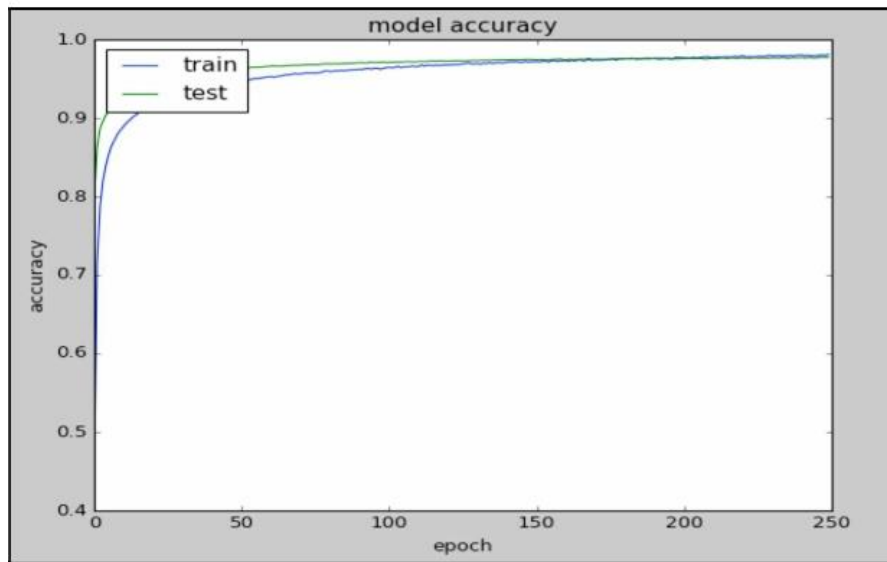
Epochs

N of times the model is exposed to the training set.

Batch_size

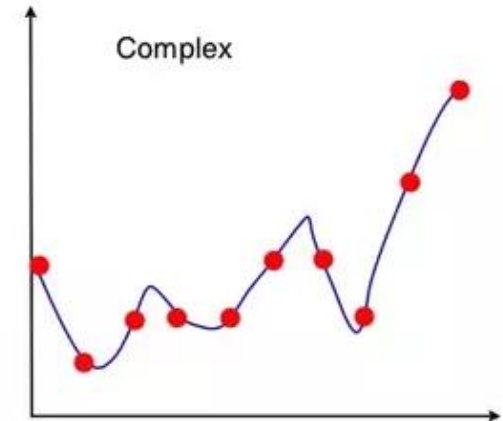
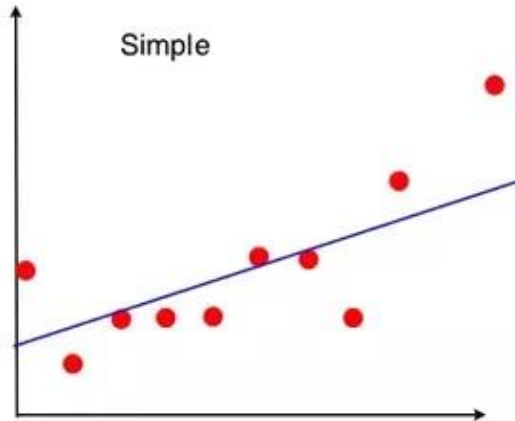
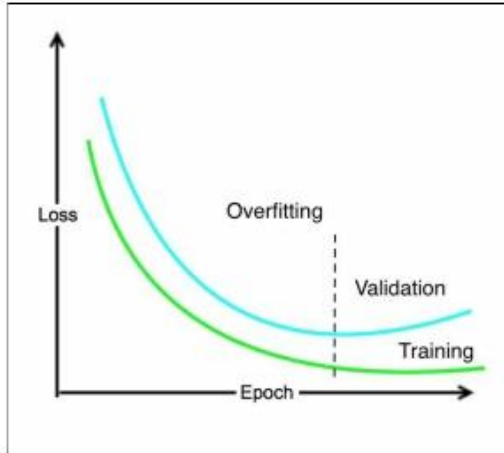
N of training instances observed before the optimizer performs weight update

- Useful to observe how accuracy increases on training and test sets



Adopting regularization for avoiding overfitting

Overfitting



- To solve overfitting problems, need to capture the complexity of a model.
- Choose the simplest model that has the minimum N of nonzero weights.

$$\min : \{loss(Training\ Data|Model)\} + \lambda * complexity(Model)$$

λ : Strigency parameter, Increasing lambda will reduce weight of fittures.

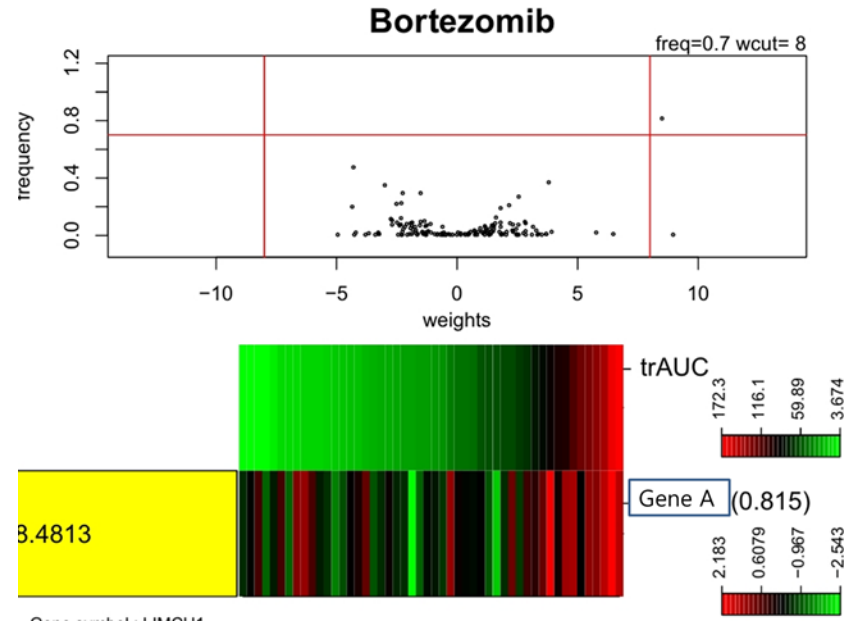
Adopting regularization for avoiding overfitting

Regularization

Lasso (L1 regularization)

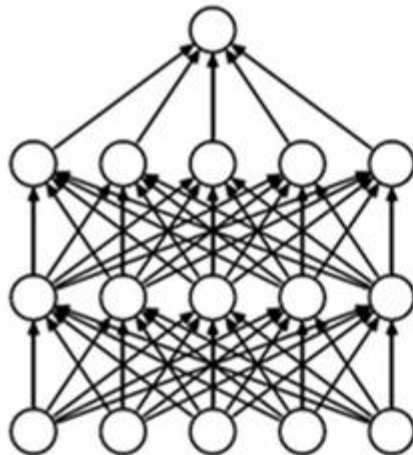
Ridge (L2 regularization)

Elastic net (Lasso+Ridge)

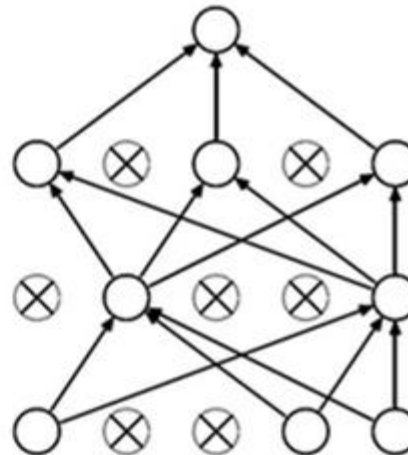


Dropout

Randomly training some of neuron in input or hidden layer



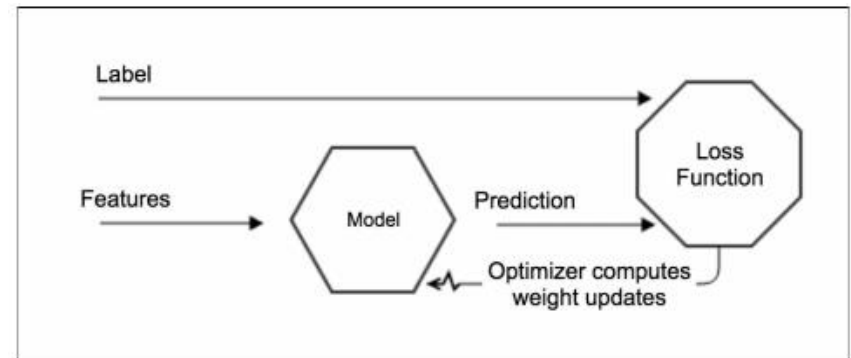
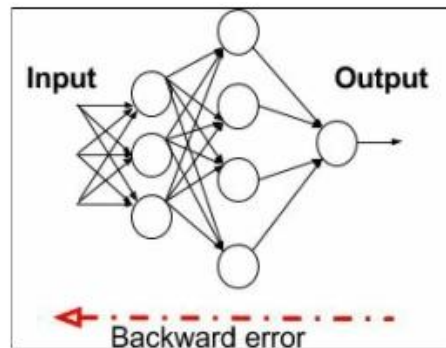
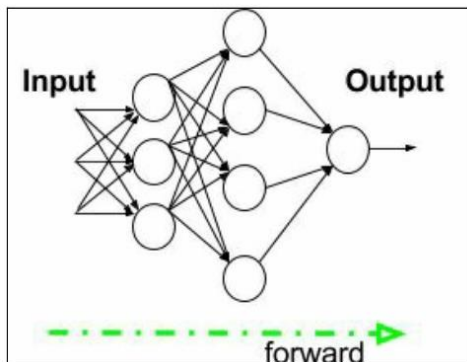
(a) Standard Neural Net



(b) After applying dropout.

A practical overview of backpropagation

- **Multilayer perceptrons learn from training data via backpropagation**
 - **A way of progressively correcting mistakes as soon as they are detected**
1. Starting all neuron with random weight
 2. Activated for each input in the training set -> propagated forward
 3. Calculate the error made in prediction
 4. Backtracking, to propagate the error back and apply optimizer
 5. Repeating the process and reduce error



끝