# MATH1902 LINEAR ALGEBRA (ADVANCED)

#### Semester 1

#### Board Tutorial for Week 6

2017

Preparatory exercises should be attempted before coming to the tutorial. Questions labelled with an asterisk are suitable for students aiming for a credit or higher.

### Important Ideas and Useful Facts:

- (i) A line in space is determined by two points, or by one point and a direction.
- (ii) A plane in space is determined either by three non-collinear points, or by one point and a perpendicular (normal) direction.
- (iii) If the vector  $\mathbf{v}$  points in the direction of a line  $\mathcal{L}$  containing the point  $P_0$ , then the parametric vector equation of  $\mathcal{L}$  is

$$\mathbf{r} - \mathbf{r}_0 = t\mathbf{v}$$
 or equivalently  $\mathbf{r} = \mathbf{r}_0 + t\mathbf{v}$ 

where  $\mathbf{r}$  is the position vector of a typical point on  $\mathcal{L}$ ,  $\mathbf{r}_0$  is the position vector of  $P_0$  and t is a parameter which varies over all real numbers.

(iv) If the vector  $\mathbf{v} = a\,\mathbf{i} + b\,\mathbf{j} + c\,\mathbf{k}$  points in the direction of a line  $\mathcal{L}$  containing the point  $P_0(x_0, y_0, z_0)$ , then the parametric scalar equations of  $\mathcal{L}$  are

$$\left. \begin{array}{rcl} x & = & x_0 + ta \\ y & = & y_0 + tb \\ z & = & z_0 + tc \end{array} \right\} \ t \in \mathbb{R}$$

and the Cartesian equations are (in the case that a, b, c are all nonzero):

$$\frac{x - x_0}{a} = \frac{y - y_0}{b} = \frac{z - z_0}{c}$$
.

(v) The shortest distance d from a point P to a line containing the point Q and pointing in the direction of  $\mathbf{v}$  is

$$d = \frac{|\mathbf{v} \times \overrightarrow{PQ}|}{|\mathbf{v}|}.$$

(vi) If the vector  $\mathbf{n}$  is normal to a plane  $\mathcal{P}$  containing the point  $P_0$ , then the vector equation of  $\mathcal{P}$  is

$$(\mathbf{r} - \mathbf{r}_0) \cdot \mathbf{n} = 0$$
 or equivalently  $\mathbf{r} \cdot \mathbf{n} = \mathbf{r}_0 \cdot \mathbf{n}$ 

where **r** is the position vector of a typical point and  $\mathbf{r}_0$  is the position vector of  $P_0$ .

(vii) If the vector  $\mathbf{n} = a \mathbf{i} + b \mathbf{j} + c \mathbf{k}$  is normal to the plane  $\mathcal{P}$  containing the point  $P_0(x_0, y_0, z_0)$ , then the Cartesian equation of  $\mathcal{P}$  is

$$ax + by + cz = d$$

where  $d = ax_0 + by_0 + cz_0$ .

(viii) If  $P_1$ ,  $P_2$ ,  $P_3$  are non-collinear points on a plane, then a normal vector to the plane is

$$\mathbf{n} = \overrightarrow{P_1P_2} \times \overrightarrow{P_1P_3}$$
.

(ix) The shortest distance d from a point P to a plane containing the point Q and with normal vector  $\mathbf{n}$  is

$$d = \frac{|\mathbf{n} \cdot \overrightarrow{PQ}|}{|\mathbf{n}|}.$$

## **Tutorial Exercises:**

- For each of (i)–(vii), find two matching descriptions from (a)–(n). 8.
  - line containing (0,0,0) in the direction of  $\mathbf{i} + \mathbf{j} + \mathbf{k}$ (i)
  - line containing (-1, 2, -1) in the direction of  $-\mathbf{i} + 2\mathbf{j} + 2\mathbf{k}$ (ii)
  - line containing (-1, 2, -1) and (0, 0, -2)(iii)
  - plane containing (0,0,0) with normal vector  $\mathbf{i} + \mathbf{j} + \mathbf{k}$ (iv)
  - $(\mathbf{v})$ plane containing (-1, 2, -1) with normal vector  $-\mathbf{i} + 2\mathbf{j} + 2\mathbf{k}$
  - (vi) plane containing (-1, 2, -1), (0, 0, -2) and (1, 3, 3)
  - plane containing (-1, 2, -1), (0, 0, -2) and (1, 3, 2)(vii)

(a) 
$$x + y + z = 0$$
 (b)  $x = y = z$  (c)  $x + y - z = 2$ 

(d) 
$$x+1 = \frac{y-2}{-2} = \frac{z+1}{-2}$$
 (e)  $7x + 6y - 5z = 10$ 

(f) 
$$x+1 = \frac{y-2}{-2} = \frac{z+1}{-1}$$
 (g)  $x-2y-2z = -3$ 

(h) 
$$(\mathbf{r} + 2\mathbf{k}) \cdot (7\mathbf{i} + 6\mathbf{j} - 5\mathbf{k}) = 0$$
 (i)  $\mathbf{r} = \mathbf{i} - 2\mathbf{j} - 5\mathbf{k} + t(\mathbf{i} - 2\mathbf{j} - 2\mathbf{k})$   
(j)  $(\mathbf{r} + 2\mathbf{k}) \cdot (\mathbf{i} + \mathbf{j} - \mathbf{k}) = 0$  (k)  $\mathbf{r} \cdot (\mathbf{i} + \mathbf{j} + \mathbf{k}) = 0$   
(l)  $(\mathbf{r} + 3\mathbf{i}) \cdot (\mathbf{i} - 2\mathbf{j} - 2\mathbf{k}) = 0$  (m)  $\mathbf{r} = \mathbf{i} - 2\mathbf{j} - 3\mathbf{k} + t(\mathbf{i} - 2\mathbf{j} - \mathbf{k})$ 

(j) 
$$(\mathbf{r} + 2\mathbf{k}) \cdot (\mathbf{i} + \mathbf{j} - \mathbf{k}) = 0$$
 (k)  $\mathbf{r} \cdot (\mathbf{i} + \mathbf{j} + \mathbf{k}) = 0$ 

(1) 
$$(\mathbf{r} + 3\mathbf{i}) \cdot (\mathbf{i} - 2\mathbf{j} - 2\mathbf{k}) = 0$$
 (m)  $\mathbf{r} = \mathbf{i} - 2\mathbf{j} - 3\mathbf{k} + t(\mathbf{i} - 2\mathbf{j} - \mathbf{k})$ 

- (n)  $\mathbf{r} = \mathbf{i} + \mathbf{i} + \mathbf{k} t(\mathbf{i} + \mathbf{i} + \mathbf{k})$
- 9. Consider the following points in space:

$$P(1,1,1)$$
,  $Q(5,-5,-3)$ ,  $R(6,-3,-1)$ ,  $S(2,3,3)$ .

- (i) Find the parametric vector, parametric scalar and Cartesian equations of the line  $\mathcal{L}_1$  passing through P and R, and also the line  $\mathcal{L}_2$  passing through Q and S.
- (ii) Find the intersection point T of  $\mathcal{L}_1$  and  $\mathcal{L}_2$ .
- (iii) Verify that T is the midpoint of both PR and QS. Are you surprised?
- 10. The following planes intersect in a line:

$$x + y + z = 2$$
 and  $x - y + 3z = 0$ .

Find a point on this line of intersection and its direction. Now write down parametric and Cartesian equations for this line.

2

11. What do we mean by the angle between two planes? Find the cosine of the angle between the two planes given by equations

$$x + y + z = 6$$
 and  $x - 2y - z = 3$ .

12. Let P and Q be fixed points in space. Suppose R is a point in space (which varies) such that

$$\overrightarrow{OR} = \lambda \overrightarrow{OP} + \mu \overrightarrow{OQ}$$

for real numbers  $\lambda$  and  $\mu$ , subject to the constraint

$$\lambda + \mu = 1.$$

Prove that R varies over the line that passes through P and Q. Describe the values of  $\lambda$  such that R is located:

- (i) somewhere on the line segment joining P to Q
- (ii) somewhere on the line beyond P on the side away from Q
- (iii) somewhere on the line beyond Q on the side away from P
- (iv) twice as far from P as it is from Q.
- 13. Let r be a fixed positive real number. Describe geometrically the configuration S in space of points whose position vectors  $\mathbf{r}$  satisfy the equation

$$|\mathbf{r}| = r$$
.

Let  $P(x_0, y_0, z_0)$  be a point on S. Find the Cartesian equation of the tangent plane to S at P.

- 14. Suppose that P is a point in space and  $\mathcal{P}$  is a plane not containing P. Let Q be any point on  $\mathcal{P}$  and let R be the closest point on  $\mathcal{P}$  to P. Explain why the dot product  $\overrightarrow{PQ} \cdot \overrightarrow{PR}$  must be positive.
- 15.\* Find the distance from P(3,0,-1) to the plane  $\mathcal{P}$  described by the equation

$$4x + 2y - z = 6.$$

3

Find the closest point to P which lies on  $\mathcal{P}$ .