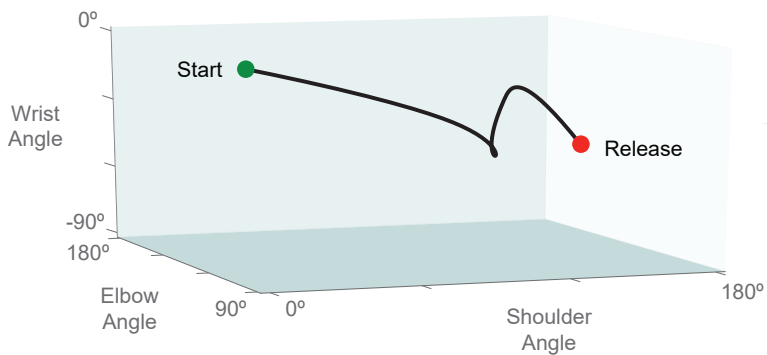


(e) Time-history of joint angles in configuration space



Apply Forward Kinematics

$$\bar{x}(t) = \bar{G}(\bar{\theta}(t))$$

