

(A)

Q1/ (i) l passes through $P(2, 3, -1)$ and $Q(3, 2, -3)$

so has direction vector $\vec{PQ} = \underline{i} - \underline{j} - 2\underline{k}$, so has vector

equation

$$l = 2\underline{i} + 3\underline{j} - \underline{k} + t(\underline{i} - \underline{j} - 2\underline{k}).$$

(ii) This becomes

$$\begin{cases} x = 2 + t \\ y = 3 - t \\ z = -1 - 2t \end{cases}$$

giving Cartesian equations

$$x - 2 = \frac{y - 3}{-1} = \frac{z + 1}{-2}$$

(iii) $A = (1, 2, 1)$, $B = (4, 3, 2)$, $C = (3, -2, 4)$ so

$\vec{AB} = 3\underline{i} + \underline{j} + \underline{k}$ and $\vec{AC} = 2\underline{i} - 4\underline{j} + 3\underline{k}$, so

$$\begin{aligned} \underline{u} &= \vec{AB} \times \vec{AC} = \begin{vmatrix} \underline{i} & \underline{j} & \underline{k} \\ 3 & 1 & 1 \\ 2 & -4 & 3 \end{vmatrix} = 7\underline{i} - 7\underline{j} - 14\underline{k} \\ &= 7(\underline{i} - \underline{j} - 2\underline{k}) \end{aligned}$$

(iv) Plane containing A, B, C has equation

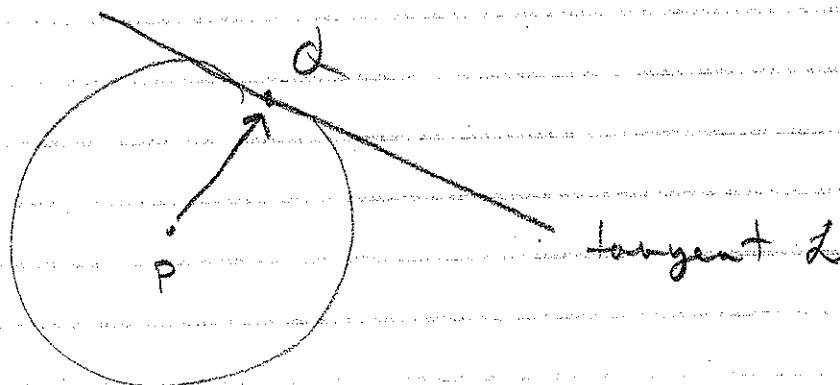
$$x - y - 2z = 1 - 2 - 2 = -3$$

(v) l has direction vector $\vec{PQ} = \frac{1}{7}\underline{u}$, normal to

the plane, so the line is perpendicular to the plane.

(B)

Q2/ (i) $P = (2, -3), Q = (5, 1)$



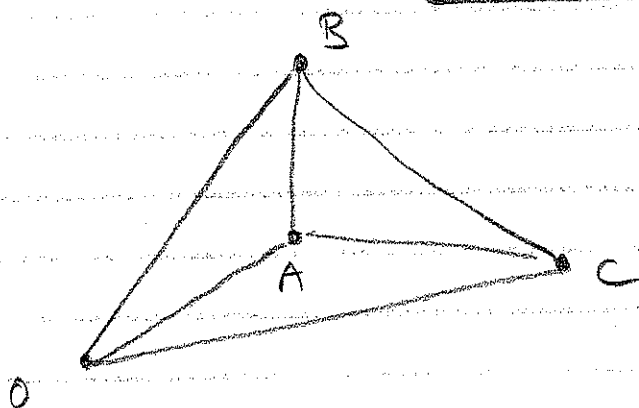
$\vec{PQ} = 3\hat{i} + 4\hat{j}$ so direction vector for L is

perpendicular to \vec{PQ} , say $\underline{v} = 4\hat{i} - 3\hat{j}$,

so L has equation

$$\underline{r} = 5\hat{i} + \hat{j} + t(4\hat{i} - 3\hat{j}).$$

(ii)



(a) $\underline{k} = \vec{OK} = \frac{\alpha}{\alpha+\beta} \underline{a}, \underline{l} = \vec{OL} = \frac{\alpha}{\alpha+\beta} \underline{b},$

$\underline{m} = \vec{OM} = \vec{OC} + \frac{\alpha}{\alpha+\beta} \vec{CB} = \underline{c} + \frac{\alpha}{\alpha+\beta} (\underline{b} - \underline{c}), \underline{n} = \vec{ON} = \vec{OC} + \frac{\alpha}{\alpha+\beta} \vec{CA} = \underline{c} + \frac{\alpha}{\alpha+\beta} (\underline{a} - \underline{c})$

(b) Let S be the midpt of KM . Then

$\vec{LS} = -\underline{l} + \underline{k} + \vec{KS} = \underline{k} - \underline{l} + \frac{1}{2} \vec{KM} = \underline{k} - \underline{l} + \frac{1}{2} (\underline{m} - \underline{k})$

$= \frac{\alpha}{\alpha+\beta} \underline{a} - \frac{\alpha}{\alpha+\beta} \underline{b} + \frac{1}{2} (\underline{c} + \frac{\alpha}{\alpha+\beta} (\underline{b} - \underline{c}) - \frac{\alpha}{\alpha+\beta} \underline{a})$

(c)

2/ (ii) (b) (cont.)

$$= \frac{1}{2} \left(\frac{x}{x+p} a - \frac{x}{x+p} b - \frac{1}{x+p} c + c \right)$$

$$= \frac{1}{2} \left(-\frac{x}{x+p} b + c + \frac{x}{x+p} (a-c) \right)$$

$$= \frac{1}{2} \left(-\frac{b}{2} + \frac{a}{2} \right)$$

$$= \frac{1}{2} \overrightarrow{LN}$$

So that S is also the midpoint of LN

This shows KM and LN intersect at their midpoints.

Q3/ (i) (a) $\begin{cases} x = 0 \\ y = 0 \\ x+y = 0 \end{cases}$ has a unique solution.

(b) $\begin{cases} x+y = 0 \\ x+y = 0 \\ x+y = 0 \end{cases}$ has infinitely many solutions.

(ii) $\begin{cases} x+2y+3z = 2 \\ x+3y+4z = 1 \\ 2x+ay+8z = 6 \end{cases}$

$$\begin{bmatrix} 1 & 2 & 3 & | & 2 \\ 1 & 3 & 4 & | & 1 \\ 2 & a & 8 & | & 6 \end{bmatrix} \sim \begin{bmatrix} 1 & 2 & 3 & | & 2 \\ 0 & 1 & 1 & | & -1 \\ 0 & a-4 & 2 & | & 2 \end{bmatrix} \sim \begin{bmatrix} 1 & 2 & 3 & | & 2 \\ 0 & 1 & 1 & | & -1 \\ 0 & 0 & a-2 & | & a-2 \end{bmatrix}$$

$$\begin{aligned} 8-2a^2 &= (a-4)(4-a^2) \\ &= 8-2a^2 - (a^3-4a^2+4a-16) \\ &= -a^3+6a^2-4a+24 \end{aligned}$$

$$\begin{aligned} 2+a-4 &= a-2 \end{aligned}$$

⑤

Q3/ (b) (iii) The system is inconsistent iff

$$p(a) = a^3 - 6a^2 - 4a + 24 = 0 \quad \text{and} \quad a-2 \neq 0$$

Certainly $p(-2) = -8 - 24 + 8 + 24 = 0$

and $-2-2 = -4 \neq 0$, so $a=-2$ yields an

inconsistent system. Observe that

$$\begin{array}{r} a^2 - 8a + 12 \\ a+2 \overline{) a^3 - 6a^2 - 4a + 24} \\ \underline{a^3 + 2a^2} \\ -8a^2 - 4a + 24 \\ \underline{-8a^2 - 16a} \\ 12a + 24 \\ \underline{12a + 24} \\ 0 \end{array}$$

so that $p(a) = (a+2)(a^2 - 8a + 12)$

$$= (a+2)(a-6)(a-2)$$

so $\boxed{a=6}$ also yields an inconsistent system

($a=2$ yields no unique solution.)

Q4/ (i) $\begin{bmatrix} 0 & n \\ 1 & 0 \end{bmatrix}^2 = \begin{bmatrix} 0 & n \\ 1 & 0 \end{bmatrix} \begin{bmatrix} 0 & n \\ 1 & 0 \end{bmatrix} = \begin{bmatrix} n & 0 \\ 0 & 1 \end{bmatrix}$

so $A^2 = \begin{bmatrix} 0 & n \\ 1 & 0 \end{bmatrix}$ for $n \neq 0$ provides infinitely many

solutions to $A^2 = I$.

(E)

Q4/ (ii)

$$\begin{vmatrix} a+b & a & a & a \\ a & a+b & a & a \\ a & a & a+b & a \\ a & a & a & a+b \end{vmatrix} = \begin{vmatrix} 2a+b & 2a+b & 2a & 2a \\ a & a+b & a & a \\ a & a & a+b & a \\ a & a & a & a+b \end{vmatrix}$$

$$= \begin{vmatrix} 3a+b & 3a+b & 3a+b & 3a \\ a & a+b & a & a \\ a & a & a+b & a \\ a & a & a & a+b \end{vmatrix} = \begin{vmatrix} 4a+b & 4a+b & 4a+b & 4a+b \\ a & a+b & a & a \\ a & a & a+b & a \\ a & a & a & a+b \end{vmatrix}$$

(iii) continuing (ii) :

$$= (4a+b) \begin{vmatrix} 1 & 1 & 1 & 1 \\ a & a+b & a & a \\ a & a & a+b & a \\ a & a & a & a+b \end{vmatrix}$$

$$= (4a+b) \begin{vmatrix} 1 & 0 & 0 & 0 \\ a & b & 0 & 0 \\ a & 0 & b & 0 \\ a & 0 & 0 & b \end{vmatrix} = (4a+b) b^3$$

$$(iv) \det(J - \lambda I) = \begin{vmatrix} 1-\lambda & 1 & 1 & 1 \\ 1 & 1-\lambda & 1 & 1 \\ 1 & 1 & 1-\lambda & 1 \\ 1 & 1 & 1 & 1-\lambda \end{vmatrix} = (4-\lambda)(-\lambda)^3$$

(a=1, b=-\lambda)
in (iii)

So eigenvalues are $\lambda = 4, 0$.

$$J = \begin{pmatrix} 1 & 1 & 1 & 1 \\ 1 & 1 & 1 & 1 \\ 1 & 1 & 1 & 1 \\ 1 & 1 & 1 & 1 \end{pmatrix} \sim \begin{pmatrix} 1 & 1 & 1 & 1 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix} \quad \text{So } \lambda_1 = \lambda_2 = \lambda_3 = \lambda_4 = 0$$

(F)

Q4 (iv) (cont.)

giving eigenspace $\left\{ \begin{bmatrix} -s-t-u \\ s \\ t \\ u \end{bmatrix} \mid s, t, u \in \mathbb{R} \right\}$

for $\lambda = 0$.

$$J - 4I = \begin{bmatrix} -3 & 1 & 1 & 1 \\ 1 & -3 & 1 & 1 \\ 1 & 1 & -3 & 1 \\ 1 & 1 & 1 & -3 \end{bmatrix} \sim \begin{bmatrix} 1 & -3 & 1 & 1 \\ 0 & -8 & 4 & 4 \\ 0 & 4 & -4 & 0 \\ 0 & 4 & 0 & -4 \end{bmatrix} \sim \begin{bmatrix} 1 & -3 & 1 & 1 \\ 0 & 1 & -1 & 0 \\ 0 & -2 & 1 & 1 \\ 0 & 1 & 0 & -1 \end{bmatrix}$$

$$\sim \begin{bmatrix} 1 & 0 & -2 & 1 \\ 0 & 1 & -1 & 0 \\ 0 & 0 & -1 & 1 \\ 0 & 0 & 1 & -1 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & 0 & -1 \\ 0 & 1 & 0 & -1 \\ 0 & 0 & 1 & -1 \\ 0 & 0 & 0 & 0 \end{bmatrix} \begin{cases} x & -w = 0 \\ y & -w = 0 \\ z & -w = 0 \end{cases}$$

giving eigenspace $\left\{ \begin{bmatrix} t \\ t \\ t \\ t \end{bmatrix} \mid t \in \mathbb{R} \right\}$

Q5 (i) If $A\underline{v} = \lambda\underline{v}$ and $\underline{v} \neq \underline{0}$ then, for any scalar a ,

$$(A + aI)\underline{v} = A\underline{v} + aI\underline{v} = \lambda\underline{v} + a\underline{v} = (\lambda + a)\underline{v},$$

which shows \underline{v} is an eigenvector for $A + aI$ with respect to eigenvalue $\lambda + a$.

(9)

Q5/ (ii) If $A\underline{v} = \lambda \underline{v}$ and $\underline{v} \neq \underline{0}$ then, for any scalar b ,

$(bA)\underline{v} = b(A\underline{v}) = b(\lambda \underline{v}) = (b\lambda)\underline{v}$, which shows \underline{v} is an eigenvector for bA with respect to eigenvalue $b\lambda$.

$$(iii) A\underline{v} = \begin{bmatrix} 0 & 1 & 0 & 0 & \dots & 0 \\ 1 & 0 & 1 & 0 & \dots & 0 \\ 0 & 1 & 0 & 1 & \dots & 0 \\ \vdots & \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & \dots & \dots & \dots & 1 & 0 \\ 0 & \dots & \dots & \dots & 1 & 0 \end{bmatrix} \begin{bmatrix} \sin \theta \\ \sin 2\theta \\ \sin 3\theta \\ \vdots \\ \sin n\theta \end{bmatrix}$$

$$= \begin{bmatrix} \sin 2\theta \\ \sin 2\theta + \sin 3\theta \\ \sin 2\theta + \sin 4\theta \\ \vdots \\ \sin(n-1)\theta + \sin n\theta \\ \sin(n-1)\theta \end{bmatrix} = \begin{bmatrix} 2 \cos \theta \sin \theta \\ 2 \cos \theta \sin 2\theta \\ 2 \cos \theta \sin 3\theta \\ \vdots \\ 2 \cos \theta \sin(n-1)\theta \\ 2 \cos \theta \sin n\theta \end{bmatrix}$$

making $\sin(n+1)\theta = \sin\left(\frac{n+1}{n+1}\right)k\pi = 0$

so $\sin(n-1)\theta = \sin(n-1)\theta + \sin(n+1)\theta = 2 \cos \theta \sin n\theta$

$$= 2 \cos \theta \begin{bmatrix} \sin \theta \\ \sin 2\theta \\ \vdots \\ \sin n\theta \end{bmatrix}$$

$$= 2 \cos \theta \underline{v}$$

so \underline{v} is an eigenvector with respect to eigenvalue

$$2 \cos \theta.$$

(H)

Q5/01 By (i) and (ii), $\underline{v} = \begin{bmatrix} \sin \theta \\ \vdots \\ \sin n\theta \end{bmatrix}$

is an eigenvector for $bA + aI$ with corresponding eigenvalue $b \cos \theta + a$ where $\theta = \frac{k\pi}{n+1}$

for integers k such that $1 \leq k \leq n$

These are all the eigenvalues because there are n of them, all distinct.

because $\cos \frac{\pi}{n+1}, \cos \frac{2\pi}{n+1}, \dots, \cos \frac{n\pi}{n+1}$
are all distinct

