# Bare Demo of NRSMRev.cls for USNC-URSI National Radio Science Meeting

Yuchen Jin and Yuchen Jin II

The University of Here, Anywhere, VA 12345, USA, http://www.here.edu

Abstract—The abstract goes here.

Index Terms—IEEE, IEEEtran, journal, LATEX, paper, template.

## I. SHOW HOMEWORK

sadfasf, sdfdsf, sdf.

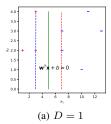
Test citations:

[1] [2] [3].

## A. Show Floats

Test figures and example block which is shown in Example I.1.

**Example I.1 (Figure Problem)** *Test those inner subgraphs, i.e.* Fig. *1a* and Fig. *1b*. Also test *1b* and (1-1):



Here could be graphs. (b) D = 0.5

Fig. 1. Test graphs.

Test subequations and the theorem block which is shown in Theorem I.1.

**Theorem I.1 (Example Theorem)** *Here we show a simple example of subequations in* (1-1):

$$\frac{\partial \mathcal{L}(\mathbf{w}, b)}{\partial \mathbf{w}} = \mathbf{w} + C \sum_{i} \frac{\partial \ell_{i}}{\partial \mathbf{w}}, \tag{1-1}$$

$$\frac{\partial \mathcal{L}(\mathbf{w}, b)}{\partial b} = C \sum_{i} \frac{\partial \ell_{i}}{\partial b}, \tag{1-2}$$

Test table, which is shown in Table I: Test equations in (2):

$$\begin{split} I(\Omega) &= \operatorname{Re} \left\{ \left. \frac{e^{-x}}{j\Omega} e^{j\Omega x} \right|_0^1 + o\left(\frac{1}{\Omega}\right) \right\} \approx \operatorname{Re} \left\{ \left. \frac{e^{-x}}{j\Omega} e^{j\Omega x} \right|_0^1 \right\} \\ &= \operatorname{Re} \left\{ \left. \frac{e^{j\Omega - 1} - 1}{j\Omega} \right\} = \frac{1}{\Omega e} \cos\left(\Omega - \frac{\pi}{2}\right) = \frac{1}{\Omega e} \sin\Omega. \end{split} \tag{2}$$

TABLE I PARAMETERS OF DAUBECHIES'S FILTER.

h[n]	g[n]
0.3327	-0.0352
0.8069	-0.0854
0.4599	0.1350
-0.1350	0.4599
-0.0854	-0.8069
0.0352	0.3327
	0.3327 0.8069 0.4599 -0.1350 -0.0854

## B. Show Algorithm

Test Algorithm in Algorithm 1:

# Algorithm 1 DWT Algorithm

**Input:** Sequence x in time domain

Output: Sequence  $\hat{\mathbf{x}}$  in wavelet domain

- 1:  $N = \lfloor \log_2(\operatorname{length}(\mathbf{x})) \rfloor$ ;
- 2:  $\mathbf{c}_N = \mathbf{x}, \ \hat{\mathbf{x}} = \varnothing;$
- 3: for i from 1 to N do
- 4:  $\mathbf{c}_{N-i}$ ,  $\mathbf{d}_{N-i}$  = analysis\_filter( $\mathbf{c}_{N-i+1}$ );
- 5: insert  $\mathbf{d}_{N-i}$  at the beginning of  $\hat{\mathbf{x}}$ .
- 6: end for

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## Test codings:

```
# HyperPlate of SVM. It contains variables
    including w and b, and convert input x
    vector to a single value y(+-1).
with tf.name_scope('SVMPlate'): #Noted that the
    dimension of y must be 1, so the constants
    should be 1 dimensional.
    self.constrain = tf.constant(
        SVMPrimalSolution.Domain, dtype=tf.
        float32, shape=[1], name='Constrain')
    self.w = self.weight_variable([1, self.xDim],
        name='Weight')
    bias = self.bias_variable([1], name='Bias')
    self.subjection = tf.multiply(self.y, tf.
        matmul(self.w, self.x) + bias)
    tf.add_to_collection('Weight', self.w)
    tf.add_to_collection('Bias', bias)
@staticmethod
def weight_variable(shape, name=None):
    '''weight_variable generates a weight
        variable of a given shape.'''
    initial = tf.truncated_normal(shape, stddev
        =0.1)
    if name is not None:
        return tf.Variable(initial, name=name)
        return tf. Variable (initial)
@staticmethod
```

### ACKNOWLEDGMENT

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### II. REFERENCES

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## APPENDIX A

PROOF OF THE FIRST ZONKLAR EQUATION

Appendix one text goes here.

APPENDIX B

Appendix two text goes here.