




# dsc: Dynamic Synthetic Control for Time Series with Heterogeneous Adjustment Speeds

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## Software

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## Summary

The dsc package introduces Dynamic Synthetic Control, a new approach for comparative case studies in time series settings. Synthetic control methods are widely used to estimate causal effects, but they often fail when treated and donor units react to shocks at different speeds. The dsc package addresses this by incorporating Dynamic Time Warping (DTW) to account for heterogeneous adjustment speeds across units, improving counterfactual estimation.

Implemented in R, dsc aligns donor units to the treated unit using speed-adjusted time series before estimating synthetic weights. This innovation helps avoid biases arising from asynchronous reactions and supports more accurate estimation of treatment effects. The package is useful for applications in economics, public policy, and political science.

## Statement of Need

Standard synthetic control techniques assume that all units react to shocks or policies at the same speed. This can result in poor fits and misleading conclusions when donor units respond more slowly or more quickly than treated ones. For example, institutional inertia might delay reactions in one country relative to another, even if underlying economic mechanisms are similar.

The dsc package provides a principled solution by using DTW to synchronize pre-treatment time series between treated and donor units. This synchronization reduces mean squared error in treatment effect estimation by up to 70% in simulations and improves placebo test performance in real-world datasets. It fills a gap in the causal inference toolkit by allowing for varying speeds of adjustment, a common real-world phenomenon that existing packages ignore.

## Model Overview

Synthetic control methods construct counterfactuals for treated units using weighted combinations of untreated donor units. Let  $y_{1t}$  denote the treated unit, and  $y_{jt}$  denote donors  $j = 2, \dots, J + 1$ . The goal is to find weights  $w_j$  such that:

$$y_{1t} \approx \sum_{j=2}^{J+1} w_j y_{jt}$$

for the pre-treatment period  $t < T$ .

However, if donor units respond to latent shocks  $z_t$  with lags, then the pre-treatment series are not aligned in time. The dsc package addresses this by warping  $y_{jt}$  to align with  $y_{1t}$  using DTW. The warped donor series  $y_{jt}^w$  is then used in synthetic control estimation.

## Implementation

The core of the dsc method is a three-step process:

1. **Warping Pre-Treatment Series:** Use DTW to align each donor series  $y_j$  to the treated unit  $y_1$  during the pre-treatment period.
2. **Propagate Speed Alignment:** Apply the inferred warping path to the post-treatment period of each donor unit.
3. **Construct Synthetic Control:** Estimate weights  $w_j$  to best fit the warped donor series  $y_j^w$  to  $y_1$  before treatment.

This preserves any speed differences introduced by the treatment itself, while eliminating those inherited from structural or institutional differences.

## Code Example

The dsc package (Cao and Chadeaux, 2024) can be installed from GitHub using:

```
devtools::install_github("conflictlab/dsc")
```

Here's a representative use case based on the Basque Country dataset:

```
library(dsc)
library(Synth)

# Load dataset
data(basque, package = "Synth")
data <- basque

# Prepare data
colnames(data)[1:4] <- c("id", "unit", "time", "value")
data$invest_ratio <- data$invest / data$value

# Specify special predictors
special_preds <- expression(list(
  list(dep.var, 1960:1969, c("mean")),
  list("invest_ratio", 1964:1969, c("mean")),
  list("popdens", 1969, c("mean")),
  list("sec.agriculture", 1961:1969, c("mean")),
  list("sec.energy", 1961:1969, c("mean")),
  list("sec.industry", 1961:1969, c("mean")),
  list("sec.construction", 1961:1969, c("mean")),
  list("sec.services.venta", 1961:1969, c("mean")),
  list("sec.services.nonventa", 1961:1969, c("mean")),
  list("school.illit", 1964:1969, c("mean")),
  list("school.prim", 1964:1969, c("mean")),
  list("school.med", 1964:1969, c("mean")),
  list("school.high", 1964:1969, c("mean")),
  list("school.post.high", 1964:1969, c("mean"))
))

# Run DSC
result <- dsc(
  data = data,
  start.time = 1955,
  end.time = 1997,
```

```
treat.time = 1970,
dependent = "Basque Country (Pais Vasco)",
predictors = NULL,
parallel = TRUE,
special.predictors = special_preds,
time.predictors.prior = 1955:1969,
time.optimize.ssr = 1955:1969,
plot.figures=TRUE
)
```

## 47 Empirical Applications

### 48 Terrorism and GDP in the Basque Country

49 We replicate Abadie and Gardeazabal (2003), estimating the effect of terrorism on GDP using  
50 DSC. Compared to traditional synthetic control, DSC shows a closer match for placebo units  
51 and reduced mean squared error.

### 52 Proposition 99: Tobacco Control in California

53 We revisit the effect of California's anti-smoking policy, Proposition 99. DSC estimates a  
54 larger reduction in cigarette consumption and outperforms the original model on placebo test  
55 sharpness.

### 56 German Reunification

57 We assess the impact of reunification on West Germany's GDP. Again, DSC improves the  
58 counterfactual fit for placebo countries and yields more precise treatment estimates.

## 59 Monte Carlo Evaluation

60 To validate performance, we simulate data where units react to shocks at varying speeds.  
61 Across 100 replications, DSC consistently produces treatment effect estimates with lower  
62 variance and bias compared to standard synthetic control.

63 We define the relative improvement as:

$$r = \log \left( \frac{\text{MSE}_{DSC}}{\text{MSE}_{SC}} \right)$$

64 The average  $r$  is negative across all scenarios, indicating that DSC yields lower mean squared  
65 errors.

## 66 Discussion and Limitations

67 The dsc method improves synthetic control estimation by accounting for reaction speed  
68 heterogeneity. However, it assumes that speed differences are stable in the pre-treatment  
69 period and that no spillover effects contaminate donor units. Extensions to multi-treatment  
70 cases or endogenously determined timing remain areas for future work.

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