Limits and Calculus for Curves

Definition

For an interval $I \subset \mathbb{R}$ and curve $\mathbf{c}: I \to \mathbb{R}^n$ with

$$\mathbf{c}(t) = \Big(c_1(t), c_2(t), \ldots, c_n(t)\Big),\,$$

the functions $c_i: I \to \mathbb{R}$, i = 1, 2, ..., n are called the components of **c**.

Define limits, derivatives and integrals component by component.

Definition

• $\lim_{t\to a} \mathbf{c}(t) = \left(\lim_{t\to a} c_1(t), \lim_{t\to a} c_2(t), \dots, \lim_{t\to a} c_n(t)\right)$

•
$$\frac{d\mathbf{c}(t)}{dt} = \dot{\mathbf{c}}(t) = \mathbf{c}'(t) = (c_1'(t), c_2'(t), \dots, c_n'(t))$$

$$\bullet \int_a^b \mathbf{c}(t)dt = \left(\int_a^b c_1(t)dt, \int_a^b c_2(t)dt, \dots, \int_a^b c_n(t)dt\right)$$

JM Kress (UNSW Maths & Stats)

MATH2111 Curves

Semester 1, 2014

9 / 29

Limits and Calculus for Curves

Definition

A curve $\mathbf{c}: I \to \mathbb{R}^n$ is

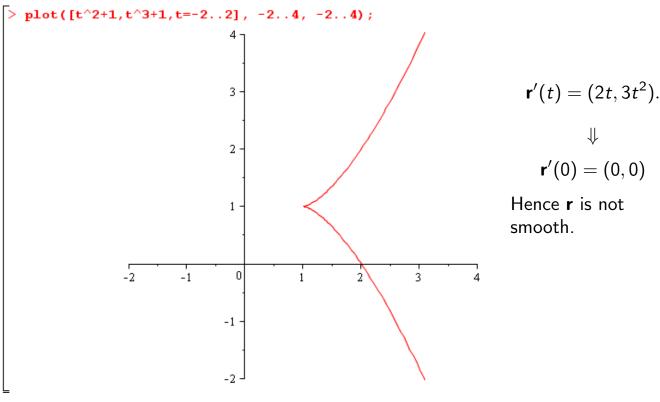
- continuous if its component functions are continuous.
- simple if it is continuous and has no multiple points (other than the end points if it is closed).
- smooth if its components are differentiable and their derivatives do not simultaneouly vanish.
- piecewise smooth if it is made up of a finite number of smooth curves.

A curve has an orientation — the direction of increasing t.

We will revisit continuity in the analysis section and give a different definition which we will show is equivalent.

Limits and Calculus for Curves

Example: $\mathbf{r}:[-2,2]\to\mathbb{R}^2$ with $\mathbf{r}(t)=(t^2+1,t^3+1)$ is not smooth.



JM Kress (UNSW Maths & Stats)

MATH2111 Curves

Semester 1, 2014

11 / 29

Differentiation Rules for Curves

Working component by component we can prove the following rules from their one variable counterparts.

$$\frac{d}{dt} \left(\mathbf{c_1}(t) + \mathbf{c_2}(t) \right) = \frac{d\mathbf{c_1}(t)}{dt} + \frac{d\mathbf{c_2}(t)}{dt}
\frac{d}{dt} \left(\lambda \mathbf{c}(t) \right) = \lambda \frac{d\mathbf{c}(t)}{dt}
\frac{d}{dt} \left(f(t)\mathbf{c}(t) \right) = \frac{df(t)}{dt} \mathbf{c}(t) + f(t) \frac{d\mathbf{c}(t)}{dt}
\frac{d}{dt} \left(\mathbf{c_1}(t) \cdot \mathbf{c_2}(t) \right) = \frac{d\mathbf{c_1}(t)}{dt} \cdot \mathbf{c_2}(t) + \mathbf{c_1}(t) \cdot \frac{d\mathbf{c_2}(t)}{dt}
\frac{d}{dt} \left(\mathbf{c_1}(t) \times \mathbf{c_2}(t) \right) = \frac{d\mathbf{c_1}(t)}{dt} \times \mathbf{c_2}(t) + \mathbf{c_1}(t) \times \frac{d\mathbf{c_2}(t)}{dt}
\frac{d}{dt} \left(\mathbf{c}(f(t)) \right) = \mathbf{c}'(f(t)) f'(t)$$

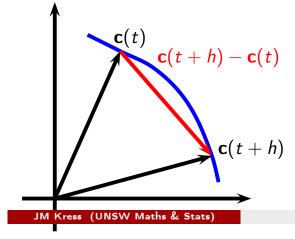
Interpretation of the Derivative

$$\frac{d\mathbf{c}(t)}{dt} = (c'_1(t), \dots, c'_n(t))$$

$$= \left(\lim_{h \to 0} \frac{c_1(t+h) - c_1(t)}{h}, \dots, \lim_{h \to 0} \frac{c_n(t+h) - c_n(t)}{h}\right)$$

$$= \lim_{h \to 0} \left(\frac{c_1(t+h) - c_1(t)}{h}, \dots, \frac{c_n(t+h) - c_n(t)}{h}\right)$$

$$= \lim_{h \to 0} \frac{\mathbf{c}(t+h) - \mathbf{c}(t)}{h}$$



As h gets smaller, the direction of $\mathbf{c}(t+h) - \mathbf{c}(t)$ approaches the direction of the tangent to the curve's image. If $\mathbf{c}'(t)$ exists and is non-zero, it is called the tangent vector to \mathbf{c} at t, or the velocity of \mathbf{c} at t. Ie, $\mathbf{v}(t) = \mathbf{c}'(t)$. The speed of \mathbf{c} at t is $|\mathbf{v}(t)| = \sqrt{\mathbf{v}(t) \cdot \mathbf{v}(t)}$. The second derivative $\mathbf{a}(t) = \mathbf{v}'(t) = \mathbf{c}''(t)$ is called the acceleration.

MATH2111 Curves

Semester 1, 2014

13 / 29

Tangent Vector Example

Consider the curve $\mathbf{r}:I\to\mathbb{R}^3$ for an interval $I\subset\mathbb{R}$ given by

$$\mathbf{r}(t) = 2\cos t\mathbf{i} + 3\sin t\mathbf{j} + \frac{\sqrt{5}}{2}\cos 2t\mathbf{k}.$$

- a) Find the velocity and acceleration vectors.
- b) Show that the velocity and acceleration vectors are perpendicular at $t = \frac{n\pi}{2}$, $n \in \mathbb{Z}$.
- c) Find the length of the curve between $\mathbf{r}(0)$ and $\mathbf{r}(2\pi)$. [Recall: length $=\int_a^b ||\mathbf{r}'(t)|| dt$.]
- d) Find the unit tangent vector at $t = \frac{\pi}{6}$.
- e) Sketch the curve and indicate the unit tangent vector found in (d).