

Experiment Design for Computer Sciences (01CH740)

Topic 02 - Point and Interval Indicators

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Part I - Introduction

Lecture Outline

In the last lecture, we talked about how experiments are important for the scientific endeavor. In this lecture, we will focus on basic concepts and techniques for representing experimental data.

- The importance of characterizing your data;
- Statistical Concepts: Population and Sample;
- Characterizing a Population: Point Estimators and Interval Estimators;
- Visualizing Estimators;

Charles Darwin

1809–1882 British Naturalist, Geologist, Biologist

To open our discussion about data, let's talk about a scientist whose work was all about collecting and understanding lots of data.



- Well known for his theory on [the origin of species](#)
- His theory correctly predicted the hereditary nature of evolution, even before genes were known.
- Actually, in his period, many people were interested in understanding the origin of the species;

Charlis Darwin

Early Life

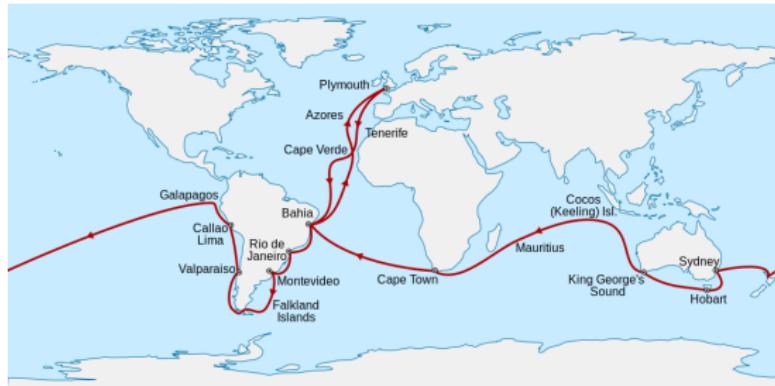


- Son of a wealthy doctor in a large family;
- Apprenticed as a doctor, but found the classes dull.
- Preferred to learn **taxidermy**, and catalog animals;

Charles Darwin

Observing the World

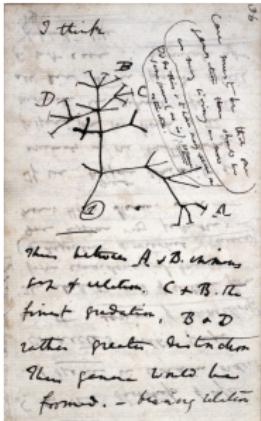
- 1831: After graduation, went on a 5 year sea voyage to catalog geological and animal samples in South America and Asia;
- During the trip, he kept extensive notes of his observations and theories;
- His observations about the diversity of mockingbirds, tortoises, and foxes gave him new insights about the origin of the species;



Charles Darwin

On the Origin of the Species

- In 1837, his notes from the Beagle's trip gave him his first insights about how "one species transforms into another"
- He gathered more and more data to confirm his theory, from marine biologists, farmers and breeders, plants, etc.
- This task of cataloguing and experimenting took over 15 years;
- Eventually published "On The Origin of the Species" in 1859, by encouragement from his friend scientists;



A note about programming language

Starting from this lecture, I will show some coding examples using the **R programming language**. I highly recommend students in this course to get used to R. Read the following link if for one nice tutorial:

R for Beginners: https://cran.r-project.org/doc/contrib/Paradis-rdebut_en.pdf

I also recommend the use of **R Studio** for working with R, instead of working directly in the command prompt. <https://rstudio.com>



Part II - Indicators

Using data to characterize a system

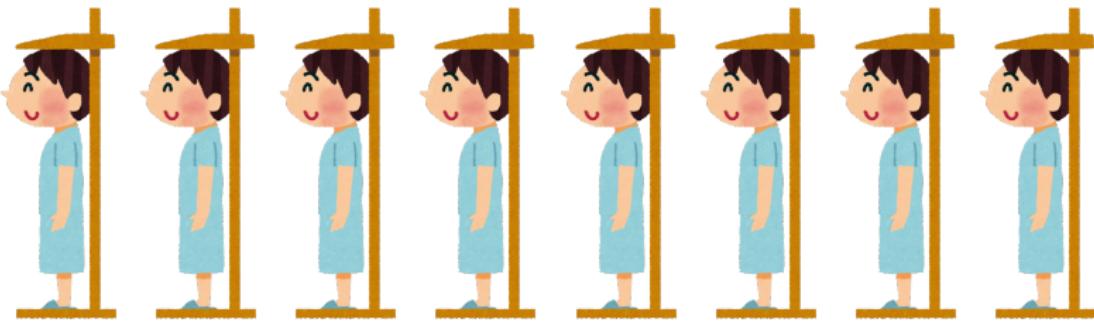
In the last lecture, we talked about using experiments to obtain data. How can we use the data to gain **knowledge** about a system?

For example, let's say that we measure the **height of one student**. Can I use this information to say something about the **height of all students** in the university?



Using data to characterize a system

From a single student's height, it seems hard to learn anything about the height of the students of the university **in general**. A better approach would be to take the height of several students.



If I calculate the **average height** of several students, what is the relationship between this value and height of students in general?

Population and Sample

This example introduces us to the concepts of statistical **Population** and **Sample**.

- **Population:** It is a large set of objects that are of interest as a whole. It can be a real set (all students in a university) or a theoretical set (all possible results of an experiment).
- **Observation:** It is one element from the population. One student from the university, or one execution of an experiment.
- **Sample:** It is a subset of the population. By examining the sample, we can **make inferences** about the population as a whole.

"Making inferences of the population from the sample". What does it mean?

Population and Sample

Making Inferences from the sample

Population



A pool has many colorful balls. If you knew exactly how many, you could calculate the **probability** of picking a ball of a certain color at random. **But you don't know!**

Sample



It is possible to **estimate** the proportion of balls in the pool. To do that, we pick up a number of balls, and examine the **proportion of the sample**.

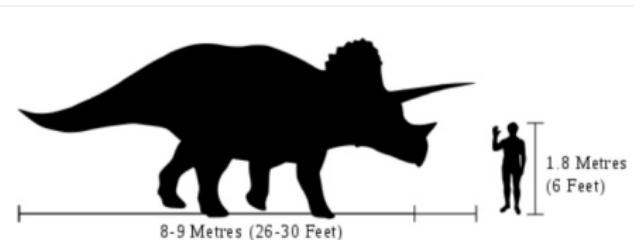
CS Example: Estimate total transfer time of a large file from the arrival time of a sample of packets. What could go wrong?

Population and Parameters

Our usual goal when obtaining and analysing experimental data is to estimate values for **parameters** of the population.

A **parameter** θ of the population is an unknown value of interest that characterizes some important aspect for our research.

Because we cannot observe the population directly, we have to estimate the parameter's true value from information gathered from the sample.



Parameter	Average Size	Maximal Size
Length	7.5–8.5 meters (25–28 ft)	9 meters (30 ft)
Height	2–2.9 meters (6.6–9.5 ft)	3 meters (9.8 ft)
Mass	6,000–8,500 kilograms (13,200–18,700 lb)	10–12 tonnes (22,000–26,000 lb)
Skull Length	2–2.2 meters (6.6–7.2 ft)	2.5–2.8 meters (8.2–9.2 ft)
Brow Horns Length (horn core)	70–100 centimetres (28–39 in)	115 centimetres (45 in)
Brow Horns Length (in Keratin)	97–130 centimetres (38–51 in)	130–150 centimetres (51–59 in)
Nasal Horn Length	10–30 centimetres (3.9–11.8 in)	30–40 centimetres (12–16 in)?

Samples and Statistics

By observing data obtained from a sample, we can **characterize** (estimate) parameters from a population of interest. For example:

- We calculate the average of the running time of multiple executions of a program, and estimate the mean running time;
- We ask the age of several students in a school, and estimate the maximum and minimum age of the students;
- We estimate the efficacy of a remedy by counting what percentage of patients get better after drinking it;
- We determine which of two neural networks is more precise by subtracting the test error of the two networks from each other;

Statistic

A statistic is a **function** calculated from data obtained from a sample.

Errors and Biases

Note that we are being very careful to always use the word **estimate** when we talk about statistics. Why is that?

In all the examples that we mentioned, if we are unlucky¹, we could obtain an estimate that is very different from the true value of the population:

Bad statistics example

To estimate the height of the students of a school, we pick 10 students, and we measure the height of the youngest one.

- **Error:** The difference between an estimate and the true value of a population's parameter;
- **Bias:** The property of a statistic that systematically produces wrong estimates;

¹or careless, or malicious

Point and Interval Indicators

The idea of estimating parameters of a population using information obtained from a sample is called **statistical inference**.

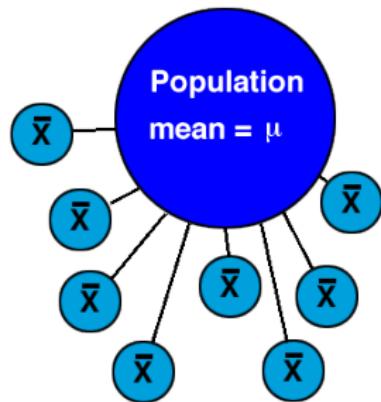
In this lecture, we will focus on two central concepts of statistical inference: **Point Estimators** and **Interval Estimators**.

- **Point Estimators:** are statistics that estimate the value of a population parameter from information in a sample;
- **Interval Estimators:** are statistics that estimate a **range of values** of a population parameter from information in a sample;

Statistics and Sampling Distributions

Suppose that you want to obtain a point estimate for an arbitrary parameter of the population (e.g. mean size);

Random samples of the population can be interpreted as a **random variable**, and any function of these samples (any statistic) will be a random variable as well.



As a random variable, any statistic also has its own **probability distribution**, called **sampling distribution**.

Most statistical tests use properties of the sampling distributions (which are not the same as the true distribution of the population). We will talk more about those later.

Definition of Point Indicator

A *point estimator* is a statistic which provides the value of maximum plausibility for an (unknown) population parameter θ .

Consider a random variable X distributed according to a given $f(X|\theta)$.

Consider also a random sample from this variable: $x = \{x_1, x_2, \dots, x_n\}$;

A given function $\hat{\Theta} = h(x)$ is called a *point estimator* of the parameter θ , and a value returned by this function for a given sample is referred to as a *point estimate* $\hat{\theta}$ of the parameter.

Examples

Point estimation problems arise frequently in all areas of science and engineering, whenever there is a need for estimating, e.g.,:

- a population mean, μ ;
- a population variance, σ^2 ;
- a population proportion, p ;
- the difference in the means of two populations, $\mu_1 - \mu_2$;
- etc..

In each case there are multiple ways of performing the estimation task, and the decision about which estimators to use is based on the mathematical properties of each statistic.

Unbiased estimators

A good estimator should consistently generate estimates that lie close to the real value of the parameter θ .

A given estimator $\hat{\Theta}$ is said to be *unbiased* for parameter θ if:

$$E[\hat{\Theta}] = \theta$$

or, equivalently:

$$E[\hat{\Theta}] - \theta = 0$$

The difference $E[\hat{\Theta}] - \theta$ is referred to as the *bias* of a given estimator.

Unbiased estimators

For example, the usual estimators for mean is an unbiased estimator;

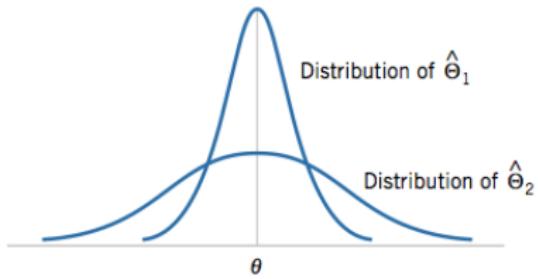
Let x_1, \dots, x_n be a random sample from a given population X , characterized by its mean μ and variance σ^2 . In this situation, it is possible to show that:

$$E[\bar{x}] = E\left[\frac{1}{n} \sum_{i=1}^n x_i\right] = \mu$$

(Remember that the expected value of one observation is the mean value of the population)

Unbiased estimators

For a population parameter θ , it is usually possible to define more than one unbiased estimator. The variances of these estimators may, however, be different



In these cases, we usually want to obtain the unbiased estimator of minimal variance. This is generally called the *minimal-variance unbiased estimator* (MVUE).

MVUE are generally chosen as estimators due to their ability of generating estimates $\hat{\theta}$ that are (relatively) close to the real value of θ .

Standard error of a point estimator

Remember that because a point estimator is a random variable, it has an associated distribution and error. For example, the standard error of an estimator $\hat{\Theta}$ is

$$\sigma_{\hat{\Theta}} = \sqrt{\text{Var} [\hat{\Theta}]}$$

However, we can't know this directly. We can **estimate** the standard error of the estimator from the data in the sample. In this case, we refer to it as the *estimated standard error*, $\hat{\sigma}_{\hat{\Theta}}$ (the notations $s_{\hat{\Theta}}$ and $\text{se}(\hat{\Theta})$ are also common).



Standard error of a point estimator

Examples

Assuming a random variable X from a gaussian distribution, and a sample error s , we can calculate the standard errors of several common point indicators²

$$\hat{\sigma}_{\bar{X}} = \frac{s}{\sqrt{n}}$$

$$\hat{\sigma}_{S^2} = s^2 \sqrt{\frac{2}{n-1}}$$

$$\hat{\sigma}_S = \frac{s}{\sqrt{2(n-1)}} + O\left(\frac{1}{n\sqrt{n}}\right) \approx \frac{s}{\sqrt{2(n-1)}}$$

²See Ahn and Fessler (2003), *Standard Errors of Mean, Variance, and Standard Deviation Estimators*: <https://git.io/v5Z5v>

Point Estimator Use Case



Consider an operation to produce coaxial cables³. The mean resistance of the production is 50Ω , with a standard deviation of 2Ω (Population mean, and population deviation).

Let's assume that the resistance value of the produced cables are distributed follow a normal distribution ($X \sim \mathcal{N}(\mu = 50, \sigma^2 = 4)$)

³Example inspired on

https://www.sas.com/resources/whitepaper/wp_4430.pdf

Point estimator use case



Suppose that we take a random sample of 25 cables is taken from this production process (an experiment, to measure if the process is correct, for example).

The **sample mean** of the observations is:

$$\bar{x} = \frac{1}{25} \sum_{i=1}^{25} x_i$$

The **sample mean** follows a normal distribution, with $E[\bar{x}] = \mu = 50\Omega^4$ and $\sigma_{\bar{x}} = \sqrt{\sigma^2/25} = 0.4\Omega$. The error depends on the sample size.

⁴since the sample mean is an unbiased estimator

The Central Limit Theorem

In the previous example, the production operation followed a normal distribution. But even for a population with an arbitrary distribution, the sampling distribution of its mean tends to be approximately normal.

More generally, let x_1, \dots, x_n be a sequence of **independent and identically distributed (iid)** random variables, with mean μ and finite variance σ^2 . Then:

$$Z_n = \frac{\sum_{i=1}^n (x_i) - n\mu}{\sqrt{n\sigma^2}} = \frac{\bar{x} - \mu}{\sqrt{\sigma^2/n}}$$

is distributed asymptotically as a standard Normal variable, that is,
 $Z_n \sim \mathcal{N}(0, 1)$.

The Central Limit Theorem

This result is known as the *Central Limit Theorem*⁵, and is one of the most useful properties for statistical inference. The CLT allows the use of techniques based on the Normal distribution, even when the population under study is not normal.

For “well-behaved” distributions (continuous, symmetrical, unimodal - the usual bell-shaped pdf we all know and love) even small sample sizes are commonly enough to justify invoking the CLT and using parametric techniques.

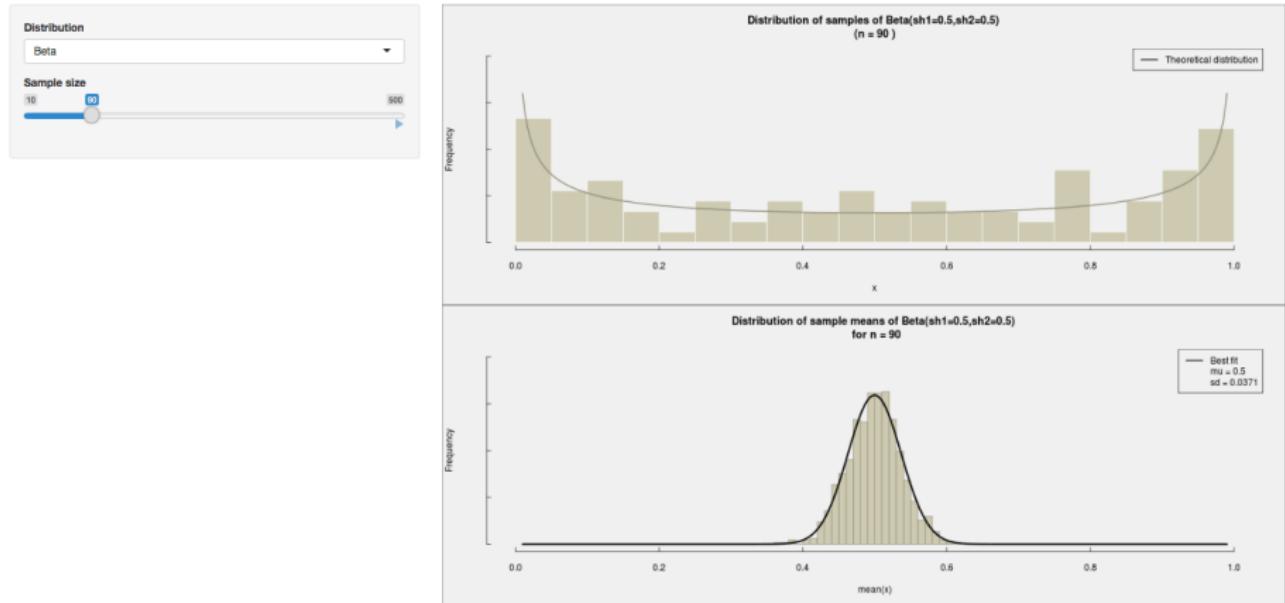
⁵For more details on the CLT, see https://www.encyclopediaofmath.org/index.php/Central_limit_theorem

Sampling Distributions

The Central Limit Theorem

For an interactive demonstration of the CLT, download the files in <https://git.io/vnPj8> and run on RStudio.

Central Limit Theorem - Continuous Distributions



Statistical Intervals

Statistical intervals are important in quantifying the uncertainty associated to a given estimate;

As an example, let's recap the coaxial cables example: *a coaxial cable manufacturing operation produces cables with a target resistance of 50Ω and a standard deviation of 2Ω . Assume that the resistance values can be well modeled by a normal distribution.*

Let us now suppose that a sample mean of $n = 25$ observations of resistance yields $\bar{x} = 48$. Given the sampling variability, it is very likely that this value is not exactly the true value of μ , but we are so far unable quantify how much uncertainty there is in this estimate.

Definition

Statistical intervals define regions that are likely to contain the true value of an estimated parameter.

More formally, it is generally possible to quantify the level of uncertainty associated with the estimation, thereby allowing the derivation of sound conclusions at predefined levels of certainty.

Three of the most common types of interval are:

- Confidence Intervals;
- Tolerance Intervals;
- Prediction Intervals;

How to Interpret a Confidence Interval

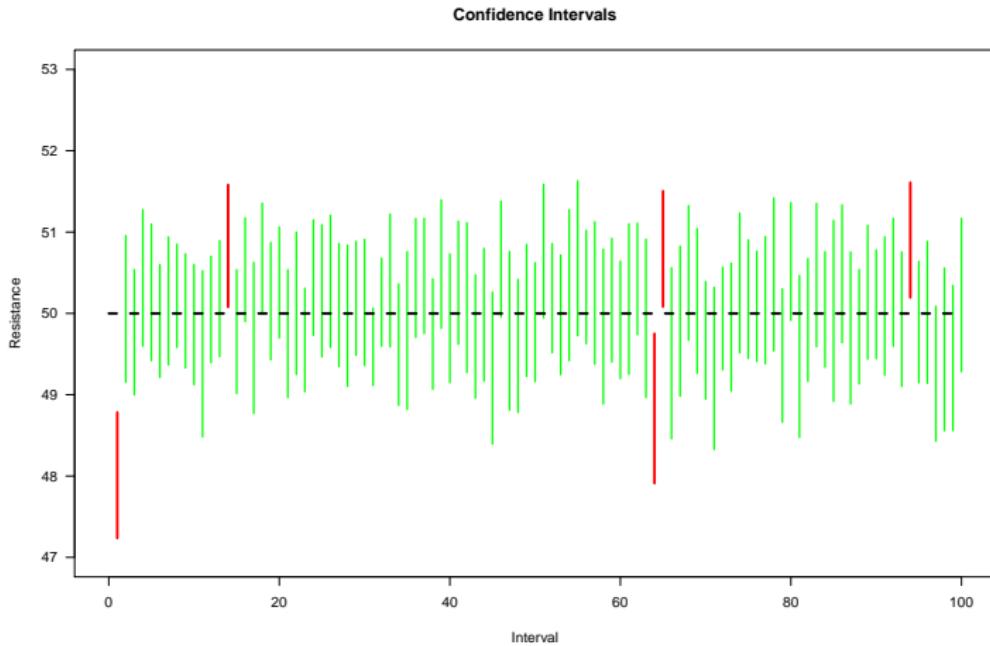
Confidence intervals quantify the degree of uncertainty associated with the estimation of population parameters such as the mean or the variance.

Can be defined as "*the interval that contains the true value of a given population parameter with a confidence level of $100(1 - \alpha)$* ";

Another useful definition is to think about confidence intervals in terms of confidence *in the method*: "The method used to derive the interval has a hit rate of 95%" - i.e., the interval generated has a 95% chance of 'capturing' the true population parameter."

Confidence Intervals

Example: 100 $CI_{.95}$ for a sample of 25 observations



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⁶For an interactive demonstration of the factors involved in the definition of a confidence interval, Run the files at <https://git.io/vxXGj> on RStudio.

CI on the Mean of a Normal Variable

The two-sided $Cl_{(1-\alpha)}$ for the mean of a normal population with known variance σ^2 is given by:

$$\bar{x} + z_{\alpha/2} \frac{\sigma}{\sqrt{n}} \leq \mu \leq \bar{x} + z_{1-\alpha/2} \frac{\sigma}{\sqrt{n}}$$

where $(1 - \alpha)$ is the confidence level and z_x is the x -quantile of the standard normal distribution. For the more usual case with an unknown variance,

$$\bar{x} + t_{\alpha/2}^{(n-1)} \frac{s}{\sqrt{n}} \leq \mu \leq \bar{x} + t_{1-\alpha/2}^{(n-1)} \frac{s}{\sqrt{n}}$$

where $t_x^{(n-1)}$ is the x -quantile of the t distribution with $n - 1$ degrees of freedom.

CI on the Variance and Standard Deviation of a Normal Variable

A two-sided confidence interval on the variance of a normal variable can be easily calculated:

$$\frac{(n-1)s^2}{\chi_{1-\alpha/2}^{2(n-1)}} \leq \sigma^2 \leq \frac{(n-1)s^2}{\chi_{\alpha/2}^{2(n-1)}}$$

where $\chi_x^{2(n-1)}$ represents the x-quantile of the χ^2 distribution with $n - 1$ degrees of freedom. For the standard deviation one simply needs to take the squared root of the confidence limits.

Wrapping up

Statistical intervals quantify the uncertainty associated with different aspects of estimation; Reporting intervals is always better than point estimates, as it provides the necessary information to quantify the location and uncertainty of your estimated values; The correct interpretation is a little tricky (although not very difficult)⁷, but it is essential in order to derive the correct conclusions based on the statistical interval of interest.

⁷See the table at the end of <https://git.io/v5ZFh>

Part III - Conclusion

Recommended Reads

More details

- *D.W. Stockburger*, The Sampling Distribution. In: Introductory Statistics: Concepts, Models, and Applications -
<http://psychstat3.missouristate.edu/Documents/IntroBook3/sbk17.htm>
- *J.G. Ramírez*, Statistical Intervals: Confidence, Prediction, Enclosure: <https://git.io/v5ZFh>

Statistics

- Crash Course Statistics Playlist, in particular videos #3 to #7:
https://www.youtube.com/playlist?list=PL8dPuuaLjXtNM_Y-bUAhb1SAdWRnmBUcr

R References

- R for beginners: https://cran.r-project.org/doc/contrib/Paradis-rdebut_en.pdf
- Rstudio: <https://rstudio.com>

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