# Lecture 21 – Turing Machines (TMs) COSE215: Theory of Computation

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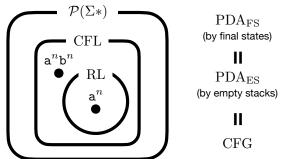


2023 Spring

#### Recall



• A pushdown automaton (PDA) is an extension of FA with a stack.



- Then, how about extensions of finite automata with other structures?
- Do they still represent the class of context-free languages (CFLs)?

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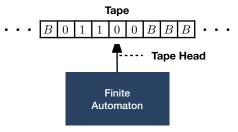
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## Turing Machines





A Turing machine (TM) is a finite automaton with a tape. It consists of the following three components:

- 1 A finite automaton with a deterministic transition function.
- 2 A tape is a one-dimensional infinite array of cells.
  - Each cell contains a tape symbol.
  - The **blank symbol** *B* is a special symbol representing an empty cell.
- 3 A tape head is a device that can read and write symbols on the tape.
  - It can move left or right one cell at a time.

# Definition of Turing Machines



#### Definition (Turing Machines)

A Turing machine (TM) is a 7-tuple

$$M = (Q, \Sigma, \Gamma, \delta, q_0, B, F)$$

- Q is a finite set of states.
- Σ is a finite set of input symbols.
- $\Gamma$  is a finite set of **tape symbols** containing input symbols  $(\Sigma \subseteq \Gamma)$ .
- $\delta: Q \times \Gamma \rightharpoonup Q \times \Gamma \times \{L, R\}$  is a transition function.
- $q_0 \in Q$  is the initial state.
- $B \in \Gamma \setminus \Sigma$  is the blank symbol.
- $F \subseteq Q$  is the set of **final states**.

# Definition of Turing Machines – Example



$$M_1 = (\{q_0, q_1, q_2\}, \{0, 1\}, \{0, 1, B\}, \delta, q_0, B, \{q_2\})$$

$$\delta(q_0, 0) = (q_0, 1, R)$$
  $\delta(q_1, 0) = (q_1, 0, L)$   
 $\delta(q_0, 1) = (q_0, 0, R)$   $\delta(q_1, 1) = (q_1, 1, L)$   
 $\delta(q_0, B) = (q_1, B, L)$   $\delta(q_1, B) = (q_2, B, R)$ 

# Definition of Turing Machines - Example



$$M_1 = (\{q_0, q_1, q_2\}, \{0, 1\}, \{0, 1, B\}, \delta, q_0, B, \{q_2\})$$

where

$$\delta(q_0,0) = (q_0,1,R)$$
  $\delta(q_1,0) = (q_1,0,L)$   
 $\delta(q_0,1) = (q_0,0,R)$   $\delta(q_1,1) = (q_1,1,L)$   
 $\delta(q_0,B) = (q_1,B,L)$   $\delta(q_1,B) = (q_2,B,R)$ 

The **transition diagram** of  $M_1$  is as follows:

$$M_1 = \underbrace{\begin{bmatrix} [0 \to 1] \ R & [0 \to 0] \ L \\ [1 \to 0] \ R & [1 \to 1] \ L \end{bmatrix}}_{\text{start}} \underbrace{\begin{bmatrix} [0 \to 0] \ R & [0 \to 0] \ R & [1 \to 1] \ L \end{bmatrix}}_{q_1} \underbrace{\begin{bmatrix} [B \to B] \ R & [Q_2] \end{bmatrix}}_{q_2}$$

## Turing Machines in Scala



$$M = (Q, \Sigma, \Gamma, \delta, q_0, B, F)$$
$$\delta : Q \times \Gamma \longrightarrow Q \times \Gamma \times \{L, R\}$$

```
// The type definitions of states, symbols, tape symbols, and head moves
type State = Int
type Symbol = Char
type TapeSymbol = Char
enum HeadMove { case L. R }
import HeadMove.*
// The definition of Turing machines
case class TM(
  states: Set[State].
  symbols: Set[Symbol],
  tapeSymbols: Set[TapeSymbol],
  trans: Map[(State, TapeSymbol), (State, TapeSymbol, HeadMove)],
  initState: State.
  blankSymbol: TapeSymbol,
  finalStates: Set[State].
```

# Turing Machines in Scala – Example

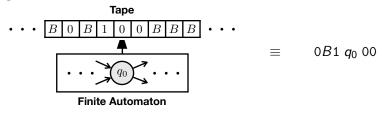


```
M_{1} = \underbrace{\begin{bmatrix} [0 \to 1] \ R & [0 \to 0] \ L \\ [1 \to 0] \ R & [1 \to 1] \ L \\ \\ \text{start} \longrightarrow \underbrace{q_{0}} \underbrace{\begin{bmatrix} [B \to B] \ L \\ q_{1} \end{bmatrix}}_{[B \to B]} \underbrace{[B \to B] \ R}_{[Q_{2}]}
```

```
// An example of Turing machine
val tm1: TM = TM(
  states = Set(0, 1, 2).
  symbols = Set('0', '1'),
  tapeSymbols = Set('0', '1', 'B'),
  trans = Map(
    (0, 0) \rightarrow (0, 1, R), (1, 0) \rightarrow (1, 0, L),
    (0, '1') \rightarrow (0, '0', R), (1, '1') \rightarrow (1, '1', L),
    (0, 'B') \rightarrow (1, 'B', L), (1, 'B') \rightarrow (2, 'B', R),
  ),
  initState = 0.
  blankSymbol = 'B',
  finalStates = Set(2).
```

## Configurations





#### Definition (Configurations of Turing Machines)

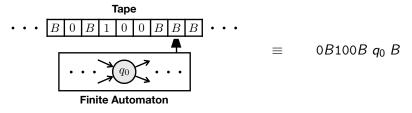
A configuration of a Turing machine M is a sequence of the form

$$X_1 \cdots X_{i-1} \ q \ X_i X_{i+1} \cdots X_n$$

- $q \in Q$  is the current state.
- $X_1 \cdots X_n \in \Gamma^*$  is the **sub-tape** between the left- and the right-most 1) non-blank symbols or 2) the symbol under the tape head.
- $X_i \in \Gamma$  is the current tape symbol under the tape head.

# Configurations





#### Definition (Configurations of Turing Machines)

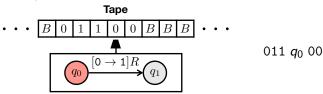
A configuration of a Turing machine M is a sequence of the form

$$X_1 \cdots X_{i-1} \ q \ X_i X_{i+1} \cdots X_n$$

- q ∈ Q is the current state.
- $X_1 \cdots X_n \in \Gamma^*$  is the **sub-tape** between the left- and the right-most 1) non-blank symbols or 2) the symbol under the tape head.
- $X_i \in \Gamma$  is the **current tape symbol** under the tape head.

#### One-Step Moves





#### Definition (One-Step Moves of Turing Machines)

**Finite Automaton** 

A **one-step move** ( $\vdash$ ) of a Turing machine M is a transition from a configuration to another configuration.

• If 
$$\delta(q, X_i) = (p, Y, L)$$
,

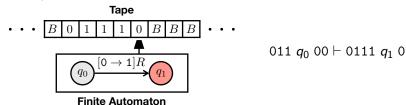
$$X_1 \cdots X_{i-1} \ q \ X_i X_{i+1} \cdots X_n \vdash X_1 \cdots X_{i-2} \ p \ X_{i-1} Y X_{i+1} \cdots X_n$$

• If 
$$\delta(q, X_i) = (p, Y, R)$$
,

$$X_1 \cdots X_{i-1} \ q \ X_i X_{i+1} \cdots X_n \vdash X_1 \cdots X_{i-1} Y \ p \ X_{i+1} \cdots X_n$$

#### One-Step Moves





## Definition (One-Step Moves of Turing Machines)

A **one-step move** ( $\vdash$ ) of a Turing machine M is a transition from a configuration to another configuration.

• If 
$$\delta(q, X_i) = (p, Y, L)$$
,

$$X_1 \cdots X_{i-1} \ q \ X_i X_{i+1} \cdots X_n \vdash X_1 \cdots X_{i-2} \ p \ X_{i-1} Y X_{i+1} \cdots X_n$$

• If 
$$\delta(q, X_i) = (p, Y, R)$$
,

$$X_1 \cdots X_{i-1} \ q \ X_i X_{i+1} \cdots X_n \vdash X_1 \cdots X_{i-1} Y \ p \ X_{i+1} \cdots X_n$$

## One-Step Moves



$$M_{1} = \begin{cases} [0 \to 1] & R & [0 \to 0] & L \\ [1 \to 0] & R & [1 \to 1] & L \end{cases}$$

$$q_{0} \text{ 0110} \quad \vdash \quad 1 & q_{0} \text{ 110} \qquad (\because \delta(q_{0}, 0) = (q_{0}, 1, R))$$

$$\vdash \quad 10 & q_{0} \text{ 10} \qquad (\because \delta(q_{0}, 1) = (q_{0}, 0, R))$$

$$\vdash \quad 100 & q_{0} \text{ 0} \qquad (\because \delta(q_{0}, 1) = (q_{0}, 0, R))$$

$$\vdash \quad 1001 & q_{0} & B \qquad (\because \delta(q_{0}, 1) = (q_{0}, 0, R))$$

$$\vdash \quad 100 & q_{1} \text{ 1} \qquad (\because \delta(q_{0}, 0) = (q_{1}, R, L))$$

$$\vdash \quad q_{1} & B \text{ 1001} \qquad (\because \delta(q_{1}, x) = (q_{1}, x, L) \text{ where } x = 0 \text{ or } 1)$$

$$\vdash \quad q_{2} & 1001 \qquad (\because \delta(q_{1}, B) = (q_{2}, B, R))$$

We say that  $M_1$  halts on input 0110 with output 1001 because it reaches a configuration having no more possible moves.

# Language of Turing Machines



#### Definition (Language of Turing Machines)

For a given Turing machine  $M = (Q, \Sigma, \Gamma, \delta, q_0, B, F)$ , the **language** of M is defined as follows:

$$L(M) = \{ w \in \Sigma^* \mid q_0 w \vdash^* \alpha \ q_f \ \beta \text{ for some } q_f \in F, \alpha, \beta \in \Gamma^* \}$$

#### Definition (Recursively Enumerable Languages)

A language L is recursively enumerable if there exists a Turing machine M such that L = L(M).

For example, the language of a Turing machine  $M_1$  is defined as follows:

$$L(M_1) = \{ w \mid w \in \{0,1\}^* \}$$

because  $M_1$  reaches a final state on any input.

## Language of Turing Machines



 $L(M) = \{ w \in \Sigma^* \mid q_0 w \vdash^* \alpha \ q_f \ \beta \text{ for some } q_f \in F, \alpha, \beta \in \Gamma^* \}$ 

```
// The type definitions of words, tapes, and configurations
type Word = String
type Tape = String
case class Config(prev: Tape, state: State, cur: TapeSymbol, next: Tape)
// A one-step move in a Turing machine
def move(tm: TM)(config: Config): Option[Config] = ...
// The initial configuration of a Turing machine
def initConfig(tm: TM)(word: Word): Config = word match
 case a <| x => Config("", tm.initState, a, x)
              => Config("", tm.initState, tm.blankSymbol, "")
// The acceptance of a word by a Turing machine
def accept(tm: TM)(word: Word): Boolean =
 def aux(config: Config): Boolean =
   tm.finalStates.contains(config.state) || (move(tm)(config) match
      case None
                            => false
      case Some(nextConfig) => aux(nextConfig)
 aux(initConfig(tm)(word))
// An example acceptance of a word "0110"
accept(tm1)("0110") // true
```

# Turing Machines as Computing Machines



#### Definition (Turing Computable Functions)

A partial function  $f: \Sigma^* \rightharpoonup \Sigma^*$  is **Turing-computable** if there exists a Turing machine  $M = (Q, \Sigma, \Gamma, \delta, q_0, B, F)$  such that

$$q_0 w \vdash^* q_f f(w)$$

for some  $q_f \in F$  and all  $w \in \Sigma^*$ , such that f(w) is defined.

For example, the function  $f: \{0,1\}^* \to \{0,1\}^*$  defined as follows is Turing-computable:

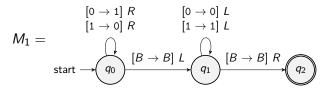
$$f(w) =$$
(the flip of each bit in  $w$ )

because there exists a Turing machine  $M_1$  such that  $q_0 w \vdash^* q_f f(w)$  for some  $q_f \in F$  and all  $w \in \{0,1\}^*$ . For instance,

$$q_0$$
 0110  $\vdash^* q_2$  1001  $q_0$  1011100  $\vdash^* q_2$  0100011

# Turing Machines as Computing Machines





```
// A multiple moves in a Turing machine
def moves(tm: TM)(config: Config): Config = move(tm)(config) match
 case None
                        => config
 case Some(nextConfig) => moves(tm)(nextConfig)
// A computation by a Turing machine
def compute(tm: TM)(w: Word): Option[Word] =
 val Config(prev, state, cur, next) = moves(tm)(initConfig(tm)(w))
  if (prev != "" || !tm.finalStates.contains(state)) None
 else if (!next.forall(tm.symbols.contains)) None
 else Some(if (cur == tm.blankSymbol) next else cur + next)
// Examples of computations by Turing machines
compute(tm1)("0110") // Some("1001")
compute(tm1)("1011100") // Some("0100011")
```

#### Summary



#### 1. Turing Machines

Definition

Turing Machines in Scala

Configurations

Language of Turing Machines

Turing Machines as Computing Machines

#### Next Lecture



• Examples of Turing Machines

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