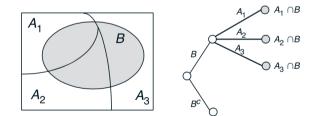
Total probability - Bayes' formula

January 14, 2021

Partition

A_1, \ldots, A_n is a partition of Ω if

- mutually exclusive: $A_i A_j = \emptyset$ for $i \neq j$
- $A_1 \cup A_2 \cup \dots A_n = \Omega$

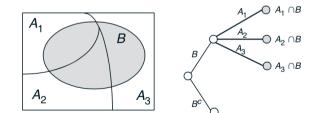




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Total probability formula - divide - and - conquer

- Partition sample space into A_1, A_2, \ldots, A_n
- Know $P(B|A_i)$ for every i
- Compute P(B)

$$P(B) = \sum_{i=1}^{n} P(BA_i) = \sum_{i=1}^{n} P(B|A_i)P(A_i).$$



Example

In semiconductor manufacturing the probability is 0.10 that a chip that is subjected to high levels of contamination during manufacturing causes a product failure. The probability is 0.005 that a chip that is not subjected to high contamination levels during manufacturing causes a product failure. In a particular production run, 20% of the chips are subject to high levels of contamination. What is the probability that a product using one of these chips fails?





Summarize information

Level of	Prob of level	Prob of failure (<i>F</i>)
contamination		subject to level
$\blacksquare \mathbf{Hight} \; (H)$	P(H) = 0.2	P(F H) = 0.1
Not hight (H^c)	$P(H^c) = 0.8$	$P(F H^c) = 0.005$

$$P(F) = P(FH) + P(FH^{c})$$

= $P(H)P(F|H) + P(H^{c})P(F|H^{c}) = 0.024$



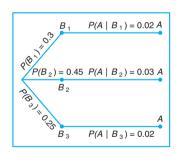


Example

In a certain assembly plant, three machines, B_1 , B_2 , and B_3 , make 30%, 45%, and 25%, respectively, of the products. It is known from past experience that 2%, 3%, and 2% of the products made by each machine, respectively, are defective. Now, suppose that a finished product is randomly selected. What is the probability that it is defective?







- $P(AB_1) = P(B_1)P(A|B_1) =$ (.3)(.02) = .006
- $P(AB_2) = P(B_2)P(A|B_2) = (.45)(.03) = .0135$
- $P(AB_3) = P(B_1)P(A|B_1) = (.25)(.02) = .005$
- $P(A) = P(AB_1) + P(AB_2) + P(AB_3) = 0.0245$





Re-evaluate

if a product was chosen randomly and found to be defective, what is the probability that it was made by machine B_3 ?

$$P(B_3|A) = \frac{P(B_3A)}{P(A)}$$
$$= \frac{0.005}{0.0245} = \frac{10}{49}$$





Bayes' Formula

- Prior probability $P(A_i)$ initial belief
- Know $P(B|A_i)$ for each i
- Given B occurs, wish to revise (update) "belief" $P(A_i|B)$

$$P(A_i|B) = \frac{P(B|A_i)P(A_i)}{\sum_{k=1}^{n} P(B|A_i)P(A_i)}$$





Bayes' rule is often used for **inference**. There are a number of "causes" that may result in a certain "effect." We observe the effect, and we wish to infer the cause.





Example

A manufacturing firm employs three analytical plans for the design and development of a particular product. For cost reasons, all three are used at varying times. In fact, plans 1, 2, and 3 are used for 30%, 20%, and 50% of the products, respectively.





The defect rate is different for the three procedures as follows:

$$P(D|P_1) = 0.01, P(D|P_2) = 0.03, P(D|P_3) = 0.02$$

where $P(D|P_j)$ is the probability of a defective product, given plan j.

If a random product was observed and found to be defective, which plan was most likely used and thus responsible?





• Need to compare $P(P_1|D)$, $P(P_2|D)$, $P(P_3|D)$

• Info:

	$ P(P_i) $	$P(D P_i)$	$P(DP_i)$
$\overline{P_1}$	0.3	0.01	0.003
P_2	0.2	0.03	0.006
P_3	0.5	0.03	0.01
			P(D) = 0.19





• $P(P_1|D) = \frac{P(P_1D)}{P(D)} = \frac{.003}{.19} = .158$

the result of the use of plan 3

• Similarly, $P(P_2|D) = .316$, $P(P_3|D) = .526$ The conditional probability of a defect given plan 3 is the largest of the three; thus a defective for a random product is most likely





Practice

Printer failures are associated with three types of problems: hardware, software, and other (such as connectors), with probabilities 0.1, 0.6, and 0.3, respectively. The probability of a printer failure given a hardware problem is 0.9, given a software problem is 0.2, and given any other type of problem is 0.5. If a customer enters the manufacturer's Web site to diagnose a printer failure, what is the most likely cause of the problem?





Example

A plane is missing and it was equally likely to have gone down in any of three possible regions. Let $1 - \alpha_i$ denote the probability the plane will be found upon a search of the i-th region when the plane is, in fact, in that region, i = 1, 2, 3. What is the conditional probability that the plane is in the i-th region, given that a search of region 1 is unsuccessful, i = 1, 2, 3?





- A_i ={the plane is in region i}
- $B = \{ \text{search of region 1 was unsuccessful} \}$
- Need $P(A_i|B) = ?$





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Need to find

$$P(A_iB)$$
 and $P(B)$

with information

- $P(A_i) = \frac{1}{3}$
- P(plane is found in region $i|A_i$) = 1 α





$$P(A_1B) = ?$$

 A_1B means that

- Plane is in region 1
- Search in region 1 was unsuccessful = plane was not found in region 1



$$P(A_1B) = ?$$

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$$P(A_1B) = P(A_1)P(B|A_1) = \frac{1}{3} * \alpha_1 = \frac{\alpha_1}{3}$$





$$P(A_1B) = ?$$

A_1B means that

- Plane is in region 1
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A_2B means that

- Plane is in region 2
- Search in region 1 was unsuccessful = plane was not found in region 1

$$P(A_2B) = P(A_2)P(B|A_2) = \frac{1}{3} * 1 = \frac{1}{3}$$





A_2B means that

- Plane is in region 2
- Search in region 1 was unsuccessful = plane was not found in region 1

$$P(A_2B) = P(A_2)P(B|A_2) = \frac{1}{3} * 1 = \frac{1}{3}$$





A_3B means that

- Plane is in region 3
- Search in region 1 was unsuccessful = plane was not found in region 1

$$P(A_3B) = P(A_3)P(B|A_3) = \frac{1}{3} * 1 = \frac{1}{3}$$





A_3B means that

- Plane is in region 3
- Search in region 1 was unsuccessful = plane was not found in region 1

$$P(A_3B) = P(A_3)P(B|A_3) = \frac{1}{3} * 1 = \frac{1}{3}$$





$$P(B) = P(A_1B) + P(A_2B) + P(A_3B)$$

$$= \alpha_1 \times \frac{1}{3} + 1 \times \frac{1}{3} + 1 \times \frac{1}{3}$$

$$= \frac{\alpha_1 + 2}{3}$$





$$P(B) = P(A_1B) + P(A_2B) + P(A_3B)$$

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$$= \frac{\alpha_1 + 2}{3}$$





$$P(A_1|B) = \frac{P(A_1B)}{P(B)} = \frac{\alpha_1}{\alpha_1 + 2}$$

$$P(A_2|B) = \frac{P(A_2B)}{P(B)} = \frac{1}{\alpha_1 + 2}$$

$$P(A_3|B) = \frac{P(A_3B)}{P(B)} = \frac{1}{\alpha_1 + 2}$$







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Summary

- Partition A_1, \ldots, A_n
 - $A_i A_j = \emptyset$ for all $i \neq j$
 - $\bigcup_i A_i = \Omega$
- Total rule

$$P(B) = P(BA_1) + \dots P(BA_n)$$

= $P(A_1)P(B|A_1) + \dots + P(A_n)P(B|A_n)$





• Bayes's rule (update information)

$$P(A_k|B) = rac{P(BA_k)}{P(B)}$$

$$= rac{P(A_k)P(B|A_k)}{P(A_1)P(B|A_1) + \cdots + P(A_n)P(B|A_n)}$$



