THE UNIVERSITY OF SYDNEY SCHOOL OF MATHEMATICS AND STATISTICS

MATH1902

LINEAR ALGEBRA (ADVANCED)

| June 2013 | Lecturer: Holger Dullin |
|-------------------|-------------------------|
| TIME ALLOWED: | One and a half hours |
| Family Name: | |
| Other Names: | |
| SID: Seat Number: | |

| The Multiple Choice Section is worth 35% of the total examination; there are 20 questions; the questions are of equal value; all questions may be attempted. Answers to the Multiple Choice questions must be entered on the Multiple Choice Answer Sheet. | |
|---|--|
| the Multiple Choice Answer Sheet. | |
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| The Extended Answer Section is worth 65% of the total examination; there are 4 questions; the questions are of equal value; all questions may be attempted; working must be shown. | |
| Approved non-programmable calculators may be used. | |

Extended Answer Section

There are four questions in this section, each with a number of parts. Write your answers in the answer book(s) provided. Ask for extra books if you need them.

- 1. Consider a pyramid with a quadratic base with corners P(0,0,0), Q(0,1,0), R(1,1,0), S(1,0,0), and apex A(1/2,1/2,h) with height h>0.
 - (a) Find the cartesian equation for the plane through QRA.
 - (b) Given that the cartesian equation of the plane through PQA is hx + z/2 = 0, find the distance of S from this plane.
 - (c) Find the distance of the line through R and A from the origin.
 - (d) Find the height h of the apex A of the pyramid for which the acute angle between adjacent faces is $\pi/3$.

[4+3+4+4=15 marks]

2. (a) Find the condition on b_1, b_2, b_3 for which the system of linear equations

$$x_1 + x_2 + 3x_3 = b_1$$
$$x_1 + 2x_2 + 2x_3 = b_2$$
$$x_1 + 3x_2 + x_3 = b_3$$

is consistent.

- (b) Solve the system with $b_1 = b_2 = b_3 = 0$.
- (c) Interpret the three equations in part (a) as cartesian equations for three planes. Describe qualitatively how these planes intersect when the condition from part (a) is satisfied.
- (d) Consider the system of m linear equations in n variables given by $A\mathbf{x} = \mathbf{b}$. Denote by \mathbf{x}_p a particular solution of the system $A\mathbf{x} = \mathbf{b}$. Denote by \mathbf{x}_h a solution of the associated homogeneous system $A\mathbf{x} = \mathbf{0}$.
 - (i) Show that $\mathbf{x}_p + \mathbf{x}_h$ is a solution to $A\mathbf{x} = \mathbf{b}$.
 - (ii) Write down a system of linear equations whose solution is $3\mathbf{x}_p 8\mathbf{x}_h$.

[4+3+4+4=15 marks]

- **3.** Recall that two $n \times n$ matrices A and B are similar if there is an invertible $n \times n$ matrix P such that PB = AP. The matrix P is called a similarity transformation. A matrix is diagonalisable if it is similar to a diagonal matrix.
 - (a) Find the eigenvalues and eigenvectors of $A = \begin{bmatrix} 0 & 1 \\ -2 & 3 \end{bmatrix}$. Thus find a similarity transformation P and a diagonal matrix D such that PD = AP.
 - (b) Suppose B is another matrix that is similar to the matrix D found in the previous part with similarity transformation $Q = \begin{bmatrix} 1 & 2 \\ 1 & 3 \end{bmatrix}$, so that QD = BQ. Find a similarity transformation between the matrices A and B.
 - (c) Show that the matrices $\begin{bmatrix} 1 & 0 \\ 1 & 1 \end{bmatrix}$ and $\begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$ are not similar, even though they have the same eigenvalues.
 - (d) Show that if two matrices A and C are similar to diagonal matrices by the same similarity transformation P, then they satisfy AC = CA.

[4+3+4+4=15 marks]

4. Given three vectors \mathbf{v}_1 , \mathbf{v}_2 , \mathbf{v}_3 , define the vectors \mathbf{u}_1 , \mathbf{u}_2 , \mathbf{u}_3 by

$$egin{aligned} \mathbf{u}_1 &= \mathbf{v}_1, \ \mathbf{u}_2 &= \mathbf{v}_2 - rac{\mathbf{u}_1 \cdot \mathbf{v}_2}{\mathbf{u}_1 \cdot \mathbf{u}_1} \mathbf{u}_1, \ \mathbf{u}_3 &= \mathbf{v}_3 - rac{\mathbf{u}_1 \cdot \mathbf{v}_3}{\mathbf{u}_1 \cdot \mathbf{u}_1} \mathbf{u}_1 - rac{\mathbf{u}_2 \cdot \mathbf{v}_3}{\mathbf{u}_2 \cdot \mathbf{u}_2} \mathbf{u}_2. \end{aligned}$$

- (a) Given that $\mathbf{v}_1 = \mathbf{i} + \mathbf{j} + \mathbf{k}$, $\mathbf{v}_2 = \mathbf{i} + 2\mathbf{j} + 3\mathbf{k}$, $\mathbf{v}_3 = 3\mathbf{i} + 3\mathbf{k}$, compute $\mathbf{u}_1, \mathbf{u}_2, \mathbf{u}_3$ and show that any two of these vectors are perpendicular.
- (b) Compute the determinant $\begin{vmatrix} 1 & 1 & 3 \\ 1 & 2 & 0 \\ 1 & 3 & 3 \end{vmatrix}$ and explain why the result implies that the vectors $\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3$ from part (a) are linearly independent.
- (c) Prove that in general any two of the vectors $\mathbf{u}_1, \mathbf{u}_2, \mathbf{u}_3$ defined in the beginning of the question are perpendicular.
- (d) Show that if $\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3$ are linearly independent, then the vectors $\mathbf{u}_1, \mathbf{u}_2, \mathbf{u}_3$ are linearly independent and hence are non-zero.

[4+4+4+3=15 marks]

End of Extended Answer Section