

The World

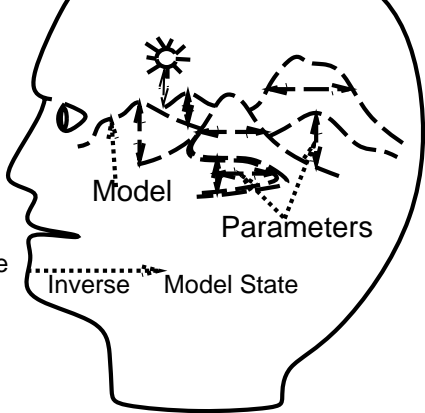


World State

Projection

Visible State

The Learner



Model

Parameters

Inverse

Model State