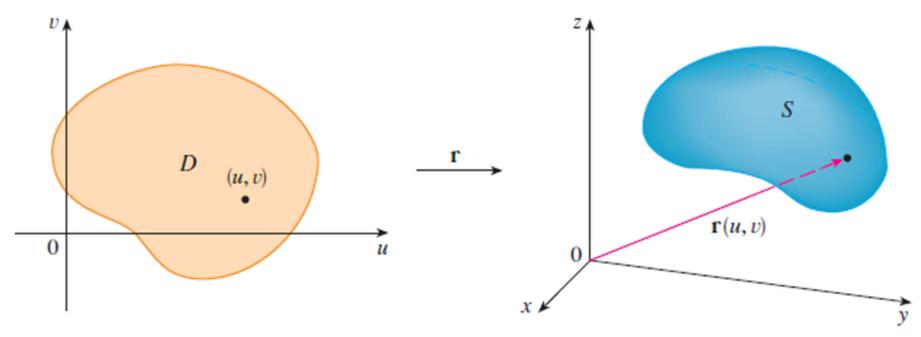
Chapter 4: Vector Calculus

Lecture 14
Surface Integrals and Applications

1. Parametric Surfaces



Vector-valued function

$$\mathbf{r}(u,v) = x(u,v)\mathbf{i} + y(u,v)\mathbf{j} + z(u,v)\mathbf{k}, (u,v) \in D \subset \mathbb{R}^2$$

Set of all points $(x, y, z) \in \mathbb{R}^3$ such that

$$x = x(u, v), y = y(u, v), z = z(u, v), (u, v) \in D \subset \mathbb{R}^2$$

is called a parametric surface S

Parametric equations for S

Example

Identify and sketch the surface with vector equation

$$\mathbf{r}(u, v) = 2\cos u \,\mathbf{i} + v \,\mathbf{j} + 2\sin u \,\mathbf{k}$$

Solution: The parametric equations for this surface are

$$x = 2\cos u$$
, $y = v$, $z = 2\sin u$

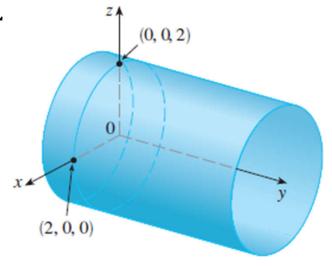
So, for any point (x, y, z) on this surface, we have

$$x^2 + z^2 = 4\cos^2 u + 4\sin^2 u = 4$$

Vertical cross-sections parallel to the xz-plane (y constant) are all circles with radius 2.

No restriction is placed on y=v

The surface is a circular cylinder with radius 2 whose axis is the y-axis

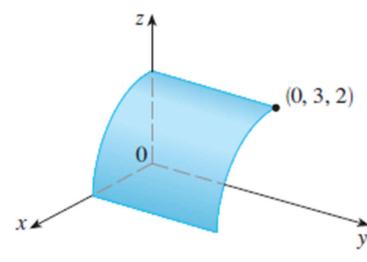


Note

• In last Example we placed no restrictions on the parameters *u* and *v* and so we obtained the entire cylinder. If, for instance, we restrict *u* and *v* by writing the parameter domain as

$$0 \le u \le \pi / 2$$
, $0 \le v \le 3$

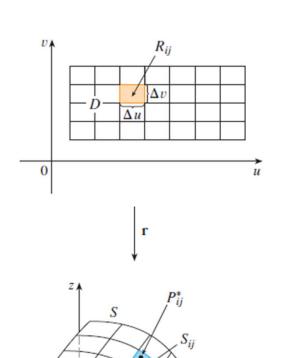
- $x \ge 0, z \ge 0, 0 \le y \le 3$
- We get a quarter-cylinder with length 3



2. Surface Integrals

f is a function defined on a surface S given by

$$\mathbf{r}(u,v) = x(u,v)\mathbf{i} + y(u,v)\mathbf{j} + z(u,v)\mathbf{k}, (u,v) \in D \subset \mathbb{R}^2$$



Divide domain D into subrectangles

$$R_{ij}$$
, $i = 1, 2, ..., m$; $j = 1, 2, ..., n$

Then surface S is divided into corresponding patches

$$S_{ij}, i = 1, 2, ..., m; j = 1, 2, ..., n$$

 $P_{ij}^* \in S_{ij}, \forall i, j$

$$\sum_{i=1}^{m} \sum_{j=1}^{n} f(P_{ij}^*) \Delta S_{ij}$$

Definition of Surface Integrals of a function

The surface integral of a function f over the surface S

is defined by

$$\iint_{S} f(x, y, z) dS = \lim_{m, n \to \infty} \sum_{i=1}^{m} \sum_{j=1}^{n} f(P_{ij}^{*}) \Delta S_{ij}$$

if this limit exists

Application:

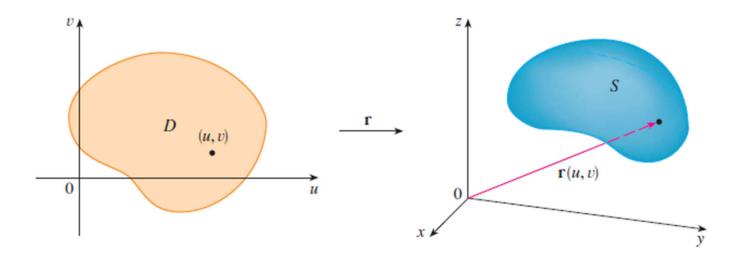
S has density $\rho(x, y, z)$

Mass of
$$S$$
: $m = \iint_{S} \rho(x, y, z) dS$

Center of mass of S at point (x, y, z):

$$\overline{x} = \frac{1}{m} \iint_{S} x \rho(x, y, z) dS, \quad \overline{y} = \frac{1}{m} \iint_{S} y \rho(x, y, z) dS, \quad \overline{z} = \frac{1}{m} \iint_{S} z \rho(x, y, z) dS$$

Evaluating Surface Integrals



$$S: \mathbf{r}(u,v) = \langle x(u,v), y(u,v), z(u,v) \rangle, (u,v) \in D \subset \mathbb{R}^2$$

$$\Delta S_{ij} \approx |\mathbf{r}_u \times \mathbf{r}_v| \Delta u \Delta v$$

where
$$\mathbf{r}_{u} = \langle x_{u}, y_{u}, z_{u} \rangle$$
, $\mathbf{r}_{v} = \langle x_{v}, y_{v}, z_{v} \rangle$

$$\iint_{S} f(x, y, z) dS = \iint_{D} f(\mathbf{r}(u, v)) | \mathbf{r}_{u} \times \mathbf{r}_{v} | dA$$

Special Surfaces: Graph

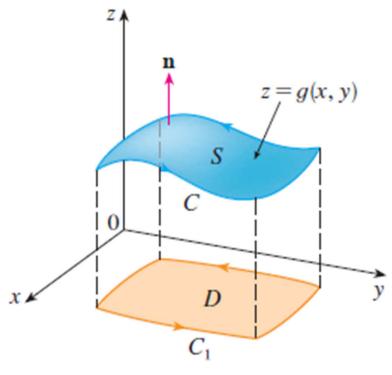
If S is the graph of a function z=g(x,y) with domain D, then

$$\mathbf{r}(x, y) = \langle x, y, g(x, y) \rangle$$

 $\mathbf{r}_{x}(x, y) = \langle 1, 0, g_{x}(x, y) \rangle$
 $\mathbf{r}_{y}(x, y) = \langle 0, 1, g_{y}(x, y) \rangle$

$$\mathbf{r}_{x} \times \mathbf{r}_{y} = \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ 1 & 0 & g_{x}(x, y) \\ 0 & 1 & g_{y}(x, y) \end{vmatrix} = \langle -g_{x}(x, y), -g_{y}(x, y), 1 \rangle$$

$$|\mathbf{r}_{x} \times \mathbf{r}_{y}| = \sqrt{g_{x}(x, y)^{2} + g_{y}(x, y)^{2} + 1}$$



$$\iint_{S} f(x, y, z) dS = \iint_{D} f(x, y, g(x, y)) \sqrt{(g_{x}(x, y))^{2} + (g_{y}(x, y))^{2} + 1} dA$$

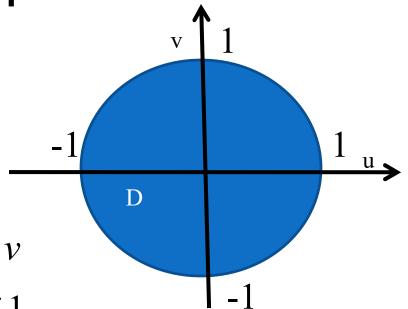
Example

Evaluate

$$\iint_{S} yzdS,$$

$$S: x = uv, \quad y = u + v, \quad z = u - v$$

where (u, v) satisfies $u^2 + v^2 \le 1$



Solution

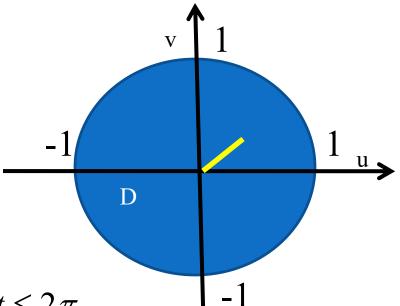
$$S: \mathbf{r} = \langle uv, u + v, u - v \rangle$$
 defined on $D: u^2 + v^2 \le 1$,
 $\mathbf{r}_u = \langle v, 1, 1 \rangle$, $\mathbf{r}_v = \langle u, 1, -1 \rangle$

$$\mathbf{r}_{u} \times \mathbf{r}_{v} = \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ v & 1 & 1 \\ u & 1 & -1 \end{vmatrix} = <-2, u + v, v - u >$$

$$|\mathbf{r}_{u} \times \mathbf{r}_{v}| = \sqrt{4 + (u + v)^{2} + (v - u)^{2}} = \sqrt{2u^{2} + 2v^{2} + 4}$$

$$I = \iint_{S} yzdS = \iint_{D} yz | r_{u} \times r_{v} | dA = \iint_{D} (u+v)(u-v)\sqrt{2u^{2} + 2v^{2} + 4}dA$$
$$= \iint_{D} (u^{2} - v^{2})\sqrt{2u^{2} + 2v^{2} + 4}dA$$

$$I = \iint_D (u^2 - v^2) \sqrt{2u^2 + 2v^2 + 4} dA$$



Change into polar coordinates:

$$D: u = r \cos t, v = r \sin t, 0 \le r \le 1, 0 \le t \le 2\pi$$

$$I = \int_{0}^{1} \int_{0}^{2\pi} r^{2} (\cos^{2} t - \sin^{2} t) \sqrt{2r^{2} + 4} r dt dr$$

$$= \int_{0}^{1} \int_{0}^{2\pi} (\cos(2t)) r^{3} \sqrt{2r^{2} + 4} dt dr = \int_{0}^{1} (\sin(2t) / 2) r^{3} \sqrt{2r^{2} + 4} \right) \Big|_{t=0}^{t=2\pi} dr$$

$$= \int_{0}^{1} 0 dr = 0$$

Oriented Surfaces: An example of one-sided strip

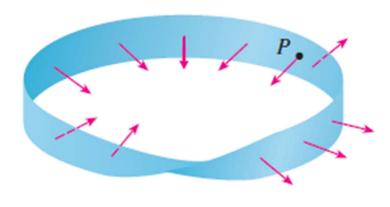
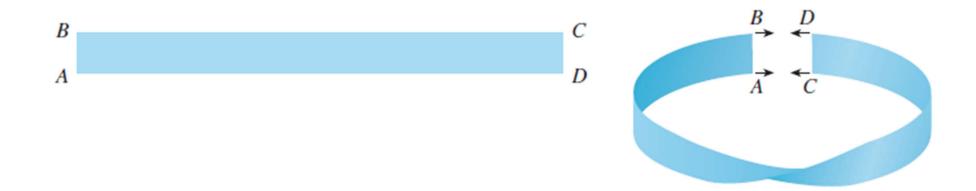


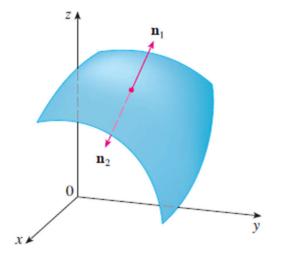
FIGURE 4 A Möbius strip

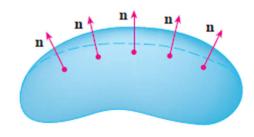


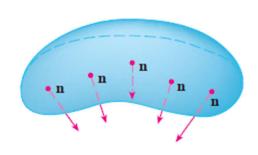
Oriented Surfaces

• Consider only orientable (two-sided) surfaces. We start with a surface that has a tangent plane at every point (x,y,z) on S (except at any boundary point). There are two unit normal vectors at (x,y,z)

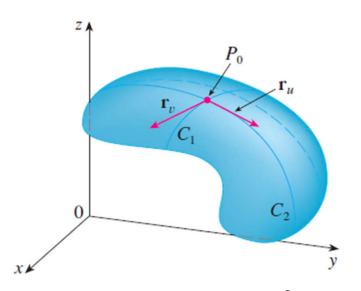
• If it is possible to choose a unit normal vector **n** at every point so that **n** varies continuously over *S*, then *S* is called an **oriented surface** and the given choice of **n** provides *S* with an **orientation**.







Normal vector for parametric surfaces



S is given by

$$\mathbf{r}(u,v) = \langle x(u,v), y(u,v), z(u,v) \rangle, (u,v) \in D \subset \mathbb{R}^2$$

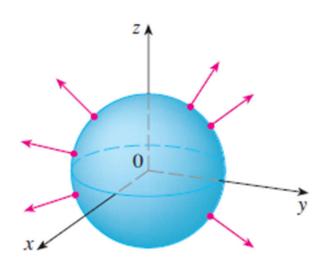
$$\mathbf{n} = \frac{\mathbf{r}_u \times \mathbf{r}_v}{|\mathbf{r}_u \times \mathbf{r}_v|}$$

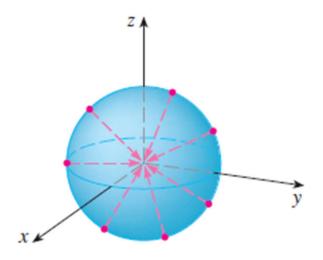
Opposite orientation: -n

S:
$$z = g(x, y)$$
, $\mathbf{r}(x, y) = \langle x, y, g(x, y) \rangle$, $(x, y) \in D$
 $\mathbf{r}_x \times \mathbf{r}_y = \langle -g_x(x, y), -g_y(x, y), 1 \rangle$

upward orientation:
$$\mathbf{n} = \frac{\mathbf{r}_x \times \mathbf{r}_y}{|\mathbf{r}_x \times \mathbf{r}_y|}$$
, downward orientation: $\mathbf{n} = -\frac{\mathbf{r}_x \times \mathbf{r}_y}{|\mathbf{r}_x \times \mathbf{r}_y|}$

Positive Orientation





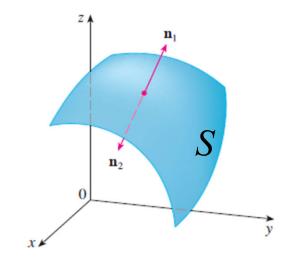
Positive orientation

Negative orientation

For a **closed surface**, that is, a surface that is the boundary of a solid region E, the convention is that the **positive orientation** is the one for which the normal vectors point outward from E, and inward-pointing normals give the negative orientation

Surface Integral of Vector Field

S: oriented surface with unit normal vector **n**



F: continuous vector field on S

Surface integral of F over S is defined by

$$\iint_{S} \mathbf{F} \bullet dS = \iint_{S} (\mathbf{F} \bullet \mathbf{n}) \ dS$$

This integral is also called the flux of F across S

Evaluation of surface integrals of vector fields

S is given by

$$\mathbf{r}(u,v) = \langle x(u,v), y(u,v), z(u,v) \rangle, (u,v) \in D \subset \mathbb{R}^2$$

Choose
$$\mathbf{n} = \frac{\mathbf{r}_u \times \mathbf{r}_v}{|\mathbf{r}_u \times \mathbf{r}_v|}$$

$$\iint_{S} \mathbf{F} \bullet dS = \iint_{S} (\mathbf{F} \bullet \frac{\mathbf{r}_{u} \times \mathbf{r}_{v}}{|\mathbf{r}_{u} \times \mathbf{r}_{v}|}) dS = \iint_{D} (\mathbf{F} \bullet \frac{\mathbf{r}_{u} \times \mathbf{r}_{v}}{|\mathbf{r}_{u} \times \mathbf{r}_{v}|}) |\mathbf{r}_{u} \times \mathbf{r}_{v}| dA$$



$$\iint_{S} \mathbf{F} \bullet dS = \iint_{D} \mathbf{F} \bullet (\mathbf{r}_{u} \times \mathbf{r}_{v}) dA$$

Surface S is a Graph

S:
$$z = g(x, y)$$
, $\mathbf{r}(x, y) = \langle x, y, g(x, y) \rangle$, $(x, y) \in D$
 $\mathbf{r}_x \times \mathbf{r}_y = \langle -g_x(x, y), -g_y(x, y), 1 \rangle$

upward orientation: $\mathbf{n} = \frac{\mathbf{r}_x \times \mathbf{r}_y}{|\mathbf{r}_x \times \mathbf{r}_y|}$, downward orientation: $\mathbf{n} = -\frac{\mathbf{r}_x \times \mathbf{r}_y}{|\mathbf{r}_x \times \mathbf{r}_y|}$

$$\mathbf{F} = \langle P, Q, R \rangle$$

Suppose S has upward orientation, then it holds on S that

$$\mathbf{F} \bullet (\mathbf{r}_{x} \times \mathbf{r}_{y}) = -P(x, y, g(x, y))g_{x}(x, y) - Q(x, y, g(x, y))g_{y}(x, y) + R(x, y, g(x, y)))$$



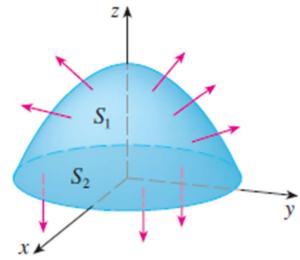
$$\iint_{S} \mathbf{F} \bullet dS = \iint_{D} \mathbf{F} \bullet (\mathbf{r}_{x} \times \mathbf{r}_{y}) dA = \iint_{D} \left(-Pg_{x} - Qg_{y} + R \right) dA$$

EXAMPLE Evaluate $\iint_S \mathbf{F} \cdot d\mathbf{S}$, where $\mathbf{F}(x, y, z) = y\mathbf{i} + x\mathbf{j} + z\mathbf{k}$ and S is the boundary of the solid region E enclosed by the paraboloid $z = 1 - x^2 - y^2$ and the plane z = 0.

SOLUTION S consists of a parabolic top surface S_1 and a circular bottom surface S_2 . Since S is a closed surface, we use the convention of positive (outward) orientation. This means that S_1 is oriented upward and D being the projection of S_1 onto the xy-plane, namely, the disk $x^2 + y^2 \le 1$. Since

$$P(x, y, z) = y$$
 $Q(x, y, z) = x$ $R(x, y, z) = z = 1 - x^2 - y^2$

on
$$S_1$$
 and $\frac{\partial g}{\partial x} = -2x$ $\frac{\partial g}{\partial y} = -2y$



$$\iint_{S_1} \mathbf{F} \cdot d\mathbf{S} = \iint_{D} \left(-P \frac{\partial g}{\partial x} - Q \frac{\partial g}{\partial y} + R \right) dA$$

$$= \iint_{D} \left[-y(-2x) - x(-2y) + 1 - x^2 - y^2 \right] dA$$

$$= \iint_{D} \left(1 + 4xy - x^2 - y^2 \right) dA$$

$$= \int_{0}^{2\pi} \int_{0}^{1} \left(1 + 4r^2 \cos \theta \sin \theta - r^2 \right) r \, dr \, d\theta$$

$$= \int_{0}^{2\pi} \int_{0}^{1} \left(r - r^3 + 4r^3 \cos \theta \sin \theta \right) \, dr \, d\theta$$

$$= \int_{0}^{2\pi} \left(\frac{1}{4} + \cos \theta \sin \theta \right) \, d\theta = \frac{1}{4} (2\pi) + 0 = \frac{\pi}{2}$$

The disk S_2 is oriented downward, so its unit normal vector is $\mathbf{n} = -\mathbf{k}$ and we have

$$\iint_{S_2} \mathbf{F} \cdot d\mathbf{S} = \iint_{S_2} \mathbf{F} \cdot (-\mathbf{k}) \, dS = \iint_D (-z) \, dA = \iint_D 0 \, dA = 0$$

since z = 0 on S_2 . Finally, we compute, by definition, $\iint_S \mathbf{F} \cdot d\mathbf{S}$ as the sum of the surface integrals of \mathbf{F} over the pieces S_1 and S_2 :

$$\iint_{S} \mathbf{F} \cdot d\mathbf{S} = \iint_{S_{1}} \mathbf{F} \cdot d\mathbf{S} + \iint_{S_{2}} \mathbf{F} \cdot d\mathbf{S} = \frac{\pi}{2} + 0 = \frac{\pi}{2}$$

Applications

Although we motivated the surface integral of a vector field using the example of fluid flow, this concept also arises in other physical situations. For instance, if **E** is an electric field (see Example 5 in Section 16.1), then the surface integral

$$\iint_{S} \mathbf{E} \cdot d\mathbf{S}$$

is called the electric flux of E through the surface S. One of the important laws of electrostatics is Gauss's Law, which says that the net charge enclosed by a closed surface S is

$$Q = \varepsilon_0 \iint_{S} \mathbf{E} \cdot d\mathbf{S}$$

where ε_0 is a constant (called the permittivity of free space) that depends on the units used. (In the SI system, $\varepsilon_0 \approx 8.8542 \times 10^{-12} \text{ C}^2/\text{N} \cdot \text{m}^2$.) Therefore, if the vector field **F** in Example 4 represents an electric field, we can conclude that the charge enclosed by S is $O = \frac{4}{3}\pi\varepsilon_0$.

Another application of surface integrals occurs in the study of heat flow. Suppose the temperature at a point (x, y, z) in a body is u(x, y, z). Then the **heat flow** is defined as the vector field

$$\mathbf{F} = -K\nabla u$$

where K is an experimentally determined constant called the **conductivity** of the substance. The rate of heat flow across the surface S in the body is then given by the surface integral

$$\iint\limits_{S} \mathbf{F} \cdot d\mathbf{S} = -K \iint\limits_{S} \nabla u \cdot d\mathbf{S}$$