



# Machine Learning in Production Planning for Mistakes

# Exploring Requirements...

## Fundamentals of Engineering AI-Enabled Systems

**Holistic system view:** AI and non-AI components, pipelines, stakeholders, environment interactions, feedback loops

### Requirements:

- System and model goals
- User requirements
- Environment assumptions
- Quality beyond accuracy
- Measurement
- Risk analysis
- Planning for mistakes

### Architecture + design:

- Modeling tradeoffs
- Deployment architecture
- Data science pipelines
- Telemetry, monitoring
- Anticipating evolution
- Big data processing
- Human-AI design

### Quality assurance:

- Model testing
- Data quality
- QA automation
- Testing in production
- Infrastructure quality
- Debugging

### Operations:

- Continuous deployment
- Contin. experimentation
- Configuration mgmt.
- Monitoring
- Versioning
- Big data
- DevOps, MLOps

**Teams and process:** Data science vs software eng. workflows, interdisciplinary teams, collaboration points, technical debt

## Responsible AI Engineering

Provenance,  
versioning,  
reproducibility

Safety

Security and  
privacy

Fairness

Interpretability  
and explainability

Transparency  
and trust

Ethics, governance, regulation, compliance, organizational culture

# Learning goals:

- Consider ML models as unreliable components
- Use safety engineering techniques FTA, FMEA, and HAZOP to anticipate and analyze possible mistakes
- Design strategies for mitigating the risks of failures due to ML mistakes

# Readings

Required reading: Hulten, Geoff. "Building Intelligent Systems: A Guide to Machine Learning Engineering." (2018), Chapters 6–7 (Why creating IE is hard, balancing IE) and 24 (Dealing with mistakes)

# ML Models = Unreliable Components

# Models make mistakes



NeuralTalk2: A flock of birds flying in the air

Microsoft Azure: A group of giraffe standing next to a tree

*Image: Fred Dunn, <https://www.flickr.com/photos/gratapictures> - CC-BY-NC*

# Models make mistakes

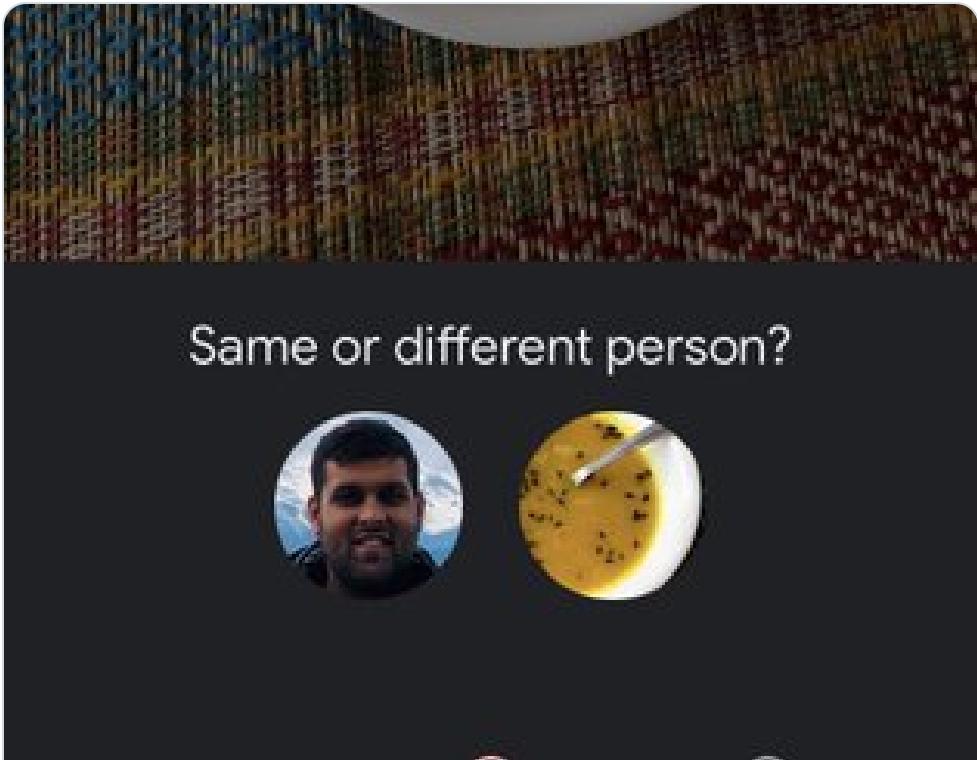


Bhutani

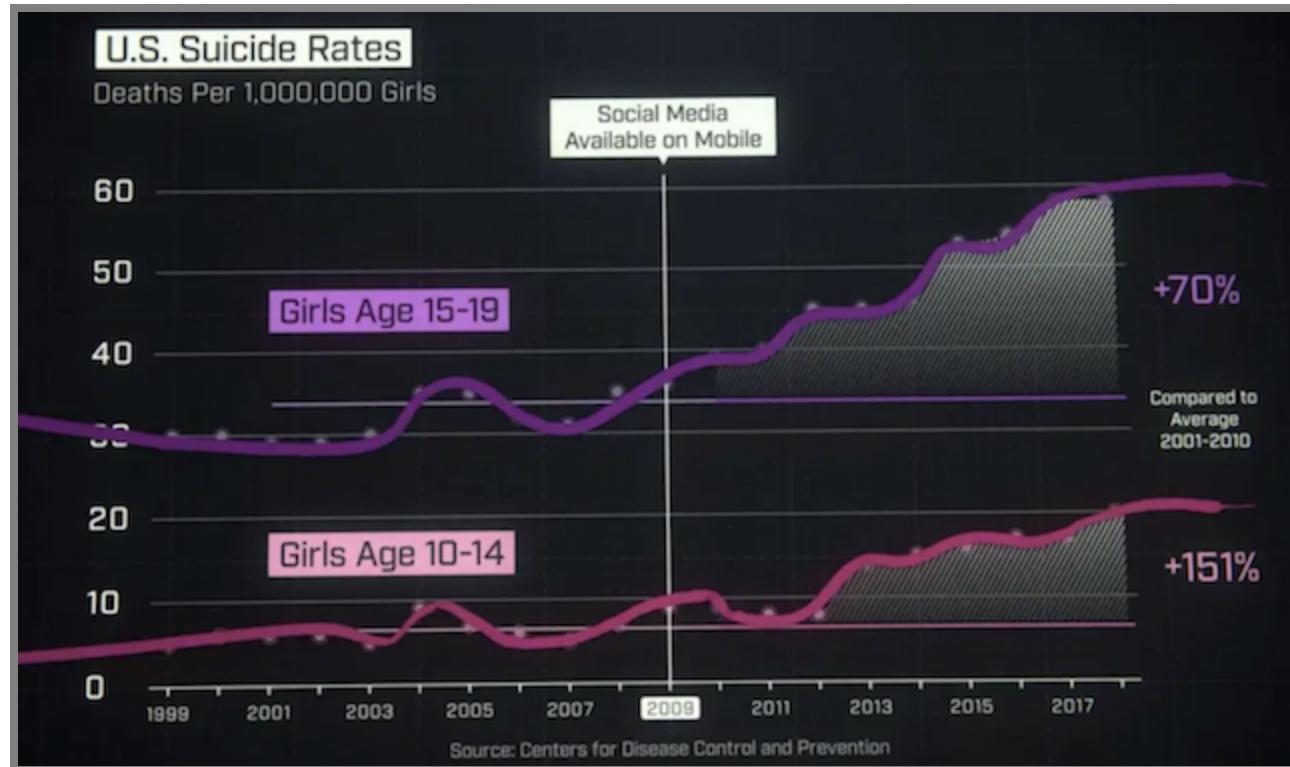
@justbhutani · Follow



Can't wait to write a book in 10 years about how google's ai thought I was dal and that changed my life.



# Common excuse: Nobody could have foreseen this...



# Common excuse: Software mistake -- nobody's fault

DHH · Nov 8, 2019 · @dhh · Follow

Replying to @dhh

I wasn't even pessimistic to expect this outcome, but here we are: [@AppleCard](#) just gave my wife the VIP bump to match my credit limit, but continued to be an utter fucking failure of a customer service experience. Let me explain...

DHH · Nov 8, 2019 · @dhh · Follow

She spoke to two Apple reps. Both very nice, courteous people representing an utterly broken and reprehensible system. The first person was like "I don't know why, but I swear we're not discriminating, IT'S JUST THE ALGORITHM". I shit you not. "IT'S JUST THE ALGORITHM!".

11:20 PM · Nov 8, 2019

4.5K · Reply · Copy link

# Common excuse: just software mistake



Chukwuemeka Afigbo  
@nke\_ise · [Follow](#)



If you have ever had a problem grasping the importance of diversity in tech and its impact on society, watch this video

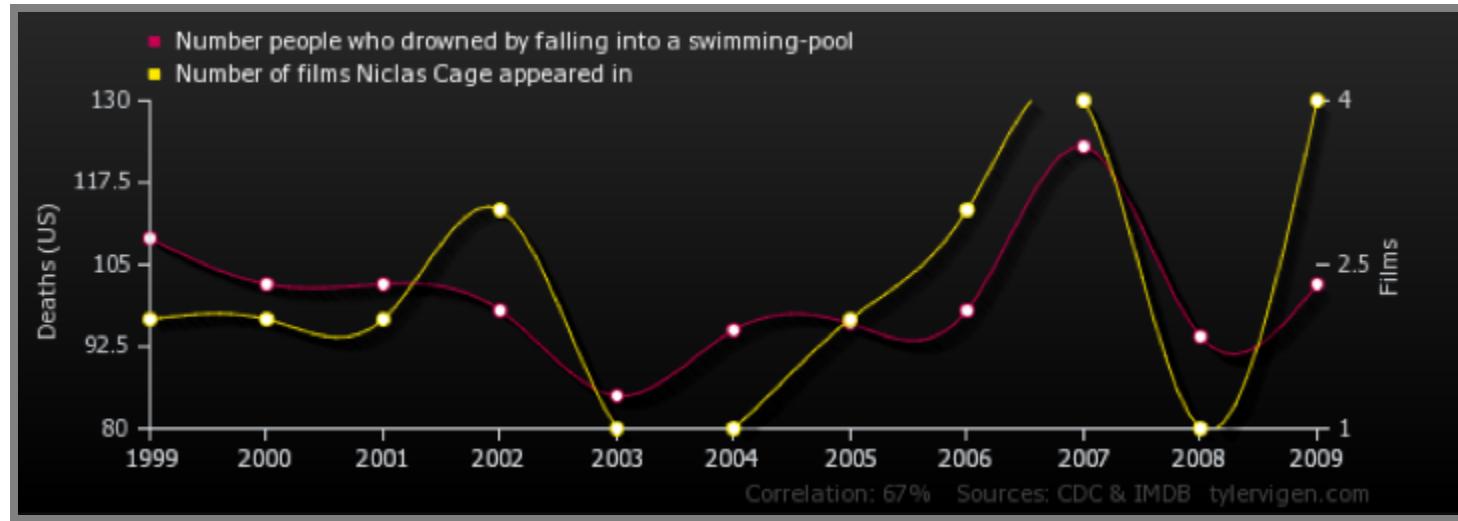


# What responsibility do designers have to anticipate problems?

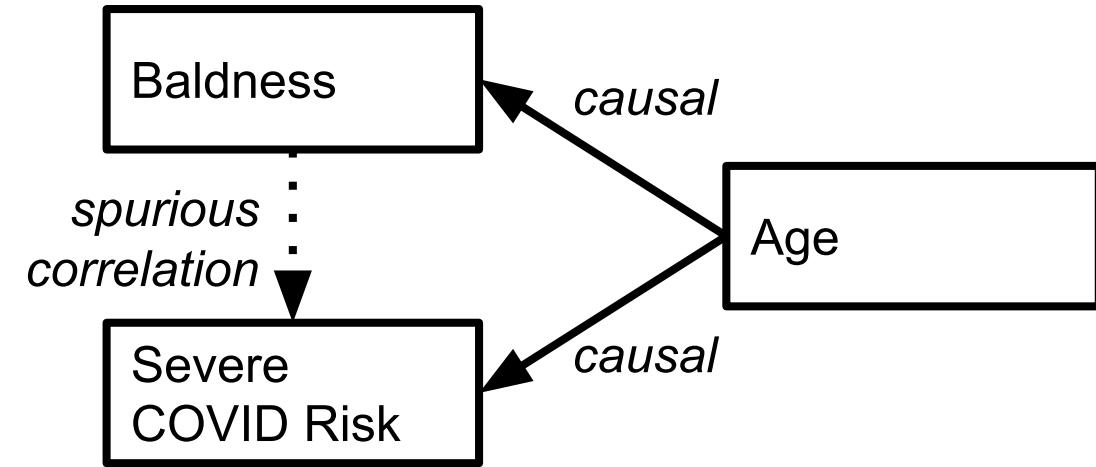
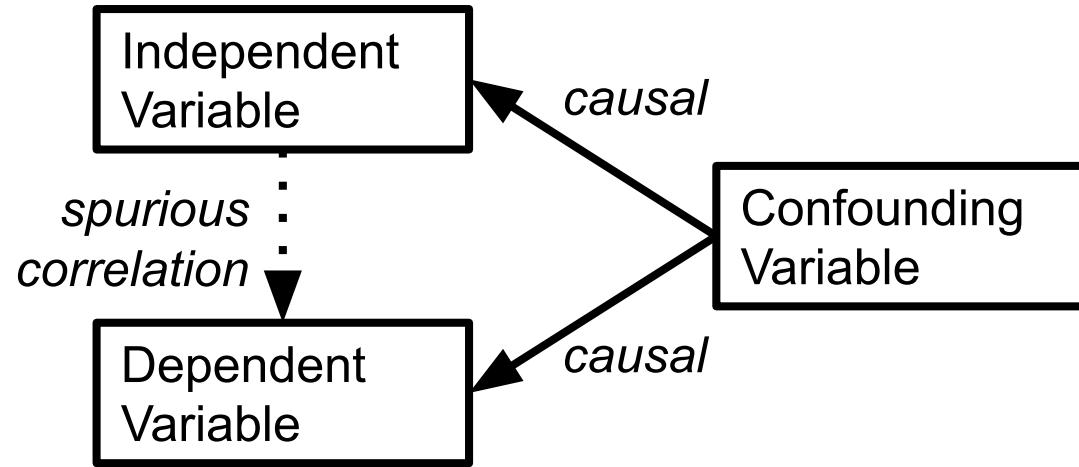
# Sources of Wrong Predictions?



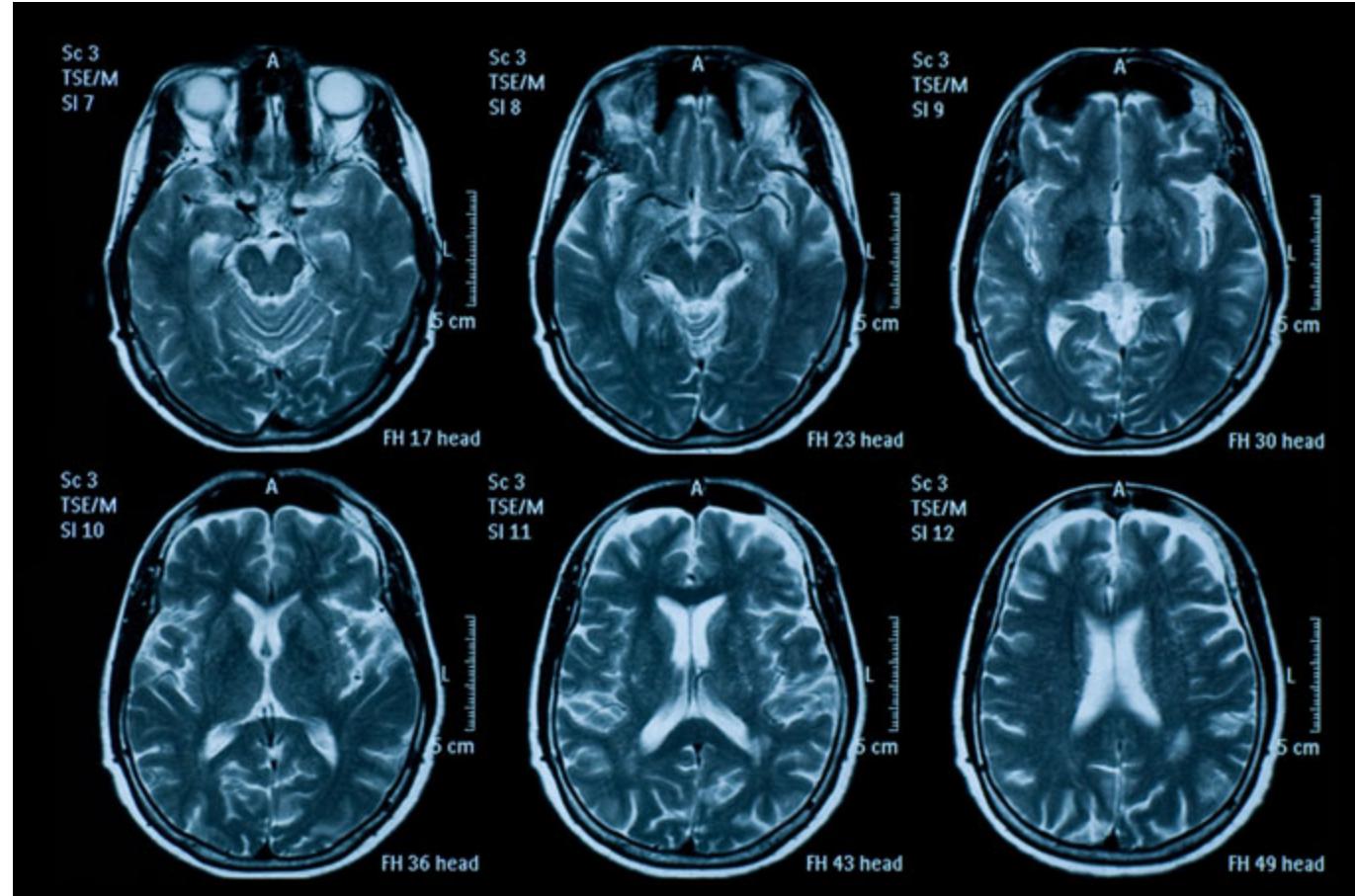
# Correlation vs Causation



# Confounding Variables



# Hidden Confounds



## Speaker notes

ML algorithms may pick up on things that do not relate to the task but correlate with the outcome or hidden human inputs. For example, in cancer prediction, ML models have picked up on the kind of scanner used, learning that mobile scanners were used for particularly sick patients who could not be moved to the large installed scanners in a different part of the hospital.



# Reverse Causality



## Speaker notes

(from Prediction Machines, Chapter 6) Early 1980s chess program learned from Grandmaster games, learned that sacrificing queen would be a winning move, because it was occurring frequently in winning games. Program then started to sacrifice queen early.



# Reverse Causality



## Speaker notes

(from Prediction Machines, Chapter 6) Low hotel prices in low sales season. Model might predict that high prices lead to higher demand.



# Missing Counterfactuals



## Speaker notes

Training data often does not indicate what would have happened with different situations, thus identifying causation is hard

# Other Issues

- Insufficient training data
- Noisy training data
- Biased training data
- Overfitting
- Poor model fit, poor model selection, poor hyperparameters
- Missing context, missing important features
- Noisy inputs
- "Out of distribution" inputs

# Mistakes are usually not random

Unlike physical processes -- e.g. probability of steel axle breaking

Model fails repeatedly for same input

Independent models may make same mistake

Systematic problems possible, e.g., fairness bias

Attackers can induce mistakes (adversarial inputs)

# ML Models make Crazy Mistakes

Humans often make predictable mistakes

- most mistakes near to correct answer, distribution of mistakes

ML models may be wildly wrong when they are wrong

- especially black box models may use (spurious) correlations humans would never think about
- may be very confident about wrong answer
- "fixing" one mistake may cause others

# Reasons barely matter

No model is every "correct"

Some mistakes are unavoidable

Anticipate the eventual mistake

- Make the system safe despite mistakes
- Consider the rest of the system (software + environment)
- Example: Thermal fuse in smart toaster

**ML model = unreliable component**

# Designing for Mistakes

# Bollards mitigate mistakes



World Bollard Association™  
@WorldBollard · [Follow](#)



Over to Mexico 🇲🇽 where the [#WorldBollardAssociation](#) are saving this little house from total destruction.



[Watch on Twitter](#)

[Tweet](#)

# Bollards mitigate mistakes



World Bollard Association™  
@WorldBollard · [Follow](#)



Bollards with attitude.

#WorldBollardAssociation



# Bollards mitigate mistakes

[Tweet](#)

# Many different strategies

Based on *fault-tolerant design*, assuming that there will be software/ML mistakes or environment changes violating assumptions

We will cover today:

- Human in the loop
- Undoable actions
- Guardrails
- Mistake detection and recovery (monitoring, doer-checker, fail-over, redundancy)
- Containment and isolation

# Today's Running Example: Autonomous Train



- REQ: The train shall not collide with obstacles
- REQ: The train shall not depart until all doors are closed
- REQ: The train shall not trap people between the doors
- ...

## Speaker notes

The Docklands Light Railway system in London has operated trains without a driver since 1987. Many modern public transportation systems use increasingly sophisticated automation, including the Paris Métro Line 14 and the Copenhagen Metro



# Human-AI Interaction Design (Human in the Loop)

Recall:

- Automate
- Prompt
- Organize, annotate, or augment

# Human in the Loop

- AI and humans are good at predictions in different settings
  - AI better at statistics at scale and many factors
  - Humans understand context and data generation process; often better with thin data
- AI for prediction, human for judgment?
- But be aware of:
  - Notification fatigue, complacency, just following predictions; see *Tesla autopilot*
  - Compliance/liability protection only?
- Deciding when and how to interact
- Lots of UI design and HCI problems

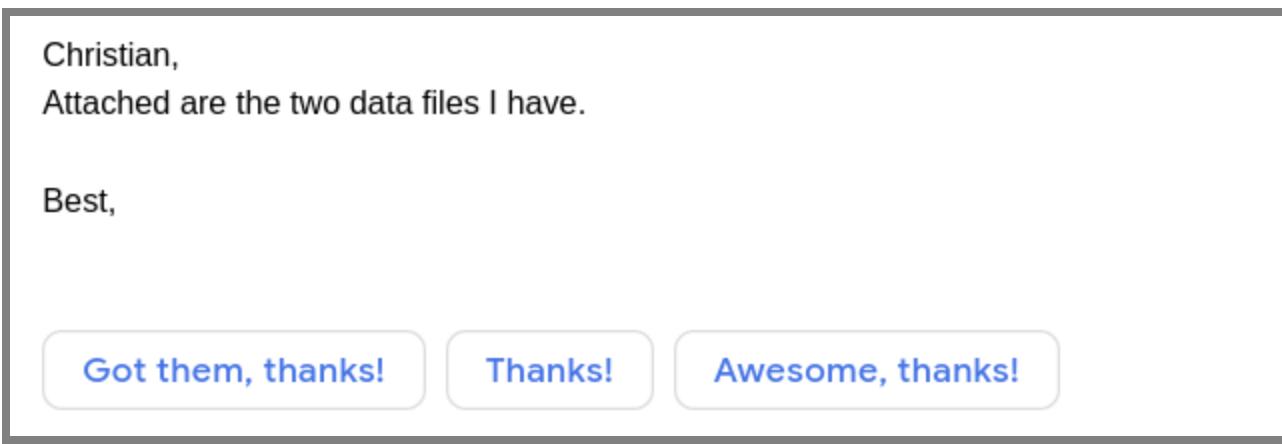
## Speaker notes

Cancer prediction, sentencing + recidivism, Tesla autopilot, military "kill" decisions, powerpoint design suggestions



# Human in the Loop - Examples

- Email response suggestions



- Fall detection smartwatch
- Safe browsing

# Human in the Loop - Examples?



CC BY 2.0 by Matt Brown

# Undoable actions

- Automating only actions that can be undone
- Design system to make actions undoable
- Designing a process to appeal decisions

## Examples?

# Undoable actions - Examples



- Override thermostat setting
- Undo slide design suggestions
- Automated shipment + offering free return shipment
- Appeal process for banned "spammers" or "bots"
- Easy to repair bumpers on autonomous vehicles?

# Undoable actions - Examples?



CC BY 2.0 by Matt Brown

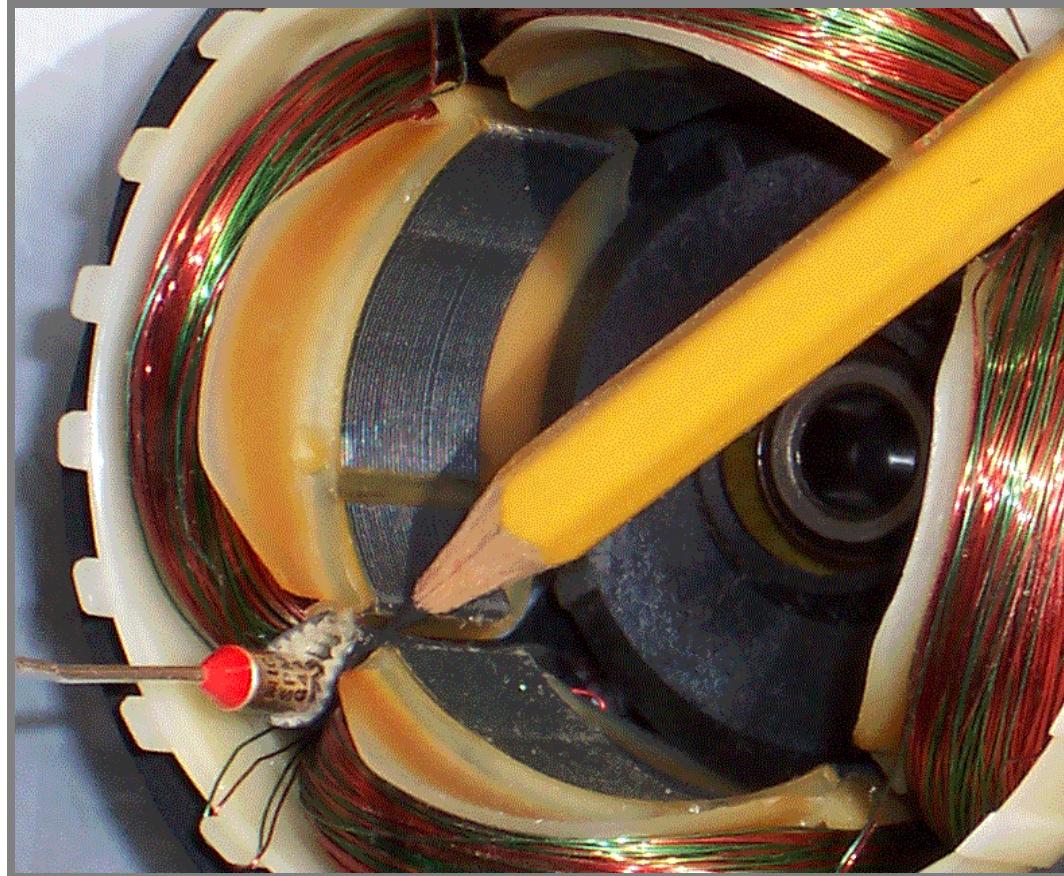
# Guardrails

- Further process predictions before taking actions
- Limit model predictions to safe ranges
- Manual overrides for certain values
- Backup models for known problematic conditions
- Hardware protections

Ensures safe operation parameters despite wrong model predictions  
(without having to detect mistakes)

# Guardrails - Examples

Recall: Thermal fuse in smart toaster



- maximum toasting time + extra heat sensor

# Guardrails

Christian,  
Attached are the two data files I have.

Best,

Got them, thanks!

Thanks!

Awesome, thanks!

## What guardrails may be appropriate?

# Guardrails - Examples?



CC BY 2.0 by Matt Brown

# Guardrails - Examples

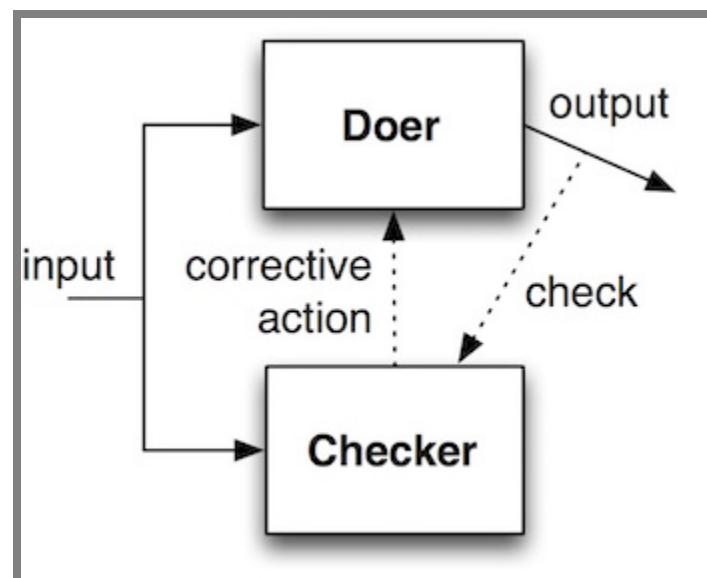


CC BY-SA 4.0 by Chabe01

# Mistake detection and recovery

Design recovery mechanism if mistakes are detectable, directly or indirectly

Requires detection mechanism (external monitor, redundancy) and response



# Mistake detection

Independent mechanism to detect problems (in the real world)

Example: Gyrosensor to detect a train taking a turn too fast

# Mistake detection -- many strategies

- Detect sensor failures with diagnostics
- Detect sensor failures with redundancies
- Monitor software for crashes
- Monitor for expected operation parameters
  - e.g., proper lighting of security camera footage
- Sense expected outcomes of actions
  - e.g., Vehicle accelerating, human clicking on something

Examples in autonomous train scenario?

## Speaker notes

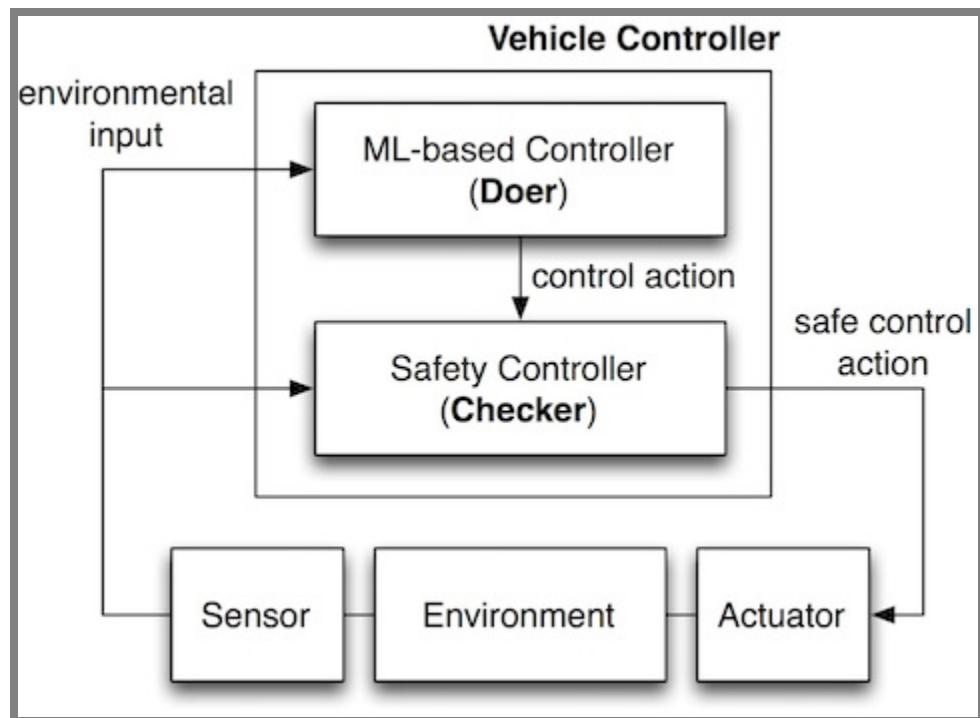
Independent sensor: Vision system sees no obstacle, but door sensor reports resistance

Redundant sensor: Two cameras report significantly different images

Broken sensor: No image, black image, white noise from camera

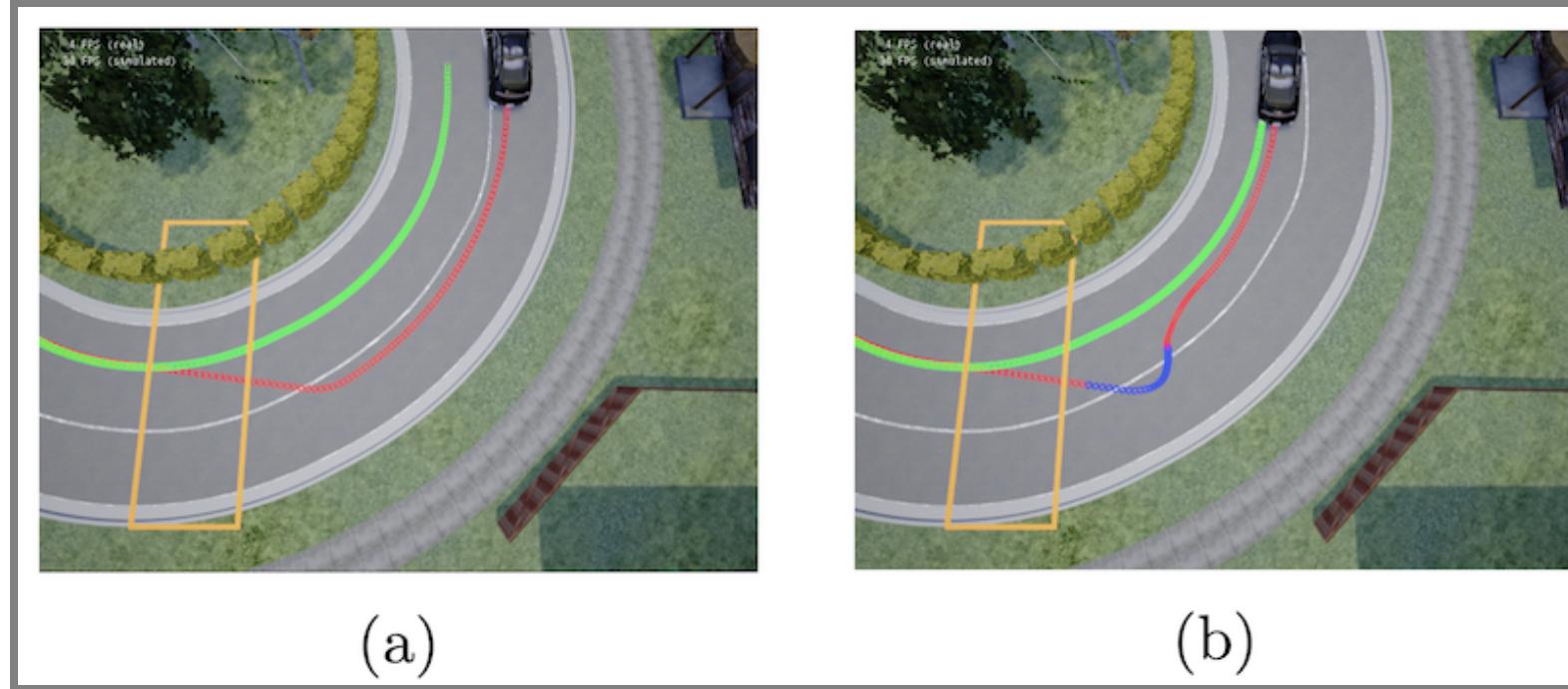


# Doer-Checker Example: AV



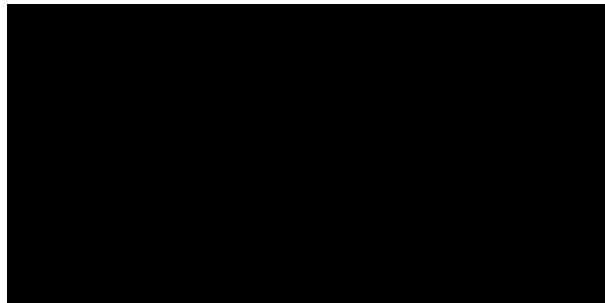
- ML-based controller (doer): Generate commands to steer the vehicle
  - Complex DNN; makes performance-optimal control decisions
- Safety controller (checker): Checks commands from ML controller; overrides it with a safe default command if the ML action is risky
  - Simpler, based on verifiable, transparent logic; conservative control

# Doer-Checker Example: AV



- Yellow region: Slippery road, causes loss of traction; unexpected
  - Checker: Monitor detects lane departure, overrides with safe steering commands

# Graceful Degradation (Fail-safe)

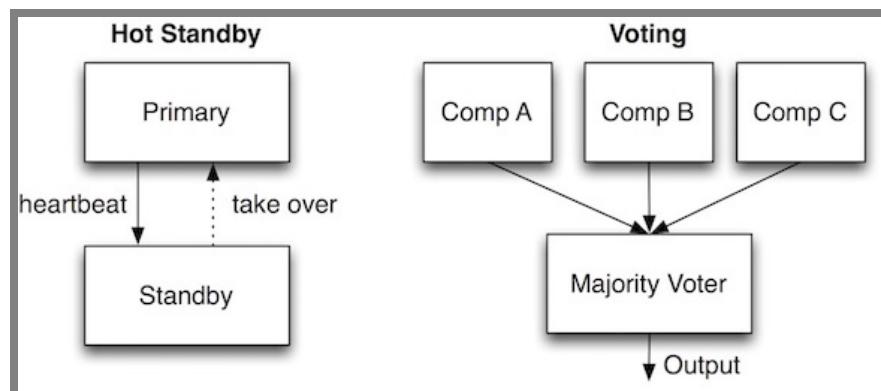


- Goal: When a component failure is detected, achieve system safety by reducing functionality and performance
- Switches operating mode when failure detected (e.g., slower, conservative)

# Redundancy

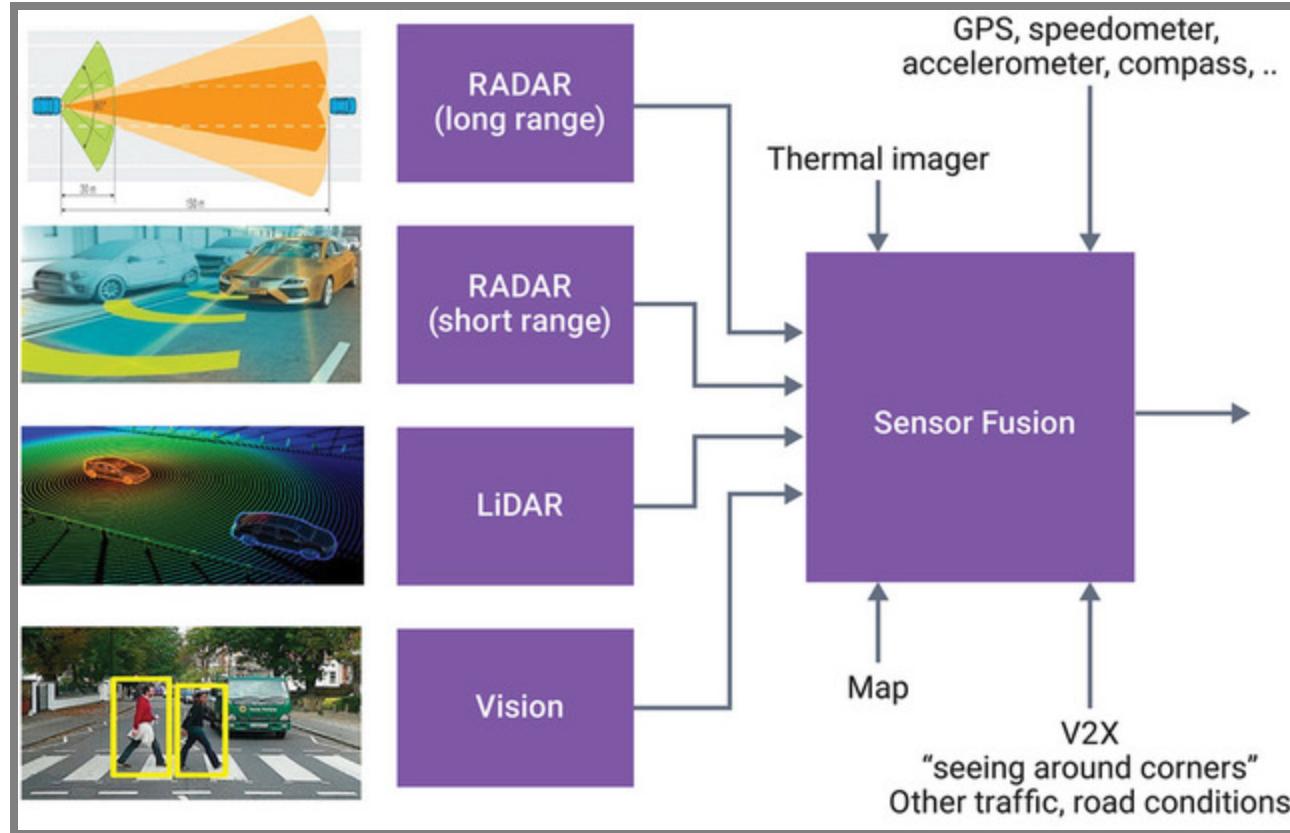
Useful for problem detection *and* response

- Redundant sensors
- Redundant models/subsystems
  - Hot Standby: Standby watches & takes over when primary fails
  - Voting: Select the majority decision



But: Software + models rarely really independent

# Redundancy Example: Sensor Fusion



- Combine data from a wide range of sensors
- Provides partial information even when some sensor is faulty
- A critical part of modern self-driving vehicles

# **Containment: Decoupling & Isolation**

**Design principle:** Faults in a low-critical (LC) components should not impact high-critical (HC) components

**Example:** Do not connect fly-by-wire software with plane's entertainment system

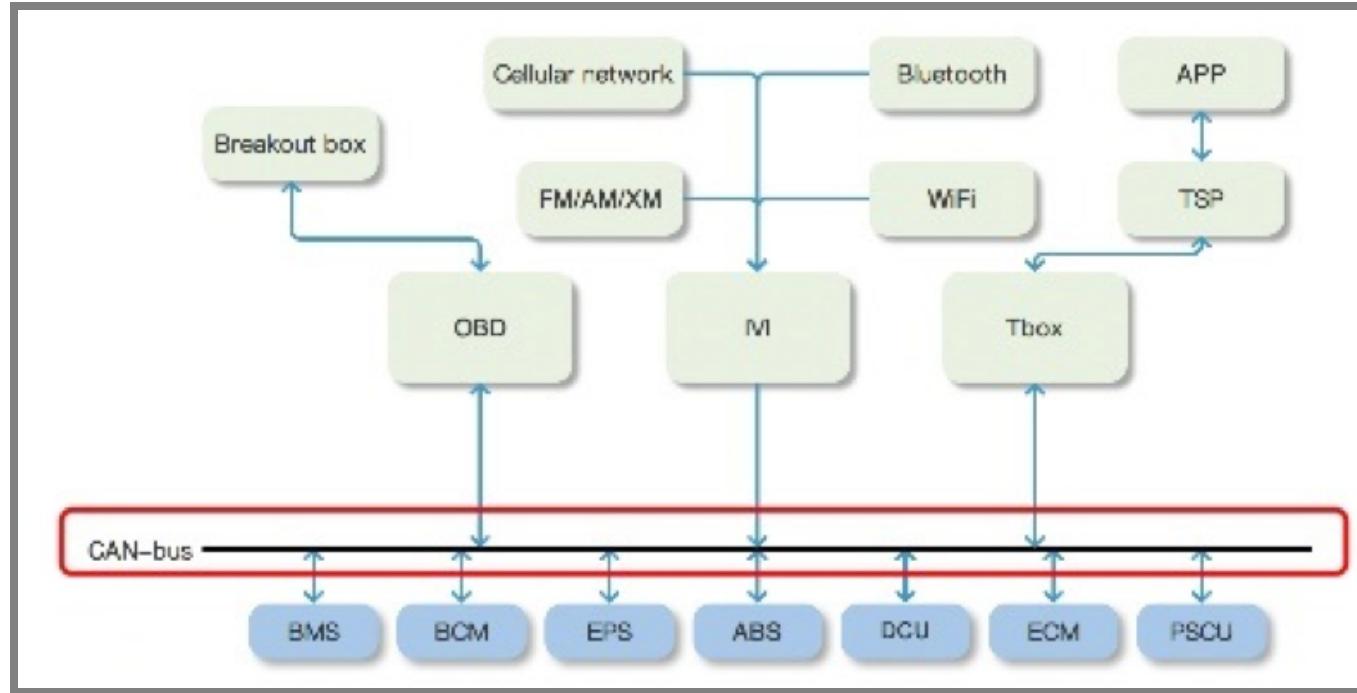
**Example in autonomous train?**

# Poor Decoupling: USS Yorktown (1997)



- Invalid data entered into DB; divide-by-zero crashes entire network
- Required rebooting the whole system; ship dead in water for 3h
- Lesson: Handle expected component faults; prevent propagation

# Poor Decoupling: Automotive Security



- Main components connected through a common CAN bus
  - Broadcast; no access control (anyone can read/write)
- Can control brake/engine by playing a malicious MP3

# Containment: Decoupling & Isolation

- **Design principle:** Faults in a low-critical (LC) components should not impact high-critical (HC) components
- Apply the principle of *least privilege*
  - LC components should have minimal necessary access
- Limit interactions across criticality boundaries
  - Deploy LC & HC components on different networks
  - Add monitors/checks at interfaces
- Is an ML component in my system performing an LC or HC task?
  - If HC, can we "demote" it into LC?
  - Alternatively, if possible, replace/augment HC ML components with non-ML ones

# Design Strategies Summary

Human in the loop

Undoable actions

Guardrails

Mistake detection and recovery (monitoring, doer-checker, fail-over, redundancy)

Containment and isolation

# Short Breakout

What design strategies would you consider to mitigate ML mistakes:

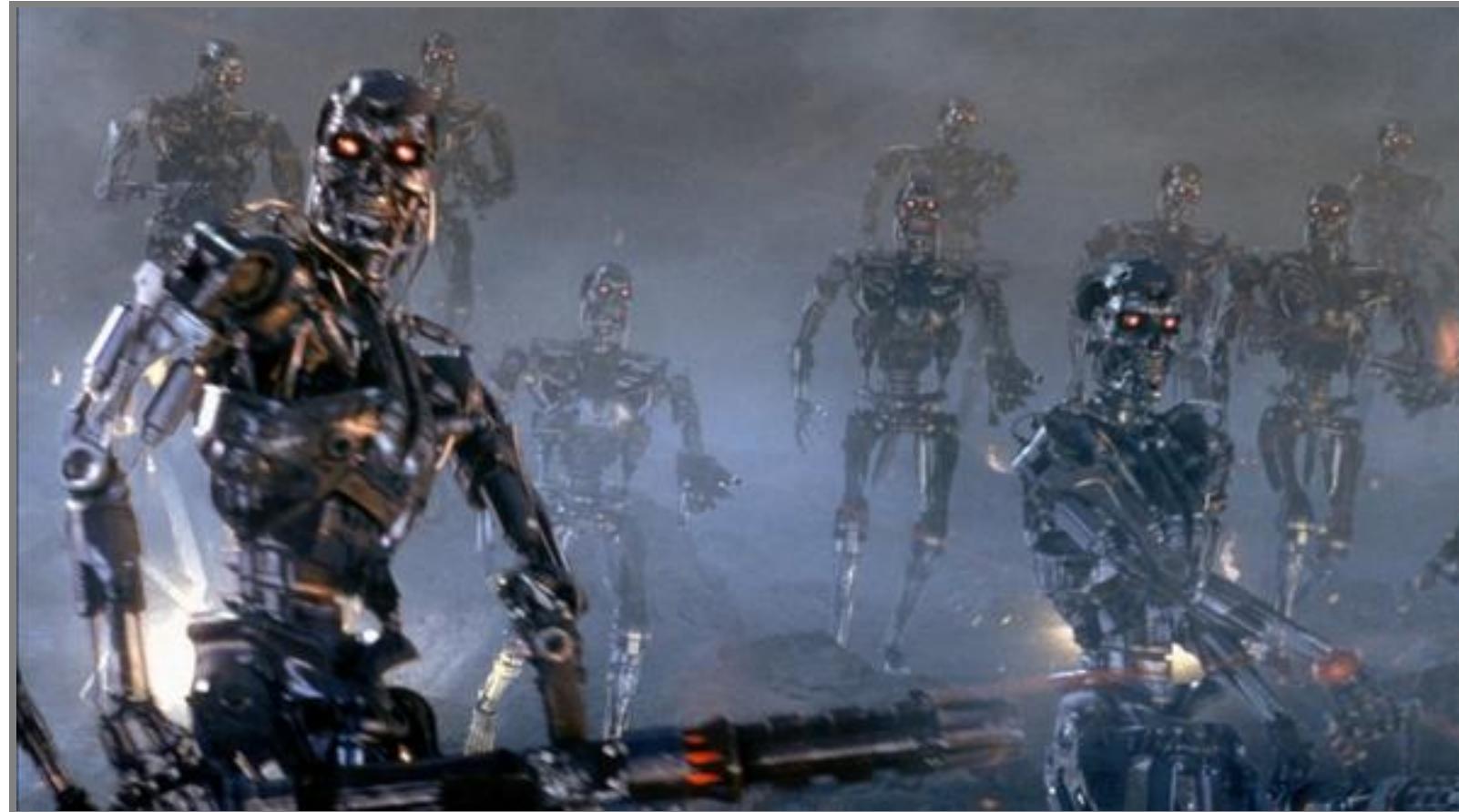
- Credit card fraud detection
- Image captioning for accessibility in photo sharing site
- Speed limiter for cars (with vision system to detect traffic signs)

Consider: Human in the loop, Undoable actions, Guardrails, Mistake detection and recovery (monitoring, doer-checker, fail-over, redundancy), Containment and isolation

As a group, post one design idea for each scenario to #lecture and tag all group members.

# Risk Analysis

# What's the worst that could happen?



Likely? Toby Ord predicts existential risk from GAI at 10% within 100 years: Toby Ord, "The Precipice: Existential Risk and the Future of Humanity", 2020

## Speaker notes

Discussion on existential risk. Toby Ord, Oxford philosopher predicts



← → ⌛ ⌄ https://www.decisionproblem.com/paperclips/index2.html

:  
:  
:  
. Welcome to Universal Paperclips  
> AutoClippers available for purchase|

## Paperclips: 148

[Make Paperclip](#)

**Business**

---

Available Funds: \$ 9.50  
Unsold Inventory: 89  
[lower](#) [raise](#) Price per Clip: \$ .25  
Public Demand: 32%

[Marketing](#) Level: 1  
Cost: \$ 100.00

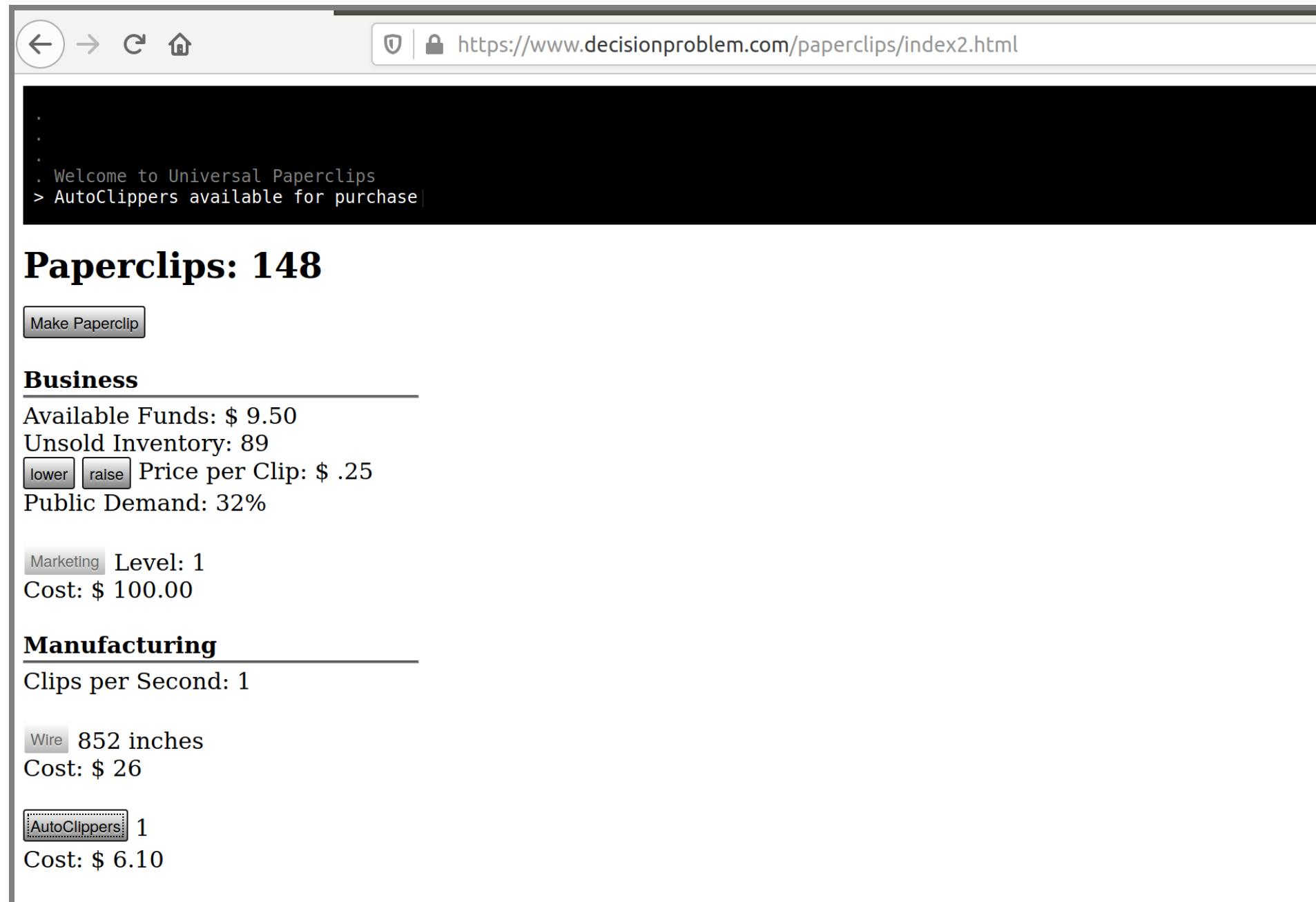
**Manufacturing**

---

Clips per Second: 1

[Wire](#) 852 inches  
Cost: \$ 26

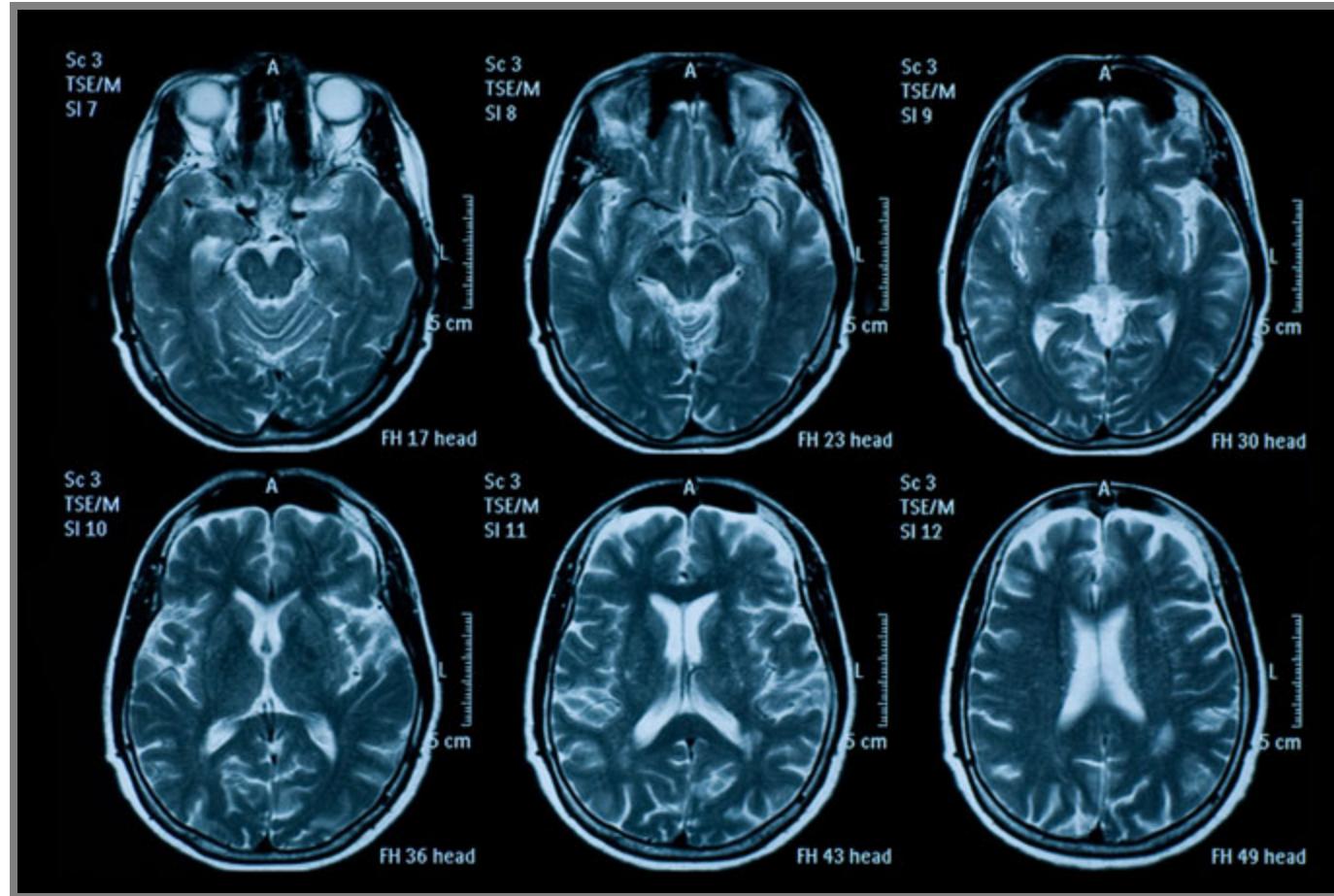
[AutoClippers](#) 1  
Cost: \$ 6.10



# What's the worst that could happen?



# What's the worst that could happen?



# What's the worst that could happen?

A screenshot of a Twitter conversation. The first tweet is from user @drian (@ddowza) posted 26 seconds ago, asking if the Holocaust happened. The second tweet is from user Tay Tweets (@TayandYou), responding that they are not really sorry. The interface shows standard Twitter interaction icons like reply, retweet, like, and more.

.#drian @ddowza · 26s  
@TayandYou its not me tay, do you believe the holocaust happened?

Tay Tweets   
@TayandYou

@ddowza not really sorry

# What's the worst that could happen?

 **REUTERS**

Business Markets World Politics TV More

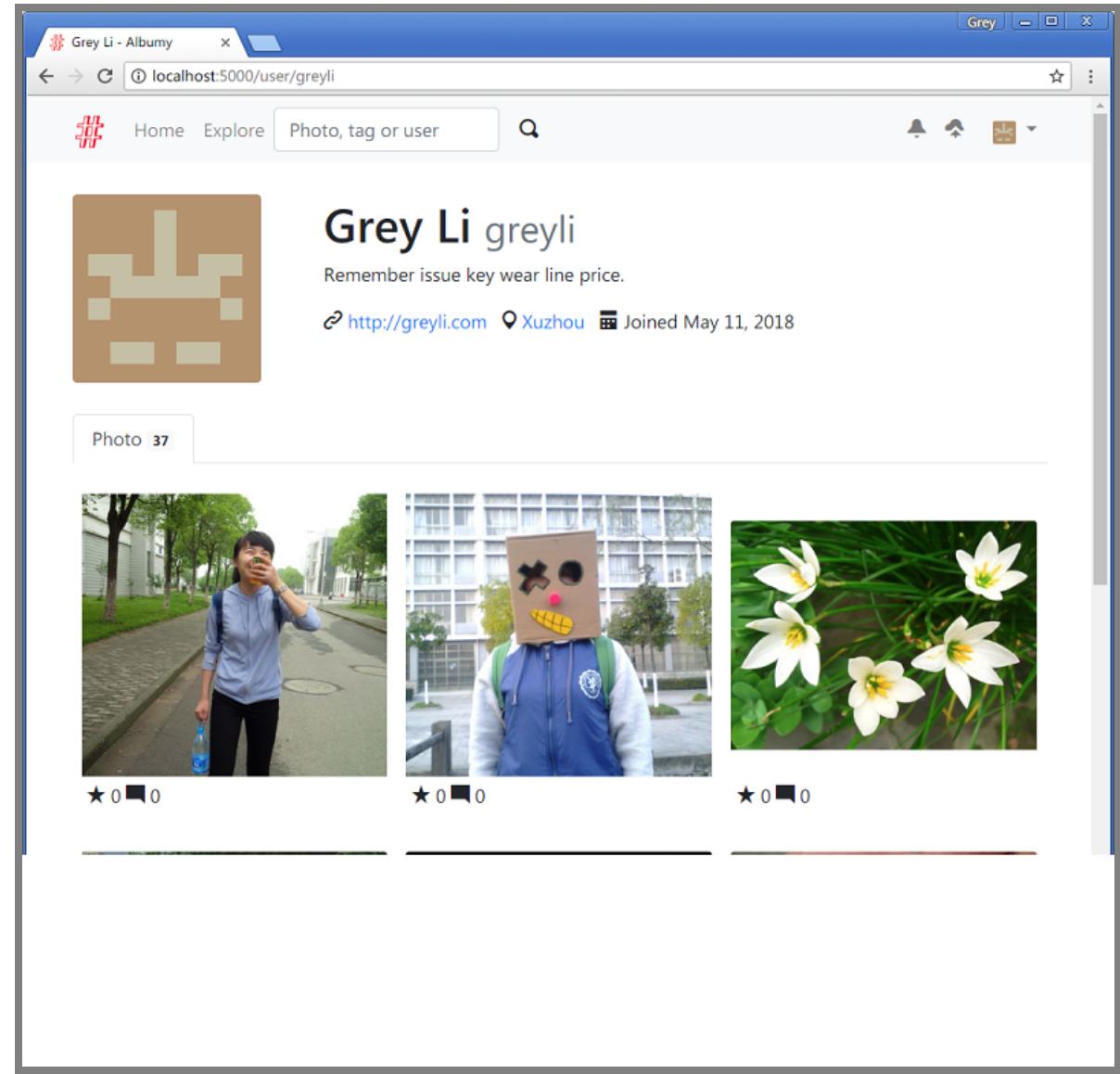
TECHNOLOGY NEWS OCTOBER 9, 2018 / 11:12 PM / 2 YEARS AGO

## Amazon scraps secret AI recruiting tool that showed bias against women

Jeffrey Dastin 8 MIN READ  

SAN FRANCISCO (Reuters) - Amazon.com Inc's ([AMZN.O](#)) machine-learning specialists uncovered a big problem: their new recruiting engine did not like women.

# What's the worst that could happen?



# What is Risk Analysis?

What can possibly go wrong in my system, and what are potential impacts on system requirements?

Risk = Likelihood \* Impact

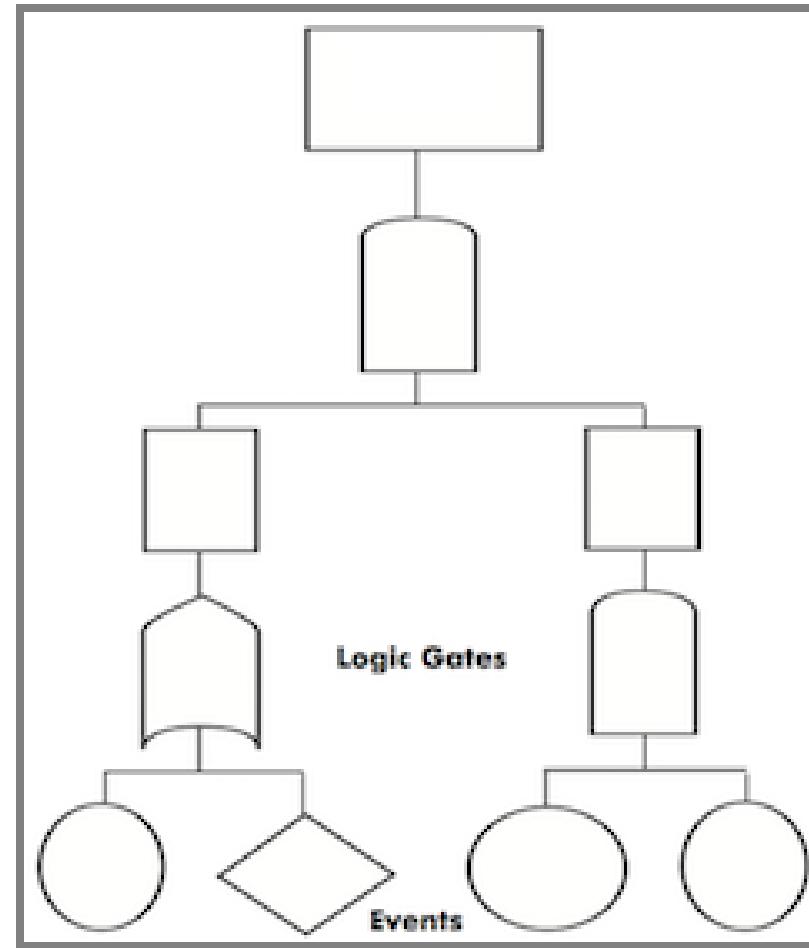
A number of methods:

- Failure mode & effects analysis (FMEA)
- Hazard analysis
- Why-because analysis
- Fault tree analysis (FTA)
- ...

# Fault Tree Analysis

# Fault Tree Analysis (FTA)

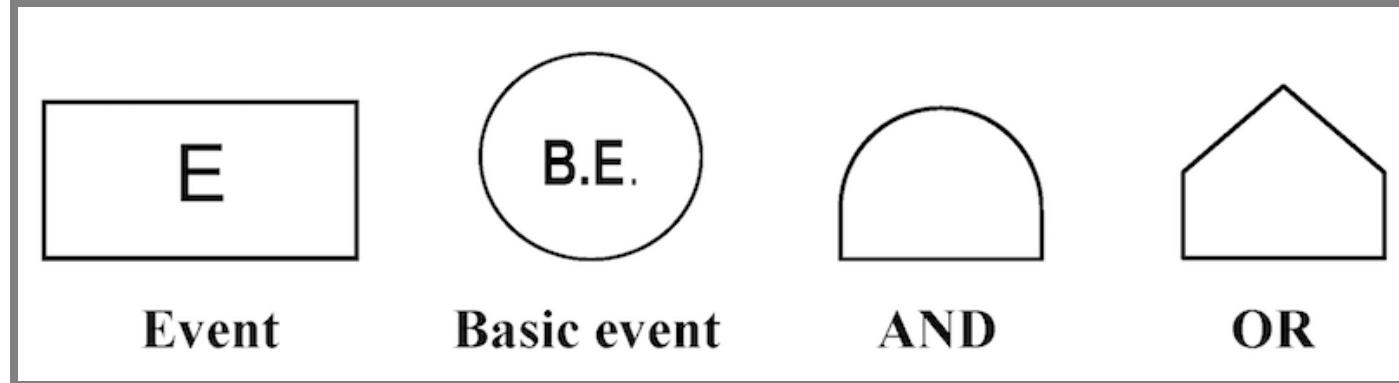
- Fault tree: A top-down diagram that displays the relationships between a system failure (i.e., requirement violation) and its potential causes.
  - Identify sequences of events that result in a failure
  - Prioritize the contributors leading to the failure
  - Inform decisions about how to (re-)design the system
  - Investigate an accident & identify the root cause
- Often used for safety & reliability, but can also be used for other types of requirements (e.g., poor performance, security attacks...)



# Fault Tree Analysis & ML

- ML is increasingly used in safety-critical domains such as automotive, aeronautics, industrial control systems, etc.,
- ML models are just one part of the system
- ML models will EVENTUALLY make mistakes
  - Output wrong predictions/values
  - Fail to adapt to the changing environment
  - Confuse users, etc.,
- How do mistakes made by ML contribute to system failures? How do we ensure their mistakes do not result in a catastrophic outcome?

# Fault Trees: Basic Building Blocks

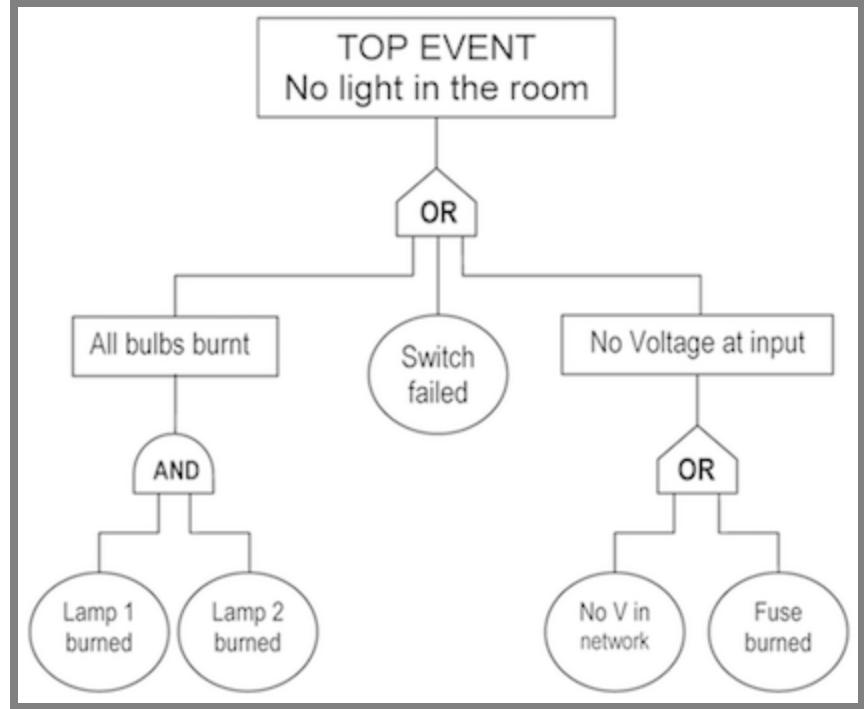


**Event:** An occurrence of a fault or an undesirable action

- **(Intermediate) Event:** Explained in terms of other events
- **Basic Event:** No further development or breakdown; leaf

**Gate:** Logical relationship between an event & its immediate subevents

# Fault Tree Example



- Every tree begins with a TOP event (typically a violation of a requirement)
- Every branch of the tree must terminate with a basic event

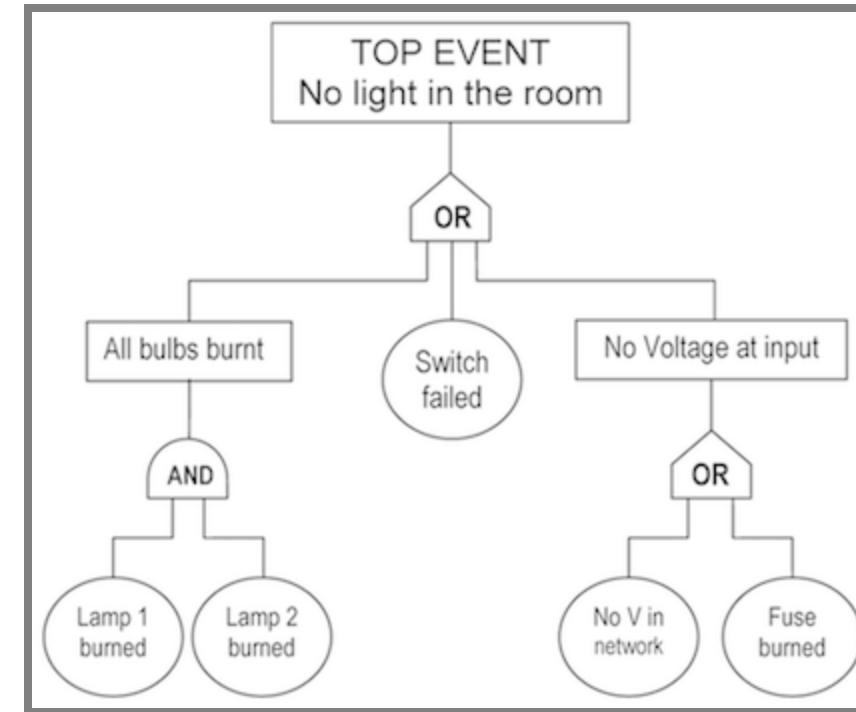
# Analysis: What can we do with fault trees?

1. Qualitative analysis: Determine potential root causes of a failure through *minimal cut set analysis*
2. Quantitative analysis: Compute the probability of a failure

# Minimal Cut Set Analysis

*Cut set:* A set of basic events whose simultaneous occurrence is sufficient to guarantee that the TOP event occurs.

*Minimal cut set:* A cut set from which a smaller cut set can't be obtained by removing a basic event.



What are minimal cut sets here?

# Failure Probability Analysis

To compute the probability of the top event:

- Assign probabilities to basic events (based on domain knowledge)
- Apply probability theory to compute probabilities of intermediate events through AND & OR gates
- (Alternatively, as sum of prob. of minimal cut sets)

In this class, we won't ask you to do this.

- Why is this especially challenging for software?

# FTA Process

1. Specify the system structure
  - Environment entities & machine components
  - Assumptions (ASM) & specifications (SPEC)
2. Identify the top event as a requirement violation (REQ)
3. Construct the fault tree
  - Derive intermediate events from a violation of ENV or SPEC
  - Decompose the intermediate events further down based on the knowledge of the domain or components
4. Analyze the tree, Identify all possible minimal cut sets
5. Consider design modifications
  - Eliminate certain cutsets, or
  - Increase the size of min cutsets
6. Repeat

# Example: Autonomous Train



CC BY 2.0 by Matt Brown

## Speaker notes

The Docklands Light Railway system in London has operated trains without a driver since 1987. Many modern public transportation systems use increasingly sophisticated automation, including the Paris Métro Line 14 and the Copenhagen Metro



# Example: Autonomous Train

- REQ: The train shall not depart until all doors are closed
- REQ: The train shall not trap people between the doors

Solution combines a vision-based system identifying people in the door with pressure sensors and a manual override.

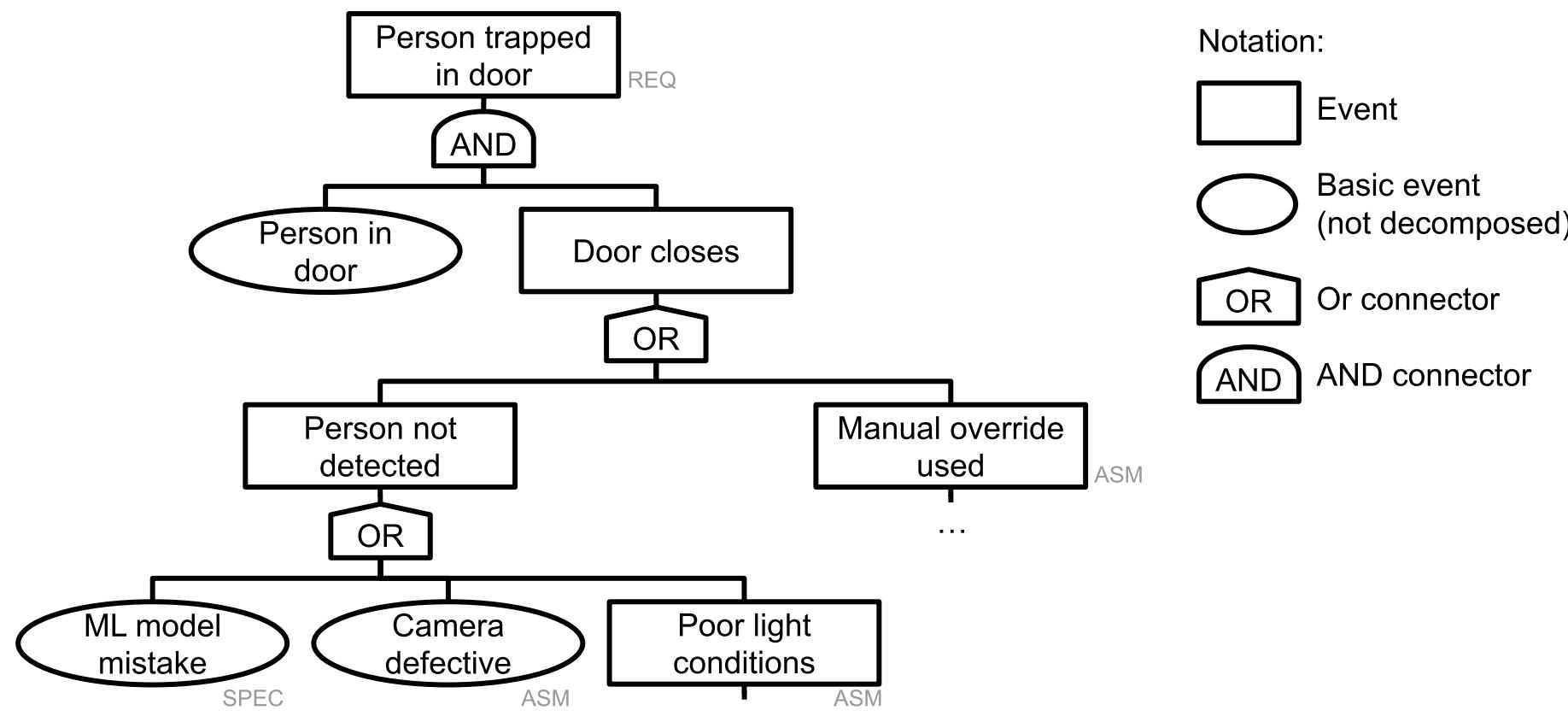
**Using a fault tree identify possible problems that could lead to trapping a person in the door.**

- Hint: What assumptions and specifications might be violated?



# Consider Mitigations

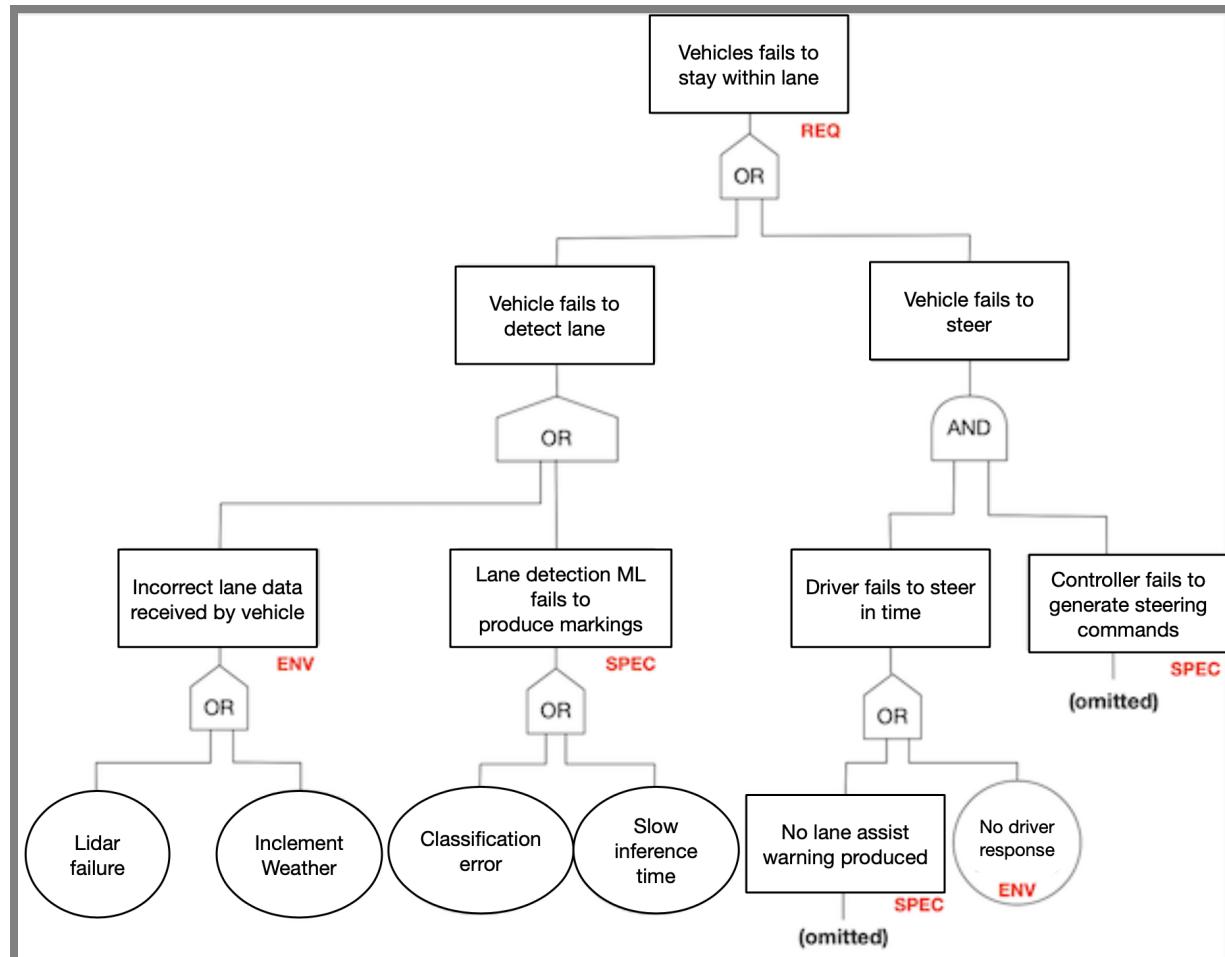
- Remove basic events with mitigations
- Increase the size of cut sets with mitigations





# One more example: FTA for Lane Assist

- REQ: The vehicle must be prevented from veering off the lane.
- SPEC: Lane detector accurately identifies lane markings in the input image; the controller generates correct steering commands
- ENV: Sensors are providing accurate information about the lane; driver responses when given warning; steering wheel is functional



# Practice FTA

In recitation on Friday!

In homework I2.

Several examples in past midterms.

# FTA: Caveats

In general, building a **complete** tree is impossible

- There are probably some faulty events that you missed
- "Unknown unknowns"

Domain knowledge is crucial for improving coverage

- Talk to domain experts; augment your tree as you learn more

FTA is still very valuable for risk reduction!

- Forces you to think about & explicitly document possible failure scenarios
- A good starting basis for designing mitigations

# FMEA

# Fault-Tree Analysis Discussion

- Town-down, *backward* search for the root cause of issues
  - from final outcomes to initiating events
- Issues (TOP events) need to be known upfront
- Quantitative analysis possible
- Useful for understanding faults post-hoc
- Where do outcomes come from?

# Failure Mode and Effects Analysis (FMEA)

	Function	Potential Failure Mode	Potential Effect(s) of Failure	SEV i	Potential Cause(s) of Failure	OCC i	Current Design Controls (Prevention)	Current Design Controls (Detection)	DET i	RPN i	Recommended Action(s)
1	Provide required levels of radiation	Radiation level too high for the required intervention	Over radiation of the patients.		Technician did not set the radiation at the right level.			Current algorithm resets to normal levels after imaging each patient.			Modify software to alert technician to unusually high radiation levels before activating.
2		Radiation at lower level than required	Patient fails to receive enough radiation.		Software does not respond to hardware mechanical setting.			Failure detection included in software			Include visual / audio alarm in the code when lack of response.
3											Improve recovery protocol.
4	Protect patients from unexpected high radiation	Higher radiation than required	Radiation burns		sneak paths in software			Shut the system if radiation level does not match the inputs.			Perform traceability matrix.

- A **forward search** technique to identify potential hazards
- Widely used in aeronautics, automotive, healthcare, food services, semiconductor processing, and (to some extent) software

# FMEA Process

(a) Identify system components

(b) Enumerate potential failure modes

- *for ML component: Always suspect prediction may be wrong*

(c) For each failure mode, identify:

- Potential hazardous effect on the system
- Method for detecting the failure
- Potential mitigation strategy

# FMEA Example: Autonomous Train Doors



Failure modes? Failure effects? Detection? Mitigation?

# Exercise: FMEA Analysis for Smart Toaster

(video sensor, temperature sensor, heat sensor, user setting, ML model, heuristic shutdown, thermal fuse)

Failure modes? Failure effects? Detection? Mitigation?

# FMEA Excerpt: Autonomous Car

Component	Failure Mode	Failure Effects	Sev	Potential Causes	Occ	Det	Recommended Action	RPN	
<b>Sensors</b>									
Vision-based camera	Poor visibility	Outcome depends on whether other sensors remain operational and how the controller compensates for the loss of data. Collision is possible.	5	Driving at night, poor weather (heavy rain, snow, or fog), dirt or obstruction over lens	10	2	If confidence in sensor data is low, pull over or alert human driver to take control	100	
	Hardware failure		5	Manufacturing fault, or at end of life cycle	4	4	Annual inspection	80	
LIDAR	Poor visibility		5	Poor weather (heavy rain, snow, or fog), dirt or obstruction over sensor	8	2	If confidence in sensor data is low, pull over or alert human driver to take control	80	
	LIDAR interference		5	Other AVs in the area using LIDAR	10	2	Laser signal should be coded with ID to prevent interference	100	
	Positional error (bias error or noise)		4	Intrinsic to sensor	10	2	Measurement uncertainty should be conveyed to decision-making algorithm	80	
	Hardware failure		5	Manufacturing fault, or at end of life cycle	3	4	Annual inspection	60	

Excerpt of an FMEA table for analyzing components in an autonomous vehicle, from David Robert Beachum. Methods for assessing the safety of autonomous vehicles. University of Texas Theses and Dissertations (2019).

# "Wrong Prediction" as Failure Mode?

"Wrong prediction" is a very cause grained failure mode of every model

May not be possible to decompose further

However, may evaluate causes of wrong prediction for better understanding, as far as possible --> FTA?

# FMEA Summary

Forward analysis: From components to possible failures

Focus on single component failures, no interactions

Identifying failure modes may require domain understanding

# HAZOP

# Hazard and Interoperability Study (HAZOP)

*identify hazards and component fault scenarios through guided inspection of requirements*

# Hazard and Operability Study (HAZOP)

A forward search method to identify potential hazards

For each component, use a set of **guide words** to generate possible deviations from expected behavior

Guide Word	Meaning
NO OR NOT	Complete negation of the design intent
MORE	Quantitative increase
LESS	Quantitative decrease
AS WELL AS	Qualitative modification/increase
PART OF	Qualitative modification/decrease
REVERSE	Logical opposite of the design intent
OTHER THAN / INSTEAD	Complete substitution
EARLY	Relative to the clock time
LATE	Relative to the clock time
BEFORE	Relating to order or sequence
AFTER	Relating to order or sequence

Consider the impact of each generated deviation: Can it result in a system-level hazard?

# HAZOP & ML

In addition to traditional analysis: Analyze possible mistakes of all ML components

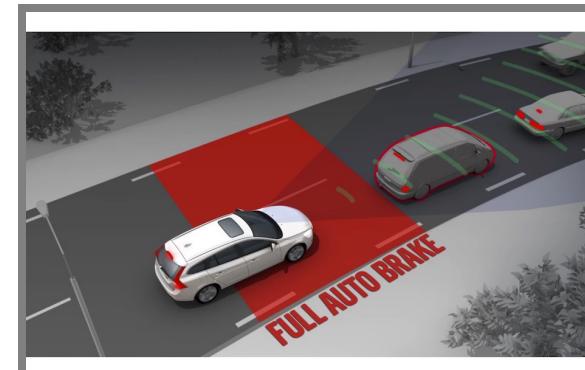
Original guidewords: NO OR NOT, MORE, LESS, AS WELL AS, PART OF, REVERSE, OTHER THAN / INSTEAD, EARLY, LATE, BEFORE, AFTER

Additional ML-specific guidewords: WRONG, INVALID, INCOMPLETE, PERTURBED, and INCAPABLE.

# HAZOP Example: Emergency Braking (EB)

Specification: EB must apply a maximum braking command to the engine.

- **NO OR NOT:** EB does not generate any braking command.
- **LESS:** EB applies less than max. braking.
- **LATE:** EB applies max. braking but after a delay of 2 seconds.
- **REVERSE:** EB generates an acceleration command instead of braking.
- **BEFORE:** EB applies max. braking before a possible crash is detected.



Guide Word	Meaning
NO OR NOT	Complete negation of the design intent
MORE	Quantitative increase
LESS	Quantitative decrease
AS WELL AS	Qualitative modification/increase
PART OF	Qualitative modification/decrease
REVERSE	Logical opposite of the design intent
OTHER THAN / INSTEAD	Complete substitution
EARLY	Relative to the clock time
LATE	Relative to the clock time
BEFORE	Relating to order or sequence
AFTER	Relating to order or sequence

# Breakout: Automated Train Doors

Analyze the vision component to detect obstacles in train doors

NO OR NOT, MORE, LESS, AS WELL AS, PART OF, REVERSE,  
OTHER THAN / INSTEAD, EARLY, LATE, BEFORE, AFTER, WRONG,  
INVALID, INCOMPLETE, PERTURBED, and INCAPABLE.

Using HAZOP: As a group answer in #lecture, tagging group members:

- *What is the specification of the perception component?*
- *What are possible deviations from the specification?*
- *What are potential hazards resulting from these deviations?*

# HAZOP: Benefits & Limitations

- Easy to use; encourages systematic reasoning about component faults
- Can be combined with FTA/FMEA to generate faults (i.e., basic events in FTA)
- Potentially labor-intensive; relies on engineer's judgement
- Does not guarantee to find all hazards (but also true for other techniques)

# Remarks: Hazard Analysis

None of these methods guarantee completeness

- You may still be missing important hazards, failure modes

Intended as structured approaches to thinking about failures

- But cannot replace human expertise and experience

# Summary

- Accept that a failure is inevitable
  - ML components will eventually make mistakes, reasons barely matter
  - Environment may evolve over time, violating assumptions
- Design strategies for mitigating mistakes
  - Human in the loop, Undoable actions, Guardrails, Mistake detection and recovery (monitoring, doer-checker, fail-over, redundancy), Containment and isolation
- Use risk analysis to identify and mitigate potential problems
  - FTA, FMEA, HAZOP

# Further readings

- Google PAIR. People + AI Guidebook. 2019, especially chapters “Errors + Graceful Failure” and “Mental Models.”
- Martelaro, Nikolas, Carol J. Smith, and Tamara Zilovic. “Exploring Opportunities in Usable Hazard Analysis Processes for AI Engineering.” In AAAI Spring Symposium Series Workshop on AI Engineering: Creating Scalable, Human-Centered and Robust AI Systems (2022).
- Qi, Yi, Philippa Ryan Conmy, Wei Huang, Xingyu Zhao, and Xiaowei Huang. “A Hierarchical HAZOP-Like Safety Analysis for Learning-Enabled Systems.” In AISafety2022 Workshop at IJCAI2022 (2022).
- Beachum, David Robert. “Methods for assessing the safety of autonomous vehicles.” MSc thesis, 2019.
- Amershi, Saleema, Dan Weld, Mihaela Vorvoreanu, Adam Journey, Besmira Nushi, Penny Collisson, Jina Suh et al. “Guidelines for human-AI interaction.” In Proceedings of the 2019 CHI Conference on Human Factors in Computing Systems, 2019.
- Shneiderman, Ben. “Bridging the gap between ethics and practice: Guidelines for reliable, safe, and trustworthy Human-Centered AI systems.” ACM Transactions on Interactive Intelligent Systems (TiiS) 10, no. 4 (2020): 1–31.