Circular dichroism in assemblies of plasmonic nanoparticles — modelling in the dipole approximation

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The system consists in a three-dimensional arrangement of small ellipsoidal particles in arbitrary orientations, as shown in figure 1. Here the position and orientation of the particles was chosen to follow an helix.

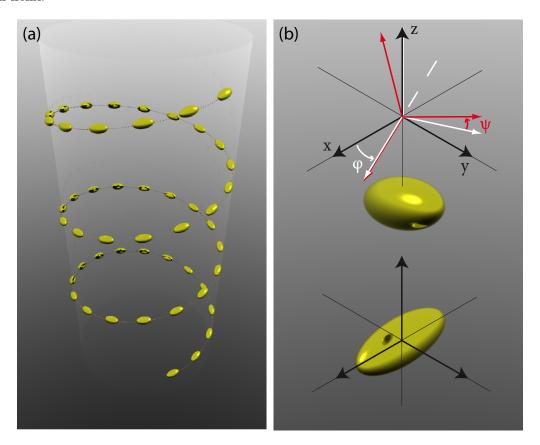


Figure 1: (a) Schematic of the 3D arrangement of particles. (b) Orientation of prolate particles in space using two Euler angles.

1 Coupled dipole model

Each dipole scatters light in proportion to the local field it experiences,

$$\mathbf{p}_{\rm dip} = \alpha \mathbf{E}_{\rm loc},\tag{1}$$

where α is the polarizability tensor describing the individual nanoparticle. The prescription of Kuwata et al. [?] was chosen, which provides an accurate approximation for particles below $\sim 100\,\mathrm{nm}$ in size. Each dipole may be placed in arbitrary orientation, and to this end the polarizability tensor must be transformed to a rotated frame.

Let us describe each nanoparticle by a diagonal polarizability tensor in the reference frame of its principal axes. The rotation of this reference frame to the actual postition of the particle can be described by three Euler angles ϕ , θ , ψ and a rotation matrix ¹

$$R = \begin{bmatrix} \cos \psi \cos \phi - \cos \theta \sin \phi \sin \psi & \cos \psi \sin \phi + \cos \theta \cos \phi \sin \psi & \sin \psi \sin \theta \\ -\sin \psi \cos \phi - \cos \theta \sin \phi \cos \psi & -\sin \psi \sin \phi + \cos \theta \cos \phi \cos \psi & \cos \psi \sin \theta \\ \sin \phi \sin \theta & -\cos \phi \sin \theta & \cos \theta \end{bmatrix}.$$
 (2)

A dipole in orientation ϕ, θ, ψ will be described by a polarizability $R^{-1}\alpha R$ in the global reference frame.

The local field

$$\mathbf{E}_{\mathrm{loc}} = \mathbf{E}_{\mathrm{inc}} + \sum_{\mathrm{dipoles}\setminus\mathrm{itself}} \mathbf{E}_{\mathrm{d}},$$
 (3)

is the sum of the incident field plus the contribution of the dipolar field associated with the other dipoles in the system. The field radiated by a dipole reads,

$$\mathbf{E}_{\mathrm{d}} = \frac{e^{i\omega r/c}}{4\pi\varepsilon_{0}} \left\{ \frac{\omega^{2}}{c^{2}r} \hat{\mathbf{r}} \times \mathbf{p} \times \hat{\mathbf{r}} + \left(\frac{1}{r^{3}} - \frac{i\omega}{cr^{2}} \right) [3(\hat{\mathbf{r}} \cdot \mathbf{p})\hat{\mathbf{r}} - \mathbf{p}] \right\}. \tag{4}$$

By grouping together the dipole moments we can cast equation 3 in matrix form,

$$A\mathbf{P} = \mathbf{E}_{\text{inc}},\tag{5}$$

where A is the interaction matrix that describes the electromagnetic coupling between the dipoles in the non-diagonal blocks,

$$A_{ij} = \frac{e^{(ikr_{ij})}}{r_{ij}} \left\{ k^2(\hat{\mathbf{r}} \otimes \hat{\mathbf{r}} - \mathbb{I}) + \frac{ikr_{ij} - 1}{r_{ij}^2} (3\hat{\mathbf{r}} \otimes \hat{\mathbf{r}} - \mathbb{I}) \right\},\tag{6}$$

and the block diagonal $A_{ii} = \alpha^{-1}$ is formed with the inverse polarizability of the individual dipoles, in the global (x, y, z) reference frame.

When the dipole moments are known by inversion of equation 5, the extinction cross-section can be obtained for a given incident field following,

$$\sigma_{\text{ext}} = \frac{4\pi k}{|\mathbf{E}_{\text{inc}}|^2} \Im(\mathbf{E}_{\text{inc}}^* \cdot \mathbf{P}). \tag{7}$$

1.1 Computation of circular dichroism

Circular dichroism can be calculated from the difference in extinction for left-handed and right-handed circularly polarised light, averaged over the full solid angle of incident light,

$$\sigma_{\rm CD} = \langle \sigma_L \rangle_{\Omega} - \langle \sigma_R \rangle_{\Omega} \,. \tag{8}$$

The incident field incident along x is written as,

$$\mathbf{E}_{\text{inc}} = \frac{\exp i(\omega t - k_x x)}{\sqrt{2}} \begin{pmatrix} 0 \\ i \\ 1 \end{pmatrix} \quad (right-handed) \tag{9}$$

$$\mathbf{E}_{\text{inc}} = \frac{\exp i(\omega t - k_x x)}{\sqrt{2}} \begin{pmatrix} 0\\1\\i \end{pmatrix} \quad (left\text{-}handed). \tag{10}$$

More generally, the incident beam will be characterised by a wave-vector \mathbf{k} and an electric vector \mathbf{E}_{inc} describing the light polarisation, and both of these vectors can be rotated using the rotation matrix R as $R^{-1}\mathbf{k}$ and $R^{-1}\mathbf{E}_{\text{inc}}$.

¹using the same conventions as http://mathworld.wolfram.com/EulerAngles.html

The interaction matrix A does not depend on the direction of the incident field, it is therefore advantageous to compute A^{-1} (at each wavelength) and perform the matrix-vector products for all the required incident fields. The CD spectra obtained experimentally are averaged over all orientations of the incident beam, it is therefore necessary to use incident wave-vectors that span the full range of $\phi \in [0, 2\pi], \theta = \pi/2, \psi \in [-\pi/2, \pi/2].$

Averaging the extinction cross-section over all incident field directions is performed by numerical integration,

$$\langle \sigma \rangle_{\Omega} = \frac{1}{4\pi} \int_{0}^{2\pi} \int_{-\pi/2}^{\pi/2} \sigma(\phi, \psi) \cos \psi d\psi d\phi. \tag{11}$$

A Gauss-Legendre quadrature scheme is used to perform the integration, so that the evaluation of the extinction cross-section is performed for a relatively low number of angles $(20 \times 20 \text{ seems sufficient})$.

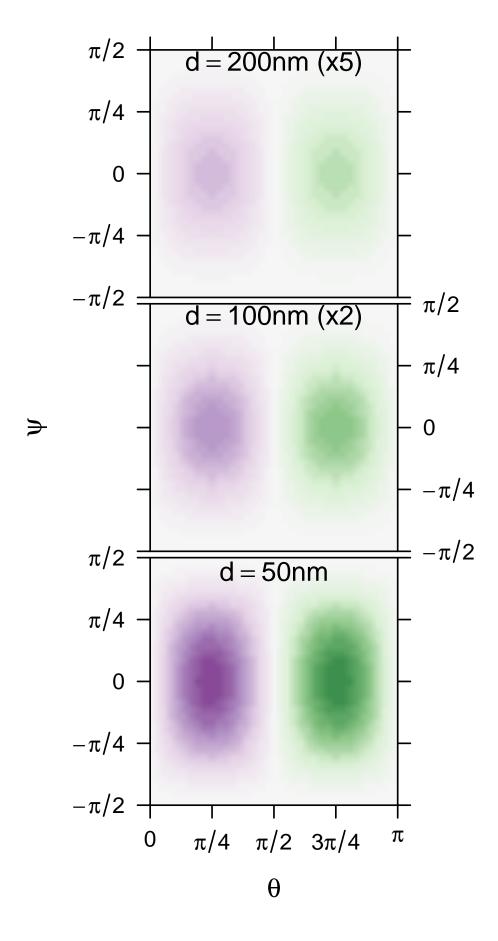


Figure 2: Peak CD value as a function of the dimer angles (θ, ψ) for three different inter-dipole distances. The peak value may be negative (purple) or positive (green). In all cases the strongest CD response is obtained for $(\theta = \pm \pi/4, \psi = 0)$ (the result is identical if the average)

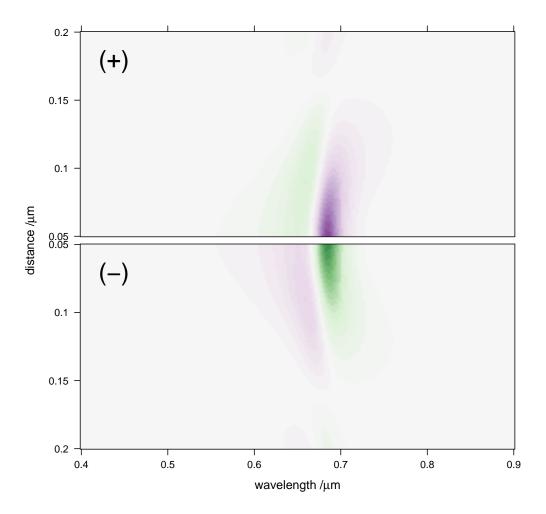


Figure 3: CD spectra as a function of inter-particle distance for a dimer with $(\theta = \pm \pi/4, \psi = 0)$.

C++ source code

This code uses the Armadillo library for complex linear algebra, and provides wrapper functions to use with R. The full code and precompiled binaries are available at R-forge.

Listing 1: Euler rotation matrix

```
1
     arma::mat euler(const double phi, const double theta, const double psi)
 2
 3
        arma::mat Rot(3,3);
 4
        const double cosphi = cos(phi), cospsi = cos(psi), costheta = cos(theta);
        const double sinphi = sin(phi), sinpsi = sin(psi), sintheta = sin(theta);
 5
        Rot(0,0) = cospsi*cosphi - costheta*sinphi*sinpsi;
 6
        Rot(0,1) = cospsi*sinphi + costheta*cosphi*sinpsi;
 7
        Rot(0,2) = sinpsi*sintheta;
 8
 9
        Rot(1,0) = -sinpsi*cosphi - costheta*sinphi*cospsi;
10
        Rot(1,1) = -sinpsi*sinphi + costheta*cosphi*cospsi;
11
        Rot(1,2) = cospsi*sintheta;
12
13
14
        Rot(2,0) = sinphi*sintheta;
15
        Rot(2,1) = -cosphi*sintheta;
        Rot(2,2) = costheta;
16
        return (Rot);
17
18
```

Listing 2: Diagonal polarizability blocks

```
arma::cx_mat diagonal_polarisability(const arma::cx_mat& Alpha, const arma::mat& Euler) {
 1
 2
 3
      const int N = Euler.n_rows;
      const arma::colvec phi = Euler.col(0), theta = Euler.col(1), psi = Euler.col(2);
 4
 5
      arma::mat Rot(3,3):
 6
      arma::cx_mat polar(3*N,3*N);
 7
 8
 9
      int ii=0;
      for(ii=0; ii<N; ii++){
10
11
        Rot = euler(phi[ii], theta[ii], psi[ii]);
12
        polar.submat(ii*3,ii*3,ii*3+2,ii*3+2) = inv(Rot) * diagmat(Alpha.col(ii)) * Rot;
13
14
      } // polar is done
15
16
      return polar;
17
18
```

Listing 3: Interaction matrix

```
1
   arma::cx_mat interaction_matrix(const arma::mat& R, const double kn, \
          const arma::cx_mat& invAlpha, const arma::mat& Euler,
2
3
          const int full) {
4
     const int N = R.n_rows;
5
     // temporary vars
6
7
     arma::mat Rot(3,3);
     const arma::cx\_double i = arma::cx\_double(0,1);
8
     arma::cx_mat A = arma::zeros < arma::cx_mat > (3*N, 3*N);
9
```

```
const arma::cx_mat I3 = arma::eye < arma::<math>cx_mat > (3, 3);
10
11
12
                      int jj=0, kk=0;
13
                      \operatorname{arma::mat} \operatorname{rk\_to\_rj} = \operatorname{arma::mat}(1,3), \operatorname{rjkhat} = \operatorname{arma::mat}(1,3), \operatorname{rjkrjk} = \operatorname{arma::mat}(3,3);
14
                      double rjk;
                      arma::cx_mat Ajk = arma::cx_mat(3,3);
15
16
17
                      // nested for loop over dipole locations
18
                      for(jj=0; jj<N; jj++)
19
                                   for(kk=0; kk<N; kk++)
20
21
                             if(jj!=kk){
22
23
                                                 rk\_to\_rj = R.row(jj) - R.row(kk);
24
25
                                                 rjk = norm(rk_to_rj,2);
26
                                                 rjkhat = rk_to_rj / rjk;
                                                 rjkrjk = trans(rjkhat) * rjkhat;
27
28
                                   if(full == 1) {
                                          Ajk = \exp(i*kn*rjk) / rjk * (kn*kn*(rjkrjk - I3) + (i*kn*rjk - arma::cx_double(1,0)) / (rjk*rjk \leftarrow I3) + (i*kn*rjk - arma::cx_double(1,0)) / (rjk*rjk - arma::cx_double(
29
                                                         ) * (3*rjkrjk - I3));
                                    } else {
30
                                          Ajk = (I3 - 3*rjkrjk) / (rjk*rjk*rjk);
31
32
33
                                    // assign block
                                    A.submat(jj*3,kk*3,jj*3+2,kk*3+2) = Ajk;
34
35
36
                             } // end loops
37
38
39
                      // diagonal blocks
                      arma::cx_mat polar = diagonal_polarisability(invAlpha, Euler);
40
41
                      A = A + polar;
42
                      // return inv(A);
43
                      return(A);
44
45
```

Listing 4: Extinction and absorption cross-sections

```
double extinction(const double kn, const arma::cx_colvec& P, const arma::cx_colvec& Eincident)
1
2
      const double c = 4*arma::math::pi()*kn * imag(cdot(Eincident, P));
3
      return c;
4
5
6
    double absorption(const double kn, const arma::cx_colvec& P, const arma::cx_mat& invpolar)
7
8
      const double c = 4*arma::math::pi()*kn*(imag(cdot(invpolar * P, P)) - \
9
               kn*kn*kn* 2/3 * real(cdot(P, P)));
10
      return c:
11
12
```

Listing 5: Angular averaging

```
1 arma::colvec averaging(const arma::mat& R, const arma::cx_mat& A, const arma::cx_mat& invalpha, \
2 const double kn, const arma::mat& QuadPhi, const arma::mat& QuadPsi)
4 {
```

```
const int N = R.n_rows, NqPhi = QuadPhi.n_rows, NqPsi = QuadPsi.n_rows;
 5
        \mathbf{const} \ \mathrm{arma::} \mathrm{colvec} \ \mathrm{nodes1} = \mathrm{QuadPhi.col}(0), \ \mathrm{weights1} = \mathrm{QuadPhi.col}(1), \ \backslash
 6
          nodes2 = QuadPsi.col(0), weights2 = QuadPsi.col(1);;
 7
        //constants
 8
        const arma::cx\_double i = arma::cx\_double(0,1);
 9
        const double pi = arma::math::pi();
10
        arma::mat Rot(3,3);
11
12
        // incident field
13
        const arma::cx_colvec RCP="(0,0) (0,1) (1,0);", LCP="(0,0) (1,0) (0,1);";
14
        arma::cx_colvec ERCP(3), ELCP(3), Eincident(3*N), P(3*N);
15
        const arma::colvec khat="1 0 0;", kvec = kn*khat;
16
        arma::mat kr;
17
        arma::cx_mat expikr;
18
        double left=0, right=0, left2=0, right2=0,phi=0,psi=0;
19
20
        // begin quadrature
21
        const double b2=pi/2, a2=2*pi, b1=-pi/2, a1=0; // a is for phi, b for psi
22
        const double C2 = (b2 - b1) / 2, D2 = (b2 + b1) / 2, \
23
          C1 = (a2 - a1) / 2, D1 = (a2 + a1) / 2;
24
25
        const arma::colvec y = nodes2*C2 + D2; // for psi
26
        const arma::colvec x = nodes1*C1 + D1; // for phi
27
28
29
        double tmpleft=0, tmpright=0, tmpleft2=0, tmpright2=0, factor, factor2;
        int ll=0,mm=0; // Nq quadrature points
30
31
        arma::cx_mat B = pinv(A); /* inverting the interaction matrix
32
             to solve AP=Eincident multiple times */
33
34
35
        for(ll=0; ll<NqPhi; ll++){ // loop over phi
          phi = x[ll];
36
          tmpleft=0; tmpright=0; tmpleft2=0; tmpright2=0;
37
      for(mm=0; mm<NqPsi; mm++){ // loop over psi
38
39
        psi = y[mm];
        \mathrm{Rot} = \mathrm{euler}(\mathrm{phi},\,\mathrm{pi}/2,\,\mathrm{psi});\,//\;\mathrm{theta\;doesn't\;vary}
40
        ELCP = sqrt(2)/2 * trans(Rot) * LCP ;
41
        ERCP = sqrt(2)/2 * trans(Rot) * RCP ;
42
        kr = R * trans(Rot) * kvec;
43
        expikr = exp(i*kr);
44
45
        factor = C1 * weights2[mm] * cos(psi) ;
46
        // left polarisation
47
      Eincident = reshape(expikr * strans(ELCP), 3*N, 1, 1);
48
49
      P = B * Eincident;
50
      // P = solve(A, Eincident);// too slow, invert A before loop
      tmpleft += factor * extinction(kn, P, Eincident);
51
      tmpleft2 += factor * absorption(kn, P, invalpha);
52
53
      // right polarisation
54
      Eincident = reshape(expikr * strans(ERCP), 3*N, 1, 1);
55
      P = B * Eincident;
56
      // P = solve(A, Eincident); // too slow, invert A before loop
57
      tmpright += factor * extinction(kn, P, Eincident);
58
59
      tmpright2 += factor * absorption(kn, P, invalpha);
60
61
62
      factor2 = C2 * weights1[11];
63
      left += factor2 * tmpleft;
      right += factor2 * tmpright;
64
      left2 += factor2 * tmpleft2;
65
```

```
66
      right2 += factor2 * tmpright2;
67
          }
68
        arma::colvec res(4) ;
69
70
        res(0) = left / (4*pi); //ext L
res(1) = right / (4*pi);//ext R
71
72
        res(2) = left2 / (4*pi); //abs L
73
        res(3) = right2 / (4*pi); //abs R
74
75
        return res ;
      }
76
```