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FMUGym: From Uncertainty-Aware Simulation to Learning-Based Control with FMI and Python

Tutorial @ 16th International Modelica & FMI Conference

Motivation

Some Quotes from Smart People

“All models are wrong, but some are useful”

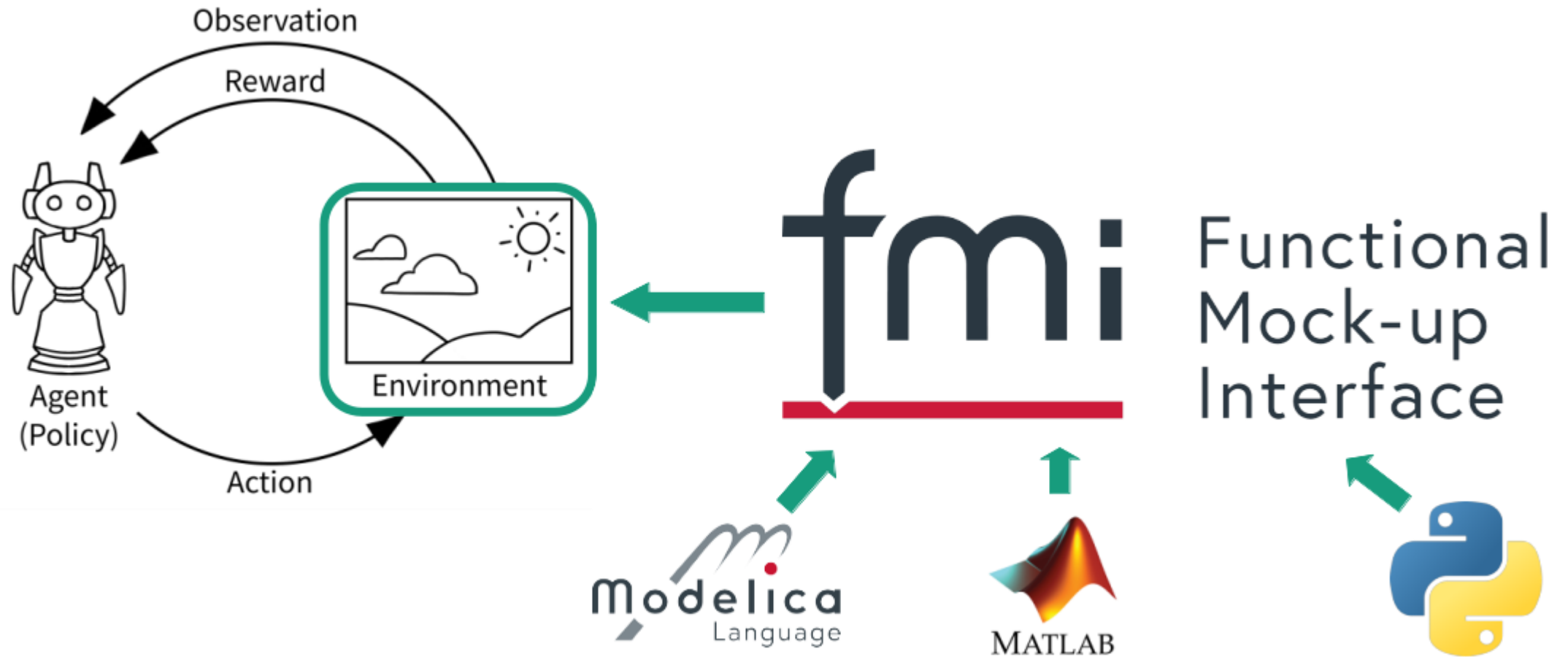
- George E. P. Box

“Very wrong models, can be very useful”

- Roberto Calandra

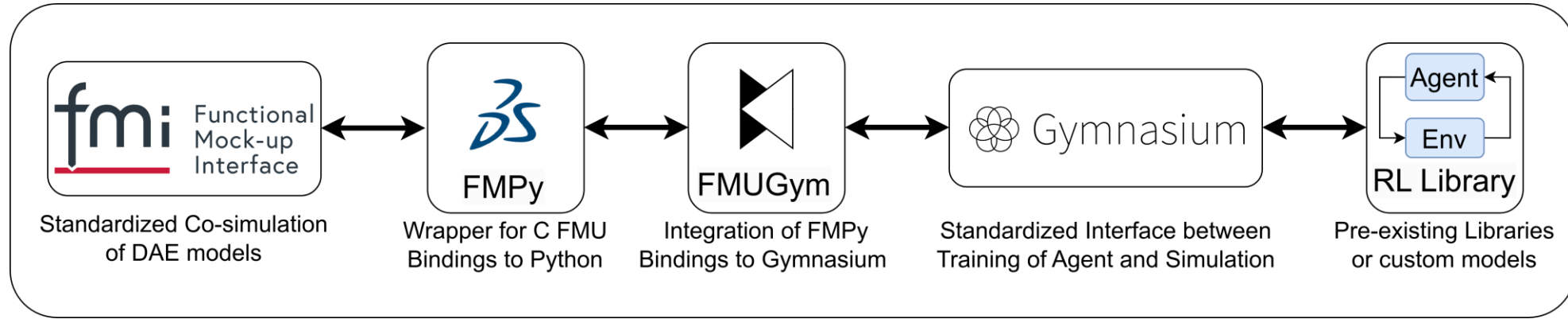
Motivation

Self-learning Control Systems: Reinforcement Learning and FMI Standard



FMUGym Interface

Connecting FMI with Reinforcement Learning Agents

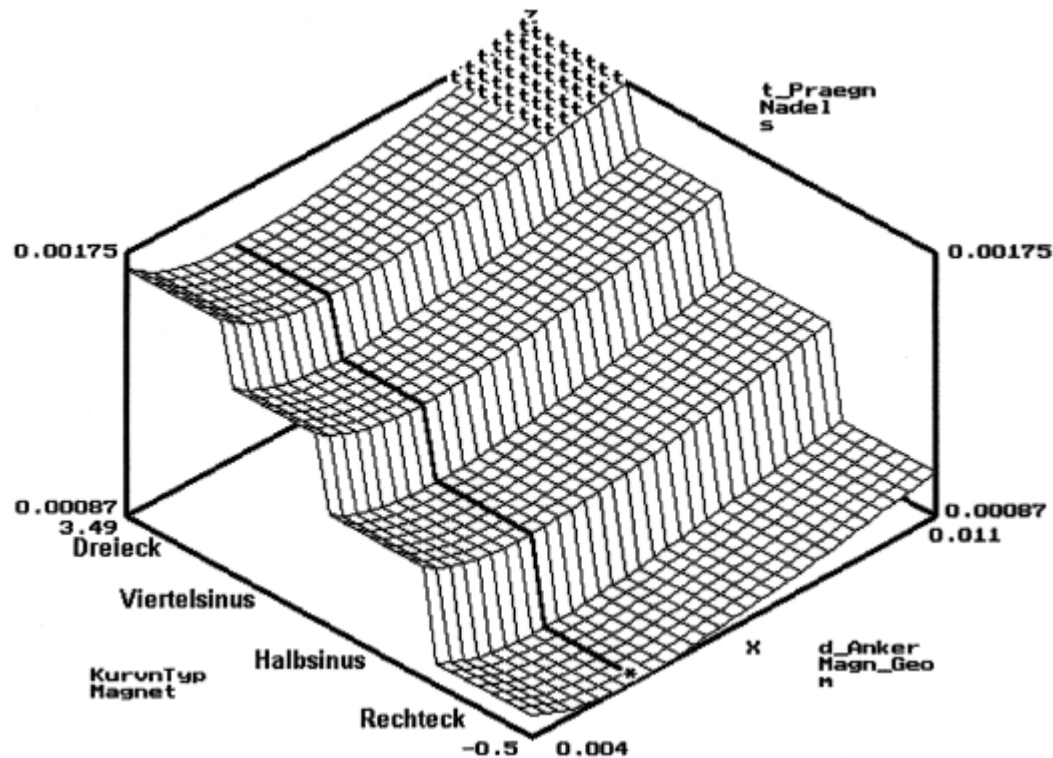


Tutorial Participation:

- **Windows** with Google Account: Colab <https://tinyurl.com/fmugym-colab> (**suggested**)
- **Windows** without Google Account: Binder <https://tinyurl.com/fmugym-binder> (very slow Reinforcement Learning)
- Additional for **Linux**: clone repo and follow local Installation <https://github.com/Fraunhofer-IIS/fmugym> (best to continue)

Tuning PID Controller

Evolutionary Algorithm

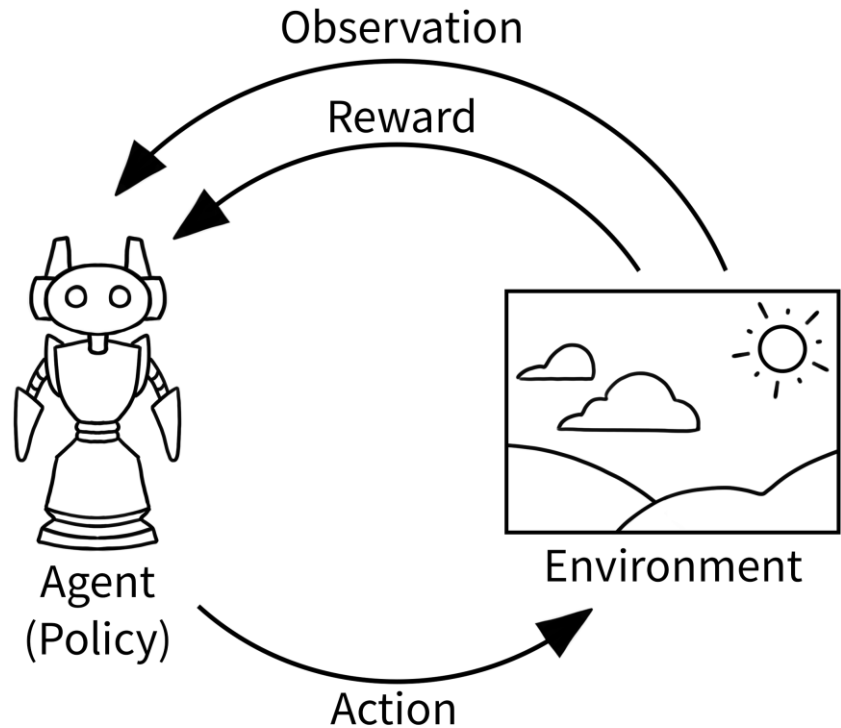


Optimization by differential evolution:

- **Evolutionary algorithms:** Generate child generations via mutation and recombination; selection based on fitness.
- Population-based, real-valued search without gradients
- **DE:** Offspring via weighted vector differences; selection by fitness
- Configuration aspects: Parent/child ratio, selection type / strategy, recombination method, mutation step-size control.
- Strong on noisy, discontinuous, high-dimensional problems

Reinforcement Learning

Connecting FMI with Reinforcement Learning Agents



Reinforcement learning (RL) as a type of machine learning:

- An **agent** interacts with its (simulated) **environment**
- The agent takes **actions** based on its current **policy** and **observations**
- The environment provides a **reward** based on its current state
- The (cumulative) reward is a metric to **optimize** the agent's policy
- While **training**, randomized actions for **exploration** can be selected
- Especially for **inference** the the experience gained is **exploited**

Feel free to reach out!



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