

BiUFLv2012

1.1

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# Chapter 1

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### 3.1 File List

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## Chapter 4

# Module Documentation

### 4.1 Methods of Paving

#### Functions

- long int `createBox` (vector< `Box` \* > &vectorBox, `Data` &data)  
*This method computes all the initial Boxes of our algorithm.*
- void `addChildren` (`Box` \*boxMother, vector< `Box` \* > &vBox)  
*This method adds children of a Box into a vector of Boxes.*
- void `filter` (vector< `Box` \* > &vectorBox, long int &nbToCompute, long int &nbWithNeighbor)  
*This method filters all the Boxes of a vector of Box.*
- void `boxFiltering` (vector< `Box` \* > &vectorBox, `Data` &data, long int &nbToCompute, long int &nbWithNeighbor)  
*This method splits a Box into two Boxes.*
- void `recomposition` (vector< `Box` \* > &vectorBox, vector< `Box` \* > &vectorBox-Final, `Data` &data, long int &nbToCompute, long int &nbWithNeighbor)  
*This method recomposes a group of Boxes into an unique one.*
- void `weightedSumOneStep` (vector< `Box` \* > &vectorBox, `Data` &data)  
*Compute the weighted sum method to split a Box in two Boxes.*

#### 4.1.1 Function Documentation

##### 4.1.1.1 `addChildren` ( `Box` \* boxMother, vector< `Box` \* > & vBox )

This method adds children of a `Box` into a vector of Boxes.

This method computes all the children Boxes of a `Box` into a vector of Boxes. A children is defined by a combination of `Facility` in which indices have not yet been opened.

## Parameters

in	<i>boxMother</i>	: A <a href="#">Box</a> for which ones wants to add children <a href="#">Boxes</a> .
in, out	<i>vBox</i>	: A vector of <a href="#">Box</a> in which one ones add all the children – <a href="#">Boxes</a> at the end (enqueue at the end of the vector).

#### 4.1.1.2 `boxFiltering ( vector< Box * > & vectorBox, Data & data, long int & nbToCompute, long int & nbWithNeighbor )`

This method splits a [Box](#) into two [Boxes](#).

Using a weighted sum method to find a supported point, ones splits a into two [Boxes](#).

## Parameters

in, out	<i>vectorBox</i>	: A vector of <a href="#">Box</a> in which one ones adds all the new <a href="#">Boxes</a> computed.
in	<i>data</i>	: A <a href="#">Data</a> object which contains all the values of the instance.
in, out	<i>nbToCompute</i>	: A long int that takes the number of <a href="#">Boxes</a> with a available decomposition.
in, out	<i>nbWithNeighbor</i>	: A long int that takes the number of <a href="#">Boxes</a> overlapped by another one.

#### 4.1.1.3 `long int createBox ( vector< Box * > & vectorBox, Data & data )`

This method computes all the initial [Boxes](#) of our algorithm.

This method computes all the [Boxes](#) in which ones the Label Setting algorithm will runs. This method uses a smart Branch&Bound (Breadth First Search, splitting on – [Facility](#) setup variables) to compute all the feasible and important [Boxes](#). Useless [Boxes](#) are avoided by the Branch&Bound.

## Parameters

in, out	<i>vectorBox</i>	: A vector of <a href="#">Box</a> , empty at the beginning, and containing all the <a href="#">Boxes</a> at the end of this method.
in	<i>data</i>	: A <a href="#">Data</a> object which contains all the values of the instance.

## Returns

A long int which represents the number of [Boxes](#) computed by the method.

#### 4.1.1.4 `filter ( vector< Box * > & vectorBox, long int & nbToCompute, long int & nbWithNeighbor )`

This method filters all the [Boxes](#) of a vector of [Box](#).

This method filters `Boxes` by eliminating all `Box` that are dominated by an other one.

#### Parameters

in, out	<i>nbTo-Compute</i>	: A long int that takes the number of <code>Boxes</code> with a available decomposition.
in, out	<i>nbWith-Neighbor</i>	: A long int that takes the number of <code>Boxes</code> overlapped by another one.

#### 4.1.1.5 recomposition ( vector< `Box` \* > & *vectorBox*, vector< `Box` \* > & *vectorBoxFinal*, `Data` & *data*, long int & *nbToCompute*, long int & *nbWithNeighbor* )

This method recomposes a group of `Boxes` into an unique one.

This method selects all the `Boxes` with the same combination of `Facility`. Ones creates an unique `Box` with this combination of `Facility` and update the bounds of this one w.r.t. the bounds of all `Boxes` selected.

#### Parameters

in, out	<i>vectorBox</i>	: A vector of <code>Box</code> in which one adds all the new <code>Boxes</code> computed.
in, out	<i>vectorBox-Final</i>	: A vector of <code>Box</code> containing all the recompose <code>Boxes</code>
in	<i>data</i>	: A <code>Data</code> object which contains all the values of the instance.
in, out	<i>nbTo-Compute</i>	: A long int that takes the number of <code>Boxes</code> with a available decomposition.
in, out	<i>nbWith-Neighbor</i>	: A long int that takes the number of <code>Boxes</code> overlapped by another one.

#### 4.1.1.6 weightedSumOneStep ( vector< `Box` \* > & *vectorBox*, `Data` & *data* )

Compute the weighted sum method to split a `Box` in two `Boxes`.

This method adds to the *vectorBox* the results of dividing each `Box` in two others. It uses the weighted sum method which splits `Box` by the first supported point founded.

#### Parameters

in	<i>vectorBox</i>	: A vector of <code>Box</code> which contains all the <code>Boxes</code> in which one computes the weighted sum method.
in	<i>data</i>	: A <code>Data</code> object which contains all the values of the instance.

#### Returns

A long int which value is the number of solutions of the algorithm proposed.

## 4.2 Methods of Generating

### Functions

- long int `runLabelSetting` (vector< `Box` \* > &vectorBox, `Data` &data)  
*This method runs the Label Setting algorithm.*
- void `filterListSolution` (list< `Solution` > &Isol)  
*Delete the solutions dominated.*

### 4.2.1 Function Documentation

#### 4.2.1.1 `filterListSolution` ( list< `Solution` > & `Isol` )

Delete the solutions dominated.

A method to delete all the dominated solutions into the objective space. This method computes a complete set of solution.

##### Parameters

in	<code>Isol</code>	: A vector of <code>Solution</code> which contains all the – Solutions to delete.
----	-------------------	---

#### 4.2.1.2 `runLabelSetting` ( vector< `Box` \* > & `vectorBox`, `Data` & `data` )

This method runs the Label Setting algorithm.

This method executes a Label Setting algorithm in each `Box` of the input vector.

##### Parameters

in	<code>vectorBox</code>	: A vector of <code>Box</code> which contains all the Boxes in which one ones runs the algorithm of Label Setting.
in	<code>data</code>	: A <code>Data</code> object which contains all the values of the instance.

##### Returns

A long int which value is the number of solutions of the algorithm proposed.

## 4.3 Others Methods

### Functions

- double `computeCorrelation` (`Data` &data)  
*This method computes the correlation.*
- float `time_ms_Diff` (timeval tvStart, timeval tvEnd)  
*This method computes the difference in milli-seconds (ms) between two times.*
- float `time_s_Diff` (timeval tvStart, timeval tvEnd)  
*This method computes the difference in seconds (ms) between two times.*

#### 4.3.1 Function Documentation

##### 4.3.1.1 `computeCorrelation` ( `Data` & `data` )

This method computes the correlation.

This method computes the correlation between the two objectives w.r.t. to the `Data`.

##### Parameters

in	<code>data</code>	: A <code>Data</code> object which contains all the values of the instance.
----	-------------------	---

##### Returns

A double representing the correlation between the two objectives.

##### 4.3.1.2 `time_ms_Diff` ( timeval `tvStart`, timeval `tvEnd` )

This method computes the difference in milli-seconds (ms) between two times.

##### Parameters

in	<code>tvStart</code>	: A structure of time represeting the begin time.
in	<code>tvEnd</code>	: A structure of time represeting the end time.

##### Returns

A double representing the difference in ms between the two times.

##### 4.3.1.3 `time_s_Diff` ( timeval `tvStart`, timeval `tvEnd` )

This method computes the difference in seconds (ms) between two times.

**Parameters**

in	<i>tvStart</i>	: A structure of time represeting the begin time.
in	<i>tvEnd</i>	: A structure of time represeting the end time.

**Returns**

A double representing the difference in s between the two times.



## 4.4 Global Variables

### Variables

- bool `modeVerbose`  
*Variable representing the Verbose mode.*
- bool `modeExport`  
*Variable representing the Export mode.*

### 4.4.1 Variable Documentation

#### 4.4.1.1 `modeExport`

Variable representing the Export mode.

This boolean gets the value TRUE if the export mode is on, and FALSE otherwise. If the export mode is on, result files are written in the folder /res.

#### 4.4.1.2 `modeVerbose`

Variable representing the Verbose mode.

This boolean gets the value TRUE if the verbose mode is on, and FALSE otherwise. If the verbose mode is on, the software prints detailed information while running.

## 4.5 Main

### Functions

- `int main (int argc, char *argv[])`  
*This is the main of the software.*

#### 4.5.1 Function Documentation

##### 4.5.1.1 `int main ( int argc, char * argv[] )`

This is the main of the software.

##### Parameters

<code>in</code>	<code>argc</code>	: An integer which represents the number of arguments passed to the line command.
<code>in</code>	<code>argv</code>	: An array of character which represents all the arguments.

## Chapter 5

# Class Documentation

### 5.1 Box Class Reference

Class to represent a [Box](#).

```
#include "Box.hpp"
```

#### Public Member Functions

- [Box](#) ([Data](#) &data)  
*Default Constructor of the class [Box](#).*
- [Box](#) ([Box](#) \*copy)  
*Constructor of copy of the class [Box](#).*
- [Box](#) ([Data](#) &data, bool \*toOpen)  
*Constructor of the class [Box](#).*
- [~Box](#) ()  
*Destructor of the class [Box](#).*
- double [getMinZ1](#) () const  
*Getter for the minimum value w.r.t. objective 1.*
- double [getMinZ2](#) () const  
*Getter for the minimum value w.r.t. objective 2.*
- double [getMaxZ1](#) () const  
*Getter for the maximum value w.r.t. objective 1.*
- double [getMaxZ2](#) () const  
*Getter for the maximum value w.r.t. objective 2.*
- double [getOriginZ1](#) () const  
*Getter for the value of the origin w.r.t. objective 1.*
- double [getOriginZ2](#) () const  
*Getter for the value of the origin w.r.t. objective 2.*
- string [getId](#) () const

*Getter for the id.*

- bool `isAssigned` (int cust) const

*method to know if a `Customer` is assigned or not.*

- bool `isOpenned` (int fac) const

*method to know if a `Facility` is opened or not.*

- int `getnbCustomerNotAffected` () const

*Getter for the number of `Customers` nonaffected.*

- int `getNbFacilityOpen` () const

*Getter for the number of `Facilities` opened.*

- bool `getHasNeighbor` () const

*Getter for the neighborhood.*

- bool `getHasMoreStepWS` () const

*Getter for the number of `Weighted Sum`.*

- `Data` & `getData` () const

*Getter for the data.*

- void `setId` (string s)

*Setter for the id of this `Box`.*

- void `setMinZ1` (double v)

*Setter for the minimum value w.r.t. objective 1.*

- void `setMinZ2` (double v)

*Setter for the minimum value w.r.t. objective 2.*

- void `setMaxZ1` (double v)

*Setter for the maximum value w.r.t. objective 1.*

- void `setMaxZ2` (double v)

*Setter for the maximum value w.r.t. objective 2.*

- void `setHasNeighbor` (bool b)

*Setter for the neighborhood.*

- void `setHasMoreStepWS` (bool b)

*Setter for the remaining weighted sum method.*

- void `computeBox` ()

*A method to expand a box, which means attempting to allocate all `Customers` to `Facilities`.*

- void `openFacility` (int fac)

*A method that opens a `Facility` in this `Box`, by adding all the location cost of the two objectives.*

- void `print` ()

*A method to print informations about this `Box`.*

### Private Attributes

- string `id_`
- `Data` & `data_`
- bool \* `isAssigned_`
- bool \* `facility_`
- bool `hasMoreStepWS_`
- bool `hasNeighbor_`
- int `nbCustomerNotAffected_`
- double `minZ1_`
- double `minZ2_`
- double `maxZ1_`
- double `maxZ2_`
- double `originZ1_`
- double `originZ2_`

### Related Functions

(Note that these are not member functions.)

- bool `isDominatedBetweenTwoBoxes` (`Box` \*box1, `Box` \*box2)  
*Method of comparison between two boxes.*
- bool `isDominatedBetweenOrigins` (`Box` \*box1, `Box` \*box2)  
*Method of comparison between two boxes.*
- void `filterDominatedBoxes` (vector< `Box` \* > &vectBox)  
*Method to filter a vector of Boxes.*
- bool `isDominatedByItsOrigin` (vector< `Box` \* > &vectBox, `Box` \*box)  
*Method of comparison between a Box and a vector of Boxes.*
- bool `isDominatedByItsBox` (vector< `Box` \* > &vectBox, `Box` \*box)  
*Method of comparison between a Box and a vector of Boxes.*

#### 5.1.1 Detailed Description

Class to represent a `Box`.

This class represents a `Box` with all its attributes and methods.

#### 5.1.2 Constructor & Destructor Documentation

##### 5.1.2.1 `Box::Box ( Data & data )`

Default Constructor of the class `Box`.

The default constructor gives a `Box` which anyone `Facility` opened.

**Parameters**

in	<i>data</i>	: A <a href="#">Data</a> object which contains all the values of the instance.
----	-------------	--

**5.1.2.2 Box::Box ( Box \* *copy* )**

Constructor of copy of the class [Box](#).

**Parameters**

in	<i>copy</i>	: A <a href="#">Box</a> to copy.
----	-------------	----------------------------------

**5.1.2.3 Box::Box ( Data & *data*, bool \* *toOpen* )**

Constructor of the class [Box](#).

This constructor gives a [Box](#) which a set of [Facilities](#) opened.

**Parameters**

in	<i>data</i>	: A <a href="#">Data</a> object which contains all the values of the instance.
in	<i>toOpen</i>	: A pointer of boolean representing the vector of <a href="#">Facility</a> to open in order to construct an object <a href="#">Box</a> .

**5.1.2.4 Box::~~Box ( )**

Destructor of the class [Box](#).

**5.1.3 Member Function Documentation****5.1.3.1 void Box::computeBox ( )**

A method to expand a box, which means attempting to allocate all [Customers](#) to [Facilities](#).

**5.1.3.2 Data & Box::getData ( ) const**

Getter for the data.

**Returns**

A reference [Data](#) of the [Data](#) of this [Box](#).

### 5.1.3.3 bool `Box::getHasMoreStepWS ( )` const

Getter for the number of Weighted Sum.

#### Returns

A boolean if this `Box` gets a remaining iteration of weighed sum method.

### 5.1.3.4 bool `Box::getHasNeighbor ( )` const

Getter for the neighborhood.

#### Returns

A boolean which value is TRUE if this `Box` overlaps or is overlapped with an other `Box`.

### 5.1.3.5 string `Box::getId ( )` const

Getter for the id.

#### Returns

A string as the sequence of 1 and 0 representing the combination of `Facility` of this `Box`.

### 5.1.3.6 double `Box::getMaxZ1 ( )` const

Getter for the maximum value w.r.t. objective 1.

#### Returns

A double as the maximum value w.r.t. objective 1 of this `Box`.

### 5.1.3.7 double `Box::getMaxZ2 ( )` const

Getter for the maximum value w.r.t. objective 2.

#### Returns

A double as the maximum value w.r.t. objective 2 of this `Box`.

#### 5.1.3.8 double **Box::getMinZ1** ( ) const

Getter for the minimum value w.r.t. objective 1.

##### Returns

A double as the minimum value w.r.t. objective 1 of this [Box](#).

#### 5.1.3.9 double **Box::getMinZ2** ( ) const

Getter for the minimum value w.r.t. objective 2.

##### Returns

A double as the minimum value w.r.t. objective 2 of this [Box](#).

#### 5.1.3.10 int **Box::getnbCustomerNotAffected** ( ) const

Getter for the number of [Customers](#) nonaffected.

##### Returns

An int as the number of [Customers](#) which are not affected to a [Facility](#).

#### 5.1.3.11 int **Box::getNbFacilityOpen** ( ) const

Getter for the number of [Facilities](#) opened.

##### Returns

An int as the number of [Facilities](#) which are opened (set to 1).

#### 5.1.3.12 double **Box::getOriginZ1** ( ) const

Getter for the value of the origin w.r.t. objective 1.

##### Returns

A double as the value of the point of origin w.r.t. objective 1 of this [Box](#).

#### 5.1.3.13 double **Box::getOriginZ2** ( ) const

Getter for the value of the origin w.r.t. objective 2.

##### Returns

A double as the value of the point of origin w.r.t. objective 2 of this [Box](#).



**5.1.3.14** `bool Box::isAssigned ( int cust ) const`

method to know if a [Customer](#) is assigned or not.

**Parameters**

<i>in</i>	<i>cust</i> : A <a href="#">Customer</a> .
-----------	--

**Returns**

A boolean which value is TRUE if the [Customer](#) is assigned to any [Facility](#).

**5.1.3.15** `bool Box::isOpenned ( int fac ) const`

method to know if a [Facility](#) is opened or not.

**Parameters**

<i>in</i>	<i>cust</i> : A <a href="#">Facility</a> .
-----------	--

**Returns**

A boolean which value is TRUE if the [Facility](#) is opened.

**5.1.3.16** `void Box::openFacility ( int fac )`

A method that opens a [Facility](#) in this [Box](#), by adding all the location cost of the two objectives.

**Parameters**

<i>in</i>	<i>fac</i> : A <a href="#">Facility</a> to open.
-----------	--

**5.1.3.17** `void Box::print ( )`

A method to print informations about this [Box](#).

**5.1.3.18** `void Box::setHasMoreStepWS ( bool b )`

Setter for the remaining weighted sum method.

**Parameters**

<i>in</i>	<i>b</i> : A boolean which value is TRUE if this <a href="#">Box</a> has a remaining iteration of weighted sum method.
-----------	--

### 5.1.3.19 void **Box::setHasNeighbor** ( bool *b* )

Setter for the neighborhood.

#### Parameters

in	<i>b</i>	: A boolean which value is TRUE if this <a href="#">Box</a> has at least one neighborhood (a <a href="#">Box</a> which overlaps or is overlapped).
----	----------	--

### 5.1.3.20 void **Box::setId** ( string *s* )

Setter for the id of this [Box](#).

#### Parameters

in	<i>s</i>	: A string which represents the id (combination of <a href="#">Facility</a> ) of this <a href="#">Box</a> .
----	----------	---

### 5.1.3.21 void **Box::setMaxZ1** ( double *v* )

Setter for the maximum value w.r.t. objective 1.

#### Parameters

in	<i>v</i>	: A double which represents the maximum value w.r.t. objective 1 of this <a href="#">Box</a> .
----	----------	--

### 5.1.3.22 void **Box::setMaxZ2** ( double *v* )

Setter for the maximum value w.r.t. objective 2.

#### Parameters

in	<i>v</i>	: A double which represents the maximum value w.r.t. objective 2 of this <a href="#">Box</a> .
----	----------	--

### 5.1.3.23 void **Box::setMinZ1** ( double *v* )

Setter for the minimum value w.r.t. objective 1.

#### Parameters

in	<i>v</i>	: A double which represents the minimum value w.r.t. objective 1 of this <a href="#">Box</a> .
----	----------	--

5.1.3.24 void **Box::setMinZ2** ( double *v* )

Setter for the minimum value w.r.t. objective 2.

## Parameters

in	<i>v</i>	: A double which represents the minimum value w.r.t. objective 2 of this <a href="#">Box</a> .
----	----------	--

## 5.1.4 Friends And Related Function Documentation

5.1.4.1 void **filterDominatedBoxes** ( vector< **Box** \* > & *vectBox* ) [related]

Method to filter a vector of [Boxes](#).

A method to filter and delete [Box](#) in a vector of [Boxes](#) by comparing each other.

## Parameters

in	<i>vectBox</i>	: A vector of <a href="#">Boxes</a> .
----	----------------	---------------------------------------

5.1.4.2 bool **isDominatedBetweenOrigins** ( **Box** \* *box1*, **Box** \* *box2* ) [related]

Method of comparison between two boxes.

A method to compare two [Boxes](#) using the bounds minZ1\_, minZ2\_, maxZ1\_, maxZ2\_, originZ1\_ and originZ2\_.

## Parameters

in	<i>box1</i>	: A <a href="#">Box</a> to compare.
in	<i>box2</i>	: A <a href="#">Box</a> to compare.

## Returns

A boolean which value is TRUE if the origin of the box1 is dominated by the box2.

5.1.4.3 bool **isDominatedBetweenTwoBoxes** ( **Box** \* *box1*, **Box** \* *box2* ) [related]

Method of comparison between two boxes.

A method to compare two [Boxes](#) using the bounds minZ1\_, minZ2\_, maxZ1\_, maxZ2\_ of each [Boxes](#).

## Parameters

in	<i>box1</i>	: A <a href="#">Box</a> to compare.
in	<i>box2</i>	: A <a href="#">Box</a> to compare.

**Returns**

A boolean which value is TRUE if the box1 is dominated by the box2.

**5.1.4.4** `bool isDominatedByItsBox ( vector< Box * > & vectBox, Box * box )`  
[related]

Method of comparison between a [Box](#) and a vector of [Boxes](#).

**Parameters**

in	<i>vectBox</i>	: A vector of <a href="#">Boxes</a> to compare.
in	<i>box</i>	: A <a href="#">Box</a> to compare.

**Returns**

A boolean which value is TRUE if one of the [Box](#) of the vector vectBox is dominated by the [Box](#) box.

**5.1.4.5** `bool isDominatedByItsOrigin ( vector< Box * > & vectBox, Box * box )`  
[related]

Method of comparison between a [Box](#) and a vector of [Boxes](#).

**Parameters**

in	<i>vectBox</i>	: A vector of <a href="#">Boxes</a> to compare.
in	<i>box</i>	: A <a href="#">Box</a> to compare.

**Returns**

A boolean which value is TRUE if [Box](#) box is dominated by one of the [Box](#) of the vector vectBox.

**5.1.5 Member Data Documentation**

**5.1.5.1** `Data& Box::data_` [private]

A reference to the [Data](#) of this [Box](#)

**5.1.5.2** `bool* Box::facility_` [private]

A boolean which represents the vector of [Facility](#) opened or not

**5.1.5.3** `bool Box::hasMoreStepWS_ [private]`

A boolean which represents if this `Box` has a remaining iteration of weighted sum method

**5.1.5.4** `bool Box::hasNeighbor_ [private]`

A boolean which represents if this `Box` has a neighbor or not

**5.1.5.5** `string Box::id_ [private]`

A string which represents the id of this `Box`

**5.1.5.6** `bool* Box::isAssigned_ [private]`

A boolean which represents the vector of `Customer` assigned or not

**5.1.5.7** `double Box::maxZ1_ [private]`

A double which represents the maximum value w.r.t. objective 1

**5.1.5.8** `double Box::maxZ2_ [private]`

A double which represents the maximum value w.r.t. objective 2

**5.1.5.9** `double Box::minZ1_ [private]`

A double which represents the minimum value w.r.t. objective 1

**5.1.5.10** `double Box::minZ2_ [private]`

A double which represents the minimum value w.r.t. objective 2

**5.1.5.11** `int Box::nbCustomerNotAffected_ [private]`

An integer which represents the number of `Customer` not affected of this `Box`

**5.1.5.12** `double Box::originZ1_ [private]`

A double which represents the value of the origin of this `Box` w.r.t. objective 1

### 5.1.5.13 double `Box::originZ2_` [private]

A double which represents the value of the origin of this `Box` w.r.t. objective 2

The documentation for this class was generated from the following files:

- /home/axel/Axel/Computing/svn/biufp2012/trunk/wolseyaward/1.1/src/[Box.hpp](#)
- /home/axel/Axel/Computing/svn/biufp2012/trunk/wolseyaward/1.1/src/[Box.cpp](#)

## 5.2 Customer Class Reference

Class to represent a `Customer`.

```
#include "Customer.hpp"
```

### Public Member Functions

- `Customer` (unsigned short &x, unsigned short &y)  
*Constructor of the class `Customer`.*
- unsigned short `getCoordX` () const  
*Getter for the x coordinate .*
- unsigned short `getCoordY` () const  
*Getter for the y coordinate.*

### Private Attributes

- unsigned short `coordX_`
- unsigned short `coordY_`

### Related Functions

(Note that these are not member functions.)

- ostream & `operator<<` (ostream &out, const `Customer` \*cust)  
*Operator overloading.*

### 5.2.1 Detailed Description

Class to represent a `Customer`.

This class represents a `Customer` with all its attributes. The pair (x,y) represents respectively the first and second coordinates in a bi-dimensional geographical space.

## 5.2.2 Constructor & Destructor Documentation

### 5.2.2.1 Customer::Customer ( unsigned short & x, unsigned short & y )

Constructor of the class [Customer](#).

#### Parameters

in	x	: An unsigned short which represents the x coordinate of the <a href="#">Customer</a> .
in	y	: An unsigned short which represents the y coordinate of the <a href="#">Customer</a> .

## 5.2.3 Member Function Documentation

### 5.2.3.1 unsigned short Customer::getCoordX ( ) const

Getter for the x coordinate .

#### Returns

An unsigned short as the x coordinate of this [Customer](#).

### 5.2.3.2 unsigned short Customer::getCoordY ( ) const

Getter for the y coordinate.

#### Returns

An unsigned short as the y coordinate of this [Customer](#).

## 5.2.4 Friends And Related Function Documentation

### 5.2.4.1 ostream & operator<< ( ostream & out, const Customer \* cust ) [related]

Operator overloading.

Overloading of the standard output stream in order to print a [Customer](#).

#### Parameters

out	out	: The standard output stream.
in	cust	: A <a href="#">Customer</a> to print in the standard output stream.

## 5.2.5 Member Data Documentation

#### 5.2.5.1 unsigned short **Customer::coordX\_** [private]

Unsigned short which represents the value of the x coordinate of this [Customer](#)

#### 5.2.5.2 unsigned short **Customer::coordY\_** [private]

Unsigned short which represents the value of the y coordinate of this [Customer](#)

The documentation for this class was generated from the following files:

- /home/axel/Axel/Computing/svn/biufp2012/trunk/wolseyaward/1.1/src/[Customer.-hpp](#)
- /home/axel/Axel/Computing/svn/biufp2012/trunk/wolseyaward/1.1/src/[Customer.-cpp](#)

## 5.3 Data Class Reference

Class to represent a [Data](#).

```
#include "Data.hpp"
```

### Public Types

- typedef vector< [Facility](#) > [ListFacilities](#)  
*The list of all facilities.*
- typedef vector< [Customer](#) > [ListCustomers](#)  
*The list of all customers.*

### Public Member Functions

- [Data](#) (unsigned int nbFacility, unsigned int nbCustomer, string name)  
*Constructor of the class [Data](#).*
- [~Data](#) ()  
*Destructor of the class [Data](#).*
- void [addFacility](#) ([Facility](#) fac)  
*Method to add a [Facility](#) to the [Data](#).*
- void [addCustomer](#) ([Customer](#) cust)  
*Method to add a [Customer](#) to the [Data](#).*
- unsigned int [getnbFacility](#) () const  
*Getter for the number of facilities.*
- unsigned int [getnbCustomer](#) () const  
*Getter for the number of customers.*
- double [getAllocationObj1Cost](#) (int cust, int fac) const



Getter for the allocation cost w.r.t. objective 1 between a *Customer* and a *Facility*.

- double `getAllocationObj2Cost` (int cust, int fac) const

Getter for the allocation cost w.r.t. objective 2 between a *Customer* and a *Facility*.

- *Facility* & `getFacility` (int fac)

Getter for a *Facility*.

- string `getFileName` () const

Getter for the name of the instance.

- void `setAllocationObj1Cost` (int cust, int fac, double val)

Setter for the allocation cost w.r.t. objective 1 between a *Customer* and a *Facility*.

- void `setAllocationObj2Cost` (int cust, int fac, double val)

Setter for the allocation cost w.r.t. objective 2 between a *Customer* and a *Facility*.

- void `setFileName` (string name)

Setter for the name of the instance.

### Private Attributes

- *ListFacilities* `facilityList_`
- *ListCustomers* `customerList_`
- string `fileName_`
- double \*\* `allocationObj1Cost_`
- double \*\* `allocationObj2Cost_`

### 5.3.1 Detailed Description

Class to represent a *Data*.

This class represents a *Data* with all its attributes, parameters.

### 5.3.2 Member Typedef Documentation

#### 5.3.2.1 `vector< Customer > Data::ListCustomers`

The list of all customers.

This is a vector from the STL Containers of object *Customer*.

#### 5.3.2.2 `vector< Facility > Data::ListFacilities`

The list of all facilities.

This is a vector from the STL Containers of object *Facility*.

### 5.3.3 Constructor & Destructor Documentation

#### 5.3.3.1 `Data::Data ( unsigned int nbFacility, unsigned int nbCustomer, string name )`

Constructor of the class `Data`.

##### Parameters

in	<i>nbFacility</i>	: The number of <code>Facility</code> of the instance.
in	<i>nbCustomer</i>	: The number of <code>Customer</code> of the instance.
in	<i>name</i>	: The name of the instance.

#### 5.3.3.2 `Data::~Data ( )`

Destructor of the class `Data`.

### 5.3.4 Member Function Documentation

#### 5.3.4.1 `void Data::addCustomer ( Customer cust )`

Method to add a `Customer` to the `Data`.

##### Parameters

<i>cust</i>	: An object <code>Customer</code> .
-------------	-------------------------------------

#### 5.3.4.2 `void Data::addFacility ( Facility fac )`

Method to add a `Facility` to the `Data`.

##### Parameters

<i>fac</i>	: An object <code>Facility</code> .
------------	-------------------------------------

#### 5.3.4.3 `double Data::getAllocationObj1Cost ( int cust, int fac ) const`

Getter for the allocation cost w.r.t. objective 1 between a `Customer` and a `Facility`.

##### Parameters

in	<i>cust</i>	: The index of the <code>Customer</code> .
in	<i>fac</i>	: The index of the <code>Facility</code> .

**Returns**

A double as the value of the allocation cost w.r.t. objective 1 for the [Customer](#) cust to the [Facility](#) fac.

**5.3.4.4 double Data::getAllocationObj2Cost ( int *cust*, int *fac* ) const**

Getter for the allocation cost w.r.t. objective 2 between a [Customer](#) and a [Facility](#).

**Parameters**

in	<i>cust</i>	: The index of the <a href="#">Customer</a> .
in	<i>fac</i>	: The index of the <a href="#">Facility</a> .

**Returns**

A double as the value of the allocation cost w.r.t. objective 2 for the [Customer](#) cust to the [Facility](#) fac.

**5.3.4.5 Facility & Data::getFacility ( int *fac* )**

Getter for a [Facility](#).

**Parameters**

in	<i>fac</i>	: The index of the <a href="#">Facility</a> to return.
----	------------	--

**Returns**

A [Facility](#).

**5.3.4.6 string Data::getFileName ( ) const**

Getter for the name of the instance.

**Returns**

A string which represents the name of the instance.

**5.3.4.7 unsigned int Data::getnbCustomer ( ) const**

Getter for the number of customers.

**Returns**

An unsigned int as the number of customers of the instance.

#### 5.3.4.8 unsigned int Data::getnbFacility ( ) const

Getter for the number of facilities.

##### Returns

An unsigned int as the number of facilities of the instance.

#### 5.3.4.9 void Data::setAllocationObj1Cost ( int *cust*, int *fac*, double *val* )

Setter for the allocation cost w.r.t. objective 1 between a [Customer](#) and a [Facility](#).

##### Parameters

in	<i>cust</i>	: The index of the <a href="#">Customer</a> .
in	<i>fac</i>	: The index of the <a href="#">Facility</a> .
in	<i>val</i>	: The value of the allocation cost of the customer <i>cust</i> to the facility <i>fac</i> w.r.t. objective 1.

#### 5.3.4.10 void Data::setAllocationObj2Cost ( int *cust*, int *fac*, double *val* )

Setter for the allocation cost w.r.t. objective 2 between a [Customer](#) and a [Facility](#).

##### Parameters

in	<i>cust</i>	: The index of the <a href="#">Customer</a> .
in	<i>fac</i>	: The index of the <a href="#">Facility</a> .
in	<i>val</i>	: The value of the allocation cost of the customer <i>cust</i> to the facility <i>fac</i> w.r.t. objective 2.

#### 5.3.4.11 void Data::setFileName ( string *name* )

Setter for the name of the instance.

##### Parameters

in	<i>name</i>	: A string which represents the name of the instance.
----	-------------	---

### 5.3.5 Member Data Documentation

#### 5.3.5.1 double\*\* Data::allocationObj1Cost\_ [private]

An array of double (2 dimensions) which represents the matrix of allocation cost w.r.t. objective 1

5.3.5.2 `double** Data::allocationObj2Cost_` [private]

An array of double (2 dimensions) which represents the matrix of allocation cost w.r.t. objective 2

5.3.5.3 `ListCustomers Data::customerList_` [private]5.3.5.4 `ListFacilities Data::facilityList_` [private]5.3.5.5 `string Data::fileName_` [private]

A string which represents the name of the instance

The documentation for this class was generated from the following files:

- [/home/axel/Axel/Computing/svn/biuf1p2012/trunk/wolseyaward/1.1/src/Data.hpp](#)
- [/home/axel/Axel/Computing/svn/biuf1p2012/trunk/wolseyaward/1.1/src/Data.cpp](#)

## 5.4 Facility Class Reference

Class to represent a [Facility](#).

```
#include "Facility.hpp"
```

### Public Member Functions

- [Facility](#) (unsigned short &x, unsigned short &y)  
*Constructor of the class [Facility](#).*
- unsigned short [getCoordX](#) () const  
*Getter for the x coordinate.*
- unsigned short [getCoordY](#) () const  
*Getter for the y coordinate.*
- double [getLocationObj1Cost](#) () const  
*Getter for the location cost w.r.t. objective 1.*
- double [getLocationObj2Cost](#) () const  
*Getter for the location cost w.r.t. objective 2.*
- void [setLocationObj1Cost](#) (double &val)  
*Setter for the location cost w.r.t. objective 1.*
- void [setLocationObj2Cost](#) (double &val)  
*Setter for the location cost w.r.t. objective 2.*

### Private Attributes

- unsigned short `coordX_`
- unsigned short `coordY_`
- double `locationObj1Cost_`
- double `locationObj2Cost_`

### Related Functions

(Note that these are not member functions.)

- `std::ostream & operator<< (std::ostream &out, const Facility *fac)`  
*Operator overloading.*

#### 5.4.1 Detailed Description

Class to represent a `Facility`.

This class represents a `Facility` with all its attributes. The pair (x,y) represents respectively the first and second coordinates in a bi-dimensional geographical space.

#### 5.4.2 Constructor & Destructor Documentation

##### 5.4.2.1 `Facility::Facility ( unsigned short & x, unsigned short & y )`

Constructor of the class `Facility`.

##### Parameters

<code>in</code>	<code>x</code>	: An unsigned integer which represents the x coordinate of the <code>Facility</code> .
<code>in</code>	<code>y</code>	: An unsigned integer which represents the y coordinate of the <code>Facility</code> .

#### 5.4.3 Member Function Documentation

##### 5.4.3.1 `unsigned short Facility::getCoordX ( ) const`

Getter for the x coordinate.

##### Returns

An unsigned short as the x coordinate of this `Facility`.

**5.4.3.2 unsigned short Facility::getCoordY ( ) const**

Getter for the y coordinate.

**Returns**

An unsigned short as the y coordinate of this [Facility](#).

**5.4.3.3 double Facility::getLocationObj1Cost ( ) const**

Getter for the location cost w.r.t. objective 1.

**Returns**

A double as the location cost w.r.t. objective 1 of this [Facility](#).

**5.4.3.4 double Facility::getLocationObj2Cost ( ) const**

Getter for the location cost w.r.t. objective 2.

**Returns**

A double as the location cost w.r.t. objective 2 of this [Facility](#).

**5.4.3.5 void Facility::setLocationObj1Cost ( double & val )**

Setter for the location cost w.r.t. objective 1.

**Parameters**

in	val	: A double which represents the value of the location cost of this <a href="#">Facility</a> w.r.t. objective 1.
----	-----	---

**5.4.3.6 void Facility::setLocationObj2Cost ( double & val )**

Setter for the location cost w.r.t. objective 2.

**Parameters**

in	val	: A double which represents the value of the location cost of this <a href="#">Facility</a> w.r.t. objective 2.
----	-----	---

**5.4.4 Friends And Related Function Documentation**

#### 5.4.4.1 `std::ostream & operator<< ( std::ostream & out, const Facility * fac )` [related]

Operator overloading.

Overloading of the standard output stream in order to print a [Facility](#).

##### Parameters

<code>out</code>	<code>out</code>	: The standard output stream.
<code>in</code>	<code>fac</code>	: A <a href="#">Facility</a> to print in the standard output stream.

### 5.4.5 Member Data Documentation

#### 5.4.5.1 `unsigned short Facility::coordX_` [private]

Unsigned short which represents the value of the x coordinate of this [Facility](#)

#### 5.4.5.2 `unsigned short Facility::coordY_` [private]

Unsigned short which represents the value of the y coordinate of this [Facility](#)

#### 5.4.5.3 `double Facility::locationObj1Cost_` [private]

Double which represents the value of the location cost of this [Facility](#) w.r.t. objective 1

#### 5.4.5.4 `double Facility::locationObj2Cost_` [private]

Double which represents the value of the location cost of this [Facility](#) w.r.t. objective 2

The documentation for this class was generated from the following files:

- `/home/axel/Axel/Computing/svn/biufp2012/trunk/wolseyaward/1.1/src/Facility.hpp`
- `/home/axel/Axel/Computing/svn/biufp2012/trunk/wolseyaward/1.1/src/Facility.cpp`

## 5.5 LabelSetting Class Reference

Class to represent a [LabelSetting](#).

```
#include "LabelSetting.hpp"
```



## Public Member Functions

- [LabelSetting](#) ([Box](#) &box)  
*Default Constructor of the class [LabelSetting](#).*
- [~LabelSetting](#) ()  
*Destructor of the class [LabelSetting](#).*
- void [compute](#) ()  
*A method to compute all solutions into a [Box](#).*
- void [computeNode](#) (int indexNode)  
*A method to compute all the labels of the algorithm at level indexNode.*
- void [print](#) ()  
*A method to print informations about the label setting algorithm.*
- unsigned int [getRank](#) () const  
*Getter for the rank (number of level).*

## Public Attributes

- [Node](#) \* [nodes\\_](#)

## Private Attributes

- unsigned int [nbRank\\_](#)
- double [boundZ1\\_](#)
- double [boundZ2\\_](#)
- [Data](#) & [data\\_](#)

### 5.5.1 Detailed Description

Class to represent a [LabelSetting](#).

This class represents a [LabelSetting](#) with all its attributes and methods.

### 5.5.2 Constructor & Destructor Documentation

#### 5.5.2.1 [LabelSetting::LabelSetting](#) ( [Box](#) & *box* )

Default Constructor of the class [LabelSetting](#).

#### Parameters

<a href="#">in</a>	<a href="#">box</a>	: A <a href="#">Box</a> object in which one runs the label setting algorithm.
--------------------	---------------------	---

### 5.5.2.2 `LabelSetting::~~LabelSetting ( )`

Destructor of the class [LabelSetting](#).

## 5.5.3 Member Function Documentation

### 5.5.3.1 `void LabelSetting::compute ( )`

A method to compute all solutions into a [Box](#).

### 5.5.3.2 `void LabelSetting::computeNode ( int indexNode )`

A method to compute all the labels of the algorithm at level *indexNode*.

#### Parameters

<i>indexNode</i>	: The level in which one ones executes the algorithm.
------------------	---

### 5.5.3.3 `unsigned int LabelSetting::getRank ( ) const`

Getter for the rank (number of level).

#### Returns

A unsigned int which value is the rank (number of level) of the algorithm.

### 5.5.3.4 `void LabelSetting::print ( )`

A method to print informations about the label setting algorithm.

## 5.5.4 Member Data Documentation

### 5.5.4.1 `double LabelSetting::boundZ1_ [private]`

A unsigned int which represents the maximum value w.r.t. objective 1 of this [Box](#)

### 5.5.4.2 `double LabelSetting::boundZ2_ [private]`

A unsigned int which represents the maximum value w.r.t. objective 2 of this [Box](#)

### 5.5.4.3 `Data& LabelSetting::data_ [private]`

A reference to the [Data](#) of this [Box](#)

#### 5.5.4.4 unsigned int `LabelSetting::nbRank_` [private]

A unsigned int which represents the number of level of this algorithm in this [Box](#)

#### 5.5.4.5 `Node*` `LabelSetting::nodes_`

A pointer of [Node](#) which represents all the solutions in each level

The documentation for this class was generated from the following files:

- `/home/axel/Axel/Computing/svn/biufp2012/trunk/wolseyaward/1.1/src/LabelSetting.hpp`
- `/home/axel/Axel/Computing/svn/biufp2012/trunk/wolseyaward/1.1/src/LabelSetting.cpp`

## 5.6 Node Class Reference

Class to represent a [Node](#).

```
#include "Node.hpp"
```

### Public Member Functions

- [Node](#) ()  
*Default Constructor of the class [Node](#).*
- [Node](#) (int size)  
*Default Constructor of the class [Node](#).*
- [~Node](#) ()  
*Destructor of the class [Node](#).*
- void [setSize](#) (unsigned int s)  
*Setter for the size of this [Node](#).*
- unsigned int [getSize](#) () const  
*Getter for the size.*
- double [getCostToEnterZ1](#) (int i) const  
*Getter for the cost to enter to this [Node](#) w.r.t. objective 1.*
- double [getCostToEnterZ2](#) (int i) const  
*Getter for the cost to enter to this [Node](#) w.r.t. objective 2.*
- void [clearLabels](#) ()  
*A method to delete all the labels of this [Node](#).*
- void [setValues](#) (int index, double z1, double z2)  
*Setter of the values of the solution ones want to set.*
- void [print](#) ()  
*A method to print informations about this [Node](#).*

## Public Attributes

- list< [Solution](#) > [labels\\_](#)

## Private Attributes

- unsigned int [size\\_](#)
- double \* [costToEnterZ1\\_](#)
- double \* [costToEnterZ2\\_](#)

### 5.6.1 Detailed Description

Class to represent a [Node](#).

This class represents a [Node](#) with all its attributes and methods.

### 5.6.2 Constructor & Destructor Documentation

#### 5.6.2.1 `Node::Node ( )`

Default Constructor of the class [Node](#).

#### 5.6.2.2 `Node::Node ( int size )`

Default Constructor of the class [Node](#).

#### Parameters

<code>in</code>	<code>size</code>	: An int which represents the size of this node.
-----------------	-------------------	--

#### 5.6.2.3 `Node::~~Node ( )`

Destructor of the class [Node](#).

### 5.6.3 Member Function Documentation

#### 5.6.3.1 `void Node::clearLabels ( )`

A method to delete all the labels of this [Node](#).

#### 5.6.3.2 `double Node::getCostToEnterZ1 ( int i ) const`

Getter for the cost to enter to this [Node](#) w.r.t. objective 1.

## Parameters

<i>i</i>	: The index.
----------	--------------

## Returns

A double as the cost to enter to this [Node](#) w.r.t. objective 1 at the index *i*.

**5.6.3.3 double Node::getCostToEnterZ2 ( int *i* ) const**

Getter for the cost to enter to this [Node](#) w.r.t. objective 2.

## Parameters

<i>i</i>	: The index.
----------	--------------

## Returns

A double as the cost to enter to this [Node](#) w.r.t. objective 2 at the index *i*.

**5.6.3.4 unsigned int Node::getSize ( ) const**

Getter for the size.

## Returns

An unsigned int as the size of this [Node](#).

**5.6.3.5 void Node::print ( )**

A method to print informations about this [Node](#).

**5.6.3.6 void Node::setSize ( unsigned int *s* )**

Setter for the size of this [Node](#).

## Parameters

<i>in</i>	<i>s</i>	: A unsigned int which represents size of this <a href="#">Node</a> .
-----------	----------	---

**5.6.3.7 void Node::setValues ( int *index*, double *z1*, double *z2* )**

Setter of the values of the solution ones want to set.

## Parameters

in	<i>index</i>	: The index.
in	<i>z1</i>	: The value of the solution w.r.t. objective 1 ones wants to set.
in	<i>z2</i>	: The value of the solution w.r.t. objective 2 ones wants to set.

## 5.6.4 Member Data Documentation

5.6.4.1 `double* Node::costToEnterZ1_` [private]

A pointer of double which represents all the values to enter to this [Node](#) w.r.t objective 1

5.6.4.2 `double* Node::costToEnterZ2_` [private]

A pointer of double which represents all the values to enter to this [Node](#) w.r.t objective 2

5.6.4.3 `list<Solution> Node::labels_`

A list of [Solution](#) which represents all the [Solutions](#) (or labels) in this [Node](#)

5.6.4.4 `unsigned int Node::size_` [private]

A unsigned int which represents the size of this [Node](#)

The documentation for this class was generated from the following files:

- [/home/axel/Axel/Computing/svn/biufp2012/trunk/wolseyaward/1.1/src/Node.hpp](#)
- [/home/axel/Axel/Computing/svn/biufp2012/trunk/wolseyaward/1.1/src/Node.cpp](#)

## 5.7 Parser Class Reference

Class to represent a [Parser](#).

```
#include "Parser.hpp"
```

## Static Public Member Functions

- static [Data](#) \* [Parsing](#) (const char \*filename)  
*Static method to parse the instance.*

### Static Private Member Functions

- static void [ignoreLine](#) (ifstream &file)  
*Static method to skip a line from the instance.*
- static void [ignoreChar](#) (ifstream &file)  
*Static method to skip a character from the instance.*

#### 5.7.1 Detailed Description

Class to represent a [Parser](#).

This class represents a [Parser](#) with all its methods to read and parse an instance file.

#### 5.7.2 Member Function Documentation

##### 5.7.2.1 void [Parser::ignoreChar](#) ( ifstream & *file* ) [static, private]

*Static* method to skip a character from the instance.

###### Parameters

<i>in</i>	<i>file</i>	: A ifstream (IOstream) which represents the file readed.
-----------	-------------	---

##### 5.7.2.2 void [Parser::ignoreLine](#) ( ifstream & *file* ) [static, private]

*Static* method to skip a line from the instance.

###### Parameters

<i>in</i>	<i>file</i>	: A ifstream (IOstream) which represents the file readed.
-----------	-------------	---

##### 5.7.2.3 Data \* [Parser::Parsing](#) ( const char \* *filename* ) [static]

*Static* method to parse the instance.

###### Parameters

<i>in</i>	<i>filename</i>	: A const char which represents the instance file.
-----------	-----------------	--

#### Returns

A [Data](#) object which contains all the values of the instance file.

The documentation for this class was generated from the following files:

- /home/axel/Axel/Computing/svn/biufp2012/trunk/wolseyaward/1.1/src/[Parser.hpp](#)
- /home/axel/Axel/Computing/svn/biufp2012/trunk/wolseyaward/1.1/src/[Parser.cpp](#)

## 5.8 Solution Class Reference

Class to represent a [Solution](#).

```
#include "Solution.hpp"
```

#### Public Member Functions

- [Solution](#) ()  
*Default constructor of the class [Solution](#).*
- [Solution](#) (double obj1, double obj2)  
*Constructor of the class [Solution](#).*
- [~Solution](#) ()  
*Destructor of the class [Solution](#).*
- void [setObj1](#) (double obj)  
*Setter for the value w.r.t objective 1 of this [Solution](#).*
- void [setObj2](#) (double obj)  
*Setter for the value w.r.t objective 2 of this [Solution](#).*
- double [getObj1](#) () const  
*Getter for the value w.r.t. objective 1 of this [Solution](#).*
- double [getObj2](#) () const  
*Getter for the value w.r.t. objective 2 of this [Solution](#).*

#### Private Attributes

- double [obj1\\_](#)
- double [obj2\\_](#)

#### Related Functions

(Note that these are not member functions.)

- bool [operator<](#) ([Solution](#) s1, [Solution](#) s2)  
*Operator overloading.*



### 5.8.1 Detailed Description

Class to represent a [Solution](#).

This class represents a [Solution](#) with all its two attributes (`obj1_` and `obj2_`).

### 5.8.2 Constructor & Destructor Documentation

#### 5.8.2.1 `Solution::Solution ( )`

Default constructor of the class [Solution](#).

#### 5.8.2.2 `Solution::Solution ( double obj1, double obj2 )`

Constructor of the class [Solution](#).

##### Parameters

in	<i>obj1</i>	: A double which represents the value of the <a href="#">Solution</a> w.r.t. objective 1.
in	<i>obj2</i>	: A double which represents the value of the <a href="#">Solution</a> w.r.t. objective 2.

#### 5.8.2.3 `Solution::~~Solution ( )`

Destructor of the class [Solution](#).

### 5.8.3 Member Function Documentation

#### 5.8.3.1 `double Solution::getObj1 ( ) const`

Getter for the value w.r.t. objective 1 of this [Solution](#).

##### Returns

A double as the value w.r.t. objective 1 of this [Solution](#).

#### 5.8.3.2 `double Solution::getObj2 ( ) const`

Getter for the value w.r.t. objective 2 of this [Solution](#).

##### Returns

A double as the value w.r.t. objective 2 of this [Solution](#).

### 5.8.3.3 void `Solution::setObj1` ( double *obj* )

Setter for the value w.r.t objective 1 of this [Solution](#).

#### Parameters

in	<i>obj</i> : A double which represents the value of the <a href="#">Solution</a> w.r.t objective 1.
----	---

### 5.8.3.4 void `Solution::setObj2` ( double *obj* )

Setter for the value w.r.t objective 2 of this [Solution](#).

#### Parameters

in	<i>obj</i> : A double which represents the value of the <a href="#">Solution</a> w.r.t objective 2.
----	---

## 5.8.4 Friends And Related Function Documentation

### 5.8.4.1 bool `operator<` ( [Solution](#) *s1*, [Solution](#) *s2* ) [related]

Operator overloading.

Overloading of the comparison operator `<` in order to compare two solutions.

#### Parameters

in	<i>s1</i> : The first <a href="#">Solution</a> to compare.
in	<i>s2</i> : The second <a href="#">Solution</a> to compare.

#### Returns

A boolean which gets `TRUE` if the value w.r.t. objective 1 of the [Solution](#) *s1* is strictly lower to the value w.r.t. objective 1 of the [Solution](#) *s2*, `FALSE` otherwise.

## 5.8.5 Member Data Documentation

### 5.8.5.1 double `Solution::obj1_` [private]

Double which represents the value w.r.t. objective 1 of this [Solution](#)

### 5.8.5.2 double `Solution::obj2_` [private]

Double which represents the value w.r.t. objective 2 of this [Solution](#)

The documentation for this class was generated from the following files:

- /home/axel/Axel/Computing/svn/biufp2012/trunk/wolseyaward/1.1/src/[Solution.-hpp](#)
- /home/axel/Axel/Computing/svn/biufp2012/trunk/wolseyaward/1.1/src/[Solution.-cpp](#)

## 5.9 ToFile Class Reference

Class to represent a [ToFile](#).

```
#include "ToFile.hpp"
```

### Static Public Member Functions

- static void [removeFiles](#) ()  
*Static method to erase file into folder /res.*
- static void [saveCorrelation](#) ([Data](#) &data)  
*Static method to save correlation into a file.*
- static void [saveInitialBoxes](#) (vector< [Box](#) \* > &vectorBox, [Data](#) &data)  
*Static method to save initial Boxes into a file.*
- static void [saveFilteringBoxes](#) (vector< [Box](#) \* > &vectorBox, [Data](#) &data)  
*Static method to save filtered Boxes into a file.*
- static void [saveReconstructionBoxes](#) (vector< [Box](#) \* > &vectorBox, [Data](#) &data)  
*Static method to save recomposed Boxes into a file.*
- static void [saveYN](#) (list< [Solution](#) > &lsol, [Data](#) &data)  
*Static method to save solutions into a file.*

### 5.9.1 Detailed Description

Class to represent a [ToFile](#).

This class represents a [ToFile](#) with all its attributes and methods.

### 5.9.2 Member Function Documentation

#### 5.9.2.1 void ToFile::removeFiles ( ) [static]

*Static method to erase file into folder /res.*

#### 5.9.2.2 void ToFile::saveCorrelation ( [Data](#) &data ) [static]

*Static method to save correlation into a file.*

## Parameters

in	<i>data</i>	: A <a href="#">Data</a> object which contains all the values of the instance.
----	-------------	--

**5.9.2.3 void ToFile::saveFilteringBoxes ( vector< Box \* > & vectorBox, Data & data )**  
[static]

*Static* method to save filtered Boxes into a file.

## Parameters

in	<i>vectorBox</i>	: A vector of filtered Boxes.
in	<i>data</i>	: A <a href="#">Data</a> object which contains all the values of the instance.

**5.9.2.4 void ToFile::saveInitialBoxes ( vector< Box \* > & vectorBox, Data & data )**  
[static]

*Static* method to save initial Boxes into a file.

## Parameters

in	<i>vectorBox</i>	: A vector of initial Boxes.
in	<i>data</i>	: A <a href="#">Data</a> object which contains all the values of the instance.

**5.9.2.5 void ToFile::saveReconstructionBoxes ( vector< Box \* > & vectorBox, Data & data )** [static]

*Static* method to save recomposed Boxes into a file.

## Parameters

in	<i>vectorBox</i>	: A vector of recomposed Boxes.
in	<i>data</i>	: A <a href="#">Data</a> object which contains all the values of the instance.

**5.9.2.6 void ToFile::saveYN ( list< Solution > & /sol, Data & data )** [static]

*Static* method to save solutions into a file.

## Parameters

in	<i>/sol</i>	: A list of Solutions.
in	<i>data</i>	: A <a href="#">Data</a> object which contains all the values of the instance.

The documentation for this class was generated from the following files:

- [/home/axel/Axel/Computing/svn/biufp2012/trunk/wolseyaward/1.1/src/ToFile.hpp](#)
- [/home/axel/Axel/Computing/svn/biufp2012/trunk/wolseyaward/1.1/src/ToFile.cpp](#)



## Chapter 6

# File Documentation

### 6.1 /home/axel/Axel/Computing/svn/biufp2012/trunk/wolseyaward/1.1/src/-Box.cpp File Reference

```
#include "Box.hpp"
```

#### Functions

- bool [isDominatedBetweenTwoBoxes](#) ([Box](#) \*box1, [Box](#) \*box2)
- bool [isDominatedBetweenOrigins](#) ([Box](#) \*box1, [Box](#) \*box2)
- void [filterDominatedBoxes](#) (vector< [Box](#) \* > &vectBox)
- bool [isDominatedByItsOrigin](#) (vector< [Box](#) \* > &vectBox, [Box](#) \*box)
- bool [isDominatedByItsBox](#) (vector< [Box](#) \* > &vectBox, [Box](#) \*box)

#### 6.1.1 Function Documentation

6.1.1.1 void [filterDominatedBoxes](#) ( vector< [Box](#) \* > & *vectBox* )

6.1.1.2 bool [isDominatedBetweenOrigins](#) ( [Box](#) \* *box1*, [Box](#) \* *box2* ) [related]

6.1.1.3 bool [isDominatedBetweenTwoBoxes](#) ( [Box](#) \* *box1*, [Box](#) \* *box2* )  
[related]

6.1.1.4 bool [isDominatedByItsBox](#) ( vector< [Box](#) \* > & *vectBox*, [Box](#) \* *box* )

6.1.1.5 bool [isDominatedByItsOrigin](#) ( vector< [Box](#) \* > & *vectBox*, [Box](#) \* *box* )

## 6.2 /home/axel/Axel/Computing/svn/biuf1p2012/trunk/wolseyaward/1.1/src/-Box.hpp File Reference

Class of the [Box](#).

```
#include <iostream>  #include <cfloat>  #include "Data.-  
hpp"
```

### Classes

- class [Box](#)

*Class to represent a [Box](#).*

### 6.2.1 Detailed Description

Class of the [Box](#).

#### Author

Salim BOUROUGAA & Alban DERRIEN & Axel GRIMAUULT & Xavier GANDIBLE-  
UX & Anthony PRZYBYLSKI

#### Date

28 August 2012

#### Version

1.1

#### Copyright

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This class represents an object [Box](#). A [Box](#) is a sub-space of dimension 2 defined in the objective space and characterized by at most two feasible solutions. These solutions correspond to the two lexicographic optimal solutions for the two objective functions when a set of [Facility](#) opened is considered.

## 6.3 /home/axel/Axel/Computing/svn/biuf1p2012/trunk/wolseyaward/1.1/src/-Customer.cpp File Reference

```
#include "Customer.hpp"
```



- ostream & [operator<<](#) (ostream &out, const [Customer](#) \*cust)

### 6.3.1 Function Documentation

6.3.1.1 ostream& operator<< ( ostream & out, const Customer \* cust )

## 6.4 /home/axel/Axel/Computing/svn/biufp2012/trunk/wolseyaward/1.1/src/- Customer.hpp File Reference

Class of the [Customer](#).

```
#include <iostream>
```

### Classes

- class [Customer](#)  
*Class to represent a [Customer](#).*

### 6.4.1 Detailed Description

Class of the [Customer](#).

#### Author

Salim BOUROUGAA & Alban DERRIEN & Axel GRIMAUULT & Xavier GANDIBLE-  
UX & Anthony PRZYBYLSKI

#### Date

28 August 2012

#### Version

1.1

#### Copyright

This class represents a customer, or client, with its geographical coordinates and its costs of location w.r.t. to the two objectives in a FLP.

## 6.5 /home/axel/Axel/Computing/svn/biufp2012/trunk/wolseyaward/1.1/src/-Data.cpp File Reference

```
#include "Data.hpp"
```

## 6.6 /home/axel/Axel/Computing/svn/biufp2012/trunk/wolseyaward/1.1/src/-Data.hpp File Reference

Class of the [Data](#).

```
#include "Facility.hpp" #include "Customer.hpp" #include  
<iostream> #include <vector> #include <cfloat>
```

### Classes

- class [Data](#)

*Class to represent a [Data](#).*

### 6.6.1 Detailed Description

Class of the [Data](#).

#### Author

Salim BOUROUGAA & Alban DERRIEN & Axel GRIMAULT & Xavier GANDIBLE-UX & Anthony PRZYBYLSKI

#### Date

28 August 2012

#### Version

1.1

#### Copyright

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This class will contains all the values, parameters of the instance. Especially, it contains the allocation cost between customers and facilities.

## 6.7 /home/axel/Axel/Computing/svn/biufp2012/trunk/wolseyaward/1.1/src/- Facility.cpp File Reference

### 6.7 /home/axel/Axel/Computing/svn/biufp2012/trunk/wolseyaward/1.1/src/- Facility.cpp File Reference

```
#include "Facility.hpp"
```

#### 6.7.1 Function Documentation

6.7.1.1 ostream& operator<< ( ostream & *out*, const Facility \* *fac* ) [related]

## 6.8 /home/axel/Axel/Computing/svn/biufp2012/trunk/wolseyaward/1.1/src/- Facility.hpp File Reference

Class of the [Facility](#).

```
#include <iostream>
```

### Classes

- class [Facility](#)  
*Class to represent a [Facility](#).*

#### 6.8.1 Detailed Description

Class of the [Facility](#).

#### Author

Salim BOUROUGAA & Alban DERRIEN & Axel GRIMAULT & Xavier GANDIBLE-  
UX & Anthony PRZYBYLSKI

#### Date

28 August 2012

#### Version

1.1

#### Copyright

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This class represents a facility, or warehouse or service, with its geographical coordinates and its costs of location w.r.t. to the two objectives in a FLP.

## 6.9 /home/axel/Axel/Computing/svn/biuf1p2012/trunk/wolseyaward/1.1/src/- Functions.cpp File Reference

```
#include "Functions.hpp"
```

### Functions

- long int `createBox` (vector< `Box` \* > &vectorBox, `Data` &data)  
*This method computes all the initial Boxes of our algorithm.*
- void `addChildren` (`Box` \*boxMother, vector< `Box` \* > &vBox)  
*This method adds children of a Box into a vector of Boxes.*
- void `filter` (vector< `Box` \* > &vectorBox, long int &nbToCompute, long int &nbWithNeighbor)  
*This method filters all the Boxes of a vector of Box.*
- void `boxFiltering` (vector< `Box` \* > &vectorBox, `Data` &data, long int &nbToCompute, long int &nbWithNeighbor)  
*This method splits a Box into two Boxes.*
- void `recomposition` (vector< `Box` \* > &vectorBox, vector< `Box` \* > &vectorBox-Final, `Data` &data, long int &nbToCompute, long int &nbWithNeighbor)  
*This method recomposes a group of Boxes into an unique one.*
- void `weightedSumOneStep` (vector< `Box` \* > &vectorBox, `Data` &data)  
*Compute the weighted sum method to split a Box in two Boxes.*
- long int `runLabelSetting` (vector< `Box` \* > &vectorBox, `Data` &data)  
*This method runs the Label Setting algorithm.*
- void `filterListSolution` (list< `Solution` > &lsol)  
*Delete the solutions dominated.*
- double `computeCorrelation` (`Data` &data)  
*This method computes the correlation.*
- float `time_ms_Diff` (timeval tvStart, timeval tvEnd)  
*This method computes the difference in milli-seconds (ms) between two times.*
- float `time_s_Diff` (timeval tvStart, timeval tvEnd)  
*This method computes the difference in seconds (ms) between two times.*

## 6.10 /home/axel/Axel/Computing/svn/biuf1p2012/trunk/wolseyaward/1.1/src/- Functions.hpp File Reference

A set of functions usefull for our software.

```
#include <vector> #include <map> #include <list> #include  
<iostream> #include <cmath> #include "Data.hpp" #include  
"Solution.hpp" #include "Box.hpp" #include "ToFile.hpp" ×  
#include "LabelSetting.hpp"
```

- long int [createBox](#) (vector< [Box](#) \* > &vectorBox, [Data](#) &data)  
*This method computes all the initial Boxes of our algorithm.*
- void [addChildren](#) ([Box](#) \*boxMother, vector< [Box](#) \* > &vBox)  
*This method adds children of a Box into a vector of Boxes.*
- void [filter](#) (vector< [Box](#) \* > &vectorBox, long int &nbToCompute, long int &nbWithNeighbor)  
*This method filters all the Boxes of a vector of Box.*
- void [boxFiltering](#) (vector< [Box](#) \* > &vectorBox, [Data](#) &data, long int &nbToCompute, long int &nbWithNeighbor)  
*This method splits a Box into two Boxes.*
- void [recomposition](#) (vector< [Box](#) \* > &vectorBox, vector< [Box](#) \* > &vectorBox-Final, [Data](#) &data, long int &nbToCompute, long int &nbWithNeighbor)  
*This method recomposes a group of Boxes into an unique one.*
- void [weightedSumOneStep](#) (vector< [Box](#) \* > &vectorBox, [Data](#) &data)  
*Compute the weighted sum method to split a Box in two Boxes.*
- long int [runLabelSetting](#) (vector< [Box](#) \* > &vectorBox, [Data](#) &data)  
*This method runs the Label Setting algorithm.*
- void [filterListSolution](#) (list< [Solution](#) > &lsol)  
*Delete the solutions dominated.*
- double [computeCorrelation](#) ([Data](#) &data)  
*This method computes the correlation.*
- float [time\\_ms\\_Diff](#) (timeval tvStart, timeval tvEnd)  
*This method computes the difference in milli-seconds (ms) between two times.*
- float [time\\_s\\_Diff](#) (timeval tvStart, timeval tvEnd)  
*This method computes the difference in seconds (ms) between two times.*

## Variables

- bool [modeExport](#)  
*Variable representing the Export mode.*

### 6.10.1 Detailed Description

A set of functions usefull for our software.

#### Author

Salim BOUROUGAA & Alban DERRIEN & Axel GRIMAUULT & Xavier GANDIBLE-UX & Anthony PRZYBYLSKI

**Date**

28 August 2012

**Version**

1.1

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This file groups all the functions for solving our problem which are not methods of Class.

## 6.11 /home/axel/Axel/Computing/svn/biufp2012/trunk/wolseyaward/1.1/src/- LabelSetting.cpp File Reference

```
#include "LabelSetting.hpp"
```

## 6.12 /home/axel/Axel/Computing/svn/biufp2012/trunk/wolseyaward/1.1/src/- LabelSetting.hpp File Reference

Class of the [Box](#).

```
#include <iostream>    #include <list>    #include "Data.-  
hpp" #include "Box.hpp" #include "Node.hpp" #include "-  
Solution.hpp" #include "Functions.hpp"
```

### Classes

- class [LabelSetting](#)  
*Class to represent a [LabelSetting](#).*

### Variables

- bool [modeVerbose](#)  
*Variable representing the Verbose mode.*

### 6.12.1 Detailed Description

Class of the [Box](#).

## 6.13

/home/axel/Axel/Computing/svn/biufp2012/trunk/wolseyaward/1.1/src/Main.cpp

### File Reference

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Author

Salim BOUROUGAA & Alban DERRIEN & Axel GRIMAULT & Xavier GANDIBLE-UX & Anthony PRZYBYLSKI

### Date

28 August 2012

### Version

1.1

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This class represents a [LabelSetting](#) which is the algorithm used to find all solutions.

## 6.13 /home/axel/Axel/Computing/svn/biufp2012/trunk/wolseyaward/1.1/src/- Main.cpp File Reference

Main of the software.

```
#include <sys/time.h> #include <stdexcept> #include <iostream> ×  
#include <string.h> #include <cfloat> #include <cmath>  
#include <cstdlib> #include "Parser.hpp" #include "Data.-  
hpp" #include "Functions.hpp" #include "ToFile.hpp"
```

### Functions

- int [main](#) (int argc, char \*argv[])

*This is the main of the software.*

### Variables

- bool [modeVerbose](#) = false

*Variable representing the Verbose mode.*

- bool [modeExport](#) = false

*Variable representing the Export mode.*

### 6.13.1 Detailed Description

Main of the software.

#### Author

Salim BOUROUGAA & Alban DERRIEN & Axel GRIMAULT & Xavier GANDIBLE-UX & Anthony PRZYBYLSKI

#### Date

28 August 2012

#### Version

1.1

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### 6.14 `/home/axel/Axel/Computing/svn/biufp2012/trunk/wolseyaward/1.1/src/-Node.cpp` File Reference

```
#include "Node.hpp"
```

### 6.15 `/home/axel/Axel/Computing/svn/biufp2012/trunk/wolseyaward/1.1/src/-Node.hpp` File Reference

Class of the [Node](#).

```
#include <iostream> #include <list> #include "Solution.-hpp"
```

#### Classes

- class [Node](#)  
*Class to represent a [Node](#).*

#### Variables

- bool [modeVerbose](#)  
*Variable representing the Verbose mode.*



## 6.16

/home/axel/Axel/Computing/svn/biufp2012/trunk/wolseyaward/1.1/src/Parser.cpp

### File Reference

61

#### 6.15.1 Detailed Description

---

Class of the [Node](#).

#### Author

Salim BOUROUGAA & Alban DERRIEN & Axel GRIMAULT & Xavier GANDIBLE-UX & Anthony PRZYBYLSKI

#### Date

28 August 2012

#### Version

1.1

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This class represents a [Node](#) which represents a level in the Label Setting algorithm.

## 6.16 /home/axel/Axel/Computing/svn/biufp2012/trunk/wolseyaward/1.1/src/-Parser.cpp File Reference

```
#include "Parser.hpp"
```

## 6.17 /home/axel/Axel/Computing/svn/biufp2012/trunk/wolseyaward/1.1/src/-Parser.hpp File Reference

Class of the [Parser](#).

```
#include <fstream> #include <iostream> #include <math.-  
h> #include "Data.hpp"
```

#### Classes

- class [Parser](#)

*Class to represent a [Parser](#).*

### 6.17.1 Detailed Description

Class of the [Parser](#).

#### Author

Salim BOUROUGAA & Alban DERRIEN & Axel GRIMAULT & Xavier GANDIBLE-UX & Anthony PRZYBYLSKI

#### Date

28 August 2012

#### Version

1.1

#### Copyright

This class represents a parser to read data from an instance file.

## 6.18 /home/axel/Axel/Computing/svn/biufp2012/trunk/wolseyaward/1.1/src/-Solution.cpp File Reference

```
#include "Solution.hpp"
```

### 6.18.1 Function Documentation

6.18.1.1 `bool operator< ( Solution s1, Solution s2 )` [\[related\]](#)

## 6.19 /home/axel/Axel/Computing/svn/biufp2012/trunk/wolseyaward/1.1/src/-Solution.hpp File Reference

Class of the [Solution](#).

### Classes

- class [Solution](#)

*Class to represent a [Solution](#).*

## 6.20

/home/axel/Axel/Computing/svn/biufp2012/trunk/wolseyaward/1.1/src/ToFile.cpp

### File Reference

63

#### 6.19.1 Detailed Description

---

Class of the [Solution](#).

#### Author

Salim BOUROUGAA & Alban DERRIEN & Axel GRIMAUULT & Xavier GANDIBLE-UX & Anthony PRZYBYLSKI

#### Date

28 August 2012

#### Version

1.1

#### Copyright

This class represents a solution. In FLP, a solution is representes by two values respectively for the objective 1 and the objective 2.

## 6.20 /home/axel/Axel/Computing/svn/biufp2012/trunk/wolseyaward/1.1/src/-ToFile.cpp File Reference

```
#include "ToFile.hpp"
```

## 6.21 /home/axel/Axel/Computing/svn/biufp2012/trunk/wolseyaward/1.1/src/-ToFile.hpp File Reference

Class of the [ToFile](#).

```
#include <list> #include <iomanip> #include <vector> ×  
#include <stdio.h> #include <fstream> #include <dirent.-  
h> #include <sys/types.h> #include <sstream> #include  
<string> #include "Box.hpp" #include "Data.hpp" #include  
"Solution.hpp"
```

### Classes

- class [ToFile](#)

*Class to represent a [ToFile](#).*

## Variables

- bool `modeExport`

*Variable representing the Export mode.*

### 6.21.1 Detailed Description

Class of the `ToFile`.

#### Author

Salim BOUROUGAA & Alban DERRIEN & Axel GRIMAULT & Xavier GANDIBLE-UX & Anthony PRZYBYLSKI

#### Date

28 August 2012

#### Version

1.1

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This class exports values, solutions to file in the folder res.