#### Primordial Black Holes

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Solution

Simulation Solution

# The Effects of a Primordial Black Hole on the Surface of a Neutron Star

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### Primordial Black Holes

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#### Introduction

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Analytic Solution

Simulation Solution

- Normal black holes have a minimum mass on the order of a few solar masses.
- In the early universe while it was very hot and dense, small perturbations could be enough to create a small black hole.
- The mass of a primordial black hole is much less than one solar mass  $(10^{-18} 10^{-6} M_{\odot})$ , and microscopic in size.

### Primordial Black Holes as Dark Matter

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Dark matter is matter that does not emit/absorb light, and is chargeless. Dark matter accounts for about a quarter of the energy in the universe, but we don't know what it is.

Primordial black holes may be a good candidate for dark matter since: they are chargeless, do not emit light, have a very small radius, and are non-relativistic. Also, most other proposed explanations of dark matter involve creating a new particle not part of the standard model.

### Flat Star Model

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- Neutron stars are flat and infinite
- Primordial black holes are point masses
- Neutron stars are incompressible fluids
- Gravitational interactions are Newtonian
- Constant velocity

# Eigenfunctions of Laplacian

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Solving for  $\varphi$ Solving for  $\eta$ Plotting  $\eta$ Solving for E

Simulation Solution Assume a product solution for the velocity potential and solve the Laplacian.

$$\varphi = R(r)Z(z)\Theta(\theta)T(t)$$

$$\nabla^{2}\varphi = 0$$

$$\implies \varphi \propto \begin{cases} J_{\mu}(kr) \\ Y_{\mu}(kr) \end{cases} \begin{cases} e^{-kz} \\ e^{kz} \end{cases} \begin{cases} \sin(\mu\theta) \\ \cos(\mu\theta) \end{cases} T(t)$$

$$\implies \varphi \propto J_{0}(kr)e^{kz}T(t)$$

T(t) comes from boundary conditions.

### Hankel Transform

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#### Definition

The Hankel transform of a function f(s) is given by

$$\mathscr{H}_{\nu}{f}(\sigma) = \int_0^\infty f(s)J_{\nu}(s\sigma)s\,ds,$$

where  $J_{\nu}$  is the Bessel function of the first kind, of order  $\nu \geq -\frac{1}{2}$ , and  $\sigma$  is a non-negative real variable.

### Corollary

The Hankel transform is self-reciprocal, that is, the inverse Hankel transform is also given by Definition 1.

# Solving for $\varphi$

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Simulation Solution From the pressure condition:

$$\begin{split} \left(\frac{\partial^2\varphi}{\partial t^2} + g\frac{\partial\varphi}{\partial z} + \frac{\partial\Phi}{\partial t}\right)\bigg|_{z=0} &= 0\\ \text{where } \Phi = \frac{-Gm}{\sqrt{r^2 + (z+vt)^2}} = \int_0^\infty a(k)J_0(kr)k\,dk\\ \varphi = \frac{Gmv}{g}\int_0^\infty \frac{J_0(kr)e^{kz}}{1+kv^2/g}\left(-\operatorname{sgn}(t)e^{-kv|t|} + 2\operatorname{H}(t)\cos(\omega_k t)\right)dk\\ \text{with } \omega_k^2 = gk \end{split}$$

### Deformation of Surface

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Analytic Solution Solving for  $\varphi$  Solving for  $\eta$  Plotting  $\eta$  Solving for E

Simulation Solution We can easily solve for the shape of the surface now that we have the velocity potential,

$$\frac{\partial \varphi}{\partial z}\Big|_{z=0} = \frac{\partial \eta}{\partial t}$$

$$\eta = \frac{Gm}{g} \int_0^\infty \frac{J_0(kr)}{1 + kv^2/g} \left( e^{-kv|t|} + 2 H(t)v \sqrt{\frac{k}{g}} \sin(\omega_k t) \right) dk.$$

Maple was used to perform numerical integration and plot the surface waves.

# Analytic Surface Waves

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Plotting  $\eta$ Solving for E

Simulation Solution

Figure: Waves!

## **Energy Transferred**

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Solving for  $\varphi$ Solving for  $\eta$ Plotting  $\eta$ Solving for E

Simulation Solution We can calculate the energy by taking the sum of the kinetic, and potential energies,

$$\begin{split} E &= \lim_{t \to \infty} \frac{1}{2} \rho \int_{-\infty}^{0} \int_{0}^{\infty} |\nabla \varphi|^{2} r dr dz \int_{0}^{2\pi} d\theta \\ &+ \rho g \int_{0}^{\infty} \int_{0}^{\eta} z dz \, r dr \int_{0}^{2\pi} d\theta \\ &= 4\pi \rho \frac{G^{2} m^{2}}{a}. \end{split}$$

We take the limit as t approaches infinity, because we are interested in the total energy transferred.

### Future Work

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Smooth Particle Hydrodynamics My focus next semester will be on simulating the collision with smooth particle hydrodynamics. Smooth particle hydrodynamics is a computational fluid dynamics method that uses N-Body methods, and is typically used for free surface simulations.