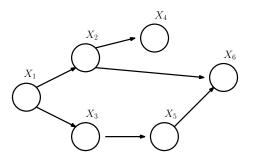
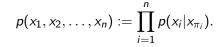
Given a directed acyclic graph (DAG) G,

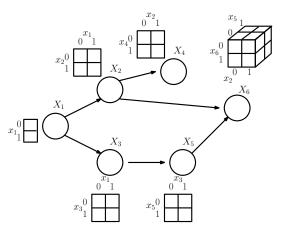
$$p(x_1, x_2, \ldots, x_n) := \prod_{i=1}^n p(x_i|x_{\pi_i}).$$



$$p(x_1,\ldots,x_6)=p(x_1)p(x_2|x_1)p(x_3|x_1)p(x_4|x_2)p(x_5|x_3)p(x_6|x_2,x_5)$$

▶ Given a directed acyclic graph (DAG) G,





Which independence assumptions are we exactly making by using a DAG model with a structure described by *G*? Important because

- we should know exactly what model assumptions we are making;
- ▶ this information will be helpful in designing inference algorithms later on.

#### Conditional independence

- ▶  $X_1$  and  $X_2$  are conditionally independent given  $X_3$ , written  $X_1 \perp X_2 \mid X_3$ , iff
  - $p(x_1, x_2|x_3) = p(x_1|x_3)p(x_2|x_3)$ , or equivalently
  - $p(x_1|x_2,x_3) = p(x_1|x_3).$

for all  $x_3$  such that  $p(x_3) > 0$ . Given  $X_3$ , there is no further relationship between  $X_1$  and  $X_2$ .

Similarly, for sets of random variables, X<sub>A</sub> and X<sub>B</sub> are conditionally independent given X<sub>C</sub> iff

$$p(x_A, x_B|x_C) = p(x_A|x_C)p(x_B|x_C)$$

or

$$p(x_A|x_B,x_C) = p(x_A|x_C)$$

for all  $x_C$  such that  $p(x_C) > 0$ .

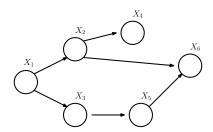
## DAG and conditional independence

#### Compare

$$p(x_1,\ldots,x_6)=p(x_1)p(x_2|x_1)p(x_3|x_1)p(x_4|x_2)p(x_5|x_3)p(x_6|x_2,x_5)$$

and

$$p(x_1,\ldots,x_6) = p(x_1)p(x_2|x_1)p(x_3|x_1,x_2)p(x_4|x_3,x_2,x_1)\cdots p(x_6|x_5,\ldots,x_1)$$



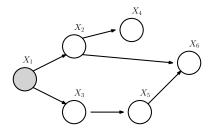
## DAG and conditional independence

#### Compare

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$$p(x_1,\ldots,x_6)=p(x_1)p(x_2|x_1)p(x_3|x_1,x_2)p(x_4|x_3,x_2,x_1)\cdots p(x_6|x_5,\ldots,x_1)$$



 $X_3 \perp X_2 \mid X_1$ . Exercise: verify this using definition.

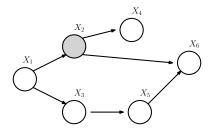
## DAG and conditional independence

#### Compare

$$p(x_1,\ldots,x_6)=p(x_1)p(x_2|x_1)p(x_3|x_1)p(x_4|x_2)p(x_5|x_3)p(x_6|x_2,x_5)$$

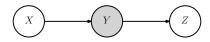
and

$$p(x_1,\ldots,x_6)=p(x_1)p(x_2|x_1)p(x_3|x_1,x_2)p(x_4|x_3,x_2,x_1)\cdots p(x_6|x_5,\ldots,x_1)$$



 $X_4 \perp \{X_1, X_3\} | X_2$ . Exercise: verify this using definition.

Three canonical graphs - cascade (Markov property)



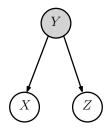
$$p(x, y, z) = p(x)p(y|x)p(z|y) \Rightarrow X \perp Z|Y,$$

since

$$p(z|x,y) = \frac{p(x,y,z)}{p(x,y)} = \frac{p(x)p(y|x)p(z|y)}{p(x)p(y|x)}$$
$$= p(z|y).$$

e.g. X "past", Y "present", Z "future"

Three canonical graphs - common parent



$$p(x, y, z) = p(y)p(x|y)p(z|y) \Rightarrow X \perp Z|Y,$$

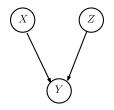
since

$$p(x,z|y) = \frac{p(y)p(x|y)p(z|y)}{p(y)} = p(x|y)p(z|y).$$

e.g. X "shoe size", Z "gray hair or not", Y "age"



Three canonical graphs - v-structure



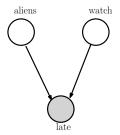
$$p(x, y, z) = p(x)p(y|x, z)p(z) \Rightarrow X \perp Z,$$

since

$$p(x,z) = \sum_{y} p(x,y,z) = p(x)p(z)$$

Can we claim  $X \perp Z \mid Y$ ? No. In fact observing Y can induce dependence between X and Z.

Three canonical graphs - v-structure

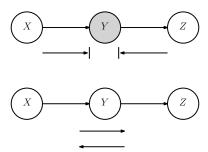


Alice is late for lunch with Bob.

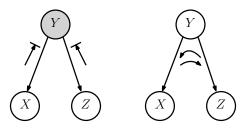
#### The Bayes ball algorithm

- ▶ Decide whether a given conditional statement  $X_A \perp X_B | X_C$  is true for a DAG G.
- ▶ Convert to a "reachability" algorithm: shade the nodes  $X_C$ , place a ball at each of the nodes  $X_A$ , let the ball bounce around G according to some rules. If none of the balls can reach any of the nodes in  $X_B$ , we assert  $X_A \perp \!\!\! \perp X_B | X_C$ .

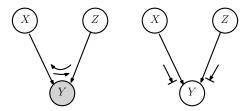
Three canonical graphs - cascade



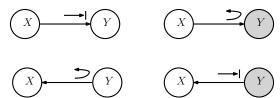
Three canonical graphs - common parent



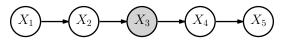
Three canonical graphs - v-structure



When source and destination are the same

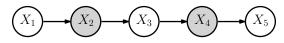


### Example 1. Markov chain



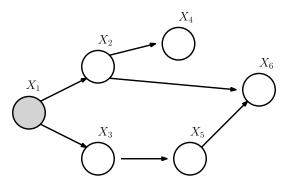
$$X_1 \perp \!\!\! \perp X_5 | X_3, X_1 \perp \!\!\! \perp X_4 | X_3$$

### Example 1. Markov chain



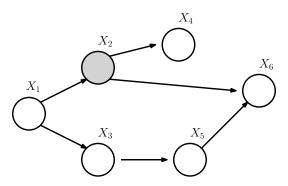
$$X_1 \perp \!\!\! \perp X_5 | \{X_2, X_4\}$$

### Example 2.



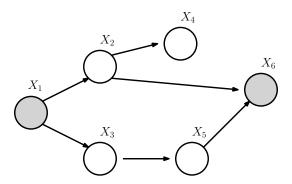
$$X_2 \perp \!\!\! \perp X_3 | X_1$$

### Example 2.



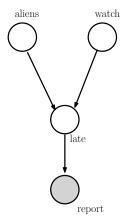
$$X_4 \perp \{X_1, X_3\} | X_2$$

### Example 2.



Can we claim  $X_2 \perp X_3 | \{X_1, X_6\}$ ?

#### Example 3.



alien  $\bot$  watch, but cannot assert alien  $\bot$  watch report

## Two equivalent characterisations

#### Given a DAG G,

- ▶ Generate a family of distributions  $\mathcal{D}_1$  as follows:
  - factorisation in terms of conditional probabilities
  - range over all possible choices of numerical values for conditional PMFs
- ▶ Generate a family of distributions  $\mathcal{D}_2$  as follows:
  - find all conditional independences by running the Bayes ball algorithm
  - consider all possible joint distributions
  - test each against the list of conditional independences; keep the distribution if all satisfied

 $\mathcal{D}_1$  and  $\mathcal{D}_2$  are the same.