

## Extended Answer Section

There are **three** questions in this section, each with a number of parts. Write your answers in the space provided below each part. If you need more space there are extra pages at the end of the examination paper.

1. The parametric vector form of the line  $\mathcal{L}_1$  is given as  $\mathbf{r}_1 = \mathbf{u}_1 + r\mathbf{v}_1$  ( $r \in \mathbb{R}$ ) where  $\mathbf{u}_1$  is the position vector of  $P_1 = (1, 1, -3)$  and  $\mathbf{v}_1 = \overrightarrow{P_1Q_1}$  where  $Q_1 = (3, 3, -2)$ . The parametric vector form of the line  $\mathcal{L}_2$  is given as  $\mathbf{r}_2 = \mathbf{u}_2 + s\mathbf{v}_2$  ( $s \in \mathbb{R}$ ) where  $\mathbf{u}_2$  is the position vector of  $P_2 = (-2, 0, 2)$  and  $\mathbf{v}_2 = -\mathbf{j} - \mathbf{k}$ .

(a) [2 marks] Give the parametric scalar equations of  $\mathcal{L}_1$ .

$$\mathbf{u}_1 = \overrightarrow{OP_1} = \underline{\hat{i}} + \underline{\hat{j}} - 3\underline{\hat{k}} \quad \text{and} \quad \mathbf{v}_1 = \overrightarrow{P_1Q_1} = \overrightarrow{OQ_1} - \overrightarrow{OP_1} \\ = (3-1)\underline{\hat{i}} + (3-1)\underline{\hat{j}} + (-2-(-3))\underline{\hat{k}} = 2\underline{\hat{i}} + 2\underline{\hat{j}} + \underline{\hat{k}}.$$

So parametric vector form of equation of  $\mathcal{L}_1$  becomes

$$\mathbf{r}_1 = (\underline{\hat{i}} + \underline{\hat{j}} - 3\underline{\hat{k}}) + r(2\underline{\hat{i}} + 2\underline{\hat{j}} + \underline{\hat{k}}) = (1+2r)\underline{\hat{i}} + (1+2r)\underline{\hat{j}} + (-3+r)\underline{\hat{k}}$$

If  $(x, y, z)$  is a point on  $\mathcal{L}_1$ , then  $\mathbf{r}_1 = x\underline{\hat{i}} + y\underline{\hat{j}} + z\underline{\hat{k}}$

$$\text{i.e.} \quad \left. \begin{array}{l} x = 1+2r \\ y = 1+2r \\ z = -3+r \end{array} \right\} \text{ where } r \in \mathbb{R}. \quad (\text{These are the parametric scalar equations of } \mathcal{L}_1)$$

(b) [2 marks] Find a unit vector  $\hat{\mathbf{n}}$  that is perpendicular to both  $\mathcal{L}_1$  and  $\mathcal{L}_2$ .

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$\mathbf{v}_1$  &  $\mathbf{v}_2$  give the directions of  $\mathcal{L}_1$  &  $\mathcal{L}_2$ , & so  $\mathbf{v}_1 \times \mathbf{v}_2$  is perpendicular to both  $\mathcal{L}_1$  and  $\mathcal{L}_2$ .

$$\mathbf{v}_1 \times \mathbf{v}_2: \quad \begin{vmatrix} \underline{\hat{i}} & \underline{\hat{j}} & \underline{\hat{k}} \\ 2 & 2 & 1 \\ 0 & -1 & -1 \end{vmatrix} = \underline{\hat{i}}(-2+1) - \underline{\hat{j}}(-2-0) + \underline{\hat{k}}(-2-0)$$

$$\mathbf{v}_1 \times \mathbf{v}_2 = -\underline{\hat{i}} + 2\underline{\hat{j}} - 2\underline{\hat{k}}$$

To obtain a unit vector in the direction of  $\mathbf{v}_1 \times \mathbf{v}_2$ , divide  $\mathbf{v}_1 \times \mathbf{v}_2$  by its length,  $|\mathbf{v}_1 \times \mathbf{v}_2| = \sqrt{(-1)^2 + 2^2 + (-2)^2} = \sqrt{9} = 3$ .

$$\text{So } \hat{\mathbf{n}} = -\frac{1}{3}\underline{\hat{i}} + \frac{2}{3}\underline{\hat{j}} - \frac{2}{3}\underline{\hat{k}}$$

[Note:  $\frac{1}{3}\underline{\hat{i}} - \frac{2}{3}\underline{\hat{j}} + \frac{2}{3}\underline{\hat{k}}$  would be equally correct.]

You can also calculate  $\mathbf{v}_1 \times \mathbf{v}_2$  as follows:

$$\begin{aligned} (2\underline{\hat{i}} + 2\underline{\hat{j}} + \underline{\hat{k}}) \times (-\underline{\hat{j}} - \underline{\hat{k}}) &= (2\underline{\hat{i}} \times (-\underline{\hat{j}})) + (2\underline{\hat{i}} \times (-\underline{\hat{k}})) + (2\underline{\hat{j}} \times (-\underline{\hat{j}})) + (2\underline{\hat{j}} \times (-\underline{\hat{k}})) \\ &\quad + (\underline{\hat{k}} \times (-\underline{\hat{j}})) + (\underline{\hat{k}} \times (-\underline{\hat{k}})) \\ &= -2\underline{\hat{k}} + 2\underline{\hat{j}} - 2\underline{\hat{i}} + \underline{\hat{i}} \quad (\text{since } \underline{\hat{i}} \times \underline{\hat{j}} = \underline{\hat{k}}, \underline{\hat{i}} \times \underline{\hat{k}} = -\underline{\hat{j}}, \underline{\hat{j}} \times \underline{\hat{k}} = \underline{\hat{i}}, \\ &\quad \underline{\hat{k}} \times \underline{\hat{j}} = -\underline{\hat{i}} \text{ and } \underline{\hat{j}} \times \underline{\hat{j}} = \underline{\hat{k}} \times \underline{\hat{k}} = 0) \\ &= -\underline{\hat{i}} + 2\underline{\hat{j}} - 2\underline{\hat{k}} \end{aligned}$$

- (c) [4 marks] The shortest distance between two lines is the length of a vector that connects the two lines and is perpendicular to both lines. For  $\mathcal{L}_1$  and  $\mathcal{L}_2$  this is expressed in the vector equation  $\mathbf{r}_1 + t\hat{\mathbf{n}} = \mathbf{r}_2$  where  $t \in \mathbb{R}$  is a parameter. The corresponding system of linear equations is

$$\left. \begin{aligned} 2r - \frac{1}{3}t &= -3 \\ 2r + s + \frac{2}{3}t &= -1 \\ r + s - \frac{2}{3}t &= 5 \end{aligned} \right\} \begin{aligned} &\rightarrow \text{These equations come from} \\ &(\text{pt on } \mathcal{L}_1) + (\text{scalar mult. of } \hat{\mathbf{n}}) = (\text{pt on } \mathcal{L}_2) \\ &(\underline{u}_1 + r\underline{v}_1) + t\hat{\mathbf{n}} = \underline{u}_2 + s\underline{v}_2 \\ &\therefore r\underline{v}_1 - s\underline{v}_2 + t\hat{\mathbf{n}} = \underline{u}_2 - \underline{u}_1 \end{aligned}$$

Solve this system of linear equations.

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We must solve

$$\begin{bmatrix} 2 & 0 & -\frac{1}{3} \\ 2 & 1 & \frac{2}{3} \\ 1 & 1 & -\frac{2}{3} \end{bmatrix} \begin{bmatrix} r \\ s \\ t \end{bmatrix} = \begin{bmatrix} -3 \\ -1 \\ 5 \end{bmatrix}$$

$$\left[ \begin{array}{ccc|c} 2 & 0 & -\frac{1}{3} & -3 \\ 2 & 1 & \frac{2}{3} & -1 \\ 1 & 1 & -\frac{2}{3} & 5 \end{array} \right]$$

$$\begin{aligned} &\xrightarrow{(R_2 \rightarrow R_2 - R_1, R_3 \rightarrow R_3 - \frac{1}{2}R_1)} \left[ \begin{array}{ccc|c} 2 & 0 & -\frac{1}{3} & -3 \\ 0 & 1 & 1 & 2 \\ 0 & 1 & -\frac{4}{6} & \frac{10+3}{2} \end{array} \right] \end{aligned}$$

$$\xrightarrow{(R_3 \rightarrow R_3 - R_2)} \left[ \begin{array}{ccc|c} 2 & 0 & -\frac{1}{3} & -3 \\ 0 & 1 & 1 & 2 \\ 0 & 0 & -\frac{3}{2} & \frac{9}{2} \end{array} \right]$$

$$\xrightarrow{(R_1 \rightarrow \frac{1}{2}R_1, R_3 \rightarrow -\frac{2}{3}R_3)} \left[ \begin{array}{ccc|c} 1 & 0 & -\frac{1}{6} & -\frac{3}{2} \\ 0 & 1 & 1 & 2 \\ 0 & 0 & 1 & -3 \end{array} \right]$$

Last equation says  $t = -3$  & by back substitution

$$s = 2 - t = 2 - (-3) = 5$$

$$r = -\frac{3}{2} + \frac{1}{6}t = -\frac{3}{2} - \frac{1}{2} = -2.$$

Solution:  $\begin{bmatrix} r \\ s \\ t \end{bmatrix} = \begin{bmatrix} -2 \\ 5 \\ -3 \end{bmatrix}.$

- (d) [2 marks] Hence find the shortest distance between  $L_1$  and  $L_2$  and find the point  $Q$  on  $L_1$  that is closest to  $L_2$ .

The point on  $L_1$  corresponding to  $r = -2$  has coordinates

$$\left. \begin{aligned} x &= 1 + 2r = -3 \\ y &= 1 + 2r = -3 \\ z &= -3 + r = -5 \end{aligned} \right\} \text{ (by Part (a))}$$

So  $Q = (-3, -3, -5)$  is the point on  $L_1$  closest to  $L_2$ .

[The question does not ask you to find the point  $M$  on  $L_2$  that is closest to  $L_1$ , but it is given by the parameter  $s = 5$ , and so the parametric vector form of the equation of  $L_2$  gives

$$\vec{OM} = \vec{u}_2 + 5\vec{v}_2 = (-2\hat{i} + 0\hat{j} + 2\hat{k}) + 5(-\hat{j} - \hat{k})$$

ie  $M$  is  $(-2, -5, -3)$ ]

If  $M$  is the point on  $L_2$  closest to  $L_1$ , then

$$\vec{QM} = t\hat{n}$$

where  $t$  is given by the solution of the system in Part (c), ie  $t = -3$ .

So shortest distance between  $L_1$  &  $L_2$  is

$$\begin{aligned} |\vec{QM}| &= |t\hat{n}| = |t||\hat{n}| \\ &= |-3| \text{ since } |\hat{n}| = 1 \\ &= \underline{\underline{3}} \end{aligned}$$

[You can check this using the coordinates of  $Q$  &  $M$ :

$$|\vec{QM}| = \sqrt{(-3+2)^2 + (-3+5)^2 + (-5+3)^2} = \sqrt{1+4+4} = 3]$$

2. (a) Let  $A = \begin{bmatrix} 3 & 1 & 0 \\ 1 & 3 & 2 \\ -1 & 1 & 2 \end{bmatrix}$  and  $B = \begin{bmatrix} 2 & 1 & 0 \\ 0 & 2 & 1 \\ 0 & 0 & 1 \end{bmatrix}$ .

(i) [3 marks] Find the inverse  $A^{-1}$ .

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$$\left[ \begin{array}{ccc|ccc} 3 & 1 & 0 & 1 & 0 & 0 \\ 1 & 3 & 2 & 0 & 1 & 0 \\ -1 & 1 & 2 & 0 & 0 & 1 \end{array} \right]$$

$$\begin{array}{l} R_2 \rightarrow R_2 - \frac{1}{3}R_1 \\ R_3 \rightarrow R_3 + \frac{1}{3}R_1 \end{array} \rightarrow \left[ \begin{array}{ccc|ccc} 3 & 1 & 0 & 1 & 0 & 0 \\ 0 & 8/3 & 2 & -1/3 & 1 & 0 \\ 0 & 4/3 & 2 & 1/3 & 0 & 1 \end{array} \right]$$

$$R_3 \rightarrow R_3 - \frac{1}{2}R_2 \rightarrow \left[ \begin{array}{ccc|ccc} 3 & 1 & 0 & 1 & 0 & 0 \\ 0 & 8/3 & 2 & -1/3 & 1 & 0 \\ 0 & 0 & 1 & 1/2 & -1/2 & 1 \end{array} \right]$$

$$R_2 \rightarrow R_2 - 2R_3 \rightarrow \left[ \begin{array}{ccc|ccc} 3 & 1 & 0 & 1 & 0 & 0 \\ 0 & 8/3 & 0 & -4/3 & 2 & -2 \\ 0 & 0 & 1 & 1/2 & -1/2 & 1 \end{array} \right]$$

$$R_2 \rightarrow \frac{3}{8}R_2 \rightarrow \left[ \begin{array}{ccc|ccc} 3 & 1 & 0 & 1 & 0 & 0 \\ 0 & 1 & 0 & -1/2 & 3/4 & -3/4 \\ 0 & 0 & 1 & 1/2 & -1/2 & 1 \end{array} \right]$$

$$R_1 \rightarrow R_1 - R_2 \rightarrow \left[ \begin{array}{ccc|ccc} 3 & 0 & 0 & 3/2 & -3/4 & 3/4 \\ 0 & 1 & 0 & -1/2 & 3/4 & -3/4 \\ 0 & 0 & 1 & 1/2 & -1/2 & 1 \end{array} \right]$$

$$R_1 \rightarrow \frac{1}{3}R_1 \rightarrow \left[ \begin{array}{ccc|ccc} 1 & 0 & 0 & 1/2 & -1/4 & 1/4 \\ 0 & 1 & 0 & -1/2 & 3/4 & -3/4 \\ 0 & 0 & 1 & 1/2 & -1/2 & 1 \end{array} \right]$$

$$\text{So } A^{-1} = \begin{bmatrix} 1/2 & -1/4 & 1/4 \\ -1/2 & 3/4 & -3/4 \\ 1/2 & -1/2 & 1 \end{bmatrix}$$

(ii) [2 marks] Hence find the  $3 \times 3$  lower triangular matrix  $X$  such that  $AX = B$ .

$$AX = B \text{ gives } A^{-1}AX = A^{-1}B \text{ so } X = A^{-1}B.$$

$$\therefore X = \begin{bmatrix} \frac{1}{2} & -\frac{1}{4} & \frac{1}{4} \\ -\frac{1}{2} & \frac{3}{4} & -\frac{3}{4} \\ \frac{1}{2} & -\frac{1}{2} & 1 \end{bmatrix} \begin{bmatrix} 2 & 1 & 0 \\ 0 & 2 & 1 \\ 0 & 0 & 1 \end{bmatrix}$$

$$= \begin{bmatrix} 1 & 0 & 0 \\ -1 & 1 & 0 \\ 1 & -\frac{1}{2} & \frac{1}{2} \end{bmatrix}$$

(iii) [1 mark] Find  $\det(A)$ . (Hint: This may be done directly, but also follows easily from a correct answer to part (ii).)

Question 2 continues on the next page

With  $X$  as in (ii),  $\det X = \frac{1}{2}$  (product of diagonal entries — since  $X$  is lower triangular).  
Also  $\det B = 4$  (product of diagonal entries — since  $B$  is upper triangular).

$$AX = B \text{ gives } (\det A)(\det X) = (\det B)$$

$$\text{i.e. } \frac{1}{2}(\det A) = 4$$

$$\underline{\underline{\det A = 8}}$$

[In truth, it is easier to use 1<sup>st</sup> row expansion:

$$\det \begin{bmatrix} 3 & 1 & 0 \\ 1 & 3 & 2 \\ -1 & 1 & 2 \end{bmatrix} = 3(6-2) - (2+2) = 8$$

(b) Consider the matrix  $C = \begin{bmatrix} 0 & 0 & 2 \\ 2 & 1 & -4 \\ 1 & 0 & -1 \end{bmatrix}$ .

(i) [2 marks] Find all eigenvalues of  $C$ .

Question 2 continues on the next page

$$C - \lambda I = \begin{bmatrix} -\lambda & 0 & 2 \\ 2 & 1-\lambda & -4 \\ 1 & 0 & -1-\lambda \end{bmatrix}$$

It is easiest to evaluate  $\det(C - \lambda I)$  by the 2<sup>nd</sup> column expansion:

$$\begin{aligned} \det(C - \lambda I) &= -0 + (1-\lambda) \det \begin{bmatrix} -\lambda & 2 \\ 1 & -1-\lambda \end{bmatrix} - 0 \\ &= (1-\lambda) (\lambda(\lambda+1) - 2) \\ &= (1-\lambda) (\lambda^2 + \lambda - 2) \\ &= (1-\lambda) (\lambda+2) (\lambda-1) \end{aligned}$$

So the eigenvalues are 1, 1 and 2 (i.e. 1 is repeated)

OR by 1<sup>st</sup> row expansion

$$\begin{aligned} \det(C - \lambda I) &= (-\lambda) \det \begin{bmatrix} 1-\lambda & -4 \\ 0 & -1-\lambda \end{bmatrix} - 0 + 2 \det \begin{bmatrix} 2 & 1-\lambda \\ 1 & 0 \end{bmatrix} \\ &= -\lambda [(1-\lambda)(-1-\lambda) - 0] + 2 [0 - (1-\lambda)] \end{aligned}$$

It helps at this point to notice that  $1-\lambda$  is a factor of both nonzero terms. So

$$\begin{aligned} \det(C - \lambda I) &= (1-\lambda) [-\lambda(-1-\lambda) - 2] \\ &= (1-\lambda) (\lambda^2 + \lambda - 2) \text{ as above.} \end{aligned}$$

If you don't notice the common factor, you can still do it:

$$\begin{aligned} \det(C - \lambda I) &= -\lambda [\lambda^2 - 1] + 2\lambda - 2 \\ &= -\lambda^3 + 3\lambda - 2 \end{aligned}$$

Here you need to notice that  $\lambda = 1$  is obviously a root, so  $\lambda - 1$  is a factor (Anyway, Part(ii) tells you that 1 is an eigenvalue)

$$\det(C - \lambda I) = (\lambda - 1)(-\lambda^2 - \lambda + 2), \text{ etc.}$$

(ii) [2 marks] Find the eigenspace of  $C$  corresponding to eigenvalue 1.

We must solve  $(C - I)\begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$

ie  $\begin{bmatrix} -1 & 0 & 2 \\ 2 & 0 & -4 \\ 1 & 0 & -2 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$

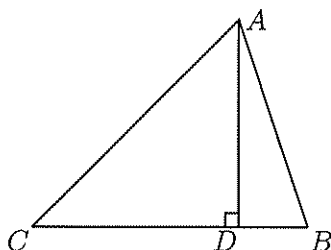
Applying E.R.O's  $R_2 \rightarrow R_2 + 2R_1$  &  $R_3 \rightarrow R_3 + R_1$ , etc.  
show that this system is equivalent to

$$\begin{bmatrix} 1 & 0 & -2 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$y$  &  $z$  are free variables & the equation gives  $x = 2z$ . So if we let  $y = s$  &  $z = t$  (arbitrary parameters) we get  $\begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 2t \\ s \\ t \end{bmatrix}$ .

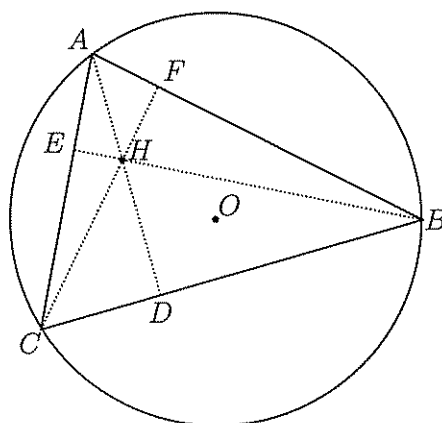
ie the 1-eigenspace is  $\left\{ \begin{bmatrix} 2t \\ s \\ t \end{bmatrix} \mid s, t \in \mathbb{R} \right\}$ .

3. Recall the definition of an *altitude* of a triangle  $ABC$ :



It is the line joining a vertex  $A$  to the opposite side at  $D$  so that  $\overrightarrow{AD}$  and  $\overrightarrow{BC}$  are orthogonal.

Let  $O$  be the centre of a circumscribing circle around a triangle  $ABC$ , and let  $H$  be the point of intersection of the altitudes  $AD$ ,  $BE$  and  $CF$ :



Let  $\overrightarrow{OA} = \mathbf{a}$ ,  $\overrightarrow{OB} = \mathbf{b}$ , and  $\overrightarrow{OC} = \mathbf{c}$ .

- (a) [2 marks] Write the vectors  $\overrightarrow{AB}$  and  $\overrightarrow{BC}$  in terms of  $\mathbf{a}$ ,  $\mathbf{b}$  and  $\mathbf{c}$ .

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$$\overrightarrow{AB} = \overrightarrow{OB} - \overrightarrow{OA} = \underline{\mathbf{b}} - \underline{\mathbf{a}}$$

$$\overrightarrow{BC} = \overrightarrow{OC} - \overrightarrow{OB} = \underline{\mathbf{c}} - \underline{\mathbf{b}}$$



(b) [2 marks] Show that  $\mathbf{b} + \mathbf{c}$  and  $\mathbf{b} - \mathbf{c}$  are orthogonal.

$$\begin{aligned} (\mathbf{b} + \mathbf{c}) \cdot (\mathbf{b} - \mathbf{c}) &= \mathbf{b} \cdot \mathbf{b} - \mathbf{b} \cdot \mathbf{c} + \mathbf{c} \cdot \mathbf{b} - \mathbf{c} \cdot \mathbf{c} \\ &= |\mathbf{b}|^2 - |\mathbf{c}|^2 \quad \text{since } \mathbf{b} \cdot \mathbf{c} = \mathbf{c} \cdot \mathbf{b}. \end{aligned}$$

Since  $O$  is the centre of the circle, the line segments  $OB$  and  $OC$  have the same length. So  $|\mathbf{b}| = |\mathbf{c}|$ , & hence

$$(\mathbf{b} + \mathbf{c}) \cdot (\mathbf{b} - \mathbf{c}) = 0.$$

By definition, this says that  $\mathbf{b} + \mathbf{c}$  &  $\mathbf{b} - \mathbf{c}$  are orthogonal.

[N.B.  $\mathbf{b} - \mathbf{c} \neq \mathbf{0}$ , since  $B \neq C$  are distinct points, but  $\mathbf{b} + \mathbf{c}$  could be  $\mathbf{0}$  — if the centre  $O$  lies on  $BC$ .]

(c) [2 marks] Hence, or otherwise, justify the statement:

A parametric vector equation for the line through  $A$  and  $D$  is

$$\mathcal{L}_1: \mathbf{r} = \mathbf{a} + t(\mathbf{b} + \mathbf{c}), \quad t \in \mathbb{R}.$$

Question 3 continues on the next page

The statement is not actually true if  $\mathbf{b} + \mathbf{c} = \mathbf{0}$  — error in the question! But it is OK if  $\mathbf{b} + \mathbf{c} \neq \mathbf{0}$ . So let us assume that  $\mathbf{b} + \mathbf{c} \neq \mathbf{0}$ .

Since  $AD$  is perpendicular to  $BC$  the vector  $\overrightarrow{AD}$  must be parallel to any nonzero vector orthogonal to  $\overrightarrow{CB}$ . Since  $\overrightarrow{CB} = \mathbf{b} - \mathbf{c}$  it follows that  $\overrightarrow{AD}$  is parallel to  $\mathbf{b} + \mathbf{c}$ , ie  $\overrightarrow{AD} = \alpha(\mathbf{b} + \mathbf{c})$  for some scalar  $\alpha$ .

The parametric vector form of the equation of the line through  $A$  in the direction of  $\mathbf{b} + \mathbf{c}$

$$\text{is } \mathbf{r} = \overrightarrow{OA} + t(\mathbf{b} + \mathbf{c}) \quad (t \in \mathbb{R})$$

$$\text{ie } \mathbf{r} = \mathbf{a} + t(\mathbf{b} + \mathbf{c}), \text{ as required.}$$

- (d) [4 marks] Express the vector  $\overrightarrow{OH}$  in terms of  $\mathbf{a}$ ,  $\mathbf{b}$  and  $\mathbf{c}$ .

(Hint: use a parametric vector equation for the line through  $C$  and  $F$ .)

There are no more questions.

Extra blank pages are provided in case you need more space for your answers.

Assuming that  $\mathbf{a} + \mathbf{b} \neq \mathbf{0}$  a parametric form for the equation of the line through  $C$  &  $F$  is

$$\mathbf{r} = \mathbf{c} + s(\mathbf{a} + \mathbf{b}) \quad (s \in \mathbb{R})$$

by the same reasoning as used for  $AD$ .

Since  $H$  lies on both  $AD$  &  $CF$  there must exist scalars  $t$  &  $s$  such that

$$\overrightarrow{OH} = \mathbf{a} + t(\mathbf{b} + \mathbf{c}) = \mathbf{c} + s(\mathbf{a} + \mathbf{b}) \quad (*)$$

Since the lines  $AD$  and  $CF$  have a unique point of intersection, there can only be one value of  $t$  and one value of  $s$  to satisfy the equation (\*). But  $t=1$  &  $s=1$  clearly works, making both sides equal to  $\mathbf{a} + \mathbf{b} + \mathbf{c}$ .

$$\text{So } \overrightarrow{OH} = \mathbf{a} + \mathbf{b} + \mathbf{c}.$$

[Note: this answer is valid in all cases, despite our assumptions that  $\mathbf{a} + \mathbf{b} \neq \mathbf{0}$  and  $\mathbf{b} + \mathbf{c} \neq \mathbf{0}$ . The point  $H$  defined by  $\overrightarrow{OH} = \mathbf{a} + \mathbf{b} + \mathbf{c}$  always lies on all three altitudes, eg.  $\overrightarrow{AH} = \overrightarrow{AO} + \overrightarrow{OH} = -\mathbf{a} + (\mathbf{a} + \mathbf{b} + \mathbf{c}) = \mathbf{b} + \mathbf{c}$ , which is orthogonal to  $\overrightarrow{BC} = \mathbf{c} - \mathbf{b}$ , etc.]